

## A common fixed point theorem for cyclic operators on partial metric spaces

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**Abstract.** In this paper, we prove a common fixed point theorem for two self-mappings satisfying certain conditions over the class of partial metric spaces. In particular, the main theorem of this manuscript extends some well-known fixed point theorems in the literature on this topic.

### 1. Introduction

Recently, studies on the existence and uniqueness of fixed points of self-mappings on partial metric spaces have gained momentum (see e.g., [1] - [4],[7], [14]-[? ],[26, 33]). The idea of partial metric space, a generalization of metric space, was introduced by Mathews [25] in 1992. When compared to metric spaces, the innovation of partial metric spaces is that the self distance of a point is not necessarily zero [24]. This feature of partial metrics makes them suitable for many purposes of semantics and domain theory in computer sciences. In particular, partial metric spaces have applications on the *Scott-Strachey order-theoretic topological models* [32] used in the logics of computer programs.

Mathews [25] proved the analog of Banach contraction mapping principle in the class of partial metric spaces. This remarkable paper of Mathews [25] constructed another important bridge between the domain theory in computer science and fixed point theory in mathematics. Thus, it becomes feasible to transform the tools from Mathematics to Computer Science.

A self-mapping  $T$  on a metric space  $X$  is called contraction if there exists a constant  $k \in [0, 1)$  such that  $d(Tx, Ty) \leq kd(x, y)$  for each  $x, y \in X$ . Banach contraction mapping principle, which states that a contraction has a fixed point, is one of the most important result in nonlinear analysis. This crucial result has been studied continuously since it was first published (See e.g. [1]-[23],[26]-[30]). As a generalization of this fundamental principle, Kirk-Srinivasan-Veeramani [23] developed the cyclic contraction. A contraction  $T : A \cup B \rightarrow A \cup B$  on non-empty set  $A, B$  is called cyclic if  $T(A) \subset B$  and  $T(B) \subset A$  hold for closed subsets  $A, B$  of a complete metric space  $X$ . In the last decade, many authors (see e.g.[21, 22, 27–29, 34]) reported some fixed point theorems for cyclic operators.

Rus [29] introduced the following definition which is a further generalization of a cyclic mapping.

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**Definition 1.1.** Let  $X$  be a nonempty set,  $m$  be a positive integer and  $T : X \rightarrow X$  be a mapping.  $X = \cup_{i=1}^m A_i$  is said to be a *cyclic representation of  $X$  with respect to  $T$*  if

- (i)  $A_i, i = 1, 2, \dots, m$  are nonempty sets.
- (ii)  $T(A_1) \subset A_2, \dots, T(A_{m-1}) \subset A_m, T(A_m) \subset A_1$ .

**Remark 1.2.** For convenience, we denote by  $\mathcal{F}$  the class of functions  $\phi : [0, \infty) \rightarrow [0, \infty)$  nondecreasing and continuous satisfying  $\phi(t) > 0$  for  $t \in (0, \infty)$  and  $\phi(0) = 0$ .

We recall the following definition.

**Definition 1.3.** (See e.g. [? ]) Let  $(X, d)$  be a metric space,  $m$  be a positive integer,  $A_1, A_2, \dots, A_m$  be nonempty subsets of  $X$  and  $X = \cup_{i=1}^m A_i$ . An operator  $T : X \rightarrow X$  is a *cyclic weak  $(\phi - \psi)$ -contraction* if

- (i)  $X = \cup_{i=1}^m A_i$  is a cyclic representation of  $X$  with respect to  $T$ ,
- (ii)  $\phi(d(Tx, Ty)) \leq \phi(d(x, y)) - \psi(d(x, y))$ , for any  $x \in A_i, y \in A_{i+1}, i = 1, 2, \dots, m$ , where  $A_{m+1} = A_1$  and  $\phi, \psi \in \mathcal{F}$ .

The main result of [22] is the following.

**Theorem 1.4.** (Theorem 6 of [22]) Let  $(X, d)$  be a complete metric space,  $m$  be a positive integer,  $A_1, A_2, \dots, A_m$  be nonempty subsets of  $X$  and  $X = \cup_{i=1}^m A_i$ . Let  $T : X \rightarrow X$  be a cyclic  $(\phi - \psi)$ -contraction with  $\phi, \psi \in \mathcal{F}$ . Then  $T$  has a unique fixed point  $z \in \cap_{i=1}^m A_i$ .

In this paper, we proved a common fixed point of two self-mappings  $T, g : X \rightarrow X$  on a partial metric space  $X$  under certain conditions.

We start some definitions and results needed in the sequel.

A partial metric on a nonempty set  $X$  is a mapping  $p : X \times X \rightarrow [0, \infty)$  such that

$$(PM1) \quad x = y \text{ if and only if } p(x, x) = p(x, y) = p(y, y),$$

$$(PM2) \quad p(x, x) \leq p(x, y),$$

$$(PM3) \quad p(x, y) = p(y, x),$$

$$(PM4) \quad p(x, y) \leq p(x, z) + p(z, y) - p(z, z).$$

for all  $x, y, z \in X$ . A pair  $(X, p)$  is said to be partial metric space.

Notice also that if  $p$  is a partial metric on  $X$ , then the functions  $d_p, d_m : X \times X \rightarrow \mathbb{R}^+$  given by

$$d_p(x, y) = 2p(x, y) - p(x, x) - p(y, y), \tag{1}$$

$$p(x, y) - p(x, x), p(x, y) - p(y, y) \tag{2}$$

are equivalent (usual) metrics on  $X$ . For details see e.g. [? ].

**Example 1.5.** (See e.g. [1, 3, 20, 24]) Consider  $X = [0, \infty)$  with  $p(x, y) = \max\{x, y\}$ . Then  $(X, p)$  is a partial metric space. It is clear that  $p$  is not a (usual) metric. Note that in this case  $d_p(x, y) = |x - y|$ .

**Example 1.6.** (See e.g. [24]) Let  $X = \{[a, b] : a, b \in \mathbb{R}, a \leq b\}$  and define  $p([a, b], [c, d]) = \max\{b, d\} - \min\{a, c\}$ . Then  $(X, p)$  is a partial metric spaces.

**Lemma 1.7.** (See e.g. [14, 15]) Let  $(X, p)$  be a PMS. Then

- (A) If  $p(x, y) = 0$  then  $x = y$ ,
- (B) If  $x \neq y$ , then  $p(x, y) > 0$ .

**Example 1.8.** (See e.g.[?] ) Let  $(X, d)$  and  $(X, p)$  be a metric space and a partial metric space, respectively. Mappings  $p_i : X \times X \rightarrow [0, \infty)$  ( $i \in \{1, 2, 3\}$ ) defined by

$$\begin{aligned} p_1(x, y) &= d(x, y) + p(x, y) \\ p_2(x, y) &= d(x, y) + \max\{\omega(x), \omega(y)\} \\ p_3(x, y) &= d(x, y) + a \end{aligned}$$

induce partial metrics on  $X$ , where  $\omega : X \rightarrow [0, \infty)$  is an arbitrary function and  $a \geq 0$ .

We notice also that each partial metric  $p$  on  $X$  generates a  $T_0$  topology  $\tau_p$  on  $X$  which has a family of open  $p$ -balls

$$\{B_p(x, \varepsilon) : x \in X, \varepsilon > 0\},$$

as a base where  $B_p(x, \varepsilon) = \{y \in X : p(x, y) < p(x, x) + \varepsilon\}$  for all  $x \in X$  and  $\varepsilon > 0$ .

**Definition 1.9.** (See e.g. [24]) Let  $(X, p)$  be a partial metric space.

- (i) A sequence  $\{x_n\}$  in  $X$  converges to  $x \in X$  whenever  $\lim_{n \rightarrow \infty} p(x, x_n) = p(x, x)$ ,
- (ii) A sequence  $\{x_n\}$  in  $X$  is called *Cauchy* whenever  $\lim_{n, m \rightarrow \infty} p(x_n, x_m)$  exists (and finite),
- (iii)  $(X, p)$  is said to be *complete* if every Cauchy sequence  $\{x_n\}$  in  $X$  converges, with respect to  $\tau_p$ , to a point  $x \in X$ , that is,  $\lim_{n, m \rightarrow \infty} p(x_n, x_m) = p(x, x)$ .

We define  $L(x_n) = \{x | x_n \rightarrow x\}$  where  $\{x_n\}$  is a sequence in a partial metric space  $(X, p)$ . The example below shows that a convergent sequence  $\{x_n\}$  in a partial metric space may not be a Cauchy. In particular, it shows that the limit of a convergent sequence is not unique.

**Example 1.10.** (See e.g.[?] ) Let  $X = [0, \infty)$  and  $p(x, y) = \max\{x, y\}$ . Let

$$x_n = \begin{cases} 0, & n = 2k, \\ 1, & n = 2k + 1. \end{cases}$$

Then clearly it is convergent sequence and for every  $x \geq 1$  we have  $\lim_{n \rightarrow \infty} p(x_n, x) = p(x, x)$ , therefore  $L(x_n) = [1, \infty)$ . But  $\lim_{n, m \rightarrow \infty} p(x_n, x_m)$  does not exist.

We state a lemma that shows the limit of a convergent sequence  $\{x_n\}$  in a partial metric space is unique.

**Lemma 1.11.** (See e.g.[?] ) Let  $\{x_n\}$  be a convergent sequence in partial metric space  $X$  such that  $x_n \rightarrow x$  and  $x_n \rightarrow y$ . If

$$\lim_{n \rightarrow \infty} p(x_n, x_n) = p(x, x) = p(y, y),$$

then  $x = y$ .

**Lemma 1.12.** (See e.g.[?] ) Let  $\{x_n\}$  and  $\{y_n\}$  be two sequences in partial metric space  $X$  such that

$$\lim_{n \rightarrow \infty} p(x_n, x) = \lim_{n \rightarrow \infty} p(x_n, x_n) = p(x, x),$$

and

$$\lim_{n \rightarrow \infty} p(y_n, y) = \lim_{n \rightarrow \infty} p(y_n, y_n) = p(y, y),$$

then  $\lim_{n \rightarrow \infty} p(x_n, y_n) = p(x, y)$ . In particular,  $\lim_{n \rightarrow \infty} p(x_n, z) = p(x, z)$  for every  $z \in X$ .

**Lemma 1.13.** (See e.g. [24],[26]) Let  $(X, p)$  be a partial metric space.

- (a)  $\{x_n\}$  is a Cauchy sequence in  $(X, p)$  if and only if it is a Cauchy sequence in the metric space  $(X, d_p)$ .  
 (b) A partial metric space  $(X, p)$  is complete if and only if the metric space  $(X, d_p)$  is complete. Furthermore,  $\lim_{n \rightarrow \infty} d_p(x_n, x) = 0$  if and only if

$$p(x, x) = \lim_{n \rightarrow \infty} p(x_n, x) = \lim_{n, m \rightarrow \infty} p(x_n, x_m).$$

**Lemma 1.14.** (See e.g. [? ]) If  $\{x_n\}$  is a convergent sequence in  $(X, d_p)$ , then it is a convergent sequence in the partial metric space  $(X, p)$ .

In this paper, we prove a common fixed point theorem on the class of the partial metric spaces as a generalization of Theorem 1.4 and the main theorem of [31].

## 2. Main Result

We start this section with the following definition for two self-mappings  $T, g : X \rightarrow X$ .

**Definition 2.1.** Let  $X$  be a nonempty set,  $m$  be a positive integer and  $T, g : X \rightarrow X$  be two mappings.  $X = \cup_{i=1}^m A_i$  is said to be a *cyclic representation of  $X$  with respect to  $(T - g)$*  if

- (i)  $A_i, i = 1, 2, \dots, m$  are nonempty sets.  
 (ii)  $T(A_1) \subset g(A_2), \dots, T(A_{m-1}) \subset g(A_m), T(A_m) \subset g(A_1)$ .

**Definition 2.2.** Let  $(X, p)$  be a partial metric space,  $m$  be a positive integer,  $A_1, A_2, \dots, A_m$  be nonempty subsets of  $X$  and  $X = \cup_{i=1}^m A_i$ . Two operators  $T, g : X \rightarrow X$  are *cyclic  $(\phi - \psi)$ -contraction* if

- (i)  $X = \cup_{i=1}^m A_i$  is a cyclic representation of  $X$  with respect to  $(T - g)$ ,  
 (ii)  $\phi(p(Tx, Ty)) \leq \phi(p(gx, gy)) - \psi(p(gx, gy))$ , for any  $x \in A_i, y \in A_{i+1}, i = 1, 2, \dots, m$ , where  $A_{m+1} = A_1$  and  $\phi, \psi \in \mathcal{F}$ .

Our main result is the following.

**Theorem 2.3.** Let  $(X, p)$  be a complete partial metric space,  $m$  be a positive integer,  $A_1, A_2, \dots, A_m$  be nonempty subsets of  $X$  and  $X = \cup_{i=1}^m A_i$ . Let  $T, g : X \rightarrow X$  be two cyclic  $(\phi - \psi)$ -contraction such that  $g(A_i)$  closed subsets of  $X$ .

- i) If  $g$  is one to one then there exists  $z \in \cap_{i=1}^m A_i$  such that  $gz = Tz$ .  
 ii) If the pair  $(T, g)$  are weakly compatible,  
 then  $T$  and  $g$  has a unique common fixed point  $z \in \cap_{i=1}^m A_i$ .

*Proof.* Let  $x_1$  be an arbitrary point in  $A_1$ . By cyclic representation of  $X$  with respect to pair  $(T, g)$ , we choose a point  $x_2$  in  $A_2$  such that  $Tx_1 = gx_2$ . For this point  $x_2$  there exists a point  $x_3$  in  $A_3$  such that  $Tx_2 = gx_3$ , and so on. Continuing in this manner we can define a sequence  $\{x_n\}$  as follows

$$Tx_n = gx_{n+1},$$

for  $n = 1, 2, \dots$ . We prove that  $\{gx_n\}$  is a Cauchy sequence. If there exists  $n_0 \in \mathbb{N}$  such that  $gx_{n_0+1} = gx_{n_0}$  then, since  $gx_{n_0+1} = Tx_{n_0} = gx_{n_0}$ , the part of existence of the coincidence point of  $T$  and  $g$  is proved. Suppose that  $gx_{n+1} \neq gx_n$  for any  $n = 1, 2, \dots$ . Then, since  $X = \cup_{i=1}^m A_i$ , for any  $n > 0$  there exists  $i_n \in \{1, 2, \dots, m\}$  such that  $x_{n-1} \in A_{i_n}$  and  $x_n \in A_{i_{n+1}}$ . Since  $(T, g)$  are cyclic  $(\phi - \psi)$ -contraction, we have

$$\begin{aligned} \phi(p(gx_n, gx_{n+1})) &= \phi(p(Tx_{n-1}, Tx_n)) \\ &\leq \phi(p(gx_{n-1}, gx_n)) - \psi(p(gx_{n-1}, gx_n)) \\ &\leq \phi(p(gx_{n-1}, gx_n)) \end{aligned} \tag{3}$$

From (3) and taking into account that  $\phi$  is nondecreasing we obtain

$$p(gx_n, gx_{n+1}) \leq p(gx_{n-1}, gx_n) \text{ for any } n = 2, 3, \dots$$

Thus  $\{p(gx_n, gx_{n+1})\}$  is a nondecreasing sequence of nonnegative real numbers. Consequently, there exists  $\gamma \geq 0$  such that  $\lim_{n \rightarrow \infty} p(gx_n, gx_{n+1}) = \gamma$ . Taking  $n \rightarrow \infty$  in (3) and using the continuity of  $\phi$  and  $\psi$ , we have

$$\phi(\gamma) \leq \phi(\gamma) - \psi(\gamma) \leq \phi(\gamma),$$

and, therefore,  $\psi(\gamma) = 0$ . Since  $\psi \in \mathcal{F}$ ,  $\gamma = 0$ , that is,

$$\lim_{n \rightarrow \infty} p(gx_n, gx_{n+1}) = 0.$$

Since  $p(gx_n, gx_n) \leq p(gx_n, gx_{n+1})$  and  $p(gx_{n+1}, gx_{n+1}) \leq p(gx_n, gx_{n+1})$ , hence

$$\lim_{n \rightarrow \infty} p(gx_n, gx_n) = \lim_{n \rightarrow \infty} p(gx_{n+1}, gx_{n+1}) = \lim_{n \rightarrow \infty} p(gx_n, gx_{n+1}) = 0. \quad (4)$$

Since

$$d_p(gx_n, gx_{n+1}) = 2p(gx_n, gx_{n+1}) - p(gx_n, gx_n) - p(gx_{n+1}, gx_{n+1}).$$

This shows that  $\lim_{n \rightarrow \infty} d_p(gx_n, gx_{n+1}) = 0$ .

In the sequel, we prove that  $\{gx_n\}$  is a Cauchy sequence in the metric space  $(X, d_p)$ .

First, we prove the following claim.

**Claim:** For every  $\epsilon > 0$  there exists  $n \in \mathbb{N}$  such that if  $b, q \geq n$  with  $b - q \equiv 1(m)$  then  $d_p(x_b, x_q) < \epsilon$ .

In fact, suppose the contrary case. This means that there exists  $\epsilon > 0$  such that for any  $n \in \mathbb{N}$  we can find  $b_n > q_n \geq n$  with  $b_n - q_n \equiv 1(m)$  satisfying

$$d_p(gx_{q_n}, gx_{b_n}) \geq \epsilon. \quad (5)$$

Now, we take  $n > 2m$ . Then, corresponding to  $q_n \geq n$  use can choose  $b_n$  in such a way that it is the smallest integer with  $b_n > q_n$  satisfying  $b_n - q_n \equiv 1(m)$  and  $d_p(gx_{q_n}, gx_{b_n}) \geq \epsilon$ . Therefore,  $d_p(gx_{q_n}, gx_{b_n-m}) \leq \epsilon$ . Using the triangular inequality

$$\epsilon \leq d_p(gx_{q_n}, gx_{b_n}) \leq d_p(gx_{q_n}, gx_{b_n-m}) + \sum_{i=1}^m d_p(gx_{b_n-i}, gx_{b_n-i+1}) < \epsilon + \sum_{i=1}^m d_p(gx_{b_n-i}, gx_{b_n-i+1}).$$

Letting  $n \rightarrow \infty$  in the last inequality and taking into account that  $\lim_{n \rightarrow \infty} d_p(gx_n, gx_{n+1}) = 0$ , we obtain

$$\lim_{n \rightarrow \infty} d_p(gx_{q_n}, gx_{b_n}) = \epsilon \implies \lim_{n \rightarrow \infty} p(gx_{q_n}, gx_{b_n}) = \frac{\epsilon}{2} \quad (6)$$

Again, by the triangular inequality

$$\begin{aligned} \epsilon &\leq d_p(gx_{q_n}, gx_{b_n}) \\ &\leq d_p(gx_{q_n}, gx_{q_{n+1}}) + d_p(gx_{q_{n+1}}, gx_{b_{n+1}}) + d_p(gx_{b_{n+1}}, gx_{b_n}) \\ &\leq d_p(gx_{q_n}, gx_{q_{n+1}}) + d_p(gx_{q_{n+1}}, gx_{q_n}) \\ &\quad + d_p(gx_{q_n}, gx_{b_n}) + d_p(gx_{b_n}, gx_{b_{n+1}}) + d_p(gx_{b_{n+1}}, gx_{b_n}) \\ &= 2d_p(gx_{q_n}, gx_{q_{n+1}}) + d_p(gx_{q_n}, gx_{b_n}) + 2d_p(gx_{b_n}, gx_{b_{n+1}}) \end{aligned} \quad (7)$$

Letting  $n \rightarrow \infty$  in (6) and taking into account that  $\lim_{n \rightarrow \infty} d_p(gx_n, gx_{n+1}) = 0$  and (6), we get

$$\lim_{n \rightarrow \infty} d_p(gx_{q_{n+1}}, gx_{b_{n+1}}) = \epsilon.$$

Hence

$$\lim_{n \rightarrow \infty} p(gx_{q_{n+1}}, gx_{b_{n+1}}) = \frac{\epsilon}{2}. \quad (8)$$

Since  $gx_{q_n}$  and  $gx_{b_n}$  lie in different adjacently labeled sets  $A_i$  and  $A_{i+1}$  for certain  $1 \leq i \leq m$ , using the fact that  $T$  and  $g$  are cyclic  $(\phi - \psi)$ -contraction, we have

$$\begin{aligned} \phi(p(gx_{q_{n+1}}, gx_{b_{n+1}})) &= \phi(p(Tx_{q_n}, Tx_{b_n})) \\ &\leq \phi(p(gx_{q_n}, gx_{b_n})) - \psi(p(gx_{q_n}, gx_{b_n})) \\ &\leq \phi(p(gx_{q_n}, gx_{b_n})). \end{aligned}$$

Taking into account (6) and (8) and the continuity of  $\phi$  and  $\psi$ , letting  $n \rightarrow \infty$  in the last inequality, we obtain

$$\phi\left(\frac{\epsilon}{2}\right) \leq \phi\left(\frac{\epsilon}{2}\right) - \psi\left(\frac{\epsilon}{2}\right) \leq \phi\left(\frac{\epsilon}{2}\right)$$

and consequently,  $\psi\left(\frac{\epsilon}{2}\right) = 0$ . Since  $\psi \in \mathcal{F}$ , then  $\epsilon = 0$  which is contradiction. Therefore, our claim is proved.

In the sequel, we will prove that  $\{gx_n\}$  is a Cauchy sequence in metric space  $(X, d_p)$ . Fix  $\epsilon > 0$ . By the claim, we find  $n_0 \in \mathbb{N}$  such that if  $b, q \geq n_0$  with  $b - q \equiv 1(m)$

$$d_p(gx_b, gx_q) \leq \frac{\epsilon}{2}. \quad (9)$$

Since  $\lim_{n \rightarrow \infty} d_p(gx_n, gx_{n+1}) = 0$  we also find  $n_1 \in \mathbb{N}$  such that

$$d_p(gx_n, gx_{n+1}) \leq \frac{\epsilon}{2m} \quad (10)$$

for any  $n \geq n_1$ .

Suppose that  $r, s \geq \max\{n_0, n_1\}$  and  $s > r$ . Then there exists  $k \in \{1, 2, \dots, m\}$  such that  $s - r \equiv k(m)$ . Therefore,  $s - r + j \equiv 1(m)$  for  $j = m - k + 1$ . So, we have

$$d_p(gx_r, gx_s) \leq d_p(gx_r, gx_{s+j}) + d_p(gx_{s+j}, gx_{s+j-1}) + \dots + d_p(gx_{s+1}, gx_s).$$

By (9) and (10) and from the last inequality, we get

$$d_p(gx_r, gx_s) \leq \frac{\epsilon}{2} + j \frac{\epsilon}{2m} \leq \frac{\epsilon}{2} + m \frac{\epsilon}{2m} = \epsilon.$$

This proves that  $\{gx_n\}$  is a Cauchy sequence in metric space  $(X, d_p)$ . Since  $(X, p)$  is complete then from Lemma 1.13, the sequence  $\{gx_n\}$  converges in the metric space  $(X, d_p)$ , say  $\lim_{n \rightarrow \infty} d_p(gx_n, x) = 0$  for some  $x \in X$ .

Therefore, by Lemma 1.13 we have

$$p(x, x) = \lim_{n \rightarrow \infty} p(gx_n, x) = \lim_{n, m \rightarrow \infty} p(gx_n, gx_m).$$

That is, there exists  $x \in X$  such that  $\lim_{n \rightarrow \infty} gx_n = x$  in partial metric  $(X, p)$ . Since  $g(A_i)$  are closed subsets of  $X$ , we have  $x \in g(A_i)$  for every  $i \in \{1, 2, \dots, m\}$ . That is,  $x \in \bigcap_{i=1}^m g(A_i)$ . Hence, there exists  $z_i \in A_i$  such that  $gz_i = x$ . Since  $g$  is one to one we have

$$g(z_1) = g(z_2) = \dots = g(z_m) = x \implies z_1 = z_2 = \dots = z_m = z.$$

Therefore,  $g(z) = x$  for  $z \in \bigcap_{i=1}^m A_i$ . In fact,  $\lim_{n \rightarrow \infty} gx_n = gz$ . On the other hand since the sequence  $\{gx_n\}$  has infinite terms in each  $A_i$  for  $i \in \{1, 2, \dots, m\}$ , we take a subsequence  $\{gx_{n_k}\}$  of  $\{gx_n\}$  with  $gx_{n_k} \in g(A_{i-1})$  where  $x_{n_k} \in A_{i-1}$ . Using the contractive condition, we can obtain

$$\begin{aligned} \phi(p(gx_{n_{k+1}}, Tz)) &= \phi(p(Tx_{n_k}, Tz)) \\ &\leq \phi(p(gx_{n_k}, gz)) - \psi(p(gx_{n_k}, gz)) \\ &\leq \phi(p(gx_{n_k}, gz)). \end{aligned}$$

Since  $gx_{n_k} \rightarrow gz$  and  $\phi$  and  $\psi$  belong to  $\mathcal{F}$ , letting  $k \rightarrow \infty$  in the last inequality, we have

$$\phi(p(gz, Tz)) \leq \phi(p(gz, gz)) - \psi(p(gz, gz)) \leq \phi(p(gz, gz)).$$

Moreover, we obtain  $p(gz, Tz) = p(gz, gz)$ , because  $\phi$  is nondecreasing and  $p(gz, gz) \leq p(gz, Tz)$ . Hence, if  $p(gz, gz) \neq 0$  then by the last inequality we have,

$$\begin{aligned} \phi(p(gz, gz)) &= \phi(p(gz, Tz)) \\ &\leq \phi(p(gz, gz)) - \psi(p(gz, gz)) \\ &< \phi(p(gz, gz)), \end{aligned}$$

which is contradiction. Since  $\phi \in \mathcal{F}$ , then,  $p(Tz, Tz) = p(gz, gz) = p(gz, Tz) = 0$ , it follows that,  $Tz = gz = x$ .

ii) Since  $g$  and  $T$  are two weakly compatible mappings, we have  $TTz = Tgz = gTz = ggz$ . That is  $Tx = gx$ . Next, we prove that  $Tx = x$ . Since  $Tz \in X$  hence there exists some  $i$  such that  $Tz \in A_i$ . By  $z \in \cap_{i=1}^m A_i$  we have  $z \in A_{i-1}$ , by using the contractive condition we obtain

$$\begin{aligned} \phi(p(Tz, TTz)) &\leq \phi(p(gz, gTz)) - \psi(p(gz, gTz)) \\ &\leq \phi(p(gz, gTz)) = \phi(p(Tz, TTz)), \end{aligned}$$

from the last inequality we have

$$\psi(p(Tz, TTz)) = 0.$$

Since  $\psi \in \mathcal{F}$ ,  $p(Tz, TTz) = 0$  and, consequently,  $x = Tz = TTz = Tx = gx$ .

Finally, in order to prove the uniqueness of a fixed point, we have  $y, z \in X$  with  $y$  and  $z$  common fixed points of  $T$  and  $g$ . The cyclic character of  $T - g$  and the fact that  $y, z \in X$  are common fixed points of  $T$  and  $g$ , imply that  $y, z \in \cap_{i=1}^m A_i$ . If  $p(y, z) \neq 0$  then by using the contractive condition we obtain

$$\begin{aligned} \phi(p(y, z)) &= \phi(p(Ty, Tz)) \leq \phi(p(gy, gz)) - \psi(p(gy, gz)) \\ &< \phi(p(gy, gz)) = \phi(p(y, z)), \end{aligned}$$

which is a contradiction. Since  $\phi \in \mathcal{F}$ ,  $p(y, z) = 0$  and, consequently,  $y = z$ . This finishes the proof.  $\square$

**Corollary 2.4.** Let  $(X, p)$  be a complete partial metric space,  $m$  be a positive integer,  $A_1, A_2, \dots, A_m$  be nonempty closed subsets of  $X$  and  $X = \cup_{i=1}^m A_i$ . Let  $T : X \rightarrow X$  be a cyclic weak  $(\phi - \psi)$ -contraction. Then  $T$  has a unique fixed point  $z \in \cap_{i=1}^m A_i$ .

*Proof.* Take  $g(x) = x$  in Theorem 2.3.  $\square$

**Corollary 2.5.** Let  $(X, p)$  be a complete partial metric space,  $m$  be a positive integer,  $A_1, A_2, \dots, A_m$  be nonempty closed subsets of  $X$ . Suppose that  $T : X \rightarrow X$  is a self-mapping and  $X = \cup_{i=1}^m A_i$  is a cyclic representation of  $X$  with respect to  $T$ . Further,  $T$  satisfies  $d(Tx, Ty) \leq d(x, y) - \psi(d(x, y))$ , for any  $x \in A_i, y \in A_{i+1}, i = 1, 2, \dots, m$ , where  $A_{m+1} = A_1$  and  $\psi \in \mathcal{F}$ . Then  $T$  has a unique fixed point  $z \in \cap_{i=1}^m A_i$ .

*Proof.* Take  $\phi(t) = t$  in Corollary 2.4.  $\square$

**Example 2.6.** Let  $X = [0, 1]$  and  $g, T : X \rightarrow X$  such that  $Tx = \frac{x^2}{12}$  and  $gx = \frac{x}{3}$ . Suppose that  $\psi, \phi : [0, \infty) \rightarrow [0, \infty)$  are defined as follows  $\psi(t) = \frac{t}{2}$  and  $\phi(t) = \frac{t}{3}$ . For  $A_i = [0, 1]$ ,  $(i = 1, 2, \dots, m)$  all conditions of Theorem 2.3 are satisfied. It is clear that  $x = 0$  is the common fixed point of  $T$  and  $g$ .

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