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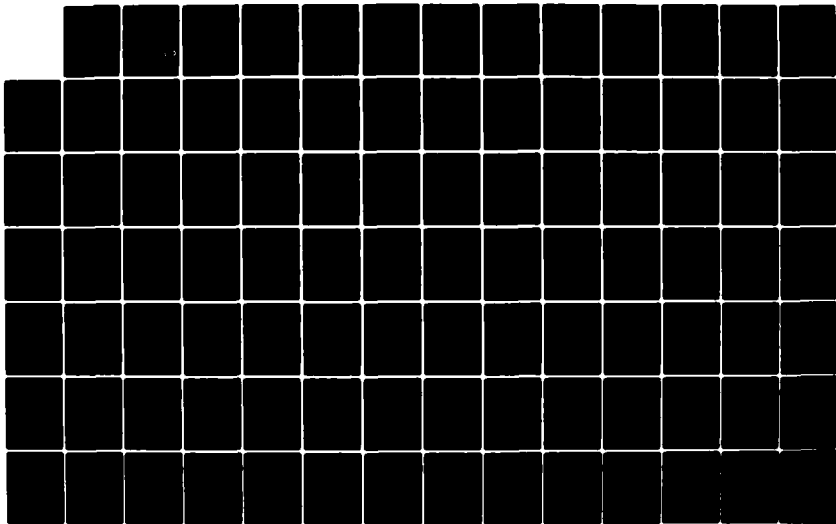
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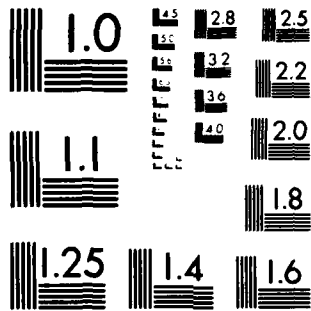
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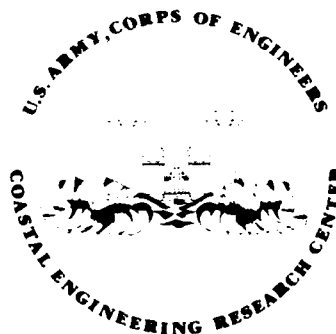
# A Numerical Model to Simulate Sediment Transport in the Vicinity of Coastal Structures

by

Marc Perlin and Robert G. Dean

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Prepared for

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PREFACE

The purpose of this report is to provide coastal engineers and researchers with a numerical model which predicts sediment transport and the resulting bathymetry in the vicinity of coastal structures. The work was carried out under the U.S. Army Coastal Engineering Research Center's (CERC) Numerical Modeling of Shoreline Response to Coastal Structures work unit, Shore Protection and Restoration Program, Coastal Engineering Area of Civil Works Research and Development.

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Comments on this publication are invited.

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*For* Billy B. Bishop, LTC, CE  
TED E. BISHOP  
Colonel, Corps of Engineers  
Commander and Director

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CONVERSION FACTORS, U.S. CUSTOMARY TO METRIC (SI) UNITS OF MEASUREMENT

U.S. customary units of measurement used in this report can be converted to metric (SI) units as follows:

Multiply	by	To obtain
inches	25.4	millimeters
	2.54	centimeters
square inches	6.452	square centimeters
cubic inches	16.39	cubic centimeters
feet	30.48	centimeters
	0.3048	meters
square feet	0.0929	square meters
cubic feet	0.0283	cubic meters
yards	0.9144	meters
square yards	0.836	square meters
cubic yards	0.7646	cubic meters
miles	1.6093	kilometers
square miles	259.0	hectares
knots	1.852	kilometers per hour
acres	0.4047	hectares
foot-pounds	1.3558	newton meters
millibars	$1.0197 \times 10^{-3}$	kilograms per square centimeter
ounces	28.35	grams
pounds	453.6	grams
	0.4536	kilograms
ton, long	1.0160	metric tons
ton, short	0.9072	metric tons
degrees (angle)	0.01745	radians
Fahrenheit degrees	5/9	Celsius degrees or Kelvins <sup>1</sup>

<sup>1</sup>To obtain Celsius (C) temperature readings from Fahrenheit (F) readings, use formula:  $C = (5/9) (F - 32)$ .

To obtain Kelvin (K) readings, use formula:  $K = (5/9) (F - 32) + 273.15$ .

A NUMERICAL MODEL TO SIMULATE SEDIMENT TRANSPORT  
IN THE VICINITY OF COASTAL STRUCTURES

by  
Marc Perlin and Robert G. Dean

I. INTRODUCTION

1. General.

The need for reliable predictions of shoreline response to man-made or natural modifications is increasing due to environmental concerns and the rising cost of remedial measures. The capability of numerical modeling in addressing problems of shoreline response has advanced with improvements in wave climatology, programs to better understand sediment transport relationships, and improvements in numerical modeling. *In-situ and remote sensing technology for the measurement of directional wave characteristics has been developed and applied, primarily within the last two decades.* In addition to providing the necessary climatology, the resulting measurements have provided the basis for evaluation and refinement of directional wave prediction procedures. Studies such as the Channel Islands Harbor Longshore Sand Transport Study (Bruno, et al., 1981) and the Nearshore Sediment Transport Study (NSTS) (Gable, 1979) have yielded a better understanding of surf zone dynamics and the resulting sediment transport. The increased capacities of large computers and reduced computing costs combined with improved numerical modeling algorithms have resulted in an extremely promising potential for the numerical modeling of shoreline problems.

Although it is doubtful that numerical modeling will ever replace completely the use of movable-bed physical models, the former type offers many advantages. The modeling of shoreline response is somewhat analogous to the problem of simulating storm surges in the coastal zone in which the scale effects and measurement difficulties essentially preclude physical modeling. For shorelines, the scale effects inherent in modeling sediment are well recognized and the costs of representing a substantial length of shoreline may be prohibitive. The laboratory representation of a realistic wave climate is at the forefront of technology.

The investigation of shoreline response can best proceed by several approaches, with each approach selected for the particular strengths which it offers. Field programs are costly, usually because of the considerable equipment and the extensive time required, but these programs are essential for quantifying the values of constants or parameters, the forms of which may be available from laboratory measurements or theoretical considerations. Laboratory studies occupy a special niche by allowing the wave conditions and independent variables to be controlled readily, experiments to be repeated, and selected measurements to be conducted. Although, as noted before, scale effects are present in laboratory measurements of sediment transport, the physics governing the process should be the same. However, the relative magnitudes of suspended versus bedload transport in the laboratory and field may differ. Laboratory studies can also provide an excellent base for evaluating certain aspects of a numerical model, including wave refraction and diffraction and the resulting shoreline patterns due to, for example, the placement of a littoral barrier. Numerical modeling offers the capability to

incorporate all the hydrodynamic wave-surf zone and sediment transport knowledge that is available from laboratory and field studies. Numerical modeling has the potential of providing accurate predictions of shoreline response to various structural and nourishment alternatives. Additionally, the possibility exists of employing numerical models and available field measurements to learn more about sediment transport mechanisms. In this latter mode, various candidate mechanisms or coefficients would be evaluated by determining the best match between measured and predicted shorelines and the bathymetry. Generally, this mode would require high-quality measurements of the forcing function (waves and nonwave-related currents) and the associated response (sediments) as well as the knowledge of appropriate conditions at the boundaries of the model.

The present report documents the development and application of an n-line numerical model to investigate bathymetric response to time-varying wave conditions and shoreline modification. The model includes both longshore and onshore-offshore sediment transport. Based on laboratory results, a new distribution of longshore sediment transport across the surf zone is used. The wave climate is specified on the model boundaries which do not need to extend to deep water. Efficient algorithms are employed for representing wave refraction and diffraction. The equation of sediment continuity and transport are solved by a completely implicit algorithm which allows a large time-step. Specified sediment transport values or specified contour positions can be accommodated at the model boundaries. The model is suitable for investigating the shoreline response to a variety of modifications such as one or more groins, terminal structures, structures with variable permeability, and beach nourishment with or without terminal structures.

## 2. Study Objectives.

The objectives of the present study include (a) the documentation of state-of-the-art models, (b) the development and documentation of an improved model which includes the capability to represent n-contour lines and (c) the application of the model to several relevant coastal engineering problems.

## II. BACKGROUND

This discussion describes significant contributions which either address numerical modeling of shorelines directly or provide improved capability for modeling.

### 1. Wave Refraction (Noda, 1972).

Noda developed an algorithm for solving the following steady state equation for wave refraction

$$\vec{\nabla} \times \vec{k} = 0 \quad (1)$$

in which  $\vec{\nabla}$ , the horizontal vector differential operator, and  $\vec{k}$ , the wave number, are defined in terms of their components as

$$\vec{\nabla} = \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} \quad (2)$$

$$\vec{k} = \vec{i} k_x + \vec{j} k_y \quad (3)$$

where  $\vec{i}$  and  $\vec{j}$  are the unit vectors in the x and y directions respectively. Equation (1) can be expressed as

$$\frac{\partial(k \sin \theta)}{\partial x} = \frac{\partial(k \cos \theta)}{\partial y} \quad (4)$$

in which  $\theta$  is the direction of the vector wave number relative to the x-axis and k denotes  $|\vec{k}|$ . Noda expanded Equation (4) to the following form

$$k \cos \theta \frac{\partial \theta}{\partial x} + \sin \theta \frac{\partial k}{\partial x} = -k \sin \theta \frac{\partial \theta}{\partial y} + \cos \theta \frac{\partial k}{\partial y} \quad (5)$$

Since  $\frac{\partial k}{\partial x}$  and  $\frac{\partial k}{\partial y}$  are known from the angular frequency  $\sigma$ , the water depth h, and the dispersion equation

$$\sigma^2 = g k \tanh kh \quad (6)$$

Equation (5) can be solved numerically, although there are problems of directional stability. The primary advantage of Equation (5) is that it allows the wave direction  $\theta$  to be determined on a specified grid, compared to unspecified locations that would be obtained by, for example, wave ray tracing.

## 2. Crenulate Bays (LeBlond, 1972).

LeBlond attempted to model the evolution of an initially straight shoreline between two headlands into a crenulate bay. The model constitutes a one-line (shoreline) representation. The transport equation employed related the total sediment transport to total water transport in the surf zone as predicted by the formulation provided by Longuet-Higgins (1970). The initial shoreline patterns resemble crenulate bays in nature; however, the predictions were found to be unstable for reasonably long periods of computational time and did not approach a realistic planform.

## 3. Crenulate Bays (Rea and Komar, 1975).

Rea and Komar employed a rather ingenious system of orthogonal grid cells to provide a cell which locally is displaced perpendicular to the general shoreline orientation. A one-line representation was employed. A simple and approximate representation of wave diffraction was employed. Although the model yielded reasonable results for the examples presented, the unique coordinate system would not be suitable for a general model as the coordinate system must be "tailored" to some degree to conform to the expected shoreline configurations.

#### 4. General One-line Shoreline Model (Price, Tomlinson, and Willis, 1972).

Price, Tomlinson, and Willis' formulation consists of the sediment continuity equation and the total sediment transport equation

$$Q_s = \frac{0.70 E_b (nC)_b \sin \alpha_b \cos \alpha_b}{\gamma_w (1 - p) (S_s - 1)} \quad (7)$$

in which  $E$  represents the wave energy density,  $(nC)$  the group velocity,  $\alpha$  the angle between the breaking wave front and the shoreline,  $\gamma_w$  the specific weight of water,  $p$  the in-place sediment porosity, and  $S_s$  the specific gravity of the sediment relative to the water in which it is immersed. The subscript "b" represents values at breaking.

Two formulations were presented by Price, Tomlinson, and Willis (1972). In the first, Equation (7) was substituted into the continuity equation and the results cast into a finite-difference form. In the second, the two equations were employed separately. The latter formulation was selected due to its simplicity and used for the results presented.

Computations were carried out for the case of beach response due to the placement of a long impermeable barrier. The total sediment transport equation by Komar (1969) was used and the planform was calculated at successive times. Refraction was apparently not accounted for in the numerical model. To verify the computations, a physical model study was carried out for the same conditions using crushed coal as the modeling material. The comparison was interpreted as good for up to 3 hours; however, for greater times, substantial differences occurred and these were interpreted as being due to wave refraction not being represented. The crushed coal was supplied to the model at the updrift end at a rate based on the Komar equation, and the results were interpreted as substantiating this relationship. However, the updrift end of the model beach receded substantially both in the numerical and physical models. In the physical model, this can only be interpreted as due to the Komar equation predictions being less than the actual transport rate, possibly due to the low specific gravity (1.35) of the crushed coal. The predicted recession of the updrift beach is puzzling, although it could be due to a problem in properly representing the updrift boundary condition.

Other one-line models for shoreline changes in the vicinity of coastal structures were developed by LeMehaute and Soldate (1977) and Perlin (1978). Perlin also developed a two-line model formulation, with one-line representing the shoreline and the second the offshore. Dragos (1981) developed an n-line model for bathymetric changes due to the presence of a littoral barrier.

### III. THE NUMERICAL MODEL

#### 1. Description.

There are several methods of modeling bathymetric changes due to the presence of a littoral barrier. An attempt can be made to either model the complete hydrodynamics and the resulting sediment transport or model using a combination of analytical and empirical sediment transport equations. The second method was chosen due to past relative success.

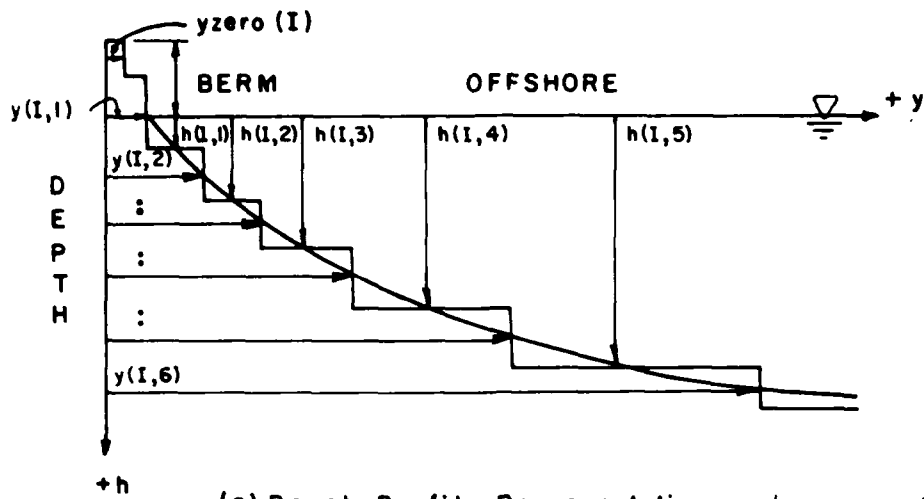
At least two methods of employing sediment transport equations exist: a fixed longshore and cross-shore grid system where the depth is allowed to vary or a fixed longshore and depth system where the cross-shore distance is allowed to change. Although it may seem somewhat awkward, the latter system was chosen for the model. This method allows the modeler to think of bathymetric changes due to a littoral barrier in terms of the effect on the contours; i.e., the contour realignment due to the structure's presence is observed. One limitation of this approach, at least as it was applied here, is that each depth contour must be single-valued; it is not possible to represent bars.

The next step in formulating the model was choosing the specific representation of the bathymetry. The model is an n-line representation of the surf zone in which the longshore direction  $x$  is divided into equal segments each  $\Delta x$  in length. The bathymetry is represented by n-contour lines, each a specified depth, which change in offshore location according to the equation of continuity. There are two components of sediment transport at each of the contour lines, a longshore component,  $Q_x$ , and an offshore component,  $Q_y$ . Figure 1 is a definition sketch showing the beach profile representation in a series of steps and the planform profile representation and notations used.

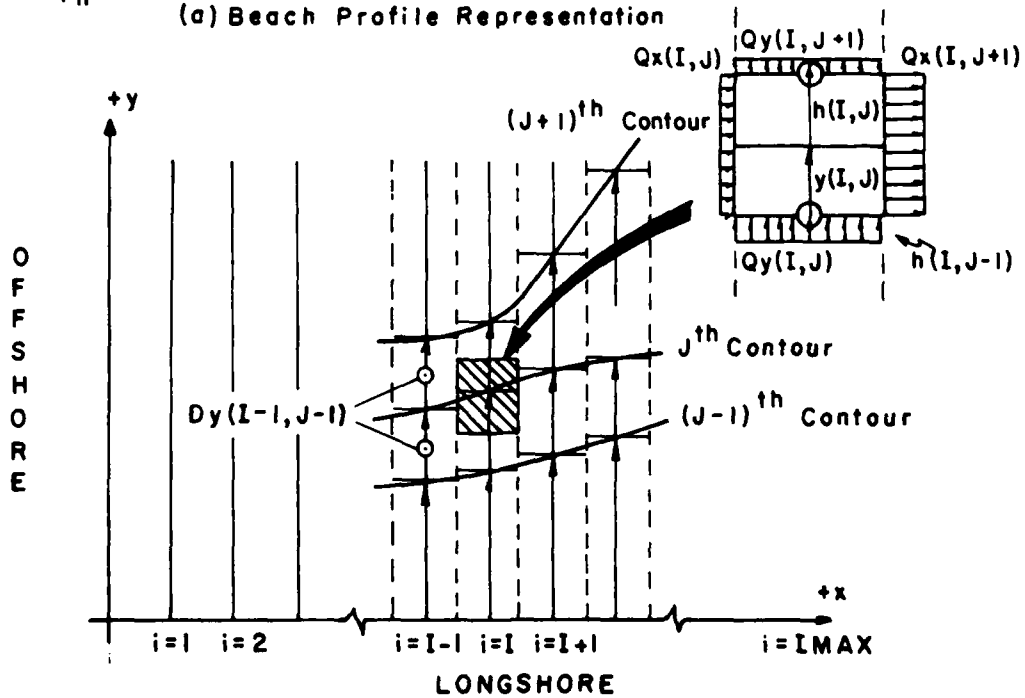
Implementation of the sediment transport equations requires knowledge of the wave field and the equilibrium offshore profile. A discussion of the refraction and diffraction schemes follows. The equilibrium profile is introduced when it is convenient. As an introduction to the logic used in the numerical model, a flow chart is presented in Figure 2.

#### 2. Refraction.

A refraction scheme compatible with variable  $\Delta y$ 's was required because of the variable distance to fixed depth contours (as opposed to the more usual fixed grid system where a grid center has a longshore and offshore coordinate with a variable depth). One of the benefits of the n-line model is the ease with which the response of the contours to a particular wave and structure condition can be visualized. A fixed grid system and an interpolation scheme could have been used to obtain the wave field; however, this would have reduced accuracy and increased computation time. The scheme developed also saves computation time because it does not use differential products terms.



(a) Beach Profile Representation



(b) Beach Planform Representation

Figure 1. Definition sketch.

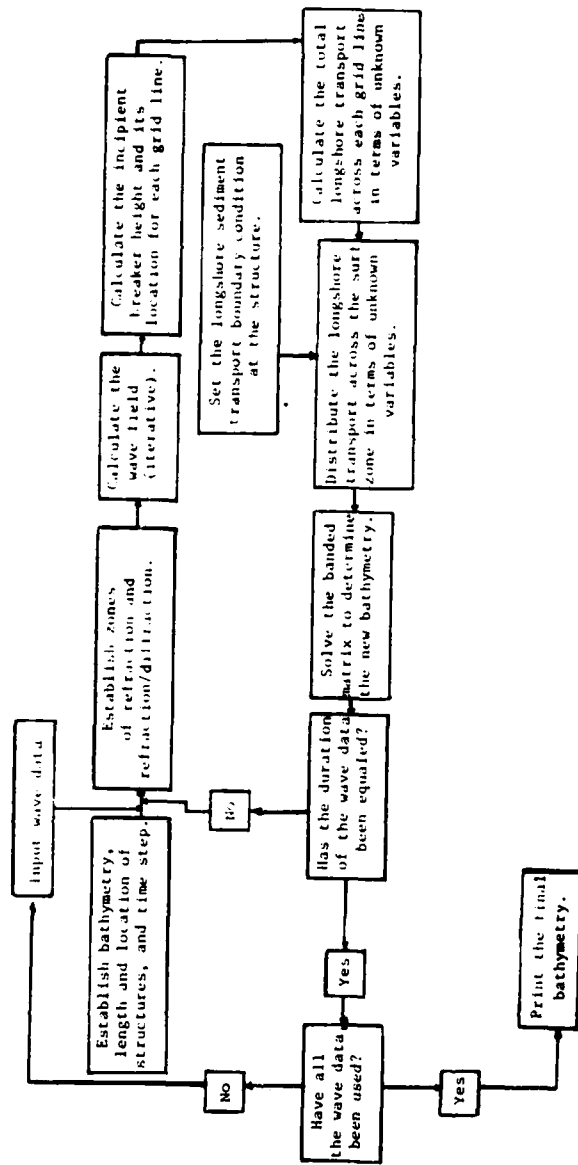


Figure 2. Flow chart.



The first of the governing equations used is the conservation of waves equation

$$\frac{d\sigma}{dt} + \vec{\nabla}_H \times \vec{k} = 0 \quad (8)$$

where  $\vec{\nabla}_H$  is the horizontal differential operator equal to  $\vec{i}(\partial/\partial x) + \vec{j}(\partial/\partial y)$  in which  $\vec{i}$  and  $\vec{j}$  are the unit vectors in the x and y directions, respectively, and x is the longshore direction, with positive to the right when facing the water, y the offshore direction, with positive seaward, and z the vertical coordinate, with positive defined as upwards. For the steady-state case, equation (8) yields

$$\frac{\partial}{\partial x} (k_y) - \frac{\partial}{\partial y} (k_x) = 0 \quad (9)$$

where  $k_x$  and  $k_y$  are the wave number projections in the respective directions. Defining  $\theta$  as the angle  $k$  makes with the y-axis positive in the counter-clockwise direction, the equation can be written in final form as

$$\frac{\partial}{\partial x} (k \cos \theta) = \frac{\partial}{\partial y} (k \sin \theta) \quad (10)$$

where  $\theta = \alpha + \pi$  (in radians). Noda (1972) and others have developed numerical solutions to expanded forms of equation (10). In the present study, equation (10) was initially central-differenced in the x-direction and forward-differenced in the y-direction with Snell's law used to specify the boundary conditions on the offshore boundary and one of the sides (i.e., the side of the wave angle approach). However, a numerical problem arose. The argument of the arcsine exceeded  $\pm 1.0$  for large  $\Delta y/\Delta x$ . To overcome this problem, a dissipative interface was used on the forward-difference term (after Abbott, 1979). The final finite-differenced form of equation (10) is

$$\theta_{i,j}^{n+1} = \sin^{-1} \left\{ \frac{1}{k_{i,j}} \left[ \tau(k \sin \theta)_{i-1,j+1} + (1-2\tau)(k \sin \theta)_{i,j+1} \right. \right. \quad (11)$$

$$\left. \left. + \tau(k \sin \theta)_{i+1,j+1} - \frac{\Delta y}{2\Delta x} \left( (k \cos \theta)_{i-1,j} - (k \cos \theta)_{i-1,j} \right) \right] \right\}$$

where  $\tau$  has been taken as 0.25. The past  $\theta_{i,j}^n$  and the present  $\theta_{i,j}^n$  wave angles are numerically averaged to give the  $\bar{\theta}_{i,j}$ . Newton's method is used to compute the wave number via the linear wave theory dispersion relation. In addition, numerical smoothing is used at the conclusion of the wave field calculation. This approximates in an ad hoc manner diffractive effects (lateral transfer of wave energy along the wave) which exist in nature but have been omitted due to use of the equation for refraction (equation 8). The smoothing routine is

$$\theta_{i,j} = \frac{1}{4} \theta_{i-1,j} + \frac{1}{2} \theta_{i,j} + \frac{1}{4} \theta_{i+1,j} \quad (12)$$

The second governing equation used in the refraction scheme is conservation of energy. Neglecting dissipation of energy due to friction, percolation, and turbulence, this equation can be expressed as

$$\vec{\nabla} \cdot (E \vec{C}_G) = 0 \quad (13)$$

where  $E$  is the average energy per unit surface area and  $\vec{C}_G$  the group velocity of the wave train. Performing the operation indicated and replacing  $\vec{C}_G$  by its components ( $C_G \sin \theta$ ) and ( $C_G \cos \theta$ ) results in the following:

$$\frac{\partial}{\partial x} (E C_G \sin \theta) + \frac{\partial}{\partial y} (E C_G \cos \theta) = 0 \quad (14)$$

Assuming linear theory,

$$E = \frac{\rho g H^2}{8} \quad (15a)$$

where  $\rho$  is the mass density of water,  $g$  the gravitational constant, and  $H$  the wave height. Dividing the equation by  $\frac{\rho g}{8}$ , finite-differencing and weighting the forward-differenced term as before, and solving for the wave height, results in the following:

$$H_{i,j}^{n+1} = \left\{ \frac{1}{(C_G \cos \theta)_{i,j}} \left[ (\tau)(H^2 C_G \cos \theta)_{i-1,j+1} + (1-2\tau)(H^2 C_G \cos \theta)_{i,j+1} \right. \right. \\ \left. \left. + (\tau)(H^2 C_G \cos \theta)_{i+1,j+1} + \frac{\Delta y}{2\Delta x} [(H^2 C_G \sin \theta)_{i+1,j} - (H^2 C_G \sin \theta)_{i-1,j}] \right] \right\}^{1/2} \quad (15b)$$

This equation is also solved by iterative techniques and the  $H_{i,j}^{n+1}$  and  $H_{i,j}^n$  are averaged at the conclusion of each iteration.

$C_G$  is determined by the linear wave theory relationship

$$C_G = \frac{C}{2} \left( 1 + \frac{2kh}{\sinh 2kh} \right) \quad (16)$$

where  $h$  is the water depth,  $k$  the wave number, and  $C$  the wave celerity. Wave height boundary conditions are input along the same boundaries as the wave angles using linear theory shoaling and refraction coefficients. The  $\theta$ 's have been previously determined. In both equations (11) and (15) for a variable grid system, the points  $(i+1, j)$  and  $(i-1, j)$  need to be determined (i.e., because the  $y$  coordinates are not fixed, adjacent values with the same subscripts can be farther or closer to shore, therefore interpolation must be used). The actual values are found by searching the  $(i+1)$  and  $(i-1)$  cross-shore lines, finding the adjacent values in the positive and negative  $y$ -direction, and interpolating to determine the value.

### 3. Diffraction.

The diffraction solution (in the lee of the structure) used in the model is based on the method of Penny and Price (1952). Assumptions used in this method include a semi-infinite breakwater, which is infinitesimally thin, linear wave theory and constant depth. A definition sketch for wave diffraction is shown in Figure 3. The quantity THETA0 represents the angle of wave incidence relative to the jetty axis, ANGLE represents the angle from the jetty at the point where the diffraction coefficient is to be computed, and RAD is the radial distance. The radial distance is then cast into a dimensionless parameter, RHOND ( $= 2\pi \text{ RAD}/L$ ), where L is the wavelength. This is equivalent to multiplying the radial distance by the wave number k.

The diffraction coefficient AMP is expressed as the modulus of the diffracted wave

$$\text{AMP} = (\text{Sum 1})^2 + (\text{Sum 2})^2 \quad (17)$$

where

$$\begin{aligned} \text{Sum 1} = & [\cos (\text{RHOND} (\cos (\text{ANGLE}-\text{THETA0}))) \cdot \left(\frac{1}{2} (1.0 + C_F + S)\right)] + \\ & [\sin (\text{RHOND} (\cos (\text{ANGLE}-\text{THETA0}))) \cdot \left(-\frac{1}{2} (S - C_F)\right)] + \\ & [\cos (\text{RHOND} (\cos (\text{ANGLE}+\text{THETA0}))) \cdot \left(\frac{1}{2} (1.0 + C_F + S)\right)] + \\ & [\sin (\text{RHOND} (\cos (\text{ANGLE}+\text{THETA0}))) \cdot \left(\frac{1}{2} (S - C_F)\right)] \quad (18) \end{aligned}$$

$$\begin{aligned} \text{Sum 2} = & [\cos (\text{RHOND} (\cos (\text{ANGLE}-\text{THETA0}))) \cdot \left(-\frac{1}{2} (S - C_F)\right)] + \\ & [\sin (\text{RHOND} (\cos (\text{ANGLE}-\text{THETA0}))) \cdot \left(\frac{1}{2} (1.0 + C_F + S)\right)] + \\ & [\cos (\text{RHOND} (\cos (\text{ANGLE}+\text{THETA0}))) \cdot \left(-\frac{1}{2} (S - C_F)\right)] + \\ & [\sin (\text{RHOND} (\cos (\text{ANGLE}+\text{THETA0}))) \cdot \left(\frac{1}{2} (1.0 + C_F + S)\right)] \quad (19) \end{aligned}$$

In Equations (18) and (19),  $C_F$  and S represent Fresnel integrals and are computed in the model by means of an approximation after Abramowitz and Stegun (1965).

Having obtained AMP, the wave height at the location in question is simply the product of the specified partially refracted incident wave height and AMP. The angle of the wave crest is computed assuming a circular wave front along any radial; this angle is then refracted using Snell's law.

Throughout the refraction and diffraction schemes, the local wave heights are limited by the value,  $0.78 \times \text{depth}$ .

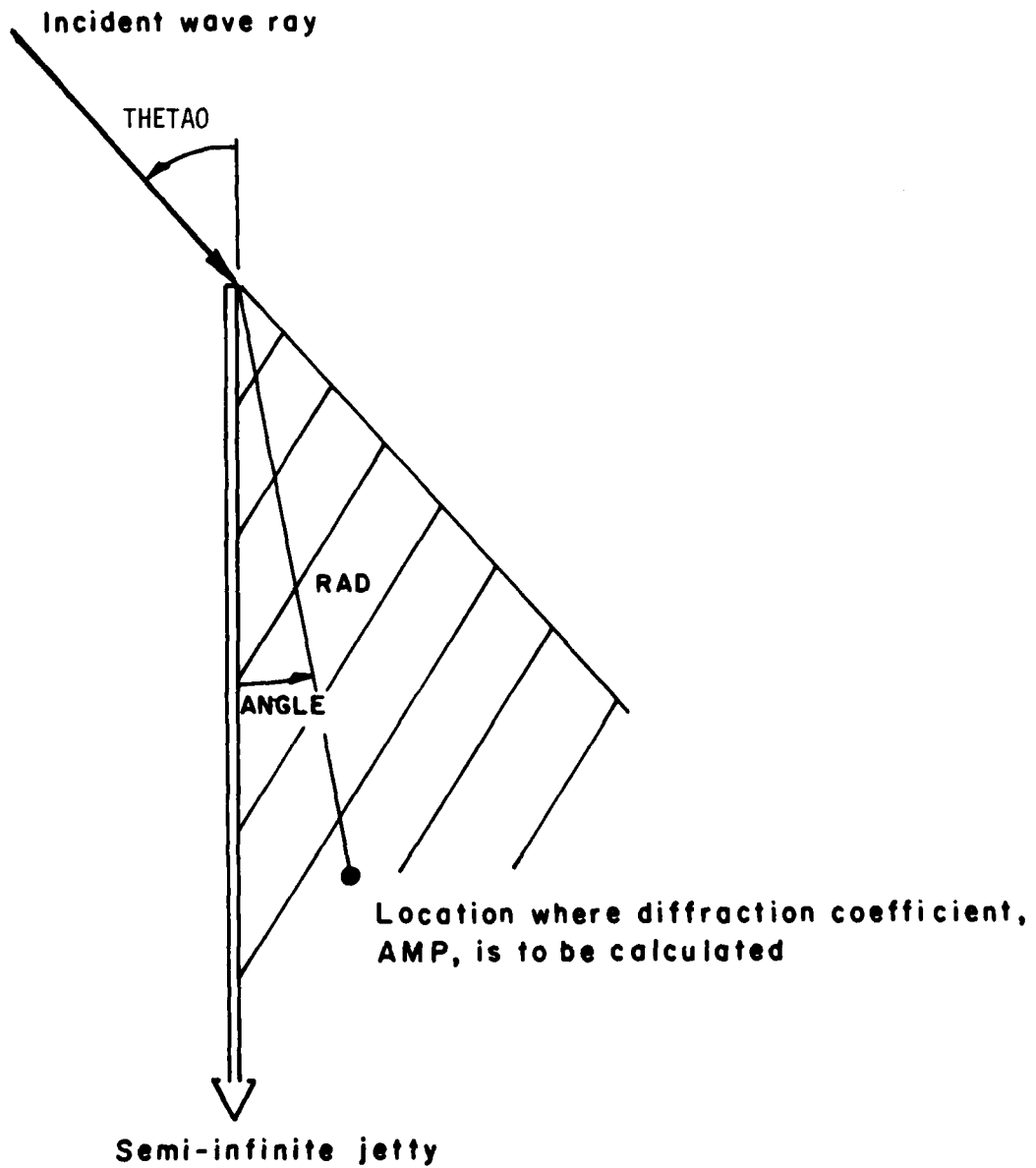


Figure 3. Definition sketch for wave diffraction.

#### 4. Sand Transport Model.

a. Governing Equations. Three basic equations are used to simulate the sediment transport and bathymetry changes according to the wave field. The equation of continuity

$$\frac{\partial y}{\partial t} + \frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} = 0 \quad (20)$$

requires as input, knowledge of the longshore and cross-shore components of sediment transport. The total transport alongshore has been measured by several investigators and many equations exist; however, the distribution of the transport across the surf zone is not well known. Fulford (1982) based on laboratory data from Savage (1959), developed a distribution of longshore sediment transport across the surf zone for the case of straight and parallel contours. Fulford's use of Savages experiment was based on two assumptions: 1) the structure must be a total littoral barrier and 2) onshore-offshore sediment transport could be neglected. Test 5-57 was chosen because the two criteria were nearly met. Savage reported that the groin acted as a total littoral barrier for the first 35 hours of the test (i.e., no bypassing occurred prior to 35 hours). This does not mean that no onshore-offshore transport occurred because as the profile steepens on the updrift side, onshore-offshore transport does occur. However, it was assumed to be negligible. In addition, the initial profile had been molded to an equilibrium profile via 150 hours of waves. Thus, the two criteria required to develop an inferred longshore distribution of sediment transport were nearly satisfied. This distribution is shown as a dashline in Figure 4. The smaller "maximum" is believed to be an extraneous effect of a groin downdrift from the location in the experiment where the data were taken. Therefore, this feature was replaced by a monotonically decreasing, smooth curve as shown by the "altered" curve. To analytically represent this distribution, a function of the following form was chosen

$$q_x(y) = (B) (y)^{n-1} e^{-(y)^n} \quad (21)$$

This type of equation is convenient because it is easily integrable, and by properly choosing the constant, B, the integral of the equation from zero to infinity can be required to equal a particular value. This too is highly desirable because, as was done in the model, the integral is set equal to one and then multiplying by the value of the well-known longshore transport equation, the value of the transport at any location across the surf zone can be determined. Further investigation suggested a value of  $n = 3$  to produce a curve similar to Fulford's curve. A more general form of the equation which allows more flexibility and curve fitting is

$$q_x(y) = B(y + a)^2 e^{\left\{ -\left[ \frac{y + a}{cy_b} \right] \right\}^3} \quad (22)$$

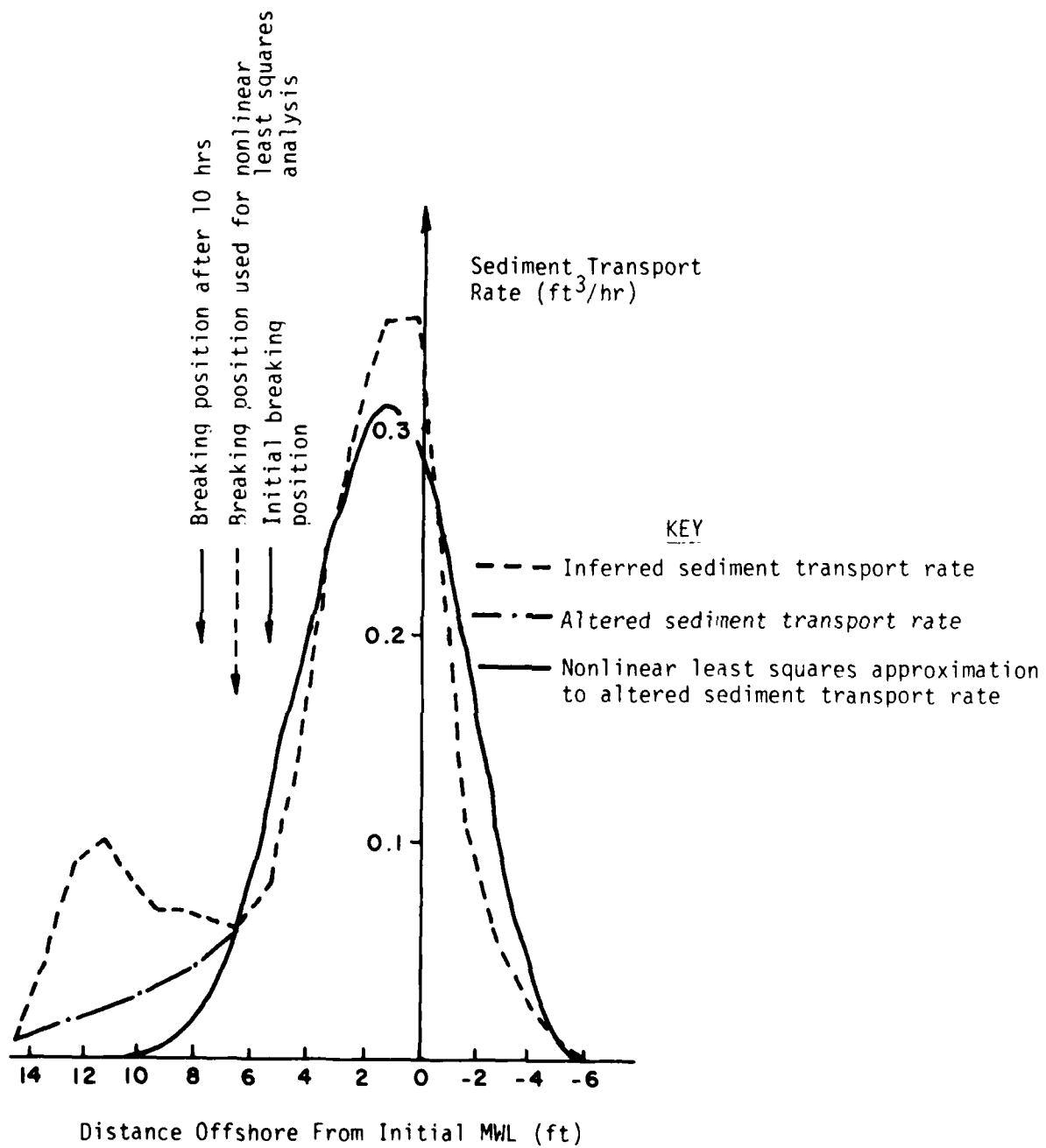


Figure 4. Distribution of sediment transport across the surf zone.

where  $y_b$  = distance to the point of breaking

$a$  = constant to allow sediment transport above mean water line (MWL) (swash transport or transport in region of wave setup) to be represented

$c$  = a constant establishing the width of the curve (to be determined)

$$B = \frac{3}{c^3 y_b^3} \quad (\text{causes } \int_0^{\infty} q_x(y) dy = 1.0)$$

Based on Fulford's (1982) results and considering  $a$  to be proportional to the breaking height divided by the beach slope, the constant of proportionality was determined to be unity; i.e.,  $a = h_b / (\partial h / \partial y)$ . Using equation (22) and a digitized version of the curve shown in Figure 4, a nonlinear least squares regression was carried out to determine the value of  $c$ . A Taylor's series expansion of the form

$$f^{k+1}(c,y) = f^k(c,y) + \frac{\partial f}{\partial c} \Delta c \quad (23)$$

where  $k$  and  $k+1$  represent the number of the iteration carried out. Least squares regression minimizes the square of the difference between observed and predicted values with respect to a change in the parameter being computed, or

$$\frac{\partial}{\partial (\Delta c)} \left\{ \sum_{n=1}^N \left[ f_{\text{OBS}} - \left( f^k(c,y) + \frac{\partial f}{\partial c} \Delta c \right) \right]^2 \right\} = 0 \quad (24)$$

where  $f_{\text{OBS}}$  represents the observed values, which in this case is  $q_x(y)_{\text{OBS}}$ . Carrying out the differentiation indicated and manipulating terms,  $\Delta c$  can be solved in terms of known quantities.

An iterative procedure was then used by updating the values of  $f^k(c,y)$ ,  $\partial f / \partial c$ , and  $c$  until an acceptably small change in  $c$  results. For the data herein, the value of  $c$  was determined to be 1.25. The final form of sediment transport of a  $y$  location in the surf zone results for a shoreline with straight and parallel contours, as

$$q_x(y) = \frac{3}{(1.25)^3 (y_b)^3} (y+a)^2 e^{-[(y+a)/(1.25 y_b)]^3} \quad (25)$$

This equation, which is also presented in Figure 4, predicts the relative transport at point  $y$ . To obtain the fraction of transport between two  $y$  coordinates, the integral of equation (25), from  $y_1$  to  $y_2$ , must be used.

$$Q_{xND} = Q_x \Big|_{y_1}^{y_2} = \int_{y_1}^{y_2} q_x(y) dy = e^{-[(y_1 + a)/(1.25 y_b)]^3} - e^{-[(y_2 + a)/(1.25 y_b)]^3} \quad (26)$$

$Q_x[ND]$  is dimensionless; therefore, to compute a value in, say, cubic feet per second, it must be multiplied by the total transport along a perpendicular to the shoreline obtained from the total longshore transport equation used in the model

$$Q = C' H_b^{5/2} \sin(2\alpha_b) \quad (27)$$

See Appendix A for a discussion of the constant  $C'$ . It is noted that the transformation of  $q_x(y)$  to  $q_x(h)$  can be effected by multiplying by the one-dimensional Jacobian ( $\Delta y/\Delta h$ ). This latter form ( $q_x(h)$ ) is more useful here because the present model simulates the changes in contour position ( $\Delta y$ ) rather than changes by depth ( $\Delta h$ ).

In the numerical model,  $Q_x(I,J)$  (see Fig. 1) is determined using equation (26) except for the shoreline contour,  $J=1$ , and the farthest offshore contour simulated,  $J = JMAX$ . The shoreline contour longshore transport,  $Q_x(I,1)$ , in order to include swash transport, uses equation (16); however, the first term is set equal to 1.0. The seawardmost contour transport,  $Q_x(I,JMAX)$ , in order to include any longshore transport not yet accounted for, neglects the second term of equation (26) (i.e., it accounts for transport from  $y(I,JMAX)$  to infinity). The dimensionless numbers are then multiplied by  $Q$  determined from equation (27). This method is based on parallel contours which may not exist. In order to compensate for the nonparallel nature of the contours (note that refraction does account for it as far as the wave field is concerned), the term  $\sin(2\alpha_b)$  of equation (27) is replaced by  $\sin(2\alpha_l)$  shoreward of the breakpoint, where  $\alpha_l$  represents the angle between the "local" wave angle and the "local" contour. It can be argued that for a spilling breaker, the remaining surf zone at any point "sees" a total transport similar to equation (27), where  $\alpha_b$  and  $H_b$  are the local values. The problem is that the constant of proportionality was determined for the entire surf zone and for nearly straight and parallel contours. This not being the case, the equation was altered on intuitive grounds to reflect the fact that the contours are no longer straight and parallel.



The second input required by the continuity equation to predict the bathymetric changes is the cross-shore sediment transport. The governing equation for onshore-offshore transport (after Bakker, 1968) is

$$Q_{y_{i,j}} = \Delta x C_{OFF_{i,j}} \left[ y_{i,j-1} - y_{i,j} + W_{EQ_{i,j}} \right] \quad (28)$$

where  $C_{OFF}$  is an activity factor (inside the surf zone =  $10^{-5}$  feet per second for the prototype simulation herein,  $10^{-4}$  feet per second for the physical model simulation) (see App. A. for a discussion) and  $W_{EQ(i,j)}$  is the positive equilibrium profile distance between  $y(i,j)$  and  $y(i,j-1)$ , determined from the equilibrium profile used in the numerical model  $h = Ay^{2/3}$  (Dean, 1977). See Appendix A for discussion of the value of A. The physical interpretation of equation (28) is that as this profile steepens (flattens), sediment is transported offshore (onshore).

b. Methods of Solution. Three separate finite-difference techniques were used to solve the equations:

- (1) Explicit longshore-continuity and explicit cross-shore continuity;
- (2) Implicit longshore-continuity and explicit cross-shore continuity for half a time-step then vice versa; and
- (3) Implicit longshore-cross-shore continuity.

An explicit formulation was first developed which used the refraction scheme, the distribution of longshore sediment transport across the surf zone, and the onshore-offshore sediment transport equation. Problems in addition to the usual ones which are encountered with explicit methods (e.g., computation time and cost) were immediately realized. In the explicit method, both transport computations are based on the former values of the contour locations and are completely uncoupled. Stability of an explicit scheme requires a small time-step. In addition, the noncoupled nature of the equations, in some cases, resulted in crossing of the contours due to the transport computed.

It is logical to assume that an implicit formulation of the longshore transport equation used as input to the continuity equation along with the explicit onshore-offshore transport component would help the numerical stability (on the other half time-step, the longshore component would be computed explicitly and the onshore-offshore transport equation would be solved implicitly with the continuity equation). Although this scheme would be superior to the explicit procedure, it still would be susceptible to crossing contours. It should be noted that the magnitude of the coefficient used in the onshore-offshore equation is very important to the extent that the simulation models natural phenomena. If the coefficient is very small or vanishes, sediment will not move offshore and contours will cross because of the variation in the distribution of longshore sediment transport across the surf zone. If the coefficient is too large, the onshore-offshore transport, may become large enough that on a particular time step, an offshore contour

would move too far shoreward, thereby crossing an inshore contour or vice versa. Once the contours cross, not only does the bathymetry become unrealistic, but mathematically, the equation which computes the longshore distribution across the surf zone changes signs at some locations and the entire model becomes physically unrealistic.

To circumvent these problems, an implicit scheme that simultaneously solves the three governing equations, was developed. Utilizing equation (26), and the one-dimensional Jacobian ( $\Delta y/\Delta h$ ) to convert to  $Q_x(h)$ , the total longshore transport equation (27), the following equation is obtained,

$$Q_{x_{i,j}} = \left\{ \left[ \exp \left( - \left( \frac{(h_{i,j-1})^{3/2} + H_{b_i} A^{3/2}}{1.25 h_{b_i}} \right)^3 \right) - \exp \left( - \left( \frac{(h_{i,j})^{3/2} + H_{b_i} A^{3/2}}{1.25 h_{b_i}} \right)^3 \right) \right] \right. \\ \left. \times \left( C' H_{b_i}^{5/2} \right) \right\} \times \sin (2\theta - 2\alpha_c) \quad (29)$$

$Q_x(i,j)$  represents the sediment transport between depths  $h(i,j)$  and  $h(i,j-1)$  (see Fig. 1). The term in brackets represents the normalized distribution of longshore transport between  $h(i,j)$  and  $h(i,j-1)$ ;  $\theta$  is the averaged wave angle at the location of  $Q_x(i,j)$  and  $\alpha_c$  is the local contour orientation angle. Defining everything except  $\sin (2\theta - 2\alpha_c)$  as  $v(i,j)$  and using a superscript to denote a time step, this equation can be written

$$Q_{x_{i,j}}^{n+1} = v_{i,j} \sin (2\theta - 2\alpha_c^{n+1}) \quad (30)$$

The assumption has been made that the wave field ( $H$  and  $\theta$ ) do not vary during the bathymetric changes over the time-step. Using the following trigonometric identities,

$$\sin (2a - 2b) = \sin 2a \cos 2b - \cos 2a \sin 2b \quad (31a)$$

$$\cos 2a = 2 \cos^2 a - 1 \quad (31b)$$

$$\sin 2a = 2 \sin a \cos a \quad (31c)$$

and recognizing that the following expression is an approximation

$$\sin (\alpha_c^{n+1})_{i,j} = \frac{\frac{1}{2} (y_{i,j}^{n+1} - y_{i-1,j}^{n+1} + y_{i,j}^n - y_{i-1,j}^n)}{\left( (\Delta x)^2 + (y_{i,j} - y_{i-1,j})^2 \right)^{1/2}} \quad (32)$$

along with assuming that the change in the denominator is small for a reasonable time-step (the numerator has been averaged over the  $n^{\text{th}}$  and  $n+1^{\text{th}}$  time-steps), equation (30) results in

$$Q_{x_{i,j}}^{n+1} + (S3)_{i,j} y_{i,j}^{n+1} - (S3)_{i,j} y_{i-1,j}^{n+1} = (RHS1)_{i,j}^n \quad (33)$$

$$\text{where } (S3)_{i,j} = \left(\frac{1}{2}\right) (v_{i,j}) \cos(2\theta) (2 \cos \alpha_c) \frac{1}{(\Delta x^2 + \Delta y^2)^{1/2}}$$

$$(RHS1)_{i,j}^n = (v_{i,j}) (2 \sin \theta \cos \theta) (\cos^2 \alpha_c - 1) - (S3)_{i,j} (y_{i,j}^n - y_{i-1,j}^n)$$

Here it has also been assumed that  $\cos^2 \alpha_c$  does not change over the time step. Equation (33) is the final form of the longshore sediment transport equation prior to its use in conjunction with the other equations.

Averaging  $y$  values on the  $n^{\text{th}}$  and  $(n+1)^{\text{th}}$  time-steps, equation (29) can be rewritten as

$$Q_{y_{i,j}} = \text{Const6}_{i,j} \left\{ \frac{1}{2} \left( y_{i,j-1}^{n+1} + y_{i,j-1}^n - y_{i,j}^{n+1} - y_{i,j}^n \right) + W_{EQ_{i,j}} \right\} \quad (34)$$

where  $\text{Const6}(i,j) = \text{Coff}(i,j) \cdot \Delta x$ . This is the final form on the onshore-offshore sediment transport equation.

The equation of continuity, finite-differenced for the  $n^{\text{th}}$  and  $(n+1)^{\text{th}}$  time-steps, can be written as

$$\frac{y_{i,j}^{n+1} - y_{i,j}^n}{\Delta t} = \frac{1}{2\Delta x \Delta h} \left\{ Q_{x_{i,j}}^{n+1} + Q_{x_{i,j}}^n - Q_{x_{i+1,j}}^{n+1} - Q_{x_{i+1,j}}^n + Q_{y_{i,j}}^{n+1} + Q_{y_{i,j}}^n - Q_{y_{i,j+1}}^{n+1} - Q_{y_{i,j+1}}^n \right\} \quad (35)$$

Defining  $R_{i,j}$  as  $1/(2\Delta x \Delta h)$ , inserting equations (33) and (34) into equation (35), and transferring all known quantities for the  $n^{\text{th}}$  time-step to the right-hand side of the equation result in

$$\begin{aligned} & y_{i,j}^{n+1} + (\Delta t R_{i,j}) S3_{i,j} y_{i,j}^{n+1} - (\Delta t R_{i,j}) S3_{i,j} y_{i-1,j}^{n+1} - (\Delta t R_{i,j}) S3_{i+1,j} y_{i+1,j}^{n+1} \\ & + (\Delta t R_{i,j}) S3_{i+1,j} y_{i,j}^{n+1} - (\Delta t R_{i,j} \text{Const6}_{i,j}) \left( \frac{1}{2} [ y_{i,j-1}^{n+1} - y_{i,j}^{n+1} ] \right) \\ & + (\Delta t R_{i,j} \text{Const6}_{i,j+1}) \left( \frac{1}{2} [ y_{i,j}^{n+1} - y_{i,j+1}^{n+1} ] \right) = (\text{AWARE})_{i,j} \quad (36) \end{aligned}$$

Equation (36) can be rewritten as

$$(1 + U + V + Z1 + Z2) y_{i,j}^{n+1} - (U)y_{i-1,j}^{n+1} - (V)y_{i+1,j}^{n+1} - (Z1)y_{i,j-1}^{n+1} - (Z2)y_{i,j+1}^{n+1} = (AWARE)_{i,j} \quad (37)$$

where

$$U = \Delta t R_{i,j} S3_{i,j}$$

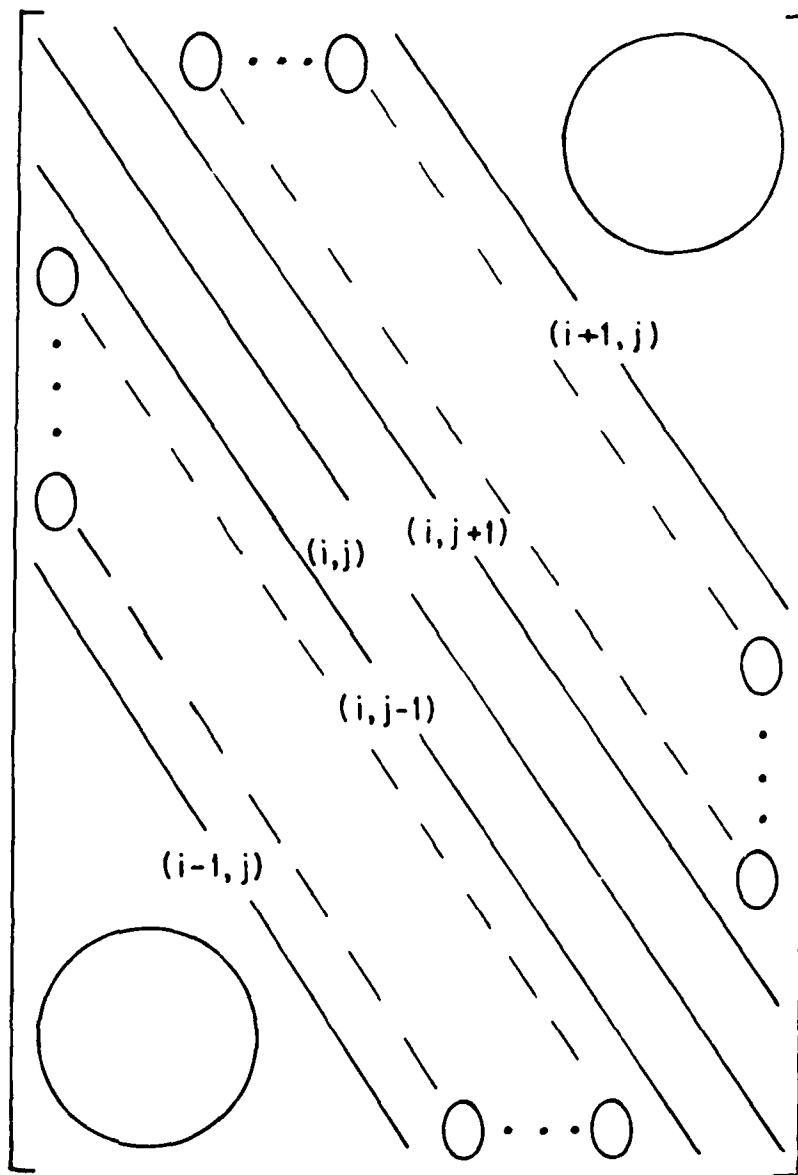
$$V = \Delta t R_{i,j} S3_{i+1,j}$$

$$Z1 = \left(\frac{\Delta t}{2}\right) R_{i,j} \text{Const6}_{i,j}$$

$$Z2 = \left(\frac{\Delta t}{2}\right) R_{i,j} \text{Const6}_{i,j+1}$$

Equation (37) is a weighted, centered scheme in which  $y_{i,j}^{n+1}$  is computed using a weighting of itself and its four adjacent grid "neighbors". The weighting factors (U, V, Z1, and Z2) are functions of the wave climate, the slope between contours, and the variables included in the original formulation. An investigation of a small gridded system demonstrated that by writing simultaneous equations, one for each  $y_{i,j}$ , a banded matrix results. This matrix can be solved by LEQT1B, one of the available routines from the International Math and Statistics Library (IMSL). A schematic representation of the matrix A which results from the matrix equation  $[A][y] = [B]$  is presented in Figure 5. In this schematic, the large zeros represent triangular corner sections of all zeros and the 0...0 represents bands of zeros, the number of which is dependent on the number of contours simulated (the number of zero bands between either remote nonzero bands and the tridiagonal nonzero bands equals two less than the number of contours modeled (in both the upper and lower codiagonals of the matrix)). An inspection of the subscripts in equation (29) yields the reason the zero bands are required. The more j values (contours) used, the more y grids there are along any perpendicular to shore. This causes zeros to appear in the matrix between bands as the weighting factors await being used to operate on  $y^{n+1}(i-1,j)$  and  $y^{n+1}(i+1,j)$ . For this reason, the expense of simulating an increasing number of contours is exponential. The LEQT1B routine, utilizes banded storage and saves both storage and computation time; however, the routine has no special way of handling the interior zero bands. One refinement which would save computation time would be to develop an algorithm to solve and store the matrix by taking advantage of these inner zero bands; however, it is beyond the scope of this project.

Of course, the matrix requires boundary values on longshore extremities and on both onshore and offshore boundaries. The longshore boundary conditions are treated by modeling a sufficient stretch of shoreline so that effects of a structure's presence are minimal. The y values along these boundaries can therefore be fixed at their initial locations. In the onshore-offshore direction, boundaries are treated quite differently. The



Note: Size of matrix full storage mode  
 $[(IMAX-2)(JMAX) \times (IMAX-2)(JMAX)]$   
 Size of matrix banded storage mode  
 $[(IMAX-2)(JMAX) \times (2JMAX + 1)]$

Figure 5. Schematic representation of banded matrix if not stored in banded storage mode.

berm and beach face are assumed to move in conjunction with the shoreline position. The required sediment transport is then computed by the change in position of the shoreline. The two equations are

$$y_{i,0}^{n+1} = y_{i,0}^n + [y_{i,1}^{n+1} - y_{i,1}^n] \quad (38a)$$

$$Q_{y_{i,1}}^{n+1} = - \left[ \frac{\text{Berm } \Delta x}{\Delta t} \right] [y_{i,1}^{n+1} - y_{i,1}^n] \quad (38b)$$

The offshore boundary is treated by keeping  $y^{n+1}(i, j_{\text{max}})$  (the contour beyond the last simulated contour) fixed, until the angle of repose is exceeded. Then, the  $y^{n+1}(i, j_{\text{max}}+1)$  is reset (at the conclusion of the  $n + 1$  time-step) to a position such that the slope equals the angle of repose. Note that  $y^{n+1}(i, 0)$  is represented in the program by  $YZERO_i$ .

There are also no-flow boundary conditions required at each of the structures being modeled. These are imposed on the adjacent  $y$ -grid points which are located downdrift (i.e., in the shadow zone) of the structure and shoreward of the structures' seaward extremities. They are imposed by setting  $S3_{i,j}$  of equation (33) and  $DISTR_{i,j}$  (the term in square brackets in equation (29)) equal to zero, thereby causing  $Q_x(i,j)$  to be zero (i.e., the no-sediment flow condition). This boundary condition is imposed automatically for every shore-perpendicular structure.

It was found that even with the implicit formulation, high frequency oscillations occurred in the  $y$  values immediately updrift and downdrift of the structure. The solution did not "blow up"; however, on larger time-steps "sloshing" (oscillating) did occur. Part of this problem was due to the boundary condition at the structure which had been such that either no sand was allowed along a contour line or the sand determined by the equations was allowed to be transported. Because of the very large angle which existed around the tip of the structure when a contour first exceeded the length of the structure, very large amounts of sediment transport were predicted. In the nature where analog sand transport rather than digitized transport occurs, this does not happen. Therefore, the boundary condition was altered to constantly allow sand transport around the end of the structure in proportion to that part of the contour representation which exceeded the structure (i.e., the transport was calculated for the location at tip of the structure as if the structure was not there and then a proportion of this value was allowed to bypass). Although the transport around the tip of the structure is based on the values from the past time-step, it more closely simulated the natural phenomenon.

Additionally, a dissipative interface is used on the  $y$  values as follows:

$$y_{i,j} = (\tau) y_{i-1,j} + (1 - 2\tau) y_{i,j} + (\tau) y_{i+1,j} \quad (39)$$

where  $\tau$  was again taken as 0.25. It is noted that only high frequency oscillations in  $y$  are affected by the use of equation (39); the total sum of  $y$  values is not affected. Also, in all the dissipative interface

schemes used, if a boundary point is being computed, either a forward-difference or a backward-difference of equation (39) is used (after Abbott, 1979):

$$\text{Backward: } y_{i,j} = (\tau)y_{i-1,j} + (1 - \tau)y_{i,j} \quad (40a)$$

$$\text{Forward: } y_{i,j} = (\tau)y_{i+1,j} + (1 - \tau)y_{i,j} \quad (40b)$$

#### IV. SIMULATIONS AND VERIFICATION

Several simulations were run; two were attempts at verifying the numerical model, the others were run to gain insight. Because a complete data set does not exist, only the available data are compared. The first modeling effort was to simulate the physical model tests of Savage (1959). A second set of cases was run for shore-perpendicular structures. Next, an effort was made to model sediment transport in the vicinity of a hypothetical dredge disposal site in the 11- to 14-foot depths off Oregon Inlet. Finally, the Channel Islands Harbor Longshore Transport Study (Bruno, et al., 1981) was modeled. Bathymetric changes were closely monitored during this study; however, the wave climate ( $H$ ,  $\theta$ ,  $T$ ) used was determined from the Littoral Environmental Observation (LEO) data and uncertainties exist as to the accuracy of the data.

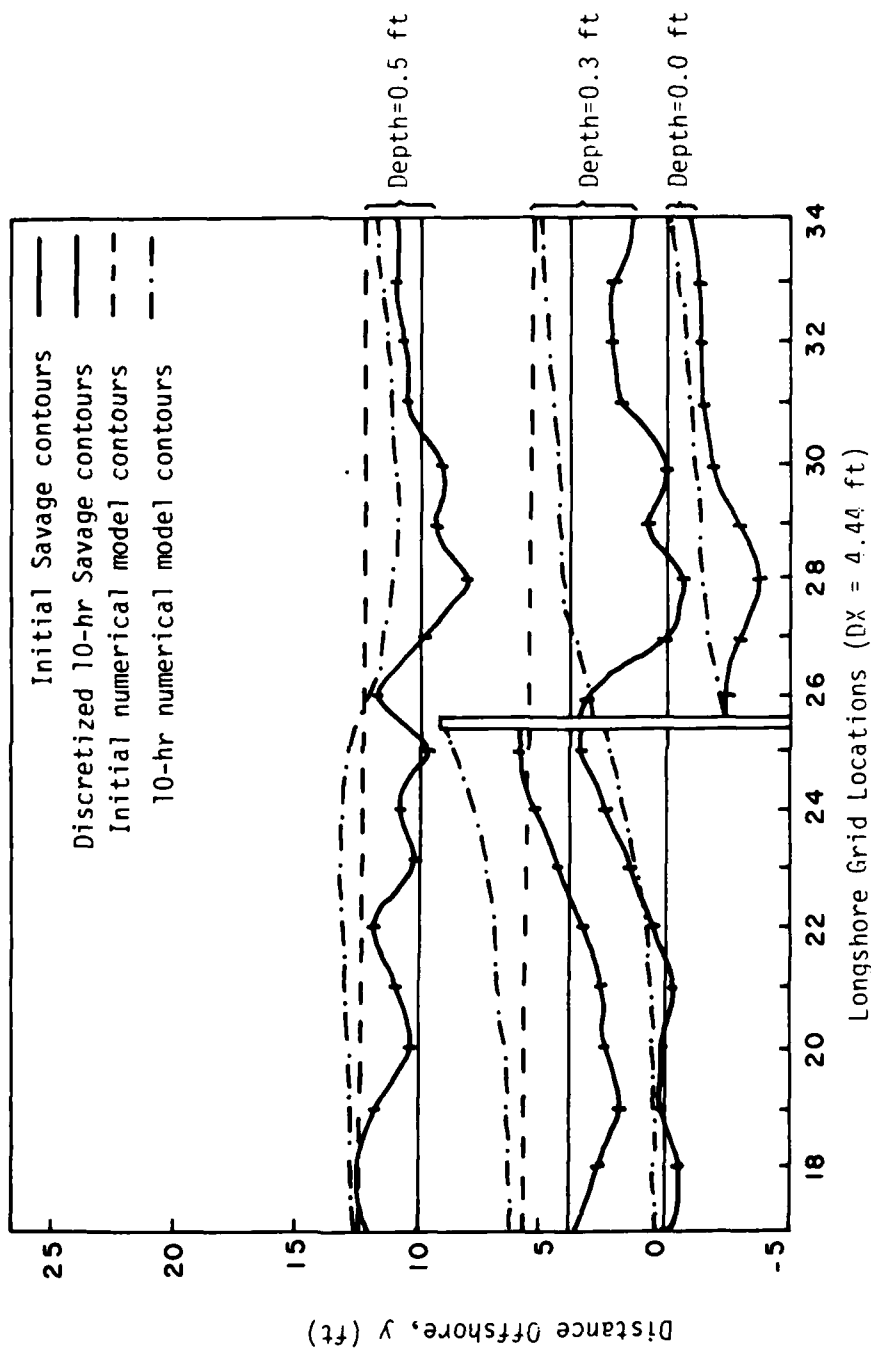
##### 1. Simulation of Savage's Physical Model Tests.

The numerical model was used to simulate one of the physical model tests of Savage (1959). Test 5-57 was simulated numerically for a 10-hour period. In this physical model, the mean sediment size was 0.22 millimeters, the wave height averaged 0.25 feet, the wave period was 1.5 second, the wave angle was  $30^\circ$  (at a depth of 2.3 feet), and the groin was approximately 9.5 feet from still water to its seaward limit.  $C_{OFF}$  was held constant at  $10^{-4}$  feet per second throughout the profile for this simulation. The offshore profile is presented in Savage (1959). Figure 6 represents three of the eight contours simulated. Note that the initial 0.3- and 0.5-foot-depth contours, in the numerical representation are too far seaward by approximately 2 feet. This is due to the  $h = Ay^{2/3}$  equation as compared to the equilibrium physical model profile. Realizing this, it is the shape of the contour which must be used as an indication of the numerical model predictions. The general trend of the contours is similar, although the numerical model contours are displaced farther seaward as expected. The major differences are in the diffraction zone.

##### 2. Several Runs Using Shore Perpendicular Structures to Demonstrate Effects of Altering Some of the Pertinent Parameters.

In the following simulations, the models were run until their near-equilibrium values were achieved. Coefficient  $C_{OFF}$  was not a function of depth (beyond the surf zone) but was held constant throughout the simulated area. Important variables are as shown in the figures. Only one wave condition ( $H_0 = 3$  feet,  $T = 7$  seconds, and a deepwater wave angle  $\alpha_0$

Note: Discrepancy between initial Savage contours and initial model contours is due to use of the  $h = Ay^{2/3}$  profile.



Longshore Grid Locations ( $DX = 4.44$  ft)

Figure 6. Simulation of the physical model of Savage (1959).



of 60°) was used as input for all four cases. Case 4.2a used an equilibrium shape factor A of 0.0899 and one groin. Case 4.2b was similar to 4.2a with the only modification being, that the A value was changed to 0.1486. In this way, a direct comparison was made based only on the shape of the equilibrium profile. Cases 4.2c and 4.2d used A-values of 0.0899 and 0.1486, respectively, but this time three shore-perpendicular, evenly spaced structures were simulated.

a. Comparison of Cases 4.2a and 4.2b. The most obvious difference between Figures 7 and 8 is the volume of sand impounded updrift and eroded downdrift. This is due to blockage of more of the active transport zone in the second case (i.e., a shorter groin is required for an equivalent performance on a steeper beach). The next obvious difference is the size of the perturbation which exists in the offshore contours. Clearly, case 4.2b is more perturbed and this is expected because larger offshore transports occur due to the steepening on the updrift side. Conversely, this means less sediment is initially bypassed (and along with the downdrift requirement for larger volumes of sand) causes larger erosional features in case 4.2b. Another interesting feature is the downdrift fillet which occurs in the third, fourth, and fifth contours. The fillet is due to the shape of the sixth contour which occurs because of the inability of the wave to transport more sediment (due to the reduction in wave height and angle in the diffraction shadow zone). The remaining difference is also due to the volume of sediment being impounded; i.e., the distance and extent of change the presence of the groin causes upcoast and downcoast.

b. Comparison of Cases 4.2c and 4.2d. The variations between cases 4.2c and 4.2d are very similar to the differences between cases 4.2a and 4.2b as would be expected with a groin field (here, three groins) as compared with a single groin (see Figs. 9 and 10). There is, however, one additional feature which can be attributed to the additional groins. Note that in the direction of littoral drift, the size of the fillet is decreasing. This is due to the updrift beach having an uninterrupted supply of sediment while the downdrift groin compartments are supplied sand at a rate determined by the bypassing. Part of this feature may also be due to the system not having attained complete equilibrium.

The effects of the fixed boundary conditions are evident on all cases run. In these example cases, the boundaries are clearly too close to the structure to provide a proper representation of the fillet contours.

### 3. Simulations of Sediment Transport of Dredge Disposal in the Vicinity of Oregon Inlet.

Hypothetical dredge disposal movement in the nearshore but beyond what is normally the surf zone at Oregon Inlet's adjacent beach to the south was modeled. In order to do these simulations, the program was altered such that for every  $n^{\text{th}}$  iteration (time periods), the contours were shifted seaward to simulate the addition of dredged sediment disposal. The program presented in Appendix B does require slight modification to simulate this situation.

In general, the fifth and sixth contours were shifted seaward on a monthly basis to simulate the disposal of 121,000 cubic yards of sediment.

Note: J=7 and 8 contours not shown

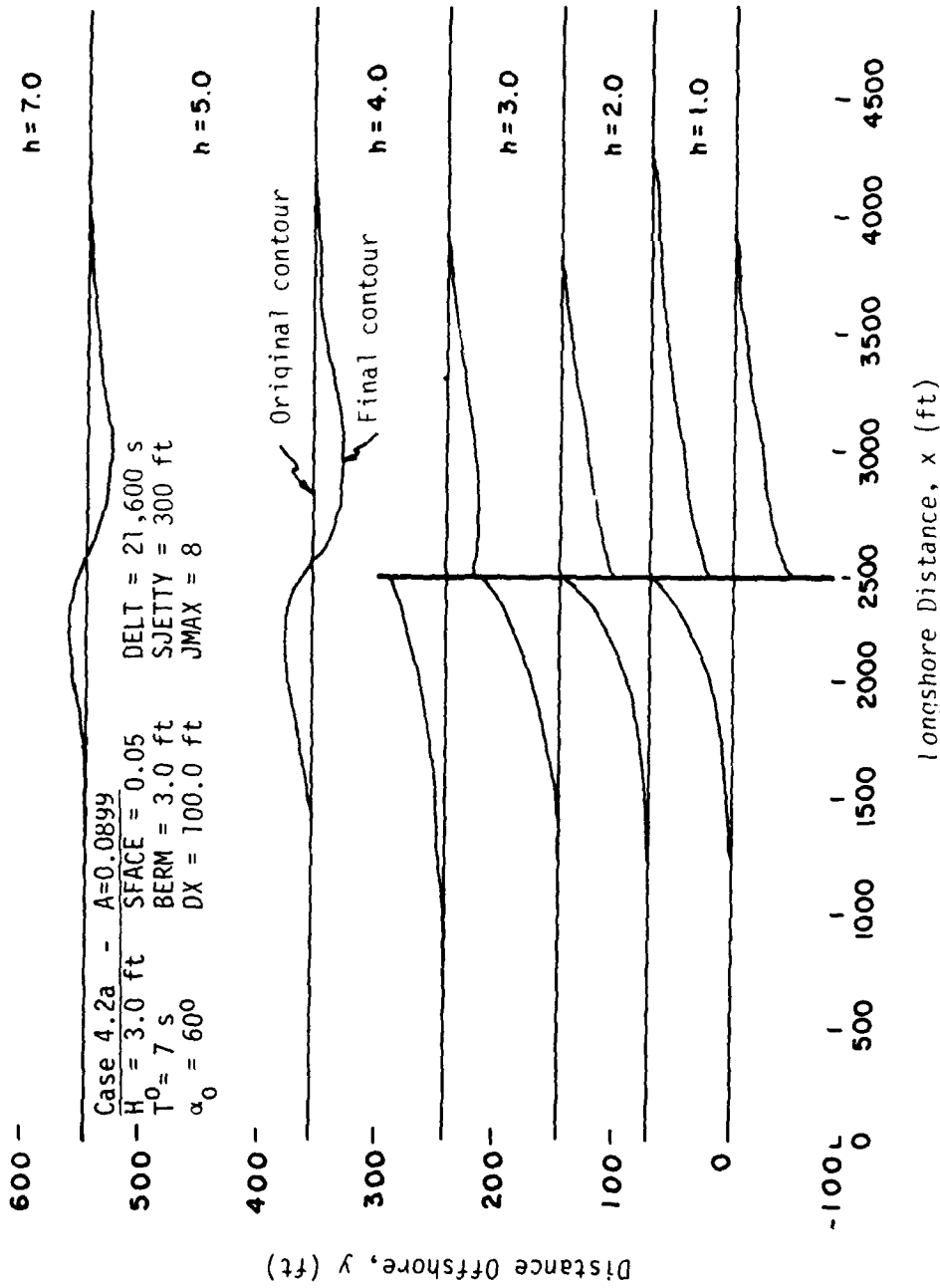


Figure 7. Equilibrium planform, case 4.2a.

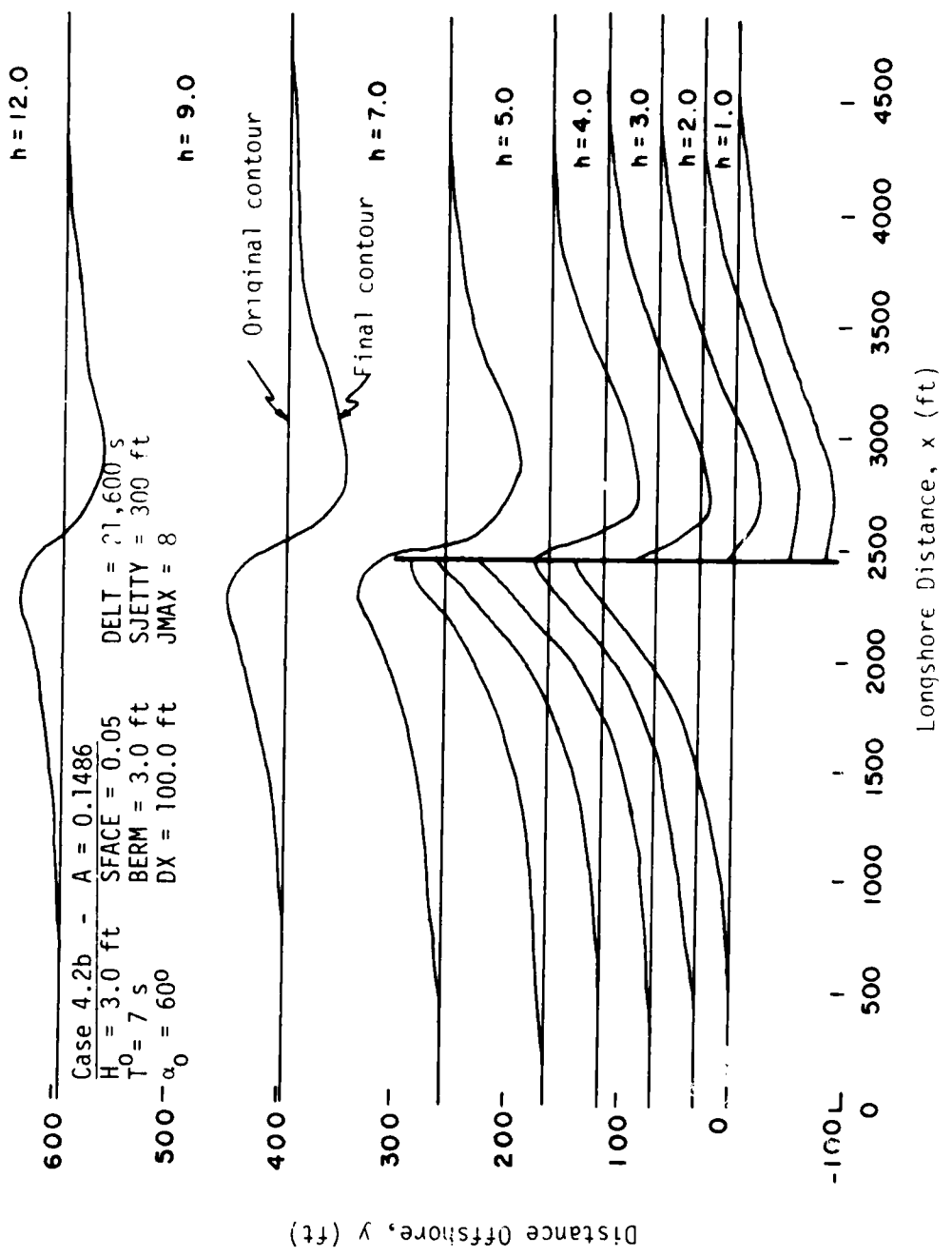
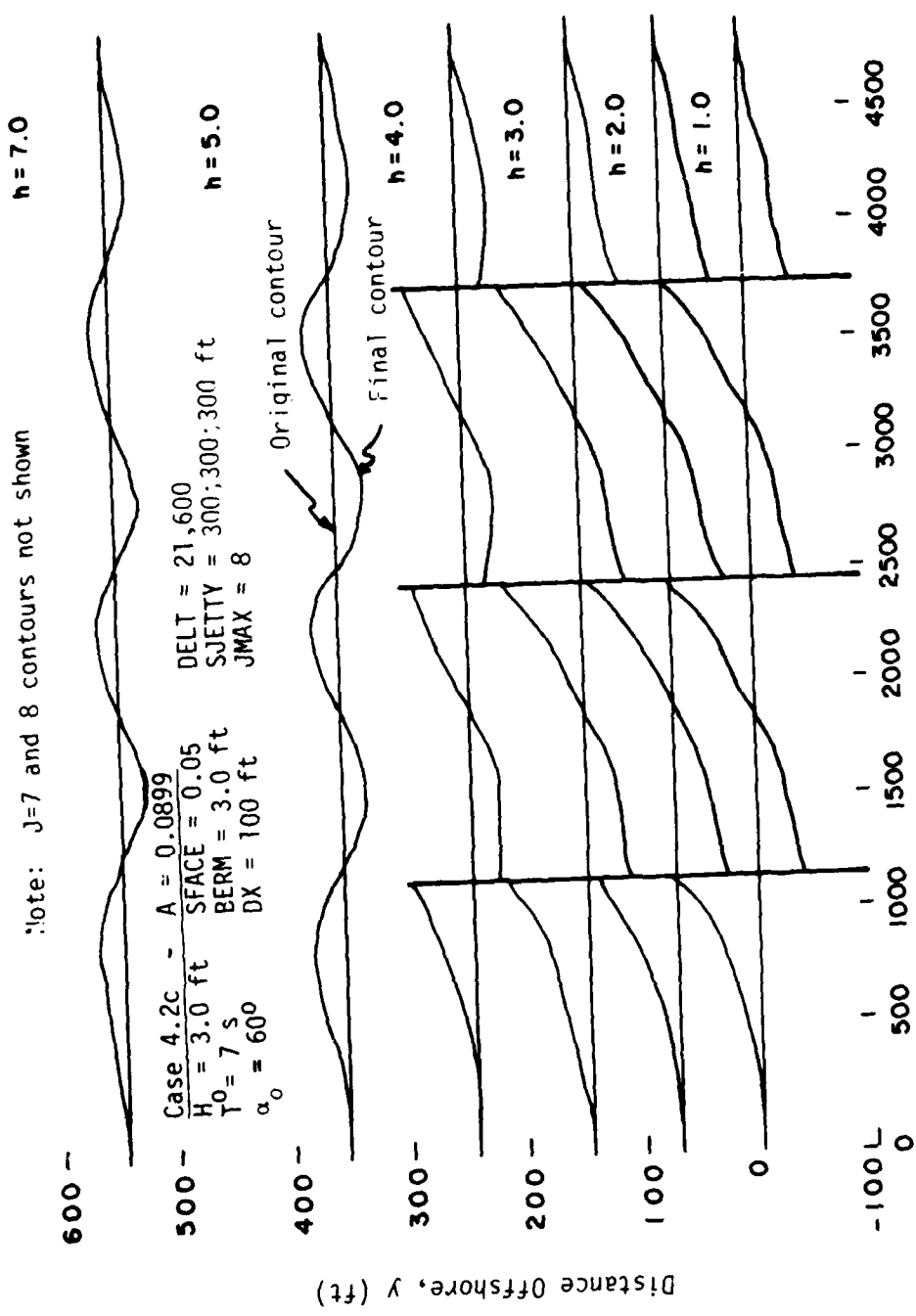


Figure 8. Equilibrium planform, case 4.2b.



Longshore Distance, x (ft)

Figure 9. Equilibrium planform, case 4.2c.

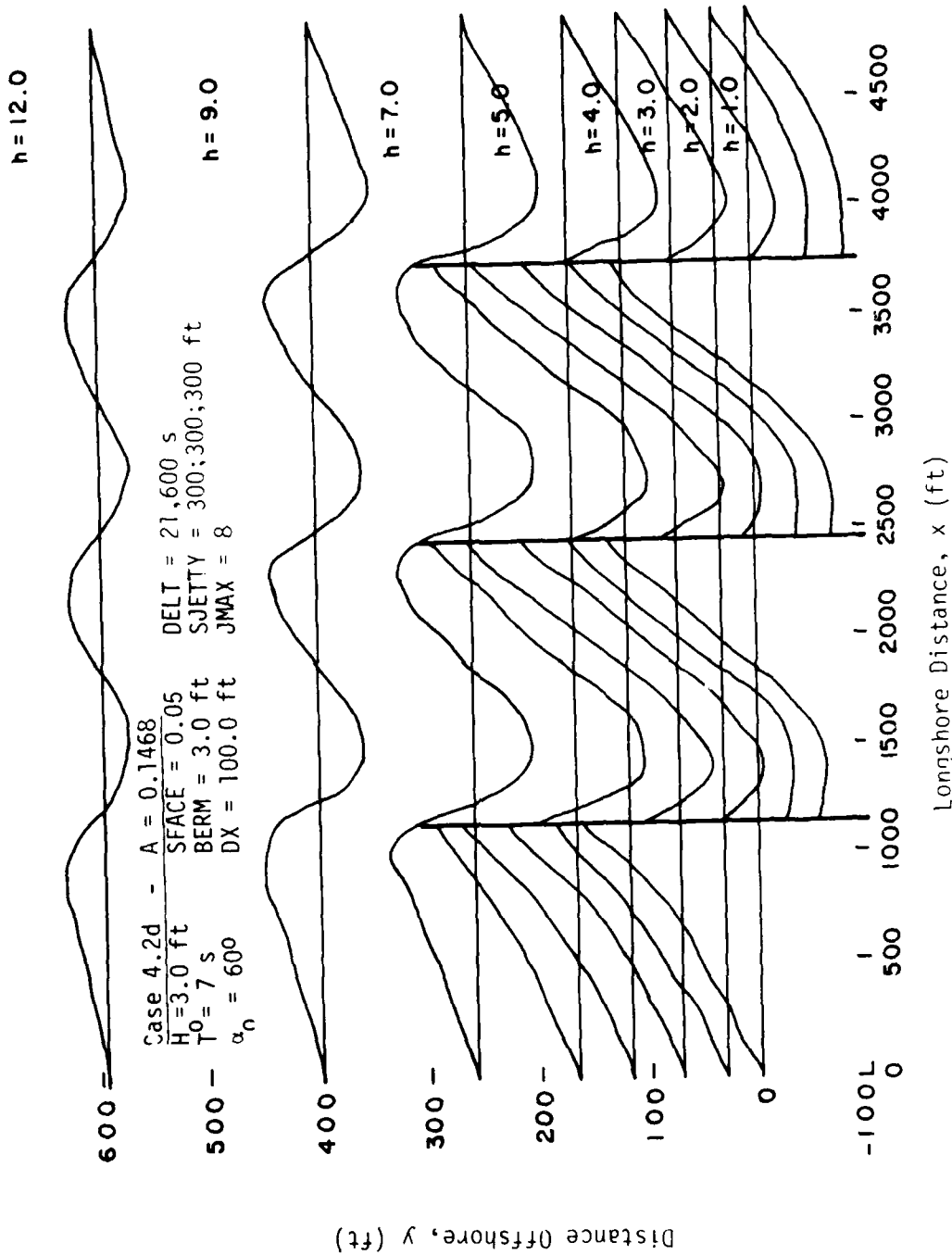


Figure 10. Equilibrium planform, case 4.2d.

In all these simulations, the following variables were held constant: (a) a time-step of 3 hours, (b) a shoreline length of 10,000 feet, (c) a longshore space-step of 200 feet, (d) an A value of  $0.15 \text{ foot}^{1/3}$  for the equilibrium profile (see Fig. 11), (e) a berm height of 5.3 feet with a beach face slope of 0.05, and (f) a duration of 1 year. The wave climate was provided by the U.S. Army Engineer Waterways Experiment Station Wave Information Study (WIS) 1975 data and was initiated at different times of the year as indicated in the specific cases below. All simulations, prior to any addition of sediment, used the bathymetry shown in Figure 12. The shoreline (relative to mean low water, MLW) was scaled from a bathymetry-topography survey provided by the U. S. Army Engineer District, Wilmington. The initial offshore bathymetry was computed according to the equilibrium profile and the 0-foot contour; i.e., the profile was shifted seaward or landward, accordingly, (see App. C.) The boundary profiles were fixed throughout the simulations. The variation of COFF outside the surf zone was used because of the importance of the time rate of change in this simulation. Table 1 presents the percentage of sediment which moves out of the control volume (i.e., imaginary boundaries around the area where sediment was added) directly onshore and the percentage of sediment remaining in the control volume at the conclusion of the simulation for each of the cases. In addition, a seventh (case 3) and eighth (case 4) were modeled. In Case 3, the only difference was that sediment was placed at the 11- and 14-foot contours. Case 4, however, was quite different and will be described in detail later. It has a 20,000-foot shoreline, a longshore space-step of 400 feet, and sediment was added on a weekly basis. Also, the resolution in the profile was better.

#### a. Specific Cases.

(1) Case 2.a. In order to provide insight for the interpretation of the other modeling efforts, a simulation of the shoreline evolution using the January to December WIS time series, with no addition of sediment, was carried out. As expected, the contours almost attain an equilibrium planform shape (i.e., straight and parallel between the fixed end profiles; they do not, however, become aligned parallel to the base line because of the end conditions). Because of the scales involved, alongshore versus onshore-offshore, plotting the contours without distortion does not yield much information. Appendix C provides a listing of the final contours for all the cases modeled.

(2) Case 2.b. The only difference between cases 2.a and 2.b is the suppression of the WIS wave angle which was set equal to zero (i.e., wave crest approach is shore-parallel at the offshore boundary of the model). This does not cause the longshore sediment transport to vanish completely. There are still local gradients in the contours which cause refraction and relative angles between wave crest and contour, thereby driving the longshore sediment transport (even if refraction was not considered, the local angle between the wave crest and contour would cause sediment transport). Note the larger onshore transport (Table 1) for this case compared with Case 2.a. This is due to the reduction in longshore transport caused by the wave angle of  $0^\circ$ . The model still tries to smooth the contour lines; however, more of the smoothing for the present case must be done by onshore-offshore transport.

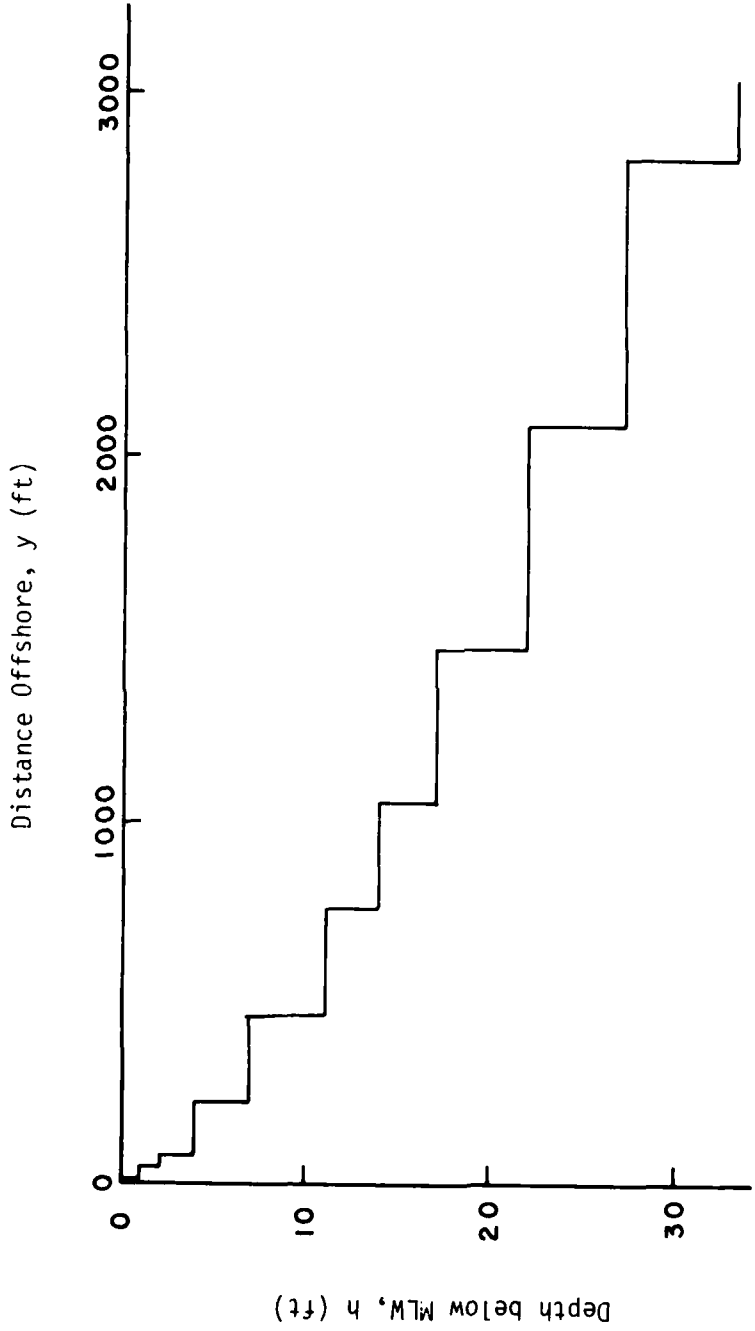


Figure 11. Stepped version of equilibrium profile used in the Oregon Inlet modeling,  $h = Ay^2/3$  ( $A = 0.15 \text{ feet}^3$ ).

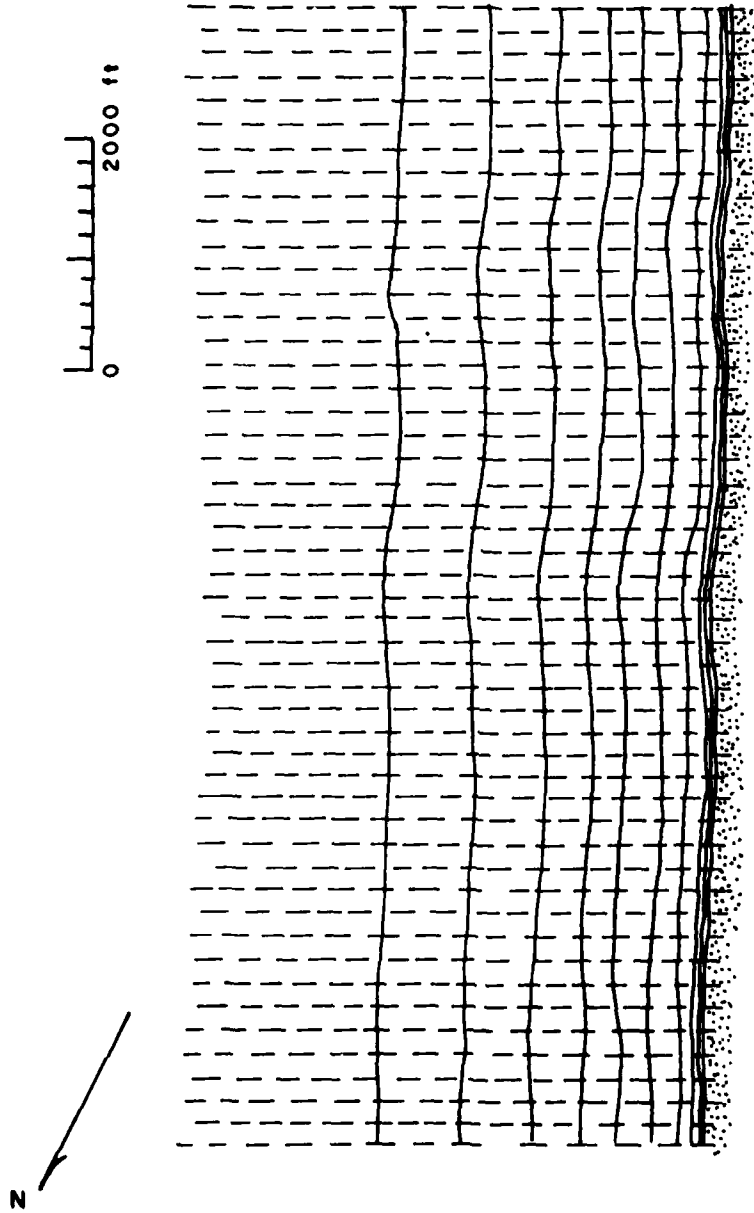


Figure 12. Initial contours used in the numerical model for all the Oregon Inlet simulations. (The scale for case 4 was twice the scale shown.)



Table 1. Summary of results at Oregon Inlet.

Case No.	Description	Pct Onshore out of control volume	Pct Remaining in control volume
2.a	No sediment added, WIS waves Jan. - Dec.	Onshore Movement (992 yd <sup>3</sup> )	Increase (14,148 yd <sup>3</sup> )
2.b	No sediment added, WIS waves ( $\alpha = 0^\circ$ ) Jan. - Dec.	Onshore Movement (1624 yd <sup>3</sup> )	Increase (9,356 yd <sup>3</sup> )
2.c1	121,000 yd <sup>3</sup> added monthly, WIS waves Jan - Dec.	31.7 (460,264 yd <sup>3</sup> )	38.6 (559,984 yd <sup>3</sup> )
2.c2	121,000 yd <sup>3</sup> added monthly, WIS waves Apr. - Mar.	32.1 (466,160 yd <sup>3</sup> )	36.9 (535,392 yd <sup>3</sup> )
2.c3	121,000 yd <sup>3</sup> added monthly, WIS waves July - June.	28.6 (415,784 yd <sup>3</sup> )	47.0 (682,088 yd <sup>3</sup> )
2.c4	121,000 yd <sup>3</sup> added monthly, WIS waves Oct. - Sept.	27.2 (395,556 yd <sup>3</sup> )	46.8 (670,848 yd <sup>3</sup> )
3	121,000 yd <sup>3</sup> added monthly at the 11- and 14-foot contours WIS waves, Jan. - Dec.	8.9 * (32,164 yd <sup>3</sup> )	78.0 (283,016 yd <sup>3</sup> )
4	27,923 yd <sup>3</sup> added weekly on the 7-8-, 9-, and 10-foot contours, WIS waves Jan. - Dec.	19.0 (275,796 yd <sup>3</sup> )	47.4 (687,525 yd <sup>3</sup> )

\* After 17 weeks, the addition of sand caused contours to cross. Prior sediment added was 363,000 yd<sup>3</sup>. Problem was rectified; however, case was not rerun.

(3) Case 2.c1. In this simulation, sediment is added to the system each month. It was simulated by advancing the 7- and 11-foot contours on a monthly basis to represent 121,000 cubic yards per month. Specifically, the sand volumes were "tapered" starting at the center of the nourished area over a distance of + 2,700 feet from the center. Table 2 presents the monthly  $\Delta y$  values for the blocks between the 7- to 11-foot contours and the 11- to-14 foot contours. Figure 13 shows the planform  $\Delta y$  values added monthly. WIS waves were used with the sequence being the normal calendar year, January through December.

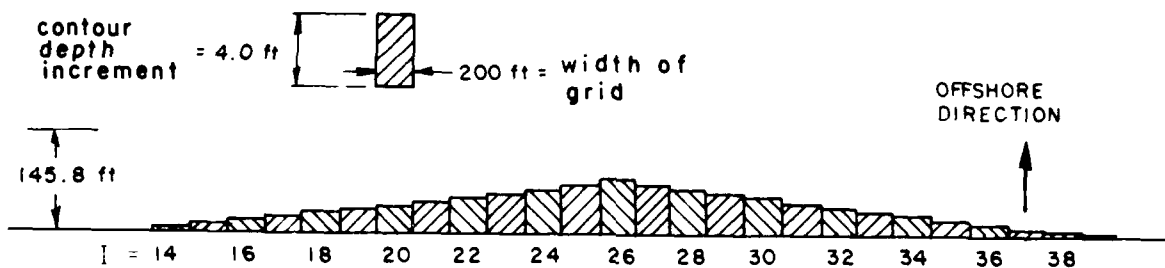


Figure 13. Monthly incremental values of  $\Delta y$  due to dredge disposal illustrated for the block between 7- and 11-foot contours.

The initial and final fifth and sixth contours have been plotted in Figures 14 and 15. The first figure has no distortion; the second is distorted 10 to 1. The simulation predicts that 31.7 percent of the dredge disposal will move shoreward out of the control volume. An additional 29.7 percent efflux occurs in the offshore and longshore directions, leaving only 38.6 percent of the total amount of sediment added remaining in the control volume. It is not clear what quantity of the sediment leaving in the longshore direction would reach shore. It is conceivable that most of this sediment would eventually reach the surf zone. The rate at which this material would move ashore would be expected to be slower than the rate at which the large mounds would move ashore because the deviation of the profile from equilibrium is much less.

(4) Cases 2.c2, 2.c3, and 2.c4. The next three simulations were the same as 2.c1 except the time series of wave events has been seasonally altered. Cases 2.c2, 2.c3 and 2.c4 use the 1975 wave climate from April through March, July through June, and October through September, respectively. The maximum variation is about 5 percent for the sediment volume moving onshore, and about 10 percent for the volume remaining. The variation in the

Table 2. Monthly values of  $\Delta y$  for the steps located between the 7- to 10-foot contours and the 11- to 14-foot contours.

Value of I	Monthly $\Delta y$ value (ft) for steps between	
	7- and 11-foot contours	11- and 14-foot contours
26	145.8	194.4
25,27	135.4	180.5
24,28	125.0	166.6
23,29	114.6	152.7
22,30	104.1	138.9
21,31	93.7	125.0
20,32	83.3	111.1
19,33	72.9	97.2
18,34	62.5	83.3
17,35	52.1	69.4
16,36	41.7	55.5
15,37	31.2	41.7
14,38	20.8	27.8
13,39	10.4	13.9
All Others	0	0

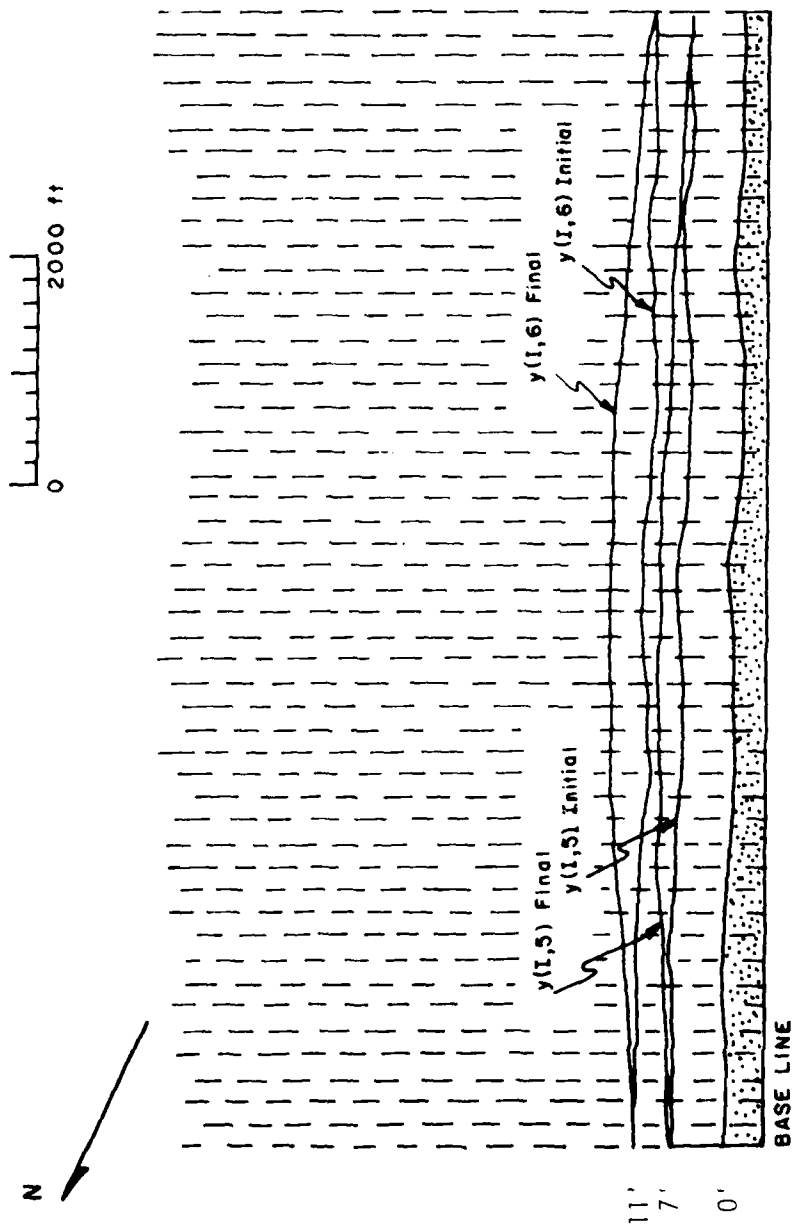


Figure 14. Initial and final 7- and 11-foot contours (no distortion).

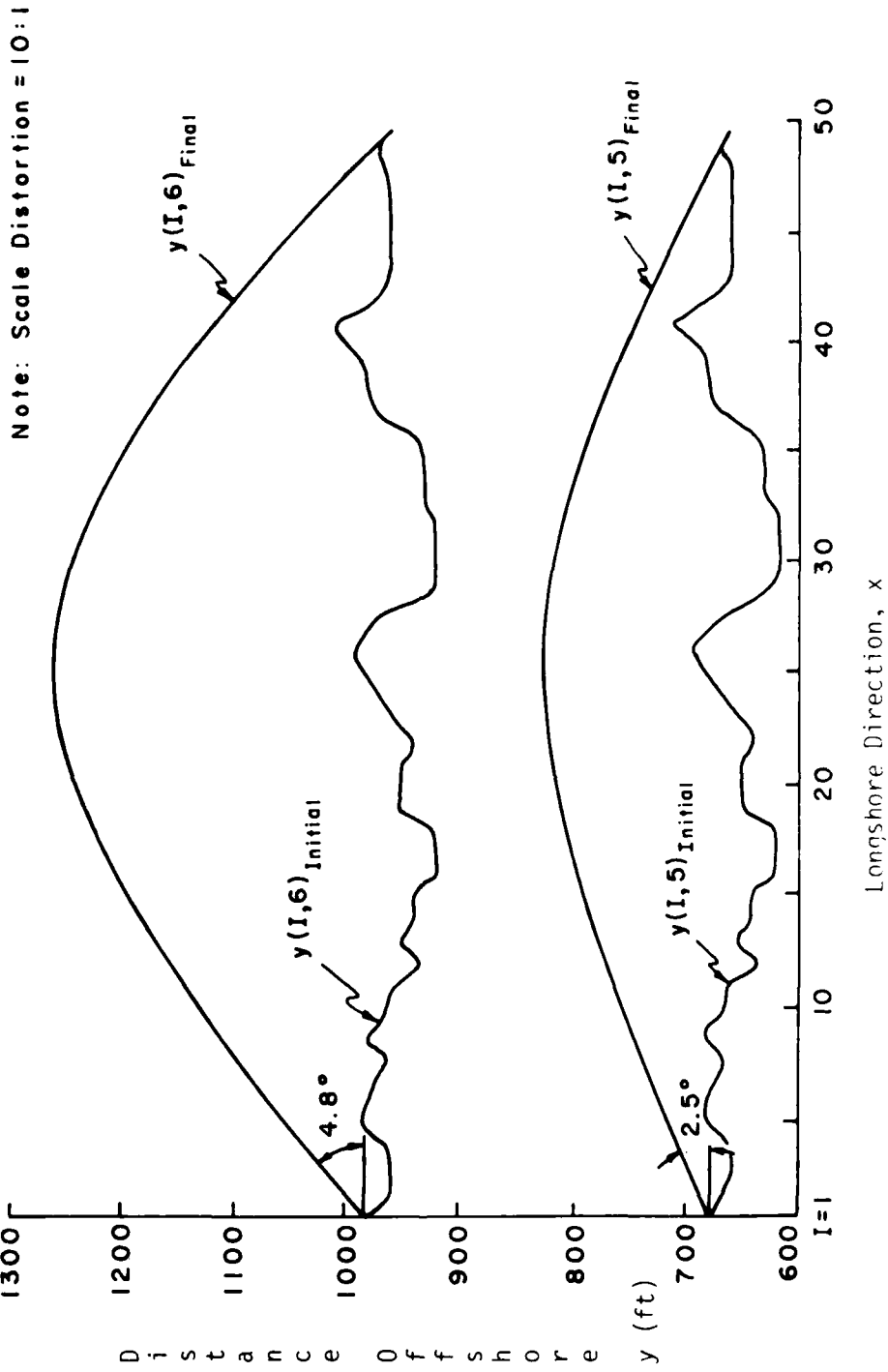


Figure 15. Initial and final contours for case 2.c1 [ $y(I,5)$  and  $y(I,6)$ ].

quantity moving onshore could be caused by waves that first tend to move more sediment longshore; then, the waves that transport more sediment onshore have a less out-of-equilibrium profile to cause movement upon. The variation in percentage remaining is due to the variation of the time series of the wave climate, with the last month in the simulation being especially important.

(5) Case 3. Instead of extending the 7- and 11-foot contours monthly to simulate the disposal of dredged sediments, the 11- and 14-foot contours were extended (194.4 feet each at the center of the disposal area). This case was modeled because the larger available dredge could not dump in more shallow water. The reduction and increase in the percent of onshore volume and the percent volume remaining (8.9 percent and 78.0 percent, respectively) demonstrate the sensitivity of the depths investigated. Qualitatively, these depths are the depths to which offshore bars occur along the Atlantic U.S. coast.

(6) Case 4. Further investigation of the disposal process demonstrated the need for an 11,000-foot shore-parallel disposal length with the sediment placed at the 11-foot contour building to about 7 feet. It was decided to model this physical situation also. The total shoreline length was changed to 20,000 feet, and the space step to 400 feet; the length of the disposal area in the longshore direction was increased to 10,800 feet. The resolution in the vicinity of the depths of the dump was improved by adding the additional contours and the profile is shown in Figure 16. As in the other seven cases, 1,452,000 cubic yards was added annually to the system; however, the addition was accomplished on a weekly basis (27,923 cubic yards per week). Sediment was still added by extending the contours seaward, but rather than placing one-fourth of the sediment at each of the four contours, the volumes were determined based on the trapezoidal cross section shown in Figure 17. This cross section more closely resembles the disposal mound formed by hopper dredging. The incremental values Figure 18 show, in planform, the extension of the contours to simulate the weekly sediment addition at the 8-foot contour.

A schematic illustration of the sediment transported from the nourished region is presented in Appendix C. Nineteen percent of the sediment added moved directly onshore out of the control volume.

b. Conclusions for the Movement of Disposed Sediment in the Vicinity of Oregon Inlet. The computer simulations, tempered with engineering judgment, demonstrate that between 15 and 35 percent of the material added to the 7- and 11-foot contours, or to the 7- 8- 9-, and 10-foot contours would be transported into the nearshore transport system during the first year. If the disposal process was continued, the system would approach steady state in terms of the volume of deposited material residing offshore.

For the case of sediment addition at the 11- and 14-foot contours, the computer simulations, tempered with engineering judgment, show that between 5 and 25 percent of the material added would be transported into the nearshore transport system during the first year.

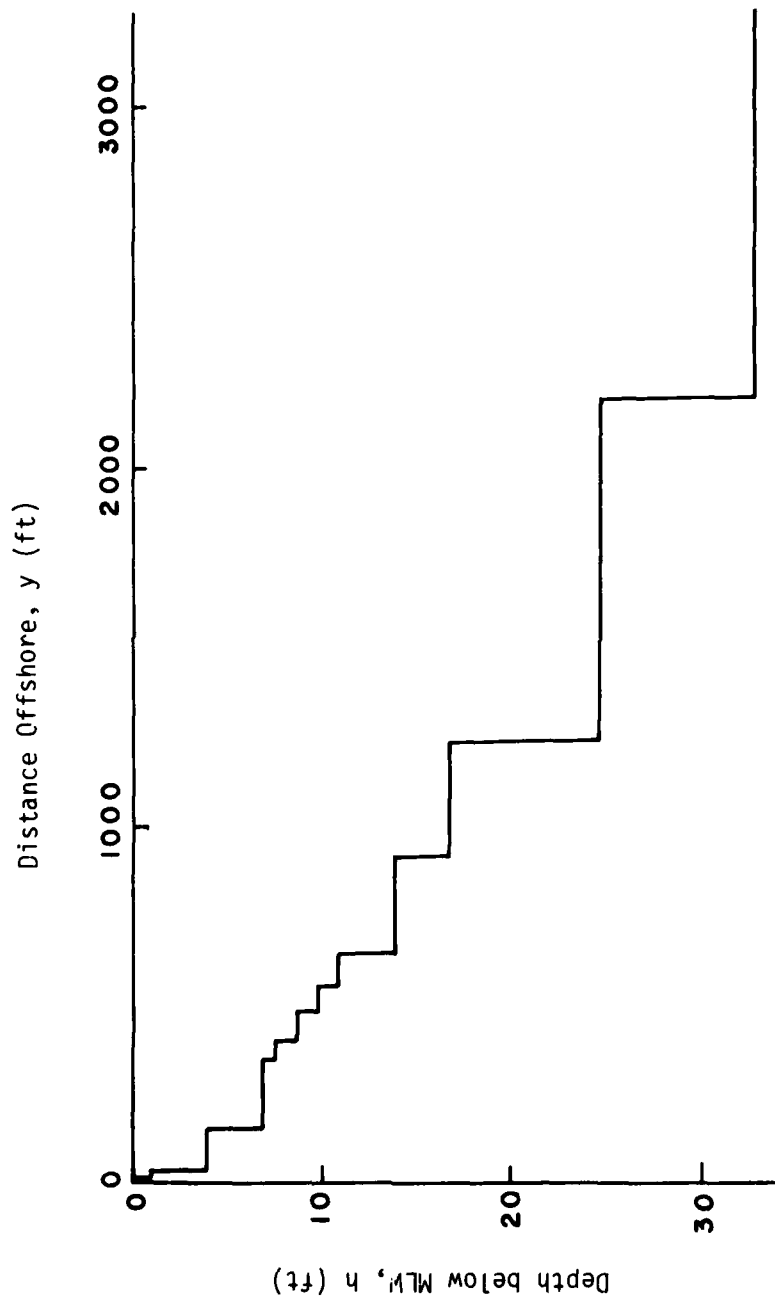


Figure 16. Stepped version of equilibrium profile used in the Oregon Inlet modeling,  $h=Ay^{2/3}$  ( $A=0.15 \text{ feet}^{1/3}$ ), case 4. Note the resolution at 7, 8, 9, and 10 feet.

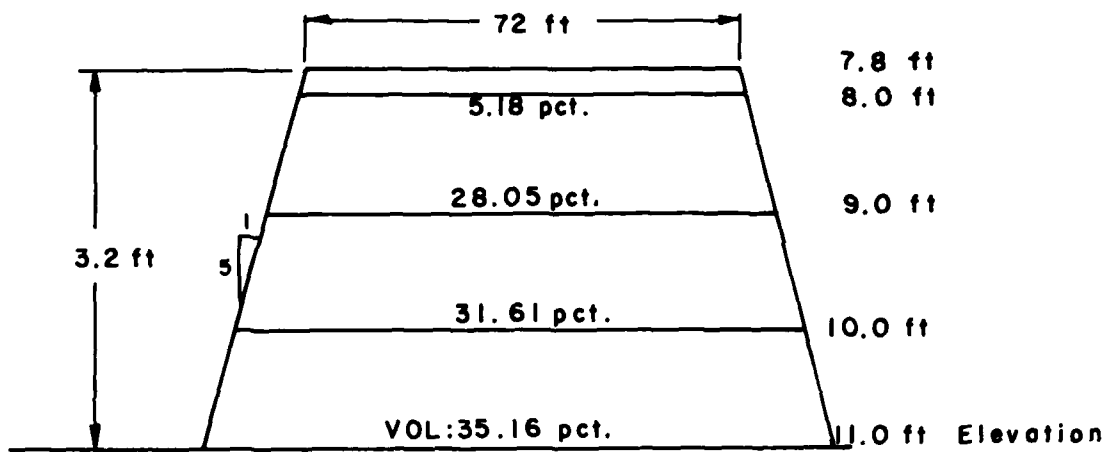


Figure 17. Shore-perpendicular cross section of disposal mound. The volumes represent the volume percentage of the trapezoidal section between contours and therefore, the quantity of sediment added to the 7-, 8-, 9-, and 10- foot contours.

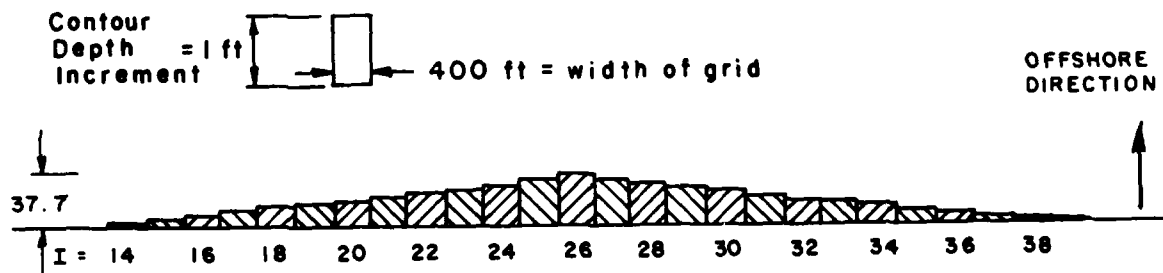


Figure 18. Incremental values of  $\Delta y$  due to dredge disposal, illustrated for the block between 8- and 9-foot contours (case 4).



4. Simulation of the Longshore Sand Transport Study at Channel Islands Harbor, California.

The CIH Longshore Sand Transport Study (Bruno, et al., 1981) was the only field study found suitable for verification purposes. Wave data collected included the LEO data and a two pressure-sensor gage array. Although the pressure gages were not in operation throughout the study, it was expected that the data they produced would be superior to that of the LEO data. However, these data were not available in a reduced form, so the LEO data were used. An adjustment of  $11^\circ$  was made to the breaker angle to orient the angle with respect to the base line, rather than to the local shoreline orientation angle. Observations had been taken twice daily at three locations; the middle location was used (observer No. 5714). Waves which approached the shoreline at angles too large to have originated in a depth of 10 meters, according to Snell's law, were set equal to  $90^\circ$  at that depth (crest of wave perpendicular to the baseline). The 10-meter depth was chosen because it is the approximate depth at the tip of the offshore breakwater (for this reason, it was also chosen as the depth of the step beyond the  $y(I, J_{MAX} + 2)^{th}$  contour). It was assumed that each of the two daily observations occurred for 12 hours and using a time-step of 6 hours, this meant two time-steps per wave. In cases where parts of the wave data ( $H_b$ ,  $\alpha_b$ , or  $T$ ) were missed by the observer or were equal to zero, the data were ignored (no computations were made), but the time was included. Because the time rate of change is important for this simulation, the variation of  $C_{OFF}$  outside the break point was used.

The period chosen to model was 20 April through 1 December 1976. The initial survey was taken after dredging of the sediment trap and for this reason was known to be out of equilibrium. The bathymetric surveys were conducted using several methods, the most advanced being a Lighter Amphibious Resupply Cargo vessel (LARC) proceeding along shore-perpendicular lines (approximately in the vicinity of each survey station) taking fathometer readings every 10 seconds, with positioning systems trilaterating the vessel's position concurrently. These data were recorded on tape. The beach-face data were taken using standard surveying methods. Because the data fluctuated randomly about the stations, depending on the speed of the craft, the  $(x, y)$  coordinate positions had to be altered to fixed changes in  $x$  and  $y$ . This was accomplished using an interpolation routine. The  $x$  values were made to coincide with the stations used in the surveys, and the  $y$  values were determined at 100-foot intervals beginning from the base line. Stations 100+00 and 118+00 were located at the north jetty and termination of the detached breakwater, respectively (these correspond to  $I$  values of 16.5 and 34.5 in the model). See Figure 19.

Monotonic profiles of the form  $h = A(y - y_{del})^{2/3}$  were fit to the data along each station line. " $y_{del}$ " represents the zero location of the fitted shoreline, the value of which was unknown. Because dredging had been done in the lee of the breakwater, there was no reason to expect the  $A$  value to correspond to the value upcoast where the influence of the structure and the dredging was negligible. For this reason, the profiles of Stations 122+00 through 134+00 were evaluated separately to determine an  $A$  value for the equilibrium profile to be used in the numerical model. For the detailed method used (LaGrange Multipliers and Newton-Raphson Method for nonlinear

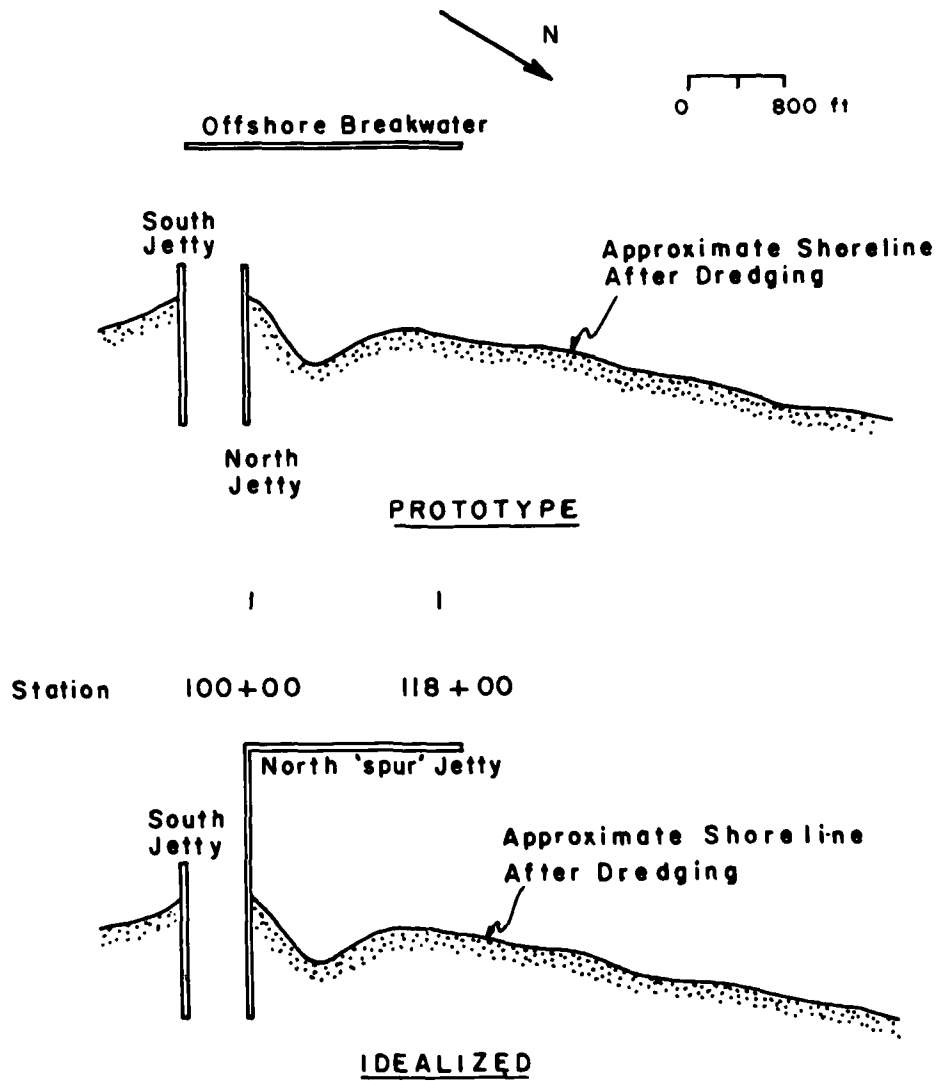


Figure 19. Idealized numerical model representation of offshore breakwater at Channel Islands Harbor, California.

equations) and the computer programs see Appendix D. The two values obtained for the surveys of 20 April and 1 December 1976 were averaged to obtain the value used in the model,  $A = 0.2606$ . Stations 101+00 through 121+00 were treated separately for the purpose of obtaining values with which to initialize those parts of the contours in the model and for comparison of the model predictions with the prototype values. Note that although the breakwater extends only to about Station 118+00, the influence of the structure and dredging extends beyond that location and so, although arbitrary, the 121+00 station was chosen as the dividing line. The initial and final values of the scaling parameter  $A$  for the profiles were 0.3233 and 0.3528, respectively. Because the initial shoreline is so irregular, a discontinuity between 121+00 and 122+00 is not evident.

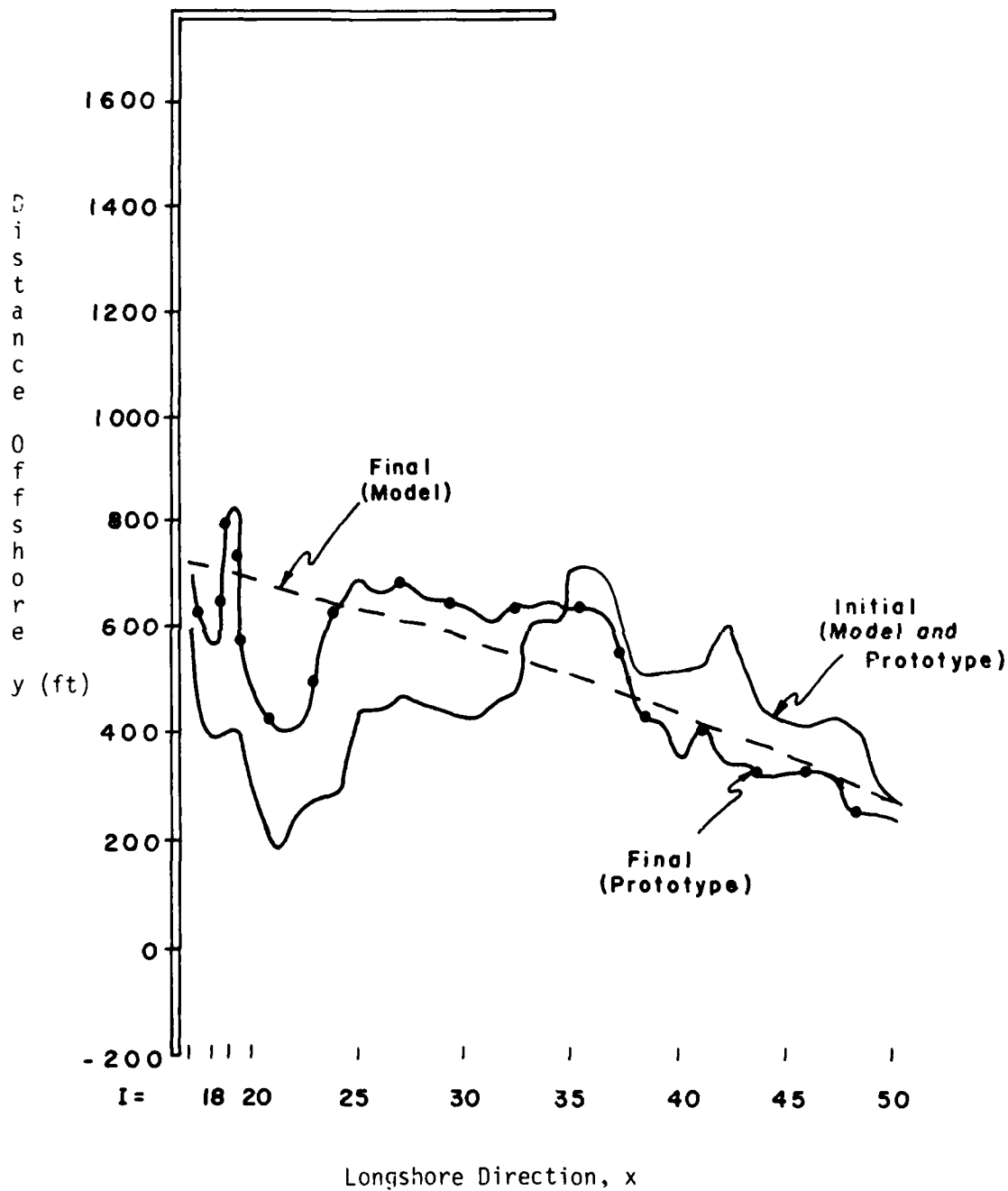
One further idealization was made. The jetty-breakwater system was idealized as shown in Figure 19. This was required to simplify the physical situation, and although waves, currents, and sediment do pass through the opening in the prototype, it is hoped that they are of secondary importance.

The results of the numerical modeling of Channel Islands Harbor are presented in Figures 20 and 21. The first figure presents the shoreline contour (depth = 0); the second figure presents the farthest offshore, modeled contour. In both cases, the initial shoreline represents the model and prototype (after fitting of the profiles). The initial shoreline contour is further offshore along the section of beach beyond the end of the breakwater, while in the lee of the breakwater, as would be expected after dredging, the shoreline is closer to the base line. The final prototype contour has undergone erosion along the reach beyond the tip of the structure, and accretion in the lee.

The model's shoreline contour has undergone similar changes, and on the average, represents the final prototype contour quite well. The  $JMAX^{th}$  contour has been displaced quite similarly to the shoreline contour with shoreward movement (erosion) along the reach beyond the tip of the breakwater and seaward movement (accretion) within. It appears that the final model's shoreline has predicted too much erosion and not enough accretion. Several parameters could be incorrect, with the onshore-offshore sediment transport rate coefficient,  $C_{OFF}$ , perhaps the most likely. Overall, the model seemed to predict reasonable values of the contours.

## V. SUMMARY AND RECOMMENDATIONS

Some of the parameters that the model does not include are important and should be mentioned. As stated previously, the model does not include bar formation. This is precluded by an  $n$ -line system. There are no provisions for water level fluctuations or currents. Improvement to the model could also be facilitated with better longshore and cross-shore sediment transport relationships. A more reliable equation for distribution of sediment transport across the surf zone would also be helpful (or further testing and calibration of the equation proposed herein). Finally, combining refraction and diffraction using equations to predict their combined effect would improve the wave field. The program was constructed such that improvement



Longshore Direction, x  
 Figure 20. CIH simulation of shoreline contour, 20 April -  
 1 December 1976 (from LEO data).

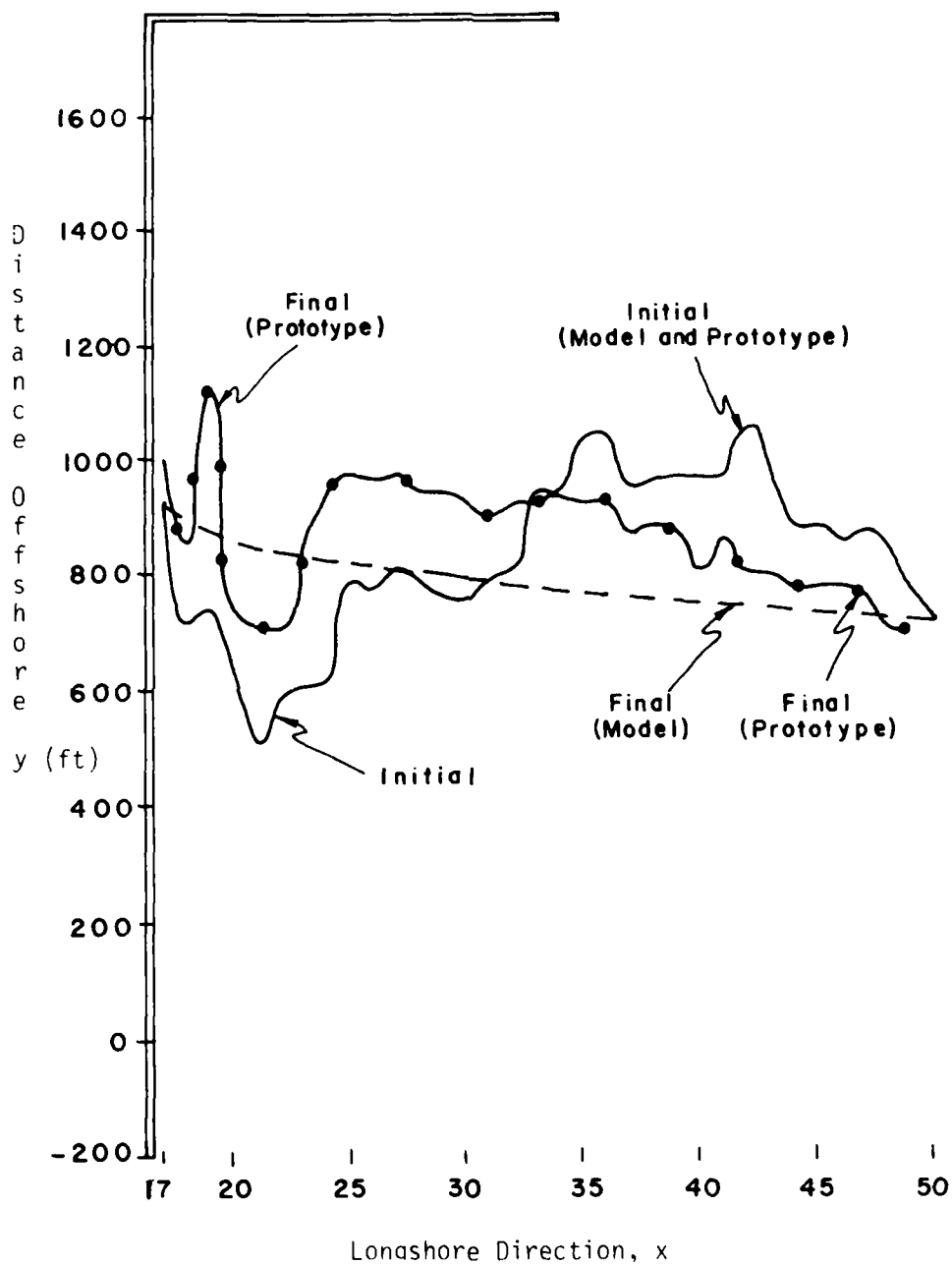


Figure 21. CIH simulation of (JMAX)<sup>th</sup> contour, 20 April - 1 December 1976 (from LEO data).

could be accomplished with minimum effort. Therefore, if a more suitable equation becomes available, the change of a subroutine should be sufficient for implementation of the equation.

Although the model is limited by the omission of the aforementioned parameters, it is reasonably correct. The ability to simulate various physical situations (shore-perpendicular structures, beach fills, breakwater and shore-perpendicular structures) has been demonstrated. In the CIH simulation where the data were first transformed to monotonically decreasing contours and LEO wave data were used, the model still predicts the prototype shoreline changes in a reasonable fashion.

Further research and model development should include exercising the model in a number of different situations. Several theoretical cases should be simulated, which if analyzed properly, would provide a tool for the coastal engineer. Combined refraction and diffraction should be included, if possible, along with any of the aforementioned parameters which have been omitted and for which relationships exist. Perhaps the most difficult problem to researchers working on modeling sediment transport in the vicinity of structures is the availability of field data. High-quality concurrent wave and bathymetric change data in the vicinity of coastal structures do not exist. One suggested field experiment is to monitor changes both updrift and downdrift of a jettied inlet which has a bypassing plant. Monitoring should begin immediately after bypassing, when the profiles are out of equilibrium. The recorded bathymetric and wave data would then provide data with which to calibrate, verify, and evaluate the existing models.

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## APPENDIX A

### DISCUSSION OF CONSTANTS AND SOME OF THE VARIABLES REQUIRED BY THE MODEL

Establishing the grid-contour system requires several variables. IMAX represents the number of cross-shore grid lines desired and JMAX the number of contours simulated. DX represents the spacing between the IMAX grid lines and DY the spacing between the contours. DX is a value which must be chosen along with IMAX and JMAX such that sufficient detail is obtained where necessary (e.g., in the shadow zone, if diffraction effects are believed to be very important, DX must be assigned a sufficiently small value so that at least some points lie within the shadow zone for the larger wave angles). DY is not a constant, but a dimensional array which is computed by the model according to the contour location. Once the depths of contours to be modeled are chosen, the initialization of DY and the y values are computed with the following equation after Dean, 1977

$$h = A y^{2/3} \quad (A-1)$$

where h is the depth, y is the offshore distance and A is the scaling parameter Dean gives values for A for several diameter sediments; however, if long-term beach profiles are available for the site being modeled, the modeler may want to choose a slightly different A value to more closely match the site-specific beach profile. Figure A-1 presents values of A versus diameter (after Moore, 1982). The model is programmed to input the h(I,J) values (depths as shown in Figure 1, called DEEP (I,J) in the program) read in the value of A (called ADEAN in program) and it then computes the y values. Also shown in Figure 1 is the height of the berm (BERM) and this value, along with the beach-face slope (SFACE), is required as program input and can be obtained from beach profile site data. Because the model does not include water level fluctuations such as tides, all values are to be referenced to a chosen datum. Other geometrical constants depending on the site include SJETTY (the length of the jetty), MMAX (the number of structures to be input), and IJET (M), M = 1,2,...MMAX (the smaller I value adjacent to the M<sup>th</sup> structure's location). If no structure is required, as in a beach fill, the value of SJETTY must be entered as 0.0, with MMAX and IJET (M) entered as 1 and (IMAX/2), respectively. As set up presently, the groin locations must be equally spaced.

One constant used throughout the program is the breaking wave criteria (CAPPA in the program) equal to 0.78. It is required in several different computations and always governs the maximum wave height allowed according to the depth.

Another group of variables assigned values within the program is the sediment and fluid properties. These include fluid mass density, sediment mass density, porosity, and the angle of repose (e.g., RHO = 1.99, RHOS = 5.14, POROS = 0.40, and REPOSE = 32°, respectively). The values can easily be changed to reflect site conditions.

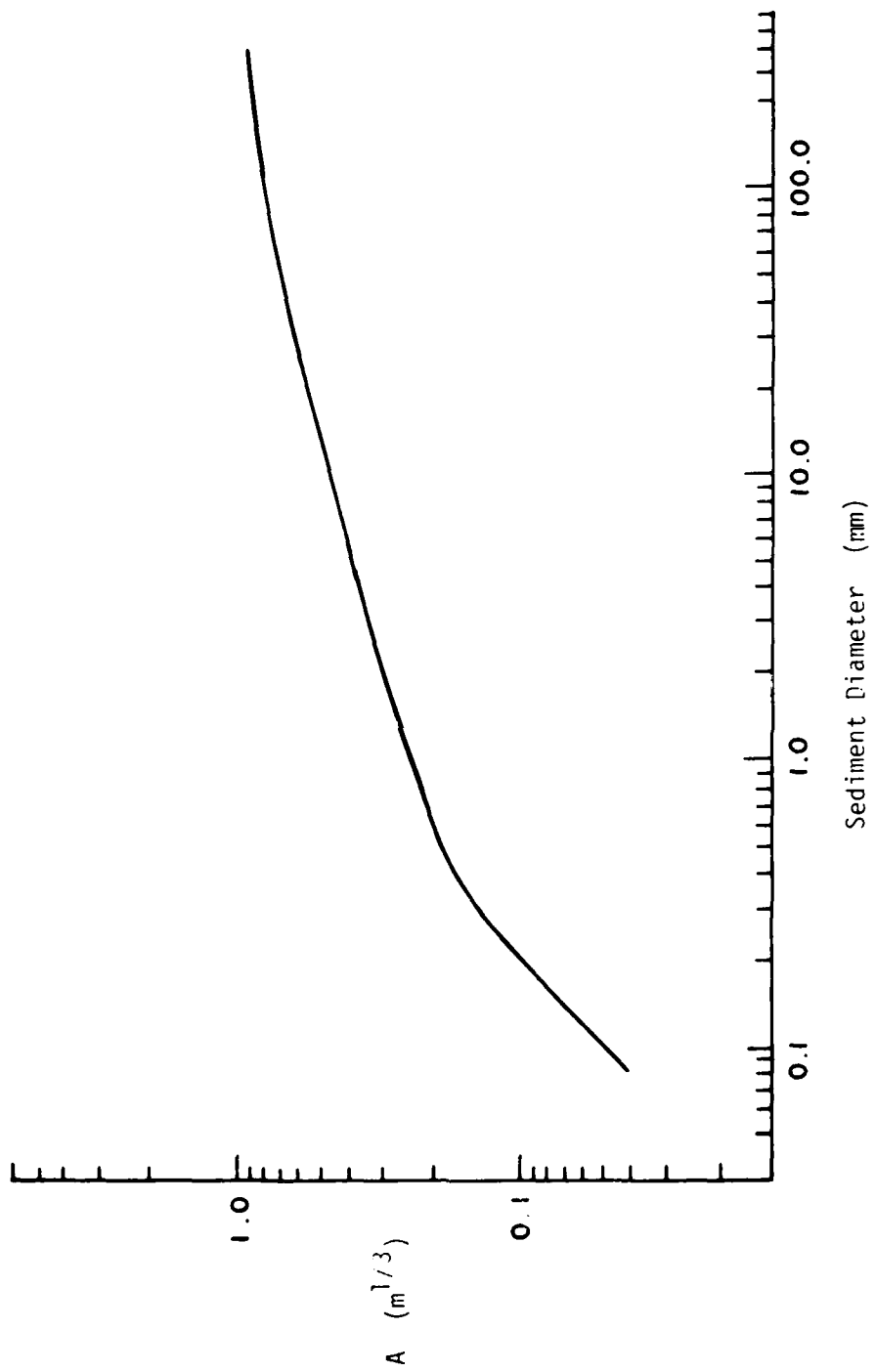


Figure A-1. A versus sediment diameter (after Moore, 1982).

Another very important set of constants is the constant chosen for the longshore and cross-shore components of sediment transport. Equation (27), the total longshore transport equation, contains the constant C' equal to

$$C' = \frac{K \rho (g)^{1/2}}{(\rho_s - \rho) (1 - p) (16) (\kappa)^{1/2}} \quad (A-2)$$

where

$K = 0.77$  (Komar and Inman, 1970)

$g$  is the acceleration of gravity (32.17 ft/sec<sup>2</sup>)

$\rho_s$  and  $\rho$  are the mass densities of the sediment and the seawater (5.14 and 1.99 slugs per cubic feet, respectively)

$p$  is the porosity (0.40), and

$\kappa$  is taken as 0.78.

Using these values to compute C' (TKSI in the program), a value of 0.325 is obtained. It is stressed that if any of these values are different for the site to be modeled, they should be changed and the program will compute another value for C'.

The parameter  $C_{OFF}$  is an "activity factor" which, based on earlier work primarily within the surf zone, was found to be

$$C_{OFF} = 10^{-5} \text{ ft/s, } h < h_b$$

To generalize this concept for transport seaward of the surf zone, the wave energy dissipation per unit volume was utilized as a measure of mobilization of the bottom sediment. Inside the surf zone, the dominant wave energy dissipation is caused by wave breaking; outside the surf zone, the dominant mode of wave energy dissipation is due to bottom friction. These two components will be denoted by  $D_1$  and  $D_2$ , respectively.

(a) Energy Dissipation by Wave Breaking. The wave energy dissipation per unit volume by wave breaking,  $D_1$ , is

$$D_1 = \frac{1}{h} \frac{\partial}{\partial y} (E C_G) \quad (A-3)$$

which, employing the spilling breaker assumption ( $H = \kappa h$ ) within the surf zone, can be shown to be

$$D_1 = \frac{5}{16} \rho g^{3/2} \kappa^2 h^{1/2} \frac{\partial h}{\partial y} \quad (\text{A-4})$$

or

$$D_1 = \frac{5}{24} \rho g^{3/2} \kappa^2 A^{3/2} \quad (\text{A-5})$$

in which A is the scale parameter in the equilibrium beach profile

$$h(y) = Ay^{2/3} \quad (\text{A-6})$$

(b) Energy Dissipation by Bottom Friction. The wave energy dissipation per unit volume due to bottom friction,  $D_2$ , is

$$D_2 = \frac{1}{h} \tau u_b = \frac{1}{h} \rho C_f \overline{|u_b| u_b^2} \quad (\text{A-7})$$

in which  $C_f$  is a bottom friction coefficient,  $u_b$  is the bottom water particle velocity and the overbar indicates a time average. For linear waves, equation (A-7) can be reduced to

$$D_2 = \frac{1}{6\pi} \frac{\rho}{h} C_f \frac{H_c^3}{\sinh^3 kh} \quad (\text{A-8})$$

The activity coefficient  $C_{OFF}$ , outside the surf zone, is expressed as

$$C_{OFF} = \frac{1}{\Gamma} \frac{D_2}{D_1} \times 10^{-5} \text{ ft/s}, \quad h > h_b \quad (\text{A-9})$$

$$C_{OFF} = \frac{4}{5\Gamma} \frac{C_f^3}{g^{3/2} \kappa^2 A^{3/2} h} \left( \frac{H}{\sinh kh} \right)^3 \times 10^{-5} \quad (\text{A-10})$$

in which  $\Gamma$  is a parameter relating the efficiency with which breaking wave energy (which occurs primarily near the water surface) mobilizes the sediment bottom ( $0 < \Gamma \leq 1$ ). Herein,  $\Gamma$  is taken to be one.

Figure A-2 presents an example of the variation of the activity coefficient versus relative depth for a particular wave period and deep water wave height. It is seen that the activity coefficient reduces rapidly with increasing depth.

The value of  $C_{OFF}$  for the physical modeling of Savage's (1959) data was taken as  $10^{-4}$  feet per second. Perlin (1978) presents some rationale for choosing a value of  $C_{OFF}$ ; however, very little testing has been done and none is based on actual field measurement.

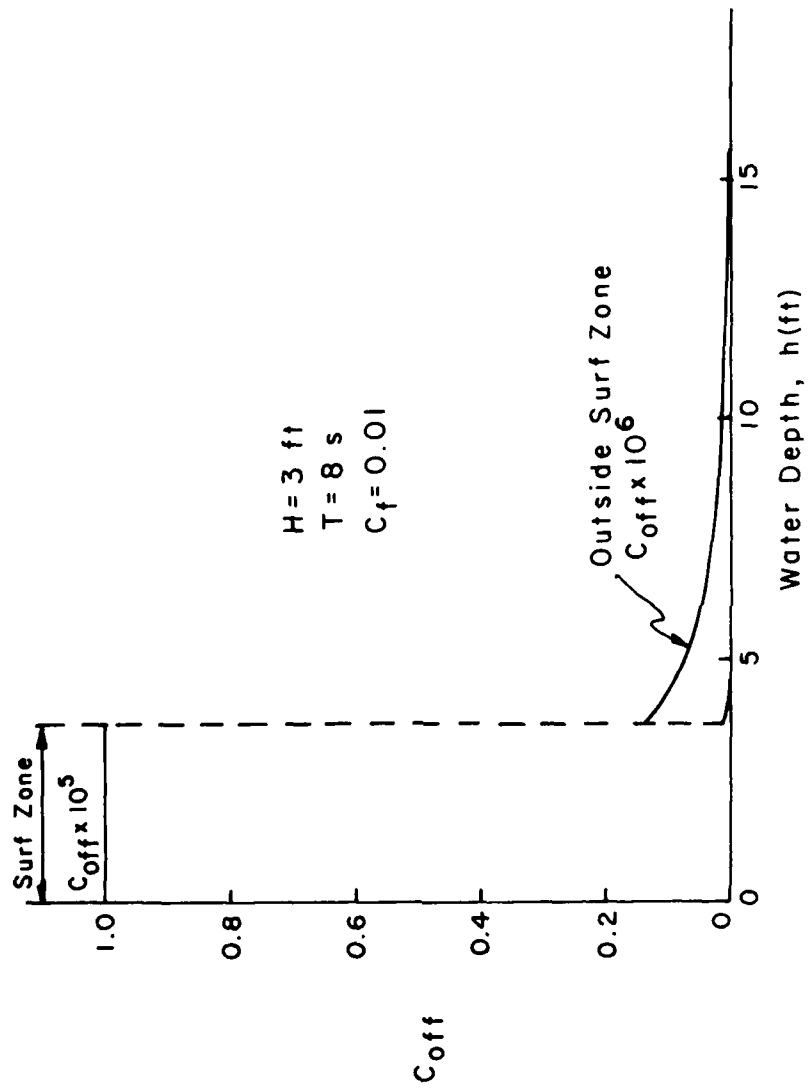


Figure A-2. Example of activity coefficient,  $C_{OFF}$  versus water depth,  $h$ , for particular wave conditions.

Finally, wave data are read into the program and the simulation begins. (For information regarding "Read Formats" for the various constants and variables, see Appendix E). Wave data required are wave height, wave period, wave angle relative to the x-axis of the model at a depth, WDEPTH and the duration of the wave climate (HS, T, ALPWIS, and a combination of NTIMES x DELT, respectively, in the model). As is always the case with numerical models, the time step and space steps are very important to both stability and accuracy. Time steps on the order of 3 to 6 hours (10,800 to 21,600 seconds) or less are recommended. However, the complexity of the bathymetry, variation and time series of the wave data, constants used (especially COFF) along with several other factors, greatly influences the stability and accuracy of the results.

Table A-1 lists several of the important variables in the computer program.

Table A-1. List of important variables in the program

---

ABAND	The input banded matrix which stores the values from equation (37)
ADEAN	The value of the scaling parameter in the equilibrium beach profile
ALPHAS	The angle a contour makes with the x-direction base line (counter-clockwise is positive)
ALPWIS	The angle (-90° to +90°) the wave crest makes with the x-direction (counter-clockwise is positive)
AMP	The amplitude of the diffracted wave in the shadow zone
ANGGEN	The wave angle at a depth, WDEPTH
ANGLOC	The local contour orientation angle
AWARE	See equations (36) and (37)
BERM	The height of the berm above water level
BMATRIX	The matrix which, upon solution of the banded matrix problem yields the new y values
C	The wave celerity
CAPPA	The breaking wave index
CC	Constant which establishes the width of the distribution of sediment transport across the surf zone
CG	The group velocity throughout the wave field
CGEN	The linear wave theory celerity at a depth, WDEPTH

CGGEN The linear wave theory group velocity at a depth, WDEPTH

CO The deepwater, linear wave theory wave celerity

COFF The onshore-offshore transport rate coefficient within the surf zone

CONST The constant in the longshore sediment transport relationship (0.77)

CONST6 The space step, DX, multiplied by the activity coefficient

DEEP The water depth at any grid location

DEEPB The initial breaking depth along each profile (between adjacent profiles)

DEEPBI The initial breaking depth along each profile (at each profile, rather than between them)

DELT The time-step in seconds (DELT x NTIMES = wave condition duration)

DIAM The mean diameter of the sediment particles

DISTR See equations (36) and (37)

DX The alongshore space-step in the x-direction (distance between I values)

DY The onshore-offshore space-step in the y-direction as defined by the stepped profile

ELO The deepwater, linear wave theory wavelength

ELTIP The wavelength at the tip of the structure

EPS The change in the wave number which is acceptably small

G The acceleration of gravity (32.17 feet/second<sup>2</sup>)

GAMMA The specific weight of seawater

H The wave height throughout the wave field

HB The maximum wave height which could exist throughout the wave field (where  $H = 0.78 * h$ )

HBI The initial breaking wave height along any profile at the y values rather than between them

HBQ The initial breaking wave height along any profile, between adjacent profiles

HGEN Average wave height at a depth, WDEPTH  
 HS The significant wave height input  
 I The longshore grid location  
 IBREAK The leeward side of the initial breaker location J value  
 IJET Represents the lesser I value adjacent to the structure (these must be evenly spaced alongshore)  
 IMAX The total number of grid points in the x-direction (alongshore)  
 J The offshore contour location  
 JMAX The value of the seawardmost contour simulated  
 JUSE (JMAX + 2) the seawardmost contour at which the wave field is calculated  
 J1 Landward contour of refraction zone  
 J2 Seaward contour of refraction zone  
 J1REF Landward J values of boundary of refraction zone  
 J2REF Seaward J values of boundary of refraction zone  
 MMAX The number of shore-perpendicular structures to be simulated (present maximum of 16)  
 NITER The counterindex in the refraction routine  
 NTIME The counterindex in the time simulation "DO" loop  
 NTIMES The number of iterations of time-step, DELT, for which a particular wave is simulated  
 NUNIV The total number of time-steps simulated at any time  
 PI The value of  $\pi = 3.141592654$   
 POROS The porosity of the sediment  
 QX The longshore sediment transport rate at a specific location  
 QXTOT The total alongshore sediment transport rate due to the height and angle of the initial breaking wave  
 QY The onshore-offshore sediment transport rate at a specific location  
 R See equations (36) and (37)



REPOSE	The angle of repose of the sediment
RHO	The mass density of seawater
RHOND	The dimensionless distance from the tip of structure where diffraction is initiated
RHOS	The mass density of sediment
RK	The wave number
S3	See equations (36) and (37)
SFACE	The slope of the shoreface
SJETTY	The length of the shore-perpendicular structure (from the base line)
SIGMA	The wave radian frequency
T	The wave period
TAU	The dissipative interface parameter
THETA	The wave angle throughout the wave field
THEATO	The wave angle at the tip of the structure
TKSI	The longshore sediment transport rate coefficient
TWOPI	Twice the value of $\pi$
U	See equations (36) and (37)
UCRIT	The critical velocity required to move the sediment according to the Sheid's diagram
V	See equations (36) and (37)
WDEPTH	The depth of water in meters to which the input wave conditions are to be transformed
WEQ	The equilibrium profile distance between contours as defined by the stepped profile
XCOOR	The x-coordinate where the wave field is to be calculated. Together with YCOOR, they determine whether the position is within or beyond the diffraction shadow zone
XDISTN	The location of the structure along the shoreline in feet
Y	The distance offshore to the contours

YCOOR      The y-coordinate where the wave field is to be calculated.  
            Together with XCOOR, they determine whether the position is within  
            or beyond the diffraction shadow zone

YDISS      The value of y after the use of the dissipative interface

YOLD        The previous value of y

YZERO      The berm contour location

Z1          See equation (37)

Z2          See equation (37)

APPENDIX B  
PROGRAM LISTING

```

100 C* ***** PROGRAM IMPLICIT SEDTRAN
200 C*THIS PROGRAM IS SET-UP TO HANDLE MULTIPLE GROINS(M<=10)
300 COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
400 COMMON/AA/YZERO(60)
500 COMMON/BB/WEQ(60,20)
600 COMMON/B/ THETA(60,20),QXTOT(60), OLDANG(60,20), DY(60,20)
700 COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
800 COMMON/N USED/JUSE,T,CD,CGEN,CGGEN,ANGGEN,DX,BERM,THETA0(10),MMAX
900 COMMON/D/SIGMA,G,ELO,JMAX,IMAX,PI,TWOPI,PIO2,HGEN,IJET(10),SJETTY
1000 COMMON/F/ADEAN,REPOSE,DIAM
1100 COMMON/AAA/DELT,NTIMES
1200 COMMON/COUNT/NUNIV
1300 COMMON/EXPL/QYEXP(60,20),YIMP(60,20)
1400 DIMENSION CHANGE(20),HC(10),TC(10)
1500 DIMENSION YORIG(60,20),YZERO0(60),SANGLE(20)
1600 NUNIV=0
1700 JMAX=8
1800 JUSE=JMAX+2
1900 IMAX=50
2000 PI=3.141592654
2100 TWOPI=PI*2.
2200 PIO2=PI/2.0
2300 REPOSE=32.*TWOPI/360.
2400 WRITE(6,732)
2500 732 FORMAT('*****')
2600 WRITE(6,733)
2700 733 FORMAT(2X,'TO WHAT DEPTH ARE THE WAVES TO BE TRANSFORMED')
2800 C*WDEPTH MUST BE A DEPTH BEYOND THE END OF THE STRUCT, PREFERABLY AT
2900 C**DEEP(JMAX) OR GREATER(OR ELSE SNELL'S LAW OR SHOAL COULD BLOWUP IN
3000 C***DEEPER WATER. IT'S IN METERS HERE!)
3100 READ(5,770) WDEPTH
3200 770 FORMAT(10X,F10.3)
3300 WDEPTH=WDEPTH*3.28084
3400 WRITE(6,762) WDEPTH
3500 762 FORMAT(2X,'THE DEPTH (IN FT) WAVES TRANSFORMED TO, WDEPTH= '
3600 * F10.3)
3700 WRITE(6,732)
3800 WRITE(6,777)
3900 777 FORMAT(2X,'ITS TIME FOR SJETTY, BERM, SFACE, AND DIAM'.//)
4000 C*SJETTY MUST BE MUCH LESS THAN Y(I,JMAX)
4100 READ(5,776) SJETTY,BERM,SFACE,DIAM
4200 776 FORMAT(2F10.3,F10.4,F10.3)
4300 WRITE(6,761) SJETTY
4400 761 FORMAT(2X,'THE LENGTH OF THE STRUCTURE, SJETTY= ',F10.3)
4500 WRITE(6,740) BERM
4600 740 FORMAT(2X,'THE HEIGHT OF THE BERM, BERM= ',F10.3)
4700 WRITE(6,739)SFACE
4800 739 FORMAT(2X,'THE SLOPE OF THE BEACH FACE, SFACE= ',F10.4)
4900 WRITE(6,738) DIAM
5000 738 FORMAT(2X,'THE SEDIMENT DIAMETER, DIAM= ',F10.3)
5100 WRITE(6,732)
5200 780 FORMAT(2X,'SUPPLY MMAX( THE NO. OF GROINS) AND THEIR I-LOC'.//)
5300 UCRIT=16.3*SQRT(DIAM*0.00328)
5400 C*THE NO. OF MULTIPLE GROINS,MMAX MUST BE GIVEN THEIR X LOCATIONS.
5500 READ(5,779) MMAX
5600 779 FORMAT(I3)
5700 DO 760 M=1,MMAX
5800 C*IJET REPS LESSER I-VALUE ADJACENT TO STRUCTURE.
5900 760 READ(5,779) IJET(M)
6000 WRITE(6,759) (M,IJET(M),M=1,MMAX)
6100 759 FORMAT(2X,'THE NUMBER',I5,' GROIN IS LOCATED AT GRID ',I5)
6200 WRITE(6,732)
6300 C*CONVERT TO RADIANS
6400 C*FIRST MUST GIVE Y COORS POSITIONS AND DEPTHS
6500 C*FIRST, MUST SET UP ALL OF THE DEEP-VALUES
6600 WRITE(6,773)
6700 773 FORMAT(2X,'NOW ENTER THE VALUE OF ADEAN')
6800 READ(5,774)ADEAN
6900 774 FORMAT(F10.4)
7000 WRITE(6,749) ADEAN
7100 749 FORMAT(2X,'THE VALUE OF ADEAN= ',F10.4,' IN THE EQ. H=AY**2/3')
7200 WRITE(6,732)

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7300      WRITE(6,772)
7400      772 FORMAT(2X,"READ IN THE SPACE STEP, Timestep",/)
7500      READ(5,775)  DX, DELT
7600      775 FORMAT(2(F10.3))
7700      WRITE(6,737)  DX
7800      737 FORMAT(2X, 'THE VALUE OF THE LONGSHORE SPACE-STEP, DX= ', F10.3)
7900      WRITE(6,736)  DELT
8000      736 FORMAT(2X, 'THE TIME-STEP IN SECONDS, DELT= ', F10.3)
8100      DATA CHANGE/1., 2., 3., 5., 7., 11., 14., 17., 25., 32., 808., 10*0.0/
8200      DO 220 J=1, JMAX+2
8300      DO 220 I=1, IMAX
8400      220 DEEP(I, J)=CHANGE(J)
8500      DATA(HC(I), I=1, 8)/1.87, 0.5, 0.35, .25, .21, .20, .19, .19/
8600      DATA(TC(I), I=1, 8)/2., 3., 4., 6., 8., 10., 12., 14. /
8700      DO 200 J=1, JMAX+2
8800      DO 200 I=1, IMAX
8900      200 Y(I, J+1)=(0.5*(DEEP(I, J+1)+DEEP(I, J)))/ADEAN)**1.5+Y(I, 1)
9000      WRITE(6,732)
9100      C*****
9200      C*WE WILL ALWAYS REQUIRE Y(I, JMAX+2) TO COMPUTE DY AND YBAR.
9300      C*WE WILL ALWAYS REQUIRE DEEP(I, JMAX+2) TO COMP SEDIMENT TRANSPORT
9400      C*****
9500      WRITE(6,734)
9600      734 FORMAT(2X, 'THE BOUNDARY Y-VALUES, I=1, IMAX ARE AS FOLLOWS',/)
9700      WRITE(6,801)  (Y(1, J), J=1, JMAX+2)
9800      WRITE(6,801)  (Y(IMAX, J), J=1, JMAX+2)
9900      WRITE(6,732)
10000     WRITE(6,735)
10100     735 FORMAT(/, 2X, 'THE DEPTHS BETWEEN CONTOURS ARE AS FOLLOWS',/)
10200     WRITE(6,801)  (DEEP(1, J), J=1, JMAX+2)
10300     WRITE(6,732)
10400     801 FORMAT(2X, 10(F8.2))
10500     DO 2 I=1, IMAX
10600     2 YZERO(I)=Y(I, 1)-(BERM/SFACE)
10700     C*WILL COMPUTE THE EQUIL WIDTH BETWEEN CONTOURS, HERE.
10800     DO 1 I=1, IMAX
10900     WEQ(I, 1)=Y(I, 1)-YZERO(I)
11000     DO 1 J=1, JMAX
11100     IF(J NE. 1) GO TO 32
11200     YTEMP1=0.0
11300     GO TO 33
11400     32 YTEMP1=((0.5*(DEEP(I, J-1)+DEEP(I, J)))/ADEAN)**1.5
11500     33 YTEMP2=((0.5*(DEEP(I, J)+DEEP(I, J+1)))/ADEAN)**1.5
11600     WEQ(I, J+1)=YTEMP2-YTEMP1
11700     1 CONTINUE
11800     C*LET'S STORE THE ORIG VALUES TO COMPUTE VOL CHANGES OVER CONTOURS, LATER
11900     DO 796 I=1, IMAX+1
12000     YZERO0(I)=YZERO(I)
12100     DO 796 J=1, JMAX+2
12200     796 YORIG(I, J)=Y(I, J)
12300     C*****
12400     C*READ THE DISK FILE AND TRANSFORM PARAMETERS INTO MY UNITS.
12500     C*****!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
12600     C*ALL ADJUSTMENTS TO WAVE ANGLE, HEIGHT, CELERITY, GROUP VEL. WILL BE MADE
12700     C**HERE, AND THRUOUT THE REST OF THE PROG. THEY WILL BE AS IF OCCURRED
12800     C***AT WDEPTH!
12900     798 READ(5,799, END=1000)  HS, T, ALPWIS
13000     799 FORMAT(10X, 3F6.1)
13100     NTIMES=1
13200     NCHECK=NUNIV+NTIMES
13300     HGEN=0.707107*HS
13400     SIGMA=TWOPI/T
13500     G=32.17
13600     CO=G*T/TWOPI
13700     ELO=CO*T
13800     IF(T.LE.2.0) GO TO 797
13900     HCC=0.23
14000     DO 444 I=2.7
14100     T2=TC(I)
14200     IF(T.GT.T2) GO TO 444
14300     T1=TC(I-1)
14400     DELTAT=T2-T1

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14500      DT=(T-T1)/DELTAT
14600      DTT=(T2-T)/DELT
14700      HCC=HC(I)*DT+HC(I-1)*DTT
14800      GO TO 446
14900      444 CONTINUE
15000      446 CONTINUE
15100      IF(HGEN.LT.HCC) GO TO 797
15200      ANGGEN=ALPWIS*TWOPI/360
15300      C*****
15400      CALL WVNUM(WDEPTH,T,DUMKK)
15500      C*ANGGEN,HGEN,CGEN,CGGEN REPRESENT THE WAVE ANGLE,HEIGHT,CELERITY AND
15600      C**GROUP VEL(RESPCT.) OF THE SPECIFIED WAVE INPUT AT A DEPTH, WDEPTH
15700      CALL WVNUM(11.0,T,DUMKKK)
15800      C11=TWOPI/(T*DUMKKK)
15900      CG11=0.5*C11*(1+(2.*DUMKKK*11.0/SINH(2.*DUMKKK*11.0)))
16000      CGEN=TWOPI/(T*DUMKK)
16100      CGGEN=0.5*CGEN*(1+(2.*DUMKK*WDEPTH/SINH(2.*DUMKK*WDEPTH)))
16200      CALL TRANS
16300      797 IF(NCHECK.NE.NUNIV) NUNIV=NCHECK
16400      709 GO TO 798
16500      1000 CONTINUE
16600      STOP
16700      END
16800      C*****
16900      SUBROUTINE TRANS
17000      C*THIS SUBROUTINE WILL COMPUTE SEDIMENT TRANSPORT
17100      COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
17200      COMMON/AA/YZERO(60)
17300      COMMON/BB/WEQ(60,20)
17400      COMMON/B/ THETA(60,20),QXTOT(60),OLDANG(60,20),DY(60,20)
17500      COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
17600      COMMON/N USED/JUSE,T.CO,CGEN,CGGEN,ANGGEN,DX,BERM,THETA0(10),MMAX
17700      COMMON/D/SIGMA.G,ELD,JMAX,IMAX,PI,TWOPI,PI02,HGEN,IJET(10),SJETTY
17800      COMMON/E/RHO,RHOS,POROS,CONST,TKSI
17900      COMMON/F/ADEAN,REPOSE,DIAM
18000      COMMON/G/IBREAK(60),HNONBR(20)
18100      COMMON/P/HBQ(60),DEEPB(60)
18200      COMMON/ZZZ/NTIME
18300      COMMON/AAA/DELT,NTIMES
18400      COMMON/COUNT/NUNIV
18500      DIMENSION YOLD(60,20),R(60,20),S(60,20),HC(60,20),QY(60,20),YDISS(
18600      * 60,20)
18700      DIMENSION RHS1(60,20),S3(60,20),THETAB(60,20),ANGL0C(60,20)
18800      DIMENSION DISTR(60,20),AWARE(60,20)
18900      C*****
19000      C*****
19100      C***** NOTE : SIZE OF ABAND AND XL HAVE TO BE CHANGED
19200      C***** ACCORDING TO JMAX+1+JMAX AND JMAX+1,RESPECT
19300      C***** CHANGE REQ'D AT 7040 AND 18650
19400      C*****
19500      * ),BMATRIX(432),ABAND(432,19),QX(60,20),XL(432,10),CONST6(60,20)
19600      COMMON/MP/ RKB(60),HBI(60),DEEPBI(60)
19700      COMMON/EXPL/QYEXP(60,20),YIMP(60,20)
19800      DIMENSION SANGLE(20)
19900      C*LET'S ZERO-OUT ALL OF THE DIMENSIONED MATRICES.
20000      DO 1000 J=1,JMAX+2
20100      SANGLE(J)=0.0
20200      DO 1000 I=1,IMAX+2
20300      YOLD(I,J)=0.0
20400      R(I,J)=0.0
20500      S(I,J)=0.0
20600      HC(I,J)=0.0
20700      QY(I,J)=0.0
20800      YDISS(I,J)=0.0
20900      RHS1(I,J)=0.0
21000      S3(I,J)=0.0
21100      THETAB(I,J)=0.0
21200      ANGL0C(I,J)=0.0
21300      DISTR(I,J)=0.0
21400      AWARE(I,J)=0.0
21500      QX(I,J)=0.0
21600      CONST6(I,J)=0.0

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21700      1000 CONTINUE
21800          RHO=1.99
21900          RHOS=5.14
22000          POROS=0.40
22100          CONST=0.77
22200          CAPPA=0.78
22300          TAU=0.25
22400          TKS1=(CONST*RHO*SQRT(G))/((RHOS-RHO)*(1.0-POROS)*16.0*SQRT(CAPPA))
22500      C* QX(I,J) IS THE TRANSPORT BETWEEN THE (I,J+1) AND (I,J) CONTOURS.
22600      C*THE 'DO 1 LOOP' SIMULATES TIME---TIME=DELT*NTIMES.
22700          COFF=0.00001
22800          GAMMA=RHO*G
22900          DO 1 NTIME=1,NTIMES
23000              NUNIV=NUNIV+1
23100      C*THE MATRICES ABAND AND BMATRX MUST BE "ZERDED OUT"
23200          K=0
23300          DO 26 I=2,IMAX-1
23400              DO 26 J=1,JMAX
23500                  K=K+1
23600                  BMATRX(K)=0.0
23700                  DO 26 L=1,JMAX+1+JMAX
23800                      26 ABAND(K,L)=0.0
23900                      XNTIME=1.0*(NTIME)
24000                      CALL PREDIF
24100      C*SMOOTHING OF THE WAVE ANGLE,THETA, IS RE'D TO ACCT FOR DIFF EFFECTS.
24200          CALL SMOOTH(THETA,IMAX,JMAX,IJET,SJETTY,MMAX,Y)
24300          CALL QTRAN
24400      C*FIRST THE LONGSHORE SEDIMENT TRANSPORT WILL BE DISTRIBUTED
24500      C****ACROSS THE SURF ZONE....
24600          CC=1.25
24700      C***QX(I,J) WILL BE DETERMINED BY SUBTRACTING FROM THE INTEGRAL
24800      C**OF QX FROM DEEP(I,J-1) TO INFINITY, THE INTEGRAL OF QX FROM DEEP(I,J)
24900      C***TO INFINITY. IN THIS WAY THE SEDIMENT TRANS FROM JMAX OUT GETS
25000      C***INCLUDED IN QX(I,JMAX). TO INCLUDE THE SWASH TRANS. WHEN J=1
25100      C*WE WILL SUBTRACT FROM 2 TO INFINITY FROM 1.0
25200      C*LOOP FOR VALUES WHICH ARE HELD CONST AND STORED.
25300          THETAB(1,1)=0.5*(THETA(1,1)+0.0)
25400          R(1,1)=0.5/(DX*(DEEP(1,1)+BERM/2.))
25500          DO 290 I=2,IMAX
25600              R(I,1)=0.5/(DX*(DEEP(I,1)+BERM/2.))
25700      C* THETAB(I,1)=0.25*(THETA(I,1)+THETA(I-1,1)+0.+0.)
25800          THETAB(I,1)=0.5*(THETA(I,1)+THETA(I-1,1))
25900      C*NO NEED TO COMPUTE PROP ANGLE AT STRUCTS BECAUSE QX =0.0 AT IJET(M)+1
26000          ANGLC(I,1)=ATAN((Y(I,1)-Y(I-1,1))/DX)
26100      C*HBQ(IJET(M)+1) IS PROPERLY SET IN THE SUBROUTINE QTRAN.
26200          DISTR(I,1)=1.0-EXP(-((DEEP(I,1)**1.5+HBQ(I)*ADEAN**1.5)/(
26300              * (CC*DEEPP(I)**1.5))**3))
26400          DISTR(I,1)=DISTR(I,1)*TKS1*HBQ(I)**2.5
26500          DO 290 J=2,JMAX
26600              R(I,J)=0.5/(DX*(DEEP(I,J)-DEEP(I,J-1)))
26700              THETAB(I,J)=0.5*(THETA(I,J)+THETA(I-1,J))
26800              ANGLC(I,J)=ATAN((Y(I,J)-Y(I-1,J))/DX)
26900              DISTR(I,J)=EXP(-((DEEP(I,J-1)**1.5+HBQ(I)*ADEAN**1.5)/(CC*DEEPP(I)
27000                  * **1.5))**3)-EXP(-((DEEP(I,J)**1.5+HBQ(I)*ADEAN**1.5)/(CC*
27100                  * DEEPP(I)**1.5))**3))
27200              DISTR(I,J)=DISTR(I,J)*TKS1*HBQ(I)**2.5
27300          290 CONTINUE
27400              DO 301 J=1,JMAX
27500                  DO 301 I=2,IMAX
27600                      AWARE(I,J)=DELT*R(I,J)*(QX(I,J)-QX(I+1,J)+QY(I,J)-QY(I,J+1))+Y(I,J)
27700                      *
27800                      * S1=2.*SIN(THETAB(I,J))*COS(THETAB(I,J))*(-1.+2.*(COS(
27900                      * ANGLC(I,J)))**2)
28000                      S2=COS(2.*THETAB(I,J))*COS(ANGLC(I,J))/(SQRT(DX**2+
28100                      * (Y(I,J)-Y(I-1,J))**2))
28200                      S3(I,J)=S2*DISTR(I,J)
28300                      IF(SJETTY EQ 0.0) GO TO 302
28400                      DO 325 M=1,MMAX
28500                          IF(I NE IJET(M)+1) GO TO 325
28600                          IF(THETA(M) GE 0.0) ISIDE=IJET(M)
28700                          IF(THETA(M) LT 0.0) ISIDE=IJET(M)+1
28800                          YSEA=0.5*(Y(ISIDE,J)+Y(ISIDE,J+1))
28900                          YSHORE=0.5*(Y(ISIDE,J)+Y(ISIDE,J-1))

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29000         IF(YSEA GT SJETTY AND YSHORE GT SJETTY) GO TO 302
29100         IF(YSEA GT SJETTY AND YSHORE LE SJETTY) GO TO 298
29200 C*BECAUSE A NO FLOW B C IS USED ALONG THE STRUCT, NO ATTN WAS PAID
29300 C**TO GETTING PROPER VALUES OF ANGLOC, THETAB,DISTR,ETC.
29400         S3(I,J)=0 0
29500         DISTR(I,J)=0 0
29600         GO TO 302
29700     325 CONTINUE
29800         GO TO 302
29900 C***ABOVE, ALL PARAMETERS(I E .S1,S2,S3,THETAB,DISTR,ANGLOC)
30000 C***ARE COMPUTED AS IF THE STRUCT IS NOT THERE THE B C AT THE
30100 C***STRUCT TIP ASSUMES QX COMPUTED AS IF NO STRUCT PRESENT AND THEN
30200 C***BYPASSES ACCORDING TO "RATIO"
30300     298 RATIO=(YSEA-SJETTY)/(YSEA-YSHORE)
30400         S3(I,J)=S3(I,J)*RATIO
30500         DISTR(I,J)=DISTR(I,J)*RATIO
30600     302 RHS1(I,J)=DISTR(I,J)*S1-S3(I,J)*(Y(I,J)-Y(I-1,J))
30700     301 CONTINUE
30800         CALL BREAK(IMAX,JMAX)
30900 C*TO DETERMINE DECAY OF CONST6(I,J),NEED WAVE NO. AT BREAKING.
31000         DO 754 I=1,IMAX+1
31100             754 CALL WVNUM(DEEPBI(I),T,RKB(I))
31200 C*USING SHIELD'S DIAG.Y AXIS=0 05 8 (TAUO=RHO*C*U**2),GET UCRIT(FT/SEC)
31300         UCRIT=.16 3*SQRT(DIAM*.00328)
31400         DO 750 I=1,IMAX+1
31500             CONST6(I,1)=COFF*DX
31600             DO 750 J=2,JMAX+2
31700 C*CONST6(I,J) GOES W/ QY(I,J) WHICH IS ASSOC W/ DEEP(I,J-1)
31800             IF(DEEP(I,J-1) LE DEEPBI(I)) GO TO 751
31900 C*HERE, MUST CAUSE COFF TO DECAY (WE'RE BEYOND SURF ZONE)
32000             UMAXB=HBI(I)*G*T*RKB(I)/(2.*TWOPI*COSH(RKB(I)*DEEPBI(I)))
32100             UMAX=H(I,J-1)*G*T*RK(I,J-1)/(2.*TWOPI*COSH(RK(I,J-1)*DEEP(I,J-1)))
32200             IF(UCRIT LT UMAX AND UCRIT LT UMAXB) GO TO 749
32300             CONST6(I,J)=0 0
32400             GO TO 750
32500     749 TOP=0 01*H(I,J-1)**3*SIGMA**3/(SINH(RK(I,J-1)*DEEP(I,J-1))**3)
32600             BOT=DEEP(I,J-1)*(0 625*TWOPI*G**1 5*0 78**2*ADEAN**1 5+
32700             * (0 01*HBI(I)**3*SIGMA**3/(DEEPBI(I)*(SINH(RKB(I)*DEEPBI(I))**3)))
32800             CONST6(I,J)=DX*COFF*TOP/BOT
32900             GO TO 750
33000     751 CONST6(I,J)=COFF*DX
33100     750 CONTINUE
33200         K=0
33300 C**PUT INTO BANDED FORM USING THE ALGORITHM A(M,N)->B(M,NN) WHERE
33400 C***NN=KB+1 M+N(KB IS THE NUMBER OF LOWER CODIAGONALS(=JMAX,HERE)).
33500         DO 304 I=2,IMAX-1
33600             DO 304 J=1,JMAX
33700             K=K+1
33800             AWARE(I,J)=AWARE(I,J)+DELT*RHS1(I,J)*R(I,J)-DELT*R(I,J)*RHS1(I+1,J
33900             * )+DELT*R(I,J)*CONST6(I,J)*WEQ(I,J)-DELT*R(I,J)*CONST6(I,J+1)*
34000             * WEQ(I,J+1)
34100             YDUM=YZERO(I)
34200             IF(J NE 1) YDUM=Y(I,J-1)
34300             AWARE(I,J)=AWARE(I,J)+DELT*R(I,J)*CONST6(I,J)*0.5*(YDUM-Y(I,J))
34400             * -DELT*R(I,J)*CONST6(I,J+1)*0.5*(Y(I,J)-Y(I,J+1))
34500             U=DELT*R(I,J)*S3(I,J)
34600             V=DELT*R(I,J)*S3(I+1,J)
34700             Z1=DELT*R(I,J)*CONST6(I,J)*0.5
34800             Z2=DELT*R(I,J)*CONST6(I,J+1)*0.5
34900 C*NOW WILL SET UP THE MATRICES ABAND AND BMATRIX.
35000             ABAND(K,JMAX+1)=1.0+U+V+Z1+Z2
35100             IF(I NE 2) GO TO 305
35200             AWARE(I,J)=AWARE(I,J)+U*Y(I-1,J)
35300             GO TO 310
35400     305 ABAND(K,1)=-U
35500     310 IF(I NE IMAX-1) GO TO 306
35600             AWARE(I,J)=AWARE(I,J)+V*Y(IMAX,J)
35700             GO TO 311
35800     306 ABAND(K,JMAX+1+JMAX)=-V
35900     311 IF(J NE 1) GO TO 307
36000             ABAND(K,JMAX+1)=ABAND(K,JMAX+1)-Z1
36100             AWARE(I,1)=AWARE(I,1)+Z1*(YZERO(I)-Y(I,1))
36200             GO TO 312

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36300      307 ABAND(K,JMAX)--Z1
36400      312 IF(J NE JMAX) GO TO 308
36500          AWARE(I,J)=AWARE(I,J)+Z2*Y(I,JMAX+1)
36600          GO TO 309
36700      308 ABAND(K,JMAX+2)=-Z2
36800      309 BMATRX(K)=AWARE(I,J)
36900      304 CONTINUE
37000          KMAX=K
37100      C**CALL IMSL ROUTINE LEQT1B TO SOLVE THE BANDED MATRIX.
37200          CALL LEQT1B(ABAND,KMAX,JMAX,JMAX,432,BMATRX,1,432,0,XL,IER)
37300      C*NOW, GIVE Y'S THEIR NEW VALUES STORING OLD VALUES IN YOLD.
37400          K=0
37500          DO 315 I=2,IMAX-1
37600              YOLD(I,JMAX+1)=Y(I,JMAX+1)
37700          DO 315 J= 1,JMAX
37800              K=K+1
37900              YOLD(I,J)=Y(I,J)
38000              Y(I,J)=BMATRX(K)
38100      315 CONTINUE
38200          DO 320 J=1,JMAX+3
38300              YOLD(1,J)=Y(1,J)
38400      320 YOLD(IMAX,J)=Y(IMAX,J)
38500      C*WILL USE ABBOTT'S DISSIPATIVE INTERFACE TO RID HIGH FREQ OSCILLATIONS
38600          DO 650 J=1,JMAX
38700              DO 650 I=2,IMAX-1
38800                  YDISS(I,J)=TAU*Y(I-1,J)+(1.-2.*TAU)*Y(I,J)+TAU*Y(I+1,J)
38900                  IF(SJETTY.EQ.0.0) GO TO 650
39000                  DO 649 M=1,MMAX
39100                      IF(I NE IJET(M).AND.I NE IJET(M)+1) GO TO 649
39200                      IF(Y(IJET(M),J).GT.SJETTY.OR.Y(IJET(M)+1,J).GT.SJETTY)GO TO 649
39300                      IF(I.EQ.IJET(M))YDISS(I,J)=TAU*Y(I-1,J)+(1.-TAU)*Y(I,J)
39400                      IF(I.EQ.(IJET(M)+1))YDISS(I,J)=TAU*Y(I+1,J)+(1.-TAU)*Y(I,J)
39500      649 CONTINUE
39600      650 CONTINUE
39700          DO 651 J=1,JMAX
39800              DO 651 I=2,IMAX-1
39900                  651 Y(I,J)=YDISS(I,J)
40000      C*THIS LOOP WILL STORE THE IMPLICIT Y VALUES REQ'D TO COMP QY&QX
40100          DO 40 I=1,IMAX+1
40200              DO 40 J=1,JMAX+3
40300      40 YIMP(I,J)=Y(I,J)
40400      C*THIS LOOP WILL EXPLICITLY MOVE CONTOURS SEAWARD IF REPOSE EXCEEDED.
40500          KOUNT=0
40600          SLOPEM=TAN(0.9*REPOSE)
40700          DO 48 I=1,IMAX
40800      43 KOUNT=KOUNT+1
40900          IF(KOUNT GT.50000) GO TO 41
41000      C*LET US COMPUTE ALL THE SLOPES(PSLOP) FOR EACH CHANGE IN DEPTH.
41100          DO 47 J=1,JMAX+1
41200              DUM=-BERM/2.0
41300              IF(J.NE.1) DUM=DEEP(I,J-1)
41400              DELH=0.5*(DEEP(I,J+1)+DEEP(I,J))-0.5*(DEEP(I,J)+DUM)
41500              PSLOP=DELH/(Y(I,J+1)-Y(I,J))
41600      47 SANGLE(J)=ATAN(PSLOP)
41700      C*FIND THE MIN NEG SLOPE ANGLE OR THEN THE POS SLOPE>REPOSE OR FORGET IT
41800          ASLOPM=-1.0E50
41900          ASLOPP=0.0
42000          DO 46 J=1,JMAX+1
42100              IF(SANGLE(J) GT.0.0) GO TO 45
42200              IF(SANGLE(J) GT.ASLOPM)ASLOPM=SANGLE(J)
42300              IF(ASLOPM.EQ.SANGLE(J)) JM=J
42400              GO TO 46
42500      45 IF(SANGLE(J).GT.REPOSE.AND.SANGLE(J) GT.ASLOPP)ASLOPP=SANGLE(J)
42600              IF(ASLOPP.EQ.SANGLE(J)) JP=J
42700      46 CONTINUE
42800              IF(ASLOPM.EQ.-1.0E50.AND.ASLOPP.EQ.0.0) GO TO 42
42900              IF(ASLOPM.EQ.-1.0E50) GO TO 44
43000              DUM=-BERM/2.
43100              IF(JM.NE.1) DUM=DEEP(I,JM-1)
43200              ALTER=((0.5/SLOPEM*(DEEP(I,JM+1)-DUM))-(Y(I,JM+1)-Y(I,JM)))/
43300              * (1.0+((DEEP(I,JM+1)-DEEP(I,JM))/(DEEP(I,JM)-DUM)))
43400              Y(I,JM+1)=Y(I,JM+1)+ALTER

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43500      Y(I, JM)=Y(I, JM)-(ALTER*(DEEP(I, JM+1)-DEEP(I, JM))/(DEEP(I, JM)-DUM))
43600      QYEXP(I, JM+1)=QYEXP(I, JM+1)+DX/DELT*ALTER*(DEEP(I, JM+1)-DEEP(I, JM)
43700      *
43800      GO TO 43
43900      44 CONTINUE
44000      DUM=-BERM/2.
44100      IF(JP.NE.1) DUM=DEEP(I, JP-1)
44200      ALTER=((0.5/SLOPEM*(DEEP(I, JP+1)-DUM))-(Y(I, JP+1)-Y(I, JP)))/
44300      * (1.0+((DEEP(I, JP+1)-DEEP(I, JP))/(DEEP(I, JP)-DUM)))
44400      Y(I, JP+1)=Y(I, JP)+ALTER
44500      Y(I, JP)=Y(I, JP)-(ALTER*(DEEP(I, JP+1)-DEEP(I, JP))/(DEEP(I, JP)-DUM))
44600      QYEXP(I, JP+1)=QYEXP(I, JP+1)+DX/DELT*ALTER*(DEEP(I, JP+1)-DEEP(I, JP)
44700      *
44800      GO TO 43
44900      42 WEQ(I, JMAX+1)=Y(I, JMAX+1)-Y(I, JMAX)
45000      48 CONTINUE
45100      C*IF WE GET SENT HERE, LOOP 444 WILL CATCH THE CROSSED CONTOURS.
45200      41 CONTINUE
45300      C*NOW WE CAN COMPUTE QX'S AND QY'S!
45400      DO 318 I=2, IMAX
45500      C*ALL IMPLIC AND EXPLIC MOVEMENT OF YZERO WILL BE TAKEN CARE OF HERE
45600      QY(I, 1)=-BERM*DX*(Y(I, 1)-YOLD(I, 1))/DELT
45700      YZERO(I)=YZERO(I)+(Y(I, 1)-YOLD(I, 1))
45800      319 DO 318 J=1, JMAX
45900      QX(I, J)=RHS1(I, J)-S3(I, J)*YIMP(I, J)+S3(I, J)*YIMP(I-1, J)
46000      318 QY(I, J+1)=CONST6(I, J+1)*(0.5*(YIMP(I, J)+YOLD(I, J)-YIMP(I, J+1)
46100      * -YOLD(I, J+1))+WEQ(I, J+1))
46200      DO 323 J=1, JMAX
46300      QX(1, J)=QX(2, J)
46400      323 QX(IMAX+1, J)=QX(IMAX, J)
46500      C*TOTAL QYS WILL BE COMP FROM IMPLIC AND EXPLIC VALUES.THEN ZERO QYEXP
46600      DO 39 I=1, IMAX+1
46700      DO 39 J=1, JMAX+3
46800      QY(I, J)=QY(I, J)+QYEXP(I, J)
46900      39 QYEXP(I, J)=0.0
47000      C*THIS CHECK WILL BOMB THINGS OUT IF CONTOURS HAVE CROSSED.
47100      DO 444 II=1, IMAX
47200      DO 444 JJ=1, JMAX
47300      C*IF CONTOURS CROSS AT ANY TIME WANT PROGRAM TO STOP!
47400      IF(Y(II, JJ).LT.Y(II, JJ+1)) GO TO 444
47500      WRITE(6, 103)
47600      WRITE(6, /*) NUNIV
47700      DO 150 J=1, JMAX
47800      150 WRITE(6, 100) (QX(I, J), I=1, IMAX)
47900      DO 151 J=1, JMAX
48000      151 WRITE(6, 101) (QY(I, J), I=1, IMAX)
48100      DO 152 J=1, JMAX
48200      152 WRITE(6, 100) (Y(I, J), I=1, IMAX)
48300      103 FORMAT(2X, 'THE CONTOURS HAVE CROSSED AND SOMETHING IS WRONG', /)
48400      DO 19 J=1, JMAX
48500      19 WRITE(6, 100) (YOLD(I, J), I=1, IMAX)
48600      GO TO 445
48700      444 CONTINUE
48800      WRITE(6, /*) NUNIV
48900      C*THE FOLLOWING STATEMENT DETERMINES AT WHAT FREQ EVERYTHING IS WRITTEN!
49000      IF(MOD(NUNIV, 10).NE.0) GO TO 1
49100      C*LET'S WRITE ALL OF IT OUT.
49200      WRITE(6, 926) NUNIV
49300      926 FORMAT(2X, 'THE TOTAL ELAPSED NUMBER OF TIME-STEPS. NUNIV= ', 15, /)
49400      800 FORMAT(2X, 14(F8.4))
49500      C*
49600      C*900 WRITE(6, 800) (THETA(I, J), J=1, JMAX)
49700      C*
49800      C*903 WRITE(6, 801) DEEP(1, J)
49900      C*
50000      C*906 WRITE(6, 800) (H(I, J), J=1, JMAX)
50100      C*
50200      C*755 WRITE(6, 800) (CONST6(I, J), I=1, IMAX)
50300      801 FORMAT(2X, 14(F8.2))
50400      WRITE(6, 107)
50500      107 FORMAT(/, 2X, 'THE LONGSHORE TRANSPORTS, QX, FOLLOW')
50600      DO 15 J=1, JMAX
50700      15 WRITE(6, 100) (QX(I, J), I=1, IMAX)

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01000) WRITE(1,100)
01001) 100 FORMAT(2X, 'THE ON OFFSHORE TRANSPORTS OF FOLLOW 1')
01002) DO 17 J=1, JMAX
01003) 17 WRITE(1,101) (X(I), J, I-1, IMAX)
01004) WRITE(1,100)
01005) 100 FORMAT(2X, 'THE NEW CONTINUM VALUES 1 FOLLOW 1')
01006) DO 18 J=1, JMAX
01007) 18 WRITE(1,102) (X(I), J, I-1, IMAX)
01008) 101 FORMAT(2X, 'ITEM 11')
01009) 102 FORMAT(2X, 'ITEM 11')
01010) 1 CONTINUE
01011) RETURN
01012) GO TO 440
01013) 440 STOP
01014) 440 CONTINUE
01015) END
01016)
01017) .....
01018) SUBROUTINE QTRAN
01019) C THIS SUBROUTINE CALC THE BREAKER HEIGHT FOR EACH
01020) C OF THE 1 GRID LINES METHOD FINIS Y LOCATIONS BEFORE AND AFTER
01021) C CORRECTION HAS OCCURRED BY REFRACTION THEN USES SIMILING TO GET THE
01022) C CORRU SNELL S LAW IS USED FOR REFRACTION OVER THE SHORT DIST TO BREAKING
01023) C U(X(I), J) IS THE TRANS BETWEEN(I, J) AND (I, J) AT THE INCIDENT
01024) C (COMMON A / C(10, 20) U(10, 20) V(10, 20) DEEP(10, 20) ALPHA(10, 20)
01025) C (COMMON A A / Z(10, 20)
01026) C (COMMON B / THE I(10, 20), U(10, 20) D(10, 20) D(10, 20)
01027) C (COMMON C / H(10, 20) C(10, 20) M(10, 20) W(10, 20) Y(10, 20)
01028) C (COMMON N USED, JUSE 1, CO, CGEN, CGEN, ANGEN BY REFRM THE I(10, 20) JMAX
01029) C (COMMON D SIGMA 0 FLD, JMAX, IMAX AT TWOP FLD THEN L(10, 20) S(10, 20)
01030) C (COMMON G BREAK(10, 20) NUMBER(20)
01031) C (COMMON E H(10, 20) W(10, 20) P(10, 20) (CONST INST
01032) C (COMMON P / H(10, 20) DEEP(10, 20)
01033) C APPA=0.70
01034) DO 1 I=2, IMAX
01035) DO 2 J=1, JMAX
01036) J=JMAX+1
01037) H(10, I)=J(10, I)+J(10, I)
01038) H(10, I)=J(10, I)+J(10, I)
01039) C CAN ONLY USE COMS ON ONE SIDE OF STRUCT CAN I AVO HERE?
01040) IF(SUJET EQ 0) GO TO 4
01041) DO 4 M=1, MMAX
01042) IF(NE IJETEM) GO TO 4
01043) IF(THETA(M) GE 0) ISIDE=IJETEM
01044) IF(THETA(M) LT 0) ISIDE=-IJETEM
01045) C AT STRUCT TIP ASSUMES 0 (IMP AS IF NO STRUCT IS PRESENT)
01046) YSEA=0 N(1, ISIDE) N(2, ISIDE) J(1)
01047) IF(YSEA GT SUJET) GO TO 3
01048) H(10, I)=ISIDE, J)
01049) H(10, I)=ISIDE, J)
01050) GO TO 3
01051) 4 CONTINUE
01052) 3 IF(H(10, I) H(10, I) GO TO 1
01053) DEEP(I)=((H(10, I) H(10, I) H(10, I) H(10, I) H(10, I) H(10, I)
01054) * DEEP(I) H(10, I) H(10, I) H(10, I) H(10, I) H(10, I)
01055) H(10, I)=CAPPA*DEEP(I)
01056) C (H(10, I) AND DEEP(I) WILL BE COMPUTED ACCORDING TO THE WAVE DIR
01057) C AT THE STRUCTURE TIP THETA
01058) IF(SUJET EQ 0) GO TO 1
01059) DO 6 M=1, MMAX
01060) IF(NE IJETEM) GO TO 6
01061) C THE TRANSPORTING WAVES WILL BE COMPUTED USING THE WAVE TO PROP SIDE
01062) IF(THETA(M) GE 0) GO TO 11
01063) DEEP(I)=((H(10, I) H(10, I) H(10, I) H(10, I) H(10, I) H(10, I)
01064) H(10, I) H(10, I) H(10, I) H(10, I) H(10, I) H(10, I)
01065) GO TO 12
01066) 11 DEEP(I)=((H(10, I) H(10, I) H(10, I) H(10, I) H(10, I) H(10, I)
01067) H(10, I) H(10, I) H(10, I) H(10, I) H(10, I) H(10, I)
01068) 12 H(10, I)=DEEP(I)*CAPPA
01069) GO TO 1
01070) 6 CONTINUE
01071) GO TO 1
01072) 2 CONTINUE
01073) 1 CONTINUE

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58100 C*IF THE OFFSHORE WAVE HT IS ZERO, NEVER GET TO HERE
58200 C*HOWEVER IF THE H IS SUCH THAT IT WOULD BREAK INSHORE OF Y(I,2)
58300 C*DEEPB(I) WOULD STILL BE ZERO AND DISTR(I,J) WOULD BLOW-UP.
58400 DO 20 I=1,IMAX
58500 IF(DEEPB(I).GT.0.0) GO TO 20
58600 DEEPB(I)=(H(I,1)*DEEP(I,1)**0.25/CAPPA)**0.8
58700 HBQ(I)=CAPPA*DEEPB(I)
58800 20 CONTINUE
58900 HBQ(1)=HBQ(2)
59000 HBQ(IMAX+1)=HBQ(IMAX)
59100 DEEPB(1)=DEEPB(2)
59200 DEEPB(IMAX+1)=DEEPB(IMAX)
59300 RETURN
59400 END
59500 C*****
59600 SUBROUTINE BREAK(IMAX,JMAX)
59700 C*ROUTINE WILL DETERMINE HB AND DEEPB ON THE GRID LINES RATHER
59800 C* THAN BETWEEN THEM. REQ'D FOR COFF BEYOND SURF ZONE.
59900 COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
60000 COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
60100 COMMON/MP/ RKB(60),HBI(60),DEEPBI(60)
60200 CAPPA=0.78
60300 DO 1 I=2,IMAX
60400 DO 2 JJ=1,JMAX
60500 J=JMAX-JJ+1
60600 IF(H(I,J).LT.HB(I,J)) GO TO 2
60700 DEEPBI(I)=((H(I,J+1)*DEEP(I,J+1)**0.25)/CAPPA)**0.8
60800 HBI(I)=CAPPA*DEEPBI(I)
60900 C***ONCE THE HEIGHT & DEPTH AT BREAKING ARE FOUND, GO TO NEXT GRID-LINE.
61000 GO TO 1
61100 2 CONTINUE
61200 1 CONTINUE
61300 DO 20 I=1,IMAX
61400 IF(DEEPBI(I).GT.0.0) GO TO 20
61500 DEEPBI(I)=(H(I,1)*DEEP(I,1)**0.25/CAPPA)**0.8
61600 HBI(I)=CAPPA*DEEPBI(I)
61700 20 CONTINUE
61800 DEEPBI(1)=DEEPBI(2)
61900 DEEPBI(IMAX+1)=DEEPBI(IMAX)
62000 HBI(1)=HBI(2)
62100 HBI(IMAX+1)=HBI(IMAX)
62200 RETURN
62300 END
62400 C*****
62500 SUBROUTINE REFRAC(JBEGIN,JEND,NPTS,IBEGIN,IEND,ISTART,M)
62600 COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
62700 COMMON/AA/YZERO(60)
62800 COMMON/B/ THETA(60,20),QXTOT(60),OLDANG(60,20),DY(60,20)
62900 COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
63000 COMMON/N USED/JUSE,T,CD,CGEN,CGGEN,AIIGGEN,DX,BERM,THETA0(10),MMAX
63100 COMMON/D/SIGMA,G,ELO,JMAX,IMAX,PI,TWJPI,PIO2,HGEN,IJET(10),SJETTY
63200 COMMON/G/IBREAK(60),HNONBR(20)
63300 COMMON/ZZZ/NTIME
63400 DIMENSION JBEGIN(60),JEND(60)
63500 C***** THIS SUBROUTINE WILL DETERMINE H AND
63600 C***** THETA AT THE MID PT OF Y VALUES.
63700 C***TAU IS THE FACTOR WHICH RECOUPLES THE REFRACTION EQS.SEE ABBOTT
63800 TAU=0.25
63900 C*MUST PRESCRIBE THE WAVE ANGLE AT THE OUTERMOST CONTOUR BOX
64000 C*SNELL'S LAW WILL BE USED TO START THINGS OFF.
64100 C*THETA(I,J) WILL BE AT AREA'S CENTER AND WILL USE Y(I,J) IN NEG Y-DIR
64200 C*WILL INITIALIZE ALL THETA'S USING SNELL'S LAW.
64300 DO 206 I=IBEGIN,IEND
64400 C*INITIALIZE TWO J-VALUES BEYOND JMAX,IF IN REGION 1.
64500 IF(JEND(I).EQ.JMAX) JINIT=2
64600 IF(JEND(I).NE.JMAX) JINIT=0
64700 DO 206 J=JBEGIN(I),JEND(I)+JINIT
64800 C*MUST CORRECT FOR THE CONTOUR ORIENTATION, ALPHAS.
64900 IF(I.NE.IBEGIN) GO TO 960
65000 ALPHAS(I,J)=ATAN((0.5*(Y(I+1,J)+Y(I+1,J+1))-0.5*(Y(I,J)
65100 * +Y(I,J+1)))/DX)
65200 GO TO 962

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65300      960 IF(I.NE.IEND) GO TO 961
65400      ALPHAS(I,J)=ATAN((0.5*(Y(I,J)+Y(I,J+1))-0.5*(Y(I-1,J)
65500      *   +Y(I-1,J+1)))/DX)
65600      GO TO 962
65700      961 ALPHAS(I,J)=ATAN((0.5*(Y(I+1,J)+Y(I+1,J+1))-0.5*
65800      *   (Y(I-1,J)+Y(I-1,J+1)))/(2.*DX))
65900      962 DALPHA=ANGGEN-ALPHAS(I,J)
66000      THETA(I,J)=ARSIN((C(I,J)/CGEN)*SIN(DALPHA))
66100      C*MUST GET THETA WRT THE X-AXIS.
66200      THETA(I,J)=THETA(I,J)+ALPHAS(I,J)
66300      206 CONTINUE
66400      C*NOW, WE MUST COMP THE BOUN WAVE HTS SO THE HTS CAN BE COMPUTED.
66500      C*WILL USE THE EQ. ***** DEL DOT (E*CG)=0.0
66600      C*NOW WE WILL CORRECT THE HT FOR SHOALING AND REFRACTION TO THE B.C.
66700      C*WILL ALSO INITIALIZE H'S WITH THESE EQUATIONS FOR ENTIRE ARRAY.
66800      DO 500 I=IBEGIN,IEND
66900      C*INITIALIZE TWO J-VALUES BEYOND JMAX IF IN REGION 1.
67000      IF(JEND(I) EQ.JMAX) JINIT=2
67100      IF(JEND(I).NE.JMAX) JINIT=0
67200      DO 500 J=JBEGIN(I),JEND(I)+JINIT
67300      H(I,J)=HGEN*SQRT(CGGEN/CG(I,J))*SQRT(COS(ANGGEN)/COS(THETA(I,
67400      *   J)))
67500      IF(HB(I,J).LT.H(I,J)) H(I,J)=HB(I,J)
67600      500 CONTINUE
67700      C*-----
67800      C*-----
67900      C*LET'S FILL THE DY ARRAY.
68000      C*DY WILL BE INDEXED AS THE THETA TO WHICH WE ARE GOING.
68100      DO 209 I=IBEGIN,IEND
68200      DO 209 J=JBEGIN(I)+1,JEND(I)
68300      DY(I,J-1)=0.5*(Y(I,J-1)+Y(I,J))-0.5*(Y(I,J)+Y(I,J+1))
68400      209 CONTINUE
68500      NITERS=100
68600      DO 100 NITER=1,NITERS
68700      SUMANG=0.0
68800      C*DO "60 LOOP" GOES FROM 2 TO IMAX IF ISTART =IBEGIN
68900      C*DO "60 LOOP" GOES FROM IMAX-1 TO 1 IF ISTART=IEND
69000      DO 60 II=IBEGIN,IEND
69100      C*MUST HAVE IT SET UP SO THAT THE KNOWN BOUNDARIES ANGLES AREN'T RECOMP
69200      IF(ISTART.EQ.IBEGIN) I=II
69300      IF(ISTART.EQ.IBEGIN .AND. I.EQ.IBEGIN) GO TO 60
69400      IF(ISTART.EQ.IEND) I=IEND-II+IBEGIN
69500      IF(ISTART.EQ.IEND .AND. I.EQ.IEND) GO TO 60
69600      C*ADX EQUALS ACTUAL DELTA X ACROSS SPACE STEP.
69700      C*ONLY ON BOUNDARIES WHERE FORWARD OR BACKWARD DIFFERENCING.
69800      IF(I.NE.IBEGIN) GO TO 6
69900      ADX=DX
70000      IP=I+1
70100      IM=I
70200      GO TO 12
70300      6 IF(I.NE.IEND) GO TO 10
70400      ADX=DX
70500      IP=I
70600      IM=I-1
70700      GO TO 12
70800      10 ADX=2.0*DX
70900      IP=I+1
71000      IM=I-1
71100      12 CONTINUE
71200      DO 40 J=JBEGIN(I),JEND(I)-1
71300      C*WILL GO FROM (JMAX-1) TO 1 BECAUSE THAT'S THE DIR WAVE COMES IN FROM.
71400      JJ=JEND(I)-1-J+JBEGIN(I)
71500      OLDANG(I,JJ)=THETA(I,JJ)
71600      C*LOCATE MIDPOINT BETWEEN TWO ADJACENT BLOCK CENTERS
71700      C*BECAUSE THETA'S JJ-VALUE IS THE SAME AS THE FIRST SHOREWARD Y VALUE
71800      C*MUST USE JJ, JJ+1, AND JJ+2 TO COMPUTE YBAR.
71900      YBAR=0.25*(Y(I,JJ)+2.0*Y(I,JJ+1)+Y(I,JJ+2))
72000      C*LOCATE APPROPRIATE INDICES ON IP AND IM GRID LINES.
72100      IMINUS=-1
72200      IPLUS=+1
72300      CALL LOC(IM,JJ,JOIM,JSIM,YBAR,IMINUS)
72400      CALL LOC(IP,JJ,JOIP,JSIP,YBAR,IPLUS)
72500      C*NOW USE THE CONSERVATION OF WAVES EQUATION.

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72600      PART1C=RK(I,JJ+1)*SIN(THETA(I,JJ+1))
72700      PART2=-DY(I,JJ)/ADX
72800      C*WILL LINEARLY INTERPOLATE TO DETERMINE RK*COS(THETA) AT I+1 AND I-1.
72900      C*IF NO ADJ SHOREWARD PT EXISTS, PUT IN ZERO FOR TERMS IN GOV. EQ.
73000      IF(JSIM.NE.O) GO TO 301
73100      PART3B=0.0
73200      GO TO 302
73300      301 TOPIM=RK(IM,JOIM-1)*COS(THETA(IM,JOIM-1))
73400      BOTIM=RK(IM,JSIM)*COS(THETA(IM,JSIM))
73500      TOTALB=0.5*(Y(IM,JOIM)+Y(IM,JOIM-1))-0.5*(Y(IM,JSIM+1)+Y(IM,JSIM))
73600      DUMB=0.5*(Y(IM,JOIM)+Y(IM,JOIM-1))-YBAR
73700      PART3B=((TOTALB-DUMB)*(TOPIM-BOTIM)/TOTALB)+BOTIM
73800      302 IF(JSIP.NE.O) GO TO 303
73900      PART3A=0.0
74000      GO TO 304
74100      303 TOPIP=RK(IP,JOIP-1)*COS(THETA(IP,JOIP-1))
74200      BOTIP=RK(IP,JSIP)*COS(THETA(IP,JSIP))
74300      TOTALA=0.5*(Y(IP,JOIP)+Y(IP,JOIP-1))-0.5*(Y(IP,JSIP+1)+Y(IP,JSIP))
74400      DUMA=0.5*(Y(IP,JOIP)+Y(IP,JOIP-1))-YBAR
74500      PART3A=((TOTALA-DUMA)*(TOPIP-BOTIP)/TOTALA)+BOTIP
74600      304 PART3=PART3A-PART3B
74700      C*NOW MUST FIND RK*SIN(THETA) FOR I+1 AND I-1 AT J+1
74800      YBARP=0.25*(Y(I,JJ+1)+2.*Y(I,JJ+2)+Y(I,JJ+3))
74900      CALL LOC(IM,JJ+1,JPOIM,JPSIM,YBARP,IMINUS)
75000      CALL LOC(IP,JJ+1,JPOIP,JPSIP,YBARP,IPLUS)
75100      IF(JPSIM.NE.O) GO TO 305
75200      PART1B=0.0
75300      GO TO 306
75400      305 TOPM=RK(IM,JPOIM-1)*SIN(THETA(IM,JPOIM-1))
75500      BOTM=RK(IM,JPSIM)*SIN(THETA(IM,JPSIM))
75600      TOTB=0.5*(Y(IM,JPOIM)+Y(IM,JPOIM-1))-0.5*(Y(IM,JPSIM+1)+
75700      * Y(IM,JPSIM))
75800      DUMPB=0.5*(Y(IM,JPOIM)+Y(IM,JPOIM-1))-YBARP
75900      PART1B=((TOTB-DUMPB)*(TOPM-BOTM)/TOTB)+BOTM
76000      306 IF(JPSIP.NE.O) GO TO 307
76100      PART1A=0.0
76200      GO TO 308
76300      307 TOPP=RK(IP,JPOIP-1)*SIN(THETA(IP,JPOIP-1))
76400      BOTP=RK(IP,JPSIP)*SIN(THETA(IP,JPSIP))
76500      TOTA=0.5*(Y(IP,JPOIP)+Y(IP,JPOIP-1))-0.5*(Y(IP,JPSIP+1)+Y(IP,JPSIP
76600      * ))
76700      DUMPA=0.5*(Y(IP,JPOIP)+Y(IP,JPOIP-1))-YBARP
76800      PART1A=((TOTA-DUMPA)*(TOPP-BOTP)/TOTA)+BOTP
76900      308 PART1=TAU*PART1B+(1.-2.*TAU)*PART1C+TAU*PART1A
77000      IF(JPSIM.EQ.O)PART1=(1.-TAU)*PART1C+TAU*PART1A
77100      IF(JPSIP.EQ.O)PART1=TAU*PART1B+(1.-TAU)*PART1C
77200      ARG=((PART1+PART2*PART3)/RK(I,JJ))
77300      C*IF THE ROUTINE IS TO BLOWUP,USE SNELLS LAW.
77400      IF(ABS(ARG).LE.1.O) GO TO 41
77500      ARG=(C(I,JJ)/C(I,JJ+1))*SIN(THETA(I,JJ+1))
77600      IF(ARG.GT.1.O) ARG=1.O
77700      THETA(I,JJ)=ARSIN(ARG)
77800      GO TO 42
77900      41 THETA(I,JJ)=ARSIN(ARG)
78000      42 THETA(I,JJ)=0.5*(THETA(I,JJ)+OLDANG(I,JJ))
78100      SUMANG=SUMANG+(ABS(THETA(I,JJ)-OLDANG(I,JJ)))
78200      40 CONTINUE
78300      60 CONTINUE
78400      C*MUST EJECT IF WE HAVE REACHED AN ACCEPTABLE ITERATION ERROR
78500      C*IF THE SUM OF THE ABSOLUTE VALUE OF ANGLE CHANGES DURING AN ITERATION
78600      C* AVERAGES LESS THAN 0.02 DEGREES PER GRID ITS CLOSE ENOUGH.
78700      IF(SUMANG.LT.(NPTS*0.0035)) GO TO 215
78800      IF(NITER.GE.50) GO TO 215
78900      100 CONTINUE
79000      WRITE(6,803)
79100      215 CONTINUE
79200      C*ITERATION LOOP FOR THE WAVE HEIGHT.
79300      DO 501 NITER=1,NITERS
79400      SUMH=0.0
79500      DO 510 II=IBEGIN,IEND
79600      C*MUST HAVE IT SET UP SO THAT THE KNOWN BOUNDARIES HTS. AREN'T RECOMP
79700      IF(ISTART.EQ.IBEGIN) I=II
79800      IF(ISTART.EQ.IBEGIN .AND. I.EQ.IBEGIN) GO TO 510

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79900      IF(ISTART.EQ.IEND)  I=IEND-II+IBEGIN
80000      IF(ISTART.EQ.IEND .AND. I.EQ.IEND)  GO TO 510
80100      C*ADX EQUALS ACTUAL DELTA X ACROSS SPACE STEP.
80200      C*ONLY ON BOUNDARIES WHERE FORWARD OR BACKWARD DIFFERENCING.
80300      IF(I.NE.IBEGIN)  GO TO 503
80400      ADX=DX
80500      IP=I+1
80600      IM=I
80700      GO TO 505
80800      503  IF(I.NE.IEND)  GO TO 504
80900      ADX=DX
81000      IP=I
81100      IM=I-1
81200      GO TO 505
81300      504  ADX=2.0*DX
81400      IP=I+1
81500      IM=I-1
81600      505  CONTINUE
81700      DO 502 J=JBEGIN(I),JEND(I)-1
81800      JJ=JEND(I)-1-J+JBEGIN(I)
81900      HOLD(I,JJ)=H(I,JJ)
82000      YBAR=0.25*(Y(I,JJ)+2.0*Y(I,JJ+1)+Y(I,JJ+2))
82100      CALL LOC(IM,JJ,JOIM,JSIM,YBAR,IMINUS)
82200      CALL LOC(IP,JJ,JOIP,JSIP,YBAR,IPLUS)
82300      PART13=(H(I,JJ+1)**2.)*CG(I,JJ+1)*COS(THETA(I,JJ+1))
82400      PART2=DY(I,JJ)/ADX
82500      IF(JSIM.NE.O)  GO TO 311
82600      PART4B=0.0
82700      GO TO 312
82800      311  TOPIMH=(H(IM,JOIM-1)**2.)*CG(IM,JOIM-1)*(SIN(THETA(IM,JOIM-1)))
82900      BOTIMH=(H(IM,JSIM)**2.)*CG(IM,JSIM)*SIN(THETA(IM,JSIM))
83000      TOTALB=0.5*(Y(IM,JOIM)+Y(IM,JOIM-1))-0.5*(Y(IM,JSIM+1)+Y(IM,JSIM))
83100      DUMB=0.5*(Y(IM,JOIM)+Y(IM,JOIM-1))-YBAR
83200      PART4B=((TOTALB-DUMB)*(TOPIMH-BOTIMH)/TOTALB)+BOTIMH
83300      312  IF(JSIP.NE.O)  GO TO 313
83400      PART4A=0.0
83500      GO TO 314
83600      313  TOPIPH=(H(IP,JOIP-1)**2.)*CG(IP,JOIP-1)*SIN(THETA(IP,JOIP-1))
83700      BOTIPH=(H(IP,JSIP)**2.)*CG(IP,JSIP)*SIN(THETA(IP,JSIP))
83800      TOTALA=0.5*(Y(IP,JOIP)+Y(IP,JOIP-1))-0.5*(Y(IP,JSIP+1)+Y(IP,JSIP))
83900      DUMA=0.5*(Y(IP,JOIP)+Y(IP,JOIP-1))-YBAR
84000      PART4A=((TOTALA-DUMA)*(TOPIPH-BOTIPH)/TOTALA)+BOTIPH
84100      314  PART4=PART4A-PART4B
84200      YBARP=0.25*(Y(I,JJ+1)+2.0*Y(I,JJ+2)+Y(I,JJ+3))
84300      CALL LOC(IM,JJ+1,JPOIM,JPSIM,YBARP,IMINUS)
84400      CALL LOC(IP,JJ+1,JPOIP,JPSIP,YBARP,IPLUS)
84500      IF(JPSIM.NE.O)  GO TO 315
84600      PART12=0.0
84700      GO TO 316
84800      315  TOPMH=(H(IM,JPOIM-1)**2)*CG(IM,JPOIM-1)*COS(THETA(IM,JPOIM-1))
84900      BOTMH=(H(IM,JPSIM)**2)*CG(IM,JPSIM)*COS(THETA(IM,JPSIM))
85000      TOTB= 5*(Y(IM,JPOIM)+Y(IM,JPOIM-1))- .5*(Y(IM,JPSIM+1)+Y(IM,JPSIM))
85100      DUMPB=0.5*(Y(IM,JPOIM)+Y(IM,JPOIM-1))-YBARP
85200      PART12=((TOTB-DUMPB)*(TOPMH-BOTMH)/TOTB)+BOTMH
85300      316  IF(JPSIP.NE.O)  GO TO 317
85400      PART11=0.0
85500      GO TO 318
85600      317  TOPPH=(H(IP,JPOIP-1)**2)*CG(IP,JPOIP-1)*COS(THETA(IP,JPOIP-1))
85700      BOTPH=(H(IP,JPSIP)**2)*CG(IP,JPSIP)*COS(THETA(IP,JPSIP))
85800      TOTA= .5*(Y(IP,JPOIP)+Y(IP,JPOIP-1))- .5*(Y(IP,JPSIP+1)+Y(IP,JPSIP))
85900      DUMPA=0.5*(Y(IP,JPOIP)+Y(IP,JPOIP-1))-YBARP
86000      PART11=((TOTA-DUMPA)*(TOPPH-BOTPH)/TOTA)+BOTPH
86100      318  PART1H=TAU*PART12+(1.-2.*TAU)*PART13+TAU*PART11
86200      IF(JPSIM.EQ.O)PART1H=(1.-TAU)*PART13+TAU*PART11
86300      IF(JPSIP.EQ.O)PART1H=TAU*PART12+(1.-TAU)*PART13
86400      ARG=((PART1H+PART2*PART4)/(CG(I,JJ)*COS(THETA(I,JJ))))
86500      C*IF THERE IS TO BE AN INVALID SQRT,USE LINEAR SHOALING.
86600      IF(ARG.GE.O.)  GO TO 44
86700      ARG=(CG(I,JJ+1)*COS(THETA(I,JJ+1)))/(CG(I,JJ)*COS(THETA(I,JJ)))
86800      IF(ARG.LT.O.O)  ARG=0.0
86900      H(I,JJ)=H(I,JJ+1)*SQRT(ARG)
87000      GO TO 45

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87100      44  H(I,JJ)=SQRT(ARG)
87200      45  H(I,JJ)=0.5*(H(I,JJ)+HOLD(I,JJ))
87300      HNONBR(JJ)=H(I,JJ)
87400  C*IBREAK(I)=JJ, THEREFORE JJ WILL BE LEEWARD SIDE OF GRID AT INIT BREAK
87500      IF(HB(I,JJ).LT.H(I,JJ).AND.HB(I,JJ+1).GE.HNONBR(JJ+1))
87600      *   IBREAK(I)=JJ
87700      IF(HB(I,JJ).LT.H(I,JJ)) H(I,JJ)=HB(I,JJ)
87800      SUMH=SUMH+ABS(H(I,JJ)-HOLD(I,JJ))
87900  502  CONTINUE
88000      510  CONTINUE
88100      IBREAK(IEND)=IBREAK(IEND-1)
88200      IBREAK(IBEGIN)=IBREAK(IBEGIN+1)
88300      IF(SUMH.LT.(NPTS*0.01)) GO TO 507
88400      IF(NITER.GE.50) GO TO 507
88500  501  CONTINUE
88600      WRITE(6,803)
88700  507  CONTINUE
88800  802  FORMAT(2X,4(F15.5),////)
88900  803  FORMAT(2X,"AFTER NITERS ITERATIONS, CONVERGENCE WAS NOT REACHED")
89000  804  FORMAT(2X,"THE WAVE HT. ROUTINE CONVERGED IN, NITER= ",I5,/)
89100  805  FORMAT(2X,"THIS IS MY CHECKING WRITE STATEMENT")
89200  806  FORMAT(2X,"THE WAVE ANGLE ROUTINE CONVERGED IN, NITER= ",I5,/)
89300      RETURN
89400      END
89500  C*****
89600      SUBROUTINE DIFF(RHOND,THETAO,ANGLE,AMP)
89700  C****DIFFRACTION ABOUT SEMI INFINITE BREAKWATER (PENNEY-PRICE)
89800      PI=3.14159265
89900      ABSS=SIN(0.5*(ANGLE-THETAO))
90000      ABSP=SIN(0.5*(ANGLE+THETAO))
90100      ABC=COS(ANGLE-THETAO)
90200      ABC1=COS(ANGLE+THETAO)
90300      XX=RHOND*ABC
90400      XXC=COS(XX)
90500      XXS=SIN(XX)
90600      XX1=RHOND*ABC1
90700      XXC1=COS(XX1)
90800      XXS1=SIN(XX1)
90900      AL=SQRT(RHOND/PI)
91000      SIG=2.0*AL*ABSS
91100      SIGP=-2.0*AL*ABSP
91200      CALL FRES(SIG,C,S,FR,FI)
91300      CALL FRES(SIGP,CP,SP,FRP,FIP)
91400      SUM1=XXC*FR+XXS*FI+XXC1*FRP+XXS1*FIP
91500      SUM2=XXC*FI-XXS*FR+XXC1*FIP-XXS1*FRP
91600      AMP=SQRT(SUM1**2+SUM2**2)
91700      RETURN
91800      END
91900  C*****
92000      SUBROUTINE FRES(A,C,S,FR,FI)
92100  C*FRESNEL INTEGRAL SUBROUTINE****AFTER ABROMOWITZ AND STEGUN.
92200      Z=ABS(A)
92300      P02=1.5707963
92400      FZ=(1.0+0.926*Z)/(2.0+1.792*Z+3.104*Z**2)
92500      GZ=1.0/(2.0+4.142*Z+3.492*Z**2+6.670*Z**3)
92600      XX=P02*Z**2
92700      CZ=COS(XX)
92800      SZ=SIN(XX)
92900      C=0.5-GZ*CZ+FZ*SZ
93000      S=0.5-FZ*CZ-GZ*SZ
93100      IF(A.GT.0.0) GO TO 50
93200      C=-C
93300      S=-S
93400  50  FR=0.5*(1.0+C+S)
93500      FI=-0.5*(S-C)
93600      RETURN
93700      END
93800  C*****
93900      SUBROUTINE PREDIF
94000  COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
94100  COMMON/AA/YZERO(60)
94200  COMMON/B/ THETA(60,20),QXTOT(60),OLDANG(60,20),DY(60,20)
94300  COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)

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94400      COMMON/N USED/JUSE,T.CO,CGEN,CGGEN,ANGGEN,DX,BERM,THETAO(10),MMAX
94500      COMMON/D/SIGMA,G,ELO,JMAX,IMAX,PI,TWOPI,PIO2,HGEN,IJET(10),SJETTY
94600      COMMON/G/IBREAK(60),HNONBR(20)
94700      DIMENSION J1(60),J2(60),J1REF(60),J3REF(60)
94800      C*THIS SUB CALCS WHERE DIFFRACTION GOVERNS AND WHERE REFRACT GOVERNS.
94900      C*IT WILL CALL REFRAC FOR OFFSHORE AREA(OFF TIP OF STRUCTURE).
95000      C*THEN IT WILL DO THE SHADOW ZONE USING DIFF(IF THETAO .NE.0.0)
95100      C* IT WILL THEN FINISH THE OTHERS USING REFRACT AGAIN.
95200      C*LET'S ZERO-OUT THE DIMENSIONED ARRAYS.
95300          DO 1000 I=1,IMAX+2
95400              J1(I)=0.0
95500              J2(I)=0.0
95600              J1REF(I)=0.0
95700          1000 J3REF(I)=0.0
95800      C*NOW, LETS FIND C,CG,RK,HB, AND WVNUM.
95900          DO 202 I=1,IMAX
96000              DO 202 J=1,JMAX+2
96100                  DEPTH=DEEP(I,J)
96200                  CALL WVNUM(DEPTH,T,DUMK)
96300                  RK(I,J)=DUMK
96400                  C(I,J)=CO*TANH(RK(I,J)*DEEP(I,J))
96500                  EN=0.5*(1.0+((2.*RK(I,J)*DEEP(I,J))/SINH(2.*RK(I,J)*DEEP(I,J))))
96600                  CG(I,J)=EN*C(I,J)
96700                  HB(I,J)=0.78*DEEP(I,J)
96800          202 CONTINUE
96900      C*WILL ATTRIB AN EQUAL REACH TO EACH SIDE OF EACH M-GROIN.
97000          DO 200 M=1,MMAX
97100              IDUML=1
97200              IF(M.NE.1) IDUML=(IJET(M)+IJET(M-1))/2
97300              IDUMR=IMAX
97400              IF(M.NE.MMAX) IDUMR=(IJET(M)+IJET(M+1))/2
97500              NPTS=0
97600              DO 1 I=IDUML,IDUMR
97700                  DO 2 J=1,JMAX
97800                      IF(Y(I,J).LT.SJETTY) GO TO 14
97900                      J1(I)=J
98000                      J2(I)=JMAX
98100                      GO TO 15
98200          14 CONTINUE
98300          2 CONTINUE
98400          15 CONTINUE
98500      C*IF NO STRUCT IS PRESENT(SJETTY=0.0), DO REFRAC THRUOUT GRID SYSTEM
98600          IF(SJETTY.EQ.0.0) J1(I)=1
98700          1 CONTINUE
98800          DO 16 I=IDUML,IDUMR
98900      C* 'REFRACT' STARTS ON THE NEXT TO LAST J-CONTOUR,NOT THE LAST!
99000          DO 16 J=J1(I),J2(I)-1
99100          16 NPTS=NPTS+1
99200      C*WILL NOW DO THE REFRACT FOR THE REGION 1 AREA.
99300      C*ISTART REPRESENTS THE DIRECTION THE SWEEPS WILL BEGIN FROM
99400      C*WILL USE DUMMY IMAX,IJET,IJET+1 IN CALL STTS SO IBEGIN,IEND, AND
99500      C***ISTART WON'T CHANGE THEM MUST RESET AFTER EACH CALL REFRAC
99600          IMAX=IDUMR
99700          IJET=IJET(M)
99800          IJETP1=IJET(M)+1
99900          IDUMLL=IDUML
100000      IF(ANGGEN.GE.0.0) CALL REFRAC(J1,J2,NPTS,IDUMLL,IMAX,IDUMLL,M)
100100      IF(ANGGEN.LT.0.0) CALL REFRAC(J1,J2,NPTS,IDUMLL,IMAX,IMAX,M)
100200          IMAX=IDUMR
100300          IJET=IJET(M)
100400          IJETP1=IJET(M)+1
100500          IDUMLL=IDUML
100600          JDUMN=J1(IJET(M))
100700          JDUMS=J1(IJET(M)+1)
100800          XDISTN=(IJET(M)-1.0)*DX+DX/2.
100900          ELTIP=T*0.5*(C(IJET(M),JDUMN)+C(IJET(M)+1,JDUMS))
101000      C*NOW MUST CHECK THE ANGLE AT THE STRUCTURE'S TIP TO SEE WHERE SHAD ZONE
101100      C*IF NO STRUCT PRESENT(SJETTY=0.0), FUTHER REFRAC/DIFF UNNECESSARY
101200          IF(SJETTY.EQ.0.0) GO TO 13
101300          THETAO(M)=0.5*(THETA(IJET(M),JDUMN)+THETA(IJET(M)+1,JDUMS))
101400          HINC=0.5*(H(IJET(M),JDUMN)+H(IJET(M)+1,JDUMS))
101500          IF(THETAO(M))10,11,12
101600      C*THIS SECTION HANDLES REFRAC/DIFF IF THETAO<0.0

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101700      10 CONTINUE
101800      C*FIRST ALL OF REGION 2 WILL GET REFRACTED.
101900          NPTS=0
102000          DO 100 I=IJET(M)+1, IDUMR
102100              J2(I)=J1(I)
102200          100 J1(I)=1
102300              DO 101 I=IJET(M)+1, IDUMR
102400                  DO 101 J=J1(I), J2(I)-1
102500          101 NPTS=NPTS+1
102600              IMAXT=IDUMR
102700              IDUMLL=IDUML
102800              IJETT=IJET(M)
102900              IJETP1=IJET(M)+1
103000              CALL REFRAC(J1, J2, NPTS, IJETP1, IMAXT, IMAXT, M)
103100              IMAXT=IDUMR
103200              IJETT=IJET(M)
103300              IJETP1=IJET(M)+1
103400              IDUMLL=IDUML
103500      C*NOW MUST DO REGION 3 OF NEG THETA0 CASE-SHADOW ZONE.
103600          DO 102 I=IDUML, IJET(M)
103700              J2(I)=J1(I)
103800          102 J1(I)=1
103900              DO 103 I=IDUML, IJET(M)
104000                  J1REF(I)=1
104100                  DO 104 J=J1(I), J2(I)+1
104200                      XCOORD=(I-1.0)*DX
104300                      YCOORD=0.5*(Y(I, J)+Y(I, J+1))
104400                      ANGLE=ATAN((XDISTN-XCOORD)/(SJETTY-YCOORD))
104500                      IF(YCOORD.GT.SJETTY) ANGLE=PI+ANGLE
104600      C*IF MOST SHOREWARD PT OUT OF SHAD ZONE, SO ARE THE OTHERS FOR THAT I.
104700                      IF(ABS(ANGLE).GT.ABS(THETA0(M))) GO TO 105
104800                      RAD=SQRT((XDISTN-XCOORD)**2+(SJETTY-YCOORD)**2)
104900                      RHOND=RAD*TWOPI/ELTIP
105000      C*DIFFRACTION TREATS THE POS THETA0 CASE.
105100                      THE=ABS(THETA0(M))
105200                      CALL DIFF(RHOND, THE, ANGLE, AMP)
105300                      H(I, J)=AMP*HINC
105400                      ANGRAD=-ANGLE
105500      C*WILL NOW REFRACT DIFF WAVES IN THE SHAD ZONE USING SNELL'S.
105600                      CTIP=ELTIP/T
105700                      ALPHAS(I, J)=ATAN((0.5*(Y(I+1, J)+Y(I+1, J+1))-0.5*
105800                      * (Y(I-1, J)+Y(I-1, J+1)))/(2.*DX))
105900                      IF(I EQ. IJET(M))ALPHAS(I, J)=ATAN((0.5*(Y(I, J)+Y(I, J+1))-0.5*(Y(I-1
106000                      * (Y(I-1, J)+Y(I-1, J+1)))/DX)
106100                      DALPHA=ANGRAD-ALPHAS(I, J)
106200                      THETA(I, J)=ARSIN((C(I, J)/CTIP)*SIN(DALPHA))
106300                      THETA(I, J)=THETA(I, J)+ALPHAS(I, J)
106400      C*MUST CHECK TO SEE IF WAVE WOULD HAVE BROKEN.
106500                      IF(HB(I, J) LE H(I, J) AND HB(I, J+1).GT.H(I, J+1))IBREAK(I)=J
106600                      IF(HB(I, J) LT H(I, J)) H(I, J)=HB(I, J)
106700          104 CONTINUE
106800              GO TO 103
106900          105 J1REF(I)=J
107000          103 CONTINUE
107100      C*NOW MUST DO REFRACTION FOR REGION 4.
107200          NPTS=0
107300          DO 106 I=IDUML, IJET(M)
107400              DO 106 J=J1REF(I), J2(I)-1
107500          106 NPTS=NPTS+1
107600              IDUMLL=IDUML
107700              IMAXT=IDUMR
107800              IJETT=IJET(M)
107900              IJETP1=IJET(M)+1
108000              CALL REFRAC(J1REF, J2, NPTS, IDUMLL, IJETT, IDUMLL, M)
108100              IDUMLL=IDUML
108200              IMAXT=IDUMR
108300              IJETT=IJET(M)
108400              IJETP1=IJET(M)+1
108500              GO TO 13
108600      C*THIS HANDLES REFRAC/DIFF IF THETA0 IS 0.0.
108700      C*FOR THIS CASE, ONLY THREE REGIONS EXIST
108800          11 CONTINUE
108900          NPTS=0

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109000      DO 120 I=IDUML,IJET(M)
109100          J2(I)=J1(I)
109200      120 J1(I)=1
109300          DO 121 I=IDUML,IJET(M)
109400          DO 121 J=J1(I),J2(I) 1
109500      121 NPTS=NPTS+1
109600          IMAXT=IDUMR
109700          IDUMLL=IDUML
109800          IJETT=IJET(M)
109900          IJETP1=IJET(M)+1
110000          CALL REFRAC(J1,J2,NPTS,IDUMLL,IJETT,IDUMLL,M)
110100          IMAXT=IDUMR
110200          IJETT=IJET(M)
110300          IJETP1=IJET(M)+1
110400          IDUMLL=IDUML
110500          DO 122 I=IJET(M)+1, IDUMR
110600          J2(I)=J1(I)
110700      122 J1(I)=1
110800          NPTS=0
110900          DO 123 I=IJET(M)+1, IDUMR
111000          DO 123 J=J1(I),J2(I)-1
111100      123 NPTS=NPTS+1
111200          IMAXT=IDUMR
111300          IDUMLL=IDUML
111400          IJETT=IJET(M)
111500          IJETP1=IJET(M)+1
111600          CALL REFRAC(J1,J2,NPTS,IJETP1,IMAXT,IMAXT,M)
111700          IMAXT=IDUMR
111800          IJETT=IJET(M)
111900          IJETP1=IJET(M)+1
112000          IDUMLL=IDUML
112100          GO TO 13
112200      C*THIS SECTION HANDLES REFRACT/DIFF IF THETA0>0.0
112300          12 CONTINUE
112400      C*FIRST, REGION 2- ALL REFRACTION.
112500          NPTS=0
112600          DO 110 I=IDUML,IJET(M)
112700          J2(I)=J1(I)
112800      110 J1(I)=1
112900          DO 111 I=IDUML,IJET(M)
113000          DO 111 J=J1(I),J2(I)-1
113100      111 NPTS=NPTS+1
113200          IMAXT=IDUMR
113300          IDUMLL=IDUML
113400          IJETT=IJET(M)
113500          IJETP1=IJET(M)+1
113600          CALL REFRAC(J1,J2,NPTS,IDUMLL,IJETT,IDUMLL,M)
113700          IMAXT=IDUMR
113800          IJETT=IJET(M)
113900          IJETP1=IJET(M)+1
114000          IDUMLL=IDUML
114100      C*NOW WILL DO REGION 3 OF THE POS THETA0 CASE.
114200          DO 112 I=IJET(M)+1, IDUMR
114300          J2(I)=J1(I)
114400      112 J1(I)=1
114500          DO 113 I=IJET(M)+1, IDUMR
114600          J1REF(I)=1
114700      C*WILL GO ONE PT. BEYOND J2(I) TO MAKE SURE OUTOF DIFF ZONE.
114800          DO 114 J=J1(I),J2(I)+1
114900          XCOORD=(I-1.0)*DX
115000          YCOORD=0.5*(Y(I,J)+Y(I,J+1))
115100          ANGLE=ATAN((XCOORD-XDISTN)/(SJETTY-YCOORD))
115200          IF(YCOORD.GT.SJETTY) ANGLE=PI+ANGLE
115300      C*IF LEAST J-VALUE IS OUT OF SHAD ZONE,SO ARE OTHER J'S (FOR EACH I)
115400          IF(ANGLE.GT.ABS(THETA0(M))) GO TO 115
115500          RAD=SQRT((XCOORD-XDISTN)**2+(SJETTY-YCOORD)**2)
115600          RHOND=RAD*TWOPI/ELTIP
115700          THE=THETA0(M)
115800          CALL DIFF(RHOND,THE,ANGLE,AMP)
115900          ANGRAD=ANGLE
116000      C*WILL NOW REFRACT DIFFRACTED WAVES IN SHAD ZONE USING SNELL'S
116100          CTIP=ELTIP/T
116200          ALPHAS(I,J)=ATAN((0.5*(Y(I+1,J)+Y(I+1,J+1)))-0.5*

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116300      * (Y(I-1,J)+Y(I-1,J+1)))/(2 *DX)
116400      IF(I EQ IJET(M)+1)ALPHAS(I,J)=ATAN((0.5*(Y(I-1,J)+Y(I-1,J+1)) - 5*
116500      * (Y(I,J)+Y(I,J+1)))/DX)
116600      DALPHA=ANGRAD-ALPHAS(I,J)
116700      THETA(I,J)=ARSIN((C(I,J)/CTIP)*SIN(DALPHA))
116800      THETA(I,J)=THETA(I,J)+ALPHAS(I,J)
116900      H(I,J)=HINC*AMP
117000      C*MUST CHECK TO SEE IF WAVE WOULD HAVE BROKEN
117100      IF(HB(I,J) LE H(I,J) AND HB(I,J+1) GT H(I,J+1))BREAK(1)
117200      IF(HB(I,J) LT H(I,J)) H(I,J)=HB(I,J)
117300      114 CONTINUE
117400      GO TO 113
117500      115 JIREF(I)=J
117600      113 CONTINUE
117700      C*NOW MUST DO REFRAC FOR REGION 4
117800      NPTS=0
117900      DO 116 I=IJET(M)+1, IDUMR
118000      DO 116 J=JIREF(I), J2(I)+1
118100      116 NPTS=NPTS+1
118200      IMAXT=IDUMR
118300      IDUMLL=IDUML
118400      IJETT=IJET(M)
118500      IJETP1=IJET(M)+1
118600      CALL REFRAC(JIREF, J2, NPTS, IJETP1, IMAXT, IMAXT, M)
118700      IMAXT=IDUMR
118800      IJETT=IJET(M)
118900      IJETP1=IJET(M)+1
119000      IDUMLL=IDUML
119100      13 CONTINUE
119200      200 CONTINUE
119300      RETURN
119400      END
119500      C*.....
119600      SUBROUTINE LOC(IM, J0, JOIM, JSIM, YBAR, IDUM)
119700      COMMON/A/ C(60,20), RK(60,20), Y(60,20), DEEP(60,20), ALPHAS(60,20)
119800      COMMON/AA/ YZERO(60)
119900      COMMON/B/ THETA(60,20), Q*TD(60), OLDANG(60,20), D*(60,20)
120000      COMMON/C/ H(60,20), CG(60,20), HOLD(60,20), HB(60,20), YB(60)
120100      COMMON/N USED/ JUSE, T, CO, CGEN, CGGEN, ANGEN, DX, BERM, THETA0(10), MMA*
120200      COMMON/D/ SIGMA, G, ELO, JMAX, IMAX, PI, TWOPI, PIO2, HGEN, IJET(10), SLE(1)
120300      C*SUBROUTINE LOC FINDS J-VALUES WHICH ARE GREATER AND LESS THAN YBAR
120400      JOIM=2
120500      2 AA=0.5*(Y(IM, JOIM)+Y(IM, JOIM-1))
120600      IF(AA GT YBAR) GO TO 4
120700      JOIM=JOIM+1
120800      C*THE FOLLOWING IS REQ'D SO THAT DY/DX<0.5
120900      C*WILL DTERMINE K SIN THETA ON IM-LINE AT A DIST YBAR
121000      C*WILL CALL THIS POINT JUSE+1
121100      IF(JOIM LE JUSE) GO TO 2
121200      JOIM=JUSE+1
121300      Y(IM, JOIM)=YBAR
121400      C* DEPTH AT THIS POINT WILL BE COMP ASSUMING CONST BEACH SLOPE ON I=IM
121500      DEL= .5*(Y(IM, JOIM-1)+Y(IM, JOIM-2)) - .5*(Y(IM, JOIM-2)+Y(IM, JOIM-3))
121600      BSLOPE=(DEEP(IM, JOIM-2)-DEEP(IM, JOIM-3))/DEL
121700      DEEP(IM, JOIM-1)=DEEP(IM, JOIM-2)+BSLOPE*(Y(IM, JOIM)-Y(IM, JOIM-1))
121800      DEPTH=DEEP(IM, JOIM-1)
121900      CALL WVNUM(DEPTH, T, DUMK)
122000      RK(IM, JOIM-1)=DUMK
122100      C(IM, JOIM-1)=CO*TANH(RK(IM, JOIM-1)*DEEP(IM, JOIM-1))
122200      EN=0.5*(1.0+((2.0*RK(IM, JOIM-1)*DEEP(IM, JOIM-1))/SINH(
122300      * 2.0*RK(IM, JOIM-1)*DEEP(IM, JOIM-1))))
122400      CG(IM, JOIM-1)=C(IM, JOIM-1)*EN
122500      C*WILL USE SNELL'S LAW TO DETERMINE THE WAVE ANGLE HERE
122600      C*ANGLE OF CONTOUR WILL BE ASSUME TO BE THE SAME AS THE JMAX+1 CONTOUR
122700      IF(IDUM EQ 1)ALPH=ATAN((Y(IM, JOIM-1)-Y(IM-1, JOIM-1))/DX)
122800      IF(IDUM EQ -1)ALPH=ATAN(((Y(IM+1, JOIM-1)-Y(IM, JOIM-1))/DX)
122900      DALPHA=ANGGEN-ALPH
123000      THETA(IM, JOIM-1)=ARSIN((C(IM, JOIM-1)/CGEN)*SIN(DALPHA))
123100      THETA(IM, JOIM-1)=THETA(IM, JOIM-1)+ALPH
123200      4 JSIM=JMAX-1
123300      6 AA=0.5*(Y(IM, JSIM)+(Y(IM, JSIM+1)))
123400      IF(AA LT YBAR) GO TO 8
123500      JSIM=JSIM-1

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123600 C*IF JSIM=0, THERE IS NO ADJ PT. SUB REFRAC CAN HANDLE IT
123700 IF(JSIM.EQ.0) GO TO 8
123800 GO TO 6
123900 8 RETURN
124000 END
124100 C*****
124200 SUBROUTINE WVNUM(DEPTH,T,RK)
124300 G=32.17
124400 EPS=0.001
124500 TWOPI=6.283185307
124600 SIGMA=TWOPI/T
124700 RK=TWOPI/(T*SQRT(G*DEPTH))
124800 DO 100 IT=1,20
124900 ARG=RK*DEPTH
125000 EK=(G*RK*TANH(ARG))-(SIGMA**2)
125100 EKPR=G*(ARG*((SECH(ARG)**2)+TANH(ARG)))
125200 RKNEW=RK-EK/EKPR
125300 IF(ABS(RKNEW-RK).LE.ABS(EPS*RKNEW)) GO TO 120
125400 RK=RKNEW
125500 100 CONTINUE
125600 WRITE(6,1000) IT,DEPTH,RK
125700 1000 FORMAT(///,10X,"ITERATION FOR K FAILED TO CONVERGE AFTER"
125800 * ,3X,13,"ITERATION",/, "OUTPUT: DEPTH, RK",3X,2F13.5)
125900 CALL EXIT
126000 120 RK=RKNEW
126100 IF(RK.GT.0.0) GO TO 140
126200 WRITE(6,1020) DEPTH,RK
126300 1020 FORMAT(///,10X," RK IS NEG",/, " OUTPUT: DEPTH, RK",3X,2F13.5)
126400 CALL EXIT
126500 140 RETURN
126600 END
126700 C*****
126800 SUBROUTINE SMOOTH(THETA,IMAX,JMAX,IJET,SJETTY,MMAX,Y)
126900 C*THIS WILL SMOOTH THE WAVE ANGLE FIELD TO ACCT FOR DIFF(ARTIFICIALLY)
127000 DIMENSION TEMP(60,20),Y(60,20),THETA(60,20),IJET(10)
127100 C*(MMAX+1) IS REQ'D BECAUSE M-GROINS HAVE M+1 REACHES OF SHORELINE
127200 DO 10 M=1,MMAX+1
127300 IF(M.NE.1) GO TO 3
127400 ILEFT=2
127500 IRIGHT=IJET(1)
127600 GO TO 5
127700 3 IF(M.NE.MMAX+1) GO TO 4
127800 ILEFT=IJET(MMAX)+1
127900 IRIGHT=IMAX-1
128000 GO TO 5
128100 4 ILEFT=IJET(M-1)+1
128200 IRIGHT=IJET(M)
128300 5 CONTINUE
128400 DO 1 J=1,JMAX-1
128500 DO 1 I=ILEFT,IRIGHT
128600 IF(I.NE.ILEFT AND I.NE.IRIGHT) GO TO 15
128700 C*TO GET HERE, MUST BE ON BOUN OR ADJ TO A STRUCTURE
128800 IF(I.EQ.2.OR.I.EQ.IMAX-1) GO TO 15
128900 C*TO GET HERE,ADJ TO A STRUCT AND CAN BE ILEFT OR IRIGHT
129000 IF(Y(I,J) GE. SJETTY) GO TO 15
129100 C*IF HERE, WITHIN JETTY AND ADJ TO EITHER SIDE
129200 IF(I.EQ.ILEFT)TEMP(I,J)=0.5*(THETA(I,J)+THETA(I+1,J))
129300 IF(I.EQ.IRIGHT)TEMP(I,J)=0.5*(THETA(I,J)+THETA(I-1,J))
129400 GO TO 1
129500 15 TEMP(I,J)=0.25*THETA(I-1,J)+0.50*THETA(I,J)+0.25*THETA(I+1,J)
129600 1 CONTINUE
129700 10 CONTINUE
129800 DO 2 J=1,JMAX-1
129900 DO 2 I=2,IMAX-1
130000 2 THETA(I,J)=TEMP(I,J)
130100 RETURN
130200 END
130300 C*****
130400 FUNCTION SECH(A)
130500 SECH=1/O/COSH(A)
130600 RETURN
130700 END
130800 C***HERE IS WHERE THE IMSL ROUTINES MUST GO!

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## APPENDIX C

### CONTOURS AND SCHEMATIC ILLUSTRATIONS

This appendix presents tables of the original contours at Oregon Inlet and the final contours for the eight numerical simulations (Tables C-1 to C-9). Also included are schematic illustrations of sediment volumes transported from the nourished region (Figs. C-1 to C-8).

Table C-1. Initial bathymetry for all simulations (prior to any sediment addition).

I=	Increasing I →										J=	
	220.000	200.000	200.000	220.000	220.000	210.000	200.000	220.000	200.000	200.000		170.000
180.000	180.000	160.000	160.000	160.000	190.000	190.000	180.000	180.000	180.000	210.000	220.000	230.000
220.000	200.000	160.000	160.000	160.000	170.000	170.000	170.000	180.000	180.000	210.000	220.000	220.000
230.000	200.000	200.000	200.000	200.000	200.000	200.000	200.000	200.000	200.000	210.000	200.000	
251.623	231.623	231.623	231.623	251.623	241.623	231.623	231.623	251.623	231.623	231.623	201.623	221.623
211.623	211.623	191.623	191.623	221.623	221.623	221.623	211.623	221.623	241.623	241.623	251.623	261.623
251.623	231.623	191.623	191.623	191.623	201.623	201.623	201.623	211.623	211.623	241.623	241.623	251.623
281.623	281.623	251.623	231.623	231.623	231.623	231.623	231.623	231.623	231.623	241.623	231.623	
309.443	289.443	289.443	289.443	309.443	309.443	289.443	289.443	309.443	289.443	289.443	259.443	279.443
269.443	269.443	249.443	249.443	279.443	279.443	279.443	269.443	279.443	299.443	299.443	309.443	319.443
309.443	289.443	249.443	249.443	249.443	259.443	259.443	259.443	269.443	269.443	299.443	309.443	309.443
319.443	339.443	309.443	289.443	289.443	289.443	289.443	289.443	289.443	289.443	289.443	289.443	
442.028	422.028	422.028	422.028	442.028	432.028	422.028	422.028	442.028	422.028	422.028	392.028	412.028
402.028	402.028	382.028	382.028	382.028	412.028	412.028	402.028	412.028	432.028	432.028	442.028	452.028
442.028	422.028	382.028	382.028	382.028	392.028	392.028	392.028	402.028	402.028	432.028	442.028	442.028
452.028	472.028	442.028	422.028	422.028	422.028	422.028	422.028	422.028	422.028	432.028	422.028	
684.758	664.758	664.758	664.758	684.758	684.758	664.758	664.758	684.758	664.758	664.758	634.758	654.758
644.758	644.758	624.758	624.758	624.758	654.758	654.758	644.758	654.758	674.758	674.758	684.758	694.758
684.758	664.758	624.758	624.758	624.758	634.758	634.758	634.758	644.758	644.758	674.758	684.758	684.758
684.758	714.758	684.758	664.758	664.758	664.758	664.758	664.758	664.758	664.758	674.758	664.758	
980.726	960.726	960.726	960.726	980.726	970.726	960.726	960.726	980.726	960.726	960.726	930.726	950.726
940.726	940.726	920.726	920.726	920.726	950.726	950.726	940.726	950.726	970.726	970.726	980.726	990.726
980.726	960.726	920.726	920.726	920.726	930.726	930.726	930.726	940.726	940.726	970.726	980.726	980.726
980.726	1010.726	980.726	960.726	960.726	960.726	960.726	960.726	960.726	960.726	970.726	960.726	
1270.414	1250.414	1210.414	1210.414	1250.414	1270.414	1270.414	1270.414	1270.414	1250.414	1250.414	1220.414	1240.414
1230.414	1230.414	1210.414	1210.414	1210.414	1240.414	1240.414	1240.414	1240.414	1230.414	1260.414	1270.414	1280.414
1270.414	1250.414	1210.414	1210.414	1210.414	1220.414	1220.414	1220.414	1230.414	1230.414	1260.414	1270.414	1280.414
1280.414	1300.414	1270.414	1250.414	1250.414	1250.414	1250.414	1250.414	1250.414	1250.414	1260.414	1250.414	
1702.228	1682.228	1682.228	1682.228	1702.228	1692.228	1682.228	1682.228	1702.228	1682.228	1682.228	1652.228	1672.228
1662.228	1662.228	1642.228	1642.228	1642.228	1672.228	1672.228	1672.228	1672.228	1672.228	1692.228	1702.228	1712.228
1702.228	1682.228	1642.228	1642.228	1642.228	1652.228	1652.228	1652.228	1652.228	1652.228	1692.228	1702.228	1712.228
1712.228	1732.228	1702.228	1682.228	1682.228	1682.228	1682.228	1682.228	1682.228	1682.228	1682.228	1682.228	

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Table C-2. Final contours, case 2.a.

THE NEW CONTOUR VALUES, V, FOLLOW													
220.000	219.421	218.883	218.266	217.691	217.119	216.550	215.985	215.425	214.871	214.322	213.779	213.240	
212.716	212.197	211.687	211.186	210.694	210.213	209.748	209.285	208.836	208.390	207.969	207.551	207.148	
206.740	206.302	205.987	205.621	205.266	204.922	204.588	204.264	203.950	203.645	203.348	203.060	202.779	
202.566	202.239	201.977	201.721	201.468	201.218	200.972	200.727	200.484	200.241	200.000			
251.623	251.018	250.439	249.873	249.297	248.719	248.161	247.616	247.058	246.491	245.948	245.440	244.937	
244.407	243.855	243.322	242.835	242.375	241.895	241.375	240.839	240.338	239.914	239.561	239.230	238.871	
238.468	238.053	237.664	237.308	236.968	236.619	236.253	235.884	235.535	235.209	234.908	234.651	234.431	
234.201	233.932	233.643	233.364	233.098	232.837	232.584	232.344	232.109	231.868	231.623			
302.443	302.134	301.834	301.567	301.314	301.069	300.823	300.584	300.344	300.104	299.862	299.625	299.382	302.038
302.300	301.732	301.197	300.731	300.295	299.811	299.261	298.768	298.229	297.838	297.504	297.175	296.810	
296.400	295.978	295.589	295.240	294.904	294.542	294.147	293.753	293.398	293.079	292.788	292.546	292.340	
292.114	291.835	291.534	291.249	290.977	290.707	290.447	290.201	289.956	289.703	289.443			
442.028	441.361	440.894	440.328	439.755	439.204	438.648	438.095	437.549	437.008	436.473	435.945	435.424	
434.911	434.407	433.912	433.427	432.950	432.482	432.020	431.564	431.112	430.667	430.231	429.810	429.404	
429.014	428.600	428.276	427.920	427.569	427.223	426.879	426.540	426.206	425.879	425.562	425.259	424.970	
424.696	424.433	424.178	423.925	423.669	423.406	423.136	422.864	422.587	422.307	422.028			
664.758	664.191	663.625	663.064	662.509	661.961	661.420	660.885	660.354	679.827	679.301	678.777	678.254	
677.735	677.220	676.713	676.215	675.730	675.259	674.803	674.361	673.933	673.518	673.116	672.725	672.340	
671.969	671.596	671.221	670.842	670.462	670.081	669.706	669.340	668.990	668.658	668.347	668.057	667.786	
667.570	667.203	667.037	666.786	666.525	666.252	665.986	665.671	665.370	665.161	664.758			
984.726	980.133	979.544	978.962	978.392	977.832	977.284	976.746	976.214	975.687	975.161	974.633	974.104	
973.574	973.043	972.516	971.997	971.489	970.997	970.525	970.076	969.651	969.248	968.865	968.497	968.137	
967.779	967.417	967.047	966.667	966.278	965.867	965.500	965.125	964.769	964.438	964.135	963.859	963.606	
963.379	963.142	962.915	962.681	962.437	962.178	961.906	961.622	961.328	961.028	960.726			
1270.414	1269.804	1269.194	1268.584	1267.985	1267.385	1266.792	1266.204	1265.622	1265.047	1264.479	1263.918	1263.365	
1262.798	1262.284	1261.758	1261.243	1260.744	1260.248	1259.770	1259.306	1258.855	1258.414	1257.995	1257.585	1257.187	
1256.402	1256.427	1256.063	1255.708	1255.363	1255.029	1254.705	1254.391	1254.089	1253.798	1253.519	1253.250	1252.990	
1252.739	1252.495	1252.256	1252.020	1251.788	1251.557	1251.328	1251.099	1250.870	1250.642	1250.414			
1702.228	1701.595	1700.963	1700.333	1699.706	1699.083	1698.464	1697.852	1697.246	1696.647	1696.057	1695.475	1694.904	
1694.342	1693.792	1693.253	1692.728	1692.212	1691.711	1691.225	1690.748	1690.287	1689.840	1689.407	1688.988	1688.584	
1686.193	1687.816	1687.454	1687.104	1686.768	1686.446	1686.130	1685.834	1685.552	1685.277	1685.014	1684.760	1684.515	
1684.279	1684.052	1683.831	1683.617	1683.408	1683.204	1683.004	1682.807	1682.613	1682.420	1682.228			



Table C-3. Final contours, case 3.b.

TIME NEW CONTOUR VALUES, Y, FOLLOW												
226.888	217.435	218.880	218.321	217.765	217.210	216.654	216.112	215.568	215.024	214.495	213.967	213.448
218.931	212.428	211.925	211.434	210.922	210.479	210.016	209.561	209.115	208.680	208.254	207.837	207.430
207.932	206.493	205.263	205.533	205.102	204.640	204.508	204.508	204.114	203.868	203.561	203.260	202.966
202.677	202.328	202.118	201.842	201.571	201.304	201.040	200.778	200.518	200.259	200.000		
251.623	251.065	250.508	249.954	249.401	248.850	248.302	247.757	247.216	246.679	246.148	245.621	245.101
248.588	248.082	247.584	247.095	246.615	246.144	245.683	245.231	244.789	244.355	243.930	243.514	243.107
248.288	248.317	248.336	248.353	248.369	248.384	248.399	248.414	248.429	248.444	248.459	248.474	248.489
234.237	234.052	233.771	233.490	233.219	232.948	232.674	232.413	232.149	231.885	231.623	231.361	231.107
309.443	308.891	308.341	307.791	307.246	306.702	306.160	305.620	305.084	304.551	304.022	303.498	302.980
382.583	381.988	381.471	380.965	380.509	380.043	379.566	379.140	378.701	378.271	377.849	377.435	377.028
296.828	296.234	295.648	295.470	295.102	294.745	294.399	294.063	293.738	293.421	293.114	292.813	292.518
298.226	291.938	291.653	291.369	291.087	290.807	290.531	290.257	289.985	289.713	289.443		
432.828	431.890	430.954	430.418	429.884	429.350	428.820	428.290	427.759	427.232	426.707	426.187	425.672
435.163	434.668	434.174	433.694	433.228	432.768	432.323	431.887	431.454	431.038	430.623	430.212	429.803
429.398	428.997	428.601	428.213	427.835	427.469	427.117	426.779	426.453	426.139	425.834	425.535	425.240
428.947	424.653	424.354	424.060	423.768	423.474	423.181	422.890	422.601	422.314	422.028		
688.758	688.237	687.717	687.190	686.676	686.156	685.635	685.114	684.591	684.069	683.548	683.029	682.516
678.011	677.515	677.032	676.561	676.104	675.660	675.228	674.806	674.392	673.982	673.574	673.166	672.756
672.344	671.933	671.524	671.124	670.735	670.361	670.004	669.665	669.343	669.034	668.735	668.441	668.148
667.952	667.553	667.248	666.938	666.625	666.311	665.997	665.685	665.375	665.066	664.758		
489.7	489.191	488.657	488.122	487.587	487.050	486.513	485.975	485.438	484.900	484.363	483.827	483.292
923.795	923.252	922.703	922.152	921.608	921.062	920.514	919.964	919.412	918.859	918.305	917.751	917.198
968.087	967.638	967.185	966.728	966.267	965.802	965.334	964.862	964.388	963.911	963.431	962.948	962.464
963.718	963.428	963.133	962.835	962.533	962.230	961.927	961.624	961.321	961.018	960.715	960.412	960.109
1278.414	1269.827	1260.834	1251.841	1242.847	1233.854	1224.861	1215.868	1206.875	1197.882	1188.889	1179.896	1170.903
1263.080	1262.478	1261.954	1261.456	1260.984	1260.540	1260.118	1259.722	1259.352	1258.997	1258.654	1258.321	1257.998
1257.085	1256.661	1256.288	1255.977	1255.738	1255.561	1255.434	1255.357	1255.330	1255.353	1255.426	1255.549	1255.722
1253.921	1252.660	1252.401	1252.146	1251.893	1251.642	1251.393	1251.147	1250.901	1250.656	1250.414		
1702.228	1701.600	1700.973	1700.348	1699.726	1699.108	1698.494	1697.886	1697.284	1696.689	1696.103	1695.525	1694.947
1694.390	1693.851	1693.315	1692.781	1692.249	1691.720	1691.193	1690.670	1690.150	1689.633	1689.118	1688.605	1688.098
1689.270	1687.893	1687.530	1687.180	1686.844	1686.520	1686.204	1685.891	1685.583	1685.280	1684.983	1684.693	1684.408
1688.336	1688.108	1687.878	1687.650	1687.425	1687.206	1686.991	1686.782	1686.578	1686.376	1686.177	1685.981	1685.788

Table C-4. Final contours, case 2.c1.

THE NEW CONTOUR VALUES, I. FOLLOW														
200.000	222.832	225.655	228.459	231.234	233.970	236.655	239.278	241.828	244.294	246.665	248.929	251.075		
233.000	254.944	256.685	258.239	259.618	260.810	261.805	262.594	263.168	263.520	263.643	263.533	263.184		
262.000	261.191	260.740	259.459	257.953	256.229	254.295	252.160	249.834	247.327	244.651	241.817	238.837		
235.725	232.492	229.151	225.714	222.193	218.602	214.951	211.253	207.519	203.764	200.000				
251.623	254.652	257.687	260.718	263.712	266.652	269.545	272.386	275.145	277.797	280.346	282.804	285.152		
207.302	209.369	291.215	292.907	294.439	295.772	296.865	297.765	298.308	298.694	298.868	298.818	298.515		
207.935	297.079	295.972	294.634	293.068	291.265	289.216	286.935	284.449	281.778	278.928	275.925	272.796		
209.535	266.119	262.565	258.909	255.172	251.353	247.456	243.493	239.492	235.520	231.623				
307.443	313.514	317.559	321.665	325.688	329.646	333.542	337.363	341.075	344.657	348.113	351.445	354.628		
357.610	360.396	362.951	365.314	367.461	369.345	370.917	372.171	373.126	373.798	374.180	374.249	373.972		
373.330	372.334	371.011	369.385	367.455	365.207	362.637	359.769	356.641	353.273	349.677	345.882	341.915		
337.768	333.404	328.673	324.214	319.450	314.581	309.623	304.600	299.541	294.483	289.443				
482.028	487.543	453.038	458.495	463.895	469.219	474.449	479.566	484.553	489.390	494.060	498.582	502.816		
506.862	510.658	514.183	517.414	520.328	522.901	525.111	526.937	528.382	529.371	529.958	530.118	529.849		
529.149	528.819	526.458	524.070	522.061	519.242	516.025	512.428	508.470	504.176	499.571	494.685	489.583		
484.171	478.590	472.617	466.868	460.760	454.511	448.146	441.690	435.170	428.608	422.028				
664.757	693.500	702.203	710.828	719.341	727.712	735.913	743.920	751.708	759.253	766.528	773.507	780.161		
786.463	792.381	797.887	802.950	807.539	811.626	815.180	818.172	820.578	822.373	823.591	824.065	823.934		
823.139	821.676	819.544	816.751	813.310	809.242	804.571	799.327	793.524	787.256	780.500	773.310	765.723		
757.770	749.480	740.082	732.003	722.872	713.521	703.986	694.304	684.514	674.654	664.758				
980.726	987.388	1014.001	1020.517	1046.898	1053.067	1079.004	1094.650	1109.953	1124.857	1139.303	1153.231	1166.576		
1179.271	1191.249	1202.442	1212.781	1222.200	1230.635	1238.024	1244.309	1249.436	1253.359	1256.035	1257.430	1257.518		
1256.205	1253.726	1249.849	1244.675	1238.238	1230.584	1221.770	1211.859	1200.921	1189.030	1176.260	1162.684	1148.372		
1133.393	1117.612	1101.693	1085.097	1068.088	1050.725	1033.071	1015.185	997.127	978.954	960.726				
1270.414	1275.696	1280.964	1286.207	1291.410	1296.559	1301.640	1306.637	1311.533	1316.308	1320.943	1325.417	1329.706		
1333.786	1337.633	1341.221	1344.522	1347.511	1350.162	1352.451	1354.354	1355.650	1356.922	1357.553	1357.733	1357.453		
1336.712	1335.509	1333.052	1331.750	1329.218	1326.273	1322.938	1319.236	1315.172	1310.832	1306.184	1301.275	1296.130		
1310.775	1305.236	1299.529	1293.683	1287.717	1281.649	1275.498	1269.283	1263.020	1256.725	1250.414				
1702.228	1701.697	1701.166	1700.636	1700.109	1699.584	1699.062	1698.548	1698.030	1697.521	1697.017	1696.519	1696.026		
1695.541	1695.061	1694.589	1694.123	1693.664	1693.213	1692.769	1692.331	1691.901	1691.478	1691.062	1690.652	1690.250		
1689.854	1689.464	1689.082	1688.705	1688.335	1687.972	1687.614	1687.263	1686.917	1686.577	1686.243	1685.913	1685.584		
1685.260	1684.952	1684.680	1684.331	1684.025	1683.722	1683.420	1683.121	1682.822	1682.525	1682.228				

Table C-5. Final contours, case 2.c2.

THE NEW CONTOUR VALUES, Y, FOLLOW

220.000	222.574	225.142	227.698	230.232	232.735	235.198	237.610	239.962	242.243	244.443	246.550	248.594
250.442	252.202	253.822	255.290	256.593	257.720	258.660	259.402	259.937	260.256	260.355	260.227	259.869
259.200	250.461	257.414	256.145	256.659	252.965	251.073	248.994	246.739	244.721	241.751	239.043	236.200
233.260	230.209	227.060	223.848	220.560	217.215	213.824	210.390	206.946	203.477	200.000		
251.623	254.307	257.181	259.990	262.707	265.552	268.275	270.949	273.563	276.104	278.562	280.926	283.187
205.327	207.332	209.187	209.877	292.388	293.708	294.821	295.716	296.382	296.611	296.995	296.924	296.689
295.985	295.117	293.992	292.618	291.000	289.148	287.075	284.796	282.327	279.682	276.875	273.917	270.824
207.614	204.301	200.896	197.407	193.846	190.224	186.555	182.849	179.119	175.374	171.623		
309.443	312.369	315.475	318.666	321.824	324.931	327.987	330.992	333.933	336.779	339.523	342.195	344.810
347.324	349.679	351.847	353.825	355.606	357.172	358.504	359.591	360.427	361.022	361.390	361.498	361.247
360.580	359.554	358.265	356.739	354.956	352.905	350.596	348.053	345.302	342.360	339.231	335.913	332.433
328.855	325.224	321.524	317.726	313.833	309.864	305.835	301.762	297.660	293.549	289.443		
402.020	405.538	409.166	412.859	416.609	420.405	424.245	428.128	432.053	436.020	440.028	444.076	448.164
404.354	409.283	414.944	421.342	428.498	436.422	445.120	454.608	464.884	475.958	487.832	500.506	514.076
503.870	502.557	500.893	499.043	496.955	494.569	491.946	489.038	485.882	482.495	478.844	475.030	470.940
406.773	402.654	400.508	400.299	400.061	400.003	400.000	400.000	400.000	400.000	400.000	400.000	400.000
604.758	603.580	602.347	601.058	600.000	600.000	600.000	600.000	600.000	600.000	600.000	600.000	600.000
813.218	830.484	847.336	863.718	879.584	894.889	909.591	923.639	936.984	949.588	961.432	972.431	977.454
971.827	959.166	946.416	932.695	918.235	903.074	887.251	870.809	853.788	836.240	818.222	799.793	781.024
704.526	752.893	743.835	734.202	724.578	714.804	704.920	694.953	684.921	674.849	664.758		
980.726	996.141	1011.526	1026.850	1042.114	1057.318	1072.462	1087.546	1102.570	1117.544	1132.468	1147.342	1162.166
1195.11	1221.161	1245.989	1270.014	1293.157	1315.340	1329.771	1340.535	1350.556	1359.797	1368.228	1375.828	1379.114
1374.609	1365.793	1356.149	1345.701	1334.479	1322.518	1309.827	1296.427	1282.333	1267.573	1252.162	1236.112	1219.542
1126.103	1107.752	1092.829	1076.727	1060.706	1044.822	1029.126	1013.665	998.404	983.304	968.344	953.504	938.774
1270.414	1273.892	1277.367	1280.834	1284.289	1287.728	1291.146	1294.535	1297.888	1301.196	1304.445	1307.622	1310.710
1313.688	1316.535	1319.224	1321.730	1324.022	1326.073	1327.844	1329.385	1330.744	1331.965	1333.086	1334.117	1335.058
1379.410	1370.594	1360.950	1350.502	1339.280	1327.319	1314.598	1301.387	1287.726	1273.665	1259.154	1244.243	1228.982
1293.050	1289.694	1285.465	1281.177	1276.844	1272.478	1268.089	1263.682	1259.265	1254.841	1250.414		
1702.228	1701.684	1701.140	1700.596	1700.054	1699.513	1698.974	1698.438	1697.906	1697.377	1696.854	1696.336	1695.825
1695.321	1694.824	1694.336	1693.856	1693.385	1692.923	1692.469	1692.023	1691.586	1691.156	1690.734	1690.319	1689.912
1680.513	1689.122	1688.718	1688.364	1687.997	1687.640	1687.291	1686.950	1686.617	1686.292	1685.974	1685.662	1685.356
1685.055	1684.759	1684.467	1684.178	1683.893	1683.611	1683.331	1683.053	1682.777	1682.502	1682.228		

Table C-6. Final contours, case 2.c3.

THE NEW CONTOUR VALUES, Y, FOLLOW											
220.000	221.005	223.603	225.509	227.313	229.089	230.828	232.523	234.167	235.753	237.272	238.716
241.348	242.519	243.563	244.530	245.353	246.044	246.595	246.999	247.250	247.344	247.277	247.047
246.101	245.308	244.519	243.498	242.328	241.012	239.554	237.957	236.227	234.369	232.393	230.306
225.855	223.507	221.089	218.609	216.071	213.480	210.843	208.168	205.462	202.736	200.000	
251.623	253.498	255.392	257.293	259.177	261.030	262.846	264.621	266.350	268.025	269.639	271.186
274.050	275.345	276.533	277.605	278.550	279.355	280.008	280.498	280.816	280.956	280.915	280.693
279.700	278.935	278.004	276.914	275.671	274.278	272.735	271.046	269.215	267.249	265.161	262.964
256.303	255.066	253.369	250.814	248.203	245.537	242.819	240.057	237.263	234.447	231.623	
309.443	311.420	313.526	315.697	317.893	319.940	321.993	324.009	325.987	327.907	329.763	331.568
335.036	336.684	338.135	339.505	340.744	341.834	342.766	343.458	343.962	344.255	344.343	344.224
343.258	342.373	341.268	339.974	338.519	336.896	335.104	333.146	331.029	328.772	326.388	323.885
318.625	315.921	313.167	310.354	307.487	304.568	301.600	298.590	295.551	292.498	289.443	
442.028	445.418	448.880	452.348	455.784	459.206	462.618	466.027	469.418	472.725	475.932	479.175
486.080	489.479	492.661	495.692	498.535	501.184	503.567	505.609	507.274	508.581	509.611	510.362
509.876	508.291	506.130	503.646	500.898	497.879	494.580	491.005	487.184	483.176	479.013	474.675
485.732	483.411	481.184	482.802	480.382	477.943	475.516	473.114	470.730	468.368	466.028	
684.758	696.120	706.490	716.309	726.334	736.809	747.685	758.088	770.505	782.855	796.988	813.373
852.453	870.788	897.250	919.475	941.203	962.353	982.669	1001.785	1019.385	1035.244	1048.852	1058.086
1057.956	1048.151	1033.429	1018.170	997.242	977.029	955.720	933.448	910.379	886.753	862.903	839.272
796.596	779.055	764.002	750.342	737.126	724.257	711.804	699.726	687.912	676.278	664.758	
940.726	946.702	1015.781	1032.198	1048.818	1066.111	1083.912	1101.890	1120.103	1139.021	1159.681	1183.592
1239.961	1271.244	1302.237	1329.025	1346.090	1362.660	1378.627	1393.615	1407.198	1419.140	1429.286	1436.598
1436.553	1428.600	1417.146	1403.576	1388.502	1372.372	1355.413	1337.697	1319.213	1289.330	1256.251	1223.058
1161.109	1136.338	1115.349	1095.497	1075.419	1055.263	1035.610	1016.477	997.673	979.099	960.726	
1270.414	1273.743	1276.935	1279.784	1282.576	1285.699	1289.080	1292.438	1295.774	1299.326	1303.099	1306.958
1315.456	1320.326	1325.416	1333.826	1350.891	1367.441	1383.428	1398.416	1411.999	1423.941	1434.087	1441.399
1441.354	1433.401	1421.947	1408.377	1393.303	1377.173	1360.214	1342.498	1324.014	1315.513	1309.511	1303.673
1293.316	1288.477	1284.093	1279.828	1275.396	1270.916	1266.612	1262.487	1258.424	1254.393	1250.414	
1762.228	1701.607	1701.066	1700.441	1699.896	1699.317	1698.746	1698.179	1697.615	1697.057	1696.506	1695.961
1694.404	1694.377	1693.869	1693.366	1692.875	1692.393	1691.923	1691.467	1691.019	1690.579	1690.149	1689.733
1688.934	1688.549	1688.173	1687.806	1687.449	1687.104	1686.769	1686.446	1686.131	1685.825	1685.527	1685.238
1684.644	1684.414	1684.161	1683.910	1683.660	1683.413	1683.170	1682.932	1682.696	1682.461	1682.228	

Table C-7. Final contours, case 2.c4.

THE NEW CONTOUR VALUES, Y, FOLLOW

220.000	221.000	223.000	225.532	227.357	229.164	230.947	232.699	234.414	236.083	237.699	239.251	240.734
242.133	243.448	244.642	245.728	246.688	247.511	248.186	248.704	249.057	249.239	249.244	249.067	240.708
240.133	247.434	248.522	249.633	249.170	249.740	249.153	239.418	237.545	235.545	233.830	231.211	228.009
224.504	224.036	221.504	218.918	216.286	213.617	210.920	208.203	205.473	202.737	200.000		
291.623	253.492	255.355	257.214	259.064	260.901	262.716	264.502	266.251	267.956	269.609	271.205	272.731
274.176	275.526	276.771	277.898	278.896	279.753	280.459	281.004	281.381	281.583	281.605	281.437	281.075
280.520	279.777	278.847	277.734	276.443	274.982	273.359	271.585	269.671	267.629	265.471	263.200	260.853
258.426	255.916	253.349	250.728	248.061	245.356	242.622	239.864	237.096	234.344	231.623		
309.443	311.824	314.207	316.594	318.982	321.367	323.741	326.099	328.431	330.730	332.986	335.188	337.320
339.366	341.307	343.125	344.802	346.317	347.652	348.789	349.712	350.405	350.858	351.058	350.994	350.662
358.062	349.197	348.071	346.688	345.061	343.202	341.126	338.853	336.401	333.790	331.036	328.166	325.192
322.133	319.093	315.814	312.579	309.309	306.014	302.702	299.360	296.050	292.744	289.443		
442.028	445.709	449.391	453.072	456.753	460.429	464.098	467.751	471.380	474.973	478.514	481.986	485.364
480.632	491.756	494.710	497.464	499.986	502.246	504.214	505.862	507.163	508.095	508.641	508.786	508.522
507.807	506.762	505.276	503.402	501.157	498.564	495.646	492.432	488.951	485.234	481.309	477.208	472.958
468.585	464.11	459.566	454.960	450.309	445.628	440.926	436.211	431.487	426.758	422.011		
684.758	699.616	714.513	729.483	744.557	759.753	775.078	790.525	806.069	821.667	837.259	852.857	878.494
903.921	928.912	953.321	976.995	999.774	1021.498	1042.010	1061.164	1078.824	1094.873	1109.216	1121.782	1127.320
1120.607	1106.894	1091.541	1074.105	1055.249	1034.889	1013.156	990.193	966.154	941.196	915.473	889.135	862.324
837.770	818.190	801.075	783.899	766.720	749.579	732.498	715.486	698.536	681.634	664.758		
980.726	1000.366	1020.022	1039.705	1059.422	1079.168	1098.927	1118.668	1138.343	1157.890	1177.226	1199.724	1220.739
1260.672	1291.908	1322.296	1351.684	1373.324	1399.434	1404.547	1418.545	1431.322	1442.782	1452.850	1461.468	1465.130
1460.350	1450.611	1439.418	1426.823	1412.903	1397.747	1381.461	1364.160	1339.492	1308.613	1276.890	1243.878	1210.323
1179.637	1155.419	1134.309	1112.934	1091.375	1069.696	1047.945	1026.156	1004.350	982.538	960.726		
1270.414	1275.657	1280.936	1286.205	1291.736	1297.314	1303.040	1308.927	1314.976	1321.182	1327.523	1333.970	1340.476
1346.987	1353.432	1359.733	1365.801	1371.125	1376.235	1381.149	1385.848	1390.348	1394.623	1398.683	1402.569	1406.331
1405.151	1405.412	1404.219	1401.624	1401.704	1402.548	1398.262	1388.961	1377.242	1359.198	1342.912	1335.469	1327.947
1320.813	1312.922	1305.514	1298.220	1291.055	1284.025	1277.123	1270.336	1263.641	1257.011	1250.414		
1702.228	1701.648	1701.068	1700.491	1699.917	1699.347	1698.782	1698.223	1697.671	1697.127	1696.591	1696.063	1695.545
1695.036	1694.536	1694.047	1693.567	1693.096	1692.636	1692.185	1691.743	1691.310	1690.886	1690.471	1690.064	1689.665
1689.275	1688.892	1688.517	1688.151	1687.792	1687.441	1687.097	1686.762	1686.433	1686.113	1685.800	1685.494	1685.195
1684.902	1684.616	1684.335	1684.060	1683.789	1683.523	1683.260	1682.999	1682.741	1682.484	1682.226		

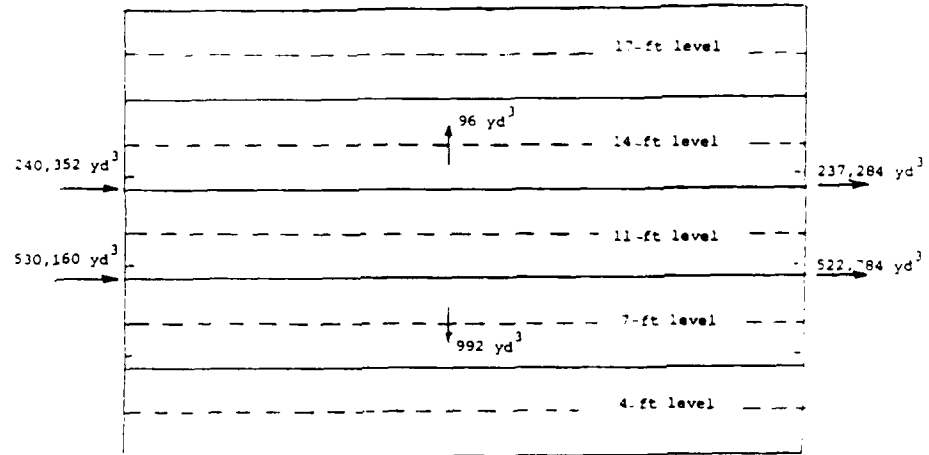
Table C-8. Final contours, case 3 (17 weeks plus sediment addition).

220.000	219.071	218.148	217.236	216.342	215.470	214.625	213.812	213.033	212.291	211.589	210.926	210.303
209.719	209.172	208.660	208.180	207.729	207.305	206.903	206.522	206.158	205.809	205.473	205.147	204.829
204.516	204.207	203.901	203.596	203.292	202.992	202.695	202.406	202.125	201.857	201.603	201.367	201.149
200.950	200.773	200.616	200.480	200.363	200.265	200.185	200.121	200.071	200.033	200.000		
251.623	250.708	249.802	248.909	248.035	247.187	246.370	245.589	244.848	244.150	243.495	242.884	242.317
241.792	241.397	240.957	240.480	240.049	239.662	239.333	239.098	238.673	238.355	238.039	237.724	237.408
237.069	236.767	236.437	236.101	235.758	235.412	235.066	234.722	234.384	234.056	233.741	233.443	233.165
232.909	232.676	232.467	232.282	232.119	231.978	231.860	231.766	231.696	231.651	231.623		
309.493	308.558	307.680	306.817	305.980	305.175	304.411	303.694	303.027	302.414	301.855	301.349	300.896
308.492	308.131	307.808	307.517	307.249	306.999	306.757	306.516	306.268	306.007	305.730	305.434	305.118
296.781	296.423	296.082	295.760	295.460	295.220	294.984	294.784	294.603	294.429	294.279	294.141	294.013
291.353	291.013	290.703	290.422	290.167	289.934	289.735	289.578	289.478	289.440	289.443		
482.028	481.318	480.621	479.951	479.321	478.745	478.232	477.789	477.421	477.129	476.913	476.770	476.696
436.683	436.722	436.798	436.899	437.013	437.127	437.225	437.299	437.302	437.252	437.156	436.952	436.699
416.373	415.968	415.482	414.916	414.278	413.576	412.822	412.026	411.198	410.354	409.508	408.679	407.882
427.128	426.722	425.764	425.148	424.568	424.020	423.508	423.083	422.643	422.312	422.028		
684.756	684.608	684.472	684.368	684.297	684.283	684.331	684.448	684.639	684.907	685.250	685.665	686.145
686.682	687.268	687.876	688.502	689.122	689.717	690.266	690.747	691.140	691.424	691.581	691.597	691.459
691.169	690.696	690.088	689.284	688.352	687.289	686.110	684.837	683.490	682.091	680.661	679.221	677.788
676.378	675.004	673.675	672.398	671.175	670.006	668.887	667.813	666.774	665.760	664.758		
980.726	981.845	1002.983	1014.190	1025.389	1036.678	1048.028	1059.430	1070.864	1082.300	1093.693	1108.458	1129.498
1158.760	1179.183	1203.166	1226.603	1249.386	1271.492	1292.545	1312.709	1331.801	1349.737	1366.447	1381.880	1389.056
1381.028	1364.718	1347.118	1328.266	1308.222	1287.085	1264.885	1241.782	1217.863	1193.239	1168.019	1142.310	1116.214
1093.293	1077.103	1064.242	1051.298	1038.315	1025.327	1012.356	999.412	986.497	973.605	960.726		
1270.414	1267.593	1264.812	1307.106	1319.506	1332.036	1344.706	1357.516	1370.450	1383.476	1396.543	1413.058	1436.496
1483.017	1469.303	1453.137	1434.383	1414.097	1392.535	1369.855	1346.324	1322.016	1297.023	1271.363	1245.044	1218.071
1689.950	1681.451	1668.760	1648.974	1627.783	1605.291	1581.617	1556.892	1531.254	1504.845	1477.603	1450.263	1422.548
1397.648	1379.716	1365.183	1350.630	1336.109	1321.650	1307.270	1292.970	1278.740	1264.563	1250.414		
1702.228	1701.187	1700.070	1699.001	1697.943	1696.900	1695.876	1694.874	1693.897	1692.948	1692.029	1691.143	1690.292
1689.876	1688.742	1687.966	1687.269	1686.613	1685.998	1685.424	1684.891	1684.399	1683.946	1683.500	1683.061	1682.628
1680.821	1680.049	1682.010	1681.607	1681.635	1681.491	1681.376	1681.287	1681.223	1681.183	1681.164	1681.166	1681.187
1681.226	1681.280	1681.349	1681.431	1681.523	1681.626	1681.737	1681.854	1681.976	1682.101	1682.228		
2180.983	2179.761	2178.582	2177.412	2176.254	2175.111	2173.988	2172.898	2171.815	2170.771	2169.760	2168.784	2167.844
2166.989	2166.094	2165.262	2164.516	2163.797	2163.125	2162.501	2161.925	2161.398	2160.919	2160.487	2160.102	2159.763
2159.468	2159.217	2159.008	2158.840	2158.710	2158.617	2158.559	2158.533	2158.539	2158.573	2158.634	2158.719	2158.828
2158.956	2159.103	2159.267	2159.445	2159.636	2159.836	2160.048	2160.266	2160.488	2160.715	2160.943		

Table C-9. Final contours, case 4.

THE NEW CONTOUR VALUES, Y, FOLLOW

220.000	231.328	222.652	223.967	225.270	226.555	227.817	230.200	231.406	232.517	233.575	234.573
235.508	236.361	237.136	237.023	238.415	239.908	239.284	239.549	239.711	239.601	239.350	238.982
238.471	237.026	237.099	236.143	235.110	233.957	232.688	231.309	229.827	228.249	226.582	224.831
221.121	219.872	217.169	215.120	213.032	210.910	208.760	206.588	204.401	202.203	200.000	
208.841	207.584	206.584	205.592	204.792	204.092	203.576	203.136	202.767	202.463	202.216	202.021
300.000	307.101	308.046	308.693	309.034	310.260	310.763	311.130	311.368	311.456	311.395	311.181
319.287	309.606	308.771	307.786	306.656	305.388	303.988	302.464	300.825	299.079	297.235	295.301
291.204	289.056	286.853	284.601	282.304	279.980	277.623	275.242	272.844	270.440	268.001	
402.028	400.472	400.915	401.354	401.787	402.207	402.608	402.984	403.324	403.622	403.865	404.045
472.161	474.070	475.657	477.506	478.999	480.317	481.402	482.356	483.045	483.493	483.688	483.621
482.685	481.815	480.684	479.299	477.674	475.822	473.760	471.505	469.075	466.490	463.766	460.922
454.938	451.825	448.650	445.421	442.140	438.841	435.507	432.152	428.784	425.408	422.028	
573.553	577.760	581.968	586.167	590.365	594.561	598.726	602.832	606.872	610.846	614.752	618.581
627.450	631.210	634.791	638.163	641.285	644.113	646.605	648.719	650.415	651.659	652.423	652.683
651.650	650.356	648.500	646.285	643.558	640.417	636.901	633.053	628.914	624.530	619.840	615.104
605.307	600.284	595.126	589.971	584.790	579.595	574.391	569.182	563.972	558.763	553.553	
806.571	808.896	811.010	812.923	814.627	816.128	817.436	818.564	819.522	820.324	820.991	821.547
750.483	765.001	773.328	781.315	788.860	795.824	802.100	807.554	812.874	817.921	819.097	819.046
817.756	815.240	811.554	806.753	800.933	794.199	786.569	778.066	769.715	760.537	751.045	741.343
721.647	711.788	701.983	692.261	682.634	673.197	663.874	654.672	645.614	635.791	626.251	
224.021	237.877	250.945	264.449	277.975	291.504	305.222	318.958	332.772	346.656	360.583	374.511
407.091	415.544	420.619	426.154	432.066	438.274	444.789	451.609	458.749	466.212	474.021	482.176
1001.281	998.054	993.025	986.283	977.944	968.165	957.000	944.619	931.005	917.927	903.452	888.531
857.066	842.330	826.762	811.213	795.714	780.284	764.926	749.634	734.397	719.199	704.021	
405.662	412.050	418.050	423.684	428.974	433.934	438.584	442.954	447.084	450.914	454.484	457.844
602.476	605.402	607.921	610.920	614.470	618.520	623.120	628.220	633.870	639.120	644.920	651.220
1071.178	1058.274	1043.652	1027.940	1010.582	991.846	971.921	950.926	928.000	903.200	876.500	848.900
937.092	921.841	906.525	891.269	875.936	860.735	845.688	830.811	816.121	801.721	788.301	775.461
800.720	786.911	772.911	758.911	745.011	731.211	717.511	703.911	690.411	677.011	663.711	650.511
1054.400	1059.050	1063.766	1067.416	1071.074	1074.744	1078.414	1082.084	1085.754	1089.424	1093.094	1096.764
1069.650	1063.310	1056.109	1048.141	1039.417	1029.945	1019.724	1008.754	997.034	984.564	971.344	957.474
1029.720	1023.423	1016.933	1010.276	1003.472	996.541	989.505	982.364	975.119	967.776	960.331	952.786
1270.414	1270.105	1269.796	1269.486	1269.176	1268.866	1268.556	1268.246	1267.936	1267.626	1267.316	1267.006
1266.353	1266.031	1265.705	1265.376	1265.043	1264.704	1264.354	1264.005	1263.654	1263.304	1262.954	1262.604
1261.605	1261.275	1260.945	1260.607	1260.260	1259.905	1259.546	1259.185	1258.824	1258.463	1258.102	1257.741
1255.640	1255.132	1254.620	1254.103	1253.583	1253.063	1252.543	1252.023	1251.503	1250.983	1250.463	1250.000



Case 2.a.

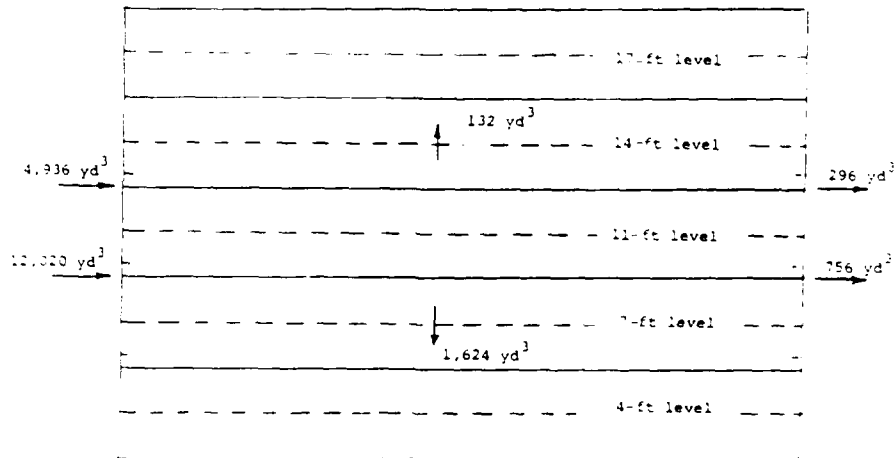
Period Considered: Twelve months, January through December, using 1970  
WIS wave hindcasts

Sediment Budget Summary:

Amount of sediment added:	None
Amount of sediment transported shoreward from nourished region:	992 yd <sup>3</sup>
Amount of sediment transported seaward from nourished region:	96 yd <sup>3</sup>
Net amount of sediment transported alongshore from nourished region:	10,444 yd <sup>3</sup>
Total amount of sediment transported from nourished region:	10,444 yd <sup>3</sup>

Figure C-1. Schematic illustration of sediment volumes transported from region, case 2.a.





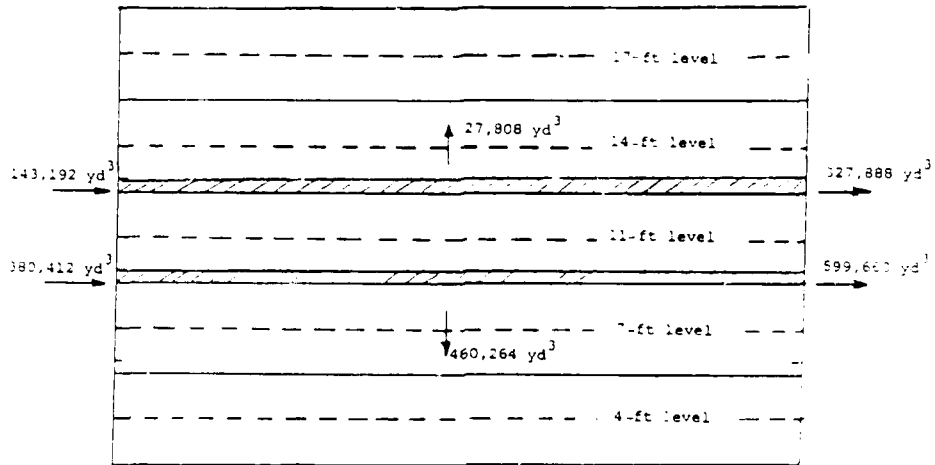
Case No. 2b.

Period considered: Twelve months, January through December, using 147  
 310 wave hindcasts, but wave angle always set equal  
 to 7°.

Sediment Budget Summary:

Amount of sediment added:	None
Amount of sediment transported seaward from nourished region:	1,624 yd <sup>3</sup>
Amount of sediment transported seaward from nourished region:	132 yd <sup>3</sup>
Net amount of sediment transported from nourished region:	-15,904 yd <sup>3</sup>
Total amount of sediment transported from nourished region:	-14,148 yd <sup>3</sup>

Figure C-2. Schematic illustration of sediment volumes transported from region, case 2.b.



Case 2.c1.

Period: 1980-1981 (12 months). Location: 10th Mile, Norfolk, Virginia (1977-1978 case windcasts).

Sediment Budget Summary:

Amount of sediment added: 1,143,904 yd<sup>3</sup> on 7- and 11-ft levels.

Amount of sediment transported seaward from nourished region: 460,264 yd<sup>3</sup> (40.2%)

Amount of sediment transported seaward from nourished region: 27,808 yd<sup>3</sup> (2.4%)

Net amount of sediment transported alongshore from nourished region: 433,444 yd<sup>3</sup> (37.8%)

Total amount of sediment transported from nourished region: 692,016 yd<sup>3</sup> (60.4%)

Figure C-3. Schematic illustration of sediment volumes transported from nourished region, case 2.c1.

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A NUMERICAL MODEL TO SIMULATE SEDIMENT TRANSPORT IN THE  
VICINITY OF COAST.. (U) COASTAL AND OFFSHORE ENGINEERING  
AND RESEARCH INC NEWARK DE M PERLIN ET AL. MAY 83

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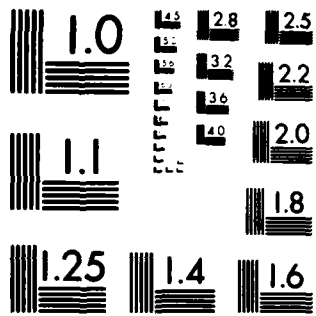
UNCLASSIFIED

CERC-MR-83-10 DACW72-80-C-0030

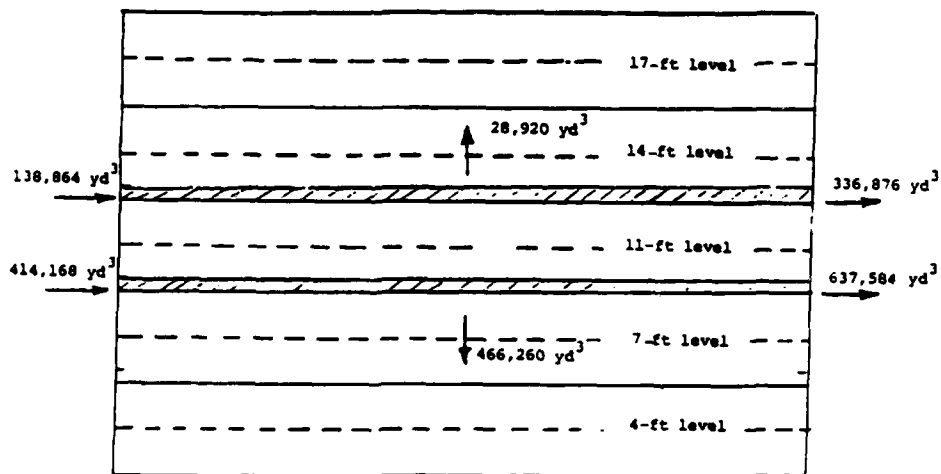
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MICROCOPY RESOLUTION TEST CHART  
NATIONAL BUREAU OF STANDARDS-1963-A



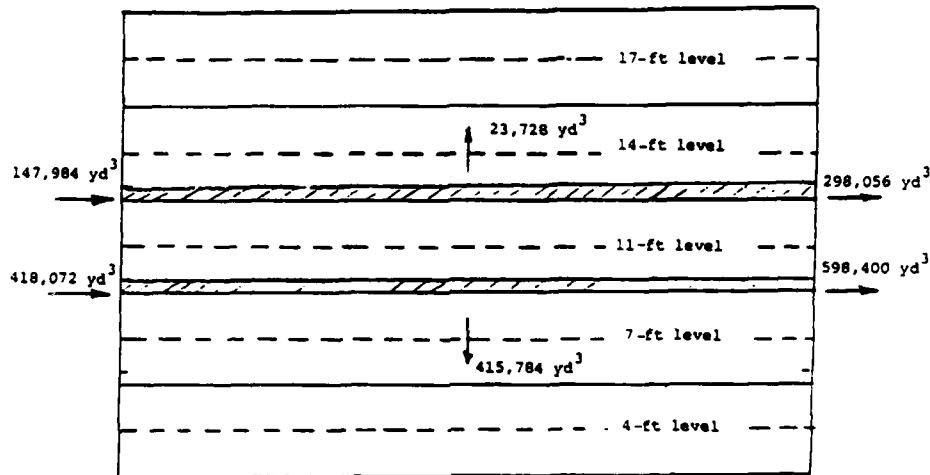
Case 2.c2.

Period considered: Twelve months, April through March, using 1975  
WIS wave hindcasts.

Sediment Budget Summary:

Amount of sediment added:	1,452,000 yd <sup>3</sup> (on 7- and 11-ft contours)
Amount of sediment transported shoreward from nourished region:	466,260 yd <sup>3</sup> (32.1pct)
Amount of sediment transported seaward from nourished region:	28,920 yd <sup>3</sup> (2.0 pct)
Net amount of sediment transported alongshore from nourished region:	421,428 yd <sup>3</sup> (29.0pct)
Total amount of sediment transported from nourished region:	916,608 yd <sup>3</sup> (63.1pct)

Figure C-4. Schematic illustration of sediment volumes transported from nourished region, case 2.c2.



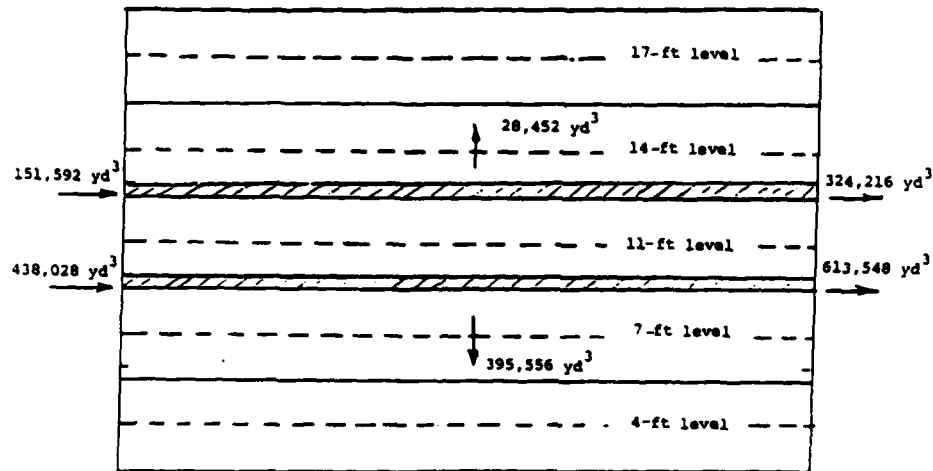
Case 2.c3.

Period considered: Twelve months, July through June, using 1975  
WIS wave hindcasts.

Sediment Budget Summary

Amount of sediment added:	1,452,000 yd <sup>3</sup> (on 7- and 11-ft contour)
Amount of sediment transported shoreward from nourished region:	415,784 yd <sup>3</sup> (28.6 pct)
Amount of sediment transported seaward from nourished region:	23,728 yd <sup>3</sup> (1.6 pct)
Net amount of sediment transported alongshore from nourished region:	330,400 yd <sup>3</sup> (22.8 pct)
Total amount of sediment transported from nourished region:	769,912 yd <sup>3</sup> (53.0 pct)

Figure C-5. Schematic illustration of sediment volumes transported from nourished region, case 2.c3.



Case 2.c4.

Period considered: Twelve months, October through September, using 1975 WIS wave hindcasts.

**Sediment Budget Summary:**

Amount of sediment added: 1,452,000 yd<sup>3</sup> (on 7- and 11-ft contours).

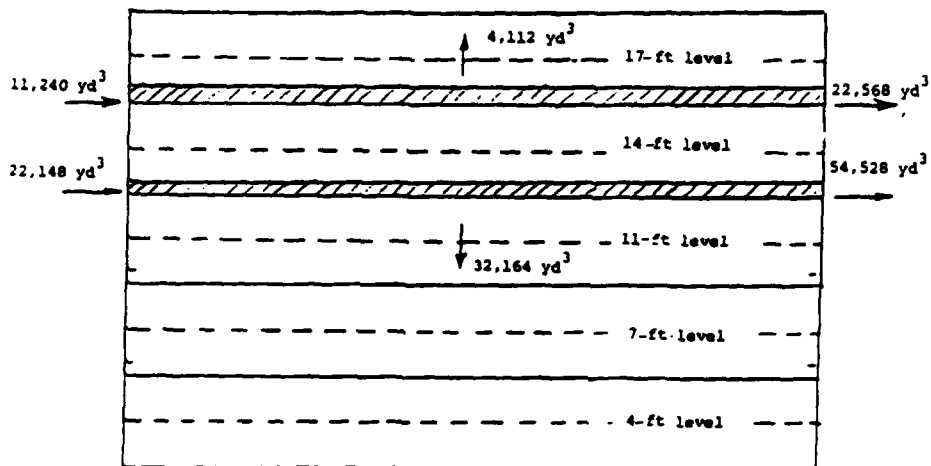
Amount of sediment transported shoreward from nourished region: 395,556 yd<sup>3</sup> (27.2 pct)

Amount of sediment transported seaward from nourished region: 28,452 yd<sup>3</sup> (2.0 pct)

Net amount of sediment transported alongshore from nourished region: 348,144 yd<sup>3</sup> (24.0 pct)

Total amount of sediment transported from nourished region: 772,152 yd<sup>3</sup> (53.2 pct)

Figure C-6. Schematic illustration of sediment volumes transported from nourished region, case 2.c4.



Case 3.

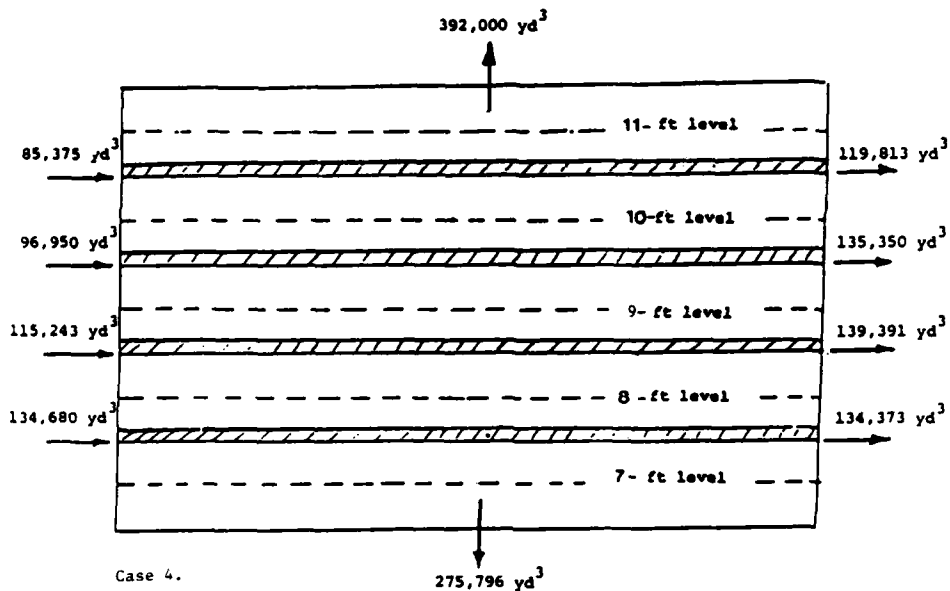
Period considered: Four months, January through April, using 1975  
WIS wave hindcasts.

Sediment Budget Summary:

Amount of sediment added	363,000 yd <sup>3</sup> (on 11- and 14-ft contours).
Amount of sediment transported shoreward from nourished region:	32,164 yd <sup>3</sup> (8.9pct)
Amount of sediment transported seaward from nourished region:	4,112 yd <sup>3</sup> (1.1 pct)
Net amount of sediment transported alongshore from nourished region:	43,708 yd <sup>3</sup> (12.0pct)
Total amount of sediment transported from nourished region:	79,984 yd <sup>3</sup> (22.0pct)

Figure C-7. Schematic illustration of sediment volumes transported from nourished region, case 3.





Period considered: Twelve months, January through December, using 1975 WIS wave hindcasts.

**Sediment Budget Summary:**

Amount of sediment added: 1,452,000 yd<sup>3</sup> (on 7-, 8-, 9-, and 10-ft contours).

Amount of sediment transported shoreward from nourished region: 275,796 yd<sup>3</sup> (19.0pct)

Amount of sediment transported seaward from nourished region: 392,000 yd<sup>3</sup> (27.0pct)

Net amount of sediment transported alongshore from nourished region: 96,679 yd<sup>3</sup> (6.7pct)

Total amount of sediment transported from nourished region: 764,475 yd<sup>3</sup> (52.6pct)

Figure C-8. Schematic illustration of sediment volumes transported from nourished region, case 4.

## APPENDIX D

### METHODOLOGY AND PROGRAM LISTING OF COMPUTER PROGRAM WHICH CONVERTS BATHYMETRIC DATA INTO MONOTONICALLY DECREASING DEPTH CONTOURS

In order to simulate prototype shorelines (and in this case to help verify the numerical model via Channel Islands Harbor data), the (x, y, z) data points must be transformed into a form suitable for use in the model (i.e., bars can not be present). First, the bathymetric data have to be put into a form with fixed longshore and offshore spacings (i.e.,  $\Delta x$  and  $\Delta y$  equal constants). This can be accomplished using one of the many available canned programs which do the interpolation. The problem is then one of finding the most suitable value of the constant, A, in the equation  $h = Ay^{2/3}$ . However, as is usually the case, the exact location of the shoreline ( $h = 0$ ) is unknown. In addition, one requires the added constraint is required that the volumes of sediment (or conversely, the water above the profiles) balance. The problem is solved using LaGrange Multipliers and the Newton Raphson technique for non linear equations.

The equation to be minimized is

$$F(A, y_{del_1}, y_{del_2}, \dots, y_{del_{IMAX}}) = \sum_{i=1}^{IMAX} \sum_{j=1}^{IMAX} (h_{meas_{i,j}} - h_{pred_{i,j}})^2 \quad (D-1)$$

where A is the scale parameter in the equilibrium beach profile,  $y_{del_i}$  are the locations of the shoreline for the IMAX profiles,  $h_{meas}$  is the interpolated depth from the survey, and  $h_{pred}$  is the depth predicted by the equation

$$h_{pred_{i,j}} = A(y_{i,j} - y_{del_i})^{2/3} \quad (D-2)$$

The constraint equation is as follows

$$\begin{aligned} g(A, y_{del_1}, \dots, y_{del_{IMAX}}) &= V_{pred} = \sum_{i=1}^{IMAX} \Delta x \left\{ \int_{y_{del_i}}^y A(y - y_{del_i})^{2/3} dy \right\} \\ &= \sum_{i=1}^{IMAX} \frac{3}{5} \Delta x A(y_f - y_{del_i})^{5/3} = V_{meas} \end{aligned} \quad (D-3)$$

where  $V_{pred}$  is the predicted volume of water above the profile to the reference datum,  $V_{meas}$  is the measured volume computed from the survey,  $\Delta x$  is the longshore distance between onshore-offshore profiles, and  $y_f$  is the distance offshore to the last point on each of the measured profiles (it was a constant after the interpolation routine was used).

LaGrange Multipliers procedure says to form the quantify  $F^*$  as

$$F^* = F - \lambda g \quad (D-4)$$

take the total differential of equation (D-4)

$$dF^* = dF - \lambda dg = \left( \frac{dF}{dA} dA + \frac{dF}{d(y_{del1})} d(y_{del1}) + \dots \frac{dF}{d(y_{del_{IMAX}})} d(y_{del_{IMAX}}) \right) - \lambda \left( \frac{dg}{dA} dA + \frac{dg}{d(y_{del1})} d(y_{del1}) + \dots \frac{dg}{d(y_{del_{IMAX}})} d(y_{del_{IMAX}}) \right) \quad (D-5)$$

Rearranging

$$0 = dF^* = \left( \frac{dF}{dA} - \lambda \frac{dg}{dA} \right) dA + \left( \frac{dF}{d(y_{del1})} - \lambda \frac{dg}{d(y_{del1})} \right) d(y_{del1}) + \dots \quad (D-6)$$

It is clear that the terms in brackets in equation (D-6) must individually equal zero, however this leaves  $(IMAX + 2)$  unknown ( $y_{del i} =$  to  $IMAX$ ,  $A$ , and  $\lambda$ ) and only  $(IMAX + 1)$  Equations. The  $(IMAX + 2)$ th equation is taken as equation (D-3). The following system of equation then results:

$$0 = \frac{dF}{dA} - \lambda \frac{dg}{dA} = \sum_{i=1}^{IMAX} \sum_{j=1}^{JMAX} [-2(h_{meas_{i,j}} - A(y_{i,j} - y_{del_i})^{2/3})(y_{i,j} - y_{del_i})^{2/3}] - \lambda \sum_{i=1}^{IMAX} \frac{3}{5} \Delta x (y_f - y_{del_i})^{5/3} \quad (D-7-1)$$

$$0 = \frac{dF}{d(y_{del1})} - \lambda \frac{dg}{d(y_{del1})} = \sum_{j=1}^{JMAX} [2(h_{meas1,j} - A(y_{1,j} - y_{del1})^{2/3})$$

$$* (2/3 A(y_{1,j} - y_{del1})^{-1/3} + \lambda \Delta x A(y_f - y_{del1})^{2/3}]$$

(D-7-2)

$$0 = \frac{dF}{d(y_{delIMAX})} - \lambda \frac{dg}{d(y_{delIMAX})} = \sum_{j=1}^{JMAX} [2(h_{measIMAX,j} - A(y_{IMAX,j} - y_{delIMAX})^{2/3})$$

$$* (2/3 A(y_{IMAX,j} - y_{delIMAX})^{-1/3}] + \lambda \Delta x A(y_f - y_{delIMAX})^{2/3}$$

(D-7-(IMAX+1))

$$V_{meas} = \sum_{i=1}^{IMAX} (3/5 \Delta x A(y_f - y_{del1})^{5/3})$$

(D-7-(IMAX+2))

Because Equations (D-7) is a system of nonlinear equations, it can not be written in matrix form as a  $[D][x] = [E]$  system of equations (the brackets denote matrices). To solve the equations, a Newton-Raphson Iteration technique for nonlinear equations was used. This is done by differentiating each of the  $(IMAX + 2)$  equations with respect to each of the unknowns, the resulting equations are then linear in terms of  $\Delta a$ ,  $\Delta y_{del1}$ , . . .  $\Delta y_{delIMAX}$ ,  $\Delta \lambda$ . The resulting matrix is inverted to obtain the  $\Delta$ (unknown) and the quantities are added to the original estimates to produce a better estimate. This iterative procedure is continued until the changes become acceptably small. The solution converged rapidly. Generally, the first row of the matrix to be inverted is ( $a_{11}$  represents the  $k^{th}$  row and the  $l^{th}$  column of the matrix).

$$a_{11} = \sum_{i=1}^{IMAX} \sum_{j=1}^{JMAX} 2(y_{i,j} - y_{del1})^{4/3}$$

$$a_{1,2} = \sum_{j=1}^{JMAX} \frac{4}{3} (y_{1,j} - y_{del1})^{-1/3} (h_{meas1,j} - 2A(y_{1,j} - y_{del1})^{2/3})$$

$$a_{1, \text{IMAX}+1} = \sum_{j=1}^{\text{JMAX}} \left[ \frac{4}{3} (y_{\text{IMAX},j} - y_{\text{del}_{\text{IMAX}}})^{-1/3} (h_{\text{meas}_{\text{IMAX},j}} - 2A(y_{\text{IMAX},j} - y_{\text{del}_{\text{IMAX}}})^{2/3}) \right]$$

$$a_{1, \text{IMAX}+2} = \sum_{i=1}^{\text{IMAX}} \left[ \frac{3}{5} \Delta x (y_f - y_{\text{del}_1})^{5/3} \right] \quad (\text{D-8})$$

The second row of the matrix is as follows:

$$a_{2,1} = \sum_{j=1}^{\text{JMAX}} \left[ \frac{4}{3} h_{\text{meas}_{1,j}} (y_{1,j} - y_{\text{del}_1})^{-1/3} - \frac{8}{3} A (y_{1,j} - y_{\text{del}_1})^{1/3} \right] + \lambda \Delta x (y_f - y_{\text{del}_1})^{2/3}$$

$$a_{2,2} = \sum_{j=1}^{\text{JMAX}} \left[ \frac{4}{9} A h_{\text{meas}_{i,j}} (y_{1,j} - y_{\text{del}_1})^{-4/3} + \frac{4}{9} A^2 (y_{1,j} - y_{\text{del}_1})^{-2/3} \right] - \lambda (2/3) \Delta x A (y_f - y_{\text{del}_1})^{-1/3}$$

$$a_{2,3} = 0$$

$$\vdots$$

$$a_{2, \text{IMAX}+1} = 0$$

$$a_{2, \text{IMAX}+2} = \Delta x A (y_f - y_{\text{del}_1})^{2/3} \quad (\text{D-9})$$

The third row is simply these elements repeated except that the ones on the right-hand side of the first and last elements are changed to twos, and the  $a_{3,3}$  element is similar to the  $a_{2,2}$  except the ones on the right hand side become twos. The remaining column elements (i.e., those when the  $k = 1$ ) are zeroes. This process is continued to fill the array, except for the last row.

The  $(\text{IMAX}+2)^{\text{th}}$  row is as follows:

$$a_{IMAX+2,1} = \sum_{i=1}^{IMAX} \frac{3}{5} \Delta x (y_f - y_{del_i})^{5/3}$$

$$a_{IMAX+2,2} = -\Delta x A (y_f - y_{del_1})^{2/3}$$

$$\vdots$$

$$a_{IMAX+2, IMAX+1} = -\Delta x A (y_f - y_{del_{IMAX}})^{2/3}$$

$$a_{IMAX+2, IMAX+2} = 0 \quad (D-10)$$

The E matrix in the [D] [x] = [E] system of equations is

$$E_1 = - \left[ \sum_{i=1}^{IMAX} \sum_{j=1}^{JMAX} 2(h \text{ meas}_{i,j} - A(y_{i,j} - y_{del_i})^{2/3})(y_{i,j} - y_{del_i})^{2/3} \right. \\ \left. - \lambda \sum_{i=1}^{IMAX} \left( \frac{3}{5} \right) \Delta x (y_f - y_{del_i})^{5/3} \right]$$

$$E_2 = - \left[ \sum_{j=1}^{JMAX} 2(h \text{ meas}_{1,j} - A(y_{1,j} - y_{del_1})^{2/3}) \left( \frac{2}{3} \right) A (y_{1,j} - y_{del_1})^{-1/3} \right. \\ \left. + \lambda (\Delta x A (y_f - y_{del_1})^{2/3}) \right]$$

$$E_{IMAX+1} = - \left[ \sum_{j=1}^{JMAX} 2(h \text{ meas}_{IMAX,j} - A(y_{IMAX,j} - y_{del_{IMAX}})^{2/3}) \right. \\ \left. + \left( \frac{2}{3} \right) A (y_{1,j} - y_{del_1})^{-1/3} + \lambda (\Delta x A (y_f - y_{del_1})^{2/3}) \right]$$

$$E_{IMAX+2} = - \left[ \sum_{i=1}^{IMAX} \left( \frac{3}{5} \right) \Delta x A (y_f - y_{del_i})^{5/3} - v \text{ meas} \right] \quad (D-11)$$

The  $[D] [x] = [E]$  system of equations was then solved, as explained previously, by solving the  $x$  column vector (which represents the changes in the unknowns,  $\Delta A, \Delta y_{del_1} \dots \Delta y_{del_{MAX}}, \Delta \lambda$ ), adding these changes to the respective variables and iterating until a final solution is obtained.

The computer program which did these calculations for the Channel Island Harbor simulation follows. A user-supplied matrix inversion routine is required (Line 37,200).

```

100  $RESET FREE
200  C*****PROGRAM  CIM/BVALUE1
300  FILE 5(KIND=PACK,TITLE="CIM42076A".FILETYPE=7)
400  FILE 6(KIND=REMOTE)
500  C*THIS PROGRAM USES THE INTERPOLATED PROFILES OF CIM.
600  C*IT FINDS THE LOCATION OF THE SHORELINE, YDEL AND THE BEST
700  C*FIT LEAST SQUARES "B" VALUE FOR H=BY**2/3
800  C*USES LAGRANGE MULTIPLIERS TO CONSTRAIN THE VOLUMES(SO THEY ARE EQUAL)
900  C*THEN IT USES NEWTON-RAPHSON ITER FOR NON-LIN EOS
1000 DIMENSION X(40)
1100 DIMENSION WKAREA(600),AMATRX(23,23),BMATRX(23,1)
1200 DIMENSION Y(40,20),Z(40,20),YDEL(40),JBEGIN(40),YDELI(40)
1300 DIMENSION DYTWO(40,20),DYONE(40,20),DYMTWO(40,20),DYMONE(40,20)
1400 DIMENSION DYMFOR(40,20),DYFOR(40,20),YDONE(40,20),YDMTWO(40,20)
1500 DIMENSION YDMONE(40,20),YETWO(40),YEONE(40),YEMONE(40)
1600 DIMENSION YEMTWO(40),YEMFOR(40),YEFIVE(40)
1700 EXPON=2./3.
1800 THIRD=0.3333333333333333
1900 C*FIRST READ IN THE PROFILES FROM DISKPACK.
2000 DO 1 I=1,34
2100 DO 1 J=1,15
2200 1 READ(5,100) X(I),Y(I,J),Z(I,J)
2300 100 FORMAT(14X,F6.0,F5.0,F5.0)
2400 C*NOW WE MUST GET A FIRST APPROX FOR YDEL
2500 C*WE WILL USE LINEAR INTERPOLATION TO DETERMINE IT.
2600 IBEGIN=1
2700 IMAX=21
2800 JMAX=15
2900 C*CHANGE PROFILE TO SPAN 1 TO IMAX(IF ALREADY DONE,WON'T HARM THINGS)
3000 ITEMP1=1
3100 ITEMP2=IMAX-IBEGIN+1
3200 K=-1
3300 DO 777 I=1,ITEMP2
3400 K=K+1
3500 DO 777 J=1,JMAX
3600 Y(I,J)=Y(IBEGIN+K,J)
3700 777 Z(I,J)=Z(IBEGIN+K,J)
3800 IMAX=ITEMP2
3900 DX=100.00
4000 DO 2 I=1,IMAX
4100 DO 3 J=1,JMAX
4200 IF(Z(I,J).GE.0.0) GO TO 3
4300 C*FIRST NEG POINT ON THE PROFILE IS SEAWARD OF Z=0.0
4400 C* WE MUST ALSO REMEMBER THIS LOCATION.
4500 C*IF Z(I,1)<0.,CHOOSE ARBITRARY PT, ROUTINE ITERATES TO SOLN.
4600 ZDUM=1.0
4700 IF(J.NE.1) ZDUM=Z(I,J-1)
4800 YDUM=Y(I,J)-50.0
4900 IF(J.NE.1) YDUM=Y(I,J-1)
5000 DELY=ZDUM/((ZDUM-Z(I,J))/(Y(I,J)-YDUM))
5100 YDEL(I)=YDUM+DELY
5200 JBEGIN(I)=J
5300 GO TO 2
5400 3 CONTINUE
5500 2 CONTINUE
5600 C*THE VALUES FOR Z ARE NEG ON FILE, MUST NOW MAKE POS.
5700 C*THE Z VALUES ARE ALSO *10.
5800 DO 35 I=1,IMAX
5900 DO 35 J=JBEGIN(I),JMAX
6000 35 Z(I,J)=-Z(I,J)/10.0
6100 C*MUST INITIALIZE "B" SO WILL MAKE A FIRST GUESS.
6200 C*MUST ALSO GUESS LAMBDA (XLAMB)
6300 B=0.30
6400 XLAMB=-2.0
6500 DO 10 ITER=1,100
6600 C*LET'S CALCULATE THE VOL OF WATER ABOVE THE PROFILE,VMEAS.
6700 C*ITS OUR CONSTRAINT,BUT SINCE YDEL IS NOT KNOWN,A PRIORI,IT WILL CHANGE
6800 VMEAS=0.0
6900 DO 200 I=1,IMAX
7000 DO 200 J=JBEGIN(I),JMAX
7100 IF(J.NE.JBEGIN(I)) GO TO 201

```



```

7200      VMEAS=VMEAS+DX*Z(I,J)*(0.5*(Y(I,J)+Y(I,J+1))-YDEL(I))
7300      GO TO 200
7400      201 IF(J.EQ.JMAX) GO TO 202
7500      VMEAS=VMEAS+DX*0.5*(Y(I,J+1)-Y(I,J-1))*Z(I,J)
7600      GO TO 200
7700      202 VMEAS=VMEAS+DX*Z(I,J)*(Y(I,J)-0.5*(Y(I,J)+Y(I,J-1)))
7800      200 CONTINUE
7900      C*PRIOR TO EQS.COMPUTE AND STORE SEVERAL VALUES WE NEED OVER AND OVER
8000      C*BECAUSE COMPUTER CAN'T RAISE A NEG VALUE TO AN EXPONENT
8100      C*MUST PRESERVE THE SIGN.
8200      DO 400 II=1,IMAX
8300      DO 401 JJ=JBEGIN(II),JMAX
8400      ARG1=Y(II,JJ)-YDEL(II)
8500      DYSIGN=SIGN(1.,ARG1)
8600      DY=ABS(Y(II,JJ)-YDEL(II))
8700      DYTWO(II,JJ)=DY**EXPON
8800      DYONE(II,JJ)=DYSIGN*DY**THIRD
8900      DYMTWO(II,JJ)=DY**(-EXPON)
9000      DYMONE(II,JJ)=DYSIGN*DY**(-THIRD)
9100      DYMFOR(II,JJ)=DY**(-2.*EXPON)
9200      DYFOR(II,JJ)=DY**(2.*EXPON)
9300      401 CONTINUE
9400      ARG2=1400.-YDEL(II)
9500      DSIGN=SIGN(1.,ARG2)
9600      DYE=ABS(ARG2)
9700      YETWO(II)=DYE**EXPON
9800      YEONE(II)=DSIGN*DYE**THIRD
9900      YEMONE(II)=DSIGN*DYE**(-THIRD)
10000     YEMTWO(II)=DYE**(-EXPON)
10100     YEMFOR(II)=DYE**(-2.*EXPON)
10200     YEFIVE(II)=DSIGN*DYE**(5.*THIRD)
10300     400 CONTINUE
10400     C*LET'S INPUT THE FIRST ROW OF THE MATRIX. A
10500     SUM1B=0.0
10600     DO 300 II=1,IMAX
10700     DO 300 JJ=JBEGIN(II),JMAX
10800     300 SUM1B=SUM1B+2.*DYFOR(II,JJ)
10900     AMATRX(1,1)=SUM1B
11000     SUMLAM=0.0
11100     DO 305 K=1,IMAX
11200     SUM1K=0.0
11300     DO 306 JJ=JBEGIN(K),JMAX
11400     306 SUM1K=SUM1K+2.*EXPON*DYMONE(K,JJ)*(Z(K,JJ)-2.*B*
11500     * DYTWO(K,JJ))
11600     SUMLAM=SUMLAM-0.6*DX*YEFIVE(K)
11700     305 AMATRX(1,K+1)=SUM1K
11800     AMATRX(1,IMAX+2)=SUMLAM
11900     C*NOW THE MIDDLE ROWS OF THE AMATRX.
12000     DO 410 LROW=2,IMAX+1
12100     SUM2B=0.0
12200     II=LROW-1
12300     DO 415 JJ=JBEGIN(II),JMAX
12400     415 SUM2B=SUM2B+2.*EXPON*Z(II,JJ)*DYMONE(II,JJ)-4.*EXPON*
12500     * B*DYONE(II,JJ)
12600     AMATRX(LROW,1)=SUM2B+XLAMB*DX*YETWO(II)
12700     DO 430 II=1,IMAX
12800     SUM2Y=0.0
12900     DO 425 JJ=JBEGIN(II),JMAX
13000     425 SUM2Y=SUM2Y+2.*EXPON*THIRD*B*Z(II,JJ)*DYMFOR(II,JJ)+THIRD*EXPON
13100     * 2.*B*B*DYMTWO(II,JJ)
13200     IF((II+1).EQ.LROW) GO TO 431
13300     AMATRX(LROW,II+1)=0.0
13400     GO TO 430
13500     431 AMATRX(LROW,II+1)=SUM2Y-XLAMB*EXPON*DX*B*YEMONE(II)
13600     430 CONTINUE
13700     410 AMATRX(LROW,IMAX+2)=DX*B*YETWO(LROW-1)
13800     C*NOW THE LAST ROW OF THE MATRIX A
13900     SUMFB=0.0
14000     DO 450 II=1,IMAX
14100     450 SUMFB=SUMFB+0.6*DX*YEFIVE(II)
14200     AMATRX(IMAX+2,1)=SUMFB

```

```

14300      DO 453  II=1,IMAX
14400      453  AMATRX(IMAX+2,II+1)=-DX*B*YETWO(II)
14500      AMATRX(IMAX+2,IMAX+2)=O.O
14600      C*NOW MUST INPUT THE BMATRX.
14700      SUMF1A=O.O
14800      SUMF1B=O.O
14900      DO 455  II=1,IMAX
15000      SUMF1B=SUMF1B+XLAMB*O.6*DX*YEFIVE(II)
15100      DO 455  JJ=JBEGIN(II),JMAX
15200      455  SUMF1A=SUMF1A-2.*(Z(II,JJ)-B*DYTWO(II,JJ))*DYTWO(II,JJ)
15300      BMATRX(1,1)=- (SUMF1A-SUMF1B)
15400      DO 460  II=1,IMAX
15500      SUMFII=O.O
15600      DO 462  JJ=JBEGIN(II),JMAX
15700      462  SUMFII=SUMFII+2.*(Z(II,JJ)-B*DYTWO(II,JJ))*EXPON*B*DYMONE(II,JJ)
15800      SUMFII=SUMFII+XLAMB*DX*B*YETWO(II)
15900      460  BMATRX(II+1,1)=-SUMFII
16000      SUMV=O.O
16100      DO 465  II=1,IMAX
16200      465  SUMV=SUMV+O.6*DX*B*YEFIVE(II)
16300      BMATRX(IMAX+2,1)=- (SUMV-VMEAS)
16400      C*NEXT LET'S CALL THE MATRIX INVERSION ROUTINE VIA IMSL
16500      CALL LEQT2F(AMATRX,1,IMAX+2,23,BMATRX,3,WKAREA,IER)
16600      C*THE SOLN IS RETURNED IN THE VECTOR BMATRX
16700      C*FINALLY, WE MUST UPDATE THE X VECTOR IN AX=B.
16800      B=B+BMATRX(1,1)
16900      XLAMB=XLAMB+BMATRX(IMAX+2,1)
17000      DO 470  II=1,IMAX
17100      470  YDEL(II)=YDEL(II)+BMATRX(II+1,1)
17200      C*CHECK THE CRITERION FOR COMPLETION
17300      SUMVEC=O.O
17400      DO 475  II=1,IMAX
17500      475  SUMVEC=SUMVEC+ABS(BMATRX(II,1))
17600      IF(SUMVEC.LT.(O.1*(IMAX+2))) GO TO 11
17700      WRITE(6,*) B,ITER,(I,YDEL(I),I=1,IMAX),XLAMB
17800      10  CONTINUE
17900      11  CONTINUE
18000      C*LET'S WRITE IT ALL OUT.
18100      WRITE(6,*) ITER,B,(I,YDEL(I),I=1,IMAX)
18200      STOP
18300      END

```

## APPENDIX E

### USER DOCUMENTATION AND INPUT AND OUTPUT FOR PROGRAM VERIFICATION

The computer program presented in Appendix B was run on a Burroughs B-7700 computer. The B7000/B6000 series FORTRAN language was designed so several existing programs written in FORTRAN would be compatible with minimal changes. It was designed to be compatible with Fortram IV, H level and to contain ANSI X3.9-1966 Standard FORTRAN as a subset.

Line 37,200 of the coding (see App. B) requires a subroutine from the IMSL subroutine package, LEQT1B and its associated subroutines. If the user's computing center has access to this package of subroutine programs they need only bind them to the program (note: copyright laws prohibited the inclusion of the IMSL coding). If not, a substitute subroutine must be user supplied. It must facilitate the solution of a banded storage mode matrix.

The program input will be described here using a card deck set-up, however, the use of diskpack or magnetic tape input follows directly. Lines 3100, 4100, 5500, 5900, 6800, 7500, and 12,900 are read statements. The cards used for the simulation presented in this appendix are shown in Figure E-1. The first card contains the value of WDEPTH, the depth of water (in meters) to which the input wave conditions are to be transformed (a partial list of variables used in the program is presented beginning on page A-8 of Appendix A). The format statements are obviously in the program coding.

The second data input card is read by line 4100 where the variables SJETTY, BERM, SFACE, and DIAM are required (length of the structure, berm height, shore face slope, and sediment diameter, respectively).

Lines 5500 reads MMAX, the number of structures to be simulated (as set-up here, a maximum of 10 structures can be modeled, however, appropriate changes in array dimensions would allow additions (structures). Line 5900, which is in a "DO" loop reads the lesser I grid value adjacent to where the structure is desired. The number of structures, MMAX, determines the number of data cards required here; 3 structures require 3 cards with the 3 I grid locations (note, the present configuration of the refraction and diffraction subroutines requires evenly spaced structures, however this can be altered if necessary).

The parameter ADEAN, which represents the value of A in the equilibrium profile used is the next value input (line 6800). As mentioned previously, whenever possible a site-specific value should be used. The space-step and time-step (DX and DELT in the coding) are input next (line 7500).

The last input values are the wave data, HS, T, ALPWIS read by line 12,900. This statement is in a loop made by the unconditional GO TO statement (line 16,400) and the read statement. There is an action specifier included in the read statement to transfer the program to statement 1000, thereby stopping execution of the program once all the wave climate data have been used. The number of data cards required for this read statement is dictated by the length of the simulation and the time-step used.

The input file and output for program verification follow.





.....  
 TO WHAT DEPTH ARE THE WAVES TO BE TRANSFORMED  
 THE DEPTH (IN FT) WAVES TRANSFORMED TO WDEPTH= 32 808  
 .....  
 ITS TIME FOR SUEITY, BERM, SPACE, AND DIAM  
 .....  
 THE LENGTH OF THE STRUCTURE, SUEITY= 300 000  
 THE HEIGHT OF THE BERM BERM= 5 000  
 THE SLOPE OF THE BEACH FACE, SPACE= 0 0500  
 THE SEDIMENT DIAMETER, DIAM= 0 220  
 .....  
 THE NUMBER 1 GROIN IS LOCATED AT GRID 25  
 .....  
 NOW ENTER THE VALUE OF ADEAN  
 THE VALUE OF ADEAN= 0 1500 IN THE EQ H=AV\*\*2/3  
 .....  
 READ IN THE SPACE STEP TIME STEP

THE VALUE OF THE LONGSHORE SPACE STEP, DELT= 100 000  
 THE TIME STEP IN SECONDS, DELT= 21600 000  
 .....  
 THE BOUNDARY X VALUES, I=1, IMAX ARE AS FOLLOWS

0 00 31 62 68 01 137 71 252 98 464 76 760 73 1050 41 1656 50 2674 85  
 0 00 31 62 68 01 137 71 252 98 464 76 760 73 1050 41 1656 50 2674 85  
 .....

THE DEPTHS BETWEEN CONTOURS ARE AS FOLLOWS

1 00 2 00 3 00 5 00 7 00 11 00 14 00 17 00 25 00 32 81  
 .....

- NIMIV\*1.
- NIMIV\*2.
- NIMIV\*3.
- NIMIV\*4.
- NIMIV\*5.
- NIMIV\*6.
- NIMIV\*7.
- NIMIV\*8.
- NIMIV\*9.
- NIMIV\*10.

THE TOTAL ELAPSED NUMBER OF TIME STEPS, NIMIV= 10

THE LONGSHORE TRANSCRIPTS OF FOLLO

0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000  
 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000  
 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000 0 000







THE NEW (CONTOUR VALUES, Y, FOLLOW

0 040	0 056	0 078	0 109	0 152	0 212	0 294	0 406	0 534	0 685	0 831	0 921	0 029
0 832	0 686	0 515	0 401	0 294	0 212	0 151	0 108	0 078	0 056	0 040	0 029	-0 021
0 015	0 011	0 008	0 005	0 004	0 003	0 002	0 001	0 001	0 000	0 000	0 000	0 000
31 621	31 626	31 631	31 636	31 643	31 650	31 661	31 674	31 692	31 714	31 744	31 784	31 835
31 902	31 988	32 101	32 248	32 438	32 683	32 997	33 396	33 893	34 481	35 191	35 766	27 425
28 051	28 751	29 351	29 849	30 248	30 563	30 809	30 999	31 145	31 258	31 345	31 412	31 463
31 502	31 532	31 555	31 572	31 585	31 595	31 603	31 610	31 615	31 619	31 623	31 623	31 623
68 011	68 058	68 076	68 096	68 119	68 147	68 182	68 226	68 281	68 351	68 439	68 550	68 690
68 864	69 083	69 356	69 605	70 115	70 634	71 274	72 057	73 013	74 157	75 548	76 758	59 315
61 527	61 920	63 064	64 024	61 805	65 449	65 565	66 380	66 729	67 002	67 221	67 395	67 535
67 645	67 733	67 813	67 888	67 902	67 936	67 964	67 988	68 007	68 025	68 041	68 041	68 041
117 706	137 763	137 811	137 878	137 945	138 022	138 114	138 225	138 358	138 519	138 713	138 947	139 229
139 568	139 873	140 457	141 032	141 714	142 521	143 471	144 566	145 895	147 408	149 231	150 840	124 560
126 171	127 997	129 512	130 822	131 939	132 891	133 698	134 381	134 957	135 441	135 847	136 185	136 468
136 702	136 896	137 057	137 190	137 300	137 392	137 468	137 536	137 594	137 650	137 706	137 762	137 818
252 982	253 067	253 150	253 234	253 321	253 411	253 507	253 608	253 716	253 831	253 952	254 081	254 217
254 358	254 505	254 655	254 805	254 951	255 090	255 215	255 319	255 393	255 427	255 404	255 349	250 614
250 559	250 535	250 569	250 643	250 747	250 872	251 011	251 158	251 308	251 458	251 605	251 747	251 883
252 012	252 134	252 249	252 357	252 458	252 554	252 645	252 731	252 815	252 898	252 982	253 066	253 150
464 758	464 759	464 761	464 761	464 761	464 763	464 764	464 765	464 766	464 767	464 768	464 770	464 771
464 773	464 774	464 775	464 775	464 775	464 775	464 774	464 773	464 771	464 769	464 766	464 761	464 756
464 752	464 748	464 744	464 742	464 741	464 740	464 739	464 740	464 740	464 741	464 742	464 744	464 745
464 746	464 748	464 749	464 750	464 751	464 752	464 753	464 754	464 755	464 756	464 757	464 758	464 759
760 725	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726
760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726
760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726	760 726
1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414
1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414
1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414	1050 414

MINIV 21.  
 MINIV 22  
 MINIV 23.  
 MINIV 24.  
 MINIV 25  
 MINIV 26.  
 MINIV 27.  
 MINIV 28.  
 MINIV 29

THE TOTAL ELAPSED NUMBER OF TIME STEPS, MINIV= 30

THE LONGEST-RE TRANS-PARTS, Q= FOLLOW

0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000
0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000
0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000
0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000	0 000



THE NEW CONTOUR VALUES, Y, FOLLOW

0 000 0 003 0 007 0 011 0 016 0 022 0 029 0 038 0 050 0 064 0 083 0 107 0 137  
 0 177 0 227 0 293 0 377 0 484 0 618 0 783 0 977 1 196 1 471 1 623 1 750 1 751  
 -1 624 1 422 1 196 0 978 0 783 0 618 0 484 0 377 0 293 0 227 0 176 0 137 0 106  
 -0 083 -0 064 -0 040 0 018 0 029 0 022 0 016 -0 011 -0 007 -0 003 0 000 0 000 0 000  
 31 623 31 642 31 662 31 685 31 710 31 738 31 771 31 817 31 860 31 918 31 990 32 077 32 184  
 32 314 32 474 32 659 32 908 33 198 33 551 33 975 34 480 35 075 35 754 36 512 37 118 26 122  
 26 729 27 487 28 168 28 764 29 270 29 695 30 048 30 339 30 577 30 773 30 933 31 063 31 170  
 31 257 31 328 31 387 31 435 31 475 31 508 31 537 31 561 31 584 31 604 31 623 31 638 31 648  
 68 011 68 045 68 150 68 208 68 270 68 340 68 421 68 516 68 626 68 757 68 913 69 098 69 318  
 69 580 69 872 70 264 70 706 71 211 71 854 72 592 73 466 74 458 75 700 77 129 78 357 79 714  
 58 945 60 376 61 540 62 614 63 489 64 229 64 852 65 378 65 821 66 192 66 505 66 767 66 987  
 67 172 67 327 67 458 67 569 67 661 67 741 67 814 67 876 67 933 67 988 68 041  
 137 706 137 828 137 941 138 064 138 191 138 312 138 489 138 666 138 868 139 099 139 366 139 674 140 030  
 140 442 140 920 141 473 142 114 142 856 143 716 144 710 145 860 147 192 148 718 150 542 152 146 123 254  
 124 860 126 687 128 213 129 547 130 699 131 694 132 554 133 298 133 939 134 493 134 971 135 384 135 740  
 136 048 136 315 136 547 136 748 136 926 137 082 137 222 137 350 137 468 137 585 137 706  
 252 982 253 115 253 241 253 372 253 501 253 633 253 769 253 908 254 051 254 198 254 348 254 502 254 657  
 254 814 254 969 255 120 255 264 255 397 255 514 255 608 255 672 255 695 255 669 255 573 255 454 250 509  
 250 190 250 293 250 266 250 290 250 353 250 447 250 564 250 697 250 842 250 994 251 149 251 306 251 462  
 251 616 251 765 251 913 252 057 252 196 252 332 252 464 252 593 252 721 252 850 252 982  
 464 758 464 761 464 761 464 765 464 768 464 770 464 772 464 774 464 776 464 778 464 780 464 782 464 784  
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1. Numerical model. 2. Shoreline evolution. 3. Sediment transport. 4. Wave transformation. 5. Littoral barrier. 1. Title.
- II. Dean, Robert G. III. Coastal Engineering Research Center (U.S.). IV. Series: Miscellaneous report (Coastal Engineering Research Center (U.S.).)

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