Research Article



Journal of Nonlinear Science and Applications Print: ISSN 2008-1898 Online: ISSN 2008-1901



# Almost Kenmotsu 3-*h*-manifolds with cyclic-parallel Ricci tensor

Wenjie Wang

Henan Engineering Laboratory for Big Data Statistical Analysis and Optimal Control, School of Mathematics and Information Sciences, Henan Normal University, Xinxiang 453007, Henan, P. R. China.

Communicated by R. Saadati

# Abstract

In this paper, we prove that the Ricci tensor of an almost Kenmotsu 3-*h*-manifold is cyclic-parallel if and only if it is parallel and hence, the manifold is locally isometric to either the hyperbolic space  $\mathbb{H}^3(-1)$ or the Riemannian product  $\mathbb{H}^2(-4) \times \mathbb{R}$ . ©2016 All rights reserved.

*Keywords:* Almost Kenmotsu 3-manifold, almost contact metric manifold, Einstein-like metric, cyclic-parallel Ricci tensor. 2010 MSC: 53D15, 53C25.

# 1. Introduction

Let us recall the following notions defined by Gray [13]. A pseudo-Riemannian manifold (M, g) is said to belong to class  $\mathcal{A}$  if its Ricci operator Q is cyclic-parallel, that is,

$$g((\nabla_X Q)Y, Z) + g((\nabla_Y Q)Z, X) + g((\nabla_Z Q)X, Y) = 0$$

$$(1.1)$$

for any vector fields X, Y, Z tangent to M. It is known that (1.1) is equivalent to requiring that the Ricci tensor is a Killing tensor, that is,

$$g((\nabla_X Q)X, X) = 0 \tag{1.2}$$

for any vector field X on M. Moreover, (M, g) is said to belong to class  $\mathcal{B}$  if its Ricci operator Q is of Codazzi-type, that is,

$$(\nabla_X Q)Y = (\nabla_Y Q)X \tag{1.3}$$

Received 2016-04-14

Email address: wangwj072@163.com (Wenjie Wang)

for any vector fields X, Y tangent to M. Here, we remark that equation (1.3) is also equivalent to requiring that the Riemannian curvature tensor is harmonic, that is,  $\operatorname{div} R = 0$ . In addition, (M, g) is said to belong to class  $\mathcal{P}$  if its Ricci operator Q is parallel, that is,

$$\nabla Q = 0. \tag{1.4}$$

A. Gray in [13] obtained an interesting result, namely  $\mathcal{E} \subset \mathcal{P} = \mathcal{A} \cap \mathcal{B}$ , where  $\mathcal{E}$  denotes the class of all Einstein manifolds. A semi-Riemannian metric whose Ricci tensor satisfying relations (1.1), (1.3) or (1.4) is called an Einstein-like metric.

Many authors studied equations (1.1)-(1.4) on some types of almost contact metric manifolds and some other manifolds. For examples, Gouli-Andreou and Xenos in [12] proved that a k-contact metric manifold of dimension 2n + 1 satisfying equation (1.3) is locally isomeric to either an Einstein-Sasakian manifold or the product space  $\mathbb{S}^n(4) \times \mathbb{R}^{n+1}$ . Moreover, they proved that a contact metric 3- $\tau$ -manifold satisfying equation (1.3) is either flat or an Einstein-Sasakian manifold. Gouli-Andreou et al. in [11] proved that a complete three-dimensional ( $\kappa, \mu, \nu$ )-contact metric manifold satisfying (1.1) is either Sasakian or a ( $\kappa, \mu$ )contact metric manifold. De and Pathak [7] obtained that a three-dimensional Kenmotsu manifold has a cyclic-parallel Ricci tensor if and only if the manifold is of constant sectional curvature -1. Generalizing this result, the cyclic-parallel Ricci tensors on three-dimensional normal almost contact metric manifolds were also studied by De and Mondal [6]. For more results regarding Equations (1.1)-(1.4) on some semi-Riemannian manifolds and almost contact metric manifolds, we refer reader to De et al. [5, 8], Calvaruso [2], Wang [18, 20, 22] and the present author [19].

We remark that Cho [3] and Wang [18] recently obtained an interesting local classification of an almost Kenmotsu 3-manifold, namely any almost Kenmotsu 3-manifold is locally symmetric if and only if it is locally isometric to either the hyperbolic space  $\mathbb{H}^3(-1)$  or the Riemannian product  $\mathbb{H}^2(-4) \times \mathbb{R}$ . We observe that almost Kenmotsu 3-manifolds under some additional geometric conditions were also investigated by Cho [4] and Wang [20, 21], respectively. Note that (1.4) implies (1.1) trivially, however the converse is not necessarily true. Therefore, in this paper we aim to present an extension of the corresponding results shown in [3, 18] on a special class of three-dimensional almost Kenmotsu manifolds. Our main results is to show that the equations (1.1)-(1.4) are equivalent to each other on an almost Kenmotsu 3-*h*-manifold.

#### 2. Almost Kenmotsu manifolds

A smooth manifold  $M^{2n+1}$  of dimensional 2n+1 is called an almost contact metric manifold if it admits an almost contact structure  $(\phi, \xi, \eta)$ , that is, there exist a (1, 1)-type tensor field  $\phi$ , a global vector field  $\xi$ and a 1-form  $\eta$  such that

$$\phi^2 = -\mathrm{id} + \eta \otimes \xi, \ \eta(\xi) = 1,$$
  

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y)$$
(2.1)

for any vector fields X, Y tangent to  $M^{2n+1}$ , where id denotes the identity map and  $\xi$  is called the Reeb vector field. On the product manifold  $M^{2n+1} \times \mathbb{R}$  of an almost contact manifold  $M^{2n+1}$  and  $\mathbb{R}$ , one can define an almost complex structure J by

$$J\left(X, f\frac{d}{dt}\right) = \left(\phi X - f\xi, \eta(X)\frac{d}{dt}\right),$$

where X denotes the vector field tangent to  $M^{2n+1}$ , t is the coordinate of  $\mathbb{R}$  and f is a smooth function. An almost contact structure is said to be normal if the above almost complex structure J is integrable, that is, J is a complex structure. According to Blair [1], the normality of an almost contact structure is given by  $[\phi, \phi] = -2d\eta \otimes \xi$ , where  $[\phi, \phi]$  denotes the Nijenhuis tensor of  $\phi$  defined by

$$[\phi, \phi](X, Y) = \phi^{2}[X, Y] + [\phi X, \phi Y] - \phi[\phi X, Y] - \phi[X, \phi Y]$$

From [1] and [15], an almost contact metric manifold is called

- (1) a contact metric manifold if  $d\eta = \Phi$ ;
- (2) an almost Kenmotsu manifold if  $d\eta = 0$  and  $d\Phi = 2\eta \wedge \Phi$ ;
- (3) an almost cosymplectic manifold if  $d\eta = 0$  and  $d\Phi = 0$ .

A normal contact metric (resp. almost Kenmotsu, almost cosymplectic) manifold is called a Sasakian (resp. Kenmotsu, cosymplectic) manifold.

We denote by  $h = \frac{1}{2}\mathcal{L}_{\xi}\phi$  and  $h' = h \circ \phi$  on an almost Kenmotsu manifold  $M^{2n+1}$ . Following [9, 10], it is seen that both h and h' are symmetric operators and the following formulas are true.

$$h\xi = l\xi = 0, \ \mathrm{tr}h = \mathrm{tr}(h') = 0, \ h\phi + \phi h = 0,$$
 (2.2)

$$\nabla \xi = h' + \mathrm{id} - \eta \otimes \xi, \tag{2.3}$$

$$\phi l\phi - l = 2(h^2 - \phi^2), \tag{2.4}$$

$$\nabla_{\xi}h = -\phi - 2h - \phi h^2 - \phi l, \qquad (2.5)$$

$$\operatorname{tr}(l) = S(\xi, \xi) = g(Q\xi, \xi) = -2n - \operatorname{tr} h^2,$$
(2.6)

where  $l := R(\cdot, \xi)\xi$  is the Jacobi operator along the Reeb vector field and the Riemannian curvature tensor R is defined by

$$R(X,Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,Y]} Z,$$

tr and S denote the trace operator and the Ricci tensor, respectively.

## 3. Almost Kenmotsu 3-h-manifolds with cyclic-parallel Ricci tensors

We first give the following definition.

**Definition 3.1.** A three-dimensional almost Kenmotsu manifold is called an almost Kenmotsu 3-*h*-manifold if it satisfies  $\nabla_{\xi} h = 0$ .

It is known that on a three-dimensional Kenmotsu manifold there holds h = 0 and hence  $\nabla_{\xi} h = 0$ holds trivially. However, Dileo and Pastore [9, Proposition 6] proved that even on a locally symmetric non-Kenmotsu almost Kenmotsu manifold there still holds  $\nabla_{\xi} h = 0$ . By using this condition, Wang [20, 21] gave some local classifications of three-dimensional almost Kenmotsu manifolds. He also presented some examples of three-dimensional almost Kenmotsu manifolds on which  $\nabla_{\xi} h = 0$  but  $h \neq 0$ .

**Example 3.2** ([21]). Let G be a three-dimensional non-unimodular Lie group (see [17]) with a left invariant local orthonormal frame fields  $\{e_1, e_2, e_3\}$  satisfying

$$[e_1, e_2] = \alpha e_2 + \beta e_3, \ [e_2, e_3] = 0, \ [e_1, e_3] = \beta e_2 + (2 - \alpha)e_3$$

for  $\alpha, \beta \in \mathbb{R}$ . If either  $\alpha \neq 1$  or  $\beta \neq 0$ , G admits a left invariant non-Kenmotsu almost Kenmotsu structure satisfying  $\nabla_{\xi} h = 0$  and  $h \neq 0$ .

For almost Kenmotsu structures defined on three-dimensional non-unimodular Lie groups we refer the reader to Dileo and Pastore [10, Section 5]. From Example 3.2, although there exist many examples of almost Kenmotsu 3-*h*-manifolds, but not all non-Kenmotsu almost Kenmotsu 3-manifolds satisfy  $\nabla_{\xi} h = 0$ .

$$R(X,Y)\xi = k(\eta(Y)X - \eta(X)Y) + \mu(\eta(Y)hX - \eta(X)hY) + \nu(\eta(Y)h'X - \eta(X)h'Y)$$
(3.1)

for any vector fields X, Y, Z and some smooth functions  $k, \mu, \nu$ . Then, if either  $\mu \neq 0$  or  $\nu \neq -2$ , then we have  $\nabla_{\xi} h = \mu h' - (\nu + 2)h \neq 0$  provided that  $h \neq 0$  (or equivalently, k < -1).

Let us recall some useful formula shown in Cho [4]. Let  $\mathcal{U}_1$  be the open subset of a three-dimensional almost Kenmotsu manifold  $M^3$  such that  $h \neq 0$  and  $\mathcal{U}_2$  the open subset of  $M^3$  defined by  $\mathcal{U}_2 = \{p \in M^3 : h = 0 \text{ in a neighborhood of } p\}$ . Hence,  $\mathcal{U}_1 \cup \mathcal{U}_2$  is an open and dense subset of  $M^3$  and there exists a local orthonormal basis  $\{\xi, e, \phi e\}$  of three smooth unit eigenvectors of h for any point  $p \in \mathcal{U}_1 \cup \mathcal{U}_2$ . On  $\mathcal{U}_1$ , we set  $he = \lambda e$  and hence  $h\phi e = -\lambda \phi e$ , where  $\lambda$  is a positive function on  $\mathcal{U}_1$ . The eigenvalue function  $\lambda$  is continuous on  $M^3$  and smooth on  $\mathcal{U}_1 \cup \mathcal{U}_2$ .

**Lemma 3.4** ([4, Lemma 6]). On  $U_1$  we have

$$\nabla_{\xi}\xi = 0, \ \nabla_{\xi}e = a\phi e, \ \nabla_{\xi}\phi e = -ae,$$
  

$$\nabla_{e}\xi = e - \lambda\phi e, \ \nabla_{e}e = -\xi - b\phi e, \ \nabla_{e}\phi e = \lambda\xi + be,$$
  

$$\nabla_{\phi e}\xi = -\lambda e + \phi e, \ \nabla_{\phi e}e = \lambda\xi + c\phi e, \ \nabla_{\phi e}\phi e = -\xi - ce,$$
  
(3.2)

where a, b, c are smooth functions.

Applying Lemma 3.4 in the following Jacobi identity

$$[[\xi, e], \phi e] + [[e, \phi e], \xi] + [[\phi e, \xi], e] = 0,$$

we obtain

$$\begin{cases} e(\lambda) - \xi(b) - e(a) + c(\lambda - a) - b = 0, \\ \phi e(\lambda) - \xi(c) + \phi e(a) + b(\lambda + a) - c = 0. \end{cases}$$
(3.3)

Moreover, applying Lemma 3.4 we have

$$\begin{cases}
Q\xi = -2(\lambda^2 + 1)\xi - (\phi e(\lambda) + 2\lambda b)e - (e(\lambda) + 2\lambda c)\phi e, \\
Qe = -(\phi e(\lambda) + 2\lambda b)\xi - (f + 2\lambda a)e + (\xi(\lambda) + 2\lambda)\phi e, \\
Q\phi e = -(e(\lambda) + 2\lambda c)\xi + (\xi(\lambda) + 2\lambda)e - (f - 2\lambda a)\phi e,
\end{cases}$$
(3.4)

where  $f = e(c) + \phi e(b) + b^2 + c^2 + 2$ .

We also need the following well known result (see also [13]).

**Lemma 3.5.** If the Ricci tensor of a Riemannian manifold is cyclic-parallel or of Codazzi-type, then the scalar curvature is a constant.

We first give the following result for Kenmotsu 3-manifolds.

**Proposition 3.6.** On a three-dimensional Kenmotsu manifold the following statements are equivalent.

- (1) The Ricci tensor is parallel;
- (2) The Ricci tensor is of Codazzi-type;
- (3) The Ricci tensor is cyclic-parallel;
- (4) The manifold is of constant sectional curvature -1.

*Proof.* It is known that on a three-dimensional Riemannian manifold the curvature tensor R is given by

$$R(Y,Z)W = g(Z,W)QY - g(Y,W)QZ + g(QZ,W)Y - g(QY,W)Z - \frac{r}{2}(g(Z,W)Y - g(Y,W)Z)$$

for any vector fields Y, Z, W. Taking the covariant derivative of the above relation along arbitrary vector field X gives

$$(\nabla_X R)(Y,Z)W = g(Z,W)(\nabla_X Q)Y - g(Y,W)(\nabla_X Q)Z + g((\nabla_X Q)Z,W)Y - g((\nabla_X Q)Y,W)Z - \frac{1}{2}X(r)(g(Z,W)Y - g(Y,W)Z)$$

for any vector fields X, Y, Z and W, where r denotes the scalar curvature.

If a three-dimensional Kenmotsu manifold  $M^3$  has a parallel Ricci tensor, then, the scalar curvature of  $M^3$  is a constant and hence by the above relation we see that the manifold is locally symmetric. On the other hand, K. Kenmotsu [16, Corollary 6] proved that a locally symmetric Kenmotsu manifold is of constant sectional curvature -1. This means  $(1) \Rightarrow (4)$ .

If a three-dimensional Kenmotsu manifold  $M^3$  is of constant sectional curvature -1, that is, R(X, Y)Z = -g(Y, Z)X + g(X, Z)Y for any vector fields X, Y, Z, then we obtain easily that the Ricci operator is given by Q = -2id. This means that the Ricci tensor is parallel (that is,  $\nabla Q = 0$ ) and hence we obtain (4)  $\Rightarrow$  (1), (4)  $\Rightarrow$  (2) and (4)  $\Rightarrow$  (3).

It can be easily seen that a three-dimensional Riemannian manifold with a Codazzi-type or a cyclicparallel Ricci tensor is of constant scalar curvature (see also Gray [13]). Moreover, J. Inoguchi in [14] proved that a three-dimensional Kenmotsu manifold having a constant scalar curvature is of constant sectional curvature -1. This means  $(2) \Rightarrow (4)$  and  $(3) \Rightarrow (4)$ . This completes the proof.

Next we give our main result, stating that the equations (1.1)-(1.4) are equivalent to each other even on a special type of non-Kenmotsu almost Kenmotsu 3-manifolds, namely non-Kenmotsu almost Kenmotsu 3-*h*-manifolds.

**Theorem 3.7.** On an almost Kenmotsu 3-h-manifold with  $h \neq 0$ , the following statements are equivalent.

- (1) The Ricci tensor is parallel;
- (2) The Ricci tensor is of Codazzi-type;
- (3) The Ricci tensor is cyclic-parallel;
- (4) The manifold is locally isometric to the product space  $\mathbb{H}^2(-4) \times \mathbb{R}$ .

*Proof.* Recently, Wang [18] and Cho [3] independently obtained that any non-Kenmotsu almost Kenmotsu 3-manifold is locally symmetric if and only if it is locally isometric to the product space  $\mathbb{H}^2(-4) \times \mathbb{R}$ . Since on a locally symmetric non-Kenmotsu almost Kenmotsu manifold there holds  $\nabla_{\xi} h = 0$ , therefore, (1)  $\Leftrightarrow$  (4) follows from [18] and [3].

Very recently, Wang [20] obtained that a three-dimensional almost Kenmotsu manifold satisfying  $\nabla_{\xi} h = 0$ and having a harmonic curvature tensor is locally isometric to either the hyperbolic space  $\mathbb{H}^3(-1)$  or the product space  $\mathbb{H}^2(-4) \times \mathbb{R}$ . This means (2)  $\Leftrightarrow$  (4).

Since the product space  $\mathbb{H}^2(-4) \times \mathbb{R}$  is locally symmetric, then in what follows we need only to show that  $(3) \Rightarrow (4)$ .

Now, we suppose that  $M^3$  is a non-Kenmotsu almost Kenmotsu 3-*h*-manifold whose Ricci tensor is cyclic-parallel. Firstly, by a direct calculation we obtain from Lemma 3.4 and relation (2.4) that

$$(\nabla_{\xi}h)e = \xi(\lambda)e + 2a\lambda\phi e \text{ and } (\nabla_{\xi}h)\phi e = -\xi(\lambda)\phi e + 2a\lambda e.$$

In view of Definition 3.1 and  $\lambda$  being a positive function, we have

$$\xi(\lambda) = a = 0. \tag{3.5}$$

Then, using (3.5) in (3.4) we obtain from Lemma 3.4 that

$$(\nabla_{\xi}Q)\xi = -\xi(\phi e(\lambda) + 2\lambda b)e - \xi(e(\lambda) + 2\lambda c)\phi e, \qquad (3.6)$$

$$(\nabla_{\xi}Q)e = -\xi(\phi e(\lambda) + 2\lambda b)\xi - \xi(f)e, \qquad (3.7)$$

$$(\nabla_{\xi}Q)\phi e = -\xi(e(\lambda) + 2\lambda c)\xi - \xi(f)\phi e, \qquad (3.8)$$

$$(\nabla_e Q)\xi = 2(\phi e(\lambda) - 3\lambda e(\lambda) + 2\lambda b - 2\lambda^2 c)\xi + (f - 2 - e(\phi e(\lambda) + 2\lambda b) - b(e(\lambda) + 2\lambda c))e$$
(3.9)

$$+ (2\lambda^3 + b(\phi e(\lambda) + 2\lambda b) - e(e(\lambda) + 2\lambda c) - \lambda f)\phi e,$$

$$(\nabla_e Q)e = (f - 2 - e(\phi e(\lambda) + 2\lambda b) - b(e(\lambda) + 2\lambda c))\xi - (e(f) + 2\phi e(\lambda))e + (e(\lambda) + \lambda\phi e(\lambda) + 2\lambda^2 b - 2\lambda c)\phi e,$$
(3.10)

$$(\nabla_e Q)\phi e = (2\lambda^3 - f\lambda + b(\phi e(\lambda) + 2\lambda b) - e(e(\lambda) + 2\lambda c))\xi + (e(\lambda) + \lambda\phi e(\lambda) - 2\lambda c + 2\lambda^2 b)e + (2\lambda(e(\lambda) + 2\lambda c) - e(f) - 4\lambda b)\phi e,$$
(3.11)

$$(\nabla_{\phi e}Q)\xi = 2(e(\lambda) - 3\lambda\phi e(\lambda) + 2\lambda c - 2\lambda^2 b)\xi + (2\lambda^3 + c(e(\lambda) + 2\lambda c) - \phi e(\phi e(\lambda) + 2\lambda b) - \lambda f)e + (f - 2 - \phi e(e(\lambda) + 2\lambda c) - c(\phi e(\lambda) + 2\lambda b))\phi e,$$
(3.12)

$$(\nabla_{\phi e}Q)e = (2\lambda^{3} - f\lambda + c(e(\lambda) + 2\lambda c) - \phi e(\phi e(\lambda) + 2\lambda b))\xi - (\phi e(f) + 4\lambda c - 2\lambda(\phi e(\lambda) + 2\lambda b))e + (\phi e(\lambda) + \lambda e(\lambda) + 2\lambda^{2}c - 2\lambda b)\phi e,$$
(3.13)

$$(\nabla_{\phi e}Q)\phi e = (f - 2 - \phi e(e(\lambda) + 2\lambda c) - c(\phi e(\lambda) + 2\lambda b))\xi + (\phi e(\lambda) + \lambda e(\lambda) + 2\lambda^2 c - 2\lambda b)e - (\phi e(f) + 2e(\lambda))\phi e.$$
(3.14)

Since on  $M^3$  the Ricci tensor is assumed to be cyclic-parallel, substituting X with e and  $\phi e$ , respectively, in (1.2) we have

$$\begin{cases} e(f) + 2\phi e(\lambda) = 0, \\ \phi e(f) + 2e(\lambda) = 0. \end{cases}$$
(3.15)

From (3.4) and (3.5) we get  $r = -2\lambda^2 - 2 - 2f$ . By Lemma 3.5 we know that the scalar curvature is a constant, then it follows that

$$e(f) = -2\lambda e(\lambda)$$
 and  $\phi e(f) = -2\lambda \phi e(\lambda)$ .

Using this in (3.15) we observe that either  $\lambda = 1$  or  $\lambda$  is a positive constant not equal to 1, where we have used (3.5) and that  $\lambda$  is continuous.

Now let us consider the second case, that is,  $\lambda$  is a positive constant not equal to 1. Setting Y = Z in Equation (1.1) and using the symmetry of the Ricci tensor give

$$g((\nabla_X Q)Y, Y) + 2g((\nabla_Y Q)Y, X) = 0.$$
(3.16)

Putting X = e and  $Y = \phi e$  in (3.16) and using (3.11) and (3.14) we have

$$b - \lambda c = 0. \tag{3.17}$$

Similarly, putting  $X = \phi e$  and Y = e in (3.16) and using (3.10) and (3.13) we have

$$c - \lambda b = 0. \tag{3.18}$$

Since  $\lambda \neq 1$ , it follows from (3.17) and (3.18) that

$$b = c = 0$$

and using this in (3.7), (3.11) and (3.12) gives

$$(\nabla_{\xi}Q)e = 0, \ (\nabla_{e}Q)\phi e = 2\lambda(\lambda - 1)\xi, \ (\nabla_{\phi e}Q)\xi = 2\lambda(\lambda - 1)e,$$

where we have used f = 2. Putting X = e,  $Y = \phi e$  and  $Z = \xi$  in equation (1.1) and using the above relation we obtain  $\lambda = 1$ , a contradiction. Then, based on the above analysis we conclude that  $\lambda = 1$ . Next we prove that in this context the cyclic-parallelism of the Ricci tensor implies the parallelism.

Putting X = e and  $Y = \phi e$  in (3.16) and using (3.11), (3.14) we get

$$b = c. \tag{3.19}$$

Using (3.5),  $\lambda = 1$  and (3.19) in the first term of Relation (3.3) we have

$$\xi(b) = 0.$$
 (3.20)

Similarly, using  $X = \xi$  and Y = e in (3.16) and applying (3.7), (3.10) we obtain

$$f - 2 - 2e(b) - 2b^2 = 0. (3.21)$$

It follows from the above relation, (3.4), and (3.19) that

$$e(b) = \phi e(b). \tag{3.22}$$

Using (3.22) and putting  $X = e, Y = \xi$ , and  $Z = \phi e$  in (1.1) we have

$$f - 2 + 2e(b) - 2b^2 = 0.$$

Comparing the above relation with (3.21) and making using of (3.20) and (3.22) we conclude that b = c is a constant. Finally, applying  $\lambda = 1$ ,  $f = 2 + 2b^2$ , and b = c = constant in equations (3.6)-(3.14) it can be easily seen that the Ricci operator Q is parallel and hence the manifold is locally symmetric.

Because Wang [18] and Cho [3] proved that any almost Kenmotsu 3-manifold is locally symmetric if and only if it is locally isometric to either the hyperbolic space  $\mathbb{H}^3(-1)$  or the product space  $\mathbb{H}^2(-4) \times \mathbb{R}$ , then the proof follows.

*Remark* 3.8. Proposition 3.4 and Theorem 3.7 can be regarded as some generalizations of the main results proved in [3], [7] and [18].

## Acknowledgment

This work was supported by the National Natural Science Foundation of China (No. 11526080) and Key Scientific Research Program in Universities of Henan Province (No. 16A110004). The author would like to thank the anonymous referee for his or her many valuable suggestions.

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