# A REMARK ON THE BLOWING-UP OF SOLUTIONS TO THE CAUCHY PROBLEM FOR NONLINEAR SCHRÖDINGER EQUATIONS 

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ABSTRACT. We consider solutions to $i u_{t}=\Delta u+|u|^{p-1} u, u(0)=u_{0}$, where $x$ belongs to a smooth domain $\Omega \subset \mathbf{R}^{N}$, and we prove that under suitable conditions on $p, N$ and $u_{0} \in H^{2}(\Omega) \cap H_{0}^{1}(\Omega),\|\nabla u(t)\|_{L^{2}}$ blows up in finite time. The range of $p$ 's for which blowing-up occurs depends on whether $\Omega$ is starshaped or not. Examples of blowing-up under Neuman or periodic boundary conditions are given.

RESUMÉ. On considère des solutions de $i u_{t}=\Delta u+|u|^{p-1} u, u(0)=u_{0}$, où la variable d'espace $x$ appartient à un domaine régulier $\Omega \subset \mathbf{R}^{N}$, et on prouve que sous des conditions adéquates sur $p, N$ et $u_{0} \in H^{2}(\Omega) \cap H_{0}^{1}(\Omega),\|\nabla u(t)\|_{L^{2}}$ explose en temps fini. Les valeurs de $p$ pour lesquelles l'explosion a lieu dépend de la forme de l'ouvert $\Omega$ (en fait $\Omega$ étoilé ou non). On donne également des exemples d'explosion sous des conditions de Neuman ou périodiques au bord.

1. Introduction and main results. Let $\Omega \subset \mathbf{R}^{N}$ (with $N \geq 1$ ) be a smooth domain and consider for $p>1$ the nonlinear Schrödinger equation (NLS),

$$
\left\{\begin{array}{l}
i u_{t}=\Delta u+|u|^{p-1} u \quad \text { on } \Omega,  \tag{1.1}\\
u(0, x)=u_{0}(x)
\end{array}\right.
$$

and

$$
\left\{\begin{array}{l}
i u_{t}=\Delta u-|u|^{p-1} u \quad \text { on } \Omega  \tag{1}\\
u(0, x)=u_{0}(x)
\end{array}\right.
$$

When $\Omega=\mathbf{R}^{N}$, it is well known that, under appropriate conditions on the smoothness of the initial data $u_{0}$, there exists a local solution (in time) to (1.1) and (1.1)_. For $(N-2) p<N+2$ and $u_{0} \in H^{1}\left(\mathbf{R}^{N}\right)$, the corresponding solution of (1.1) - is unique and exists globally in time. For $1<p<1+4 / N$ and $u_{0} \in H^{1}\left(\mathbf{R}^{N}\right)$ the solution of (1.1) is global. (See e.g. Th. Cazenave [1], J. Ginibre and G. Velo [2], and references of these papers.) For $p \geq 1+4 / N$ and initial data $u_{0} \in S\left(\mathbf{R}^{N}\right)$ such that the energy

$$
E\left(u_{0}\right)=\frac{1}{2} \int_{\mathbf{R}^{N}}\left|\nabla u_{0}\right|^{2} d x-\frac{1}{p+1} \int_{\mathbf{R}^{N}}\left|u_{0}\right|^{p+1} d x \leq 0
$$

R. T. Glassey [3] proves that there exists a finite time $T_{*}>0$ such that

$$
\lim _{t \uparrow T_{*}}\|\nabla u(t)\|_{L^{2}}=\infty
$$

[^0]When $\Omega=\mathbf{R}^{N}$, other examples of initial data for which the solution $u(t)$ blows up in finite time are known. H. Berestycki and Th. Cazenave [4] prove that if $R>0$ is a minimum-action solution ( $=$ ground state) of $-\Delta R+\omega R=R^{p}$ on $\mathbf{R}^{N}(p \geq 1+4 / N)$ for some $\omega>0$, then the solution $u(t)$ of (1.1) with initial data $u_{0}(x)=\lambda^{N / 2} R(\lambda x)(\lambda>1)$ blows up in finite time (note that $e^{-i \omega t} R(x)$ is a solitary wave solution of (NLS), and that $\left.E\left(u_{0}\right) \geq 0\right)$.

When $p=1+4 / N$ and $\Omega=\mathbf{R}^{N}$, Michael Wienstein has observed that if $R$ satisfies $-\Delta R+R=R^{p}$ on $\mathbf{R}^{N}$, then for $(a, b, c, d) \in \mathbf{R}^{4}, a d-b c=1$, the function

$$
\psi(t, x):=(a+b t)^{-N / 2} R\left(\frac{x}{a+b t}\right) \cdot \exp \left(i \frac{b|x|^{2}+c+d t}{a+b t}\right),
$$

is a solution of (NLS) which blows up in finite time (cf. M. Weinstein [5]).
When $\Omega \neq \mathbf{R}^{N}, N \leq 2$ and $p<1+4 / N, \mathrm{H}$. Brézis and Th. Gallouët [6] prove that, for $u_{0} \in H_{0}^{1}(\Omega)$, there exists a unique global solution to (1.1). But for $N \geq 3$, due to the fact that when $\Omega \neq \mathbf{R}^{N}$ the behavior of $e^{i t \Delta}$ is not well known, much less can be said about the global existence or the blowing-up of solutions in finite time. However for $p=1+4 / N, N=1$ or 2 and $\Omega$ being a ball, numerical computations made by A. Patera, C. Sulem, and P. L. Sulem $[\mathbf{7}, \mathbf{8}]$ suggest that there are solutions which blow up in finite time. In this paper we prove that depending on the shape of the domain $\Omega$ and the value of $p$ there are solutions of (1.1) which blow up in finite time. (We do not study local existence and uniqueness of the Cauchy problem (1.1). We suppose that a local solution is given and we prove that it blows up in finite time --or rather it cannot exist globally in some appropriate space-- whenever the initial data satisfies a certain set of conditions.)

The main results are the following.
(1.2) Proposition. Let $\Omega$ be a smooth starshaped domain in $\mathbf{R}^{N}$ and $p \geq$ $1+4 / N$. Let $T>0$ and consider a solution $u(t)$ of $(1.1)\left(\right.$ with $\left.u(0)=u_{0}\right)$ such that

$$
\begin{equation*}
u \in C^{1}\left([0, T], L^{2}(\Omega)\right) \cap C\left([0, T], H^{2} \cap H_{0}^{1} \cap L^{p+1}(\Omega)\right) \tag{1.3}
\end{equation*}
$$

Then if $\int_{\Omega}|x|^{2}\left|u_{0}(x)\right|^{2} d x<\infty$ and $u_{0}$ satisfies either of the following conditions (1.4) or (1.5), then there exists $T_{*}$ (depending on $u_{0}$ ) such that $T<T_{*}$ (i.e. the solution blows up in finite time).

$$
\begin{equation*}
E\left(u_{0}\right):=\frac{1}{2} \int_{\Omega}\left|\nabla u_{0}\right|^{2} d x-\frac{1}{p+1} \int_{\Omega}\left|u_{0}\right|^{p+1} d x<0 \tag{1.4}
\end{equation*}
$$

$$
\left\{\begin{array}{l}
E\left(u_{0}\right) \geq 0, \quad \operatorname{Im} \int_{\Omega}\left(x \cdot \nabla u_{0}\right) \bar{u}_{0}(x) d x>0 \quad \text { and }  \tag{1.5}\\
\left|\operatorname{Im} \int_{\Omega}\left(x \cdot \nabla u_{0}\right) u_{0}(x) d x\right|^{2} \geq E\left(u_{0}\right) \cdot \int_{\Omega}\left|x u_{0}(x)\right|^{2} d x
\end{array}\right.
$$

For a domain $\Omega$ which is not starshaped Proposition (1.6) holds ( $N \geq 2$ ):
(1.6) Proposition. Let $\omega$ be a smooth domain in $\mathbf{R}^{N}$, starshaped with respect to some point $x_{0} \in \omega$ and let $r>0$ such that $B\left(x_{0}, r\right) \subset \omega$. Then if $\Omega:=\omega \cap$ ${\overline{B\left(x_{0}, r\right)}}^{c}, p \geq 5$ and $u_{0}$ is such that $\int_{\Omega}|x|^{2}\left|u_{0}(x)\right|^{2} d x<\infty$ and satisfies either of conditions (1.4) or ( 1.5 bis ), then the solution of the ( $N L S$ ) (1.1) satisfying (1.3),
blows up in finite time.

$$
\left\{\begin{array}{l}
E\left(u_{0}\right) \geq 0, \quad \operatorname{Im} \int\left(\nabla \varphi \cdot \nabla u_{0}\right) \bar{u}_{0}(x) d x>0 \quad \text { and }  \tag{1.5bis}\\
\left|\operatorname{Im} \int\left(\nabla \varphi \cdot \nabla u_{0}\right) \bar{u}_{0}(x) d x\right|^{2} \geq 4 N E\left(u_{0}\right) \int \varphi(x)\left|u_{0}(x)\right|^{2} d x
\end{array}\right.
$$

where

$$
\varphi(x):=\frac{1}{2}\left|x-x_{0}\right|^{2}+\frac{r^{N}}{(N-2)\left|x-x_{0}\right|^{N-2}} \quad \text { when } N \geq 3
$$

and

$$
\varphi(x):=\frac{1}{2}\left|x-x_{0}\right|^{2}-r^{2} \log \left|x-x_{0}\right| \quad \text { when } N=2
$$

If one is interested in the blowing-up of solutions which satisfy other boundary value conditions than Dirichlet (i.e. $\left.H_{0}^{1}(\Omega)\right)$ such as Neuman or periodic conditions, one can construct such solutions using (1.2) (cf. Remark 4.9 below). Note that the condition $\int_{\Omega}|x|^{2}\left|u_{0}(x)\right|^{2} d x<\infty$ is satisfied when $\Omega$ is bounded and $u_{0} \in H_{0}^{1}(\Omega)$; actually this condition seems technical when $\Omega$ is unbounded and one can give the following variant of Proposition (1.2).
(1.7) Proposition. Let $\Omega$ be a smooth domain in $\mathbf{R}^{N}$ such that there exists $k_{\leq N}^{\geq 1}, a \in \mathbf{R}^{N}$ and $1 \leq j_{1}<j_{2}<\cdots<j_{k} \leq N$ such that if $\vec{n}(x)$ is the outer normal to the boundary $\partial \Omega$ one has

$$
\forall x \in \partial \Omega \quad\left(x_{j_{1}}-a_{j_{1}}\right) n_{j_{1}}(x)+\cdots+\left(x_{j_{k}}-a_{j_{k}}\right) n_{j_{k}}(x) \geq 0
$$

Then if $u_{0} \in H_{0}^{1}(\Omega)$ satisfies

$$
\begin{equation*}
\int_{\Omega}\left(\left|x_{j_{1}}\right|^{2}+\cdots+\left|x_{j_{k}}\right|^{2}\right)\left|u_{0}(x)\right|^{2} d x<\infty \tag{1.8}
\end{equation*}
$$

and either of conditions (1.4) or (1.9), the solution $u$ of (1.1) satisfying (1.3) blows $u p$ in finite time if $p \geq 1+4 / k$.

$$
\left\{\begin{array}{l}
E\left(u_{0}\right) \geq 0, \quad \operatorname{Im} \int\left(\nabla \varphi \cdot \nabla u_{0}\right) \bar{u}_{0}(x) d x>0 \quad \text { and }  \tag{1.9}\\
\left|\operatorname{Im} \int_{\Omega}\left(\nabla \varphi \cdot \nabla u_{0}\right) \bar{u}_{0}(x) d x\right|^{2} \geq 2 E\left(u_{0}\right) \int \varphi\left|u_{0}(x)\right|^{2} d x
\end{array}\right.
$$

where

$$
\varphi(x)=\frac{1}{2}\left(\left|x_{j_{1}}-a_{j_{1}}\right|^{2}+\cdots+\left|x_{j_{k}}-a_{j_{k}}\right|^{2}\right)
$$

In particular if $\Omega$ is bounded in $k$ directions and $p \geq 1+4 / k$ the condition (1.8) is fulfilled and the only condition for the blowing-up is (1.4) (or (1.9)).

It is clear that the condition $p \geq 1+4 / k$ in (1.7) is not optimal in the sense that $p<1+4 / k$ does not imply global existence. In $\S 4.7$ we prove that the condition $p \geq 5$ in (1.6) is optimal in the sense that there are global solutions for $p<5$ and any value of $E\left(u_{0}\right)$; at the same time there are solutions which blow up when $1+4 / N \leq p<5$ (and $E\left(u_{0}\right) \leq 0$ ).

The proof of these results is a slight modification of the one given by R.T. Glassey [3] (see below).

The author wishes to thank Alain Haraux who brought his attention to this question.
2. Preliminary results. In what follows, we consider a sufficiently smooth solution of (1.1) for which the following hold for some $T>0$ :

$$
\begin{align*}
& i u_{t}=\Delta u+|u|^{p-1} u .  \tag{1.1}\\
& u(0, x)=u_{0}(x) \not \equiv 0 \\
& u(t) \in H_{0}^{1}(\Omega) \text { for } 0 \leq|t| \leq T \quad \text { (Dirichlet boundary condition). } \\
& \int_{\Omega}|u(t, x)|^{2} d x=\int_{\Omega}\left|u_{0}(x)\right|^{2} d x \text { for } 0 \leq|t| \leq T . \\
& \frac{1}{2} \int_{\Omega}|\nabla u(t, x)|^{2} d x-\frac{1}{p+1} \int_{\Omega}|u(t, x)|^{p+1} d x=: E(u(t))=E\left(u_{0}\right)
\end{align*}
$$

$$
\text { for } 0 \leq|t| \leq T
$$

For instance any classical solution of (1.1) satisfies (2.3) and (2.4). (To obtain (2.3) multiply the equation (1.1) by $\bar{u}$, integrate over $\Omega$ and take the imaginary part; to obtain (2.4) multiply (1.1) by $\bar{u}_{t}$, take the real part and integrate over $\Omega$.)

Following R. T. Glassey we consider the "variance" of $u$ (in fact that of $|u|^{2}$ ) but we modify this variance according to the shape of $\Omega$. More precisely let $\varphi$ satisfy

$$
\begin{equation*}
\varphi \geq 0, \quad \varphi \not \equiv 0, \quad \varphi \in C^{4}\left(\mathbf{R}^{N}\right) \tag{2.5}
\end{equation*}
$$

and define for $t \in[-T, T]$

$$
\begin{equation*}
V(t):=\frac{1}{2} \int_{\Omega} \varphi(x)|u(t, x)|^{2} d x \tag{2.6}
\end{equation*}
$$

Define also the Hessian of $\varphi$ by

$$
\begin{equation*}
H(\varphi)(x):=\left(\partial_{k j}^{2} \varphi(x)\right)_{1 \leq k, j \leq N} \tag{2.7}
\end{equation*}
$$

and for $\xi \in \mathbf{C}^{N}$

$$
\begin{equation*}
(H(\varphi) \xi \mid \xi):=\sum_{1 \leq k, j \leq N} \partial_{k j}^{2} \varphi(x) \xi_{j} \bar{\xi}_{k} . \tag{2.8}
\end{equation*}
$$

To prove the results about the blowing-up of solutions we prove first the following lemma and in the next sections we choose the function $\varphi$ according to $\Omega$.
(2.9) Lemma. Let $u \in C^{1}\left([0, T], L^{2}(\Omega)\right) \cap C\left([0, T], H^{2} \cap H_{0}^{1} \cap L^{p+1}(\Omega)\right)$ be a solution of (1.1) with $u(0, x)=u_{0}(x), \varphi$ satisfying (2.5) with compact support and $V$ defined as in (2.6). Then $V \in C^{2}([0, T])$ and for each $t$ one has

$$
\begin{aligned}
V^{\prime}(t)= & \operatorname{Im} \int_{\Omega} \varphi(x) \bar{u}(t, x) \Delta u(t, x) d x \\
V^{\prime \prime}(t)= & 2 \int_{\Omega}(H(\varphi) \nabla u \mid \nabla u)(t, x) d x \\
& +\left(\frac{2}{p+1}-1\right) \int_{\Omega} \Delta \varphi \cdot|u|^{p+1}(t, x) d x \\
& -\frac{1}{2} \int_{\Omega} \Delta^{2} \varphi \cdot|u|^{2}(t, x) d x \\
& -\int_{\partial \Omega}|\nabla u(t, x) \cdot \vec{n}(x)|^{2} \nabla \varphi(x) \cdot \vec{n}(x) d x
\end{aligned}
$$

where $\vec{n}(x)$ is the outer normal at $x \in \partial \Omega(\Omega$ is supposed to be smooth).

Proof. The fact that $V \in C^{2}$ is straightforward, but for the sake of completeness we sketch here the proof. As $\varphi \in C_{c}^{4}\left(\mathbf{R}^{N}\right)$ and $u \in C^{1}\left([-T, T], L^{2}(\Omega)\right)$ it is clear that $V \in C^{1}([-T, T])$ and

$$
V^{\prime}(t)=\operatorname{Re} \int_{\Omega} \varphi \bar{u}(t, x) u_{t}(t, x) d x
$$

but by (1.1) $u_{t}=-i \Delta u-i|u|^{p-1} u$ and hence (denoting by $\langle\cdot, \cdot\rangle$ the duality $\left.H^{-1}, H_{0}^{1}\right)$ :

$$
V^{\prime}(t)=\operatorname{Im}\langle\Delta u(t), \varphi \bar{u}(t)\rangle
$$

Now, for $h \in \mathbf{R}, h \neq 0$, we have

$$
\begin{align*}
V^{\prime}(t+h)-V^{\prime}(t)= & \operatorname{Im}\langle\Delta u(t+h), \varphi[\bar{u}(t+h)-\bar{u}(t)]\rangle  \tag{2.10}\\
& +\operatorname{Im}\langle\Delta(u(t+h)-u(t)), \varphi \cdot \bar{u}(t)\rangle
\end{align*}
$$

or, equivalently,

$$
\begin{align*}
V^{\prime}(t+h)-V^{\prime}(t)= & \operatorname{Im}\langle\Delta(u(t+h)-u(t)), \varphi[\bar{u}(t+h)-\bar{u}(t)]\rangle  \tag{2.11}\\
& +2 \operatorname{Im} \int_{\Omega} \nabla \varphi \cdot \nabla \bar{u}(t)[u(t+h)-u(t)] d x \\
& +\operatorname{Im} \int_{\Omega} \Delta \varphi \cdot \bar{u}(t)[u(t+h)-u(t)] d x
\end{align*}
$$

The first term in (2.11) can be written as

$$
\begin{align*}
& \operatorname{Im}\langle\Delta(u(t+h)-u(t)), \varphi[\bar{u}(t+h)-\bar{u}(t)]\rangle  \tag{2.12}\\
& \quad=-\operatorname{Im} \int_{\Omega}[\bar{u}(t+h)-\bar{u}(t)] \nabla \varphi \cdot \nabla(u(t+h)-u(t)) d x
\end{align*}
$$

and using the fact that $u \in C^{1}\left([-T, T], L^{2}(\Omega)\right)$ and $u \in C\left([-T, T], H_{0}^{1}(\Omega)\right)$, one sees that by (2.11), (2.12) $\lim _{h \rightarrow 0} \frac{1}{h}\left[V^{\prime}(t+h)-V^{\prime}(t)\right]$ exists and

$$
\begin{equation*}
V^{\prime \prime}(t)=2 \operatorname{Im} \int_{\Omega} \nabla \varphi \cdot \nabla \bar{u}(t) \cdot u_{t}(t) d x+\operatorname{Im} \int_{\Omega} \Delta \varphi \cdot \bar{u}(t) u_{t}(t) d x \tag{2.13}
\end{equation*}
$$

This identity proves that $V \in C^{2}([-T, T])$.
In the sequel, for the sake of simplicity we drop the subscript $\Omega$, the variable $t$ and set

$$
\begin{align*}
A_{1} & :=\operatorname{Im} \int \nabla \varphi \cdot \nabla \bar{u} \cdot u_{t} d x  \tag{2.14}\\
A_{2} & :=\operatorname{Im} \int \Delta \varphi \cdot \bar{u} \cdot u_{t} d x \tag{2.15}
\end{align*}
$$

(so $V^{\prime \prime}=2 A_{1}+A_{2}$ ). By (1.1) one has $u_{t}=-i \Delta u-i|u|^{p-1} u$, and we can study $A_{1}, A_{2}$.

For $A_{2}$ : an integration by parts give

$$
A_{2}=-\operatorname{Re} \int \Delta \varphi \cdot|u|^{p+1} d x+\operatorname{Re} \int \Delta \varphi \cdot|\nabla u|^{2} d x+\operatorname{Re} \int \bar{u} \nabla u \cdot \nabla(\Delta \varphi) d x
$$

But $\operatorname{Re} \bar{u} \nabla u=\frac{1}{2} \nabla\left(|u|^{2}\right)$ and hence

$$
\begin{equation*}
A_{2}=-\operatorname{Re} \int \Delta \varphi|u|^{p+1} d X+\operatorname{Re} \int \Delta \varphi \cdot|\nabla u|^{2} d x-\frac{1}{2} \int \Delta^{2} \varphi \cdot|u|^{2} d x \tag{2.16}
\end{equation*}
$$

For $A_{1}$ : using (1.1) we have by integration by parts

$$
\begin{align*}
& A_{1}=-\operatorname{Re} \int(\nabla \varphi \cdot \nabla \bar{u}) \Delta u d X-\operatorname{Re} \int \nabla \varphi \cdot \nabla u \cdot|u|^{p-1} u d x \\
& A_{1}=-\operatorname{Re} \int(\nabla \varphi \cdot \nabla \bar{u}) \Delta u d x-\frac{1}{p+1} \int \nabla \varphi \cdot \nabla\left(|u|^{p+1}\right) d x  \tag{2.17}\\
& A_{1}=-\operatorname{Re} \int(\nabla \varphi \cdot \nabla \bar{u}) \Delta u d x+\frac{1}{p+1} \int \Delta \varphi \cdot|u|^{p+1} d x .
\end{align*}
$$

On the other hand

$$
-\operatorname{Re} \int(\nabla \varphi, \nabla \bar{u}) \Delta u d x=B_{1}+B_{2}+B_{3}
$$

where

$$
\begin{align*}
& B_{1}:=-\operatorname{Re} \int_{\partial \Omega}(\nabla \varphi \cdot \nabla u)(\nabla \bar{u} \cdot \vec{n}) d x,  \tag{2.18}\\
& B_{2}:=\operatorname{Re} \sum_{1 \leq k \leq N} \int_{\Omega} \partial_{k} \varphi\left(\nabla \bar{u} \cdot \partial_{k} \nabla u\right) d x,  \tag{2.19}\\
& B_{3}:=\operatorname{Re} \sum_{1 \leq k \leq N} \int_{\Omega} \partial_{k} u\left(\nabla \bar{u} \cdot \partial_{k} \nabla \varphi\right) d x .
\end{align*}
$$

First note that by (2.8), $B_{3}$ can be written

$$
\begin{equation*}
B_{3}=\int_{\Omega}(H(\varphi) \nabla u \mid \nabla u) d x . \tag{2.20}
\end{equation*}
$$

We remark also that $\operatorname{Re} \nabla \bar{u} \cdot \partial_{k} \nabla u=\frac{1}{2} \partial_{k}|\nabla u|^{2}$ and hence

$$
\begin{gather*}
B_{2}=\int_{\Omega} \nabla \varphi \cdot \nabla\left(\frac{1}{2}|\nabla u|^{2}\right) d x  \tag{2.21}\\
B_{2}=\frac{1}{2} \int_{\partial \Omega}(\nabla \varphi \cdot \vec{n})|\nabla u|^{2} d x-\frac{1}{2} \int_{\Omega} \Delta \varphi|\nabla u|^{2} d x
\end{gather*}
$$

Concerning $B_{1}$, note that $\left.u\right|_{\partial \Omega}=0$ and hence on $\partial \Omega \nabla u=(\nabla u \cdot \vec{n}) \vec{n}$ : this yields

$$
B_{1}=-\int_{\partial \Omega}(\nabla \varphi \cdot \vec{n})|\nabla u|^{2} d x
$$

Finally using this and (2.21), (2.20) we get

$$
\begin{aligned}
A_{1}= & -\frac{1}{2} \int_{\partial \Omega}(\nabla \varphi \cdot \vec{n})|\nabla u|^{2} d x-\frac{1}{2} \int_{\Omega} \Delta \varphi|\nabla u|^{2} d x \\
& +\int_{\Omega}(H(\varphi) \nabla u \mid \nabla u) d x+\frac{1}{p+1} \int_{\Omega} \Delta \varphi|u|^{p+1} d x
\end{aligned}
$$

and this, together with (2.16), gives the lemma.
Now for the proof of the propositions of $\S 1$, we have to choose an appropriate function $\varphi$.
3. Proof of Proposition (1.2) and (1.7). Without loss of generality we may assume that $\Omega$ is starshaped with respect to $0 \in \Omega$, i.e.

$$
\begin{equation*}
\forall x \in \partial \Omega, \quad x \cdot \vec{n}(x) \geq 0 \tag{3.1}
\end{equation*}
$$

First let $\psi \in C_{c}^{\infty}(\mathbf{R})$ be such that

$$
\begin{gathered}
\psi(-y)=\psi(y) \quad \forall y \in \mathbf{R} \\
\psi(y)=1 \quad \text { for }|y| \leq 1, \\
\psi(y)=0 \quad \text { for }|y| \geq 2 \\
\psi^{\prime}(y) \leq 0
\end{gathered} \quad \forall y \in \mathbf{R}_{+}, ~ \$
$$

and define $f_{m}(x):=\psi(|x| / m)$ for $x \in \mathbf{R}^{N}$ and $m \geq 1$. Next, for a solution $u$ such as in Proposition (1.2), define

$$
V(t):=\frac{1}{4} \int_{\Omega}|x|^{2}|u(t, x)|^{2} d x
$$

and

$$
V_{m}(t):=\frac{1}{4} \int_{\Omega}|x|^{2} f_{m}(x)|u(t, x)|^{2} d x
$$

By Lemma 2.9 we know that

$$
\begin{aligned}
V_{m}^{\prime \prime}(t)= & 2 \int_{\Omega}\left(H\left(\varphi_{m}\right) \nabla u \mid \nabla u\right)(t, x) d x \\
& +\left(\frac{2}{p+1}-1\right) \int_{\Omega} \Delta \varphi_{m}|u|^{p+1}(t, x) d x \\
& -\frac{1}{2} \int_{\Omega} \Delta^{2} \varphi_{m}|u|^{2}(t, x) d x \\
& -\int_{\partial \Omega}|\nabla u(t, x)|^{2} \nabla \varphi_{m}(x) \cdot \vec{n}(x) d x
\end{aligned}
$$

where

$$
\varphi_{m}:=\frac{1}{2}|x|^{2} f_{m}(x)
$$

and by the above hypotheses on $\varphi_{m}$ and $u$ one sees easily that $\left(V_{m}^{\prime \prime}\right)_{m}$ converges in $L^{1}([-T, T])$ to

$$
\begin{align*}
W(t):= & 2 \int_{\Omega}|\nabla u|^{2}(t, x) d x+\left(\frac{2}{p+1}-1\right) N \int_{\Omega}|u|^{p+1}(t, x) d x  \tag{3.2}\\
& -\int_{\partial \Omega}|\nabla u(t, x)|^{2} x \cdot \vec{n}(x) d x
\end{align*}
$$

(here we use the fact that if $\varphi(x):=\frac{1}{2}|x|^{2},(H(\varphi) \nabla u \mid \nabla u)=|\nabla u|^{2}$ and $\left.\Delta \varphi=N\right)$. On the other hand $V_{m}(t) \uparrow V(t)$ as $m \rightarrow \infty$ and

$$
\begin{align*}
V_{m}^{\prime}(t) & =\operatorname{Im} \int_{\Omega} \varphi_{m} \bar{u}(t, x) \Delta u(t, x) d x \\
& =\operatorname{Im} \int_{\Omega} \bar{u}(t, x) \nabla \varphi_{m}(x) \cdot \nabla u(t, x) d x \\
V_{m}(t) & =V_{m}(0)+V_{m}^{\prime}(0) \cdot t+\int_{0}^{t}(t-s) V_{m}^{\prime \prime}(s) d s  \tag{3.3}\\
V_{m}^{\prime}(0) & \rightarrow-\operatorname{Im} \int_{\Omega} \bar{u}_{0}(x) x \cdot \nabla u_{0}(x) d x \\
V(t) & =V(0)-\left(\operatorname{Im} \int_{\Omega} \bar{u}_{0}(x) x \cdot \nabla u_{0}(x) d x\right) t+\int_{0}^{t}(t-s) W(s) d s
\end{align*}
$$

But by (2.4) and (3.1) we have

$$
\begin{aligned}
W(t) & \leq 4 E\left(u_{0}\right)+\left(\frac{2 N+4}{p+1}-N\right) \int_{\Omega}|u(t, x)|^{p+1} \\
& \leq 4 E\left(u_{0}\right) \leq 0 \quad \text { if } p \geq 1+4 / N
\end{aligned}
$$

and hence

$$
\begin{equation*}
0<V(t) \leq V(0)-\left(\operatorname{Im} \int_{\Omega} \bar{u}_{0} x \cdot \nabla u_{0}(x) d x\right) t+2 E\left(u_{0}\right) \cdot t^{2} . \tag{3.4}
\end{equation*}
$$

Now it is clear that if $u_{0}$ satisfies (1.4) or (1.5) the solution $u(t)$ cannot exist globally (notice that if $E\left(u_{0}\right)<0$, the blow-up occurs for some $T_{*}>0$ and also for some $T_{* *}<0$ ). This proves Proposition (1.2).

The proof of Proposition (1.7) is the same as above by choosing (we may suppose $a=0$ )

$$
\varphi(x):=\frac{1}{2}\left(\left|x_{j_{1}}\right|^{2}+\cdots+\left|x_{j_{k}}\right|^{2}\right)
$$

and then $\Delta \varphi=k, \Delta^{2} \varphi=0$

$$
\begin{gathered}
(H(\varphi) \nabla u \mid \nabla u)=\left|\partial_{j_{1}} u\right|^{2}+\cdots+\left|\partial_{j_{k}} u\right|^{2} \leq|\nabla u|^{2} \\
\nabla \varphi \cdot \vec{n}=x_{j_{1}} \cdot n_{j_{1}}(x)+\cdots+x_{j_{k}} \cdot n_{j_{k}}(x) \geq 0 \\
W(t) \leq 4 E\left(u_{0}\right)+\left(\frac{2 k+4}{p+1}-k\right) \int_{\Omega}|u(t, x)|^{p+1} d x
\end{gathered}
$$

( $W$ is defined in 3.2). Now if $p \geq 1+4 / k$ one has $W(t) \leq 4 E\left(u_{0}\right)$ and hence one observes that (3.4) holds and the proof of Proposition 1.7 is over.
4. Proof of Proposition (1.6). Without loss of generality one can assume that $x_{0}=0$ and $r=1$. Thus

$$
\partial \Omega=\left\{x \in \mathbf{R}^{N} ;|x|=1\right\} \cup \partial \omega
$$

(note that $\partial \omega \cap\{x ;|x|=1\}=\varnothing$ ), and denoting by $\vec{n}(x)$ the outward normal at $x \in \partial \Omega$ on has

$$
\begin{cases}\text { if }|x|=1 & \vec{n}(x)=-x  \tag{4.1}\\ \text { if } x \in \partial \omega & \vec{n}(x) \cdot x \geq 0\end{cases}
$$

Now define for $x \in \bar{\Omega}$

$$
\begin{cases}\varphi(x):=\frac{1}{2}|x|^{2}+\frac{1}{(N-2)|x|^{N-2}} & \text { if } N \geq 3  \tag{4.2}\\ \varphi(x):=\frac{1}{2}|x|^{2}-\log |x| & \text { if } N=2\end{cases}
$$

(the case $N=1$ is already contained in Proposition (1.2)), and

$$
\begin{equation*}
V(t):=\frac{1}{2} \int_{\Omega} \varphi(x)|u(t, x)|^{2} d x \tag{4.3}
\end{equation*}
$$

As in $\S 3$, consider $f_{m}(x):=\psi(|x| / m)$ where $\psi \in C_{c}^{\infty}(\mathbf{R})$ and

$$
V_{m}(t):=\frac{1}{2} \int_{\Omega} \varphi(x) f_{m}(x)|u(t, x)|^{2} d x
$$

In the same fashion, one can check easily that $\left(V_{m}^{\prime \prime}\right)_{m}$ converges in $L^{1}([-T, T])$ to

$$
\begin{align*}
W(t):= & 2 \int_{\Omega}(H(\varphi) \nabla u \mid \nabla u)(t, x) d x \\
& +\left(\frac{2}{p+1}-1\right) N \int|u|^{p+1}(t, x) d x  \tag{4.4}\\
& -\int_{\partial \Omega}|\nabla u(t, x) \cdot \vec{n}(x)|^{2} \nabla \varphi \cdot \vec{n}(x) d x
\end{align*}
$$

(here we use the fact that $\Delta \varphi=N$ ).
But $\nabla \varphi=\left(1-|x|^{-N}\right) X$ and
if $x \in \partial \Omega|x|=1$ then $\nabla \varphi \cdot \vec{n}(x)=0$;
if $x \in \partial \omega$ then $\nabla \varphi(x) \cdot \vec{n}(x) \geq 0$.
This means that

$$
\begin{equation*}
\forall x \in \partial \Omega \quad \nabla \varphi(x) \cdot \vec{n}(x) \geq 0 \tag{4.5}
\end{equation*}
$$

On the other hand

$$
\partial_{k j}^{2} \varphi=\left(1-|x|^{-N}\right) \delta_{k j}+N|x|^{-(N+2)} x_{j} x_{k}
$$

and

$$
\begin{align*}
(H(\varphi) \nabla u \mid \nabla u) & \leq|\nabla u|^{2}+(N-1)|x|^{-N}|\nabla u|^{2}  \tag{4.6}\\
& \leq N|\nabla u|^{2} \quad \text { since }|x| \geq 1 .
\end{align*}
$$

Hence (4.5) and (4.6) yield

$$
\begin{aligned}
W(t) & \leq N\left(2 \int_{\Omega}|\nabla u|^{2}+\left(\frac{2}{p+1}-1\right) \int|u|^{p+1}\right) \\
& \leq N\left(4 E\left(u_{0}\right)+\left(\frac{6}{p+1}-1\right) \int|u|^{p+1}\right) \\
W(t) & \leq 4 N E\left(u_{0}\right) \quad(\text { since } p \geq 5) .
\end{aligned}
$$

So we get

$$
0<V(t) \leq V(0)+V^{\prime}(0) t+2 N E\left(u_{0}\right) t^{2}
$$

and again this proves Proposition (1.6), noting that (when $E\left(u_{0}\right) \geq 0$ )

$$
V^{\prime}(0)=\operatorname{Im} \int \varphi \bar{u}_{0} \Delta u_{0}=-\operatorname{Im} \int_{\Omega}\left(\nabla \varphi \cdot \nabla u_{0}\right) \bar{u}_{0}(x) d x
$$

(4.7) Remark. When $\Omega$ is starshaped and $N \leq 2, p<1+4 / N$ the solution of (1.1) satisfying (1.3) is global in time, no matter what the sign of $E\left(u_{0}\right)$ is. When $\Omega$ is not starshaped and $1+4 / N \leq p<5$ the situation is somewhat complicated.

Consider for instance $\Omega=B(0,1)^{c}$ where $B(0,1)=\left\{x \in \mathbf{R}^{N},|x| \leq 1\right\}, N \geq 2$.
If $u_{0}$ is spherically symmetric with respect to the origin 0 , it is clear that the solution $u(t)$ is spherically symmetric for each $t$. On the other hand if $\varphi \in C_{c}^{1}(\Omega)$ is spherically symmetric, then for any $\sigma \in \mathbf{R}^{N}$ with $|\sigma|=1$

$$
\begin{aligned}
|\varphi(r \sigma)|^{2} & =-2 \int_{r}^{\infty} \varphi(z \sigma) \sigma \cdot \nabla \varphi(z \sigma) d x \\
& \leq 2\left(\int_{1}^{\infty} z^{-(N-1)}|\varphi(z \sigma)|^{2} d z\right)^{1 / 2}\left(\int_{1}^{\infty} z^{N-1}|\nabla \varphi(z \sigma)|^{2} d z\right)^{1 / 2}
\end{aligned}
$$

and this yields

$$
\begin{equation*}
\|\varphi\|_{L^{\infty}(\Omega)} \leq C\|\varphi\|_{L^{2}}^{1 / 2}\|\nabla \varphi\|_{L^{2}}^{1 / 2} \tag{4.8}
\end{equation*}
$$

Now if $u(t)$ is a spherically symmetric solution of (1.1)

$$
\begin{aligned}
\|\nabla u(t)\|^{2} & \leq 2 E\left(u_{0}\right)+\frac{2}{p+1} \int|u(t)|^{p+1} \\
& \leq 2 E\left(u_{0}\right)+C\|u(t)\|_{L^{\infty}}^{p+1}\|u(t)\|_{L^{2}}^{2} .
\end{aligned}
$$

But $\|u(t)\|_{L^{2}}=\left\|u_{0}\right\|_{L^{2}}=C^{t e}$ and hence by (4.8) we get

$$
\|\nabla u(t)\|_{L^{2}}^{2} \leq C+C\|\nabla u(t)\|_{L^{2}}^{(p-1) / 2} .
$$

So if $p<5$ then $\|\nabla u(t)\|_{L^{2}} \leq C^{t e}$ and using again (4.8) we get a uniform estimate for $\|u(t)\|_{L^{\infty}}$ and this proves that the spherically symmetric solutions of (1.1) are global in time, whatever $E\left(u_{0}\right)$ can be.

Consider now, for the sake of simplicity, the case where $N=2, \Omega=B(0,1)^{c}$ and $1+4 / N \leq p<5$. We are going to construct a solution of (1.1) which blows up in finite time.

Let $\Omega_{+}:=\left\{(x, y) \in \mathbf{R}^{2}, x>0, y>0, x^{2}+y^{2}>1\right\}$.
It is clear that $\Omega_{+}$is starshaped with respect to the point $(1,1)$. Now let $v_{0} \in$ $C_{0}^{\infty}\left(\Omega_{+}\right)$be such that $E\left(v_{0}\right)<0$. By Proposition (1.2) the solution $v(t)$ of (1.1) with $v(t) \in H_{0}^{1}\left(\Omega_{+}\right)$and $v(0)=v_{0}$ blows up in finite time. If one considers $u(t)$ defined as

$$
u(t, x, y)= \begin{cases}v(t, x, y) & \text { if } x \geq 0, y \geq 0 \\ -v(t, x, y) & \text { if } x \geq 0, y \leq 0 \\ v(t,-x,-y) & \text { if } x \leq 0, y \leq 0 \\ -v(t,-x, y) & \text { if } x \leq 0, y \geq 0\end{cases}
$$

then $u(t)$ is a solution of (1.1) $u(t) \in H_{0}^{1}(\Omega)$ and blows up in finite time.
(4.9) REMARK. If one considers other boundary conditions than Dirichlet (that is other than $\left.u(t) \in H_{0}^{1}(\Omega)\right)$, using (1.2) one can construct solutions of (1.1) which blow up in finite time. Indeed consider, for example, the case where $N=1$, and the periodic boundary condition on $\Omega=]-1,+1[$, i.e.

$$
u(t,-1)=u(t,+1), \quad u_{x}(t,-1)=u_{x}(t,+1)
$$

If one takes an initial data $u_{0}$ such that

$$
u_{0}(-x)=-u_{0}(x) \quad \forall x \in[-1,+1], \quad u_{0} \in H_{0}^{1}(]-1,+1[)
$$

then the solution of (1.1) with $u(0, x)=u_{0}(x)$ satisfies

$$
\begin{aligned}
& u(t,-x)=-u(t, x) \quad \forall x \in[-1,+1] \\
& u(t,-1)=u(t,+1)=0, \quad u_{x}(t,-1)=u_{x}(t, 1)
\end{aligned}
$$

So if $p \geq 5$ and

$$
\frac{1}{2} \int_{-1}^{+1}\left|u_{0 x}\right|^{2}-\frac{1}{p+1} \int_{-1}^{+1}\left|u_{0}\right|^{p+1}<0
$$

the periodic solution $u(t)$ blows up in finite time (because it does so in $H_{0}^{1}([-\mathbf{1},+\mathbf{1}])$ by Proposition (1.2)).

For the Neuman boundary condition (i.e. for instance $\Omega=] 0,2\left[\right.$ and $u_{x}(t, 0)=$ $\left.u_{x}(t, 2)=0\right)$ consider an initial data $v_{0} \in H_{0}^{1}(-1,+1)$ such that

$$
\forall x \in[-1,+1] \quad v_{0}(x)=v_{0}(-x)
$$

$p \geq 5$ and

$$
\frac{1}{2} \int_{0}^{1}\left|v_{0 x}\right|^{2} d x-\frac{1}{p+1} \int_{0}^{1}\left|v_{0}\right|^{p+1} d x<0
$$

Then the solution $v(t) \in H_{0}^{1}(]-1,+1[)$ with $v(0)=v_{0}$ blows up in finite time and satisfies

$$
v(t, x)=v(t,-x) \quad \forall x \in[-1,+1] .
$$

Hence $v_{x}(t, 0)=0$, and if $u(t)$ is defined as

$$
u(t, x)= \begin{cases}v(t, x) & \text { for } 0 \leq x \leq 1 \\ -v(t, 2-x) & \text { for } 1 \leq x \leq 2\end{cases}
$$

$u(t)$ is a solution of (1.1) with $u(t) \in H^{1}(] 0,2[), u_{x}(t, 0)=u_{x}(t, 2)=0$, and $u(t)$ blows up in finite time.

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