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### ALMOST RICCI SOLITONS AND K-CONTACT GEOMETRY

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Abstract: We give a short Lie-derivative theoretic proof of the following recent result of Barros et al. "A compact non-trivial almost Ricci soliton with constant scalar curvature is gradient, and isometric to a Euclidean sphere". Next, we obtain the result: A complete almost Ricci soliton whose metric gis K-contact and flow vector field X is contact becomes Ricci soliton with constant scalar curvature. In particular, for X strict, g becomes compact Sasakian Einstein. Finally, we show that the Lie-bracket of two distinct Ricci soliton vector fields with the same metric generates a steady Ricci soliton.

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*Keywords*: Almost Ricci soliton, Conformal vector field, Constant scalar curvature, *K*-contact metric, Einstein Sasakian metric.

# 1 Introduction

Modifying the Ricci soliton equation by allowing the dilation constant  $\lambda$  to become a variable function, Pigola et al. [8] defined an almost Ricci soliton as a Riemannian manifold (M, g) satisfying the condition:

$$\pounds_X g_{ij} + 2R_{ij} = 2\lambda g_{ij}.\tag{1}$$

where X is a vector field on M,  $g_{ij}$  and  $R_{ij}$  are the components of the metric tensor g and its Ricci tensor in local coordinates  $(x^i)$ ,  $\pounds_X$  is the Lie-derivative operator along X, and  $\lambda$  is a smooth function on M. A simple example is the canonical metric g on a Euclidean sphere with X a non-homothetic conformal vector field. For  $\lambda$  constant, (1) becomes the Ricci soliton. The almost Ricci soliton is said to be shrinking, steady, and expanding according as  $\lambda$  is positive, zero, and negative respectively; otherwise is indefinite. If the vector field X is the gradient of a smooth function f, upto the addition of a Killing vector field,  $(M, g, X, \lambda)$  is called a gradient almost Ricci soliton, in which case the equation (1) assumes the form:

$$\nabla_i \nabla_j f + R_{ij} = \lambda g_{ij}.$$
 (2)

For an almost Ricci soliton with X homothetic, g is Einstein and hence  $\lambda$  becomes constant and it becomes the trivial Ricci soliton. For X non-homothetic, g is a non-trivial almost Ricci soliton. We also note for an almost Ricci soliton that X is conformal if and only if g is Einstein.

Ricci solitons are special solutions of the Ricci flow equation

$$\frac{\partial}{\partial t}g_{ij}(t) = -2R_{ij}(t),\tag{3}$$

of the form  $g_{ij}(t) = \sigma(t)\psi_t^*g_{ij}$  with initial condition  $g_{ij}(0) = g_{ij}$ , where  $\psi_t$  are diffeomorphisms of M and  $\sigma(t)$  is the scaling function. In the same vein, we can view almost Ricci soliton as a special solution of Ricci flow, by considering the ansatz:

$$g_{ij}(t) = \sigma(t, x^k) \psi_t^* g_{ij}, \tag{4}$$

where  $\psi_t$  are diffeomorphisms of M generated by the family of vector fields Y(t), and  $\sigma(t, x^k)$  can be viewed as a pointwise scaling function that depends not only on time t, but also on the coordinates  $x^k$  of points. The initial conditions:  $g_{ij}(0) = g_{ij}, \psi_0$  = identity, imply  $\sigma(0, x^k) = 1$ . Differentiating (4) with respect to t, using the Ricci flow equation (3), and substituting t = 0shows

$$-2R_{ij} = \left(\frac{\partial}{\partial t}\sigma(t, x^k)\right)|_{t=0}g_{ij} + \pounds_{Y(0)}g_{ij},$$

Labelling Y(0) as X and the time-independent function  $\left(\frac{\partial}{\partial t}\sigma(t,x^k)\right)|_{t=0}$  as  $-2\lambda$ , we obtain the almost Ricci soliton equation (1).

# 2 Compact Almost Ricci Soliton

It is well known that a compact Ricci soliton is gradient. This need not be true for almost Ricci soliton. In [3], Barros and Ribeiro Jr. showed that a compact gradient almost Ricci soliton with non-trivial conformal vector field is isometric to a Euclidean sphere. Intrigued by the fact that a compact Ricci soliton with constant scalar curvature is trivial (i.e. X is Killing and gis Einstein), Barros, Batista and Ribeiro Jr. [2] proved the following result.

**Theorem 1 (B-B-R)** Let  $(M^n, g, X, \lambda)$  be a compact oriented almost Ricci soliton. If Ric, S and  $dv_g$  denote respectively the Ricci tensor, scalar curvature and the volume form with respect to g, then

$$\int_{M} |Ric - \frac{S}{n}g|^2 dv_g = \frac{n-2}{2n} \int_{M} g(\nabla S, X) dv_g.$$
(5)

If, in addition; n > 2, the almost Ricci soliton is non-trivial and the scalar curvature is constant, then (M, g) is isometric to a Euclidean sphere and the almost Ricci soliton is gradient.

In this paper we provide a short Lie-derivative theoretic proof of this result, based on equations of evolution of Christoffel symbols and curvature quantities along the flow vector field X. We denote the Levi-Civita connection, connection coefficients, and components of curvature tensor of g by  $\nabla$ ,  $\Gamma_{jk}^{i}$ , and  $R_{kji}^{h}$  respectively.

Another Proof Of Theorem 1 (B-B-R). Let us denote the inverse of  $g_{ij}$  by  $g^{ij}$ . Taking the Lie-derivative of the relation  $g_{ij}g^{jk} = \delta_i^k$  along X, using equation (1) and subsequently operating the resulting equation by  $g^{il}$  we immediately get

$$\pounds_X g^{kl} = 2R^{kl} - 2\lambda g^{kl}.$$
(6)

Next, the use of equation (1) in the formula (page 23, Yano [9]):

$$\pounds_X \Gamma_{ij}^h = \frac{1}{2} g^{ht} [\nabla_j (\pounds_X g_{it}) + \nabla_i (\pounds_X g_{jt}) - \nabla_t (\pounds_X g_{ij})],$$

yields the evolution equation

$$\mathcal{L}_X \Gamma_{ij}^h = \nabla^h R_{ij} - \nabla_j R_i^h - \nabla_i R_j^h - (\nabla^h \lambda) g_{ij} + (\nabla_j \lambda) \delta_i^h + (\nabla_i \lambda) \delta_j^h.$$

$$(7)$$

Let us follow the notational convention:  $\nabla_k \nabla_j Z^h - \nabla_j \nabla_k Z^h = R^h_{kji} Z^i$ , where  $Z^i$  are components of an arbitrary vector field, and  $R^k_{kji} = R_{ji}$ . Using equation (7) in the following commutation formula (page 23, [9]):

$$\nabla_k(\pounds_X \Gamma^h_{ij}) - \nabla_j(\pounds_X \Gamma^h_{ik}) = \pounds_X R^h_{kji},$$

we obtain the evolution equation:

$$\begin{aligned} \pounds_X R^h_{kji} &= \nabla_j \nabla_k R^h_i - \nabla_k \nabla_j R^h_i + \nabla_j \nabla_i R^h_k - \nabla_k \nabla_i R^h_j \\ &+ \nabla_k \nabla^h R_{ij} - \nabla_j \nabla^h R_{ik} + (\nabla_k \nabla_i \lambda) \delta^h_j \\ &- (\nabla_k \nabla^h \lambda) g_{ij} - (\nabla_i \nabla_j \lambda) \delta^h_k + (\nabla_j \nabla^h \lambda) g_{ik}. \end{aligned}$$

Contracting this equation with  $g^{hk}$  and using the twice contracted Bianchi identity:  $\nabla_i R_j^i = \frac{1}{2} \nabla_j S$ , we have

$$\pounds_X R_{ji} = \nabla_j \nabla_i S - \nabla_h \nabla_j R_i^h - \nabla_h \nabla_i R_j^h + \Delta R_{ij} - (\Delta \lambda) g_{ij} - (n-2) \nabla_i \nabla_j \lambda.$$

Lie-differentiating  $S = R_{ij}g^{ij}$  along X, and using the above equation and equation (6) provides the evolution equation for the scalar curvature:

$$\pounds_X S = 2R_{ij}R^{ij} + \Delta S - 2\lambda S - 2(n-1)\Delta\lambda.$$
(8)

Writing  $\pounds_X S$  as  $g(\nabla S, X)$ , integrating the above equation over the compact M and using the Gauss divergence theorem we get

$$\int_{M} [R_{ij}R^{ij} - \lambda S - \frac{1}{2}g(\nabla S, X)]dv_g = 0.$$
(9)

At this point, we note

$$div(SX) = \nabla_i(SX^i) = g(\nabla S, X) + SdivX,$$

and integrate it over M in order to get

$$\int_{M} [g(\nabla S, X) + S divX] dv_g = 0.$$
(10)

Now we contract equation (1) with  $g^{ij}$  in order to get  $divX = n\lambda - S$ , and use it in (10) to obtain

$$\int_{M} (n\lambda S - S^2 + g(\nabla S, X)) dv_g = 0.$$

Eliminating  $\int_M (\lambda S) dv_g$  between the above equation and (9) and noting  $|Ric - \frac{S}{n}g|^2 = R_{ij}R^{ij} - \frac{S^2}{n}$  we obtain equation (5), proving the first part

of the theorem.

For the second part, we use the hypothesis that S is constant in equation (5) to conclude that g is Einstein. Thus, equation (1) reduces to  $\pounds_X g_{ij} = 2(\lambda - \frac{S}{n})g_{ij}$ , i.e. X is a non-homothetic conformal vector field on M. With the setting  $\lambda - \frac{S}{n} = \rho$ , the foregoing conformal equation assumes the form

$$\pounds_X g_{ij} = 2\rho g_{ij}.\tag{11}$$

Using the conformal integrability condition (p. 26, [9])

$$\pounds_X R_{ij} = (2-n)\nabla_i \nabla_j \rho - (\Delta \rho) g_{ij}$$

and the Einstein condition  $R_{ij} = \frac{S}{n}g_{ij}$  we get

$$(\Delta \rho + \frac{2S}{n}\rho)g_{ij} = (2-n)\nabla_i \nabla_j \rho.$$
(12)

Contracting it with  $g^{ij}$  gives  $\Delta \rho = -\frac{S}{n-1}\rho$ . Using this in the identity:  $\Delta \rho^2 = \nabla^i \nabla_i (\rho^2) = 2[|\nabla \rho|^2 + \rho \Delta \rho]$ , and integrating over M gives  $\int_M |\nabla \rho|^2 = \frac{S}{n-1} \int_M \rho^2$ . This shows that S > 0. Consequently, equation (12) becomes

$$\nabla_i \nabla_j \rho = -\frac{S}{n(n-1)} \rho g_{ij}.$$
(13)

This implies, by virtue of Obata's theorem [7]: "A complete Riemannian manifold (M, g) of dimension  $n \geq 2$  admits a non-trivial solution  $\rho$  of the system of partial differential equations  $\nabla_i \nabla_j \rho = -c^2 \rho g_{ij}$  (*c* a positive constant) if and only if *M* is isometric to a Euclidean sphere of radius 1/c" that (M, g) is isometric to a Euclidean sphere of radius  $\sqrt{\frac{n(n-1)}{S}}$ .

Equation (13) can also be expressed as  $\pounds_{\nabla\rho}g_{ij} = \frac{2S}{n(1-n)}\rho g_{ij}$ . Combining this with (11) we obtain

$$\pounds_{X-\frac{n(n-1)}{S}\nabla\rho}g_{ij} = 0.$$

Hence  $X = \nabla(\frac{n(1-n)}{S}\rho)$  + a Killing vector field, i.e. the almost Ricci soliton is gradient, completing the proof.

#### **3** K-Contact Metric As Almost Ricci Soliton

A (2m + 1)-dimensional smooth manifold M is called a contact manifold if it carries a global 1-form  $\eta$  such that  $\eta \wedge (d\eta)^m \neq 0$  everywhere on M. For a given contact 1-form  $\eta$  there exists a unique vector field  $\xi$  (Reeb vector field) such that  $(d\eta)(\xi, .) = 0$  and  $\eta(\xi) = 1$ . Polarizing  $d\eta$  on the contact subbundle  $\eta = 0$ , one obtains a Riemannian metric g and a (1,1)-tensor field  $\varphi$  such that

$$(d\eta)(Y,Z) = g(Y,\varphi Z), \eta(Z) = g(\xi,Z), \varphi^2 = -I + \eta \otimes \xi,$$
(14)

for arbitrary vector fields Y, Z on M. We call g an associated metric of  $\eta$  and  $(\varphi, \eta, \xi, g)$  a contact metric structure. A K-contact metric is a contact metric for which  $\xi$  is Killing, equivalently:

$$Ric(\xi, Y) = 2mg(\xi, Y), \tag{15}$$

for an arbitrary vector field Y on M. This condition is also equivalent to:

$$Ric(\xi,\xi) = 2m. \tag{16}$$

For details we refer to [4]. A contact metric g on  $M^{2m+1}$  is called Sasakian if the almost Kaehler structure induced on the cone  $(\mathcal{R}^+ \times M)$  with metric  $dr^2 + r^2 g$ , is Kaehler (see Boyer and Galicki [5]). A Sasakian metric is Kcontact, but the converse need not be true, except in dimension 3.

We would like to consider an almost Ricci soliton  $(M, g, X, \lambda)$  such that g is a K-contact metric and X is a contact vector field. Let us recall that a vector field X on a contact manifold is said to be a contact vector field if

$$\pounds_X \eta = f\eta, \tag{17}$$

for a smooth function f on M. The contact vector field X is called strict when f = 0.

Using Cartan's magic formula, we find that  $\pounds_{\xi}\eta = di_{\xi}\eta + i_{\xi}d\eta = d(1) + d\eta(\xi, .) = 0$ , i.e.  $\xi$  is a strict contact vector field. We note from equation (1) that, if we take g as a K-contact metric and X as  $\xi$ , then (as  $\xi$  is Killing), the K-contact metric g reduces to an Einstein metric and  $\lambda$  becomes constant, equal to the Einstein constant 2m, as seen from equation (16). We generalize this special situation in the form of the following result.

**Theorem 2** Let  $(M, g, X, \lambda)$  be a complete almost Ricci soliton with g a Kcontact metric and X a contact vector field. Then it becomes Ricci soliton
and g has constant scalar curvature. In particular, if X is strict, then g is
Sasakian Einstein.

**Proof.** First of all, we have, by definition of the contact structure,  $\omega = \eta \wedge (d\eta)^m \neq 0$  and thus is a volume element. Denote it by  $\omega$ . Using the hypothesis (17) we compute  $\pounds_X d\eta = d\pounds_X \eta = (df) \wedge \eta + f(d\eta)$ . Consequently, the formula:  $\pounds_X \omega = (divX)\omega$  yields the relation divX = (m+1)f. On the other hand, the trace of equation (1) is  $divX = (2m+1)\lambda - S$ . Comparing the two values of divX we have

$$S = (2m+1)\lambda - (m+1)f.$$
 (18)

Next, we Lie-differentiate the second equation in (14) along X, and then use equations (1), (15) and (17) in order to get

$$\pounds_X \xi = (f - 2\lambda + 4m)\xi. \tag{19}$$

The Lie-derivative of  $g(\xi,\xi) = 1$  (as  $\xi$  is unit) along X, and the use of equations (1) and (16) provides  $g(\pounds_X\xi,\xi) = 2m - \lambda$ . The inner product of (19) with  $\xi$  and the foregoing equation lead us to the relation:  $f = \lambda - 2m$ . Consequently, we have

$$\pounds_X \eta = (\lambda - 2m)\eta, \quad \pounds_X \xi = (2m - \lambda)\xi.$$
<sup>(20)</sup>

At this point, we take the Lie-derivative of the first equation in (14), along X and use equations (1) and (17) in order to obtain

$$\eta(Z)\nabla f - (Zf)\xi + 2(f - 2\lambda)\varphi Z = -4Q\varphi Z + 2(\pounds_X\varphi)Z, \qquad (21)$$

where Z is an arbitrary vector field on M, and Q is the Ricci tensor of type (1,1), defined by  $g(Q_{\cdot,\cdot}) = Ric(.,\cdot)$ . Substituting  $\xi$  for Z in equation (21) and using the property  $\varphi \xi = 0$  and equation (20) we find  $\nabla f = (\xi f)\xi$ , i.e.  $df = (\xi f)\eta$ . Taking its exterior derivative, using Poincare lemma:  $d^2 = 0$ , and then wedge product with  $\eta$  we have  $(\xi f)\eta \wedge d\eta = 0$ . As  $\eta \wedge d\eta$  cannot vanish anywhere, otherwise the definition of the contact structure would be violated, we conclude that  $\xi f = 0$ , and hence df = 0, i.e. f is constant on M. Consequently, equation (21) reduces to the following evolution equation for  $\varphi$ :

$$\pounds_X \varphi = 2Q\varphi - (2m + \lambda)\varphi. \tag{22}$$

As shown earlier,  $f = \lambda - 2m$ , and f is constant, we conclude that  $\lambda$  is constant and hence the almost Ricci soliton becomes Ricci soliton. Appealing to equation (18), we find that S is constant. This proves first part. For the second part, the hypothesis f = 0 immediately implies  $\lambda = 2m$  and thus we get from (18) that S = 2m(2m + 1). Plugging these findings in equation (8) and carrying out a straightforward computation shows  $|Ric - 2mg|^2 = 0$ . Hence Ric = 2mg, i.e. g is Einstein with Einstein constant 2m.

As (M, g) is complete, thanks to Myers' theorem, (M, g) becomes compact. In order to turn g into Sasakian, we recall the following result of Morimoto [6]: "Let  $(M, \eta, g)$  be a compact K-contact manifold such that g is  $\eta$ -Einstein, i.e. its Ricci tensor satisfies  $Ric = ag + b\eta \otimes \eta$  for real constants a, b. If a > -2, then g is Sasakian". This result was also proved independently by Boyer and Galicki [5], and Apostolov et al. [1]. In our case, a = 2m and b = 0, and hence the aforementioned result holds. Thus, we conclude that gis Sasakian, and complete the proof.

#### 4 Commutation Of Ricci Soliton Vector Fields

We consider two distinct Ricci solitons with the same Riemannian metric and show that the Lie-bracket of their flow vector fields give rise to a steady Ricci soliton. More precisely, we prove

**Proposition 1** Let  $(M, g, X_1, \lambda_1)$  and  $(M, g, X_2, \lambda_2)$  be two distinct nontrivial Ricci solitons. Then,  $[X_1, X_2]$  determines a steady Ricci soliton on Mwith a metric homothetic to g.

**Proof** By hypothesis, we have

$$\pounds_{X_1}g + 2Ric = 2\lambda_1 g, \quad \pounds_{X_2}g + 2Ric = 2\lambda_2 g, \tag{23}$$

where  $\lambda_1$  and  $\lambda_2$  are constants. As these are two distinct Ricci solitons, we may assume without any loss of generality, that  $\lambda_1 < \lambda_2$ . The two equations in (23) show that  $X_1 = X_2 + H$  where H is a homothetic vector field satisfying  $\pounds_H g = 2(\lambda_1 - \lambda_2)g$ . The following computation:

$$\begin{aligned} \pounds_{[X_1,X_2]}g &= \pounds_{[X_2+H,X_2]}g = \pounds_{[H,X_2]}g = \pounds_H \pounds_{X_2}g - \pounds_{X_2} \pounds_H g \\ &= \pounds_H (-2Ric + 2\lambda_2g) - \pounds_{X_2} (2(\lambda_1 - \lambda_2)g) = 4(\lambda_1 - \lambda_2)Ric, \end{aligned}$$

shows that

$$\pounds_{\frac{1}{2(\lambda_2-\lambda_1)}[X_1,X_2]}g + 2Ric = 0.$$

Taking into account the fact that the Ricci tensor is invariant under a homothetic transformation and noticing that  $[X_1, X_2]$  cannot be conformal (otherwise g would become Einstein) we conclude that  $(M, \frac{1}{2(\lambda_2 - \lambda_1)}g, [X_1, X_2], 0)$ is a Ricci soliton which is steady. This completes the proof.

# 5 Concluding Remarks

1. In the proof of Theorem 1, Barros, Batista and Ribiero Jr. used a result of Yano and Nagano and the Hodge-de Rham decomposition. Our proof uses a theorem of Obata and does not need Hodge-de Rham decomposition.

2. The hypotheses of Theorem 2 can be interpreted in terms of contact Hamiltonians as follows. The contact Hamiltonian associated to a contact vector field X defined by equation (17) is a function  $\mathcal{H}$  defined as  $\eta(X)$ , and the function f turns out to be equal to  $\xi\mathcal{H}$ . The vector field X is the Hamiltonian vector field associated to  $\mathcal{H}$ . Computing  $\pounds_X \mathcal{H} = \pounds_X(\eta(X)) =$  $(\pounds_X \eta) X = f\eta(X) = f\mathcal{H} = (\xi\mathcal{H})\mathcal{H}$  shows that the contact vector field X is strict, i.e.  $f = \xi\mathcal{H} = 0$  if and only if the associated Hamiltonian  $\mathcal{H}$  is a first integral of X, i.e. is preserved along the flow of the Hamiltonian vector field X.

3. For the second part of Theorem 2, we found that  $\lambda = 2m$ , Ric = 2mg and hence Q = 2mI. Using these and the hypothesis f = 0 in equations (20) and (22) we infer that X preserves all structure tensors  $\eta, \xi, g, \varphi$ , and hence is an infinitesimal automorphism of the Sasakian structure on M.

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