A CANONICAL TRANSFORMATION NEAR A BOUNDARY POINT

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ABSTRACT. A local homogeneous canonical transformation is constructed which straightens a curved boundary and freezes the coefficients of the principal part of a pseudo-differential operator in the neighborhood of a nonglancing ray.

Duistermaat and Hörmander [1] have studied the propogation along bicharacteristics of wave front sets of solutions of certain partial differential equations, using Fourier integral operators to effect a canonical transformation taking the given operator (locally) into $\partial/\partial x_1$. Hörmander [2] has also studied the problem with the aid of specially constructed pseudo-differential operators. Lax and Nirenberg [3] have applied the latter method to the study of boundary value problems, but thus far their approach has not handled the glancing ray case. As a first step towards adapting the approach of [1] to deal with boundary value problems, we construct a canonical transformation, away from glancing rays, which simultaneously reduces the boundary and the equation to a convenient form. I wish to thank Ralph Phillips for many helpful conversations.

Let $p(x, t; \xi, \tau)$ be a real symbol which is positive homogeneous of degree $m \ge 0$, m an integer, and with $(x, t, \xi, \tau) \in \mathbb{R}^{n-1} \times \mathbb{R} \times \mathbb{R}^{n-1} \times \mathbb{R}$. Let $0 \ne (\xi^0, \tau^0)$ satisfy $\partial p(0, 0; \xi^0, \tau^0)/\partial \tau \ne 0$. Let Γ be a smooth surface in \mathbb{R}^n , passing through (0, 0), and such that the normal to Γ at (0, 0) points in the direction of the t axis.

Theorem. There is a canonical map $\chi: (x, t, \xi, \tau) \xrightarrow{\mathbf{x}} (y, s, \eta, \sigma) \in \mathbb{R}^{2n}$, defined in a conic neighborhood \mathfrak{U} of $(0, 0, \xi^0, \tau^0)$, homogeneous of degree one in (ξ, τ) , and such that for $(x, t, \xi, \tau) \in \mathfrak{U}$,

(i) $(x, t) \in \Gamma \implies s = 0$,

(ii) $p(x, t; \xi, \tau) = p(0, 0; \eta, \sigma) \stackrel{\text{def}}{=} p_0(\eta, \sigma).$

Received by the editors November 23, 1973.

AMS (MOS) subject classifications (1970). Primary 35A30.

¹ Sponsored by the United States Army under Contract No. DA-31-124-ARO-D-462.

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Proof. For χ to be canonical means that the Poisson brackets of the image points satisfy

$$\{y_{i'}, y_{j}\} = \{y_{i'}, s\} = \{y_{i}, \sigma\} = \{s, \eta_{i}\} = \{\eta_{i}, \sigma\} = 0,$$

$$\{s, \sigma\} = 1, \qquad \{y_{i}, \eta_{j}\} = \delta_{ij},$$

where

$$\{u, v\} = \sum_{l} \left(\frac{\partial u}{\partial x_{l}} \frac{\partial v}{\partial \xi_{l}} - \frac{\partial u}{\partial \xi_{l}} \frac{\partial v}{\partial x_{l}} \right) + \left(\frac{\partial u}{\partial t} \frac{\partial v}{\partial \tau} - \frac{\partial u}{\partial \tau} \frac{\partial v}{\partial t} \right)$$

$$\stackrel{\text{def}}{=} H_{v} u \stackrel{\text{def}}{=} \left[b_{v}^{(1)} \cdot \left(\nabla_{x}, \frac{\partial}{\partial t} \right) - b_{v}^{(2)} \cdot \left(\nabla_{\xi}, \frac{\partial}{\partial \tau} \right) \right] u, \quad b_{v} = (b_{v}^{(1)}, b_{v}^{(2)}).$$

Our construction of χ is a modification of that given by Duistermaat and Hörmander [1] in free space. The functions η_i will be constructed successively on $\Gamma \times R^n$ by assigning each on an initial manifold transverse to the linear span of those b_{η_i} which are already known, and such that $b_{\eta_i}^{(1)}$ is tangential to Γ . This last fact will enable us to construct s such that s = 0 on Γ . Once η is constructed, σ is determined by (ii). To extend η and σ off of Γ , we shall use the equation $b_p \eta = 0$ together with (ii); a simple application of the chain rule shows that this construction implies the canonical relations $\{\eta_i, \sigma\} = 0$. Finally, we shall use the initial condition $(y, s)(0, 0, \eta, \sigma) = (y, s)$ together with the equations $b_{\eta_i}(y, s) =$ $b_{\sigma}(y, s) = 0$ to determine (y, s).

We now construct χ . Let N_1 be a neighborhood of (0, 0) in Γ , and C_1 a conic neighborhood of (ξ^0, τ^0) in \mathbb{R}^n such that for $(x, t) \in N_1$ and $0 \neq (\xi, \tau) \in C_1$,

(1)
$$\langle n, \nabla_{\mathcal{F},\tau} \rangle p \neq 0,$$

where *n* is the normal to Γ at (x, t). On N_1 , let $v_1(x, t)$ be a nonsingular tangential vector field such that $\langle (\xi^0, \tau^0), v_1(0, 0) \rangle = \xi_1^0$, and define

(2)
$$\eta_1(x, t, \xi, \tau) = \langle (\xi, \tau), v_1(x, t) \rangle, \quad (x, t, \xi, \tau) \in N_1 \times C_1.$$

Because of (1), $b_p^{(1)}$ is not tangential to N_1 , and hence we can extend the definition of η_1 off of $N_1 \times C_1$ by using (2) as an initial condition for

(3)
$$\{\eta_1, p\} = H_p \eta_1 = 0.$$

We define recursively triples $\{N_i, \nu_i, \eta_i\}, i = 2, \dots, n-1$ as follows. License or copyright restrictions may apply to redistribution; see https://www.anfs.org/jburnal-terms-of-use

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Let $N_i \ni (0, 0)$ be a smooth (n - 1)-dimensional surface in N_{i-1} , transverse to the span of the vectors v_1, \dots, v_{i-1} and not orthogonal to (ξ^0, τ^0) unless $\xi_i^0 = \xi_{i+1}^0 = \dots = \xi_{n-1}^0 = 0$. Let v_i be a nonsingular vector field in N_i such that $\langle (\xi^0, \tau^0), v_i(0, 0) \rangle = \xi_i^0$. Define

(4)
$$\eta_i = \langle (\xi, \tau), v_i(x, t) \rangle, \quad (x, t, \xi, \tau) \in N_i \times C_1,$$

and extend η_i by the equations.

$$\{\eta_i, \eta_i\} = 0, \qquad j < i,$$

and

(6)
$$\{\eta_i, p\} = 0.$$

The consistency of the construction of η using (5) and (6) follows from the identity $[H_u, H_v] = H_{\{u,v\}}$. For example, the equations $\{\eta_j, \eta_k\} = 0$ are satisfied by construction along a submanifold M_k , j < k, and $\{\eta_j, p\} = \{\eta_k, p\} = 0$ along integral curves of H_p through M_k . On these integral curves, then,

$$\{p, \{\eta_{j}, \eta_{k}\}\} = H_{\{\eta_{j}, \eta_{k}\}}p = [H_{\eta_{j}}, H_{\eta_{k}}]p = H_{\eta_{j}}\{p, \eta_{k}\} - H_{\eta_{k}}\{p, \eta_{j}\} = 0,$$

so that $\{\eta_i, \eta_k\} = 0$ along these curves.

Remark. If Γ is the hyperplane t = 0, it suffices to set $\eta = \xi$ on $N_1 \times C_1$ and use (6) to extend the definition of η_i .

The condition $\partial p(0, 0; \xi^0, \tau^0)/\partial \tau \neq 0$, together with the above construction, ensures that there is a conic neighborhood \mathcal{U} of $(0, 0; \xi^0, \tau^0)$ in which σ is uniquely defined by (ii) if we set $\sigma(0, 0; \xi^0, \tau^0) = \tau^0$. Locally, σ is defined as a function of $Z = (\eta, p)$, from which we conclude that

$$\{\sigma, \eta_j\} = H_{\eta_j} \sigma = \sum_k \frac{\partial \sigma}{\partial \eta_k} \{\eta_j, \eta_k\} + \frac{\partial \sigma}{\partial p} \{\eta_j, p\} = 0.$$

According to [1], we can now determine (y, s) in \mathcal{U} by assigning (y, s) on an *n*-dimensional manifold transverse to the span of b_{η_j} , $j = 1, \dots, n-1$, and b_{σ} , provided that these vectors together with the radial vector $(0, 0; \xi, \tau)$ are linearly independent. Such a manifold is the subspace x = 0, t = 0. To see this, we need only observe that

$$b_{\eta_{i}}(0, 0, \xi, \tau) = (e_{j}, 0, 0, \partial \eta_{j}/\partial t),$$

where e_j is a standard unit basis vector in \mathbb{R}^{n-1} , and that the *n*th component of $b_{\tau}(0, 0, \xi, \tau)$ is (cf. (ii)) License or copyright festifications may have been table to redistribution; see https://www.ams.org/journal-terms-of-use

$$\frac{\partial\sigma}{\partial\tau}(0, 0, \xi, \tau) = \frac{\partial p_0}{\partial\sigma} \left\{ \frac{\partial p}{\partial\tau} - \sum \frac{\partial p_0}{\partial\eta_j} \frac{\partial\eta_j}{\partial\tau} \right\} = \frac{\partial p_0}{\partial\sigma} \frac{\partial p}{\partial\tau}(0, 0, \xi, \tau) \neq 0.$$

We assign initial conditions

(7) $(y, s)(0, 0, \xi, \tau) = (0, 0).$

Using (7) together with equations $H_{\eta_i}(y, s) = (e_i 0), H_{\sigma}(y, s) = (0, 1)$, serves to define (y, s) in \mathfrak{U} .

There remains to show that (i) holds. But s is invariant on the integral curves of each H_{η_j} , and if $(x, t) \in N_j$, then $b_{\eta_j}^{(1)} = v_j$ is tangent to Γ . Given $(x', t', \xi', \tau') \in \mathbb{U}$ with $(x', t') \in N_1$, we follow successively the integral curves of H_{η_i} , $i = 1, \dots, n-1$, through $(x^i, t^i, \xi^i, \tau^i)$ till (x, t) hits N_{i+1} at (x^{i+1}, t^{i+1}) and $(\xi, \tau) = (\xi^{i+1}, \tau^{i+1})$, with N_n defined as the point (0, 0). We conclude that for some $P = (0, 0, \xi^n, \tau^n) \in \mathbb{U}$, $s(x, t, \xi, \tau) = s(P) = 0$ by (7). Theorem 1 is proved.

As a corollary of the proof, we note that if Γ is the hyperplane t = 0, then χ can be extended to a conical neighborhood of any cone C = $(0, 0, V \setminus \{0\})$, where V is a closed simply connected cone, and where $\partial p / \partial \tau \neq 0$ on $C \setminus \{0\}$. Since $\chi(0, 0, \xi, \tau) = (0, 0, \xi, \tau)$, condition (ii), together with a simple homotopy argument, allows us to drop the assumption that V be simply connected.

Remark. If p has the parity of m, then χ extends by homogeneity to a two-sided conic set.

Some applications and extensions will be reported on elsewhere.

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