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# A new approach for supervised power disaggregation by using a deep recurrent LSTM network

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Motivation

Model layout

Deep Recurrent Neural Network (RNN)

LSTM units

Application to NILM

Cost function

Regularization

Experiments

Conclusion

## Limitations of current NILM approaches

### Unsupervised event based

event detection

event matching

clustering

reconstruction

- difficult for multi-state loads
- not suitable for variable loads
- not scalable to a large number of loads and events

- no load specific disaggregation
- hand crafted feature extraction
- sampling frequency higher than the line frequency needed

missing robustness

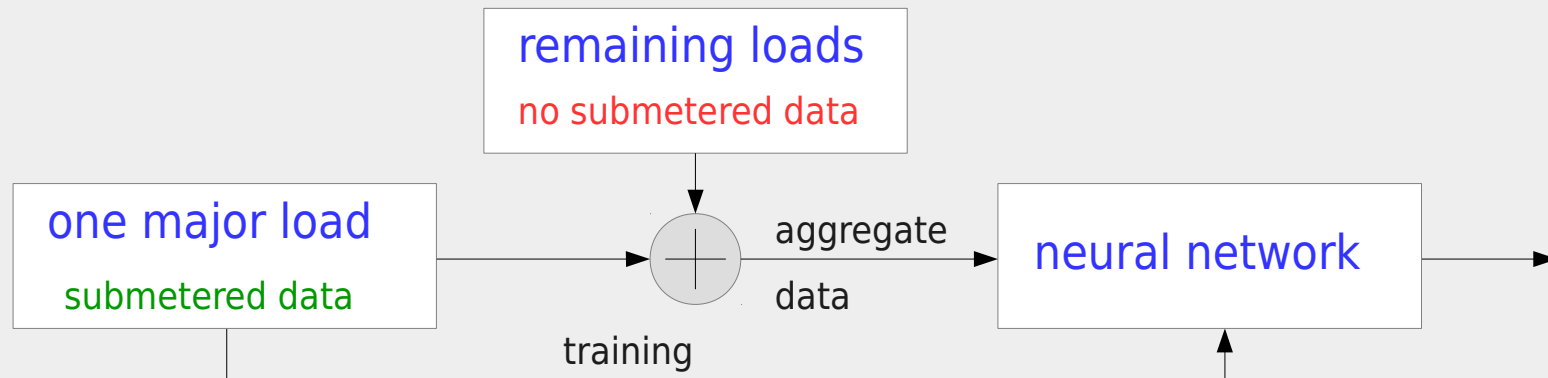
### Supervised eventless

Factorial Hidden Markov Model (FHMM) for single channel source separation

- not scalable due to exponential complexity
- exact training and inference intractable
- HMM of each load has to be known

missing scalability

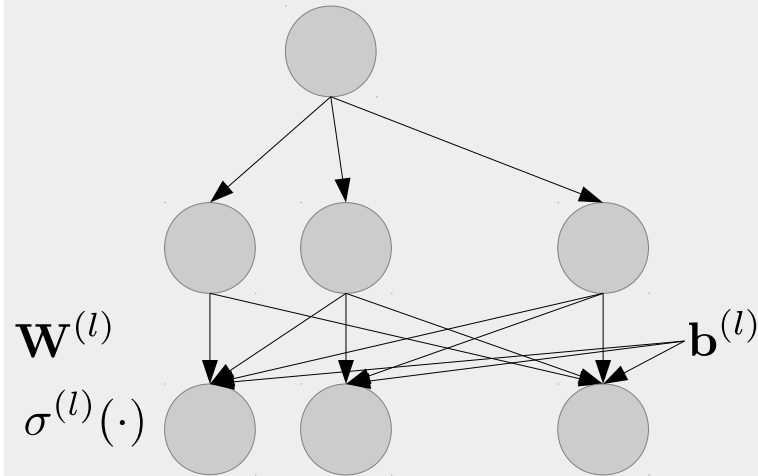
## Supervised Neural Network based approach for single channel source extraction



- remaining loads treated as time varying noise
  - scalable to many loads
  - no hand crafted feature extraction
  - assignment of power traces to specific loads possible
  - suitable for multi-state and variable load devices
  - suitable for low frequency (<1Hz) real power data only
- submetered training data needed

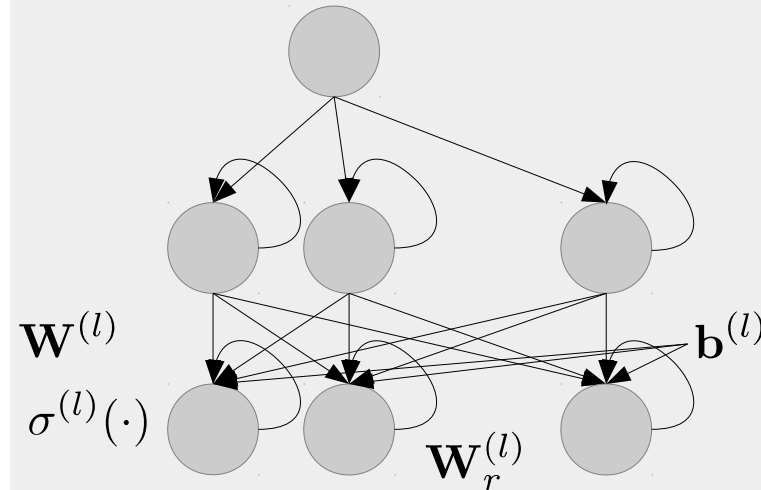
# Recurrent Neural Network (RNN)

Feedforward Neural Network



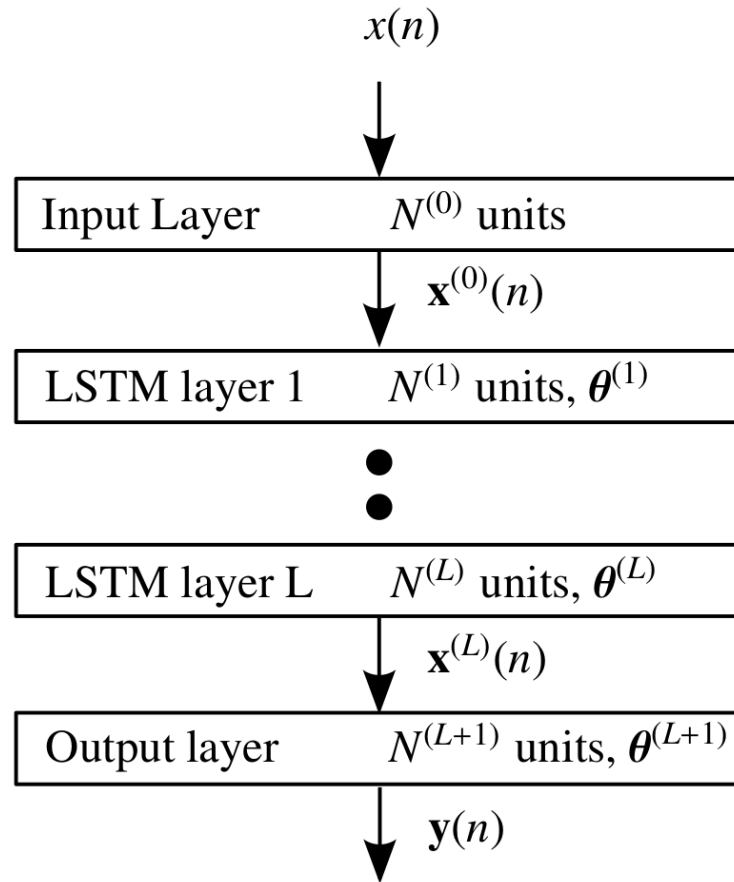
- multiple layers of units
- feedforward connections
- universal static mapper
- used for classification and regression

Recurrent Neural Network



- feedback connections allowed in each layer
- can learn any causal time-varying mapping
- used for sequence labeling and prediction

## Layout



- Use forward-backward processing to allow noncausal mapping

## Mapping

$$\mathbf{x}^{(0)}(n) = [x(n), x(n-1), \dots, x(n - N^{(0)} + 1)]^T \in \mathbb{R}^{N^{(0)}}$$

$$\text{Gates } \mathbf{i}^{(l)}(n) = g(\mathbf{x}^{(l-1)}(n), \mathbf{x}^{(l)}(n-1), \mathbf{s}^{(l)}(n-1))$$

$$\mathbf{o}^{(l)}(n) = \dots$$

$$\mathbf{f}^{(l)}(n) = \dots$$

$$g(\mathbf{x}, \mathbf{y}, \dots, \mathbf{z}) = \mathbf{W}_x \mathbf{x} + \mathbf{W}_y \mathbf{y} + \dots + \mathbf{W}_z \mathbf{z} + \mathbf{b}$$

States

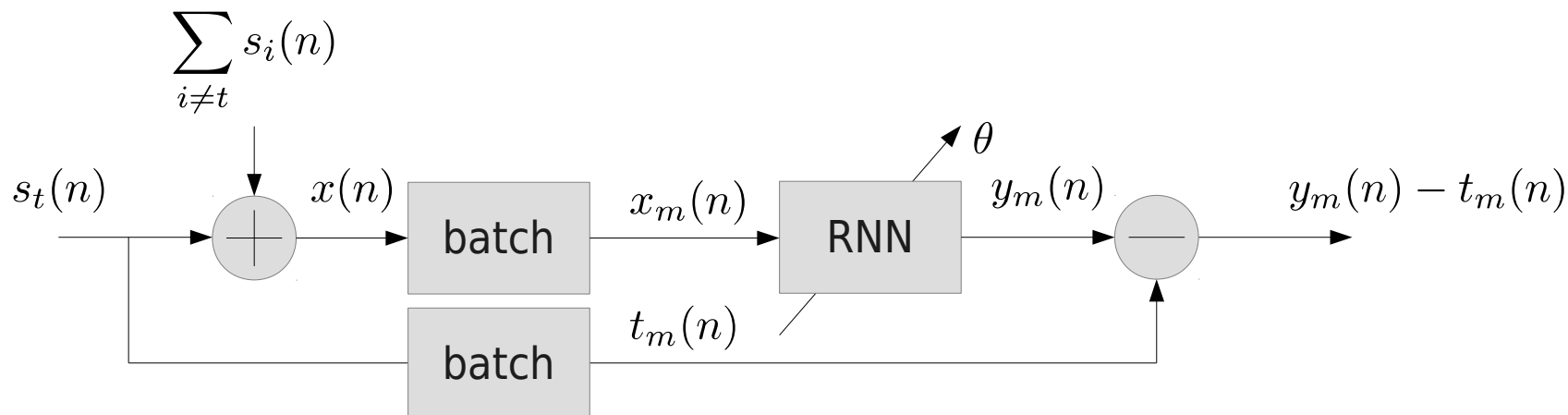
$$\begin{aligned} \mathbf{s}^{(l)}(n) = & \mathbf{i}^{(l)}(n) \circ \tanh \left( g(\mathbf{x}^{(l-1)}(n), \mathbf{x}^{(l)}(n-1)) \right) \\ & + \mathbf{f}^{(l)}(n) \circ \mathbf{s}^{(l)}(n-1) \end{aligned}$$

Output

$$\mathbf{x}^{(l)}(n) = \mathbf{o}^{(l)}(n) \circ \tanh(\mathbf{s}^{(l)}(n))$$

$$\mathbf{y}(n) = \sigma^{(L+1)}(\mathbf{W}^{(L+1)} \mathbf{x}^{(L)}(n) + \mathbf{b}^{(L+1)}) \in \mathbb{R}^{N^{(L+1)}}$$

## Extraction of target signal $s_t(n)$ with bidirectional RNN



### Training pairs

$$x_m(1), \dots, x_m(B)$$

$$t_m(1), \dots, t_m(B)$$

...signals divided into M  
blocks of length B

### Cost

$$J(\boldsymbol{\theta}) = \sum_{m=1}^M \sum_{n=1}^B (y_m(n) - t_m(n))^2 + \lambda_1 \|\boldsymbol{\theta}\|_1 + \lambda_2 \|\boldsymbol{\theta}\|_2^2$$

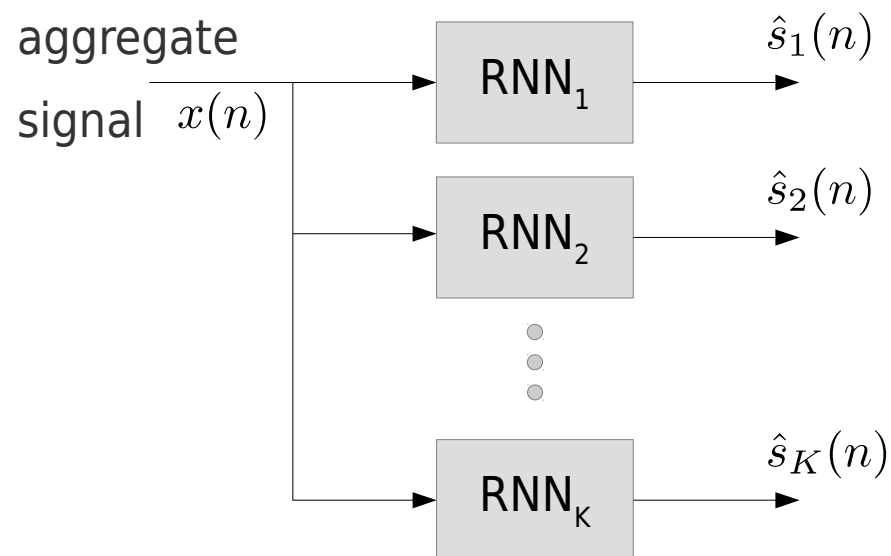
### Optimization

stochastic gradient descent

momentum

learning reate decay

## Extraction of multiple loads



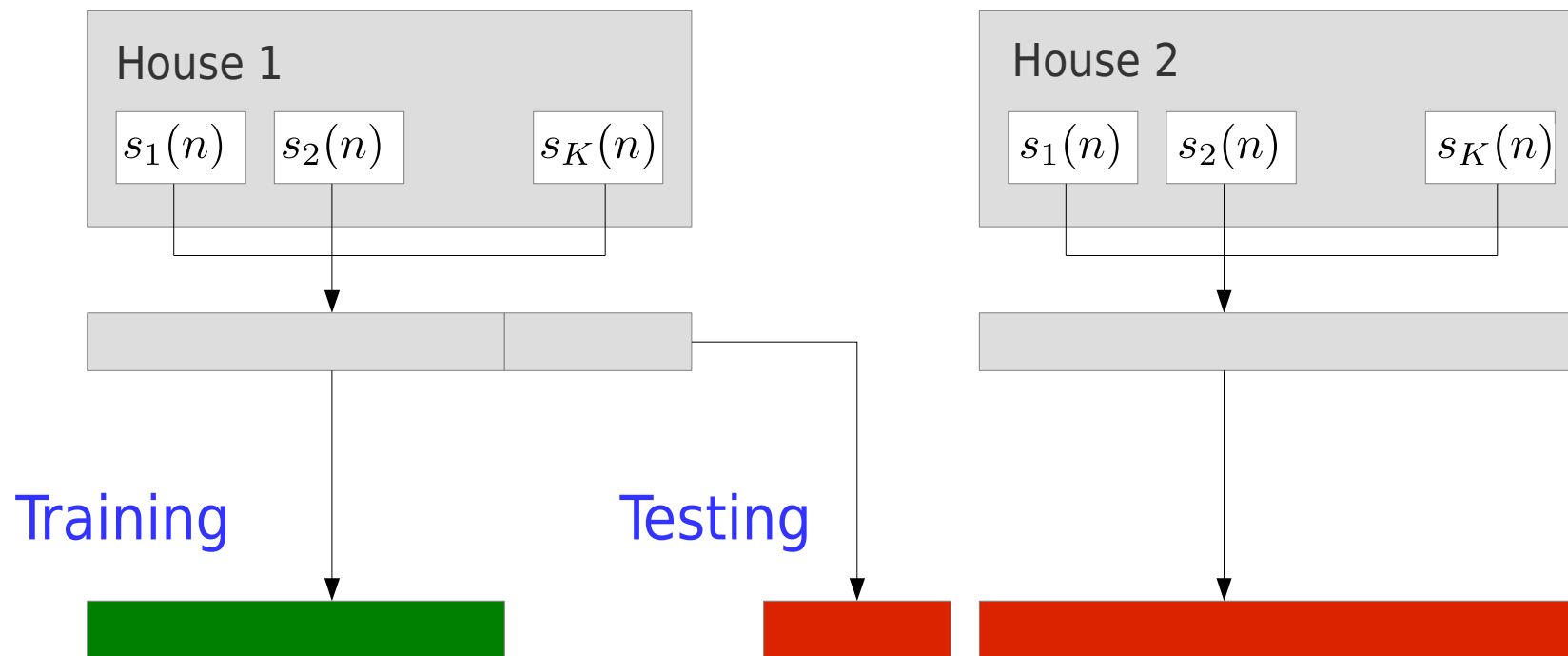
- Train multiple models by using multiple submeter measurements
- Use one model to extract one major load separately out of the aggregate signal  
→ easily extendable to new loads



## Using Reference Energy Disaggregation Dataset (REDD)

- #loads:  $K=16$
- #hours: 620h

- #loads:  $K=9$
- #hours: 258h



## Network setup

- Input layer
  - $N^{(0)} = 10$
- Two recurrent layers
  - $N^{(1)} = N^{(2)} = 140$
- Output layer
  - $N^{(L+1)} = 1$
- #Parameters 485801

## Target appliances

- Refrigerator
  - on/off device
  - periodic power consumption
  - small amplitude
- Dishwasher
  - multi-state device
  - nonperiodic
  - fixed pattern
- Microwave
  - multi-state device
  - nonperiodic
  - random pattern

## Metrics

- Estimated energy

$$\hat{E}_t = \frac{1}{F_s} \sum_{n=1}^N \hat{s}_t(n)$$

- Consumed energy

$$E_t = \frac{1}{F_s} \sum_{n=1}^N s_t(n)$$

- NRMS

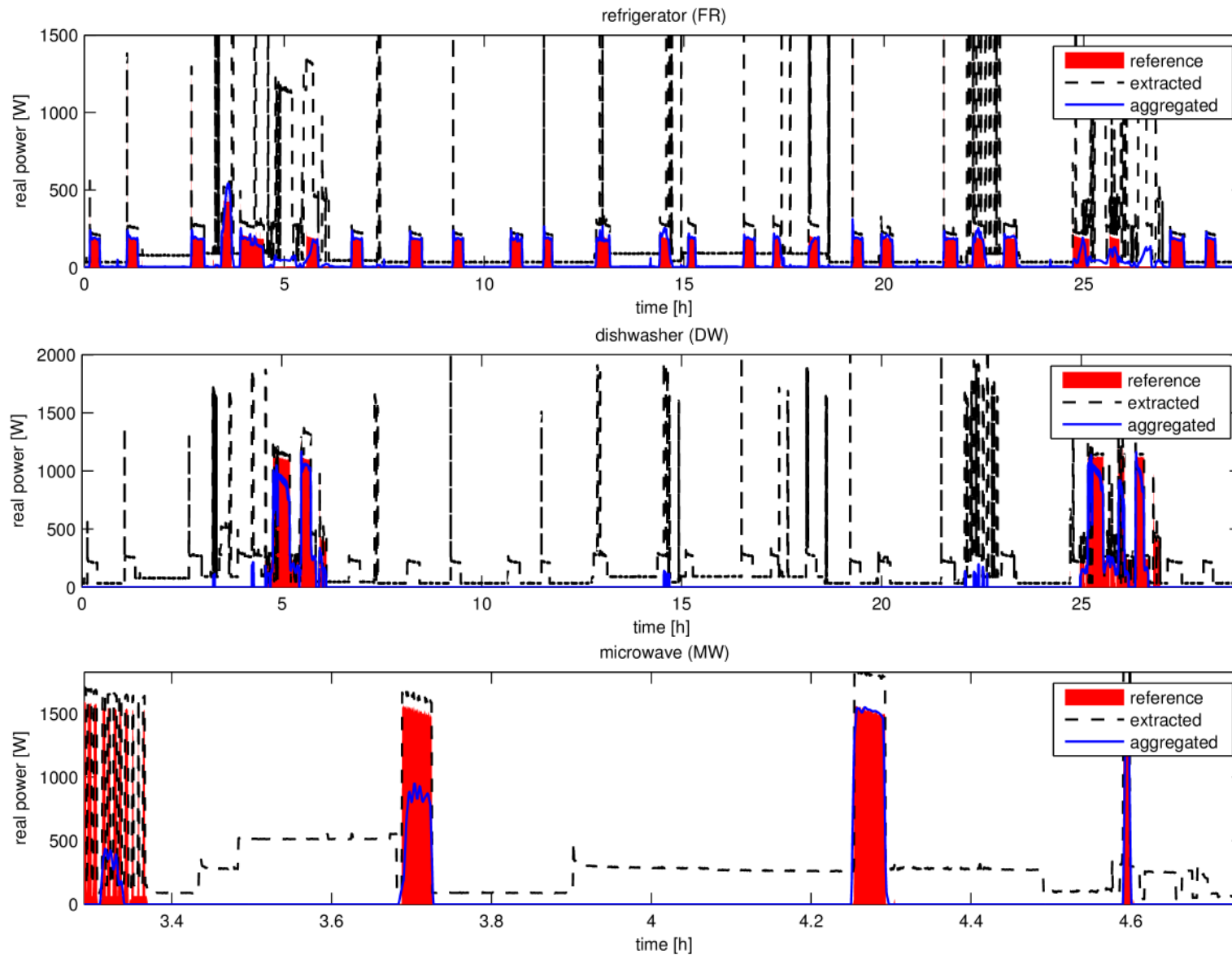
$$\text{NRMS} = \sqrt{\frac{\sum_{n=1}^N (\hat{s}_t(n) - s_t(n))^2}{\sum_{n=1}^N s_t^2(n)}}$$

### For active periods

$$s_t(n) \geq \gamma, \hat{s}_t(n) \geq \gamma$$

- Precision
- Recall
- F1 score

## Results for house 1



- details in following MATLAB demonstration

## Metrics for validation on house 1

Appl.	$E_t$	$\hat{E}_t$	NRMS	F1	R	P
FR	23.9	23.0	0.33	0.91	0.98	0.85
DW	11.1	10.50	0.35	0.79	0.87	0.73
MW	7.8	7.9	0.74	0.66	0.83	0.54

**Table 1.** Validation on test set of house 1 with  $E = 63.37kWh$

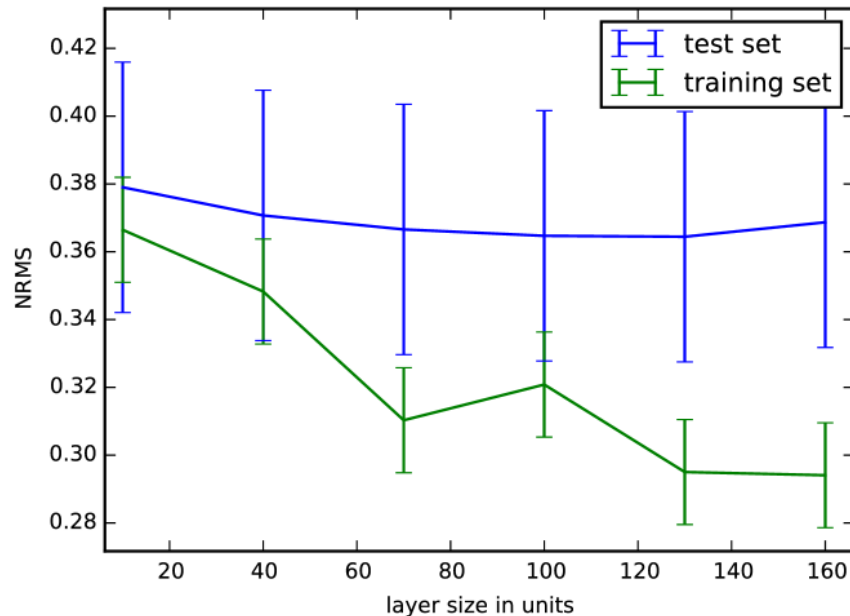
## Metrics for validation on house 2

Appl.	$E_t$	$\hat{E}_t$	NRMS	F1	R	P
FR	20.7	20.6	0.35	0.93	0.96	0.91
DW	2.36	3.26	0.31	0.68	1.0	0.52
MW	4.0	2.11	0.58	0.09	0.05	0.5

**Table 2.** Validation on house 2 with  $E = 36.6kWh$

- Models trained from house 1 work well for house 2 → high robustness

## Overfitting to training set



- result heavily dependent on initialization
- larger layer allows for more complex mappings
- network tends to overfit to training data
- increase of validation error between 120 and 160 units  
layer size chosen to 140 units

## Advantages of the approach

- Bidirectional RNN can be used for supervised load disaggregation
- Good performance for appliances with recurring patterns
- Eventless for all types of loads
- Allow low-frequency ( $<1\text{Hz}$ ) power meter
- No feature engineering

## Drawbacks

- Need submeter data
- Networks tend to overfit for little training data

## Future work

- Combination of DNN and HMM for disaggregation
- Domain adaption for different loads of same kind