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# A simple description of holographic domain walls in confining theories — extended hydrodynamics

# Romuald A. Janik, Matti Järvinen $^{b,c}$ and Jacob Sonnenschein $^d$

<sup>a</sup> Institute of Theoretical Physics, Jagiellonian University, Łojasiewicza 11, 30-348 Kraków, Poland

E-mail: romuald.janik@gmail.com, matti.jarvinen@apctp.org, cobi@tauex.tau.ac.il

ABSTRACT: In the context of theories with a first order phase transition, we propose a general covariant description of coexisting phases separated by domain walls using an additional order parameter-like degree of freedom. In the case of a holographic Witten model with a confining and deconfined phase, the resulting model extends hydrodynamics and has a simple formulation in terms of a spacetime action with corresponding expressions for the energy-momentum tensor. The proposed description leads to simple analytic profiles of domain walls, including expressions for surface tension density, which agree nicely with holographic numerical solutions, despite the apparent complexity of those gravitational backgrounds.

Keywords: Effective Field Theories, Gauge-gravity correspondence

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<sup>&</sup>lt;sup>b</sup>Asia Pacific Center for Theoretical Physics, Pohang 37673, Republic of Korea

<sup>&</sup>lt;sup>c</sup>Department of Physics, Pohang University of Science and Technology, Pohang 37673, Republic of Korea

<sup>&</sup>lt;sup>d</sup> The Raymond and Beverly Sackler School of Physics and Astronomy, Tel Aviv University, Ramat Aviv 69978, Israel

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#### 1 Introduction

The seminal transition from a deconfined phase to a confining one is one of the most important processes in elementary particle physics. It is of relevance both for the physics of the early universe and for the process of transforming quark-gluon plasma into the observed hadrons in the course of heavy-ion collisions. In addition to the observational and experimental motivations, also from a theoretical point of view the study of the deconfined to confining transition is a fundamental and poorly understood building block of QCD.

Some time after the discovery of the holographic duality, it has been realized that the gravitational backgrounds may serve as useful laboratories to study separately confining and deconfined dynamics and then also the transition between them. A variety of holographic backgrounds have been proposed for that purpose; some of them are bottom-up models and others are top-down ones.

In the early years of the AdS/CFT correspondence, phase transitions were primarily studied in the equilibrium setting by comparing the free energies of two distinct dual gravitational backgrounds. The issue of describing a passage through the phase transition in real time has only been addressed quite recently in a number of works, starting from a linearized analysis [1, 2] to fully dynamical studies of phase separation and domain wall dynamics [3–10].

These studies could deal successfully primarily with cases where both phases of the relevant theories were deconfined. The full gravitational description in the most physically interesting case of a transition between a confining and a deconfined phase has proved so far to be prohibitively difficult, apart from the pioneering work [11] dealing with the time evolution of plasma-balls. The goal of the present paper is to propose a simple description of the coexisting phases and domain walls from the boundary field theory point of view, which could serve potentially as a proxy for the full gravitational description in the same sense as hydrodynamics corresponds to dual gravitational backgrounds through the fluid/gravity duality [12]. We believe, however, that the range of applicability of the proposed description is in fact very general and goes beyond holography.

Let us mention here two lines of research, whose scope partially overlaps with our approach.

In [4], a boundary description of evolving domain walls in theories with two deconfined phases was proposed in terms of second order "spatial" hydrodynamics. Since our main focus of interest are theories with the confining/deconfined transition, a purely hydrodynamic description would not be applicable. Moreover, we would like to obtain analytically the very simple looking domain wall profiles which are seen in a wide variety of holographic models.

Reference [13] studied Linde's approach to tunneling at finite temperature [14, 15] in a theory with the confining/deconfined transition through a certain specific Ansatz on the gravitational side. Our approach is, in contrast, based on boundary field theory considerations and is *a-priori* applicable to very general dynamical configurations including hydrodynamic flows on the deconfined side. There are, nevertheless, marked qualitative

similarities as a scalar field with a double well kind of potential appears naturally both here and in [13] (see also the earlier work [16]).

Our present work is based on a prototype model utilizing the idea of [17] of compactifying the Euclidean time coordinate and one space coordinate on an  $S^1$ . The analysis of this model made in [17] and [18] yielded the holographic confining/deconfined phase diagram. The two dimensional sub-manifold of the full geometrical background that is spanned by the compact coordinate and the holographic coordinate, can have a topology of either cylinder (cy.) or a cigar (ci.). It is well known that for a ci. topology that involves the Euclidean time direction the background is that of a black-hole and it is the dual of the thermal deconfined phase. On the other hand the ci. that involves a space coordinate corresponds to a confining phase [19]. For backgrounds that depend only on the holographic coordinate there are only two non-trivial and non-singular possibilities that are depicted in figure 1.

A numerical holographic study of a static domain wall interpolating between backgrounds that correspond to a confining and deconfined phases at  $T = T_c$  was made in [20]. In principle a similar type of analysis could be done also for a dynamical domain wall at  $T \neq T_c$ . However, the gravitational description of such a composite system is extremely complicated. Because of that we adopted in this paper a strategy of analyzing the system at the level of the energy-momentum tensor of the boundary field theory, and use the known numerical plasma-ball domain wall solution [20] as additional holographic input which constrains both the overall structure and the precise coefficients of the field theory energy-momentum tensor. The main observation from the analysis of the data from [20] is that, in particular, the energy density throughout the domain wall can be fitted to a good precision with a simple Ansatz involving the hyperbolic tangent function.

The guideline idea of this paper is to write down the energy momentum tensor as a linear combination of the energy-momentum tensors of the two coexisting confining and deconfined phases and of the domain wall. The linear combination is controlled by a scalar field  $\gamma(x,t)$  which in the static case takes the form of a hyperbolic tanh function of x the coordinate perpedicular to the domain wall. We identified two options for the interpolation and the dependence of the surface tension on  $\gamma$ . We find a very good fit with the numerical results for both of these two options.

We determine an action for  $\gamma$ . The solution of the corresponding equations of motion for the static case is the hyperbolic tanh function mentioned above. For the non-static case of  $T \neq T_c$  we couple the action of  $\gamma$  to a hydrodynamical action so that the full action is built from the "fields"  $\gamma$  and T the temperature. It turned out that the coupling to the hydrodynamics rendered the symmetric potential of  $\gamma$  with two minima into an asymmetric one. For a small deviation from the critical temperature we solve the equations of motion and determine an accelerating domain wall solution.

We then present several applications based only on the general structure of the proposed energy-momentum tensor: (i) First we link its parametrization to the surface tension of the domain wall. (ii) Then we compare equations for an equilibrium circular droplet with standard thermodynamic considerations. (iii) Finally we reproduce the formula for thermodynamic nucleation probability from [21] using Euclidean solutions as suggested by Linde [14, 15].

The description proposed in the present paper was developed based on a conformal version of the holographic model [17] for which there exists the numerical solution of the domain wall [20]. We believe, however, that the resulting framework should have a much more general range of applicability.

Indeed quite different (nonconformal) holographic models, which have a  $1^{st}$  order phase transition between two *deconfined* phases exhibit a domain wall profile which is very well fitted by a tanh function [7, 9]. Since an underlying tanh shape of the domain wall arises analytically in our framework, this suggests that the framework could also be applied in those settings. We verified this explicitly in the case of the nonconformal model of [5] also with two *deconfined* phases.

Let us mention finally an interesting interpretation of our proposed framework. Extracting the free energy as a quartic polynomial in  $\gamma$  essentially provides a Landau type description of a  $1^{st}$  order phase transition. Our formulation (8.4), in one of the two options, can be then understood as promoting the Landau order parameter  $\gamma$  to a dynamical effective field and coupling it in a natural way with hydrodynamic degrees of freedom. In this sense our approach bears some similarity that of [22], for example, where the coupling of Landau-like order parameter to hydrodynamics was also used to study the dynamics of a  $1^{st}$  order phase transition. In our approach, however, the hydrodynamics and the order parameter are degrees of freedom of a single theory, and only the deconfined phase is described through hydrodynamics.

The study of the holographic transition between confining and deconfined phases and of plasma balls was presented in many other publications. In addition to the ones mentioned earlier, a partial list includes [23–28] and references therein, [29–41]. Recently, applications of holography to first order phase transitions in the early universe and to the production of gravitational waves has received a lot of attention [42–45].

The paper is organized as follows. After the introduction at section 1, we review in section 2 the basic holographic setups that correspond to a confining phase and to a deconfining one. We use the prototype of Witten's model with a (ci, cy) geometry for the confining phase and (cy, ci) geometry for the deconfined phase. We spell out the geometrical parameterization and its corresponding parameters of the large  $N_c$  gauge theory for both the low and high temperature phases. We then review the computation of the difference of the classical gravity action between the two phases that translates to the difference of the free energies in boundary field theory, and present a sketch of the phase diagram. Section 3 is devoted to the plasma-ball domain wall. We review the numerical solution of the domain wall [20] that interpolates between the confining and deconfined phases. The structure of the domain wall is then analyzed in section 3.2. We discuss some observations on how this structure arises in gauge/gravity duality in section 3.3. The next section, section 4 is devoted to the covariant description of the domain wall from the point of view of the boundary field theory. The general structure of the energy-momentum tensors is discussed in section 4.1 and in section 4.2: we address the comparison of the energy-momentum tensors with the holographic results which can be done by using two different options. We denote them as option A and option B. We compare the solution with the numerical solution and analyze the equation of motion for  $\gamma$ , section 5 is devoted to an action density

formulation of the system. We start with an action for perfect fluid hydrodynamics in section 5.1, and then in section 5.2 we present the action for the scalar field  $\gamma$  and finally in section 5.3 we write down the final formulation. In section 6 we discuss some generic physical applications. The domain wall surface tension is described in section 6.1. Next we analyze the circular droplet in section 6.2. Thermodynamic nucleation probability and Euclidean solutions is determined in section 6.3. For  $T \neq T_c$  the domain wall is not static. The accelerating planar domain wall solution is written down in section 7. This includes the effective actions and the corresponding accelerating solutions in section 7.1 and the coupling to hydrodynamics in section 7.2. Comments on generality are made in section 8 and in section 9 we summarize, conclude and write down several open questions. In appendix A we generalize the construction of the domain wall also to a six-dimensional setup. In appendix B we checked that indeed our description works quite well also for domain walls in the non-conformal bottom-up holographic model of [5] with two deconfined phases for which we had numerical data. Finally in appendix C we derive the  $n^{\mu}n^{\nu}$  terms in the energy-momentum tensor in the Witten model from an action.

# 2 The basic holographic setup

To describe using holography the transition between the confining and deconfined phases of the YM theory, one needs a holographic background that at low temperature is dual to the former phase and at high temperature to the latter. The distinction between these two phases can be made by the expectation value of a rectangular Wilson line that stretches along the time and one space directions: the confining and deconfined phases are characterized by an area and perimeter law behaviours of the expectation value of such Wilson lines respectively. In [19] the holographic stringy duals of Wilson lines were analyzed and sufficient conditions for confining background were identified. These criteria apply both to bottom-up and top-down confining backgrounds. In this work we will be interested mainly in the latter but our conclusions will apply also to the former scenarios. Several different gravitational backgrounds that are confining backgrounds were written down (for a review see [28] and references therein). It is well known that the gravitational duals of deconfined systems take the form of black-hole backgrounds.

Thus, the idea is to determine a background that interpolates between these two types of backgrounds. At temperature equal to the critical temperature a static domain wall background is anticipated. This case was analyzed thoroughly in [20] for a background that asymptotes to  $AdS_5 \times S^5$  at the boundary. At temperatures that are below or above the critical temperature the system should take the form of a dynamical domain wall.

Originally, the gauge/gravity correspondence dealt with supersymmetric systems. Various mechanisms have been incorporated to break supersymmetry. A prototype mechanism of supersymmetry breaking is based on compactifying one space-time coordinate on  $S^1$  and imposing anti-periodic boundary conditions on fermionic fields [17]. When the compactified coordinate is the Euclidean time it corresponds to introducing temperature on the dual boundary field theory. Alternatively one can compactify one space-coordinate. In

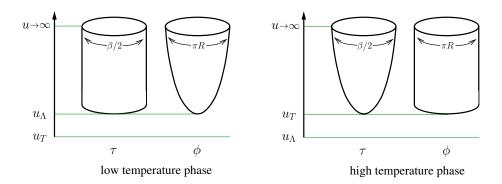


Figure 1. The topology of the solutions which dominate in the low temperature (confined) and high temperature (deconfined) phases of the compactified D3 brane model, as reflected in the  $(\tau, u)$  and  $(\phi, u)$  submanifolds.

this case, in the limit of zero radius of compactification the dimension of the boundary field theory is reduced by one.

The two dimensional sub-manifold of the full geometrical background that is spanned by the compact coordinate denoted by either  $\tau$  for the Euclidean time direction or  $\phi$  for the space direction and the holographic coordinate, denoted by u can have a topology of either cylinder (cy.) or a cigar (ci.). It is well known that for a ci. topology that involves the  $\tau$  direction the background is that of a black-hole. Using the criteria for a confining background mentioned above, it is easy to realize that a ci. background with  $\tau$  direction is not dual to a confining phase. On the other hand a ci. background along the  $\phi$  direction does admit confinement.

It turns out that for backgrounds that correspond to the near horizon limit of large number of  $D_p$  branes with one time and one space directions compactified there are solutions to the corresponding Einstein equations of motion that depend only on the holographic coordinate u with the following topologies

$$((\tau, u), (\phi, u)) = (cy, cy) \qquad \text{or} \quad (cy, ci) \qquad \text{or} \quad (ci, cy) \qquad \text{or} \quad (ci, ci) . \tag{2.1}$$

The first case (cy, cy) is flat and the last (ci, ci) is necessarily singular.<sup>1</sup> Thus we are left with only two setups which are non-trivial and non-singular: the (ci, cy) and (cy, ci) cases that are depicted in figure 1 where we denote by  $\beta$  and  $2\pi R$  the circumference of the compact time  $\tau$  and space  $\phi$  directions respectively.

The analysis of a holographic backgrounds that admit this structure was performed in [18]. To understand in detail the properties of the geometrical background and its dual boundary field theory, we briefly review the case of D3 branes. We will refer to this model as a d=3 Witten model (with d being the number of spatial dimensions or equivalently the noncompact space-time dimensions), when we want to emphasize its dimensionality or contrast with the original one [17] with a nontrivial dilaton profile. The first setup is with a cylinder in the  $(\tau, u)$  sub-manifold and a cigar r in the  $(\phi, u)$ , namely the (cy, ci) set

<sup>&</sup>lt;sup>1</sup>Note, however, that a metric that depends not only on u but also on other coordinates can be associated with a non-singular (ci, ci) topology.

up. We refer to it as the low temperature setup. The boundary field theory dual to this background in the limit of  $R \to 0$  relates to 3d pure YM-like theory. In [18] the background of large number of D4 branes was described [46]. This corresponds in the same limit to 4d YM-like theory. The reason we take the case of D3 branes is that it is conformal and hence somewhat easier to handle. We then describe also the high temperature setup of the (ci, cy) topology.

# 2.1 The (cylinder, cigar) low temperature phase

The (cy, ci) background, which is a solution of the type IIB string theory background is characterized by the metric, the RR four-form and a dilaton given by

$$ds^{2} = \left(\frac{u}{R_{D3}}\right)^{2} \left[d\tau^{2} + \delta_{ij}dx^{i}dx^{j} + f(u)d\phi^{2}\right] + \left(\frac{R_{D3}}{u}\right)^{2} \left[\frac{du^{2}}{f(u)} + u^{2}d\Omega_{5}^{2}\right],$$

$$F_{(5)} = \frac{2\pi N_{c}}{V_{5}}\epsilon_{5}, \quad e^{\phi} = g_{s}, \quad R_{D3}^{4} \equiv 4\pi g_{s}N_{c}l_{s}^{4}, \quad f(u) \equiv 1 - \left(\frac{u_{\Lambda}}{u}\right)^{4}, \quad (2.2)$$

where  $x^i$  (i=1,2) are the uncompactified world volume coordinates of the D3 branes. The volume of the five sphere  $\Omega_5$  is denoted by  $V_5$  and the corresponding volume form by  $\epsilon_5$ ,  $l_s$  is the string length and  $g_s$  is the string coupling. As discussed above, the sub-manifold of the background spanned by  $\phi$  and u has the topology of a cigar (as on the left-hand side of figure 1) where the minimum value of u at the tip of the cigar is  $u_{\Lambda}$ . The tip of the cigar is non-singular if and only if the periodicity of  $\phi$  is

$$\delta\phi = \frac{4\pi}{3} \left(\frac{R_{D3}^4}{u_{\Lambda}^2}\right)^{1/2} = 2\pi R \tag{2.3}$$

and we identify this with the periodicity of the circle that the 3 + 1-dimensional gauge theory lives on.

The parameters of this gauge theory, the four-dimensional gauge coupling  $g_4$ , the low-energy three-dimensional gauge coupling  $g_3$ , the glueball mass scale  $M_{gb}$ , and the string tension  $T_{st}$  are determined from the gravity background in the following form:

$$g_4^2 = (2\pi)g_s, \qquad g_3^2 = \frac{g_4^2}{2\pi R} = \left(\sqrt{\frac{g_s}{\pi N_c}} \frac{u_\Lambda}{l_s^2}\right)^{1/2}, \qquad M_{gb} = \frac{1}{R}$$

$$T_{st} = \frac{1}{2\pi l_s^2} \sqrt{g_{tt}g_{xx}}|_{u=u_\Lambda} = \frac{1}{2\pi l_s^2} \left(\frac{u_\Lambda}{R_{D3}}\right)^2 = \frac{\sqrt{4\pi N_c g_s}}{4R^2} = \frac{\sqrt{\lambda_4}}{R^2}, \tag{2.4}$$

where  $\lambda_4 \equiv 2g_4^2 N_c$ ,  $M_{gb}$  is the typical scale of the glueball masses computed from the spectrum of excitations around the background given<sup>2</sup> in (2.2), and  $T_{st}$  is the confining string tension in this model (given by the tension of a fundamental string stretched at  $u = u_{\Lambda}$  where its energy is minimized). The gravity approximation is valid whenever  $\lambda_4 \gg R$ , otherwise the curvature at  $u \sim u_{\Lambda}$  becomes large. Note that as usual in gravity

<sup>&</sup>lt;sup>2</sup>In fact, as was discussed in [47] part of the glueball spectra in holography is described by closed strings in this background and not by the spectra of fluctuations of the bulk fields.

approximations of confining gauge theories, the string tension is much larger than the "glueball" mass scale in this limit determined for excitations of the bulk fields. As was mentioned above, the Wilson line of this gauge theory admits an area law behavior [46], as can be easily seen using the conditions for confinement of [19].

Naively, at energies lower than the Kaluza-Klein scale 1/R the dual gauge theory is effectively three dimensional; however, it turns out that the theory confines and develops a mass gap of order  $M_{gb}=1/R$ , so (in the regime where the gravity approximation is valid) there is no real separation between the confined three-dimensional fields and the higher Kaluza-Klein modes on the circle. As discussed in [17], in the opposite limit of  $\lambda_4 \ll R/l_s$ , the theory approaches the pure 2+1 dimensional pure Yang-Mills theory at energies small compared to 1/R, since in this limit the scale of the mass gap is exponentially small compared to 1/R. It is believed that there is no phase transition when varying  $\lambda_4 l_s/R$  between the gravity regime and the pure Yang-Mills regime, but it is not clear how to check this.

# 2.2 The (cigar,cylinder) high temperature phase

The high temperature phase which associates with the (ci, cy) setup of figure 1. is described by the following gravity background

$$ds^{2} = \left(\frac{u}{R_{D3}}\right)^{2} \left[f(u)d\tau^{2} + \delta_{ij}dx^{i}dx^{j} + d\phi^{2}\right] + \left(\frac{R_{D3}}{u}\right)^{2} \left[u^{2}d\Omega_{5}^{2} + \frac{du^{2}}{f(u)}\right],$$

$$F_{(5)} = \frac{2\pi N_{c}}{V_{5}}\epsilon_{5}, \quad e^{\phi} = g_{s}, \quad R_{D3}^{4} \equiv \pi g_{s}N_{c}l_{s}^{4}, \quad f(u) \equiv 1 - \left(\frac{u_{T}}{u}\right)^{4}, \tag{2.5}$$

in the same notations as in (2.2).

In a similar manner to the low temperature phase, now to avoid a singularity at the tip of the cigar, if we require that the periodicity for the  $\tau$  coordinate obeys the same condition as in (2.3) but now with  $u_T$  replacing  $u_{\Lambda}$ . This replacement has to be made also in the relations between  $g_4^2$  and  $g_3^2$  and the parameters of the background. An important difference between the low and high temperature phases is that now following [19] the string tension vanishes since

$$T_{st} = \frac{1}{2\pi l_s^2} \sqrt{g_{tt} g_{xx}}|_{u=u_T} = \frac{1}{2\pi l_s^2} \left(\frac{u_\Lambda}{R_{D3}}\right)^2 \sqrt{1 - \left(\frac{u_T}{u}\right)}_{u=u_T} = 0.$$
 (2.6)

#### 2.3 Free energy and the phase diagram

The determination of the holographic phase diagram for the model of [46] was performed in [18]. Here we summarise the results and convert them to Witten's of three dimensional YM theory [17]. In order to decide which background dominates at a given temperature T one needs to compute the free energies of these backgrounds, given by the classical supergravity action times the temperature, and see which one has a lower free energy. As usual, the classical action actually diverges and needs to be regulated and renormalized. This can be achieved by determining the difference between the actions of the two solutions, which turns out to be finite. Using this method it is clear that the free energies of the two

solutions coincide when the (asymptotic) circumferences of the two circles are equal,  $\beta = 2\pi R$ , since the two solutions are identical then except for a relabelling of the coordinates. Thus, at this temperature  $T_c = 1/2\pi R$  there is a first order phase transition between the two backgrounds. The transition is of first order since the solutions do not smoothly connect there, but continue to exist as separate solutions both below and above the transition. It is easy to see that the background (cy, ci) dominates at low temperatures  $T < 1/2\pi R$ , while the background (ci, cy) dominates at high temperatures,  $T > 1/2\pi R$ .

The physical interpretation of this phase transition is straightforward. As was mentioned above, the stringy dual of the Wilson line stretched between an external quark anti-quark pair located on the boundary admits an area low behaviour at low temperature and a perimeter law at the high temperature phase.

Similarly, a computation of the value of the free energy in the two phases (which requires adding appropriate counter-terms) yields a result of order  $N_c^0$  in the low-temperature phase, and a result of order  $N_c^2$  in the high-temperature phase.

As one increases  $\frac{R}{l_s}$  compared to the scale set by the four dimensional gauge coupling  $\lambda_4$ , the supergravity background becomes highly curved, and the theory at low energies approaches the three dimensional pure Yang-Mills theory. It is believed that the confining deconfined transition described above is connected to the transition of the large  $N_c$  pure Yang-Mills theory in this limit. However, this connection is somewhat subtle [20], since even for large  $\frac{R}{l_s\lambda_4}$  it is clear by the symmetry arguments described above that there is always a phase transition line at  $T=1/2\pi R$  while the confining deconfining phase transition in the pure Yang-Mills theory occurs at a temperature of order  $\Lambda_{QCD}\ll 1/R$ . Due to the  $T\leftrightarrow 1/2\pi R$  symmetry there must then be at least one more phase transition line at a temperature much larger than 1/R. Thus, it was argued in [18] that new phases must appear as one approaches the three dimensional Yang-Mills limit. The phase structure of this theory in that limit includes several phase transition lines, which, presumably, all join into the line  $T=1/2\pi R$  in the gravity limit. A minimal conjecture for the phase structure is depicted in figure 2.

#### 3 The plasma-ball domain wall

In this section we discuss various aspects of the domain wall between confining and deconfining phases from the holographic perspective. This will serve to motivate the extended hydrodynamic picture for the domain wall and coexisting phases which we introduce and study in the remaining part of the paper.

# 3.1 Numerical study of the domain wall in gauge/gravity duality

The most important motivation for our work is the numerical study of the structure of the domain wall in gauge/gravity duality. The main observation is that, in particular, the energy density throughout the wall can be fitted to a good precision with a simple Ansatz involving the hyperbolic tangent function. We will study this in detail in the case of the (cy, ci) to (ci, cy) confinement-deconfinement transition, but the same has been shown to

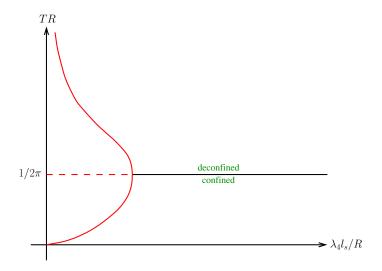


Figure 2. Possible phase diagram of the compactified D3 brane model as a function of the gauge coupling  $\lambda_4$  and the temperature.

hold also for transitions between two (deconfined) black hole phases in five dimensional Einstein-dilaton gravity [7].

In [20] the domain wall solution between a confining (cy, ci) geometry and the deconfining (ci, cy) geometry was constructed numerically by solving the Einstein equations for higher dimensional gravity. More precisely, the authors of this article considered planar domain wall solutions to the Einstein gravity with a cosmological constant in five and six dimensions, which are closely related to  $AdS_5$  (d=3) and  $AdS_6$  (d=4) spaces, respectively. Notice that the six dimensional geometry differs from the holographic model [17, 46] of compact D4 background as there is no dilaton (or the dilaton is constant) and the background is conformal. We will discuss here the domain wall in this five dimensional geometry, and the results for the six dimensional geometry are given in appendix A. The numerical study is restricted to the critical temperature where the solution is static. Generalizations to spherical domains [36] and real-time evolution producing such spherical plasma balls [11] have been also considered in the literature.

The confining five-dimensional geometry (AdS<sub>5</sub> with one spatial direction compactified) is the reduction of (2.2) to five dimensions:

$$ds_{\text{con.}}^2 = \left(\frac{u}{R_{D3}}\right)^2 (d\tau^2 + \delta_{ij} dw^i dw^j + f(u) d\phi^2) + \left(\frac{R_{D3}}{u}\right)^2 \frac{du^2}{f(u)}$$
(3.1)

where

$$f(u) = 1 - \left(\frac{\pi R_{D3} T_c}{u}\right)^4, (3.2)$$

 $R_{D3}^2$  is the AdS radius,  $\tau$  is the euclidean time,  $\phi$  is the compactified spatial coordinate, the indices i, j run from 1 to 2, and the critical temperature is related to the radius of compactification through  $T_c = 1/2\pi R$ . This solution and the deconfining geometry at

critical temperature,

$$ds_{\text{decon.}}^2 = \left(\frac{u}{R_{D3}}\right)^2 (f(u)d\tau^2 + \delta_{ij}dw^i dw^j + d\phi^2) + \left(\frac{R_{D3}}{u}\right)^2 \frac{du^2}{f(u)u^2}$$
(3.3)

satisfy the five-dimensional Einstein equations with a cosmological constant,

$$R_{\mu\nu} = -\frac{4}{R_{D3}^2} g_{\mu\nu} \ . \tag{3.4}$$

The interpolating geometry between these two geometries was solved numerically by using a special set of coordinates (see [20] for details) but we find it useful to write it in Fefferman-Graham coordinates:

$$ds^{2} = \frac{1}{z^{2}} \left[ \mathcal{A}(z, x) d\tau^{2} + \mathcal{B}(z, x) d\phi^{2} + \mathcal{C}(z, x) dy^{2} + \mathcal{D}(z, x) dx^{2} + dz^{2} \right], \qquad (3.5)$$

where y denotes the spatial coordinate parallel to the domain wall:  $y = w_1$ . The coordinates z and x can be understood to be nontrivial combinations of  $w_2$  and u. In Fefferman-Graham coordinates, the holographic coordinate z vanishes at the UV boundary (so that it is  $z \sim 1/u$  near the boundary). The spatial coordinate x is interpreted as the coordinate perpendicular to the wall. The factors A, B, C, and D depend on the coordinates z and x only. The units of the solution (also setting  $R_{D3}$  to one) are chosen such that

$$\mathcal{A}, \mathcal{B}, \mathcal{C}, \mathcal{D} \to 1 \text{ as } z \to 0.$$
 (3.6)

After this the overall energy scale  $\sim T_c$  is the only free parameter. The solution enjoys a  $\mathbb{Z}_2$  symmetry which reflects the symmetry of the setup under the exchange  $\tau \leftrightarrow \phi$  at the critical temperature:

$$\mathcal{A}(z,x) = \mathcal{B}(z,-x), \qquad \mathcal{C}(z,x) = \mathcal{C}(z,-x), \qquad \mathcal{D}(z,x) = \mathcal{D}(z,-x), \tag{3.7}$$

where we chose the center of the domain wall to lie at x=0. In our conventions the solution asymptotes to the deconfined geometry (3.3) (confined geometry (3.1)) as  $x \to -\infty$   $(x \to +\infty)$ .

Before going to the structure of the domain wall in these solutions, we discuss the qualitative behavior and the topology of the interpolating geometry. In the bulk the geometry ends at a horizon at some  $z = z_h(x)$ , where

$$\mathcal{A}(z_h(x), x) = 0, \qquad (x \le 0); \qquad (3.8)$$

$$\mathcal{B}(z_h(x), x) = 0, \qquad (x \ge 0). \tag{3.9}$$

These conditions correspond to the end points of the cigars in the confining (cy, ci) and deconfining (ci, cy) geometries, respectively. In Fefferman-Graham coordinates these end points are actually second order zeroes. In the middle of the wall, x = 0, both the conditions (3.8) and (3.9) are satisfied at some (finite)  $z_h$ . Therefore the x = 0 slice of the interpolating solution has the topology (ci, ci).

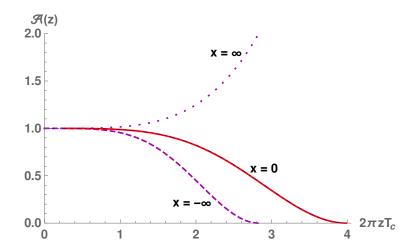


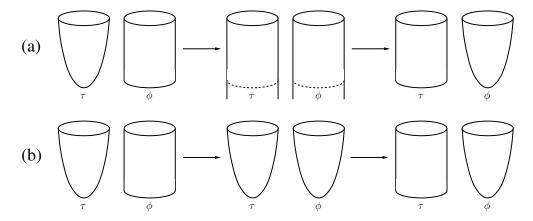
Figure 3. Evolution of the metric component  $A(z) = z^2 g_{\tau\tau}(z)$  in the Fefferman-Graham coordinates with varying x. The dashed and dotted magenta curves show the metric in the cigar (deconfined) and cylinder (confined) limits, respectively. The red curve is the metric in the middle of the domain wall, x = 0. The dot-dashed thin blue curve is the cigar geometry with z-dependence rescaled by the factor 1.41.

This observation may be verified by plotting the components of the metric: see figure 3 for the shape of  $\mathcal{A}(z,x)$  in the middle as compared to the limiting functions<sup>3</sup> at  $x \to \pm \infty$ . Due to the symmetry (3.7),  $\mathcal{B}(z,x)$  shows the same behavior (with  $x = -\infty$  and  $x = +\infty$  exchanged). We notice that the factors  $\mathcal{A}(z,0)$  and  $\mathcal{B}(z,0)$  in the middle of the wall (the red curve in the plot) are almost exactly given by a rescaled cigar geometry (the dot-dashed blue curve). The cigars in the middle are therefore elongated by a moderate factor 1.41 with respect to the cigars in the confining and deconfining limits. This also means that the dependence of  $z_h(x)$  is on x is rather weak.

This result may appear surprising given the fact that the (x-independent) (ci, ci) solution is singular. However if this topology only appears in a single slice of a higher dimensional geometry, there is no singularity.

This observation means roughly the following. There are two simple "idealized" ways to interpolate between the (cy, ci) and (ci, cy) geometries in (3.1) and in (3.3) (see the sketch in figure 4). The first one is  $(ci, cy) \to (cy, cy) \to (cy, ci)$  shown in figure 4a: we start from the geometry (3.3) and treat  $T_c$  in f(u) as a parameter. We smoothly reduce its value taking  $T_c \to 0$  in the end which leads to the (cy, cy) geometry with  $f(u) \to 1$ , i.e., the pure AdS<sub>5</sub> solution. We then introduce the blackening factor in the  $d\phi^2$  component, turning back nonzero  $T_c$  and smoothly evolve it to the original value, finally obtaining the (cy, ci) solution. The second one is  $(ci, cy) \to (ci, ci) \to (cy, ci)$  shown in figure 4b: now we add instead a second blackening factor in the  $d\phi^2$  term from the start, and smoothly evolve the parameter  $T_c$  in this blackening factor to the value of the blackening factor of the  $d\tau^2$  term, therefore obtaining a (ci, ci) geometry. Then we reduce the value of the  $T_c$ 

<sup>&</sup>lt;sup>3</sup>Notice that the "cylinder" form at  $x \to +\infty$  is  $\mathcal{A}(z) = 1 + z^4/z_h^4$  in the Fefferman-Graham coordinates, while for the flat (cy, cy) geometry one has  $\mathcal{A}(z) = 1$ .



**Figure 4.** Possible "interpolations" between the deconfined and confined geometries in figure 1. Top row (a): interpolation through the (cy, cy) geometry. Bottom row (b): interpolation through the (ci, ci) geometry.

parameter of the blackening factor of the  $d\tau^2$  term smoothly to zero, which gives the final (cy, ci) geometry. We stress that neither of these simple interpolations give rise to a solution of the five-dimensional Einstein equations, with the understanding that the interpolation is understood as a dependence on the coordinate x perpendicular to the domain wall. However our point is that the interpolation defined by the x-dependence in the geometry of [20] which does solve the Einstein equations, is clearly closer to the second than the first option. The main difference between the numerical geometry and the ideal picture appears to be the fact that the cigars of the (ci, ci) slice are elongated, as shown in figure 3.

#### 3.2 Analysis of the energy momentum tensor of the domain wall

We then go on discussing the field theory observables i.e., the components of the energy-momentum tensor  $T_{\mu\nu}$ . They are found as the coefficients of the subleading  $\mathcal{O}(z^4)$  terms of the geometry at the boundary. Notice that due to the form of the metric in (3.5),  $T_{\mu\nu}$  is diagonal. We have extracted these coefficients from the domain wall solution of [20] and show the results in figures 5 and 6. The tensor is diagonal and only depends on the coordinate x. To plot the results, we use the normalized<sup>4</sup> energy-momentum tensor

$$\hat{T}_{\mu\nu}(x) = -\frac{4\pi G_5}{R_{D3}^3 (\pi T_c)^4} \left( T_{\mu\nu}(x) - T_{xx} \right)$$
(3.10)

where  $G_5$  is the Newton constant. That is, we divide out the trivial known proportionality constant, and subtract the value of  $T_{xx}$  (the pressure perpendicular to the domain wall) which is constant for the domain wall solution due to the conservation law  $\partial_{\mu}T^{\mu\nu} = 0$ . The value of the constant is

$$T_{xx} = \frac{R_{D3}^3}{16\pi G_5} \left(\pi T_c\right)^4 . {3.11}$$

With this normalization,  $\hat{T}_{\tau\tau} = 1$  for the deconfined geometry of (3.9), for example.

<sup>&</sup>lt;sup>4</sup>Our sign conventions (in the Euclidean signature) are such that for the deconfined phase  $T_{\tau\tau} = -\epsilon < 0$  (where  $\epsilon$  is the energy density) whereas the spatial component  $T_{ii}$  of the energy momentum tensor are positive.

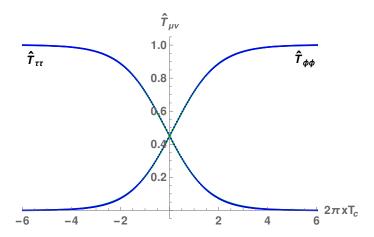


Figure 5. Phenomenological fitting of the (normalized) components of the energy-momentum tensor  $\hat{T}_{\tau\tau}$  and  $\hat{T}_{\phi\phi}$ . Blue dots show the energy-momentum tensor extracted from the numerically constructed geometry of [20], and the green curves are given by the fit in equation (3.12).

The results for the normalized energy density  $\hat{T}_{\tau\tau}$  and the pressure in the compactified direction  $\hat{T}_{\phi\phi}$  are shown<sup>5</sup> in figure 5. The blue dots show the data obtained from the numerical solution, and the green curves are given by the following fit:

$$\hat{T}_{\tau\tau}(-x) = \hat{T}_{\phi\phi}(x) = \frac{1}{2} + \frac{1}{2} \tanh\left(q_* \frac{x - x_0}{2}\right) . \tag{3.12}$$

The system is therefore in the deconfined (confined) phase in the domain x < 0 (x > 0). For the fit parameters we obtain

$$\frac{q_*}{2\pi T_c} \approx 1.148 \,, \qquad 2\pi T_c x_0 \approx 0.181 \,.$$
 (3.13)

The quality of the fit is very good: it appears to be even better than a similar fit for an interface between two deconfined phases in [7].

Since  $x^0$  is nonzero, there is a small but significant shift of the profile of the energy density from the middle of the domain wall, which is at x=0 as determined by the  $\mathbb{Z}_2$  symmetry. The shift also gives rise to a nontrivial component of the pressure parallel to the wall,  $\hat{T}_{yy}$ . This component is given by

$$\hat{T}_{yy}(x) = 1 - \hat{T}_{\tau\tau}(x) - \hat{T}_{\phi\phi}(x),$$
 (3.14)

which is obtained by combining the tracelessness condition  $T^{\mu}_{\mu} = 0$  with (3.10). Inserting here the fit from (3.12) gives the prediction

$$\hat{T}_{yy} = \frac{1}{2} \left[ \tanh \left( q_* \frac{x + x_0}{2} \right) - \tanh \left( q_* \frac{x - x_0}{2} \right) \right] . \tag{3.15}$$

<sup>&</sup>lt;sup>5</sup>Due to numerical inaccuracy the asymptotic values of  $\hat{T}_{\mu\nu}$  agree with the analytic formulas in (3.10) and in (3.11) only within an accuracy of about one or two per cent. Since we are mainly interested in the x-dependence at the domain wall, we "renormalized" the numerical data such that, for example,  $\hat{T}_{\tau\tau}$  does approach one (zero) for  $x \to -\infty$  ( $x \to +\infty$ ).

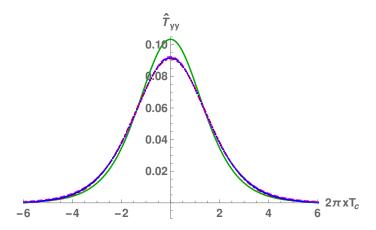


Figure 6. Phenomenological fitting of the (normalized)  $\hat{T}_{yy}$  component of the energy-momentum tensor. The blue dots show the energy-momentum tensor extracted from the numerically constructed geometry of [20]. The green curve is the prediction from the fit of figure 5, given in equation (3.15). The dashed magenta and dot-dashed red fits were obtained by using the former and latter formulas of equation (3.16), respectively.

We compare this prediction (green curves), with the parameter values from (3.13), to numerical data (blue dots) in figure 6. The maximal deviation is about ten percent and is due to two sources: the error in the tanh fits and inaccuracy of the numerical solution (so that the trace  $T^{\mu}_{\mu}$  is not precisely zero). The error from both sources has roughly the same size. Notice that due to the relatively small size of the shift  $x_0$ , the magnitude of  $\hat{T}_{yy}$  is suppressed roughly by a factor of ten with respect to the step size in figure 5. This is why the errors are better visible in figure 6.

We also fitted the data for  $\hat{T}_{yy}$  directly using the following functions:

$$\hat{T}_{yy}(x) = \frac{c^{(2)}}{\left(\cosh\frac{q_*^{(2)}x}{2}\right)^2}, \qquad \hat{T}_{yy}(x) = \frac{c^{(4)}}{\left(\cosh\frac{q_*^{(4)}x}{2}\right)^4}. \tag{3.16}$$

The first of these functions has an obvious motivation: taking the small  $x_0$  approximation of (3.15) leads to

$$\hat{T}_{yy} \approx \frac{q_* x_0}{2} \frac{1}{\left(\cosh\frac{q_* x}{2}\right)^2}$$
 (3.17)

and the motivation for the second function will become clear below. The results for the two parameter fits to data are shown in figure 6 with dashed magenta curves for the  $cosh^{-2}$  fit and dot-dashed red curves for the  $cosh^{-4}$  fit. The fits are so good that it is difficult to disentangle them for the data (blue dots) so we conclude that within the precision of our numerics, both fits work extremely well. The fit parameters are in this case

$$\frac{q_*^{(2)}}{2\pi T_c} \approx 1.023, \qquad c^{(2)} \approx 0.0925;$$

$$\frac{q_*^{(4)}}{2\pi T_c} \approx 0.681, \qquad c^{(4)} \approx 0.0910.$$
(3.18)

From these fit results and the results for the tanh fit in (3.13) we observe that  $q_*^{(2)}$  is close to  $q_*$ : we find  $q_*^{(2)} < q_*$ , and the difference is around ten per cent. We also notice that  $q_*^{(2)}/q_*^{(4)} \simeq 1.5$ . We will discuss these findings further by using an extended hydrodynamic framework below in section 4.

# 3.3 Modelling the domain wall in gauge/gravity duality

The above findings, in particular the success of the simple tanh fit in figure 5, give rise to two natural questions. The first is if there is a simple effective description (in terms of the field theory degrees of freedom) of the domain wall which gives rise to the observed structure. This is the main topic of the current article and will be addressed in detail in the following sections. The second is whether this structure can be obtained from gauge/gravity duality in some analytic approximation. This second question turns out to be difficult. We have however obtained some limited understanding on how the domain wall arises from the solutions of the Einstein equations, which we will now discuss.

We observe that the Einstein equations in Fefferman-Graham coordinates imply that there are two conserved bulk currents: the first (J) satisfies

$$\partial_z J^z + \partial_x J^x = 0$$
,  $J^z = \frac{1}{z^3} \sqrt{\frac{\mathcal{BC}}{\mathcal{A}}} \mathcal{D}^{3/2} \frac{\partial}{\partial z} \left(\frac{\mathcal{A}}{\mathcal{D}}\right)$ ,  $J^x = \frac{1}{z^3} \sqrt{\frac{\mathcal{B}}{\mathcal{AC}}} \mathcal{D}^{3/2} \frac{\partial}{\partial x} \left(\frac{\mathcal{A}}{\mathcal{D}}\right)$ , (3.19)

and the second  $(\tilde{J})$  is obtained by interchanging  $\mathcal{A} \leftrightarrow \mathcal{B}$ . The existence of such currents is no surprise: they reflect the Smarr relation for black holes which states that the energy of the black hole can be computed both from the asymptotics and from horizon data [48]. In the case of homogeneous black hole geometries in our setup, the conservation of the bulk current J implies the standard thermodynamic relation  $\varepsilon + p = sT$ . For the domain wall setup, we find that the conserved "charge density" is at the boundary

$$J^z|_{z=0} \propto \hat{T}_{\tau\tau} - \hat{T}_{yy} \tag{3.20}$$

which shows a smooth step from one to zero over the domain wall as we see from figures 5 and 6. At the horizon  $z = z_h$  we find that

$$J^{z}|_{z=z_{h}} = s_{h} \sqrt{2 \mathcal{A}''(z_{h})}, \quad (x < 0); \quad J^{z}|_{z=z_{h}} = 0, \quad (x > 0); \quad (3.21)$$

where

$$s_h = \frac{\sqrt{\mathcal{B}(z_h)\mathcal{C}(z_h)\mathcal{D}(z_h)}}{z_h^3} \tag{3.22}$$

is the area element of the black hole.

These results suggest the following picture. As we have seen in figure 3 the geometry in the deconfined phase varies relatively little as we move from  $x = \infty$  to x = 0. Therefore the bulk charge density  $J^z(z,x)$  becomes essentially a step function at the horizon. During the evolution of the charge density from the horizon to the boundary, determined by equation (3.19) and the other Einstein equations, the charge is diffused a bit which gives rise to the smooth step. Notice that because the total charge  $\int dx J^z$  is conserved under

this evolution and because  $J^x$  vanishes far from the domain wall, only minor rearrangement of the charge is possible.

We can make some quantitative estimates which support the above picture by resorting to simple modeling. First, because we have seen that  $z_h$  depends only mildly on x in the domain wall solution, we take  $z_h$  to be constant. Second, we take the boundary condition for the current at the horizon to be exactly the step function. Third, we simply study the propagation due to a scalar field in plain  $AdS_5$  geometry. Fourth, we look at the current  $\Delta J = J - \tilde{J} = J - J(A \leftrightarrow B)$ , which links to the difference  $\hat{T}_{\tau\tau} - \hat{T}_{\phi\phi}$ , instead of (3.20). This last simplification is useful because  $\hat{T}_{\tau\tau} - \hat{T}_{\phi\phi}$  is odd in x and has a simple tanh profile for the domain wall solution without any shifts. The model setup may be formally obtained from (3.19) (and its  $A \leftrightarrow B$  interchanged counterpart) through the Ansatz C = 1 = D and

$$A(z,x) = \exp(+\xi(z,x)), \qquad B(z,x) = \exp(-\xi(z,x)),$$
 (3.23)

with  $\xi(z,x) = -\xi(z,-x)$ , so that the symmetry condition in (3.7) is satisfied. Since  $\mathcal{A}$  and  $\mathcal{B}$  approach one at the boundary,  $\xi$  must vanish there.

We find that  $\xi$  satisfies the Laplacian in AdS<sub>5</sub>,

$$z^{3} \frac{\partial}{\partial z} \left( \frac{1}{z^{3}} \frac{\partial}{\partial z} \xi(z, x) \right) + \frac{\partial^{2}}{\partial x^{2}} \xi(z, x) = 0, \qquad (3.24)$$

and the current is given by

$$\Delta J^{\mu} = \frac{2}{z^3} \frac{\partial}{\partial x_{\mu}} \xi(z, x) \ . \tag{3.25}$$

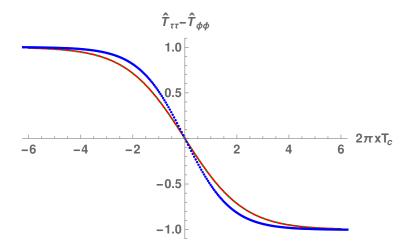
The solution which satisfies the boundary conditions  $\xi(0, x) = 0$  and  $\Delta J^z(z_h, x) = -\operatorname{sgn}(x)$  is given by

$$\Delta J^{z}(z,x) = -\int_{-\infty}^{\infty} dk \, \frac{z_{h} I_{1}(kz) \sin(kx)}{\pi kz \, I_{1}(kz_{h})}$$
(3.26)

where  $I_1$  is the modified Bessel function of the first kind.

Finally we compare the boundary value of  $\Delta J^z$  to the numerical data for  $\hat{T}_{\tau\tau} - \hat{T}_{\phi\phi}$  in figure 7. To do this, we fixed  $z_h = 1/(\pi T_c)$  as obtained from the AdS solution of (3.3) with the understanding that u = 1/z. One might expect that we should use the Fefferman-Graham value for  $z_h$  which is smaller by a factor of  $\sqrt{2}$  but we feel that the above choice is better since the geometry of (3.3) is closer to empty AdS<sub>5</sub> (which we are in practice using here) than the black hole geometry in Fefferman-Graham coordinates. Actually, the results for both values are roughly equally good, with the best fit value lying between the two. From the plot we see that  $\Delta J^z(0,x)$  is very well fitted by the tanh function (green dotted curve), and the value of  $q_*/(2\pi T_c) \approx 0.897$  from this fit is slightly below the value 1.148 obtained by fitting the data directly in (3.13).

We have therefore demonstrated that the simple model, with diffusion of the conserved bulk charge obtained from propagators for empty AdS<sub>5</sub>, roughly agrees with the numerical data for the full solution of Einstein equations for the domain wall. In particular, the profile obtained for  $\hat{T}_{\tau\tau} - \hat{T}_{\phi\phi}$  is again extremely close to the tanh form, and the width of the domain wall is close to the width of the exact solution. There are also some obvious shortcomings: the simple model does not capture the shifts of the tanh profile for  $\hat{T}_{\tau\tau}$  and



**Figure 7**.  $\hat{T}_{\tau\tau} - \hat{T}_{\phi\phi}$  from a simple model compared to the numerical data for the domain wall. The blue dots are numerical data from the exact solution, the red solid curve is given by (3.26) at z = 0, and the dotted green curve is a tanh fit to the red curve.

 $\hat{T}_{\phi\phi}$  (i.e., a nonzero value of  $x_0$  in (3.12)) which are linked to nonzero surface tension. Moreover, we did not find a way to derive systematically the approximation of equations (3.24) and (3.25) from the Einstein equations. While the Ansatz of equation (3.23) solves the current conservation equations assuming (3.24), some of the other Einstein equations are not satisfied.

We will therefore shift our considerations to the boundary theory and proceed to model directly the energy-momentum tensor of the coexisting phases and domain walls.

# 4 A covariant energy-momentum tensor for the domain wall and coexisting phases

As explained in the introduction, our goal is to find a simple covariant formulation which would allow us to describe a system made up of coexisting domains of the confining and deconfined phases and domain walls separating them. At the same time we would like to retain the possibility of describing arbitrary plasma flows in the deconfined phase, hence our formulation should necessarily extend hydrodynamics.

Ideally, following the approach of fluid/gravity duality, we would model the holographic spacetime geometry locally as either a patch of the confining geometry or fluid/gravity geometry or a plasma-ball domain wall. Unfortunately, the gravitational description of such a composite system is extremely complicated, as we indicated in the previous section. Therefore, we decided to perform the modelling at the level of the energy-momentum tensor of the boundary field theory, and use the known numerical plasma-ball domain wall solution as additional holographic input which would constrain both the overall structure and the precise coefficients of the field theory energy-momentum tensor. Similarly as in the case of conventional hydrodynamics, we treat the conservation laws of the postulated energy-momentum tensor as the resulting dynamical equations of our model.

#### 4.1 Energy-momentum tensors — general structure

The energy-momentum tensors of the two phases are well known. For the confining phase in the d=3 Witten's model [17] we have

$$T_{\mu\nu}^{\rm conf} = \eta_{\mu\nu} - 4n_{\mu}n_{\nu} \tag{4.1}$$

where  $n^{\mu}$  is a unit vector pointing in the direction of the auxiliary  $\phi$  circle. As the energy-momentum tensor in the deconfined phase we take the leading order perfect fluid hydrodynamics:

$$T_{\mu\nu}^{\text{deconf}} = p_{\text{hydro}}(T) \left( \eta_{\mu\nu} + 4u_{\mu}u_{\nu} \right) . \tag{4.2}$$

In this paper we neglect all dissipative terms.  $p_{\text{hydro}}(T)$  is the hydrodynamic pressure expressed as a function of the temperature. With the normalization of (4.1), we have

$$p_{\text{hvdro}}(T_c) = 1 \ . \tag{4.3}$$

Let us now move to the domain-wall solution reviewed in section 3 and recast its energy-momentum tensor in a covariant manner. To this end, let us identify the tensors that we have at our disposal. Apart from the metric  $\eta_{\mu\nu}$ , we have the flow velocity in the deconfined phase  $u^{\mu}$  (which corresponds to a fluid at rest for the solution from section 3), the vector  $n^{\mu}$  in the direction of the  $\phi$  circle, and a new ingredient — a vector perpendicular to the domain wall  $v^{\mu}$  (in the later parts of this paper we will take  $v^{\mu}$  to be proportional to a gradient of a scalar field  $v_{\mu} \propto \partial_{\mu} \gamma$ ).

For the numerical domain wall solution described in the previous section, the energy-momentum tensor turns out to be formed just from  $diagonal^6$  combinations of the above vectors i.e. it is a linear combination of

$$\eta_{\mu\nu}, \quad u_{\mu}u_{\nu}, \quad v_{\mu}v_{\nu}, \quad n_{\mu}n_{\nu}$$
 (4.4)

subject to the condition of tracelessness. Hence we have three independent scalar coefficients.

Clearly the energy-momentum tensors of the confined and deconfined phase also fit the above structure. Therefore we will parametrize the overall energy-momentum tensor as

$$T_{\mu\nu}(x) = T_{\mu\nu}^{\text{mix}}(x) + T_{\mu\nu}^{\Sigma}(x)$$
 (4.5)

where  $T_{\mu\nu}^{\rm mix}(x)$  is a linear combination of the energy-momentum tensors of the two coexisting phases

$$T_{\mu\nu}^{\text{mix}}(x) = \Gamma(x)T_{\mu\nu}^{\text{conf}}(x) + (1 - \Gamma(x))T_{\mu\nu}^{\text{deconf}}(x)$$
 (4.6)

The mixing coefficient  $\Gamma(x)$  will be an additional non-hydrodynamic degree of freedom, which we add to the hydrodynamic degrees of freedom  $p_{\text{hydro}}$  and  $u^{\mu}$ . The goal of this paper is essentially to provide consistent equations of motion and energy-momentum tensor for

<sup>&</sup>lt;sup>6</sup>There could be a possible non-diagonal quartic term  $(u \cdot v) \left(u^{\mu}v^{\nu} + v^{\mu}u^{\nu} - \frac{1}{2}(u \cdot v)\eta^{\mu\nu}\right)$ . However for the known domain wall solution this term is identically zero, hence we ignore this term in the present paper.

this additional degree of freedom. The scalar  $\Gamma(x) = 1$  in the confined phase and  $\Gamma(x) = 0$  in the deconfined phase, at  $T = T_c$ .

The second part of the energy-momentum tensor (4.5),  $T^{\Sigma}_{\mu\nu}(x)$  is assumed to vanish when  $\Gamma(x)$  is a constant equal to either 0 or 1. Hence it has support essentially only on the domain wall. We will see later that it is responsible for describing the surface tension of the wall. We can write it in general as

$$T_{\mu\nu}^{\Sigma} = \Sigma \left( -\eta_{\mu\nu} + Av_{\mu}v_{\nu} - Bu_{\mu}u_{\nu} - Cn_{\mu}n_{\nu} \right) \tag{4.7}$$

where  $\Sigma$ , A, B and C are coefficients which should be determined.

By specializing to the static planar domain wall solution, we can deduce a further requirement for  $T^{\Sigma}_{\mu\nu}$ . Conservation of energy-momentum implies that the  $T_{xx}$  component is constant. Since this is automatically satisfied by the first two terms

$$\Gamma(x) + (1 - \Gamma(x)) \underbrace{p_{\text{hydro}}(T_c)}_{=1} = 1, \qquad (4.8)$$

it follows that  $T_{xx}^{\Sigma}$  is a constant. But since we assumed that  $T_{\mu\nu}^{\Sigma}$  vanishes far away from the domain wall, that constant must be equal to zero. Therefore we find that A=1 when evaluated on the domain wall solution, so

$$T_{\mu\nu}^{\Sigma} = \Sigma \left( -\eta_{\mu\nu} + v_{\mu}v_{\nu} - Bu_{\mu}u_{\nu} - Cn_{\mu}n_{\nu} \right) . \tag{4.9}$$

In our setup  $T_{\mu\nu}^{\Sigma}$  has to be traceless, so

$$B - C = 3$$
. (4.10)

Let us summarize the structure obtained so far. The energy-momentum tensor of a system combining the confined and deconfined phases has the form

$$T_{\mu\nu}(x) = \Gamma T_{\mu\nu}^{\rm conf}(x) + (1 - \Gamma) T_{\mu\nu}^{\rm deconf}(x) + \Sigma \left( -\eta_{\mu\nu} + v_{\mu}v_{\nu} - Bu_{\mu}u_{\nu} + (3 - B)n_{\mu}n_{\nu} \right) . \tag{4.11}$$

The dynamical variables are: the hydrodynamic pressure  $p_{\text{hydro}}$  and flow velocity  $u^{\mu}$  in the deconfined phase, the vector  $v^{\mu}$  and  $\Gamma$ ,  $\Sigma$  and B coefficients. We will express the latter four quantities in terms of a single scalar field  $\gamma$ .

#### 4.2 Energy-momentum tensor — comparison with holography

We will now go back to the holographic solution for the numerical domain wall geometry described in the previous section, in order to determine  $\Gamma$ ,  $\Sigma$  and B. It turns out that two different fits motivated by the analysis of section 3.2 are possible. We will discuss them now in turn. We start with the most natural one in view of the fit results of section 3.2.

**Option A.** The coefficient  $\Gamma$  is treated as an independent scalar field  $\gamma$  and  $\Sigma$  and B will turn out to be simple functionals of  $\gamma$ . The solution of [20] is very well reproduced if

$$\Gamma(x) \equiv \gamma(x) = \frac{1}{2} + \frac{1}{2} \tanh\left(\frac{q_* x}{2}\right)$$
 (4.12)

Then looking at the  $T_{xx} - T_{yy}$  component of the energy momentum tensor of [20] we may express  $\Sigma$  as

$$\Sigma = c \cdot \frac{\gamma'^2}{\gamma(1-\gamma)} = c \cdot \frac{q_*^2}{4\cosh^2\frac{q_*x}{2}} . \tag{4.13}$$

Notice that unlike the fit of section 3.2, this description does not include a shift  $x^0$ . The shift parameter is, in effect, replaced by the coefficient c here. This combination has the interpretation of the surface tension density, whose integral over x gives the surface tension (see section 6.1). Now examining any other component like  $T_{tt}$  we find that

$$B = 1 + \Gamma = 1 + \gamma . \tag{4.14}$$

We expect that the expression for B could be different for other theories.

Before we continue, let us comment on the holographic interpretation of the scalar field  $\gamma$ . Consider the region where  $\gamma$  is very small. Then the energy-momentum tensor is essentially

$$T_{\mu\nu} = T_{\mu\nu}^{\text{deconf}} + \gamma(x) \left( T_{\mu\nu}^{\text{conf}} - T_{\mu\nu}^{\text{deconf}} \right) + \mathcal{O}\left(\gamma^2\right) . \tag{4.15}$$

Holographically, we can understand  $\gamma$  as the boundary limit of a linearized perturbation of the planar black hole geometry, and thus a quasi-normal mode (QNM). This quasi-normal mode is slightly nonstandard as its behaviour is like

$$q(x) \sim e^{q_* x} \tag{4.16}$$

so it has purely imaginary momentum and vanishing frequency. Indeed such QNM's were identified in the context of nonequilibrium steady states in [49], with the imaginary momentum setting the scale for the characteristic width, and earlier in the context of an absorption length in [50]. As this holographic degree of freedom is crucial for the description of a domain wall, and thus we should incorporate it directly into any low-energy effective description. We give some additional comments on the possible interpretation of  $\gamma$  in section 8.

**Option B.** The second option is slightly less natural. Its advantage is its relation to a canonical scalar field action as we will see in the following section as well as a link to Landau's description of phase transitions which we touch on in section 8.

Since as we saw in section 3.2, the  $T_{xx} - T_{yy}$  can also be fit by  $1/\cosh^4$ , which allows for taking

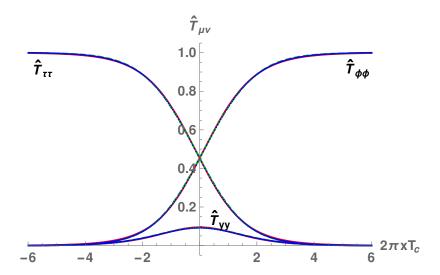
$$\Sigma = c \cdot \gamma'^2 = c \cdot \frac{q_*^2}{16 \cosh^4 \frac{q_* x}{2}} \tag{4.17}$$

without the  $\gamma(1-\gamma)$  denominator appearing in (4.13). The drawback is that the  $q_*$  coming from the above expression is not compatible with the mixing coefficient  $\Gamma = \gamma$  and (4.12). One can nevertheless cure this discrepancy by taking the following more involved expression for  $\Gamma$ :

$$\Gamma = \gamma^2 (3 - 2\gamma) \ . \tag{4.18}$$

This explicit form is motivated by the considerations of section 7. The coefficient B is again given by

$$B = 1 + \Gamma . (4.19)$$



**Figure 8**. Final fits of the model to the numerical solution for the domain wall. The blue dots, solid red curve, and dashed green curve show the numerical data, fit using the option A, and fit using the option B, respectively.

Comparison with the numerical solution. We then compare our formulation to the components of the energy momentum tensor extracted from the numerical solution for the domain wall [20] which we discussed in section 3.1. By using the expression for the complete energy momentum tensor in (4.11) (and transforming to Euclidean conventions), we obtain for the normalized components  $\hat{T}_{\mu\nu}$  defined in (3.10)

$$\hat{T}_{\tau\tau} = 1 - \Gamma - \frac{1}{4}\Sigma\Gamma, \qquad \hat{T}_{\phi\phi} = \Gamma - \frac{1}{4}\Sigma(1 - \Gamma), \qquad \hat{T}_{yy} = \frac{1}{4}\Sigma, \qquad (4.20)$$

where we already inserted  $B = 1 + \Gamma$ . We remind that for the two options discussed above we have

$$\Gamma = \gamma$$
,  $\Sigma = c \frac{{\gamma'}^2}{\gamma(1-\gamma)}$ , (Option A); (4.21)

$$\Gamma = \gamma^2 (3 - 2\gamma), \qquad \qquad \Sigma = c \gamma^2, \qquad \qquad \text{(Option B)},$$

and for both options

$$\gamma(x) = \frac{1}{2} + \frac{1}{2} \tanh\left(\frac{q_* x}{2}\right)$$
 (4.23)

We have carried out a least squared fit of  $q_*$  and c to the data for  $\hat{T}_{\mu\nu}$  extracted from the numerical domain wall solution to the Einstein equations. We used the components  $\hat{T}_{\tau\tau}$  and  $\hat{T}_{yy}$  for the fit (and excluded  $\hat{T}_{\phi\phi}$  because it gives no additional information due to reflection symmetry about the center of the wall). The fit results are shown in figure 8. The fit for option B is slightly better than the fit for option A, with 30% smaller root mean square error. It is however difficult to see this from the plot because both curves are so close to the data. Actually, the deviation from the numerical data is smaller than its accuracy for both fits.

The fit results are given by

$$\frac{q_*}{2\pi T_c} \approx 1.055, \qquad c (2\pi T_c)^2 \approx 0.342, \qquad \text{(Option A)};$$
 (4.24)

$$\frac{q_*}{2\pi T_c} \approx 1.055$$
,  $c(2\pi T_c)^2 \approx 0.342$ , (Option A); (4.24)  
 $\frac{q_*}{2\pi T_c} \approx 0.682$ ,  $c(2\pi T_c)^2 \approx 3.167$ , (Option B).

We note that the value of  $q_*$  for option A (option B) agrees well with the fit result to  $\hat{T}_{yy}$ carried out in section 3.2 with the  $cosh^{-2}$  ( $cosh^{-4}$ ) Ansatz, i.e.,  $q_*^{(2)}$  ( $q_*^{(4)}$ ) in equation (3.18). This is as expected: using the tanh form for  $\gamma$  leads to  $\hat{T}_{yy} \propto \cosh^{-2}(q_*x/2)$  for option A and to  $\hat{T}_{yy} \propto \cosh^{-4}(q_*x/2)$  for option B. Therefore the main difference between the final fit and the fits of section 3.2 is that the final fit is able to describe all components of  $T_{\mu\nu}$ in terms of a single value of  $q_*$ . For option A, the (relatively small) difference between the values of  $q_*$  for the separate fits of the components in section 3.2 is alleviated here by a smart choice of the "subleading"  $\propto \Sigma$  terms for  $\hat{T}_{\tau\tau}$  and  $\hat{T}_{\phi\phi}$  in (4.20), which arises in turn from the choice of the function  $B(\Gamma)$ . For option B, the (much larger) difference between the values of  $q_*$  was removed by an appropriate choice of  $\Gamma(\gamma)$  as we already pointed out above.

Equation of motion for  $\gamma$ . The above fitted expressions relied on the assumption that for the domain wall solution of [20],  $\gamma$  is given by a tanh function:

$$\gamma(x) = \frac{1}{2} + \frac{1}{2} \tanh\left(\frac{q_* x}{2}\right) \tag{4.26}$$

Of course, this should not be an assumption but should follow from some specific equations of motion. It's well known that (4.26) is a solution of the virial theorem

$$\gamma' = \sqrt{2V(\gamma)}$$
 with  $V(\gamma) = \frac{q_*^2}{2}\gamma^2(1-\gamma)^2$ . (4.27)

Indeed (4.27) is a solution of the equations of motion for any scalar action of the form

$$\mathcal{L}_{\gamma}^{\text{preliminary}} = -a(\gamma) \left( \frac{1}{2} (\partial \gamma)^2 + V(\gamma) \right)$$
 (4.28)

with arbitrary prefactor function  $a(\gamma)$ . The Lagrangian (4.28) cannot be the whole story, however, as the energy-momentum tensor derived from (4.28) does not include the  $u^{\mu}u^{\nu}$ terms appearing in (4.11). We thus need to couple the scalar action to hydrodynamics in the deconfined phase. We will perform this construction in the following section and provide an action which will generate equations of motion for  $\gamma$  and reproduce the structure of the energy-momentum tensor<sup>7</sup> (4.11). Together with the standard energy-momentum conservation equations for the hydrodynamic variables we will thus have a fully specified system.

<sup>&</sup>lt;sup>7</sup>Under the assumption of  $\gamma(x)$  satisfying the virial theorem.

#### 5 An action density and the final formulation

In this section we will propose a general from of an action for  $\gamma(x)$ , whose corresponding energy-momentum tensor will be capable of reproducing the structure (4.9).

Before we do that, we will review an action formulation for perfect fluid hydrodynamics as it will provide the natural ingredients for introducing the dependence on hydrodynamics into the action for  $\gamma(x)$ .

#### 5.1 An action for perfect fluid hydrodynamics

An action for perfect fluid hydrodynamics was first introduced in [51], we will, however, use a later formulation by [52] as it matches with the on-shell action in holography.

Following this formulation, as the elementary hydrodynamic degree of freedom one takes the vector  $\beta^{\mu}$  related to the temperature through

$$T = \frac{1}{\sqrt{-g_{\mu\nu}\beta^{\mu}\beta^{\nu}}} \ . \tag{5.1}$$

We get then the following variation, expressed in terms of the conventional flow velocity  $u^{\mu} = T\beta^{\mu}$ :

$$\delta T = -\frac{1}{2} T u_{\mu} u_{\nu} \delta g^{\mu\nu} . \tag{5.2}$$

The hydrodynamic Lagrangian is then simply given by the pressure expressed as a function of the temperature

$$\mathcal{L}_{\text{hydro}} = p(T)$$
 (5.3)

Using the formula

$$T_{\mu\nu} = \frac{-2}{\sqrt{-g}} \frac{\delta(\sqrt{-g}\mathcal{L})}{\delta g^{\mu\nu}} = -2 \frac{\delta \mathcal{L}}{\delta g^{\mu\nu}} + g_{\mu\nu}\mathcal{L}$$
 (5.4)

one recovers the hydrodynamic perfect fluid energy-momentum tensor

$$T_{\mu\nu}^{\text{hydro}} = \underbrace{T\partial_T p}_{\varepsilon+p} u_{\mu} u_{\nu} + p g_{\mu\nu} . \tag{5.5}$$

The conservation law of the above energy-momentum tensor, i.e. the hydrodynamic equations of motion, can be derived from the Lagrangian using constrained variations in  $\beta^{\mu}$  as described in section 7 of ref. [52]. As this is rather complicated, we will always use directly the energy-momentum conservation laws as equations of motion for the hydrodynamic degrees of freedom.

The linear combination of the hydrodynamic and confining energy-momentum tensors follows from the Lagrangian

$$\mathcal{L} = (1 - \Gamma)p(T) + \Gamma . \tag{5.6}$$

#### 5.2 The action for the scalar field $\gamma$

We will primarily consider a formulation just in terms of the *physical* 3D coordinates, ignoring the auxiliary angular  $\phi$  coordinate as we assume no dependence on  $\phi$ . For this

reason, we will not recover now the  $n^{\mu}n^{\nu}$  terms in the energy-momentum tensor. We will show in appendix C, how to formally reproduce also those terms.

Consider a rather general scalar field action coupled to the hydrodynamic degrees of freedom through a dependence on  ${\cal T}$ 

$$\mathcal{L}_{\gamma} = -\frac{1}{2}a(\gamma, T)g^{\mu\nu}\partial_{\mu}\gamma\partial_{\nu}\gamma - b(\gamma, T) . \qquad (5.7)$$

We ignore possible terms with  $\beta^{\mu}\partial_{\mu}\gamma$  as we do not have any information about them from known gravity solutions. The resulting energy momentum tensor is

$$T^{\Sigma}_{\mu\nu} = a\partial_{\mu}\gamma\partial_{\nu}\gamma - \left(\frac{1}{2}a(\partial\gamma)^{2} + b\right)g_{\mu\nu} - T\left((\partial\gamma)^{2}\partial_{T}a + \partial_{T}b\right)u_{\mu}u_{\nu} . \tag{5.8}$$

Let us now specialize to the domain wall solution from section 3.2 and impose the constraint

$$T_{xx}^{\Sigma} = 0. (5.9)$$

Recall from the discussion in section 4.2 that for the planar domain wall solution at  $T = T_c$  we would like to have

$$\gamma' = \sqrt{2V(\gamma)} \ . \tag{5.10}$$

Plugging this into (5.9) gives

$$a\gamma'^2 - \frac{1}{2}a\gamma'^2 - b = 0 (5.11)$$

which yields (at  $T = T_c$ )

$$b = aV (5.12)$$

So the scalar action becomes (again the argument holds strictly speaking just at  $T = T_c$ )

$$\mathcal{L}_{\gamma} = -a(\gamma, T) \left( \frac{1}{2} (\partial \gamma)^2 + V(\gamma, T) \right) . \tag{5.13}$$

Recall that for any  $a(\gamma, T)$  the virial theorem solution (5.10) solves the equations of motion coming from this action.

Let us now, for simplicity, assume an overall power-law dependence on the temperature,  $^{8}$  and take  $T_{c}=1$ , i.e.

$$a(\gamma, T) = T^{\alpha} a(\gamma), \qquad V(\gamma, T) = T^{\beta} V(\gamma).$$
 (5.14)

Evaluating (5.8) using the virial theorem (5.10) at T=1 we get

$$T_{\mu\nu}^{\Sigma} = a \left[ \underbrace{\partial_{\mu} \gamma \partial_{\nu} \gamma}_{(\partial \gamma)^2 v_{\mu} v_{\nu}} - (\partial \gamma)^2 \eta_{\mu\nu} - (\partial \gamma)^2 \left( \frac{3}{2} \alpha + \frac{1}{2} \beta \right) u_{\mu} u_{\nu} \right]. \tag{5.15}$$

We see that we recover the structure of (4.9), when specializing to a solution satisfying the virial theorem (5.10). Otherwise we have the general form (5.8) with (5.12) and (5.14). For

 $<sup>^8{</sup>m Of}$  course this should be treated just as an approximation close to  $T_c$  and not as a fundamental assumption.

a formal extension of the above treatment which includes the  $n^{\mu}n^{\nu}$  terms in the energymomentum tensor see appendix C. The coefficient B appearing in (4.9) is expressed as

$$B = \frac{3}{2}\alpha + \frac{1}{2}\beta \ . \tag{5.16}$$

From the planar domain wall solution that we have at our disposal, we cannot fix the individual coefficients  $\alpha$  and  $\beta$  apart from the above linear combination. We leave their determination for future study. We will however present an argument in section 7 which suggests that the possible  $\gamma$  dependence of B arises solely through the coefficient  $\alpha$ . The coefficient  $\beta$  essentially characterises how the width of the domain wall changes as we move away from  $T = T_c$ . The surface tension density is given by

$$\Sigma = a(\gamma) \left( \frac{1}{2} (\partial \gamma)^2 + V(\gamma) \right) \longrightarrow a(\gamma) (\partial \gamma)^2$$
 (5.17)

where the latter form follows when using the virial theorem.

#### The final formulation

Let us summarize here our final form of the action

$$\mathcal{L}_{final} = (1 - \Gamma(\gamma))p(T) + \Gamma(\gamma) - a(\gamma, T) \left(\frac{1}{2}(\partial \gamma)^2 + V(\gamma, T)\right)$$
 (5.18)

with  $a(\gamma,T)=T^{\alpha}a(\gamma)$ , and  $V(\gamma,T)=T^{\beta}V(\gamma)$  understood as approximate expressions for temperatures close to  $T_c = 1$ . From the action (5.18), we derive equations of motion for  $\gamma$  as well as the energy-momentum tensor, whose conservation laws yield the remaining equations of motion for the hydrodynamic degrees of freedom.<sup>9</sup>

In order to fully specify the above action, we need to pick the prefactor  $a(\gamma)$  and the potential  $V(\gamma)$ . Furthermore, we need to express  $\Gamma(\gamma)$  in terms of the elementary scalar field  $\gamma$ . The fits of the energy-momentum tensor presented in section 4.2 yield the two natural options

$$\Gamma(\gamma) = \gamma , \qquad a(\gamma) = c \frac{1}{\gamma(1 - \gamma)} , \qquad \text{(Option A)} ; \qquad (5.19)$$

$$\Gamma(\gamma) = \gamma^2 (3 - 2\gamma) , \qquad a(\gamma) = c , \qquad \text{(Option B)} , \qquad (5.20)$$

$$\Gamma(\gamma) = \gamma^2 (3 - 2\gamma), \qquad a(\gamma) = c,$$
 (Option B),

with the potential

$$V(\gamma) = \frac{q_*^2}{2} \gamma^2 (1 - \gamma)^2 \ . \tag{5.21}$$

The  $\alpha$  and  $\beta$  coefficients characterize how the parameters of the scalar action behave as we move away from  $T = T_c$ . Since we have numerical data purely at  $T = T_c$ , we can currently fix only their linear combination (5.16) which is given by the function  $B(\Gamma)$ . From a numerical fit for the d=3 Witten model we have

$$B(\Gamma) = 1 + \Gamma \ . \tag{5.22}$$

<sup>&</sup>lt;sup>9</sup>As mentioned in section 5.1, we do not derive the equations of motion for the hydrodynamic degrees of freedom directly from the action as it would involve a constrained variational principle as described in section 7 from ref. [52].

For other models we expect that the expression for  $B(\Gamma)$  will get modified (see appendix A and B for explicit examples). On the other hand, even for those different models, the expressions (5.19)–(5.21) can remain unchanged.

Finally let us note that even though the potential appearing directly in the scalar action (5.21) remains symmetric under the interchange  $\gamma \leftrightarrow 1 - \gamma$  even as we move away from  $T = T_c$ , the overall potential for  $\gamma$  automatically breaks this symmetry (as it should!) due to the first two terms in (5.18) describing the individual phases of the theory. We will return to this point later in section 7.2 and in section 8 from a more general perspective.

# 6 Some generic physical applications

We will now illustrate the general structure of the proposed energy-momentum tensor (4.11) with a couple of applications. Here we focus on considerations which are very generic and depend just on the form of the energy-momentum tensor and not on the details of the formulation proposed in section 5.3.

Firstly, we link the parametrization of the energy-momentum tensor with the surface tension of the domain wall. Then we compare equations for an equilibrium circular droplet with standard thermodynamic considerations. Finally, we reproduce the formula for thermodynamic nucleation probability from [21] using Euclidean solutions as suggested by Linde [14, 15].

In this section it is convenient to use the notation

$$P(x) \equiv \Gamma(x) + (1 - \Gamma(x))p_{\text{hvdro}}(T) \tag{6.1}$$

for the coefficient of  $\eta_{\mu\nu}$  in  $T_{\mu\nu}^{\rm mix}(x)$ :

$$T_{\mu\nu}^{\text{mix}}(x) = (\Gamma(x) + (1 - \Gamma(x))p_{\text{hydro}}(T)) \eta_{\mu\nu} + 4(1 - \Gamma(x))p_{\text{hydro}}(T)u_{\mu}u_{\nu} - 4\Gamma(x)n_{\mu}n_{\nu}$$
  
=  $P(x)\eta_{\mu\nu} + 4(P(x) - \Gamma(x))u_{\mu}u_{\nu} - 4\Gamma(x)n_{\mu}n_{\nu}$ . (6.2)

P(x) can be interpreted as an overall pressure valid in both phases.

Since in the d=3 Witten model the physical d=3 theory is dimensionally reduced on the  $\phi$  circle from the auxiliary boundary d=4 theory, one has to take care for which theory the particular energy-momentum tensor is defined. Up to this point, we always considered the energy momentum tensor for the full auxiliary d=4 theory, which would be the expression read off directly from the holographic dual geometry. In this section we will focus on applications dealing with the physical dimensionally reduced theory, hence we should dimensionally reduce the energy-momentum tensor as well.

In order to avoid cumbersome notation, here we will use units such that the range of the  $\phi$  circle coordinate is equal to 1. Then the components of the physical energy momentum tensor will be

$$T^{3d}_{\mu\nu}(x) = \int T^{4d}_{\mu\nu}(x) d\phi = \left(\int d\phi\right) \cdot T^{4d}_{\mu\nu}(x)$$
 (6.3)

so  $T_{\mu\nu}^{3d}$  is just obtained from  $T_{\mu\nu}^{4d}$  by dropping the  $n_{\mu}n_{\nu}$  term. Hence we do not need to explicitly add the <sup>3d</sup> or <sup>4d</sup> superscripts.

#### 6.1 The domain wall surface tension

The surface tension extracted from the planar domain wall solution is given by the following integral

 $\Sigma = \int_{-\infty}^{\infty} (T_{xx} - T_{yy}) dx \tag{6.4}$ 

where y is the direction along the domain wall, while x is the perpendicular direction. Let us comment on the units. The elements of the energy momentum tensor for the auxiliary boundary theory have dimension  $energy^4$ . We integrate over  $\phi$  as in (6.3) and then over x so  $\Sigma$  has dimension  $energy^2$  which is the dimension of the surface tension in a 3-dimensional theory. Plugging in (4.11) we get

$$\Sigma = \int_{-\infty}^{\infty} \Sigma(x) \ dx \tag{6.5}$$

which motivates the notation for  $\Sigma(x)$ . Of course, following our assumptions on the support of  $T^{\Sigma}_{\mu\nu}(x)$  this integral gets contributions essentially just from the region of the domain wall. This indeed holds in the concrete models proposed in section 5.3.

Let us make a further comment here. We saw that the  $T^{\Sigma}_{\mu\nu}$  could arise as the energy-momentum tensor coming from an effective scalar field theory through

$$T_{\mu\nu} = \frac{-2}{\sqrt{-g}} \frac{\delta(\sqrt{-g}\mathcal{L})}{\delta g^{\mu\nu}} = -2 \frac{\delta\mathcal{L}}{\delta g^{\mu\nu}} + g_{\mu\nu}\mathcal{L} . \tag{6.6}$$

Hence the coefficient of  $\eta_{\mu\nu}$  in  $T^{\Sigma}_{\mu\nu}$  (recall (4.9)) has the interpretation of the on-shell action density evaluated on the domain wall solution. As for static solutions the Euclidean action is minus the Minkowski one, the surface tension would be identified with the value of the Euclidean scalar field action evaluated on the domain wall solution. This is indeed a very natural behaviour.

#### 6.2 A circular droplet

Let us first recall the standard thermodynamic analysis of a droplet of one phase in another phase [21] adapted to the current dimensionality (d = 2 + 1). Suppose that we have a droplet of radius R of the phase with pressure  $P_{\text{droplet}}$ . The spatial volume (here area) of the droplet is  $V_{\text{droplet}} = \pi R^2$ , and its circumference is  $A = 2\pi R$ . The surface tension of the interface is  $\Sigma$ . The environment has volume V and pressure P. The total thermodynamic potential of the system is given by

$$\Omega = -P_{\text{droplet}}V_{\text{droplet}} - PV + \Sigma A . \tag{6.7}$$

We should extremize the above formula w.r.t. R, keeping in mind that  $dV/dR = -dV_{\text{droplet}}/dR$  as  $V + V_{\text{droplet}} = V_{\text{total}} = \text{const.}$  We get

$$\frac{\partial\Omega}{\partial R} = -(P_{\text{droplet}} - P)2\pi R + 2\pi \Sigma = 0.$$
 (6.8)

Hence we obtain the equation for the equilibrium size of the droplet

$$P_{\text{droplet}} - P = \frac{\Sigma}{R} \ . \tag{6.9}$$

We will now proceed to show how the above equation arises from (4.11) in the thin wall approximation.

We will use here the polar coordinate system as in the present case the spherical domain wall is really circular since we have just two spatial coordinates for the physical theory.

$$ds^{2} = -dt^{2} + dr^{2} + r^{2}d\theta^{2} + d\phi^{2} . {(6.10)}$$

Recall that  $\phi$  is the auxiliary coordinate of the Witten's circle and we assume that nothing depends on it. The physical coordinates of the theory are t, r and  $\theta$ . The nontrivial conservation law takes the form

$$\partial_r T^{rr} - r T^{\theta\theta} + \frac{1}{r} T^{rr} = 0 . agen{6.11}$$

The vector fields are  $u^{\mu} = (1, 0, 0, 0)$  and  $v^{\mu} = (0, 1, 0, 0)$  and the relevant components of the energy-momentum tensor (4.11) are

$$T^{\theta\theta} = \frac{P - \Sigma}{r^2} , \qquad T^{rr} = P - \Sigma + \Sigma = P . \qquad (6.12)$$

We thus get

$$\partial_r P = -\frac{1}{r} \Sigma \ . \tag{6.13}$$

In the thin-wall approximation we assume that the size of the droplet is much larger than the width of the domain wall. Since  $\Sigma$  is nonzero only in the vicinity of the domain wall, we may replace in this approximation 1/r by 1/R. Then integrating both sides of equation (6.13) we obtain

$$\underbrace{P(r = +\infty) - P(r = 0)}_{P - P_{\text{droplet}}} = -\frac{\Sigma}{R}$$
(6.14)

which reproduces (6.9).

Of course, in order to compute the value of  $\Sigma$  and obtain the full profile P(r) and not only the asymptotic values, we need to specify the expression of  $\Sigma$  in terms of a scalar field  $\gamma$  and solve the equations of motion for  $\gamma$  following from (5.18). However for reproducing the thermodynamic equilibrium condition (6.9), these specific details are not necessary.

#### 6.3 Thermodynamic nucleation probability and Euclidean solutions

The nucleation probability of a bubble of one phase in an environment of the other phase can be computed in two ways. On the one hand, one can use standard thermodynamic arguments of [21] which make use of the value of the surface tension. On the other hand, one can use the field theoretical perspective of Linde [14, 15], which is a finite temperature generalization of the considerations of Coleman [53, 54]. In this approach one constructs a solution of the Euclidean equations of motion for a configuration of a static bubble of one phase embedded in the other phase with standard Euclidean time periodicity.

Finding the relevant Euclidean solution within holography is a formidable task which would require using nontrivial numerical relativity methods, especially in the context of

confining and deconfined phases described within the Witten's model [17] (or use metric Ansätze like in [13]). However, since our boundary formulation in terms of the energy-momentum tensor is in essence a shortcut to the dual holographic background, we can just solve instead equations on the boundary. Moreover, it turns out that to get the nucleation probability in the thin wall approximation, we do not need to find any explicit solutions at all.

Let us first recall the thermodynamic approach from [21]. The probability of a thermal fluctuation producing a nucleus of another phase is given by

probability 
$$\propto e^{-R_{\min}/T}$$
 (6.15)

where  $R_{\min}$  is the minimal work to form the nucleus (this follows from the probability of a fluctuation of a closed system  $\propto e^S$ ). This can be expressed in terms of the thermodynamic potentials of the uniform phase

$$\Omega_{\text{before}} = -P(V + V_{\text{droplet}}) \tag{6.16}$$

and of the system with the droplet

$$\Omega_{\text{after}} = -PV - P_{\text{droplet}} V_{\text{droplet}} + \Sigma A .$$
(6.17)

Then

$$R_{\min} = \Omega_{\text{after}} - \Omega_{\text{before}} = -(P_{\text{droplet}} - P)V_{\text{droplet}} + \Sigma A \tag{6.18}$$

so

probability 
$$\propto e^{-\frac{1}{T}\left(-(P_{\text{droplet}}-P)V_{\text{droplet}}+\Sigma A\right)}$$
. (6.19)

This formula should be applied to the equilibrium droplet with size R given by (6.9).

Let us now show how one can reproduce (6.19) from Linde's approach employing our framework. In principle we should find a gravitational solution for an equilibrium droplet of size R, compute its Euclidean on-shell gravitational action and subtract the action of the uniform phase without a droplet. All this quite nontrivial. As explained earlier, we can sidestep these difficulties using the proposed general structure of the energy-momentum tensor.

Clearly, the key ingredients to reproduce are the thermodynamic potentials (6.16) and (6.17), which, when divided by T should coincide with the values of the *Euclidean* on-shell action for the field configurations.

A-priori the knowledge of just the energy-momentum tensor does not allow to obtain the on-shell action. However if we assume, as is the case in our construction, that the energy-momentum tensor arises from some Lagrangian density through (6.6), we see that we can read off the Minkowski Lagrangian density from the coefficient of  $\eta_{\mu\nu}$ , change sign when passing to Euclidean signature and integrate it over Euclidean spacetime to obtain the on-shell thermal action.

 $<sup>^{10}</sup>$ In the same sense as from hydrodynamics one can get to the dual gravitational background through fluid/gravity duality.

Consequently, from (6.2) and (4.9) we get for the on-shell value of the Euclidean Lagrangian density

$$\mathcal{L}_E(x) = -P(x) + \Sigma(x) . \tag{6.20}$$

Hence the on-shell action for the uniform phase would be

$$S_{\text{before}}^{\text{on-shell}} = \int \mathcal{L}_E(x) d\tau d^2x d\phi = -\frac{1}{T} P(V + V_{\text{droplet}})$$
 (6.21)

where  $V + V_{\text{droplet}}$  is just the total volume and  $\Sigma = 0$  since we are in the uniform phase. The on-shell action for the circular droplet configuration in the thin wall approximation (i.e. at large R) would then be

$$S_{\text{after}}^{\text{on-shell}} = \int \mathcal{L}_E(x) d\tau d^2x d\phi = -\frac{1}{T} \left( PV + P_{\text{droplet}} V_{\text{droplet}} - \Sigma A \right)$$
 (6.22)

where the integral of  $\Sigma(x)$  would get contribution only from the domain wall and in the large R limit integrate to the surface tension times the bubble boundary area. We neglect corrections from the variation of P(x) within the domain wall region as they would be suppressed by 1/R. Taking the difference of (6.22) and (6.21), we reproduce the thermodynamic nucleation probability (6.19).

Again we see that in the thin wall approximation of large bubble size, we do not need to specify any microscopic details and just the overall knowledge of the surface tension suffices. We can view the above computations as a physical consistency check of the proposed general structure of the energy-momentum tensor (4.11) and the interpretation of the coefficient of  $\eta_{\mu\nu}$  as the on-shell action density.

# 7 Accelerating planar domain wall solution

As we move away from  $T = T_c$ , the pressures of the two phases on both sides of the domain wall will no longer balance, and the domain wall will start to move with a uniform acceleration. It is instructive to consider this case, as it gives a nontrivial application (and consistency check) of the proposed framework but also leads to some further constraints on  $\Gamma(\gamma)$  when  $a(\gamma) = 1$ . As it turns out, such accelerating solutions may be obtained simply by moving away from  $T = T_c$  in the hydrodynamic part of the action. Namely, the asymmetry imposed by the coupling of the  $\gamma$  field to the hydrodynamic action provides exactly the necessary asymmetry in the effective potential for  $\gamma$ .

#### 7.1 Effective actions and accelerating solutions

However, before considering the coupling to hydrodynamics, let us first recall how accelerating domain wall solutions arise from simple effective actions. We consider small  $T - T_c \propto \varepsilon$ . Assuming a standard kinetic term (as in option B above), i.e., setting  $a(\gamma, T) = 1$  in the scalar action (5.13), we search for a generalization of the potential (5.21). If we require that the locations of the two minima remain at  $\gamma = 0$  and  $\gamma = 1$ , the unique fourth order polynomial (up to  $\mathcal{O}(\varepsilon)$  corrections in the normalization and a trivial constant term) which works is

$$V_{\varepsilon}(\gamma) = \frac{q_*^2}{2} (\gamma - 1)^2 \left[ \gamma^2 - \frac{\varepsilon}{3q_*} (1 + 2\gamma) \right] . \tag{7.1}$$

This definition also determines the normalization of  $\varepsilon$ 

We may then search for accelerating solutions by adding  $\mathcal{O}(\varepsilon)$  correction terms to the static domain wall solution. Interestingly, a very simple solution exists, and the perturbed solution may be conveniently written as

$$\gamma(t,x) = \frac{1}{2} \left[ 1 + \tanh\left(q_* \left(\frac{x - x_0}{2} - \frac{\varepsilon t^2}{4}\right)\right) \right] . \tag{7.2}$$

This solution is however only valid for small  $\varepsilon t^2$ , otherwise the perturbation grows large. Knowing the solution near t=0 is however enough for the full time evolution because we can always use Lorent covariance to boost to a frame where the domain wall is almost at rest. That is, it is enough to write the result in an explicitly covariant form to capture the full time evolution at  $\mathcal{O}(\varepsilon)$ . A covariant way to write the result is

$$\gamma(t,x) = \frac{1}{2} \left[ 1 + \tanh\left(\frac{q_*}{2} \left( \sqrt{(x - x_0 - \varepsilon^{-1})^2 - t^2} - \varepsilon^{-1} \right) \right) \right]. \tag{7.3}$$

For this expression the convergence as  $\varepsilon \to 0$  is uniform over all x and t.

Above we pointed out that the static tanh solution for the domain wall is obtained for the scalar action of (5.13) for any choice of  $a(\gamma, T)$  if the potential is the standard choice of (5.21). Therefore one might expect that accelerating solution of (7.3) also generalizes to nontrivial choices of  $a(\gamma, T)$ . This turns out indeed to be the case. The potential however needs to be different from (7.1) if we want the solution to remain in simple form.

We consider here only the case  $a(\gamma,T)=c/\gamma/(1-\gamma)$ , corresponding to option A above. For this choice, one can indeed easily check that the potential of (7.1) does not work. Instead, the potential in this case must have zeroes at  $\gamma=0$  and  $\gamma=1$  that cancel the poles of a such that the product aV is regular. Therefore we write

$$V_{\varepsilon}(\gamma) = \frac{q_*^2}{2} \gamma (1 - \gamma)^2 \left( \gamma - \frac{2}{q_*} \varepsilon \right) . \tag{7.4}$$

Since the potential term appearing in the full equation of motion is

$$\propto \frac{1}{a(\gamma)} \frac{d}{d\gamma} \left[ a(\gamma)V(\gamma) \right] \propto \gamma (1 - \gamma)$$
 (7.5)

we expect that the asymptotic values of the domain wall solution are exactly  $\gamma = 0$  and  $\gamma = 1$  even after adding the perturbation. And indeed we may verify that (7.3) is a solution for this potential up to terms  $\mathcal{O}(\varepsilon)$ . In particular, we chose the normalization of the perturbation term in (7.4) such that it the acceleration matches with that given by constant a and potential (7.1).

#### 7.2 Coupling to hydrodynamics

We then consider the coupling between  $\gamma$  and the hydrodynamic degrees of freedom. As mentioned above, these couplings will in effect lead to asymmetric terms for the potential of  $\gamma$ , eliminating the need of introducing such terms explicitly.

We use the full hydrodynamic action, given in (5.18) above, with the definitions in (5.19)–(5.21). The hydrodynamic terms in the action can be rearranged as

$$(1 - \Gamma)p(T) + \Gamma = p(T) - (p(T) - 1)\Gamma = p(T) - \Delta p(T)\Gamma \tag{7.6}$$

where  $\Delta p(T) = p(T) - 1$  is the pressure difference between the deconfined and confined phases. The  $\Gamma$  term in the action may be interpreted as a change in the potential for  $\gamma$ :

$$a(\gamma)V(\gamma) \to a(\gamma)V(\gamma) + \Delta p(T)(\Gamma - 1) \equiv a(\gamma)V_{\text{eff}}(\gamma)$$
 (7.7)

From here on we need to consider the two options separately. For option A (i.e.,  $a(\gamma) = c/\gamma/(1-\gamma)$  and  $\Gamma(\gamma) = \gamma$ ) we find that

$$V_{\text{eff}}(\gamma) = \frac{q_*^2}{2} \gamma^2 (1 - \gamma)^2 - \frac{\Delta p(T)}{c} \gamma (1 - \gamma)^2 = \frac{q_*^2}{2} \gamma (1 - \gamma)^2 \left(\gamma - \frac{2\Delta p(T)}{cq_*^2}\right) . \tag{7.8}$$

This result, somewhat miraculously, has exactly the same form as (7.4). Notice that we did not assume that  $T - T_c$  is small so far. In the limit of small temperature difference  $T - T_c = \mathcal{O}(\varepsilon)$ , we find that

$$\Delta p(T) = s_c(T - T_c) + \mathcal{O}(\varepsilon^2), \qquad (7.9)$$

where  $s_c = s(T_c) = p'(T_c)$  is the entropy at the critical temperature. Comparing to (7.4), we identify

$$\varepsilon = \frac{s_c(T - T_c)}{cq_*} \ . \tag{7.10}$$

For option B, i.e., with  $a(\gamma) = c$  we find that

$$V_{\text{eff}}(\gamma) = \frac{q_*^2}{2} \gamma^2 (1 - \gamma)^2 - \frac{\Delta p(T)}{c} (1 - \Gamma(\gamma)) . \tag{7.11}$$

For this expression to agree with (7.1), we must have  $1 - \Gamma(\gamma) \propto (\gamma - 1)^2 (1 + 2\gamma)$ . This holds if we choose

$$\Gamma(\gamma) = \gamma^2 (3 - 2\gamma), \tag{7.12}$$

and this expression also satisfied the properties  $\Gamma(0) = 0$ ,  $\Gamma(1) = 1$ , and  $\Gamma(\gamma) + \Gamma(1-\gamma) = 1$  expected from symmetry. We have therefore derived the form introduced for option B in (4.18) above. Inserting it in (7.11) we obtain

$$V_{\text{eff}}(\gamma) = \frac{q_*^2}{2} (1 - \gamma)^2 \left( \gamma^2 - \frac{2\Delta p(T)}{cq_*^2} (1 + 2\gamma) \right) . \tag{7.13}$$

Comparing with (7.1) at small  $T - T_c$ , we identify

$$\varepsilon = \frac{6s_c(T - T_c)}{cq_*} \ . \tag{7.14}$$

The difference between this relation and (7.10) is not a surprise because the physical interpretation of the parameters c and  $q_*$  is also different between the two options.

Because we had to make a specific choice for  $\Gamma(\gamma)$  in equation (7.12) for the effective potential to have the desired form for option B, this option may seem less preferable than option A. We however remark that the same choice of  $\Gamma(\gamma)$  gave an extremely good fit of the numerical data for the static domain wall solution. Therefore there is in practice very

little freedom in choosing the function, and it is interesting that the same function works both for the accelerating solution and the numerical data.

In summary, we have shown that the coupling between  $\gamma$  and hydrodynamics automatically reproduces the accelerating solution (7.3) without the need of introducing an asymmetry in the potential  $V(\gamma)$  explicitly. This observation strongly supports our model. The accelerating solutions are however found with one potentially important limitation: above we assumed implicitly that the temperature T is independent of the coordinates x and t. While this is reasonable for the static solution, the backreaction of the accelerating solution to the hydrodynamics is expected to lead to a nontrivial profile to the temperature. That is, the simple accelerating solutions are only found when the backreaction to the hydrodynamics due to the wall motion is neglected.

The success of the model with the accelerating solution raises an important question which we already touched upon above: to which extent can we use the accelerating solutions to pin down the functions in the model, in particular the choices of  $\Gamma(\gamma)$ ? It is clear that the solution (7.3) is only (at least up to trivial modifications) obtained with the choices of  $\Gamma(\gamma)$  we did above, for both options A and B. However, the physical solution does not need to have exactly the form of (7.3). For example, the shape of the profile of the domain wall could receive nontrivial corrections in the accelerating case. In any case we should require that the solution for  $\gamma(x,t)$  continues to asymptote to zero and one in the deconfined and confined phases, respectively. While this is in principle a matter of (re)definition of  $\gamma$  and  $\Gamma(\gamma)$ , possible variations would need to be compensated by modifying the coupling between  $\gamma$  and the hydrodynamic degrees of freedom since the action for them far from the domain wall should be unchanged. This would lead to a complicated action which we do not want. Therefore the function  $\Gamma(\gamma)$  should match with the forms used above at least near  $\gamma = 0$ and  $\gamma = 1$ . For other values of  $\gamma$ , there is in principle no constraint, but apparently our choices are the only ones leading to potentials  $V_{\rm eff}$  that are low-order polynomials. In any case the choice for  $\Gamma(\gamma)$  must be quite close to those used here, otherwise the agreement with the numerical solutions found in figure 8 is spoiled.

Finally, let us comment on the implications for the temperature dependence of the potentials a and V as well as the resulting energy-momentum tensor (which we already discussed above in section 5.2). Notice that, as we have demonstrated, accelerating solutions do not require any explicit temperature dependence in these functions. However we wish to check if such a dependence can be added without damaging the nice picture found above.

Since the coupling to hydrodynamics automatically introduces the needed asymmetry in the effective potential of  $\gamma$  for  $\varepsilon \neq 0$ , it makes no sense to introduce an asymmetry in  $V(\gamma,T)$  explicitly (even though it would be possible to do this). Modifying the overall coefficient of the potential, in the same way as in (5.14), but with constant  $\beta$ , is however possible. To lowest order in  $\varepsilon$  this simply means renormalizing the value of the coupling in the potential, i.e.,  $q_* \to q_*(1 + c_q \varepsilon)$ , everywhere. Similarly, one can introduce temperature dependence of the overall coefficient of  $a(\gamma,T)$ . But actually this function is even less constrained by the accelerating solutions. This happens because, as we noticed in section 5.2, the static  $T = T_c \tanh$  profile satisfies the equations of motion from the action

for  $\gamma$  in (5.13) for any  $a(\gamma)$ . It follows that the  $\mathcal{O}(\varepsilon)$  domain wall solution only depends on the leading  $\mathcal{O}(\varepsilon^0)$  term of  $a(\gamma, T)$ . Therefore we can have

$$a(\gamma, T) = a(\gamma) + \varepsilon \hat{a}(\gamma) + \mathcal{O}\left(\varepsilon^2\right)$$
 (7.15)

with any  $\hat{a}(\gamma)$  without affecting the accelerating solution at  $\mathcal{O}(\varepsilon)$ . The coefficient  $\alpha$  in (5.14) is  $\alpha \propto \hat{a}(\gamma)/a(\gamma)$  in the limit  $T \to T_c$ . Putting these observations together, the  $\gamma$  dependence required for the formula (5.16) to agree with our choice  $B = 1 + \Gamma$  can arise from  $a(\gamma, T)$  through the coefficient  $\alpha$ .

# 8 Comments on generality

The description proposed in the present paper was developed based on a conformal<sup>11</sup> version of the holographic Witten's model [17] for which there exists the numerical solution of the domain wall [20] interporating between coexisting confining and deconfined phases. We believe, however, that the resulting framework should have a much more general range of applicability.

Indeed quite different (nonconformal) holographic models, which have a  $1^{st}$  order phase transition between two *deconfined* phases exhibit a domain wall profile which is very well fitted by a tanh function [7, 9]. Since an underlying tanh shape of the domain wall arises analytically in our framework, this suggests that the framework could also be applied in those settings. In appendix B we checked that indeed our description works quite well also for domain walls in the nonconformal bottom-up holographic model of [5] with two deconfined phases for which we had numerical data.

The reasoning leading to our proposal was in fact very general and the insight from holography was essentially used technically only to constrain the form of  $\Gamma(\gamma)$ ,  $a(\gamma)$  and  $B(\gamma)$  and eliminate possible nondiagonal terms<sup>12</sup>  $u^{\mu}v^{\nu}$ . The key qualitative input from holography was really the reassurance that such a simple model could indeed work so well even for a strongly interacting field theory with the very nontrivial gravitational configuration dual to the domain wall [20].

For a general system with a  $1^{st}$  order phase transition we thus expect that one could model the energy-momentum tensor as

$$T_{\mu\nu} = (1 - \Gamma) T_{\mu\nu}^{\text{phase A}} + \Gamma T_{\mu\nu}^{\text{phase B}} + T_{\mu\nu}^{\Sigma}$$
 (8.1)

with  $\Gamma$  being a function of  $\gamma$  and the surface tension energy momentum tensor  $T^{\Sigma}_{\mu\nu}$  following from an action of the form

$$\mathcal{L}_{\gamma} = -a(\gamma, T) \left( \frac{1}{2} (\partial \gamma)^2 + V(\gamma, T) \right)$$
(8.2)

with

$$V(\gamma, T) \propto \gamma^2 (1 - \gamma)^2$$
 (8.3)

Note that conformality refers only to the bulk and the physical boundary theory dimensionally reduced on the  $\phi$  circle is of course nonconformal.

<sup>&</sup>lt;sup>12</sup>Such terms could nevertheless still reappear if they would be multiplied by  $(u \cdot v)$ .

With the current available data we cannot differentiate between options A and B or rule out an alternative, but the two choices  $a(\gamma,T)=c(T)/\gamma(1-\gamma)$  and  $a(\gamma,T)=\tilde{c}(T)$  seem most natural.

Let us note finally an interesting interpretation of our framework (applicable only in case of option B i.e. with the canonical scalar action with  $a(\gamma) = 1$ ). Consider the overall action density for option B

$$\mathcal{L} = (1 - \Gamma(\gamma))p(T) + \Gamma(\gamma) - \frac{1}{2}c(T)(\partial\gamma)^2 - d(T)\gamma^2(1 - \gamma^2)$$
(8.4)

where we explicitly separated out temperature dependence and emphasised that  $\Gamma$  is a known functional<sup>13</sup> of  $\gamma$ , which is the elementary field here. The Euclidean Lagrangian aims to model the holographic on-shell action<sup>14</sup> which evaluates holographically the free energy. So restricting (8.4) to constant configurations gives an expression for the free energy as a quartic polynomial in  $\gamma$ :

$$F = -(1 - \Gamma(\gamma))p(T) - \Gamma(\gamma) + d(T)\gamma^{2}(1 - \gamma^{2})$$

$$(8.5)$$

which essentially provides a Landau type description of a  $1^{st}$  order phase transition, with the two minima changing places as one goes across the transition. Our formulation (8.4) can be then understood as promoting the Landau order parameter  $\gamma$  to a dynamical effective field and coupling it in a natural way with hydrodynamic degrees of freedom. The above interpretation fails for option A due to the  $1/\gamma(1-\gamma)$  prefactor of the scalar field action and thus also of the potential. So from this point of view option B might be preferable.

# 9 Summary and outlook

In the present paper we investigated theories with a  $1^{st}$  order phase transitions with special emphasis on the description of domain walls separating regions of coexisting phases. A striking feature of the dual holographic descriptions of domain walls in various theories is that the domain wall profiles appear to be much simpler than one would expect from the rather complicated gravitational backgrounds. This is especially apparent for the case of Witten theory, where the plasma-ball domain wall gravitational solution [20] is particularly nontrivial.

The observation that the boundary physics seems much simpler than the full gravitational description, suggests that one could model it directly on the level of the boundary field theory energy-momentum tensor. To this end, we introduced an additional degree of freedom  $\gamma$ , akin to an order parameter distinguishing the two phases and proposed a unified description incorporating both the energy-momentum tensors of the two coexisting phases as well as a piece localized essentially in the vicinity of the domain wall and describing its surface tension profile.

<sup>&</sup>lt;sup>13</sup>For the system investigated here it is given by  $\Gamma(\gamma) = \gamma^2 (3 - 2\gamma)$ .

<sup>&</sup>lt;sup>14</sup>This was the reason that we used the hydrodynamic action formulation of [52] instead of [51].

In the case of the Witten model [17] with a confining and deconfined phases, we arrived at a description in terms of a simple action for  $\gamma$  with a quartic potential coupled with hydrodynamics of the plasma in the deconfined phase. For the static planar domain wall, one can obtain simple analytical formulas for all components of the energy-momentum tensor.

We believe that the overall framework should be applicable in a very general context of theories with a  $1^{st}$  order phase transition. We checked that indeed one can get a very good description also for the Witten model in another dimensionality as well as for a nonconformal bottom-up holographic model from [5] with two coexisting plasma phases, but we expect that similar modelling should hold even beyond holography.

The obtained results lead to a wide variety of open questions which should spark various directions of further research.

- The holographic data at our disposal does not allow us to distinguish between two variants of the proposed action (option A and option B), as well as to control the variations of the parameters as we move away from  $T = T_c$ . Even at  $T = T_c$ , we find that the  $B(\Gamma)$  coefficient in the domain wall energy-momentum tensor depends on the specific theory. Indeed, one can view these parameters as analogs of transport coefficients in hydrodynamics, hence an understanding of their variability in different holographic models would be very interesting.
- Going further along these lines, it would be interesting to investigate natural ways of systematically improving the model by including e.g. higher derivative terms in an analogous way to going to higher order hydrodynamics or refining the scalar potential.
- An obvious question that raises from the model proposed in this paper is how to interpret the field  $\gamma$  as an order parameter. In particular,  $1-\gamma$  as an order parameter for deconfinement. One may try to relate it to the standard order parameters for deconfinement, like the VEV of a Polyakov loop which in principle one can try to compute holographically as a function of x in the domain wall background, and see if its profile is similar to that found for  $\gamma$ .<sup>15</sup>
- It would be very important to have a wide range of holographic gravitational solutions which would allow one to clarify these issues. Time dependent solutions of the holographic Einstein equations would be especially instructive, as these could fix possible  $(u \cdot v) \left( u^{\mu} v^{\nu} + v^{\mu} u^{\nu} \frac{1}{2} (u \cdot v) \eta^{\mu \nu} \right)$  terms in  $T_{\mu\nu}$  and corresponding coupling terms in the scalar action for  $\gamma$ . As a first step, it should be instructive to construct the gravity solutions for a spherical domain wall [36], and for a flat accelerating one.
- Going further along these lines, one could investigate the incorporation of dissipation within the proposed framework. Indeed understanding the impact of dissipation in the above context should be quite important for the relevant physics.
- The whole processes of transition from one phase to another in both directions are quite complex and are believed to include bubble nucleation and bubble coalescing.

<sup>&</sup>lt;sup>15</sup>We thank Ofer Aharony for raising this point.

It will be interesting to analyze these sub-processes using the action and the energy momentum tensor proposed in this paper.

- The model proposed in this paper has been inspired by holography. Thus it is related a priori to gauge dynamical systems with large  $N_c$  and large  $\lambda_{\rm t\,Hooft}$ . A very interesting question is to what extend can one extrapolate from the results derived here also to real world of  $N_c = 3$  and  $\lambda_{\rm t\,Hooft} \sim 1$ . One obvious question is the nature of the transition.
- Another obvious question that follows the model proposed in this paper is can one
  determine using it physical properties that can be experimentally observed. Using the
  hydrodynamical description of the quark gluon fluid such properties were computed
  and compared to experimental data. The question is what additional information
  can be extracted about them using our domain-wall model.
- The action of our model resemble the one in Coleman's seminal papers on bounce [53, 54]. It would be interesting to use the results of the latter papers to determine the decay width of the "false vacuum" for systems at temperature different from the critical one.
- While the covariant description presented in this article was strongly motivated by numerical data obtained through holography, we did not derive any of the ingredients of the model by using the gravity dual. Naturally, such a derivation would be desirable. An attempt in this direction was presented in section 3.3, where we studied a simple model for the domain wall geometry in the Witten's model. This model however failed to explain some features of the numerically obtained exact geometry, and we found no way to improve it systematically towards an exact solution of the Einstein equations. It would be extremely interesting if the connection between the gravity solutions and the boundary description could be made more precise either by improving this attempt or by some other means.
- Since finding domain wall solutions to Einstein equations is typically rather difficult, it may be useful to explore ways to simplify the problem on the gravity side. Such a simplifying approach might be to use the limit of large number of dimensions. This is actually well motivated for domain walls or phase transitions in QCD: as was pointed out in [55, 56], a class of geometries which produces IR features similar to QCD [29] is well approximated by a dimensional reduction of a high dimensional AdS space.
- In this paper we have considered the holographic description of glue dynamics. An obvious question is how would the incorporation of fundamental quarks affect the system. It is well known that such a system is characterized in addition to the confining/deconfining transition also the one associated with chiral symmetry breaking. The holographic dual of both phase transitions, which incorporates flavor branes was analyzed in [18]. It will be very interesting to construct a model analogous to the one presented here that includes also quark degrees of freedom and correspondingly mesons and baryons.

• As was mentioned above the model proposed in this paper has been inspired by holographic duality with a gravitational background. However, the holographic duality is in fact an even deeper type of duality than the form in which it is commonly used. It relates the gauge dynamics of a boundary field theory and *string theory* that resides in the bulk. In [57, 58] it was argued that this type of duality does a much better job in describing the spectra and decay processes of hadrons. Thus, the confining phase should be described by string degrees of freedom. It would be interesting to uplift the model of this paper into a stringy model which may yield a better description of the hadronization process.

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#### A The domain wall in a six-dimensional setup

In this appendix we discuss the results of section 3.2 for a generalization of the domain wall geometry which has one additional spatial dimension, and was also discussed in [20]. One can consider even more general solutions of the Einstein equations with a cosmological constant for d + 2-dimensional gravity, with d equalling the number of spatial dimensions (including the compactified dimension), but we restrict here to d = 3 (the main text) and d = 4 (this appendix). Notice that the six-dimensional geometry therefore differs from the Witten's model [17] of compact D4 background [46] as there is no dilaton (or the dilaton is constant) and the background is conformal. That is, the geometry is closely related to AdS<sub>6</sub>: in particular, in the deconfining and confining limits it is obtained from (3.3) and (3.1), respectively, simply by adding one spatial dimension (i.e., now  $i, j = 1 \dots 3$  in these formulas) and modifying the blackening factor to

$$f(u) = 1 - \left(\frac{4\pi RT_c}{5u}\right)^5, \tag{A.1}$$

where R is the radius of the AdS<sub>6</sub> space.

We may extract the components of  $T_{\mu\nu}$  from the domain wall solution and fit them by using the Ansätze in (3.12) and in (3.16) in the same way as for the five-dimensional

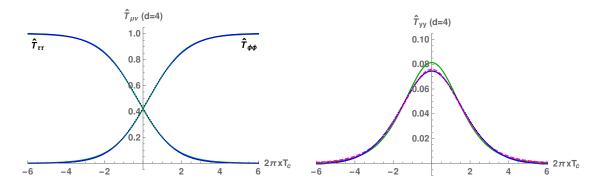


Figure 9. Fitting of the (normalized) components of the energy-momentum tensor for the sixdimensional geometry. Left: tanh fit to  $\hat{T}_{\tau\tau}$  and to  $\hat{T}_{\phi\phi}$ . Blue dots show the energy-momentum tensor extracted from the numerically constructed geometry of [20], and the green curves are given by the fit in equation (3.12). Right: fits to  $\hat{T}_{yy}$ . The green curve is the prediction from the fit of figure 5, given in equation (3.15). The dashed magenta and dot-dashed red fits were obtained by using the former and latter formulas of equation (3.16), respectively.

geometry in section 3.2. The results are shown in figure 9, where the left (right) plot is the counterpart of figure 5 (figure 6). The notation is as in section 3.2. The fit parameters for the tanh fit are given by

$$\frac{q_*}{2\pi T_c} \approx 1.054, \qquad 2\pi T_c x_0 \approx 0.311, \qquad (d=4)$$

for the tanh fit and by

$$\frac{q_*^{(2)}}{2\pi T_c} \approx 0.981, \qquad c^{(2)} \approx 0.0758, 
\frac{q_*^{(4)}}{2\pi T_c} \approx 0.652, \qquad c^{(4)} \approx 0.0747, \qquad (d=4),$$
(A.3)

for the cosh fits.

The main observation from these fits is that dependence on d appears to be mild. The ratios between the various values of  $q_*$  are essentially unchanged. The value of  $x_0$  is a bit higher than for d = 3, but  $\hat{T}_{yy}$  is in turn smaller. This happens because (3.14) depends on d and reads, in general,

$$\hat{T}_{yy}(x) = \frac{1}{d-2} \left( 1 - \hat{T}_{\tau\tau}(x) - \hat{T}_{\phi\phi}(x) \right) . \tag{A.4}$$

We have also carried out the fit to the data by using our final model for the energy momentum tensor in (4.11).<sup>16</sup> As it turns out, for d=4 a good fit to data is obtained by using

$$B(\Gamma) = 2 \tag{A.5}$$

instead of  $B(\Gamma) = 1 + \Gamma$ , which was used for d = 3 in section 4.2. The fit results for d = 4 are shown in figure 10 and is almost identical to the result for d = 3 in figure 8. That is, the fit is again excellent. The deviation of the data from the fit (which is poorly visible in the plots) is of the same magnitude in all fits, but a bit larger for d = 4 than for d = 3.

<sup>&</sup>lt;sup>16</sup>For d=4 the coefficient of the  $n_{\mu}n_{\nu}$  term is  $\Sigma(4-B)$ .

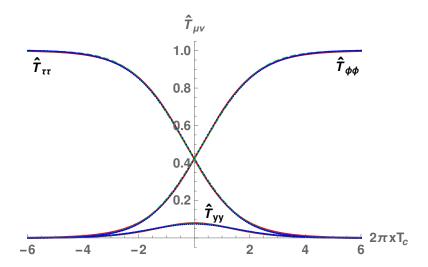


Figure 10. Final fits of the model to the numerical solution for the domain wall for d = 4. The blue dots, solid red curve, and dashed green curve show the numerical data, fit using the option A, and fit using the option B, respectively.

# B The domain wall for a nonconformal model with two deconfined phases

In this appendix we check that our framework is applicable in the context of a quite different holographic model studied in [5] — a bottom-up gravity+scalar system in a 4D bulk with the scalar field potential

$$V(\Phi) = -6\cosh\left(\frac{\Phi}{\sqrt{3}}\right) - 0.2\,\Phi^4\tag{B.1}$$

The scale breaking conformality is set by a nonzero source for the operator dual to the scalar field  $\Phi$ . This model exhibits a  $1^{st}$  order phase transition with the two coexisting phases being deconfined, both described holographically by black holes. The numerical simulations in [5] followed the evolution from the spinodal instability to the formation of domains of the two coexisting phases separated by domain walls. Here we analyze one of the domain walls appearing in the final state configuration.

We first fit the  $q_*$  and c parameters for options A and B (recall (4.21)–(4.23)) from the surface tension density  $\Sigma(x) = T_{xx} - T_{yy}$ . The outcome is shown in figure 11 (left). Consequently we have

$$\gamma(x) = \frac{1}{2} + \frac{1}{2} \tanh \frac{q_*(x - x_{\text{center}})}{2}$$
(B.2)

where  $x_{center}$  is the position of the center of the domain wall, which was not *a-priori* fixed in the numerical simulation of [5]. We then determine  $B(\Gamma)$  by reproducing the energy density  $T_{tt}$  using the formula

$$T_{tt} = (1 - \Gamma) \epsilon_{\text{phase A}} + \Gamma \epsilon_{\text{phase B}} + (1 - B(\Gamma)) \Sigma$$
 (B.3)

where we use the generalized version (8.1) which takes into account appropriate energy densities of the two distinct deconfined phases. The last term follows from

$$T_{\mu\nu}^{\Sigma} = \Sigma \left( -\eta_{\mu\nu} + v_{\mu}v_{\nu} - Bu_{\mu}u_{\nu} \right) \tag{B.4}$$

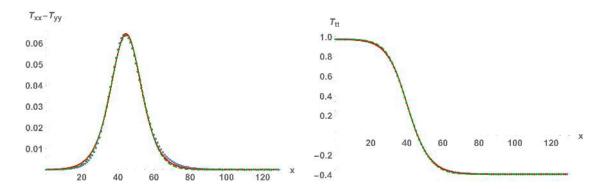


Figure 11. Reproducing the numerical domain wall between two deconfined phases for the nonconformal bottom-up holographic gravity+scalar theory from [5]. On the left: surface tension density  $T_{xx} - T_{yy}$  fitted using option A (red) and option B (dashed green). On the right: energy density  $T_{tt}$  using the same  $B(\Gamma)$  for both options. The numerical data marked by blue dots are taken from simulations performed in [5].

which differs from (4.9) just by the absence of the  $n_{\mu}n_{\nu}$  term as in the present case there is no  $\phi$  direction. Recall that for option A,  $\Gamma(\gamma) = \gamma$ , while for option B,  $\Gamma(\gamma) = \gamma^2(3-2\gamma)$ . We use a common  $B(\Gamma)$  in both cases. We find that for this theory

$$B(\Gamma) = 6.25 - 3.5 \,\Gamma \tag{B.5}$$

works very well, as shown in figure 11 (right).

# C The $n^{\mu}n^{\nu}$ terms from an action

For completeness, let us discuss how one could formally implement the  $n^{\mu}n^{\nu}$  in the energy-momentum tensor as coming from an action. Now of course the action would have to be considered as a *four-dimensional* action including the  $\phi$  circle. We should just look at solutions which do not involve any dependence on  $\phi$ .

A natural way to proceed is to introduce a vector  $N^{\mu}$  and

$$N = \frac{1}{\sqrt{g_{\mu\nu}N^{\mu}N^{\nu}}} \tag{C.1}$$

so that the unit vector  $n^{\mu}$  is given by

$$n^{\mu} = NN^{\mu} \ . \tag{C.2}$$

All this is rather artificial as we have to keep N=1 and  $N^{\mu}=(0,0,0,1)$  fixed and nondynamical. Proceeding as before, we get the variation

$$\delta N = \frac{1}{2} N n_{\mu} n_{\nu} \delta g^{\mu\nu} \tag{C.3}$$

and we see that the confining energy-momentum tensor

$$T_{\mu\nu}^{\rm conf} = g_{\mu\nu} - 4n_{\mu}n_{\nu} \tag{C.4}$$

arises from the Lagrangian density

$$\mathcal{L}^{\text{conf}} = q(N) = N^4 . \tag{C.5}$$

Let us now move to the scalar action. The only change will be that the coefficients can now be functions of both T and N. Again for simplicity we take a power law Ansatz

$$a(T, N, \gamma) = T^{\alpha} N^{\kappa} a(\gamma), \qquad V(T, N, \gamma) = T^{\beta} N^{\rho} V(\gamma).$$
 (C.6)

In the formula for  $T^{\Sigma}_{\mu\nu}$  we thus have the following terms (evaluated at T=N=1)

$$-a(\gamma)\left(\alpha(\partial\gamma)^{2}+(\alpha+\beta)V(\gamma)\right)u_{\mu}u_{\nu}+a(\gamma)\left(\kappa(\partial\gamma)^{2}+(\kappa+\rho)V(\gamma)\right)n_{\mu}n_{\nu}$$
 (C.7)

as well as

$$a(\gamma)\partial_{\mu}\gamma\partial_{\nu}\gamma - a(\gamma)\left(\frac{1}{2}(\partial\gamma)^2 + V(\gamma)\right)g_{\mu\nu}$$
 (C.8)

Now we should impose the tracelessness condition. We can do it now as currently we have a model of the energy-momentum tensor of the *four-dimensional* boundary theory. We get two equations arising from the coefficients of  $(\partial \gamma)^2$  and  $V(\gamma)$  in the trace:

$$\alpha + \kappa = 1$$
  $\alpha + \beta + \kappa + \rho = 4$ . (C.9)

The numerical fits lead to

$$B = \frac{3}{2}\alpha + \frac{1}{2}\beta = 1 + \Gamma, \qquad -C = \frac{3}{2}\kappa + \frac{1}{2}\rho = 2 - \Gamma$$
 (C.10)

where B and C are the coefficients in (4.9). But again we would like to emphasize that this is just a formal exercise as we always take  $N \equiv 1$  in the Witten model [17].

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