

A Cognitive Ego-Vision System for Interactive Assistance

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not PDAs or cell-phones

- pure databases
- “blind”



... but cognitive abilities

- situated
- attentive
- (inter-)active

VAMPIRE

Visual Active Memory Processes and Interactive REtrieval





- “human in the loop” systems
 - shared attention and perception
 - mediated embodiment
 - **user controls system's perception**
- augmented reality
 - **system controls user's perception**
- on-board sensors only: mobile
- challenges for perception
 - no ambient sensors
 - arbitrary motions
 - limited field of view



- assistance in object manipulation
 - step-wise instructions
 - guidance to object positions
 - supervision and correction
- evaluation scenario
 - “cocktail assistant”

- cognitive assistance system
- *ego-vision* paradigm
- *perception* & interaction
- *memory* for cognitive systems

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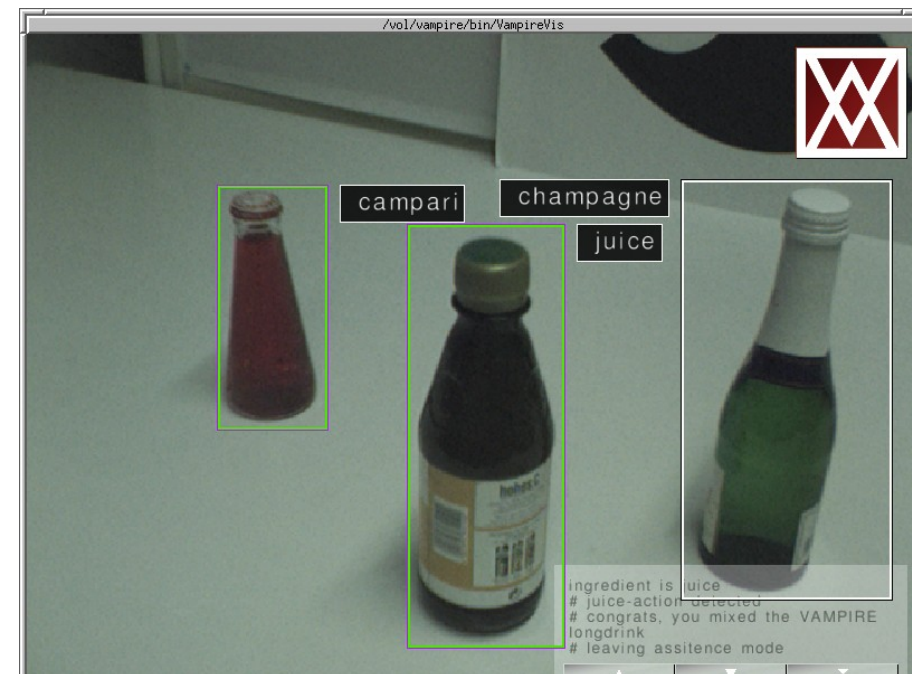
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Cocktail Recipe: Vampire Gimlet

1 1/2 oz Vodka
1 oz Rose's Concentrated Lime Juice
1 oz Peppermint Schnapps

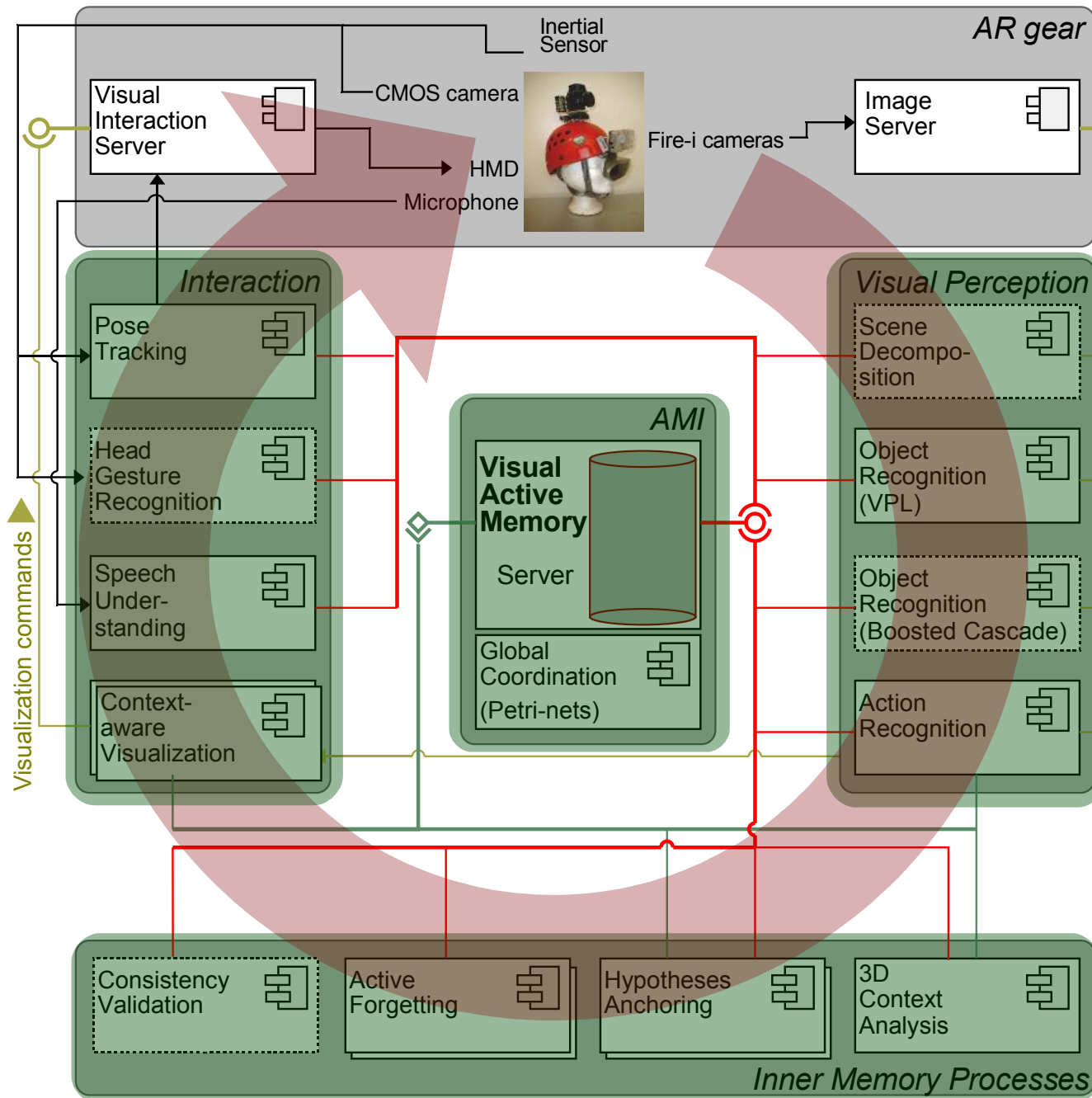
Combine ingredients with ice, shake, strain into cocktail glass.

© barmeister.com



Sketch of a System Architecture

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● follows EVS loop

● visual active memory

- integration

- memory processes

● perception

● inner processes

- cognitive functions

- context

● interaction

- visualization

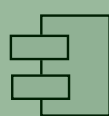


Visual Perception

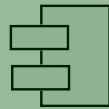
Scene
Decompo-
sition



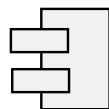
Object
Recognition
(VPL)



Object
Recognition
(Boosted Cascade)



Action
Recognition



- account for ego-vision challenges
- scene decomposition
 - mosaicing approach^[1]
- *what is where?*
- two opposed appearance-based solutions
 - VPL classifier^[2]
 - online training
 - boosted cascade^[3]
 - cluttered background

[1] Gorges et al. Mosaics from Arbitrary Stereo Video..., DAGM 2004

[2] Bekel et al. Adaptive computer vision: online learning..., DAGM 2004

[3] Viola and Jones. Rapid object detection..., CVPR 2001

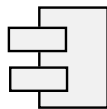


Visual Perception

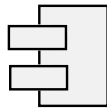
Scene
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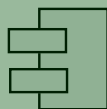
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Action
Recognition

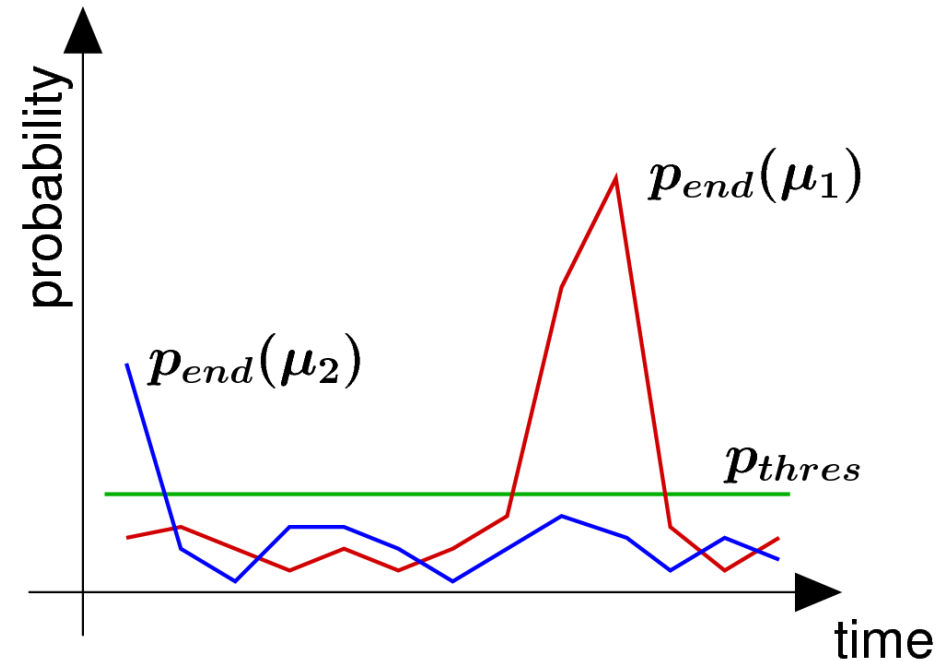


- *what is going on?*
- *supervision in assistance*
 - step-wise instructions
 - correction
- *has the action been performed correctly?*
- *ego-vision*
 - simple model of attention
 - user looks where she acts
- *analyze trajectory of manipulated objects*
 - track object
 - classify trajectory: pouring, shaking,...





- initialized on centered objects
- capture object trajectory
- kernel-based tracker^[1]



- *condensation algorithm*
 - segmentation-free classification
- originally for hand trajectories^[2]
- detection on threshold

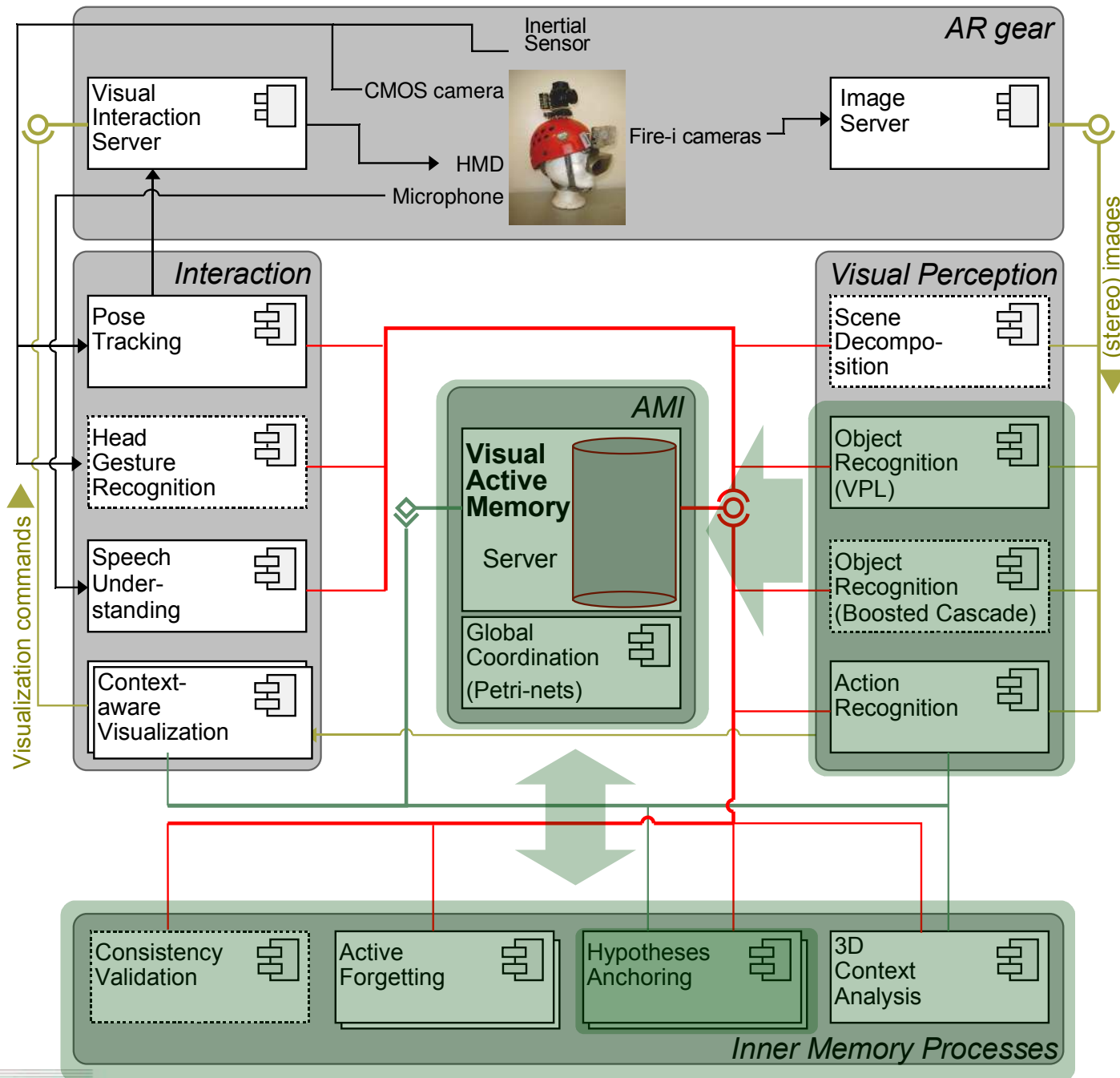
[1] Comaniciu et al. Kernel-Based Object Tracking, PAMI, 2003

[2] Fritsch, Hofemann et al. Combining [...] for Gesture Recognition, ICPR, 2004



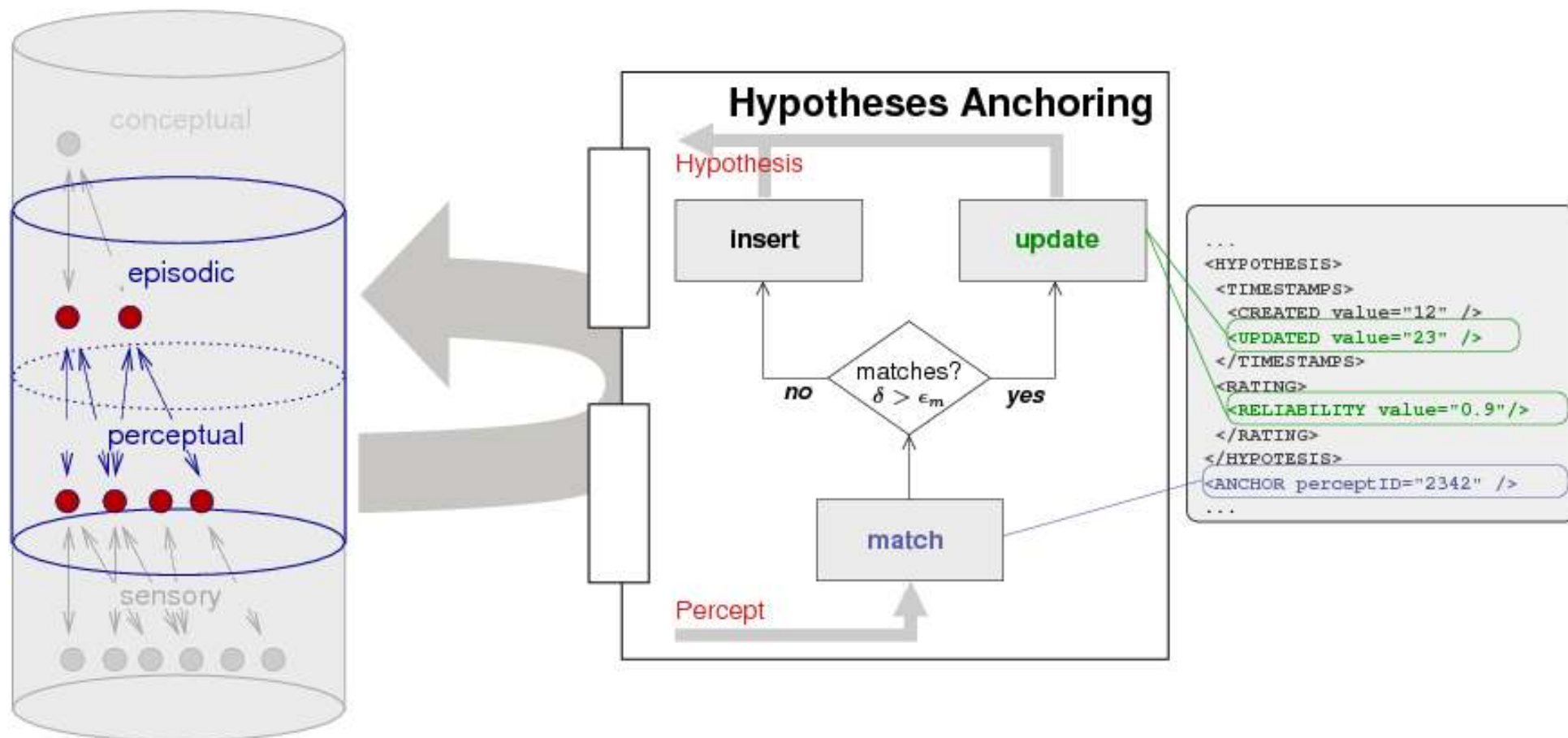
The Visual Active Memory Concept

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- perceptions into memory
- memorize & analyze
 - what?
 - where?
- inner processes
 - context analysis
 - forgetting
 - consistency validation
 - anchoring

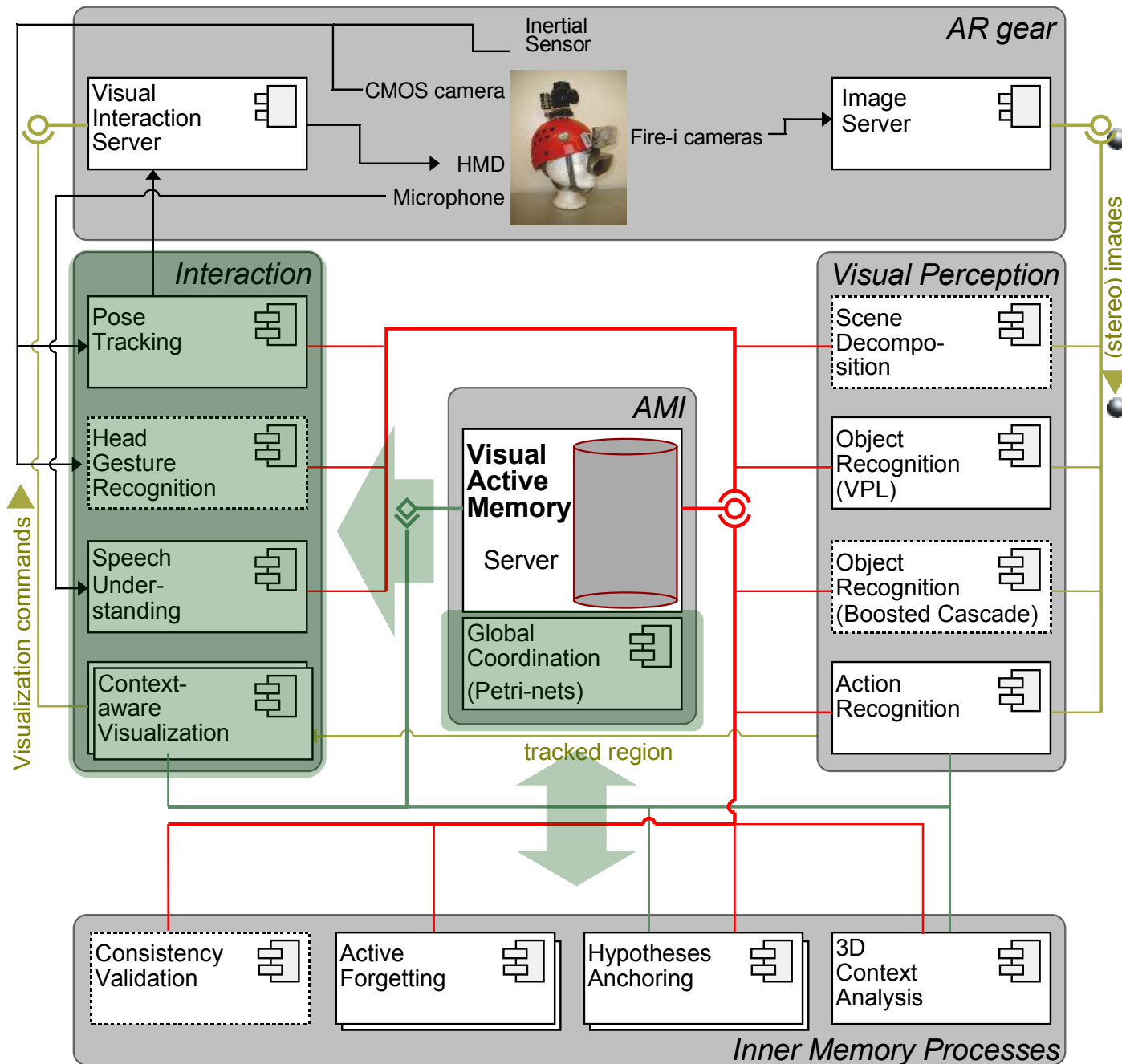




- memory is layered
- map percepts to episodes
- related to anchoring
[Coradeschi & Saffiotti]

- episodic \leftrightarrow real world
- generic process
 - actions & objects
- hypotheses: support & doubt





global coordination

- recipe handling
- state-based control
- error handling

interaction

- speech
- head gestures
- visualization
- answer queries



- individual components

- recognition rate
(~80% in action recognition)
- others

- user studies

- online, real world
- task oriented
 - “teach some objects!”
 - “prepare a cocktail!”

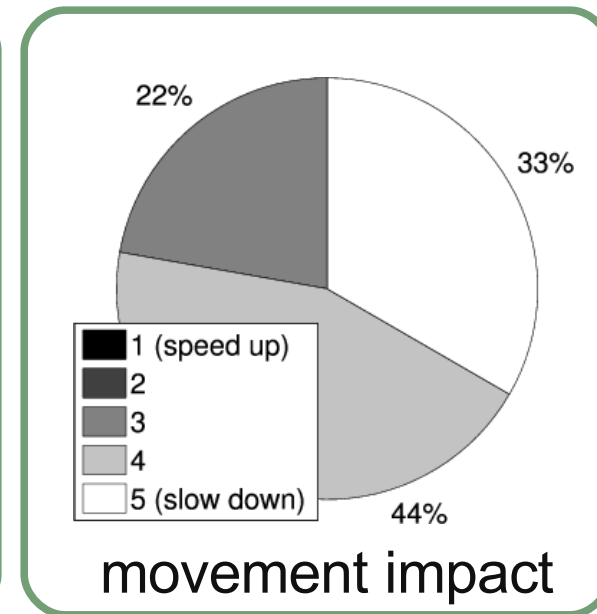
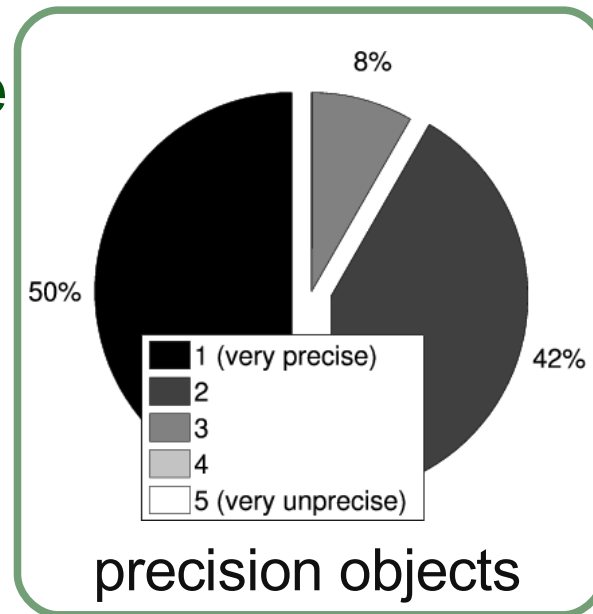
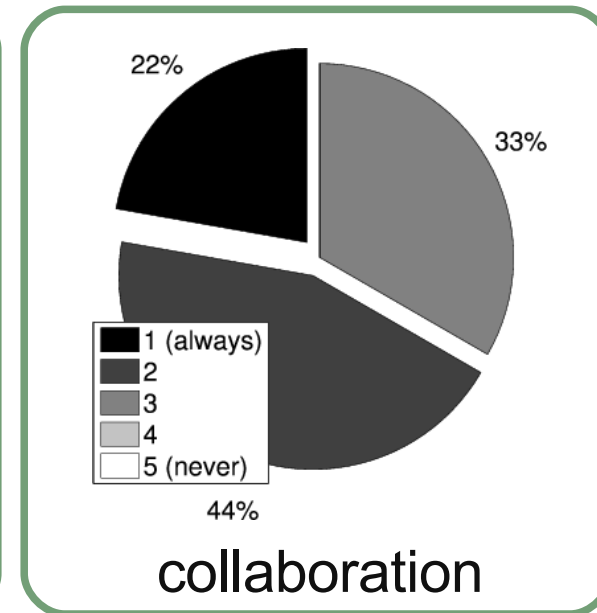
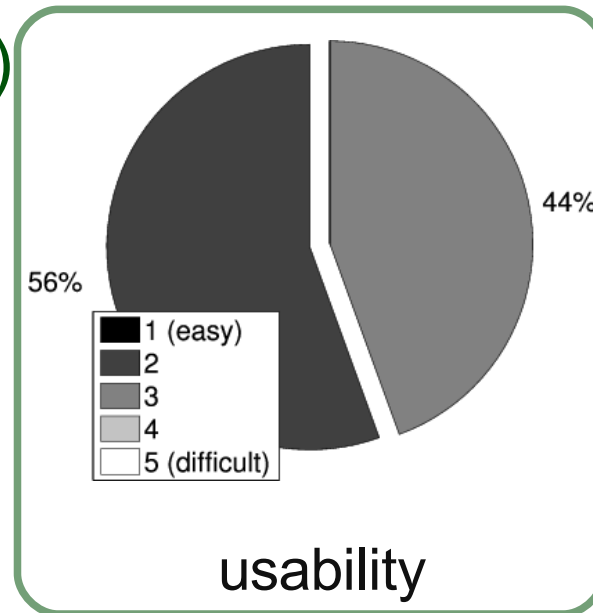
- 11 first time users

- all solved the task

- some explanation required



- questionnaire (24 answers)
 - usable
 - collaboration works
 - object highlight precise
 - reactive
 - reliable
 - impact on movement
- **“fun to use!”**
- **ego-vision for assistance**



Ego Vision

- mediated embodiment
- shared
 - perception
 - attention
- mutual control
 - challenges for perception

Active Memory

- architectural concept
- memory processes
 - perception
 - anchoring

Outlook

- Active Memory: towards a cognitive architecture (robotics)
- Ego-Vision: focus attention and collaboration
- Assistance System:
 - lighter hardware
 - challenging scenario



Thank you!

Questions?

credits:

Ingo Bax, Holger Bekel, Nicolas Gorges, Christoph Gräßl, Nils Hofemann, Marcel Richter, Jan Schäfer, Hannes Siegl, Christoph Stock, Sebastian Wrede, Timo Zinßer

