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REVIEW

A renaissance of neural networks in drug discovery

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ABSTRACT

Introduction: Neural networks are becoming a very popular method for solving machine learning and artificial intelligence problems. The variety of neural network types and their application to drug discovery requires expert knowledge to choose the most appropriate approach.

Areas covered: In this review, the authors discuss traditional and newly emerging neural network approaches to drug discovery. Their focus is on backpropagation neural networks and their variants, self-organizing maps and associated methods, and a relatively new technique, deep learning. The most important technical issues are discussed including overfitting and its prevention through regularization, ensemble and multitask modeling, model interpretation, and estimation of applicability domain. Different aspects of using neural networks in drug discovery are considered: building structure-activity models with respect to various targets; predicting drug selectivity, toxicity profiles, ADMET and physicochemical properties; characteristics of drug-delivery systems and virtual screening.

Expert opinion: Neural networks continue to grow in importance for drug discovery. Recent developments in deep learning suggests further improvements may be gained in the analysis of large chemical data sets. It's anticipated that neural networks will be more widely used in drug discovery in the future, and applied in non-traditional areas such as drug delivery systems, biologically compatible materials, and regenerative medicine.

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Deep learning; neural network ensembles; neural networks; overfitting; structure-activity relationships

1. Introduction

No other machine-learning method has such a long and rich history full of great hope and deep frustration as artificial neural networks (ANNs). McCulloch and Pitts [1], in the 1940s, attempted to create a mathematical model of the human brain. Following the important development of the perceptron, the first algorithm for pattern recognition by a two-layer ANN was proposed by Rosenblatt [2]. However, as this was unable to simulate the basic exclusive-or operation, a period of stagnation of neural network research ensued. Neural network research revived following the invention (and several independent reinventions) of the backpropagation algorithm [3], offering an efficient solution to the exclusive-or problem. Neural networks became very popular in the mid-1980s due to the concept of parallel distributed processing (connectionism) popularized by Rumelhart and McClelland, the development of neocognitron (the first convolutional ANN) by Fukushima [4], self-organizing maps by Kohonen [5], and energy-based recurrent ANNs by Hopfield [6]. This optimism was followed by the second period where ANNs were in competition with some newly emerged, very efficient, and mathematically well-grounded methods. Very recently, ANNs received another stimulus due to the development of the deep-learning concept by Hinton and colleagues [7–9]. These methods may outperform alternative state-of-the-art machine-

learning methods in drug data modeling benchmarking competitions. In addition, deep learning has achieved human-competitive and higher performance on several important image and speech recognition benchmarks and has the potential to revolutionize machine learning and artificial intelligence.

The first application of ANNs to drug discovery dates back to the early 1970s when Hiller et al. [10] published a study using the Rosenblatt perceptron to classify substituted 1,3-dioxanes as physiologically active or inactive. In this work, elements of the chemical structures were projected onto the perceptron retina; the perceptron was trained using a set of compounds with known activities, and the trained neural network demonstrated good recognition ability on both the training and the test sets of compounds. The next stage of development occurred in 1990 with the first publications of Aoyama et al. dealing with the use of ANNs in Quantitative Structure–Activity Relationship (QSAR) studies [11]. For the last 25 years, this approach to modeling structure–activity relationships has matured into a well-established scientific field with numerous theoretical approaches and successful practical applications (see review articles [12–16]). The field now encompasses the use of ANNs for predicting not only different types of biological activity but also physicochemical, Absorption Distribution Metabolism Excretion and Toxicity

Article highlights

- Backpropagation neural networks are universal approximators for structure-activity relationships
- Different regularization techniques efficiently prevent overfitting and enhance predictive performance
- Bayesian regularized neural networks are a reliable and effective tool with numerous applications in medicinal chemistry and materials design
- Associative neural networks use ensemble modeling to increase and predictive ability of structure-activity models and assess the reliability of prediction
- Deep learning involves formation of different levels of data representation
- Deep neural networks could particularly be useful for analyzing huge amounts of chemical and biological information for drug discovery, although they are computationally demanding.

This box summarizes key points contained in the article.

(ADMET), biodegradability and spectroscopic properties, and reactivity. The aim of this article is to review some important concepts and ideas accumulated in this field and to provide a guide to where the field is heading in the future.

2. Backpropagation neural networks

Multilayer feed-forward neural networks, also known as multilayer perceptrons, comprise the most widely used architecture for ANNs (see Figure 1). They consist of units implementing the McCulloth–Pitts' model of neurons [1], which produce their output by computing the weighted sum of their inputs followed by a nonlinear transform (see Figure 1).

$$y = f(z) = f\left(-t + \sum_i w_i x_i\right),$$

where x_i is i th input of the unit, w_i is the corresponding adjustable weight mimicking the synaptic strength of biological neuron, z is the overall input to the unit, whereas $f(z)$ is a nonlinear transform function that could be associated with the activation of neural cells occurring whenever the overall input (which corresponds to cell membrane potential) exceeds some threshold value t . The latter function is usually taken as a step threshold function (e.g. in perceptrons [2]), a sigmoid function

(either logistic function or hyperbolic tangent $f(z) = th(z) = (\exp(z) - \exp(-z)) / (\exp(z) + \exp(-z))$) in most of the modern applications, and a linear rectifier function in recent deep-learning studies.

In multilayer feed-forward ANNs, all units are organized into several layers; the units in each $(i + 1)$ th layer receiving signals only from the i th layer. So, information flow proceeds in one direction from the first (input) layer, via one or several intermediate (hidden) layers, to the final (output) layer (see Figure 1). Multilayer feed-forward ANNs essentially generate models that consist of linear combinations of nonlinear kernel functions, so can be considered as universal mapping devices capable of approximating any continuous function given sufficient data. When these types of ANNs are used to predict properties of chemical compounds for drug discovery, units in the input layer accept the molecular descriptors, signals propagate via the nonlinear transfer functions in the hidden layers to the output layer, which predicts the corresponding property values. It has been shown mathematically that the relationship between any chemical property on its structure can be approximated using a multilayer feed-forward ANN and fragment descriptors [17,18]. When ANNs are applied to drug discovery, the modeled properties are often physico-chemical and ADMET properties of organic compounds; toxicity end points; binding constants; or IC_{50} values with respect to various macromolecular biological targets, types, and profiles of biological activity, etc. (e.g. see comprehensive tables in the review article [13]).

To make correct predictions, an ANN must be trained using experimentally measured properties of a set of compounds. In training the model, the backpropagation ANN modifies the weights w so as to minimize the difference between predicted and experimental property values. Such coefficients are usually modified iteratively using the partial derivatives of the average prediction error with respect to the weights. Such derivatives can be efficiently computed by propagating errors in the opposite direction, from the output to the input layer, using the chain differentiation rule [3]. Once computed, they can be used to modify weights by taking a small step in the direction opposite to the gradient vector or conjugated to it, as in the 'delta-rule' algorithm [3,19]. Several more elaborate algorithms, such as resilient propagation [20] and the

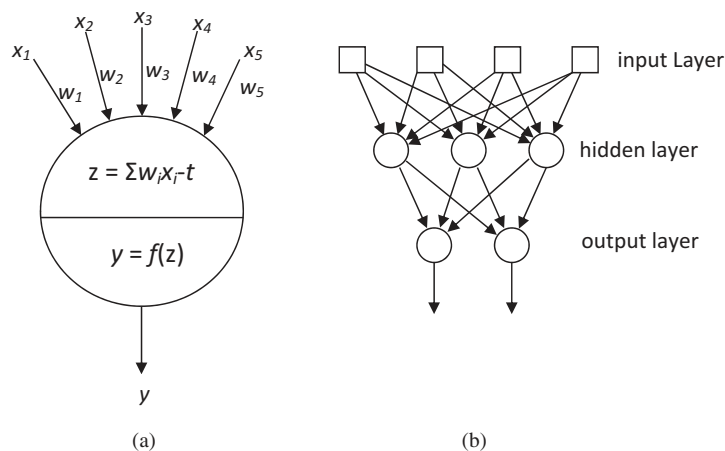


Figure 1. (a) McCulloth-Pitts' model of neurons; (b) multi-layer feed-forward ANN. Input data are propagated from the input layer to the output one. Input units are shown as squares in order not to confuse them with hidden and output units in which actual computation takes place.

Levenberg–Marquardt algorithm [21], have been shown to accelerate training. Nonetheless, for very large ANNs, the ‘delta-rule’ algorithm is still commonly used to train backpropagation neural networks.

In constructing QSAR models for drug discovery using multilayer ANNs, overtraining can occur [22]. This causes the ANNs to learn to predict the properties of the training set very well while failing to make useful predictions for compounds not used in training. Overfitting can be avoided by the use of a validation set of compounds, also not used in training, that monitor the predictive performance of the neural network model and stop training when it starts to deteriorate [14,22]. A third set of compounds called a test set, not used in training or validation, is required to give an unbiased assessment of the predictive performance of the neural network model. The overtraining problem can also be tackled using various regularization techniques, such as L1-, L2-, and max-norm [23] regularization with weights decay; Bayesian regularization [24–26]; or the dropout technique [27] suggested recently for deep learning (see below). In these cases, it is not necessary to use data in a validation set (or even, theoretically, in a test set).

Several other useful methods for applying backpropagation ANNs to drug discovery have been proposed. One concerns the use of ANNs with several output units corresponding to closely related properties (e.g. anticancer activity) to build QSAR models for all of them [28], the so-called multitask learning concept [29]. One study has demonstrated that the simultaneous prediction of 11 types of tissue–air partition coefficients using a single ANN with 11 output units is much more accurate in comparison with predictions made by 11 separate ANNs with a single output unit [28] due to the inductive transfer between the data concerning related end points. This opens up the possibility of building usefully predictive QSAR models for small data sets (e.g. for human end points) whenever more abundant data on closely related data (e.g. for rat end points) are available.

Another methodology useful for drug discovery concerns the concept of learned symmetry [30]. For example, if molecules form a congeneric set with common symmetrical skeleton with equivalent attachment points, then models should predict the same activity for molecules with equivalent substitution patterns. Such models were built by applying ANNs to training sets expanded by adding copies of molecules with equivalent substitution patterns. Their improved performance was demonstrated for 1,4-dihydropyridine calcium channel blockers of type and for hallucinogenic phenylalkylamines [30].

Neural networks can sometimes be used to interpret QSAR models. Analysis of neural network weights can be used to identify the most significant descriptors contributing to the model [31]. The distribution of partial derivatives of ANN outputs with respect to inputs was proposed as an index of descriptor relevance in another study [32]. Such analyses allow not allow accurate property predictions and model interpretations as do traditional statistical methods, but also revealing information on the nonlinearity of QSAR relationships, important for drug discovery.

Another method that is particularly useful for drug discovery is the autoencoder backpropagation ANN that employs a

small hidden layer to reproduce input signals on the output units. If such ANN is trained on a set of compounds belonging to the same class, then by computing the reconstruction error (i.e. the difference between the values of the input and output units) for any test compound, one can detect whether it belongs to the same class. Hence, autoencoder ANNs solve the one-class classification (novelty detection) problem [33]. A virtual screening system based on autoencoder ANNs with molecular fingerprints as descriptors was developed and tested on a series of the inhibitors of glycogen synthase kinase [34]. It outperformed alternative approaches based on pharmacophore hypotheses and molecular docking in a retrospective study.

3. Bayesian-regularized neural networks

As described in the previous section, neural networks with a single hidden layer are ‘universal approximators,’ able to model any continuous function to arbitrary accuracy given sufficient training data. Feed-forward neural networks, like all other types of regression, can suffer from overtraining, overfitting, confusion about the optimal architecture for the network, becoming trapped in poor local optima on complex response surfaces, and inherent instability. Instability is common in regression because, as Tikhonov first stated, ‘regression is an ill-posed problem in statistics’ [35]. Instability is manifest by models becoming very sensitive to small changes in some model parameters and general lack of training robustness. Ill-posed problems can be converted into well-posed problems by regularization, a process where the complexity of a model is balanced against its ability to reproduce the training data faithfully.

The idea is conceptually simple and a balance is found between the ability of the model to fit the training data and the complexity of the model. Regression aims to minimize the cost function:

$$\min_f \sum_{i=1}^n V(f(\hat{x}_i), \hat{y}_i) + \lambda R(f),$$

where the λ parameter alters the balance between bias (model is too simple to capture any underlying relationships between, for example, molecular structure and drug activity) and variance (where the model is too complex and fits the data underlying relationship and the noise in the data [solid curve in Figure 2]).

Bayesian methods can be used to automatically find the optimal value of the regularization constant(s) (λ in the above example). The theory is relatively complex and has been described fully in prior publications [24]. The bottom line is that Bayesian regularization generates neural network models with few, if any, of the problems of unregularized backpropagation or feed-forward neural networks. Applying related methods that use a sparse Bayesian prior can generate very good quantitative structure–activity relationship models for pharmaceutically relevant properties that are robust, sparse, and often interpretable. These methods achieve excellent feature selection, an important issue for developing models that are optimally predictive and easier to understand in terms of

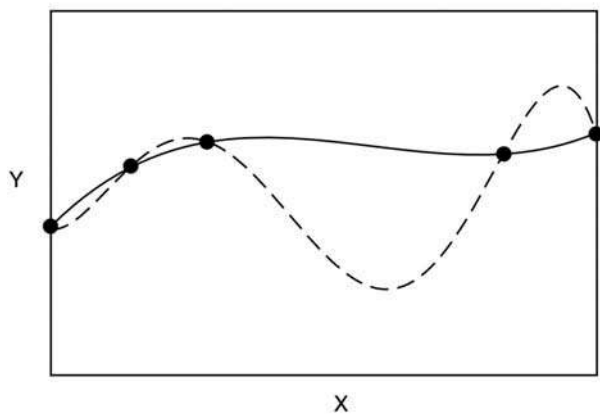


Figure 2. The solid and sashed functions both incur zero loss on the given data points. Regularization will induce a model to prefer the solid function, which may generalize better to other data points sampled from the underlying unknown distribution.

the underlying structure–activity relationships [36,37]. Bayesian-regularized neural networks generate robust models with optimal complexity, avoiding under- or overfitting, and also are relatively insensitive to the number of nodes used in the hidden layer.

Bayesian-regularized neural networks have been applied to a relatively wide variety of molecular design and property prediction problems [38]. The seminal works by Mackay [39], Bishop [40], and Figueiredo [41] laid out the theory of neural networks and Bayesian regularization. Burden and Winkler first applied them to QSAR and later to Quantitate Structure-Property Relationship (QSPR) problems. Researchers from AstraZeneca have employed Bayesian-regularized neural networks to model important physicochemical properties of drugs such as aqueous solubility [42] and log D the pH-dependent distribution of drugs between lipophilic and aqueous phases [43]. They have been used to successfully and quantitatively model acute toxicity of chemicals to *Tetrahymena pyriformis* [44], have been employed to predict the binding of peptide epitopes to MHC class II [45], the activities of inhalation anesthetics [46], etc. Recent studies using the Kaggle benchmark data sets have shown that Bayesian neural networks perform on average as well as the new deep-learning methods [47].

Bayesian-regularized neural networks have been used to develop a very large and widely applicable model of aqueous solubility of small organic molecules [48]. Modeling of drug activities has been an important application of Bayesian neural networks. Orre et al. used these modeling methods to find adverse drug combinations [49], Winkler and Burden used these methods to make quantitative predictions of drug partitioning through the blood–brain barrier [50], and Polley et al. reported robust and predictive models of intestinal absorption of drugs [51] and the potency and selectivity of farnesyl transferase inhibitors used for cancer therapy [52]. Caballero et al. added genetic selection to a Bayesian neural network (Bayesian-Regularized Genetic Neural Networks [BRGNN]) to model the selective inhibition of the calcium-activated potassium channel by clotrimazole analogs [53]. Fernandez et al.

used BRGNN methods to model a diverse range of biological and physicochemical properties of small molecules [54]. They also modeled cyclin-dependent kinase inhibition by 1H-pyrazolo[3,4-d]pyrimidine derivatives using Bayesian-regularized neural network ensembles [53] and subsequently applied BRGNN techniques to create quantitative QSAR models for several drug–target interaction data sets.

Bayesian-regularized neural networks have also been used to make seminal contributions to the prediction of possible adverse biological effects of nanomaterials [55,56] and to the design of cell-targeting nanoparticles for personalized medicine [57]. In a related vein, Bayesian-regularized neural networks have been used to predict the very complex mesophases that occur in amphiphilic drug delivery systems [56], a computational problem that is essentially intractable by methods such as molecular dynamics simulations.

4. Ensemble and consensus models

The error of each machine-learning method involves two major factors: bias and variance. As unregularized neural networks are ‘ill-posed’ methods, small perturbations in data or descriptors may result in large changes in the predicted values [58,59]. Thus, models developed using the same or similar data set but with different initialization of neural network weights can provide different predictions for new data. The ensemble average, calculated over multiple predictors, can decrease the variance and is another way to improve the model generalization compared to that of individual networks. Clearly, the more similar the individual networks, the smaller the advantage of ensemble averages. To increase the variance of individual networks, differences in their training data sets could be maximized. However, it is essential that the training sets will contain the same information as the given data set. This can be achieved with the so-called bagging approach [59], which creates new training data sets by sampling with replacement from the initial set. Another way of increasing variance is to use different descriptors for each model. This can be achieved by subsampling descriptors from the initial set (this is used in bagging) or by using different sets of descriptors. Models developed by averaging models derived from different sets of descriptors are frequently called consensus models. Ensembles have been used in chemistry and drug discovery since the 1990s [22,58], while consensus models have become more popular since the 2000s [60,61]. Ensemble and consensus methods were recently used successfully for prediction of diverse properties, such as inhibitors of CYP450 [62], analysis of non-nucleoside HIV reverse-transcriptase inhibitors [63], potential endocrine disruptors [64], and others. Ensembles of neural network models frequently provided higher prediction accuracy compared to other methods in these studies.

Ensemble or consensus model prediction variation can be used to estimate the applicability domain of models. The basic hypothesis is that predictions of individual models will diverge for data points far from the training set points. Thus, high variance of prediction (Standard Deviation [STD]) can be used to detect molecules for which predictions are less reliable.

Benchmarking of different definitions of the applicability domain identified STD as the best measure of prediction reliability of molecules from regression studies [65]. A similar measure was also one the best ones for classification studies [66].

The training of individual neural network or their ensembles is a rather time-consuming problem and can be impractical if new data become available and models must be repeatedly retrained. The Associative Neural Network (ASNN) method based on a model of thalamocortical organization of the brain addresses this problem [67]. Each neural network in the ASNN ensemble can be considered a representation of one cortex column in the brain. The predicted values of each model, ordered by magnitude, can be considered a spatiotemporal representation of the training set by the ASNN. Thus, training samples are stored in the 'memory of the ASNN' as spatiotemporal patterns, together with predicted and real values. For each new sample, the ASNN retrieves the most similar stored patterns and uses prediction errors of these patterns to correct the prediction of the new data point. This 'local correction' efficiently increases prediction accuracy of the ensemble by decreasing the bias of the ensemble method. Moreover, the new patterns can be easily added to the 'memory' of the ASNN without a need to retrain the whole network, thus allowing the neural network to instantaneously learn new data. This feature tunes the global models to a local subset of data. For example, the ALOGPS 2.1 program was initially developed to predict octanol/water partition coefficients using organic molecules only [68]. The addition of a small training set of Pt complexes with measured logP values allowed this program to successfully predict Pt complexes in a blind test set [69]. It is interesting that the accuracy of this model was higher than models developed with Pt complexes. In a similar way, the logP algorithm was tuned to predict logD by providing *in house* data measured in pharma companies [70].

The high prediction power of the algorithm was demonstrated in several studies, where the ASNN-based models provided one of the highest prediction accuracies for prediction of physicochemical properties [71–73] as well as contributed the top ranked models in recent challenges organized by US EPA ToxCast and NIH Tox21 programs [74,75].

5. Self-organizing maps and related approaches

Kohonen's Self-Organizing Maps (SOM) is a biology-inspired topology-preserving nonlinear dimensionality reduction method that can map molecules from multidimensional descriptor space onto a 2D grid of neurons [5]. In this case, each molecule activates a single 'winner' neuron with the closest distance between its code vector and the molecule in descriptor space. The training algorithm of SOM guarantees that close molecules activate topologically close neurons in the competitive layer. Projection of molecules to the location of the corresponding winning neurons produces a map, in which neighborhood relations between molecules are mostly preserved. As structurally similar molecules tend to have similar activities, then molecules belonging to the same activity class are mapped either to the same neuron or to several

neighboring neurons. The neurons can be colored according to the activity class of molecules mostly mapped to them. Such colored layer of neurons can be used for predicting activities of new molecules projected onto it and hence for conducting virtual screening. This mapping procedure underlies the use of SOM for drug discovery [76].

Not only individual molecules, but also local atom or bond descriptors, molecular fields, and mixture components can be mapped to neurons in the competitive layer to produce novel descriptors useful for drug discovery. 3D-QSAR methods CoMSA [77] and volume learning algorithm (VLA) [78] are based on mapping molecular fields. Recent publication on classification of mixtures of Chinese herbal medicines based on SOM is an example of this approach [79]. Quantitative predictions can be performed by hybrid ANNs containing SOM as the input layer for multilayer ANN. The classical example for this are the counter-propagation ANN, while the most recent example – the network for 'deep learning' of chemical data, in which the SOM layer of neurons is followed by layers of backpropagation ANN [80]. The latter network was used for predicting antibacterial activity of peptides.

Modifications of the generative topographic mapping, a probabilistic analog of SOM based on Bayesian learning, have recently been used in the field of drug discovery for visualizing chemical space [81], building activity landscapes [82], classification [83] and regression [82] QSAR models, comparing chemical libraries [81], predicting activity profiles [84], and performing inverse-QSAR studies [84].

6. Other types of neural networks

There are several dozens of other general-purpose types of neural networks, some of which have been used in structure–activity modeling and drug discovery [13,14]. They include Cascade-Correlation network with dynamically growing number of neurons; Radial Basis Functions Neural Network along with the Probabilistic Neural Network; and General Regression Neural Network closely related to it, a family of ANNs based on adaptive resonance theory (ART-1, ART-2, ARTMAP, etc.). One should also mention specialized ANNs designed to work directly with molecular graphs without the use of a precomputed set of molecular descriptors: a 'neural device for searching direct correlations between structures and properties of chemical compounds' with convolution architecture (see later) [85], recursive neural networks [86], graph machines [87], etc. Despite some success stories, currently these types of NNs are however rarely used for drug discovery.

A recurrent neural network (RNN) is a class of ANN where connections between units form a directed cycle. This creates a type of neural network that can model dynamic temporal behavior. Unlike feed-forward neural networks, RNNs can use their internal memory to process arbitrary sequences of inputs. They are particularly suitable for predicting time-varying parameters, although Bayesian neural networks and other have also been shown to do this successfully [88]. The theory of RNNs and their application to unsupervised pattern recognition have been described by Orre et al. [89]. This type of neural network has not been used often for drug discovery or modeling of related medical activities or properties. Goh et al. first

460 applied RNNs to predicting drug dissolution profiles, and
 AQ15 important problem in the pharmaceutical industry [90]. More
 recently, Bonet and coworkers used RNNs to predict HIV drug
 resistance [91].

7. Deep learning

465 The term 'deep learning' refers to training multilayer ANNs
 with more than one of hidden layer and a large number
 (thousands) of hidden layer nodes (see major publications
 [8,9]). Before the advent of first 'deep' ANNs in the middle of
 470 2000s, almost all standard machine-learning methods could
 be considered as 'shallow': they could formally be described
 by means of at most two layers of processing units [8].
 Although multilayer ANNs with any number of hidden layers
 could formally be constructed, their training using backpropa-
 475 gation-based optimization algorithms usually fails whenever
 the number of hidden layers exceeds three or four [8]. This can
 be explained by the increased risk of overfitting with larger
 numbers of weights. It is also due to another peculiarity of the
 backpropagation algorithm, in which the values of error deriva-
 480 tives, which are propagated from the output layer back to
 the input one, vanish rapidly with the distance from the out-
 put layer. This is due to the multiplication of several small
 partial derivatives as required by the chain differentiation rule.
 As a result, only a couple of layers closest to the output one
 485 can actually be trained, whereas all weight parameters in the
 remaining hidden layers stay almost unchanged during the
 training. Since all adjustable weights of multilayer ANNs are
 usually initialized with small random numbers, during the
 training, the network tries to approximate the 'functional
 490 dependence' of the output values on the random numbers
 formed on the hidden units near the input layer and, not
 surprisingly, fails.

An efficient solution to this problem was found in 2006 by
 Hinton and Salakhutdinov [7] who suggested splitting the
 learning process into two stages: (1) representation learning
 495 [92] and (2) training the network using the learned represen-
 tation. In the first successful implementation of this methodol-
 ogy, a cascade of Restricted Boltzmann Machines (RBMs) was
 used to learn a hierarchy of internal data representations [7].
 Then, the weight parameters learned by RBMs were used to
 500 initialize the weights of the deep multilayer ANNs that were
 subsequently readjusted during the training using the stan-
 dard backpropagation algorithm. In this way, multilayer ANNs
 with virtually any number of hidden layers can be trained
 efficiently.

505 After this pioneering study, the methodology of deep
 learning was augmented in several important ways. First, the
 sigmoidal transfer function was replaced by the linear rectifier
 function, usually producing stronger models [93]. Second, a
 AQ16 new, powerful regularization technique, weight dropout [27],
 510 was introduced. To implement weight dropout nodes is ran-
 domly switched off during the training. The regularizing effect
 of the dropout technique in conjunction with the use of a
 rectifier transfer function means that it becomes possible to
 515 train very large ANNs with a huge number of hidden layer
 nodes and their interconnections without overtraining or

overfitting [9]. Furthermore, it appears that with sufficiently
 big large data sets, it is not necessary to pretrain ANNs using
 cascades of RBMs or other autoencoders to learn data repre-
 sentation and the weights except between the final hidden
 and the output layers can just be set randomly once. 520

Another important technique that was successfully inte-
 grated with deep learning is convolutional architecture [94].
 Convolutional ANNs have roots in the neocognitron [4] archi-
 tecture specially designed to mimic information processing in
 visual cortex. Distinct from the standard multiple-layer ANNs 525
 working with fixed-size data vectors, convolutional ANNs are
 designed to work with data in the form of multiple arrays with
 variable size, such as 2D pixel matrices for images, while
 providing necessary invariance to irrelevant data transforma-
 tions, such as shifts or distortions of images. Convolutional 530
 ANNs consist of two kinds of layers: convolutional layers and
 pooling layers. Each unit in a convolutional layer takes signals
 from a small patch of units from the previous layer through a
 set of weights shared by all units in the layer. Each unit in a
 pooling layer computes the maximum of signals coming from 535
 a patch of units in the previous layer. Stacks of several con-
 volution and pooling units allow extraction of complex rele-
 vant features from images. In deep ANNs, convolution and
 pooling layers are typically placed at the input side of the
 network. 540

An important factor in the recent success of ANNs with
 deep learning is the use of fast graphics processing units
 (GPU) that significantly accelerate the training due to paral-
 lelization. Currently, a deep-learning ANN composed of millions
 of units with hundreds of millions adjustable weights orga- 545
 nized in several dozen layers can be trained with huge data
 sets of hundreds of millions examples. Such networks have
 already achieved human or higher performance in solving
 tasks such as image and speech recognition.

Deep learning is not just a new term to designate the state- 550
 of-the-art in the domain of ANNs. It cannot be reduced to a
 simple application of additional techniques, such as dropout
 and rectifier units, or simple augmentation of the number of
 hidden layers in multilayer ANNs. Neither it cannot be reduced
 AQ17 to a mere application of deep-learning software to solve old 555
 problems using traditional approaches. Deep learning is a new
 philosophy of predictive modeling. The success of the applica-
 tion of standard 'shallow' machine-learning methods is greatly
 influenced by how well the features representing data have
 been chosen using experience and domain knowledge. With 560
 very well-designed features, even the simplest linear or near-
 est-neighbors machine-learning methods can be applied to
 build predictive models. The great promise of the deep learn-
 ing is to be able to extract necessary features with required
 invariance properties automatically from raw data via repre- 565
 sentation learning [9,92]. Deep-learning ANNs form multiple
 levels of representation in their hidden layers, with each sub-
 sequent layer forming representation of a higher, more com-
 plex and abstract, level than the previous one. With multiple
 570 (up to several dozen) hidden layers of nonlinear units, such
 ANN can learn extremely complex functions of its inputs with
 all necessary invariance properties, that is not always possible
 using standard machine-learning methods and manually tai-
 lored features. Due to the process of representation learning,

575 deep learning can easily profit from related data sets with
multiple labels via multitask and transfer learning [29,95], as
580 well as from data without labels via semi-supervised and
transductive learning [96]. So, deep learning can be consid-
ered as an important step towards what is called artificial
585 intelligence [8]. However, on the negative side, they cannot
as easily perform sparse feature selection, important for opti-
mizing predictions of new data and for simple interpretation
of models. Methods such as Multiple Linear Regression with
Expectation Maximization [37] can achieve efficient sparse
590 feature selection so can be complementary to deep-learning
methods. Additionally, on the positive side, although they
perform as well on average as state-of-the-art shallow neural
network methods like Bayesian-regularized neural networks,
they may be faster to train and large cluster or GPU hardware,
handle large data sets, and may be easier to code
algorithmically.

Representation learning provided by deep multilayer ANNs
will play an increasingly important role in computational drug
discovery [97–99]. However, the question of molecular descrip-
595 tors used to capture the important properties of molecules is
still a relatively poorly answered one. Despite the large number
and variety of molecular descriptors, none can be guaranteed
to have universal applicability and provide optimal solutions to
all problems arising in drug discovery. Deep-learning ANNs may
600 alleviate this issue somewhat by generating novel and useful
complex representations that may be more suited to solving
specific tasks in this domain, albeit at the expense of generating
models whose interpretation is even more difficult. However,
the discovery of more suitable and chemically interpretable
605 molecular descriptors is still an important, poorly solved pro-
blem in QSAR. One can also expect that the ability to integrate a
large amount of related data using deep multilayer ANNs with
multiple outputs will be very useful for drug discovery as it
allows reuse of previously accumulated data and knowledge
610 to meet new challenges in drug discovery.

Although first publications on the use of deep learning in
the field of drug discovery appeared very recently [100–102],
some of the key ideas underlying the concept of deep learning
have already been used for building QSAR models. In 1997,
615 the first multilayer ANN with convolutional layers containing
shared weights ('receptors') and pooling layers ('collectors'),
capable of extracting molecular features from raw data, was
reported [85]. Like deep learning, convolutional ANNs were
inspired by the neocognitron [4] architecture for image recog-
620 nition. The analysis of pixels in images was replaced by anal-
ysis of atoms and bonds in molecules. The resulting 'neural
device for searching direct correlations between structures
and properties of organic compounds' allowed construction
of QSAR models using raw molecular data without preliminary
625 computation of molecular descriptors [85]. Another idea
applied to QSAR modeling and discussed above is the use of
ANNs with several outputs to predict several properties using
the multitask learning framework [28].

630 Public attention was drawn to the application of deep learn-
ing to drug discovery in 2012 after publication in *The New York
Times* of the results of a Kaggle competition sponsored by
Merck [103]. The competition was won by a deep-learning

ANN with a 15% improvement in accuracy over Merck's stan-
dard method. In 2014, an arcXiv article [104] written by the
635 winning team showed that multitask (multiple outputs) deep
ANNs outperformed alternative methods. Subsequently, in a
more comprehensive study published [100], it was demon-
strated that ANNs with several hidden layers largely provided
better prospective predictions than Random Forests on a set of
640 large, diverse QSAR data sets taken from Merck's drug discovery
efforts. They also showed that the dropout regularization tech-
niques and rectifier transfer function significantly improved
prediction performance of QSAR models. For best deep ANN
performance, they concluded that the ANNs should be not only
645 deep but also wide, i.e., contain a lot of units in each of the
layers. This contradicts the traditional belief that ANNs should
contain as few as possible adjustable parameters in order to
avoid overfitting. It was also demonstrated that a clear advan-
tage of using multitask ANNs with several output units over the
650 use of single-task ANNs with a single output unit for each
property is most pronounced for relatively small data sets,
whereas with large data sets, the effect can be even opposite.
Surprisingly, pretraining deep ANNs using stacks of RBM mod-
els was shown to deteriorate predictive performance of QSAR
655 models in this study.

Two massive, multitask ANNs for drug discovery have
recently been reported [101,105]. One of them was trained
on a data set of nearly 40 million protein-ligand measure-
ments across 259 biological targets [101]. Another was trained
660 on 2 million data points for 1280 biological targets [105]. In
both cases, it has been shown that massively multitask ANNs
trained with deep learning significantly outperform single-task
methods, and their predictive performance improves as addi-
tional tasks (targets) and data points are added. This improve-
665 ment is significantly influenced by both the amount of data
and the number of tasks (targets). It has also been demon-
strated for toxicity prediction that, by combining reactive
centers, such networks can learn complex internal representa-
tion that resemble well-established toxicophores [106].

8. Conclusions 670

In this review, we analyzed recent developments in the appli-
cation of neural networks to drug discovery: building QSAR
models to predict activity profiles and drug-target interac-
tions, binding constants with respect to various targets, drug
675 selectivity, inhibition constants for different enzymes, toxicity
profiles, ADMET and physicochemical properties, characteris-
tics of drug-delivery systems, etc., as well as performing virtual
screening. The more traditional approaches, such as 'shallow'
neural networks, Bayesian, and ensemble/consensus learning,
680 were shown to be very important tools in drug discovery. We
have shown that these methods are widely used in the con-
temporary research and very often generate the most valuable
models. Moreover, these methods allow interpretation of
QSAR models and identification of the most important mole-
685 cular features. Ensemble and consensus modeling may pro-
vide additional advantages by decreasing the variance of
individual models as well as improving the estimation of the
applicability domain of models. Neural networks are becoming

690 even more prominent due to recent progress in deep-learning
 695 technology. Training of millions of neurons with millions of
 data points that was not feasible a few years ago can now be
 accomplished. Deep-learning technology provides interesting
 and powerful complementary capability to drug discovery
 using neural network models, and we expect to see a rapid
 growth in applications in the nearest future.

9. Expert opinion

700 The neural networks are very important tools in drug discov-
 705 ery. While they initially suffered from overfitting and over-
 training and incorrect model validation, these problems have
 now been essentially overcome. Methods such as early stop-
 ping [22], bias correction as used in Associative Neural
 Networks [74,75], Bayesian regularization [24–26], and training
 with dropout techniques [27] allow development of highly
 predictive robust models. Hence, application of the traditional
 neural networks to drug design and increasingly other fields
 such as materials has matured. Neural networks are sometimes
 criticized as a black-box approach. However, this is as much
 due to use of poorly interpretable descriptors as a problem
 with the neural network method. There are increasingly
 sophisticated methods for analyzing the significance of neural
 network weights [31], or general purpose methods such as
 predicted Matched Molecular Pairs [107] allows more facile
 interpretation of models. Additionally, neural network models
 can be interpreted by analysis of the distribution of partial
 derivatives of ANN outputs with respect to inputs or calcula-
 tion their sensitivities, as discussed above [31,32].

715 Neural networks, in particular those using deep-learning
 technology, will continue to be used actively in drug discovery
 in the future. They will be particularly useful for analysis of
 720 large data sets that are increasingly generated by automated
 high-throughput technologies so are well suited to the chal-
 lenges of Big Data [108]. We expect that neural networks will
 be increasingly used for other challenging tasks such as force
 field parameterization, optimization of drug delivery systems,
 ADMET prediction and drug classification, prediction of syn-
 725 thesis difficulty, and especially for multitask learning and sim-
 ultaneously prediction of multiple biological activities or
 properties. We also expect that learning by combining super-
 vised and unsupervised data, learning of highly imbalanced
 data sets, learning of data weighted by measurement accu-
 730 racies, etc., will become more commonplace. In particular, we
 expect that the advantages of deep-learning networks in ana-
 lysis of large and complex data for which traditional statistical
 machine-learning methods sometimes fail will be fully
 735 exploited.

ANNs are also finding applications in augmenting expen-
 sive quantum chemistry calculations, accurate prediction of
 protein structures, simulation of small molecule–protein as
 well as protein–protein interactions, simulations of PK/PD
 parameters, and prediction of *in vivo* toxicity. It is feasible
 740 that future algorithm-based system biology and machine-
 learning approaches will be merged in a single application.
 For example, system biology approaches where differential
 equations that simulate the cells require a lot of adjustable
 parameters, some of which are very difficult to measure, may

benefit from this fusion. Such parameters can be estimated
 using neural networks and be coupled with simulation out-
 puts to identify the most likely biological system states.

750 However, one should not overstate the potential of deep-
 learning technology over traditional QSAR/QSPR for analysis
 of small data sets with a limited number of descriptors. The
 gain in the performance can come from using a big amount
 of previously unused related data. The gain may also arise
 from the ability of deep learning to create new, complex
 molecular descriptors through representation learning [92].
 755 We also expect that the ability of deep learning to create
 multiple levels of data representations with different com-
 plexity could provide fundamentally new ways of analyzing
 structure–activity relationships and solving the problems of
 great importance for drug discovery, such as the problem of
 activity cliffs [109]. Indeed, very rugged and bumpy activity
 landscapes with numerous activity cliffs with respect to
 input descriptors or low-level representations might appear
 to be very smooth and simple with respect to high-level
 representations being formed in deep-learning systems,
 which is the essence of representation learning. The ability
 of metric learning, a kind of linear representation learning,
 to eliminate activity cliffs in activity landscapes has recently
 been demonstrated [110]. One can expect that nonlinear
 representation learning provided by neural networks should
 give an even greater effect.

760 Until recently, multilayer backpropagation neural networks
 (shallow or deep) and self-organizing maps formed two sepa-
 rate branches of development, perhaps, with an exception of
 VLA [78], which clustered input descriptors using SOM for
 neural network learning. At the present time, however, there
 is a clear trend towards their convergence [80]. Incorporation
 of SOM-like layers into deep-learning systems might endow
 the latter with the means of data mapping, and visualization
 proved to be useful for drug discovery.

Declaration of interest

765 IV Tetko is the CEO of BIGCHEM GmbH, which licenses OCHEM and ASNN
 software. The authors have no other relevant affiliations or financial
 involvement with any organization or entity with a financial interest in
 or financial conflict with the subject matter or materials discussed in the
 manuscript apart from those disclosed.

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