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# An Asymptotic Formula for the Green's Function of an Elliptic Operator

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## 1. Introduction

Let  $G^\varepsilon(x, y)$  be the Green's function with pole at  $y$  of the Dirichlet problem for the uniformly elliptic operator  $L^\varepsilon$ , i.e., the weak solution of

$$\begin{cases} L^\varepsilon u := -\varepsilon a_{ij} u_{x_i x_j} + b_i u_{x_i} = \delta_y & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where  $0 < \varepsilon \leq 1$ ,  $\delta_y$  is the Dirac measure at  $y \in \Omega$ ,  $\Omega \subseteq \mathbb{R}^N$  is bounded and open, and we adopt, here and in the following, the summation convention. In this paper we show that under certain conditions on the vector field  $b$ , as  $\varepsilon \searrow 0$   $G^\varepsilon(\cdot, y)$  converges exponentially to 0, uniformly on compact subsets of  $\Omega \setminus \{y\}$ , with rate of decay  $\frac{-I(x, y) + o(1)}{\varepsilon}$ ,  $I(x, y) \geq 0$ , and we give a representation formula for  $I(x, y)$ .

The exponential decay as  $\varepsilon \searrow 0$  of the Green's functions of the parabolic operators  $\frac{\partial}{\partial t} + L^\varepsilon$  was studied by Varadhan [17, 18] in the case  $b \equiv 0$ , and by Friedman [7, 8] in the general case. Friedman employed the Ventcel-Freidlin estimates from the theory of large deviations of stochastically perturbed dynamical systems and some rather delicate parabolic estimates due to Aronson. His result is the following. For any  $x(\cdot) \in W_{loc}^{1,2}([0, \infty), \bar{\Omega})$  define

$$(1.1) \quad \|\dot{x}(s) + b(x(s))\|^2 := a^{ij}(x(s))(\dot{x}(s) + b(x(s)))_i (\dot{x}(s) + b(x(s)))_j,$$

where  $((a^{ij})) = a^{-1}$  is the inverse matrix of  $a$ . If  $\partial\Omega$ ,  $a_{ij}$  and  $b_i$  are smooth,

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then the Green's function with pole in  $y$ ,  $q^\varepsilon(t, x, y)$ , of  $\frac{\partial}{\partial t} + L^\varepsilon$ , satisfies

$$(1.2) \quad \lim_{\varepsilon \searrow 0} -\varepsilon \log q^\varepsilon(t, x, y) = \inf \left\{ \frac{1}{4} \int_0^t \|\dot{x}(s) + b(x(s))\|^2 ds \mid x(0) = x, \right. \\ \left. x(t) = y, x(s) \in \Omega \forall 0 \leq s \leq t \right\}.$$

The corresponding formula we propose for the elliptic case is the following:

$$(1.3) \quad \lim_{\varepsilon \searrow 0} -\varepsilon \log G^\varepsilon(x, y) = I(x, y) := \inf \left\{ \frac{1}{4} \int_0^t \|\dot{x}(s) + b(x(s))\|^2 ds; \right. \\ \left. x(\cdot) \in W^{1,2}([0, t], \Omega), x(0) = x, x(t) = y, \text{ for some } t \in [0, \infty) \right\}.$$

It is clear, however, that unlike the parabolic case, such a formula can be true only under some strong assumptions on the vector field  $b$ , since in the simple case  $b \equiv 0$ ,  $G^\varepsilon \rightarrow +\infty$  as  $\varepsilon \searrow 0$  uniformly on compact subsets of  $\Omega \setminus \{y\}$ . The main result of this paper is the proof of formula (1.3) in the case that  $b$  satisfies the following condition:

$$(B1) \quad \begin{cases} \text{if } x(\cdot) \in W_{\text{loc}}^{1,2}([0, \infty), \bar{\Omega}), \text{ then} \\ \int_0^\infty \|\dot{x}(s) + b(x(s))\|^2 ds = \infty. \end{cases}$$

Condition (B1) was first used by Fleming [5] in the study of a singular perturbation problem arising in stochastic control theory. Its physical meaning is that it takes an infinite amount of energy to resist the flow determined by  $-b$  and stay forever in  $\bar{\Omega}$ . In particular,  $b$  is "regular", i.e., it has no zeroes in  $\bar{\Omega}$ . We remark that the definition of  $I(x, y)$  coincides with that of "quasipotential" of the vector field  $b$  with respect to the point  $y$  in Freidlin-Wentzell [6, p. 108].

Our proof of (1.3) is completely independent of formula (1.2) and also of the probabilistic methods used by Friedman. Instead we follow the PDE approach to WKB-type results initiated in the recent paper by L.C. Evans and H. Ishii [4], where new, totally analytic and simpler proofs are given of three results due respectively to Varadhan, Fleming, and Ventcel-Freidlin. The idea of Evans-Ishii is basically the following: 1) apply a logarithmic transformation to the unknown function, in our case

$$v^\varepsilon(x, y) := -\varepsilon \log G^\varepsilon(x, y),$$

and find a PDE that  $v^\varepsilon$  solves; 2) prove estimates, independent of  $\varepsilon$ , on  $v^\varepsilon$  and its gradient; 3) show that a subsequence of  $v^\varepsilon$  converges as  $\varepsilon \searrow 0$ , to the *viscosity solution* of a Hamilton-Jacobi equation (see Crandall-Lions [2], Crandall-Evans-Lions [1] and P.L. Lions [14]); 4) by deterministic control theory methods find a representation formula for such a solution.

The main difficulties in the implementation of this plan in our case are in the treatment of the two boundary layers that our problem exhibits, one at the boundary  $\partial\Omega$ , where  $v^\varepsilon$  goes to  $+\infty$ , and the other around the singularity  $y$ , where  $v^\varepsilon$  goes to  $-\infty$ : notice that the limit  $I(x, y)$  is positive and bounded. To deal with these problems we shall establish in §2 suitable estimates of  $v^\varepsilon$  around  $y$ , and we shall introduce in §3 various approximating problems.

The pioneering work about singular perturbation of elliptic operators is due to Levinson [13]. We refer to Schuss [15] for an introduction to the physical motivations and an extensive bibliography. The theory of viscosity solutions has been utilized for problems of this type also by P.L. Lions [14, Ch. 6] and Kamin [12]. For results in the nonregular case, i.e.,  $b$  having one or more zeroes in  $\Omega$ , we refer to Freidlin-Wentzell [6], Friedman [8, Ch. 14], Kamin [11], Day [3], and the papers quoted therein. Kamin [19] has also treated recently a nonregular problem where the relevant Hamilton-Jacobi equation has more than one viscosity solution.

The paper is organized as follows: in §2 we list the hypotheses, recall a few definitions and basic facts about the Green's function, prove the estimates for  $v^\varepsilon$  and deduce from them a convergence result; in §3 we prove the representation formula for the limit.

### Acknowledgements.

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## 2. Estimates and Convergence

Throughout the paper we assume the summation convention and  $0 < \varepsilon \leq 1$ . We will write for brevity  $H := W_{\text{loc}}^{1,2}([0, \infty), \mathbb{R}^N)$ .

Let  $\Omega \subseteq \mathbb{R}^N$ ,  $N \geq 2$ , satisfy

(A1)  $\Omega$  is open, bounded and connected, with smooth boundary  $\partial\Omega$ .

Let  $S^{N \times N}$  be the space on  $N \times N$  symmetric matrices and let  $a : \Omega \rightarrow S^{N \times N}$  satisfy

$$(A2) \quad \begin{cases} a \in C^{1,\alpha}(\Omega) & \text{for some } \alpha > 0 \text{ and} \\ a_{ij}(x)\xi_i\xi_j \geq |\xi|^2 & \text{for every } \xi \in \mathbb{R}^N, x \in \Omega. \end{cases}$$

Let  $b : \bar{\Omega} \rightarrow \mathbb{R}^N$  satisfy

$$(B0) \quad b \in C^{1,\alpha}(\Omega) \text{ for some } \alpha > 0.$$

and define

$$d_i^\varepsilon := b_i + \varepsilon a_{ij}x_j, \quad D := \sup_{\substack{0 < \varepsilon \leq 1 \\ i=1,\dots,N}} \|d_i^\varepsilon\|_{L^\infty(\Omega)}.$$

It is well known that in the above hypotheses, for every  $f \in C^0(\bar{\Omega})$ , the unique weak solution of

$$(2.1) \quad \begin{cases} -(\varepsilon a_{ij}u_{x_i})_{x_j} + d_i^\varepsilon u_{x_i} = f & \text{in } \Omega, \\ u \in W_0^{1,2}(\Omega), \end{cases}$$

belongs to  $W_{loc}^{2,N}(\Omega) \cap C^0(\bar{\Omega})$  and it solves

$$(2.2) \quad \begin{cases} -\varepsilon a_{ij}u_{x_i x_j} + b_i u_{x_i} = f \text{ a.e. in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

see for instance [9, Ch. 9]. The problem adjoint to (2.1) is

$$(2.3) \quad \begin{cases} -(\varepsilon a_{ij}v_{x_i} + d_j^\varepsilon v)_{x_j} = \psi & \text{in } \Omega, \\ v \in W_0^{1,2}(\Omega), \end{cases}$$

which is also uniquely solvable in the weak sense.

DEFINITION [16]. A function  $G^\varepsilon(x, y)$  defined for  $x, y \in \Omega, x \neq y$  is a Green's function for the problem (2.1) if  $G^\varepsilon(\cdot, y) \in L^1(\Omega), \forall y \in \Omega$ , and

$$\int_{\Omega} G^\varepsilon(x, y)\psi(x)dx = v(y) \text{ for all } y \in \Omega,$$

for every  $\psi \in C^0(\bar{\Omega})$  and  $v$  the corresponding weak solution of (2.3).

From the theory of Stampacchia [16] it follows that there exists a unique Green's function for the problem (2.1), and it satisfies the following properties:

$$(2.4) \quad \begin{cases} G^\varepsilon(x, y) = \tilde{G}^\varepsilon(y, x) \\ \text{where } \tilde{G}^\varepsilon \text{ is the Green's function for problem (2.3), i.e.} \\ \int_{\Omega} \tilde{G}^\varepsilon(x, y)f(x)dx = u(y) \quad \forall y \in \Omega, \\ \text{for all } f \in C^0(\bar{\Omega}) \text{ and } u \text{ the corresponding solution of (2.1);} \end{cases}$$

$$(2.5) \quad \tilde{G}^\varepsilon(x, y) \geq 0;$$

$$(2.6) \quad \begin{cases} \text{for each } y \in \Omega \ G^\varepsilon(\cdot, y), \tilde{G}^\varepsilon(\cdot, y) \in W_0^{1,q}(\Omega) \\ \text{for every } q < \frac{N}{N-1}; \end{cases}$$

$$(2.7) \quad \begin{cases} \tilde{G}^\varepsilon(\cdot, y) \in W_{\text{loc}}^{1,2}(\Omega \setminus \{y\}) \\ \text{and it is a weak solution in } \Omega \setminus \{y\} \text{ of} \\ -(\varepsilon a_{ij} v_{x_i} + d_j^\varepsilon v)_{x_j} = 0. \end{cases}$$

PROPOSITION 2.8. *Under assumptions (A1), (A2), (B0) we have  $G^\varepsilon(\cdot, y) \in C^{3,\alpha}(\Omega \setminus \{y\})$  and it satisfies*

$$-\varepsilon a_{ij} G_{x_i x_j}^\varepsilon + b_i G_{x_i}^\varepsilon = 0 \text{ for all } x \in \Omega \setminus \{y\}.$$

PROOF. Fix  $\varepsilon$  and  $y$  and define  $u(x) = G^\varepsilon(x, y)$ . Let  $f_n$  be an approximation of the identity and let  $u^n$  be the weak solution of

$$\begin{cases} -(\varepsilon a_{ij} u_{x_i}^n)_{x_j} + d_i^\varepsilon u_{x_i}^n = f_n & \text{in } \Omega \\ u^n = 0 & \text{on } \partial\Omega. \end{cases}$$

By [16, Thm. 9.1] we have

$$\|u^n\|_{W_0^{1,q}(\Omega)} \leq K \quad \text{for } q < \frac{N}{N-1}.$$

Then a subsequence of  $u^n$  converges in  $L^q(\Omega)$  and weakly in  $W_0^{1,q}(\Omega)$  to  $u$ . Now fix  $\Omega' \subset\subset \Omega \setminus \{y\}$  with smooth boundary. For  $n$  big enough  $u^n$  solves

$$-\varepsilon(a_{ij} u_{x_i}^n)_{x_j} + d_i^\varepsilon u_{x_i}^n = 0 \quad \text{in } \Omega'.$$

Thus, by standard methods we have

$$\int_{\Omega'} |Du^n|^2 \, dx \leq C,$$

so that a subsequence of  $u_n$  converges in  $L^2(\Omega')$  and weakly in  $W^{1,2}(\Omega')$ , necessarily to  $u$ . Thus  $u$  is a weak solution in  $\Omega'$  of

$$-(\varepsilon a_{ij} u_{x_i})_{x_j} + d_i^\varepsilon u_{x_i} = 0.$$

Thus  $u$  is continuous and the proposition follows from the Schauder theory. □

By the above proposition and the strong maximum principle we have  $G^\varepsilon(x, y) > 0$  for all  $x \in \Omega$ ,  $x \neq y$ , so that we can define

$$v^\varepsilon(x, y) := -\varepsilon \log G^\varepsilon(x, y).$$

It is easy to check that  $v^\varepsilon(\cdot, y)$  satisfies

$$(2.9) \quad \begin{cases} -\varepsilon a_{ij} v_{x_i x_j}^\varepsilon + a_{ij} v_{x_i}^\varepsilon v_{x_j}^\varepsilon + b_i v_{x_i}^\varepsilon = 0 & \text{in } \Omega \setminus \{y\}, \\ v^\varepsilon(x, y) \rightarrow -\infty & \text{as } x \rightarrow y, \\ v^\varepsilon(x, y) \rightarrow +\infty & \text{as } x \rightarrow \partial\Omega. \end{cases}$$

For the solution of the above PDE it is possible to obtain interior estimates for the gradient independent of  $\varepsilon$ , as shown by Evans-Ishii [4]:

LEMMA 2.10. *For each  $\Omega' \subset\subset \Omega \setminus \{y\}$  there exists a constant  $C(\Omega')$ , independent of  $\varepsilon$ , such that every  $C^3$  solution of the PDE in (2.9) satisfies*

$$\sup_{\Omega'} |D_x v^\varepsilon| \leq C(\Omega').$$

PROOF. See [4, Lemma 2.2]. □

We are now going to prove interior estimates, independent of  $\varepsilon$ , for  $|v^\varepsilon|$ . To do this we will estimate the Green's function of the adjoint problem  $\tilde{G}^\varepsilon$  and exhibit the dependence of the constants on  $\varepsilon$ . The crucial exponential dependence on  $\varepsilon^{-1}$  of the bounds for  $\tilde{G}^\varepsilon$  comes from the constant in the Harnack inequality:

LEMMA 2.11. *Let  $\Omega' \subseteq \Omega$  be open and  $u \in W^{1,2}(\Omega')$ ,  $u \geq 0$ , be a solution of*

$$-(\varepsilon a_{ij} u_{x_i} + d_j^\varepsilon u)_{x_j} = 0 \quad \text{in } \Omega'.$$

*Then, for any ball  $B(z, 4r) \subset \Omega'$ ,  $r > \frac{4\varepsilon}{3}$ , we have*

$$(2.12) \quad \sup_{B(z,r)} u \leq C^{r/\varepsilon} \inf_{B(z,r)} u,$$

*where  $C = C(N, D, \|a_{ij}\|_{L^\infty(\Omega)})$ .*

PROOF. Fix  $x_0 \in B(z, r)$  and define

$$\tilde{a}_{ij}(x) := a_{ij}(x_0 + \varepsilon x), \quad \tilde{d}_j(x) := d_j^\varepsilon(x_0 + \varepsilon x), \quad \tilde{u}(x) := u(x_0 + \varepsilon x).$$

Then  $\tilde{u}$  solves

$$-(\tilde{a}_{ij} \tilde{u}_{x_i} + \tilde{d}_j \tilde{u})_{x_j} = 0 \quad \text{in } \tilde{\Omega} := \{x \mid x_0 + \varepsilon x \in \Omega'\},$$

$\tilde{a}$  satisfies (A2) and  $\|\tilde{d}_j\|_{L^\infty(\tilde{\Omega})} \leq D$ . Since  $B(0,4) \subseteq \tilde{\Omega}$ , by the Harnack inequality there exists  $C$  such that

$$\sup_{B(x_0,\epsilon)} u = \sup_{B(0,1)} \tilde{u} \leq C \inf_{B(0,1)} \tilde{u} = C \inf_{B(x_0,\epsilon)} u .$$

Since any two points in  $B(z,r)$  can be connected by a chain of  $\lceil \frac{2r}{\epsilon} \rceil$  appropriately overlapping balls of radius  $\epsilon$ , we obtain (2.12). □

REMARK 2.13. The dependence on  $\epsilon$  of the constant in the Harnack inequality displayed in (2.12) is sharp, as the following simple example shows:

$$-\epsilon \Delta u + u_{x_i} = 0 \quad \text{in } \mathbb{R}^N$$

has the positive solution  $u(x) = e^{x_i/\epsilon}$  that assumes the values  $e^{r/\epsilon}$  and  $e^{-r/\epsilon}$  on the boundary of  $B(0,r)$ . □

PROPOSITION 2.14. Assume (A1), (A2), (B0). The function  $\tilde{G}^\epsilon(x,y)$  defined in (2.4) satisfies the inequality

$$\tilde{G}^\epsilon(x,y) \geq \frac{C_1 e^{-C_2 \frac{|x-y|}{\epsilon}}}{|x-y|^{N-2}}, \quad \text{for } \frac{4\epsilon}{3} \leq |x-y| \leq 1 \wedge \text{dist}(y, \partial\Omega)/2$$

where  $C_1$  and  $C_2$  are constants independent of  $\epsilon$ .

PROOF. Fix  $x \neq y$  and define  $r = |x-y|$ ,  $u(z) := \tilde{G}^\epsilon(z,y)$ . Define  $S_1 := \{z \in \Omega \mid \frac{r}{2} \leq |z-y| \leq r\}$ ,  $S_2 := \{z \in \Omega \mid \frac{r}{4} \leq |z-y| \leq \frac{3r}{2}\}$  and let  $\zeta \in C_0^\infty(\Omega)$  be such that  $0 \leq \zeta \leq 1$ ,  $\zeta \equiv 1$  in  $S_1$ ,  $\zeta \equiv 0$  in  $\Omega \setminus S_2$ ,  $|D\zeta| \leq \frac{C}{r}$ . By (2.7), using  $\phi = u\zeta^2$  as a test function, we get

$$\epsilon \int_{\Omega} |Du|^2 \zeta^2 dz \leq \left(\frac{\epsilon C}{r} + D\right) \int_{\Omega} \sum_i |u_{x_i}| u \zeta dz + \frac{C}{r} \int_{\Omega} u^2 \zeta dz$$

where we indicate by  $C$  any constant depending only on  $N, D$  and  $\|a_{ij}\|_{L^\infty(\Omega)}$ . Thus

$$(2.15) \quad \int_{S_1} |Du|^2 dz \leq \frac{C}{\epsilon} \left(\frac{C\epsilon}{r^2} + \frac{C}{r} + \frac{C}{\epsilon}\right) \int_{S_2} u^2 dz \leq \left(\frac{C}{r^2} + \frac{C}{\epsilon^2}\right) r^N \sup_{S_2} u^2 .$$



Now let  $\phi \in C_0^\infty(\Omega)$  be such that  $0 \leq \phi \leq 1$ ,  $\phi \equiv 1$  in  $B(y, \frac{r}{2})$ ,  $\phi \equiv 0$  in  $\Omega \setminus B(y, r)$ ,  $|D\phi| \leq \frac{C}{r}$ . As a consequence of (2.4) and the regularity of the coefficients we have

$$\int_{\Omega} (\varepsilon a_{ij} u_{x_i} \phi_{x_j} + d_i^\varepsilon u \phi_{x_i}) dx = \phi(y).$$

Then

$$\begin{aligned} 1 &\leq \varepsilon \frac{C}{r} \int_{S_1} |Du| dz + \frac{C}{r} \int_{S_1} u dz \\ &\leq \frac{\varepsilon C}{r} r^{N/2} (r^N (\frac{C}{r^2} + \frac{C}{\varepsilon^2}) \sup_{S_2} u^2)^{1/2} + Cr^{N-1} \sup_{S_2} u \\ &\leq Cr^{N-2} \sup_{S_2} u \end{aligned}$$

for  $r \leq 1$ , where we have got the second inequality from Schwarz inequality and (2.15). Now, in order to apply the Harnack inequality (Lemma 2.11), we observe that any ball  $B(z, R)$  with  $z \in S_2$  and  $R = \frac{r}{20}$  is such that  $B(z, 4R) \subseteq \Omega \setminus \{y\}$ , and that any two points in  $S_2$  can be connected by a chain of appropriately overlapping such balls whose number depends only on  $N$ . Then we obtain

$$1 \leq Cr^{N-2} C^{r/\varepsilon} u(x),$$

which yields the conclusion. □

REMARK 2.16. For this proof we borrowed some ideas from Grüter-Widman [10]. □

In order to get the estimate from above of  $G^\varepsilon$  around the pole  $y$  we shall use hypothesis (B1). Define

$$\Omega_\gamma := \{x \in \mathbb{R}^N : \text{dist}(x, \Omega) < \gamma\}.$$

The main consequence of (B1) is the following Lemma, which is a slight extension of Lemma 4.2 in [4]:

LEMMA 2.17. Assume (B0) and (B1) and let  $\tilde{b}$  be a Lipschitz extension of  $b$  to a neighbourhood of  $\Omega$ . Then there exist  $\alpha > 0$ ,  $T > 0$ ,  $\gamma > 0$  such that

$$\int_0^S |\dot{x}(s) - \tilde{b}(x(s))|^2 ds \geq \alpha S$$

for all  $S \geq T$  and for all  $x(\cdot) \in W^{1,2}([0, S], \bar{\Omega}_\gamma)$ .

PROOF. First observe that (B1) is equivalent to

$$\int_0^\infty |\dot{x}(s) - b(x(s))|^2 ds = \infty$$

for all  $x(\cdot) \in W_{loc}^{1,2}([0, \infty), \bar{\Omega})$ . Then the proof (by contradiction) is essentially the same as that of Lemma 4.2 in [4]. □

LEMMA 2.18. *Under the assumptions of Lemma 2.17 there exist  $\gamma > 0$  and  $w \in W^{1,\infty}(\Omega_\gamma)$  such that*

$$(2.19) \quad \tilde{b}_i w_{x_i} \geq 3, \quad \text{a.e. in } \Omega_\gamma.$$

PROOF. For a given  $x(\cdot) \in H$ ,  $x(0) = x$ , let  $t_x$  be the first exit time of  $x(\cdot)$  from  $\Omega_\gamma$ , i.e.

$$t_x := \inf \{t > 0 : x(t) \notin \Omega_\gamma\}.$$

Let  $\alpha, T, \gamma$  be the constants provided by Lemma 2.17 and define for  $x \in \bar{\Omega}_\gamma$

$$w(x) := \inf \left\{ \int_0^{t_x} \left( \frac{3}{\alpha} |\dot{x}(s) - \tilde{b}(x(s))|^2 - 3 \right) ds : x(\cdot) \in H, x(0) = x \right\}.$$

By standard arguments  $w$  is Lipschitz continuous in  $\bar{\Omega}_\gamma$ .

Now, observe that  $w$  is the value function of the control problem of minimizing

$$\int_0^{t_x} \left( \frac{3}{\alpha} |\beta(s) - \tilde{b}(x(s))|^2 - 3 \right) ds$$

where  $x(\cdot)$  satisfies  $\dot{x}(s) = \beta(s)$ ,  $x(0) = x$ , and the control  $\beta(\cdot) \in L_{loc}^2([0, \infty), \mathbb{R}^N)$ . The Hamilton-Jacobi-Bellman equation associated to this problem is

$$\frac{\alpha}{12} |Dw|^2 - \tilde{b}_i w_{x_i} + 3 = 0.$$

Since  $w$  is continuous it is a viscosity solution of this equation (see [14, Thm. 1.10]), then by Rademacher's theorem it also satisfies the equation a.e., which implies (2.19). □

PROPOSITION 2.20. *Assume (A1), (A2), (B0), (B1). Then the function  $\tilde{G}^\varepsilon(x, y)$  defined in (2.4) satisfies*

$$\tilde{G}^\varepsilon(x, y) \leq \frac{C_1 e^{C_2 \frac{|x-y|}{\varepsilon}}}{|x-y|^N}, \quad \text{for } 20\varepsilon/3 < |x-y| < \text{dist}(y, \partial\Omega)/2 \text{ and } \varepsilon < C_3,$$

where the constants  $C_1, C_2, C_3$  are independent of  $\varepsilon$ .

PROOF. We extend  $b$  to a Lipschitz vector field  $\tilde{b}$  defined in a neighbourhood of  $\Omega$  and consider the function  $w$  constructed in Lemma 2.18. We call

$$w^\eta(x) := (w * \rho_\eta)(x), \quad \text{for } 0 < \eta < \gamma, \quad x \in \Omega,$$

the convolution of  $w$  with a mollifier  $\rho_\eta$ . Then  $w^\eta$  is smooth and satisfies

$$\begin{aligned} \sup_{\Omega} |w^\eta| &\leq C, \quad \text{for } 0 < \eta < \gamma, \\ b_i w_{x_i}^\eta &\geq 3 - C\eta \quad \text{in } \Omega, \end{aligned}$$

and

$$|w_{x_i x_j}^\eta| \leq C/\eta^2 \quad \text{in } \Omega.$$

Now we choose  $\eta_0$  small enough so that  $v := w^{\eta_0}$  satisfies

$$b_i v_{x_i} \geq 2,$$

and

$$-\varepsilon a_{ij} v_{x_i x_j} \geq -\varepsilon C/\eta_0^2.$$

Therefore  $v$  satisfies

$$-\varepsilon a_{ij} v_{x_i x_j} + b_i v_{x_i} \geq 1, \quad \text{for all } \varepsilon \leq \eta_0^2/C =: C_3, \quad x \in \Omega.$$

Now let  $u^\varepsilon$  be the solution of

$$\begin{aligned} -\varepsilon a_{ij} u_{x_i x_j}^\varepsilon + b_i u_{x_i}^\varepsilon &= 1, \quad \text{a.e. in } \Omega, \\ u^\varepsilon &= 0, \quad \text{on } \partial\Omega. \end{aligned}$$

By the Alexandrov-Bakelman-Pucci maximum principle (see e.g. [9, Thm. 9.1]) we then have

$$\sup_{\Omega} u^\varepsilon \leq \sup_{\Omega} v + \sup_{\partial\Omega} v^- \leq C, \quad \text{for } \varepsilon \leq C_3.$$

Using the definition of  $\tilde{G}^\varepsilon$  we get

$$\int_{\Omega} \tilde{G}^\varepsilon(x, y) dx = u^\varepsilon(y) \leq C, \quad \text{for } \varepsilon \leq C_3, \quad y \in \Omega.$$

Now taking  $\rho = |x - y|/5$ ,  $4\varepsilon/3 < \rho < \text{dist}(x, \partial\Omega)/4$ , by the Harnack inequality (Lemma 2.11) we have

$$\tilde{G}^\varepsilon(x, y) \leq C^{\rho/\varepsilon} \inf_{z \in B(x, \rho)} \tilde{G}^\varepsilon(z, y) \leq \frac{C^{\rho/\varepsilon}}{\rho^N} \int_{\Omega} \tilde{G}^\varepsilon(x, y) dx.$$

□

**THEOREM 2.21.** *Assume (A1), (A2), (B0), (B1). For each  $y \in \Omega$  there exists a sequence  $\varepsilon_k \searrow 0$  and a function  $v(\cdot, y) \in C^{0,1}(\bar{\Omega})$  such that  $\lim_k v^{\varepsilon_k}(\cdot, y) = v(\cdot, y)$  uniformly on compact subsets of  $\Omega \setminus \{y\}$  and  $v(\cdot, y)$  is a viscosity solution of the Hamilton-Jacobi equation*

$$(2.22) \quad a_{ij}v_{x_i}v_{x_j} + b_iv_{x_i} = 0 \quad \text{in } \Omega \setminus \{y\}.$$

Moreover there exists a positive constant  $C$  such that

$$(2.23) \quad |v(x, y)| \leq C|x - y|, \text{ for } |x - y| \leq 1 \wedge \text{dist}(y, \partial\Omega)/2.$$

**PROOF.** Lemma 2.10 and Propositions 2.14 and 2.20 imply that  $\{v^\varepsilon(\cdot, y), 0 < \varepsilon \leq 1\}$  is bounded in  $W_{loc}^{1,\infty}(\Omega)$ . Therefore a subsequence converges uniformly to  $v(\cdot, y) \in W_{loc}^{1,\infty}(\Omega)$ , which is a viscosity solution of (2.22) because  $v^\varepsilon(\cdot, y)$  solves (2.9), see Crandall-Lions [2, §IV.1]. By the results of Crandall-Lions [2, §I.4], (2.22) implies  $|Dv(\cdot, y)| \leq C$  in  $\Omega \setminus \{y\}$  and then  $v(\cdot, y)$  has a unique Lipschitz extension to  $\bar{\Omega}$ . □

### 3. The Representation Formula for the Limit

We recall the definition:

$$I(x, y) := \inf \left\{ \frac{1}{4} \int_0^t \|\dot{x}(s) + b(x(s))\|^2 ds \mid 0 \leq t < \infty, \right. \\ \left. x(\cdot) \in W^{1,2}([0, t], \Omega), x(0) = x, x(t) = y \right\}$$

where  $\|\dot{x}(s) + b(x(s))\|^2$  is defined by (1.1). Our main result is the following:

**THEOREM 3.1.** *Assume (A1), (A2), (B0), (B1). Then*

$$\lim_{\varepsilon \searrow 0} v^\varepsilon(\cdot, y) = I(\cdot, y)$$

uniformly on compact subsets of  $\Omega \setminus \{y\}$ .

**PROOF.** Let  $v(\cdot, y) = \lim_k v^{\varepsilon_k}(\cdot, y)$  uniformly on compact subsets of  $\Omega \setminus \{y\}$  for some  $\varepsilon_k \searrow 0$ . Our goal is to prove that  $v(x, y) = I(x, y)$  for all  $x, y \in \Omega$ . For  $x \in \Omega$  let  $\tau_x$  be the first exit time of  $x(\cdot) \in H, x(0) = x$ , from  $\Omega \setminus \{y\}$ . Since by Theorem 2.21  $v(\cdot, y)$  is a viscosity solution of (2.22) and we are assuming

(B1), the following representation formula of Evans-Ishii [4, Thm. 4.1] holds:

$$v(x, y) = \inf\left\{\frac{1}{4} \int_0^{\tau_x} \|\dot{x}(s) + b(x(s))\|^2 ds + v(x(\tau_x), y) \mid x(\cdot) \in H, x(0) = x\right\},$$

for all  $x \in \Omega \setminus \{y\}$ .

Since either  $x(\tau_x) = y$  or  $x(\tau_x) \in \partial\Omega$ , we have

$$\begin{aligned} v(x, y) &\leq \inf\left\{\frac{1}{4} \int_0^{\tau_x} \|\dot{x}(s) + b(x(s))\|^2 ds + v(x(\tau_x), y) \mid x(\cdot) \in H, x(0) = x, \right. \\ &\qquad\qquad\qquad \left. x(\tau_x) = y\right\} \\ &= \inf\left\{\frac{1}{4} \int_0^{\tau_x} \|\dot{x}(s) + b(x(s))\|^2 ds \mid x(\cdot) \in H, x(0) = x, x(\tau_x) = y\right\} \\ &= I(x, y) \end{aligned}$$

because (2.23) implies  $v(y, y) = 0$ .

We are now going to prove that  $v(x, y) \geq I(x, y)$  for all  $x, y \in \Omega$ . We fix  $y \in \Omega$  and in order to simplify the notation we drop the second variable  $y$  in  $v^\epsilon$ ,  $v$ ,  $I$  and in all the functions defined in the following. Define  $\Omega' = \Omega \cup \{x \notin \Omega \mid \text{dist}(x, \partial\Omega) < \beta\}$ , for  $\beta > 0$  small, let  $\tau'_x$  be the exit time of  $x(\cdot) \in H$   $x(0) = x \in \Omega'$  from  $\Omega' \setminus \{y\}$ , and extend  $a$  and  $b$  to be Lipschitz and bounded in all  $\mathbb{R}^N$ . For  $\lambda \geq 0$ ,  $x \in \Omega'$ , define

$$I'_\lambda(x) := \inf\left\{\frac{1}{4} \int_0^{\tau'_x} e^{-\lambda s} \|\dot{x}(s) + b(x(s))\|^2 ds \mid x(\cdot) \in H, x(0) = x, \right. \\ \left. x(\tau'_x) = y \text{ if } \tau'_x < \infty\right\}.$$

For all  $\lambda \geq 0$   $I'_\lambda$  is locally Lipschitz with  $|DI'_\lambda| \leq \frac{1}{4}(1 + \|b\|_{L^\infty(\Omega)})^2$  so that

$$(3.2) \qquad |I'_\lambda| \leq C, \qquad C \text{ independent of } \lambda,$$

and it is not difficult to show, using the argument in [4, Lemma 2.4], that  $I'_\lambda$  is a viscosity solution of

$$\begin{cases} \lambda I'_\lambda + a_{ij} I'_{\lambda x_i} I'_{\lambda x_j} + b_i I'_{\lambda x_i} = 0 & \text{in } \Omega' \setminus \{y\} \\ I'_\lambda(y) = 0. \end{cases}$$

Now define for  $0 < \gamma < \beta$  the mollification

$$I'_\lambda{}^\gamma(x) := (I'_\lambda * \rho_\gamma)(x), \qquad x \in \bar{\Omega},$$

where  $\rho_\gamma$  is an approximation of the identity. It is easy to deduce from Jensen's inequality, (A2), (B0) and (3.2) that

$$\lambda I'_\lambda{}^\gamma + a_{ij} I'_{\lambda x_i}{}^\gamma I'_{\lambda x_j}{}^\gamma + b_i I'_{\lambda x_i}{}^\gamma \leq C\gamma, \qquad x \in \Omega,$$

where  $C$  is independent of  $\gamma$  and  $\lambda$ . (3.2) implies also

$$-\varepsilon a_{ij} I_{\lambda x_i x_j}^{\gamma} \leq \frac{C\varepsilon}{\gamma^2}, \quad \text{for all } x \in \Omega,$$

so that  $I_{\lambda}^{\gamma}$  satisfies

$$(3.3) \quad L_{\lambda}^{\varepsilon} I_{\lambda}^{\gamma} \leq C_0 \left( \gamma + \frac{\varepsilon}{\gamma^2} \right) \quad \text{in } \Omega$$

for a suitable constant  $C_0$  independent of  $\varepsilon$ ,  $\gamma$  and  $\lambda$ , where  $L_{\lambda}^{\varepsilon}$  is the quasilinear elliptic operator

$$L_{\lambda}^{\varepsilon} w := -\varepsilon a_{ij} w_{x_i x_j} + a_{ij} w_{x_i} w_{x_j} + b_i w_{x_i} + \lambda w.$$

Furthermore, since  $I_{\lambda}^{\gamma}(y) = 0$ , we have  $I_{\lambda}^{\gamma}(y) \leq C_1 \gamma$  and thus

$$(3.4) \quad I_{\lambda}^{\gamma}(x) \leq C_1 \gamma + C_2 R \quad \text{for all } x \in \partial B(y, R),$$

where the constants are independent of  $\lambda$ ,  $\gamma$  and  $R$ ,  $0 < R < \text{dist}(y, \partial\Omega)$ .

Now fix a constant  $M$  such that

$$(3.5) \quad I_{\lambda}^{\gamma} \leq M, \quad \text{on } \partial\Omega, \quad \text{for all } \lambda, \gamma,$$

and define  $v_{\lambda, R}^{\varepsilon}$  to be the solution of

$$(3.6) \quad \begin{cases} L_{\lambda}^{\varepsilon} v_{\lambda, R}^{\varepsilon} = 0 & \text{in } \Omega \setminus B(y, R), \\ v_{\lambda, R}^{\varepsilon} = C_1 \gamma + C_2 R & \text{on } \partial B(y, R), \\ v_{\lambda, R}^{\varepsilon} = M & \text{on } \partial\Omega, \end{cases}$$

(for the existence and regularity of  $v_{\lambda, R}^{\varepsilon}$  see e.g. [9, Thm. 15.10]). By the comparison principle [9, Thm. 10.1] and (3.3-4-5) we have

$$(3.7) \quad I_{\lambda}^{\gamma} \leq v_{\lambda, R}^{\varepsilon} + \frac{C_0}{\lambda} \left( \gamma + \frac{\varepsilon}{\gamma^2} \right) \quad \text{in } \Omega \setminus B(y, R),$$

and

$$(3.8) \quad v_{\lambda, R}^{\varepsilon} \geq 0 \quad \text{in } \Omega \setminus B(y, R).$$

Again by the comparison principle, (3.6) (3.8) and (2.9) (2.20) we get

$$v_{\lambda, R}^{\varepsilon} \leq v^{\varepsilon} + C_1 \gamma + C_2 R + CR + \varepsilon(C - N \log R) \quad \text{in } \Omega \setminus B(y, R).$$

Combining this last inequality with (3.7) and letting  $\varepsilon \rightarrow 0$ ,  $\gamma \rightarrow 0$  and  $R \rightarrow 0$  in this order we get

$$(3.9) \quad I_{\lambda}^{\gamma}(x) \leq v(x) \quad \text{for all } x \in \Omega.$$

We are now going to show that

$$I_\lambda(x) := \inf \left\{ \frac{1}{4} \int_0^{\tau_x} e^{-\lambda s} \|\dot{x}(s) + b(x(s))\|^2 ds \mid x(\cdot) \in H, x(0) = x, x(\tau_x) = y \right\}$$

satisfies

$$(3.10) \quad I_\lambda(x) \leq \liminf_{\beta \searrow 0} I'_\lambda(x) \leq v(x) \text{ for all } x \in \Omega.$$

Fix  $\varepsilon > 0$ . Let  $\beta_n \searrow 0$  as  $n \rightarrow \infty$ ,  $\Omega_n := \Omega \cup \{x \notin \Omega \mid \text{dist}(x, \partial\Omega) < \beta_n\}$ , let  $\tau_x^n$  be the exit time from  $\Omega_n \setminus \{y\}$  of  $x(\cdot) \in H, x(0) = x$  and let  $I'_{\lambda,n}$  be  $I'_\lambda$  for  $\beta = \beta_n$ . Now take  $x_n(\cdot) \in H$  such that  $x_n(0) = x, x_n(\tau_x^n) = y$  if  $\tau_x^n < \infty$  and

$$\frac{1}{4} \int_0^{\tau_x^n} e^{-\lambda s} \|\dot{x}_n(s) + b(x_n(s))\|^2 ds \leq I'_{\lambda,n}(x) + \varepsilon.$$

Define

$$z_n(s) := \begin{cases} x_n(s) & \text{for } s \leq \tau_x^n \\ \text{the solution of } \begin{cases} \dot{z} = -b(z) \\ z(\tau_x^n) = y \end{cases} & \text{for } s > \tau_x^n, \text{ if } \tau_x^n < \infty. \end{cases}$$

It is easy to see, using (3.9), that for all  $T > 0$

$$\frac{1}{4} \int_0^T e^{-\lambda s} |\dot{z}_n(s)|^2 ds \leq Cv(x) + C\varepsilon + CT,$$

so that the sequence  $\{z_n(\cdot)\}$  is bounded in  $W^{1,2}([0, T], \Omega_0)$ . Hence there exists  $z(\cdot) \in H$  and a subsequence of  $z_n(\cdot)$ , still denoted by  $z_n(\cdot)$ , which converges to  $z(\cdot)$  weakly in  $W^{1,2}([0, T], \Omega_0)$  and uniformly on  $[0, T]$ .

Now for  $x(\cdot) \in H, x(0) = x$  define

$$s_x := \begin{cases} \inf\{s : x(s) = y\} & \text{if } \{s : x(s) = y\} \neq \emptyset \\ +\infty & \text{if } \{s : x(s) = y\} = \emptyset. \end{cases}$$

We claim that  $z(s) \in \bar{\Omega}$  for all  $0 \leq s \leq s_x$ . To prove this assume  $z(\tilde{s}) \notin \bar{\Omega}$ . Let  $\alpha := \text{dist}(z(\tilde{s}), \partial\Omega)$  and fix  $\bar{n}$  such that  $|z_n(s) - z(s)| < \frac{\alpha}{2}$  for  $0 \leq s \leq \tilde{s}, n > \bar{n}$ . Let  $\tilde{n}$  be such that  $\beta_{\tilde{n}} < \frac{\alpha}{2}$  and define  $\bar{\bar{n}} := \max\{\bar{n}, \tilde{n}\}$ . Then for all  $n > \bar{\bar{n}}$  we have  $z_n(\tilde{s}) \notin \Omega_n$  and thus  $x_n(\tau_x^n) = y$  with  $\tau_n := \tau_x^n[x_n(\cdot)] < \tilde{s}$ . Hence  $\tau_n$  has a subsequence converging to  $\bar{s} \leq \tilde{s}$  and it is easy to see that  $z(\bar{s}) = y$ , which implies  $\tilde{s} > s_x$  and proves the claim.

Now define

$$J_\lambda(x) := \inf \left\{ \frac{1}{4} \int_0^{s_x} e^{-\lambda s} \|\dot{x}(s) + b(x(s))\|^2 ds \mid x \in H, x(0) = x, x(s) \in \bar{\Omega} \right. \\ \left. \text{for } 0 \leq s \leq s_x \right\}.$$

We claim that

$$(3.11) \quad J_\lambda(x) \leq \liminf_n I'_{\lambda,n}(x).$$

To prove this we recall that for each  $T > 0$  the functional

$$x(\cdot) \mapsto \int_0^T e^{-\lambda s} \|\dot{x}(s) + b(x(s))\|^2 ds$$

is sequentially weakly lower semicontinuous by a classical theorem of Tonelli. Then

$$\int_0^T e^{-\lambda s} \|\dot{z}(s) + b(z(s))\|^2 ds \leq \liminf_n \int_0^T e^{-\lambda s} \|\dot{z}_n(s) + b(z_n(s))\|^2 ds \\ \leq \liminf_n \int_0^{r_n} e^{-\lambda s} \|\dot{x}_n(s) + b(x_n(s))\|^2 ds \\ \leq \liminf_n 4I'_{\lambda,n}(x) + 4\varepsilon.$$

Thus

$$J_\lambda(x) \leq \frac{1}{4} \int_0^{s_x} e^{-\lambda s} \|\dot{z}(s) + b(z(s))\|^2 ds \\ \leq \liminf_n I'_{\lambda,n}(x) + \varepsilon,$$

and the claim is proved by the arbitrariness of  $\varepsilon$ .

Next we claim that

$$(3.12) \quad I_\lambda(x) \leq J_\lambda(x).$$

We first observe that by a Lemma of Evans-Ishii (see [4, Remark 4.3]) hypothesis (B1) implies that there exist  $T_0, \lambda_0$  such that

$$\frac{1}{4} \int_0^T e^{-\lambda s} \|\dot{x}(s) + b(x(s))\|^2 ds \geq v(x) + 1 \geq J_\lambda(x) + 1,$$



for all  $T \geq T_0$ ,  $0 \leq \lambda \leq \lambda_0$ ,  $x(\cdot) \in H$  satisfying  $x(s) \in \bar{\Omega}$  for all  $0 \leq s \leq T_0$ . Then, if we assume  $\lambda \leq \lambda_0$  and fix  $0 < \varepsilon < 1$ , we can find  $x(\cdot) \in H$  such that

$$(3.13) \quad \begin{cases} x(0) = x, \quad x(s_x) = y, \quad s_x \leq T_0, \quad x(s) \in \bar{\Omega} \text{ for } 0 < s < s_x, \\ \frac{1}{4} \int_0^{s_x} e^{-\lambda s} \|\dot{x}(s) + b(x(s))\|^2 ds \leq J_\lambda(x) + \varepsilon. \end{cases}$$

Since  $\partial\Omega$  is smooth there exists a smooth function  $\phi : \mathbb{R}^N \rightarrow \mathbb{R}$  such that

$$\begin{cases} \Omega = \{x \in \mathbb{R}^N \mid \phi(x) > 0\}, \quad \partial\Omega = \{x \in \mathbb{R}^N \mid \phi(x) = 0\}, \\ |D\phi| = 1 \text{ on } \partial\Omega. \end{cases}$$

Define

$$(3.14) \quad \bar{x}(s) := \begin{cases} x + sD\phi(x) & \text{for } 0 \leq s \leq \varepsilon \\ x(s - \varepsilon) + \varepsilon D\phi(x(s - \varepsilon)) & \text{for } \varepsilon \leq s < s_x + \varepsilon \\ y + (2\varepsilon + s_x - s)D\phi(y) & \text{for } s_x + \varepsilon \leq s \leq s_x + 2\varepsilon. \end{cases}$$

Clearly

$$I_\lambda(x) \leq \frac{1}{4} \int_0^{s_x + 2\varepsilon} e^{-\lambda s} \|\bar{x}(s) + b(\bar{x}(s))\|^2 ds,$$

and using the definitions (1.1) (3.13) (3.14) and the smoothness of  $a$ ,  $b$ , and  $\phi$ , it is not hard to show that

$$\int_0^{s_x} |\dot{x}(s)|^2 ds \leq C,$$

and to deduce from it that

$$I_\lambda(x) \leq \frac{1}{4} \int_0^{s_x} e^{-\lambda s} \|\dot{x}(s) + b(x(s))\|^2 ds + 0(\varepsilon) \leq J_\lambda(x) + 0(\varepsilon).$$

This proves the claim (3.12), and then, by (3.11) and the arbitrariness of  $\beta_n \searrow 0$ , the proof of (3.10) is complete. It remains to show that

$$(3.15) \quad I_\lambda(x) \rightarrow I(x) \text{ for all } x \in \Omega.$$

Using [4, Remark 4.3] as above, we find  $\lambda_0, T_0$  such that for all  $\lambda \leq \lambda_0$  and fixed  $\varepsilon > 0$  there exists  $x_\lambda(\cdot) \in H$  such that

$$\begin{cases} x_\lambda(0) = x, \quad x_\lambda(\tau_x) = y, \quad \tau_x < T_0, \\ \frac{1}{4} \int_0^{\tau_x} e^{-\lambda s} \|\dot{x}_\lambda(s) + b(x_\lambda(s))\|^2 ds \leq I_\lambda(x) + \varepsilon. \end{cases}$$

Then

$$\begin{aligned} I_\lambda(x) + \varepsilon &\geq \frac{1}{4} e^{-\lambda T_0} \int_0^{r_x} \|\dot{x}_\lambda(s) + b(x_\lambda(s))\|^2 ds \\ &\geq e^{-\lambda T_0} I(x) \geq I(x) - \varepsilon \end{aligned}$$

for  $\lambda$  small enough. This gives (3.15) and completes the proof.  $\square$

REMARK 3.16. Several ideas in this proof are taken from Evans-Ishii [4, §2].  $\square$

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