# A FIXED POINT THEOREM FOR A PAIR OF MAPS SATISFYING A GENERAL CONTRACTIVE CONDITION OF INTEGRAL TYPE 

P. VIJAYARAJU, B. E. RHOADES, AND R. MOHANRAJ

Received 18 October 2004 and in revised form 20 July 2005

We give a general condition which enables one to easily establish fixed point theorems for a pair of maps satisfying a contractive inequality of integral type.

Branciari [1] obtained a fixed point result for a single mapping satisfying an analogue of Banach's contraction principle for an integral-type inequality. The second author [3] proved two fixed point theorems involving more general contractive conditions. In this paper, we establish a general principle, which makes it possible to prove many fixed point theorems for a pair of maps of integral type.

Define $\Phi=\left\{\varphi: \varphi: \mathbb{R}^{+} \rightarrow \mathbb{R}\right\}$ such that $\varphi$ is nonnegative, Lebesgue integrable, and satisfies

$$
\begin{equation*}
\int_{0}^{\epsilon} \varphi(t) d t>0 \quad \text { for each } \epsilon>0 \tag{1}
\end{equation*}
$$

Let $\psi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$satisfy that
(i) $\psi$ is nonnegative and nondecreasing on $\mathbb{R}^{+}$,
(ii) $\psi(t)<t$ for each $t>0$,
(iii) $\sum_{n=1}^{\infty} \psi^{n}(t)<\infty$ for each fixed $t>0$.

Define $\Psi=\{\psi: \psi$ satisfies (i)-(iii) $\}$.
Lemma 1. Let $S$ and $T$ be self-maps of a metric space $(X, d)$. Suppose that there exists a sequence $\left\{x_{n}\right\} \subset X$ with $x_{0} \in X, x_{2 n+1}:=S x_{2 n}, x_{2 n+2}:=T x_{2 n+1}$, such that $\overline{\left\{x_{n}\right\}}$ is complete and there exists a $k \in[0,1)$ such that

$$
\begin{equation*}
\int_{0}^{d(S x, T y)} \varphi(t) d t \leq \psi\left(\int_{0}^{d(x, y)} \varphi(t) d t\right) \tag{2}
\end{equation*}
$$

for each distinct $x, y \in \overline{\left\{x_{n}\right\}}$ satisfying either $x=$ Ty or $y=S x$, where $\varphi \in \Phi, \psi \in \Psi$.

Then, either
(a) S or $T$ has a fixed point in $\left\{x_{n}\right\}$ or
(b) $\left\{x_{n}\right\}$ converges to some point $p \in X$ and

$$
\begin{equation*}
\int_{0}^{d\left(x_{n}, p\right)} \varphi(t) d t \leq \sum_{i=n}^{\infty} \psi^{i}(d) \quad \text { for } n>0 \tag{3}
\end{equation*}
$$

where

$$
\begin{equation*}
d:=\int_{0}^{d\left(x_{0}, x_{1}\right)} \varphi(t) d t \tag{4}
\end{equation*}
$$

Proof. Suppose that $x_{2 n+1}=x_{2 n}$ for some $n$. Then $x_{2 n}=x_{2 n+1}=S x_{2 n}$, and $x_{2 n}$ is a fixed point of S. Similarly, if $x_{2 n+2}=x_{2 n+1}$ for some $n$, then $x_{2 n+1}$ is a fixed point of $T$.

Now assume that $x_{n} \neq x_{n+1}$ for each $n$. With $x=x_{2 n}, y=x_{2 n+1}$, (2) becomes

$$
\begin{equation*}
\int_{0}^{d\left(x_{2 n+1}, x_{2 n+2}\right)} \varphi(t) d t \leq \psi\left(\int_{0}^{d\left(x_{2 n}, x_{2 n+1}\right)} \varphi(t) d t\right) \tag{5}
\end{equation*}
$$

Substituting $x=x_{2 n}, y=x_{2 n-1}$, (2) becomes

$$
\begin{equation*}
\int_{0}^{d\left(x_{2 n+1}, x_{2 n}\right)} \varphi(t) d t \leq \psi\left(\int_{0}^{d\left(x_{2 n}, x_{2 n-1}\right)} \varphi(t) d t\right) \tag{6}
\end{equation*}
$$

Therefore, for each $n \geq 0$,

$$
\begin{equation*}
\int_{0}^{d\left(x_{n}, x_{n+1}\right)} \varphi(t) d t \leq \psi\left(\int_{0}^{d\left(x_{n-1}, x_{n}\right)} \varphi(t) d t\right) \leq \cdots \leq \psi^{n}(d) . \tag{7}
\end{equation*}
$$

Let $m, n \in \mathbb{N}, m>n$. Then, using the triangular inequality,

$$
\begin{equation*}
d\left(x_{n}, x_{m}\right) \leq \sum_{i=n}^{m-1} d\left(x_{i}, x_{i+1}\right) . \tag{8}
\end{equation*}
$$

It can be shown by induction that

$$
\begin{equation*}
\int_{0}^{d\left(x_{n}, x_{m}\right)} \varphi(t) d t \leq \sum_{i=n}^{m-1} \int_{0}^{d\left(x_{i}, x_{i+1}\right)} \varphi(t) d t \tag{9}
\end{equation*}
$$

Using (7) and (9),

$$
\begin{equation*}
\int_{0}^{d\left(x_{n}, x_{m}\right)} \varphi(t) d t \leq \sum_{i=n}^{\infty} \psi^{i}(d) \leq \sum_{i=n}^{\infty} \psi^{i}(d) . \tag{10}
\end{equation*}
$$

Taking the limit of (10) as $m, n \rightarrow \infty$ and using condition (iii) for $\psi$, it follows that $\left\{x_{n}\right\}$ is Cauchy, hence convergent, since $X$ is complete. Call the limit $p$. Taking the limit of (10) as $m \rightarrow \infty$ yields (3).

Theorem 2. Let $(X, d)$ be a complete metric space, and let $S$, $T$ be self-maps of $X$ such that for each distinct $x, y \in X$,

$$
\begin{equation*}
\int_{0}^{d(S x, T y)} \varphi(t) d t \leq \psi\left(\int_{0}^{M(x, y)} \varphi(t) d t\right) \tag{11}
\end{equation*}
$$

where $k \in[0,1), \varphi \in \Phi, \psi \in \Psi$, and

$$
\begin{equation*}
M(x, y):=\max \left\{d(x, y), d(x, S x), d(y, T y), \frac{[d(x, T y)+d(y, S x)]}{2}\right\} \tag{12}
\end{equation*}
$$

Then $S$ and $T$ have a unique common fixed point.
Proof. We will first show that any fixed point of $S$ is also a fixed point of $T$, and conversely.
Let $p=S p$. Then

$$
\begin{equation*}
M(p, p)=\max \left\{0,0, d(p, T p), \frac{d(p, T p)}{2}\right\}=d(p, T p) \tag{13}
\end{equation*}
$$

and (11) becomes

$$
\begin{equation*}
\int_{0}^{d(p, T p)} \varphi(t) d t \leq \psi\left(\int_{0}^{d(p, T p)} \varphi(t) d t\right) \tag{14}
\end{equation*}
$$

which, from (1), implies that $p=T p$.
Similarly, $p=T p$ implies that $p=S p$.
We will now show that $S$ and $T$ satisfy (2).

$$
\begin{equation*}
M(x, S x)=\max \left\{d(x, S x), d(x, S x), d(S x, T S x), \frac{[d(x, T S x)+0]}{2}\right\} . \tag{15}
\end{equation*}
$$

From the triangular inequality,

$$
\begin{equation*}
\frac{d(x, T S x)}{2} \leq \frac{[d(x, S x)+d(S x, T S x)]}{2} \leq \max \{d(x, S x), d(S x, T S x)\} . \tag{16}
\end{equation*}
$$

Thus, (11) becomes

$$
\begin{equation*}
\int_{0}^{d(S x, T S x)} \varphi(t) d t \leq k \int_{0}^{d(S x, T S x)} \varphi(t) d t, \tag{17}
\end{equation*}
$$

a contradiction to (1).
Therefore, for all $x \in X, M(x, S x)=d(x, S x)$, and (2) is satisfied. If condition (a) of Lemma 1 is true, then $S$ or $T$ has a fixed point. But it has already been shown that any fixed point of $S$ is also a fixed point of $T$, and conversely. Thus $S$ and $T$ have a common fixed point.

Suppose that conclusion (b) of Lemma 1 is true. Then, from (3),

$$
\begin{equation*}
\int_{0}^{d\left(S x_{2 n}, T p\right)} \varphi(t) d t \leq \psi\left(\int_{0}^{d\left(x_{2 n}, p\right)} \varphi(t) d t\right), \tag{18}
\end{equation*}
$$

which implies, since $X$ is complete, that $\lim d\left(S x_{2 n}, T p\right)=0$.

Therefore,

$$
\begin{equation*}
d(p, T p) \leq d\left(p, S x_{2 n}\right)+d\left(S x_{2 n}, T p\right) \longrightarrow 0, \tag{19}
\end{equation*}
$$

and $p$ is a fixed point of $T$, hence a fixed point of $S$. Condition (11) clearly implies uniqueness of the fixed point.

Every contractive condition of integral type automatically includes a corresponding contractive condition not involving integrals, by setting $\varphi(t) \equiv 1$ over $\mathbb{R}^{+}$.

There are many contractive conditions of integral type which satisfy (2). Included among these are the analogues of the many contractive conditions involving rational expressions and/or products of distances. We conclude this paper with one such example.

Corollary 3. Let $(X, d)$ be a complete metric space, $S$ and $T$ self-maps of $X$ such that, for each distinct $x, y \in X$,

$$
\begin{equation*}
\int_{0}^{d(S x, T y)} \varphi(t) d t \leq k \int_{0}^{n(x, y)} \varphi(t) d t \tag{20}
\end{equation*}
$$

where $\varphi \in \Phi, k \in[0,1)$, and

$$
\begin{equation*}
n(x, y):=\max \left\{\frac{d(y, T y)[1+d(x, S x)]}{1+d(x, y)}, d(x, y)\right\} \tag{21}
\end{equation*}
$$

Then $S$ and $T$ have a unique common fixed point.
Proof.

$$
\begin{equation*}
n(x, S x)=\max \{d(S x, T S x), d(x, S x)\} \tag{22}
\end{equation*}
$$

As in the proof of Theorem 2, it is easy to show that any fixed point of $S$ is also a fixed point of $T$, and conversely.

If $n(x, S x)=d(S x, T S x)$, then an argument similar to that of Theorem 2 leads to a contradiction. Therefore $n(x, S x)=d(x, S x)$, and either $S$ or $T$ has a common fixed point, or (3) is satisfied. In the latter case, with $\lim x_{n}=p, n(p, p)=0$, so that, from (20), $p$ is a fixed point of $S$, hence of $T$. Uniqueness of $p$ is easily established.

Corollary 3 is also a consequence of Lemma 1.
We now provide an example, kindly supplied by one of the referees, to show that Lemma 1 is more general than [2, Theorem 3.1].

Example 4. Let $X:=\{1 / n: n \in \mathbb{N} \cup\{0\}\}$ with the Euclidean metric and $S, T$ are self-maps of $X$ defined by

$$
S\left(\frac{1}{n}\right)=\left\{\begin{array}{ll}
\frac{1}{n+1} & \text { if } n \text { is odd }  \tag{23}\\
\frac{1}{n+2} & \text { if } n \text { is even, } \\
0 & \text { if } n=\infty
\end{array} \quad T\left(\frac{1}{n}\right)= \begin{cases}\frac{1}{n+1} & \text { if } n \text { is even } \\
\frac{1}{n+2} & \text { if } n \text { is odd } \\
0 & \text { if } n=\infty\end{cases}\right.
$$

For each $n$, define $x_{2 n+1}=S x_{2 n}, x_{2 n+2}=T x_{2 n+1}$. With $x_{0}=1$, let $O(1)$ denote the orbit of $x_{0}=1$; that is, $O(1)=\{1,1 / 2,1 / 3, \ldots\}$ and $\overline{O(1)}=O(1) \cup\{0\}=X$. For $x, y \in O(1)$, $y=1 / m, m$ even and $x=1 / n=T y=1 /(m+1), S x=1 /(m+2)$, so that

$$
\begin{gather*}
d(S x, T y)=\left|\frac{1}{m+1}-\frac{1}{m+1}\right|=\frac{1}{m+1}-\frac{1}{m+2}=\frac{1}{(m+1)(m+2)},  \tag{24}\\
d(x, y)=\left|\frac{1}{n}-\frac{1}{m}\right|=\left|\frac{1}{m+1}-\frac{1}{n}\right|=\frac{1}{m}-\frac{1}{m+1}=\frac{1}{m(m+1)} .
\end{gather*}
$$

Thus

$$
\begin{equation*}
\frac{d(S x, T y)}{d(x, y)}=\frac{m}{m+2} \leq 1 \tag{25}
\end{equation*}
$$

Also

$$
\begin{equation*}
\sup _{n \in \mathbb{N}} \frac{d(S x, T y)}{d(x, y)}=1 \tag{26}
\end{equation*}
$$

so that there is no number $c \in[0,1)$ such that $d(S x, T y) \leq c d(x, y)$ for $x, y \in O(1)$ and $x=T y$. Therefore, [2, Theorem 3.1] cannot be used. On the other hand, the hypotheses of Lemma 1 are satisfied. To see this, it will be shown that condition (2) is satisfied for some $\varphi \in \Phi$.

We will first show that for any $x=1 / n, y=1 / m \in O(1)$ satisfying either $x=T y$ or $y=S x$,

$$
\begin{equation*}
d(S x, T y) \leq\left|\frac{1}{n+1}-\frac{1}{m+1}\right| \tag{27}
\end{equation*}
$$

There are four cases.
Case 1. $y=1 / m$, $m$ even, $x=1 / n=T y=1 /(m+1)$, and $S x=1 /(m+2)$. Then

$$
\begin{equation*}
d(S x, T y)=\left|\frac{1}{m+2}-\frac{1}{m+1}\right|=\left|\frac{1}{n+1}-\frac{1}{m+1}\right| . \tag{28}
\end{equation*}
$$

Case 2. $y=1 / m, m$ odd, $x=1 / n=T y=1 /(m+2)$, and $S x=1 /(m+3)$. Then

$$
\begin{align*}
d(S x, T y) & =\left|\frac{1}{m+3}-\frac{1}{m+2}\right|=\frac{1}{m+2}-\frac{1}{m+3} \\
& \leq \frac{1}{m+1}-\frac{1}{m+3}=\left|\frac{1}{n+1}-\frac{1}{m+1}\right| . \tag{29}
\end{align*}
$$

Case 3. $x=1 / n, n$ even, $y=1 / m=S x=1 /(n+2)$, and $T y=1 /(n+3)$. Then

$$
\begin{align*}
d(S x, T y) & =\left|\frac{1}{n+2}-\frac{1}{n+3}\right|=\frac{1}{n+2}-\frac{1}{n+3}  \tag{30}\\
& \leq \frac{1}{n+1}-\frac{1}{n+3}=\left|\frac{1}{n+1}-\frac{1}{n+3}\right| .
\end{align*}
$$

Case 4. $x=1 / n, n$ odd, $y=1 / m=S x=1 /(n+1)$, and $T y=1 /(n+2)$. Then

$$
\begin{equation*}
d(S x, T y)=\left|\frac{1}{n+1}-\frac{1}{n+2}\right|=\left|\frac{1}{n+1}-\frac{1}{m+1}\right| \tag{31}
\end{equation*}
$$

Thus in all cases, (20) is satisfied.
Define $\varphi$ by $\varphi(t)=t^{1 / 2-2}[1-\log t]$ for $t>0$ and $\varphi(0)=0$. Then, for any $\tau>0$,

$$
\begin{equation*}
\int_{0}^{\tau} \varphi(t) d t=\tau^{1 / \tau} \tag{32}
\end{equation*}
$$

and $\varphi \in \Phi$.
Using [1, Example 3.6],

$$
\begin{align*}
\int_{0}^{d(S x, T y)} \varphi(t) d t & \leq d(S x, T y)^{1 / d(S x, T y)} \\
& \leq\left|\frac{1}{n+1}-\frac{1}{m+1}\right|^{1 /|(1 / n+1)-(1 / m+1)|}  \tag{33}\\
& \leq \frac{1}{2}\left|\frac{1}{n}-\frac{1}{m}\right|^{1 /|(1 / n)-(1 / m)|}=d(x, y)^{1 / d(x, y)}
\end{align*}
$$

for each $x, y$ as in Lemma 1, and condition (2) is satisfied with $\psi(t)=t / 2$.

## Acknowledgment

The authors thank each of the referees for careful reading of the manuscript.

## References

[1] A. Branciari, A fixed point theorem for mappings satisfying a general contractive condition of integral type, Int. J. Math. Math. Sci. 29 (2002), no. 9, 531-536.
[2] S. Park, Fixed points and periodic points of contractive pairs of maps, Proc. College Natur. Sci. Seoul Nat. Univ. 5 (1980), no. 1, 9-22.
[3] B. E. Rhoades, Two fixed-point theorems for mappings satisfying a general contractive condition of integral type, Int. J. Math. Math. Sci. 2003 (2003), no. 63, 4007-4013.
P. Vijayaraju: Department of Mathematics, Anna University, Chennai-600 025, India

E-mail address: vijay@annauniv.edu
B. E. Rhoades: Department of Mathematics, Indiana University, Bloomington, IN 47405-7106, USA

E-mail address: rhoades@indiana.edu
R. Mohanraj: Department of Mathematics, Anna University, Chennai-600 025, India

E-mail address: vrmraj@yahoo.com

## Mathematical Problems in Engineering

# Special Issue on <br> Modeling Experimental Nonlinear Dynamics and Chaotic Scenarios 

## Call for Papers

Thinking about nonlinearity in engineering areas, up to the 70 s, was focused on intentionally built nonlinear parts in order to improve the operational characteristics of a device or system. Keying, saturation, hysteretic phenomena, and dead zones were added to existing devices increasing their behavior diversity and precision. In this context, an intrinsic nonlinearity was treated just as a linear approximation, around equilibrium points.

Inspired on the rediscovering of the richness of nonlinear and chaotic phenomena, engineers started using analytical tools from "Qualitative Theory of Differential Equations," allowing more precise analysis and synthesis, in order to produce new vital products and services. Bifurcation theory, dynamical systems and chaos started to be part of the mandatory set of tools for design engineers.

This proposed special edition of the Mathematical Problems in Engineering aims to provide a picture of the importance of the bifurcation theory, relating it with nonlinear and chaotic dynamics for natural and engineered systems. Ideas of how this dynamics can be captured through precisely tailored real and numerical experiments and understanding by the combination of specific tools that associate dynamical system theory and geometric tools in a very clever, sophisticated, and at the same time simple and unique analytical environment are the subject of this issue, allowing new methods to design high-precision devices and equipment.

Authors should follow the Mathematical Problems in Engineering manuscript format described at http://www .hindawi.com/journals/mpe/. Prospective authors should submit an electronic copy of their complete manuscript through the journal Manuscript Tracking System at http:// mts.hindawi.com/ according to the following timetable:

| Manuscript Due | February 1, 2009 |
| :--- | :--- |
| First Round of Reviews | May 1, 2009 |
| Publication Date | August 1,2009 |

## Guest Editors

José Roberto Castilho Piqueira, Telecommunication and Control Engineering Department, Polytechnic School, The University of São Paulo, 05508-970 São Paulo, Brazil; piqueira@lac.usp.br

Elbert E. Neher Macau, Laboratório Associado de Matemática Aplicada e Computação (LAC), Instituto Nacional de Pesquisas Espaciais (INPE), São Josè dos Campos, 12227-010 São Paulo, Brazil ; elbert@lac.inpe.br

Celso Grebogi, Department of Physics, King's College, University of Aberdeen, Aberdeen AB24 3UE, UK; grebogi@abdn.ac.uk

