Annali della Scuola Normale Superiore di Pisa *Classe di Scienze*

HANS WILHELM ALT Luis A. Caffarelli Avner Friedman

A free boundary problem for quasi-linear elliptic equations

Annali della Scuola Normale Superiore di Pisa, Classe di Scienze 4^e série, tome 11, nº 1 (1984), p. 1-44

<http://www.numdam.org/item?id=ASNSP_1984_4_11_1_0>

© Scuola Normale Superiore, Pisa, 1984, tous droits réservés.

L'accès aux archives de la revue « Annali della Scuola Normale Superiore di Pisa, Classe di Scienze » (http://www.sns.it/it/edizioni/riviste/annaliscienze/) implique l'accord avec les conditions générales d'utilisation (http://www.numdam.org/conditions). Toute utilisation commerciale ou impression systématique est constitutive d'une infraction pénale. Toute copie ou impression de ce fichier doit contenir la présente mention de copyright.

\mathcal{N} umdam

Article numérisé dans le cadre du programme Numérisation de documents anciens mathématiques http://www.numdam.org/

A Free Boundary Problem for Quasi-Linear Elliptic Equations (*).

HANS WILHELM ALT - LUIS A. CAFFARELLI - AVNER FRIEDMAN

0. - Introduction.

Consider the problem of minimizing the functional

$$(0.1) J(u) = \int_{\Omega} \left(F(|\nabla u|^2) + \lambda^2 I_{\{u>0\}} \right) dx \quad (\lambda > 0)$$

in the class of functions u satisfying $u = u^0$ on a part S of $\partial \Omega$, $u^0 \ge 0$. Here Ω is a domain in \mathbb{R}^n and F(t) is a convex function of t for t > 0, F(0) = 0, F'(0) > 0. The special case F(t) = t was studied by Alt and Caffarelli [1] who proved Lipschitz continuity and nondegeneracy of a minimum u. They also studied the free boundary $\Gamma = \partial \{u > 0\} \cap \Omega$ and proved the analyticity of Γ if n = 2; further, if $n \ge 3$, $x^0 \in \Gamma$ and Γ satisfies the « flatness condition » at x^0 , then Γ is analytic in a neighborhood of x^0 .

The results of [1] were used by Alt, Caffarelli and Friedman [2-4] in their study of jet flows of inviscid, irrotational and incompressible fluid.

In this paper we shall extend all the results of [1] to the functional (0.1). In particular we establish Lipschitz continuity and nondegeneracy of a minimum, and analyticity of the free boundary (if $n \ge 3$, the flatness condition is assumed, as before).

The results of this paper extend with obvious changes to the more general

(*) This work is partially supported by Deutsche Forschungsgemeinschaft, SFB 72 and by National Science Foundation Grants 7406375 A01 and MCS 791 5171.

Pervenuto alla Redazione il 29 Settembre 1982 ed in forma definitiva il 2 Maggio 1983. functional

(0.2)
$$J(u) = \int_{\Omega} \left[F(x, |\nabla u(x)|^2) + \lambda^2(x) I_{\{u>0\}}(x) \right] dx$$

where $\lambda(x) > 0$, $\lambda \in C^{\alpha}(\Omega)$.

In a future publication we shall apply the results of this paper to the study of jets and cavities of compressible fluids.

1. - The minimization problem; basic properties.

Let F(t) be a function in $C^{2,1}[0,\infty)$, satisfying:

(1.1)
$$F(0) = 0, \qquad c_0 < F'(t) < C_0, \\ 0 < F''(t) < \frac{C_0}{1+t} \quad (c_0, C_0 \text{ positive constants}).$$

Let Ω be a domain in \mathbb{R}^n , not necessarily bounded. For any $\lambda > 0$, consider the functional

$$J(v)=\int\limits_{\Omega}ig(F(|
abla v|^2)+\lambda^2 I_{\{u>0\}}ig)\,dx$$

over the class of admissible functions

$$K = \{ v \in L^1_{\mathrm{loc}}(\varOmega), \,
abla v \in L^2(\varOmega) \, \, \mathrm{and} \, \, v = u^0 \, \, \mathrm{on} \, \, S \}$$

where S is a given subset of $\partial \Omega$ and u^0 is a given function. We assume that locally $\partial \Omega$ is a Lipschitz graph, that S is measurable with $H^{n-1}(S) > 0$, and that

$$u^0 \ge 0$$
, $u^0 \in L^1_{\text{loc}}(\Omega)$, $\nabla u_0 \in L^2(\Omega)$.

Set

$$f(p) = F(|p|^2).$$

From (1.1) we find that f(p) is convex; moreover,

(1.2)
$$\beta |\xi|^2 \leq \sum \frac{\partial^2 f(p)}{\partial p_i \partial p_j} \xi_i \xi_0 < \beta^{-1} |\xi|^2 \quad \text{for all } \xi \in \mathbb{R}^n,$$

consequently

(1.3)
$$\begin{cases} \beta |p|^2 < f_p(p) \cdot p, \\ \beta |p|^2 < f(p) < \beta^{-1} |p|^2 \end{cases}$$

for some small constant $\beta > 0$, where $f_p = \nabla_p f$.

3

Consider the problem: find u such that

(1.4)
$$J(u) = \min_{v \in K} J(v), \quad u \in K.$$

This means that we have to deal with the differential operator

$$\mathscr{L}v = \nabla \cdot (f_p(\nabla v))$$

THEOREM 1.1. If $J(u^0) < \infty$ then there exists a solution to problem (1.4).

PROOF. The proof is the same as in [1], Theorem 1.3. Let $\{u_k\}$ be a minimizing sequence. Then, by (1.3),

$$\int_{\Omega} |\nabla u_k|^2 \ll \frac{1}{\beta} J(u_k) \, .$$

It follows that $u_k - u^0$ are bounded in $L^2(\Omega \cap B_R)$ for any large R. Therefore there is a $u \in K$ such that, for a subsequence,

$$abla u_k o
abla u \quad ext{weakly in } L^2_{loc}(\Omega) \ ,$$
 $u_k o u \quad ext{a.e. in } \Omega \ .$

The pointwise convergence implies

$$\int_{\Omega \cap B_R} I_{\{u>0\}} \leqslant \liminf_{k \to \infty} \int_{\Omega \cap B_R} I_{\{u_k>0\}},$$

and since f is convex we have (see, for instance [6; pp. 232-3])

$$\int_{\Omega \cap B_R} f(|\nabla u|) \leq \liminf_{k \to \infty} \int_{\Omega \cap B_R} f(|\nabla u_k|);$$

 \mathbf{thus}

$$J(u) \leqslant \liminf_{k \to \infty} J(u_k) \, .$$

DEFINITION 1.2. $u \in K$ is called a *local minimum* of J if, for some $\varepsilon_0 > 0$, $J(u) \leq J(v)$ for any $v \in K$ with

$$\|\nabla(v-u)\|_{L^{2}(\Omega)}+\|I_{\{v>0\}}-I_{\{u>0\}}\|_{L^{1}(\Omega)}<\varepsilon_{0}.$$

LEMMA 1.3. If u is a local minimum then u is \mathcal{L} -subsolution, that is,

(1.5)
$$\int_{\Omega} \nabla \zeta \cdot f_p(\nabla u) < 0 \quad \text{for all } \zeta \in C_0^{\infty}(\Omega) , \quad \zeta > 0 .$$

PROOF. For any $\varepsilon > 0$,

$$\begin{split} 0 &\leq \frac{1}{\varepsilon} \left(J(u - \varepsilon \zeta) - J(u) \right) \leq \frac{1}{\varepsilon} \int_{\Omega} \left(f(\nabla u - \varepsilon \nabla \zeta) - f(\nabla u) \right) \\ &\leq - \int_{\Omega} \nabla \zeta \cdot f_{\mathfrak{p}}(\nabla u - \varepsilon \nabla \zeta) \,, \end{split}$$

since by convexity

4

(1.6)
$$f(p) - f(q) \leqslant (p-q) \cdot f_p(p) .$$

Now take $\varepsilon \to 0$.

LEMMA 1.4. If w is a local \mathscr{L} -solution in B_R , that is, $w \in H^{1,2}(B_R)$ and

(1.7)
$$\int \nabla \zeta \cdot f_{\mathfrak{p}}(\nabla w) = 0 \quad \text{for all } \zeta \in C_0^{\infty}(B_R),$$

and if $w \ge u$ on ∂B_R , then $w \ge u$ in B_R . If w = u on ∂B_R then w is uniquely determined.

PROOF. Taking $\zeta = (u - w)^+$ in (1.5), (1.7) and comparing, we get, using the convexity (1.2) of f:

$$0 \geq \int_{B_R} (f_p(\nabla u) - f_p(\nabla w)) \cdot \nabla (u - w)^+$$

=
$$\int_{B_R \cap \{u > w\}} (f_p(\nabla u) - f_p(\nabla w)) \cdot \nabla (\nabla u - \nabla w)$$

>
$$\beta \int_{B_R} |\nabla (u - w)^+|^2;$$

hence $u - w \leq 0$. If w_1 is another solution of (1.7) then the above proof gives $w_1 - w \leq 0$. Similarly $w - w_1 \leq 0$, so that $w = w_1$:

•

LEMMA 1.5. If u is a local minimum then

$$(1.8) \qquad \qquad 0 < u < \sup_{\Omega} u^{0}.$$

PROOF. Setting $M = \sup_{o} u^{o}$, we have, for small $\varepsilon > 0$,

$$0 < \frac{1}{\varepsilon} \left(J(u + \varepsilon \min (M - u, 0)) - J(u) \right)$$

= $\frac{1}{\varepsilon} \int_{\Omega} \left(f(\nabla u + \varepsilon \nabla \min (M - u, 0)) - f(\nabla u) \right)$
< $\int_{\Omega} \nabla \min (M - u, 0) \cdot f_{\nu} (\nabla u + \varepsilon \nabla \min (M - u, 0)), \quad \text{by (1.6).}$

5

Taking $\varepsilon \to 0$ we get

$$0 \leq \int_{\Omega} \nabla \min (M - u, 0) \cdot f_{p}(\nabla u)$$

= $-\int_{\{u > M\}} \nabla u \cdot f_{p}(\nabla u) \leq -\beta \int_{\{u > M\}} |\nabla u|^{2}$
= $-\beta \int_{\Omega} |\nabla \min (M - u, 0)|^{2}$

by (1.3), which yields $u \leq M$ a.e. in Ω .

Similarly, to prove that $u \ge 0$ we begin with (ε positive and small)

$$0 \leq \frac{1}{\varepsilon} \left(J(u - \varepsilon \min(u, 0)) - J(u) \right)$$

= $\frac{1}{\varepsilon} \int_{\Omega} \left(f \left(\nabla (u - \varepsilon \min(u, 0)) - f(\nabla u) \right) \right)$
< $- \int_{\Omega} \nabla \min(u, 0) \cdot f_{\rho} \left(\nabla (u - \varepsilon \min(u, 0)) \right).$

Taking $\varepsilon \to 0$ we get

$$\begin{split} 0 \geq & \int_{\Omega} \nabla \min(u, 0) \cdot f_{p}(\nabla u) \\ = & \int_{\{u < 0\}} \nabla u \cdot f_{p}(\nabla u) \geq \beta \int_{\{u < 0\}} |\nabla u|^{2} = \beta \int_{\Omega} |\nabla \min(u, 0)|^{2} , \end{split}$$

from which we deduce that $u \ge 0$.

In §2 it will be shown that, for any local minimum u, the set $\{u > 0\}$ is open. Let us use this fact already in the next statements of this section.

LEMMA 1.6. If u is a local minimum then u is \mathscr{L} -solution in $\{u > 0\}$. The proof is the same as that of Lemma 1.3, taking ζ any function in $C_0^{\infty}(\{u > 0\})$.

LEMMA 1.7. If G is an open set, $u \in H^{1,2}(G)$ and $\mathcal{L}u = 0$ in G, then $u \in C^{2+\alpha}$ for any $0 < \alpha < 1$.

PROOF. We can take G to be a ball. The equation $\mathcal{L}u = 0$ has the form

$$\partial_{j}(f_{p_{j}}(\nabla u)) = 0 \qquad \left(\partial_{j} = \frac{\partial}{\partial x_{j}}\right)$$

Applying ∂_k and setting $w_k = \partial_k u$ we get, formally,

$$\partial_j (a_{ij}(\nabla u) \partial_i w_k) = 0$$

where

6

is uniformly elliptic matrix. Thus the Nash-de Giorgi estimate should give a C^{α} estimate on $\hat{c}_k u$ for some $\alpha \in (0, 1)$.

In order to derive the C^{α} estimate rigorously, we approximate u on ∂G by smooth functions \tilde{u}_m (in the L^2 trace norm). By [6; Theorem 14.8] there exists a unique solution u_m of

$$\mathscr{L} u_m = 0 \quad \text{in } G ,$$

 $u_m = \tilde{u}_m \quad \text{on } \partial G$

with $u_m \in C^{2+\alpha}(\overline{G})$. The formal argument given above can be applied to u_m . It gives

 $|\boldsymbol{u}_m|_{1+\alpha}^{\boldsymbol{G}} \leqslant \boldsymbol{C}_m$

as well as

$$|\boldsymbol{u}_m|_{1+\alpha}^K \leqslant C$$

where K is any compact subset of G (C is independent of m). Since u_m and the minimizer of

$$\int\limits_{G} F(|
abla v|^2) \ , \quad v = \widetilde{u}_m \ ext{on} \ \partial G$$

 $\mathbf{7}$

coincide by Lemma 1.4, it follows that for some constants C, \tilde{C}

$$\int_G |\nabla u_m|^2 \ll C \!\!\!\!\int_G F(|\nabla u_m|^2) \ll \widetilde{C} \; .$$

Thus, for a subsequence,

 $egin{array}{ll} u_m o ilde u & ext{weakly in } H^{1,2}(G) \;, \ u_m o u & ext{ in } L^2(\partial G) \;(ext{in the trace sense}) \,. \end{array}$

It follows, again by Lemma 1.4, that $\tilde{u} = u$ and thus $u \in C^{1+\alpha}(K)$. Then the coefficients $a_{ij}(\nabla u)$ are Hölder continuous so that by elliptic estimates w_k is of class $C^{1+\alpha}$.

DEFINITION 1.8. We define functions ψ, Φ by

[1.10)
$$\begin{cases} \psi(p) = pf_{p} - f(p) = 2|p|^{2}F'(|p|^{2}) - F(|p|^{2}), \\ \Phi(s) = 2sF'(s) - F(s), \end{cases}$$

so that $\Phi(|p|^2) = \psi(p)$.

THEOREM 1.9. If u is a local minimum then

$$\lim_{s\to 0} \int_{\partial\{u>s\}} (\varPhi(|\nabla u|^2) - \lambda^2) \eta \cdot \nu = 0$$

for any $\eta \in H_0^{1,2}(\Omega; \mathbb{R}^n)$, where v is the outward normal.

The proof of this very weak formulation of the free boundary condition is similar to the proof of Theorem 2.5 in [1].

2. - Regularity and nondegeneracy.

We set

$$\int_A v = \frac{1}{\mu(A)} \int_A v \, d\mu.$$

Since we shall use this notation mostly when either A is a ball $B_r(x^0) = \{|x - x^0| < r\}$ and $\mu = L^n$ or A is a sphere $\partial B_r(x^0)$ and $\mu = H^{n-1}$, we often omit in the notation the measure $d\mu$.

LEMMA 2.1. Any local minimum u is in $C^{\alpha}(\Omega)$, for any $0 < \alpha < 1$. PROOF. Let $B_r \subset \Omega$ and let v be the solution of

(2.1)
$$\int_{B_r} \nabla \zeta \cdot f_p(\nabla v) = 0 \quad \text{for all } \zeta \in C_0^{\infty}(B_r),$$
$$v - u \in H_0^{1,2}(B_r);$$

its existence follows by minimization. Then

(2.2)
$$\int_{B_r} (f(\nabla u) + \lambda^2 I_{\{u>0\}}) \leq \int_{B_r} (f(\nabla v) + \lambda^2 I_{\{u>0\}})$$
$$= \int_{B_r} (f(\nabla v) + \lambda^2)$$

since v > 0 in B_r , by the maximum principle. By convexity (1.2),

$$[f(\nabla u) \ge f(\nabla v) + f_p(\nabla v) \cdot \nabla (u-v) + \beta |\nabla (u-v)|^2.$$

Integrating this relation and using (2.1) with $\zeta = u - v$, we find, after comparing with (2.2), that

(2.3)
$$\int_{B_r} |\nabla(u-v)|^2 \leq C \int_{B_r} \lambda^2 I_{\{u=0\}}.$$

We can now use the method of Morrey [11; Th. 5.3.6] in order to deduce the assertion of the lemma.

In the sequel we denote positive constants depending only on β and n by C or c.

 \mathbf{Set}

8

$$E_+ = \{u > 0\}, \quad E_0 = \{u = 0\}.$$

By Lemma 2.1, E_+ is open and E_0 is closed in Ω . Set

$$d(x) = \operatorname{dist}(x, E_0) \, .$$

LEMMA 2.2. Suppose $x_0 \in \Omega$, $d(x_0) < \frac{1}{2} \operatorname{dist}(x_0, \partial \Omega)$. Then

 $u(x_0) \leqslant C\lambda d(x_0)$

where C is a constant depending only on β , n.

PROOF. We assume that

$$(2.4) u(x_0) > Md(x_0)$$

and derive an upper bound on M. By scaling (i.e., by considering

$$\tilde{u}(x') = \frac{1}{r} u(x_0 + r(x' - x_0)), \quad r = d(x_0))$$

we may assume that $d(x_0) = 1$. Since $\mathscr{L}u = 0$ in $B_1(x_0)$, by Harnack's inequality [6; p. 189] and (2.4) we have

(2.5)
$$\inf_{B_{s/4}(x_0)} u > cu(x_0) > cM .$$

Let y be a point in $\partial B_1(x_0) \cap E_0$. We define a function v by (2.1) with B_r replaced by $B_1(y)$. Then $v \ge u$ in $B_1(y)$ and (cf. (2.3))

(2.6)
$$\int_{B_1(\mathbf{y})} |\nabla(\mathbf{u}-\mathbf{v})|^2 \leq C \int \lambda^2 I_{\{u=0\}}.$$

Recalling (2.5) we have

$$v \ge cM$$
 in $B_{\frac{3}{2}}(x_0) \cap B_1(y)$

and then, by Harnack's inequality [6; p. 189],

(2.7)
$$v \ge C^*$$
 in $B_{\dagger}(y)$, $C^* = cM$.

We take for simplicity y = 0 and introduce the function

$$w(x) = C^*(\exp(-\mu |x|^2) - \exp(-\mu))$$

We compute

(2.8)
$$\mathscr{L}w(x) = \nabla \cdot f_p(\nabla w(x)) = \nabla \cdot f_p(-2\mu x C^* \exp(-\mu |x|^2))$$
$$= f_{p_j p_i}(-2\mu x C^* \exp(-\mu |x|^2))(4\mu^2 x_i x_j - 2\mu \delta_{ij}) C^* \exp(-\mu |x|^2).$$

Hence

$$\mathscr{L}w(x) > 0$$
 if $\frac{1}{2} < |x| < 1$ and μ sufficiently large.

Thus

$$w$$
 is an \mathscr{L} -subsolution in $B_1 \setminus B_{\frac{1}{2}}$,
 $w = 0$ on ∂B_1 ,

and, by (2.7),

10

$$w \leqslant C^* \leqslant v$$
 on $\partial B_{\frac{1}{2}}$.

Since $\mathscr{L}v < \mathscr{L}w$, the proof of the maximum principle gives

$$v(x) \ge C^* \left(\exp\left(-\mu |x|^2\right) - \exp\left(-\mu\right) \right) \ge c C^* (1 - |x|) \quad \text{in } B_1 \searrow B_{\frac{1}{2}}.$$

Recalling (2.7) we then have,

(2.9)
$$v(x) \ge cM(1-|x|)$$
 in B_1 .

Take two disjoint balls $B_{\frac{1}{2}}(y_i)$ (i = 1, 2) in $B_{\frac{1}{2}}(y)$. Let ξ vary on $\partial B_1(y)$ and denote by $l_i(\xi)$ the largest segment with endpoints ξ , $\eta_i(\xi)$, going from ξ into y_i , such that $\eta_i(\xi) \notin B_{\frac{1}{2}}(y_i)$ and $u(\eta_i(\xi)) = 0$ $(\eta_i(\xi) = \xi$ if $u(\xi) > 0)$. Denote by S_i the union of all the segments $l_i(\xi)$, and let $S = S_1 \cup S_2$.

As in [1; Lemma 1.3] we get, using (2.9),

$$eM|S| \leqslant \int_{S} |\nabla(u-v)| \leqslant |S|^{\frac{1}{2}} \left\{ \int_{S} |\nabla(u-v)|^{2} \right\}^{\frac{1}{2}},$$

so that

$$M^2|S| \leq C \int_{S} |\nabla(u-v)|^2 \leq C \int_{B_1(y)} \lambda^2 I_{\{u=0\}}$$

where (2.6) was used. Since $S \supset \{u = 0\} \cap B_1(y)$, we deduce that $M^2 \leq C\lambda^2$ and the assertion of the lemma follows.

THEOREM 2.3. $u \in C^{0,1}(\Omega)$; moreover, for any domain $D \subset \Omega$ containing a free boundary point the Lipschitz coefficient of u in D is estimated by $C\lambda$ where C depends on n, β, D and Ω only.

PROOF. Suppose $d(x) < \frac{1}{3} \operatorname{dist}(x, \partial \Omega)$. By Lemma 2.2 applied to

$$ilde{u}(x') = rac{1}{d(x)} u(x+d(x)x')$$

we have

$$\tilde{u}(x') \leqslant C\lambda$$
 in B_1 .

By elliptic estimates (e.g. Lemma 1.7) we then get

$$|\nabla \tilde{u}(0)| \leq C\lambda$$
,

that is, $|\nabla u(x)| \leq C\lambda$. Thus, for any domain $D \subset \Omega$, $|\nabla u(x)|$ is bounded in $D \cap E_+ \cap N$ where N is a small neighborhood of the free boundary. Since further $u \in C^{2+\alpha}$ in E^+ , it follows that $u \in C^{0,1}(\Omega)$.

To prove the second part of the theorem, consider any domains $D \subset D' \subset \Omega$, D containing free boundary points. We shall prove that

$$(2.10) |\nabla u(x)| < C\lambda$$

for all $x \in D \cap E_+$ with C depending only on n, β, D, D' and Ω .

Let $r_0 = \frac{1}{3} \operatorname{dist} (D', \partial \Omega) \ x \in D'$. We argue as in [1; Theorem 4.3]. Since D' is connected and not contained in E_+ , we find a sequence of points x_0, \ldots, x_k in D' (k depending only on D' and Ω) with

$$x_j \in B_{r_0/2}(x_{j-1})$$
 for $j = 1, ..., k$,

such that $x_0 = x$, $B_{r_0}(x_j)$ is contained in E_+ for j = 0, ..., k-1, and such that $B_{r_0}(x_k)$ is not contained in E_+ . By Lemma 2.2,

$$u(x_k) \leqslant C \lambda r_0$$
.

Since u is a \mathscr{L} -solution in each $B_{r_o}(x_j)$, j = 0, ..., k-1, we have, by Harnack's inequality [6; p. 189],

$$u(x_{j+1}) \geqslant cu(x_j)$$

Inductively we then obtain

$$u(x) = u(x_0) \leqslant C \lambda r_0$$
 for all $x \in D'$.

Now let $x \in D \cap E_+$. If $d(x) > r_1 \equiv \frac{1}{2} \operatorname{dist}(D, \partial D')$, then

$$|\nabla u(x)| \leq \frac{C}{r_1} \sup_{D'} u < C\lambda$$

by the uniform estimate on u in D'. On the other hand, if $d(x) < r_1$ then $|\nabla u(x)| \leq C\lambda$ by Lemma 2.2. This completes the proof of the theorem.

As a consequence of Theorem 2.1 we shall prove:

LEMMA 2.4. For any domain $D \subset \Omega$ there exists a constant C (depending only on n, β, D and Ω) such that for any absolute (local) minimum u and for

any (small) ball $B_r \subset D$

12

(2.11)
$$if \ \frac{1}{r} \int_{\partial B_r} u \ge C\lambda \quad then \ u > 0 \ in \ B_r.$$

PROOF. If B_r contains a free boundary point then $|\nabla u| \leq C\lambda$ in B_r , by the proof of Theorem 2.3, with *C* depending on n, β, D and Ω only. Since *u* vanishes at some point of B_r we conclude that

$$u \leqslant C\lambda r$$
 in $\overline{B_r}$,

which contradicts (2.11) if C in (2.11) is large enough.

We next state a nondegeneracy lemma.

LEMMA 2.5. For any p > 1 and for any $0 < \varkappa < 1$ there exists a constant c_{\varkappa} such that for any global (local) minimum and for any (small) ball $B_r \subset \Omega$

PROOF. Take for simplicity r = 1; otherwise we work with a scaled function. Set

$$\varepsilon = \frac{1}{\sqrt{\varkappa}} \sup_{B_{\sqrt{\varkappa}}} u$$
.

By the L^{∞} estimate of [6; p. 184],

$$\varepsilon < C \left(\oint_{B_1} u^p \right)^{1/p}.$$

Consider the function

$$v = \begin{cases} C_1 \varepsilon (\exp\left[-\mu |x|^2\right] - \exp\left[-\mu x^2\right]) & \text{in } B_{\sqrt{x}} \backslash B_x \\ 0 & \text{in } B_x, \end{cases}$$

By (2.8), $\mathscr{L}v < 0$ in $B_{\sqrt{\varkappa}} \setminus B_{\varkappa}$ if μ is small enough; that is, v is a supersolution. We choose C_1 such that

$$v = \sqrt{\varkappa} \varepsilon \geqslant u$$
 on $\partial B_{\sqrt{\varkappa}}$.

Then min (u, v) is an admissible function and therefore

$$J(u) \ll J(\min(u, v)),$$

which gives

$$\int_{B_{\varkappa}} (f(\nabla u)) + \lambda^2 I_{\{u>0\}} \leq \int (f(\nabla \min(u, v)) + \lambda^2 I_{\{\min(u, v)>0\}})$$

or

$$\begin{split} \int_{B_{\sqrt{x}}} (f(\nabla u) + \lambda^2 I_{\{u > 0\}}) &\leq \int (f(\nabla \min (u, v)) - f(\nabla u)) \\ &\leq \int_{B_{\sqrt{x}} \setminus B_{x}} \nabla (\min (u, v) - u) \cdot f_{\nu} (\nabla \min (u, v)) \\ &= -\int_{B_{\sqrt{x}} \setminus B_{x}} \nabla \max (u - v, 0) \cdot f_{\nu} (\nabla v) \\ &\leq \int_{B_{\sqrt{x}} \setminus B_{x}} u f_{\nu} (\nabla v) \cdot \nu , \end{split}$$

where we have used the fact that v is a supersolution. Since also

$$\frac{\partial v}{\partial v} \leqslant C \varepsilon$$
 on ∂B_{\varkappa}

we find that

(2.13)
$$\int_{B_{\star}} (f(\nabla u) + \lambda^2 I_{\{u>0\}}) < C \varepsilon \int_{\partial B_{\star}} u.$$

On the other hand we can estimate the last integral by (cf. [1])

$$\frac{C}{\lambda}\left(\frac{\varepsilon}{\lambda}+1\right)\int\limits_{B_{\varkappa}}(|\nabla u|^{2}+\lambda^{2}I_{\{u>0\}}) \leq \frac{C}{\lambda}\left(\frac{\varepsilon}{\lambda}+1\right)\int\limits_{B_{\varkappa}}(f(\nabla u)+\lambda^{2}I_{\{u>0\}})$$

Taking ε/λ sufficiently small we then obtain

$$\int\limits_{B_{\star}} (|
abla u|^2 + \lambda^2 I_{\{u>0\}}) = 0 \; ,$$

that is u = 0 in B_{κ} .

REMARK 2.6. Lemma 2.5 remains true if B_r is not contained in Ω provided u = 0 in $B_r \cap \partial \Omega$. Lemma 2.4 also remains true if B_r is not contained in Ω

provided $B_{xr} \subset \Omega$, u = 0 on $B_r \cap \partial \Omega$, and $B_r \cap \partial \Omega$ is smooth, that is any point of $\partial B_r/B_{er}(\partial \Omega)$ can be connected with the center of B_r by a tube with thickness of order er and length of order r). Then the statement (2.11) is replaced by:

$$\frac{1}{r} \oint_{\partial B_r \setminus B_{sr}(\partial \Omega)} u \ge C(\varepsilon, \varkappa) \lambda \quad \text{which implies } u > 0 \text{ in } B_{\varkappa r},$$

for any given $\varepsilon > 0$, $\varkappa < 1$; Theorem 2.3 is also valid in $B_r \cap \overline{\Omega}$.

COROLLARY 2.7. For any domain $D \subset \Omega$ there exist positive constants c, C such that if $B_r(x)$ is a ball in $D \cap \{u > 0\}$ touching $\partial \{u > 0\}$, then

$$cr \leqslant u(x) \leqslant Cr$$
.

THEOREM 2.8. For any $D \subset \Omega$ there exists a constant c, 0 < c < 1, such that for any absolute (local) minimum u and for any (small) ball $B_r \subset D$ with center in the free boundary,

$$(2.14) c < \frac{\mathfrak{L}^n(B_r \cap \{u > 0\})}{\mathfrak{L}^n(B_r)} < 1 - c;$$

c depends on D, but not on λ .

14

PROOF. By Lemma 2.5 there exists $y \in B_r$ with $u(y) > c\lambda r$. Using Lipschitz continuity we get

$$\int_{\partial B_{xr}(y)} u \geq \frac{c\lambda}{2} r$$

if \varkappa is small enough. Hence

$$\frac{1}{\varkappa r} \oint_{\partial B_{xr}(y)} u \geq \frac{c\lambda}{2\varkappa},$$

which implies, by Lemma 2.4, that u > 0 in $B_{xr}(y)$. This gives the lower estimate in (2.14).

Next, let v be as in (2.1). Then, by (2.3),

(2.15)
$$\lambda_{B_{r}}^{2} \int_{B_{r}} I_{\{u>0\}} \geq c \int_{B_{r}} |\nabla(u-v)|^{2} \geq \frac{c}{r^{2}} \int_{B_{r}} |u-v|^{2},$$

where Poincaré's inequality was used. If $y \in B_{\varkappa r}$ (\varkappa small) then, by Harnack's

inequality and Lemma 2.5,

$$v(y) \ge c \left(\oint_{B_{\tau/2}} u^2 \right)^{1/2} \ge c \lambda r .$$

By Lipschitz continuity of u we also have

$$u(y) \leqslant C \lambda \varkappa r$$
.

Therefore

$$(v-u)(y) \geqslant c\lambda r$$

if \varkappa is small enough. Substituting this into the right-hand side of (2.15) we find that

$$\int_{B_r} I_{\{u=0\}} \ge \frac{c}{\lambda^2 r^2} \int_{B_{xy}} |u-v|^2 \ge \frac{c}{r^2} r^{n+2} = cr^n$$

and the upper estimate in (2.14) follows.

REMARK 2.9. Theorem 2.8 implies that $\mathfrak{L}^n(\partial \{u > 0\}) = 0$.

3. – The measure $\Lambda = \mathscr{L}u$ and the function q.

In Theorem 1.9 we proved that the free boundary condition

$$\varPhi(|
abla u|^2) = \lambda^2$$

is satisfied in a very weak sense. Since $\Phi(0) = 0$ and (by (1.2)) $\Phi' \ge c > 0$ there is a unique value $\lambda^* > 0$ with

(3.1)
$$\Phi(\lambda^{*2}) = \lambda^2.$$

Hence the free boundary condition can be written as

$$|\nabla u| = \lambda^*$$
,

 \mathbf{or}

(3.2)
$$-f_{\nu}(\nabla u)\cdot v = -2\frac{\partial u}{\partial \nu}F'(|\nabla u|^2) = Q,$$

if

$$(3.3) Q \equiv 2\lambda^* F'(\lambda^{*2}) .$$

We shall prove (3.3) in the sense that

$$\nabla \cdot f_p(\nabla u) = Q H^{n-1} \mathfrak{L} \partial \{u > 0\} \text{ in } \Omega,$$

where, of course, we need the fact that the free boundary $\partial \{u > 0\}$ is (n-1)-dimensional. This we will show first.

By Lemma 1.2,

$$\nabla \cdot f_p(\nabla u) = A$$

where Λ is a positive Radon measure supported on the free boundary

$$\Gamma = \partial \{u > 0\} \cap \Omega .$$

In the sequel we shall not indicate the explicit dependence of constants upon λ .

THEOREM 3.1. For any $D \subset \Omega$ there exist positive constants c, C such that for any ball $B_r \subset D$ with center in the free boundary

$$(3.4) cr^{n-1} \leq \int_{B_r} d\Lambda \leq Cr^{n-1} .$$

PROOF. Let $\zeta \in C_0^{\infty}(\Omega)$, $\zeta \ge 0$. Then

$$\int_{\Omega} \zeta d\Lambda = \int_{\Omega} \nabla \zeta \cdot f_{\nu}(\nabla u) \; .$$

Approximating I_{B_r} from below by suitable test functions ζ we get, using the Lipschitz continuity u, that for almost all r,

$$\int_{B_r} dA = \int_{\partial B_r} v \cdot f_p(\nabla u) \, dH^{n-1} \leqslant Cr^{n-1} \, .$$

To establish the left-hand side of (3.4) we may normalize by taking r = 1. Set

$$\widetilde{\mathscr{Q}}v =
abla \cdot (a
abla v) \qquad \left(a(x) = F'(|
abla u(x)|^2)
ight)$$

This is a linear selfadjoint uniformly elliptic operator. Denote its Green's function in B_1 with pole x by G_x . By [6; p. 184], if

$$egin{array}{lll} egin{array}{ccc} egin{array}{ccc} egin{array}{cccc} eta v = f & ext{in } B_1\,, \ v = 0 & ext{on } \partial B_1\, \end{array} \end{array}$$

then

(3.5)
$$|v|_{L^{\infty}(B_{1/2})} \leq C|f|_{L^{p}(B_{1})} \quad \text{if } p > \frac{n}{2}.$$

Representing v in terms of Green's function we deduce that (3.5) for all f means

(3.6)
$$\sup_{x \in B_{1/2}} \int_{B_1} G_x^q < C \qquad \left(\frac{1}{q} + \frac{1}{p} = 1\right).$$

Now let $x \in B_{\frac{1}{2}} \setminus \overline{B}_{\frac{1}{2}}$. Then $\widetilde{\mathscr{D}}G_x = 0$ in $B_{\frac{1}{2}}$ and, by (3.6), G_x is bounded in $L^q(B_{\frac{1}{2}})$. Hence, by elliptic estimates [6; p. 184]

$$G_x(y) \leqslant C \quad \text{if } y \in B_{\frac{1}{4}}, \ x \in B_{\frac{1}{4}} \setminus B_{\frac{1}{4}},$$

and by the symmetry of Green's function

$$G_{\mathbf{y}}(x) \leqslant C$$
 if $y \in G_{\frac{1}{2}}$, $x \in B_{\frac{1}{2}} \setminus B_{\frac{1}{2}}$.

Similarly

(3.7)
$$\begin{aligned} G_{y}(x) \leqslant C & \text{if } x \in D_{1}, \ y \in D_{2}, \ \text{dist} (D_{1}, D_{2}) \geqslant \delta, \\ D_{1} \cup D_{2} \subset B_{1}, & \text{dist} (D_{2}, \partial B_{1}) \geqslant \delta \end{aligned}$$

where C is a constant depending on δ but not on D_1, D_2 .

Now let w be the solution of

$$\widetilde{\mathscr{Z}}w = 0$$
 in B_1 ,
 $w = u$ on ∂B_1 .

By nondegeneracy, for any $0 < \varkappa < 1$ there exists a point $y \in B_{\varkappa}$ with $u(y) > c\varkappa$. By Lipschitz continuity,

$$u > 0$$
 in $B_{c(x)}(y)$

with c(z) sufficiently small; hence also $d\Lambda = 0$ in $B_{c(z)}(y)$. Since

$$\widetilde{\mathscr{L}}(w-u) = \Lambda$$
, $w = 0$ on ∂B_1 ,

we can write

(3.8)
$$(w-u)(y) = \int_{B_1} G_y d\Lambda = \int_{B_1 \setminus B_c(x)} G_y d\Lambda < C(x) \int_{B_1} d\Lambda$$

where we have used (3.7) with $\delta = \delta(\varkappa)$.

By the maximum principle $w \ge u$; therefore, by nondegeneracy (for p > 1)

$$\left(\oint_{B_{1/2}} w^p \right)^{1/p} \geq \left(\oint_{B_{1/2}} u^p \right)^{1/p} \geq c \qquad (c > 0) \ .$$

Using Harnack's inequality [6; p. 184], if p < n/(n-2), we get

$$w(y) \ge c \left(\int_{B_1} w^p \right)^{1/p} \ge c \; .$$

Also, since u vanishes at the center of B_1 , by Lipschitz continuity,

$$u(y) \leqslant C \varkappa.$$

Choosing \varkappa small enough we get

18

$$w(y) - u(y) \geqslant c - C \varkappa > \frac{c}{2},$$

and recalling (3.8) we obtain

$$\int_{B_1} d\Lambda \geqslant c \; .$$

The next theorem follows easily from Theorem 3.1, precisely as in [1]. THEOREM 3.2 (Representation theorem). Let u be a local minimum. Then:

- (1) $H^{n-1}(D \cap \partial \{u > 0\}) < \infty$ for every $D \subset \Omega$.
- (2) There is a Borel measure q_u such that

$$\mathscr{L} u = q_u H^{n-1} \mathfrak{L} \partial \{u > 0\}$$
 ,

that is, for every $\zeta \in C_0^{\infty}(\Omega)$

$$-\int_{\Omega} \nabla \zeta \cdot f_p(\nabla u) = \int_{\Omega \cap \partial\{u>0\}} \zeta q_u \, dH^{n-1}.$$

(3) For any $D \subset \Omega$ there exist positive constants c, C such that for every ball $B_r(x) \subset D$ with $x \in \partial \{u > 0\}$,

$$c \leq q_u(x) \leq C, \quad cr^{n-1} \leq H^{n-1}(B_r(x) \cap \partial\{u > 0\}) \leq Cr^{n-1}.$$

19

From (1) it follows [5; 4.5.11] that the set $A = \{u > 0\}$ has a finite perimenter locally in Ω , that is, $\mu_u \equiv -\nabla I_A$ is a Borel measure. We denote by $\partial_{\text{red}}A$ the reduced boundary of A, *i.e.*, the set of points $x \in \Omega$ for which the normal $\nu_u(x)$ of A at x exists and $|\nu_u(x)| = 1$; see [5] [7].

We shall deal with blow up sequences

$$u_m(x) = \frac{1}{\varrho_m} u(x_m + \varrho_m x), \quad u(x_m) = 0, \quad x_m \to x_0 \in \Omega.$$

Since $|\nabla u| \leq C$, for a subsequence,

(3.9) $u_m \to u_0$ uniformly in C_{loc}^{α} , for all $\alpha < 1$,

$$(3.10) \qquad \nabla u_m \to \nabla u_0 \quad \text{weakly star in } L^{\infty}_{\text{loc}},$$

We also have:

- $(3.11) \quad \partial \{u_m > 0\} \to \partial \{u_0 > 0\} \quad \text{locally in the Hausdorff distance},$
- $(3.12) \quad I_{\{u_m > 0\}} \quad \to I_{\{u_0 > 0\}} \quad \text{in } L^1_{\text{loc}} ,$
- $(3.13) \quad \nabla u_m \qquad \rightarrow \nabla u_0 \qquad \text{a.e.}$

The proof of (3.11) follows from (3.9) and the nondegeneracy. The same arguments show that if $x_m \in \partial \{u_m > 0\}$ then $x_0 \in \partial \{u_0 > 0\}$.

To prove (3.12) let $x \in \partial \{u_0 > 0\} \cap \Omega$. Then there exists a sequence $y_m \in \partial \{u_m > 0\}$ such that $y_m \to x$. By nondegeneracy (Lemma 2.5 with p = 2)

$$\frac{1}{r} \left(\int_{\partial B_r(y_m)} u_m^2 \right)^{1/2} > c \; .$$

Hence

$$\frac{1}{r} \left(\int_{\partial B_r(x)} u_0^2 \right)^{1/2} > c \; .$$

Since u_0 is clearly also in $C^{0,1}$, the proof of Theorem 2.8 applies to u_0 . Consequently

$$\mathfrak{L}^n(\partial \{u_0>0\})=0.$$

Combining this fact with (3.11), the assertion (3.12) follows.

By elliptic estimates

$$\nabla u_m \rightarrow \nabla u_0$$
 uniformly in compact subsets of $\{u_0 > 0\}$

and

(3.14)
$$\nabla f_{v}(\nabla u_{0}) = 0 \quad \text{in } \{u_{0} > 0\}.$$

Thus in order to prove (3.13) it remains to show that

$$(3.15) \qquad \nabla u_m \to \nabla u_0 \quad \text{a.e. on } \{u_0 = 0\}.$$

In the set $\{u_0 = 0\}$ a.a. points x_0 have density 1; denote the set of such points by S. We claim that if $x_0 \in S$ then

(3.16)
$$u_0(x_0 + x) = o(|x|)$$
.

Indeed, if $u_0(y) > \gamma r$ for some $y \in B_r(x_0)$, $\gamma > 0$ and a sequence $r \to 0$, then (by the Lipschitz continuity of u_0)

$$u_0 > \frac{\gamma}{2} r$$
 in $B_{c\gamma r}(y)$

for some small c > 0. This means that $\{u_0 > 0\}$ has positive density at x_0 , contradicting $x_0 \in S$.

From (3.16) we deduce that, for any $\varepsilon > 0$,

$$\frac{u_m}{r} < \varepsilon$$
 in $B_r(x_0)$ for small r ,

provided *m* is large enough, say $m \ge m_0(\varepsilon, r)$. By nondegeneracy it then follows that $u_m = 0$ in $B_{r/2}(x_0)$ and, consequently, $u_0 = 0$ in a neighborhood of x_0 . Thus the set S is open. Furthermore, the above argument shows that $u_m = u_0$ in any compact subset of S, if *m* is large enough. This completes the proof of (3.15).

In order to identify the function q_u in Theorem 3.2, we need the following two important statements about the minimum.

LEMMA 3.3. If $u(x_m) = 0$, $x_m \to x_0 \in \Omega$, then any blow up limit u_0 with respect to $B_{0m}(x_m)$ is absolute minimum for J in any ball.

PROOF. Let

$$u_m(x)=\frac{1}{\varrho_m}\,u(x_m+\,\varrho_m x)$$

and suppose that (3.9), (3.10) hold. Then also (3.11)-(3.13) are satisfied.

Set $D = B_R(0)$ and take any $v, v - u_0 \in H_0^{1,2}(D), \eta \in C_0^{\infty}(D), 0 \leq \eta \leq 1$. Let

$$v_m = v + (1-\eta)(u_m - u_0).$$

Since $v_m = u_m$ on ∂D ,

(3.17)
$$\int_{D} (f(\nabla u_m) + \lambda^2 I_{\{u_m > 0\}}) < \int_{D} (f(\nabla v_m) + \lambda^2 I_{\{v_m > 0\}}).$$

Since $|\nabla u_m| \leq C$, $\nabla u_m \rightarrow \nabla u_0$ a.e.,

$$\int_D f(\nabla u_m) \to \int_D f(\nabla u_0) \quad \text{as } m \to \infty.$$

Similarly

$$\int_D f(\nabla v_m) \to \int_D f(\nabla v) \; .$$

Noting also that

$$I_{\{v_m>0\}} \leqslant I_{\{v>0\}} + I_{\{\eta<1\}},$$

we obtain from (3.17)

$$\int_{D} (f(\nabla u_0) + \lambda^2 I_{\{u_0 > 0\}}) \leq \int_{D} (f(\nabla u) + \lambda^2 I_{\{v > 0\}}) + \gamma(\eta)$$

where $\gamma(\eta) = \lambda_{b}^{2} \int_{D} I_{\{\eta < 1\}}$. Choosing a sequence of η 's with $\gamma(\eta) \rightarrow 0$, the assertion follows.

Next we prove an estimate for $|\nabla u|$ at the free boundary from above (see [1; Remark 6.4]), which will also be used in Section 4, where we prove the corresponding Hölder estimate.

LEMMA 3.4. Let u be a local minimum and let λ^* be defined by (3.1). If $x_0 \in \{u > 0\}$ then

(3.18)
$$\lim_{x \to x_0, u(x) > 0} \sup |\nabla u(x)| = \lambda^*$$

PROOF. Denote the left-hand side of (3.18) by γ . Then there exists a sequence z_k such that

$$|u(z_k) > 0$$
, $|
abla u(z_k)| o \gamma$.

Denote by y_k the nearest point to z_k on $\partial \{u > 0\}$ and set $\varrho_k = |z_k - y_k|$.

Consider a blow up sequence about $B_{o_k}(y_k)$ with limit u_0 , such that

$$\frac{z_k-y_k}{\varrho_k} \to -e_n.$$

Then u_0 is \mathscr{L} -subsolution in \mathbb{R}^n and $\mathscr{L}u_0 = 0$ in $\{u_0 > 0\}$. By Lemma 3.3 the blow-up limit u_0 is an absolute minimum, hence $B_1(-e_n)$ is contained in $\{y_0 > 0\}$ by (3.12). Moreover $u_0(0) = 0$ and

$$egin{array}{ll} |
abla u_0| &\leqslant \gamma & ext{ in } \{u_0>0\} \ , \ |
abla u_0(-e_0)| &= \gamma \end{array}$$

which implies that $\gamma > 0$.

Choose a unit vector e such that

$$|\nabla u_0(-e_n)| = -\nabla u_0(-e_n) \cdot e$$

and consider the function $\partial u_0/\partial e$. We have (see the proof of Lemma 1.7)

$$\mathscr{L}_{\mathbf{0}}\left(\frac{\partial u_{\mathbf{0}}}{\partial e}\right) = 0 \quad \text{in } \{u_{\mathbf{0}} > 0\}$$

where \mathscr{L}_0 is a uniformly divergence-form elliptic operator. Also

(3.19)
$$\begin{aligned} \frac{\partial u_0}{\partial e} &> -\gamma \qquad \text{in } B_1(-e_n) ,\\ \frac{\partial u_0(-e_n)}{\partial e} &= -\gamma . \end{aligned}$$

Applying the maximum principle we conclude from (3.19) that

$$rac{\partial u_0(x)}{\partial e} = - \gamma \quad ext{ or } u_0(x) = - \gamma x \cdot e + c ext{ for } x \in B_1(-e_n) \ .$$

Since $u_0(0) = 0$ and $u_0 > 0$ in $B_1(-e_n)$, the constant c is equal to zero and $e = e_n$. Thus

$$u_0(x) = -\gamma x_n$$
 for $x \in B_1(-e_n)$.

By continuation the same argument shows that

(3.20)
$$u_0(x) = -\gamma x_n \quad \text{whenever } x_n \leq 0.$$

We next claim that

$$(3.21) u_0 = 0 in some strip \{0 < x_n < \varepsilon_0\}.$$

Indeed, suppose this is not true, and define

$$s = \lim_{\substack{x_n \downarrow 0, u_0(x', x_n) > 0 \\ x' \in \mathbb{R}^{n-1}}} \sup_{\substack{\partial u_0(x', x_n) \\ \partial x_n}} \frac{\partial u_0(x', x_n)}{\partial x_n}.$$

By Lipschitz continuity of u, u_0 is uniformly Lipschitz continuous and thus $s < \infty$. Suppose s > 0 and let

$$\frac{\partial u_0}{\partial x_n}(y_k, h_k) \to s , \qquad h_k \downarrow 0 .$$

Consider a blow up sequence with respect to $B_{h_k}(y_k, 0)$ with limit u_{00} . Arguing as before we conclude that

$$u_{00}(x', x_n) = sx_n \quad \text{for all } x_n > 0 .$$

But we also have (by (3.20))

$$u_{00}(x', x_n) = -\gamma x_n$$
 for all $x_n < 0$.

Thus, u_{00} is a minimum (Lemma 3.3), and any point (x', 0) is a free boundary point. It follows that the set $\{u_{00} = 0\}$ has density zero at any point (x', 0), a contradiction to Theorem 2.8.

We have thus proved that s = 0 and, consequently, $u_0(x', x_n) = o(x_n)$ if $x_n \neq 0$. Hence, for any $\varepsilon > 0$,

$$\frac{1}{r} \left(\int_{B_r(x_0)} u_0^2 \right)^{1/2} < \varepsilon$$

for any $x_0 = (y_0, h_0)$, $r = h_0$, with h_0 small enough. It follows, by nondegeneracy, that $u_0 = 0$ in some strip $\{0 < x_n < \varepsilon_0\}$, which contradicts the assumption that (3.21) was not satisfied.

Having proved (3.20), (3.21) we can now apply Theorem 1.9 to deduce that, on the free boundary $\{x_n = 0\}$, $|\nabla u_0|$ coincides with λ^* , *i.e.*, $\gamma = \lambda^*$.

In the next statement we use the following notation (see [5; 3.1.21]). For any set E and $x_0 \in E$ we define the (topological) tangent plane of E

at x_0 by

$$\operatorname{Tan}(E, x_0) = \left\{ v; v = \lim_{m \to 0} r_m v_m, r_m > 0, x_0 + v_m \in E, v_m \to 0 \right\}.$$

THEOREM 3.5 (Identification of q_u). Let $x_0 \in \partial_{red} \{u > 0\}$ and suppose that

$$heta^{st n-1}(H^{n-1}\mathfrak{L}\partial\{u>0\},x_{\scriptscriptstyle 0})\!\leqslant\! 1$$
 .

Then Tan $(\partial \{u > 0\}, x_0) = \{x; x \cdot v_u(x_0) = 0\}$. If, in addition,

$$\int_{B_r(x_0) \cap \partial\{n>0\}} |q_u - q_u(x_0)| \, dH^{n-1} = o(r^{n-1}) \quad as \ r \to 0$$

then, $q_u(x_0) = Q$ and, as $x \to 0$,

(3.22)
$$u(x_0 + x) = \lambda^* \max \{-x \cdot \nu_u(x_0), 0\} + o(|x|),$$

where λ^* , Q are defined as in (3.1) and (3.2).

PROOF. Take for simplicity $\nu_u(x_0) = e_n$. Let u_m be a blow up sequence with respect to balls $B_{e_m}(x_0)$, with blow up limit u_0 . Then $I_{\{u_m>0\}}$ converges in L^1_{loc} to $I_{\{u_0>0\}}$ (by (3.12)) and to $I_{\{u_n>0\}}$ since,

$$\int_{B_r(x)} |I_{\{u>0\}} - I_{\{u: (v-r_0) \cdot v_u(x_0) > 0\}}| = o(r^n) \quad \text{as } r \to 0 ,$$

if $v_u(x_0)$ is the normal to $\{u > 0\}$ at x_0 . It follows that $u_0 = 0$ in $\{x_n \ge 0\}$ and $u_0 > 0$ a.e. in $\{x_n < 0\}$.

In order to show that $u_0 > 0$ in $\{x_n < 0\}$, we proceed as in [1; p. 121] to deduce that

$$H^{n-1}(\partial \{u_m > 0\} \cap D) \to 0 \quad \text{if } m \to \infty,$$

for any $D \subset \{x_n < 0\}$. We then conclude that for any $\zeta \in C_0^{\infty}(D)$

$$(3.23) \quad -\int_{D} f_{p}(\nabla u_{0}) \cdot \nabla \zeta \leftarrow -\int_{D} f_{p}(\nabla u_{m}) \cdot \nabla \zeta = \int_{\partial \{u_{m} > 0\}} \zeta(x) q_{u}(x_{0} + \varrho_{m}x) dH^{n-1}(x) \to 0$$

where (3.13) was used. Thus u_0 is a solution of $\mathscr{L}u_0 = 0$ and it is therefore smooth in $\{x_n < 0\}$ (Lemma 1.7). The maximum principle now implies that $u_0 > 0$ in $\{x_n < 0\}$. Now let

$$\zeta(x) = \min\left(2\left(1-\frac{|x_n|}{2}\right), 1\right) \, \eta(x_1, ..., x_{n-1})$$

where $\eta \in C_0^{\infty}(B'_r)$, $\eta \ge 0$ (B'_r) is an (n-1)-dimensional ball with radius r). Proceeding as in [1; p. 121] and using also (3.13), we get

(3.24)
$$\int_{\mathbb{R}^n} f_p(\nabla u_0) \cdot \nabla \zeta = -\lim_{m \to \infty} \int_{\mathbb{R}^n} f_p(\nabla u_m) \cdot \nabla \zeta$$
$$= \lim_{m \to \infty} \int_{\partial \{u_m > 0\}} \zeta q_u(x_0 + \varrho_m x) \, dH^{n-1} = q_u(x_0) \int_{\mathbb{R}^{n-1}} \eta \, dH^{n-1} \, .$$

Notice that, unlike in (3.23), the test functions here are not supported just in $\{x_n < 0\}$. From (3.24) we deduce the boundary conditions

(3.25)
$$f_{p}(\nabla u_{0}) \cdot e_{n} = q_{u}(x_{0}) \text{ on } \{x_{n} = 0\}$$

in the sense that

$$-\int_{B_r \cap \{x_n > 0\}} f_p(\nabla u_0) \cdot \nabla \zeta = q_u(x_0) \int_{B'_r} \zeta(x', 0) \, dH^{n-1} \qquad \forall \zeta \in C_0^1(B_r) \, .$$

Since $\mathscr{L}u_0 = 0$ in $\{x_n < 0\}$, by boundary regularity for elliptic equations (see proof of Lemma 1.7) it follows that u_0 satisfies (3.25) in the classical sense.

Since furthermore u_0 is an absolute minimum (Lemma 3.3) we deduce from Theorem 1.9 that

(3.26)
$$\frac{\partial u_0}{\partial \nu} = -\lambda^* \quad \text{on } \partial \{x_n < 0\},$$

or $q_u(x_0) = Q$.

We have to show that u_0 is a half plane solution with slope λ^* . To prove this we use Lemma 3.4, which tells us that

$$0 < u_0(x) \leqslant -\lambda^* x_n \quad \text{if } x_n < 0 ,$$

and $\widetilde{\mathscr{J}}u_0 = 0$ in $\{u_0 < 0\}$, where

$$\widetilde{\mathscr{P}} w = f_{p_i p_j} (\nabla u_0) \, \partial_{ij} w$$
.

Therefore, the function

$$v(x) \equiv -\lambda^* x_n - u_0(x)$$

is nonnegative in $\{x_0 < 0\}$ and $\tilde{\mathscr{P}}v = 0$. Hence, if v is positive at some point in $\{x_n < 0\}$, it must be positive everywhere in $\{x_n < 0\}$, by the maximum principle, and, further,

$$\frac{\partial v}{\partial \nu} < 0 \qquad \text{on } \partial \{x_n < 0\} ,$$

that is, $\partial u_0/\partial \nu > -\lambda^*$, which contradicts (3.26). Consequently $\nu = 0$ in $\{x_n < 0\}$, that is,

$$u_0(x) = \begin{cases} -\lambda^* x_n & \text{for } x_n < 0, \\ 0 & \text{for } x_n \ge 0. \end{cases}$$

Since finally the blow up sequence was arbitrary whereas the limit is unique, the assertion (3.22) follows.

Since the conclusion of Theorem 3.5 holds for H^{n-1} a.a. $x_0 \in \hat{c}_{red} \{ u > 0 \}$ we obtain:

THEOREM 3.6. For H^{n-1} a.a. x in $\hat{c}_{red}\{u > 0\}$

$$q_u(x) = Q \; .$$

REMARK 3.7. From the positive density property (Theorem 2.8 and [5; 4.5.6 (3)] it follows that $H^{n-1}(\{u > 0\} \setminus \hat{c}_{red}\{u > 0\}) = 0$. Hence

(3.27)
$$q_u = Q \quad H^{n-1} \text{ a.e. on } \partial \{u > 0\}.$$

4. – Estimates on $|\nabla u|$.

 $\mathbf{26}$

For the regularity theory of the free boundary we need the following strengthened version of Lemma 3.4.

THEOREM 4.1. Let u be a local minimum. For any $D \subset \Omega$ there exist positive constants C, $\alpha < 1$ depending only on β , λ and D such that, for any ball $B_r(x) \subset D$ which intersects the free boundary,

(4.1) $\sup_{B_r(x)} |\nabla u(x)| \leq \lambda^* + Cr^{\alpha}$

PROOF. We have

$$a_{ij}(\nabla u)\partial_{ij}u = 0 \quad \text{in } \{u > 0\}$$

where the uniformly positive and bounded matrix a_{ij} is defined as in (1.9).

Therefore, by [6; pp. 270-271], the function $v = |\nabla u|^2$ satisfies

(4.2)
$$\mathcal{M}v \equiv \partial_i (\exp{(\gamma v)} a_{ij} (\nabla u) \partial_j v) \ge 0 \quad \text{in } \{u > 0\}$$

where γ is some positive constant. For any $\varepsilon > 0$, the function

$$U_{\varepsilon} = (|\nabla u|^2 - (\lambda^*)^2 - \varepsilon)^+$$

is M-subsolution in $\{u > 0\}$ and, by Lemma 3.4, it vanishes in a neighborhood of the free boundary. We extend U_{ε} by 0 into $\{u = 0\}$ and set

$$h_{\varepsilon}(r) = \sup_{B_r} U_{\varepsilon}$$

for any r, where the origin is taken to be a free boundary point. Then $h_{\varepsilon}(r) - U_{\varepsilon}$ is \mathcal{M} -supersolution in the entire ball B_r and

$$egin{aligned} h_arepsilon(r) &- U_arepsilon \geqslant 0 & ext{ in } B_r \ &= h_arepsilon(r) & ext{ in } ilde{B}_r = B_r \cap \{u=0\} \;. \end{aligned}$$

By [6; p. 193] with $1 \le p < n/(n-2)$,

$$\inf_{B_{r/2}} [h_{\varepsilon}(r) - U_{\varepsilon}(x)] \ge cr^{-n/p} \|h_{\varepsilon} - U_{\varepsilon}\|_{L^{p}(B_{r})} \ge ch_{\varepsilon}(r) ,$$

since $\mathfrak{L}^n(\tilde{B}_r) \ge cr^n$ by the positive density property (Theorem 2.8). Taking $\varepsilon \to 0$ we get

$$\inf_{B_{r/2}} [h_0(r) - U_0] \ge c h_0(r) \qquad (0 < c < 1)$$

 \mathbf{or}

$$\sup_{B_{r/2}} U_0 \leq (1-c) h_0(r) \, .$$

Thus

$$h_0\left(\frac{r}{2}\right) \leqslant (1-c) h_0(r) ,$$

from which we deduce that $h_0(x) \leq Cs^{\alpha}$ for some C > 0, $0 < \alpha < 1$, and (4.1) follows.

REMARK 4.2. If, in Theorem 4.1, $B_r(x) \subset B_R(x) \subset D$ then

(4.3)
$$\sup_{B_r} |\nabla u| \leq \mu + C \left(\frac{r}{R}\right)^{\alpha}.$$

Indeed, this follows by applying Theorem 4.1 to $\tilde{u}(x') = (1/R)u(x + Rx')$.

THEOREM 4.3. Let n = 2 and assume that u is any local minimum and that $D \subset \subseteq \Omega$. Then for any small ball $B_r \subset D$ with center in the free boundary,

(4.4)
$$\int_{B_r \cap \{u > 0\}} (\lambda^{*2} - |\nabla u|^2)^+ \leqslant \frac{C}{\log(1/r)}.$$

PROOF. For any $\zeta \in C_0^{\infty}(\Omega)$, $\zeta \ge 0$, $\varepsilon > 0$, the function

$$v \equiv u - \min(u, \varepsilon \zeta) = \max(u - \varepsilon \zeta, 0)$$

is admissible, so that $J(u) \leq J(v)$, or

(4.5)
$$\int_{\{0 < u \leq e\zeta\}} \lambda^2 = \int [f(\nabla v) - f(\nabla u)] \equiv I.$$

We have

$$f(\nabla v) - f(\nabla u) = \int_0^1 f_p(\nabla u + t\nabla(v - u)) \cdot \nabla(v - u) dt$$

= $f_p(\nabla u) \cdot \nabla(v - u) + \int_0^1 dt \int_0^t \nabla(v - u) f_{pp}(\nabla u + s\nabla(v - u)) \nabla(v - u) ds$.

On the set $\{u > \varepsilon \zeta\}$ we have $v - u = -\varepsilon \zeta$, hence

$$\int_{\{u>\varepsilon\zeta\}}\int_{0}^{1}dt\int_{t}^{1}\nabla(v-u)f_{pp}(\nabla u+s\nabla(v-u))\nabla(v-u)\,ds \leq C\varepsilon^{2}\int_{\{u>\varepsilon\zeta\}}|\nabla\zeta|^{2}\,.$$

On the set $\{u \leq \varepsilon \zeta\}$ we have v = 0 and thus

$$\int_{\{u \leq s\zeta\}} \int_{0}^{1} dt \int_{0}^{t} \nabla(v-u) f_{pp} (\nabla u + s \nabla(v-u)) ds = \int_{\{u \leq s\zeta\}} \int_{0}^{1} dt \int_{t}^{1} \nabla u f_{pp} ((1-s) \nabla u) \nabla u ds.$$

 \mathbf{Next}

$$0 = -f(0) = f(\nabla u) - \int_{0}^{1} f_{p}((1-t)\nabla u) \cdot (\nabla u) dt$$

= $f(\nabla u) - f_{p}(\nabla u) \cdot \nabla u + \int_{0}^{1} dt \int_{0}^{t} \nabla u f_{pp}((1-s)\nabla u)(-\nabla u) ds.$

29

Combining these facts we find that

$$I \leq \int_{\{u \leq \varepsilon\zeta\}} (f_p(\nabla u) \cdot \nabla u - f(\nabla u)) + C\varepsilon^2 \int_{\{u > \varepsilon\zeta\}} |\nabla \zeta|^2 + \int_{\Omega} f_p(\nabla u) \nabla (v - u) dv$$

In the last integral the integrand vanishes on the set $\{u = 0\}$. Since also v - u = 0 on $\partial \{u > 0\}$ and $\nabla \cdot f_{\nu}(\nabla u) = 0$ on $\{u > 0\}$, this integral vanishes. (for a rigorous proof approximate v - u by $-\min(u - \delta, \varepsilon\zeta)$ for $\delta > 0$.) We thus obtain from (4.5) and (3.1), (1.10),

(4.6)
$$\int_{\{0 < u \le \varepsilon\zeta\}} \Phi(\lambda^{*2}) \ll \int_{\{0 < u \le \varepsilon\zeta\}} \Phi(|\nabla u|^2) + C\varepsilon^2 \int_{\{u > \varepsilon\zeta\}} |\nabla \zeta|^2.$$

This is true for any $n \ge 2$.

Now we specialize to n = 2, and take $B_r \subset B_e \subset B_R$ with center x_0 in the free boundary. Thus $u \leq Cr$ in B_r . Choosing $\varepsilon = Cr$ and

$$\zeta(x) = \begin{cases} \frac{\log(\varrho/|x-x_0|)}{\log(\varrho/r)} & \text{for } x \in B_{\varrho} \setminus B_{r}, \\ 1 & \text{for } x \in B_{r}, \end{cases}$$

we get

$$\int_{B_r \cap \{u>0\}} (\varPhi(\lambda^{*2}) - \varPhi(|\nabla u|^2))^+ \leq \int_{B_\varrho} (\varPhi(|\nabla u|^2) - \varPhi(\lambda^*))^+ + \frac{Cr^2}{\log(\varrho/r)}.$$

Using Remark 4.2 and the estimate $c \leq \Phi' \leq C$ (c, C positive) we find that

$$\frac{1}{r^2} \int_{B_r \cap \{u>0\}} (\lambda^{*2} - |\nabla u|^2)^+ \leq C \left(\frac{\varrho}{r^2}\right)^2 \left(\frac{\varrho}{R}\right)^{\alpha} + \frac{C}{\log(\varrho/r)}.$$

Choosing $R = \varrho^{\frac{1}{2}}$, $\varrho = r^{\varepsilon}$ with $\varepsilon > 1$, $(2 + \alpha/2)\varepsilon > 2$, we get (4.4).

COROLLARY 4.4. Let n = 2 and let u be a local minimum. Then every blow up limit of u at $x_0 \in \partial \{u > 0\} \cap \Omega$ is a half plane solution with slope λ^* in some neighborhood of the origin.

PROOF. - From Theorems 4.1, 4.3 we see that, for any blow up limit u_0 , with respect to balls $B_{\rho_m}(x_0)$,

$$|\nabla u_0| = \lambda^* \quad \text{in } \{u_0 > 0\} .$$

Now let us use the fact that $v = |\nabla u_0|^2$ is an M-subsolution (see (4.2)),

which implies (if γ is large enough in (4.2)) that

 $\mathcal{M}v \ge c |D^2 u_0|^2$

for some small positive constant c. Since $v = \lambda^{*2}$ we conclude that u_0 is linear in each connected component of $\{u_0 > 0\}$, therefore

$$u_0(x) = q_0 \max(-x \cdot v_0, s_0) + q_1 \max(x \cdot v_0, s_1)$$

for some unit vector ν_0 and some numbers $q_k > 0$, $0 \leq s_k \leq \infty$, k = 0, 1. Since the origin is a free boundary point, we may assume that $s_0 = 0$.

Since $\{u_0 = 0\}$ has positive density at the origin (by Lemma 3.3 and Theorem 2.8) we must have $s_1 > 0$. By Theorem 1.9 we also have $q_0 = \lambda^*$.

5. - Flat free boundary points.

30

DEFINITION 5.1. Let $0 < \sigma_+$, $\sigma_- \leq 1$ and $\tau > 0$. We say that u belongs to class $F(\sigma_+, \sigma_-; \tau)$ in $B_{\varrho} = B_{\varrho}(0)$ if u is a local minimum in $B_{\varrho}(0)$ with $0 \in \partial \{u > 0\}$, and

(5.1)
$$u(x) = 0 \qquad \text{for } x_n \ge \sigma_+ \varrho ,$$

 $(5.2) u(x) \ge -\lambda^*(x_n + \sigma_{-\varrho}) for x_n \le -\sigma_{-\varrho},$

$$|\nabla u| \leq \lambda^* (1+\tau) \qquad \text{in } B_{\varrho} \,.$$

If the origin is replaced by x_0 and the direction of flatness e_n is replaced by a unit vector ν , then we say that u belongs to the class $F(\sigma_+, \sigma_-; \tau)$ in $B_{\varrho}(x_0)$ in direction ν .

THEOREM 5.1. There exists a positive constant C = C(n) such that, for any small $\sigma > 0$, if $u \in F(\sigma, 1; \sigma)$ in B_{ϱ} then $u \in F(2\sigma, C\sigma; \sigma)$ in $B_{\alpha/2}$.

Thus flatness from above implies flatness from below. In proving the theorem we shall need:

LEMMA 5.2. If B is a ball in $\{u = 0\}$ touching $\partial \{u > 0\}$ at x_0 , then

(5.4)
$$\limsup_{x \to x_0} \frac{u(x)}{\operatorname{dist}(x, B)} = \lambda^* .$$

PROOF. Denote the left-hand side by l and let $y_k \rightarrow x_0$, $u(y_k) > 0$, $d_k = \text{dist}(y_k, B)$,

$$\frac{u(y_k)}{d_k} \rightarrow l$$

By nondegeneracy l > 0. Consider a blow up sequence u_k with respect to $B_{d_k}(x_k)$ where x_k is a point on ∂B with $|x_k - y_k| = d_k$.

For a subsequence,

$$rac{x_k-y_k}{d_k} o e \,, \qquad u_k o u_0 \,.$$

We claim that

(5.5) $u_0(x) = l \max(-x \cdot e, 0)$.

Indeed, we have

$$\widetilde{\mathscr{I}} u_0 = 0$$
 in $\{u_0 > 0\}$

where

$$\widetilde{\mathscr{P}}w \equiv f_{p_ip_j}(\nabla u_0)\partial_{ij}w$$

is a uniformly elliptic operator. Thus

$$\widetilde{\mathscr{L}}(u_0(x) + lx \cdot e) = 0 \quad \text{for } x \in \{u_0 > 0\}$$

and by construction $u_0(x) + lx \cdot e < 0$ when $x \cdot e < 0$, and $u_0(x) + lx \cdot e = 0$ for x = -e. The maximum principle yields that (5.5) holds for x near -e, and then by analytic continuation, the same argument shows that (5.5) holds if $x \cdot e < 0$. If $x \cdot e > 0$ then $u_0(x) = 0$ by construction, so that again (5.5) holds.

Since u_0 is an absolute minimum by Lemma 3.3, we deduce from (5.5) and Theorem 1.9 that $l = \lambda^*$.

PROOF OF THEOREM 5.1. By homogeneity we may assume that $\rho = 1$, $\lambda^* = 1$. Let

$$egin{aligned} &\eta(y) = \exp\left(\!-rac{9|y|^2}{1-9|y|^2}
ight) & ext{ for } |y| \! < \!rac{1}{3} \ &= 0 & ext{ for } |y| \! > \!rac{1}{3}, \end{aligned}$$

and choose $s \ge 0$ maximal such that

$$B_1 \cap \{u > 0\} \subset D \equiv D_{\sigma} \equiv \{x \in B_1; x_n < \sigma - s\eta(x')\}$$

where $x = (x', x_n)$. Thus there exists a point

$$z \in B_{\frac{1}{2}} \cap \partial D \cap \partial \{u > 0\}.$$

Also, $s < \sigma$ since $0 \in \partial \{u > 0\}$.

We will prove an estimate for $u(\xi)$ from below for points $\xi \in \partial B_{\frac{3}{4}}$, $\xi_n < -\frac{1}{2}$. For that consider the solution v of

$$\begin{split} \mathscr{L} v &=
abla \cdot ig(f_{s}(
abla v) ig) = 0 & ext{in} & D igarrow \overline{B(\xi)} \ , \ v &= 0 & ext{on} & \partial D \cap B_{1} \ , \ v &= (1+\sigma)(\sigma-x_{n}) & ext{on} & \partial D igarrow B_{1} \ , \ v &= -(1-arkappa \sigma) x_{n} & ext{on} & \partial B(\xi) \ , \end{split}$$

where $B(\xi) = B_{\frac{1}{20}}(\xi)$ and \varkappa is a large positive constant to be chosen later. Such a function exists by minimization, and by elliptic estimates up to the boundary (see proof of Lemma 1.7) v is smooth in $D \setminus B(\xi)$ (possibly not at the corners).

We claim that

(5.6)
$$u(x_{\xi}) \geqslant v(x_{\xi})$$
 for some $x_{\xi} \in \partial B(\xi)$

provided \varkappa is a sufficiently large constant. Indeed, otherwise we have $u \leq v$ on $\partial B(\xi)$; also $u \leq v$ on ∂D by (5.3) (with $\tau = \sigma$). Therefore $u \leq v$ on $\partial (D \setminus B(\xi))$. Then by the maximum principle (Lemma 1.4) also $u \leq v$ on $\overline{D} \setminus \overline{B(\xi)}$. It follows from Lemma 5.2 that

(5.7)
$$1 \ll \limsup_{x \to z} \frac{u(x)}{\operatorname{dist}(x, \partial D)} \ll \partial_{-\nu} v(z) .$$

On the other hand we have an estimate

$$(5.8) \qquad \qquad \partial_{-v} v(z) \leq (\lambda + C\sigma) - c \varkappa \sigma$$

with constants C, c independent of \varkappa and σ . Before we show this, let us finish the proof of the theorem. Choosing \varkappa large enough we see that (5.8) contradicts (5.7), consequently (5.6) is true.

Using this and (5.3) we find that for any $x \in B_{4}(\xi)$

$$u(x) \ge u(x_{\xi}) - \frac{3}{10} (1 + \sigma) \ge v(x_{\xi}) - \frac{3}{10} (1 + \sigma)$$
$$\ge -x_{\xi_n} - \frac{3}{10} - C\sigma \ge \frac{3}{10} - C\sigma \ge 0$$

if σ is small enough. Thus u > 0 in $B_{\frac{1}{2}}(\xi)$ and, consequently, $\mathscr{L}u = 0$ in $B_{\frac{1}{2}}(\xi)$.

Set

$$w(x) = (1 + \sigma)(\sigma - x_n) - u(x) .$$

Then $w \ge 0$ in $B_{\frac{1}{2}}(\xi)$ (by (5.3)) and

$$w(x_{\xi}) \leqslant -x_{\xi_n} - v(x_{\xi}) + C\sigma \leqslant C\sigma .$$

Since

$$0 = - \mathscr{L} u = f_{p_i p_j}(\nabla u) \partial_{ij} w \quad \text{in } B_{\frac{1}{2}}(\xi) ,$$

we get by Harnack's inequality,

$$w(\xi) \leqslant Cw(x_{\xi}) \leqslant C\sigma ,$$

 \mathbf{or}

$$u(\xi) \ge -\xi_n - C\sigma \qquad (\xi \in \partial B_{\frac{3}{4}}, \xi_n < -\frac{1}{2}).$$

We now integrate along vertical lines and, using (5.3), obtain

$$u(\xi + \alpha e_n) \ge u(\xi) - (1 + \sigma)\alpha \ge - (\xi_n + \alpha) - C\sigma$$

which implies the asserted flatness from below, i.e., $u \in F(2\sigma, C\sigma; \sigma)$ in B_{+} .

To complete the proof we have to establish (5.8), where the first term on the right comes from elliptic estimates and the values of v on ∂D , and the second term from the maximum principle due to the values of v on $\partial B(\xi)$. More precisely, we will estimate v from above by a \mathscr{L} -supersolution $v_1 - \varkappa \sigma v_2$, where

$$\widetilde{\mathscr{P}}w=a_{ij}\partial_{ij}w\,,\quad a_{ij}(x)=f_{p_ip_j}(\nabla v(x))\,,$$

and with v_1, v_2 defined as follows. First

$$v_1 = \frac{\gamma_1}{\mu_1} (1 - \exp(-\mu_1 d_1))$$
 in D ,

where

$$d_1(x) = -x_n + \sigma - s\eta(x'),$$

and with positive constants μ_1, γ_1 depending on σ . Then

$$1 \leq |\nabla d_{\mathfrak{l}}| \leq 1 + C\sigma$$
, $|\nabla^2 d_{\mathfrak{l}}| \leq C\sigma$,

hence

 $\mathbf{34}$

$$\begin{aligned} \widetilde{\mathscr{L}}v_1 &= \gamma_1 \exp\left(-\mu_1 d_1\right) a_{ii} (\partial_{ij} d_1 - \mu_1 \partial_i d_1 \partial_j d_1) \\ &\leq \gamma_1 \exp\left(-\mu_1 d_1\right) (C\sigma - c\mu_1) < 0 \end{aligned}$$

if

$$\mu_1 = C_1 \sigma$$
, C_1 large enough.

For $x \in D$

(5.9)
$$v_1(x) \ge \gamma_1 d_1(x) (1 - C\mu_1) \ge (1 + 2\sigma) d_1(x)$$

if $\gamma_1 = 1 + C_2 \sigma$, C_2 large enough, and (σ small)

$$(1+2\sigma)d_1(x) \ge v(x)$$
 for $x \in \partial(D \setminus B(\xi))$.

Since $\widetilde{\mathscr{I}}v = 0$ the maximum principle yields

$$(5.10) v_1 \geqslant v in D \setminus B(\xi) .$$

At the point z we compute

$$|\nabla v_1(z)| = \gamma_1 |\nabla d_1| \leq 1 + C\sigma.$$

We define v_2 depending on ξ by

$$v_2 = rac{\gamma_2}{\mu_2} \left(\exp\left(\mu_2 d_2\right) - 1
ight) \quad ext{in } ilde{D} \smallsetminus B(\xi)$$

with constants γ_2, μ_2 . Here $\tilde{D} \subset D$ is a domain with smooth boundary containing

$$D \setminus B_{\frac{1}{10}}(\{(x', 0); x' \in \mathbb{R}^{n-1}, |x'| = 1\}),$$

and d_2 is a function in $C^2(D \setminus B(\xi))$ satisfying

Then

$$\begin{split} \widetilde{\mathscr{L}} v_2 &= \gamma_2 \exp\left(\mu_2 d_2\right) a_{ij} (\partial_{ij} d_2 + \mu_2 \partial_i d_2 \partial_j d_2) \\ &\geqslant \gamma_2 \exp\left(\mu_2 d_2\right) (-C + c \mu_2) > 0 \end{split}$$

if μ_2 is large enough. Then choose γ_2 such that

$$v_2 = 1$$
 on $\partial B(\xi)$.

At the point z

$$|
abla v_2(z)| = \gamma_2 |
abla d_2(z)| \ge c > 0$$
.

Thus the function

$$w \equiv v_1 - \varkappa \sigma v_2$$

is a $\widetilde{\mathscr{D}}$ -supersolution in $\widetilde{D} \setminus B(\xi)$ with (see (5.10))

$$w = v_1 \geqslant v$$
 on ∂D ,

and for $x \in \partial B(\xi)$ (by (5.9))

$$w(x) \ge d_1(x) - \varkappa \sigma \ge - (1 - \varkappa \sigma) x_n = v(x)$$

Therefore $w \ge v$ on $\partial(\tilde{D} \setminus B(\xi))$ and the maximum principle yields $w \ge v$ in $\tilde{D} \setminus B(\xi)$; in particular,

$$\partial_{-\nu} v(z) \leq \partial_{-\nu} w(z) = |\nabla v_1(z)| - \varkappa \sigma |\nabla v_2(z)|$$

$$\leq (1 + C\sigma) - \varkappa \sigma ,$$

which is the estimate (5.8) we had to prove.

We shall denote points in \mathbb{R}^n by (y, h) with $y \in \mathbb{R}^{n-1}$, and balls in \mathbb{R}^{n-1} by B'_o , or $B'_o(y)$.

LEMMA 5.3 (Non-homogeneous blow up). Let $u_k \in F(\sigma_k, \sigma_k; \tau_k)$ in B_{ϱ_k} with $\sigma_k \to 0, \ \tau_k \sigma_k^{-2} \to 0$. Set, for $y \in B'_1$,

$$\begin{split} f_k^+(y) &= \sup\left\{h; \left(\varrho_k y, \sigma_k \varrho_k h\right) \in \partial\{u_k > 0\}\right\},\\ f_k^-(y) &= \inf\left\{h; \left(\varrho_k y, \sigma_k \varrho_k h\right) \in \partial\{u_k > 0\}\right\}. \end{split}$$

Then, for a subsequence,

$$f(y) \equiv \limsup_{\substack{z \to y \\ k \to \infty}} f_k^+(z) = \liminf_{\substack{z \to y \\ k \to \infty}} f_k^-(z) \quad for \ all \ y \in B_1'.$$

Further, $f_k^+ \to f$, $f_k^- \to f$ uniformly, f(0) = 0 and f is continuous.

The proof which is based on Theorem 5.1 is identical with the proof of [1; Lemma 7.3].

LEMMA 5.4. f is subharmonic.

PROOF. For simplicity we take $\varrho_k = 1$, $\lambda^* = 1$. If the assertion is not true then there is a ball $B'_{\sigma}(y_0) \subset B'_1$ and a harmonic function g in a neighborhood of this ball such that

$$g > f$$
 on $\partial B'_{\varrho}(y_0)$ and $f(y_0) > g(y_0)$.

We proceed as in [1], setting

$$egin{aligned} Z &= B_ec{}_ec{}_ec{}_0) imes R \;, \quad Z^{\pm}(arphi) &= \{(y,\,h) \in Z \,; \, h \, \gtrless \, arphi(y)\} \;, \ &Z_0(arphi) &= \{(y,\,h) \in Z \,; \, h \, = \, arphi(y)\} \;, \end{aligned}$$

and letting $d_{\delta}(Z^{+}(\sigma_{k}g))$ be a test function which converges (as $\delta \to 0$) to the characteristic function of $Z^{+}(\sigma_{k}g)$ (say, $d_{\delta}(A)(x) = \min \{(1/\delta) \text{ dist} (x, \mathbb{R}^{n}/A), 1\}$).

We have, by Theorems 3.2 and 3.6,

$$-\int_{\Omega} f_p(\nabla u_k) \cdot \nabla d_{\delta}(Z^+(\sigma_k g)) = \int_{\partial_{\mathrm{red}}\{u_k > 0\}} Q d_{\delta}(Z^+(\sigma_k g)) \, dH^{n-1}.$$

Taking $\sigma \to 0$ (and assuming that $Z^0(\sigma_k g) \cap \partial \{u_k > 0\}$ has H^{n-1} measure zero; otherwise we replace g by g + c for some suitable small c), we get

$$\int_{\partial (Z^+(\sigma_k \boldsymbol{\varrho})) \cap \{u_k > 0\}} f_{\boldsymbol{\varrho}}(\nabla u_k) \cdot \boldsymbol{\nu} \, dH^{n-1} = \int_{Z^+(\sigma_k \boldsymbol{\varrho}) \cap \partial_{\mathrm{red}}\{u_k > 0\}} Q \, dH^{n-1}.$$

Using the fact that $f_p(\nabla u_k) = 2F'(|\nabla u_k|^2) \nabla u_k$ and (3.3), (5.3), we see that the integrand on the left-hand side is bounded by $Q(1 + C\tau_k)$. Hence

$$(5.11) \quad H^{n-1}(Z^+(\sigma_k g) \cap \partial_{\mathrm{red}}\{u_k > 0\}) \leq (1 + C\tau_k)H^{n-1}(Z^0(\sigma_k g) \cap \{u_k > 0\}).$$

The set

$$E_k = \{u_k > 0\} \cup Z^-(\mathbf{g}_k g)$$

has finite perimeter in the cylinder Z, with

(5.12)
$$H^{n-1}(Z \cap \partial_{\operatorname{red}} E_k) \leq H^{n-1}(Z^+(\sigma_k g) \cap \partial_{\operatorname{red}} \{u_k > 0\})$$
$$+ H^{n-1}(Z^0(\sigma_k g) \cap \{u_k = 0\}).$$

By the excess area estimate of [1; p. 136]

$$H^{n-1}(Z \cap \partial_{\operatorname{red}} E_k) \! \geqslant \! H^{n-1}(Z^0(\sigma_k g)) + c\sigma_k^2$$

for k large enough. Substituting this into (5.12) and using (5.11), we get a contradiction to the relation $\tau_k = o(\sigma_k^2)$ which was assumed in Lemma 5.3.

The following lemma will be needed later on in proving further regularity of the function f(y).

LEMMA 5.5. Let w be a function satisfying:

 $\Delta w = 0$ in $B_1^- \equiv B_1 \cap \{h < 0\},\$

w(y, 0) = g(y) in the sense that w(y, h) as a function of y converges to g in L^1 as $h \uparrow 0$,

g is subharmonic and continuous in B'_1 , g(0) = 0,

- 10

 $w(0, h) \leqslant C|h|,$

$$w \ge -C$$
.

Then

(5.13)
$$\int_{0}^{1/2} \frac{1}{r^{2}} \int_{\partial B'_{r}}^{\partial g(y)} dH^{n-2} \leqslant C_{0}$$

where C_0 is a constant dpending only on C.

Notice that the integrand is nonnegative, since g is subharmonic and g(0) = 0.

PROOF. Denote by $G_{(y',h')}$ the Green function for Δ in B_1^- with singularity at (y', h'). Then

$$C|h'| \ge w(0, h') = -\int_{\partial B_1^- \cap \{h=0\}} g(y) \frac{\partial}{\partial \nu} G_{(\nu', h')}(y, 0) \, dy - \int_{\partial B_1^- \cap \{h<0\}} w \, \frac{\partial}{\partial \nu} G_{(\nu', h')} dH^{n-1} \, .$$

Here it is assumed that w has L^1 boundary values on $\partial B_1^- \cap \{h < 0\}$ (otherwise replace B_1 by B_{1-c} with a suitable small positive c). The function

$$\zeta(y',h') = -\int_{\partial B_1^- \cap \{h<0\}} \frac{\partial}{\partial \nu} G_{(y',h')} dH^{n-1}$$

is harmonic in B_1^- , with boundary values 1 on $\partial B_1^- \cap \{h' < 0\}$, and 0 on

 $\partial B_1^- \cap \{h'=0\}$. Hence

$$\zeta(0,h') \leqslant C|h'| .$$

It follows that

.

38

(5.14)
$$-\int_{B'_1} g(y) \frac{\partial}{\partial \nu} G_{(0,h')}(y, 0) \, dy \leqslant C|h'| \, .$$

Since the Poisson kernel in (5.14) depends only on |y|, say,

$$-rac{\partial}{\partial
u} \, G_{(\mathbf{0}, h')}(y, \, 0) = arphi_{h'}(|y|)$$

this estimate can be written as

$$\int_{0}^{1} \frac{r^{n-2}\varphi_{h'}(r)}{|h'|} \left(\int_{\partial B'_{r}} g \, dH^{n-2} \right) dr \leqslant C,$$

where the average of g over $\partial B'_r$ is nonnegative, since g is subharmonic with g(0) = 0. One easily computes that

$$rac{arphi_{h'}(r)}{|h'|} = c((r^2+h'^2)^{-n/2}-(h'^2r^2+1)^{-n/2})
onumber \ r c(r^{-n}-1)$$

as $|h'| \searrow 0$, where c is a constant depending only on n. Thus we obtain

$$\int_{0}^{1} \frac{1-r^{n}}{r^{2}} \left(\oint_{\partial B'_{r}} g \, dH^{n-2} \right) dr \leqslant C ,$$

which implies (5.13).

LEMMA 5.6. There exists a positive constant C such that, for any $y \in B'_{r/2}$,

(5.15)
$$\int_{0} \frac{1}{r^{2}} \left(\int_{\partial B'_{r}(y)} f - f(y) \right) \leq C .$$

Here f is the function appearing in Lemma 5.4. Lemma 5.6 is analogous to Lemma 7.6 in [1]. Once this lemma is proved we shall be able to proceed as in [1] to establish regularity of the free boundary.

PROOF. For simplicity we take $\varrho_k = 1$, $\lambda^* = 1$. For large k the u_k are

of class $F(8\sigma_k, 8\sigma_k; \tau_k)$ in $B_{\frac{1}{2}}(y, \sigma_k f_k^+(y))$. Therefore it suffices to prove the lemma for y = 0.

Set

(5.16)
$$w_k(y,h) = \frac{u_k(y,h) + h}{\sigma_k}$$

Since the free boundary of u_k lies in the strip $|x_n| \leq c\sigma_k$ and since $|\nabla u_k| \leq 1 + C\tau_k, \ \tau_k \leq \sigma_k$, we have and $w_k \leq C$ in B_1^- . The flatness assumption also implies that $w_k \ge -C$ in B_1^- . Thus

(5.17)
$$|w_k| \leq C$$
 in B_1^- .

LEMMA 5.7. For a subsequence,

$$\lim_{k\to\infty} w_k \equiv w \quad \text{ exists everywhere in } B_1^-,$$

the convergence is uniform in compact subsets of B_1^- , and w satisfies:

$$(5.18) a_{ij}\partial_{ij}w = 0 in B_1^-$$

where

$$a_{ij} = f_{p_i p_j}(-\lambda^* e_n) = F'(\lambda^{*2}) \delta_{ij} + 2F''(\lambda^{*2}) \lambda^{*2} \delta_{in} \delta_{jn},$$

(5.19)
$$w(0, h) \leq 0$$

(5.19)
$$w(0, h) < 0$$
,
(5.20) $w(y, 0) = f(y)$

in the sense that $\lim_{h \to 0} w(y, h) = f(y)$,

$$(5.21) |w| \leq C.$$

Observe that the proof of Lemma 5.5 extends (by affine transformation) to the linear elliptic operator in (5.18). Hence, once Lemma 5.7 is proved, Lemma 5.5 can be applied to the function f, so that (5.15) follows.

PROOF OF LEMMA 5.7. The u_k satisfy

$$\nabla \cdot f_p(\nabla u_k) = 0 \quad \text{in } B_1 \cap \{h < -\sigma_k\} .$$

Writing this equation in non-divergence form, it is clear that

(5.22)
$$\mathscr{L}_k w_k \equiv f_{p_l p_j} (\nabla u_k) \partial_{ij} w_k = 0$$

if $h < -\sigma_k$. From the flatness assumptions on the u_k and Lemma 1.7 we conclude that, for a subsequence,

$$u_k(y, h) \rightarrow -h$$

in C^2 in compact subsets of B_1^- . Recalling (5.17) we conclude that also $w_k \to w$ in C^2 in compact subsets of B_1^- , and w satisfies (5.18). Clearly (5.21) is also valid.

Since.

(5.23)
$$-\frac{\partial}{\partial h}w_k = -\frac{1}{\sigma_k} \left(\frac{\partial}{\partial h} u_k + 1 \right) < \frac{|\nabla u_k| - 1}{\sigma_k} < \frac{\tau_k}{\sigma_k}$$

and $w_k(0, 0) = 0$, we have for $h \leq 0$,

$$w_k(0, h) \leqslant |h| \frac{\tau_k}{\sigma_k} \to 0$$
.

Thus $w(0, h) \leq 0$, and (5.19) is proved. It remains to establish (5.20). We first show that, for any small $\delta > 0$ and any large constant K

(5.24)
$$w_k(y, h\sigma_k) \rightarrow f(y)$$
 uniformly for $y \in B'_{1-\delta}$, $-K \leqslant h \leqslant -1$.

By Lemma 5.3 it suffices to prove

(5.25)
$$w_k(y, h\sigma_k) - f_k^+(y) \to 0.$$

From (5.23) we obtain

(5.26)
$$w_{k}(y, h\sigma_{k}) - f_{k}^{+}(y) \leqslant w_{k}(y, \sigma_{k}f_{k}^{+}(y)) - f_{k}^{+}(y) + (f_{k}^{+}(y) - h)\tau_{k}/\sigma_{k}$$
$$= (f_{k}^{+}(y) - h)\tau_{k}/\sigma_{k} \leqslant (1 + K)\tau_{k}/\sigma_{k} \to 0.$$

In order to show (5.25) from below we take any sequence $y_k \in B_{1-\delta}'$, $-K \leq h_k \leq -1$, and consider u_k in $B_{R\sigma_k}(x_k)$, where x_k is the free boundary point

$$x_k = (y_k, \sigma_k f_k^+(y_k))$$

and R any large constant. We know that

$$u_k \in F(\tilde{\delta}_k, 1; \tau_k) \quad \text{in } B_{R\sigma_k}(x_k),$$

if

$$\tilde{\delta}_k = \frac{1}{R} \sup_{y \in B'_{R\sigma_k}(y_k)} \left(f_k^+(y) - f_k^+(y_k) \right),$$

where $\delta_k \to 0$ by Lemma 5.3. It follows from the flatness theorem (Theorem 5.1) that

$$u_k \in F(2\delta_k, C\delta_k; \tau_k)$$
 in $B_{(R/2)\sigma_k}(x_k)$,

 \mathbf{if}

$$\delta_k = \max\left(\tilde{\delta}_k, \tau_k\right)$$
.

Hence for any h with |h| < R/2

$$u_k(x_k + h\sigma_k e_n) \ge -\left(h\sigma_k + C\delta \cdot \frac{R}{2}\sigma_k\right),$$

that is,

$$w_k(x_k+h\sigma_k e_n)-f_k^+(y_k)=rac{u_k(x_k+h\sigma_k e_n)+h\sigma_k}{\sigma_k} \ge -Crac{R}{2}\,\delta_k o 0\,,$$

which together with (5.26) proves (5.25).

For any $\varepsilon > 0$ choose a C^3 function g_{ε} such that

(5.27)
$$f - 2\varepsilon \leqslant g_{\varepsilon} \leqslant f - \varepsilon \quad \text{on } B_1',$$

and let u_{ε} be the solution of (see (5.18))

$$\begin{aligned} \mathscr{L}_{0} u_{\varepsilon} &\equiv a_{ij} \partial_{ij} u_{\varepsilon} = 1 & \text{ in } B_{1}^{-}, \\ (5.28) & u_{\varepsilon} &= g_{\varepsilon} & \text{ on } \partial B_{1-\delta}^{-} \cap \{h = 0\}, \\ & u_{\varepsilon} &= \inf_{B_{1}^{-}} w & \text{ on } \partial B_{1-\delta}^{-} \cap \{h < 0\} \end{aligned}$$

with δ as in (5.24).

By (5.24) and (5.27),

(5.29)
$$w_k > u_{\varepsilon} \quad \text{on } \partial(B_{1-\delta} \cap \{h < -K\sigma_k\})$$

for any large constant K (independent of δ, ε), provided k is sufficiently large (depending on ε, K).

The function w_k is a bounded function (uniformly with respect to k) satisfying a uniformly elliptic equation (uniformly also with respect to k) in $B_1^- \cap \{h \leq -\sigma_k\}$. By elliptic estimates (see the proof of Lemma 1.7) we deduce that

$$|
abla w_k| \leqslant rac{C}{K\sigma_k} \qquad B_{1-\delta}^- \cap \{h \leqslant -K\sigma_k\}$$

where C is a constant independent of k, K. Consequently

$$\begin{aligned} \mathscr{L}_{k}u_{\varepsilon} &= \left(f_{\mathfrak{p}_{i}\mathfrak{p}_{j}}(\nabla u_{k}) - f_{\mathfrak{p}_{i}\mathfrak{p}_{j}}(-e_{n})\right)\partial_{ij}u_{\varepsilon} + 1 \\ &\geq 1 - \frac{C}{K} \left\|u_{\varepsilon}\right\|_{C^{1,1}(B_{1-\delta}^{-})} > 0 \quad \text{ in } B_{1-\delta}^{-} \cap \{h < -K\sigma_{k}\} \end{aligned}$$

if K is large enough (depending on δ and ε). Thus $\mathscr{L}_k u_{\varepsilon} \geq \mathscr{L}_k w_k$. Recalling (5.29) and applying the maximum principle, we get $u_{\varepsilon} \leq w_k$ in $B_{1-\delta}^- \cap \{h \leq -K\sigma_k\}$ if k is large enough. It follows that $w(y,h) \geq u_{\varepsilon}(y,h)$ in $B_{1-\delta}^-$ and, consequently,

$$\lim_{h \neq 0} w(y, h) \! \geq \! g_{\varepsilon}(y) \! \geq \! f(y) - 2\varepsilon \; .$$

Similarly by working with a solution of

$$egin{aligned} &\mathscr{L}_{\mathfrak{o}} \widetilde{u}_{arepsilon} = -1 & ext{in} \ \ B_{1}^{-} \ , \ &\widetilde{u}_{arepsilon} = \widetilde{g}_{arepsilon} & ext{on} \ \ \partial B_{1}^{-} \cap \{h = 0\} \ (f + arepsilon \leqslant \widetilde{g}_{arepsilon} \leqslant f + 2arepsilon) \ , \ &\widetilde{u}_{arepsilon} = \sup_{B_{1}^{-}} w & ext{on} \ \ \partial B_{1}^{-} \cap \{h < 0\} \ , \end{aligned}$$

we obtain $\overline{\lim_{h \neq 0}} w(y, h) \leq f(y) + 2\varepsilon$. Since ε is arbitrary. (5.20) follows.

6. - Smoothness of the free boundary.

Using Theorem 5.1 and Lemma 5.6 we can now proceed precisely as in [1] and establish that f is «better than» Lipschitz continuous (Lemma 7.8 of [1]) and that the flatness condition implies better flatness in a smaller ball (Lemmas 7.9, 7.10). Using also Theorem 4.1 we obtain as in [1; Theorem 8.1]:

THEOREM 6.1. Suppose u is a local minimum and $D \subset \Omega$. Then there exist positive constants α , β , σ_0 , τ_0 , C such that if

(6.1)
$$u \in F(\sigma, 1; \infty)$$
 in $B_{\varrho}(x_0) \subset D$ in direction ν

with $\sigma \leqslant \sigma_0$, $\varrho \leqslant \tau_0 \sigma^{2/\beta}$, then

$$B_{\varrho/4}(x_0) \cap \partial \{u > 0\}$$
 is a $C^{1,\alpha}$ surface,

more precisely, a graph in direction v of a $C^{1,\alpha}$ function, and, for any x_1, x_2

on this surface,

$$|\nu(x_1)-\nu(x_2)| \leqslant C\sigma \left|\frac{x_1-x_2}{\varrho}\right|^{\alpha}.$$

We refer to (6.1) as the flatness condition.

From the first part of the proof of Theorem 3.5 we see that if $x_0 \in \partial_{red} \{u > 0\}$ then

$$u \in F(\sigma_{\varrho}, 1; \infty)$$
 in $B_{\varrho}(x_0)$ in direction $\nu_u(x_0)$

with $\sigma_{\rho} \rightarrow 0$ for $\rho \rightarrow 0$. Hence, applying Theorem 6.1 we obtain:

THEOREM 6.2. Let u be a local minimum. Then $\partial_{\text{red}}\{u > 0\}$ is a $C^{1,\alpha}$ surface locally in Ω , and the remainder of $\partial\{u > 0\}$ has H^{n-1} measure zero.

For n = 2, any blow up sequence u_k with respect to balls $B_{\varrho_k}(x_0)$ $(x_0 \in \partial \{u > 0\})$ has a subsequence which is convergent to a linear function $\lambda^* \max \{-x \cdot v, 0\}$, at least in a neighborhood of the origin, by Corollary 4.4. Using (3.11), (3.12) we see that

$$u \in F(\sigma_k, 1; \infty)$$
 in $B_{\varrho_k}(x_0)$ in direction ν ,

with $\sigma_k \to 0$ as $k \to \infty$. Hence Theorem 6.1 can be applied. We get:

THEOREM 6.3. Let n = 2 and let u be a local minimum. Then $\partial \{u > 0\}$ is a $C^{1,\alpha}$ curve locally in Ω .

Higher regularity follow from [8-10]; in particular, if F(t) is analytic (C^{∞}) then

(6.2) for
$$n \ge 3$$
, $\partial_{red} \{u > 0\}$ is locally analytic (C^{∞}) ;
for $n = 2$, $\partial \{u > 0\}$ is locally analytic (C^{∞}) .

REMARK 6.4. All the results of this paper extend with minor changes to the case where λ is a function $\lambda(x)$, bounded, uniformly positive and Hölder continuous. In the definition of flatness we require that

$$\operatorname{osc}_{B_\varrho} \lambda^*(x) \leq \lambda^*(0) \, \tau$$

where $\lambda^*(x)$ is defined by (3.1) with $\lambda = \lambda(x)$. If λ and F are in $C^{k,\alpha}$ then $\partial_{\text{red}}\{u > 0\}$ (for $n \ge 3$) and $\partial\{u > 0\}$ (for n = 2) belong to $C^{k+1,\alpha}$; if λ and F are analytic (C^{∞}) then (6.2) holds.

44

Finally, all the results extend to the functional (0.2) provided F(x, t) is smooth enough.

REFERENCES

- [1] H. W. ALT L. A. CAFFARELLI, Existence and regularity for a minimum problem with free boundary, J. Reine Angew. Math., **325** (1981), pp. 105-144.
- [2] H. W. ALT L. A. CAFFARELLI A. FRIEDMAN, Axially symmetric jet flows, Arch. Rational Mech. Anal., 81 (1983), pp. 97-149
- [3] H. W. ALT L. A. CAFFARELLI A. FRIEDMAN, Asymmetric jet flows, Comm. Pure Appl. Math., 35 (1982), pp. 29-68.
- [4] H. W. ALT L. A. CAFFARELLI A. FRIEDMAN, Jet flows with gravity, J. Reine Angew. Math., 331 (1982), pp. 58-103.
- [5] H. FEDERER, Geometric Measure Theory, Springer Verlag, vol. 153, Berlin-Heidelberg-New York, 1969.
- [6] D. GILBARG N. S. TRUDINGER, Elliptic Partial Differential Equations of Second Order, Springer Verlag, vol. 224, Berlin-Heidelberg-New York, 1977.
- [7] E. GIUSTI, Minimal Surfaces and Functions of Bounded Variations, Notes on Pure Mathematics, Australian National University, Camberra, 1977.
- [8] V. M. ISAKOV, Inverse theorems concerning the smoothness of potentials, Differential Equations, 11 (1974), pp. 50-56 (Translated from Russian).
- [9] V. M. ISAKOV, Analyticity of nonlinear transmission problems, Differential Equations, 12 (1976), pp. 41-47 (Translated from Russian).
- [10] D. KINDERLEHRER L. NIRENBERG, Regularity in free boundary problems, Ann. Scuola Norm. Sup. Pisa, 4 (4) (1977), pp. 373-391.
- [11] C. B. MORREY, Jr., Multiple Integrals in the Calculus of Variations, Springer Verlag, Berlin-Heidelberg-New York, 1966.

Institut für Angewandte Mathematik Universität Bonn D-5300 Bonn, Germany

University of Chicago Chicago, Illinois

Northwestern University Evanston, Illinois