

ALMOST QUASI-YAMABE AND GRADIENT ALMOST QUASI-YAMABE SOLITONS ON QUASI-SASAKIAN MANIFOLDS

K. DE AND U. C. DE

ABSTRACT. In this offering exposition, we intend to investigate *almost quasi-Yamabe and gradient almost quasi-Yamabe solitons* within the context of three-dimensional quasi-Sasakian manifolds.

1. INTRODUCTION

In [9], several years ago, Hamilton publicized the concept of *Yamabe soliton*. According to the author, a Riemannian metric g of a complete Riemannian manifold (M^n, g) is called a *Yamabe soliton* if it obeys

$$(1.1) \quad \frac{1}{2} \mathcal{L}_W g = (r - \lambda) g,$$

where W , λ , r , and \mathcal{L} indicate a smooth vector field, a real number, the well-known scalar curvature, and Lie-derivative, respectively. Here, W is termed as the soliton field of the *Yamabe soliton*. A *Yamabe soliton* is called shrinking or expanding in case $\lambda > 0$ or $\lambda < 0$, respectively, whereas *steady* if $\lambda = 0$. Yamabe solitons have been investigated by several geometers in various context (see, [2], [3], [8], [15], [16], [17]). The so called *Yamabe soliton* becomes the *almost Yamabe soliton* if λ is a C^∞ function. In [1], Barbosa and Ribeiro introduced the above notion that was completely classified by Seko and Maeta [14] on hypersurfaces in Euclidean spaces.

The Yamabe soliton reduces to a *gradient Yamabe soliton* if the soliton field W is gradient of a C^∞ function $\gamma: M^n \rightarrow \mathbb{R}$. In this occasion, from (1.1), we have

$$(1.2) \quad \nabla^2 \gamma = (r - \lambda)g,$$

where $\nabla^2 \gamma$ indicates the Hessian of γ . The idea of gradient Yamabe soliton was generalized by Huang and Li [10] and named as *quasi-Yamabe gradient soliton*.

Received September 6, 2020; revised December 17, 2020.

2020 *Mathematics Subject Classification*. Primary 53C21, 53C25; Secondary 53C50.

Key words and phrases. 3-dimensional quasi-Sasakian manifolds; Yamabe solitons, gradient Yamabe solitons; almost quasi-Yamabe solitons.

According to Huang and Li, g (Riemannian metric) obeys the equation

$$(1.3) \quad \nabla^2 \gamma = \frac{1}{m} d\gamma \otimes d\gamma + (r - \lambda) g,$$

where $\lambda \in \mathbb{R}$ and m is a positive constant. If $m = \infty$, the foregoing equation reduces to Yamabe gradient soliton.

A few years ago in [13], taking λ as a C^∞ function, Pirhadi and Razavi investigated an *almost quasi-Yamabe gradient soliton*. They got a few fascinating formulas and produced a necessary and sufficient condition under which an arbitrary compact almost Yamabe soliton is necessarily gradient. Recently, Chen [7] studied almost quasi-Yamabe solitons within the context of almost Cosymplectic manifolds. According to Chen, a Riemannian metric is said to be an (AQY) metric if there exists a smooth vector field W , a C^∞ function λ , and a positive constant m such that

$$(1.4) \quad \frac{1}{2} \mathcal{L}_W g = \frac{1}{m} W^b \otimes W^b + (r - \lambda) g$$

holds, where the 1-form W^b is associated to W . In this article, the terminology “almost quasi-Yamabe” is written as (AQY) that is used throughout the paper. The (AQY) metric is called closed if the 1-form W^b is closed. The metric becomes trivial if $W \equiv 0$. Furthermore, when $m = \infty$, the previous equation gives the almost Yamabe soliton. If $W = D\gamma$, the previous equation reduces to (AQY) gradient soliton (g, γ, m, λ) .

The above discussion motivate us to investigated (AQY) solitons and gradient (AQY) solitons in 3-dimensional quasi-Sasakian manifold.

The present article is structured as follows: At first, we recall a few fundamental facts and formulas of 3-dimensional quasi-Sasakian manifolds, which we need throughout the article. We investigate (AQY) soliton and gradient (AQY) soliton on 3-dimensional quasi-Sasakian manifolds in the next section. Precisely, the following prime Theorems are proved.

Theorem 1.1. *Let the Riemannian metric of a quasi-Sasakian manifold M^3 with the structure-function $\beta = \text{constant}$ be a closed (AQY) soliton (g, W, m, λ) . Then, either the manifold is of constant sectional curvature β^2 or the (AQY) soliton’s potential vector field is pointwise collinear with the characteristic vector field ξ .*

Theorem 1.2. *Let the Riemannian metric of a quasi-Sasakian manifold M^3 with the structure-function $\beta = \text{constant}$ be the gradient (AQY) soliton. Then, either the manifold is of constant sectional curvature β^2 or the gradient potential function of the (AQY) soliton is pointwise collinear with the Reeb vector field ξ .*

2. PRELIMINARIES

Let M^3 be a connected differentiable manifold equipped with an *almost contact metric structure* (η, ξ, ϕ, g) , where η, ξ, ϕ are a 1-form, a vector field, and

a (1, 1)-type tensor field such that [5], [6]

$$(2.1) \quad \phi^2 E = -E + \eta(E)\xi, \quad \eta(\xi) = 1.$$

Then also

$$(2.2) \quad \phi \xi = 0, \quad \eta \circ \phi = 0, \quad \eta(E) = g(E, \xi).$$

The fundamental 2-form Φ of M^3 is defined by

$$\Phi(E, F) = g(E, \phi F), \quad E, F \in \mathfrak{X}(M).$$

Then $\Phi(E, \xi) = 0, E \in \mathfrak{X}(M)$. M^3 is called *quasi-Sasakian* if the above 2-form Φ is closed ($d\Phi = 0$) and the almost contact structure (η, ξ, ϕ) is normal. This concept was introduced by Blair [4]. The normality condition shows that the induced almost complex structure of $M \times \mathbb{R}$ is integrable. Equivalently, M^3 is called normal if the torsion tensor field $N = [\phi, \phi] + 2\xi \otimes d\eta$ vanishes. It is to be noted that the rank of such *quasi-Sasakian structure* is always odd [4].

An almost contact metric manifold M^3 is called a *quasi-Sasakian manifold* if and only if [11]

$$(2.3) \quad \nabla_E \xi = -\beta \phi E, \quad E \in \mathfrak{X}(M),$$

for a certain function β on M^3 , called the structure-function of the manifold such that $\xi\beta = 0$. It is clear that such a quasi-Sasakian manifold reduces to a cosymplectic manifold if and only if $\beta = 0$. From (2.3), we have [11]

$$(2.4) \quad (\nabla_E \phi)(F) = \beta(g(E, F)\xi - \eta(F)E)$$

and

$$(2.5) \quad R(E, F)\xi = -(E\beta)\phi F + (F\beta)\phi E + \beta^2\{\eta(F)E - \eta(E)F\}, \quad E, F \in \mathfrak{X}(M).$$

In M^3 , the Ricci tensor S is written as [12]

$$(2.6) \quad S(F, Z) = \left(\frac{r}{2} - \beta^2\right)g(F, Z) + \left(3\beta^2 - \frac{r}{2}\right)\eta(F)\eta(Z) - \eta(F)d\beta(\phi Z) - \eta(Z)d\beta(\phi F).$$

From (2.6), it is obvious that if $\beta = \text{constant}$, then M is an η -Einstein manifold.

It is well-known that a Riemannian manifold M^3 assumes the following curvature form

$$(2.7) \quad R(E, F)Z = g(F, Z)QE - g(E, Z)QF + S(F, Z)E - S(E, Z)F - \frac{r}{2}[g(F, Z)E - g(E, Z)F]$$

for all $E, F, Z \in \mathfrak{X}(M)$. As a consequence of (2.6), we can easily obtain

$$(2.8) \quad QE = \left(\frac{r}{2} - \beta^2\right)E + \left(3\beta^2 - \frac{r}{2}\right)\eta(E)\xi + \eta(E)(\phi \text{grad } \eta) - d\eta(\phi E)\xi,$$

where $d\gamma(E) = g(\text{grad } \gamma, E)$.

Since $\beta = \text{constant}$ the equations (2.6) and (2.8) reduce to

$$(2.9) \quad S(F, Z) = \left(\frac{r}{2} - \beta^2\right)g(F, Z) + \left(3\beta^2 - \frac{r}{2}\right)\eta(F)\eta(Z)$$

and

$$(2.10) \quad QE = \left(\frac{r}{2} - \beta^2\right)E + \left(3\beta^2 - \frac{r}{2}\right)\eta(E)\xi,$$

respectively. Now before going to the next section, we state the following result [7].

Lemma 2.1. *For any vector fields E, F on M^3 , for a gradient (AQY) soliton $(M^3, g, \gamma, m, \lambda)$, we have*

$$(2.11) \quad \begin{aligned} R(E, F)D\gamma &= \frac{r - \lambda}{m}\{(F \ \gamma)E - (E \ \gamma)F\} \\ &\quad + (E(r - \lambda))F - (F(r - \lambda))E, \end{aligned}$$

where D indicates the gradient operator of g .

3. PROOF OF THE MAIN THEOREMS

Proof of Theorem 1.1. Let us consider a closed (AQY) soliton (g, W, m, λ) on a quasi-Sasakian manifold M^3 with the structure-function $\beta = \text{constant}$. Since W^b is closed, equation (1.4) can be written as

$$(3.1) \quad \nabla_F W = (r - \lambda)F + \frac{1}{m}g(W, F)W.$$

Executing the covariant derivative of (3.1) along the vector field E , we get

$$(3.2) \quad \begin{aligned} \nabla_E \nabla_F W &= (E(r - \lambda))F + (r - \lambda)\nabla_E F + \frac{1}{m}g(\nabla_E W, F)W \\ &\quad + \frac{1}{m}g(W, \nabla_E F)W + \frac{1}{m}g(W, F)\nabla_E W. \end{aligned}$$

Exchanging E and F in (3.2), we lead

$$(3.3) \quad \begin{aligned} \nabla_F \nabla_E W &= (F(r - \lambda))E + (r - \lambda)\nabla_F E + \frac{1}{m}g(\nabla_F W, E)W \\ &\quad + \frac{1}{m}g(W, \nabla_F E)W + \frac{1}{m}g(W, E)\nabla_F W \end{aligned}$$

and

$$(3.4) \quad \nabla_{[E, F]} W = (r - \lambda)[E, F] + \frac{1}{m}g(W, [E, F])W.$$

Utilizing (3.1)–(3.4), and together with $R(E, F)W = \nabla_E \nabla_F W - \nabla_F \nabla_E W - \nabla_{[E, F]} W$, we infer

$$(3.5) \quad \begin{aligned} R(E, F)W &= (E(r - \lambda))F - (F(r - \lambda))E \\ &\quad + \frac{r - \lambda}{m}g(W, F)E - \frac{r - \lambda}{m}g(W, E)F. \end{aligned}$$

Executing the inner product of (3.5) with ξ gives

$$(3.6) \quad \begin{aligned} g(R(E, F)W, \xi) &= \{(E(r - \lambda)) - \frac{r - \lambda}{m} g(W, E)\} \eta(F) \\ &\quad - \{(F(r - \lambda)) - \frac{r - \lambda}{m} g(W, F)\} \eta(E). \end{aligned}$$

Again, from relation (2.5), we obtain that

$$(3.7) \quad g(R(E, F)W, \xi) = \beta^2 \{g(F, W)\eta(E) - g(E, W)\eta(F)\}.$$

Combining equation (3.6) and (3.7), and replacing E and F by ϕE and ξ , respectively, yield that

$$\beta^2 g(\phi E, W) = -\phi E(r - \lambda) + \frac{r - \lambda}{m} g(\phi E, W),$$

which is identical to

$$(3.8) \quad \left(\frac{r - \lambda}{m} - \beta^2\right) \phi W = \phi D(r - \lambda).$$

On the other side, utilizing (2.9) and contracting (3.5) over F , we get

$$(3.9) \quad \left(\frac{r}{2} - \beta^2\right) W - \left(3\beta^2 - \frac{r}{2}\right) \eta(W)\xi = -2\left\{D(r - \lambda) - \frac{r - \lambda}{m} W\right\}.$$

Now applying ϕ in the previous equation yields

$$(3.10) \quad \left(\frac{r}{2} - \beta^2\right) \phi W = -2\left\{\phi D(r - \lambda) - \frac{r - \lambda}{m} \phi W\right\},$$

which combining with (3.8), gives

$$(3.11) \quad \left(\frac{r}{2} - 3\beta^2\right) \phi W = 0.$$

This implies that either $r = 6\beta^2$ or $\phi W = 0$.

Case (i): If $r = 6\beta^2$, then from (2.9), we get $S = 2\beta^2 g$, that is an Einstein manifold. Hence from (2.7), it follows that the manifold is of constant sectional curvature β^2 .

Case (ii): If $\phi W = 0$, then by operating ϕ , we infer $W = \eta(W)\xi$. This accomplishes the proof. \square

Utilizing $\phi W = 0$ in (3.8), we infer

$$\phi D r = \phi D \lambda.$$

By operating ϕ on the foregoing equation and utilizing (2.1), we obtain

$$(3.12) \quad D r = D \lambda - (\xi \lambda) \xi.$$

If λ is invariant under the characteristic vector field ξ , we conclude from the above

$$r - \lambda = \text{constant} = c \quad (\text{say}).$$

Putting this value in (3.5), we get

$$(3.13) \quad R(E, F)W = \frac{c}{m} [g(W, F)E - g(W, E)F].$$

This means that the sectional curvature containing the potential vector field is constant.

Again, we know that when $\lambda = \text{constant}$, the closed (AQY) soliton reduces to the closed quasi-Yamabe soliton. If $\lambda = \text{constant}$ in (3.12), we conclude that the manifold is of constant scalar curvature. Thus, we can write the following corollaries.

Corollary 3.1. *If a non Einstein quasi-Sasakian manifold M^3 with the structure-function $\beta = \text{constant}$ admits a closed (AQY) soliton (g, γ, m, λ) , then the sectional curvature containing the potential vector field is constant, provided λ is invariant under the characteristic vector field ξ .*

Corollary 3.2. *If a quasi-Sasakian manifold M^3 with the structure-function $\beta = \text{constant}$ admits a closed quasi-Yamabe soliton (g, W, m, λ) , then either the manifold is of constant sectional curvature β^2 or the manifold is of constant scalar curvature.*

Proof of Theorem 1.2. Let us presume that the Riemannian metric of a quasi-Sasakian manifold M^3 with the structure-function $\beta = \text{constant}$ be the gradient (AQY) soliton. Then the inner product of (2.11) with ξ gives

$$(3.14) \quad g(R(E, F) D\gamma, \xi) = \frac{r - \lambda}{m} \{ (F \gamma) \eta(E) - (E \gamma) \eta(F) \} + (E(r - \lambda)) \eta(F) - (F(r - \lambda)) \eta(E).$$

On the other side, from equation (2.5), we obtain that

$$(3.15) \quad g(R(E, F) D\gamma, \xi) = \beta^2 \{ (F \gamma) \eta(E) - (E \gamma) \eta(F) \}.$$

Combining equation (3.14) and (3.15), and superseding E and F by ϕE and ξ , respectively, reveal that

$$(3.16) \quad \left(\beta^2 - \frac{r - \lambda}{m} \right) (\phi E W) + \phi E (r - \lambda) = 0.$$

On the other side, contracting (2.11) over E and using (2.10), we get

$$(3.17) \quad \left(\frac{r}{2} - \beta^2 \right) (F \gamma) + \left(3\beta^2 - \frac{r}{2} \right) \eta(F) \eta(D\gamma) = 2 \frac{r - \lambda}{m} (F \gamma) - 2(F(r - \lambda)).$$

Replacing F by ϕF in the foregoing equation and comparing with (3.16) give

$$(3.18) \quad \left(\frac{r}{2} - 3\beta^2 \right) (\phi E \gamma) = 0.$$

This implies that either $r = 6\beta^2$ or $(\phi E \gamma) = 0$.

Case (i): If $r = 6\beta^2$, then by similar argument like the Theorem 1.1, we conclude that the manifold is of constant sectional curvature β^2 .

Case (ii): If $(\phi E \gamma) = 0$, then by operating ϕ , we infer

$$(3.19) \quad D\gamma = (\xi \gamma) \xi.$$

This finishes the proof. □

By the the execution of covariant derivative of (3.19) along E together with (2.3) and (3.1), we find that

$$\frac{1}{m} g(E, D\gamma) D\gamma + (r - \lambda)E = (E(\xi\gamma))\xi - \beta(\xi\gamma)\phi E,$$

which becomes

$$(3.20) \quad \frac{1}{m} (\xi\gamma)^2 \eta(E)\xi + (r - \lambda)E = (E(\xi\gamma))\xi - \beta(\xi\gamma)\phi E,$$

where equation (3.19) is used. Replacing $E = \xi$ in (3.20), and then taking inner product operation with ξ , we get

$$(3.21) \quad \frac{1}{m} (\xi\gamma)^2 + (r - \lambda) = \xi(\xi\gamma).$$

Again, by contracting equation (3.20) along E , we infer

$$(3.22) \quad \frac{1}{m} (\xi\gamma)^2 + 3(r - \lambda) = \xi(\xi\gamma).$$

From the last two equation, we obtain

$$(3.23) \quad (r - \lambda) = 0.$$

Using (3.23), from (3.22), we get that

$$\frac{1}{m} (\xi\gamma)^2 = \xi(\xi\gamma).$$

Let $\xi = \frac{\partial}{\partial u}$, then the previous equation becomes

$$(3.24) \quad \frac{\partial^2 \gamma}{\partial u^2} = \frac{1}{m} \left(\frac{\partial \gamma}{\partial u} \right)^2.$$

From the foregoing partial differential equation, we can obtain $\gamma = -m \ln u$, $u > 0$, and m is a non-zero positive integer satisfying (3.24). By considering the above arguments, we can write the following corollaries.

Corollary 3.3. *If a non Einstein quasi-Sasakian manifold M^3 with the structure-function $\beta = \text{constant}$ admits a gradient (AQY) soliton (g, γ, m, λ) , then $r = \lambda$.*

Corollary 3.4. *If a non Einstein quasi-Sasakian manifold M^3 equipped with a gradient (AQY) soliton (g, γ, m, λ) satisfies the partial differential equation (3.24), provided the structure-function $\beta = \text{constant}$, then the potential function is given by $\gamma = -m \ln u$, $u > 0$.*

Acknowledgment. The authors are thankful to the referee for his/her valuable suggestions towards the improvement of the paper.

REFERENCES

1. Barbosa E. and Ribeiro E. Jr., *On conformal solutions of the Yamabe flow*, Arch. Math. (Basel) **101** (2013), 79–89.
2. Blaga A. M., *A note on warped product almost quasi-Yamabe solitons*, Filomat **33** (2019), 2009–2016.
3. Blaga A. M., *Some geometrical aspects of Einstein, Ricci and Yamabe solitons*, J. Geom. Symmetry Phys. **52** (2019), 17–26.
4. Blair D. E., *The theory of quasi-Sasakian structure*, J. Differential Geom. **1** (1967), 331–345.
5. Blair D. E., *Contact Manifolds in Riemannian geometry*, Lecture Notes in Math. 509, Springer-Verlag, Berlin-New York, 1976.
6. Blair D. E., *Riemannian Geometry of Contact and Symplectic Manifolds*, Progress in Maths. 203, Birkhäuser Boston, Inc., 2002.
7. Chen X., *Almost quasi-Yamabe solitons on almost cosymplectic manifolds*, Int. J. Geom. Methods Mod. Phys. **17**(5) (2020), #2050070, 16 pp.
8. Desmukh S. and Chen B. Y., *A note on Yamabe solitons*, Balkan J. Geom. Appl. **23** (2018), 37–43.
9. Hamilton R. S., *The Ricci flow on surfaces*, Contemp. Math. **71** (1988), 237–261.
10. Huang G. and Li H., *On a classification of the quasi Yamabe gradient solitons*, Methods Appl. Anal. **21** (2014), 379–390.
11. Olszak Z., *Normal almost contact manifolds of dimension three*, Ann. Polon. Math. **47** (1986), 41–50.
12. Olszak Z., *On three dimensional conformally flat quasi-Sasakian manifolds*, Period. Math. Hungar. **33** (1996), 105–113.
13. Pirhadi V. and Razavi A., *On the almost quasi-Yamabe solitons*, Int. J. Geom. Methods Mod. Phys. **14** (2017), #1750161, 9 pp.
14. Seko T. and Maeta S., *Classifications of almost Yamabe solitons in Euclidean spaces*, J. Geom. Phys. **136** (2019), 97–103.
15. Sharma R., *A 3-dimensional Sasakian metric as a Yamabe soliton*, Int. J. Geom. Methods Mod. Phys. **9** (2012), #1220003, 5 pp.
16. Suh Y. J. and De U. C., *Yamabe solitons and Ricci solitons on almost co-Kähler manifolds*, Canad. Math. Bull. **62** (2019), 653–661.
17. Wang Y., *Yamabe solitons on three dimensional Kenmotsu manifolds*, Bull. Belg. Math. Soc. **23** (2016), 345–355.

K. De, Department of Mathematics, Kabi Sukanta Mahavidyalaya, Bhadreswar, P.O.-Angus, Hooghly, Pin 712221, West Bengal, India,
e-mail: krishnendu.de@outlook.in

U. C. De, Department of Pure Mathematics, University of Calcuta, 35 Ballygunje Circular Road, Kolkata 700019, West Bengal, India,
e-mail: uc.de@yahoo.com