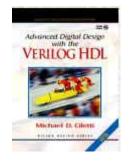
Advanced Digital Design with the Verilog HDL



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Chaps 1 - 3: Review of Combinational and Sequential Logic (rev 9/17/2003)

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COURSE OVERVIEW

- Review of combinational and sequential logic design
- Modeling and verification with hardware description languages
- Introduction to synthesis with HDLs
- Programmable logic devices
- State machines, datapath controllers, RISC CPU
- Architectures and algorithms for computation and signal processing
- Synchronization across clock domains
- Timing analysis
- Fault simulation and testing, JTAG, BIST

Some References

Note: For an up-to-date list of books, including reviews, see www.sutherland.com

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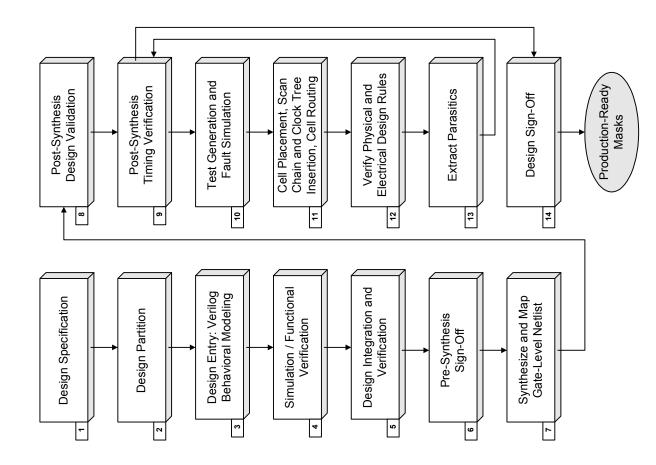
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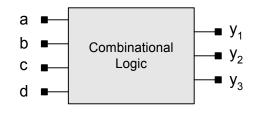
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COMBINATIONAL LOGIC

Combinational logic forms Boolean functions of the input variables. The outputs at any time, t, are a function of only the inputs at time t. The variables are assumed to be binary.

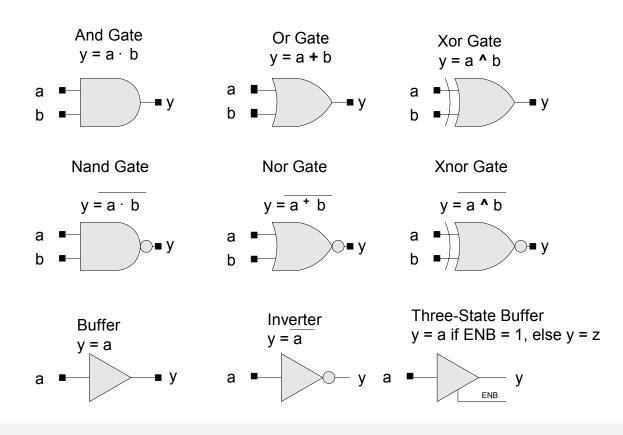


$y_1 = f_1(a, b, c, d)$	
$y_2 = f_2(a, b, c, d)$	
y ₃ = f ₃ (a, b, c, d)	
$y_4 = f_4(a, b, c, d)$	

A binary variable may have a value of 0 or 1. Later, the logic value system will be expanded to have more values to support a hardware description language.

POSITIVE LOGIC: Low voltage corresponds to logic 0 and a high voltage corresponds to a logic 1.

LOGIC GATES



LOGIC GATES - NOTATION

+ denotes logical "or"

denotes logical "and"

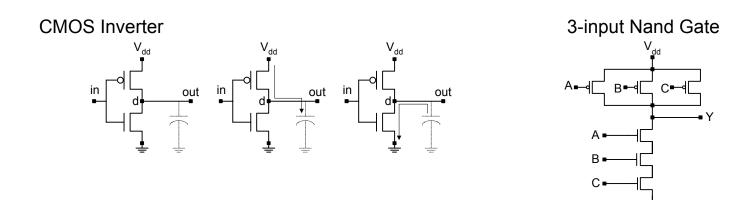
^ denotes exclusive or

 \oplus denotes "exclusive or"

' denotes logical negation

overbar denotes logical negation

LOGIC GATES - CMOS TECHNOLOGY



BOOLEAN ALGEBRA (p 16)

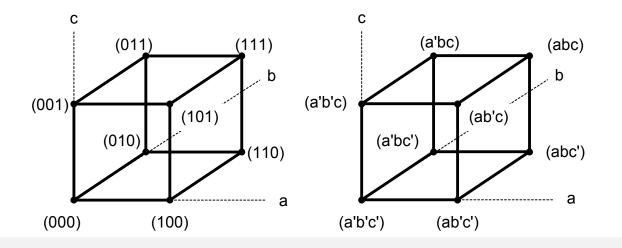
A binary Boolean algebra consists of a set $\mathbf{B} = \{0, 1\}$ and the operators + and , having commutative and distributive properties such that for two Boolean variables A and B having values in \mathbf{B} , a + b = b + a, and a b = b a. The operators + and have identity elements 0 and 1, respectively, such that for any Boolean variable a, a + 0 = a, and a 1 = a. Each Boolean variable a has a complement, denoted by a', such that a + a' = 1, and a a' = 0.

Terminology:

- + is called the sum operator, the "OR" operator, or the disjunction operator.
- is called the product operator, the "AND" operator, or the conjunction operator.
- The multi-dimensional space spanned by a set of n binary-valued Boolean variables is denoted by Bⁿ.
- A point in **B**ⁿ is called a vertex of and is represented by an n-dimensional vector of binary valued elements, e.g. (100).
- A binary variable can be associated with the dimensions of a binary Boolean space, and a point is identified with the values of the variables.

BOOLEAN CUBES

- A literal is an instance of a variable or its complement.
- A point in **B**ⁿ is called a cube.
- A product of literals is a cube.
- A cube contains one or more vertices.



BOOLEAN FUNCTIONS

A completely specified m-dimensional Boolean function is a mapping from \mathbf{B}^n into \mathbf{B}^m , denoted by f: $\mathbf{B}^n \to \mathbf{B}^m$. An incompletely specified function is defined over a subset of \mathbf{B}^n , and is considered to have a value of "don't-care" at points outside of the subset of definition: f: $\mathbf{B}^n \to \{0, 1, *\}$, where * denotes don't-care.

"On" Set: $\{x: x \in B^n \text{ and } f(x) = 1\}$

"Off" Set: $\{\mathbf{x}: \mathbf{x} \in \mathbf{B}^n \text{ and } f(\mathbf{x}) = 0\}$

"dc" Set: $\{\mathbf{x}: \mathbf{x} \in \mathbf{B}^n \text{ and } f(\mathbf{x}) = *\}$

The don't-care set accommodates input patterns that never care, or outputs that will not be observed.

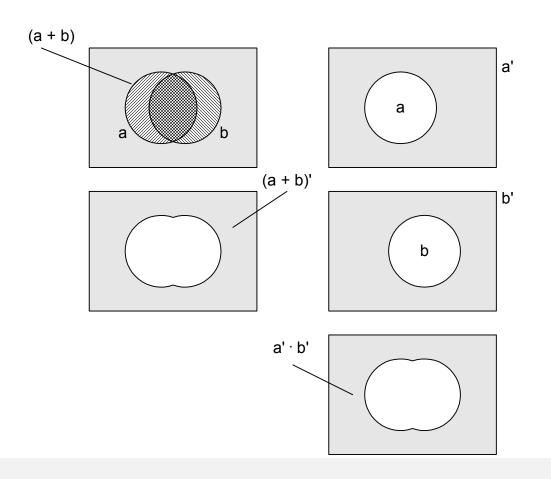
BOOLEAN ALGEBRA

Boolean Algebra Laws	SOP Form	POS Form	
Combinations with 0, 1	a + 0 = a a + 1 = 1	a · 1 =a a · 0 = 0	
Commutative	a + b = b + a	ab = ba	
Associative	(a + b) + c = a + (b + c) = a + b + c	(ab)c = a(bc) = abc	
Distributive	a(b + c) = ab + ac	a + bc = (a + b)(a + c)	
Idempote	a + a = a	a · a = a	
Involution	(a')' = a		
Complementarity	a + a' = 1	a · a' = 0	

DeMorgan's Laws

$$(a + b + c + ...)' = a'b'c'.... and (abc)' = a' + b' + c'$$

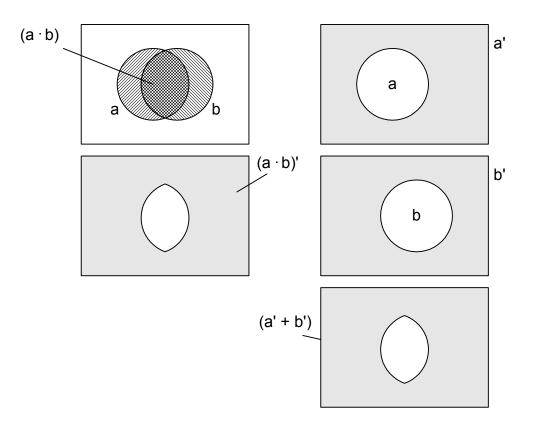
For two variables: $(a + b)' = a' \cdot b'$



DeMorgan's Laws

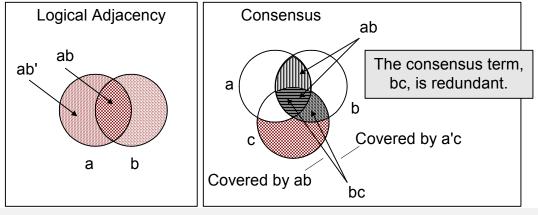
$$(a + b + c + ...)' = a'b'c'.... and (abc)' = a' + b' + c'$$

For two variables: $(a \cdot b)' = a' + b'$



THEOREMS FOR BOOLEAN ALGEBRAIC MINIMIZATION

Theorem	SOP Form	POS Form
Logical Adjacency	ab + ab' = a	(a + b) (a + b') = a
Absorption	a + ab = a ab' + b = a + b	a(a + b) = a (a + b')b = ab
or:	a + a'b = a + b	(a' + b)a = ab
Multiplication and Factoring	(a + b)(a' + c) = ac + a'b	ab + a'c = (a + c)(a' + b)
Consensus	ab + bc +a'c = ab + a'c	(a + b)(b + c)(a' + c) = (a + b)(a' + c)



THEOREMS ... MINIMIZATION (Cont.)

Exclusive-Or Laws	
Combinations with 0, 1	a ⊕ 0 = a a ⊕ 1 = a' a ⊕ a = 0 a ⊕ a' = 1
Commutative Associative Distributive	$a \oplus b = b \oplus a$ $(a \oplus b) \oplus c = a \oplus (b \oplus c) = a \oplus b \oplus c$ $a (b \oplus c) = ab \oplus ac$ $(a \oplus b)' = a \oplus b' = a' \oplus b = ab + a'b'$

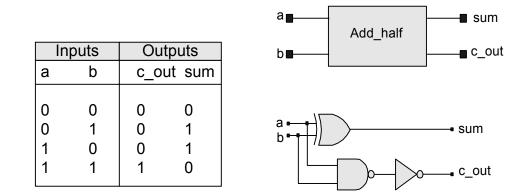
REPRESENTATION OF COMBINATIONAL LOGIC

Common representations of combinational logic:

- Truth Table
- Boolean Equations

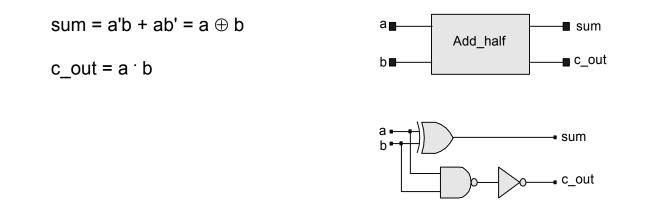
- Binary Decision Diagrams
- Circuit Schematic

EXAMPLE: HALF-ADDER TRUTH TABLE



REPRESENTATION OF COMBINATIONAL LOGIC (Cont.)

EXAMPLE: HALF-ADDER BOOLEAN EQUATIONS



SOP NOTATION (p 23)

• A cube is formed as the product of literals in which a literal appears in either uncomplemented or complemented form.

Example: *ab'cd* is a cube; *ab'cbd* is not.

• A Boolean expression is a set of cubes, and is typically expressed in sum-of-products form (SOP) as the "or" of product terms (cubes).

Example: abc' + bd

- Each term of a Boolean expression in SOP form is called an implicant of the function.
- A minterm is a cube in which every variable appears. The variable will be in either true (uncomplemented) or complemented (but not both) form. Thus, a minterm corresponds to a point (vertex) in Bⁿ. (A term that is not a minterm represents two or more points in Bⁿ). The minterms correspond to the rows of the truth table at which the function has a value of 1.

Example: The cube ab'cd is a minterm in \mathbf{B}^4 .

Example: The cube *abc* is not a minterm. It represents *abcd* + *abcd*'.

SOP NOTATION

• A Boolean expression in SOP form is said to be canonical if every cube has all of the literals in complemented or uncomplemented form.

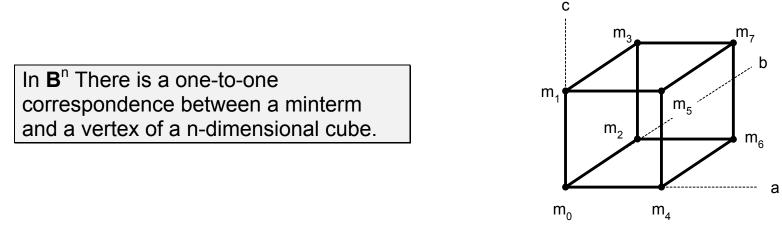
Example: The expression *abcd* + *a'bcd* is a canonical sum of products.

- A canonic SOP function is also called a standard sum of products (SSOP).
- Decimal notation: a minterm is denoted by m_i , and the pattern of 1s and 0s in the binary equivalent of the decimal number i indicates the true and complemented literals.

•

Example: $m_7 = a'bcd$.

SOP NOTATION (Cont.)



Example: $m_3 = a' \cdot b \cdot c_{in}$

A Boolean function is a set of minterms (vertices) at which the function is asserted

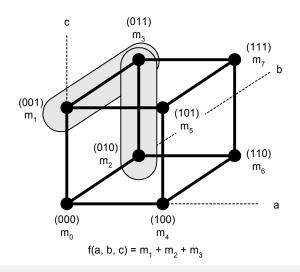
A Boolean function is expressed as a sum of minterms.

Example: $c_{out} = m_1 + m_3 + m_5 + m_7 = \sum m(1, 3, 5, 7)$

sum = $m_3 + m_5 + m_6 + m_7 = \sum m(3, 5, 6, 7)$

SOP NOTATION (Cont.)

Example:



POS NOTATION (p 26)

A Boolean function can be expressed in a "product of sums" form.

Example (Full adder):

c_out' = a'b'c_in' + a'b'c_in + a'bc_in' + ab'c_in'

c_out = (a'b'c_in' + a'b'c_in + a'bc_in' + ab'c_in')'

Apply DeMorgan's Law:

Inputs		Outputs		
а	b	c_in	c_oi	ut sum
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	0	1
1	0	1	1	0
1	1	0	1	0
1	1	1	1	1

 $c_out = (a + b + c_in)^{-} (a + b + c_in')^{-} (a + b'_c_in)^{-} (a' + b + c_in)^{-}$

A Boolean expression in POS form is said to be canonical (standard) if each factor has all of the literals in complemented or uncomplemented form, but not both.

POS NOTATION (Cont.)

A maxterm is an OR-ed sum of literals in which each variable appears exactly once in true or complemented form. A canonic POS expansion consists of a product of the maxterms of the truth table of a function. The decimal notation of a maxterm is based on the rows of the truth table at which the function is zero (i.e. where f' is asserted). The complements of the variables are used to form the POS expression.

Example:

c_out = $M_0 \cdot M_1 \cdot M_2 \cdot M_4 = \prod M(0, 1, 2, 4)$

 $c_out = (a + b + c_in)^{-}(a + b + c_in')^{-}(a + b' c_in)^{-}(a' + b + c_in)^{-}$

Note: A canonical SOP expression can be a very efficient representation of a Boolean function because there might be very few terms at which the function is asserted. Alternatively, *f*' expressed as a POS expression might be very efficient because there are only a few terms at which the function is de-asserted.

A SOP expression has a direct hardware implementation as a two-level And-Or logic circuit.

The cost of hardware implementing a Boolean expression is related to the number of terms in the expression and to the number of literals in a term.

Although a Boolean expression can always be expressed in a canonical form, with every cube containing every literal (in complemented or uncomplemented form), such descriptions usually have more efficient descriptions. In practice, minimization is important.

A Boolean expression in SOP form is said to be minimal if it contains a minimal number of product terms and literals (i.e. a given term cannot be replaced by another that has fewer literals).

A minimum SOP form corresponds to a two-level logic circuit having the fewest gates and the fewest number of gate inputs.

A Boolean expression in POS form is said to be minimal of it contains a minimal number of factors and literals (i.e. a given factor cannot be replace by another having fewer literals).

Three approaches:

- (1) Karnaugh maps and extended karnaugh maps (Feasible for up to 6 variables)
- (2) Quine-McCluskey minimization (computer-based)

(3) Boolean minimization (manual) uses the theorems describing relationships between Boolean variables to find simpler equivalent expressions (It is not straightforward, is not easy, and requires experience. Now embedded in synthesis tools such as mis II.)

In a Boolean expression, a cube that is contained in another cube is redundant.

A Boolean expression is nonredundant (irredundant) if no cube contains another cube.

Example: Redundant Expression f(a, b) = a + ab

The expression is redundant because *ab* is a subset of *a*.

After removing the redundant cube: f(a, b) = a

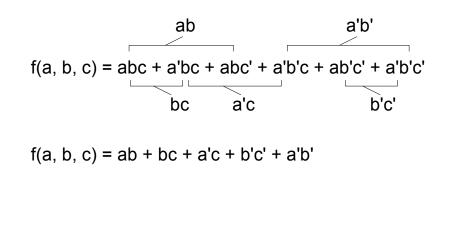
Example: Nonredundant Expression f(c, d) = c'd' + cd

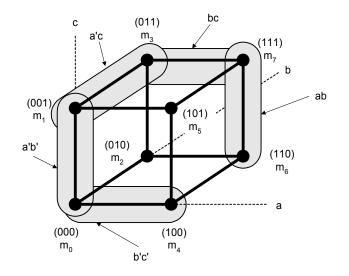
The cubes of a nonredundant expression do not share a common vertex, i.e. their corresponding sets of vertices are pairwise disjoint.

Note: The minimum SOP form and minimum POS forms of a Boolean expression are not unique.

Basic approach: To simplify/minimize a Boolean expression, repeatedly combine cubes that differ in only the same literal, and eliminate redundant implicants.

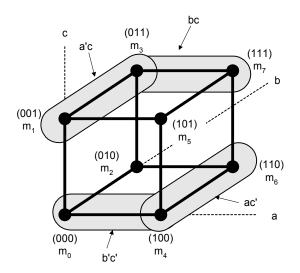
Example:





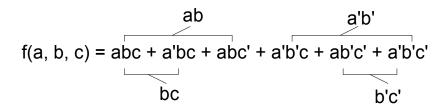
An equivalent, minimal expression removes the cubes ab + a'b' and adds the <u>cube</u> ac'.

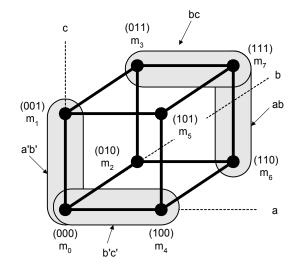
f(a, b, c) = ac' + a'c + bc + b'c'



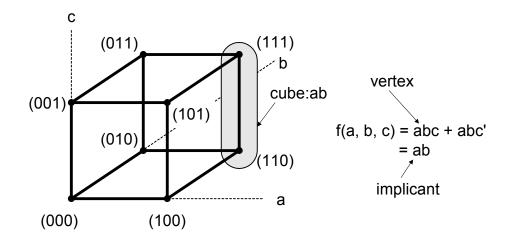
Note: f(a, b, c) = ac' + a'c + a'b'c + abc is also equivalent, but not minimal.

Another equivalent and minimal expression is given by:





<u>Implicant</u>: Each term of a Boolean expression in SOP form is called an implicant of the function. An implicant may cover more than one vertex of the function.



An implicant covers a vertex if the vertex is included in the set of vertices at which the implicant is asserted. The fewer the number of literals in a cube, the larger the set of covered vertices. So the hardware implementation is minimized if a cube has as few literals as possible

<u>Prime Implicant</u>: An implicant which does not imply any other implicant of the function is called a prime implicant. A prime implicant is a cube that is not properly contained in some other cube of the function.

Example: f(a, b, c, d) = a'b'cd + a'bcd + ab'cd + abcd + a'b'c'd'

= a'cd + acd + a'b'c'd'

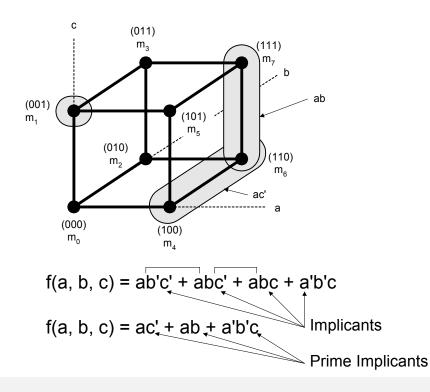
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= cd + a'b'c'd'
```

Note that *a'cd* and *acd* both imply *cd*, so they are not prime implicants. The term *a'b'c'd* is a prime implicant.

A prime implicant cannot be combined with another implicant to eliminate a literal or to be eliminated from the expression by absorption.

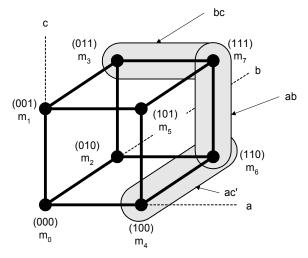
An implicant that implies another implicant is said to be "covered" by it; the set of its vertices is a subset of the vertices of the implicant that covers it. The covering implicant, having fewer literals, has more vertices.

The set of prime implicants of a Boolean expression is unique.



Essential prime implicant: A prime implicant that is not covered by any set of other implicants is an essential prime implicant.

Example: f(a, b, c) = a'bc + abc + ab'c' + abc'



Prime Implicants: Essential Prime Implicants: {ac', ab, bc} {ac', bc}

SOP Expression: Minimal SOP Expression: f(a, b, c) = ac' + ab + bcf(a, b, c) = ac' + bc

Process for minimization:

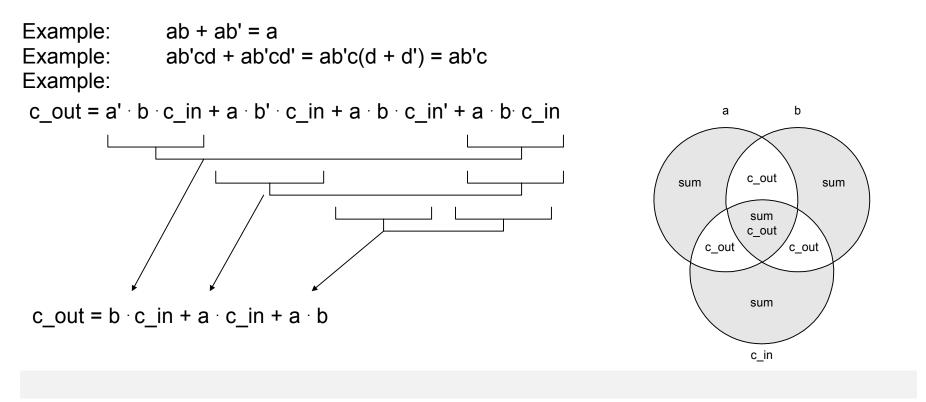
(1) Find the set of all prime implicants

(2) Find a minimal subset which covers all of the prime implicants (includes essential prime implicants).

<u>Minimal Cover</u>: A subset of prime implicants that covers all of the prime implicants is called a minimal cover for the function.

Example: f(a, b, c, d) = a'b'cd + a'bcd + ab'cd + abcd + a'b'c'd' = a'cd + acd + a'b'c'd' = cd + a'b'c'd'Prime implicants: $\{cd, a'b'c'd'\}$ Minimal cover: $\{cd, a'b'c'd'\}$

Combine terms that are logically adjacent, i.e. that differ in only one literal.



Apply logical adjacency to complementary expressions.

Example:

Consider the expression: (c + db)(a + e') + c'(d' + b')(a + e')

and note that:

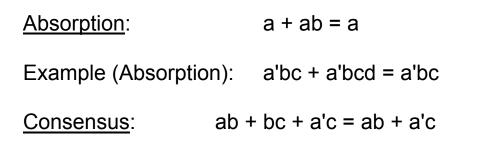
(c + db)' = c'(d' + b')

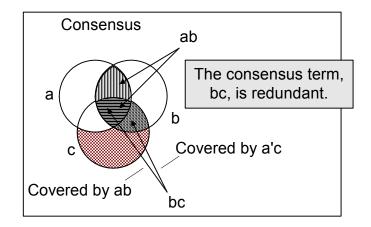
Then

$$(c + db)(a + e') + c'(d' + b')(a + e') = (c + db)(a + e') + (c + db)'(a + e')$$

= a + e'

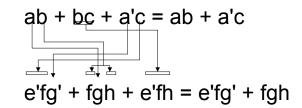
Use absorption and consensus to eliminate redundant terms.





ab + bc + a'c = ab + a'c

Example: Consensus



Use absorption repeatedly to eliminate literals.

Example: efgh' + e'f'g'h' + e'f = efgh' + e'(f + f'g'h')

= efgh' + e'(f + g'h')

= f(egh' + e') + e'g'h'

= f(gh' + e') + e'g'h'

= fgh' + e'f + e'g'h'

Introduce redundant terms to support absorption and logical adjacency.

A logical expression in SOP form is preserved under the following operations:

(1) Add the term: aa'

(2) Add the consensus term, bc, to the terms *ab* + *a'c*

(3) Add *ab* to *a* or to *b*.

A logical expression in POS form is preserved under the following operations:

(1) Multiply by the factor (a + a')

(2) Introduce the consensus factor, (b + c), in (a + b) (a' + c)

(3) Multiply a by the factor (a + b)

Consensus: ab + bc + a'c = ab + a'c

Example: Completion of consensus

Consider:

bcd + bce + ab + a'c

Terms from consensus

Add the consensus term:

b'c + bcd + bce + ab + bc + a'c

Absorb terms:

ab + c

Expanding with the consensus term is helpful when it can absorb other terms or eliminate a literal.

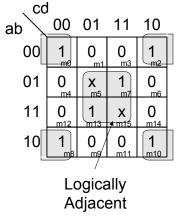
SIMPLIFICATION WITH EXCLUSIVE-OR

	a⊕0= a				
	a⊕1= a'				
	$a \oplus a = 0$				
	a⊕a'= 1				
	$a \oplus b = b \oplus a$	Commutative Law			
	$(a \oplus b) \oplus c = a \oplus (b \oplus c) = a \oplus b \oplus c$	Associative Law			
	$a(b \oplus c) = ab \oplus ac$	Distributive Law			
	$(a \oplus b)' = a \oplus b' = a' \oplus b = ab + a'b'$	Distributive Law			
Example:	sum = a' · b' · c_in + a' · b · c_in' + a · b' · c_in' + a · b · c_in				
	sum = (a \oplus b) \oplus c_in = a \oplus b \oplus c_in				

KARNAUGH MAPS (SOP FORM) (p 36)

Karnaugh maps reveal logical adjacencies and opportunities for eliminating a literal from two or more cubes. K-maps facilitate finding the largest possible cubes that cover all 1s without redundancy. Requires <u>manual</u> effort.

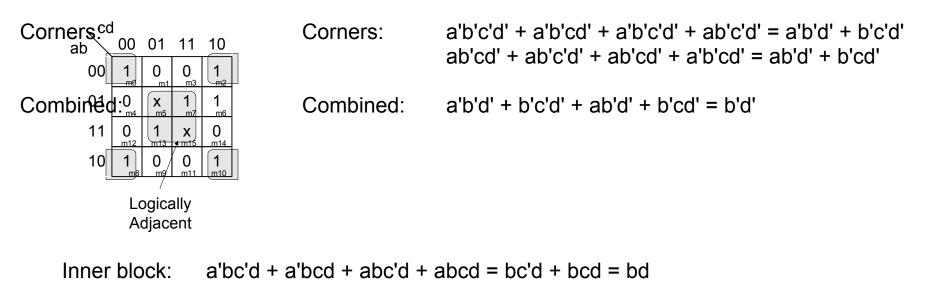
Example:



• The map shows all possible (16) vertices for a 4-variable function.

- Row ordering assures that each row (column) is logically adjacent to its physically adjacent neighboring row (column).
- The top-most and bottom-most rows are adjacent.
- The left-most and right-most columns are adjacent.
- Logically adjacent cells that contain a 1 can be combined.
- A rectangular cluster of cells that are logically adjacent can be combined.
- Use don't-cares to form prime implicants.

KARNAUGH MAPS (Cont.)

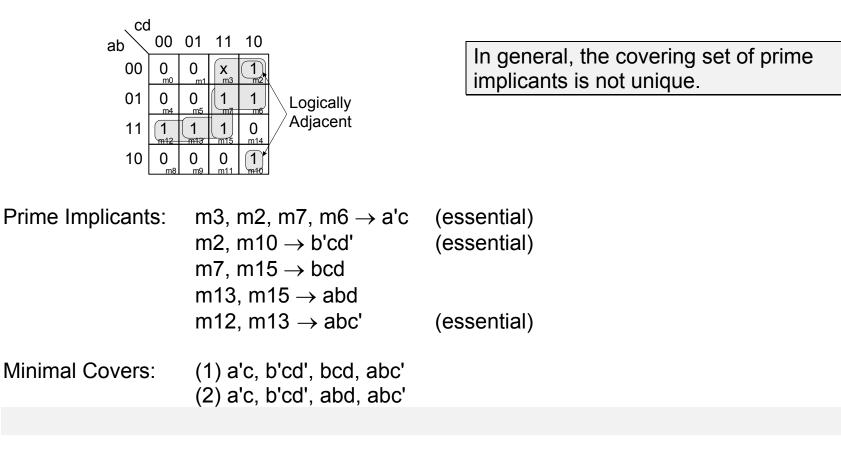


 $f = b'd' + bd = (b \oplus d)'$

Note: Each corner terms imply *b'd'*, and *b'd'* does not imply another implicant. Therefore, it is a prime implicant. It is also an essential prime implicant. Similarly, *bd* is an essential prime implicant.

KARNAUGH MAPS (Cont.)

To form a minimal realization from a Karnaugh map, (1) identify all of the essential prime implicants, using don't-cares as needed (2) use the prime implicants to form a cover of the remaining *1s* in the map (ignoring don't-cares).



KARNAUGH MAPS (Cont.)

General Process to Form a Minimal Cover:

(1) Select an uncovered minterm and identify all of its neighboring cells containing a 1 or an x. A single term (not necessarily a minterm) that covers the minterm and all of its adjacent neighbors having a 1 or an x is an essential prime implicant. Add the term to the set of essential prime implicants.

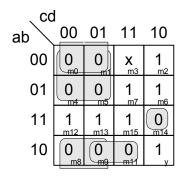
(2) Repeat (1) until all of the essential prime implicants have been selected.

(3) Find a minimal set of prime implicants that cover the other 1s in the map (do not cover cells containing x).

The above steps may produce more than one possible minimal cover. Select the cover having the fewest literals.

KARNAUGH MAPS (POS FORM) (p 39)

The minimal product of sums form of a Boolean expression is found by finding a minimal cover of the *Os* in the Karnaugh map, then applying DeMorgan's Theorem to the result.



m0, m1, m4, m5: a'b'c'd' + a'b'c'd + a'bc'd' + a'bc'd \rightarrow a'c' m0, m1, m8, m9: a'b'c'd' + a'b'c'd + ab'c'd' + ab'c'd \rightarrow b'c' m9, m11: ab'c'd + ab'cd \rightarrow ab'd m14: abcd'

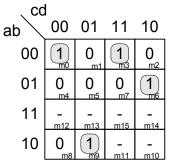
Result: f'(a, b, c, d) = a'c' + b'c' + ab'd + abcd'

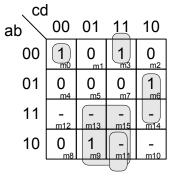
f(a, b, c, d) = (a + c)(b + c)(a' + b + d')(a' + b' + c' + d)

K-MAPS AND DON'T-CARES

Don't cares represent situations where an input cannot occur, or the output does not matter. Use (cover) don't cares when they lead to an improved representation.

Example. Suppose a function is asserted when the BCD representation of a 4-variable input is 0, 3, 6 or 9. f(a, b, c, d) = a'b'c'd' + ab'cd + abc'd' + abc'd + abcd + abcd' + ab'c'd + ab'cd has 32 literals.





Without don't cares

With don't cares

Without don't-cares (16 literals): f(a, b, c, d) = a'b'c'd' + a'b'cd + a'bcd' + ab'c'd

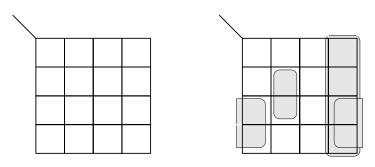
With don't cares (12 literals): f(a, b, c, d) = a'b'c'd' + b'cd + bcd' + ad

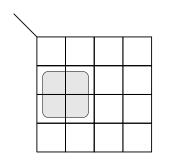
f(a, b, c, d) = a'b'c'd' + b'cd + ab + ac'd

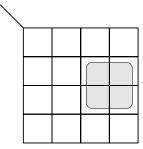
EXTENDED KARNAUGH MAPS

A 4-variable Karnaugh map can be extended by entering variables to indicate assertion contingent on the variable being asserted; no entry indicates that the function is not asserted if the variable is not asserted.

Example:







EXTENDED KARNAUGH MAPS (Cont.)

Process:

(1) Find the minimal cover with the variables de-asserted.

(2) For each variable, find the minimal sum with all *1s* changed to *x* in the map, and all other variables set to *0*. Form the product of the minimal sum and the variable.

(3) Form the sum obtained by combining (1) with the sum of the results of (2).

Note: The result is a minimal representation if the map-entered variables can be assigned independently.

Note: *fe* is contained in *e* and *f*.

GLITCHES AND STATIC HAZARDS (p 42)

The output of a combinational circuit may make a transition even though the patterns applied at its inputs do not imply a change. These unwanted switiching transients are called "glitches."

Glitches are a consequence of the circuit structure and the application of patterns that cause the glitch to occur. A circuit in which a glitch may occur under the application of appropriate inputs signals is said to have a hazard.

A **static 1-hazard** occurs if an output has an initial value of *1*, and an input pattern that does not imply an output transition causes the output to change to *0* and then return to *1*.

1-Hazard		

A **static 0-hazard** occurs if an output has an initial value of *0*, and an input pattern that does not imply an output transition causes the output to change to *1* and then return to *0*.

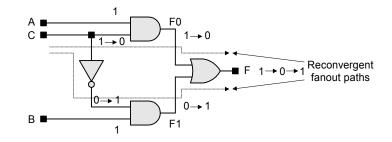
GLITCHES AND STATIC HAZARDS

Static hazards are caused by differential propagation delays on reconvergent fanout paths.

A "minimal" realization of a circuit might not be hazard-free.

Static hazards can be eliminated by introducing redundant cubes in the cover of the output expression (the added cubes are called a hazard cover).

STATIC HAZARDS: Example



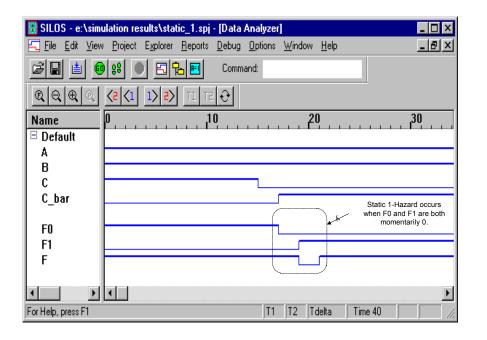
Consider F = AC + BC'

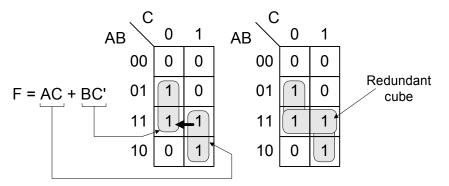
Initial inputs: A = 1, B = 1, C = 1 and F = 1

New inputs: A = 1, B = 1, C = 0 and F = 1

- In a physical realization of the circuit (i.e. non-zero propagation delays), the path to *F1* will be longer than the path to *F0*, causing a change in *C* to reach *F1* later than it reaches *F0*.
- Consequently, when C changes from 1 to 0, the output undergoes a momentary transition to 0 and returns to 1.
- The presence of a static hazard is apparent in the Karnaugh map of the output.

STATIC HAZARDS: Example (Cont.)





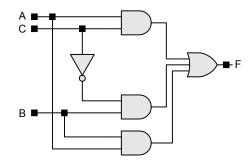
• AC de-asserts before BC' asserts

- Hazards might not be significant in a synchronous sequential circuit if the clock period can be extended.
- A hazard is problematic if the signal serves as the input to an asynchronous subsystem. (e.g a counter or a reset circuit).
- In this example, the hazard occurs because the cube AC is initially asserted, while BC' is not. The switched input causes AC to de-assert before BC' can assert.
- Hazard Removal: A hazard can be removed by covering the adjacent prime implicants by a redundant cube (AB, a 'hazard cover") to eliminate the dependency on *C* (the boundary between the cubes is now covered).

STATIC HAZARDS: Example (Cont.)

• Hazard covers require extra hardware.

Example: For the hazard-free cover: F = AC + BC' + AB



ELIMINATION OF STATIC HAZARDS (SOP Form)

If the output cubes of the initial and final inputs are covered by the same prime implicant, a glitch cannot occur. Otherwise, if the output cubes of the initial and final inputs are not covered by the same prime implicant a glitch can occur, depending on the accumulated delays along the signal propagation paths from the inputs to the output.

For a circuit whose static 1-hazard is caused by a transition in a single bit of a single signal:

- Form a SOP cover in which every pair of adjacent *1s* is covered by a cube. This gurantees that every single-bit input change is covered by such a prime implicant.
- The set of prime implicants is a hazard-free cover for a two-level (And-Or) realization of the circuit, but a better alternative might be found.

ELIMINATION OF STATIC HAZARDS (Cont.)

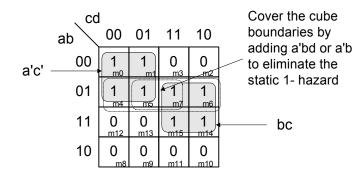
To eliminate a static 0-hazard:

- Method #1: Cover the adjacent *0s* in the corresponding POS expression.
- Method #2: First eliminate the static 1-hazards. Then form complement function and consider whether the implicants of the *0s* of the expression that is free of static 1-hazards also cover all adjacent *0s* of the original function. If they do not, then a static 0-hazard exists.

EXAMPLE: ELIMINATION OF STATIC HAZARDS

Static 1-hazard:

$$f = \sum m(0, 1, 4, 5, 6, 7, 14, 15) = a'c' + bc$$

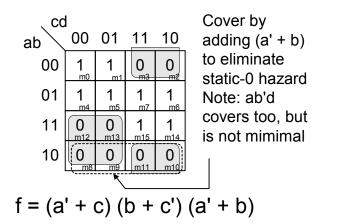


f = a'c' + bc + a'b

- With *a* = 0, *b* = 1, and *D* = 1, a glitch can occur as *c* changes from 1 to 0 or visa-versa.
- Adding the redundant prime implicant term eliminates the static 1-hazard.
- Note: m₄ and m₆ interface

Static 0-hazard (First method): From *0s* of the K-map and DeMorgan's Law:

f' = ac' + b'c and f = (a' + c) (b + c')



Add a'b to f', and including the redundant prime implicant product factor (a' + b) in f to eliminate the static 0-hazard.

EXAMPLE: ELIMINATION OF STATIC HAZARDS (Cont.)

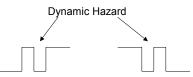
Note: In this example, the POS expression that eliminates the static 0-hazard is equivalent to the expression that eliminates the static 1-hazard.

f = (a' + c) (b + c') (a' + b)f = a'ba' + a'bb + a'c'a' + a'c'b + cba' + cbb + cc'a' + cc'b f = a'b + a'c' + bc

Note: see text for additonal details

DYNAMIC HAZARDS (Multiple glitches)

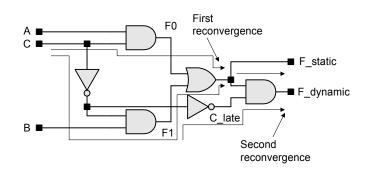
• A circuit has a dynamic hazard if an input transition is supposed to cause a single transition in an output, but causes two or more transitions before reached its expected value.



- Dynamic hazards are a consequence of multiple static hazards caused by multiply reconvergent paths in a multilevel circuit.
- Dynamic hazards are not easy to eliminate.
- Elimination of all static hazards eliminates dynamic hazards.
- Approach: Transform a multilevel circuit into a two-level circuit and eliminate all of the static hazards.

DYNAMIC HAZARDS (Cont.)

EXAMPLE:

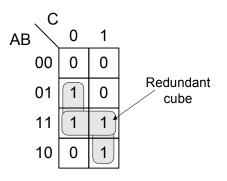


F_static has a static 1-hazard.

F_dynamic has a dynamic hazard.

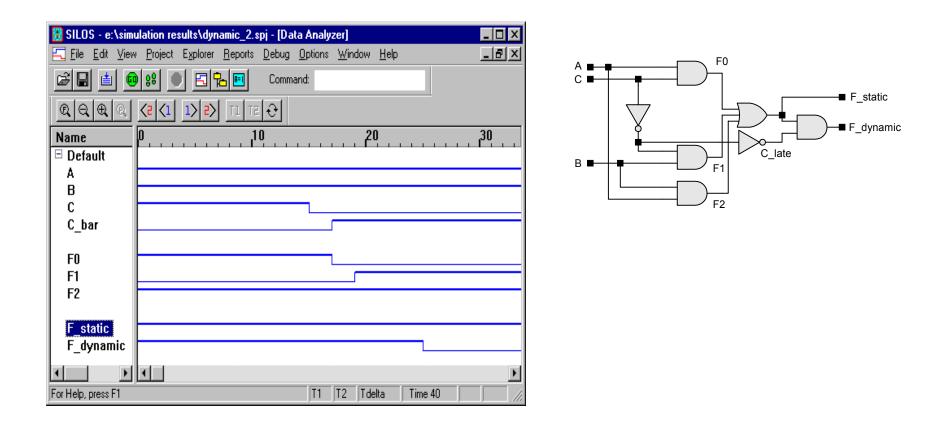
DYNAMIC HAZARDS (Cont.)

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The redundant cube eliminates the static 1-hazard and assures that $F_dynamic$ will not depend on the arrival of the effect of the transition in *C*.

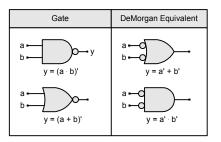
DYNAMIC HAZARDS (Cont.)



BUILDING BLOCKS: NAND-NOR STRUCTURES (p 55)

In CMOS technology, AND gates and OR gates are not implemented as efficiently as NAND gates and NOR gates. An SOP form or a POS form can always be converted to a NAND logic structure or a NOR logic structure. The "NAND" gate and "NOR" gate are universal logic gates - any Boolean function can be realized from only NAND gates or only NOR gates.

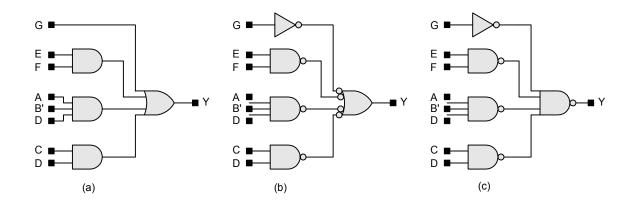
DeMorgan's Theorem provides equivalent structures for NAND and NOR gates.



Networks realizing SOP forms can be transformed to a realization that uses only nand gates and inverters.

EXAMPLE: SOP TO NAND STRUCTURES

Y = G + EF + AB'D + CD



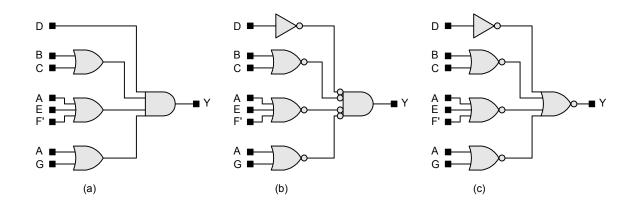
- In the original And-Or structure: replace And by Nand, place inversion bubbles at inputs of Or, include inverter for G to balance bubble at input of Or.
- In the new circuit, replace Or gates having bubble inputs by equivalent Nand gates.

Check: Y = [(G') (EF)' (AB'D)' (CD)']' = (G')' + [(EF)']' + [(AB'D)']' + [(CD)']'

Y = G + EF + AB'D + CD

EXAMPLE: POS TO NOR STRUCTURES

Y = D(B + C) (A + E + F') (A + G)



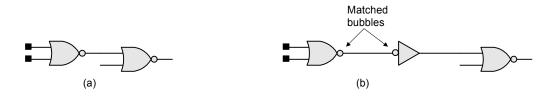
- In the original Or-And structure: replace Or by Nor, place inversion bubbles at inputs of And, include inverter for D to balance bubble at input of the And gate.
- In the new circuit, replace And gates having bubble inputs by equivalent Nor gates.

Check: Y = [D' + (B + C)' + (A + E + F')' + (A + G)']' = (D')' [(B + C)']' [(A + E + F')']' [(A + G)']'Y = D (B + C) (A + E + F') (A + G)

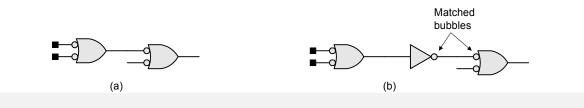
EXAMPLE: GENERAL STRUCTURES

Conversion to Nand:

- In the original structure: replace And by Nand; place inversion bubbles at inputs of Or.
- To convert the new circuit to a Nand structure, replace Or gates having bubble inputs by equivalent Nand gates.
- If, after the above change have been made, the output of a Nand gate drives the input of a nand gate, place an inverter at the input of the driven Nand gate.



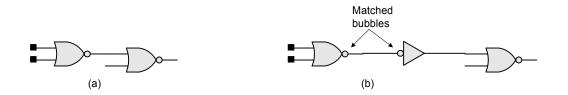
• If the output of an Or gate having bubbles at its inputs drives an Or gate with bubbles at its inputs, place an inverter between the gates.



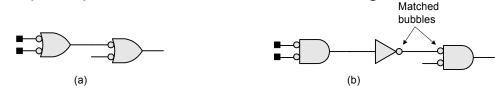
EXAMPLE: GENERAL STRUCTURES (Cont.)

Conversion to Nor:

- Replace Or by Nor; place inversion bubbles at inputs of And.
- •
- To convert the new circuit to a Nor structure, replace And gates having bubble inputs by equivalent Nor gates.
- If, after the above change have been made, the output of a Nor gate drives the input of a Nor gate, place an inverter at the input of the driven Nor gate.

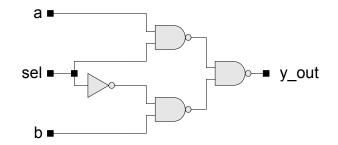


• If the output of an And gate having bubbles at its inputs drives an And gate with bubbles at its inputs, place an inverter between the gates.



BUILDING BLOCKS: MULTIPLEXERS (p 60)

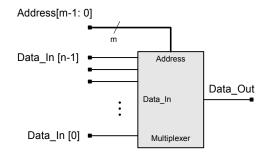
MUXES PROVIDE STEERING FOR DATAPATHS.



y_out = sel · a + sel' · b

MULTIPLEXERS

• A multiplexer has *n* datapath inputs and a single output. An m-bit address determines which of the inputs is connected to the output.



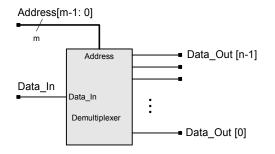
Input channel selection:

Data_Out = Data_In [Address[k]]

• A multiplexer is used to control the flow of data in a digital machine.

DEMULTIPLEXERS

A demultiplexer has a single datapath input, *n* datapath outputs, and *m* address inputs. The m-bit address determines which of the *n* outputs is connected to the input.

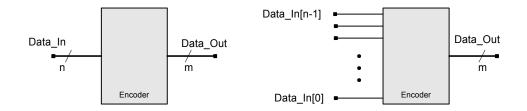


Output channel selection:

Data_Out [n-1: 0] = Data_In [Address[k]]

ENCODERS

An encoder has *n* inputs and *m* outputs, with $n = 2^m$. Ordinarily, only one of the inputs is asserted at a time. A unique output bit pattern (code) is assigned to each of the n inputs. The asserted output is determined by the index of the asserted bit of the n-bit binary input word.



Example: n = 4, m = 2, Data_In [3] = 1 and Data_In [k] = 0 for $0 \le k \le n, k \ne 3$

Data_Out $[1:0] = 11_2 = 3_{10}$

A Mux does not change the data input, but encoders transform the data input to form the data output. The encoder assigns a unique bit pattern to each input line.

PRIORITY ENCODERS

A priority encoder allows multiple input bits to be asserted simultaneously, and uses a priority rule to form an output bit pattern.

Example:

Data_In [3:0]	Data_out [1:0]
1	00
1 -	01
- 1	10
1	11

Note: "-" denotes a don't care condition.

DECODERS

A decoder has *m* inputs and *n* outputs, with $n = 2^m$. Only one of the outputs is asserted at a time. The asserted output is determined by the decimal equivalent of the m-bit binary input word.



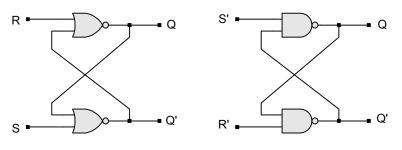
Example: n = 4, m = 2

Data_In = 11_2 and Data_Out [3] = 1 and Data_Out[k] = 0 for k \neq 3

STORAGE ELEMENTS: R-S LATCH

- Storage elements are used to store information in a binary format (e.g. state, data, address, opcode, machine status).
- Storage elements may be clocked or unclocked.
- Two types: level-sensitive, edge-sensitive

Example: R-S latch (Unclocked) The state of an R-S latch is dependent on the value of its R and S inputs.



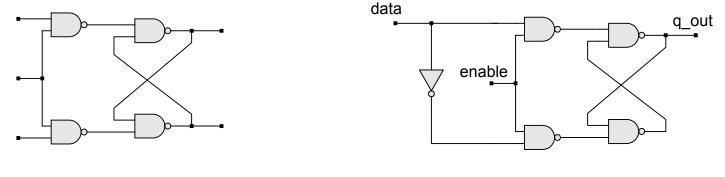
Note: Avoid applying *11* to a R-S Nor latch, and *00* to an R'S' Nand latch. The circuit is unstable and oscillation will result.

S	R	Q _{next}	Q' _{next}	
0	0	Q	Q'	Hold
0	1	0	1	Reset
1	0	1	0	Set
1	1	0	0	Not Allowed

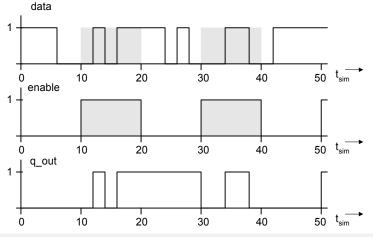
S'	R'	Q _{next}	Q' _{next}	
0	0	1	1	Not Allowed
0	1	1	0	Set
1	0	0	1	Reset
1	1	Q	Q'	Hold

STORAGE ELEMENTS: TRANSPARENT LATCHES

Latches are level-sensitive storage elements; data storage is dependent on the level (value) of the input clock (or enable) signal. The output of a transparent latch changes in response to the data input while the latch is enabled. Changes at the input are visible at the output

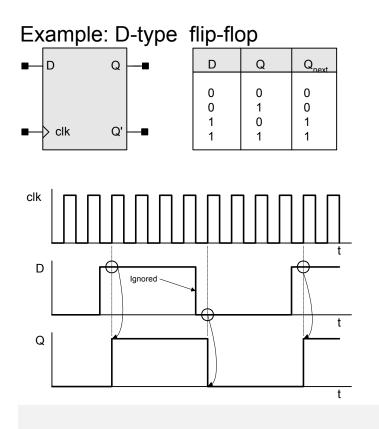


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STORAGE ELEMENTS: FLIP-FLOPS

Flip-flops are edge-sensitive storage elements; data storage is synchronized to an edge of a clock. The value of data stored depends on the data that is present at the data input(s) when the clock makes a transition at its active (rising or falling) edge.

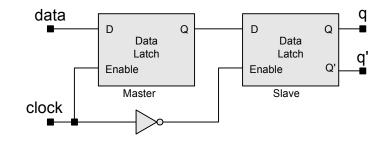


- Characteristic equation: $q_{next} = D$.
- This example is active on the rising (positive) edge of the clock.
- Intermediate data transitions are ignored.
- Timing constraints (setup, hold, minimum pulse width) must be met.

MASTER-SLAVE FLIP-FLOP

A master-slave configuration of two data latches samples the input during the active cycle of the clock applied to the master stage. The input is propagated to the output during the slave cycle of the clock.

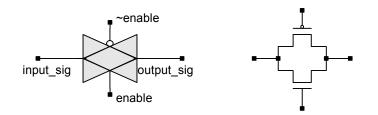
Master-slave implementation of a negative edge-triggered D-type flip-flop:



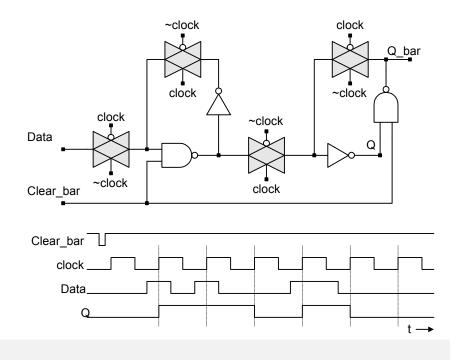
Timing constraint: the output of the master stage must settle before the enabling edge of the slave stage. The master stage is enabled on the inactive edge of the clock, and the slave stage is enabled on the active edge. Timing constraints apply to the active edge.

CMOS TECHNOLOGY - MASTER-SLAVE FLIP-FLOP

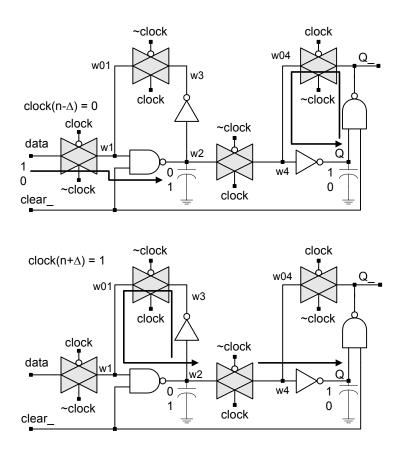
CMOS Transmission Gate:



D-type flip-flops in CMOS technology are formed by combining transmission gates with glue logic to form a master-slave circuit.



CMOS TECHNOLOGY MASTER-SLAVE FLIP-FLOP (Cont.)

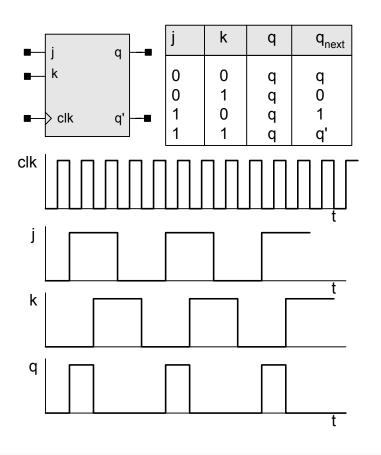


- Master stage: output capacitor (node w2) is charged and sustained by the feedback loop. The delays of the master stage determine the setup conditions of the flipflop.
- Slave stage: The output of the slave stage is sustained while the master stage is charging. At the active edge of the flipflop, the output of the master stage charges the output of the slave stage, which is sustained by the feedback loop during the active cycle.
- Note: the read operation is nondestructive.

J-K FLIP-FLOP

J-K Flip-flops are edge-sensitive storage elements; data storage is synchronized to an edge of a clock. The value of data stored is conditional, depending on the data that is present at the *j* and *k* inputs when the clock makes a transition at its active (rising or falling) edge. Cell libraries may omit the J-K flip-flop and implement the functionality with a D-type flip-flop combined with input logic.

• Characteristic Equation: q_{next} = jq' + k'q



T FLIP-FLOP

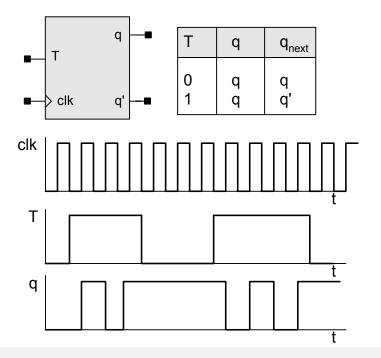
T-type flip-flops are edge-sensitive storage elements; data storage is synchronized to an edge of a clock. The value of data stored is conditional, depending on the T-input and the state of the device when the clock makes a transition at its active (rising or falling) edge. If T is asserted, the output toggles, otherwise it has no change.

A T-type flip-flop can be more efficient in implementing a counter.

• Characteristic Equation:

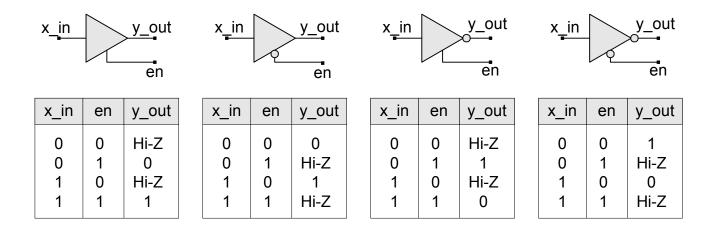
 q_{next} = q T' + q' T = $q \oplus$ T

• Note: connect *T* to the *j* and *k* inputs of a j-k flip-flop to for a T-type flip-flop.

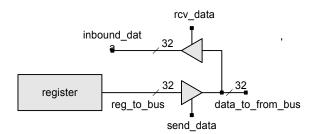


BUILDING BLOCKS: THREE-STATE DEVICES

Three-state devices provide high-impedance interface devices.

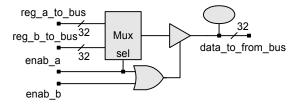


Typical applications: i/o pad and bus isolation.



BUILDING BLOCKS: THREE-STATE DEVICES (Cont.)

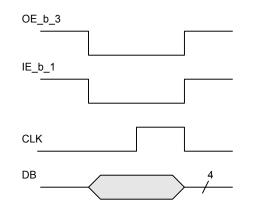
Combine a multiplexer with a three-state device to reduce bus loading of multiple bus drivers.

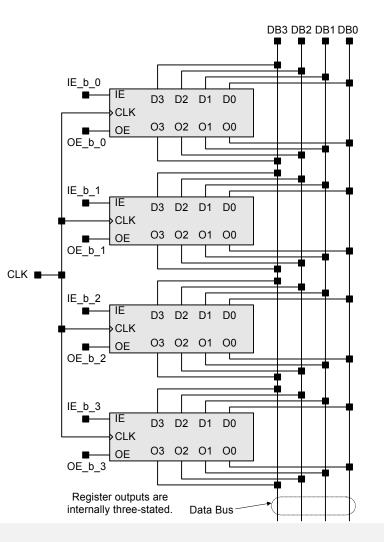


BUILDING BLOCKS: BUSSES

- Busses provide parallel datapaths and control interfaces and between functional units.
- Synchronous and asynchronous busses
- Handshaking protocols are required for coherent communication
- Key Issues: Bus Contention and Arbitration

Example: Register-to-Register transfer on a 4bit datapath.



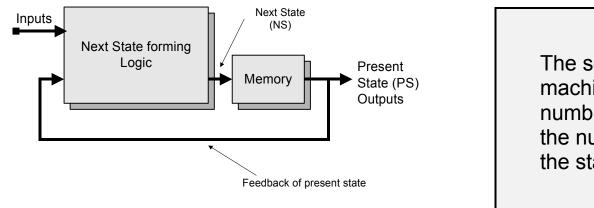


SEQUENTIAL MACHINES (p 80)

• Sequential machines, also called finite state machines, are characterized by an input/output relationship in which the value of the outputs at a given time depend on the history of the applied inputs as well as their present value.

Example: A machine that is to count the number of 1s in a serially transmitted frame of bits.

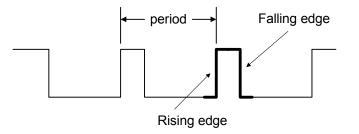
- The history of the inputs applied to a sequential machine is represented by the **state** of the machine, and requires hardware elements that store information, i.e. requires memory to store the state of the machine as an encoded binary word.
- All sequential machines require feedback that allows the next state of the machine to be determined from the present state and inputs.



The set of states of a sequential machine is always finite, and the number of states is determined by the number of bits that represent the state.

SEQUENTIAL MACHINES (Cont.)

- Sequential machines may be asynchronous or synchronous (clocked).
- The state transitions of a (edge-triggered) flip-flop-based synchronous machine are synchronized by the active edge (i.e. rising or falling) of a common clock. State changes give rise to changes in the combinational logic that determines the next state and the output of the machine.



• A lower bound on the cycle time (period) of the machine's clock is set by the requirement that the period of the clock must be long enough to allow all transients activated by an a transition of the clock to settle at the outputs of the combinational logic before the next active edge occurs.

SEQUENTIAL MACHINES (Cont.)

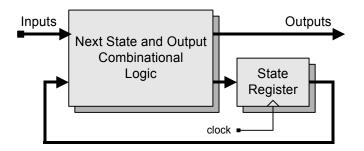
- The inputs to the flip-flops must remain stable for a sufficient interval before and after the active edge of the clock. The former constraint establishes an upper bound on the longest path through the circuit, which constrains the latest allowed arrival of data. The latter constraint imposes a lower bound on the shortest path through the combinational logic that is driving the storage device. It constrains the earliest time at which data from the previous cycle could be overwritten.
- Together, these constraints ensure that valid data is stored. Otherwise, timing violations may occur at the inputs to the flip-flops, with the result that invalid data is stored.
- In an edge-triggered clocking scheme, the clock isolates a storage register's inputs from its output, thereby allowing feedback without race conditions.
- The outputs of a state machine controls the synchronous datapath operations and register operations of more general digital machine.

FINITE STATE MACHINES

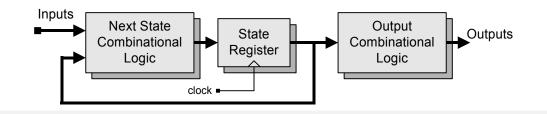
- Synchronous (i.e. clocked) finite state machines (FSMs) have widespread application in digital systems, e.g. as datapath controllers in computational units and processors. Synchronous FSMs are characterized by a finite number of states and by clock-driven state transitions.
- Mealy Machine: The next state and the outputs depend on the present state and the inputs.
- Moore Machine: The next state depends on the present state and the inputs, but the output depends on only the present state.

FINITE STATE MACHINES (Cont.)

Mealy machine



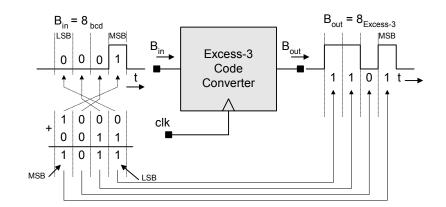
Moore machine



MEALY FINITE STATE MACHINE - EXAMPLE

A serially-transmitted BCD (8421 code) word is to be converted into an Excess-3 code. An Excess-3 code word is obtained by adding 3 to the decimal value and taking the binary equivalent. Excess-3 code is self-complementing [Wakerly, p. 80], i.e. the 9's complement of a code word is obtained by complementing the bits of the word.

Decimal Digit	8-4-2-1 Code (BCD)	Excess-3 Code
0	0000	0011
1	0001	0100
2	0010	0101
3	0011	0110
4	0100	0111
5	0101	1000
6	0110	1001
7	0111	1010
8	1000	1011
9	1001	1100
		1 1



MEALY FINITE STATE MACHINE - EXAMPLE (Cont.)

next state/output

input

S 2/0

S 4/0

S 4/1

S 5/1

S 6/0

S 0/1

-/-

0

S 1/1

S 3/1

S 4/0

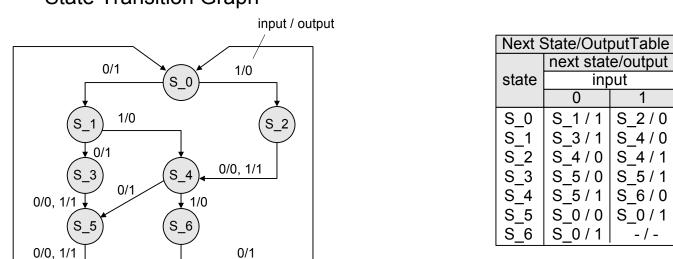
S 5/0

S 5/1

S 0/0

S 0/1

The serial code converter is described by the state transition graph of a Mealy FSM.



State Transition Graph

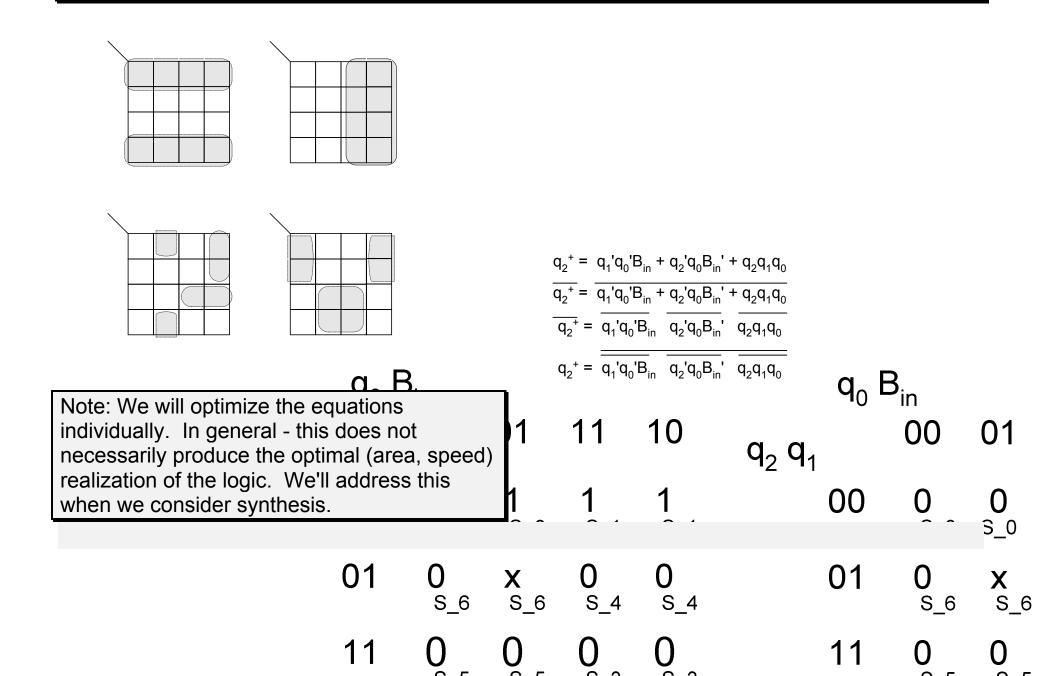
- The vertices of the state transition graph of a Mealy machine are labeled with the states. ۲
- The branches are labeled with (1) the input that causes a transition to the indicated next state, ۲ and (2) with the output that is asserted in the present state for that input.
- The state transition is synchronized to a clock. •
- The state table summarizes the machine's behavior in tabular format.

To design a D-type flip-flop realization of a FSM having the behavior described by a state transition graph, (1) select a state code, (2) encode the state table, (3) develop Boolean equations describing the input of a D-type flip-flop, and (4) using K-maps, optimize the Boolean equations.

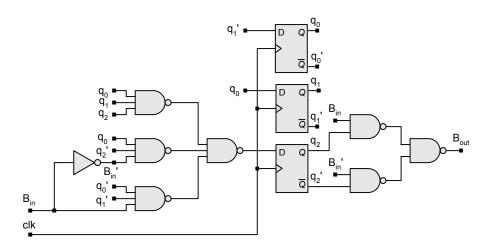
Next State/Output Table				
	next stat	e/output		
state	inp	out		
	0	1		
S_0	S_1/1	S_2/0		
S_1	S_3/1	S_4/0		
S_2	S_4/0 S_4/1			
S_3	S_5/0	S_5/1		
S_4	S_5/1	S_6/0		
S_5	S_0/0 S_0/1			
S_6	S_0 / 1	- / -		

State Assigment				
q ₀				
q ₂	q ₁	0	1	
0	0	S_0	S_1	
0	1	S_6	S_4	
1	0		S_2	
1	1	S_5	S_3	

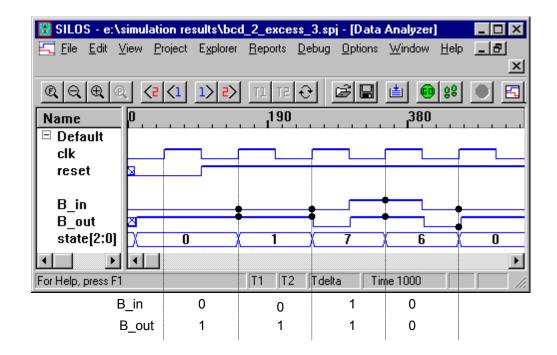
	Encoded Next state/ Output Table					
	state	next	state	output		
	$q_2^{} q_1^{} q_0^{}$	q ₂ + q	1 ⁺ q ₀ ⁺			
		inp	out	inp	out	
		0	1	0	1	
S_0	000	001	101	1	0	
S_1	001	111	011	1	0	
S_2	101	011	011	0	1	
S_3	111	110	110	0	1	
S_4	011	110	010	1	0	
S_5	110	000	000	0	1	
S_6	010	000	-	1	-	
	100	-	-	-	-	



Realization of the sequential BCD-to-Excess-3 code converter (Mealy machine):



Simulation results for Mealy machine:



DESIGN OF A SERIAL LINE CODE CONVERTER (p 89)

Serial Line Codes [Wakerly] are used for serial data transmission or storage. Data recovery requires a clock to define the boundaries of the data bits, a synchronizing signal to define word boundaries, and a data stream. As an alternative to having three separate signal channels, a phone system or a disk read/write head will have a single channel and use a coding scheme to enable clock recovery and synchronization.

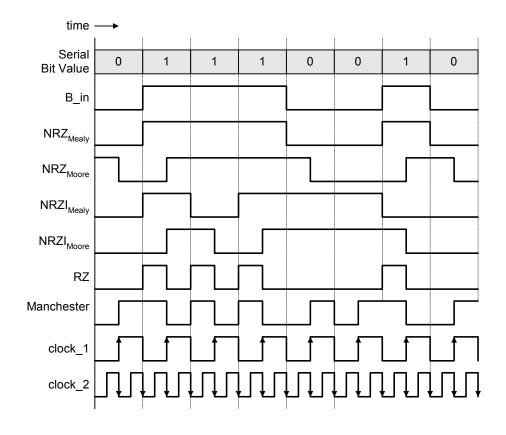
NRZ Code (Non-Return to Zero): The signal waveform duplicates the bit pattern over the entire bit time. Phase lock loops (PLL) can recover the clock if there are no long series of 1s or 0s.

NRZI Code (Non-Return to Zero Invert-on-Ones) A *0* in the bit stream causes the value of the previous bit to be transmitted; a *1* in the bit stream causes the value of the complement of the previous bit to be transmitted. A PLL can recover the clock if there is no long string of *0*s.

RZ Code (Return-to-Zero): A 0 in the bit stream is transmitted as a 0 for the entire bit time. A 1 in the bit stream is transmitted as a 1 for 1/2 of the bit time, and 0 for the remaining bit time (typically). A PLL can recover the clock if there is no long string of 0s.

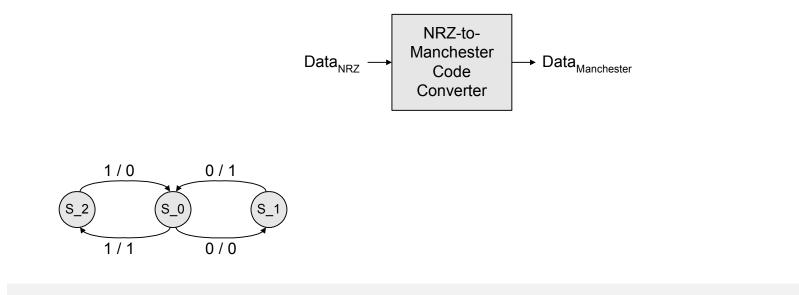
Manchester Code: A 0 in the bit stream is transmitted as a 0 for the lead half of the bit time, and as a 1 for the remaining half. A 1 in the bit stream is transmitted as a 1 for the leading half of the bit time, and as a 0 for the remaining bit time. Requires higher bandwidth, but allows clock recovery independent of the data stream.

SERIAL LINE CODE FORMATS



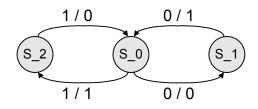
MEALY FSM - SERIAL LINE CODE CONVERTER (p 92)

Objective: Design a Mealy-type FSM that converts a data stream in NRZ format to a data stream in Manchester code format.

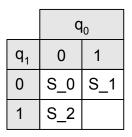


MEALY FSM - SERIAL LINE CODE CONVERTER (Cont.)

State Transition Graph



State Code:



State Table:

	next state/output			
state	input			
	0 1			
S_0	S_1/0	S_2/1		
S_1	S_1/0 S_2/ S_0/1 -			
S_2	-	S_0 / 0		

Encoded State Table:

	state	next state		out	put
	$q_1^{} q_0^{}$	$q_{1}^{+}q_{0}^{+}$			
		input		inp	but
		0	1	0	1
S_0	00	01	10	0	1
S_1	01	00	-	1	-
S_2	10	-	00	-	0

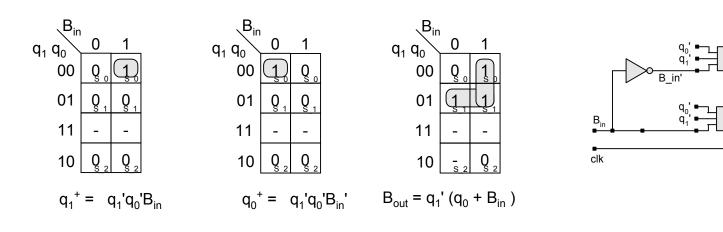
Q

B_{out}

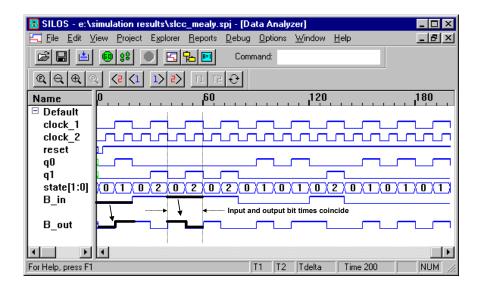
MEALY FSM - SERIAL LINE CODE CONVERTER (Cont.)

	state	next state		out	put
	$q_1 q_0$	$q_{1}^{+} q_{0}^{+}$			
		input		inp	but
		0	1	0	1
S_0	00	01	10	0	1
S_1	01	00	00	1	-
S_2	10	00	00	-	0

Karnaugh Maps:

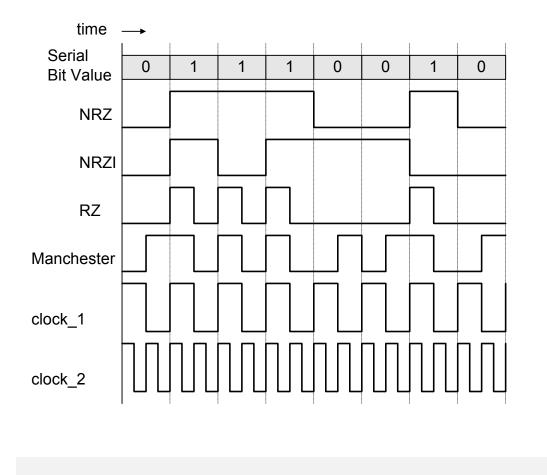


MEALY FSM - SERIAL LINE CODE CONVERTER (Cont.)



Note: The Mealy machine's output is subject to glitches in the input bit stream.

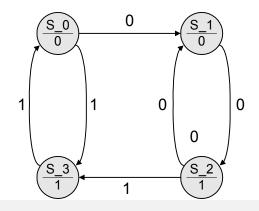
SERIAL LINE CODE CONVERTER - MOORE FSM (p 93)



State Table:

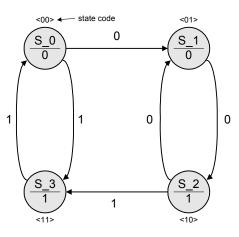
	next state/output				
state	inp	but			
	0 1				
S_0 S_1 S_3	S_1/0 S_2/1	S_3 / 1 - S_0 / 1			
S_2	S_1/0	S_3/0			

State Transition Graph:



SERIAL LINE CODE CONVERTER - MOORE FSM (Cont.)

State Transition Graph



Encoded State Table:

	state	next state		output
	$q_1^{} q_0^{}$	q ₁ +	q_0^+	
		inp	but	
		0	1	
S_0	00	01	11	0
S_1	01	10	-	0
S_3	11	-	00	1
S_2	10	01	11	1

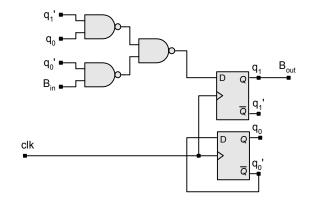
State code:

		q ₀			
q.	1	0	1		
0		S_0	S_1		
1		S_2	S_3		

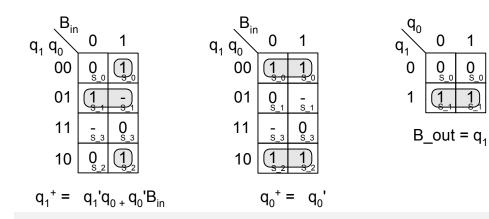
SERIAL LINE CODE CONVERTER - MOORE FSM (Cont.)

Encoded State Table:

				output
	$q_1^{} q_0^{}$	$q_{1}^{+}q_{0}^{+}$		
		input		
		0	1	
S_0	00	01	11	0
S_1	01	10	-	0
S_3	11	-	00	1
S_2	10	01	11	1



Karnaugh Maps



SERIAL LINE CODE CONVERTER - MOORE FSM (Cont.)

🔡 SILOS - e:V	simulation res	ults\slcc_moore.spj - [Data Analyzer] 💦 📃 🗙
<u>Eile E</u> dit	⊻iew <u>P</u> roject	E <u>x</u> plorer <u>R</u> eports <u>D</u> ebug <u>O</u> ptions <u>W</u> indow <u>H</u> elp
		<u> 코</u> ×
28	😡 88 🔵	Command:
<u>@</u> @@	2 <2 <1	
Name	0,,,,	80 160
🖻 Default		NRZ bit time
clock_1		
clock_2		
reset		
state[1:0]	<u>(X1X2X3</u>	X0 <u>X</u> 3X0X3X0X1X2X1X2X3X0X1X2X1X2X1XX
B_in		
B_out		
		← Manchester bit time
•		
For Help, press F	1	T1 T2 Tdelta Time 200 //

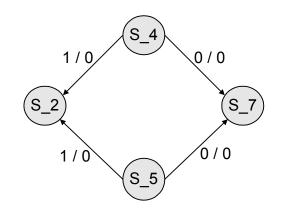
The Manchester encoder must run at twice the frequency of the incoming data.

The output bit stream lags the input bit stream by one-half the input cycle time.

EQUIVALENT STATES (p 95)

Two states are equivalent if they have the same next state and output for all inputs. Equivalent states can be combined without changing the input/output behavior of the machine. Combine equivalent states to simplify the state table and the STG. For every FSM there is a unique equivalent machine that is minimal.

		Next S	Output		
		Inpu	t	Input	
	State	0 1		0	1
Equivalent States	\$_0 \$_1 \$_2 \$_3 \$_4 \$_5 \$_6 \$_7	S_6 S_1 S_2 S_7 S_7 S_7 S_7 S_0 S_4S_5	S_3 S_6 S_5 S_3 S_2 S_2 S_1 S_1 S_1 S_3	0 0 0 0 0 0 0	0 1 1 0 0 0 0



COMBINATION OF EQUIVALENT STATES

Consider conditions for pair-wise equivalence and eliminate states that cannot be equivalent. Form an array representing pair-wise combinations of states.

(1) Eliminate cells that have a different output for the same input (Shaded cells)

(2) For the remaining states, identify the conditions that are necessary for equivalence, and enter into the array (Labeled cells).

The remaining cells identify equivalent states.

S_1						
S_2		S_6 - S_4				
S_3		S_1 - S_7 S_6 - S_3	S_2 - S_7 S_4 - S_3			
S_4	S_6 - S_7 S_3 - S_2					
S_6	S_3 - S_1				S_7 - S_0 S_2 - S_1	
S_7	S_6 - S_4				S_2 - S_3	S_0 - S_4 S_1 - S_3
	S_0	S_1	S_2	S_3	S_4	S_6

COMBINATION OF EQUIVALENT STATES (Cont.)

	Next S	Output		
	Inpu	Inp	out	
State	0	1	0	1
S_0 S_1 S_3 S 4	S_4	S_3	0	0
S_1	S_4 S_1	S_3 S_4 S_3	0	1
S_3	S_0	S_3	0	1
S_4	S_0	S_1	0	0

COMBINATION OF EQUIVALENT STATES (Cont.)

(3) Strike out any cells having the label of a shaded state-pair. (Labeled cells with \).

(4) Remove cells that have a label that has been struck out in (3) (Shaded cells with labels).

S_1						
S_2		S_6 - S_4				
S_3		S_1 - S_7 S_6 - S_3	\$_2-\$_7 \$_4-\$_3			
S_4	S_6 - S_7 S_3 - S_2					
S_6	S_3 - S_1				S_7 - S_0 S_2 - S_1	
S_7	S_6 - S_4				S_2 - S_3	S_0 - S_4 S_1 - S_3
	S_0	S_1	S_2	S_3	S_4	S_6