

A 100-MHz 100-dB Operational Amplifier with Multipath Nested Miller Compensation Structure

Ruud G. H. Eschauzier, Leo P. T. Kerklaan, and Johan H. Huijsing, *Senior Member, IEEE*

Abstract—A 100-MHz bipolar operational amplifier has a gain of 100 dB. The op amp owes its high unity-gain bandwidth and high gain to an all-n-p-n signal path and multipath nested Miller compensation (MNMN). The phase margin with a 100-pF load is 40° at 100 MHz and the amplifier settles in 60 ns to 0.1% on a 1-V step. For comparison, a similar op amp without the multipath technique has been realized. The unity-gain bandwidth of this nested Miller compensation (NMC) op amp is 60 MHz and the settling time is 70 ns. Theory and measurements confirm that the multipath technique almost doubles the bandwidth of nested Miller compensated amplifiers.

I. INTRODUCTION

SPEED or bandwidth demands are generally in conflict with demands on low-frequency accuracy or gain in an operational amplifier (op amp). Op amps consisting of three gain stages to obtain an acceptable dc gain cannot be frequency compensated by conventional means. A widespread compensation method like simple pole splitting is only capable of handling the two dominant poles that occur in two-stage amplifiers.

For this reason, high-frequency bypass techniques are extensively used in high-frequency high-gain amplifiers [1]. In these amplifiers one gain stage is bypassed by a capacitor, short circuiting the stage for high frequencies. This compensation method greatly worsens the settling time of the operational amplifier because of the strong and inevitable pole-zero doublet the feedforward capacitor introduces [2].

A more effective way to compensate an amplifier containing three gain stages or more is by nested Miller compensation (NMC) [3]. This compensation technique nests Miller feedback loops, as shown in Fig. 1. The structure starts off with an output device with a Miller capacitor connected across it. For every gain stage added to the circuit, an additional Miller capacitor is introduced, closing a wider feedback loop.

Manuscript received April 27, 1992; revised July 10, 1992. This work was supported by the Technology Foundation (STW).

R. G. H. Eschauzier and J. H. Huijsing are with the Department of Electrical Engineering, Delft University of Technology, 2628 CD Delft, The Netherlands.

L. P. T. Kerklaan was with the Department of Electrical Engineering, Delft University of Technology, 2628 CD Delft, The Netherlands. He is now with Philips Industrial Electronics, 5600 MO Eindhoven, The Netherlands.

IEEE Log Number 9203617.

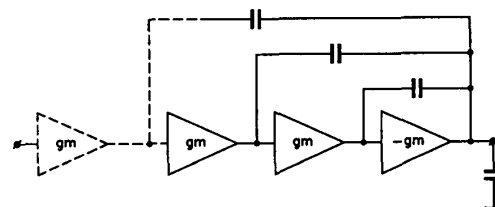


Fig. 1. Principle of nested Miller compensation.

Unfortunately, NMC causes a bandwidth reduction compared to simple pole splitting. The bandwidth halves, for example, when stepping from a two-stage simple Miller compensated amplifier to a three-stage amplifier with nested Miller compensation.

The multipath nested Miller compensation (MNMN) structure proposed in this paper overcomes the bandwidth reduction typical of conventional NMC by introducing an *independent* path for high frequencies. The MNMN structure consists of NMC with a multipath input stage connected in parallel with the regular input stage of the op amp. The multipath stage directly drives the output transistor, bypassing the intermediate stage for high frequencies.

In the ideal case no pole-zero doublets occur, because the multipath input stage can be independently configured from the remainder of the amplifier. In practice, the matching depends on the ratio of transconductances and the ratio of capacitors, both being among the best controlled parameters in a standard IC process.

To take full benefit of the MNMN, the operational amplifier presented is based on an all-n-p-n topology, allowing an extremely high unity-gain bandwidth. Combined with an effective class-AB control, the result represents the state of the art in high-bandwidth precision operational amplifiers.

For comparison, two operational amplifiers have been realized. The first is compensated using NMC and displays a unity-gain bandwidth of 60 MHz with a 100-pF load. The second op amp has an additional multipath input stage, which raises the bandwidth to 100 MHz under the same conditions.

The organization of the paper is as follows. The next section addresses the principle of operation of the nested and the multipath nested Miller compensation structures.

In Section III the two realized op amps are discussed, including the all-n-p-n topology and class-AB control. Section IV gives the experimental results. The paper finishes with the conclusions and references.

II. PRINCIPLE OF OPERATION

A. Nested Miller Compensation

Fig. 2 shows the simplified schematic of a three-stage amplifier with NMC. Fig. 3 is the corresponding Bode plot. It shows the frequency characteristic of the output stage, resulting from C_{m1} and C_{m2} .

The output stage has two dominant poles p_1 and p_2 , represented in Fig. 2 by the corresponding resistors and capacitors. Inserting C_{m1} splits the poles, such that p_1 shifts to a higher frequency p'_1 and p_2 to a lower frequency p'_2 . This is the effect of normal pole splitting, resulting in a well-behaved combination of the intermediate and output stage.

Miller capacitor C_{m2} , which closes the second loop, acts on the newly placed pole p'_1 and the additional pole p_3 , the latter being introduced by the input stage. Splitting these two poles results in a straight 20-dB/decade rolloff from the dominating pole frequency p''_2 up to the unity-gain frequency ω_0 . The Miller capacitors also help reduce distortion by applying all internal gain across the output stage.

The process of pole splitting is further clarified by Fig. 4(a) and (b). These figures show the root loci for C_{m1} and C_{m2} , respectively. Pole p'_1 , positioned by the inner Miller capacitor C_{m1} , limits the bandwidth of the op amp. To first order p'_1 depends on the ratio of the transconductance of the output stage and the load capacitor C_l :

$$p'_1 = \frac{g_{m1}}{C_l}. \quad (1)$$

The design criteria for the NMC follow from requiring a Butterworth frequency response from the amplifier with unity-gain feedback:

$$\frac{g_{m2}}{C_{m1}} = \frac{1}{2} p'_1 \quad (2)$$

$$\frac{g_{m3}}{C_{m2}} = \frac{1}{4} p'_1 = \omega_0 \quad (3)$$

where g_{m2} is the transconductance of the intermediate stage and g_{m3} is the transconductance of the first stage. Expression (2) gives a hint about the dimensioning of a NMC amplifier. The unity-gain frequency of the inner loop, set by the transconductance of the intermediate stage g_{m2} and the inner Miller capacitor C_{m1} , has to equal half the limiting pole frequency p'_1 .

As (3) reveals, the unity-gain bandwidth of the NMC op amp ω_0 is one-fourth of the limiting pole frequency p'_1 . This is half the value that could be obtained in a two-stage amplifier with simple Miller compensation.

The bandwidth reduction is due to the downward shift of pole p'_1 when the outer Miller loop with capacitor C_{m2}

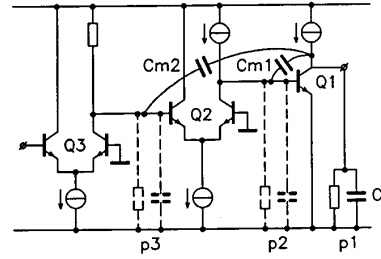


Fig. 2. Three-stage NMC.

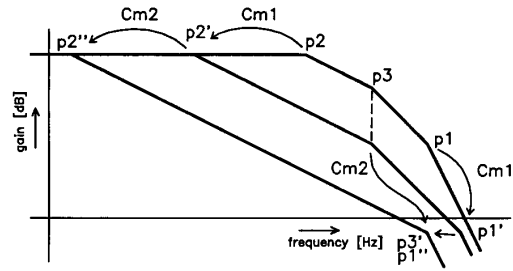


Fig. 3. Bode plot of the NMC structure.

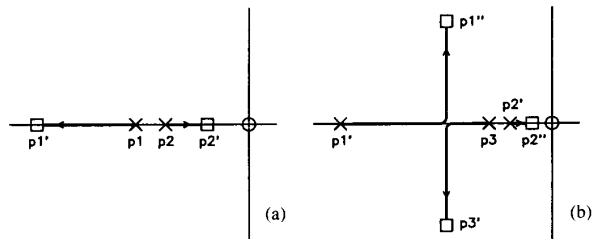


Fig. 4. Root locus of the NMC structure with effects of (a) C_{m1} and (b) C_{m2} .

is closed. At approximately half its frequency pole p'_1 collides with p_3 . Fig. 4(b) illustrates this effect. Pole frequency $|p''_1|$ obeys

$$|p''_1| = \frac{1}{2} \sqrt{2} p'_1. \quad (4)$$

B. Multipath Nested Miller Compensation

Fig. 5 demonstrates how adding an independent parallel input stage transforms the NMC structure into the MNMC structure. Transistors Q_1 through Q_3 together with the two capacitors C_{m1} and C_{m2} build up the conventional NMC structure. The multipath input stage is transistor pair Q_4 . This differential pair directly drives the output transistor, overruling Q_2 for high frequencies.

In Fig. 6 the Bode plot of the MNMC amplifier is shown. Drawn as a dashed line is the high-gain low-frequency part established by the three-stage NMC amplifier. The solid line represents the high-frequency part created by the two transistors Q_4 and Q_1 and Miller capacitor C_{m1} . Since this HF part is solely determined by a two-stage amplifier with simple Miller compensation, no

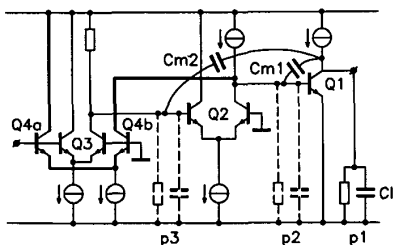


Fig. 5. Multipath NMC.

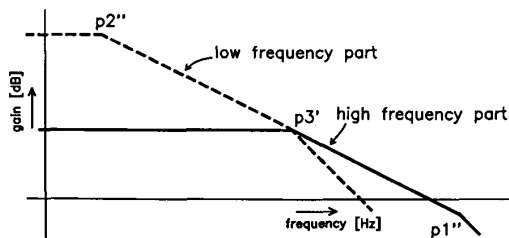


Fig. 6. Bode plot of the MNMC structure.

bandwidth reduction takes place. Matching of the high- and low-frequency parts is easy, as the following analysis confirms.

It is important to note that the multipath input stage adds a zero to the transfer function. The positions of the poles do not change compared to NMC. This makes clear that the dimensioning of the MNMC circuit should be different from the NMC circuit, otherwise the second pole p_1'' will stay at its place and no bandwidth improvement is to be expected. The position of pole p_1'' with respect to its original position p_1' before closing the second Miller loop is given by

$$p_1'' = \frac{p_1'}{2} + \frac{p_1'}{2} \sqrt{1 - \frac{4g_{m2}}{p_1' C_{m1}}} \quad (5)$$

From (5) it follows that the greater ratio g_{m2}/C_{m1} (the unity-gain frequency of the inner Miller loop) compared to the limiting pole frequency p_1' , the lower the bandwidth of the circuit. Setting g_{m2} to zero leads to $p_1'' = p_1'$. Obviously, in this case there is no bandwidth reduction, since only two stages are active. A better choice is

$$\frac{g_{m2}}{C_{m1}} \approx 0.1p_1' \quad (6)$$

With this ratio, the bandwidth reduction is only about 10% and still three stages contribute to the low-frequency gain.

Putting the multipath zero on top of pole p_3' requires

$$\frac{g_{m3}}{C_{m2}} = \frac{g_{m4}}{C_{m1}} \quad \text{if} \quad \frac{g_{m2}}{C_{m1}} \ll p_1' \quad (7)$$

The condition in (7) is satisfied by (6). As (7) reveals, the matching of the pole and the zero only depends on the matching of transconductances and capacitors.

The position of the doublet is

$$\omega_{pz} = \frac{g_{m2}}{C_{m1}} \quad (8)$$

Or, with (6)

$$\omega_{pz} \approx 0.1p_1' \approx 0.2\omega_0 \quad (9)$$

since for a phase margin of 60° the unity-gain frequency ω_0 of the op amp should be half p_1' ($\approx p_1''$).

The root locus in Fig. 7 shows the movement of the poles in the MNMC structure. In contrast to NMC, closing the outer Miller loop only moves the poles a fraction, because of the low value g_{m2}/C_{m1} . Pole p_3' is eliminated by the multipath zero.

III. CIRCUIT DESCRIPTION

A. All-n-p-n Topology

Fig. 8 is a simplified schematic of the op amp with NMC. To assure a high bandwidth, only n-p-n transistors are present in the signal path. As a consequence, in the push-pull output stage an emitter follower has to be used for the push and an inverting amplifier for the pull transistor. The emitter following Q_{400} has a capacitor C_{p1} connected from its base to ground and the inverting amplifier Q_{500} a Miller capacitor from base to collector. Capacitors C_{m1} and C_{p1} have equal values.

Surprisingly, when driven by a current signal both transistor configurations behave symmetrically [4]. Not only do they have the same transimpedance z_t , but also their output impedances z_{out} are equal.

$$z_t = \frac{1}{sC_{m1}} = \frac{1}{sC_{p1}} \quad (10)$$

$$z_{out} = \frac{1}{s\beta_f C_{m1}} = \frac{1}{s\beta_f C_{p1}} \quad (11)$$

Because of the differential second stage in Fig. 8, the circuit has a capacitor C_{p2} added to it to balance out Miller capacitor C_{m2} .

The level-shift circuit, depicted as a voltage source in Fig. 8, has the characteristics of an all-pass current network [4]. In Fig. 9 the circuit is shown. For input currents there are two separate routes from input to output. For low frequencies the signal goes through the resistor and the p-n-p transistor. For high frequencies the path is through the capacitor and the n-p-n current follower. The crossover frequency f_{np} is set by the RC product. As long as f_{np} is lower than the f_t of the p-n-p transistor, no pole-zero doublets occur, because no current is lost in the all-pass network. The bandwidth of the level-shift circuit equals the n-p-n's f_t . The location of the level shift in the circuit is dictated by noise considerations. Situating the level shift directly following the input stage would have increased the noise, because this would mean abandoning the passive collector loads.

The MNMC op amp is largely similar to the NMC op

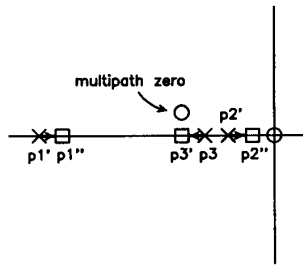


Fig. 7. Root locus of the MNMC structure.

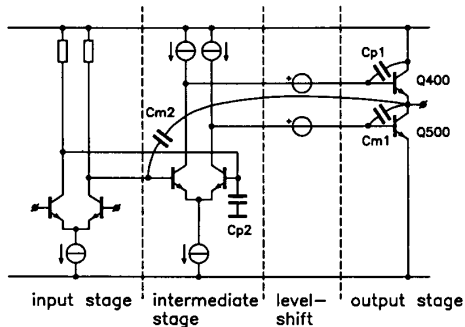


Fig. 8. Simplified schematic of the NMC op amp.

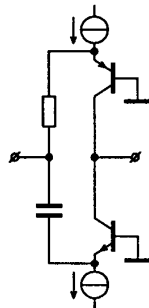


Fig. 9. All-pass level-shift circuit.

amp in Fig. 8. Added is the multipath input stage, as Fig. 10 points out.

B. Class-AB Control

The feedback class-AB circuit controls the quiescent current of the output stage and prevents cutoff of the output devices by assuring a minimum quiescent current [5].

The control circuitry is independent from the signal path, as demonstrated in Fig. 11. The signal is applied to the output transistors as two differential currents, while the class-AB circuit controls the biasing by two common currents. Class-AB operation does not interfere with the output signal, because the common currents cancel in the output stage (i.e., when one of the transistors is controlled at its quiescent current due to a high output current, the

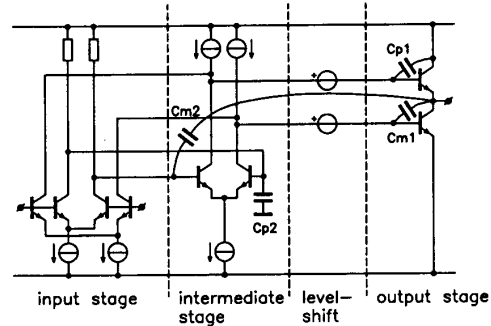


Fig. 10. Simplified schematic of the MNMC op amp.

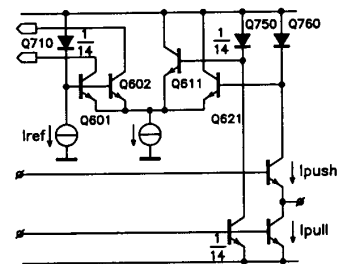


Fig. 11. Class-AB control.

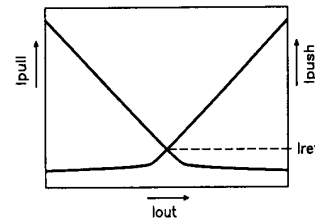


Fig. 12. Class-AB characteristic.

class-AB control doubles the driving of the other transistor).

The class-AB circuit incorporates a combined error amplifier and decision gate. The decision gate, comprising Q_{611} and Q_{621} , selects the smaller of the two transistor currents in the output stage. Controlling this current keeps the output transistors from shutting off. The transistors Q_{611} and Q_{621} function as two emitter followers, but only the device corresponding to the lowest output current becomes properly biased. This active emitter follower transfers its input voltage to the common-emitter node of the error amplifier.

The error amplifier consists of the decision gate together with Q_{601} and Q_{602} . The input voltages of the decision gate are derived from the push and pull transistor currents by diodes Q_{750} and Q_{760} . The reference of the error amplifier is current I_{ref} across diode Q_{710} . Fig. 12 shows the class-AB characteristic. The quiescent current is set by I_{ref} and the emitter ratios of the transistors. The minimum value is limited to half the quiescent current.

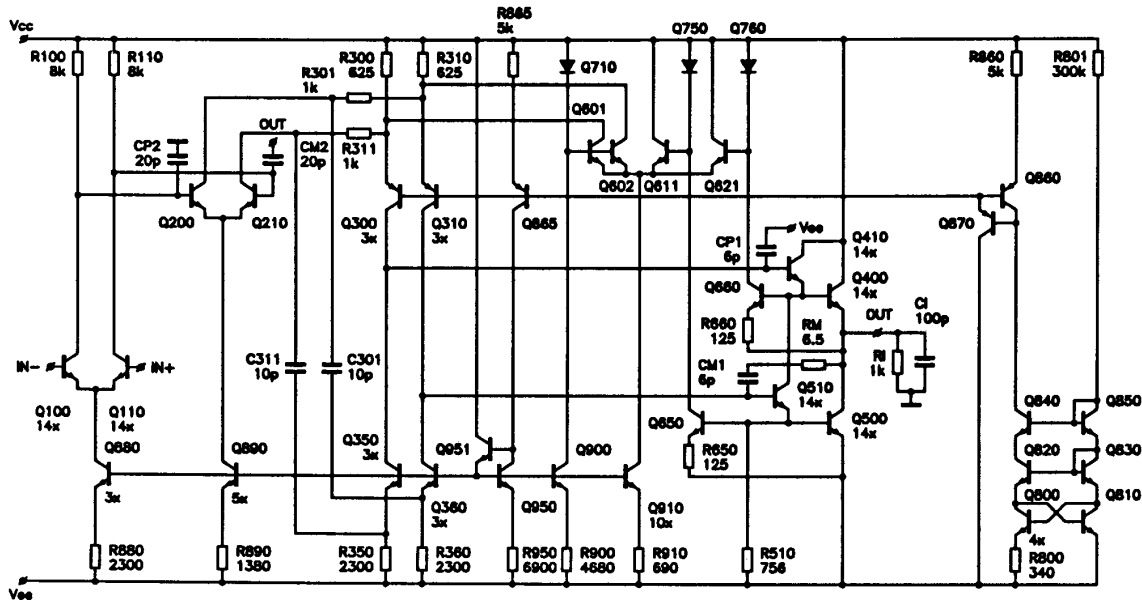


Fig. 13. Total schematic of the NMC op amp.

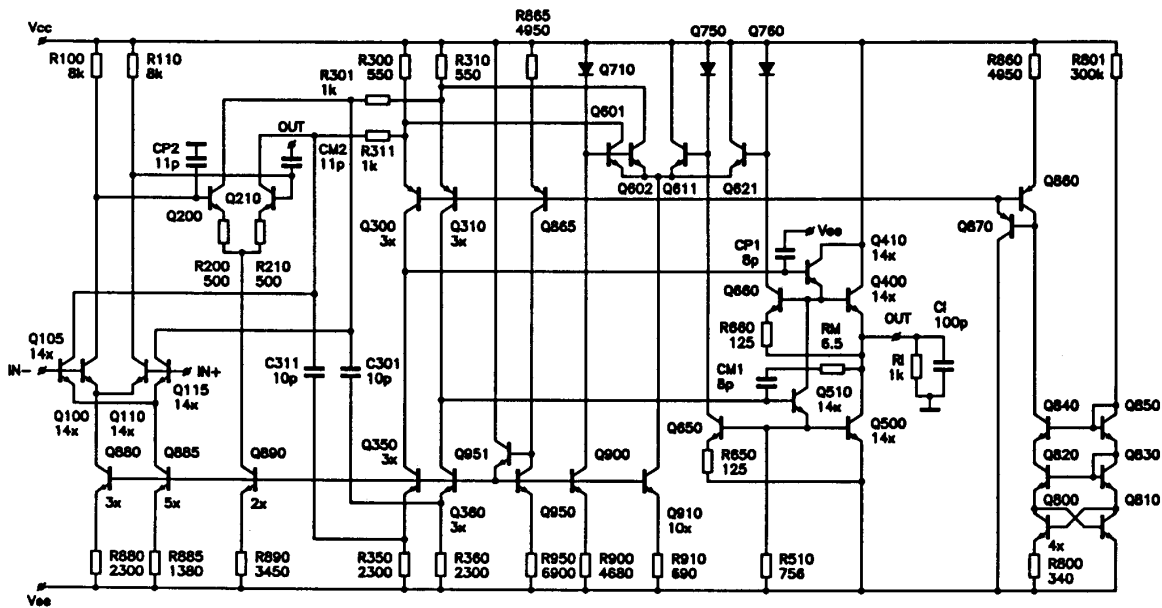


Fig. 14. Total schematic of the MNMC amplifier.

C. Total Schematic

Fig. 13 shows the total schematic of the NMC operational amplifier. This circuit diagram includes the biasing and level-shift elements. The actual circuit uses Darlington transistors in the output stage to improve the gain. The bias current is generated in the PTAT current source consisting of Q_{800} – Q_{850} [6]. Resistor R_{801} initiates a small current in the right-hand branch. Because of the cross-coupled structure, the magnitude of the current is of no

consequence to the PTAT output current and start-up is guaranteed. The PTAT current is $100 \mu\text{A}$ at room temperature. The quiescent current of the output transistors is set to 4.5 mA.

The MNMC op amp (Fig. 14) is, apart from the additional input stage with Q_{105} and Q_{115} , largely comparable to the operational amplifier without the multipath technique. To limit the bandwidth reduction, indicated by (5), the transconductance of the intermediate stage is reduced

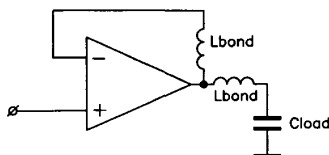


Fig. 15. Separate voltage and current terminals at the output.

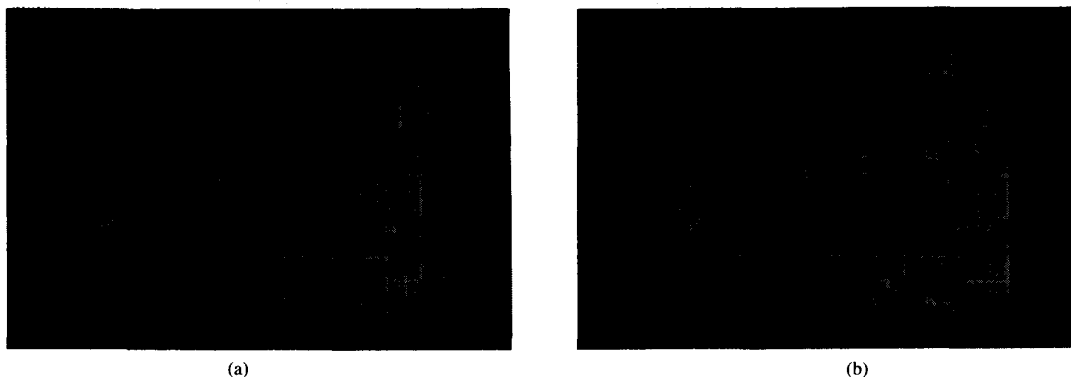


Fig. 16. Photomicrographs of the (a) NMC op amp and (b) MNMC op amp.

by lowering the tail current of Q_{200} and Q_{210} and inserting degeneration resistors R_{200} and R_{210} . The doublet frequency, according to (8), is 15 MHz.

The lower tail current of the intermediate stage ensures that, despite the extra input stage of the MNMC op amp, the total supply currents of the two amplifiers are equal.

IV. REALIZATIONS AND EXPERIMENTAL RESULTS

The chips were fabricated in a 3-GHz f_i n-p-n bipolar IC process. To be able to drive a 100-pF load with a unity-gain bandwidth of 100 MHz, load and feedback are separated by two output pins and corresponding bond wires (Fig. 15). The pins act as current and voltage terminals and isolate the driving of the load from the feedback path. Without this measure the load capacitance and inductance of the bonding wires would introduce a pair of complex poles in the feedback loop, resulting in instability of the circuit.

Clearly the two output bonding wires can be seen in Fig. 16. Fig. 16(a) is a photomicrograph of the NMC and Fig. 16(b) of the MNMC op amp. The die area of both amplifiers is equal. The extra area needed on the MNMC chip for the multipath input stage is used in the NMC amplifier to accommodate the Miller capacitors. These capacitors are larger due to the lower bandwidth of the op amp. The die area of the chips is $1.2 \text{ mm} \times 1.5 \text{ mm}$.

In Fig. 17 the Bode plots of the op amps are shown. The NMC op amp has a unity-gain bandwidth of 60 MHz with a phase margin of 40° . The unity-gain bandwidth

of the MNMC op amp is 100 MHz, with a phase margin of slightly less than 40° . Both op amps are loaded by a 100-pF capacitor in parallel with a 1-k Ω resistor, as is the case in the following measurements.

Fig. 18 gives the slew response of the op amps to an input step of 1 V. Since the input stages are not degenerated by emitter resistors, the slew rate is determined by the unity-gain bandwidth of the amplifiers. The slew rate of the NMC op amp (Fig. 18(a)) is $20 \text{ V}/\mu\text{s}$, and that of the MNMC op amp (Fig. 18(b)) is $35 \text{ V}/\mu\text{s}$.

Fig. 19 gives an impression of the small-signal settling of the amplifiers. The input step is 100 mV. The 0.1% settling time corresponding to the NMC (Fig. 19(a)) is 40 ns. The step response very much resembles the designed for Butterworth curve. As Fig. 19(b) indicates a slow settling component is detectable in the step response of the MNMC amplifier. The doublet spacing corresponding to the slow settling component is approximately 5%. The 0.1% settling time is 50 ns.

The contribution of the slow settling component to the total settling time becomes relatively less important for large input steps. Because most of the large-signal step response is governed by slewing of the op amp, the MNMC settles faster to 0.1% after a 1-V input step than its NMC counterpart. This is confirmed by the plots in Fig. 20. Settling times are 70 and 60 ns, respectively.

The last plot concerning the two op amps is shown in Fig. 21(a) and (b), which represents the input-referred voltage noise of the NMC and MNMC op amps, respectively. The voltage noise of the op amps is $2 \text{ nV}/\sqrt{\text{Hz}}$.

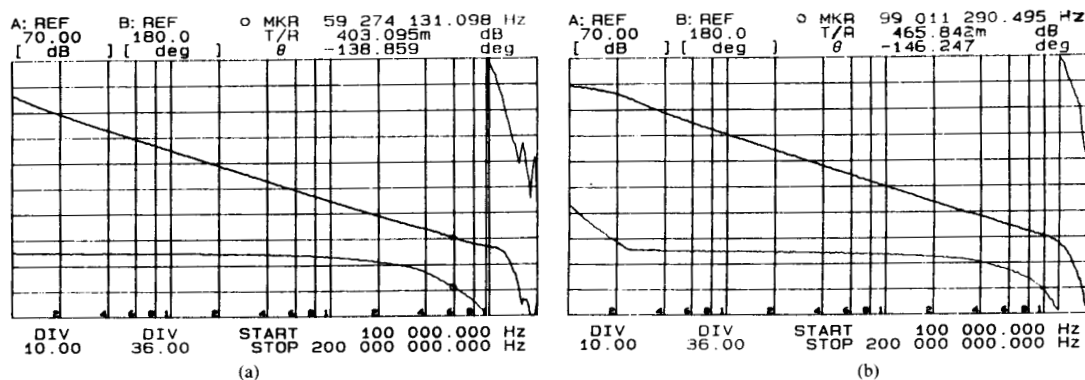


Fig. 17. Bode plots of the (a) NMC op amp and (b) MNMC op amp.

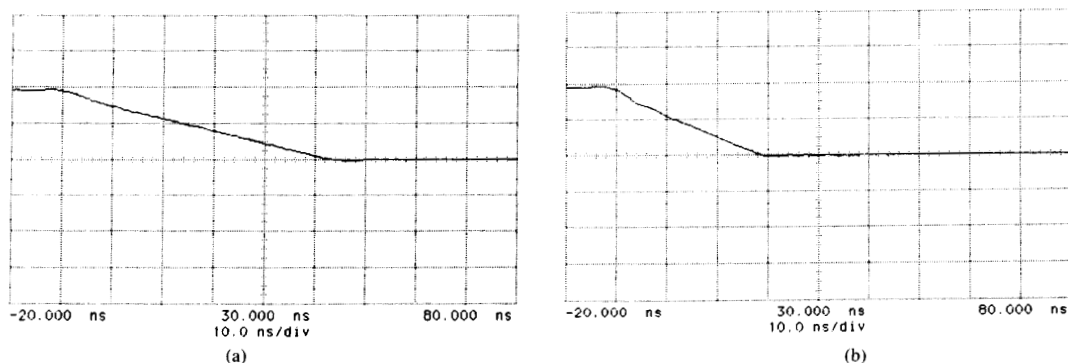


Fig. 18. Slew response of the (a) NMC op amp and (b) MNMC op amp (500 mV/div).

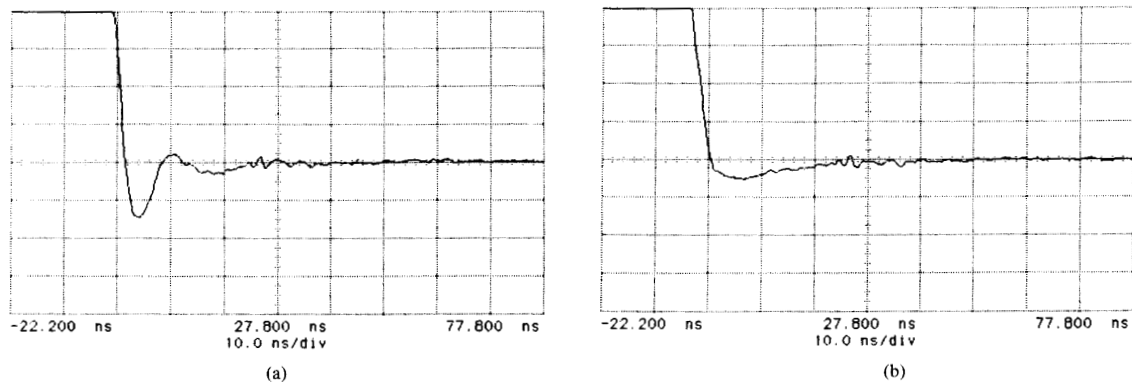


Fig. 19. Small-signal settling of the (a) NMC op amp and (b) MNMC op amp (5 mV/div).

For frequencies above 15 MHz (the crossover frequency of the multipath input stage) the noise of the MNMC op amps goes up slightly. Because the intermediate stage is not active in this frequency region, noise of the level-shift

circuits contributes to the input noise through the multipath input stage. The total input noise is limited to 4 nV/ $\sqrt{\text{Hz}}$ over the bandwidth of the MNMC op amp. Table I summarizes the measurement results.

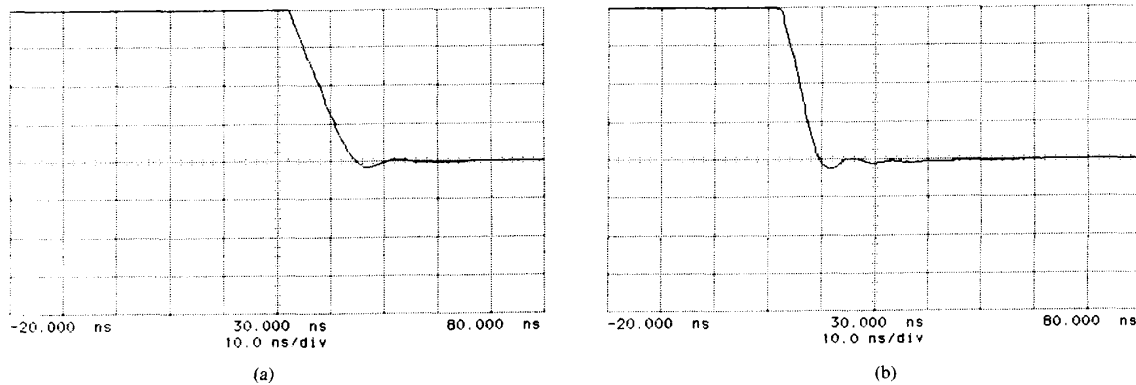


Fig. 20. Large-signal settling of the (a) NMC op amp and (b) MNMC op amp (50 mV/div).

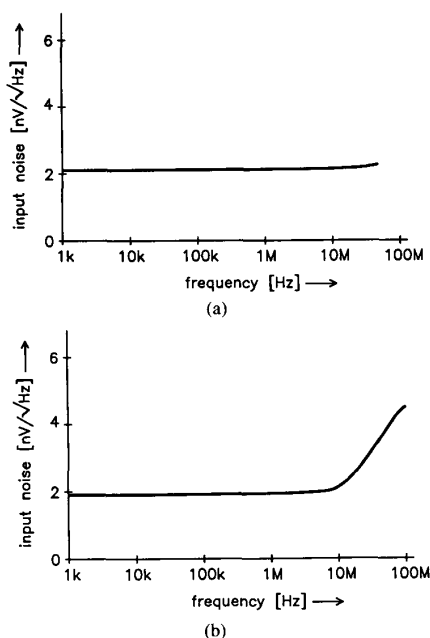


Fig. 21. Input-referred voltage noise of (a) the NMC op amp, and (b) the MNMC op amp.

TABLE I
MEASUREMENT RESULTS

Parameter	NMC	MNMC
Unity-Gain Frequency	60 MHz	100 MHz
DC Gain	100 dB	100 dB
Settling Time (0.1%) ($V_i = 0.1$ V)	40 ns	50 ns
Settling Time (0.1%) ($V_i = 1$ V)	70 ns	60 ns
Input Noise Voltage (1 kHz)	2 nV/√Hz	2 nV/√Hz
(50 MHz, 100 MHz)	2 nV/√Hz	4 nV/√Hz
Output Impedance (50 MHz)	10 Ω	10 Ω
Maximum Output Current	±50 mA	±50 mA
Supply Current	9.5 mA	9.5 mA

($T_A = 25^\circ\text{C}$, $V_{cc} = 8$ V, $C_l = 100$ pF, and $R_l = 1$ kΩ except where indicated.)

V. CONCLUSIONS

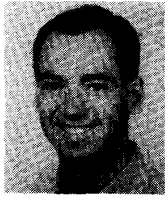
Nested Miller compensation and multipath nested Miller compensation open the door for a next generation of fast and accurate operational amplifiers. The MNMC amplifier presented drives a 100-pF load with a unity-gain bandwidth of 100 MHz. The multipath technique introduces a well-controlled pole-zero doublet, the matching of which depends on capacitor and current ratios only. In a test chip the doublet spacing was 5%. The unity-gain bandwidth of the NMC op amp is 60 MHz. Since feed-forward components are absent in this amplifier, no pole-zero doublets occur. The gain of both op amps is 100 dB.

ACKNOWLEDGMENT

The authors would like to thank the following people of Philips Nijmegen for their valuable contributions in the fabrication of the test chips: E. van Tuyl for making available the facilities, M. Rolsma for his help during the layout and simulation, and T. Clerkx for his support in finishing the chips.

REFERENCES

- [1] NE 5534 Data Sheet, Signetics, 1978; TDA 1034 Data Sheet, Philips, Apr. 1976.
- [2] B. Y. Kamath, R. G. Meyer, and P. R. Gray, "Relationship between frequency response and settling time of operational amplifiers," *IEEE J. Solid-State Circuits*, vol. SC-9, pp. 347-352, Dec. 1974.
- [3] J. H. Huijsing, "Multi-stage amplifier with capacitive nesting for frequency compensation," U.S. Patent Appl. Ser. 602234, filed Apr. 19, 1984.
- [4] J. H. Huijsing and F. Tol, "Monolithic operational amplifier design with improved HF behavior," *IEEE J. Solid-State Circuits*, vol. SC-11, pp. 323-328, Apr. 1976.
- [5] E. Seevinck, W. De Jager, and P. Buitendijk, "A low-distortion output stage with improved stability for monolithic power amplifiers," *IEEE J. Solid-State Circuits*, vol. 23, pp. 794-801, June 1988.
- [6] G. C. M. Meijer, "Integrated circuits and components for bandgap references and temperature transducers," Internal Report, Delft Univ. Technology, Delft, The Netherlands, 1982.



Ruud G. H. Eschauzier was born in Vlaardingen, The Netherlands, on August 10, 1967. He received the M.S. degree in electrical engineering in 1990, from the Delft University of Technology. He is now a Ph.D. student at the Electronic Instrumentation Laboratory of the Delft University. His research subjects include analog integrated circuits with extremely high bandwidth-to-power ratios.



Leo P. T. Kerklan was born in Amsterdam, The Netherlands, on January 22, 1955. He received the M.S. degree in electrical engineering from the University of Delft, The Netherlands, in 1988 on the subject of the design of a nested feedback structure op amp.

He is now with Philips Industrial Electronics, Eindhoven, The Netherlands, where he is currently engaged in the design of high-frequency video electronics.



Johan H. Huijsing (SM'81) was born in Bandung, Indonesia, on May 21, 1938. He received the M.Sc. degree in electrical engineering from the Delft University of Technology, Delft, The Netherlands, in 1969, and the Ph.D. degree from this university in 1981 for work on operational amplifiers (thesis: "Integrated Circuits for Accurate Linear Analogue Electric Signal Processing," supervised by Prof. Dr. Ir. J. Davids).

Since 1969 he has been a member of the Research and Teaching Staff of the Electronic Instrumentation Laboratory, Department of Electrical Engineering, Delft University of Technology, where he is now Professor of Electronic Instrumentation. He teaches courses on electrical measurement techniques, electronic instrumentation, operational amplifiers, and analog-to-digital converters. His field of research is analog circuit design (operational amplifiers, analog multipliers, etc.) and integrated smart sensors (signal conditioning on the sensor chip, frequency and digital converters which incorporate sensors, bus interfaces, etc). He is the author or coauthor of some 70 scientific papers and 12 patents.