

1-bit Compressive Sensing

Petros Boufounos
Richard Baraniuk



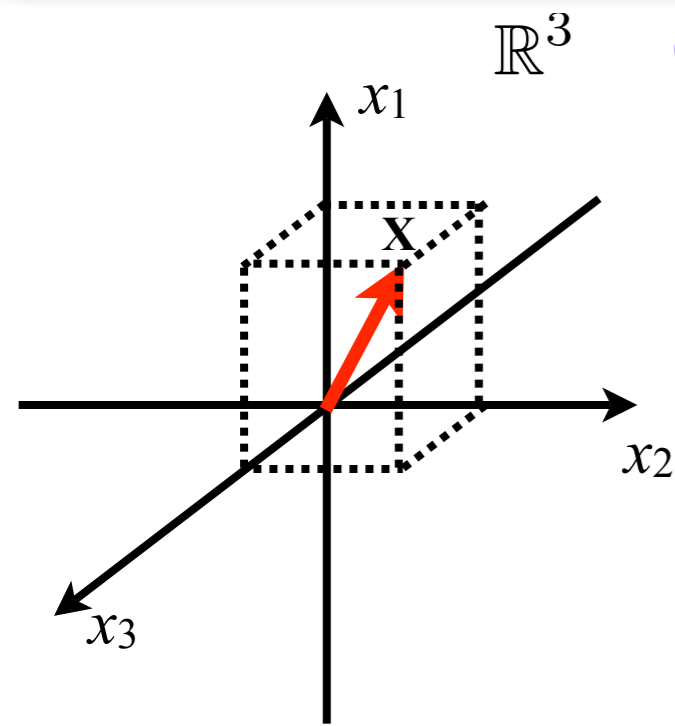
Compressive Sensing

1. Signal Model

2. Random linear measurements

3. Non-linear reconstruction

Signal Models



Classical Model: Signal lies in a **linear vector space** (e.g. bandlimited functions)

Sparse Model: Signals of interest are often **sparse** or **compressible**

Image



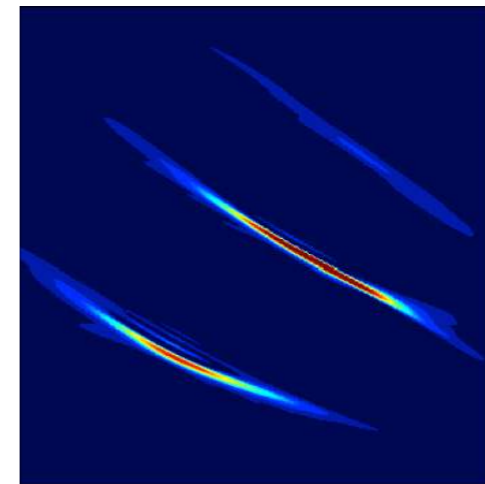
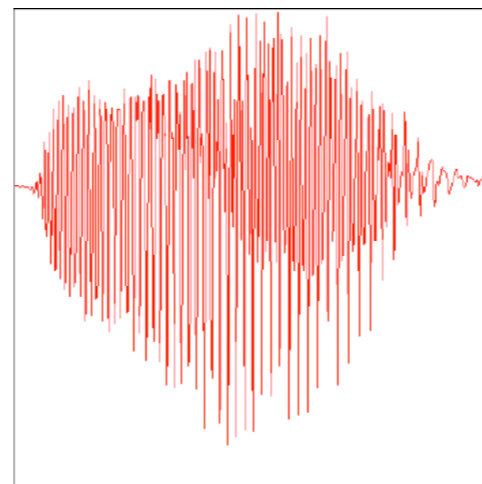
Signal



Transform

Wavelet

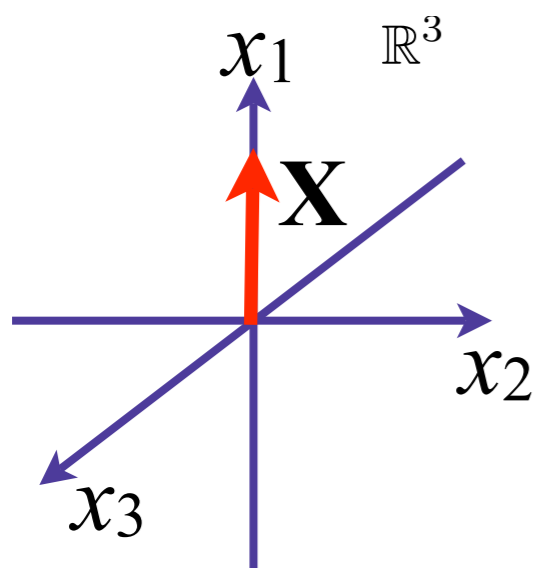
Bat Sonar Chirp



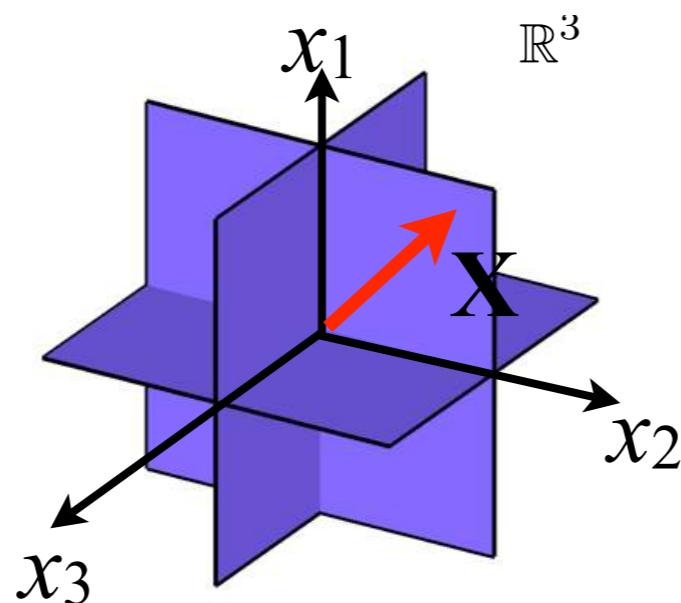
Gabor/
STFT

i.e., very **few large coefficients**, many close to zero.

Sparse Signal Models

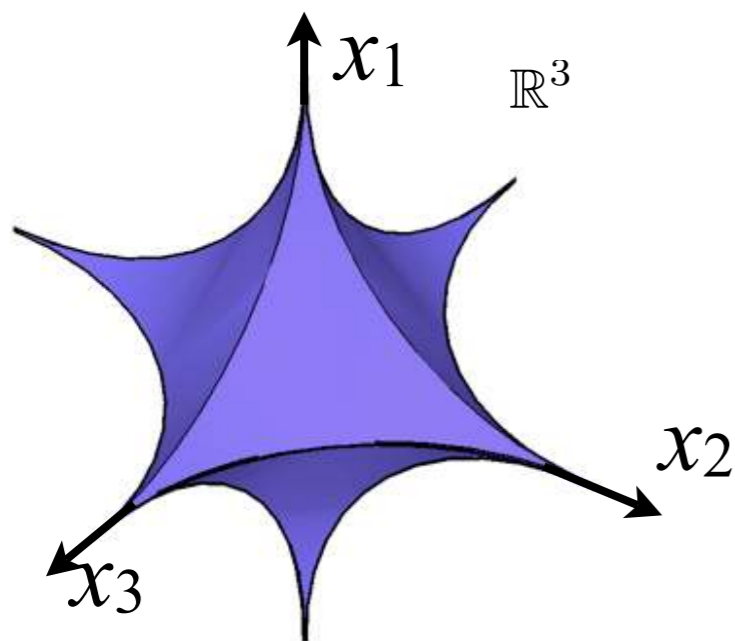


1-sparse



2-sparse

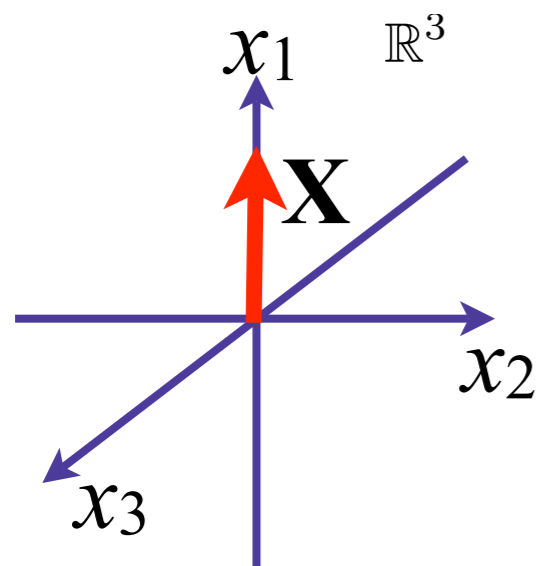
Sparse signals have few non-zero coefficients.



Compressible signals have few significant coefficients. The coefficients decay as a power law.

Compressible (ℓ_p ball, $p < 1$)

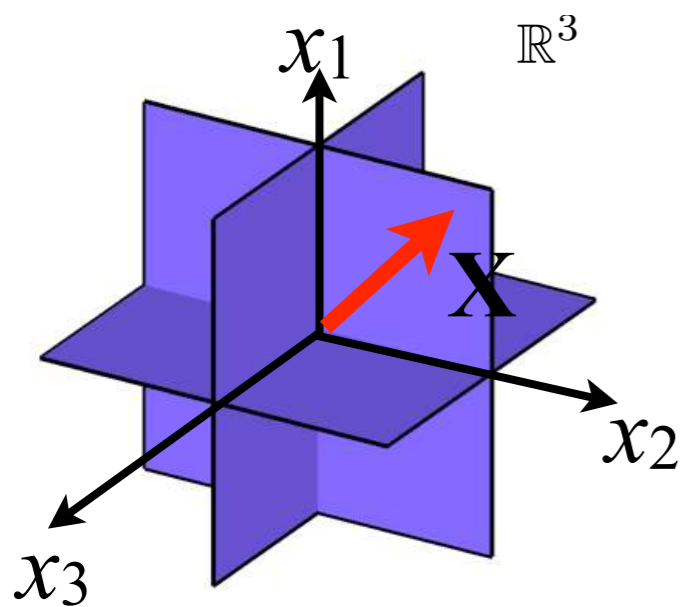
Compressive Sensing in a Nutshell



1-sparse

If a signal is **sparse**, do not waste effort sampling the **empty space**.

Instead, use fewer samples and allow **ambiguity**.

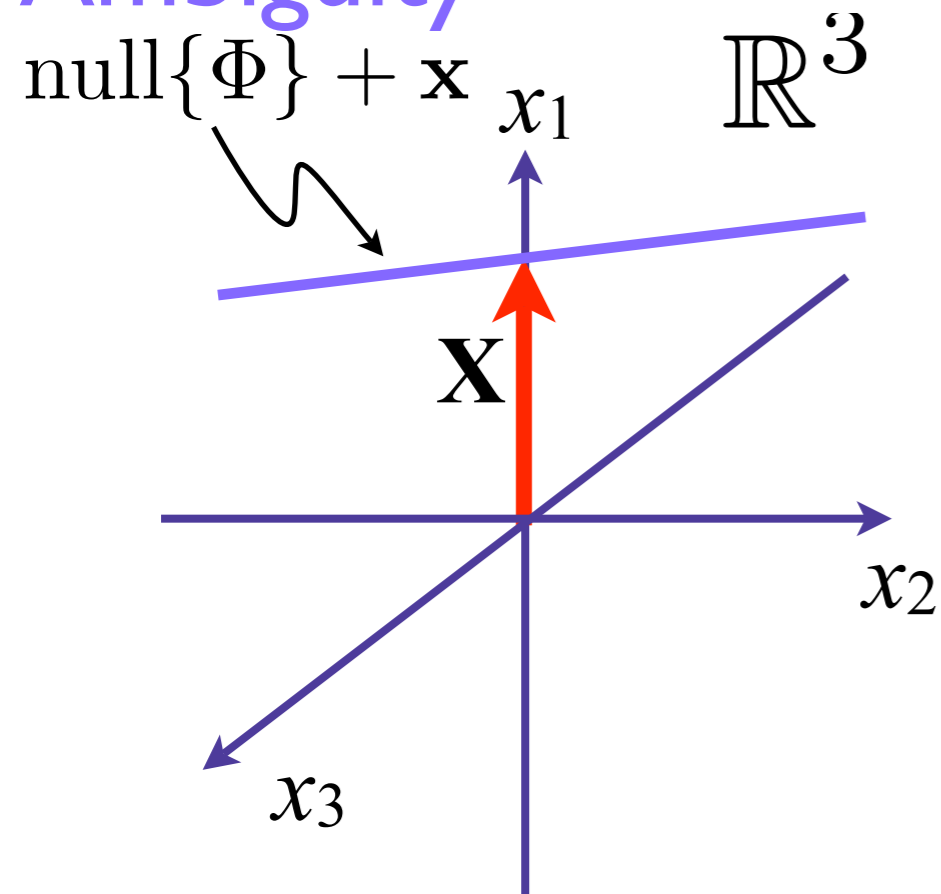


2-sparse

Use the **sparsity model** to reconstruct and **uniquely resolve the ambiguity**.

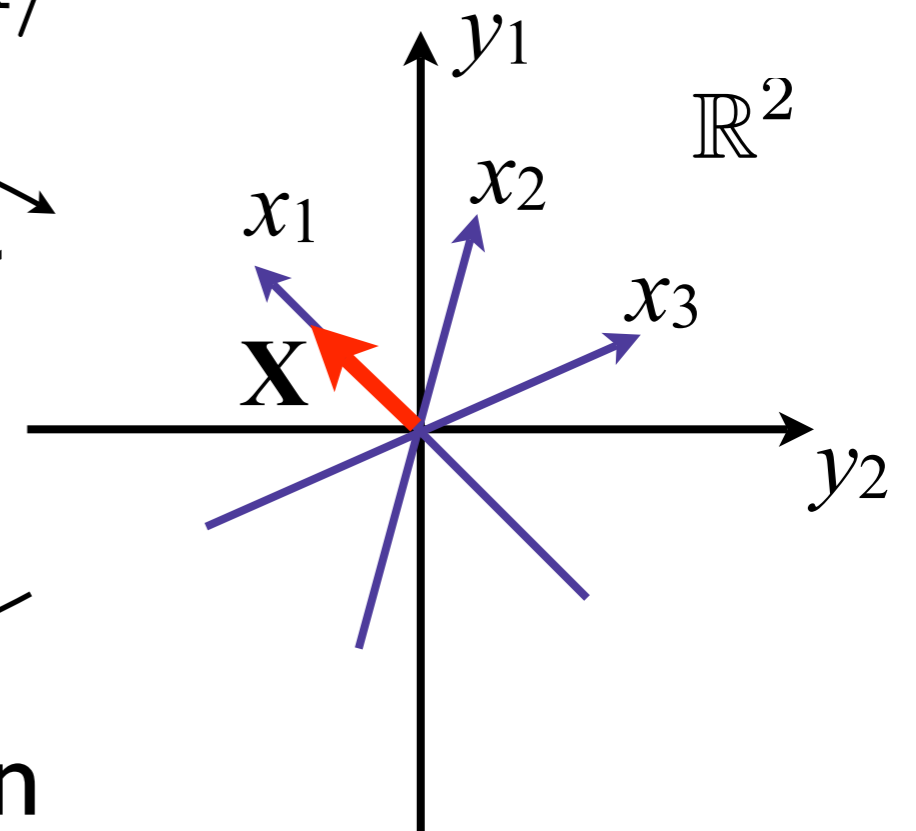
Compressive Measurements

Ambiguity



$$\mathbf{y} = \Phi \mathbf{x}$$
$$y_i = \langle \phi_i, \mathbf{x} \rangle$$

Measurement
(Projection)



Reconstruction

Φ has rank $M \ll N$

Φ is usually random w/ $M = O(K \log N / K)$

N = Signal dimensionality

M = Number of measurements

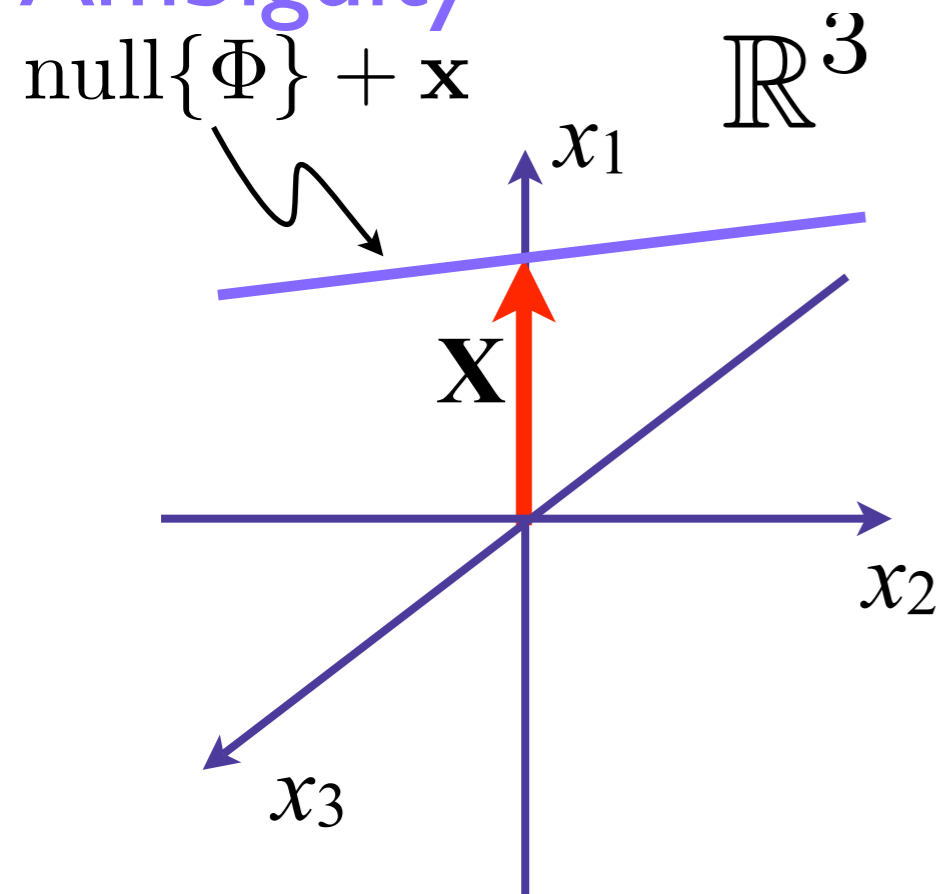
K = Signal sparsity

(dimensionality of \mathbf{y})

$$N \gg M \gtrsim K$$

Non-linear Reconstruction

Ambiguity



Reconstruction should be:

1. Consistent with measurements:

$$\mathbf{y} = \Phi \mathbf{x}$$

2. Consistent with the model:

\mathbf{x} is as sparse as possible

Sparsity measure

~~$\min_{\mathbf{x}} \|\mathbf{x}\|_0$ subject to $\mathbf{y} = \Phi \mathbf{x}$~~

~~$\min_{\mathbf{x}} \|\mathbf{x}\|_1$ subject to $\mathbf{y} = \Phi \mathbf{x}$~~

\Updownarrow

Expensive!

Compressive Sensing

1. Signal Model

2. Random linear measurements

3. Non-linear reconstruction

Beyond Linear Measurements: 1-bit Quantization

Q: Can we quantize measurements to **1-bit**:

$$\mathbf{y} = \text{sign}(\Phi \mathbf{x})$$

$$y_i = \text{sign}(\langle \phi_i, \mathbf{x} \rangle)$$

and recover the signal (within a positive scaling factor)?

1-bit measurements are **inexpensive**.

Focus on **bits** rather than measurements.

Exact recovery is **not possible**.

Sign information from 1-bit measurements:

$$y_i = \text{sign}(\Phi \mathbf{x})_i \Leftrightarrow y_i \cdot (\Phi \mathbf{x})_i \geq 0$$

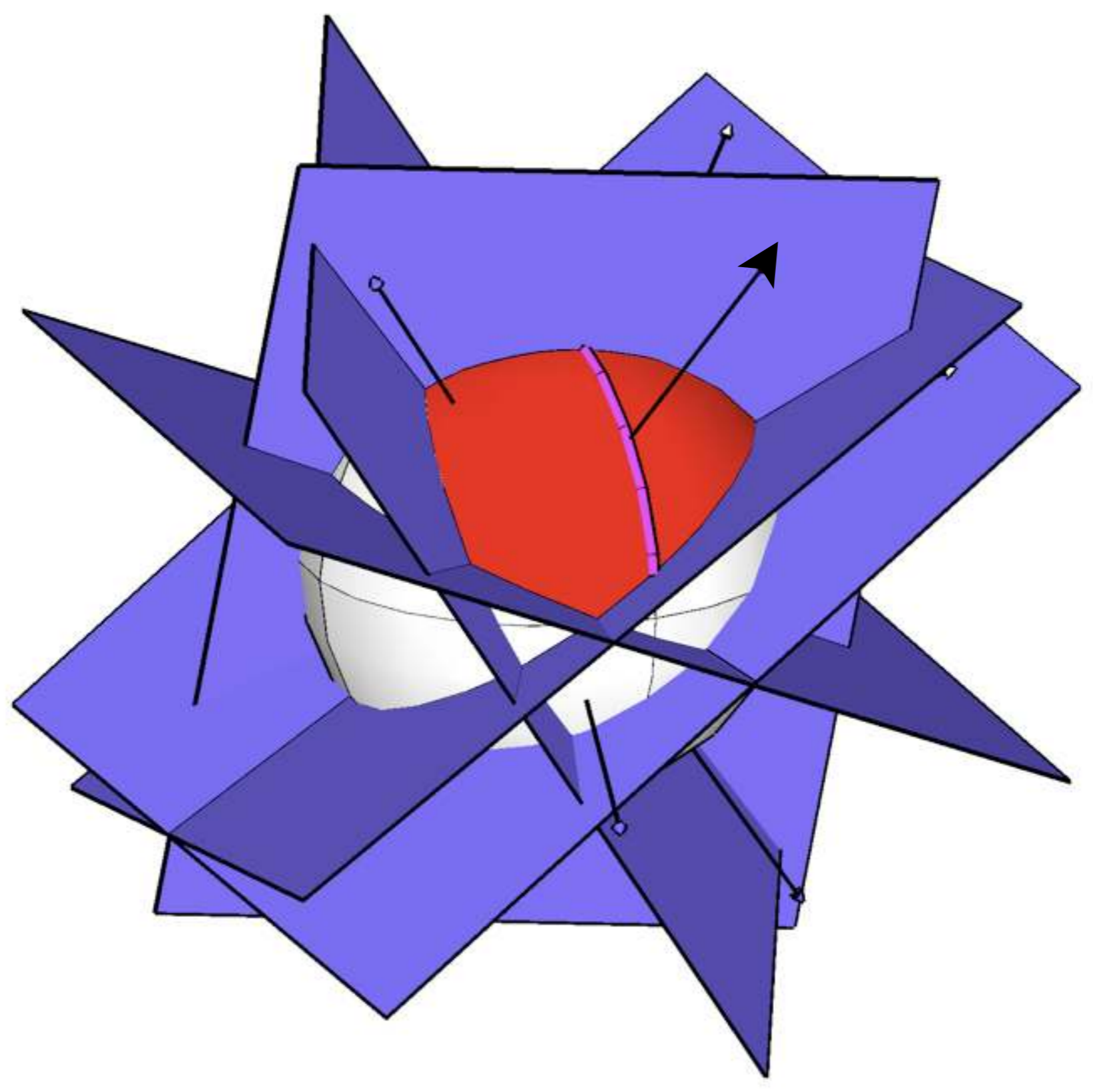
Reconstruction should enforce **model**.

Reconstruction should be **consistent** with measurements.

Reconstruction should enforce a **non-trivial solution**.

$$\begin{aligned} \hat{\mathbf{x}} &= \arg \min_{\mathbf{x}} \|\mathbf{x}\|_1 \\ \text{subject to} & \quad y_i \cdot (\Phi \mathbf{x})_i \geq 0 \\ \text{and} & \quad \|\mathbf{x}\|_2 = 1 \end{aligned}$$

Information in 1-bit Measurements



Constraint Relaxation

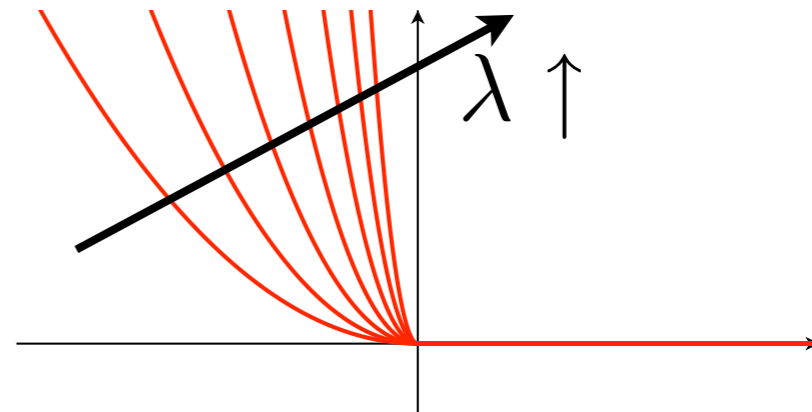
$$\begin{aligned}\hat{\mathbf{x}} &= \arg \min_{\mathbf{x}} \|\mathbf{x}\|_1 \\ \text{subject to } & y_i \cdot (\Phi \mathbf{x})_i \geq 0 \\ \text{and } & \|\mathbf{x}\|_2 = 1\end{aligned}$$

We relax the inequality constraints:

$$\begin{aligned}\hat{\mathbf{x}} &= \arg \min_{\mathbf{x}} \|\mathbf{x}\|_1 + \frac{\lambda}{2} \sum_i f(y_i \cdot (\Phi \mathbf{x})) \\ \text{subject to } & \|\mathbf{x}\|_2 = 1\end{aligned}$$

where $f(x)$ is a one sided quadratic:

$$f(x) = \begin{cases} x^2 & x \leq 0 \\ 0 & x > 0 \end{cases}$$



$$\hat{\mathbf{x}} = \arg \min_{\mathbf{x}} \|\mathbf{x}\|_1 + \frac{\lambda}{2} \sum_i f(y_i \cdot (\Phi \mathbf{x}))$$

subject to $\|\mathbf{x}\|_2 = 1$

Unconstrained minimization:

$$Y \equiv \text{diag}(\mathbf{y})$$

$$\text{Cost}(\mathbf{x}) = g(\mathbf{x}) + \frac{\lambda}{2} f(Y\Phi \mathbf{x})$$

$$\text{Cost}'(\mathbf{x}) = g'(x) + \frac{\lambda}{2} (Y\Phi)^T f(Y\Phi \mathbf{x})$$

$$(g'(\mathbf{x}))_i = \begin{cases} -1 & x_i < 0 \\ [-1, 1] & x_i = 0 \\ +1 & x_i > 0 \end{cases} \quad \text{and} \quad \left(\frac{f'(\mathbf{x})}{2} \right)_i = \begin{cases} -x_i & x_i \leq 0 \\ 0 & x_i > 0 \end{cases}$$

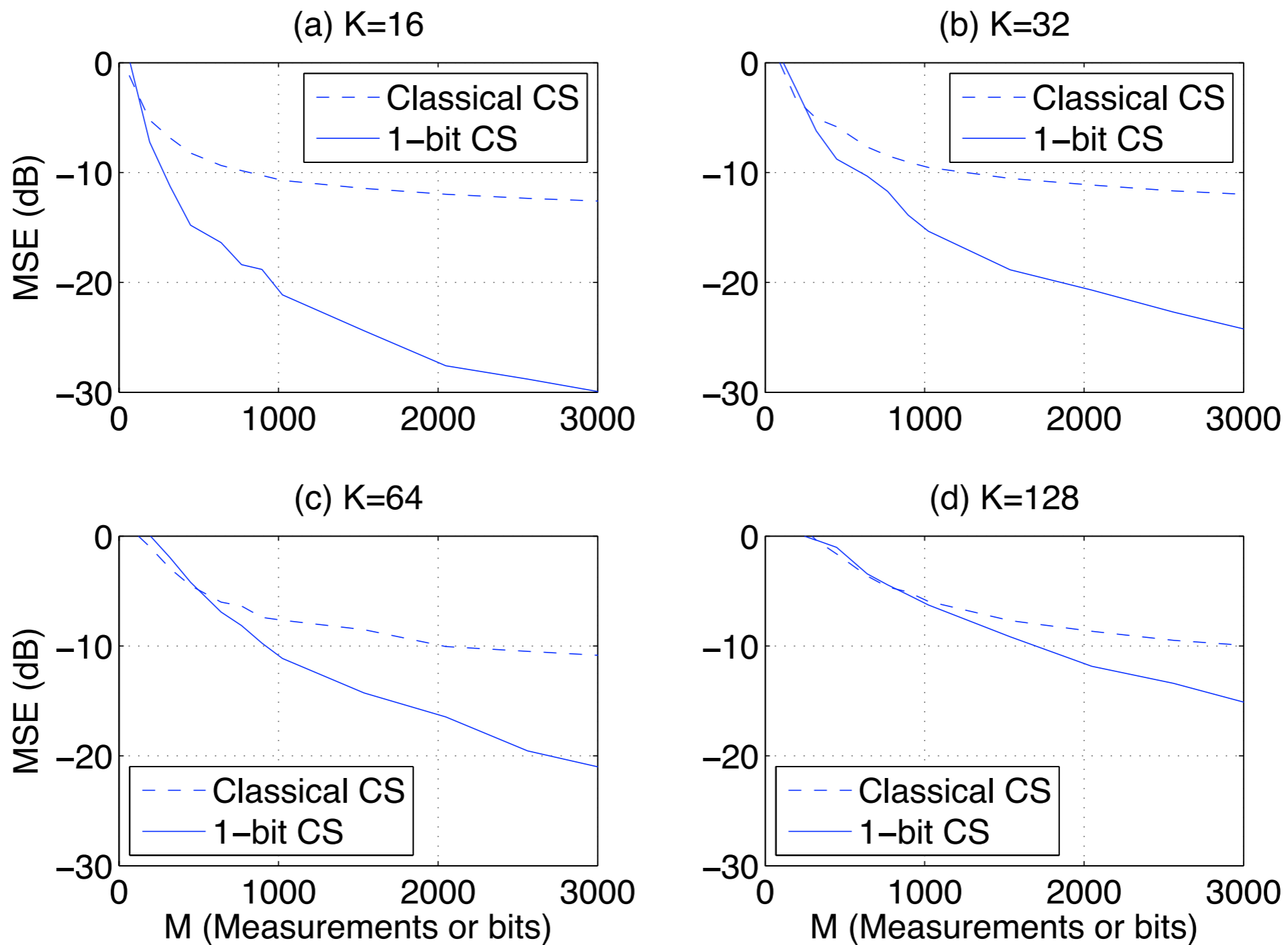
No change if gradients are **projected on unit sphere.**

Big Picture: Gradient descent until equilibrium.

Initialization parameters: $\hat{\mathbf{x}}, \tau$

1. **Compute** quadratic gradient: $\mathbf{h} = (\mathbf{Y}\Phi)^T f'(\mathbf{Y}\Phi\mathbf{x})$
2. **Project** onto sphere: $\mathbf{h}_p = \mathbf{h} - \langle \hat{\mathbf{x}}, \mathbf{h} \rangle \hat{\mathbf{x}}$
3. **Quadratic gradient descent**: $\hat{\mathbf{x}} \leftarrow \hat{\mathbf{x}} - \tau \mathbf{h}_p$
4. **Shrink** (ℓ_1 gradient descent):
$$\hat{x}_i \leftarrow \text{sign}(\hat{x}_i) \max \left\{ |\hat{x}_i| - \frac{\tau}{\lambda}, 0 \right\}$$
5. **Normalize**: $\hat{\mathbf{x}} \leftarrow \frac{\hat{\mathbf{x}}}{\|\hat{\mathbf{x}}\|}$
6. **Iterate** until equilibrium.

Reconstruction Error ($N=512$)



If the signal is an **image**, we have more information!
(i.e., a **better signal model**)

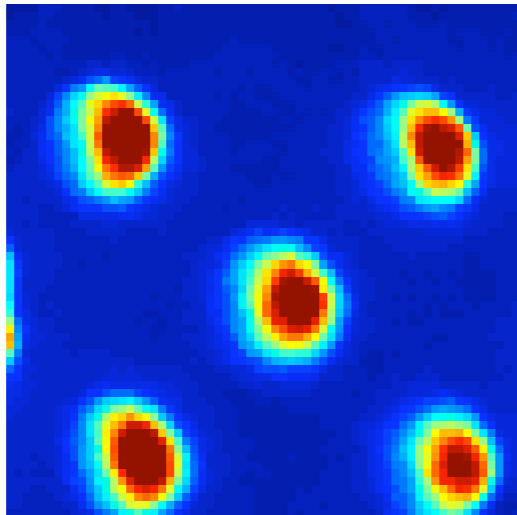
Images are **sparse in wavelets** and **positive**:

$$\begin{aligned} \mathbf{x} &= \mathbf{W}\alpha \\ x_i &\geq 0 \\ \text{and } \alpha &\text{ is sparse} \end{aligned}$$

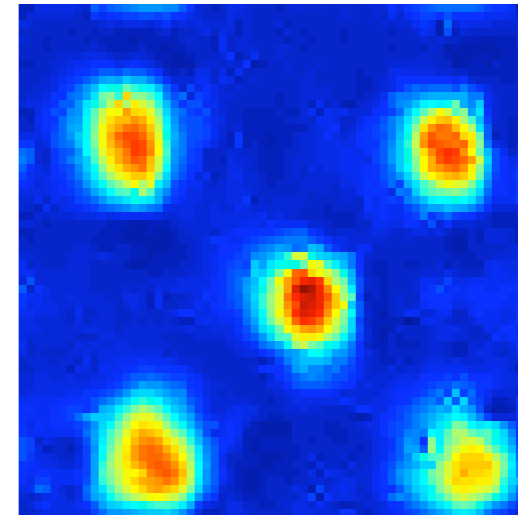
Incorporate **better model** in the reconstruction:

$$\begin{aligned} \hat{\alpha} &= \arg \min_{\alpha} \|\alpha\|_1 \\ \text{subject to } &y_i \times (\Phi \mathbf{W})_i \geq 0 \\ &\text{and } (\mathbf{W}\alpha)_i \geq 0 \\ &\text{and } \|\alpha\|_2 = 1 \end{aligned}$$

Reconstruction on unit sphere 1 bit per pixel

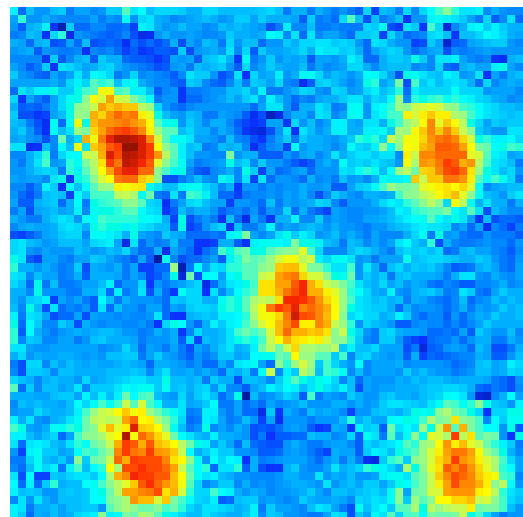


Original Image
4096 pixels
256 levels

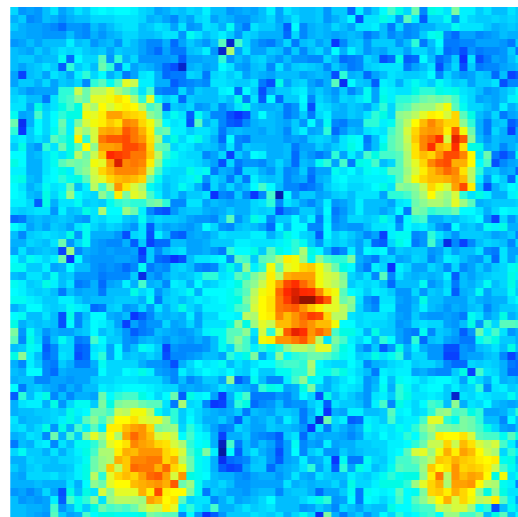


4096 measurements
1 bit per measurement

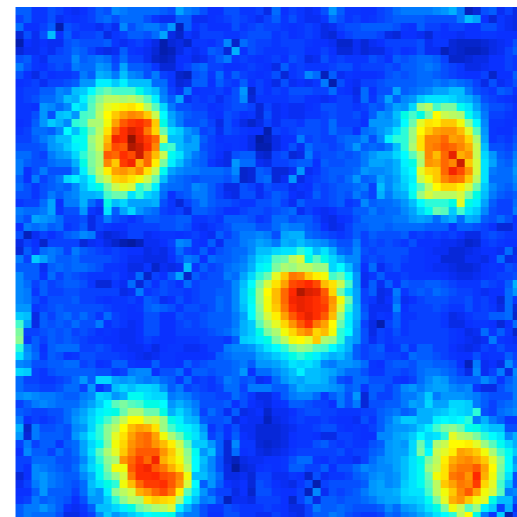
Classical Compressive Sensing, 1 bit per pixel



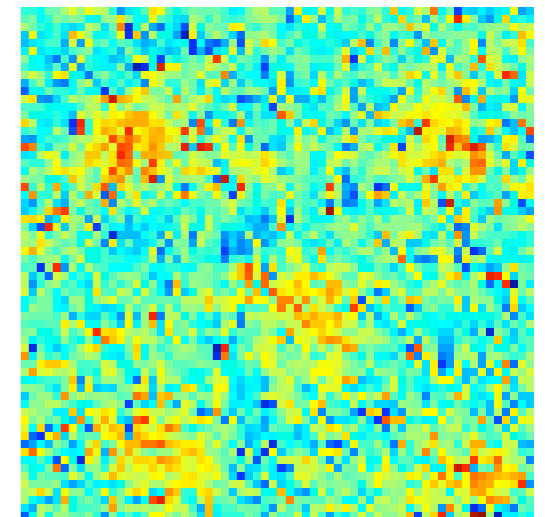
4096 measurements
1 bit per measurement



2048 measurements
2 bits per measurement

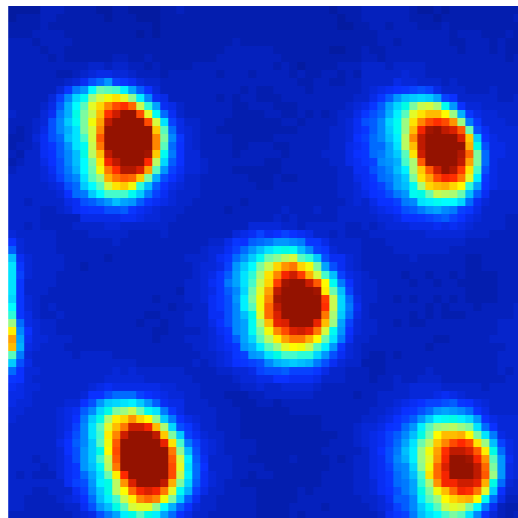


1024 measurements
4 bits per measurement

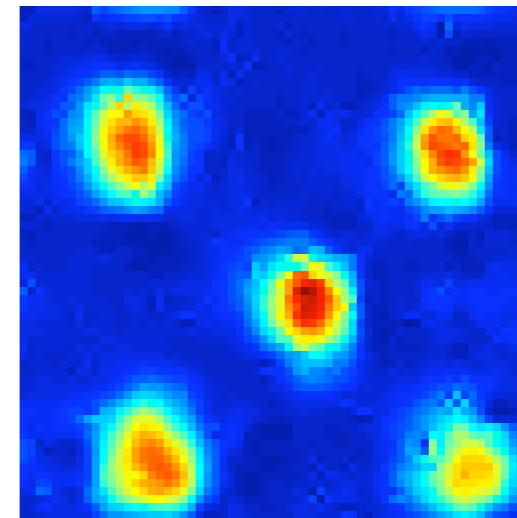


512 measurements
8 bits per measurement

Reconstruction on unit sphere

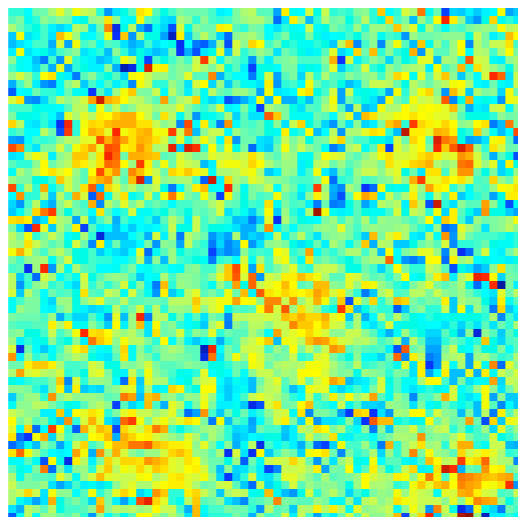


Original Image
4096 pixels
256 levels



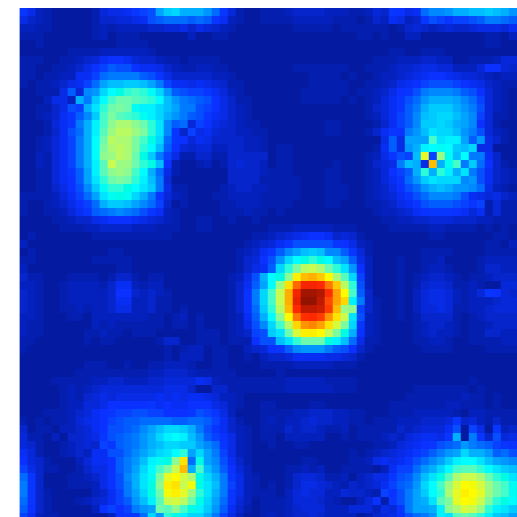
4096 measurements
1 bit per measurement
4096 bits (1 bit per pixel)

Classical Compressive Sensing



512 measurements
8 bits per measurement

Reconstruction on unit sphere



512 measurements
1 bit per measurement
512 bits (0.125 bits per pixel)

Q: Can we quantize measurements to 1-bit:

$$\mathbf{y} = \text{sign}(\Phi \mathbf{x})$$

$$y_i = \text{sign}(\langle \phi_i, \mathbf{x} \rangle)$$

and recover the signal (within a positive scaling factor)?

YES:

- 1-bit measurements only provide sign information
- We treat measurements as constraints
- We do not try to recover amplitude information
- We enforce reconstruction on the unit sphere
- Better signal model provides dramatic improvements