# A survey on two model equations for compressible viscous fluid 

By

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In this paper we shall discuss again the temporally global problem of the two model equations treated in [5] and [6]. The notation to be used here is similar to that in [5] and [6].

## § 1. On the generalized Burgers' equation

For the initial-value problem of the generalized Burgers' equation

$$
\begin{align*}
& \left\{\begin{array}{l}
\frac{\partial}{\partial t} v(x, t)=\frac{\mu}{\rho(x, t)} \frac{\partial^{2}}{\partial x^{2}} v(x, t)-v \cdot \frac{\partial}{\partial x} v, \\
\frac{\partial}{\partial t} \rho(x, t)+\frac{\partial}{\partial x}(\rho v)=0,(v, \text { one-dimensional velocity; } \rho, \text { density (scalar } \\
\quad \text { quantity); } \\
x \in R^{1}, \text { spatial variable } ; t, \text { temporal variable }(\geqq 0) ; \mu \text { positive constant), }
\end{array}\right.  \tag{1.1}\\
& \left\{\begin{array}{l}
v(x, 0)=v_{0}(x) \in H^{2+\alpha}, \\
\rho(x, 0)=\rho_{0}(x) \in H^{1+\alpha},\left(0<\bar{\rho}_{0} \equiv \inf \rho_{0} \leqq \rho_{0} \leqq \bar{\rho}_{0} \equiv\left|\rho_{0}\right|^{(0)}<+\infty\right),
\end{array}\right.
\end{align*}
$$

we have already obtained ([4], [5], [6]):
Theorem 1. For some $T \in(0,+\infty)$, there exists a unique solution $(v, \rho)$ of $(1.1)$ $-(1.2)$ belonging to $H_{T}^{2+\alpha} \times B_{T}^{1+\alpha}$.

Moreover, we have a result that there is a unique temporally global solution ( $v, \rho$ ) of (1.1)-(1.2) belonging to $H_{T}^{2+\alpha} \times B_{T}^{1+\alpha}$ for an arbitrary $T \in(0,+\infty)$ under the condition that $v_{0}$ is to be represented as

$$
\begin{equation*}
v_{0}=v_{01}+v_{02}\left(v_{01}, v_{02} \in H^{2+\alpha} ; v_{01}^{\prime} \leqq 0, v_{02} \in L_{1}\left(R^{1}\right)\right) . \tag{1.3}
\end{equation*}
$$

We shall show here the existence of a unique temporally global solution of (1.1)(1.2) such as mentioned above, without any additional conditions. For this purpose
it is required to have a priori estimates for $(v, \rho)$ in $H_{T}^{2+\alpha} \times B_{T}^{1+\alpha}$.
Now, if ( $v, \rho$ ) is a solution of (1.1)-(1.2) belonging to $H_{T}^{2+\alpha} \times B_{T}^{1+\alpha}$ for $T \epsilon$ $(0,+\infty)$, then

$$
\begin{equation*}
\rho(x, t)=\rho_{0}\left(x_{0}(x, t)\right) \exp \left\{-\int_{0}^{t} v_{x}(\bar{x}(\tau ; x, t), \tau) d \tau\right\}, \tag{1.4}
\end{equation*}
$$

where $\bar{x}(\tau ; x, t)$ satisfies

$$
\left\{\begin{array}{l}
\frac{d}{d \tau} \bar{x}(\tau ; x, t)=v(\bar{x}(\tau ; x, t), \tau),  \tag{1.5}\\
\bar{x}(t ; x, t)=x(\tau \in[0, T])
\end{array}\right.
$$

and

$$
\begin{equation*}
x_{0}(x, t)=\bar{x}(0 ; x, t) . \tag{1.6}
\end{equation*}
$$

The transformation $\left(x_{0}=x_{0}(x, t), t_{0}=t\right)$ from $R^{1} \times[0, T]$ into itself is obviously one-to-one and onto. We call $\left(x_{0}, t_{0}\right)$ the ( $v$-)charcteristic co-ordinates ([4], [7]). We define by use of the above co-ordinates

$$
\begin{equation*}
\hat{v}\left(x_{0}, t_{0}\right)=v\left(\bar{x}\left(t_{0} ; x_{0}, 0\right), t=t_{0}\right), \quad \text { etc. } \tag{1.7}
\end{equation*}
$$

Then, (1.1)-(1.2) is transformed into

$$
\left\{\begin{align*}
&\left\{\hat{v}_{t_{0}}\left(x_{0}, t_{0}\right)=\right.  \tag{1.8}\\
& \frac{\mu}{\rho_{0}\left(x_{0}\right)}\left(\frac{\hat{v}_{x_{0}}}{1+\omega\left(x_{0}, t_{0}\right)}\right)_{x_{0}}  \tag{1.9}\\
& \rho\left(x_{0}, t_{0}\right)= \rho_{0}\left(x_{0}\right) \frac{1}{1+\omega}, \quad\left(\omega=\int_{0}^{t_{0}} \hat{v}_{x_{0}}\left(x_{0}, t_{0}^{\prime}\right) d t_{0}^{\prime}\right) . \\
& \hat{v}\left(0, x_{0}\right)=v_{0}\left(x_{0}\right) \in H^{2+x},
\end{align*}\right.
$$

where the suffixes $t_{0}$ etc. denote differentiation in $t_{0}$ etc., respectively. Here, we note that

$$
\left\{\begin{align*}
e^{-t\left|v_{x}\right|_{t}^{(0)}} & \leqq \frac{\partial x_{0}}{\partial x}=\frac{1}{1+\omega}=\exp \left\{-\int_{0}^{t} v_{x}(\bar{x}(\tau ; x, t), \tau) d \tau\right\}  \tag{1.10}\\
& \left.\leqq e^{t\left|v_{x}\right|_{t}^{(0)}}, \quad \hat{v} \in H_{T}^{2+a}, \frac{1}{1+\omega} \in B_{T}^{1+\alpha} \text { (thus, } \in H_{T}^{1+\alpha}\right)
\end{align*}\right.
$$

It is already known ([4], [5]) that, in order to have a priori estimates for $(v, \rho)$ in $H_{T}^{2+\alpha} \times B_{T}^{1+\alpha}$, it suffices to have those for $|v|_{T}^{(0)},|\rho|_{T}^{(0)},\left|\rho^{-1}\right|_{T}^{(0)}$. It is obvious from (1.1) -(1.2) that

$$
\begin{equation*}
|v|_{T}^{(0)} \leqq\left|v_{0}\right|^{(0)} \tag{1.11}
\end{equation*}
$$

Thus, it remains to have a priori estimates for $|\rho|_{T}^{(0)}$ and $\left|\rho^{-1}\right|_{T}^{(0)}$, accordingly those for $\left|\frac{1}{1+\omega}\right|_{T}^{(0)}$ and $|1+\omega|_{T}^{(0)}$ (cf. (1.8)). Now, we put

$$
\left\{\begin{array}{l}
Y^{a}\left(x_{0}, t_{0}\right) \equiv \int_{a}^{x_{0}} \frac{\rho_{0}\left(x_{0}^{\prime}\right)}{\mu}\left\{v_{0}\left(x_{0}^{\prime}\right)-\hat{v}\left(x_{0}^{\prime}, t_{0}\right)\right\} d x_{0}^{\prime}  \tag{1.12}\\
-\log \left(1+\omega\left(a, t_{0}\right)\right)
\end{array}\right.
$$

Then, by (1.8), $Y^{a}$ satisfies

$$
\left\{\begin{array}{l}
\left(Y^{a}\right)_{t_{0}}=-\frac{\hat{v}_{x_{0}}}{1+\omega}=\frac{\mu}{1+\omega}\left(\frac{\left(Y^{a}\right)_{x_{0}}}{\rho_{0}}\right)_{x_{0}}-\frac{v_{0}^{\prime}}{1+\omega}  \tag{1.13}\\
Y^{a}\left(x_{0}, 0\right)=0, \quad\left(\left(Y^{a}\right)_{x_{0}}=\frac{\rho_{0}}{\mu}\left(v_{0}-\hat{v}\right)\right)
\end{array}\right.
$$

Obviously, $Y^{a}$ satisfies Täcklind's condition. Therefore, for any $a$ and $a^{\prime} \in R^{1}, Y^{a}=$ $Y^{a^{\prime}}$. Thus, we define

$$
\begin{equation*}
Y \equiv Y^{a}=Y^{a^{\prime}} . \tag{1.14}
\end{equation*}
$$

We remark that

$$
\begin{equation*}
Y\left(x_{0}, t_{0}\right)=Y\left(a, t_{0}\right)+\int_{a}^{x_{0}} \frac{\rho_{0}}{\mu}\left(v_{0}-\hat{v}\right) d x_{0}^{\prime} \tag{1.15}
\end{equation*}
$$

and that, by (1.13),

$$
\begin{equation*}
Y_{t_{0}}=(-\log (1+\omega))_{t_{0}} . \tag{1.16}
\end{equation*}
$$

Thus, we have

$$
\begin{equation*}
\frac{1}{1+\omega}=e^{Y} . \tag{1.17}
\end{equation*}
$$

From (1.10) and (1.17) follows that

$$
\begin{equation*}
Y\left(x_{0}, t_{0}\right)=-\left.\int_{0}^{t_{0}} v_{x}(\bar{x}(\tau ; x, t), \tau) d \tau\right|_{\substack{x=x\left(x_{0}, t_{0}\right) \\ t=t_{0}}} . \tag{1.18}
\end{equation*}
$$

From above, we have

$$
\begin{equation*}
\left|Y\left(\cdot, t_{0}\right)\right|^{(0)} \leqq|Y|_{T}^{(0)} \leqq\left.\left|v_{x}\right|\right|_{T} ^{(0)} \cdot T, \quad\left(t_{0} \in[0, T]\right) \tag{1.19}
\end{equation*}
$$

By (1.17), it suffices for us to have a priori estimates for $\left|e^{Y}\right|_{T}^{(0)}$ and $\left|e^{-Y}\right|_{T}^{(0)}$ (or $\left.|Y|_{T}^{(0)}\right)$. By (1.15), it holds that, for an arbitrary number $a \in R^{1}$,

$$
\left\{\begin{align*}
1+\omega\left(x_{0}, t_{0}\right)= & e^{-Y\left(x_{0}, t_{0}\right)}=e^{-Y\left(a, t_{0}\right)}  \tag{1.20}\\
& \times \exp \left\{-\int_{a}^{x_{0}} \frac{\rho_{0}}{\mu}\left(v_{0}-\hat{v}\right) d x_{0}^{\prime}\right\} .
\end{align*}\right.
$$

Therefore,

$$
\begin{align*}
\int_{a}^{a+l}(1+\omega) d x_{0} & =l+\int_{0}^{t_{0}}\{\hat{v}(a+l, \tau)-\hat{v}(a, \tau)\} d \tau  \tag{1>0}\\
& =e^{-Y\left(a, t_{0}\right)} \times \int_{a}^{a+l} \exp \left\{-\int_{a}^{x_{0}} \frac{\rho_{0}}{\mu}\left(v_{0}-\hat{v}\right) d x_{0}^{\prime}\right\} d x_{0} \tag{1.21}
\end{align*}
$$

First, take $l=1$. Then, we have an inequality

$$
\begin{equation*}
1+2\left|v_{0}\right|^{(0)} \cdot T \geqq e^{-Y\left(a, t_{0}\right)} \times \exp \left\{-\frac{2 \rho_{0}}{\mu}\left|v_{0}\right|^{(0)}\right\} . \tag{1.22}
\end{equation*}
$$

Hence, it holds that

$$
\begin{equation*}
e^{-Y\left(a, t_{0}\right)} \leqq\left(1+2\left|v_{0}\right|^{(0)} \cdot T\right) \exp \left\{\frac{2 \rho_{0}}{\mu}\left|v_{0}\right|^{(0)}\right\} . \tag{1.23}
\end{equation*}
$$

Next, take $l=1+2\left|v_{0}\right|^{(0)} \cdot T$. Then, we have

$$
\begin{equation*}
1 \leqq \int_{a}^{a+1+2\left|v_{0}\right| T}(1+\omega) d x_{0} . \tag{1.24}
\end{equation*}
$$

Thus, it holds that

$$
\begin{equation*}
e^{Y\left(a, t_{0}\right)} \leqq\left(1+2\left|v_{0}\right|^{(0)} \cdot T\right) \exp \left\{\left(1+2\left|v_{0}\right|^{(0)} \cdot T\right) \frac{2 \mu}{\rho_{0}}\left|v_{0}\right|^{(0)}\right\} . \tag{1.25}
\end{equation*}
$$

By (1.23) and (1.25), we have a priori estimates for $|\rho|_{T}^{(0)}$ and $\left|\rho^{-1}\right|_{T}^{(0)}$. From the discussion made above follows:

Theorem 2. There exists a unique temporally global solution $(v, \rho)$ of (1.1)-(1.2) such that it belongs to $H_{T}^{2+\alpha} \times B_{T}^{1+\alpha}$ for any $T \in(0,+\infty)$.

## § 2. On the generalized Burgers' equation with a pressure model term

Here, we shall discuss the Gauchy problem of the following system of differential equations

$$
\begin{gather*}
\left\{\begin{array}{l}
v_{t}(x, t)=\frac{\mu}{\rho(x, t)} v_{x x}(x, t)-v \cdot v_{x}-K \frac{\rho_{x}}{\rho}, \\
\rho_{t}(x, t)+(\rho v)_{x}=0, \quad\left(K, \text { positive constant } ; x \in R^{1}, t \geqq 0\right),
\end{array}\right.  \tag{2.1}\\
\left\{\begin{array}{c}
v(x, 0)=v_{0}(x) \in H^{2+\alpha}, \quad \rho(x, 0)=\rho_{0}(x) \in H^{1+\alpha}\left(0<\bar{\rho}_{0} \leqq \rho_{0} \leqq \bar{\rho}_{0}<+\infty,\right. \\
\text { cf. (1.2)), } \left.\rho_{0}^{\prime} \in L_{0} / R^{1}\right) .
\end{array}\right. \tag{2.2}
\end{gather*}
$$

In order to show that there exists a unique temporally global solution of (2.1)-(2.2) such as discussed in § 1, it suffices to obtain a priori estimates for $|v|_{T}^{(0)},|\rho|_{T}^{(0)}$, and $\left|\rho^{-1}\right|_{T}^{(0)}$, where $(v, \rho)$ is assumed to be a solution of (2.1)-(2.2) belonging to $H_{T}^{2+\alpha} \times$ $B_{T}^{1+\alpha}$ for $T \in(0,+\infty)$. This is based on reasons analogous to those in $\S 1$ and on
the fact that $-\rho^{-1} \cdot \rho_{x}$ is to be expressed in the following way (cf. [6], [7])

$$
\left\{\begin{align*}
&-\frac{\rho_{x}}{\rho}=\left(\frac{\rho_{0}^{\prime}}{\rho_{0}}\right)\left(x_{0}(x, t) \frac{\partial x_{0}}{\partial x}-\rho\left[v-v_{0}\left(x_{0}(x, t)\right)\right.\right. \\
& \times \exp \left\{-k \rho \int_{0}^{t} \bar{x}_{x}(\tau ; x, t)^{-1} d \tau\right\}-k \int_{0}^{t} \exp \{-k \rho(x, t) \\
&\left.\times \int_{\tau}^{t} \bar{x}_{x}\left(\tau^{\prime} ; x, t\right)^{-1} d \tau^{\prime}\right\} \times\{\rho(x, t) v(\bar{x}(\tau ; x, t), \tau) \\
& \times \bar{x}_{x}(\tau ; x, t)^{-1}-\left(\frac{\rho_{0}^{\prime}}{\rho_{0}}\right)\left(x_{0}(x, t)\right)  \tag{2.3}\\
&\left.\left.\times \exp \left\{-\int_{0}^{\tau} v_{x}\left(\bar{x}\left(\tau^{\prime} ; x, t\right), \tau^{\prime}\right) d \tau^{\prime}\right\}\right\} d \tau\right],\left(k=\frac{K}{\mu}\right), \\
&\left(N . B: \rho(x, t)=\rho_{0}\left(x_{0}(x, t)\right) \frac{\partial x_{0}}{\partial x}=\rho(\bar{x}(\tau ; x, t), \tau) \times \bar{x}_{x}(\tau ; x, t)\right) .
\end{align*}\right.
$$

Now, we assume that $(v, \rho) \in H_{T}^{2+\alpha} \times B_{T}^{1+\alpha}$ satisfies (2.1)-(2.2). Then, by expressing (2.1)-(2.2) in the $(v-$-)characteristic co-ordinates, we have

$$
\begin{gather*}
\left\{\hat{v}_{t_{0}}\left(x_{0}, t_{0}\right)=\frac{\mu}{\rho_{0}\left(x_{0}\right)}\left(\frac{\hat{v}_{x_{0}}}{1+\omega}\right)_{x_{0}}-\frac{K}{\rho_{0}}\left(\frac{\rho_{0}}{1+\omega}\right)_{x_{0}}, \quad \hat{\rho}=\frac{\rho_{0}}{1+\omega},\right.  \tag{2.4}\\
\hat{v}\left(x_{0}, 0\right)=v_{0}\left(x_{0}\right) \in H^{1+\alpha}, \quad\left(\rho_{0} \in H^{1+\alpha}\left(0<\bar{\rho}_{0} \leqq \rho_{0} \leqq \overline{\bar{\rho}}_{0}<+\infty ; \rho_{0}^{\prime} \in L_{1}\left(R^{1}\right)\right),\right. \tag{2.5}
\end{gather*}
$$

where we note that $(\hat{v}, \hat{\rho})$ belongs to $H_{T}^{2+\alpha} \times B_{T}^{1+\alpha}$. Hence, $\hat{v}$ is expressed in the following way

$$
\left\{\begin{align*}
\hat{v}\left(x_{0}, t_{0}\right)= & \int_{R^{1}} G\left(x_{0}, t_{0} ; \xi, 0\right) v_{0}(\xi) d \xi  \tag{2.6}\\
& -\int_{0}^{t_{0}} d \tau \int_{R^{1}} G\left(x_{0}, t_{0} ; \xi, \tau\right) \frac{K}{\rho_{0}}\left(\frac{\rho_{0}}{1+\omega}\right)_{\xi} d \xi
\end{align*}\right.
$$

where $G\left(x_{0}, t_{0} ; \xi, \tau\right)$ is the fundamental solution of (2.4) as a linear equation. Moreover, noting that

$$
\begin{equation*}
\left(\frac{\rho_{0}}{1+\omega}\right)_{\xi}=\left(\frac{\rho_{0}}{1+\omega}-\rho_{0}+\rho_{0}\right)_{\xi}=-\left(\frac{\rho_{0} \omega}{1+\omega}\right)_{\xi}+\rho_{0}^{\prime}(\xi) \tag{2.7}
\end{equation*}
$$

we have

$$
\left\{\begin{array}{c}
\int_{0}^{t_{0}} d \tau \int_{R^{1}} G \frac{K}{\rho_{0}}\left(\frac{\rho_{0}}{1+\omega}\right)_{\xi} d \xi=\frac{K}{\mu} \int_{0}^{t_{0}} d \tau \int_{R_{1}^{1}}\left(\frac{\mu}{\rho_{0}} G\right)_{\xi}  \tag{2.8}\\
\times \frac{\rho_{0} \omega}{1+\omega}+d \xi \int_{0}^{t_{0}} d \tau \int_{R^{1}} G \frac{K \rho_{0}^{\prime}}{\rho_{0}} d \xi \equiv I_{1}+I_{2}
\end{array}\right.
$$

As for $I_{1}$, it holds that

$$
\begin{align*}
I_{1}= & -\frac{K}{\mu} \int_{0}^{t_{0}} d \tau \int_{R^{1}} d \xi\left(\frac{\mu}{1+\omega}\left(\frac{G}{\rho_{0}}\right)_{\xi}\right)_{\xi} \\
& \times\left\{\rho_{0}(\xi) \int_{0}^{\tau} \hat{v}\left(\xi, \tau^{\prime}\right) d \tau^{\prime}-\int_{0}^{\tau} d \tau^{\prime} \int_{-\infty}^{\xi} \hat{v}\left(\xi^{\prime}, \tau\right) \rho_{0}^{\prime}\left(\xi^{\prime}\right) d \xi^{\prime}\right\}_{1} \\
& \left(N . B .: \rho_{0} \hat{v}_{\xi}=\left(\rho_{0} \hat{v}-\int_{-\infty}^{\xi} \hat{v} \rho_{0}^{\prime}\left(\xi^{\prime}\right) d \xi^{\prime}\right)_{\xi}\right) \\
= & \frac{K}{\mu} \int_{0}^{t_{0}} d \tau \int_{R^{1}} d \xi \frac{\partial G}{\partial \tau}\{\cdots\}_{1}  \tag{2.9}\\
= & \frac{K}{\mu}\left[\rho_{0}\left(x_{0}\right) \cdot \int_{0}^{t_{0}} \hat{v}\left(x_{0}, \tau\right) d \tau-\int_{0}^{t_{0}} d \tau \int_{-\infty}^{x_{0}} \hat{v}(\xi, \tau) \rho_{0}^{\prime}(\xi) d \xi\right. \\
& \left.-\int_{0}^{t_{0}} d \tau \int_{R^{1}} G\left(x_{0}, t_{0} ; \xi, \tau\right)\left\{\rho_{0}(\xi) \hat{v}(\xi, \tau)-\int_{-\infty}^{\xi} \hat{v}\left(\xi^{\prime}, \tau\right) \rho_{0}^{\prime}\left(\xi^{\prime}\right) d \xi^{\prime}\right\} d \xi\right] .
\end{align*}
$$

Hence, it follows that

$$
\begin{align*}
& |v|_{t_{0}}^{(0)} \leqq\left|v_{0}\right|^{(0)}+K\left|\frac{\rho_{0}^{\prime}}{\rho_{0}}\right|^{(0)} \cdot t_{0} \\
& \quad+\frac{2 K}{\mu}\left(\left|\rho_{0}\right|^{(0)}+\left\|\rho_{0}^{\prime}\right\|_{L_{1}\left(R^{1}\right)}\right) \cdot \int_{0}^{t_{0}}|\hat{v}|_{z}^{(0)} d \tau,\left(t_{0} \in[0, T]\right) \tag{2.10}
\end{align*}
$$

Thus, we have

$$
\begin{align*}
|v|_{t_{0}}^{(0)} & \leqq\left|v_{0}\right|^{(0)} \cdot e^{C_{0} T}+\frac{K}{C_{0}}\left|\frac{\rho_{0}^{\prime}}{\rho_{0}}\right|^{(0)} \cdot\left(e^{C_{0} T}-1\right) \\
& \equiv C_{1}(T)(<+\infty),\left(C_{1}(T) \nearrow \text { as } T \nearrow, C_{0} \equiv \frac{2 K}{\mu}\left(\bar{\rho}_{0}+\left\|\rho_{0}^{\prime}\right\|_{L_{1}\left(R^{1}\right)}\right) .\right. \tag{2.11}
\end{align*}
$$

Taking (2.4) into consideration, we define, for an arbitrary number $a \in R^{1}$,

$$
\begin{equation*}
Y^{a}\left(x_{0}, t_{0}\right) \equiv \int_{a}^{x_{0}} \frac{\rho_{0}}{\mu}\left(v_{0}-\hat{v}\right) d x_{0}^{\prime}-\log \left(1+\omega\left(a, t_{0}\right)\right)+\int_{0}^{t_{0}} \frac{K}{\mu} \frac{\rho_{0}}{1+\omega\left(a, t_{0}^{\prime}\right)} d t_{0}^{\prime} \tag{2.12}
\end{equation*}
$$

$Y^{a}$ satisfies the relation

$$
\left\{\begin{array}{l}
\left(Y^{a}\right)_{t_{0}}=\frac{\mu}{1+\omega}\left(\frac{\left(Y^{a}\right)_{x_{0}}}{\rho_{0}}\right)_{x_{0}}-\frac{v_{0}^{\prime}-k \rho_{0}}{1+\omega}=\frac{-\hat{v}_{x_{0}}+k \rho_{0}}{1+\omega}  \tag{2.13}\\
Y^{a}\left(x_{0}, 0\right)=0, \quad\left(k=\frac{K}{\mu}\right)
\end{array}\right.
$$

$Y^{a}$ satisfies Täcklind's condition. Therefore,

$$
\begin{equation*}
Y^{a}=Y^{a^{\prime}} \equiv Y \quad\left(\text { for any } a \text { and } a^{\prime} \in R^{1}\right) \tag{2.14}
\end{equation*}
$$

Here, we note that, for an arbitrary $a \in R^{1}$,

$$
\begin{equation*}
Y\left(x_{0}, t_{0}\right)=Y^{a}\left(a, t_{0}\right)+\int_{a}^{x_{0}} \frac{\rho_{0}}{\mu}\left(v_{0}-\hat{v}\right) d x_{0}^{\prime} \tag{2.15}
\end{equation*}
$$

From (2.13) follows the relation

$$
\left\{\begin{array}{l}
(1+\omega)_{t_{0}}+(1+\omega) Y_{t_{0}}=k \rho_{0}  \tag{2.16}\\
(1+\omega)\left(x_{0}, 0\right)=1
\end{array}\right.
$$

Hence, we have

$$
\begin{equation*}
(1+\omega)\left(x_{0}, t_{0}\right)=e^{-Y\left(x_{0}, t_{0}\right)}\left\{1+k \rho_{0}\left(x_{0}\right) \cdot \int_{0}^{t_{0}} e^{Y\left(x_{0}, \tau\right)} d \tau\right\} \tag{2.17}
\end{equation*}
$$

Thus, for an arbitrary and fixed $a \notin R^{1}$,

$$
\begin{align*}
e^{Y\left(a, t_{0}\right)} \cdot & \left(1+\omega\left(x_{0}, t_{0}\right)\right)=\exp \left\{-\int_{a}^{x_{0}} \frac{\rho_{0}}{\mu}\left(v_{0}-v\right) d x_{0}^{\prime}\right\} \\
& \times\left[1+k \rho_{0}\left(x_{0}\right) \cdot \int_{0}^{t_{0}} d t_{0}^{\prime} e^{Y\left(a, t_{0}^{\prime}\right)}\right.  \tag{2.18}\\
& \left.\times \exp \left\{\int_{a}^{x_{0}} \frac{\rho_{0}}{\mu}\left(v_{0}\left(x_{0}^{\prime}\right)-\hat{v}\left(x_{0}^{\prime}, t_{0}^{\prime}\right)\right) d x_{0}^{\prime}\right\}\right]_{A}, \quad\left(0 \leqq t_{0} \leqq T\right)
\end{align*}
$$

Therefore, by integrating in $x_{0}$ both sides of (2.18) over a closed interval $[a, a+l]$ $(l>0)$ we have

$$
\begin{align*}
& (0<) e^{Y\left(a, t_{0}\right)} \cdot\left\{l+\int_{0}^{t_{0}}(\hat{v}(a+l, \tau)-\hat{v}(a, \tau)) d \tau\right\} \\
& \quad=\int_{a}^{a+0} d x_{0} \exp \left\{-\int_{a}^{x_{0}} \frac{\rho_{0}}{\rho}\left(v_{0}-\hat{v}\right) d x_{0}^{\prime}\right\} \times[\cdots]_{A} \tag{2.19}
\end{align*}
$$

Take $l=1+2 C_{1}(T) T \equiv L(T)$. Then, we obtain an inequality

$$
\begin{align*}
e^{Y\left(a, t_{0}\right)} & \leqq L(T) \exp \left\{\frac{\overline{\bar{\rho}}_{0} L(T)}{\mu}\left(\left|v_{0}\right|^{(0)}+C_{1}(T)\right)\right\} \\
\times & {\left[1+k \overline{\bar{\rho}}_{0} \cdot \exp \left\{\frac{\overline{\bar{\rho}}_{0} L(T)}{\mu}\left(\left|v_{0}\right|^{(0)}+C_{1}(T)\right)\right\} \cdot \int_{0}^{t_{0}} e^{Y\left(a, t_{0}^{\prime}\right)} d t_{0}^{\prime}\right], \quad\left(0 \leqq t_{0} \leqq T\right) } \tag{2.20}
\end{align*}
$$

Thus, for an arbitrary $a \in R^{1}$, we have

$$
\begin{align*}
\left(1+\omega\left(a, t_{0}\right)\right)^{-1} & =e^{Y\left(a, t_{0}\right)}\left(1+k \rho_{0}(a) \cdot \int_{0}^{t_{0}} e^{Y(a, \tau)} d \tau\right)^{-1}  \tag{2.21}\\
& \leqq e^{Y\left(a, t_{0}\right)} \leqq C_{2}(T)(<+\infty), \quad\left(C_{2}(T) \nearrow \text { as } T \nearrow\right) .
\end{align*}
$$

Next, seeing that, by (2.13), the following equality holds

$$
\left\{\begin{array}{l}
Y\left(x_{0}, t_{0}\right)=\int_{0}^{t_{0}} d \tau \int_{R^{1}} \bar{G}\left(x_{0}, t_{0} ; \xi, \tau\right) \frac{k \rho_{0}-v_{0}^{\prime}}{1+\omega} d \xi  \tag{2.22}\\
(\bar{G} \text { is the fundamental solution of (2.13) as a linear equation) }
\end{array}\right.
$$

we have

$$
\begin{equation*}
|Y|_{t_{0}}^{(0)} \leqq\left(k \overline{\bar{\rho}}_{0}+\left|v_{0}^{\prime}\right|^{(0)}\right) t_{0} \cdot\left|\frac{1}{1+\omega}\right|_{t_{0}}^{(0)} . \tag{2.23}
\end{equation*}
$$

Thus, it holds that

$$
\begin{align*}
(1+\omega) & \leqq \exp \left(|Y|_{\iota_{0}}^{(0)}\right) \cdot\left(1+k \bar{\rho}_{0} t_{0} \cdot \exp \left(|Y|_{t_{0}^{(0)}}^{(0)}\right)\right)  \tag{2.24}\\
& \leqq C_{3}(T)(<+\infty), \quad\left(C_{3}(T) / \text { as } T \nearrow\right)
\end{align*}
$$

By the discussion made above, we obtain:
Theorem 3. There exists a unique temporally global solution $(v, \rho)$ of (2.1)-(2.2) such that it belongs to $H_{T}^{2+\alpha} \times B_{T}^{1+\alpha}$ for any $T \in(0,+\infty)$.

Finally, we add that Kazhikhov and Shelukhin ([9]) have recently obtained a good result contributing to the study of our related problems.

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