# A CANONICAL TRANSFORMATION NEAR A BOUNDARY POINT 

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ABSTRACT. A local homogeneous canonical transformation is constructed which straightens a curved boundary and freezes the coefficients of the principal part of a pseudo-differential operator in the neighborhood of a nonglancing ray.

Duistermaat and Hörmander [1] have studied the propogation along bicharacteristics of wave front sets of solutions of certain partial differential equations, using Fourier integral operators to effect a canonical transformation taking the given operator (locally) into $\partial / \partial x_{1}$. Hörmander [2] has also studied the problem with the aid of specially constructed pseudo-differential operators. Lax and Nirenberg [3] have applied the latter method to the study of boundary value problems, but thus far their approach has not handled the glancing ray case. As a first step towards adapting the approach of [1] to deal with boundary value problems, we construct a canonical transformation, away from glancing rays, which simultaneously reduces the boundary and the equation to a convenient form. I wish to thank Ralph Phillips for many helpful conversations.

Let $p(x, t ; \xi, \tau)$ be a real symbol which is positive homogeneous of degree $m \geq 0, m$ an integer, and with $(x, t, \xi, \tau) \in R^{n-1} \times R \times R^{n-1} \times R$. Let $0 \neq\left(\xi^{0}, \tau^{0}\right)$ satisfy $\partial p\left(0,0 ; \xi^{0}, \tau^{0}\right) / \partial \tau \neq 0$. Let $\Gamma$ be a smooth surface in $R^{n}$, passing through ( 0,0 ), and such that the normal to $\Gamma$ at $(0,0)$ points in the direction of the $t$ axis.

Theorem. There is a canonical map $\chi:(x, t, \xi, \tau) \xrightarrow{\boldsymbol{\chi}}(y, s, \eta, \sigma) \in R^{2 n}$, defined in a conic neighborbood $\mathbb{U}$ of $\left(0,0, \xi^{0}, \tau^{0}\right)$, bomogeneous of degree one in $(\xi, \tau)$, and such that for $(x, t, \xi, \tau) \subseteq \mathcal{U}$,
(i) $(x, t) \in \Gamma \Rightarrow s=0$,
(ii) $p(x, t ; \xi, \tau)=p(0,0 ; \eta, \sigma) \stackrel{\text { def }}{\overline{=}} p_{0}(\eta, \sigma)$.

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Proof. For $\chi$ to be canonical means that the Poisson brackets of the image points satisfy

$$
\begin{aligned}
& \left\{y_{i}, y_{j}\right\}=\left\{y_{i}, s\right\}=\left\{y_{i}, \sigma\right\}=\left\{s, \eta_{i}\right\}=\left\{\eta_{i}, \sigma\right\}=0 \\
& \{s, \sigma\}=1, \quad\left\{y_{i}, \eta_{j}\right\}=\delta_{i j}
\end{aligned}
$$

where

$$
\begin{aligned}
\{u, v\} & =\sum_{l}\left(\frac{\partial u}{\partial x_{l}} \frac{\partial v}{\partial \xi_{l}}-\frac{\partial u}{\partial \xi_{l}} \frac{\partial v}{\partial x_{l}}\right)+\left(\frac{\partial u}{\partial t} \frac{\partial v}{\partial \tau}-\frac{\partial u}{\partial \tau} \frac{\partial v}{\partial t}\right) \\
& \stackrel{\text { def }}{=} H_{v} u \stackrel{\text { def }}{=}\left[b_{v}^{(1)} \cdot\left(\nabla_{x}, \frac{\partial}{\partial t}\right)-b_{v}^{(2)} \cdot\left(\nabla_{\xi}, \frac{\partial}{\partial \tau}\right)\right] u, \quad b_{v}=\left(b_{v}^{(1)}, b_{v}^{(2)}\right)
\end{aligned}
$$

Our construction of $\chi$ is a modification of that given by Duistermat and Hörmander [1] in free space. The functions $\eta_{i}$ will be constructed successively on $\Gamma \times R^{n}$ by assigning each on an initial manifold transverse to the linear span of those $h_{\eta_{i}}$ which are already known, and such that $h_{\eta_{i}}^{(1)}$ is tangential to $\Gamma$. This last fact will enable us to construct $s$ such that $s=0$ on $\Gamma$. Once $\eta$ is constructed, $\sigma$ is determined by (ii). To extend $\eta$ and $\sigma$ off of $\Gamma$, we shall use the equation $h_{p} \eta=0$ together with (ii); a simple application of the chain rule shows that this construction implies the canonical relations $\left\{\eta_{i}, \sigma\right\}=0$. Finally, we shall use the initial condition $(y, s)(0,0, \eta, \sigma)=(y, s)$ together with the equations $h_{\eta_{i}}(y, s)=$ $b_{\sigma}(y, s)=0$ to determine $(y, s)$.

We now construct $\chi$. Let $N_{1}$ be a neighborhood of $(0,0)$ in $\Gamma$, and $C_{1}$ a conic neighborhood of $\left(\xi^{0}, \tau^{0}\right)$ in $R^{n}$ such that for $(x, t) \in N_{1}$ and $0 \neq(\xi, \tau) \in C_{1}$,

$$
\begin{equation*}
\left\langle n, \nabla_{\xi, \tau}\right\rangle p \neq 0 \tag{1}
\end{equation*}
$$

where $n$ is the normal to $\Gamma$ at $(x, t)$. On $N_{1}$, let $v_{1}(x, t)$ be a nonsingular tangential vector field such that $\left\langle\left(\xi^{0}, \tau^{0}\right), v_{1}(0,0)\right\rangle=\xi_{1}^{0}$, and define

$$
\begin{equation*}
\eta_{1}(x, t, \xi, \tau)=\left\langle(\xi, \tau), v_{1}(x, t)\right\rangle, \quad(x, t, \xi, \tau) \in N_{1} \times C_{1} . \tag{2}
\end{equation*}
$$

Because of (1), $b_{p}^{(1)}$ is not tangential to $N_{1}$, and hence we can extend the definition of $\eta_{1}$ off of $N_{1} \times C_{1}$ by using (2) as an initial condition for

$$
\begin{equation*}
\left\{\eta_{1}, p\right\} \equiv H_{p} \eta_{1}=0 . \tag{3}
\end{equation*}
$$

We define recursively triples $\left\{N_{i}, v_{i}, \eta, i=2, \cdots, n-1\right.$ as follows.

Let $N_{i} \ni(0,0)$ be a smooth ( $n-1$ )-dimensional surface in $N_{i-1}$, transverse to the span of the vectors $v_{1}, \cdots, v_{i-1}$ and not orthogonal to $\left(\xi^{0}, \tau^{0}\right)$ unless $\xi_{i}^{0}=\xi_{i+1}^{0}=\cdots=\xi_{n-1}^{0}=0$. Let $v_{i}$ be a nonsingular vector field in $N_{i}$ such that $\left\langle\left(\xi^{0}, \tau^{0}\right), v_{i}(0,0)\right\rangle=\xi_{i}^{0}$. Define

$$
\begin{equation*}
\eta_{i}=\left\langle(\xi, \tau), v_{i}(x, t)\right\rangle, \quad(x, t, \xi, \tau) \in N_{i} \times C_{1}, \tag{4}
\end{equation*}
$$

and extend $\eta_{i}$ by the equations.

$$
\begin{equation*}
\left\{\eta_{i}, \eta_{j}\right\}=0, \quad j<i \tag{5}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\{\eta_{i}, p\right\}=0 \tag{6}
\end{equation*}
$$

The consistency of the construction of $\eta$ using (5) and (6) follows from the identity $\left[H_{u}, H_{v}\right]=H_{\{u, v\}}$. For example, the equations $\left\{\eta_{j}, \eta_{k}\right\}=0$ are satisfied by construction along a submanifold $M_{k^{\prime}}, j<k$, and $\left\{\eta_{j^{\prime}} p\right\}=$ $\left\{\eta_{k}, p\right\}=0$ along integral curves of $H_{p}$ through $M_{k}$. On these integral curves, then,

$$
\left.\left\{p,\left\{\eta_{j}, \eta_{k}\right\}\right\}=H_{\left\{\eta_{j}, \eta_{k}\right.}\right\} p=\left[H_{\eta_{j}}, H_{\eta_{k}}\right] p=H_{\eta_{j}}\left\{p, \eta_{k}\right\}-H_{\eta_{k}}\left\{p, \eta_{j}\right\}=0,
$$

so that $\left\{\eta_{j}, \eta_{k}\right\}=0$ along these curves.
Remark. If $\Gamma$ is the hyperplane $t=0$, it suffices to set $\eta=\xi$ on $N_{1} \times C_{1}$ and use (6) to extend the definition of $\eta_{i}$

The condition $\partial \rho\left(0,0 ; \xi^{0}, \tau^{0}\right) / \partial \tau \neq 0$, together with the above construction, ensures that there is a conic neighborhood $\mathbb{U}$ of $\left(0,0 ; \xi^{0}, \tau^{0}\right)$ in which $\sigma$ is uniquely defined by (ii) if we set $\sigma\left(0,0 ; \xi^{0}, \tau^{0}\right)=\tau^{0}$. Locally, $\sigma$ is defined as a function of $Z \equiv(\eta, p)$, from which we conclude that

$$
\left\{\sigma, \eta_{j}\right\}=H_{\eta_{j}} \sigma=\sum_{k} \frac{\partial \sigma}{\partial \eta_{k}}\left\{\eta_{j}, \eta_{k}\right\}+\frac{\partial \sigma}{\partial p}\left\{\eta_{j}, p\right\}=0
$$

According to [1], we can now determine ( $y, s$ ) in $\mathcal{U}$ by assigning ( $y, s$ ) on an $n$-dimensional manifold transverse to the span of $b_{\eta_{j}}, j=1, \cdots, n-1$, and $b_{\sigma}$, provided that these vectors together with the radial vector $(0,0 ; \xi, \tau)$ are linearly independent. Such a manifold is the subspace $x=0, t=0$. To see this, we need only observe that

$$
b_{\eta_{j}}(0,0, \xi, \tau)=\left(e_{j}, 0,0, \partial \eta_{j} / \partial t\right)
$$

where $e_{j}$ is a standard unit basis vector in $R^{n-1}$, and that the $n$th com-


$$
\frac{\partial \sigma}{\partial \tau}(0,0, \xi, \tau)=\frac{\partial p_{0}}{\partial \sigma}\left\{\frac{\partial p}{\partial \tau}-\sum \frac{\partial p_{0}}{\partial \eta_{j}} \frac{\partial \eta_{j}}{\partial \tau}\right\}=\frac{\partial p_{0}}{\partial \sigma} \frac{\partial p}{\partial \tau}(0,0, \xi, \tau) \neq 0
$$

We assign initial conditions

$$
\begin{equation*}
(y, s)(0,0, \xi, \tau)=(0,0) \tag{7}
\end{equation*}
$$

Using (7) together with equations $H_{\eta_{i}}(y, s)=\left(e_{i} 0\right), H_{\sigma}(y, s)=(0,1)$, serves to define $(y, s)$ in $U$.

There remains to show that (i) holds. But $s$ is invariant on the integral curves of each $H_{\eta_{j}}$, and if $(x, t) \in N_{j}$, then $b_{\eta_{j}}^{(1)}=v_{j}$ is tangent to $\Gamma$. Given $\left(x^{\prime}, t^{\prime}, \xi^{\prime}, \tau^{\prime}\right) \in \mathcal{U}$ with $\left(x^{\prime}, t^{\prime}\right) \in N_{1}$, we follow successively the integral curves of $H_{\eta_{i},}{ }^{i}=1, \cdots, n-1$, through $\left(x^{i}, t^{i}, \xi^{i}, \tau^{i}\right)$ till $(x, t)$ hits $N_{i+1}$ at $\left(x^{i+1}, t^{i+1}\right)$ and $(\xi, \tau)=\left(\xi^{i+1}, \tau^{i+1}\right)$, with $N_{n}$ defined as the point $(0,0)$. We conclude that for some $P=\left(0,0, \xi^{n}, r^{n}\right) \in \mathcal{U}, s(x, t, \xi, r)=$ $s(P)=0$ by (7). Theorem 1 is proved.

As a corollary of the proof, we note that if $\Gamma$ is the hyperplane $t=0$, then $X$ can be extended to a conical neighborhood of any cone $C=$ $(0,0, V \backslash\{0\})$, where $V$ is a closed simply connected cone, and where $\partial p / \partial \tau \neq 0$ on $C \backslash\{0\}$. Since $\chi(0,0, \xi, \tau)=(0,0, \xi, \tau)$, condition (ii), together with a simple homotopy argument, allows us to drop the as sumption that $V$ be simply connected.

Remark. If $p$ has the parity of $m$, then $\chi$ extends by homogeneity to a two-sided conic set.

Some applications and extensions will be reported on elsewhere.

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