# All-Optical Humidity Sensor Using SnO<sub>2</sub> Nanoparticle Drop Coated on Straight Channel Optical Waveguide

Nur Abdillah SIDDIQ<sup>1\*</sup>, Wu Yi CHONG<sup>2</sup>, Yono Hadi PRAMONO<sup>1</sup>, Melania Suweni MUNTINI<sup>1</sup>, Asnawi ASNAWI<sup>1,3</sup>, and Harith AHMAD<sup>2,4</sup>

<sup>1</sup>Department of Physics, Institut Teknologi Sepuluh Nopember, Surabaya 60111, Indonesia

<sup>2</sup>Photonics Research Centre, University of Malaya, Kuala Lumpur 50603, Malaysia

<sup>3</sup>Department of Physics, Surabaya State University, Surabaya 60231, Indonesia

<sup>4</sup>Department of Physics, Faculty of Science and Technology, Airlangga University, Surabaya 60115, Indonesia

\*Corresponding author: Nur Abdillah SIDDIQ E-mail: siddiq16@mhs.physics.its.ac.id

**Abstract:** The straight channel optical waveguide coated with the  $SnO_2$  nanoparticle is studied as an all-optical humidity sensor. The proposed sensor shows that the transmission loss of the waveguide increases with increasing relative humidity (RH) from 56% to 90% with very good repeatability. The sensitivity to changes in relative humidity is ~2 dB/% RH. The response time of the humidity sensor is 2.5 s, and the recovery time is 3.5 s. The response to humidity can be divided into 3 different regions, which are correlated to the degree of water adsorption in the SnO<sub>2</sub> nanoparticle layer. Compared with the previous all-optical humidity sensor based on SnO<sub>2</sub>, the proposed sensor exhibits more rapid response, simpler fabrication process, and higher sensitivity. The proposed sensor has a potential application in the long distance, remote agriculture, and biological humidity sensing.

Keywords: Humidity measurement; SnO<sub>2</sub> nanoparticle; optical sensors

Citation: Nur Abdillah SIDDIQ, Wu Yi CHONG, Yono Hadi PRAMONO, Melania Suweni MUNTINI, Asnawi ASNAWI, and Harith AHMAD, "All-Optical Humidity Sensor Using SnO<sub>2</sub> Nanoparticle Drop Coated on Straight Channel Optical Waveguide," *Photonic Sensors*, 2020, 10(2): 123–133.

# 1. Introduction

Aside from temperature, relative humidity (RH) is one of the most frequently measured physical qualities in advance applications such as material processing and manufacturing [1, 2]. Recently, a number of humidity sensors with response time of less than 1 s have been developed. These sensors can be categorized into electrical, acoustic, and optical systems. Among these sensors, the fastest response time to humidity changes is 3 ms, demonstrated in an optical system [3], compared with 8 ms in the electrical system [4] and 1 s in the acoustical system

[5]. Besides exhibiting the fastest response time, all-optical humidity sensors also have advantages such as immunity to electromagnetic interference and nuclear radiation (for high-energy physics application), water and corrosion resistance, and ability to operate in low temperature environment. Fiber-based optical sensors also allow long-range transmission of optical signals with very low loss, enabling sensor probes to be deployed in remote areas [6, 7].

The main parameter that dictates the humidity sensor performance is the rate of change in a material property to the change in the surrounding

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DOI: 10.1007/s13320-019-0563-8

Received:10 January 2019 / Revised: 3 May 2019

Article type: Regular

relative humidity. Among various materials for humidity sensors, metal oxides nanoparticles have attracted special interest due to their high surface contact area with water molecules, controllable porosity, nano-sized grains, low cost, and simple construction [8-11]. Tin (IV) oxide or SnO<sub>2</sub> (an n-type semiconductor) is one of the useful and popular materials for humidity sensing from metal oxide group and offers a potential for developing portable and inexpensive humidity sensing device [12]. Besides that, the reason why  $SnO_2$  is broadly used in the humidity sensor research is that it possesses many unique optical and electrical properties like wide band gap ( $E_g$ = 3.6 eV at 300 K), remarkable receptivity variation in the gaseous environment, high optical transparency in the visible range (up to 97%), low resistivity, and excellent chemical stability [13]. Various nanostructures of SnO<sub>2</sub> like nanowire and nanofiber [12, 13] have been studied as the humidity sensor based on the interdigitated electrode configuration. The performance of the SnO<sub>2</sub> nanostructure is remarkably superior as the humidity sensor, but there is some drawback in developing these sensors in the electronic system such as the complexity of fabrication, the use of gold (Au) as an electrode that will increase the fabrication cost, and the signals generated are prone to electromagnetic interference.

Using SnO<sub>2</sub> as a sensing material for all-optical humidity sensing has been reported in [14] based on a planar slab optical waveguide and in [7, 15] based on the optical fibers. The range of relative humidity measured by the planar slab optical waveguide based sensor (3% RH – 98% RH) is broader than the values reported by the optical fiber based sensors (20% RH – 90% RH). In this paper, we report an all-optical humidity sensor in the form of the SnO<sub>2</sub> nanoparticle layer coated on a planar stripe optical waveguide. SnO<sub>2</sub> nanoparticle layer coating is achieved by using the simple drop coating technique, which is a simple and effective method to fabricate the humidity sensor [4, 16]. The major improvement introduced in the present research is the simple coating method of the  $SnO_2$  nanomaterial onto a planar optical waveguide. The proposed all-optical humidity sensor responds to the relative humidity change between 56% RH and 90% RH with a sensitivity of ~2 dB/% RH, a very good repeatability, and a response time.

The range of relative humidity response is broader than that of other optical humidity sensors such as the microfiber tapered-based humidity sensor using the ZnO nanoparticle layer (50% RH – 70% RH) [17] and the microfiber coupler-based humidity sensor using polyethylene oxide (70% RH – 85% RH) [18]. The sensitivity is also higher than that of the microfiber humidity sensor using ZnO nanorods (0.5221 dB/% RH) [19]. Therefore, all optical humidity sensors based on the SnO<sub>2</sub> nanoparticles have a potential for being used in high-energy physics applications and long-distance humidity sensing that require the fast response time.

# 2. Device fabrication and experiment

A silicon wafer with  $7 \mu m$  of thermal oxide (TO<sub>x</sub>) layer was used as the substrate and undercladding layer for the optical waveguide. Germanium and boron codoped silica layer were then deposited onto the substrate as a core layer. The core layer was patterned by using photolithography and etched by using inductively coupled plasma (ICP) etching followed by spin coating of ZPU13 polymer (ChemOptics, Korea) as the overcladding. To enable exposure of the propagating light field in the core to the surrounding, the ZPU13 polymer coating was etched by using oxygen plasma etching down to the top surface of the waveguide core.

Meanwhile,  $SnO_2$  solution was prepared by dissolving 200 mg of  $SnO_2$  nanopowder (Sigma Aldrich) with 20 ml of deionized (DI) water to obtain 1 wt% of solution concentration. The mixture was then ultrasonicated for 1 hour at the room temperature to homogenously disperse the nanopowder. A drop of  $0.5 \,\mu L \, SnO_2$  solution was applied onto the waveguide and then allowed to dry under the ambient condition. The time taken for the SnO<sub>2</sub> droplet to dry in the ambient environment is approximately 8 minutes. Drop coating of the SnO<sub>2</sub> layer was demonstrated in [20], which produced a room temperature gas sensor. But instead of using large droplet volume of  $>5 \mu$ L, multiple-drop -coating of smaller droplet volume (0.5 µL for three times) was used in this work to produce a  $SnO_2$ nanoparticle layer with a smaller coverage area, preventing cracking of the film and increasing the adhesion between the sensing film and the planar waveguide. In addition, the multiple-drop-coating technique was also reported in [16] in coating graphene oxide layer on optical waveguides to achieve humidity sensing.

To create a controlled relative humidity environment, a homemade humidity box with controlled relative humidity between 20% RH and 90% RH was set up as depicted in Fig. 1. Two analogue mass flow controllers (MFC) were used to control the flow rate of nitrogen gas. To increase the relative humidity in the box, nitrogen gas was mixed in the mixing chamber containing deionized water to produce humid air. Meanwhile, to decrease the humidity, dry nitrogen was introduced directly to the box. A hygrometer (HI 8562 Hanna Instruments) was used to calibrate the relative humidity in the humidity box.

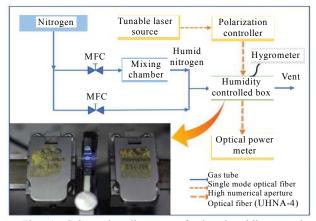


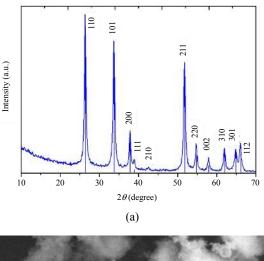
Fig. 1 Schematic diagram of the humidity sensing measurement system (inset) with the  $SnO_2$  nanoparticle coated on the straight channel optical waveguide.

The fiber butt-coupling technique was used for light coupling with the SnO<sub>2</sub> coated waveguide. The optical source was a C-band tunable laser source (ANDO 4321). It was connected to a fiber polarization controller (PC) by using a standard optical fiber patch cord. single-mode The polarization controller output was connected to a standard fiber pigtail, with the other end fusion spliced to high numerical aperture optical fiber (Nufern UNHA-4) to achieve a better mode matched with the SnO<sub>2</sub> coated waveguide. A pair of 5-axis fiber alignment stages (Newport M-562-XYZ) were used to obtain the maximum coupling between the fibers and the waveguide as shown in the inset of Fig. 1. The transmitted power was measured by using an optical power meter (THORLABS S144C). Care was taken to keep the fiber to waveguide connection unaffected during measurement. The PC was adjusted to obtain the highest optical transmittance through the SnO<sub>2</sub> coated waveguide. In this case, The TM polarization was used, which showed a higher optical transmission than TE polarization.

# 3. Results and discussion

#### 3.1 Characterizations of SnO<sub>2</sub> nanoparticles

The X-ray diffraction (XRD) pattern and scanning electron microscope (SEM) image of SnO<sub>2</sub> nanoparticles are shown in Fig. 2. Based on the XRD result depicted in Fig. 2(a), all reflection peaks of SnO<sub>2</sub> nanoparticles match well with the diffraction pattern of the tetragonal rutile SnO<sub>2</sub> structure (JCPDS Card No 41-1445). Impurity peaks are not observed in the XRD pattern, which means the SnO<sub>2</sub> nanoparticles are pure and have only the tetragonal rutile structure. The crystallite size can be estimated by using the Debye-Scherer formula  $D=k\lambda/(\beta\cos\theta)$ [10], where k = 0.94 is the shape factor,  $\lambda =$ 0.1541874 nm is the Cu-K $\alpha$  wavelength, and  $\beta =$ 0.1 rad is the full width at half maximum of the peak. The highest intensity peak, centered at  $2\theta=26.65^{\circ}$ , can be assigned to  $\text{SnO}_2$  [110] reflection having *d*-spacing of 3.3447 Å, and the crystallite size (*D*) is 27.08 nm. Meanwhile, the SEM image of  $\text{SnO}_2$  as shown in Fig. 2(b) indicates that the grain size of  $\text{SnO}_2$  is larger than the crystallite size calculated with the XRD pattern. We believe that the agglomeration of  $\text{SnO}_2$  nanoparticles took place, which resulted in a larger  $\text{SnO}_2$  grain [21].



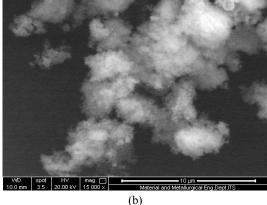
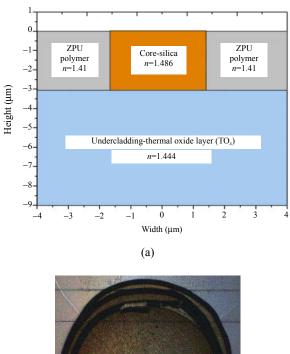


Fig. 2 Characterization of  $SnO_2$  nanoparticles: (a) XRD pattern of  $SnO_2$ , indicating that the nanoparticles are tetragonal rutile shaped and (b) SEM images of  $SnO_2$  nanoparticles.

### 3.2 Humidity sensing test

The structure of the fabricated waveguide is shown in Fig. 3(a). Both the height and width of the waveguide core were  $3 \mu m$ . Then, the microscope image of the drop coated SnO<sub>2</sub> layer on the optical waveguide is depicted in Fig. 3(b). The coffee ring effect during the drying process can be clearly seen, which is attributed to the symmetrical dimension of the SnO<sub>2</sub> nanoparticles. The insertion loss of uncoated straight waveguide was 12.7 dB. After coating with 3 drops of SnO<sub>2</sub>, the insertion loss increased from 2 dB to 14.7 dB. The resulting SnO<sub>2</sub> coating with  $0.5 \,\mu$ L SnO<sub>2</sub> solution had a diameter of 1.4 mm, and its average thickness was measured by using a Dektak D150 surface profiler and found to be about 2.27  $\mu$ m as shown in Fig.4(a). The effect of drop coating volume to average thickness and diameter of the resulting SnO<sub>2</sub> coating is depicted in Fig. 4(b). It can be seen that an increase in the droplet volume will increase the thickness and diameter from 1.82  $\mu$ m to 8.2  $\mu$ m and 1.2 mm to 2.2 mm, respectively.





(b)

Fig. 3 Proposed device as a humidity sensor: (a) cross section of the proposed device before coating with  $SnO_2$  nanoparticle and (b) photo of drop coated  $SnO_2$  in the top of optical channel waveguide.

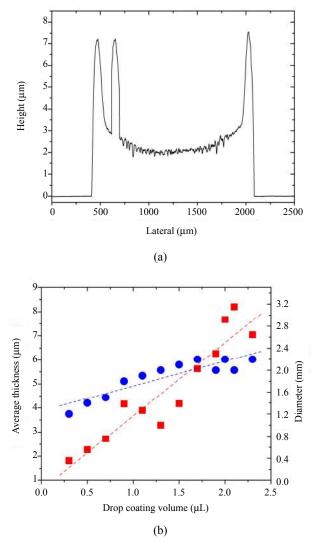


Fig. 4 SnO<sub>2</sub> film: (a) surface profile obtained from Dektak D150 with drop coating volume of  $0.5 \,\mu\text{L}$  and (b) effect of drop coating volume to the average thickness and diameter of SnO<sub>2</sub> coating at three times drop process.

For a clearer interpretation of proposed sensor response to humidity changes, optical attenuation was used instead of the measured transmitted power. The optical attenuation (*Loss*) is defined as

$$Loss = P_{\rm init} - P_{\rm RH} \tag{1}$$

where  $P_{\text{init}}$  and  $P_{\text{RH}}$  are transmitted power in the initial condition (ambient condition) and transmitted power at a certain value of relative humidity, respectively.

Figure 5 shows the change in the optical attenuation when the humidity was increased from 20% RH to 90% RH. The optical attenuation increased, corresponding to a decrease in the

transmitted power through the  $SnO_2$  coated waveguide, when the relative humidity was increased. The magnitude of optical attenuation also increased with an increase in the relative humidity, indicating that this response could be used for relative humidity measurement. The proposed sensor showed a poor response towards the change in the relative humidity level below 56% RH. The flat response of SnO<sub>2</sub> based sensor in the range of below 60% RH was also reported in [12] and in [22] that was based on the field-effect transistor (FET) nanodevice because the pure SnO<sub>2</sub> did not show a significant change in the impedance until humidity reached as high as 60% RH, while a significant response was observed in the humidity level between 56% RH and 90% RH with the attenuation increasing from 2.9dB to 56.9dB. Due to the range limitation of the calibration hygrometer and homemade humidity box, the changes in the relative humidity from 0 to 20% RH and 90% RH to 100% RH were not measured.

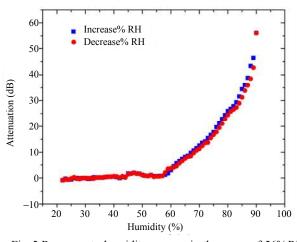


Fig. 5 Response to humidity occurrs in the range of 56% RH to 90% RH.

Figure 6 shows the response of  $\text{SnO}_2$  coated optical waveguide to changes in the relative humidity from ambient condition (~54% RH) to different values of higher relative humidity (%RH). It can be seen that the proposed sensor shows an excellent reversible response to changes in %RH. The sensitivity of the proposed sensor is calculated to be ~2 dB/% RH. The high sensitivity of the proposed sensor is attributed to the nanosize of the  $SnO_2$  nanoparticles (27.08 nm) used in this work. The smaller size of  $SnO_2$  corresponds to the larger surface area, which increases water adsorption and results in a better sensitivity of the sensor [23]. Note that the response time in Fig.6 is relatively longer compared with the other all-optical humidity sensors

[14, 16], which were limited by the relatively large humidity box [ $50 \times 40 \times 12 \text{ (cm}^3$ )] that was not hermetically sealed. The large box was used instead of small box to cover a pair of 5-axis fiber alignment stages. However, the large humidity box is not suitable for studying the response and recovery time because of the slow humidity adjustment rate.

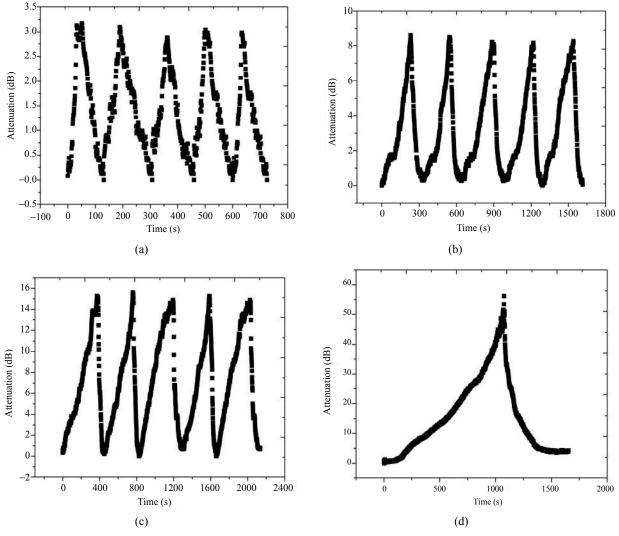


Fig. 6 Change in attenuation when humidity increases in the humidity-controlled box at (a) 63% RH, (b) 66% RH, (c) 70% RH, and (d) 90% RH.

In order to measure the response time of the proposed sensor itself, exhaling from a person (with near 100% RH measured by using a hygrometer) was introduced to the sensor in the ambient condition (54% RH). The result is shown in Figs. 7(a) and 7(b). The proposed sensor exhibited a fast response to the presence and absence of humid air

flow. From Fig. 7(b), the response time of less than 2.5 s and recovery time of less than 3.5 s were observed in the RH measurements. The response (increase) slope seemed to have a larger gradient than the recovery slope (decrease), and the similar response/recovery curves were also reported in other optical humidity sensors [15]. The response time

and recovery time of the proposed sensor were faster than that reported in [14] whose response time and recovery time were 3s and 10 minutes, respectively. In addition, the recovery time was faster than that of the fiber optic-based sensor [15]. The comparison of this work with previous all-optical sensor based  $SnO_2$  nanoparticle is shown in Table 1.

Table 1 Comparison between this work and previous work in all-optical humidity sensor with based SnO2 nanoparticles.

Parameter	Based planar optical waveguide [14]	Based optical fiber		This work
		[7]	[15]	This work
SnO <sub>2</sub> location	Cladding of planar optical waveguide	End of the optical fiber	On the tapered fiber	Uppercladding of planar optical waveguide
SnO <sub>2</sub> deposition	Screen printing	Electrospray pyrolysis	Sputtering	Drop coating
Thickness of SnO <sub>2</sub>	20 µm	Hundreds of nanometers	280 nm	2.27 µm
Width of SnO <sub>2</sub>	Length 4 mm	Diameter 125 µm	Length 4.2 mm	Diameter 1.4 mm
Response time	3 s	-	1.5 s	2.5 s
Recovery time	10 min	-	4 s	3.5 s
Range of humidity measurement	3% RH – 98% RH	2% RH – 40 % RH	20% RH – 90% RH	56% RH – 90% RH

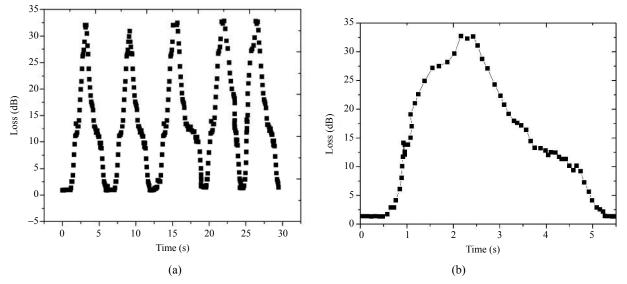


Fig. 7 Response time of the proposed sensor: (a) periodic response/recovery curves of the proposed sensor exposed to nearly 100% RH from ambient humidity (54% RH) and (b) a single response/recovery curves.

#### 3.3 Analysis of humidity sensing ability

To ascertain the polarization dependency of light transmission through the  $SnO_2$  coated waveguide, the polarization dependent loss was measured. The optical polarization state of light incident upon the  $SnO_2$  coated waveguide was changed by adjusting the polarization controller, and the polarization states of light at the waveguide output was measured by using a polarimeter (Thorlabs PAX 5710). The result is shown in Fig. 8. It can be seen that  $SnO_2$ 

film does not have significant polarization selection characteristics at different laser pump powers or wavelengths, which means that the response of the proposed sensor to relative humidity change is not polarization dependent.

By analyzing the results obtained, a model of water adsorption mechanism in the  $SnO_2$  layer is proposed and shown in Fig. 9. Figures 9(a) and 9(b) show photos of the  $SnO_2$  coating on the proposed waveguide at ambient humidity (~54% RH) and humid air (~100% RH), respectively. A few water

droplets indicated by bright spots can be seen on the surface of the SnO<sub>2</sub> coating. When humid air from person exhaling was introduced, these spots became more apparent and appeared to be joining up because water droplet in the SnO<sub>2</sub> layer surface was reflecting the camera light [24]. We believe that this indicates water permeation into the SnO<sub>2</sub> film, which reduced the beam confinement in the waveguide and resulted in an increase in the light transmission loss. Figure 9(c) shows the water adsorption mechanism of our proposed model. At lower humidity (< 56% RH), the water vapors only adhered onto the surface of the SnO2 layer. At intermediate humidity (56%RH - 86%RH), a small amount of water penetrated into the SnO<sub>2</sub> layer, which caused a small radiation loss and affected the transverse guiding of light in the cladding. Meanwhile, at higher humidity (>86% RH), water was adsorbed in huge amount into the volume of the film, therefore causing a significant radiation loss. This mechanism helps to explain the observation in Fig. 5, which have 3 slopes: (a) slope below 56% RH that indicates the surface adsorption of water by the SnO<sub>2</sub> layer, (b) slope between 56% RH and 86% RH that indicates the increasing adsorption of water by the  $SnO_2$  layer, and (c) slope above 86% RH that indicates near saturated adsorption of water by the SnO<sub>2</sub> layer. The proposed sensor's insensitivity to relative humidity lower than 56% RH might be caused by the thickness of the film which resulted in a very small water adsorption level which could not affect the light confinement in the waveguide core significantly.

The ability to introduce  $\text{SnO}_2$  coating by using the drop coated method provides a simple and effective means for humidity sensor fabrication. The proposed sensor can operate in the humidity range from 56% RH to 90% RH. This relative humidity range is widely used in agricultural and biological applications, such as feeding room, greenhouse, and proving room [25].

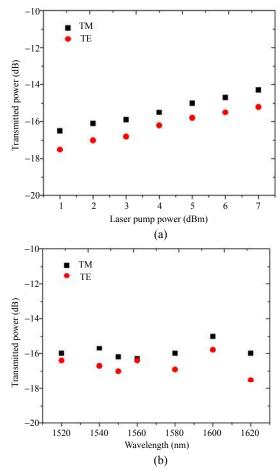


Fig. 8 Response of transmitted power to TE and TM polarizations for different pump powers (a) and wavelengths (b).

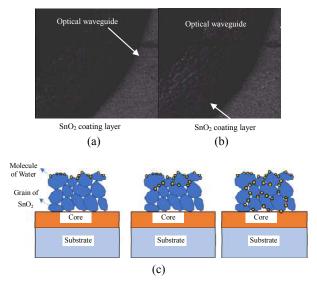


Fig. 9 Absorption phenomenon in different conditions of humidity: (a) before humid air was introduced in the ambient environment, (b) when humid air from exhaling was introduced, and (c) schematic of water absorptions at low humidity, intermediate humidity, and large humidity.

# **3.4 Comparison with another all-optical humidity sensor**

Many works have also been reported on optical humidity sensor based on optical fiber with various structures, such as side-polished/D-shaped [26], tapered [27], and U-bend [28]. The fastest response time reported to date was achieved by using a U-bend microfiber (3 ms) [3]. However, since the uses of these fibers require the removal of the fiber cladding, the mechanical strength of the fibers is compromised [29]. In addition, this fabrication process is also relatively time consuming [30].

The planar waveguide, on the other hand, is relatively strong. The waveguide core can be exposed by using a standard etching process used in the established semiconductor manufacturing industry. In terms of mass production, the planar waveguide-based sensor is much more attractive than their optical fiber counterparts because it allows mounting of miniature integrated optical circuits onto a single substrate platform [31]. In addition, accurately localized deposition of  $SnO_2$  drop coatings can be achieved in mass production by use of an automated micropipette positioning and dispensing system.

In terms of the sensing material, various sensing materials such as Ag-polyaniline [32], graphene oxide [18], reduced graphene oxide [33], and titanium oxide [34], have been used on the planar optical waveguide. A comparison of their performances is summarized in Table 2. It can be seen that the sensitivity of the proposed sensor is higher than that of another sensor, but the measurement range and response time are still to be improved. This can be achieved with the removal of the coffee ring effect by using the ion doping like KCl [12] or Ag [35], composited with graphene oxide [36–38], MoS<sub>2</sub> [39], or TiO<sub>2</sub> [40] to achieve a broader measurement range and a shorter response time.

Table 2 Comparison between various materials of planar optical waveguide as humidity sensor for interval 2008–2018.

Reference	Year	Sensing material	Range	Sensitivity	Response time
[32]	2008	Ag-polyaniline	20% RH–92% RH	35.6 mV/% RH	8 s
[18]	2014	Graphene oxide (GO)	60% RH-100% RH	0.553 dB/% RH	~1 s
[33]	2016	Reduced-GO	35% RH–95% RH	0.22 dB/% RH	0.68 s
[34]	2016	TiO <sub>2</sub>	35% RH–95% RH	0.21 dB/% RH	0.72 s
ThisWork	2018	$SnO_2$	56% RH–90 % RH	2 dB/% RH	2.5 s

# 4. Conclusions

The humidity sensing ability of a  $SnO_2$ -coated planar optical waveguide by the simple multiple drop coating method has been studied. The loss of the proposed sensor is found to be affected by the relative humidity of its surroundings. A decrease in the transmitted power at higher humidity is due to water adsorption that radiates light from the core. The proposed sensor exhibits a fast response of less than 2.5 s to humid air. In addition, it shows a good sensitivity of ~2 dB/% RH in the humidity range from 56% RH to 90% RH with a very good repeatability. The proposed sensor has a potential application in the long distance and remote agricultural and biological humidity sensing.

# Acknowledgment

This work is partially supported by the Ministry of Research, Technology & Higher Education of Indonesia with PMDSU scholarship funding, and the Malaysia Ministry of Higher Education (MOHE) (LRGS(2015)/NGOD/UM/KPT). We thank Gan and Wensin for assistance during the humidity measurement preparation and waveguide fabrication. **Open Access** This article is distributed under the terms of the Creative Commons Attribution 4.0 International License (http://creativecommons.org/licenses/by/4.0/), which permits unrestricted use, distribution, and reproduction in any medium, provided you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons license, and indicate if changes were made.

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