A Framework for Event Composition in Distributed Systems

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Overview

Introduction

- Events and Pub/Sub systems
- Example
- Motivation
- Composite Event Detection
 - Model and composition language
 - Mobile Composite Event Detectors
 - Policies
- Conclusion

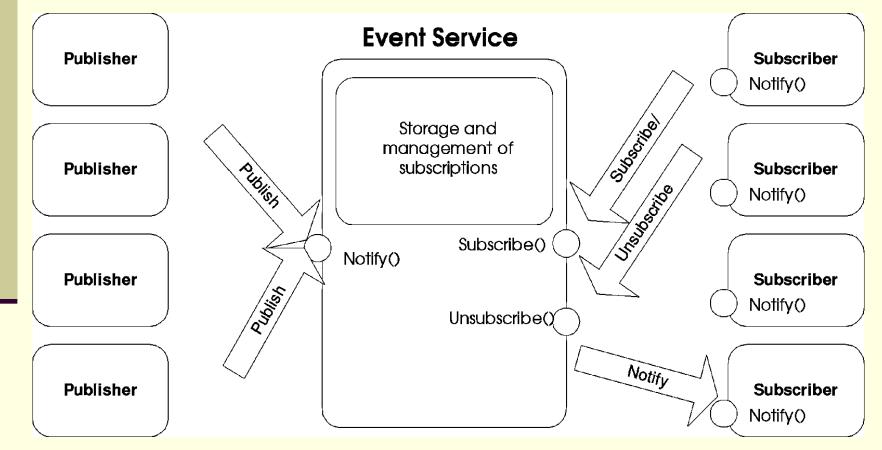
Introduction

Events

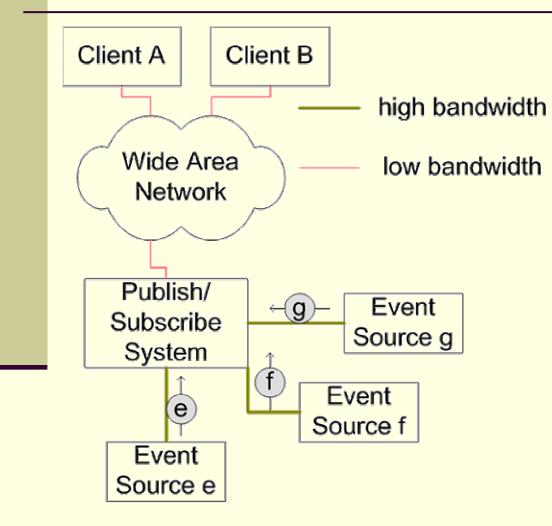
- Something has happend
- Modelled as an object
- Publish/Subscribe Systems
 - "Proxy" for events
 - Decoupling space, time and synchronization
 - JMS, JORAM
 - Gryphon (IBM)
 - used at Sydney Olympics, US Tennis Open,...

Introduction (2)

Interface of a Pub/Sub System:



Example – Pub/Sub System

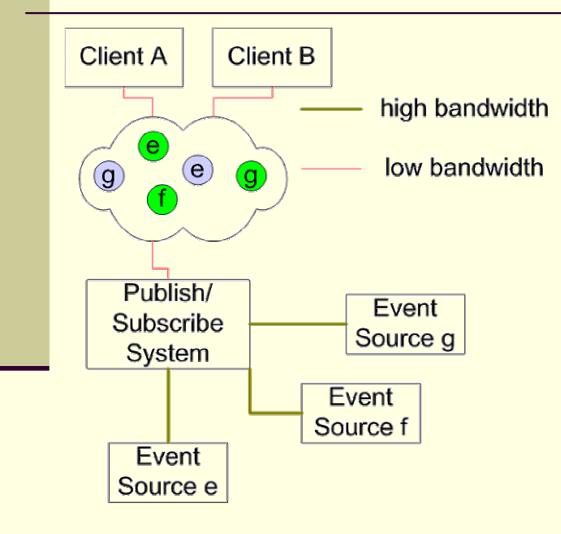


Sources: produce events of type e,f and g.

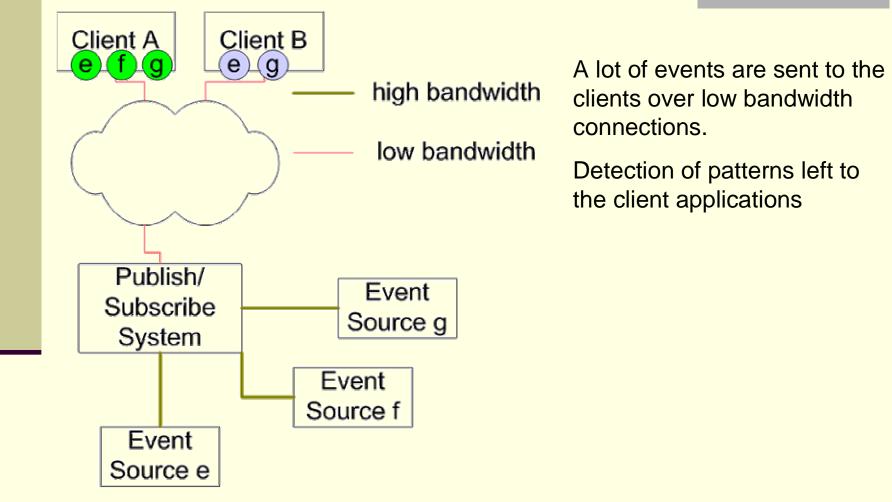
Client A: subscribed for events of type e,f,g and is interested to know, whether they occured in a sequence c1 = (e; f; g)

Client B: subscribed for events of type e and g and is interested to know, whether they occured within a 5 minute time interval. $c2 = (e,g)_{T=5min}$

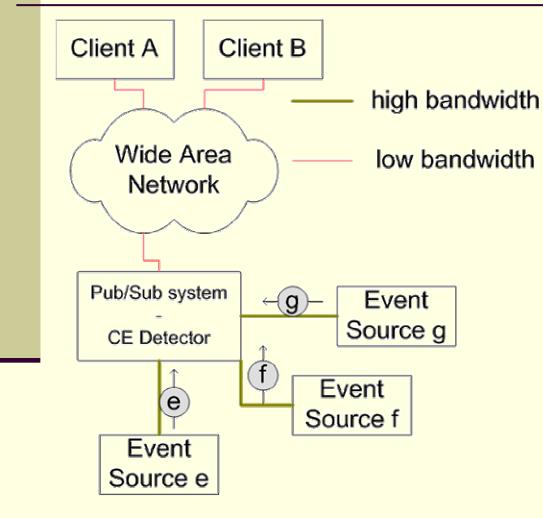
Example – Pub/Sub System (2)



Example – Pub/Sub System (3)



Example - Pub/Sub System and CE detector (4)

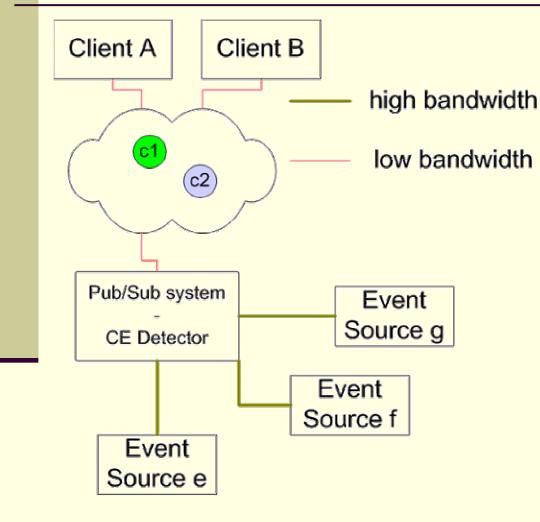


Pub/Sub system is extended with a Composite Event (CE) Detector

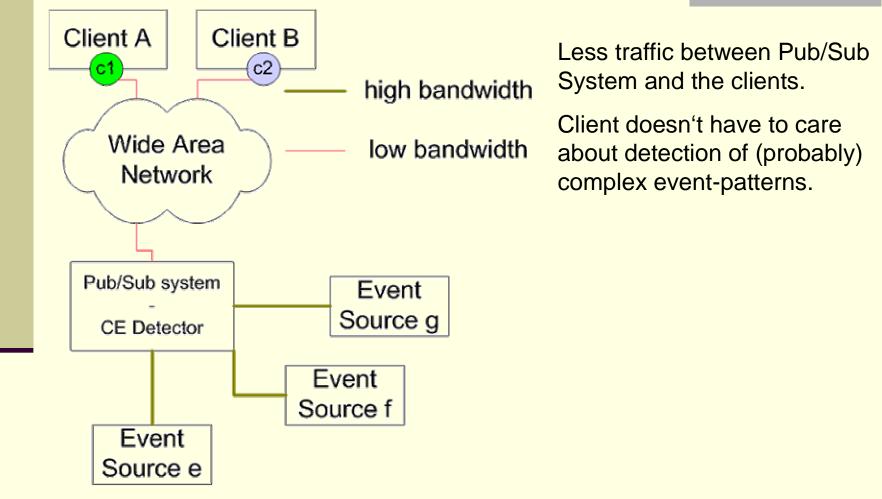
Client A: subscribes for CE c1 = (e ; f ; g) (Sequence)

Client B: subscribes for CE $c2 = (e, g)_{T=5min}$

Example - Pub/Sub System and CE detector (5)



Example - Pub/Sub System and CE detector (6)



Motivation

Abstraction of Events

- Composition of atomic events
- CE represented as a new atomic event
- Composition of CE
- Reduction of bandwidth usage

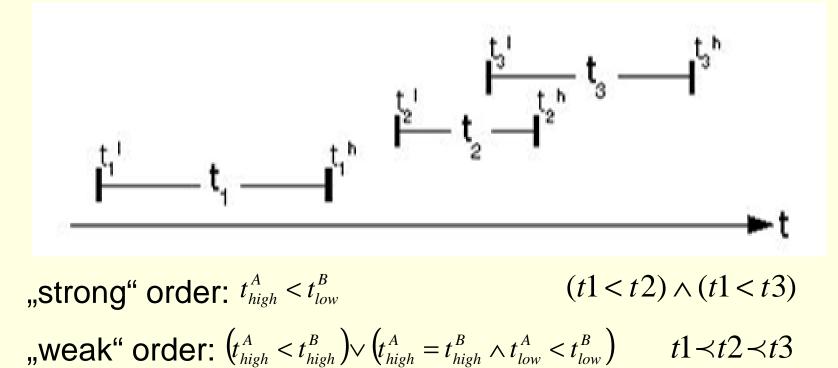
Composite Event (CE) Detection

Result: CE Detection Framework

- Regular language for CE specification
- Compiler translates the "core CE language" into detectors
- Realised as finite automata
- Assumptions on infrastructure
 - 1. An underlying Pub/Sub System
 - Events carry a timestamp, denoted by an time interval

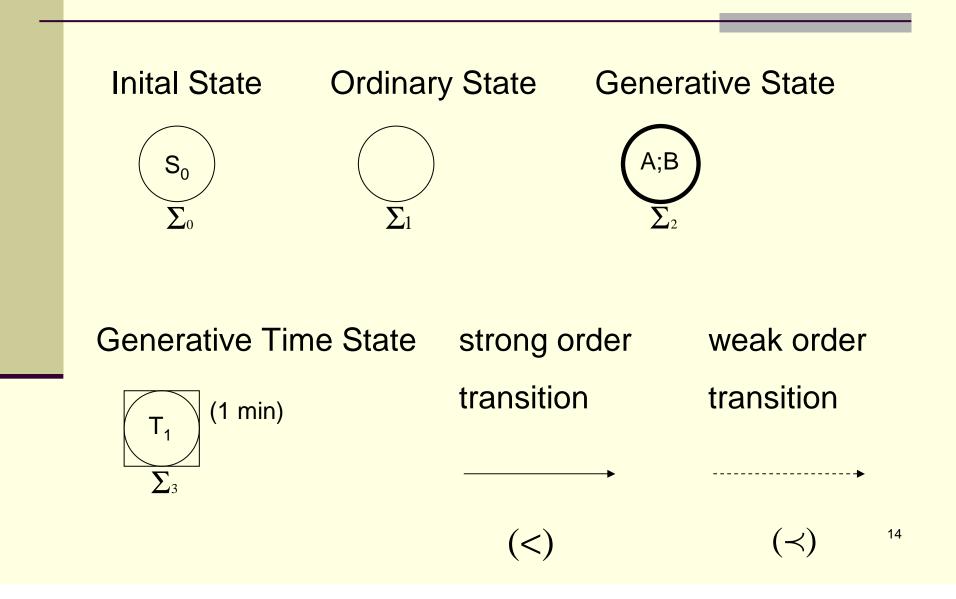
Composite Event (CE) Detection (2)

Time Model:



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Composite Event (CE) Detection (3)

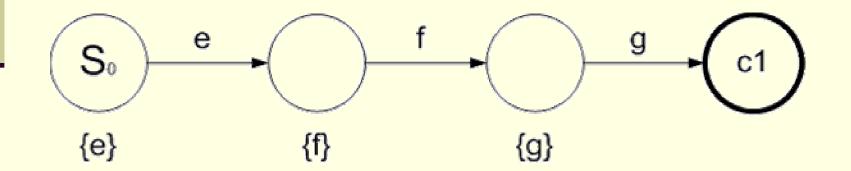


Composite Event (CE) Detection (4)

Continue example:

Client A: c1 = (e;f;g) (sequence of 3 events)

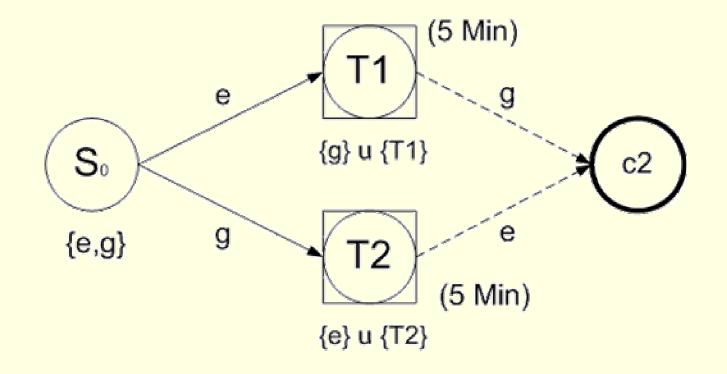
Transformation into automaton:



Composite Event (CE) Detection (5)

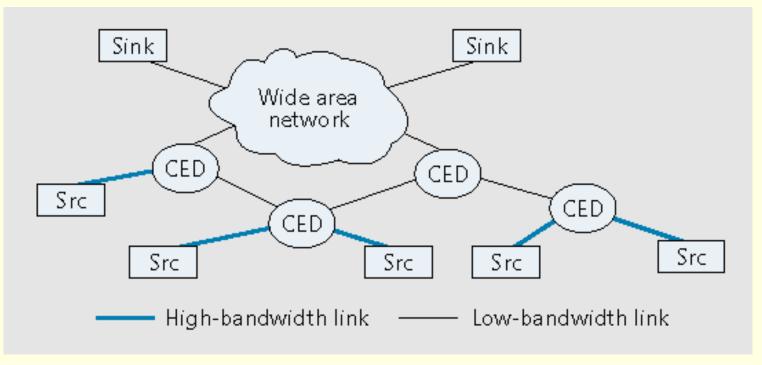
Client B: $c2 = (e, g)_{T=5min}$

Transformation into automaton:



Distributed Detection

- In the example: monolithic system for event detection
- Distribute detectors over the network



Mobile Composite Event Detectors

A Mobile Detector can factorize	CE expressions
instantiate new detectors	to reduce own load
migrate to another node	to reduce bandwidth usage at bottlenecks
destroy itself	if no longer needed

Detectors move to "optimal" site
Tradeoff between bandwidth usage and latency

Distribution Policy

- 1. Determine location of a detector.
- 2. Decide on the degree of decomposition and distribution.
- 3. Decide on duplication of certain (often used) detectors.
- Optimization in terms of bandwidth usage and latency.

Detection Policy

- When can an input stream of events safely be processed?
- Best Effort Detection: events in input stream are consumed without delay.
- Guaranteed Detection: consumption of an event in the input stream, if event is stable.
 - stable: An event is stable, if an event of the same source arrived with a later timestamp.

Detection Policy (2) – Problems

- What if a source is rarely publishing events?
 - Publish dummy heartbeat events.
 - Load on bandwidth.
- What if a source is disconnected?
- Research is done on a probabilistic stability measure.

Conclusion

- System tested on artifical office example
 - Bandwidth usage can be brought down significantly
 - But no "real world" test yet
- Paper is sloppy concerning the formal definitions
- Composite event detection with FSMs isn't really new (already done for database trigger events)

Conclusion (2)

Contributions

- Idea of detection of composite events applied to distributed systems
- Notion of mobile, decomposable and clonable detectors

Thank You **Questions?**

Appendix A – Time Model

Events have a timestamp denoted by a time interval t = [t_{low},t_{high}]

Partial Order:

Time intervals of event A and B do not overlap

• A < B iff
$$t_{high}^A < t_{low}^B$$

strong order

denoted by a solid arrow in the FSM

Appendix A – Time Model (2)

Total Order

- Time intervals do overlap
- $A \prec B \quad \text{iff} \quad \left(t_{high}^A < t_{high}^B\right) \lor \left(t_{high}^A = t_{high}^B \land t_{low}^A < t_{low}^B\right)$ weak order
- denoted by a dashed arrow in the FSM

Appendix B – Core CE Language

Atoms: Events {A,B,C,...} in input stream Negation: $[\neg E \subseteq \Sigma] \equiv [\Sigma \setminus E \subseteq \Sigma]$ Concatenation: C_1C_2 (C_1 weakly followed by C_2) Sequence: $C_1;C_2$ (C_1 strongly followed by C_2) Iteration: C_1^* Alternation: $C_1|C_2$ Timing: $(C_1,C_2)_{T = \text{timespec.}}$ Parallelisation: $C_1||C_2$

Appendix B – Core CE Language (2)

Brian enters the room followed by Peter [*B*];[*P*]

Brian enters the room before Peter $[B \subseteq \{B, P\}]$

Brian enters and Peter follows within an hour $([B], [P \subseteq \{P, T1\}])_{T1=1h}$

Someone else enters the room when Brian is away $[B][\neg B \subseteq A][B]$

Appendix C - Implementation

- Framework built on top of JORAM (Java Open Reliable Asynchronous Messaging), which is a open-source implementation of JMS (Java Message Service).
- Download at: <u>http://joram.objectweb.org/</u>
- Source of the framework not yet available for download (but probably soon)