# Hans Wilhelm Alt <br> Luis A. Caffarelli <br> Avner Friedman <br> A free boundary problem for quasi-linear elliptic equations 

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# A Free Boundary Problem for Quasi-Linear Elliptic Equations (*). 

HANS WILHELM ALT - LUIS A. CAFFARELLI - AVNER FRIEDMAN

## 0. - Introduction.

Consider the problem of minimizing the functional

$$
\begin{equation*}
J(u)=\int_{\Omega}\left(F\left(|\nabla u|^{2}\right)+\lambda^{2} I_{\{u>0\}}\right) d x \quad(\lambda>0) \tag{0.1}
\end{equation*}
$$

in the class of functions $u$ satisfying $u=u^{0}$ on a part $S$ of $\partial \Omega, u^{0} \geqslant 0$. Here $\Omega$ is a domain in $R^{n}$ and $F(t)$ is a convex function of $t$ for $t>0, F(0)=0$, $F^{\prime}(0)>0$. The special case $F(t)=t$ was studied by Alt and Caffarelli [1] who proved Lipschitz continuity and nondegeneracy of a minimum $u$. They also studied the free boundary $\Gamma=\partial\{u>0\} \cap \Omega$ and proved the analyticity of $\Gamma$ if $n=2$; further, if $n \geqslant 3, x^{0} \in \Gamma$ and $\Gamma$ satisfies the «flatness condition" at $x^{0}$, then $\Gamma$ is analytic in a neighborhood of $x^{0}$.

The results of [1] were used by Alt, Caffarelli and Friedman [2-4] in their study of jet flows of inviscid, irrotational and incompressible fluid.

In this paper we shall extend all the results of [1] to the functional (0.1). In particular we establish Lipschitz continuity and nondegeneracy of a minimum, and analyticity of the free boundary (if $n \geqslant 3$, the flatness condition is assumed, as before).

The results of this paper extend with obvious changes to the more general

[^0]functional
\[

$$
\begin{equation*}
J(u)=\int_{\Omega}\left[F\left(x,|\nabla u(x)|^{2}\right)+\lambda^{2}(x) I_{\{u>0\}}(x)\right] d x \tag{0.2}
\end{equation*}
$$

\]

where $\lambda(x)>0, \lambda \in C^{\alpha}(\Omega)$.
In a future publication we shall apply the results of this paper to the study of jets and cavities of compressible fluids.

## 1. - The minimization problem; basic properties.

Let $F^{\prime}(t)$ be a function in $C^{2,1}[0, \infty)$, satisfying:

$$
\begin{array}{ll}
F(0)=0, & c_{0} \leqslant F^{\prime}(t) \leqslant C_{0} \\
0 \leqslant F^{\prime \prime}(t) \leqslant \frac{C_{0}}{1+t} & \left(c_{0}, C_{0} \text { positive constants }\right) . \tag{1.1}
\end{array}
$$

Let $\Omega$ be a domain in $R^{n}$, not necessarily bounded. For any $\lambda>0$, consider the functional

$$
J(v)=\int_{\Omega}\left(F\left(|\nabla v|^{2}\right)+\lambda^{2} I_{\{u>0\}}\right) d x
$$

over the class of admissible functions

$$
K=\left\{v \in L_{\mathrm{loc}}^{1}(\Omega), \nabla v \in L^{2}(\Omega) \text { and } v=u^{0} \text { on } S\right\}
$$

where $S$ is a given subset of $\partial \Omega$ and $u^{0}$ is a given function. We assume that locally $\partial \Omega$ is a Lipschitz graph, that $S$ is measurable with $H^{n-1}(S)>0$, and that

$$
u^{0} \geqslant 0, \quad u^{0} \in L_{\mathrm{loc}}^{1}(\Omega), \quad \nabla u_{0} \in L^{2}(\Omega)
$$

Set

$$
f(p)=F\left(|p|^{2}\right)
$$

From (1.1) we find that $f(p)$ is convex; moreover,

$$
\begin{equation*}
\beta|\xi|^{2} \leqslant \sum \frac{\partial^{2} f(p)}{\partial p_{i} \partial p_{j}} \xi_{i} \xi_{0}<\beta^{-1}|\xi|^{2} \quad \text { for all } \xi \in R^{n} \tag{1.2}
\end{equation*}
$$

consequently

$$
\left\{\begin{array}{l}
\beta|p|^{2} \leqslant f_{p}(p) \cdot p  \tag{1.3}\\
\beta|p|^{2} \leqslant f(p) \leqslant \beta^{-1}|p|^{2}
\end{array}\right.
$$

for some small constant $\beta>0$, where $f_{p}=\nabla_{p} f$.

Consider the problem: find $u$ such that

$$
\begin{equation*}
J(u)=\min _{v \in K} J(v), \quad u \in K \tag{1.4}
\end{equation*}
$$

This means that we have to deal with the differential operator

$$
\mathscr{L} v=\nabla \cdot\left(f_{\mathcal{D}}(\nabla v)\right)
$$

Theorem 1.1. If $J\left(u^{0}\right)<\infty$ then there exists a solution to problem (1.4).
Proof. The proof is the same as in [1], Theorem 1.3. Let $\left\{u_{k}\right\}$ be a minimizing sequence. Then, by (1.3),

$$
\int_{\Omega}\left|\nabla u_{k}\right|^{2} \leqslant \frac{1}{\beta} J\left(u_{k}\right)
$$

It follows that $u_{k}-u^{0}$ are bounded in $L^{2}\left(\Omega \cap B_{R}\right)$ for any large $R$. Therefore there is a $u \in K$ such that, for a subsequence,

$$
\begin{aligned}
\nabla u_{k} \rightarrow \nabla u & \text { weakly in } L_{\mathrm{loc}}^{2}(\Omega) \\
u_{k} \rightarrow u & \text { a.e. in } \Omega
\end{aligned}
$$

The pointwise convergence implies

$$
\left.\int_{\Omega \cap B_{R}} I_{\{u>0\}} \leqslant \liminf \int_{k \rightarrow \infty} I_{\Omega \cap B_{R}} I_{k}>0\right\}
$$

and since $f$ is convex we have (see, for instance [6; pp. 232-3])

$$
\int_{\Omega \cap B_{R}} f(|\nabla u|) \leqslant \liminf _{k \rightarrow \infty} \int_{\Omega \cap B_{R}} f\left(\left|\nabla u_{k}\right|\right) ;
$$

thus

$$
J(u) \leqslant \liminf _{k \rightarrow \infty} J\left(u_{k}\right)
$$

Definition 1.2. $u \in K$ is called a local minimum of $J$ if, for some $\varepsilon_{0}>0$, $J(u) \leqslant J(v)$ for any $v \in K$ with

$$
\|\nabla(v-u)\|_{L^{2}(\Omega)}+\left\|I_{\{v>0\}}-I_{\{u>0\}}\right\|_{L^{1}(\Omega)}<\varepsilon_{0}
$$

LEMMA 1.3. If $u$ is a local minimum then $u$ is $\mathscr{L}$-subsolution, that is,

$$
\begin{equation*}
\int_{\Omega} \nabla \zeta \cdot f_{p}(\nabla u) \leqslant 0 \quad \text { for all } \zeta \in C_{0}^{\infty}(\Omega), \quad \zeta \geqslant 0 \tag{1.5}
\end{equation*}
$$

Proof. For any $\varepsilon>0$,

$$
\begin{aligned}
0 & \leqslant \frac{1}{\varepsilon}(J(u-\varepsilon \zeta)-J(u)) \leqslant \frac{1}{\varepsilon} \int_{\Omega}(f(\nabla u-\varepsilon \nabla \zeta)-f(\nabla u)) \\
& \leqslant-\int_{\Omega} \nabla \zeta \cdot f_{p}(\nabla u-\varepsilon \nabla \zeta)
\end{aligned}
$$

since by convexity

$$
\begin{equation*}
f(p)-f(q) \leqslant(p-q) \cdot f_{p}(p) \tag{1.6}
\end{equation*}
$$

Now take $\varepsilon \rightarrow 0$.
Lemma 1.4. If $w$ is a local $\mathscr{L}$-solution in $B_{R}$, that is, $w \in H^{1,2}\left(B_{R}\right)$ and

$$
\begin{equation*}
\int \nabla \zeta \cdot f_{p}(\nabla w)=0 \quad \text { for all } \zeta \in C_{0}^{\infty}\left(B_{R}\right) \tag{1.7}
\end{equation*}
$$

and if $w \geqslant u$ on $\partial B_{R}$, then $w \geqslant u$ in $B_{R}$. If $w=u$ on $\partial B_{R}$ then $w$ is uniquely determined.

Proof. Taking $\zeta=(u-w)^{+}$in (1.5), (1.7) and comparing, we get, using the convexity (1.2) of $f$ :

$$
\begin{aligned}
0 & \geqslant \int_{B_{R}}\left(f_{p}(\nabla u)-f_{p}(\nabla w)\right) \cdot \nabla(u-w)^{+} \\
& =\int_{B_{R} \cap\{u>w\}}\left(f_{p}(\nabla u)-f_{p}(\nabla w)\right) \cdot \nabla(\nabla u-\nabla w) \\
& \geqslant \beta \int_{B_{R}}\left|\nabla(u-w)^{+}\right|^{2} ;
\end{aligned}
$$

hence $u-w \leqslant 0$. If $w_{1}$ is another solution of (1.7) then the above proof gives $w_{1}-w \leqslant 0$. Similarly $w-w_{1} \leqslant 0$, so that $w=w_{1}$ :

Lemma 1.5. If $u$ is a local minimum then

$$
\begin{equation*}
0 \leqslant u \leqslant \sup _{\Omega} u^{0} \tag{1.8}
\end{equation*}
$$

Proof. Setting $M=\sup _{\Omega} u^{0}$, we have, for small $\varepsilon>0$,

$$
\begin{aligned}
0 & \leqslant \frac{1}{\varepsilon}(J(u+\varepsilon \min (M-u, 0))-J(u)) \\
& =\frac{1}{\varepsilon} \int_{\Omega}(f(\nabla u+\varepsilon \nabla \min (M-u, 0))-f(\nabla u)) \\
& \leqslant \int_{\Omega} \nabla \min (M-u, 0) \cdot f_{p}(\nabla u+\varepsilon \nabla \min (M-u, 0)), \quad \text { by }(1.6) .
\end{aligned}
$$

Taking $\varepsilon \rightarrow 0$ we get

$$
\begin{aligned}
0 & \leqslant \int_{\Omega} \nabla \min (M-u, 0) \cdot f_{p}(\nabla u) \\
& =-\int_{\{u>M\}} \nabla u \cdot f_{p}(\nabla u) \leqslant-\beta \int_{\{u>M\}}|\nabla u|^{2} \\
& =-\beta \int_{\Omega}|\nabla \min (M-u, 0)|^{2}
\end{aligned}
$$

by (1.3), which yields $u \leqslant M$ a.e. in $\Omega$.
Similarly, to prove that $u \geqslant 0$ we begin with ( $\varepsilon$ positive and small)

$$
\begin{aligned}
0 & \leqslant \frac{1}{\varepsilon}(J(u-\varepsilon \min (u, 0))-J(u)) \\
& =\frac{1}{\varepsilon} \int_{\Omega}(f(\nabla(u-\varepsilon \min (u, 0)))-f(\nabla u)) \\
& \leqslant-\int_{\Omega} \nabla \min (u, 0) \cdot f_{p}(\nabla(u-\varepsilon \min (u, 0))) .
\end{aligned}
$$

Taking $\varepsilon \rightarrow 0$ we get

$$
\begin{aligned}
0 & \geqslant \int_{\Omega} \nabla \min (u, 0) \cdot f_{p}(\nabla u) \\
& =\int_{\{u<0\}} \nabla u \cdot f_{p}(\nabla u) \geqslant \beta \int_{\{u<0\}}|\nabla u|^{2}=\beta \int_{\Omega}|\nabla \min (u, 0)|^{2},
\end{aligned}
$$

from which we deduce that $u \geqslant 0$.
In § 2 it will be shown that, for any local minimum $u$, the set $\{u>0\}$ is open. Let us use this fact already in the next statements of this section.

Lemma 1.6. If $u$ is a local minimum then $u$ is $\mathscr{L}$-solution in $\{u>0\}$.
The proof is the same as that of Lemma 1.3, taking $\zeta$ any function in $O_{0}^{\infty}(\{u>0\})$.

Lemma 1.7. If $G$ is an open set, $u \in H^{1,2}(G)$ and $\mathscr{L} u=0$ in $G$, then $u \in C^{2+\alpha}$ for any $0<\alpha<1$.

Proof. We can take $G$ to be a ball. The equation $\mathscr{L} u=0$ has the form

$$
\partial_{i}\left(f_{p_{s}}(\nabla u)\right)=0 \quad\left(\partial_{j}=\frac{\partial}{\partial x_{j}}\right)
$$

Applying $\partial_{k}$ and setting $w_{k}=\partial_{k} u$ we get, formally,

$$
\partial_{j}\left(a_{i j}(\nabla u) \partial_{i} w_{k}\right)=0
$$

where

$$
\begin{equation*}
a_{i j}(p)=f_{p_{1} v_{j}}(p) \tag{1.9}
\end{equation*}
$$

is uniformly elliptic matrix. Thus the Nash-de Giorgi estimate should give a $C^{\alpha}$ estimate on $\hat{\partial}_{k} u$ for some $\alpha \in(0,1)$.

In order to derive the $C^{\alpha}$ estimate rigorously, we approximate $u$ on $\partial G$ by smooth functions $\tilde{u}_{m}$ (in the $L^{2}$ trace norm). By [6; Theorem 14.8] there exists a unique solution $u_{m}$ of

$$
\begin{aligned}
\mathscr{L} u_{m}=0 & \text { in } G \\
u_{m}=\tilde{u}_{m} & \text { on } \partial G
\end{aligned}
$$

with $u_{m} \in C^{2+\alpha}(\bar{G})$. The formal argument given above can be applied to $u_{m}$. It gives

$$
\left|u_{m}\right|_{1+\alpha}^{G} \leqslant C_{m}
$$

as well as

$$
\left|u_{m}\right|_{1+\alpha}^{K} \leqslant C
$$

where $K$ is any compact subset of $G$ ( $C$ is independent of $m$ ). Since $u_{m}$ and the minimizer of

$$
\int_{G} F\left(|\nabla v|^{2}\right), \quad v=\tilde{u}_{m} \text { on } \partial G
$$

coincide by Lemma 1.4, it follows that for some constants $O, \tilde{C}$

$$
\int_{G}\left|\nabla u_{m}\right|^{2} \leqslant C \int_{G} F\left(\left|\nabla u_{m}\right|^{2}\right) \leqslant \tilde{C}
$$

Thus, for a subsequence,

$$
\begin{array}{ll}
u_{m} \rightarrow \tilde{u} & \text { weakly in } H^{1,2}(G) \\
u_{m} \rightarrow u & \text { in } L^{2}(\partial G) \text { (in the trace sense) } .
\end{array}
$$

It follows, again by Lemma 1.4, that $\tilde{u}=u$ and thus $u \in C^{1+x}(K)$. Then the coefficients $a_{i j}(\nabla u)$ are Hölder continuous so that by elliptic estimates $w_{k}$ is of class $C^{1+\alpha}$.

Definition 1.8. We define functions $\psi, \Phi$ by

$$
\left\{\begin{array}{l}
\psi(p)=p f_{p}-f(p)=2|p|^{2} F^{\prime}\left(|p|^{2}\right)-F\left(|p|^{2}\right)  \tag{1.10}\\
\Phi(s)=2 s F^{\prime}(s)-F(s)
\end{array}\right.
$$

so that $\Phi\left(|p|^{2}\right)=\psi(p)$.
Theorem 1.9. If $u$ is a local minimum then

$$
\lim _{\varepsilon \rightarrow 0} \int_{\partial\{u>\varepsilon\}}\left(\Phi\left(|\nabla u|^{2}\right)-\lambda^{2}\right) \eta \cdot v=0
$$

for any $\eta \in H_{0}^{1,2}\left(\Omega ; R^{n}\right)$, where $v$ is the outward normal.
The proof of this very weak formulation of the free boundary condition is similar to the proof of Theorem 2.5 in [1].

## 2. - Regularity and nondegeneracy.

We set

$$
f_{A} v=\frac{1}{\mu(A)} \int_{A} v d \mu
$$

Since we shall use this notation mostly when either $A$ is a ball $B_{r}\left(x^{0}\right)$ $=\left\{\left|x-x^{0}\right|<r\right\}$ and $\mu=L^{n}$ or $A$ is a sphere $\partial B_{r}\left(x^{0}\right)$ and $\mu=H^{n-1}$, we of.ten omit in the notation the measure $d \mu$.

Lemma 2.1. Any local minimum $u$ is in $C^{\alpha}(\Omega)$, for any $0<\alpha<1$.
Proof. Let $B_{\tau} \subset \Omega$ and let $v$ be the solution of

$$
\begin{align*}
& \int_{B_{r}} \nabla \zeta \cdot f_{p}(\nabla v)=0 \quad \text { for all } \zeta \in C_{0}^{\infty}\left(B_{r}\right),  \tag{2.1}\\
& v-u \in H_{0}^{1,2}\left(B_{r}\right)
\end{align*}
$$

its existence follows by minimization. Then

$$
\begin{align*}
\int_{B_{r}}\left(f(\nabla u)+\lambda^{2} I_{\{u>0\}}\right) & \leqslant \int_{B_{r}}\left(f(\nabla v)+\lambda^{2} I_{\{u>0\}}\right)  \tag{2.2}\\
& =\int_{B_{r}}\left(f(\nabla v)+\lambda^{2}\right)
\end{align*}
$$

since $v>0$ in $B_{r}$, by the maximum principle. By convexity (1.2),

$$
f(\nabla u) \geqslant f(\nabla v)+f_{p}(\nabla v) \cdot \nabla(u-v)+\beta|\nabla(u-v)|^{2}
$$

Integrating this relation and using (2.1) with $\zeta=u-v$, we find, after comparing with (2.2), that

$$
\begin{equation*}
\int_{B_{r}}|\nabla(u-v)|^{2} \leqslant C \int_{B_{r}} \lambda^{2} I_{\{u=0\}} \tag{2.3}
\end{equation*}
$$

We can now use the method of Morrey [11; Th. 5.3.6] in order to deduce the assertion of the lemma.

In the sequel we denote positive constants depending only on $\beta$ and $n$ by $C$ or $c$.

Set

$$
E_{+}=\{u>0\}, \quad E_{0}=\{u=0\}
$$

By Lemma 2.1, $E_{+}$is open and $E_{0}$ is closed in $\Omega$.
Set

$$
d(x)=\operatorname{dist}\left(x, E_{0}\right)
$$

Lemma 2.2. Suppose $x_{0} \in \Omega, d\left(x_{0}\right)<\frac{1}{2} \operatorname{dist}\left(x_{0}, \partial \Omega\right)$. Then

$$
u\left(x_{0}\right) \leqslant C \lambda d\left(x_{0}\right)
$$

where $C$ is a constant depending only on $\beta, n$.

Proof. We assume that

$$
\begin{equation*}
u\left(x_{0}\right)>M d\left(x_{0}\right) \tag{2.4}
\end{equation*}
$$

and derive an upper bound on $M$. By scaling (i.e., by considering

$$
\left.\tilde{u}\left(x^{\prime}\right)=\frac{1}{r} u\left(x_{0}+r\left(x^{\prime}-x_{0}\right)\right), \quad r=d\left(x_{0}\right)\right)
$$

we may assume that $d\left(x_{0}\right)=1$. Since $\mathscr{L} u=0$ in $B_{1}\left(x_{0}\right)$, by Harnack's inequality [ $6 ;$ p. 189] and (2.4) we have

$$
\begin{equation*}
\inf _{B_{0 / 4}\left(x_{0}\right)} u \geqslant c u\left(x_{0}\right) \geqslant c M . \tag{2.5}
\end{equation*}
$$

Let $y$ be a point in $\partial B_{1}\left(x_{0}\right) \cap E_{0}$. We define a function $v$ by (2.1) with $B_{r}$ replaced by $B_{1}(y)$. Then $v \geqslant u$ in $B_{1}(y)$ and (cf. (2.3))

$$
\begin{equation*}
\int_{B_{1}(v)}|\nabla(u-v)|^{2} \leqslant C \int_{B_{1}(v)} \lambda^{2} I_{\{u=0\}} . \tag{2.6}
\end{equation*}
$$

Recalling (2.5) we have

$$
v \geqslant c M \quad \text { in } B_{2}\left(x_{0}\right) \cap B_{1}(y)
$$

and then, by Harnack's inequality [6; p. 189],

$$
\begin{equation*}
v \geqslant C^{*} \text { in } B_{\frac{1}{2}}(y), \quad C^{*}=c M \tag{2.7}
\end{equation*}
$$

We take for simplicity $y=0$ and introduce the function

$$
w(x)=C^{*}\left(\exp \left(-\mu|x|^{2}\right)-\exp (-\mu)\right)
$$

We compute

$$
\begin{align*}
& \mathscr{L}_{w(x)}=\nabla \cdot f_{p}(\nabla w(x))=\nabla \cdot f_{p}\left(-2 \mu x C^{*} \exp \left(-\mu|x|^{2}\right)\right)  \tag{2.8}\\
& \quad=f_{p_{j} p_{i}}\left(-2 \mu x C^{*} \exp \left(-\mu|x|^{2}\right)\right)\left(4 \mu^{2} x_{i} x_{j}-2 \mu \delta_{i j}\right) C^{*} \exp \left(-\mu|x|^{2}\right) .
\end{align*}
$$

Hence

$$
\mathscr{L} w(x)>0 \quad \text { if } \frac{1}{2}<|x|<1 \text { and } \mu \text { sufficiently large. }
$$

Thus

$$
w \text { is an } \mathscr{L} \text {-subsolution in } B_{1} \backslash B_{\frac{1}{2}},
$$

$w=0$ on $\partial B_{1}$,
and, by (2.7),

$$
w \leqslant C^{*} \leqslant v \quad \text { on } \partial B_{\frac{1}{2}} .
$$

Since $\mathscr{L}_{v}<\mathscr{L}_{w}$, the proof of the maximum principle gives

$$
v(x) \geqslant C^{*}\left(\exp \left(-\mu|x|^{2}\right)-\exp (-\mu)\right) \geqslant c C^{*}(1-|x|) \quad \text { in } B_{1} \backslash B_{\frac{1}{2}} .
$$

Recalling (2.7) we then have,

$$
\begin{equation*}
v(x) \geqslant c M(1-|x|) \quad \text { in } B_{1} . \tag{2.9}
\end{equation*}
$$

Take two disjoint balls $B_{\frac{1}{d}}\left(y_{i}\right)(i=1,2)$ in $B_{\frac{1}{2}}(y)$. Let $\xi$ vary on $\partial B_{1}(y)$ and denote by $l_{i}(\xi)$ the largest segment with endpoints $\xi, \eta_{i}(\xi)$, going from $\xi$ into $y_{i}$, such that $\eta_{i}(\xi) \notin B_{\frac{1}{8}}\left(y_{i}\right)$ and $u\left(\eta_{i}(\xi)\right)=0 \quad\left(\eta_{i}(\xi)=\xi\right.$ if $\left.u(\xi)>0\right)$. Denote by $S_{i}$ the union of all the segments $l_{i}(\xi)$, and let $S=S_{1} \cup S_{2}$.

As in [1; Lemma 1.3] we get, using (2.9),

$$
c M|S| \leqslant \int_{S}|\nabla(u-v)| \leqslant|S|^{\frac{1}{2}}\left\{\int_{S}|\nabla(u-v)|^{2}\right\}^{\frac{1}{3}},
$$

so that

$$
M^{2}|S| \leqslant C \int_{S}|\nabla(u-v)|^{2} \leqslant C \int_{B_{1}(v)} \lambda^{2} I_{\{u=0\}}
$$

where (2.6) was used. Since $S \supset\{u=0\} \cap B_{1}(y)$, we deduce that $M^{2} \leqslant C \lambda^{2}$ and the assertion of the lemma follows.

Theorem 2.3. $u \in C^{0,1}(\Omega)$; moreover, for any domain $D$ сС $\Omega$ containing a free boundary point the Lipschitz coefficient of $u$ in $D$ is estimated by $C \lambda$ where $C$ depends on $n, \beta, D$ and $\Omega$ only.

Proof. Suppose $d(x)<\frac{1}{3} \operatorname{dist}(x, \partial \Omega)$. By Lemma 2.2 applied to

$$
\tilde{u}\left(x^{\prime}\right)=\frac{1}{d(x)} u\left(x+d(x) x^{\prime}\right)
$$

we have

$$
\tilde{u}\left(x^{\prime}\right) \leqslant C \lambda \quad \text { in } B_{1} .
$$

By elliptic estimates (e.g. Lemma 1.7) we then get

$$
|\nabla \tilde{u}(0)| \leqslant C \lambda,
$$

that is, $|\nabla u(x)| \leqslant C \lambda$. Thus, for any domain $D \subset \subset \Omega,|\nabla u(x)|$ is bounded in $D \cap E_{+} \cap N$ where $N$ is a small neighborhood of the free boundary. Since further $u \in C^{2+\alpha}$ in $E^{+}$, it follows that $u \in C^{0,1}(\Omega)$.

To prove the second part of the theorem, consider any domains $D \subset \subset D^{\prime} \subset \subset \Omega, D$ containing free boundary points. We shall prove that

$$
\begin{equation*}
|\nabla u(x)| \leqslant C \lambda \tag{2.10}
\end{equation*}
$$

for all $x \in D \cap E_{+}$with $C$ depending only on $n, \beta, D, D^{\prime}$ and $\Omega$.
Let $r_{0}=\frac{1}{3} \mathrm{dist}\left(D^{\prime}, \partial \Omega\right) x \in D^{\prime}$. We argue as in [1; Theorem 4.3]. Since $D^{\prime}$ is connected and not contained in $E_{+}$, we find a sequence of points $x_{0}, \ldots, x_{k}$ in $D^{\prime}\left(k\right.$ depending only on $D^{\prime}$ and $\Omega$ ) with

$$
x_{j} \in B_{r_{0} / 2}\left(x_{j-1}\right) \quad \text { for } j=1, \ldots, k,
$$

such that $x_{0}=x, B_{r_{0}}\left(x_{j}\right)$ is contained in $E_{+}$for $j=0, \ldots, k-1$, and such that $B_{r_{0}}\left(x_{k}\right)$ is not contained in $E_{+}$. By Lemma 2.2,

$$
u\left(x_{k}\right) \leqslant C \lambda r_{0} .
$$

Since $u$ is a $\mathscr{L}$-solution in each $B_{r_{0}}\left(x_{j}\right), j=0, \ldots, k-1$, we have, by Harnack's inequality [6; p. 189],

$$
u\left(x_{j+1}\right) \geqslant c u\left(x_{j}\right)
$$

Inductively we then obtain

$$
u(x)=u\left(x_{0}\right) \leqslant C \lambda r_{0} \quad \text { for all } x \in D^{\prime} .
$$

Now let $x \in D \cap E_{+}$. If $d(x)>r_{1} \equiv \frac{1}{2} \operatorname{dist}\left(D, \partial D^{\prime}\right)$, then

$$
|\nabla u(x)| \leqslant \frac{C}{r_{1}} \sup _{D^{\prime}} u \leqslant C \lambda
$$

by the uniform estimate on $u$ in $D^{\prime}$. On the other hand, if $d(x)<r_{1}$ then $|\nabla u(x)| \leqslant C \lambda$ by Lemma 2.2. This completes the proof of the theorem.

As a consequence of Theorem 2.1 we shall prove:
Lemma 2.4. For any domain $D \subset \subset \Omega$ there exists a constant $C$ (depending only on $n, \beta, D$ and $\Omega$ ) such that for any absolute (local) minimum $u$ and for
any (small) ball $B_{r} \subset D$

$$
\begin{equation*}
\text { if } \frac{1}{r} \int_{\partial B_{r}} u \geqslant C \lambda \quad \text { then } u>0 \text { in } B_{r} \text {. } \tag{2.11}
\end{equation*}
$$

Proof. If $B_{r}$ contains a free boundary point then $|\nabla u| \leqslant C \lambda$ in $B_{r}$, by the proof of Theorem 2.3, with $C$ depending on $n, \beta, D$ and $\Omega$ only. Since $u$ vanishes at some point of $B_{r}$ we conclude that

$$
u \leqslant C \lambda r \quad \text { in } \overline{B_{r}},
$$

which contradicts (2.11) if $C$ in (2.11) is large enough.
We next state a nondegeneracy lemma.

Lemma 2.5. For any $p>1$ and for any $0<x<1$ there exists a constant $c_{x}$ such that for any global (local) minimum and for any (small) ball $B_{r} \subset \Omega$

$$
\begin{equation*}
\text { if } \frac{1}{r}\left(f_{B_{r}} u^{p}\right)^{1 / p} \leqslant c_{\varkappa} \lambda \quad \text { then } u=0 \text { in } B_{\varkappa r} \tag{2.12}
\end{equation*}
$$

Proof. Take for simplicity $r=1$; otherwise we work with a scaled function. Set

$$
\varepsilon=\frac{1}{\sqrt{x}} \sup _{B \sqrt{x}} u .
$$

By the $L^{\infty}$ estimate of [6; p. 184],

$$
\varepsilon<C\left(f_{B_{1}} u^{p}\right)^{1 / p} .
$$

Consider the function

$$
v=\left\{\begin{array}{l}
C_{1} \varepsilon\left(\exp \left[-\mu|x|^{2}\right]-\exp \left[-\mu x^{2}\right]\right) \quad \text { in } B_{\sqrt{x}} \backslash B_{x} \\
0 \quad \text { in } B_{x},
\end{array}\right.
$$

By (2.8), $\mathscr{L} v<0$ in $B_{\sqrt{x}} \backslash B_{\varkappa}$ if $\mu$ is small enough; that is, $v$ is a supersolution. We choose $C_{1}$ such that

$$
v=\sqrt{x} \varepsilon \geqslant u \quad \text { on } \quad \partial B_{\sqrt{x}}
$$

Then $\min (u, v)$ is an admissible function and therefore

$$
J(u) \leqslant J(\min (u, v))
$$

which gives

$$
\int_{B_{\varkappa}}(f(\nabla u))+\lambda^{2} I_{\{u>0\}} \leqslant \int_{B_{\sqrt{\chi}} \backslash B_{\varkappa}}\left(f(\nabla \min (u, v))+\lambda^{2} I_{\{\min (u, v)>0\}}\right)
$$

or

$$
\begin{aligned}
\int_{B_{\sqrt{x}}}\left(f(\nabla u)+\lambda^{2} I_{\{u>0\}}\right) \leqslant \int_{B_{\sqrt{x}} \backslash B_{\varkappa}}(f(\nabla \min (u, v)) & -f(\nabla u)) \\
& \leqslant \int_{B_{\sqrt{x}} \backslash B_{x}} \nabla(\min (u, v)-u) \cdot f_{p}(\nabla \min (u, v)) \\
& =-\int_{\left(B_{\sqrt{x}} \backslash B_{\chi}\right) \cap\{u>v\}} \nabla \max (u-v, 0) \cdot f_{p}(\nabla v) \\
& \leqslant \int_{\partial B_{x}} u f_{p}(\nabla v) \cdot v,
\end{aligned}
$$

where we have used the fact that $v$ is a supersolution. Since also

$$
\frac{\partial v}{\partial v} \leqslant C \varepsilon \quad \text { on } \quad \partial B_{\varkappa}
$$

we find that

$$
\begin{equation*}
\int_{B_{B_{x}}}\left(f(\nabla u)+\lambda^{2} I_{\{u>0\}}\right) \leqslant C \varepsilon \int_{\partial B_{x}} u . \tag{2.13}
\end{equation*}
$$

On the other hand we can estimate the last integral by (cf. [1])

$$
\frac{C}{\lambda}\left(\frac{\varepsilon}{\lambda}+1\right) \int_{B_{x}}\left(|\nabla u|^{2}+\lambda^{2} I_{\{u>0\}}\right) \leqslant \frac{C}{\lambda}\left(\frac{\varepsilon}{\lambda}+1\right) \int_{B_{x}}\left(f(\nabla u)+\lambda^{2} I_{\{u>0\}}\right)
$$

Taking $\varepsilon / \lambda$ sufficiently small we then obtain

$$
\int_{B_{x}}\left(|\nabla u|^{2}+\lambda^{2} I_{\{u>0\}}\right)=0,
$$

that is $u=0$ in $B_{x}$.
Remark 2.6. Lemma 2.5 remains true if $B_{r}$ is not contained in $\Omega$ provided $u=0$ in $B_{r} \cap \partial \Omega$. Lemma 2.4 also remains true if $B_{r}$ is not contained in $\Omega$
provided $B_{\alpha r} \subset \Omega, u=0$ on $B_{r} \cap \partial \Omega$, and $B_{r} \cap \partial \Omega$ is smooth, that is any point of $\partial B_{r} / B_{\varepsilon r}(\partial \Omega)$ can be connected with the center of $B_{r}$ by a tube with thickness of order $\varepsilon r$ and length of order $r$ ). Then the statement (2.11) is replaced by:

$$
\frac{1}{r} \int_{\partial B_{r} \backslash B_{a r}(\partial \Omega)} u \geqslant C(\varepsilon, x) \lambda \text { which implies } u>0 \text { in } B_{\varkappa r},
$$

for any given $\varepsilon>0, x<1$; Theorem 2.3 is also valid in $B_{r} \cap \bar{\Omega}$.
Corollary 2.7. For any domain $D \subset \subset \Omega$ there exist positive constants e, $C$ such that if $B_{r}(x)$ is a ball in $D \cap\{u>0\}$ touching $\partial\{u>0\}$, then

$$
c r \leqslant u(x) \leqslant C r .
$$

Theorem 2.8. For any $D \subset \subset$ there exists a constant $c, 0<c<1$, such that for any absolute (local) minimum $u$ and for any (small) ball $B_{r} \subset D$ with center in the free boundary,

$$
\begin{equation*}
c<\frac{\mathfrak{L}^{n}\left(B_{r} \cap\{u>0\}\right)}{\mathscr{L}^{n}\left(B_{r}\right)}<1-c ; \tag{2.14}
\end{equation*}
$$

c depends on $D$, but not on $\lambda$.
Proof. By Lemma 2.5 there exists $y \in B_{r}$ with $u(y)>c \lambda r$. Using Lipschitz continuity we get

$$
f_{\partial B_{x r}(v)} u \geqslant \frac{c \lambda}{2} r
$$

if $x$ is small enough. Hence

$$
\frac{1}{\chi r} f_{\partial B_{x r}(v)} u \geqslant \frac{c \lambda}{2 \varkappa},
$$

which implies, by Lemma 2.4, that $u>0$ in $B_{x r}(y)$. This gives the lower estimate in (2.14).

Next, let $v$ be as in (2.1). Then, by (2.3),

$$
\begin{equation*}
\lambda^{2} \int_{B_{r}} I_{\{u>0\}} \geqslant c \int_{B_{r}}|\nabla(u-v)|^{2} \geqslant \frac{c}{r^{2}} \int_{B_{r}}|u-v|^{2}, \tag{2.15}
\end{equation*}
$$

where Poincare's inequality was used. If $y \in B_{z r}$ ( $\kappa$ small) then, by Harnack's
inequality and Lemma 2.5,

$$
v(y) \geqslant c\left(f_{B_{r / 2}} u^{2}\right)^{1 / 2} \geqslant c \lambda r
$$

By Lipschitz continuity of $u$ we also have

$$
u(y) \leqslant C \lambda \kappa r
$$

Therefore

$$
(v-u)(y) \geqslant c \lambda r
$$

if $x$ is small enough. Substituting this into the right-hand side of (2.15) we find that

$$
\int_{B_{r}} I_{\{u=0\}} \geqslant \frac{c}{\lambda^{2} r^{2}} \int_{B_{x y}}|u-v|^{2} \geqslant \frac{c}{r^{2}} r^{n+2}=c r^{n}
$$

and the upper estimate in (2.14) follows.
Remark 2.9. Theorem 2.8 implies that $\mathbb{L}^{n}(\partial\{u>0\})=0$.

## 3. - The measure $\Lambda=\mathscr{L} u$ and the function $q$.

In Theorem 1.9 we proved that the free boundary condition

$$
\Phi\left(|\nabla u|^{2}\right)=\lambda^{2}
$$

is satisfied in a very weak sense. Since $\Phi(0)=0$ and (by (1.2)) $\Phi^{\prime} \geqslant c>0$ there is a unique value $\lambda^{*}>0$ with

$$
\begin{equation*}
\Phi\left(\lambda^{* 2}\right)=\lambda^{2} \tag{3.1}
\end{equation*}
$$

Hence the free boundary condition can be written as

$$
|\nabla u|=\lambda^{*}
$$

or

$$
\begin{equation*}
-f_{p}(\nabla u) \cdot v=-2 \frac{\partial u}{\partial v} F^{\prime}\left(|\nabla u|^{2}\right)=Q \tag{3.2}
\end{equation*}
$$

if

$$
\begin{equation*}
Q \equiv 2 \lambda^{*} F^{\prime}\left(\lambda^{* 2}\right) \tag{3.3}
\end{equation*}
$$

We shall prove (3.3) in the sense that

$$
\nabla \cdot f_{p}(\nabla u)=Q H^{n-1} \mathcal{L} \partial\{u>0\} \text { in } \Omega,
$$

where, of course, we need the fact that the free boundary $\partial\{u>0\}$ is $(n-1)$ dimensional. This we will show first.

By Lemma 1.2,

$$
\nabla \cdot f_{p}(\nabla u)=\Lambda
$$

where $\Lambda$ is a positive Radon measure supported on the free boundary

$$
\Gamma=\partial\{u>0\} \cap \Omega .
$$

In the sequel we shall not indicate the explicit dependence of constants upon $\lambda$.

Theorem 3.1. For any $D \subset \subset \Omega$ there exist positive constants $c, C$ such that for any ball $B_{r} \subset D$ with center in the free boundary

$$
\begin{equation*}
e r^{n-1} \leqslant \int_{B_{r}} d \Lambda \leqslant C r^{n-1} . \tag{3.4}
\end{equation*}
$$

Proof. Let $\zeta \in C_{0}^{\infty}(\Omega), \zeta \geqslant 0$. Then

$$
\int_{\Omega} \zeta d \Lambda=\int_{\Omega} \nabla \zeta \cdot f_{p}(\nabla u) .
$$

Approximating $I_{B_{r}}$ from below by suitable test functions $\zeta$ we get, using the Lipschitz continuity $u$, that for almost all $r$,

$$
\int_{B_{r}} d \Lambda=\int_{\partial B_{r}} v \cdot f_{p}(\nabla u) d H^{n-1} \leqslant C r^{n-1} .
$$

To establish the left-hand side of (3.4) we may normalize by taking $r=1$. Set

$$
\widetilde{\mathscr{L}} v=\nabla \cdot(a \nabla v) \quad\left(a(x)=F^{\prime}\left(|\nabla u(x)|^{2}\right)\right) .
$$

This is a linear selfadjoint uniformly elliptic operator. Denote its Green's function in $B_{1}$ with pole $x$ by $G_{x}$. By [6; p. 184], if

$$
\begin{aligned}
\tilde{\mathscr{L}} v=f & \text { in } B_{1}, \\
v=0 & \text { on } \partial B_{1}
\end{aligned}
$$

then

$$
\begin{equation*}
|v|_{L^{\infty}\left(B_{1 / 2}\right)} \leqslant C|f|_{L^{p}\left(B_{1}\right)} \quad \text { if } p>\frac{n}{2} . \tag{3.5}
\end{equation*}
$$

Representing $v$ in terms of Green's function we deduce that (3.5) for all $f$ means

$$
\begin{equation*}
\sup _{x \in B_{1 / 2}, B_{1}} \int_{x} G_{x}^{a} \leqslant C \quad\left(\frac{1}{q}+\frac{1}{p}=1\right) . \tag{3.6}
\end{equation*}
$$

Now let $x \in B_{\frac{1}{2}} \backslash \bar{B}_{\frac{1}{2}}$. Then $\tilde{\mathscr{L}} G_{x}=0$ in $B_{\frac{1}{2}}$ and, by (3.6), $G_{x}$ is bounded in $L^{a}\left(B_{2}\right)$. Hence, by elliptic estimates [ $\left.6 ; p .184\right]$

$$
G_{x}(y) \leqslant C \quad \text { if } y \in B_{\frac{1}{1}}, x \in B_{\frac{1}{}} \backslash B_{\frac{1}{}},
$$

and by the symmetry of Green's function

$$
G_{y}(x) \leqslant C \quad \text { if } y \in G_{k}, x \in B_{i} \backslash B_{t} .
$$

Similarly

$$
\begin{array}{ll}
G_{y}(x) \leqslant C \quad \text { if } x \in D_{1}, y \in D_{2}, & \operatorname{dist}\left(D_{1}, D_{2}\right) \geqslant \delta, \\
D_{1} \cup D_{2} \subset B_{1}, & \operatorname{dist}\left(D_{2}, \partial B_{1}\right) \geqslant \delta \tag{3.7}
\end{array}
$$

where $C$ is a constant depending on $\delta$ but not on $D_{1}, D_{2}$.
Now let $w$ be the solution of

$$
\begin{aligned}
\widetilde{\mathscr{L}} w=0 & \text { in } B_{1} \\
w=u & \text { on } \partial B_{1} .
\end{aligned}
$$

By nondegeneracy, for any $0<x<1$ there exists a point $y \in B_{x}$ with $u(y)>c x$. By Lipschitz continuity,

$$
u>0 \quad \text { in } B_{c(x)}(y)
$$

with $c(\varkappa)$ sufficiently small; hence also $d \Lambda=0$ in $B_{c(x)}(y)$. Since

$$
\tilde{\mathscr{L}}(w-u)=\Lambda, \quad w=0 \text { on } \partial B_{1},
$$

we can write

$$
\begin{equation*}
(w-u)(y)=\int_{B_{1}} G_{y} d \Lambda=\int_{B_{1} \backslash B_{c(x)}(v)} G_{y} d \Lambda \leqslant C(\chi) \int_{B_{1}} d \Lambda \tag{3.8}
\end{equation*}
$$

where we have used (3.7) with $\delta=\delta(\varkappa)$.

By the maximum principle $w \geqslant u$; therefore, by nondegeneracy (for $p>1$ )

$$
\left(f_{B_{1 / 2}} w^{p}\right)^{1 / p} \geqslant\left(f_{B_{1 / 3}} u^{p}\right)^{1 / p} \geqslant c \quad(c>0)
$$

Using Harnack's inequality $[6 ; \mathrm{p} .184]$, if $p<n /(n-2)$, we get

$$
w(y) \geqslant c\left(f_{B_{1}} w^{p}\right)^{1 / p} \geqslant c
$$

Also, since $u$ vanishes at the center of $B_{1}$, by Lipschitz continuity,

$$
u(y) \leqslant C x .
$$

Choosing $x$ small enough we get

$$
w(y)-u(y) \geqslant c-C u>\frac{c}{2}
$$

and recalling (3.8) we obtain

$$
\int_{B_{1}} d \Lambda \geqslant c
$$

The next theorem follows easily from Theorem 3.1, precisely as in [1].
Theorem 3.2 (Representation theorem). Let u be a local minimum. Then:
(1) $H^{n-1}(D \cap \partial\{u>0\})<\infty$ for every $D \subset \subset \Omega$.
(2) There is a Borel measure $q_{u}$ such that

$$
\mathscr{L} u=q_{u} H^{n-1} £ \partial\{u>0\}
$$

that is, for every $\zeta \in C_{0}^{\infty}(\Omega)$

$$
-\int_{\Omega} \nabla \zeta \cdot f_{p}(\nabla u)=\int_{\Omega \cap \hat{0}\{u>0\}} \zeta q_{u} d H^{n-1}
$$

(3) For any $D \subset \subset \Omega$ there exist positive constants $c, C$ such that for every ball $B_{r}(x) \subset D$ with $x \in \partial\{u>0\}$,

$$
c \leqslant q_{u}(x) \leqslant C, \quad c r^{n-1} \leqslant H^{n-1}\left(B_{r}(x) \cap \partial\{u>0\}\right) \leqslant C r^{n-1}
$$

From (1) it follows [5; 4.5.11] that the set $A=\{u>0\}$ has a finite perimenter locally in $\Omega$, that is, $\mu_{u} \equiv-\nabla I_{A}$ is a Borel measure. We denote by $\partial_{\text {red }} A$ the reduced boundary of $A$, i.e., the set of points $x \in \Omega$ for which the normal $\nu_{u}(x)$ of $A$ at $x$ exists and $\left|v_{u}(x)\right|=1$; see [5] [7].

We shall deal with blow up sequences

$$
u_{m}(x)=\frac{1}{\varrho_{m}} u\left(x_{m}+\varrho_{m} x\right), \quad u\left(x_{m}\right)=0, \quad x_{m} \rightarrow x_{0} \in \Omega
$$

Since $|\nabla u| \leqslant C$, for a subsequence,

$$
\begin{align*}
u_{m} \rightarrow u_{0} & \text { uniformly in } C_{\mathrm{loc}}^{\alpha}, \text { for all } \alpha<1,  \tag{3.9}\\
\nabla u_{m} \rightarrow \nabla u_{0} & \text { weakly star in } L_{\mathrm{loc}}^{\infty}, \tag{3.10}
\end{align*}
$$

We also have:
(3.11) $\partial\left\{u_{m}>0\right\} \rightarrow \partial\left\{u_{0}>0\right\}$ locally in the Hausdorff distance,
(3.12) $I_{\left\{u_{m}>0\right\}} \rightarrow I_{\left\{u_{0}>0\right\}} \quad$ in $L_{\text {loc }}^{1}$,
(3.13) $\nabla u_{m} \rightarrow \nabla u_{0} \quad$ a.e.

The proof of (3.11) follows from (3.9) and the nondegeneracy. The same arguments show that if $x_{m} \in \partial\left\{u_{m}>0\right\}$ then $x_{0} \in \partial\left\{u_{0}>0\right\}$.

To prove (3.12) let $x \in \partial\left\{u_{0}>0\right\} \cap \Omega$. Then there exists a sequence $y_{m} \in \partial\left\{u_{m}>0\right\}$ such that $y_{m} \rightarrow x$. By nondegeneracy (Lemma 2.5 with $p=2$ )

$$
\frac{1}{r}\left(\int_{\partial B_{r}\left(v_{m}\right)} u_{m}^{2}\right)^{1 / 2} \geqslant c
$$

Hence

$$
\frac{1}{r}\left(f_{\partial B_{r}(x)} u_{0}^{2}\right)^{1 / 2} \geqslant c
$$

Since $u_{0}$ is clearly also in $C^{0,1}$, the proof of Theorem 2.8 applies to $u_{0}$. Consequently

$$
\mathcal{L}^{n}\left(\partial\left\{u_{0}>0\right\}\right)=0
$$

Combining this fact with (3.11), the assertion (3.12) follows.
By elliptic estimates

$$
\nabla u_{m} \rightarrow \nabla u_{0} \quad \text { uniformly in compact subsets of }\left\{u_{0}>0\right\}
$$

and

$$
\begin{equation*}
\nabla \cdot f_{p}\left(\nabla u_{0}\right)=0 \quad \text { in }\left\{u_{0}>0\right\} . \tag{3.14}
\end{equation*}
$$

Thus in order to prove (3.13) it remains to show that

$$
\begin{equation*}
\nabla u_{m} \rightarrow \nabla u_{0} \quad \text { a.e. on }\left\{u_{0}=0\right\} \tag{3.15}
\end{equation*}
$$

In the set $\left\{u_{0}=0\right\}$ a.a. points $x_{0}$ have density 1 ; denote the set of such points by $S$. We claim that if $x_{0} \in S$ then

$$
\begin{equation*}
u_{0}\left(x_{0}+x\right)=o(|x|) \tag{3.16}
\end{equation*}
$$

Indeed, if $u_{0}(y)>\gamma r$ for some $y \in B_{r}\left(x_{0}\right), \gamma>0$ and a sequence $r \rightarrow 0$, then (by the Lipschitz continuity of $u_{0}$ )

$$
u_{0}>\frac{\gamma}{2} r \quad \text { in } B_{c \gamma r}(y)
$$

for some small $c>0$. This means that $\left\{u_{0}>0\right\}$ has positive density at $x_{0}$, contradicting $x_{0} \in S$.

From (3.16) we deduce that, for any $\varepsilon>0$,

$$
\frac{u_{m}}{r}<\varepsilon \quad \text { in } B_{r}\left(x_{0}\right) \text { for small } r,
$$

provided $m$ is large enough, say $m \geqslant m_{0}(\varepsilon, r)$. By nondegeneracy it then follows that $u_{m}=0$ in $B_{r / 2}\left(x_{0}\right)$ and, consequently, $u_{0}=0$ in a neighborhood of $x_{0}$. Thus the set $S$ is open. Furthermore, the above argument shows that $u_{m}=u_{0}$ in any compact subset of $S$, if $m$ is large enough. This completes the proof of (3.15).

In order to identify the function $q_{u}$ in Theorem 3.2, we need the following two important statements about the minimum.

Lemma 3.3. If $u\left(x_{m}\right)=0, x_{m} \rightarrow x_{0} \in \Omega$, then any blow up limit $u_{0}$ with respect to $B_{\varrho_{m}}\left(x_{m}\right)$ is absolute minimum for $J$ in any ball.

Proof. Let

$$
u_{m}(x)=\frac{1}{\varrho_{m}} u\left(x_{m}+\varrho_{m} x\right)
$$

and suppose that (3.9), (3.10) hold. Then also (3.11)-(3.13) are satisfied.

Set $D=B_{R}(0)$ and take any $v, v-u_{0} \in H_{0}^{1,2}(D), \eta \in C_{0}^{\infty}(D), 0 \leqslant \eta \leqslant 1$. Let

$$
v_{m}=v+(1-\eta)\left(u_{m}-u_{0}\right)
$$

Since $v_{m}=u_{m}$ on $\partial D$,

$$
\begin{equation*}
\int_{D}\left(f\left(\nabla u_{m}\right)+\lambda^{2} I_{\left\{u_{m}>0\right\}}\right) \leqslant \int_{\boldsymbol{D}}\left(f\left(\nabla v_{m}\right)+\lambda^{2} I_{\left\{v_{m}>0\right\}}\right) . \tag{3.17}
\end{equation*}
$$

Since $\left|\nabla u_{m}\right| \leqslant C, \nabla u_{m} \rightarrow \nabla u_{0}$ a.e.,

$$
\int_{D} f\left(\nabla u_{m}\right) \rightarrow \int_{D} f\left(\nabla u_{0}\right) \quad \text { as } m \rightarrow \infty
$$

Similarly

$$
\int_{\boldsymbol{D}} f\left(\nabla v_{m}\right) \rightarrow \int_{\boldsymbol{D}} f(\nabla v)
$$

Noting also that

$$
I_{\left\{v_{m}>0\right\}} \leqslant I_{\{v>0\}}+I_{\{\eta<1\}},
$$

we obtain from (3.17)

$$
\int_{\mathcal{D}}\left(f\left(\nabla u_{0}\right)+\lambda^{2} I_{\left\{u_{0}>0\right\}}\right) \leqslant \int_{D}\left(f(\nabla u)+\lambda^{2} I_{\{v>0\}}\right)+\gamma(\eta)
$$

where $\gamma(\eta)=\lambda^{2} \int_{D} I_{\{\eta<1\}}$. Choosing a sequence of $\eta$ 's with $\gamma(\eta) \rightarrow 0$, the assertion follows.

Next we prove an estimate for $|\nabla u|$ at the free boundary from above (see [1; Remark 6.4]), which will also be used in Section 4, where we prove the corresponding Hölder estimate.

Lemma 3.4. Let $u$ be a local minimum and let $\lambda^{*}$ be defined by (3.1). If $x_{0} \in\{u>0\}$ then

$$
\begin{equation*}
\lim _{x \rightarrow x_{0}, u(x)>0}|\nabla u(x)|=\lambda^{*} \tag{3.18}
\end{equation*}
$$

Proof. Denote the left-hand side of (3.18) by $\gamma$. Then there exists a sequence $z_{k}$ such that

$$
u\left(z_{k}\right)>0, \quad\left|\nabla u\left(z_{k}\right)\right| \rightarrow \gamma .
$$

Denote by $y_{k}$ the nearest point to $z_{k}$ on $\partial\{u>0\}$ and set $\varrho_{k}=\left|z_{k}-y_{k}\right|$.

Consider a blow up sequence about $B_{e_{k}}\left(y_{k}\right)$ with limit $\mu_{0}$, such that

$$
\frac{z_{k}-y_{k}}{\varrho_{k}} \rightarrow-e_{n} .
$$

Then $u_{0}$ is $\mathscr{L}$-subsolution in $R^{n}$ and $\mathscr{L} u_{0}=0$ in $\left\{u_{0}>0\right\}$. By Lemma 3.3 the blow-up limit $u_{0}$ is an absolute minimum, hence $B_{1}\left(-e_{n}\right)$ is contained in $\left\{y_{0}>0\right\}$ by (3.12). Moreover $u_{0}(0)=0$ and

$$
\begin{aligned}
& \left|\nabla u_{0}\right| \leqslant \gamma \quad \text { in }\left\{u_{0}>0\right\}, \\
& \left|\nabla u_{0}\left(-e_{0}\right)\right|=\gamma
\end{aligned}
$$

which implies that $\gamma>0$.
Choose a unit vector $e$ such that

$$
\left|\nabla u_{0}\left(-e_{n}\right)\right|=-\nabla u_{0}\left(-e_{n}\right) \cdot e
$$

and consider the function $\partial u_{0} / \partial e$. We have (see the proof of Lemma 1.7)

$$
\mathscr{L}_{0}\left(\frac{\partial u_{0}}{\partial e}\right)=0 \quad \text { in }\left\{u_{0}>0\right\}
$$

where $\mathscr{L}_{0}$ is a uniformly divergence-form elliptic operator. Also

$$
\begin{align*}
& \frac{\partial u_{0}}{\partial e} \geqslant-\gamma \quad \text { in } B_{1}\left(-e_{n}\right),  \tag{3.19}\\
& \frac{\partial u_{0}\left(-e_{n}\right)}{\partial e}=-\gamma
\end{align*}
$$

Applying the maximum principle we conclude from (3.19) that

$$
\frac{\partial u_{0}(x)}{\partial e}=-\gamma \quad \text { or } u_{0}(x)=-\gamma x \cdot e+c \text { for } x \in B_{1}\left(-e_{n}\right)
$$

Since $u_{0}(0)=0$ and $u_{0}>0$ in $B_{1}\left(-e_{n}\right)$, the constant $c$ is equal to zero and $e=e_{n}$. Thus

$$
u_{0}(x)=-\gamma x_{n} \quad \text { for } x \in B_{1}\left(-e_{n}\right) .
$$

By continuation the same argument shows that

$$
\begin{equation*}
u_{0}(x)=-\gamma x_{n} \quad \text { whenever } x_{n} \leqslant 0 . \tag{3.20}
\end{equation*}
$$

We next claim that

$$
\begin{equation*}
u_{0}=0 \quad \text { in some strip }\left\{0<x_{n}<\varepsilon_{0}\right\} \tag{3.21}
\end{equation*}
$$

Indeed, suppose this is not true, and define

$$
s=\limsup _{\substack{x_{n} \nmid 0, u_{0}\left(x^{\prime}, x_{n}\right)>0 \\ x^{\prime} \in R^{n-1}}} \frac{\partial u_{0}\left(x^{\prime}, x_{n}\right)}{\partial x_{n}}
$$

By Lipschitz continuity of $u, u_{0}$ is uniformly Lipschitz continuous and thus $s<\infty$. Suppose $s>0$ and let

$$
\frac{\partial u_{0}}{\partial x_{n}}\left(y_{k}, h_{k}\right) \rightarrow s, \quad h_{k} \downarrow 0
$$

Consider a blow up sequence with respect to $B_{h_{k}}\left(y_{k}, 0\right)$ with limit $u_{00}$. Arguing as before we conclude that

$$
u_{00}\left(x^{\prime}, x_{n}\right)=s x_{n} \quad \text { for all } x_{n}>0
$$

But we also have (by (3.20))

$$
u_{00}\left(x^{\prime}, x_{n}\right)=-\gamma x_{n} \quad \text { for all } x_{n}<0
$$

Thus, $u_{00}$ is a minimum (Lemma 3.3), and any point ( $x^{\prime}, 0$ ) is a free boundary point. It follows that the set $\left\{u_{00}=0\right\}$ has density zero at any point ( $x^{\prime}, 0$ ), a contradiction to Theorem 2.8.

We have thus proved that $s=0$ and, consequently, $u_{0}\left(x^{\prime}, x_{n}\right)=o\left(x_{n}\right)$ if $x_{n} \downarrow 0$. Hence, for any $\varepsilon>0$,

$$
\frac{1}{r}\left(f_{B_{r}\left(x_{0}\right)} u_{0}^{2}\right)^{1 / 2}<\varepsilon
$$

for any $x_{0}=\left(y_{0}, h_{0}\right), r=h_{0}$, with $h_{0}$ small enough. It follows, by nondegeneracy, that $u_{0}=0$ in some strip $\left\{0<x_{n}<\varepsilon_{0}\right\}$, which contradicts the assumption that (3.21) was not satisfied.

Having proved (3.20), (3.21) we can now apply Theorem 1.9 to deduce that, on the free boundary $\left\{x_{n}=0\right\},\left|\nabla u_{0}\right|$ coincides with $\lambda^{*}, i . e ., \gamma=\lambda^{*}$.

In the next statement we use the following notation (see [5; 3.1.21]). For any set $E$ and $x_{0} \in E$ we define the (topological) tangent plane of $E$
at $x_{0}$ by

$$
\operatorname{Tan}\left(E, x_{0}\right)=\left\{v ; v=\lim _{m \rightarrow 0} r_{m} v_{m}, r_{m}>0, x_{0}+v_{m} \in E, v_{m} \rightarrow 0\right\}
$$

Theorem 3.5 (Identification of $q_{u}$ ). Let $x_{0} \in \partial_{\text {red }}\{u>0\}$ and suppose that

$$
\theta^{* n-1}\left(\boldsymbol{H}^{n-1} £ \partial\{u>0\}, x_{0}\right) \leqslant 1 .
$$

Then $\operatorname{Tan}\left(\partial\{u>0\}, x_{0}\right)=\left\{x ; x \cdot v_{u}\left(x_{0}\right)=0\right\}$. If, in addition,

$$
\int_{B_{r}\left(x_{0}\right)}\left|q_{n \partial\{n>0\}}-q_{u}\left(x_{0}\right)\right| d H^{n-1}=o\left(r^{n-1}\right) \quad \text { as } r \rightarrow 0
$$

then,$q_{u}\left(x_{0}\right)=Q$ and, as $x \rightarrow 0$,

$$
\begin{equation*}
u\left(x_{0}+x\right)=\lambda^{*} \max \left\{-x \cdot v_{u}\left(x_{0}\right), 0\right\}+o(|x|) \tag{3.22}
\end{equation*}
$$

where $\lambda^{*}, Q$ are defined as in (3.1) and (3.2).
Proof. Take for simplicity $v_{u}\left(x_{0}\right)=e_{n}$. Let $u_{m}$ be a blow up sequence with respect to balls $B_{e_{m}}\left(x_{0}\right)$, with blow up limit $u_{0}$. Then $I_{\left\{u_{m}>0\right\}}$ converges in $L_{\text {loc }}^{1}$ to $I_{\left\{u_{0}>0\right\}}\left(\right.$ by (3.12)) and to $I_{\left\{u_{n}>0\right\}}$ since,

$$
\int_{B_{r}(x)}\left|I_{\{u>0\}}-I_{\left\{v ;\left(y-r_{0}\right) \cdot v_{u}\left(x_{0}\right)>0\right\}}\right|=o\left(r^{n}\right) \quad \text { as } r \rightarrow 0,
$$

if $\nu_{u}\left(x_{0}\right)$ is the normal to $\{u>0\}$ at $x_{0}$. It follows that $u_{0}=0$ in $\left\{x_{n} \geqslant 0\right\}$ and $u_{0}>0$ a.e. in $\left\{x_{n}<0\right\}$.

In order to show that $x_{0}>0$ in $\left\{x_{n}<0\right\}$, we proceed as in [1; p. 121] to deduce that

$$
H^{n-1}\left(\partial\left\{u_{m}>0\right\} \cap D\right) \rightarrow 0 \quad \text { if } m \rightarrow \infty
$$

for any $D \subset \subset\left\{x_{n}<0\right\}$. We then conclude that for any $\zeta \in C_{0}^{\infty}(D)$

$$
\begin{equation*}
-\int_{D} f_{p}\left(\nabla u_{0}\right) \cdot \nabla \zeta \leftarrow-\int_{D} f_{p}\left(\nabla u_{m}\right) \cdot \nabla \zeta=\int_{\partial\left\{u_{m}>0\right\}} \zeta(x) q_{u}\left(x_{0}+\varrho_{m} x\right) d H^{n-1}(x) \rightarrow 0 \tag{3.23}
\end{equation*}
$$

where (3.13) was used. Thus $u_{0}$ is a solution of $\mathscr{L} u_{0}=0$ and it is therefore smooth in $\left\{x_{n}<0\right\}$ (Lemma 1.7). The maximum principle now implies that $u_{0}>0$ in $\left\{x_{n}<0\right\}$.

Now let

$$
\zeta(x)=\min \left(2\left(1-\frac{\left|x_{n}\right|}{2}\right), 1\right) \eta\left(x_{1}, \ldots, x_{n-1}\right)
$$

where $\eta \in C_{0}^{\infty}\left(B_{r}^{\prime}\right), \eta \geqslant 0\left(B_{r}^{\prime}\right.$ is an $(n-1)$-dimensional ball with radius $r$ ). Proceeding as in [1; p. 121] and using also (3.13), we get

$$
\begin{align*}
\int_{R^{n}} f_{\mathcal{D}}\left(\nabla u_{0}\right) \cdot \nabla \zeta= & -\lim _{m \rightarrow \infty} \int_{\mathcal{K}^{n}} f_{p}\left(\nabla u_{m}\right) \cdot \nabla \zeta  \tag{3.24}\\
& =\lim _{m \rightarrow \infty} \int_{\partial\left(u_{m}>0\right\}} \zeta q_{u}\left(x_{0}+\varrho_{m} x\right) d H^{n-1}=q_{u}\left(x_{0}\right) \int_{R^{n-1}} \eta d H^{n-1} .
\end{align*}
$$

Notice that, unlike in (3.23), the test functions here are not supported just in $\left\{x_{n}<0\right\}$. From (3.24) we deduce the boundary conditions

$$
\begin{equation*}
f_{p}\left(\nabla u_{0}\right) \cdot e_{n}=q_{u}\left(x_{0}\right) \quad \text { on }\left\{x_{n}=0\right\}, \tag{3.25}
\end{equation*}
$$

in the sense that

$$
-\int_{B_{r} \cap\left\{x_{n}>0\right\}} f_{p}\left(\nabla u_{0}\right) \cdot \nabla \zeta=q_{u}\left(x_{0}\right) \int_{B_{r}^{\prime}} \zeta\left(x^{\prime}, 0\right) d H^{n-1} \quad \forall \zeta \in C_{0}^{1}\left(B_{r}\right) .
$$

Since $\mathscr{L} u_{0}=0$ in $\left\{x_{n}<0\right\}$, by boundary regularity for elliptic equations (see proof of Lemma 1.7) it follows that $u_{0}$ satisfies (3.25) in the classical sense.

Since furthermore $u_{0}$ is an absolute minimum (Lemma 3.3) we deduce from Theorem 1.9 that

$$
\begin{equation*}
\frac{\partial u_{0}}{\partial \nu}=-\lambda^{*} \quad \text { on } \partial\left\{x_{n}<0\right\} \tag{3.26}
\end{equation*}
$$

or $q_{u}\left(x_{0}\right)=Q$.
We have to show that $u_{0}$ is a half plane solution with slope $\lambda^{*}$. To prove this we use Lemma 3.4, which tells us that

$$
0<u_{0}(x) \leqslant-\lambda^{*} x_{n} \quad \text { if } x_{n}<0,
$$

and $\widetilde{\mathscr{L}} u_{0}=0$ in $\left\{u_{0}<0\right\}$, where

$$
\widetilde{\mathscr{L}} w=f_{p, p}\left(\nabla u_{0}\right) \partial_{i j} w .
$$

Therefore, the function

$$
v(x) \equiv-\lambda^{*} x_{n}-u_{0}(x)
$$

is nonnegative in $\left\{x_{0}<0\right\}$ and $\widetilde{\mathscr{L}} v=0$. Hence, if $v$ is positive at some point in $\left\{x_{n}<0\right\}$, it must be positive everywhere in $\left\{x_{n}<0\right\}$, by the maximum principle, and, further,

$$
\frac{\partial v}{\partial \nu}<0 \quad \text { on } \partial\left\{x_{n}<0\right\}
$$

that is, $\partial u_{0} / \partial v>-\lambda^{*}$, which contradicts (3.26). Consequently $v=0$ in $\left\{x_{n}<0\right\}$, that is,

$$
u_{0}(x)= \begin{cases}-\lambda^{*} x_{n} & \text { for } x_{n} \leqslant 0 \\ 0 & \text { for } x_{n} \geqslant 0\end{cases}
$$

Since finally the blow up sequence was arbitrary whereas the limit is unique, the assertion (3.22) follows.

Since the conclusion of Theorem 3.5 holds for $H^{n-1}$ a.a. $x_{0} \in \hat{C}_{\text {red }}\{u>0\}$ we obtain:

Theorem 3.6. For $H^{n-1}$ a.a. $x$ in $\partial_{\text {red }}\{u>0\}$

$$
q_{u}(x)=Q .
$$

Remark 3.7. From the positive density property (Theorem 2.8 and $\left[5 ; 4.5 .6\right.$ (3)] it follows that $H^{n-1}\left(\{u>0\} \backslash \partial_{\text {red }}\{u>0\}\right)=0$. Hence

$$
\begin{equation*}
q_{u}=Q \quad H^{n-1} \text { a.e. } \quad \text { on } \partial\{u>0\} . \tag{3.27}
\end{equation*}
$$

## 4. - Estimates on $|\nabla u|$.

For the regularity theory of the free boundary we need the following strengthened version of Lemma 3.4.

Theorem 4.1. Let $u$ be a local minimum. For any $D \subset \subset \Omega$ there exist positive constants $C, \alpha<1$ depending only on $\beta, \lambda$ and $D$ such that, for any ball $B_{r}(x) \subset D$ which intersects the free boundary,

$$
\begin{equation*}
\sup _{B_{r}(x)}|\nabla u(x)| \leqslant \lambda^{*}+C r^{\alpha} \tag{4.1}
\end{equation*}
$$

Proof. We have

$$
a_{i j}(\nabla u) \partial_{i,} u=0 \quad \text { in }\{u>0\}
$$

where the uniformly positive and bounded matrix $a_{i j}$ is defined as in (1.9).

Therefore, by [6; pp. 270-271], the function $v=|\nabla u|^{2}$ satisfies

$$
\begin{equation*}
\mathscr{H} v \equiv \partial_{i}\left(\exp (\gamma v) a_{i j}(\nabla u) \partial_{j} v\right) \geqslant 0 \quad \text { in }\{u>0\} \tag{4.2}
\end{equation*}
$$

where $\gamma$ is some positive constant. For any $\varepsilon>0$, the function

$$
U_{\varepsilon}=\left(|\nabla u|^{2}-\left(\lambda^{*}\right)^{2}-\varepsilon\right)^{+}
$$

is $\mathcal{M}$-subsolution in $\{u>0\}$ and, by Lemma 3.4, it vanishes in a neighborhood of the free boundary. We extend $U_{\varepsilon}$ by 0 into $\{u=0\}$ and set

$$
h_{\varepsilon}(r)=\sup _{B_{r}} U_{\varepsilon}
$$

for any $r$, where the origin is taken to be a free boundary point. Then $h_{\varepsilon}(r)-U_{\varepsilon}$ is $\mathcal{N}$-supersolution in the entire ball $B_{r}$ and

$$
\begin{aligned}
h_{\varepsilon}(r)-U_{\varepsilon} & \geqslant 0 & & \text { in } B_{r} \\
& =h_{\varepsilon}(r) & & \text { in } \widetilde{B}_{r}=B_{r} \cap\{u=0\}
\end{aligned}
$$

By $[6 ; p .193]$ with $1 \leqslant p<n /(n-2)$,

$$
\inf _{B_{r / 2}}\left[h_{\varepsilon}(r)-U_{\varepsilon}(x)\right] \geqslant c r^{-n / p}\left\|h_{\varepsilon}-U_{\varepsilon}\right\|_{L^{p}\left(B_{r}\right)} \geqslant c h_{\varepsilon}(r)
$$

since $\mathcal{L}^{n}\left(\widetilde{B}_{r}\right) \geqslant c r^{n}$ by the positive density property (Theorem 2.8). Taking $\varepsilon \rightarrow 0$ we get

$$
\inf _{B_{r / 2}}\left[h_{0}(r)-U_{0}\right] \geqslant c h_{0}(r) \quad(0<c<1)
$$

or

$$
\sup _{B_{r / 2}} U_{0} \leqslant(1-c) h_{0}(r)
$$

Thus

$$
h_{0}\left(\frac{r}{2}\right) \leqslant(1-c) h_{0}(r)
$$

from which we deduce that $h_{0}(x) \leqslant C s^{\alpha}$ for some $C>0,0<\alpha<1$, and (4.1) follows.

Remark 4.2. If, in Theorem 4.1, $B_{r}(x) \subset B_{R}(x) \subset D$ then

$$
\begin{equation*}
\sup _{B_{r}}|\nabla u| \leqslant \mu+O\left(\frac{r}{R}\right)^{\alpha} . \tag{4.3}
\end{equation*}
$$

Indeed, this follows by applying Theorem 4.1 to $\tilde{u}\left(x^{\prime}\right)=(1 / R) u\left(x+R x^{\prime}\right)$.

Theorem 4.3. Let $n=2$ and assume that $u$ is any local minimum and that $D \subset \subset \Omega$. Then for any small ball $B_{r} \subset D$ with center in the free boundary,

$$
\begin{equation*}
\int_{B_{r} \cap\{u>0\}}\left(\lambda^{* 2}-|\nabla u|^{2}\right)^{+} \leqslant \frac{C}{\log (1 / r)} \tag{4.4}
\end{equation*}
$$

Proof. For any $\zeta \in C_{0}^{\infty}(\Omega), \zeta \geqslant 0, \varepsilon>0$, the function

$$
v \equiv u-\min (u, \varepsilon \zeta)=\max (u-\varepsilon \zeta, 0)
$$

is admissible, so that $J(u) \leqslant J(v)$, or

$$
\begin{equation*}
\int_{\{0<u \leqslant \varepsilon\}\}} \lambda^{2}=\int[f(\nabla v)-f(\nabla u)] \equiv I \tag{4.5}
\end{equation*}
$$

We have

$$
\begin{aligned}
& f(\nabla v)-f(\nabla u)=\int_{0}^{1} f_{p}(\nabla u+t \nabla(v-u)) \cdot \nabla(v-u) d t \\
& \quad=f_{p}(\nabla u) \cdot \nabla(v-u)+\int_{0}^{1} d t \int_{0}^{t} \nabla(v-u) f_{p p}(\nabla u+s \nabla(v-u)) \nabla(v-u) d s .
\end{aligned}
$$

On the set $\{u>\varepsilon \zeta\}$ we have $v-u=-\varepsilon \zeta$, hence

$$
\int_{\{u>s \varepsilon\}} \int_{0}^{1} d t \int_{t}^{1} \nabla(v-u) f_{p p}(\nabla u+s \nabla(v-u)) \nabla(v-u) d s \leqslant \sigma \varepsilon^{2} \int_{\{u>\varepsilon \zeta\}}|\nabla \zeta|^{2} .
$$

On the set $\{u \leqslant \varepsilon \zeta\}$ we have $v=0$ and thus

$$
\int_{\{u \leq e \zeta\}} \int_{0}^{1} d t \int_{0}^{t} \nabla(v-u) f_{p p}(\nabla u+s \nabla(v-u)) d s=\int_{\{u \leqslant s\}\}} \int_{0}^{1} d t \int_{i}^{1} \nabla u f_{p p}((1-s) \nabla u) \nabla u d s
$$

Next

$$
\begin{aligned}
0=-f(0) & =f(\nabla u)-\int_{0}^{1} f_{v}((1-t) \nabla u) \cdot(\nabla u) d t \\
& =f(\nabla u)-f_{p}(\nabla u) \cdot \nabla u+\int_{0}^{1} d t \int_{0}^{t} \nabla u f_{p p}((1-s) \nabla u)(-\nabla u) d s .
\end{aligned}
$$

Combining these facts we find that

$$
I \leqslant \int_{\{u \leqslant \varepsilon \zeta\}}\left(f_{p}(\nabla u) \cdot \nabla u-f(\nabla u)\right)+C \varepsilon^{2} \int_{\{u>\varepsilon \zeta\}}|\nabla \zeta|^{2}+\int_{\Omega} f_{p}(\nabla u) \nabla(v-u)
$$

In the last integral the integrand vanishes on the set $\{u=0\}$. Since also $v-u=0$ on $\partial\{u>0\}$ and $\nabla \cdot f_{p}(\nabla u)=0$ on $\{u>0\}$, this integral vanishes. (for a rigorous proof approximate $v-u$ by $-\min (u-\delta, \varepsilon \zeta)$ for $\delta>0$.) We thus obtain from (4.5) and (3.1), (1.10),

$$
\begin{equation*}
\int_{\{0<u \leqslant \varepsilon \xi\}} \Phi\left(\lambda^{* 2}\right) \leqslant \int_{\{0<u \leqslant \varepsilon \xi\}} \Phi\left(|\nabla u|^{2}\right)+C \varepsilon^{2} \int_{\{u>\varepsilon \xi\}}|\nabla \zeta|^{2} \cdot \tag{4.6}
\end{equation*}
$$

This is true for any $n \geqslant 2$.
Now we specialize to $n=2$, and take $B_{r} \subset B_{\varrho} \subset B_{R}$ with center $x_{0}$ in the free boundary. Thus $u \leqslant C r$ in $B_{r}$. Choosing $\varepsilon=C r$ and

$$
\zeta(x)= \begin{cases}\frac{\log \left(\varrho| | x-x_{0} \mid\right)}{\log (\varrho / r)} & \text { for } x \in B_{\varrho} \backslash B_{r} \\ 1 & \text { for } x \in B_{r}\end{cases}
$$

we get

$$
\int_{B_{r} \cap\{u>0\}}\left(\Phi\left(\lambda^{* 2}\right)-\Phi\left(|\nabla u|^{2}\right)\right)^{+} \leqslant \int_{B_{e}}\left(\Phi\left(|\nabla u|^{2}\right)-\Phi\left(\lambda^{*}\right)\right)^{+}+\frac{C r^{2}}{\log (\varrho / r)}
$$

Using Remark 4.2 and the estimate $c \leqslant \Phi^{\prime} \leqslant C(c, C$ positive) we find that

$$
\frac{1}{r^{2}} \int_{B_{r} \cap\{u>0\}}\left(\lambda^{* 2}-|\nabla u|^{2}\right)^{+} \leqslant C\left(\frac{\varrho}{r^{2}}\right)^{2}\left(\frac{\varrho}{R}\right)^{\alpha}+\frac{C}{\log (\varrho / r)}
$$

Choosing $R=\varrho^{\frac{1}{2}}, \varrho=r^{\varepsilon}$ with $\varepsilon>1,(2+\alpha / 2) \varepsilon>2$, we get (4.4).
Corollary 4.4. Let $n=2$ and let $u$ be a local minimum. Then every blow up limit of $u$ at $x_{0} \in \partial\{u>0\} \cap \Omega$ is a half plane solution with slope $\lambda^{*}$ in some neighborhood of the origin.

Proof. - From Theorems 4.1, 4.3 we see that, for any blow up limit $u_{0}$, with respect to balls $B_{\varrho_{m}}\left(x_{0}\right)$,

$$
\left|\nabla u_{0}\right|=\lambda^{*} \quad \text { in }\left\{u_{0}>0\right\}
$$

Now let us use the fact that $v=\left|\nabla u_{0}\right|^{2}$ is an $\mathcal{M}$-subsolution (see (4.2)),
which implies (if $\gamma$ is large enough in (4.2)) that

$$
\mathcal{M} v \geqslant c\left|D^{2} u_{0}\right|^{2}
$$

for some small positive constant $c$. Since $v=\lambda^{\text {k }}$ we conclude that $u_{0}$ is linear in each connected component of $\left\{u_{0}>0\right\}$, therefore

$$
u_{0}(x)=q_{0} \max \left(-x \cdot v_{0}, s_{0}\right)+q_{1} \max \left(x \cdot v_{0}, s_{1}\right)
$$

for some unit vector $\nu_{0}$ and some numbers $q_{k}>0,0 \leqslant s_{k} \leqslant \infty, k=0$, 1 . Since the origin is a free boundary point, we may assume that $s_{0}=0$.

Since $\left\{u_{0}=0\right\}$ has positive density at the origin (by Lemma 3.3 and Theorem 2.8) we must have $s_{1}>0$. By Theorem 1.9 we also have $q_{0}=\lambda^{*}$.

## 5. - Flat free boundary points.

Definition 5.1. Let $0<\sigma_{+}, \sigma_{-} \leqslant 1$ and $\tau>0$. We say that $u$ belongs to class $\vec{F}\left(\sigma_{+}, \sigma_{-} ; \tau\right)$ in $B_{\varrho}=B_{\varrho}(0)$ if $u$ is a local minimum in $B_{\varrho}(0)$ with $0 \in \partial\{u>0\}$, and

$$
\begin{array}{ll}
u(x)=0 & \text { for } x_{n} \geqslant \sigma_{+} \varrho \\
u(x) \geqslant-\lambda^{*}\left(x_{n}+\sigma_{-} \varrho\right) & \text { for } x_{n} \leqslant-\sigma_{-} \varrho \\
|\nabla u| \leqslant \lambda^{*}(\mathbf{1}+\tau) & \text { in } B_{\varrho} \tag{5.3}
\end{array}
$$

If the origin is replaced by $x_{0}$ and the direction of flatness $e_{n}$ is replaced by a unit vector $\nu$, then we say that $u$ belongs to the class $F\left(\sigma_{+}, \sigma_{-} ; \tau\right)$ in $B_{\varrho}\left(x_{0}\right)$ in direction $\nu$.

Theorem 5.1. There exists a positive constant $C=C(n)$ such that, for any small $\sigma>0$, if $u \in F(\sigma, 1 ; \sigma)$ in $B_{e}$ then $u \in F(2 \sigma, C \sigma ; \sigma)$ in $B_{\varrho / 2}$.

Thus flatness from above implies flatness from below.
In proving the theorem we shall need:
Lemina 5.2. If $B$ is a ball in $\{u=0\}$ touching $\partial\{u>0\}$ at $x_{0}$, then

$$
\begin{equation*}
\limsup _{x \rightarrow x_{0}} \frac{u(x)}{\operatorname{dist}(x, B)}=\lambda^{*} \tag{5.4}
\end{equation*}
$$

Proof. Denote the left-hand side by $l$ and let $y_{k} \rightarrow x_{0}, u\left(y_{k}\right)>0$, $d_{k}=\operatorname{dist}\left(y_{k}, B\right)$,

$$
\frac{u\left(y_{k}\right)}{d_{k}} \rightarrow l
$$

By nondegeneracy $l>0$. Consider a blow up sequence $u_{k}$ with respect to $B_{d_{k}}\left(x_{k}\right)$ where $x_{k}$ is a point on $\hat{c} B$ with $\left|x_{k}-y_{k}\right|=d_{k}$.

For a subsequence,

$$
\frac{x_{k}-y_{k}}{d_{k}} \rightarrow e, \quad u_{k} \rightarrow u_{0}
$$

We claim that

$$
\begin{equation*}
u_{0}(x)=l \max (-x \cdot e, 0) \tag{5.5}
\end{equation*}
$$

Indeed, we have

$$
\tilde{\mathscr{L}} u_{0}=0 \quad \text { in }\left\{u_{0}>0\right\}
$$

where

$$
\widetilde{\mathscr{L}} w \equiv f_{v_{i} v_{j}}\left(\nabla u_{0}\right) \partial_{i j} w
$$

is a uniformly elliptic operator. Thus

$$
\widetilde{\mathscr{L}}\left(u_{0}(x)+l x \cdot e\right)=0 \quad \text { for } x \in\left\{u_{0}>0\right\}
$$

and by construction $u_{0}(x)+l x \cdot e \leqslant 0$ when $x \cdot e<0$, and $u_{0}(x)+l x \cdot e=0$ for $x=-e$. The maximum principle yields that (5.5) holds for $x$ near - $e$, and then by analytic continuation, the same argument shows that (5.5) holds if $x \cdot e<0$. If $x \cdot e \geqslant 0$ then $u_{0}(x)=0$ by construction, so that again (5.5) holds.

Since $u_{0}$ is an absolute minimum by Lemma 3.3, we deduce from (5.5) and Theorem 1.9 that $l=\lambda^{*}$.

Proof of Theorem 5.1. By homogeneity we may assume that $\varrho=1$, $\lambda^{*}=1$. Let

$$
\begin{aligned}
\eta(y) & =\exp \left(-\frac{9|y|^{2}}{1-9|y|^{2}}\right) & & \text { for }|y|<\frac{1}{3} \\
& =0 & & \text { for }|y|>\frac{1}{3}
\end{aligned}
$$

and choose $s \geqslant 0$ maximal such that

$$
B_{1} \cap\{u>0\} \subset D \equiv D_{\sigma} \equiv\left\{x \in B_{1} ; x_{n}<\sigma-s \eta\left(x^{\prime}\right)\right\}
$$

where $x=\left(x^{\prime}, x_{n}\right)$. Thus there exists a point

$$
z \in B_{\frac{1}{2}} \cap \partial D \cap \partial\{u>0\}
$$

Also, $s \leqslant \sigma$ since $0 \in \partial\{u>0\}$.

We will prove an estimate for $u(\xi)$ from below for points $\xi \in \partial B_{\frac{3}{4}}$, $\xi_{n}<-\frac{1}{2}$. For that consider the solution $v$ of

$$
\begin{aligned}
\mathscr{L} v & =\nabla \cdot\left(f_{p}(\nabla v)\right)=0 & & \text { in } \quad D \backslash \overline{B(\xi)} \\
v & =0 & & \text { on } \partial D \cap B_{1} \\
v & =(1+\sigma)\left(\sigma-x_{n}\right) & & \text { on } \partial D \backslash B_{1} \\
v & =-(1-x \sigma) x_{n} & & \text { on } \partial B(\xi),
\end{aligned}
$$

where $B(\xi)=B_{10}(\xi)$ and $x$ is a large positive constant to be chosen later. Such a function exists by minimization, and by elliptic estimates up to the boundary (see proof of Lemma 1.7) $v$ is smooth in $\mathrm{D} \backslash B(\xi)$ (possibly not at the corners).

We claim that

$$
\begin{equation*}
u\left(x_{\xi}\right) \geqslant v\left(x_{\xi}\right) \quad \text { for some } x_{\xi} \in \partial B(\xi) \tag{5.6}
\end{equation*}
$$

provided $x$ is a sufficiently large constant. Indeed, otherwise we have $u \leqslant v$ on $\partial B(\xi)$; also $u \leqslant v$ on $\partial D$ by (5.3) (with $\tau=\sigma$ ). Therefore $u \leqslant v$ on $\partial(D \backslash B(\xi)$ ). Then by the maximum principle (Lemma 1.4) also $u \leqslant v$ on $\bar{D} \backslash \overline{B(\xi)}$. It follows from Lemma 5.2 that

$$
\begin{equation*}
1 \leqslant \limsup _{x \rightarrow z} \frac{u(x)}{\operatorname{dist}(x, \partial D)} \leqslant \partial_{-v} v(z) \tag{5.7}
\end{equation*}
$$

On the other hand we have an estimate

$$
\begin{equation*}
\partial_{-\nu} v(z) \leqslant(\lambda+C \sigma)-c x \sigma \tag{5.8}
\end{equation*}
$$

with constants $C, c$ independent of $x$ and $\sigma$. Before we show this, let us finish the proof of the theorem. Choosing $\varkappa$ large enough we see that (5.8) contradicts (5.7), consequently (5.6) is true.

Using this and (5.3) we find that for any $x \in B_{8}(\xi)$

$$
\begin{aligned}
u(x) & \geqslant u\left(x_{\xi}\right)-\frac{3}{10}(1+\sigma) \geqslant v\left(x_{\xi}\right)-\frac{3}{10}(1+\sigma) \\
& \geqslant-x_{\xi_{n}}-\frac{3}{10}-C \sigma \geqslant \frac{3}{10}-C \sigma>0
\end{aligned}
$$

if $\sigma$ is small enough. Thus $u>0$ in $B_{\frac{1}{f}}(\xi)$ and, consequently, $\mathscr{L} u=0$ in $B_{\frac{1}{8}}(\xi)$.

Set

$$
w(x)=(1+\sigma)\left(\sigma-x_{n}\right)-u(x) .
$$

Then $w \geqslant 0$ in $B_{3}(\xi)$ (by (5.3)) and

$$
w\left(x_{\xi}\right) \leqslant-x_{\xi_{n}}-v\left(x_{\xi}\right)+C \sigma \leqslant C \sigma .
$$

Since

$$
0=-\mathscr{L}^{u} u=f_{p_{i}, j}(\nabla u) \partial_{i j} w \quad \text { in } B_{b}(\xi),
$$

we get by Harnack's inequality,

$$
w(\xi) \leqslant C w\left(x_{\xi}\right) \leqslant C \sigma,
$$

or

$$
u(\xi) \geqslant-\xi_{n}-C \sigma \quad\left(\xi \in \partial B_{\frac{1}{2}}, \xi_{n}<-\frac{1}{2}\right) .
$$

We now integrate along vertical lines and, using (5.3), obtain

$$
u\left(\xi+\alpha e_{n}\right) \geqslant u(\xi)-(1+\sigma) \alpha \geqslant-\left(\xi_{n}+\alpha\right)-C \sigma
$$

which implies the asserted flatness from below, i.e., $u \in F(2 \sigma, C \sigma ; \sigma)$ in $B_{\frac{1}{2}}$.
To complete the proof we have to establish (5.8), where the first term on the right comes from elliptic estimates and the values of $v$ on $\partial D$, and the second term from the maximum principle due to the values of $v$ on $\partial B(\xi)$. More precisely, we will estimate $v$ from above by a $\mathscr{L}$-supersolution $v_{1}-\chi \sigma v_{2}$, where

$$
\tilde{\mathscr{L}}_{w} w=a_{i j} \partial_{i j} w, \quad a_{i j}(x)=f_{p_{i} p_{j}}(\nabla v(x)),
$$

and with $v_{1}, v_{2}$ defined as follows. First

$$
v_{1}=\frac{\gamma_{1}}{\mu_{1}}\left(1-\exp \left(-\mu_{1} d_{1}\right)\right) \quad \text { in } D
$$

where

$$
d_{1}(x)=-x_{n}+\sigma-s \eta\left(x^{\prime}\right)
$$

and with positive constants $\mu_{1}, \gamma_{1}$ depending on $\sigma$. Then

$$
1 \leqslant\left|\nabla d_{1}\right| \leqslant 1+C \sigma, \quad\left|\nabla^{2} d_{1}\right| \leqslant C \sigma,
$$

hence

$$
\begin{aligned}
\widetilde{\mathscr{L}} v_{\mathbf{1}} & =\gamma_{1} \exp \left(-\mu_{1} d_{1}\right) a_{i j}\left(\partial_{i j} d_{1}-\mu_{1} \partial_{i} d_{1} \partial_{j} d_{1}\right) \\
& \leqslant \gamma_{1} \exp \left(-\mu_{1} d_{1}\right)\left(C \sigma-c \mu_{1}\right)<0
\end{aligned}
$$

if

$$
\mu_{1}=C_{1} \sigma, \quad O_{1} \text { large enough } .
$$

For $x \in D$

$$
\begin{equation*}
v_{1}(x) \geqslant \gamma_{1} d_{1}(x)\left(1-C \mu_{1}\right) \geqslant(1+2 \sigma) d_{1}(x) \tag{5.9}
\end{equation*}
$$

if $\gamma_{1}=1+C_{2} \sigma, C_{2}$ large enough, and ( $\sigma$ small)

$$
(1+2 \sigma) d_{1}(x) \geqslant v(x) \quad \text { for } x \in \partial(D \backslash B(\xi))
$$

Since $\widetilde{\mathscr{L}}_{v}=0$ the maximum principle yields

$$
\begin{equation*}
v_{1} \geqslant v \quad \text { in } D \backslash B(\xi) \tag{5.10}
\end{equation*}
$$

At the point $z$ we compute

$$
\left|\nabla v_{1}(z)\right|=\gamma_{1}\left|\nabla d_{1}\right| \leqslant 1+C \sigma
$$

We define $v_{2}$ depending on $\xi$ by

$$
v_{2}=\frac{\gamma_{2}}{\mu_{2}}\left(\exp \left(\mu_{2} d_{2}\right)-1\right) \quad \text { in } \tilde{D} \backslash B(\xi)
$$

with constants $\gamma_{2}, \mu_{2}$. Here $\tilde{D} \subset D$ is a domain with smooth boundary containing

$$
D \backslash B_{17}\left(\left\{\left(x^{\prime}, 0\right) ; x^{\prime} \in R^{n-1},\left|x^{\prime}\right|=1\right\}\right),
$$

and $d_{2}$ is a function in $C^{2}(D \backslash B(\xi))$ satisfying

$$
\begin{array}{cl}
d_{2}=0 & \text { on } \partial \tilde{D}, \\
d_{2}=1 & \text { on } \partial B(\xi), \\
\left|\nabla d_{2}\right| \geqslant c>0 & \text { in } \tilde{D} \backslash \overline{B(\xi)} .
\end{array}
$$

Then

$$
\begin{aligned}
\widetilde{\mathscr{L}} v_{2} & =\gamma_{2} \exp \left(\mu_{2} d_{2}\right) a_{i j}\left(\partial_{i j} d_{2}+\mu_{2} \partial_{i} d_{2} \partial_{j} d_{2}\right) \\
& \geqslant \gamma_{2} \exp \left(\mu_{2} d_{2}\right)\left(-C+c \mu_{2}\right)>0
\end{aligned}
$$

if $\mu_{2}$ is large enough. Then choose $\gamma_{2}$ such that

$$
v_{2}=1 \quad \text { on } \partial B(\xi) .
$$

At the point $z$

$$
\left|\nabla v_{2}(z)\right|=\gamma_{2}\left|\nabla d_{2}(z)\right| \geqslant c>0 .
$$

Thus the function

$$
w \equiv v_{1}-\varkappa \sigma v_{2}
$$

is a $\widetilde{\mathscr{L}}$-supersolution in $\widetilde{D} \backslash B(\xi)$ with (see (5.10))

$$
w=v_{1} \geqslant v \quad \text { on } \quad \partial \tilde{D},
$$

and for $x \in \partial B(\xi)$ (by (5.9))

$$
w(x) \geqslant d_{1}(x)-\varkappa \sigma \geqslant-(1-\varkappa \sigma) x_{n}=v(x)
$$

Therefore $w \geqslant v$ on $\partial(\widetilde{D} \backslash B(\xi))$ and the maximum principle yields $w \geqslant v$ in $\widetilde{D} \backslash B(\xi)$; in particular,

$$
\begin{aligned}
\partial_{-\nu} v(z) & \leqslant \partial_{-v} w(z)=\left|\nabla v_{1}(z)\right|-\varkappa \sigma\left|\nabla v_{2}(z)\right| \\
& \leqslant(1+C \sigma)-\varkappa \sigma,
\end{aligned}
$$

which is the estimate (5.8) we had to prove.
We shall denote points in $R^{n}$ by ( $y, h$ ) with $y \in R^{n-1}$, and balls in $R^{n-1}$ by $B_{e}^{\prime}$, or $B_{e}^{\prime}(y)$.

Lemma 5.3 (Non-homogeneous blow up). Let $u_{k} \in F\left(\sigma_{k}, \sigma_{k} ; \tau_{k}\right)$ in $B_{e t}$ with $\sigma_{k} \rightarrow 0, \tau_{k} \sigma_{k}^{-2} \rightarrow 0$. Set, for $y \in B_{1}^{\prime}$,

$$
\begin{aligned}
& f_{k}^{+}(y)=\sup \left\{h ;\left(\varrho_{k} y, \sigma_{k} \varrho_{k} h\right) \in \partial\left\{u_{k}>0\right\}\right\}, \\
& f_{k}^{-}(y)=\inf \left\{h ;\left(\varrho_{k} y, \sigma_{k} \varrho_{k} h\right) \in \partial\left\{u_{k}>0\right\}\right\} .
\end{aligned}
$$

Then, for a subsequence,

$$
f(y) \equiv \lim _{\substack{z \rightarrow y \\ k \rightarrow \infty}} f_{\bar{k}}^{+}(z)=\underset{\substack{z \rightarrow y \\ k \rightarrow \infty}}{\liminf } f_{\bar{k}}^{-}(z) \quad \text { for all } y \in B_{1}^{\prime} .
$$

Further, $f_{k}^{+} \rightarrow f, t_{k}^{-} \rightarrow f$ uniformly, $f(0)=0$ and $f$ is continuous.
The proof which is based on Theorem 5.1 is identical with the proof of [1; Lemma 7.3].

Lemma 5.4. $f$ is subharmonic.
Proof. For simplicity we take $\varrho_{k}=1, \lambda^{*}=1$. If the assertion is not true then there is a ball $B_{\sigma}^{\prime}\left(y_{0}\right)$ cc $B_{1}^{\prime}$ and a harmonic function $g$ in a neighborhood of this ball such that

$$
g>f \text { on } \partial B_{\varrho}^{\prime}\left(y_{0}\right) \text { and } f\left(y_{0}\right)>g\left(y_{0}\right)
$$

We proceed as in [1], setting

$$
\begin{gathered}
Z=B_{\varrho}^{\prime}\left(y_{0}\right) \times R, \quad Z^{ \pm}(\varphi)=\{(y, h) \in Z ; h \gtrless \varphi(y)\}, \\
Z_{0}(\varphi)=\{(y, h) \in Z ; h=\varphi(y)\},
\end{gathered}
$$

and letting $d_{\delta}\left(Z^{+}\left(\sigma_{k} g\right)\right)$ be a test function which converges (as $\delta \rightarrow 0$ ) to the characteristic function of $Z^{+}\left(\sigma_{k} g\right)$ (say, $d_{\delta}(A)(x)=\min \{(1 / \delta)$ dist. ( $x, R^{n} / A$ ), 1$\}$ ).

We have, by Theorems 3.2 and 3.6,

$$
-\int_{\Omega} f_{p}\left(\nabla u_{k}\right) \cdot \nabla d_{\delta}\left(Z^{+}\left(\sigma_{k} g\right)\right)=\int_{\hat{\partial}_{\mathrm{red}}\left\{u_{k}>0\right\}} Q d_{\delta}\left(Z^{+}\left(\sigma_{k} g\right)\right) d H^{n-1}
$$

Taking $\sigma \rightarrow 0$ (and assuming that $Z^{0}\left(\sigma_{k} g\right) \cap \partial\left\{u_{k}>0\right\}$ has $H^{n-1}$ measure zero; otherwise we replace $g$ by $g+c$ for some suitable small $c$ ), we get

$$
\int_{\hat{o}\left(Z^{+}\left(\sigma_{k} g\right)\right) \cap\left\{u_{k}>0\right\}} f_{p}\left(\nabla u_{k c}\right) \cdot \nu d H^{n-1}=\int_{Z^{+}\left(\sigma_{k} g\right) \cap \hat{c}_{\mathrm{rad}}\left\{u_{k}>0\right\}} Q d H^{n-1}
$$

Using the fact that $f_{p}\left(\nabla u_{k}\right)=2 F^{\prime}\left(\left|\nabla u_{k}\right|^{2}\right) \nabla u_{k}$ and (3.3), (5.3), we see that the integrand on the left-hand side is bounded by $Q\left(1+C \tau_{k}\right)$. Hence

$$
\begin{equation*}
H^{n-1}\left(Z^{+}\left(\sigma_{k} g\right) \cap \partial_{\mathrm{red}}\left\{u_{k}>0\right\}\right) \leqslant\left(1+C \tau_{k}\right) H^{n-1}\left(Z^{0}\left(\sigma_{k} g\right) \cap\left\{u_{k}>0\right\}\right) \tag{5.11}
\end{equation*}
$$

The set

$$
\boldsymbol{E}_{k}=\left\{u_{k}>0\right\} \cup Z^{-}\left(\mathrm{g}_{k} g\right)
$$

has finite perimeter in the cylinder $Z$, with

$$
\begin{align*}
& H^{n-1}\left(Z \cap \partial_{\mathrm{red}} E_{k}\right) \leqslant H^{n-1}\left(Z^{+}\left(\sigma_{k} g\right) \cap \partial_{\mathrm{red}}\left\{u_{k}>0\right\}\right)  \tag{5.12}\\
& \\
& \quad+H^{n-1}\left(Z^{0}\left(\sigma_{k} g\right) \cap\left\{u_{k}=0\right\}\right)
\end{align*}
$$

By the excess area estimate of $[1 ; \mathrm{p} .136]$

$$
H^{n-1}\left(Z \cap \partial_{\mathrm{red}} E_{k}\right) \geqslant H^{n-1}\left(Z^{0}\left(\sigma_{k} g\right)\right)+c \sigma_{k}^{2}
$$

for $k$ large enough. Substituting this into (5.12) and using (5.11), we get a contradiction to the relation $\tau_{b c}=o\left(\sigma_{k}^{2}\right)$ which was assumed in Lemma 5.3.

The following lemma will be needed later on in proving further regularity of the function $f(y)$.

Lemma 5.5. Let $w$ be a function satisfying:

$$
\begin{aligned}
& \Delta w=0 \text { in } B_{1}^{-} \equiv B_{1} \cap\{h<0\} \\
& w(y, 0)=g(y) \text { in the sense that } w(y, h) \text { as a function of } y \text { converges to } g \\
& \text { in } L^{1} \text { as } h \uparrow 0, \\
& g \text { is subharmonio and continuous in } B_{1}^{\prime}, g(0)=0, \\
& w(0, h) \leqslant C|h| \\
& w \geqslant-C
\end{aligned}
$$

Then

$$
\begin{equation*}
\int_{0}^{1 / 2} \frac{1}{r^{2}} \int_{\partial B_{r}^{\prime}} g(y) d H^{n-2} \leqslant C_{0} \tag{5.13}
\end{equation*}
$$

where $C_{0}$ is a constant dpending only on $C$.
Notice that the integrand is nonnegative, since $g$ is subharmonic and $g(0)=0$.

Proof. Denote by $G_{\left(y^{\prime}, h^{\prime}\right)}$ the Green function for $\Delta$ in $B_{1}^{-}$with singularity at ( $y^{\prime}, h^{\prime}$ ). Then

$$
C\left|h^{\prime}\right| \geqslant w\left(0, h^{\prime}\right)=-\int_{\partial B_{1}^{-}} g(y) \frac{\partial}{\partial v} G_{\left(y^{\prime}, h^{\prime}\right)}(y, 0) d y-\int_{\partial B_{1}^{-}} \int_{\cap\{h<0)} w \frac{\partial}{\partial v} G_{\left(\nu^{\prime}, h^{\prime}\right)} d H^{n-1}
$$

Here it is assumed that $w$ has $L^{1}$ boundary values on $\partial B_{1}^{-} \cap\{h<0\}$ (otherwise replace $B_{1}$ by $B_{1-c}$ with a suitable small positive $c$ ). The function

$$
\zeta\left(y^{\prime}, h^{r}\right)=-\int_{\partial B_{1}^{-} \cap\{h<0\}} \frac{\partial}{\partial v} G_{\left(y^{\prime}, h^{\prime}\right)} d H^{n-1}
$$

is harmonic in $B_{1}^{-}$, with boundary values 1 on $\partial B_{1}^{-} \cap\left\{h^{\prime}<0\right\}$, and 0 on
$\partial B_{1}^{-} \cap\left\{h^{\prime}=0\right\}$. Hence

$$
\zeta\left(0, h^{\prime}\right) \leqslant C\left|h^{\prime}\right|
$$

It follows that

$$
\begin{equation*}
-\int_{B_{1}^{\prime}} g(y) \frac{\partial}{\partial v} G_{\left(0, h^{\prime}\right)}(y, 0) d y \leqslant C\left|h^{\prime}\right| \tag{5.14}
\end{equation*}
$$

Since the Poisson kernel in (5.14) depends only on $|y|$, say,

$$
-\frac{\partial}{\partial \nu} G_{\left(0, h^{\prime}\right)}(y, 0)=\varphi_{h^{\prime}}(|y|)
$$

this estimate can be written as

$$
\int_{0}^{1} \frac{r^{n-2} \varphi_{h^{\prime}}(r)}{\left|h^{\prime}\right|}\left(f_{\partial B_{r}^{\prime}} g d H^{n-2}\right) d r \leqslant C
$$

where the average of $g$ over $\partial B_{r}^{\prime}$ is nonnegative, since $g$ is subharmonic with $g(0)=0$. One easily computes that

$$
\begin{aligned}
\frac{\varphi_{h^{\prime}}(r)}{\left|h^{\prime}\right|} & =c\left(\left(r^{2}+h^{\prime 2}\right)^{-n / 2}-\left(h^{\prime 2} r^{2}+1\right)^{-n / 2}\right) \\
& \nexists c\left(r^{-n}-1\right)
\end{aligned}
$$

as $\left|h^{\prime}\right| \searrow 0$, where $e$ is a constant depending only on $n$. Thus we obtain

$$
\int_{0}^{1} \frac{1-r^{n}}{r^{2}}\left(f_{\partial B_{r}^{\prime}} g d H^{n-2}\right) d r \leqslant C
$$

which implies (5.13).
Lemma 5.6. There exists a positive constant $C$ such that, for any $y \in B_{r / 2}^{\prime}$,

$$
\begin{equation*}
\int_{0} \frac{1}{r^{2}}\left(\int_{\partial B_{r}^{\prime}(v)} f-f(y)\right) \leqslant C . \tag{5.15}
\end{equation*}
$$

Here $f$ is the function appearing in Lemma 5.4. Lemma 5.6 is analogous to Lemma 7.6 in [1]. Once this lemma is proved we shall be able to proceed as in [1] to establish regularity of the free boundary.

Proof. For simplicity we take $\varrho_{k}=1, \lambda^{*}=1$. For large $k$ the $u_{k}$ are
of class $F\left(8 \sigma_{k}, 8 \sigma_{k} ; \tau_{k}\right)$ in $B_{\frac{1}{2}}\left(y, \sigma_{k} f_{k}^{+}(y)\right)$. Therefore it suffices to prove the lemma for $y=0$.

Set

$$
\begin{equation*}
w_{k}(y, h)=\frac{u_{k}(y, h)+h}{\sigma_{k}} \tag{5.16}
\end{equation*}
$$

Since the free boundary of $u_{k}$ lies in the strip $\left|x_{n}\right| \leqslant c \sigma_{k}$ and since $\left|\nabla u_{k}\right| \leqslant 1+C \tau_{k}, \tau_{k} \leqslant \sigma_{k}$, we have and $w_{k} \leqslant C$ in $B_{1}^{-}$. The flatness assumption also implies that $w_{k} \geqslant-C$ in $B_{1}^{-}$. Thus

$$
\begin{equation*}
\left|w_{k}\right| \leqslant C \quad \text { in } B_{1}^{-} \tag{5.17}
\end{equation*}
$$

Lemma 5.7. For a subsequence,

$$
\lim _{k \rightarrow \infty} w_{k} \equiv w \quad \text { exists everywhere in } B_{1}^{-}
$$

the convergence is uniform in compact subsets of $B_{1}^{-}$, and $w$ satisfies:

$$
\begin{equation*}
a_{i j} \partial_{i j} w=0 \quad \text { in } B_{1}^{-} \tag{5.18}
\end{equation*}
$$

where

$$
a_{i j}=f_{p_{i} p_{j}}\left(-\lambda^{*} e_{n}\right)=F^{\prime}\left(\lambda^{* 2}\right) \delta_{i j}+2 F^{\prime \prime}\left(\lambda^{* 2}\right) \lambda^{* 2} \delta_{i n} \delta_{j n}
$$

$$
\begin{equation*}
w(0, h) \leqslant 0 \tag{5.19}
\end{equation*}
$$

$$
\begin{equation*}
w(y, 0)=f(y) \tag{5.20}
\end{equation*}
$$

in the sense that $\lim _{h \neq 0} w(y, h)=f(y)$,

$$
\begin{equation*}
|w| \leqslant C \tag{5.21}
\end{equation*}
$$

Observe that the proof of Lemma 5.5 extends (by affine transformation) to the linear elliptic operator in (5.18). Hence, once Lemma 5.7 is proved, Lemma 5.5 can be applied to the function $f$, so that (5.15) follows.

Proof of Lemma 5.7. The $u_{k}$ satisfy

$$
\nabla \cdot f_{p}\left(\nabla u_{k}\right)=0 \quad \text { in } B_{1} \cap\left\{h<-\sigma_{k}\right\}
$$

Writing this equation in non-divergence form, it is clear that

$$
\begin{equation*}
\mathscr{L}_{k} w_{k} \equiv f_{p_{i} p_{j}}\left(\nabla u_{k}\right) \partial_{i j} w_{k}=0 \tag{5.22}
\end{equation*}
$$

if $h<-\sigma_{k}$. From the flatness assumptions on the $u_{k}$ and Lemma 1.7 we conclude that, for a subsequence,

$$
u_{k}(y, h) \rightarrow-\hbar
$$

in $C^{2}$ in compact subsets of $B_{1}^{-}$. Recalling (5.17) we conclude that also $w_{k} \rightarrow w$ in $C^{2}$ in compact subsets of $B_{1}^{-}$, and $w$ satisfies (5.18). Clearly (5.21) is also valid.

Since.

$$
\begin{equation*}
-\frac{\partial}{\partial h} w_{k}=-\frac{1}{\sigma_{k}}\left(\frac{\partial}{\partial h} u_{k}+1\right) \leqslant \frac{\left|\nabla u_{k}\right|-1}{\sigma_{k}} \leqslant \frac{\tau_{k}}{\sigma_{k}} \tag{5.23}
\end{equation*}
$$

and $w_{k}(0,0)=0$, we have for $h \leqslant 0$,

$$
w_{k}(0, h) \leqslant|h| \frac{\tau_{k}}{\sigma_{k}} \rightarrow 0
$$

Thus $w(0, h) \leqslant 0$, and (5.19) is proved. It remains to establish (5.20).
We first show that, for any small $\delta>0$ and any large constant $K$

$$
\begin{equation*}
w_{k}\left(y, h \sigma_{k}\right) \rightarrow f(y) \quad \text { uniformly for } y \in B_{1-\delta}^{\prime},-K \leqslant h \leqslant-1 \tag{5.24}
\end{equation*}
$$

By Lemma 5.3 it suffices to prove

$$
\begin{equation*}
w_{k}\left(y, h \sigma_{k}\right)-f_{k}^{+}(y) \rightarrow 0 \tag{5.25}
\end{equation*}
$$

From (5.23) we obtain

$$
\begin{align*}
& w_{k}\left(y, h \sigma_{k}\right)-f_{k}^{+}(y) \leqslant w_{k}\left(y, \sigma_{k} f_{k}^{+}(y)\right)-f_{k}^{+}(y)+\left(f_{k}^{+}(y)-h\right) \tau_{k} / \sigma_{k}  \tag{5.26}\\
&=\left(f_{k}^{+}(y)-h\right) \tau_{k} / \sigma_{k} \leqslant(1+K) \tau_{k} / \sigma_{k} \rightarrow 0
\end{align*}
$$

In order to show (5.25) from below we take any sequence $y_{k} \in B_{1-\delta}^{\prime}$, $-K \leqslant h_{k} \leqslant-1$, and consider $u_{k}$ in $B_{\boldsymbol{R}_{k}}\left(x_{k}\right)$, where $x_{k}$ is the free boundary point

$$
x_{k}=\left(y_{k}, \sigma_{k} f_{k}^{+}\left(y_{k}\right)\right)
$$

and $R$ any large constant. We know that
if

$$
u_{k} \in F\left(\tilde{\delta}_{k}, 1 ; \tau_{k}\right) \quad \text { in } B_{R \sigma_{k}}\left(x_{k}\right)
$$

$$
\tilde{\delta}_{k}=\frac{1}{\bar{R}^{2}} \sup _{y \in B_{I \sigma_{k}}^{\prime}\left(v_{k_{k}}\right)}\left(f_{k}^{+}(y)-f_{k}^{+}\left(y_{k}\right)\right),
$$

where $\tilde{\delta}_{k} \rightarrow 0$ by Lemma 5.3. It follows from the flatness theorem (Theorem 5.1) that

$$
u_{k} \in F\left(2 \delta_{k}, C \delta_{k} ; \tau_{k}\right) \quad \text { in } B_{(R / 2)_{k}}\left(x_{k}\right),
$$

if

$$
\delta_{k}=\max \left(\tilde{\delta}_{k}, \tau_{k}\right) .
$$

Hence for any $h$ with $|h|<R / 2$

$$
u_{k}\left(x_{k}+h \sigma_{k} e_{n}\right) \geqslant-\left(h \sigma_{k}+C \delta \cdot \frac{R}{2} \sigma_{k}\right),
$$

that is,

$$
w_{k}\left(x_{k}+h \sigma_{k} e_{n}\right)-f_{k}^{+}\left(y_{k}\right)=\frac{u_{k}\left(x_{k}+h \sigma_{k} e_{n}\right)+h \sigma_{k}}{\sigma_{k}} \geqslant-C \frac{R}{2} \delta_{k} \rightarrow 0,
$$

which together with (5.26) proves (5.25).
For any $\varepsilon>0$ choose a $C^{3}$ function $g_{\varepsilon}$ such that

$$
\begin{equation*}
f-2 \varepsilon \leqslant g_{\varepsilon} \leqslant f-\varepsilon \quad \text { on } B_{1}^{\prime}, \tag{5.27}
\end{equation*}
$$

and let $u_{\varepsilon}$ be the solution of (see (5.18))

$$
\begin{align*}
\mathscr{L}_{0} u_{\varepsilon} & \equiv a_{i j} \partial_{i j} u_{\varepsilon}=1 & & \text { in } B_{1}^{-}, \\
u_{\varepsilon} & =g_{\varepsilon} & & \text { on } \partial B_{1-\delta}^{-} \cap\{h=0\},  \tag{5.28}\\
u_{\varepsilon} & =\inf _{B_{1}^{-}} w & & \text { on } \partial B_{1-\delta}^{-} \cap\{h<0\}
\end{align*}
$$

with $\delta$ as in (5.24).
By (5.24) and (5.27),

$$
\begin{equation*}
w_{k}>u_{\varepsilon} \quad \text { on } \partial\left(B_{1-\delta}^{-} \cap\left\{h<-\boldsymbol{K} \sigma_{k}\right\}\right) \tag{5.29}
\end{equation*}
$$

for any large constant $K$ (independent of $\delta, \varepsilon$ ), provided $k$ is sufficiently large (depending on $\varepsilon, K$ ).

The function $w_{k}$ is a bounded function (uniformly with respect to $k$ ) satisfying a uniformly elliptic equation (uniformly also with respect to $k$ ) in $B_{1}^{-} \cap\left\{h \leqslant-\sigma_{k}\right\}$. By elliptic estimates (see the proof of Lemma 1.7) we deduce that

$$
\left|\nabla w_{k}\right| \leqslant \frac{C}{\boldsymbol{K} \sigma_{k}} \quad B_{1-\delta}^{-} \cap\left\{h \leqslant-K \sigma_{k}\right\}
$$

where $C$ is a constant independent of $k, K$. Consequently

$$
\begin{aligned}
& \mathscr{L}_{k} u_{\varepsilon}=\left(f_{v_{i} p_{j}}\left(\nabla u_{k}\right)-f_{v_{t} p_{j}}\left(-e_{n}\right)\right) \partial_{i j} u_{\varepsilon}+1 \\
& \geqslant 1-\frac{C}{K}\left\|u_{\varepsilon}\right\|_{C^{1,1\left(B_{1-\delta}^{-}\right)}}>0 \quad \text { in } B_{1-\delta}^{-} \cap\left\{h<-K \sigma_{k}\right\}
\end{aligned}
$$

if $K$ is large enough (depending on $\delta$ and $\varepsilon$ ). Thus $\mathscr{L}_{k} u_{\varepsilon} \geqslant \mathscr{L}_{k} w_{k}$. Recalling (5.29) and applying the maximum principle, we get $u_{\varepsilon} \leqslant w_{k}$ in $B_{1-\delta}^{-} \cap\left\{h \leqslant-K \sigma_{k}\right\}$ if $k$ is large enough. It follows that $w(y, h) \geqslant u_{\varepsilon}(y, h)$ in $B_{1-\delta}^{-}$and, consequently,

$$
\frac{\lim _{h \downarrow 0}}{} w(y, h) \geqslant g_{\varepsilon}(y) \geqslant f(y)-2 \varepsilon .
$$

Similarly by working with a solution of

$$
\begin{aligned}
\mathscr{L}_{0} \tilde{u}_{\varepsilon} & =-1 & & \text { in } B_{1}^{-} \\
\tilde{u}_{\varepsilon} & =\tilde{g}_{\varepsilon} & & \text { on } \partial B_{1}^{-} \cap\{h=0\}\left(f+\varepsilon \leqslant \tilde{g}_{\varepsilon} \leqslant f+2 \varepsilon\right), \\
\tilde{u}_{\varepsilon} & =\sup _{B_{1}^{-}} w & & \text { on } \partial B_{1}^{-} \cap\{h<0\},
\end{aligned}
$$

we obtain $\lim _{h \uparrow 0} w(y, h) \leqslant f(y)+2 \varepsilon$. Since $\varepsilon$ is arbitrary. (5.20) follows.

## 6. - Smoothness of the free boundary.

Using Theorem 5.1 and Lemma 5.6 we can now proceed precisely as in [1] and establish that $f$ is «better than" Lipschitz continuous (Lemma 7.8 of [1]) and that the flatness condition implies better flatness in a smaller ball (Lemmas 7.9, 7.10). Using also Theorem 4.1 we obtain as in [1; Theorem 8.1]:

THEOREM 6.1. Suppose $u$ is a local minimum and $D \operatorname{CC} \Omega$. Then there exist positive constants $\alpha, \beta, \sigma_{0}, \tau_{0}, C$ such that if

$$
\begin{equation*}
u \in F(\sigma, 1 ; \infty) \quad \text { in } B_{\varrho}\left(x_{0}\right) \subset D \text { in direction } v \tag{6.1}
\end{equation*}
$$

with $\sigma \leqslant \sigma_{0}, \varrho \leqslant \tau_{0} \sigma^{2 / \beta}$, then

$$
B_{\varrho / 4}\left(x_{0}\right) \cap \partial\{u>0\} \quad \text { is a } C^{1, \alpha} \text { surface }
$$

more precisely, a graph in direction $\nu$ of a $C^{1, x}$ function, and, for any $x_{1}, x_{2}$
on this surface,

$$
\left|\nu\left(x_{1}\right)-\nu\left(x_{2}\right)\right| \leqslant C \sigma\left|\frac{x_{1}-x_{2}}{\varrho}\right|^{\alpha}
$$

We refer to (6.1) as the flatness condition.
From the first part of the proof of Theorem 3.5 we see that if $x_{0} \in \partial_{\text {red }}\{u>0\}$ then

$$
u \in \boldsymbol{F}\left(\sigma_{Q}, 1 ; \infty\right) \quad \text { in } B_{\varrho}\left(x_{0}\right) \text { in direction } v_{u}\left(x_{0}\right)
$$

with $\sigma_{\varrho} \rightarrow 0$ for $\varrho \rightarrow 0$. Hence, applying Theorem 6.1 we obtain:
Theorem 6.2. Let u be a local minimum. Then $\partial_{\text {red }}\{u>0\}$ is a $C^{1, x}$ surface locally in $\Omega$, and the remainder of $\partial\{u>0\}$ has $H^{n-1}$ measure zero.

For $n=2$, any blow up sequence $u_{k}$ with respect to balls $B_{e_{k}}\left(x_{0}\right)$ $\left(x_{0} \in \partial\{u>0\}\right)$ has a subsequence which is convergent to a linear function $\lambda^{*} \max \{-x \cdot v, 0\}$, at least in a neighborhood of the origin, by Corollary 4.4. Using (3.11), (3.12) we see that

$$
u \in F\left(\sigma_{k}, 1 ; \infty\right) \quad \text { in } B_{e_{k}}\left(x_{0}\right) \text { in direction } \nu
$$

with $\sigma_{k} \rightarrow 0$ as $k \rightarrow \infty$. Hence Theorem 6.1 can be applied. We get:
Theorem 6.3. Let $n=2$ and let $u$ be a local minimum. Then $\partial\{u>0\}$ is a $C^{1, \alpha}$ curve locally in $\Omega$.

Higher regularity follow from [8-10]; in particular, if $F(t)$ is analytic $\left(C^{\infty}\right)$ then

$$
\begin{align*}
& \text { for } n \geq 3, \quad \partial_{\text {red }}\{u>0\} \text { is locally analytic }\left(C^{\infty}\right) \\
& \text { for } n=2, \quad \partial\{u>0\} \quad \text { is locally analytic }\left(C^{\infty}\right) \tag{6.2}
\end{align*}
$$

Remark 6.4. All the results of this paper extend with minor changes to the case where $\lambda$ is a function $\lambda(x)$, bounded, uniformly positive and Hölder continuous. In the definition of flatness we require that

$$
\operatorname{osc}_{B_{e}} \lambda^{*}(x) \leqslant \lambda^{*}(0) \tau
$$

where $\lambda^{*}(x)$ is defined by (3.1) with $\lambda=\lambda(x)$. If $\lambda$ and $F^{\prime}$ are in $C^{k, \alpha}$ then $\partial_{\text {red }}\{u>0\}$ (for $n \geq 3$ ) and $\partial\{u>0\}$ (for $n=2$ ) belong to $C^{k+1, \alpha}$; if $\lambda$ and $F$ are analytic $\left(C^{\infty}\right)$ then ( 6.2 ) holds.

Finally, all the results extend to the functional (0.2) provided $F(x, t)$ is smooth enough.

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Institut für Angewandte Mathematik Universität Bonn
D-5300 Bonn, Germany
University of Chicago
Chicago, Illinois

Northwestern University
Evanston, Illinois


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