

A Survey on Protocols, Platforms and Simulation Tools for Wireless Sensor Networks

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Abstract

Wireless Sensor Networks (WSNs) are becoming very common technology which combine sensing, processing, and wireless multi-hop networking. This paper provides a wide review of the present state about WSNs at the time of its writing. Following a top-down approach, WSNs concept, definition and applications is provided. Furthermore, an overview of WSNs constraints and judgment metrics such as lifetime and latency is given. Then, the communication protocol stack for WSNs is described, and protocols developed for each layer are discussed. Finally, this paper provides review and comparisons of current simulation programs. All of these features make the paper valuable for an extensive variety of possible readers, researchers in WSNs, students starting research in WSNs, specialists wanting to offer WSN solutions, and WSN application designers.

Keywords: *Wireless sensor networks; communication protocol stack; Platforms; Simulator Tools; Ad hoc networks*

1. Introduction

Wireless Sensor Networks (WSNs), are one of the most important technologies for the current century. Normally, WSNs composed of interconnected sensor nodes that are capable of not only sensing, but also interactive with each other [1–3]. In recent years, WSNs have acquired global attention, mainly with the development of smart sensors which evolved due to spread in Micro-Electro-Mechanical Systems (MEMS) technology [4–6]. The benefits of WSNs allow observing, and control functionality. Probable applications contain environmental monitoring, industrial monitoring and control, alarm and security systems, home automation, and military targeting and exploration [1, 7, 8]. The wiring cost and the extensive implementation time are the main challenges in the implementation of the conventional wired sensor networks. For that reason, the wired sensor networks have been replaced by WSNs. In the WSNs, the deployment is simpler; just drop sensor nodes from the airplane into the target area in place of wiring from the target area to the station. Recently, WSNs have acquired great attention from industry and academia in worldwide. A huge number of study activities has been made to discover and resolve several design issues, and great improvements have been made in the design and development WSNs [9].

The previously described features assure an extensive number of applications for WSNs. For example, doctor can monitor remotely the vital signs for patients. While this allows the doctor to good comprehend the patient's present state, it also is suitable for the patients. Also, sense chemical agents in the surroundings can be made using WSNs. They can assistance detect the type and location of pollutants. Basically, WSNs will supply the user with a good comprehending of the environment [5, 10]. In general, WSNs applications can be categorized into two groups: monitoring and tracking as shown in Figure 1. Monitoring applications

comprise indoor/outdoor environmental monitoring, patient monitoring, power monitoring, manufacturing works and process automation, and structural and seismic monitoring. Tracking applications comprise tracking animals, objects, humans, and vehicles [4, 11].

Implementation of these and other WSNs applications is limited by the WSNs constraints. The WSNs constraints can be classified into two types; resource and design constraints. Resource constraints comprise a small communication range, limited amount of energy, low processing and limited bandwidth in sensor node. Design constraints are based on the application necessities and depend on the application. The size of the network and the deployment method are mainly depend on the environment [4, 5, 12]. one of the still open research issues in the WSNs technology is how to design WSNs which provide both extended network lifetime and QoS with the constrained power source equipped on the sensor nodes [13]. The root to solve this problem is to increase the energy efficiency of networking so that the largest amount of valuable information can be transferred per unit energy [14]. In other words, we are not merely minimizing the power consumption, but in its place maximizing energy efficiency so that the greatest QoS is delivered within such power constraints.

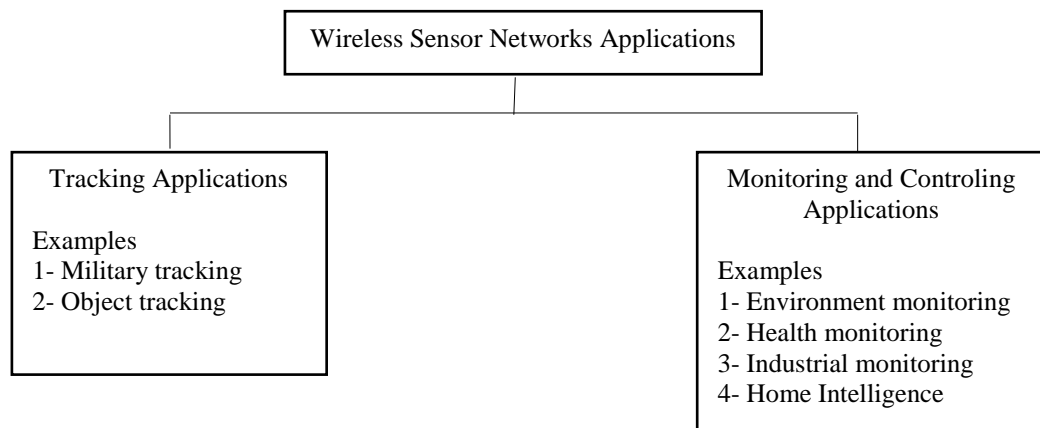


Figure 1. Classification of WSNs Applications

This paper is broadly divided into seven sections; Section 2 discusses judgment metrics on the WSNs. Section 3 relate to the discussion about the hardware structure of sensor nodes. Section 4 focuses on the WSNs platforms. Section 5 discusses the communication protocols in WSNs. Section 6, relating to the issue of simulation programs of WSN. Section 7, concludes this paper.

2. Judgment Metrics on the WSNs

A There are several metrics that are used to judge the quality of WSNs. Some of these include;

- 1) **Network Lifetime (LT):** which is a significant metric depending on several factors, including lifetime definition, energy consumption model, protocols and network architecture, channel characteristics, and data collection initiation[15].
- 2) **Energy Efficiency (EE):** which aims to reduce the amount of energy consumption for a given task (*e.g.*, Energy efficient clustering scheme (EECS) [16]).
- 3) **Energy-Per-Useful-Bit (EPUB):** which captures overhead due to physical layer modulation [17].

- 4) **Latency:** which can be defined as the time required to send a packet through a network from source to the sink [18].

The network lifetime becomes a critical metric used to judge the quality of WSNs, where several techniques have been made to increase the network LT. Some of these include power aware storage, energy-aware MAC protocols, duty-cycling schemes, redundant placement of nodes, data dissemination and routing protocols, and tiered system architectures [19]. As we mentioned above that the network lifetime depends on the definition, so we listed below some common definitions of network lifetime which are used in previous work:

Definition 2.1: Network lifetime can be defined as the time duration from the beginning of the network job to the moment when the first node dies [19].

Definition 2.2: Network lifetime is the maximum time after which the desired network performance cannot be achieved [20].

Definition 2.3: Network lifetime is defined as the time period during which the data rate is preserved above a minimum required data rate [21].

Definition 2.4: Network lifetime is defined as the time duration from start the first transmission in the WSNs to the moment when the number of nodes which have not finished their remaining energy falls below a threshold, which is depended on the type of application [15].

Definition 2.5: Network Lifetime can be defined as the time period which the required Signal-to-Noise Ratio (SNR) at the sink is met with a specific probability [22].

3. Hardware Structure

The functionality of a sensing node is generally implemented through four basic units which are; transceiver, processing, sensing and power units as shown in Figure 2. The transceiver unit allows the sensor node to interconnect with other sensor nodes. The processing unit is used to allow management and data processing in the sensor node. The function of sensing unit is observing specific phenomenon. The power unit is used to provide the system supply voltage and it can be supported by an energy harvesting unit such as small-scale wind mills or solar cells. Also, it may have optional unit such as mobilize subsystem and location finding system [5, 4, 23]. Therefore, the average energy consumption per unit time of sensor node can be express as:

$$E = E_{Transceiver} + E_{Processing} + E_{Sensing} + E_{Optional} - E_{Harvest} \quad (1)$$

where $E_{Transceiver}$, $E_{Processing}$, $E_{Sensing}$ and $E_{Optional}$ are the energy consumption per unit time in transceiver unit, processing unit sensing unit and optional units respectively, and $E_{Harvest}$ is the energy gained per unit time in harvest unit. In the following we will discuss each main unit individually.

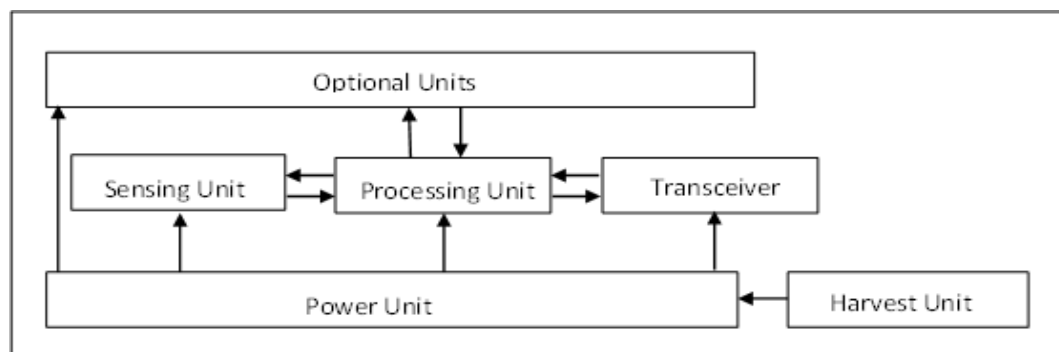


Figure 2. Architecture of Wireless Sensing Node

3.1. Transceiver Unit

The transceiver unit is composed of transmitter circuit, receiver circuit, and an antenna which are used to send and receive packets. The purposes of the transceiver unit are the selection of a frequency channel, a transmit power, the modulation scheme, symbol synchronization, and clock generation [24]. The main components of transceiver at transmitter side are baseband digital circuit, analog transmitted circuit and power amplifier. Similarly the main components of transceiver at receiver side are baseband digital circuit, analog receiver circuit and LNA amplifier [26–28] as shown in Figure 3. The total power consumption for transmitting and for receiving, denoted by P_{tx} and P_{rx} , are given by:

$$P_{tx} = P_{Dct} + P_{Act} + P_{amp} + P_t = P_{to} + (\alpha + 1)P_t \quad (2)$$

$$P_{rx} = P_{Dcr} + P_{Acr} + P_{LNA} = P_{ro} \quad (3)$$

where P_{Dct} and P_{Act} are the power consumptions of the digital circuit at transmitter side and the analog circuit at transmitter side, respectively, the two components can be modeled as a constant, P_{to} . P_{amp} and P_t are the power consumptions of the power amplifier and transmitted power. $\alpha = \xi/\eta - 1$ with ξ and η being the drain efficiency and the peak-to-average ratio, respectively. Similarly, P_{Dcr} , P_{Acr} , and P_{LNA} are the power consumptions of the digital circuit at receiver side, the analog circuit at receiver side, and LNA, respectively, the three components can be modeled as a constant, P_{ro} . The characteristics of some of low power transceiver units are summarized in Table 1 [28]–[30].

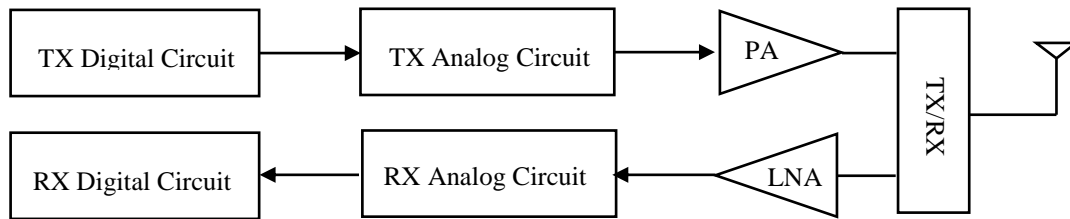


Figure 3. Transceiver Unit Structure

Table 1. Features of Some Current Transceivers

Name	Manufacturer	Band (MHz)	Data rate (kbps)	Sleep (μA)	TX (mA)	RX (mA)
MRF49XA	Microchip	433/868/915	256	.3	15	11
MRF89XA	Microchip	915	25	.1	25	3
MCMRF24J40	Microchip	2400	250	2	22	18
AT86RF212B	Atmel	700/800/900	1000	.2	18	9.2
NSnRF2401A	Nordic Semiconductor	2400	1000	0.9	13.0	19.0
NSnRF24L01	Nordic Semiconductor	2400	2000	0.9	11.3	12.3
NSnRF905	Nordic Semiconductor	433-915	50	2.5	12.5	14.0
nRF24L01+	Nordic Semiconductor	2400	250	.9	11.3	13.5
RFMTR1001	SRFMonolithic	868	115.2	0.7	12	3.8
RFMTR3100	SRFMonolithic	433	576	0.7	10	7.0
SEXE1201A	Semtech	433	64	0.2	11.0	6.0
SEXE1203F	Semtech	433-915	152.3	0.2	33.0	14.0
TICC2420	Texas Instruments	2400	250	1	17.4	18.8
TICC2500	Texas Instruments	2400	500	0.4	21.2	17.0
TICC1000	Texas Instruments	433-915	76.8	0.2	10.4	9.3

TICC1100	Texas Instruments	433-915	500	0.4	15.5	16.5
TICC2538	Texas Instruments	2400	250	1.3	24	20
TICC2531	Texas Instruments	2400	250	.4	29	20.5

3.2. Processing Unit

The central component of sensor node is processing unit which is used to allow management and data processing in the sensor node. Micro-Controller Unit (MCU) is usually implements the processing unit, which is consist of a micro-processor, memories, and other peripherals [1]. The energy consumption per unit of time for processing unit is given by:

$$E_{Processing} = C_{avg}V_{sub}^2f + V_{sub}(I_0e^{\frac{V_{sub}}{nV_t}}) \quad (4)$$

where C_{avg} is the average capacitance switched per cycle, V_{sub} is the supply voltage, V_t is the thermal voltage, I_0 is the leakage current, and f is sensor frequency, n is the constant that depends on the processor. The Features of MCUs from several manufacturers are given in Table 2 [1, 28-29].

Table 2. Features of Some MCUs

Name	Manufacturer	SRAM (kB)	FLASH (kB)	1MIPS (mA)	Sleep (μ A)
AT89C51RE2 (8051)	Atmel	8	128	7.4	75
ATmega103L (AVR)	Atmel	4	128	1.38	1
CY8C29666	Cypress	2	32	10	5
M68HC08	Freescale	2	61	3.75	22
PIC18LF8722	Microchip	3.9	128	1.0	2.32
PIC24FJ128	Microchip	8	128	1.6	21
XE8802 (CoolRisc)	Semtech	1	22	0.3	1.9
MSP430F1611	Texas Instruments	10	48	0.33	1.3

3.3. Sensing Unit

There are a wide range of low power sensors appropriate for WSNs. Small sensing time, acceptable accuracy and low power consumption are essential requirements for sensing. The energy consumption per unit time in sensing unit at sensor node can be express as [31]:

$$E_{Sensing} = \frac{T_{sense}}{T} bV_{sub}I_{sense} \quad (4)$$

where I_{sense} is the total current required for sensing activity, T_{sense} is the sensing time, T is the sensing period, and b is the number of bit which generate at each activity. The features of some low power sensors are given in Table 3 [1, 28, 32] he central component.

Table 3. Features of Some Low Power Sensors

Name	Type	Sensing time	Active current
SLG64-0075	Liquid-Flow	30ms	5.1mA
SFM4100	Gases- Flow	4.6ms	12.5mA
VTISCA3000	Acceleration	10ms	120 μ A
VTISCP1000	Airpressure	110ms	25 μ A
SensorionSHT15	Humidity	210ms	300 μ A

AvagoAPDS-9002	Illumination	1.0ms	2.0mA
HitachiHM55B	Magneticfield	30ms	9.0mA
FastraxiTRAX03	Position	4.0s	32mA
DallasDS620U	Temperature	200ms	800 μ A

3.4. Energy Harvesting Unit

Due to nature and environment, energy harvesting units don't provide a constant power rate. So, these units are mainly worked in combination with a storage device such as a rechargeable battery or super-capacitor. Storage device stores additional energy and offers it later, when there is no energy can be harvested from the environment. We listed below some common scavenging sources which are used in WSNs [33]:

- **Solar cells** use light of sun to produce electricity and it are very common energy harvesting sources. Small panel supplies sufficient power to sensor node. A rechargeable battery or a super-capacitor is usually used with solar cells.
- **Small- scale wind mills** are unusually energy harvesting sources and it appropriate for outdoor applications.
- **Radiant energy** is harvesting technique that convert energy from electromagnetic waves.
- **Vibration energy** is harvesting method that convert vibration energy. It common uses with civil engineering applications.
- **Thermal energy** is harvesting technique that convert the temperature difference between two materials to energy. here are a wide

3.5. Power Unit

The power unit stores energy in battery and supply suitable voltage levels. It consists of battery and a voltage regulator [28].

4. WSNs Platforms

In recent years, WSNs platforms have improved significantly and many different manufacturers build wireless sensor nodes. Still, because of the severe energy constrains, the current level of technology can't achieve all the requirements. In general, This platforms are classified into three categories, each of which shows diverse hardware setup commensurate with varied applications [9].

- **Adapted General-Purpose Computers:** are low power embedded PCs, tablet PCs, and smart phones. It generally run on operating system such as Windows, Mac OS, Linux, and Android. These platforms are mainly work with wireless communications standards such as GSM, UMTS, LTE, Bluetooth, and wireless LAN. These platforms are programmed using higher level programming languages such as Java and C++, which makes develop and implement software components more easy.
- **Embedded Sensor Modules:** are grouped from different chips such as MCU and transceiver. Due to mass production of these chips, the cost of these categories is cheap and widely used. C/C++ is generally used to program the MCUs of these platforms. Examples of this category include Mica, Mica2Dot, and WeC.
- **System on chip (SoC):** is one chip contain transceiver, sensors, and the MCU. These platforms have a small size and low energy consumption. Examples of this category include smart dust node and PASTA node.

Nowadays, quite a few platforms for WSNs are available. This diverse group of these platforms give the option to select a platform which fits with the requirements of the applications. The characteristics of some sensor platforms are presented in Table 4 [9, 32–34].

5. Communication Protocols

In WSNs, there are five communication layers: physical layer, data link layer, network layer, transport layer, and application layer as shown in Figure 4 [37]. In the following, we discuss the most significant features of each communication layer.

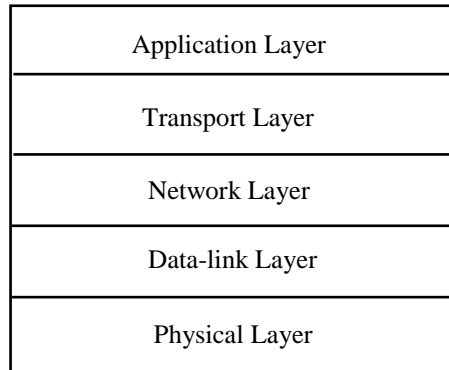


Figure 4. Sensor Network Architecture

Table 4. The Characteristics of Some Sensor Platforms

Platforms Name	Microcontroller	Transceiver	Program + Data Memory	Programming
KMote	TI MSP430	250 kbit/s 2.4 GHz IEEE 802.15.4 Chipcon Transceiver	10 KB RAM 48 KB flash	TinyOS and SOS Support
NeoMote	ATmega 128L	TI CC2420 802.15.4/ZigBee compliant radio	4 KB RAM 128 KB flash	TinyOS and SOS Support
PowWow	MSP430F1612	TI CC2420 802.15.4/ZigBee compliant radio	5 KB RAM 55 KB flash	C /C++
TelosB	TI MSP430 MCU	250 kbit/s 2.4 GHz IEEE 802.15.4 Chipcon Transceiver	5 KB RAM 48 KB flash	TinyOS and SOS Support
panStamp	Atmega328P	TI CC1101 (868/915 MHz)	2 KB RAM 32 KB flash	C /C++
Ublimote2	TI's MSP430F2618	TI's CC2520 2.4 GHz ZigBee® / IEEE 802.15.4	8 KB RAM 116 KB flash	C /C++
Mica	ATmega 103 - 4 MHz 8-bit	RFM TR1000 radio 50 kbit/s	4 KB RAM 128 KB flash	TinyOS Support
Mica2	ATMEGA 128L	Chipcon 868/916 MHz	4 KB RAM 128 KB flash	TinyOS and SOS Support
XYZ	ML67 series MCU	TI CC2420 802.15.4/ZigBee compliant radio	32 KB RAM 256 KB flash	C /C++
FireFly	Atmel ATmega 1281	Chipcon CC2420	8 KB RAM 128 KB flash	C /C++

5.1. Physical Layer

Physical layer is the lower layer of the communication layers and it provides the interface to the sensor node to communicate with other node over the physical medium. The function of physical layer is carrier frequency generation, modulation, and signal detection. In WSNs, the physical layer should be given a special care due to the characteristic constraints, such as low-power consumption and hardware design , such as low-power consumption and hardware design [35]-[36].

5.2. Data-link Layer

The second layer of the communication stack is Data link layer (DLL) and it generally consist of two sub-layers: Logical Link Control (LLC) and Medium Access Control (MAC). In the following, we will only discuss the MAC sub-layer, because it has high important effects on the energy consumption and latency issues [1, 38]. The functions of MAC protocols are providing connections for the routing protocol and managing transceiver unit on a shared wireless medium. In general, there are two categories of MAC protocols [8, 39-40]:

- 1) Schedule-based Protocols which is depend on scheduling and reservation. Time-division multiple access (TDMA) is a good example of these type of protocols, in which the time is divided into several time slots. Each time slot is assigned to a sensor node and a node can transfer message during its assigned time.
- 2) Contention-Based MAC Protocols, in which nodes compete to reserve shared wireless media and trying to avoid packet collisions. In this type of MAC protocols, duty cycling is used to advanced energy saving, where the time is divided into a long sleep period and a small active period. This type of MAC protocols can be classified, according to the synchronization of data exchanged, into two categories: unsynchronized and synchronized protocols as shown in Figure 5, [41-42].

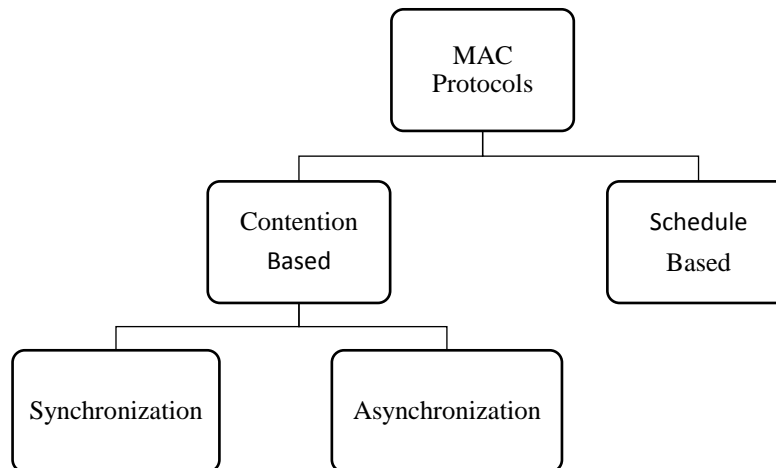


Figure 5. Category of MAC Protocols

5.2.1. Unsynchronized low Duty-Cycle MAC protocols: Duty cycling mechanism is used in unsynchronized low duty-cycle MAC protocols where nodes listening to physical medium asynchronously to check for any probable flow [41, 43]. Example of an unsynchronized MAC protocol is presented in Figure 6. In this MAC protocol example, transmissions are start with a Request to Send (RTS) preamble packet. If the destination is in active state and receives the RTS preamble packet, it sends a Clear to Send (CTS) packet. Then the source will transmit a data packet. If the destination is in a sleep state when source send an RTS packet, then the RTS preamble packet works as a wake-up signal and the source will repeat attempts to retransmit the RTS packet, after going into a power saving period for a short time, until the destination wakes up and receives the RTS packet.

5.2.2. Synchronized low Duty-Cycle MAC protocols: Scheduling mechanism is used in synchronized low duty-cycle MAC protocols to ensure that sensor nodes approve

Routing (DSR). In on-demand, the routes are created only when required such as Ad-hoc On-demand Distance Vector routing (AODV) [1].

- **Data centric routing:** the content of message is used to determine the routes instead of using node identifiers so it more compatible for WSNs than the node-centric protocols. This type of routing protocols can be categorized into three categories; negotiation based, interest based, and query based approaches. In negotiation-based protocols, data transmission takes place after exchange negotiation messages. During the negotiation phase, a node can decide that the data is not wanted so this reduces energy consumption. In the interest based protocols, a sink node request data from each node in the network by transferring a request telling the data it needs then nodes forward the required data to the sink node. In query based approaches, high level language such as database program might be used to express a query. For example, a query might request average humidity or pressure in specific region during a period of time [45].
- **Location-based routing:** in which the routing decisions is made based on geographical position. A basic principle operation of location-based routing protocols is to choose a next hop which is nearest to the target node [6].
- **Multipath routing:** that aims to increase reliability by transmitting a message from a source node to a destination node through several paths [2], [6]. The power unit stores energy in battery and supply suitable voltage levels. It consists of battery and a voltage regulator [28].
- **Hierarchical Routing:** is a method of routing in WSNs that is based on breaks the WSN into clusters. Each cluster consist of group of nodes and cluster head, which is responsibility of exchange data from the cluster to the other cluster heads. [2].
- **Mobility-based Routing:** used to serve WSN with mobile nodes and mobility in WSNs generates new challenges to routing protocols [45].
- **QoS-based Routing:** is the routing protocols which consider QoS requirements in terms of latency, fault tolerance, and reliability in routing decision [2, 6, 45].

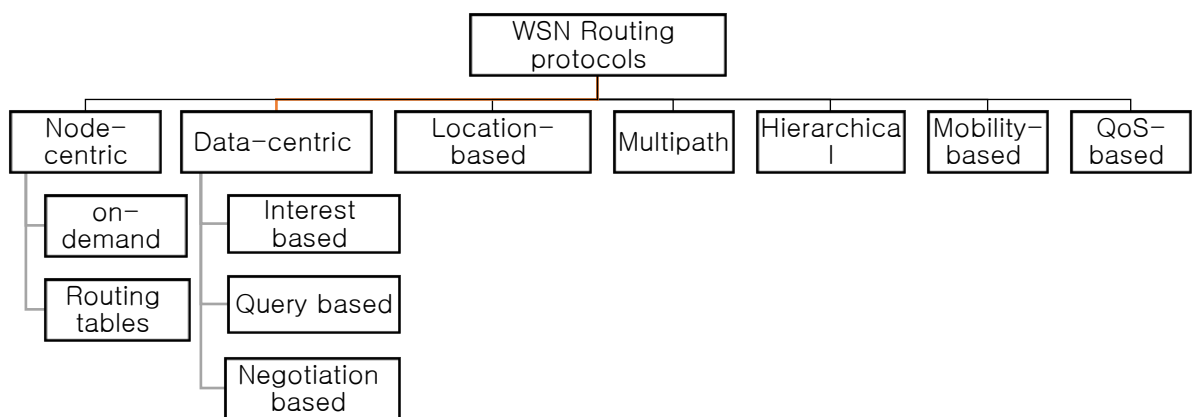


Figure 8. WSNs Routing Protocols

5.4. Transport Layer

The fourth layer in the WSN communication protocol stack is the transport layer. It provides services such as flow control, multiplexing and reliability between end

users [47]. The power unit stores energy in battery and supply suitable voltage levels. It consists of battery and a voltage regulator [28].

5.5. Application Layer

The last layer of the WSN communication protocol stack is the application layer and it makes common services for the application. The Sensor Management Protocol (SMP), and the Sensor Query and Data Dissemination Protocol (SQDDP) are examples of application protocols in WSNs [5, 47].

Table 5. Routing Protocols in WSNs

Category	Protocols
Node-centric Routing	AODV, DSR
Location-based Protocols	BVGF, TBF, GeRaF, Span, GEAR, GAF, SMECN, MECN
Data-centric Protocols	Home Agent Based Information Dissemination, Quorum-Based Information Dissemination, Energy-aware Routing, Information-Directed Routing, SPIN, Information-Directed Routing Directed Diffusion, Energy-aware Routing, Rumor Routing, Gradient Based Routing, COUGAR, ACQUIRE, EAD, Information-Directed Routing, Gradient Based Routing
Hierarchical Protocols	APTEEN, HEED, LEACH, TEEN, PEGASIS
Mobility-based Protocols	Data MULES, SEAD, Joint Mobility and Routing, TTDD
Multipath-based Protocols	N-to-1 Multipath Discovery, Sensor-Disjoint Multipath, Braided Multipath
QoS-based protocols	Energy-aware routing, SPEED, SAR

6. Simulation Programs of WSNs

WSNs consists of a high number of sensing nodes, which is used to monitor and study phenomena and providing information that was not available before in places which are difficult to reach. It is hard to build a WSN model analytically and it usually leads to oversimplified analysis with limited accuracy. Therefore, simulation is essential to study WSN and it requires a suitable model based on accurate assumptions. Simulation provides exact environmental settings for calculating and improving the design factors. It also provides great vision about the effects of the different factors. The available simulator programs are mostly developed in C++ or Java and it are either open source or commercial as shown in Figure 9 [47]. The features and comparison of each of these WSN simulating tools are given in Table 6.

6.1. Commercial Simulators

There are a little number of commercial simulators tools such as OPNET, QualNet and NetSim which are able to simulate, in real-time, a big number of nodes. Due to cost reasons, commercial simulator programs may not be the good choice for researchers. We listed below characteristics and features of some commercial sensor network simulators:

- **OPNET Modeler Wireless Suite** is a simulation tool and modeling for different kinds of wireless networks. It is developed by OPNET Technologies, Inc. and based on the familiar product OPNET Modeler [48], [49].

- **QualNet** is network emulation and simulation and it enables real-time network simulation. It is provided by Scalable Networks Technologies, Inc. and it has ability to deal with real networks and other simulations [50].
- **NetSim** is a state-of-the-art network simulator for lab experimentation, R&D. Several technologies such as Wireless LAN, WSNs, Wi Max, IP, TCP, *etc.*, are covered in NetSim. It allow researchers in WSNs topic to simulate energy efficient and power management, efficient protocol design, self-configuration, routing, localization, LEACH *etc.*, [51].

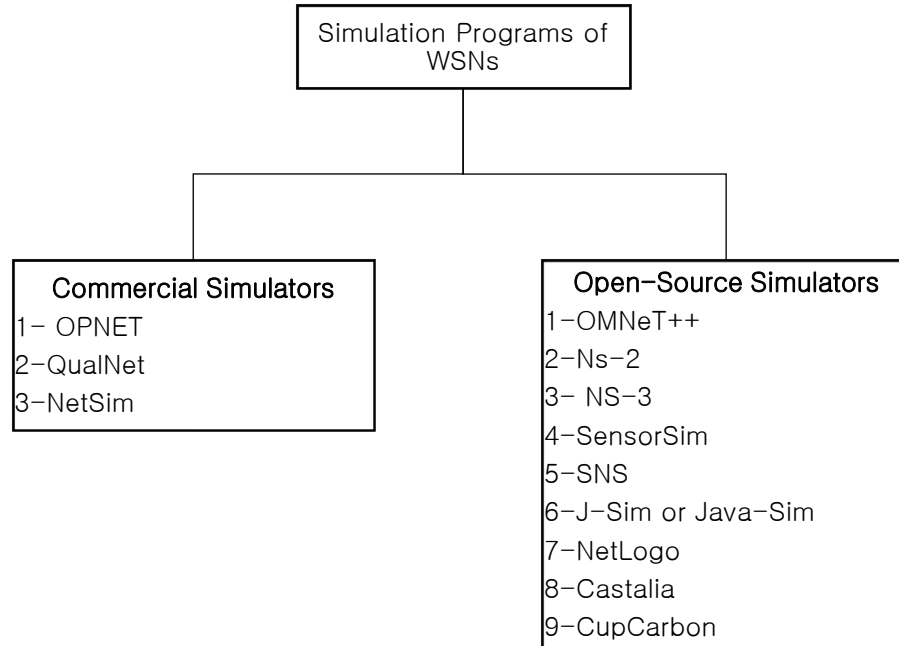


Figure 9. Simulation Programs of WSNs

6.2. Open-Source Simulators

Open-Source or Academic simulators are often suitable to help with research projects and some of them under development. We listed below characteristics and features of the most relevant academic WSNs simulators:

- **OMNeT++** is an extensible, modular, component-based C++ simulation library and framework, primarily for building network simulators. It can be run on the most common operating systems such as Mac OS, Windows, and Linux. There are some frameworks which enable OMNeT++ to be used for WSNs such as Mixim [48, 52].
- **Ns-2** "is a discrete event simulator targeted at networking research which provides support for MAC and routing, protocols, among many others. It supports simulation for wireless and mobile network and it provides various modules for mobile WSNs. There are some simulation frameworks that enable Ns-2 to simulate WSNs such MannaSim [48, 53].
- **Ns-3** "is a discrete-event network simulator, targeted primarily for research and educational use. Ns-3 is free software, licensed under the GNU license, and is publicly available for research, development, and use NS-3 is not an extension of NS-2; it is a new simulator". The recent version NS-3.13 was released on 17 September 2014 [54].

Table 6. Comparison between Different Wireless Sensor Simulation Programs

No	Simulator	Operation system	Programming language	Type	Recent version
1	OPNET	windows/Linux	C/C++	Commercial	9.1
2	QualNet	windows/Linux	C/C++	Commercial	5.2
3	NetSim	windows	C / C++ and Java	Commercial	8
4	OMNeT++	windows/Linux	C / C++ and Java	Open Source	4.5
5	Ns-2	Linux	C/C++	Open Source	2.35
6	Ns-3	Linux	C/C++	Open Source	3.21
7	SensorSim	Linux	C/C++	Open Source	1
8	J-Sim	windows/Linux	Java	Open Source	1.3
9	NetLogo	windows/Linux	Java	Open Source	5.1.0
10	Castalia	Linux	C/C++	Open Source	3.2
11	CupCarbon	windows/Linux	Java	Open Source	1

- **SensorSim** is provided by the University of California at Los Angeles (UCLA). It has additional extended Ns-2 by including support for WSNs simulation. Also, it includes the definition of sensor node, and sink nodes, a mobility model, wireless communication channels, physical media, and a power model [55].
- **J-Sim or Java-Sim** is open-source component-based framework for WSNs simulation. It includes the definition of sensor nodes, target, and sink nodes, a mobility model, wireless communication channels, physical media, and a power model [48].
- **NetLogo** “is a simulation of data dissemination flooding technique in wireless sensor network. Such a network is used to detect and report certain events across an expanse of a remote area - *e.g.*, a battlefield sensor network that detects and reports troop movements. The idea behind this network is that it can be deployed simply by scattering sensor units across the area, *e.g.*, by dropping them out of an airplane; the sensors should automatically activate, self-configure as a wireless network with a mesh topology” [56].
- **Castalia** “is a WSNs simulator for early-phase algorithm/protocol testing built at the Networks and Pervasive Computing program of National ICT Australia. It supports realistic channel and radio models, a key element for accurate early-phase WSN simulation. It provides support for defining versatile physical processes. It also supports enhanced modeling of the sensing devices and other often-neglected attributes of a WSN such as node clock drift”. The recent version Castalia 3.2 was released on 30 March 2011 [57].
- **CupCarbon** is a multi-agent and discrete event WSN simulator. Networks can be designed and prototyped in an ergonomic user-friendly interface using the Open-Street-Map (OSM) framework by deploying sensors directly on the map. It can be used to study the behavior of a network and its costs.

The sensors are composed of a microcontroller, a battery, an antenna and a sensor unit. The main objectives of CupCarbon are both educational and scientific. It can help trainers to explain the basic concepts and how sensor networks work and it can help scientists to test their wireless topologies, protocols, *etc.*, [58].

7. Conclusion

At present, WSNs are a hot research topic and it has increasingly improved the way to monitor industrial phenomenon and environmental over the last two decades. In this article, a wide survey of the recent state of the art about WSNs, the concept, definition and applications, is provided. Also, an overview of WSNs constrains and judgment metrics such as lifetime and latency is given. Furthermore, a wide review of existing hardware and platforms of WSNs is provided. To fully understanding of WSNs, comprehensive description of the communication protocol stack, which include five layers; physical layer, data link layer, network layer, transport layer, and application layer, is given. Moreover, WSNs MAC protocols is classify into two categories: contention-based and schedule-based MAC protocols. Also, contention-Based MAC protocols is classify into two categories: asynchronous and synchronous. This classification aims to identify the research trend of WSN MAC protocols based on methods they use. Moreover, in this article, the routing techniques are categorized based on their operation as node-centric, data-centric, location based, multipath routing, hierarchical protocols, mobility-based protocols, and QoS-based protocols. Finally, to help researchers and designers to selecting a suitable simulation, a wide review of current simulation programs is provided.

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