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**Published on:** 23 Oct 2020 - bioRxiv (Cold Spring Harbor Laboratory)

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1 **Altered food habits? Understanding the feeding preference of free-ranging Grey langur**  
2 **(*Semnopithecus entellus*) within an urban settlement.**

3

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24 **ABSTRACT**

25 Urbanization affects concurrent human-animal movements as a result of altered resource availability and  
26 land use pattern, which leads to considerable ecological consequences. While some animals find  
27 themselves adrift, homeless with the uncertainty of resources resulting from the urban encroachment,  
28 few of them manage to survive by altering their natural behavioural patterns, and co-exist with humans.  
29 Folivorous colobines, such as grey langur, whose feeding repertoire largely consists of plant parts, tend  
30 to be more attuned to the urban high-calorie food sources to attain maximum fitness benefits within the  
31 concrete jungle having an insignificant green cover. However, such a mismatch between their  
32 generalized feeding behaviour and specialized gut physiology reminds us of the Liem's paradox and  
33 demands considerable scientific attention which could tell us the story behind colobines' successful co-  
34 existence within human settlements. Besides understanding their population dynamics, the effective  
35 management of these urbanized, free-ranging, non-human primate populations also depends on their  
36 altered feeding preferences, altogether which could lead us to the development of an ecologically sound  
37 urban ecosystem. Here, we have used a field-based experimental set up which allows langurs to choose  
38 between natural and urban food options, being independent of any inter-specific conflicts over resources  
39 due to food scarcity. The multinomial logit model reveals the choice-based decision making of these  
40 free-ranging grey langurs in an urban settlement of West Bengal, India, where they have not only  
41 learned to approach the human-provisioned urban food items but also shown a keen interest in it. While  
42 urbanization imposes tremendous survival challenges to these animals, it also opens up for various  
43 alternative options for human-animal co-existence which is reflected in this study, and could guide us  
44 for the establishment of a sustainable urban ecosystem in the future.

45

46

47

48 **HIGHLIGHTS**

49 • The feeding repertoire of free-ranging grey langurs at Dakshineswar largely consists of urban  
50 food items in contrast to the langurs of Nangi, and Nalpur who mostly depend on natural food  
51 sources.

52

53 • High human-langur interactions together with the scarcity of natural plant-based food sources  
54 could be considered as an intriguing driving force behind langurs' altered feeding habits in  
55 Dakshineswar.

56

57 • The field-based experimental set up allows free-ranging langurs to choose between natural and  
58 urban food options in an urban settlement like Dakshineswar.

59

60 • Urban food items outperformed natural food items as the most chosen one, indicating langurs'  
61 altered feeding preferences which facilitate their successful co-existence within an urban  
62 ecosystem.

63

64 **KEYWORDS**

65 Grey langur, free-ranging, urbanization, co-existence, feeding preference.

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68

69 The global urban human population is set to reach the five billion mark by 2028 (ONU, 2018),  
70 facilitating urban sprawling and subsequently contributing to natural habitat loss worldwide at an  
71 unprecedented rate. This is expected to affect a large number of animals whose habitat ranges overlap  
72 with urban areas (He et al., 2014; Martinuzzi et al., 2015; McDonald et al., 2008; Murray & St. Clair,  
73 2015). Habitat fragmentation and encroachment due to such urban expansion, which is often irreversible,  
74 has forced many homeless animals to live in close proximity to humans (Bateman & Fleming, 2012),  
75 giving rise to frequent human-animal conflict (Devi & Saikia, 2008; Omondi et al., 2004; Messmer 2000;  
76 Woodruffe et al., 2005). At the same time, some of these animals have also shown considerable  
77 behavioural adaptations like altered nesting or denning habits, vocalization, migratory activities, mating  
78 and breeding patterns, feeding behaviour (Able & Belthoff, 1998; Estes & Mannan, 2003; Kettlewell,  
79 1961; Lowry et al., 2013; Slabbekoorn & Peet, 2003; Swedell et al., 2011) together with life history  
80 modification to survive amidst anthropogenic stress. Such anthropogenic stress often creates  
81 unpredictable selection pressure on these urban animals, leading to a sharp decline in species richness  
82 and composition within an urban ecosystem (Erinjery et al., 2017; Fuentes, 2012; Kale et al., 2012; H.  
83 N. Kumara & Singh, 2004; Paul et al., 2016; Singh & Raghunatha Rao, 2004; Vitousek et al., 1997).  
84 However, despite significant loss of biodiversity, urban expansion offers various high-calorie resource  
85 options to the generalist species who have higher dietary as well as foraging plasticity, and therefore,  
86 can adjust more readily to the altered habitat in contrast to the specialists (Fisher & Owens, 2004;  
87 Vázquez & Simberloff, 2002). Moreover, such anthropogenic food sources remain available throughout  
88 the year, thus providing a risky yet reliable and easily accessible resource option which is thought to be

89 one of the major driving forces behind human-animal co-existence within urban settlements (Bateman &  
90 Fleming, 2012; Lowry et al., 2013; Thabethe & Downs, 2018; Widdows et al., 2015). In some cases,  
91 urban-dwelling free-ranging animals have been shown to acquire a preference toward anthropogenic  
92 food items to minimize their foraging activities, so that could invest more energy and time in nurturing  
93 social relationships which is essential to attain better fitness benefits (Bryson-Morrison et al., 2016,  
94 2017; Hoffman & O’Riain, 2012; Saj et al., 1999; Sha & Hanya, 2013; Thatcher et al., 2019).

95

96 India has more than 400 mammalian species, of which 17 are non-human primates with different  
97 conservation status (Karanth et al., 2010; Honnavalli N. Kumara et al., 2010; Molur et.al.,2003) who  
98 have ecological as well as socio-cultural importance. Three of these non-human primate species i.e.,  
99 Rhesus macaques (*Macaca mulatta*), bonnet macaques (*Macaca radiata*) and Hanuman langurs  
100 (*Semnopithecus entellus*) are frequently found in Indian cities, market places, temples, roadside  
101 settlements, etc., where they are often provisioned with human offered food items and space,  
102 worshipped and protected by *Hindus* (Sharma et al., 2011). Their wide distribution range and various  
103 feeding habits reflect their generalistic nature where they use a handful of novel strategies such as “coo-  
104 calls”, begging gestures, car raiding, etc. to acquire the available food items directly from humans  
105 (Arbib et al., 2008; Deshpande et al., 2018; Sha et al., 2009; Sinha, 2005). However, such close human-  
106 animal interaction is often lethal, affecting their chances of survival within urban ecosystems (Gosselink  
107 et al., 2007; Grinder & Krausman, 2001; Paul et al., 2016; Vijayan & Pati, 2002). Furthermore, these  
108 high-calorie urban food items could have a substantial effect on these animals’ physiology underlying  
109 their behavioural patterns, thereby reshaping intra and inter-specific group dynamics in contrast to their  
110 natural counterparts (Orams, 2002; Trave et al., 2017; Higginbottom & Scott, 2004). In this scenario, it

111 is imperative to understand how the oppression of urban expansion has thinned down the natural  
112 resources and influenced the lives of these animals, leading to urban-adaptation in these species.

113

114 While several studies have been carried out on the naturally omnivorous macaques (Goldstein &  
115 Richard, 1989; Ganguly & Chauhan, 2018; Laska, 2001; Oppenheimer 1977), to understand their  
116 opportunistic feeding behaviour to co-exist with human settlements, there has been no study yet to  
117 quantify and compare the dietary preference of folivorous Hanuman langurs in urban areas. Due to their  
118 deity value, this species is endowed with ample human provisioning. However, their specialized  
119 tripartite stomach structure largely aids in the digestion of a leafy diet (Bauchop & Martucci, 1968;  
120 Caton, 1999). Moreover, unlike the terrestrial macaques, the arboreal nature of Hanuman langurs  
121 (Khanal et al., 2018) is also barring them from availing enough human provisioning which could  
122 supplement their cellulose-based diet. Therefore, it seems to be all the more difficult for these large-  
123 bodied colobines to obtain sufficient resources that could be invested in maintaining reproductive fitness  
124 within an ecosystem where their natural food options are either unavailable or scarce to support their  
125 energy demand.

126

127 Grey langurs (*Semnopithecus entellus*), commonly called Hanuman langurs have colonized various parts  
128 of the Indian subcontinent, ranging from the desert to forest fringes, and have lived with a diversified  
129 resource structure and human interference (Ashalakshmi et al., 2014; Chetan et al., 2014;  
130 Oppenheimer, 1977). In comparison to the other species of Hanuman langur, grey langurs'  
131 (*Semnopithecus entellus*) social organization is highly flexible (Caton, 1999; Newton, 1988; Rajpurohit  
132 et al., 2006; Sterck, 1999) and is often modified by the male-male competition followed by infanticides

133 (Broom et al., 2004; Hrdy SB 1974; Sharma et al., 2010). Besides unimale-bisexual troops, all-male  
134 bands are also common in these langurs (L. S. Rajpurohit et al., 2003). Even though they exploit a wide  
135 range of plant species including various plant parts, only a fraction of these so-called “Least Concern  
136 species” (IUCN 2003) can reach their reproductive age, which is again expected to reduce due to the  
137 adverse effect of urban encroachment (Kumara et.al., 2020). On the contrary, such urban settlements  
138 provide easy access to various anthropogenic low-fiber food sources which are mostly processed yet  
139 offer high-calorie to these ruminant folivores (Sayers, 2013). Few articles have reported human-langur  
140 cooperation through the food provisioning in Indian cities and towns, portraying them as ecological  
141 generalists in terms of habitat and diet. This mismatch in their expected and observed diet has made  
142 them one of the prime examples of Liem’s paradox which refers to the odd pairing of specialized  
143 anatomical features with a generalistic diet (Binning et al., 2009; Liem, 1980). However, it was later  
144 argued that such “asymmetry allows optimally foraging consumers to evolve phenotypic specializations  
145 on nonpreferred resources without compromising their ability to use preferred resources” (Robinson &  
146 Wilson, 1998). Hence, the development of alternate feeding patterns in these urbanized free-ranging  
147 gray langurs demands considerable scientific attention which could provide important insights into their  
148 eco-ethological adaptation for better management and policy-making to develop a sustainable urban  
149 ecosystem. Several studies have manifested ‘food-resources’ as one of the major contributing factors  
150 that limit primate’s group size and composition (Chapman, 1990). The Van Schaik model posits that in  
151 folivorous non-human primates, the intra-group scramble feeding-competition leads to differential  
152 reproductive success which has an immense role in establishing the hierarchical relationship within the  
153 group (Van Schaik 1989; Borries 1993). Therefore, the feeding behaviour of the grey langurs can  
154 provide interesting insights into the social dynamics, as well as the urban adaptation of the species. In



155 this article, we have focused on the feeding preference of group-living, free-ranging grey langurs in the  
156 urban areas of West Bengal, India, in a habitat where they successfully co-exist with humans.

157

158

159

## 160 **METHODS**

### 161 *Study area and study animals*

162 Free-ranging langur troops were identified through regular census methods between September 2018 to  
163 December 2018 in various parts of West Bengal, India, of which three distinct langur troops (one in  
164 Dakshineswar (22.6573° N, 88.3624° E), one in Nangi (22.4973° N, 88.2214° E), and one in Sarenga,  
165 Nalpur (22.5307° N, 88.1840° E)) were selected for long-term field-based observations, considering the  
166 various level of human interferences received by the langurs (ESM1,2). Observers visited the areas at  
167 random times during the day and walked on all roads, by-lanes, and fields covered with vegetation of the  
168 above three selected urban settlements. Whenever a troop of langurs was sighted, it was observed *ad*  
169 *libitum* for a minimum of 15 minutes to a maximum of one hour, during which the observer recorded  
170 their location, troop size, and behaviours (later categorized as either intra- or inter-specific interactions).  
171 These data were used to categorize langurs into four distinct life stages based on their physical and  
172 behavioural characteristics (Infant- dark fur colour and fully dependent on adults for their movement and  
173 feeding; Juvenile- light fur colour similar to adults but smaller in size and partially dependent on adults  
174 for their movement and feeding; sub adult- fully independent of adults but yet to attain sexual maturity,  
175 body size is typically in between that of juveniles and adults; adult- fully grown, independent individual  
176 who is sexually mature) and also to note their territories (by using GPS- eTrex30, Garmin).

177

178 *Long-term study*

179 For long-term field-based observations, we followed these three troops between January 2019 to March  
180 2020 and recorded their behaviours using a combination of an equal number of instantaneous scans and  
181 all occurrences sessions (AOS) (Altmann, 1974). Whenever any feeding behaviour was observed, the  
182 observer recorded the details of the initiator, recipient, and their respective behaviours along with the  
183 food types (food-census) and location. Then, we categorized food items being eaten by the langurs into  
184 two distinct categories like ‘natural’ and ‘urban’ food sources (ESM 3a,b).

185

186 *Food-choice test*

187 We carried out a choice-based experiment in a field set-up to find out the feeding preferences of free-  
188 ranging langurs in an urban settlement like Dakshineswar where they received maximum human  
189 interference, including maximum food offerings (ESM 3a) (manuscript in preparation) and depend  
190 mostly on ‘urban’ food sources, unlike the langurs of Nalpur and Nangi (Figure 1). We offered a food  
191 tray of cardboard, with four types of food items (which were recorded as the ‘most frequently eaten’  
192 food items during the food-census), each of them having a comparable quantity and size (ESM 4), at any  
193 random times of a day between 0600 to 1800 hours. We used cauliflower and brinjal as ‘natural food’  
194 items, whereas bread and peanuts were used as ‘urban food’ items. All of these offered food items were  
195 fresh and suitable for human consumption. These were presented on the food tray in random order to  
196 avoid any ‘side-bias’. Since peanuts were seen to be one of the most frequently eaten urban food items,  
197 we used it for the choice-based experiment and offered it in a small paper bag (which is usually used by  
198 people to offer peanuts to langurs during provisioning), making its quantity visually similar to the other

199 food items. Based on the food-census data, we sub-divided the study area, Dakshineswar, into three  
200 distinct zones representing various feeding options available to langurs (ESM 5). The experimenter  
201 randomly chose one zone and presented the food tray to a spot where the maximum number of troop  
202 members can have equal access to the food tray. The experimenter either waited until the food tray was  
203 empty or waited for ten minutes if the food tray remained unattended or partially attended by the  
204 langurs, before closing the session. Once started, the experiment remained undisturbed i.e. no human  
205 interference was allowed and the entire experiment was video-recorded. In order to avoid any bias,  
206 which could influence subsequent trials, the videos were decoded only in April 2020, after the  
207 completion of all experiments. We conducted a total of 83 experiments in the field set-up of which 74  
208 experiments (where the food trays were attended by the langurs without having any human interference)  
209 were considered for the final analysis (ESM 6).

210

### 211 *Scoring method*

212 For each experiment, we recorded the times (in seconds) when a food item was ‘approached’ or  
213 attempted to be received by the langurs (FA), chosen to be eaten (FC), the delay between FA and FC (in  
214 seconds) (delay), number of rejection received by a food item (RJ), and the presence or absence of  
215 aggression shown by the langurs to possess a food item (AG). Then we scored the food items for each of  
216 these categories to reflect the langurs’ feeding preference separately for each experiment. Since the food  
217 tray had four food items, each of them had five scoring options for FA and FC. The food that was  
218 attempted to be taken first received a score of five and the last (fourth) one was given a score of two. If a  
219 food item remained unattempted, it received a score of one. Similar scoring was done for FC, where the  
220 food scored ‘one’ if it was not chosen to be eaten and ‘five’ for being eaten first. RJ was scored on a  
221 scale of a maximum of ‘eight’ to a minimum of ‘zero’, where food items scored ‘zero’ if they were not

222 rejected at all, and scored ‘eight’ when rejected for FA. Foods were scored ‘one’ if they received  
223 aggression and ‘zero’ if not, considering AG as an indication to the possessiveness for the most  
224 preferred food item which langurs did not want to share with. For ‘delay’ we scored them between  
225 ‘zero’ to ‘five’ where ‘zero’ represents no delay, ‘four’ for the maximum delay between FA and FC, and  
226 ‘five’ for the foods which were approached but not chosen to be eaten until the end of the experimental  
227 session.

228

### 229 *Statistical analysis*

230 We used the scores for FA, FC, RJ, AG, and delay for all statistical analyses which were carried out  
231 using *StatistiXL* (version 2.0), and *R* (version 4.0.2). We ran a correlation analysis to check the inter-  
232 relation between various factors like ‘attempt’ (FA), ‘choice’ (FC), ‘delay’, ‘rejection’ (RJ), and  
233 ‘aggression’ (AG) which were affecting the final food selection by the langurs. To verify the results of  
234 the correlation we used a generalized linear models (GLM) and checked which parameter was finally  
235 affecting the final selection of the food items. We used the FC as the response variable, whereas FA,  
236 AG, RJ, and ‘delay’ were incorporated into the model as the predictor variables. We used a ‘Poisson’  
237 distribution for the response variable to run the model. The distribution of the residuals was evaluated to  
238 check how well the model fits the data (ESM 7). A ‘principal component analysis’ (PCA) was conducted  
239 for descriptors like FA, FC, AG, RJ, and delay to check their effect on the food selection separately for  
240 three zones (Figure 2).

241

242

243

244 ***Multinomial logit model***

245 To explain the preference of one food over another, i.e., food choice, we ran varied combination of  
246 multinomial logit models (MLM). Since we were interested in checking the predictive values of  
247 different independent variables like aggression, rejection, etc. on the final outcome of food choice, we  
248 ran 2 different sets of MLMs – separately for the ‘approach’ and ‘choice’ probabilities (Table 1). These  
249 two sets had four sub-models each where we employed a ‘leave one component out’ (LOCO) approach  
250 to meet our goal. The LOCO approach leaves one food component out at each sub-model step to check  
251 the order of selection of the subsequent food item. Besides, the models also evaluate the importance of  
252 the independent variables or descriptors in the outcome.

253

254 The first set used the food approach as the outcome and the second set used the goal function of final  
255 food choice. When one food was approached i.e being attempted to be received by langurs, the  
256 probabilities of approaching the next food items can be determined subsequently by using set 1 MLMs.  
257 We ran four sub-set MLMs to check what would be the next approached food items separately while  
258 considering either brinjal, bread, cauliflower, or peanuts as the ‘first approached’ food item (Table 1a).  
259 Higher scores of the odds ratio confirm the results of MLM estimates thereafter (Table 2a) and  
260 subsequently rank the different food approach preferences according to the LOCO tactic.

261

262 Simultaneously, the set 2 MLMs were processed to establish and validate the preferred order of food  
263 items being chosen (final food choice) by the langurs during the experiment (Table 1b, 2b). The LOCO  
264 here assumes that one food has been consumed (and thus exhausted) and subsequently calculates the  
265 probabilities of choosing the next item. Since all food items were provided equally (i.e. equal probability

266 of choice at the beginning), the model considered the frequencies of alternatives equal to 0.25. We used  
267 the Newton-Raphson method from the package ‘*mlogit*’ in *R* to run the MLM (Croissant, 2020). The  
268 estimates of the MLM were plotted after normalizing to 1.0 (to avoid the negative values) for the visual  
269 representation (Figure 5).

270

271

### 272 *Food sharing*

273 We recorded the incidents of food sharing between langurs, if any, out of the total 221 successful cases  
274 (where the food items were attended by langurs) from a total of 296 cases (four food options for 74  
275 experiments). We included the details of the initiator, recipient, proportion of food being shared, and the  
276 interest of the initiator to share the food item with the recipient (i.e. shared forcefully or not). We used  
277 social network analysis (SNA) by using *Cytoscape* where we used various life stages (adult, subadult,  
278 juvenile, and infant) as a ‘node’ and an incident of food sharing between them as a ‘link’, separately for  
279 each food type (Figure 3). Here, we calculated the ‘*indegree*’ and ‘*outdegree*’ for each node representing  
280 the number of food sharing behaviour initiated and received by them respectively.

281

### 282 *Ethical note*

283 No langurs were harmed during this work. All work reported here was purely observation-based and did  
284 not involve direct handling of langurs in any manner, therefore, was in accordance with approved  
285 guidelines of animal rights regulations of the Government of India. The research reported in this paper  
286 was sanctioned by DST-INSPIRE, Government of India (approval number:

287 DST/INSPIRE/04/2018/001287, dated 24<sup>th</sup> July 2018), and was also notified to the Principal Chief  
288 Conservator of Forests (PCCF), West Bengal, India.

289

## 290 **RESULTS**

### 291 *Food census*

292 Feeding habit of free-ranging langurs greatly varied between locations (Contingency chi square:  $\chi^2 =$   
293 122.15, df = 2,  $p > 0.0001$ ). Langurs of Dakshineswar largely depended on urban food sources (83%)  
294 which were mostly human offered (manuscript in preparation), whereas in Nalpur and Nangi they  
295 mostly relied on the natural food sources (84% and 82% respectively) (Figure 1).

296

### 297 *Food choice test*

298 We carried out a total of 83 experimental trials in Dakshineswar, of which 74 were successful. The  
299 experimental outcomes were perused by ‘Correlation analysis’ and ‘Generalized linear model (GLM)’.  
300 Correlation analysis- Rejection (RJ) was seen to be highly correlated to attempt (FA), choice (FC), and  
301 ‘delay’. A significant positive correlation ( $r = 0.755$ ,  $p < 0.01$ ) was found between RJ and ‘delay’. On  
302 the other hand, high negative correlations with FA and FC ( $r = \text{FA: } -0.504$ ,  $\text{FC: } -0.814$ ;  $p < 0.01$ )  
303 represented inverse relations of the same with these factors. FC was highly and positively correlated to  
304 FA ( $r = 0.685$ ,  $p < 0.01$ ), especially towards a few food items like bread and brinjal (bread = 0.786,  
305 brinjal = 0.726, cauliflower = 0.594, peanuts = 0.606). On the contrary, ‘delay’ had significant negative  
306 effects on FC ( $r = -0.76$ ,  $p < 0.01$ ) (Figure 4).

307

308 The GLM confirmed the significant effects of predictor variables like attempt, rejection and delay on the  
309 final food choice. Considering the estimates and p-values, while FA (positive) and RJ (negative) showed  
310 more significant effects on the FC ( $p < 0.01$ ), ‘delay’ had a lesser impact (negative) ( $p < 0.05$ ) (Table 3).  
311 An even distribution of the residuals on either side of ‘0.0 line’ indicated that the model had a good valid  
312 fit (ESM 7).

313

314 Aggression (AG) had a slight negative influence on both FC and RJ ( $-0.29 \leq r \leq 0$  i.e. weak negative)  
315 (Figure 4, Table 3). However, the linear model (LM) plot revealed that when AG was not present (left  
316 panel, aggression = 0) and ‘delay’ was minimum (red color bands), FC was highest for lower RJ and  
317 *vice-versa*. Right panel showed that the presence of AG increased the ‘delay’ in FC (width of the colour  
318 bands represents the ‘increase’) (Figure 6a). Furthermore, a detailed LM plot revealed that with an  
319 increase in the FA, probabilities for FC increased, but both RJ and ‘delay’ lowered the FC (Figure 6b).

320

### 321 *Principal component analysis (PCA)*

322 Results of PCA showed that most of the variability in the experimental observations could be explained  
323 through PC1 (79.20%), and subsequently another 10.60% by PC2 (Table 4). The PCA biplot revealed  
324 that the ‘zones’ had no impact on food selection by langurs. The arrows associated with descriptors  
325 ‘attempt’ and ‘choice’ remained close to each other, and pointed in the direction of the increasing values  
326 of both PC1 and PC2 (the signs of the eigenvectors are also positive for both PC1 and 2, Table 4, Figure  
327 2), thereby confirming their positive effects on the food selection. However, ‘delay’ almost overlapped  
328 with the ‘rejection’ and pointed in the direction of the low value of PC1 but high value of PC2 (the signs  
329 of the eigenvectors for PC1 is negative and positive for PC2, Table 4, Figure 2), revealing their negative



330 impact on the food selection. The individual loading of ‘aggression’ was only -0.99 on PC5, therefore  
331 considered to have a minimal effect (Table 4).

332

### 333 *Multinomial logit model*

334 The multinomial logit model (MLM) provided a higher score for bread (estimate value: -0.075) among  
335 others, revealing the probability of approaching bread as the 2<sup>nd</sup> alternative, followed by cauliflower  
336 (estimate value: -0.155), and peanuts (estimate value: -0.368) when brinjal was attempted first.

337 Similarly, the MLM picked up bread, cauliflower, and peanuts, one by one, as the first attempted food  
338 item, and checked the probability of approach for the rest. Together with MLM estimate values, odds  
339 ratio confirmed the highest approach probabilities for brinjal, followed by bread, cauliflower, and  
340 peanuts (Table 1a, 2a, Figure 5a). However, for the choice probabilities, bread scored highest for both  
341 the MLM estimates and odds ratio, followed by brinjal, cauliflower, and peanuts (Table 1b, 2b, Figure  
342 5b).

343

### 344 *First attempted vs eaten food*

345 Bread and brinjal were chosen as the first attempted food item (scored ‘five’ for FA) for 31% and 32%  
346 cases respectively, followed by cauliflower (23%) and peanuts (14%). However, not always the first  
347 attempted foods were chosen to be eaten first. Langurs switched their preference between the first  
348 attempt to first choice for 29.7% cases, and mostly for bread (Goodness of fit:  $\chi^2 = 31.08$ ,  $df = 3$ ,  
349  $p < 0.0001$ ) (ESM 6).

350

351 *Food sharing*

352 Only 18% of the total successful cases were recorded where langurs shared the received food items with  
353 their troop members during the experimental trials. However, the shared food items mostly consisted of  
354 the least preferred peanuts (53%), and cauliflower (22%) (Goodness of fit:  $\chi^2 = 44.72$ ,  $df = 3$ ,  $p <$   
355  $0.0001$ ) (ESM 8). Social network analysis revealed that food sharing mostly occurs between adults  
356 (Goodness of fit: *Outdegree*:  $\chi^2 = 75.35$ ,  $df = 3$ ,  $p < 0.0001$ ; *Indegree*:  $\chi^2 = 40.39$ ,  $df = 3$ ,  $p < 0.0001$ )  
357 and largely for peanuts, and cauliflower (Figure 3).

358

359 **DISCUSSION**

360 Folivores colobines have received considerable research attention because of their unique ability to  
361 ingest large quantities of foliage (Newton, 1992; Oates 1988; Struhsaker & Oates, 1975). Their  
362 multipartite stomachs are lined with mucus-secreting glands which facilitate the fermentation of leafy  
363 diet in the presence of cellulolytic bacteria (Caton, 1999). However, the dietary composition of free-  
364 ranging Hanuman langurs (*Semnopithecus entellus*) seems to be relatively complex. They often use a  
365 diverse array of plant parts including leaves, stalks, shoots, buds, flowers, and fruit to utilize the  
366 available resources at its best (Yoshiba, 1967; Vandercone et al., 2012). Besides, Srivastava and Winkler  
367 added insectivory and human-provisioning to the Hanuman langurs' feeding repertoire (Srivastava,  
368 1989,1991; Winkler 1988). However, these feeding habits were mostly seasonal and plant parts still  
369 accounted for a significant portion of their regular diet (Koenig & Borries, 2001) similar to the langur  
370 group of Nungi, and Nalpur.

371

372 Surprisingly, the langur troop of Dakhineswar, West Bengal, India, was spotted to thrive largely (83% of  
373 the total diet) on the ‘urban’ food sources for their sustenance within human settlements, throughout the  
374 year. Similar to other free-ranging scavengers like dogs, jackals, monkeys, (Butler & du Toit, 2002; Paul  
375 et al., 2016; Sanyal et al., 2010) this langur troop was observed to rely upon human generosity and food  
376 provisioning, seeking easy access to the ‘urban’ food sources (Dasgupta et al., manuscript in  
377 preparation). However, unlike these carnivorous, and omnivorous scavengers, langur’s stomach  
378 physiology looks alike to that of herbivores such as Macropodidae (Caton, 1999). Therefore, human-  
379 provisioned ‘urban’ food sources could have an inevitable health impact, followed by potential  
380 behavioural alteration in these urban-adapted free-ranging langurs.

381

382 Our field-based observational data reflected the highest degree of human interference in Dakhineswar  
383 where langurs frequently approached humans to acquire ‘urban’ food sources, in contrast to the langurs  
384 of Nangi, and Nalpur where they opted for foraging and scavenging and depended mostly on ‘natural’  
385 food sources. Therefore, high human-langur interactions could be considered as an intriguing driving  
386 force behind langurs’ altered feeding habits in Dakhineswar. Moreover, the scarcity of plants and crop  
387 fields within the urban settlement like Dakhineswar might be another reason behind langurs’ consistent  
388 dependence on the ‘urban’ food options. In this context, the choice-based field experiment allowed us to  
389 understand whether it was the scarcity of the ‘natural food’ sources or the easy accessibility of the  
390 ‘urban food’ sources that lured them to get accustomed to the urban ecosystem.

391

392 The experimental set up allowed langurs to choose between natural and urban food sources, keeping  
393 aside the factors like scantiness, and human influences. Langurs chose brinjal, and bread consistently

394 either as the first or second food options, in all the three zones of Dakhineswar, reflecting their feeding  
395 preferences within urban settlements. The outcomes of the experiments manifested the ‘attempt’ to be a  
396 significant precursor to the food selection. Moreover, its close association to the descriptor, ‘food  
397 choice’, for the increasing values of both principal components 1 and 2 in the PCA confirmed the  
398 significance of langur’s approach towards a particular food item. Therefore, it can be interpreted that the  
399 food had to be approached first prior to the final selection, allowing langurs for choice-based decision-  
400 making. However, the effects of ‘rejection’ and ‘delay’ were also substantial, and the final food  
401 selection by the langurs seemed to be non-random but a consequence of all the above three factors. A  
402 significant positive correlation between ‘rejection’ and ‘delay’ revealed that more delays in food  
403 selection might lead to the ultimate rejection of that particular food item. A greater rate of rejection  
404 negatively facilitated the final choice, whereas swifter attempts towards food led to less rejection.  
405 Therefore, when an increased ‘attempt’ escalated the probabilities for the final food selection, ‘delay’  
406 gave rise to a dilemma between ‘food choice’ and ‘rejection’ which finally lowered the chances of  
407 selection for a given food item. ‘Aggression’ also had some negative effects on both ‘choice’ and  
408 ‘rejection’. Although it increased the ‘delay’ in final food selection, langurs used aggression to possess  
409 their chosen food items without being forced to share it with other troop members. Hence, our  
410 experiments revealed an active preference-based food selection by langurs within an urban settlement  
411 like Dakhineswar, driven neither by human interference, nor the scantiness of natural food options but  
412 by a keen interest towards specific food items. The multinomial logit model contemplated all of these  
413 factors for the final food selection by the langurs and revealed brinjal and bread to be the most attempted  
414 and first approached food items, followed by cauliflower and peanuts. However, bread outperformed  
415 brinjal as the most chosen food item for which langurs often switched their first approached food to the  
416 final selection, indicating their inclination to the urban food option.

417

418 In the case of food-provisioning where humans provide a food item of their choice to the animals, the  
419 animals have no scope to choose but to receive the offered food items. In our experimental set-up  
420 langurs had the liberty to choose from a platter of offered food items, without any human interference,  
421 and the underlying assumption was that the outcome of the experiment would be influenced only by  
422 their preference, if any. Our findings suggested that these langurs engaged with the items that were  
423 offered in the food-tray and chose bread and brinjal solely based on their feeding preference. Moreover,  
424 the social network analysis revealed that the adult langurs occasionally had the privilege to receive a  
425 food share from the focal langur, which rarely comprised of bread or brinjal, in contrast to the juveniles  
426 and subadults who hardly managed to get access to it, thereby showing their fondness for it.

427

#### 428 *Conclusions*

429 Although the impact of such ‘urban’ food sources on Hanuman langurs’ physiology is still debatable  
430 (Geffroy et al., 2017; Maréchal et al., 2016), it can be interpreted that these free-ranging Hanuman  
431 langurs of Dakhineswar not only learned to approach human-provisioned ‘urban’ foods but they  
432 acquired preferences for some of it which could facilitate their co-existence within an urban ecosystem.  
433 However, resource provisioning is often being correlated to peoples’ intension to get in touch with the  
434 wildlife, imposing a considerable threat to free-ranging animals’ survival chances (Orams, 2002; Trave  
435 et al., 2017). Yet, such man-animal interaction opens up possibilities for alternative easy access to  
436 resources like food and shelter for these animals who have lost their home due to urban encroachment  
437 (Cox & Gaston, 2018; Lowry et al., 2013; Theobald et al., 1997). Moreover, it has been shown that the  
438 ability to digest carbohydrates provided ancestral dog populations an advantage over wolves, facilitating

439 the process of domestication, as the dogs could now utilize human-generated resources (Axelsson et al.,  
440 2013). Undoubtedly, our experimental results are an example of such urban adaptation where folivorous  
441 arboreal Hanuman langurs find their interest in terrestrial urban food items. Therefore, besides their  
442 deity value, the free-ranging Hanuman langurs' successful co-existence with humans and their wide  
443 distribution throughout the Indian subcontinent could be well-explained by their altered yet  
444 opportunistic feeding pattern.

445

#### 446 **COMPETING INTERESTS**

447 We have no competing financial interests.

448

#### 449 **ACKNOWLEDGEMENTS**

450 DD and AB equally contributed to this work. DD, RK, DB, SM, SK, ABh, and SG carried out the field  
451 work. MP and DD coded the entire data. AB and MP carried out all the statistical analyses. AB prepared  
452 the correlation matrix, ran PCA, GLM, and MLM to interpret the data. MP conceptualized the study, got  
453 grants to support the work , designed the fieldwork and supervised the work. MP, DD, PB drafted the  
454 manuscript. PS prepared the GIS map. PB provided the laboratory support to carry out the analysis.  
455 Author AB acknowledges the DSKPD Fellowship of University grants commission (no. BL/17-  
456 18/0490). All the authors acknowledge Dr. Anindita Bhadra, Associate Professor, Indian Institute of  
457 Science Education and Research- Kolkata, India, for her valuable inputs to the study and gave final  
458 approval for publication.

459

460 **FUNDING**

461 This work was funded by project from Department of Science and Technology, India  
462 (DST/INSPIRE/04/2018/001287) and was supported by the Department of Environmental Science,  
463 University of Calcutta, Kolkata, India.

464

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## 767 **LEGENDS TO FIGURES**

768 **Figure 1:** Stacked bar diagram showing the feeding habit of free-ranging langurs at three locations,  
769 Dakshineswar, Nalpur, and Nangi. Black and grey bars represent the percentage of ‘natural’ and ‘urban’  
770 food items being eaten by the free-ranging langurs.

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772 **Figure 2:** Biplot representing the distribution of variables in 2D space for the Principal component  
773 analysis (PCA) having descriptors like attempt, choice, delay, rejection, and aggression. Circles  
774 represent three different zones of Dakshineswar

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776 **Figure 3:** Food-sharing networks of free-ranging hanuman langurs for various food items like a) bread,  
777 b) brinjal, c) cauliflower, and d) peanuts. The solid black circle represents a node, depicting a particular  
778 life stage of langurs. The black arrow represents one food-sharing behaviour between two nodes, which  
779 originated from the initiator and directed towards the recipient.

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781 **Figure 4:** The correlogram representing the inter-relation between factors like ‘attempt’ (FA), ‘choice’  
782 (FC), ‘rejection’ (RJ), ‘aggression’ (AG), and ‘delay’. It provides the correlation coefficient values ( $r$ )  
783 for each combination of factors and separately for each of the four food items along with their level of  
784 significance.

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786 **Figure 5:** Bar diagrams representing the normalized values of MLM estimates separately for a)  
787 ‘approach’, and b) ‘choice’ probabilities. The X-axis represents the a) first approached and b) first  
788 chosen foods.

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790 **Figure 6:** Linear model (LM) plot representing the variations in the choice of food for ‘rejection’ and  
791 ‘delay’. The width of the colour bands increases with the delay. a) LM plots showing different levels of  
792 ‘aggression’ has different effects on food choice. The left panel represents data for ‘zero aggression’,  
793 whereas the right panel shows that the ‘presence of aggression’ increases the delay in food choice. b)  
794 LM plots showing the effects of ‘attempt’ on food choice, together with ‘delay’ and ‘rejection’. Each  
795 panel represents a particular ‘delay’ score. For example, the top left panel is for ‘no delay’ or ‘zero’  
796 delay score, and the bottom right is for the ‘maximum delay’ i.e. score five.

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## 798 **LEGENDS TO TABLES**

799 **Table 1:** Table representing the estimates, and p-values of the multinomial logit models, set 1 and 2  
800 respectively for a) approach, and b) choice probabilities. These two sets represent four sub-models each.  
801 Here, we employed a ‘leave one component out’ (LOCO) approach which leaves one food component  
802 out at each sub-model step to check the order of selection of the subsequent food item.

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804 **Table 2:** Table representing the odds ratio separately for a) approach, and b) choice probabilities.

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806 **Table 3:** Table showing the outcomes of the generalised linear model (GLM). ‘Attempt’ shows a  
807 positive estimate value for  $p < 0.01$ , whereas ‘rejection’ and ‘delay’ come up with negative estimate  
808 values for  $p < 0.01$  and  $p < 0.05$  respectively. Though ‘aggression’ has a negative estimate value, it is not  
809 significant. Significant codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 '' 1.

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811 **Table 4:** Tabulated representation for the principal component analysis (PCA). It represents the  
812 ‘proportion of variance’ for each principal component (PC), followed by a ‘cumulative proportion’. It  
813 also displays the individual loading for each descriptor like ‘attempt’, ‘choice’, ‘delay’, ‘rejection’, and  
814 ‘aggression’.

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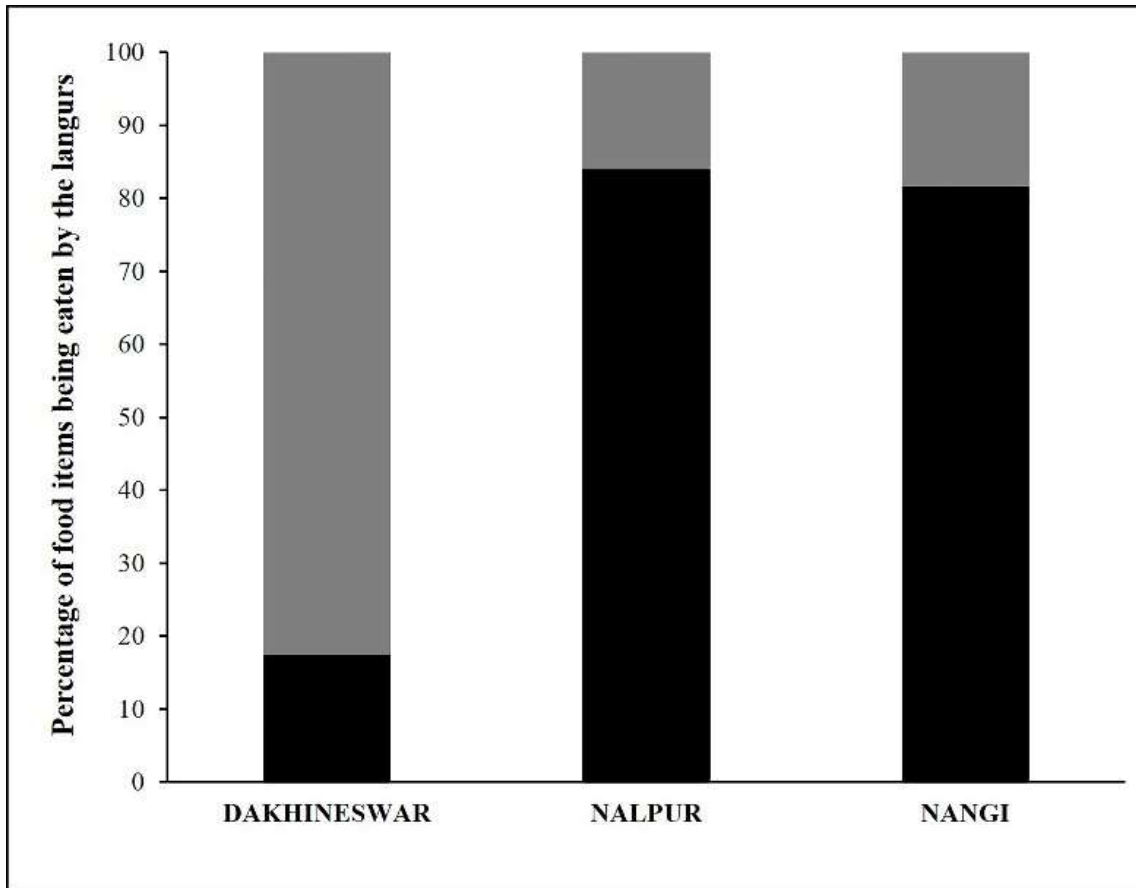
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828 **Figure 1**



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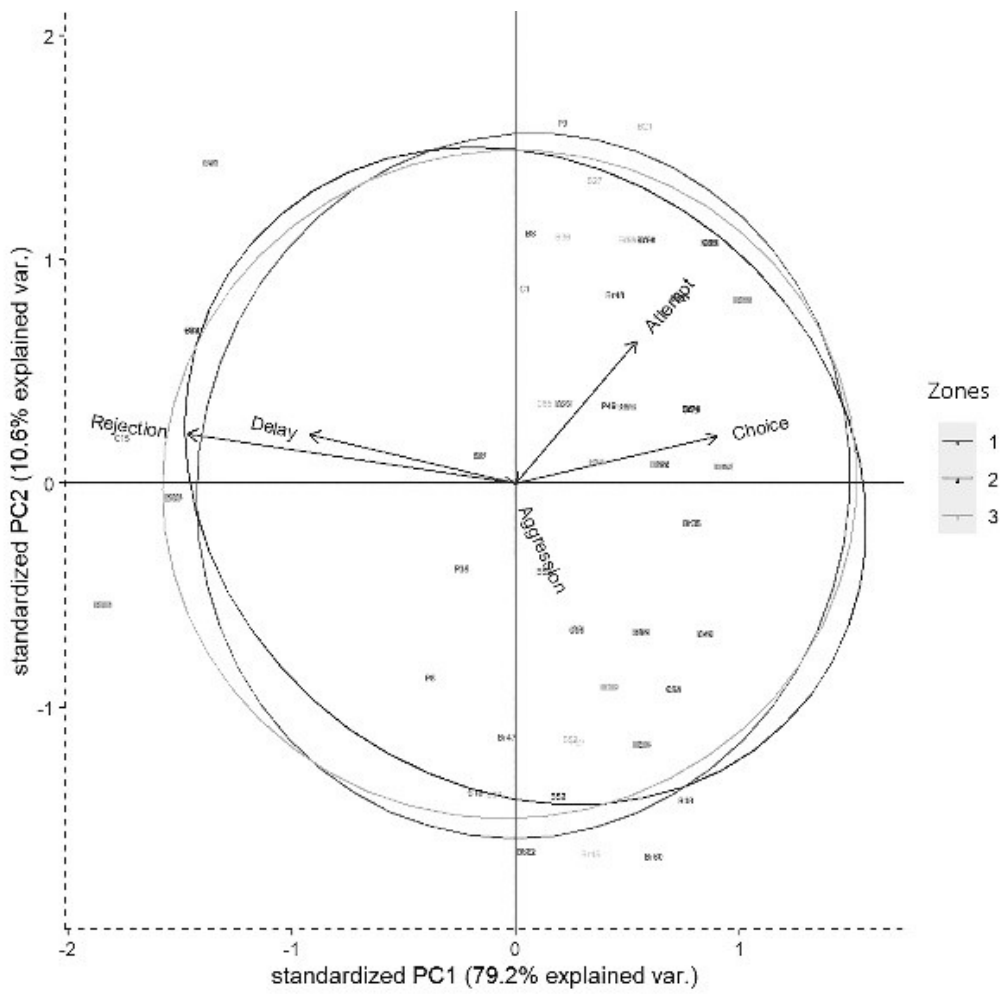
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837 **Figure 2**

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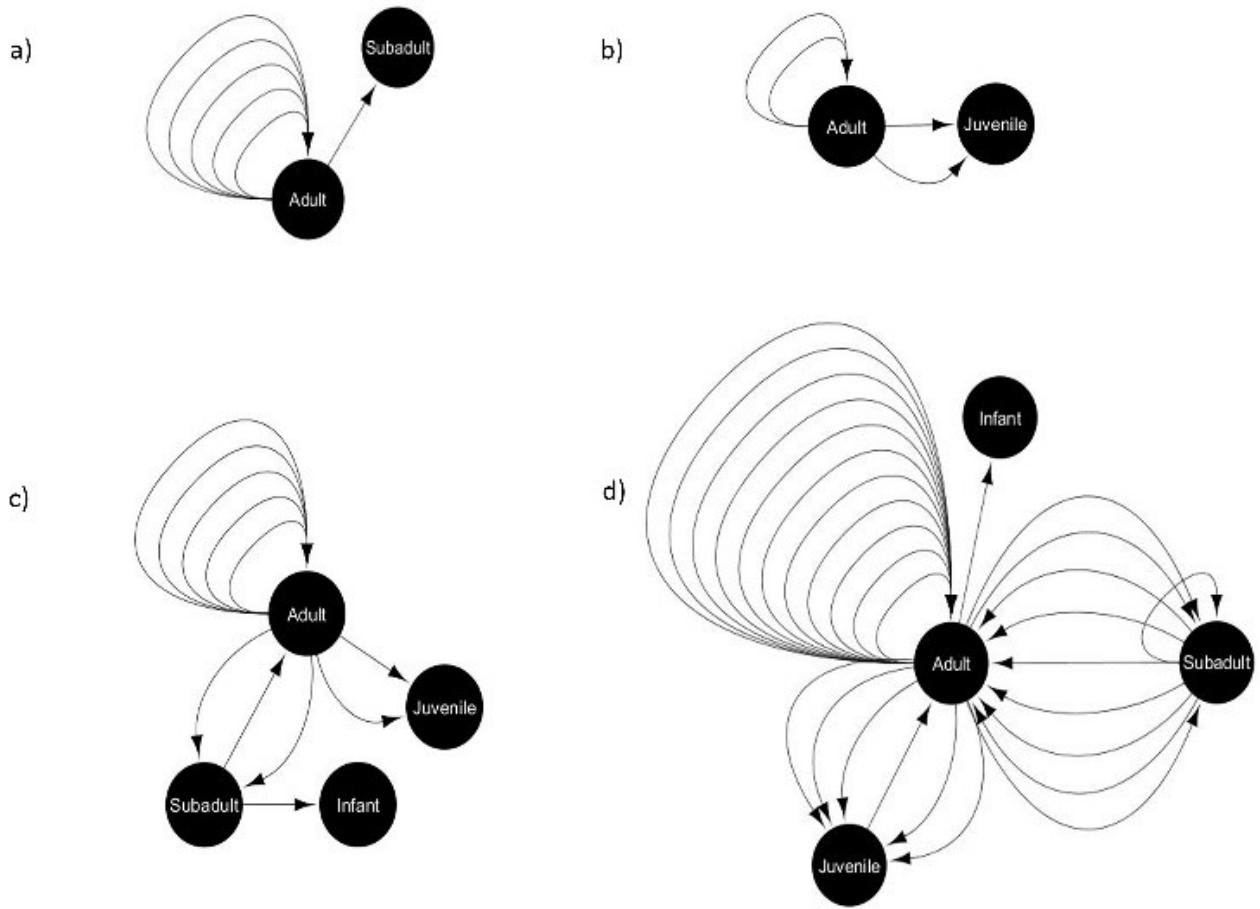
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845 **Figure 3**



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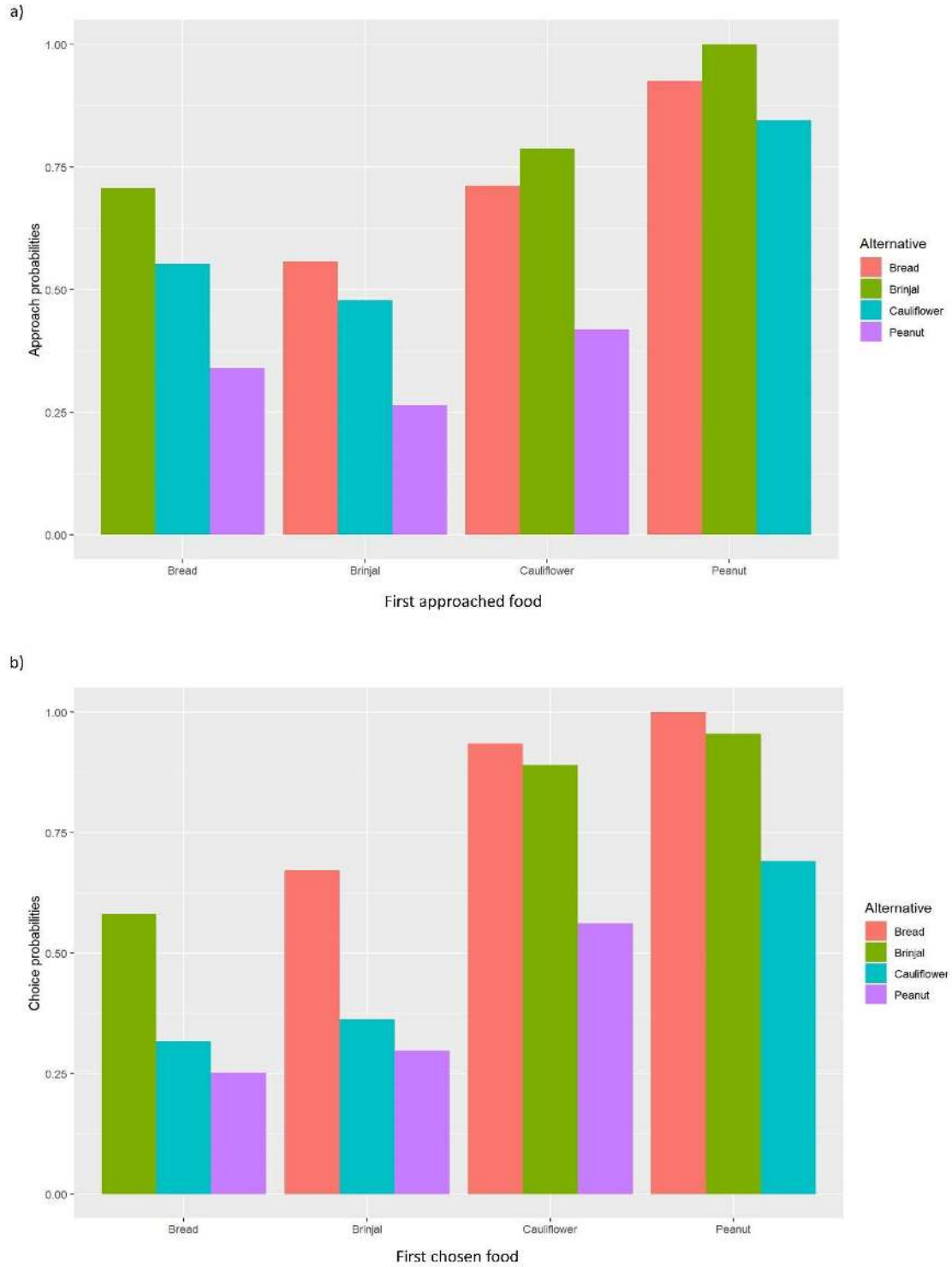
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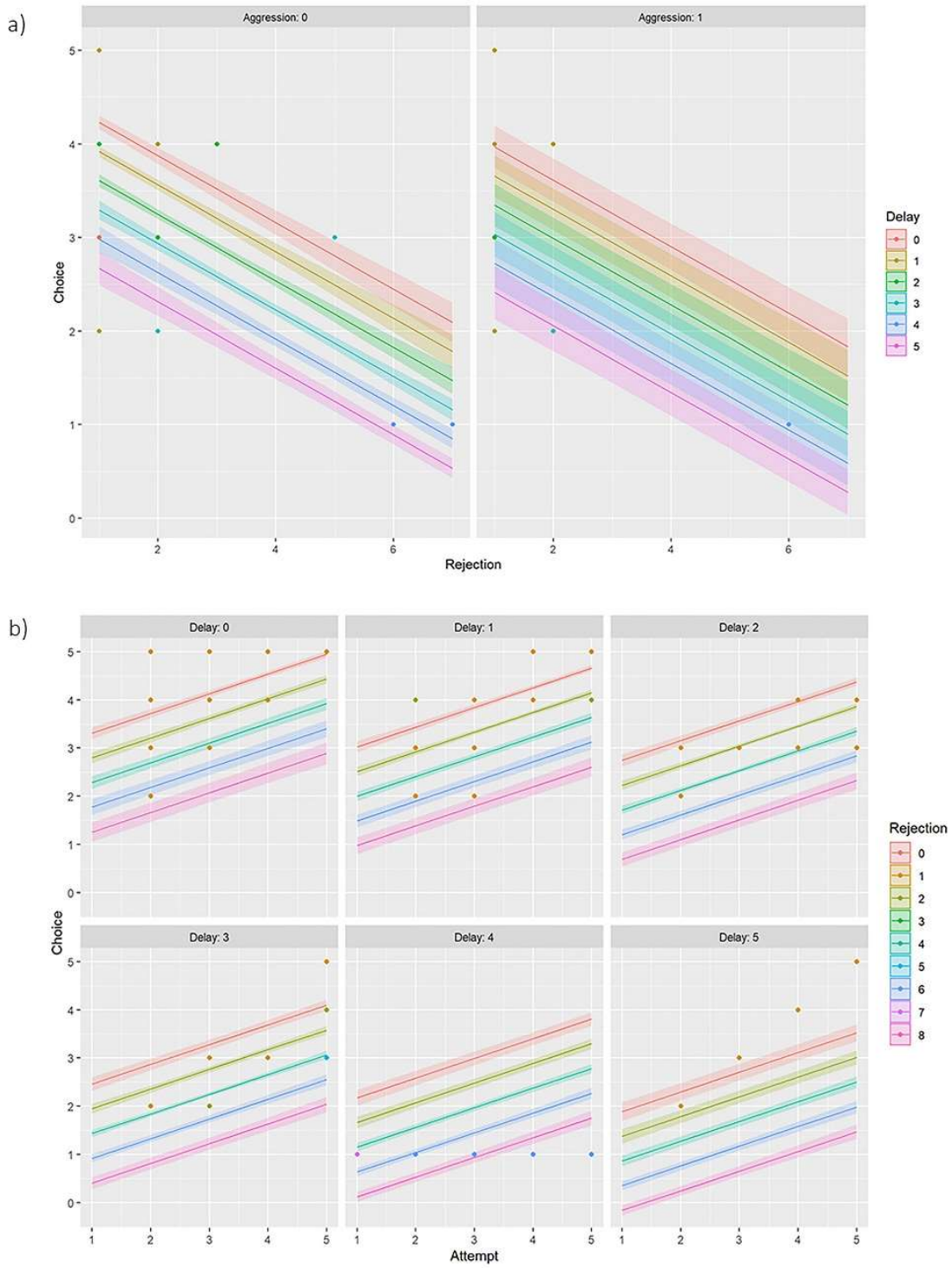
851 **Figure 4**



852 **Figure 5**



870 **Figure 6**



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897 **Table 1.**

<b>a)</b>	Coefficients	Estimate	Std. Error	z value	p value
Bread is approached first	Attempt: Brinjal	0.075	0.129	0.580	0.562
	Attempt: Cauliflower	-0.080	0.126	-0.631	0.528
	Attempt: Peanuts	-0.293	0.126	-2.322	0.020 *
Brinjal is approached first	Attempt: Bread	-0.075	0.129	-0.580	0.562
	Attempt: Cauliflower	-0.155	0.128	-1.206	0.228
	Attempt: Peanuts	-0.367	0.128	-2.868	0.004 **
Cauliflower is approached first	Attempt: Bread	0.080	0.126	0.631	0.528
	Attempt: Brinjal	0.155	0.128	1.206	0.228
	Attempt: Peanuts	-0.213	0.124	-1.713	0.087 .
Peanuts is approached first	Attempt: Bread	0.293	0.126	2.322	0.020 *
	Attempt: Brinjal	0.368	0.128	2.868	0.004 **
	Attempt: Cauliflower	0.213	0.124	1.713	0.087 .
<b>b)</b>	Coefficients	Estimate	Std. Error	z value	p value
Bread is chosen first	Choice: Brinjal	-0.045	0.114	-0.399	0.690
	Choice: Cauliflower	-0.309	0.113	-2.747	0.006 **
	Choice: Peanuts	-0.374	0.113	-3.301	0.001 ***
Brinjal is chosen first	Choice: Bread	0.045	0.114	0.399	0.690
	Choice: Cauliflower	-0.264	0.111	-2.371	0.018 *
	Choice: Peanuts	-0.328	0.112	-2.935	0.003 **
Cauliflower is chosen first	Choice: Bread	0.309	0.113	2.747	0.006 **
	Choice: Brinjal	0.264	0.111	2.371	0.018 *
	Choice: Peanuts	-0.065	0.109	-0.596	0.551
Peanuts is chosen first	Choice: Bread	0.374	0.113	3.301	0.001 ***
	Choice: Brinjal	0.328	0.112	2.935	0.003 **
	Choice: Cauliflower	0.065	0.109	0.596	0.551

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900 **Table 2**

a) Approach probabilities		
		Odds ratio
903	Bread is approached first	Attempt: Brinjal 1.078
904		Attempt: Cauliflower 0.923
905		Attempt: Peanuts 0.746
906	Brinjal is approached first	Attempt: Bread 0.928
907		Attempt: Cauliflower 0.857
908		Attempt: Peanuts 0.692
909	Cauliflower is approached first	Attempt: Bread 1.083
910		Attempt: Brinjal 1.167
911		Attempt: Peanuts 0.808
912	Peanuts is approached first	Attempt: Bread 1.340
913		Attempt: Brinjal 1.445
914		Attempt: Cauliflower 1.238
b) Choice probabilities		
		Odds ratio
916	Bread is chosen first	Choice: Brinjal 0.956
917		Choice: Cauliflower 0.734
918		Choice: Peanuts 0.688
919	Brinjal is chosen first	Choice: Bread 1.047
920		Choice: Cauliflower 0.768
921		Choice: Peanuts 0.720
922	Cauliflower is chosen first	Choice: Bread 1.362
923		Choice: Brinjal 1.302
924		Choice: Peanuts 0.937
925	Peanuts is chosen first	Choice: Bread 1.453
926		Choice: Brinjal 1.389
927		Choice: Cauliflower 1.067



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929 **Table 3.**

	Estimate	Std. Error	z value	p value
Attempt	0.152	0.031	4.950	7.43e-07 ***
Rejection	-0.171	0.028	-6.102	1.05e-09 ***
Delay	-0.067	0.030	-2.252	0.0243 *
Aggression	-0.041	0.158	-0.259	0.7957

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955 **Table 4.**

	PC1	PC2	PC3	PC4	PC5
Proportion of Variance	0.792	0.106	0.072	0.026	0.004
Cumulative proportion	0.792	0.898	0.970	0.996	1.000
Loadings of eigenvectors:					
Attempt	0.266	0.859		0.437	
Choice	0.444	0.285	0.153	-0.835	
Delay	-0.456	0.298	-0.789	-0.284	
Rejection	-0.724	0.303	0.595	-0.172	
Aggression					-0.999

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