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## A TEST FOR EQUALITY OF MEANS WHEN COVARIANCE MATRICES ARE UNEQUAL<sup>1</sup>

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Let  $x_\alpha^{(g)}$  be an observation from the  $p$ -variate normal distribution  $N(\mu^{(g)}, \Sigma_g)$ ,  $\alpha = 1, \dots, N_g$ ,  $g = 1, \dots, q$ . Consider testing the null hypothesis<sup>2</sup>

$$(1) \quad H: \mu^{(1)} = \dots = \mu^{(q)}.$$

When the covariance matrices  $\Sigma_g$  are equal, the hypothesis is a form of the so-called general linear hypothesis, and a number of tests are available. (See Chapter 8 of Anderson (1958), for example.) When  $q = 2$ , Bennett (1951) has extended the procedure of Scheffé (1943) to give an exact test based on Hotelling's generalized  $T^2$ . (See Section 5.6 of Anderson (1958).) In this note we extend previous procedures to  $q > 2$ .

As an example, let  $q = 3$  and  $N_1 = N_2 = N_3 = N$ , say. Let

$$(2) \quad \begin{aligned} y_\alpha &= a_1 x_\alpha^{(1)} + a_2 x_\alpha^{(2)} + a_3 x_\alpha^{(3)}, \\ z_\alpha &= b_1 x_\alpha^{(1)} + b_2 x_\alpha^{(2)} + b_3 x_\alpha^{(3)}, \end{aligned}$$

where  $\sum_{g=1}^3 a_g = 0$ ,  $\sum_{g=1}^3 b_g = 0$  and  $(a_1, a_2, a_3)$  and  $(b_1, b_2, b_3)$  are linearly independent. (In practice the indexing of the observations in each sample would be done randomly.) Then the hypothesis (1) is equivalent to the hypothesis

$$(3) \quad \varepsilon y_\alpha = \sum_{g=1}^3 a_g \mu^{(g)} = 0, \quad \varepsilon z_\alpha = \sum_{g=1}^3 b_g \mu^{(g)} = 0.$$

The covariance matrix of  $(y'_\alpha \quad z'_\alpha)$  is

$$(4) \quad \begin{pmatrix} a_1^2 \Sigma_1 + a_2^2 \Sigma_2 + a_3^2 \Sigma_3 & a_1 b_1 \Sigma_1 + a_2 b_2 \Sigma_2 + a_3 b_3 \Sigma_3 \\ a_1 b_1 \Sigma_1 + a_2 b_2 \Sigma_2 + a_3 b_3 \Sigma_3 & b_1^2 \Sigma_1 + b_2^2 \Sigma_2 + b_3^2 \Sigma_3 \end{pmatrix}.$$

The hypothesis (3) can be tested by a  $T^2$ -statistic

$$(5) \quad T^2 = N(\bar{y}' \quad \bar{z}') S^{-1} \begin{pmatrix} \bar{y} \\ \bar{z} \end{pmatrix},$$

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where

$$(6) \quad S = \frac{1}{N-1} \sum_{\alpha=1}^N \begin{pmatrix} y_{\alpha} - \bar{y} \\ z_{\alpha} - \bar{z} \end{pmatrix} \begin{pmatrix} y_{\alpha} - \bar{y} \\ z_{\alpha} - \bar{z} \end{pmatrix}'$$

and  $\bar{y}$  and  $\bar{z}$  are the sample mean vectors. When the null hypothesis is true,  $(N-2p)T^2/(N-1)2p$  has the  $F$ -distribution with  $2p$  and  $N-2p$  degrees of freedom.

It does not matter what linear combinations (2) are used for the test because the  $T^2$ -statistic is invariant with regard to linear transformations; indeed, the linear combinations may be chosen as some contrasts of special interest. The fact that the test is based on a sample covariance matrix  $S$  with only  $N-1$  degrees of freedom is a characteristic also of the case  $q=2$ , for which Scheffé (1943) showed that this was the maximum number of degrees of freedom for a  $t$ -test when  $p=1$ . Here  $N$  must be greater than  $2p$ . This extension to  $q=3$  neglects the fact that the off-diagonal submatrices in (4) are symmetric; if such symmetry is imposed on the estimate of (4), the resulting test criterion will not be  $T^2$  and may not have a distribution simply related to the  $F$ -distribution.

For any  $q > 3$  with equal  $N_{\theta}$  (2) may be replaced by any  $q-1$  linearly independent linear combinations, the coefficients of each summing to 0,

$$(7) \quad y_{\alpha}^{(i)} = \sum_{\theta=1}^q a_{\theta}^{(i)} x_{\alpha}^{(\theta)}, \quad i = 1, \dots, q-1, \quad \alpha = 1, \dots, N.$$

A  $T^2$ -statistic may be constructed from the resulting  $N$  vectors of  $(q-1)p$  components. If not all  $N_{\theta}$  are equal, suppose  $N_1$  to be the smallest; define

$$(8) \quad y_{\alpha}^{(i)} = a_1^{(i)} x_{\alpha}^{(1)} + \sum_{\theta=2}^q a_{\theta}^{(i)} (N_1/N_{\theta})^{\frac{1}{2}} \cdot \left[ x_{\alpha}^{(\theta)} - (1/N_1) \sum_{\beta=1}^{N_1} x_{\beta}^{(\theta)} + (N_1 N_{\theta})^{-\frac{1}{2}} \sum_{\beta=1}^{N_{\theta}} x_{\beta}^{(\theta)} \right], \quad \alpha = 1, \dots, N_1.$$

Then

$$(9) \quad \bar{y}^{(i)} = \sum_{\alpha=1}^N a_{\theta}^{(i)} \bar{x}^{(\theta)},$$

and the sample covariance matrix is computed from  $y_{\alpha}^{(i)}$ . (See Section 5.6 of Anderson (1958) for details.)

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