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A note on a discrete analytic function

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An unsolved problem in discrete analytic function theory has been to find a suitable analogue of the function \sqrt{z} . An analogue $z^{(\alpha)}$, of the function z^{α} , is found here for discrete analytic functions of the first kind (or *monodiffric* functions). This function resolves a conjecture of |saacs in the negative, and at the same time it introduces multi-valued functions into the discrete analytic theory.

1. Introduction

In [3, Problem 1] it was stated that a discrete analytic analogue of the function \sqrt{z} had not been found, and a result has been obtained by the author [7] in connection with a discrete analytic theory for *q*-difference functions. In this note the monodiffric analogue $z^{(\alpha)}$, of the classical function z^{α} , is found.

Isaacs [9, 10] conjectured that there were no rational monodiffric functions other than polynomials, and in the following, it is shown that the function $z^{(\alpha)}$ resolves this conjecture in the negative. Also, multivalued functions are introduced into the theory.

Monodiffric functions were defined by Isaacs [9, 10] and further developed by Kurowski [11] and Berzsenyi [1, 2]. They are defined on the set of gaussian integers and satisfy the forward-difference equation,

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(1.1)
$$f(z+1) - f(z) = \frac{f(z+i) - f(z)}{i}$$

The monodiffric function corresponding to z^n (*n* a non-negative integer) is denoted by $z^{(n)}$ and was found by |saacs to be

(1.2)
$$z^{(n)} = \sum_{j=0}^{n} {n \choose j} x^{(n-j)} i^{j} y^{(j)}; z^{(0)} = 1,$$

where z = (x, y) and $x^{(j)} = x(x-1) \dots (x-j+1)$; $x^{(0)} = 1$.

Discrete analytic functions of the second kind were introduced by Ferrand [5] and extensively developed by Duffin [4] and others. They are defined by the difference quotient equality,

$$\frac{f(z+1+i)-f(z)}{1+i} = \frac{f(z+1)-f(z+i)}{1-i}$$

In this latter theory however, the corresponding function $z^{(n)}$ does not have a simple algebraic form.

2. Preliminaries

In monodiffric theory it is usual to employ forward-differences but it will be more convenient here to utilize backward-differences, the results obtained applying equally well to the standard monodiffric scheme. Accordingly the following definitions of the operators E_1 , E_2 , Δ_1 and Δ_2 are made:

(2.1)
$$E_{1}f(z) = f(z-1) , E_{2}f(z) = f(z-i) ,$$
$$\Delta_{1}f(z) = (1-E_{1})f(z) = f(z) - f(z-1) ,$$
$$\Delta_{2}f(z) = \frac{(1-E_{2})}{i} f(z) = \frac{f(z)-f(z-i)}{i} .$$

If $\Delta_1 f(z) = \Delta_2 f(z)$, then f is said to be monodiffric at the point z, and a common operator Δ can be used, where

$$(2.2) \qquad \Delta \equiv \Delta_1 = \Delta_2 .$$

The domain of definition is to be restricted to the set G of

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gaussian integers. Hence,

$$G = \{z; z = x + iy, where x, y are integers\}$$
.

Subsequently a complex number z will be used synonymously with its components (x, y) .

Subsets of G in the four quadrants of the complex plane are defined as follows:

 $\begin{aligned} G_1 &= \{z; \ z \in G, \ x > 0, \ y > 0\} \ , \quad G_2 &= \{z; \ z \in G, \ x < 0, \ y > 0\} \ , \\ G_3 &= \{z; \ z \in G, \ x < 0, \ y < 0\} \ , \quad G_4 &= \{z; \ z \in G, \ x > 0, \ y < 0\} \ , \end{aligned}$

and on the axes,

$$X^{-} = \{z; z \in G, x \ge 0, y = 0\}, X^{-} = \{z; z \in G, x \le 0, y = 0\},$$

 $Y^{+} = \{z; z \in G, x = 0, y \ge 0\}, Y^{-} = \{z; z \in G, x = 0, y \le 0\}.$

Before proceeding to the derivation of $z^{(\alpha)}$ it will be shown that if a function is defined for points of G on the axes (on X^+ , X^- , Y^+ and Y^-), then it can be extended as a monodiffric function into G.

Kurowski [11] constructed an operator E which provides the extension of a function, defined on the X-axis, to a monodiffric function defined on a half plane.

Defining the operators $(1-i\Delta_1)^m$ and $(1-\Delta_2)^m$ by

$$(1-i\Delta_1)^m = \sum_{k=0}^m {m \choose k} (-i)^k \Delta_1^k ; \quad (1-i\Delta_1)^0 = I ,$$

$$(1-\Delta_2)^m = \sum_{k=0}^m {m \choose k} (-1)^k \Delta_2^k ; \quad (1-\Delta_2)^0 = I ;$$

where m is a positive integer, Δ_1 and Δ_2 are as defined in (2.1), and I is the identity operator; then the following two theorems are equivalent to Kurowski's result and will only be stated.

THEOREM 2.1. If $z = (x, y) \in G$, and a function f is defined for $z \in X^+ \cup X^-$ (on the X-axis), then a monodiffric function with these

prescribed values is determined uniquely for $z \in G_3 \cup G_4 \cup Y$ (below the X-axis) and is given by

$$f(z) = (1-i\Delta_1)^{-y} f(x, 0) = \sum_{j=0}^{-y} {-y \choose j} (-i)^j \Delta_1^j [f(x, 0)] .$$

THEOREM 2.2. The function f defined by

$$f(z) = (1-\Delta_2)^{-x} f(0, y) = \sum_{j=0}^{-x} {-x \choose j} (-1)^j \Delta_2^j [f(0, y)]$$

is the unique monodiffric function for $z \in G_2 \cup G_3 \cup X^-$ (to the left of the Y-axis), with prescribed values f(0, y) on $Y^+ \cup Y^-$.

On the other hand, if f is defined on the positive-half X and Y axes, then a monodiffric function is determined explicitly for all $z \in G_1$ in the first quadrant, as the following theorem shows.

THEOREM 2.3. If a function f is defined on X^+ and Y^+ , then it has a unique monodiffric extension into G_1 , and in fact for $z = (x, y) \in G_1$,

$$\begin{split} f(z) &= (1-i)^{-(x+y)} \left\{ \sum_{j=0}^{x} {x+y \choose j} (-i)^{j} (1-i\Delta_{1})^{x-j} [f(x-j, 0)] \right. \\ &+ \sum_{j=x+1}^{x+y} {x+y \choose j} (-i)^{j} (1-\Delta_{2})^{j-x} [f(0, j-x)] \right\} \,. \end{split}$$

Proof. From (2.2), if f is monodiffric at $z\in G_1$, then $\Delta_1 f(z) = \Delta_2 f(z) \ , \ {\rm and} \ {\rm so} \ {\rm by} \ (2.1),$

$$f(z) = (1-i)^{-1} [f(z-i)-if(z-1)]$$

= $(1-i)^{-1} [E_2 - iE_1] f(z)$.

Similarly,

$$f(z) = (1-i)^{-2} [E_2 - iE_1]^2 f(z)$$
,

and in general,

$$f(z) = (1-i)^{-n} [E_2 - iE_1]^n f(z)$$
,

so that for n = x + y,

$$f(z) = (1-i)^{-(x+y)} \sum_{\substack{j=0\\j=0}}^{x+y} {x+y \choose j} (-i)^{j} E_{2}^{x+y-j} E_{1}^{j} f(z)$$
$$= (1-i)^{-(x+y)} \sum_{\substack{j=0\\j=0}}^{x+y} {x+y \choose j} (-i)^{j} f(x-j, j-x) .$$

When $0 < j \leq x$, the argument of f lies in G_{\downarrow} and when $x \leq j \leq x+y$ it lies in G_2 . Hence by Theorems 2.1 and 2.2 the expression for f(z)in the above statement of the theorem is obtained. Uniqueness follows from the constructive method used, completing the proof of the theorem.

As a consequence of the above three theorems, it follows that if a function is defined on the axes, then it has a monodiffric extension to all points of G, the resulting function being unique at least in G_1 , G_2 and G_1 .

An alternative form of the above theorem, which is given by the case $n \approx x + y - 1$, proves useful and is now stated.

THEOREM 2.4. For $z \in G_1$ and with f defined on the positive-half axes as in the above theorem, then

$$\begin{aligned} f(z) &= (1-i)^{-(x+y-1)} \left\{ \sum_{j=0}^{x-1} {x+y-1 \choose j} (-i)^{j} (1-i\Delta_{1})^{x-j-1} f(x-j, 0) \\ &+ \sum_{j=x}^{x+y-1} {x+y-1 \choose j} (-i)^{j} (1-\Delta_{2})^{j-x} f(0, 1+j-x) \right\} . \end{aligned}$$

3. The function $z^{(\alpha)}$

A monodiffric function $z^{(\alpha)}$ is said to be an analogue of the classical function z^{α} if

(3.1)
$$\begin{cases} (i) \quad \Delta z^{(\alpha)} = \alpha z^{(\alpha-1)}, \\ (ii) \quad 0^{(\alpha)} = 0; \quad \alpha > 0, \\ (iii) \quad z^{(0)} = 1, \end{cases}$$

where Δ is defined by (2.2).

When $\alpha = n$, a non-negative integer, $z^{(n)}$ is given by |saacs's function (1.2), where for the backward-difference case, $x^{(j)} = x(x+1) \dots (x+j-1)$. A general form is now obtained for $z^{(\alpha)}$ (α not a negative integer - but otherwise an arbitrary constant) which is consistent with |saacs's function when α is a non-negative integer.

For
$$x \in X^+ \cup X^-$$
 on the X-axis, the function $x^{(\alpha)}$ is defined by
(3.2) $x^{(\alpha)} = \frac{\Gamma(x+\alpha)}{\Gamma(x)}$,

where α is not a negative integer, and where Γ is the classical gamma function. This function satisfies (3.1) with $\Delta = \Delta_1$.

When $\alpha = n$, a non-negative integer, $x^{(\alpha)}$ reduces to, $x^{(n)} = x(x+1) \dots (x+n-1)$; $x^{(0)} = 1$,

so that $x^{(n)} = 0$; $x = 0, -1, -2, \ldots, -n+1$. When α is not an integer, then since $\Gamma(x)$ has a pole when x is a negative integer, it follows that

(3.3)
$$x^{(\alpha)} = 0; x \in X^{-1}$$

For points of G on the Y-axis $(iy \in Y^+ \cup Y^-)$, the function $(iy)^{(\alpha)}$ is defined by

$$(3.4) \qquad (iy)^{(\alpha)} = i^{\alpha}y^{(\alpha)} ,$$

where $y^{(\alpha)}$ is given by (3.2). This function satisfies (3.1) with $\Delta = \Delta_2$.

The case when α is a non-negative integer has been solved by [saacs. When α is a negative integer, the function $x^{(\alpha)}$, as defined by (3.2), has a singularity at each of the points $x = 1, 2, \ldots, -\alpha$. Subsequently it will be assumed that α is not an integer.

From Theorem 2.1 it follows that the function

$$z^{(\alpha)} = (1-i\Delta_1)^{-y} x^{(\alpha)} ; \quad z = (x, y) \in G_3 \cup G_{\downarrow} \cup Y^- ;$$

is the unique monodiffric function in this region, with prescribed values $x^{(\alpha)}$ on the X-axis. Hence,

$$z^{(\alpha)} = \sum_{j=0}^{-\mathcal{Y}} \begin{pmatrix} -\mathcal{Y} \\ j \end{pmatrix} (-i)^{j} \Delta_{1}^{j} x^{(\alpha)} ,$$

and since $\Delta_1 x^{(\alpha)} = \alpha x^{(\alpha-1)}$, $\Delta_1^j x^{(\alpha)} = \alpha(\alpha-1)$, $(\alpha-j+1)x^{(\alpha-j)}$, it

follows on simplification that

(3.5)
$$z^{(\alpha)} = \sum_{j=0}^{-y} {\alpha \choose j} x^{(\alpha-j)} i^j y^{(j)}$$

From (3.3) it follows that

$$(3.6) \qquad z^{(\alpha)} = 0 ; z \in G_3 \cup Y \cup X .$$

Similarly,

$$z^{(\alpha)} = (1 - \Delta_2)^{-x} (iy)^{(\alpha)}; \quad z = (x, y) \in G_2 \cup G_3 \cup X^-,$$

is the unique monodiffric function with values $(iy)^{(\alpha)}$ on the Y-axis, and this reduces to

(3.7)
$$z^{(\alpha)} = \sum_{j=0}^{-x} {\alpha \choose j} x^{(j)} i^{\alpha-j} y^{(\alpha-j)}$$

Once again $z^{(\alpha)} = 0$; $z \in G_3 \cup Y \cup X$, and so this definition is consistent with (3.5).

By construction, the function $z^{(\alpha)}$ (given by (3.5), (3.6) and (3.7)), is monodiffric and it can be readily verified that it satisfies

conditions (i) and (ii) of (3.1).

For the remaining region $\ensuremath{G_1}$, it follows from Theorem 2.3 that for $z \in \ensuremath{G_1}$,

$$z^{(\alpha)} = (1-i)^{-(x+y)} \left\{ \sum_{j=0}^{x} {x+y \choose j} (-i)^{j} (1-i\Delta_{1})^{x-j} (x-j)^{(\alpha)} + \sum_{\substack{j=x+1 \\ j=x+1}}^{x+y} {x+y \choose j} (-i)^{j} (1-\Delta_{2})^{j-x} [i(j-x)]^{(\alpha)} \right\},$$

and so by (3.5) and (3.7),

(3.8)
$$z^{(\alpha)} = (1-i)^{-(x+y)} \sum_{j=0}^{x+y} {x+y \choose j} (-i)^j (x-j, j-x)^{(\alpha)},$$

where for j = 0, 1, ..., x, $(x-j, j-x)^{(\alpha)}$ is given by (3.5), and by (3.7) when $z^{j} = x+1, x+2, ..., x+y$. The function is monodiffric by Theorem 2.3 and it satisfies $0^{(\alpha)} = 0$. It remains to be verified that $\Delta_{z}^{(\alpha)} = \alpha z^{(\alpha-1)}$.

THEOREM 3.1. For $z \in G_1$, the function $z^{(\alpha)}$ as defined by (3.8) satisfies the condition

$$\Delta z^{(\alpha)} = \alpha z^{(\alpha-1)}$$

Proof. Let $z \in G_1$. From (2.1),

$$\Delta_{l}z^{(\alpha)} = z^{(\alpha)} - (z-1)^{(\alpha)}$$

and so by (3.8),

$$\Delta_{1}z^{(\alpha)} = (1-i)^{-(x+y)} \left\{ \sum_{j=0}^{x+y} \left(\sum_{j=0}^{x+y} (-i)^{j} (x-j, j-x)^{(\alpha)} - (1-i) \sum_{j=0}^{x+y-1} \left(\sum_{j=0}^{x+y-1} (-i)^{j} (x-1-j, j+1-x)^{(\alpha)} \right) \right\}$$

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$$= (1-i)^{-(x+y)} \left\{ (x, -x)^{(\alpha)} + \sum_{j=0}^{x+y-1} {x+y \choose j+1} (-i)^{j+1} (x-j-1, j+1-x)^{(\alpha)} - \sum_{j=0}^{x+y-1} {x+y-1 \choose j} (-i)^{j+1} (x-j-1, j+1-x)^{(\alpha)} - \sum_{j=0}^{x+y-1} {x+y-1 \choose j} (-i)^{j} (x-j-1, j+1-x)^{(\alpha)} \right\}$$

and on combining the first two sums,

$$\Delta_{1}z^{(\alpha)} = (1-i)^{-(x+y)} \left\{ (x, -x)^{(\alpha)} + \frac{x+y-2}{j=0} \begin{pmatrix} x+y-1\\ j+1 \end{pmatrix} (-i)^{j+1} (x-j-1, j+1-x)^{(\alpha)} - \sum_{j=0}^{x+y-1} \begin{pmatrix} x+y-1\\ j \end{pmatrix} (-i)^{j} (x-1-j, j+1-x)^{(\alpha)} \right\}$$
$$= (1-i)^{-(x+y)} \sum_{j=0}^{x+y-1} \begin{pmatrix} x+y-1\\ j \end{pmatrix} (-i)^{j} [(x-j, j-x)^{(\alpha)} - (x-1-j, j+1-x)^{(\alpha)}] .$$

Now if $Z \in G_2$ or G_1 then it has been shown previously that $\Delta_1 Z^{(\alpha)} = \Delta_2 Z^{(\alpha)} = \alpha Z^{(\alpha-1)}$, and from this it follows that

$$(Z-i)^{(\alpha)} - (Z-1)^{(\alpha)} = \alpha(1-i)Z^{(\alpha-1)}$$

Hence with Z = (x-j, j+1-x),

$$\Delta_{1}z^{(\alpha)} = (1-i)^{-(x+y)} \sum_{\substack{j=0\\j = 0}}^{x+y-1} {x+y-1 \choose j} (-i)^{j} \alpha (1-i) (x-j, j+1-x)^{(\alpha-1)}$$
$$= \alpha z^{(\alpha-1)}$$

(from Theorem 2.4). Since $z^{(\alpha)}$ is monodiffric it follows that $\Delta z^{(\alpha)} = \Delta_1 z^{(\alpha)} = \alpha z^{(\alpha-1)}$, completing the proof of the theorem.

Hence $z^{(\alpha)}$ has been specified for all points of G and it can be seen that (3.5) and (3.7) demonstrate an analogy with the binomial expansion of the function $z^{\alpha} = (x+iy)^{\alpha}$. In the region G_1 the expression for $z^{(\alpha)}$ given by (3.8) is a little more complicated, but it can be shown that (3.8) becomes

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$$(3.9) z^{(\alpha)} = \sum_{j=0}^{\infty} {\alpha \choose j} x^{(\alpha-j)} i^j y^{(j)} + \sum_{j=0}^{\infty} {\alpha \choose j} x^{(j)} i^{\alpha-j} y^{(\alpha-j)}$$

where the two divergent series are summable (E, q) for q > 0 in the Euler sense (see Hardy [6]). This represents a remarkable analogy with the binomial expansion of z^{α} and the proof, being lengthy, is given in [8].

To summarize the preceding results:- the monodiffric function corresponding to z^{α} is given by:

$$(3.10) \quad z^{(\alpha)} = \begin{cases} \sum_{j=0}^{\infty} {\alpha \choose j} x^{(\alpha-j)} i^{j} y^{(j)} + \sum_{j=0}^{\infty} {\alpha \choose j} x^{(j)} i^{\alpha-j} y^{(\alpha-j)} ; & z \in G_1 \\ \sum_{j=0}^{x} {\alpha \choose j} x^{(j)} i^{\alpha-j} y^{(\alpha-j)} ; & z \in G_2 \cup Y^+ \\ 0 ; & z \in G_3 \cup X^- \cup Y^- \\ \sum_{j=0}^{y} {\alpha \choose j} x^{(\alpha-j)} i^{j} y^{(j)} ; & z \in G_1 \cup X^+ \\ \end{cases}$$

4. Properties and discussion

Isaacs [9, 10] conjectured that there were no monodiffric functions, rational in x and y, other than polynomials. Now from the definition of $x^{(\alpha)}$, it follows that if $z \in G_{l_1}$ (x > 0, y < 0), then

$$\binom{\alpha}{j} x^{(\alpha-j)} y^{(j)} = \frac{(\alpha-j+1)(\alpha-j+2)\dots(\alpha-j+x-1)y(y+1)\dots(y+j-1)}{(x-1)!} ,$$

and so for $z \in G_{\mu}$, the function $z^{(\alpha)}$, given in (3.10) by

$$z^{(\alpha)} = \sum_{j=0}^{-y} {\alpha \choose j} x^{(\alpha-j)} i^j y^{(j)} ,$$

is both monodiffric and rational in x and y. This shows that isaacs's conjecture is false.

In the classical case, the function z^{α} is multi-valued, and in fact if z_1^{α} denotes a particular branch, then it is well known that

$$z^{\alpha} = e^{2i\alpha n\pi} z_{1}^{\alpha}; n = 0, \pm 1, \pm 2, \ldots$$

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In the region G_2 , $z^{(\alpha)}$ (given in 3.10) is multi-valued due to the presence of the factor i^{α} , and in fact if $z_1^{(\alpha)}$ denotes a branch, then

$$z^{(\alpha)} = e^{2i\alpha n\pi} z_{1}^{(\alpha)}; n = 0, \pm 1, \pm 2, \dots;$$

demonstrating a close analogy with the function z^{α} .

The representation of $z^{(\alpha)}$ in G_1 is promising. It is derived from a combination of values of $z^{(\alpha)}$ on the positive half axes; it is multivalued; it is a very good approximation to x^{α} on the positive X-axis and to $(iy)^{\alpha}$ on the positive Y-axis.

On the other hand the representation of $z^{(\alpha)}$ in G_3 and G_4 illustrates a certain lack of symmetry in the usage of monodiffric functions. The function is single-valued in G_3 and G_4 and in fact is zero in G_3 - a poor analogy with the classical function z^{α} .

In view of the above observations, a need is suggested for an alternative method of defining discrete analyticity, which retains the algebraic simplicity of monodiffric functions, and which at the same time introduces a symmetry similar to the Schwarz Reflection Principle. Such a theory is discussed in [8].

In the preceding analysis, a backward-difference scheme was used to define a monodiffric function. However if the more usual forward-difference scheme is used, all of the corresponding results, comments and criticisms apply without loss of generality, where $x^{(\alpha)}$ is defined by $(-1)^{\alpha}\Gamma(\alpha-x)/\Gamma(-x)$.

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