

Achievement of continuity of (φ, ψ) -derivations without linearity

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Abstract

Suppose that \mathfrak{A} is a C^* -algebra acting on a Hilbert space \mathfrak{H} , and φ, ψ are mappings from \mathfrak{A} into $B(\mathfrak{H})$ which are not assumed to be necessarily linear or continuous. A (φ, ψ) -derivation is a linear mapping $d : \mathfrak{A} \rightarrow B(\mathfrak{H})$ such that

$$d(ab) = \varphi(a)d(b) + d(a)\psi(b) \quad (a, b \in \mathfrak{A}).$$

We prove that if φ is a multiplicative (not necessarily linear) $*$ -mapping, then every $*$ - (φ, φ) -derivation is automatically continuous. Using this fact, we show that every $*$ - (φ, ψ) -derivation d from \mathfrak{A} into $B(\mathfrak{H})$ is continuous if and only if the $*$ -mappings φ and ψ are left and right d -continuous, respectively.

1 Introduction

Recently, a number of analysts [2, 4, 12, 13, 14] have studied various generalized notions of derivations in the context of Banach algebras. There are some applications in the other fields of research [7]. Such mappings have been extensively studied in pure algebra; cf. [1, 3, 9]. A generalized concept of derivation is as follows.

Definition 1.1. Suppose that \mathfrak{B} is an algebra, \mathfrak{A} is a subalgebra of \mathfrak{B} , \mathfrak{X} is a \mathfrak{B} -bimodule, and $\varphi, \psi : \mathfrak{A} \rightarrow \mathfrak{B}$ are mappings. A linear mapping $d : \mathfrak{A} \rightarrow \mathfrak{X}$ is a (φ, ψ) -derivation if

$$d(ab) = \varphi(a)d(b) + d(a)\psi(b) \quad (a, b \in \mathfrak{A}).$$

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By a φ -derivation we mean a (φ, φ) -derivation. Note that we do not have any extra assumptions such as linearity or continuity on the mappings φ and ψ .

The automatic continuity theory is the study of (algebraic) conditions on a category, e.g. C^* -algebras, which guarantee that every mapping belonging to a certain class, e.g. derivations, is continuous. S. Sakai [16] proved that every derivation on a C^* -algebra is automatically continuous. This is an affirmative answer to the conjecture made by I. Kaplansky [11]. J. R. Ringrose [15] extended this result for derivations from a C^* -algebra \mathfrak{A} to a Banach \mathfrak{A} -bimodule \mathfrak{X} . B. E. Johnson and A. M. Sinclair [10] proved that every derivation on a semisimple Banach algebra is automatically continuous. Automatic continuity of module derivations on JB^* -algebras have been studied in [8]. The reader may find a collection of results concerning these subjects in [6, 17, 18].

M. Brešar and A. R. Villena [4] proved that for an inner automorphism φ , every (id, φ) -derivation on a semisimple Banach algebra is continuous, where id denotes the identity mapping. In [12], it is shown that every (φ, ψ) -derivation from a C^* -algebra \mathfrak{A} acting on a Hilbert space \mathfrak{H} into $B(\mathfrak{H})$ is automatically continuous, if φ and ψ are continuous $*$ -linear mappings from \mathfrak{A} into $B(\mathfrak{H})$.

This paper consists of five sections. We define the notion of a (φ, ψ) -derivation in the first section and give some examples in the second. In the third section, by using methods of [12], we prove that if φ is a multiplicative (not necessarily linear) $*$ -mapping from a C^* -algebra \mathfrak{A} acting on a Hilbert space \mathfrak{H} into $B(\mathfrak{H})$, then every $*$ - φ -derivation $d : \mathfrak{A} \rightarrow B(\mathfrak{H})$ is automatically continuous. In the fourth section, we show that for not necessarily linear or continuous $*$ -mappings $\varphi, \psi : \mathfrak{A} \rightarrow B(\mathfrak{H})$ the continuity of a $*$ - (φ, ψ) -derivation $d : \mathfrak{A} \rightarrow B(\mathfrak{H})$ is equivalent to the left d -continuity of φ and the right d -continuity of ψ . The mapping φ (resp. ψ) is called left (resp. right) d -continuous if $\lim_{x \rightarrow 0} (\varphi(x)d(b)) = 0$, for all $b \in \mathfrak{A}$ (resp. $\lim_{x \rightarrow 0} (d(b)\psi(x)) = 0$, for all $b \in \mathfrak{A}$). Obviously these conditions happen whenever $\lim_{x \rightarrow 0} \varphi(x) = 0 = \lim_{x \rightarrow 0} \psi(x)$, in particular whenever φ and ψ are bounded linear mappings. Thus we extend the main results of [12] to a general framework. Furthermore, we prove that if d is a continuous $*$ - (φ, ψ) -derivation, then we can replace φ and ψ with mappings with ‘at most’ zero separating spaces. The last section is devoted to study the continuity of the so-called generalized $*$ - (φ, ψ) -derivations from \mathfrak{A} into $B(\mathfrak{H})$.

The reader is referred to [6] for undefined notation and terminology.

2 Examples

In this section, let \mathfrak{B} be an algebra, let \mathfrak{A} be a subalgebra of \mathfrak{B} , and let \mathfrak{X} be a \mathfrak{B} -bimodule. The following are some examples concerning Definition 1.1.

Example 2.1. Every ordinary derivation $d : \mathfrak{A} \rightarrow \mathfrak{X}$ is an id -derivation, where $id : \mathfrak{A} \rightarrow \mathfrak{A}$ is the identity mapping.

Example 2.2. Every homomorphism $\rho : \mathfrak{A} \rightarrow \mathfrak{A}$ is a $(\frac{\rho}{2}, \frac{\rho}{2})$ -derivation.

Example 2.3. Let $\varphi, \psi : \mathfrak{A} \rightarrow \mathfrak{A}$ be homomorphisms, and let $x \in \mathfrak{X}$ be a fixed element. Then the linear mapping $d_x : \mathfrak{A} \rightarrow \mathfrak{X}$ defined by

$$d_x(a) := \varphi(a)x - x\psi(a) \quad (a \in \mathfrak{A}),$$

is a (φ, ψ) -derivation, which is called the inner (φ, ψ) -derivation corresponding to x .

Example 2.4. Assume that $\gamma, \theta : \mathcal{C}[0, 2] \rightarrow \mathcal{C}[0, 2]$ are arbitrary mappings, where $\mathcal{C}[0, 2]$ denotes the C^* -algebra of all continuous complex valued functions on $[0, 2]$. Take $\lambda \in \mathbb{C}$ and fixed elements f_1, f_2 , and h_0 in $\mathcal{C}[0, 2]$ such that

$$f_1 h_0 = 0 = f_2 h_0.$$

For example, let us take

$$\begin{aligned} h_0(t) &:= (1-t)\chi_{[0,1]}(t), \\ f_1(t) &:= (t-1)\chi_{[1,2]}(t), \\ f_2(t) &:= \left(t - \frac{3}{2}\right)\chi_{[\frac{3}{2},2]}(t), \end{aligned}$$

where χ_E denotes the characteristic function of E . Define $\varphi, \psi, d : \mathcal{C}[0, 2] \rightarrow \mathcal{C}[0, 2]$ by

$$\begin{aligned} \varphi(f) &:= \lambda f + \gamma(f)f_1, \\ \psi(f) &:= (1-\lambda)f + \theta(f)f_2, \\ d(f) &:= fh_0. \end{aligned}$$

Then d is a (φ, ψ) -derivation, since

$$\begin{aligned} \varphi(f)d(g) + d(f)\psi(g) &= (\lambda f + \gamma(f)f_1)(gh_0) + (fh_0)((1-\lambda)g + \theta(f)f_2) \\ &= \lambda fgh_0 + \gamma(f)gf_1h_0 + (1-\lambda)fgh_0 + \theta(f)fh_0f_2 \\ &= fgh_0 \\ &= d(fg). \end{aligned}$$

Moreover, we may choose γ and θ such that φ and ψ are neither linear nor continuous.

3 Multiplicative mappings

In this section, we are going to show how a multiplicative property gives us the linearity. We start our work with some elementary properties of (φ, ψ) -derivations.

Lemma 3.1. *Let \mathfrak{B} be an algebra, let \mathfrak{A} be a subalgebra of \mathfrak{B} , and let \mathfrak{X} be a \mathfrak{B} -bimodule. If $d : \mathfrak{A} \rightarrow \mathfrak{X}$ is a (φ, ψ) -derivation, then*

- (i) $(\varphi(ab) - \varphi(a)\varphi(b))d(c) = d(a)(\psi(bc) - \psi(b)\psi(c));$
 - (ii) $(\varphi(a+b) - \varphi(a) - \varphi(b))d(c) = 0 = d(a)(\psi(b+c) - \psi(b) - \psi(c));$
 - (iii) $(\varphi(\lambda a) - \lambda\varphi(a))d(b) = 0 = d(a)(\psi(\lambda b) - \lambda(\psi(b)));$
- for all $a, b, c \in \mathfrak{A}$, and all $\lambda \in \mathbb{C}$.

Proof. Let $a, b, c \in \mathfrak{A}$ and $\lambda \in \mathbb{C}$. For the first equation we have

$$\begin{aligned} 0 &= d((ab)c) - d(a(bc)) \\ &= \varphi(ab)d(c) + d(ab)\psi(c) - \varphi(a)d(bc) - d(a)\psi(bc) \\ &= \varphi(ab)d(c) + (\varphi(a)d(b) + d(a)\psi(b))\psi(c) \\ &\quad - \varphi(a)(\varphi(b)d(c) + d(b)\psi(c)) - d(a)\psi(bc) \\ &= (\varphi(ab) - \varphi(a)\varphi(b))d(c) - d(a)(\psi(bc) - \psi(b)\psi(c)). \end{aligned}$$

Calculating $d((a+b)c) - d(bc) - d(ac)$ and $d(a(\lambda b)) - \lambda d(ab)$, we obtain the other equations. ■

We also need the following lemma. Recall that, for a Hilbert space \mathfrak{H} , a subset Y of $B(\mathfrak{H})$ is said to be self-adjoint if $u^* \in Y$ for each $u \in Y$.

Lemma 3.2. *Let \mathfrak{H} be a Hilbert space, and let Y be a self-adjoint subset of $B(\mathfrak{H})$. Assume that $\mathfrak{L}_0 = \bigcup_{u \in Y} u(\mathfrak{H})$, and \mathfrak{L} is the closed linear span of \mathfrak{L}_0 . If $\mathfrak{K} = \mathfrak{L}^\perp$, then*

$$\mathfrak{K} = \bigcap_{u \in Y} \ker(u).$$

Proof. Let $k \in \mathfrak{K}$. Then $\langle \ell, k \rangle = 0$, for all $\ell \in \mathfrak{L}$. Since Y is self-adjoint,

$$\langle u(k), h \rangle = \langle k, u^*(h) \rangle = 0$$

for all $h \in \mathfrak{H}$ and all $u \in Y$. Therefore $u(k) = 0$, for all $u \in Y$. Hence $\mathfrak{K} \subseteq \bigcap_{u \in Y} \ker(u)$.

The inverse inclusion can be proved similarly. ■

Recall that a mapping $f : \mathfrak{A} \rightarrow B(\mathfrak{H})$ is called a $*$ -mapping, if $f(a^*) = f(a)^*$, for all $a \in \mathfrak{A}$. If we define $f^* : \mathfrak{A} \rightarrow B(\mathfrak{H})$, by $f^*(a) := (f(a^*))^*$, then f is a $*$ -mapping if and only if $f^* = f$.

Theorem 3.3. *Suppose that \mathfrak{A} is a C^* -algebra acting on a Hilbert space \mathfrak{H} . Let $\varphi : \mathfrak{A} \rightarrow B(\mathfrak{H})$ be a $*$ -mapping and let $d : \mathfrak{A} \rightarrow B(\mathfrak{H})$ be a $*$ - φ -derivation. If φ is multiplicative, i.e. $\varphi(ab) = \varphi(a)\varphi(b)$ ($a, b \in \mathfrak{A}$), then d is continuous.*

Proof. Set

$$Y := \{\varphi(\lambda b) - \lambda\varphi(b) \mid \lambda \in \mathbb{C}, b \in \mathfrak{A}\} \cup \{\varphi(b+c) - \varphi(b) - \varphi(c) \mid b, c \in \mathfrak{A}\}.$$

Since φ is a $*$ -mapping, Y is a self-adjoint subset of $B(\mathfrak{H})$. Put

$$\mathfrak{L}_0 := \bigcup \{u(h) \mid u \in Y, h \in \mathfrak{H}\}.$$

Let \mathfrak{L} be the closed linear span of \mathfrak{L}_0 , and let $\mathfrak{K} := \mathfrak{L}^\perp$. Then $\mathfrak{H} = \mathfrak{K} \oplus \mathfrak{L}$, and by Lemma 3.2, we get

$$\mathfrak{K} = \bigcap \{\ker(u) \mid u \in Y\}. \quad (3.1)$$

Suppose that $p \in B(\mathfrak{H})$ is the orthogonal projection of \mathfrak{H} onto \mathfrak{K} , then by (3.1) we have

$$\varphi(\lambda b)p = \lambda\varphi(b)p, \quad (3.2)$$

$$\varphi(b+c)p = \varphi(b)p + \varphi(c)p, \quad (3.3)$$

for all $b, c \in \mathfrak{A}$, and all $\lambda \in \mathbb{C}$. Now we claim that

$$p\varphi(a) = \varphi(a)p, \quad p d(a) = d(a) = d(a)p \quad (a \in \mathfrak{A}). \quad (3.4)$$

To show this, note that by Lemma 3.1, we have

$$\begin{aligned} d(a)(\varphi(\lambda b) - \lambda\varphi(b)) &= 0, \\ d(a)(\varphi(b+c) - \varphi(b) - \varphi(c)) &= 0, \end{aligned}$$

for all $a, b, c \in \mathfrak{A}$, and all $\lambda \in \mathbb{C}$. Thus $d(a)\mathfrak{L} = 0$, and so $d(a)(1-p) = 0$, for all $a \in \mathfrak{A}$. Since d is a $*$ -mapping, it follows that $pd(a) = d(a) = d(a)p$, for all $a \in \mathfrak{A}$. Similarly, since φ is multiplicative, we deduce from (3.2) and (3.3) that

$$\begin{aligned} (\varphi(\lambda b) - \lambda\varphi(b))\varphi(a)p &= \varphi(\lambda b)\varphi(a)p - \lambda\varphi(b)\varphi(a)p \\ &= \lambda\varphi(ba)p - \lambda\varphi(ba)p \\ &= 0, \end{aligned}$$

and

$$\begin{aligned} (\varphi(b+c) - \varphi(b) - \varphi(c))\varphi(a)p &= \varphi(b+c)\varphi(a)p - \varphi(b)\varphi(a)p - \varphi(c)\varphi(a)p \\ &= \varphi((b+c)a)p - \varphi(ba)p - \varphi(ca)p \\ &= 0, \end{aligned}$$

for all $a, b, c \in \mathfrak{A}$, and all $\lambda \in \mathbb{C}$. Therefore $\varphi(a)(\mathfrak{K}) \subseteq \mathfrak{K}$. Since φ is a $*$ -mapping, we conclude that $p\varphi(a) = \varphi(a)p$, for all $a \in \mathfrak{A}$. Now define the mapping $\Phi : \mathfrak{A} \rightarrow B(\mathfrak{H})$ by $\Phi(a) = \varphi(a)p$. One can easily see that Φ is a $*$ -homomorphism, and so it is automatically continuous. Using (3.4), we obtain

$$\begin{aligned} d(ab) &= d(ab)p \\ &= \varphi(a)d(b)p + d(a)\varphi(b)p \\ &= \varphi(a)pd(b) + d(a)\varphi(b)p \\ &= \Phi(a)d(b) + d(a)\Phi(b) \quad (a, b \in \mathfrak{A}). \end{aligned}$$

Hence d is a Φ -derivation. We deduce from Theorem 3.7 of [12] that d is continuous. ■

4 d -continuity

We start this section with the following definition.

Definition 4.1. Suppose that \mathfrak{A} and \mathfrak{B} are two normed algebras, and $T, S : \mathfrak{A} \rightarrow \mathfrak{B}$ are two mappings.

(i) The mapping T is *left (resp. right) S -continuous* if $\lim_{x \rightarrow 0} (T(x)S(b)) = 0$, for all $b \in \mathfrak{A}$ (resp. $\lim_{x \rightarrow 0} (S(b)T(x)) = 0$, for all $b \in \mathfrak{A}$). If T is both left and right S -continuous, then it is simply called S -continuous.

(ii) As for linear mappings, the *separating space* of a mapping T is defined to be

$$\mathfrak{S}(T) := \{b \in \mathfrak{B} \mid \exists \{a_n\} \subseteq \mathfrak{A}, a_n \rightarrow 0, T(a_n) \rightarrow b\}.$$

We notice that for a nonlinear mapping T , this set is not necessarily a linear subspace and it may even be empty. Recall that if \mathfrak{A} and \mathfrak{B} are complete spaces and T is linear, then the closed graph theorem implies that T is continuous if and only if $\mathfrak{S}(T) = \{0\}$.

In Example 2.4, if we consider γ and θ to be $*$ -mappings, then the continuity of d together with Corollary 4.5 below imply that φ and ψ are d -continuous mappings.

Lemma 4.2. *Let \mathfrak{A} be a normed algebra, let \mathfrak{X} be a normed \mathfrak{A} -bimodule, and let $d : \mathfrak{A} \rightarrow \mathfrak{X}$ be a (φ, ψ) -derivation for two mappings $\varphi, \psi : \mathfrak{A} \rightarrow \mathfrak{A}$. If φ and ψ are left and right d -continuous mappings, respectively, then*

$$a(\psi(bc) - \psi(b)\psi(c)) = 0 = (\varphi(bc) - \varphi(b)\varphi(c))a,$$

for all $b, c \in \mathfrak{A}$ and all $a \in \mathfrak{S}(d)$.

Proof. Suppose that $a \in \mathfrak{S}(d)$. Then $a = \lim_{n \rightarrow \infty} d(a_n)$ for some sequence $\{a_n\}$ converging to zero in \mathfrak{A} . By Lemma 3.1 (i), we have

$$\begin{aligned} a(\psi(bc) - \psi(b)\psi(c)) &= \lim_{n \rightarrow \infty} d(a_n)(\psi(bc) - \psi(b)\psi(c)) \\ &= \lim_{n \rightarrow \infty} (\varphi(a_n b) - \varphi(a_n)\varphi(b))d(c) \\ &= \lim_{n \rightarrow \infty} \varphi(a_n b)d(c) \\ &\quad - \lim_{n \rightarrow \infty} \varphi(a_n)d(bc) + \lim_{n \rightarrow \infty} \varphi(a_n)d(b)\psi(c) \\ &= 0 \quad (b, c \in \mathfrak{A}), \end{aligned}$$

since φ is left d -continuous. ■

In the rest of this section, we assume that \mathfrak{A} is a C^* -subalgebra of $B(\mathfrak{H})$, the C^* -algebra of all bounded linear operators on a Hilbert space \mathfrak{H} . Also φ, ψ , and d are mappings from \mathfrak{A} into $B(\mathfrak{H})$. Removing the assumption ‘linearity’ and weakening the assumption ‘continuity’ on φ and ψ , we extend the main result of [12] as follows.

Theorem 4.3. *Let φ be a $*$ -mapping and let d be a $*$ - φ -derivation. If φ is left d -continuous, then d is continuous. Conversely, if d is continuous then φ is left d -continuous.*

Proof. Set

$$Y := \{\varphi(bc) - \varphi(b)\varphi(c) \mid b, c \in \mathfrak{A}\}.$$

Since φ is a $*$ -mapping, Y is a self-adjoint subset of $B(\mathfrak{H})$. Put

$$\mathfrak{L}_0 := \bigcup \{u(h) \mid u \in Y, h \in \mathfrak{H}\}.$$

Let \mathfrak{L} be the closed linear span of \mathfrak{L}_0 , and let $\mathfrak{K} := \mathfrak{L}^\perp$. Then $\mathfrak{H} = \mathfrak{K} \oplus \mathfrak{L}$, and by Lemma 3.2, we have

$$\mathfrak{K} = \bigcap \{\ker(u) \mid u \in Y\}. \tag{4.1}$$

Suppose that $p \in B(\mathfrak{H})$ is the orthogonal projection of \mathfrak{H} onto \mathfrak{K} , then by (4.1), we have

$$\varphi(bc)p = \varphi(b)\varphi(c)p, \tag{4.2}$$

for all $b, c \in \mathfrak{A}$. We claim that

$$p\varphi(a) = \varphi(a)p, \quad pd(a) = d(a)p \quad (a \in \mathfrak{A}). \quad (4.3)$$

To prove this, note that by Lemma 3.1 and (4.2), we have

$$(\varphi(bc) - \varphi(b)\varphi(c))d(a)p = d(b)(\varphi(ca) - \varphi(c)\varphi(a))p = 0,$$

for all $a, b, c \in \mathfrak{A}$. Thus $ud(a)p = 0$, for all $a \in \mathfrak{A}$, and all $u \in Y$. So

$$ud(a)(\mathfrak{K}) = ud(a)p(\mathfrak{H}) = \{0\}.$$

This means that $d(a)(\mathfrak{K})$ is contained in the kernel of each u in Y . So by (4.1), $d(a)(\mathfrak{K}) \subseteq \mathfrak{K}$. Since d is a $*$ -mapping, it follows that $pd(a) = d(a)p$. Similarly, using (4.2), we get

$$\begin{aligned} (\varphi(bc) - \varphi(b)\varphi(c))\varphi(a)p &= \varphi(bc)\varphi(a)p - \varphi(b)\varphi(c)\varphi(a)p \\ &= \varphi(bca)p - \varphi(bca)p \\ &= 0 \quad (a, b, c \in \mathfrak{A}). \end{aligned}$$

Therefore $\varphi(a)(\mathfrak{K}) = \varphi(a)p(\mathfrak{H}) \subseteq \mathfrak{K}$. Since φ is a $*$ -mapping we conclude that $p\varphi(a) = \varphi(a)p$, for all $a \in \mathfrak{A}$. Now define the mappings $\Phi, D : \mathfrak{A} \rightarrow B(\mathfrak{H})$ by $\Phi(a) := \varphi(a)p$, and $D(a) := d(a)p$. We show that Φ is a multiplicative $*$ -mapping and D is a $*$ - Φ -derivation. Clearly (4.2) implies that Φ is multiplicative, and by (4.3) we have

$$(\Phi(a))^* = (\varphi(a)p)^* = p^*(\varphi(a))^* = p\varphi(a^*) = \Phi(a^*) \quad (a \in \mathfrak{A}).$$

Thus Φ is a multiplicative $*$ -mapping. Now for $a, b \in \mathfrak{A}$,

$$\begin{aligned} D(ab) &= d(ab)p \\ &= \varphi(a)d(b)p + d(a)\varphi(b)p \\ &= \varphi(a)pd(b)p + d(a)p\varphi(b)p \\ &= \Phi(a)D(b) + D(a)\Phi(b). \end{aligned}$$

Thus D is a $*$ - Φ -derivation, and it is continuous by Theorem 3.3. Now, we show that $\mathfrak{S}(d) = \{0\}$. Let $a \in \mathfrak{S}(d)$, then there exists a sequence $\{a_n\}$ converging to 0 in \mathfrak{A} such that $d(a_n) \rightarrow a$ as $n \rightarrow \infty$. Take $h = k + \ell \in \mathfrak{K} \oplus \mathfrak{L} = \mathfrak{H}$. By Lemma 4.2, and by the fact that each $a \in \mathfrak{S}(d)$ is a bounded operator on \mathfrak{H} , and that $\ell \in \mathfrak{L}$ is in the closed linear span of elements of the form $(\varphi(bc) - \varphi(b)\varphi(c))h$, where $b, c \in \mathfrak{A}, h \in \mathfrak{H}$, we have $a(\ell) = 0$. It follows from continuity of D that

$$a(k) = a(p(h)) = \lim_{n \rightarrow \infty} d(a_n)(p(h)) = \lim_{n \rightarrow \infty} D(a_n)(h) = 0.$$

Thus $a(h) = a(k) + a(\ell) = 0$, and so d is continuous.

Conversely, let d be a continuous φ -derivation. Then

$$\lim_{x \rightarrow 0} \varphi(x)d(b) = \lim_{x \rightarrow 0} d(xb) - \lim_{x \rightarrow 0} d(x)\varphi(b) = 0 \quad (b \in \mathfrak{A}). \quad \blacksquare$$

Theorem 4.4. *Every φ -derivation d is automatically continuous, provided that φ is d -continuous, and at least one of φ or d is a $*$ -mapping.*

Proof. Let $d : \mathfrak{A} \rightarrow B(\mathfrak{H})$ be a φ -derivation. Then clearly d^* is a φ^* -derivation. Set

$$\varphi_1 := \frac{1}{2}(\varphi + \varphi^*), \quad \varphi_2 := \frac{1}{2\mathbf{i}}(\varphi - \varphi^*), \quad d_1 := \frac{1}{2}(d + d^*), \quad d_2 := \frac{1}{2\mathbf{i}}(d - d^*).$$

Obviously these are $*$ -mappings, $\varphi = \varphi_1 + \mathbf{i}\varphi_2$, $d = d_1 + \mathbf{i}d_2$, and φ_k is d_j -continuous for $1 \leq k, j \leq 2$. A straightforward calculation shows that if φ is a $*$ -mapping then $\varphi_1 = \varphi = \varphi_2$, and d_1, d_2 are φ -derivations. Similarly, if d is a $*$ -mapping, then $d_1 = d = d_2$ and d is a φ_j -derivation for $j = 1, 2$. Since φ or d is a $*$ -mapping, then φ_k is a $*$ -mapping and d_j is a $*$ - φ_k -derivation for $1 \leq k, j \leq 2$. By Theorem 4.3, the d_j 's are continuous, and so $d = d_1 + \mathbf{i}d_2$ is also continuous. ■

Corollary 4.5. *Let φ and ψ be $*$ -mappings and let d be a $*$ - (φ, ψ) -derivation. Then d is automatically continuous if and only if φ and ψ are left and right d -continuous, respectively.*

Proof. Suppose that φ and ψ are left and right d -continuous, respectively. Since d, φ , and ψ are $*$ -mappings, then both φ and ψ are d -continuous. Hence $\frac{\varphi+\psi}{2}$ is also d -continuous. We have

$$\begin{aligned} 2d(ab) &= d(ab) + d^*(ab) \\ &= \varphi(a)d(b) + d(a)\psi(b) + \left(\varphi(b^*)d(a^*) + d(b^*)\psi(a^*)\right)^* \\ &= \varphi(a)d(b) + d(a)\psi(b) + \psi(a)d(b) + d(a)\varphi(b) \\ &= (\varphi + \psi)(a)d(b) + d(a)(\varphi + \psi)(b) \quad (a, b \in \mathfrak{A}). \end{aligned}$$

Thus d is a $*$ - $\frac{\varphi+\psi}{2}$ -derivation. It follows from Theorem 4.4 that d is continuous.

Conversely if d is a continuous (φ, ψ) -derivation, then

$$\lim_{x \rightarrow 0} \varphi(x)d(b) = \lim_{x \rightarrow 0} d(xb) - \lim_{x \rightarrow 0} d(x)\psi(b) = 0 \quad (b \in \mathfrak{A}),$$

and

$$\lim_{x \rightarrow 0} d(b)\psi(x) = \lim_{x \rightarrow 0} d(bx) - \lim_{x \rightarrow 0} \varphi(b)d(x) = 0 \quad (b \in \mathfrak{A}).$$

So φ and ψ are left and right d -continuous, respectively. ■

Lemma 4.6. *Let d be a (φ, ψ) -derivation. Then there are two mappings Φ and Ψ with $\Phi(0) = 0 = \Psi(0)$ such that d is a (Φ, Ψ) -derivation.*

Proof. Define Φ and Ψ by

$$\begin{aligned} \Phi(a) &:= \varphi(a) - \varphi(0), \\ \Psi(a) &:= \psi(a) - \psi(0), \end{aligned}$$

for all $a \in \mathfrak{A}$. We have

$$\begin{aligned} 0 = d(0) &= d(a \cdot 0) = \varphi(a)d(0) + d(a)\psi(0) = d(a)\psi(0) \quad (a \in \mathfrak{A}), \\ 0 = d(0) &= d(0 \cdot a) = \varphi(0)d(a) + d(0)\psi(a) = \varphi(0)d(a) \quad (a \in \mathfrak{A}). \end{aligned}$$

Thus

$$\Phi(a)d(b) + d(a)\Psi(b) = \varphi(a)d(b) + d(a)\psi(b) = d(ab) \quad (a, b \in \mathfrak{A}).$$

Hence d is a (Φ, Ψ) -derivation. ■

Corollary 4.7. *If $*$ -mappings φ and ψ are continuous at zero, then every $*$ - (φ, ψ) -derivation d is automatically continuous.*

Proof. Apply Lemma 4.6 and Corollary 4.5. ■

Clearly the assumption of Corollary 4.7 comes true whenever φ and ψ are linear and bounded. The next theorem states that when we deal with a continuous $*$ - (φ, ψ) -derivation, we may assume that φ and ψ have ‘at most’ zero separating spaces.

Theorem 4.8. *Let φ and ψ be $*$ -mappings. If d is a continuous $*$ - (φ, ψ) -derivation, then there are $*$ -mappings φ' and ψ' from \mathfrak{A} into $B(\mathfrak{H})$ with ‘at most’ zero separating spaces such that d is a $*$ - (φ', ψ') -derivation.*

Proof. Set

$$\begin{aligned} Y &:= \{d(a) \mid a \in \mathfrak{A}\}, \\ \mathfrak{L}_0 &:= \cup\{d(a)h \mid a \in \mathfrak{A}, h \in \mathfrak{H}\}. \end{aligned}$$

Let \mathfrak{L} be the closed linear span of \mathfrak{L}_0 in \mathfrak{H} , and let $\mathfrak{K} := \mathfrak{L}^\perp$. Suppose that $p \in B(\mathfrak{H})$ is the orthogonal projection of \mathfrak{H} onto \mathfrak{L} . It follows from continuity of operators $d(a)$ that $d(a)(\mathfrak{L}) \subseteq \mathfrak{L}$ ($a \in \mathfrak{A}$), and so

$$pd(a) = d(a)p \quad (a \in \mathfrak{A}),$$

and

$$p\varphi(a) = \varphi(a)p, \quad p\psi(a) = \psi(a)p \quad (a \in \mathfrak{A}).$$

For a typical element $\ell = d(b)h$ of \mathfrak{L}_0 , we have

$$\begin{aligned} \varphi(a)\ell &= \varphi(a)d(b)h \\ &= d(ab)h - d(a)\psi(b)h \in \mathfrak{L}. \end{aligned}$$

Therefore $\varphi(a)(\mathfrak{L}_0) \subseteq \mathfrak{L}$ and hence $\varphi(a)(\mathfrak{L}) \subseteq \mathfrak{L}$.

The same argument shows that $\psi(a)(\mathfrak{L}) \subseteq \mathfrak{L}$. Now we define φ' and ψ' from \mathfrak{A} into $B(\mathfrak{H})$ by $\varphi'(a) := \varphi(a)p$ ($a \in \mathfrak{A}$), and $\psi'(a) := \psi(a)p$ ($a \in \mathfrak{A}$). Clearly φ' and ψ' are $*$ -mappings. Furthermore, d is a $*$ - (φ', ψ') -derivation. In fact for all $a, b \in \mathfrak{A}$, and $h \in \mathfrak{H}$, we have

$$\begin{aligned} d(ab)h &= \varphi(a)d(b)h + d(a)\psi(b)h \\ &= \varphi(a)pd(b)h + pd(a)\psi(b)h \\ &= \varphi'(a)d(b)h + d(a)\psi'(b)h, \end{aligned}$$

since p commutes with $d(a)$, $\varphi(a)$, and $\psi(a)$. Suppose that $\mathfrak{S}(\varphi') \neq \emptyset$ and $a \in \mathfrak{S}(\varphi')$. If $a = \lim_{n \rightarrow \infty} \varphi'(a_n)$ for some sequence $\{a_n\}$ in \mathfrak{A} converging to zero, then

$$\begin{aligned} a(k) &= \lim_{n \rightarrow \infty} \varphi'(a_n)k \\ &= \lim_{n \rightarrow \infty} \varphi(a_n)pk \\ &= \lim_{n \rightarrow \infty} \varphi(a_n)0 \\ &= 0 \quad (k \in \mathfrak{K}). \end{aligned}$$

Let $\ell_0 = d(b)h \in \mathfrak{L}_0$, where $b \in \mathfrak{A}$ and $h \in \mathfrak{H}$. Then

$$\begin{aligned} a(\ell_0) &= \lim_{n \rightarrow \infty} \varphi'(a_n)d(b)h \\ &= \lim_{n \rightarrow \infty} d(a_nb)h - \lim_{n \rightarrow \infty} d(a_n)\psi(b)h \\ &= 0, \end{aligned}$$

and by continuity of operator a , we get $a(\ell) = 0$ ($\ell \in \mathfrak{L}$), and hence $a = 0$. Similarly the separating space of ψ' is empty or $\{0\}$. ■

5 Generalized (φ, ψ) -derivations

In this section, we study the continuity of generalized (φ, ψ) -derivations.

Definition 5.1. Suppose that \mathfrak{B} is an algebra, \mathfrak{A} is a subalgebra of \mathfrak{B} , \mathfrak{X} is a \mathfrak{B} -bimodule, $\varphi, \psi : \mathfrak{B} \rightarrow \mathfrak{B}$ are mappings, and $d : \mathfrak{A} \rightarrow \mathfrak{X}$ is a (φ, ψ) -derivation. A linear mapping $\delta : \mathfrak{A} \rightarrow \mathfrak{X}$ is a *generalized (φ, ψ) -derivation* corresponding to d if

$$\delta(ab) = \varphi(a)d(b) + \delta(a)\psi(b) \quad (a, b \in \mathfrak{A}).$$

Proposition 5.2. *Suppose that \mathfrak{A} is a C^* -algebra acting on a Hilbert space \mathfrak{H} . A generalized $*$ - (φ, ψ) -derivation $\delta : \mathfrak{A} \rightarrow B(\mathfrak{H})$ corresponding to the (φ, ψ) -derivation d is automatically continuous provided that $\varphi : \mathfrak{A} \rightarrow B(\mathfrak{H})$ is a left d -continuous $*$ -mapping, and $\psi : \mathfrak{A} \rightarrow B(\mathfrak{H})$ is both a right d -continuous and a δ -continuous $*$ -mapping.*

Proof. Suppose that $\{a_n\}$ is a sequence in \mathfrak{A} , and $a_n \rightarrow 0$ as $n \rightarrow \infty$. By the Cohen factorization theorem, there exist a sequence $\{b_n\}$ in \mathfrak{A} , and an element $c \in \mathfrak{A}$ such that $a_n = cb_n$, for all $n \in \mathbb{N}$, and $b_n \rightarrow 0$ as $n \rightarrow \infty$. By Corollary 4.5, d is continuous, so $d(a_n) = d(cb_n) \rightarrow 0$ as $n \rightarrow \infty$. A straightforward computation shows that

$$(\delta - d)(xy) = (\delta - d)(x)\psi(y) \quad (x, y \in \mathfrak{A}).$$

Thus

$$\begin{aligned} \delta(a_n) &= (\delta - d)(a_n) + d(a_n) \\ &= (\delta - d)(c)\psi(b_n) + d(a_n), \end{aligned}$$

which converges to zero as $n \rightarrow \infty$, since ψ is right $(\delta - d)$ -continuous. ■

Corollary 5.3. *Let \mathfrak{A} be a C^* -algebra acting on a Hilbert space \mathfrak{H} . Suppose that $\varphi, \psi : \mathfrak{A} \rightarrow B(\mathfrak{H})$ are continuous at zero. Then every generalized $*$ - (φ, ψ) -derivation $d : \mathfrak{A} \rightarrow B(\mathfrak{H})$ is automatically continuous.*

Proof. Using the same argument as in the proof of Lemma 4.6, we may assume that $\varphi(0) = 0 = \psi(0)$. Thus φ and ψ are S -continuous for each mapping S . Now the result is obtained from Theorem 5.2. ■

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