# An extension of the Walsh-Hadamard transform to calculate and model epistasis in genetic landscapes of arbitrary shape and complexity 

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#### Abstract

Accurate models describing the relationship between genotype and phenotype are necessary in order to understand and predict how mutations to biological sequences affect the fitness and evolution of living organisms. The apparent abundance of epistasis (genetic interactions), both between and within genes, complicates this task and how to build mechanistic models that incorporate epistatic coefficients (genetic interaction terms) is an open question. The Walsh-Hadamard transform represents a rigorous computational framework for calculating and modeling epistatic interactions at the level of individual genotypic values (known as genetical, biological or physiological epistasis), and can therefore be used to address fundamental questions related to sequence-to-function encodings. However, one of its main limitations is that it can only accommodate two alleles (amino acid or nucleotide states) per sequence position. In this paper we provide an extension of the Walsh-Hadamard transform that allows the calculation and modeling of background-averaged epistasis (also known as ensemble epistasis) in genetic landscapes with an arbitrary number of states per position ( 20 for amino acids, 4 for nucleotides, etc.). We also provide a recursive formula for the inverse matrix and then derive formulae to directly extract any element of either matrix without having to rely on the computationally intensive task of constructing or inverting large matrices. Finally, we demonstrate the utility of our theory by using it to model epistasis within a combinatorially complete multiallelic genetic landscape of a tRNA, revealing that both pairwise and higher-order genetic interactions are enriched between physically interacting positions.


## Author Summary

An important question in genetics is how the effects of mutations combine to alter phenotypes. Genetic interactions (epistasis) describe non-additive effects of pairs of mutations, but can also involve higher-order (three- and four-way etc.) combinations. Quantifying higher-order interactions is experimentally very challenging requiring a large number of measurements. Techniques based on deep mutational scanning (DMS, also known as MPRAs and MAVEs) represent valuable sources of data to study epistasis. However, the best way to extract the relevant pair-wise and higher-order epistatic coefficients (genetic interaction terms) from this data for the task of phenotypic prediction remains an unresolved problem. The Walsh-Hadamard transform represents a rigorous computational framework for calculating and modeling epistatic interactions at the level of individual genotypic values. Critically, this formalism currently only allows for two alleles (amino acid or nucleotide states) per sequence position, hampering applications in more biologically realistic scenarios. Here we present an extension of the Walsh-Hadamard transform that overcomes this limitation and demonstrate the utility of our theory by using it to model epistasis within a combinatorially complete multiallelic genetic landscape of a tRNA.

## Introduction

A fundamental challenge in biology is to understand and predict how changes (or mutations) to biological sequences (DNA, RNA, proteins) affect their molecular function and ultimately the phenotype of living organisms. The phenomenon of 'epistasis' (genetic interactions) - broadly defined as the dependence of mutational effects on the genetic context in which they occur [1, 2, 3] - is widespread in biological systems, yet knowledge of the underlying mechanisms remains limited. Defining the extent of epistasis and better understanding of its origins has relevance in fields ranging from genetic prediction, molecular evolution, infectious disease and cancer drug development, to biomolecular structure determination and protein engineering [3].

Evolutionarily related sequences, natural genetic variation within populations, and more recently results of techniques such as deep mutational scanning (DMS) [4] - also known as massively parallel reporter assays (MPRAs) and multiplex assays of variant effect (MAVEs) - represent valuable sources of data to study epistasis [5, 1]. In particular, DMS enables the systematic measurement of mutational effects across entire combinatorially complete genetic landscapes [5, 6, 7, 8, 9, 10, 11, 12, 13]. Importantly, the typical use of engineered genotypes, haploid individuals and near-identical environmental (laboratory) conditions in these experiments allows population genetic considerations - such as dominance, variable allele frequencies and linkage disequilibrium - to be ignored [14]. In other words, measurements obtained from deep mutational scanning and related methods permit the modeling of epistasis in the mechanistic sense (sequence-to-function encoding) rather than in the evolutionary sense i.e. at the population genetic level. Nevertheless, precisely how to extract the most biologically relevant pairwise and higher-order epistatic coefficients (genetic interaction terms) from this type of data is an unresolved problem.

Quantitative definitions of epistasis vary among fields, but it has been argued that one particular formula-
tion termed 'background-averaged' epistasis, also known as 'ensemble' epistasis [1, 12], may provide the most useful information on the epistatic structure of biological systems [2]. The underlying rationale is that by averaging the effects of mutations across many different genetic backgrounds (contexts), the method is robust to local idiosyncrasies in the relationship between genotype and phenotype. It has been previously pointed out that the definition of background-averaged epistasis is conceptually similar to that of 'statistical epistasis' attributed to Fisher, but instead of measuring the average effect of allele substitutions against the population average genetic background i.e. averaging over all genotypes present in a given population (taking into account their individual frequencies), the approach instead averages over all possible genotypes (assuming equal genotype weights) [1, 2].

The current mathematical formalism of background-averaged epistasis is based on the Walsh-Hadamard transform [2]. Interestingly, although widely used in physics and engineering, the Walsh-Hadamard transform was first applied to non-biological fitness landscapes in the field of genetic algorithms (GA) [15], subsequently being proposed as the basis of a framework for the computation of higher-order epistasis in empirical settings [16]. However, the Walsh-Hadamard transform can only accommodate two alleles (amino acid or nucleotide states) per sequence position, with no extension to multialleleic landscapes (cardinality greater than two) yet made, as confirmed by multiple recent reports [2, 17, 18, 19]. Alternative implementations for multiallelic landscapes either rely on 'one-hot encoding' elements of larger alphabets as biallelic sequences requiring the manipulation of prohibitively large Walsh-Hadamard matrices - or constructing graph Fourier bases [18], which is mathematically complex and provides no straightforward way to interpret epistatic coefficients. The result is that the application of background-averaged epistasis has been severely limited and its properties remain largely unexplored in more biologically realistic scenarios.

In this work we provide an extension of the Walsh-Hadamard transform that allows the calculation and modeling of background-averaged epistasis in genetic landscapes with an arbitrary number of states ( 20 for amino acids, 4 for nucleotides, etc.). We also provide a recursive formula for the inverse matrix, which is required to infer epistatic coefficients using regression. Furthermore, we derive convenient formulae to directly extract any element of either matrix without having to rely on the computationally intensive task of constructing or inverting large matrices. Lastly, we apply these formulae to the analysis of a multiallelic DMS dataset, demonstrating that sparse models inferred from the background-averaged representation (embedding) of the underlying genetic landscape more regularly include epistatic terms corresponding to direct physical interactions.

## Results

## Extension of the Walsh-Hadamard transform to multiallelic landscapes

In this work, a genotype sequence is represented as a one-dimensional ordering of monomers, each of which can take on $s$ possible states (or alleles), for example $s=4$ for nucleotide sequences or $s=20$ for amino acid sequences. Without loss of generality, the $s$ states can be labelled $0,1,2, \ldots, s-1$, where 0 denotes the
wild-type allele. We are going to consider genotype sequences of length $n \in \mathbb{N}$, i.e. sequences taking values in $S^{n}$, where $S:=\{0,1, \ldots, s-1\}$.

Each genotype $\vec{i} \in S^{n}$ is associated with its phenotype $y_{i}$. Note that here we use the term 'phenotype' as shorthand for 'molecular phenotype score' from a quantitative laboratory assay (DMS) reporting on a molecular function for each genotype of interest. In quantitative genetics terminology this might be referred to as 'genotypic value' because environmental deviation is negligible due to the controlled nature of the experiments, but our subject here is the macromolecule not an individual from a population [14]. In the context of empirical genotype-phenotype landscapes, the phenotypic effect of a genotype $\vec{i}$ is typically measured with respect to the wild-type, i.e. it is given by $y_{\vec{i}}-y_{(0, \ldots, 0)}$.

It is important to emphasize that in what follows we implicitly restrict ourselves to the haploid reference base, because our primary goal is the modeling of sequence-to-function encodings for individual genotype sequences - for the ultimate purpose of understanding and engineering macromolecules - not the modeling of sequence evolution or quantification of sources of phenotypic variance in populations.

If the phenotypic effects of individual mutations were independent, they would be additive, meaning that the phenotypic effect of $\vec{i}=\left(i_{1}, \ldots, i_{n}\right)$ would be the sum of the phenotypic effects of the single mutants $\left(i_{1}, 0, \ldots, 0\right), \ldots,\left(0, \ldots, 0, i_{n}\right)$. The epistatic coefficient quantifies how much the observed phenotypic effect of $\vec{i}$ deviates from this assumption. In the case of background-averaged epistasis, we quantify the interactions between a set of mutations by averaging over all possible genotypes for the remaining positions in the sequence. For example, if $n=3$ and $s=2$, the pairwise epistatic coefficient involving the mutations at positions 2 and 3 is calculated by averaging over all states (backgrounds) for the remaining positions, in this case given by the two states of the first position ( $*$ denotes the positions at which the averaging is performed), i.e.

$$
\begin{aligned}
\varepsilon_{(*, 1,1)}= & \frac{1}{2}\left(\left[\left(y_{(1,1,1)}-y_{(1,0,0)}\right)-\left(y_{(1,1,0)}-y_{(1,0,0)}\right)-\left(y_{(1,0,1)}-y_{(1,0,0)}\right)\right]+\right. \\
& {\left.\left[\left(y_{(0,1,1)}-y_{(0,0,0)}\right)-\left(y_{(0,1,0)}-y_{(0,0,0)}\right)-\left(y_{(0,0,1)}-y_{(0,0,0)}\right)\right]\right) } \\
= & \frac{1}{2}\left(\left[y_{(1,1,1)}-y_{(1,1,0)}-y_{(1,0,1)}+y_{(1,0,0)}\right]+\left[y_{(0,1,1)}-y_{(0,1,0)}-y_{(0,0,1)}+y_{(0,0,0)}\right]\right) .
\end{aligned}
$$

More generally, in [2] it is shown that for $s=2$ and any sequence length $n$, phenotypic effects can be decomposed into background-averaged epistatic coefficients with

$$
\bar{\varepsilon}_{n}=\hat{V}_{n} \cdot \hat{H}_{n} \cdot \bar{y}_{n},
$$

where $\bar{y}_{n}$ is the vector $\left(y_{i}, \vec{i} \in[0,1]^{n}\right), \bar{\varepsilon}_{n}$ is the vector $\left(\varepsilon_{\vec{j}}, j \in[*, 1]^{n}\right)$ and $\hat{H}_{n}$ and $\hat{V}_{n}$ are $2^{n} \times 2^{n}$ matrices defined recursively as follows:

$$
\hat{H}_{n+1}=\left(\begin{array}{cc}
\hat{H}_{n} & \hat{H}_{n} \\
\hat{H}_{n} & -\hat{H}_{n}
\end{array}\right) \quad \hat{H}_{0}=1
$$

$$
\hat{V}_{n+1}=\left(\begin{array}{cc}
\frac{1}{2} \hat{V}_{n} & 0 \\
0 & -\hat{V}_{n}
\end{array}\right) \quad \hat{V}_{0}=1
$$

The matrix $\hat{H}$ is known as the Walsh-Hadamard transform [20, 21] and $\hat{V}$ is a diagonal weighting (or normalisation) matrix to correct the sign and account for averaging over different numbers of backgrounds as a function of epistatic order [2].

In this work, we provide an extension of this theory to describe background-averaged epistasis for sequences with an arbitrary number of states $s$. Before writing a general formula, we consider the simplest possible multi-state (multiallelic) landscape i.e. a sequence of length $n=1$ with $s=3$,

$$
\left(\begin{array}{l}
\varepsilon_{(*)} \\
\varepsilon_{(1)} \\
\varepsilon_{(2)}
\end{array}\right)=\left(\begin{array}{ccc}
1 / 3 & 0 & 0 \\
0 & -1 & 0 \\
0 & 0 & -1
\end{array}\right) \cdot\left(\begin{array}{ccc}
1 & 1 & 1 \\
1 & -1 & 0 \\
1 & 0 & -1
\end{array}\right) \cdot\left(\begin{array}{l}
y_{(0)} \\
y_{(1)} \\
y_{(2)}
\end{array}\right):=V_{1} \cdot H_{1} \cdot \bar{y}_{1} .
$$

Consistent with the definition of background-averaged epistasis for biallelic landscapes [2], the zeroth-order epistatic coefficient $\varepsilon_{(*)}$ is the mean phenotypic value across all genotypes and the first-order epistatic coefficients $\varepsilon_{(1)}$ and $\varepsilon_{(2)}$ are simply the respective individual phenotypic effects of genotypes $y_{(1)}$ and $y_{(2)}$ with respect to the wild-type. However, the key feature of $H_{1}$ for multiallelic landscapes - and where it departs from the canonical Walsh-Hadamard transform - is the introduction of zero elements to exclude phenotypes that are irrelevant for the calculation of a given epistatic coefficient. In other words, these phenotypes are excluded because they correspond neither to relevant intermediate genotypes nor alternative genetic backgrounds. We remind the reader that as we are interested in phenotypes at the level of individual genotypes, i.e. the haploid reference base, additive effects of different alleles at the same position (locus) are irrelevant and can be ignored.

If we now consider a sequence of length $n=2$ with $s=3$, then the $H_{2}$ and $V_{2}$ matrices become $9 \times 9\left(s^{n} \times s^{n}\right)$ and can be constructed from recurring to the case $n=1$ above, giving
$\left(\begin{array}{c}\varepsilon_{(*, *)} \\ \varepsilon_{(*, 1)} \\ \varepsilon_{(*, 2)} \\ \varepsilon_{(1, *)} \\ \varepsilon_{(1,1)} \\ \varepsilon_{(1,2)} \\ \varepsilon_{(2, *)} \\ \varepsilon_{(2,1)} \\ \varepsilon_{(2,2)}\end{array}\right)=\left(\begin{array}{ccccccccc}\frac{1}{9} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{3} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -\frac{1}{3} & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -\frac{1}{3} & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -\frac{1}{3} & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 0 & -1 & 1 & 1 & 1 \\ 1 & 1 & 1 & -1 & -1 & -1 & -1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & -1 & 0 & 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & -1 & -1 & -1 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1\end{array}\right) \cdot\left(\begin{array}{l}y_{(0,0)} \\ y_{(0,1)} \\ y_{(0,2)} \\ y_{(1,0)} \\ y_{(1,1)} \\ y_{(1,2)} \\ y_{(2,0)} \\ y_{(2,1)} \\ y_{(2,2)}\end{array}\right)$
$:=V_{2} \cdot H_{2} \cdot \bar{y}_{2}$,
where the colors highlight the block structure of the matrices. In $V_{2}$, the red square corresponds to $\frac{1}{s} V_{1}$ and the light red squares to $-V_{1}$. In $H_{2}$, the gray squares correspond to $H_{1}$ and the blue squares to $-H_{1}$. In Table 1 we show the results of background-averaged epistatic coefficients calculated by applying the above formula to an empirical multiallelic landscape with $n=2$ and $s=3$ [6].

| Nucleic acid <br> sequence | Base $s=3$ <br> representation | Phenotypic effect <br> $\bar{y}_{2}$ | Epistatic term <br> $\bar{\varepsilon}=V_{2} \cdot H_{2} \cdot \bar{y}_{2}$ |
| :---: | :---: | :---: | :---: |
| GC | $(0,0)$ | 0 | -0.17 |
| GA | $(0,1)$ | -0.14 | -0.21 |
| GT | $(0,2)$ | -0.07 | 0.02 |
| AC | $(1,0)$ | -0.13 | -0.24 |
| AA | $(1,1)$ | -0.8 | -0.53 |
| AT | $(1,2)$ | -0.01 | 0.19 |
| TC | $(2,0)$ | -0.19 | -0.05 |
| TA | $(2,1)$ | 0 | 0.33 |
| TT | $(2,2)$ | -0.18 | 0.08 |

Table 1: Interaction terms based on background-averaged epistasis $(\bar{\varepsilon})$ for an empirical multiallelic genotype-phenotype landscape consisting of all combinations of two mutations each at positions 6 and 66 in the tRNA- $\operatorname{Arg}(C C U)$ [6], i.e. $n=2$ and $s=3$. The first two columns indicate nucleic acid sequences and their base 3 representations. Here the 'GC' reference (wild-type) genotype corresponds to that of $S$. cerevisiae, denoted by $(0,0)$. The second two columns show the measured phenotypic effects and corresponding background-averaged epistatic coefficients. See Results for a regression analysis of the entire dataset.

More generally, for any value of $s$, when $n=1$,

$$
\left(\begin{array}{c}
\varepsilon_{(*)} \\
\varepsilon_{(1)} \\
\varepsilon_{(2)} \\
\vdots \\
\varepsilon_{(s-1)}
\end{array}\right)=\left(\begin{array}{ccccc}
1 / s & 0 & 0 & \ldots & 0 \\
0 & -1 & 0 & \ldots & 0 \\
0 & 0 & -1 & \ddots & \vdots \\
\vdots & \vdots & \ddots & \ddots & 0 \\
0 & 0 & \ldots & 0 & -1
\end{array}\right) \cdot\left(\begin{array}{ccccc}
1 & 1 & 1 & \ldots & 1 \\
1 & -1 & 0 & \ldots & 0 \\
1 & 0 & -1 & \ddots & \vdots \\
\vdots & \vdots & \ddots & \ddots & 0 \\
1 & 0 & \ldots & 0 & -1
\end{array}\right) \cdot\left(\begin{array}{c}
y_{(0)} \\
y_{(1)} \\
y_{(2)} \\
\vdots \\
y_{(s-1)}
\end{array}\right):=V_{1} \cdot H_{1} \cdot \bar{y}_{1},
$$

where $\varepsilon_{(*)}$ corresponds to averaging phenotypes over all possible genotypes and the remaining coefficients simply correspond to the phenotypic effects of each mutation.

For $n=2$, we have to consider different combinations of mutations in both positions. In this case, the phenotypes can be written as

$$
y_{(0,0)}, y_{(0,1)}, \ldots, y_{(0,(s-1))}, y_{(1,0)}, \ldots, y_{(1,(s-1))}, \ldots, y_{((s-1), 0)}, \ldots, y_{((s-1),(s-1))} .
$$

A natural ordering of the phenotypes is given by interpreting genotype $\vec{i}$ as the base $s$ representation of an integer (see Table $\mathbb{}$. From this, we can see how the first $s$ genotypes correspond to combining the wild-type allele at the first position with a state from the case $n=1$, i.e. to genotypes that can be written $0 \frown \vec{i}:=(0, \vec{i})$, with $\vec{i} \in S^{1}$. The next $s$ genotypes correspond to the first mutated allele at the first position combined with
all the genotypes of $n=1$, i.e. $1 \frown \vec{i}, \vec{i} \in S^{1}$, and so on. Therefore, we can write the matrices $H$ and $V$ following a block structure. In the case $n=2$ and any given $s$, we would then have

$$
H_{2}=\left(\begin{array}{ccccc}
H_{1} & H_{1} & H_{1} & \ldots & H_{1} \\
H_{1} & -H_{1} & 0 & \ldots & 0 \\
H_{1} & 0 & -H_{1} & \ddots & \vdots \\
\vdots & \vdots & \ddots & \ddots & 0 \\
H_{1} & 0 & \ldots & 0 & -H_{1}
\end{array}\right),
$$

where the number of $H_{1}$ blocks corresponds to the number of states of the first position, so $s$. Moreover, each of these blocks must be normalized to yield the corresponding background-averaged epistatic terms. Therefore $V_{2}$ can also be expressed as a function of $V_{1}$ as follows:

$$
V_{2}=\left(\begin{array}{cccc}
\frac{1}{s} V_{1} & 0 & \ldots & 0 \\
0 & -V_{1} & \ddots & \vdots \\
\vdots & \ddots & \ddots & 0 \\
0 & \ldots & 0 & -V_{1}
\end{array}\right) .
$$

Given these two matrices, we can write the background-averaged epistatic coefficients for the case of $n=2$ and $s$ different states per position as $\bar{\varepsilon}_{2}=V_{2} \cdot H_{2} \cdot \bar{y}_{2}$. More generally, the decomposition of phenotypic effects into background-averaged epistatic coefficients is given by

$$
\begin{equation*}
\bar{\varepsilon}_{n}=V_{n} \cdot H_{n} \cdot \bar{y}_{n}, \tag{1}
\end{equation*}
$$

where $H_{n}$ and $V_{n}$ can be defined recursively as

$$
H_{n+1}=\left(\begin{array}{ccccc}
H_{n} & H_{n} & H_{n} & \ldots & H_{n}  \tag{2}\\
H_{n} & -H_{n} & 0 & \ldots & 0 \\
H_{n} & 0 & -H_{n} & \ddots & \vdots \\
. & . & . & . & H_{0}=1 \quad \text { and } \quad H_{n} \text { is } s^{n} \times s^{n} \text {, }, \text {, }
\end{array}\right) \quad{ }^{\text {, }}
$$

$$
V_{n+1}=\left(\begin{array}{ccccc}
\frac{1}{s} V_{n} & 0 & 0 & \ldots & 0  \tag{3}\\
0 & -V_{n} & 0 & \ldots & 0 \\
\vdots & \vdots & \ddots & \ddots & 0 \\
\vdots & \vdots & \ddots & \ddots & 0 \\
0 & 0 & \ldots & 0 & -V_{n}
\end{array}\right) \quad V_{0}=1 \quad \text { and } \quad V_{n} \text { is } s^{n} \times s^{n} .
$$

## Recursive inverse matrix

Equation (1) defines the vector of epistatic coefficients, $\bar{\varepsilon}_{n}$, as a function of the vector of phenotypes, $\bar{y}_{n}$, which in general is the quantity that is measured experimentally. However, usually phenotypic measurements are only available for a subset of genotypes. An alternative is therefore to estimate the epistatic coefficients $\bar{\varepsilon}_{n}$ by regression,

$$
\begin{equation*}
\bar{y}_{n}=H_{n}^{-1} \cdot V_{n}^{-1} \cdot \bar{\varepsilon}_{n}, \tag{4}
\end{equation*}
$$

where the product $H_{n}^{-1} \cdot V_{n}^{-1}$ represents a matrix of sequence features. This is analogous to the more widely used one-hot encoding strategy, which implicitly relies on a 'background-relative' (or 'biochemical') view of epistasis when regressing to full order [2]. We discuss other advantages of estimating background-averaged epistatic coefficients using regression at the end of this manuscript.

Since $V_{n}$ is a diagonal matrix, its inverse is also a diagonal matrix whose elements are the inverse of the elements of $V_{n}$.

The inverse of $H_{n}$ is the matrix $A_{n}$ which can be defined recursively as

$$
A_{n+1}=\frac{1}{s}\left(\begin{array}{ccccc}
A_{n} & A_{n} & A_{n} & \cdots & A_{n}  \tag{5}\\
A_{n} & (1-s) A_{n} & A_{n} & \cdots & A_{n} \\
A_{n} & A_{n} & (1-s) A_{n} & \ddots & \vdots \\
\vdots & \vdots & \ddots & \ddots & A_{n} \\
A_{n} & A_{n} & \ldots & A_{n} & (1-s) A_{n}
\end{array}\right) \quad A_{0}=1 \quad \text { and } \quad A_{n} \text { is } s^{n} \times s^{n} \text {. }
$$

See Proposition 1 in S1 Text for a proof of this result. This is the most efficient method to determine the full matrix $A_{n}$ (see Results) and, to the best of our knowledge, the first reported recursive definition of the inverse Walsh-Hadamard transform.

## Formulae to obtain elements of the matrices

When regressing phenotypes on genotypes, a common goal is to determine whether epistatic coefficients up to the $r^{\text {th }}$ order (where $r<n$ ) are sufficient to describe the complexity of the biological system. Furthermore, as mentioned above, some fraction of phenotype values within combinatorially complete genetic landscapes are typically unavailable, representing missing data. Restricting the epistatic order and missing phenotypes respectively correspond to omitting rows and columns from $H_{n}$ (and vice versa from $A_{n}$ ). Formulae to directly obtain elements of the matrices in equations (1) and (4) would therefore be convenient.

In order to write the matrix element $\left(H_{n}\right)_{i j}$, we need to compare the genotype sequences $\vec{i}, \vec{j} \in S^{n}$,

$$
\vec{i}=\left(i_{1}, i_{2}, \ldots, i_{n}\right)
$$

$$
\vec{j}=\left(j_{1}, j_{2}, \ldots, j_{n}\right),
$$

where $\vec{i}$ denotes the $i^{\text {th }}$ element in $S^{n}, S=\{0,1, \ldots, s-1\}$, and the elements of $S^{n}$ are ordered by the base $s$ representation of integers. For instance, for any value of $n$, we will denote the wild-type state with index $i=1$ and write $\vec{i}=\overrightarrow{1}=(0, \ldots, 0)$. The element denoted with index $i=2$ would be $\vec{i}=\overrightarrow{2}=(0, \ldots, 0,1)$ and so on.

The elements of $H_{n}$ can be written as

$$
\left(H_{n}\right)_{i j}= \begin{cases}(-1)^{\left(E_{n}\right)_{i j}} & \text { if }\left(M_{n}\right)_{i j}=n \\ 0 & \text { otherwise }\end{cases}
$$

where $M$ and $E$ are $s^{n} \times s^{n}$ matrices whose elements are

$$
\begin{gather*}
\left(E_{n}\right)_{i j}=\sum_{\substack{k=1 \\
i_{k} \cdot j_{k}>0}}^{n} \delta_{i_{k} j_{k}}  \tag{6}\\
\left(M_{n}\right)_{i j}=\sum_{\substack{k=1 \\
i_{k} \cdot j_{k}>0}}^{n} \delta_{i_{k} j_{k}}+\sum_{\substack{k=1 \\
i_{k} \cdot j_{k}=0}}^{n} 1=\left(E_{n}\right)_{i j}+\sum_{\substack{k=1 \\
i_{k} \cdot j_{k}=0}}^{n} 1,
\end{gather*}
$$

where $\delta_{i j}$ denotes the Kronecker delta of $i, j$, which is equal to 1 when $i=j$ and 0 if $i \neq j$. In words, $\left(E_{n}\right)_{i j}$ counts the number of positions at which the genotype sequences $\vec{i}$ and $\vec{j}$ carry the same mutated allele and $\left(M_{n}\right)_{i j}$ is equal to $\left(E_{n}\right)_{i j}$ plus the number of positions where $\vec{i}$ or $\vec{j}$ carry the wild-type allele. See Proposition 2 in S1 Text for a proof of this result.

Furthermore, the elements of $A_{n}$ can be written as

$$
\begin{equation*}
\left(A_{n}\right)_{i j}=\frac{1}{s^{n}}(1-s)^{\left(E_{n}\right)_{i j}}, \tag{7}
\end{equation*}
$$

where $E_{n}$ is defined as in (6). See Proposition 3 in S1 Text for a proof of this result.
Finally, the matrices $V_{n}$ and $V_{n}^{-1}$ are diagonal matrices whose diagonal elements can be written as

$$
\begin{equation*}
\left(V_{n}\right)_{i i}=(-1)^{n-W_{n}(\vec{i})} \frac{1}{s^{W_{n}(\vec{i})}} \tag{8}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(V_{n}^{-1}\right)_{i i}=(-1)^{n-W_{n}(\vec{i})} s^{W_{n}(\vec{i})}, \tag{9}
\end{equation*}
$$

where

$$
W_{n}(\vec{i}):=\sum_{k=1}^{n} w_{k} \text {, with } w_{k}:=\delta_{i_{k} 0}
$$

and $\vec{i}$ again denotes the $i^{t h}$ element in $S^{n}$ when ordered by the base $s$ representation of integers. In words, $w_{k}=1$ if the genotype sequence $\vec{i}$ carries the wild-type allele at position $k$ and $W_{n}(\vec{i})$ counts the number of positions in $\vec{i}$ carrying the wild-type allele. We prove this result in Proposition 4 in S1 Text.

## Generalization to different numbers of states per position

We can generalize the formulae described in the previous subsection further by considering that each position can have different numbers of states. In this case, we can denote $s_{k}$ the number of possible states at position $k$. For $n=1$, this corresponds to exactly the same matrix as in the previous case but with $s=s_{1}$, which is the number of possible states in this position. For $n=2$, the matrix changes because now the new position can have a different number of possible states, $s_{2}$. Following the recursive definition of $H_{n}$, we can construct $H_{2}$ by repeating $H_{1} s_{2}$ times, with the structure stated in (2). Therefore, we have

$$
H_{2}=\underbrace{\left(\begin{array}{ccccc}
H_{1} & H_{1} & H_{1} & \ldots & H_{1} \\
H_{1} & -H_{1} & 0 & \ldots & 0 \\
H_{1} & 0 & -H_{1} & \ddots & \vdots \\
\vdots & \vdots & \ddots & \ddots & 0 \\
H_{1} & 0 & \ldots & 0 & -H_{1}
\end{array}\right)}_{s_{2} \text { blocks of size } s_{1} \Longrightarrow s_{2} s_{1}} .
$$

So the structure is exactly the same but the size of the matrix for each $n$ varies according to the number of possible states of the new position. The definition of $H_{n}$ is the same as in (2) but the dimensions of the matrix are $\prod_{k=1}^{n} s_{k} \times \prod_{k=1}^{n} s_{k}$. Similarly, the inverse matrix $A_{n+1}$ can be written recursively as

$$
A_{n+1}=\frac{1}{s_{n+1}}\left(\begin{array}{ccccc}
A_{n} & A_{n} & A_{n} & \cdots & A_{n}  \tag{10}\\
A_{n} & \left(1-s_{n+1}\right) A_{n} & A_{n} & \cdots & A_{n} \\
A_{n} & A_{n} & \left(1-s_{n+1}\right) A_{n} & \ddots & \vdots \\
\vdots & \vdots & \ddots & \ddots & A_{n} \\
A_{n} & A_{n} & \cdots & A_{n} & \left(1-s_{n+1}\right) A_{n}
\end{array}\right), \quad A_{0}=1 \quad \text { and } \quad A_{n} \text { is } \prod_{k=1}^{n} s_{k} \times \prod_{k=1}^{n} s_{k} .
$$

The matrix $A_{n}$ defined in (10) is the inverse of the matrix $H_{n}$ in the general case where each position can have a different number of states.

In this general case, the elements of $H_{n}$ and $A_{n}$ can be written as

$$
\left(H_{n}\right)_{i j}= \begin{cases}(-1)^{\left(E_{n}\right)_{i j}} & \text { if }\left(M_{n}\right)_{i j}=n \\ 0 & \text { otherwise }\end{cases}
$$

$$
\left(A_{n}\right)_{i j}=\frac{\prod_{k=1}^{n}\left(1-s_{k}\right)^{e_{k}}}{\prod_{k=1}^{n} s_{k}}
$$

We prove the results in this subsection in Propositions 5, 6 and 7 in S1 Text.
The above formulae permit the calculation and modeling of background-averaged epistasis in arbitrarilyshaped genetic landscapes, i.e. with any number of alleles (states) per position, as well as the direct construction of sub-matrices for regression to any desired epistatic order and/or in the presence of missing data. In the following subsections we report benchmarking results comparing the performance of alternative methods to obtain $H_{n}$ and $A_{n}$, as well as results from the application of our theory extension to an empirical multiallelic genotype-phenotype landscape.

## Benchmarking

Fig 1 a-d provides a visualization of the matrices $H_{n}$ and $A_{n}$ for different values of $n$ and $s$, clearly showing a fractal pattern in all cases due to their recursive nature.

In this paper, we provide different methods to construct $A_{n}=H_{n}^{-1}$. First, $H_{n}$ can be numerically inverted using standard matrix inversion algorithms (here we use the linalg.inv function from the SciPy library in Python), referred to as "Recursive $H_{n}$ inverse" in Fig 1, ,f. Alternatively, the recursive definition of the inverse given by equation (5) can be used, which we refer to as "Recursive $A_{n}$ ". As can be seen in Fig 1 , this method is faster than numerically inverting $H_{n}$.

Finally, we also provide a convenient formula for extracting specific individual elements of $A_{n}$ (Proposition 3), referred to as "All elements $A_{n}$ " in Fig $\mathbb{1}$,f. This method is more computationally intensive than the previously described methods, due to the formula relying on the computation of $\left(E_{n}\right)_{i j}$, which equates to counting the number of sequence positions that are identically mutated in vectors $\vec{i}$ and $\vec{j}$, each of size $n$. However, in situations where subsets of elements (or sub-matrices) - rather than full matrices - are desired,


Figure 1: Benchmarking results and heat map representations of matrices corresponding to the binary (biallelic) and multi-state (multiallelic) extension of the Walsh-Hadamard transform, and their corresponding inverses. a, $H_{6}$ WalshHadamard transform. b, $H_{4}$ multi-state extension of the Walsh-Hadamard transform for $s=3 . \mathbf{c}, A_{6}$ Inverse WalshHadamard transform. d, $A_{4}$ multi-state extension of the inverse Walsh-Hadamard transform for $s=3$. e, Computational time on a MacBook Pro (13-inch, 2017, 2.3 GHz dual-core Intel Core i5) for extracting elements of $A_{n}$ matrices of various dimensions and numbers of states (alleles) per position ( $s \in[2,10]$ ). Comparisons are shown between numerically inverting the recursively constructed $H_{n}$ (using scipy. linalg. inv), i.e. "Recursive $H_{n}$ inverse", using the recursive formula for $A_{n}$, using the formula to extract all elements of $A_{n}$ and extracting 10 random elements of $A_{n}$ (see legend). The mean across 10 replicates is depicted. Linear regression lines were fit to data from matrices with at least 100 elements. f, Similar to e but indicating memory usage. Linear regression lines were fit to data from matrices with at least 10 elements.

Proposition 3 provides a method that can be faster and more memory efficient (see " 10 elements $A_{n}$ " in Fig『e,f).

For example, in the case of a 10-mer DNA sequence, constructing the full inverse transform $A_{10}$ with $s=4$ would require $>10^{23}$ bytes ( 100 million petabytes) of memory in the best-case scenario ("Recursive $H_{n}$ inverse" in Fig 1f, log-linear extrapolation). Similarly, the full inverse transform for a 4-mer amino acid sequence ( $A_{4}$ with $s=20$ ) would impose a memory footprint $>10^{20}$ bytes. On the other hand, calculating the subset of elements from these matrices required for the prediction of a single phenotype using epistatic coefficients up to third order (three-way genetic interaction terms) is feasible in both situations using Proposition 3 ( 3,675 and 29,678 elements; 2.5 GB and 192 GB of memory; 1.8 and 99 seconds, respectively). This memory footprint can easily be diminished further using data chunking, which is a unique benefit of this method.

## Application to a multiallelic genotype-phenotype landscape

In order to demonstrate the utility of our theory, we used it to model epistasis within a combinatorially complete multiallelic genetic landscape of a tRNA. Fig2a-c summarises the model system and DMS experimental strategy employed in [6]. Briefly, a budding yeast strain was used in which the single-copy arginine-CCU tRNA (tRNA- $\operatorname{Arg}(\mathrm{CCU})$ ) gene is conditionally required for growth. A library of variants of this gene was designed to cover all $5,184\left(2^{6} \times 3^{4}\right)$ combinations of the 14 nucleotide substitutions observed in ten positions in post-whole-genome duplication yeast species (Fig $2 \mathrm{a}, \mathrm{b}$ ). The library was transformed into S. cerevisiae, expressed under restrictive conditions and the enrichment of each genotype in the culture was quantified by deep sequencing before and after selection ( Fig 2 k ). After reprocessing of the raw data, we retained high quality fitness estimates for 3,847 variants ( $74.2 \%$ ).

Although the findings in [6] were based on the application of background-averaged epistasis theory, the prior limitation of the Walsh-Hadamard transform to only two alleles per sequence position required the authors to adopt an $a d$ hoc strategy that involved performing separate analyses on combinatorially complete biallelic sub-landscapes.

However, with the extensions provided in this work, we were able model background-averaged epistasis in this multiallelic landscape using all available data simultaneously. We trained Lasso regression models of the form in equation (4) to predict variant fitness from nucleotide sequences, where the inferred model parameters correspond to background-averaged epistatic coefficients up to eighth order ( Fig 2 d ; see Methods). To determine the effect of data sparsity on the results, we sub-sampled the original data to obtain training dataset sizes ranging from $64 \%$ to $1 \%$ of all variants with high quality fitness estimates. The resulting models incorporate many higher-order epistatic coefficients (Fig2e, 'Background-averaged models') yet exhibit extreme sparsity, with the median number of non-zero coefficients of any order ranging from 19 to 60 i.e. approximately $1 \%$ of all possible coefficients of eighth order or less (Fig 2f, S1 Fig). Fig 2e indicates model performance on held out test data, with all models except those fit using the most severely subsampled data $(1 \%)$ tending to explain more than $50 \%$ of the total explainable variance.


Figure 2: Learning sparse models from the near combinatorially complete fitness landscape of a tRNA. a, Species phylogenetic tree and multiple sequence alignment of the tRNA-Arg(CCU) orthologues indicating variable positions across the seven yeast species and the synthesized library below: R (A or G); B (C, G or T); D (A, G or T); Y (C or T); M (A or $C$ ); H (A, C or T). b, Secondary structure of S. cerevisiae $\mathrm{tRNA}-\operatorname{Arg}(\mathrm{CCU})$ indicating variable positions (open and closed red circles) and three Watson-Crick base pairing (WCBP) interactions between pairs of variable positions i.e. $[1,71],[2,70]$ and $[6,66]$ (red lines and closed red circles). $\mathbf{c}$, DMS experiment to quantify the phenotypic effects of all variants in the combinatorially complete genetic landscape. See [6] for details. d, Cartoon depiction of alternative feature matrices for inferring epistatic coefficients by linear regression. $G^{-1}$ in the lower panel indicates the matrix of one-hot encoded sequence features - or embeddings - typically used when fitting models of genotype-phenotype landscapes [2]. The upper panel represents the matrix of sequence features used to infer background-averaged epistatic coefficients, as in equation (4). e, Numbers of non-zero espistatic coefficients of different orders in Lasso regression models inferred using different random fractions of the DMS data indicated in panels a-c. $\mathbf{f}$, Performance of Lasso regression models. The median number of model coefficients is indicated. Colour scale as in panel g. g, Enrichment of direct physical interactions (red lines in panel b) in non-zero epistatic coefficients (see panel h). ${ }^{*}, P<0.05$; **, $P<0.01 ; * * *, P<0.001 . h$, Strategy for testing enrichment of direct physical interactions in Lasso regression model coefficients. i, Same as panel $g$, except enrichment test results are shown separately for epistatic coefficients of different orders. Error bars indicate nonparametric bootstrap $95 \%$ confidence intervals of the mean in all panels.

For comparison, we used the same procedure to fit Lasso regression models of the form $\bar{y}=G^{-1} \cdot \bar{\varepsilon}$, where $G^{-1}$ represents a matrix of one-hot encoded sequence features i.e. the presence or absence of a given mutation - or mutation combination (interaction) - with respect to the reference (wild-type) genotype is denoted by a ' 1 ' or ' 0 ' respectively (Fig $2 d-\mathrm{f}$, 'One-hot models'). The definition of $G$ and its relationship to the biochemical (or background-relative) view of epistasis is explained in [2]. The sparsity of one-hot models is similar to that of background-averaged models regardless of training set size (Fig $2 \mathrm{e}, \mathrm{f}$ ). However, the latter tend to incorporate greater numbers of higher-order epistatic terms, particularly with larger training set sizes (Fig 2 e , orders $3,4,5+$ ), whereas the former tend to perform slightly better with very small training set sizes (Fig 2f).

To evaluate whether the inferred models report on biologically relevant features of the underlying genetic landscapes, we tested whether sparse model coefficients were more likely to comprise genetic interactions (or modulators thereof) involving known physically interacting positions in the wild-type tRNA secondary structure (Fig $2 \mathrm{p}, \mathrm{h}$ ). Regardless of data sparsity, background-averaged model coefficients tend to be significantly enriched for physical interactions ( Fig 2 z , S1 Fig). On the other hand, in the case of even moderate subsampling of training data (16\%), one-hot model coefficients show no such enrichment (Fig 2k). Importantly, repeating a similar enrichment analysis using randomly selected model coefficients of identical number and distribution over coefficient orders speaks to the validity of the Fisher's Exact Test null hypothesis with only minor inflation of the corresponding test statistic (S1 Fig). Restricting the enrichment analysis to epistatic coefficients of specific orders shows qualitatively similar results, with background-averaged model coefficients up to fourth order significantly enriched for physical interacting position pairs, even at the most severe sub-sampling fractions (Fig 2, S1 Fig).

## Discussion

We have provided an extension to the most rigorous computational framework available for describing and modeling empirical genotype-phenotype mappings. Beyond the study of background-averaged epistasis with respect to mutations in the primary sequence, this also permits the inclusion of 'epimutations' (changes in the epigenetic state of DNA), amino acid post-translational modifications or even particular environmental/experimental conditions.

In the simplest application, background-averaged epistatic coefficients (genetic interaction terms) can be directly computed from phenotypic measurements via the decomposition in equation (1). However, estimating epistatic coefficients by regression - as in equation (4) - is a more natural choice in the presence of missing data, when data for multiple related phenotypes is available [22] and/or in the presence of global epistasis [23, 24]. Our mathematical results provide three alternative methods to compute the multi-state (multiallelic) extension of the inverse Walsh-Hadamard transform $A_{n}$, one of which allows the direct extraction of specific elements or sub-matrices. In which situations might this capability be desirable?

First, constructing full $A_{n}$ matrices - particularly by numerical inversion - is impractical for large genetic landscapes. Second, the result of the product $H_{n}^{-1} \cdot V_{n}^{-1}$ represents a matrix of sequence features when
setting up the inference of epistatic (model) coefficients $\bar{\varepsilon}_{n}$ from phenotypic measurements $\bar{y}_{n}$ as a regression task [22, 23, 25, 26]. The ability to construct this feature matrix in batches (of rows) allows computational resource-efficient iteration over large datasets when using frameworks such as TensorFlow or PyTorch.

Third, there are currently no methods to comprehensively map empirical genotype-phenotype landscapes with size greater than the low millions of genotypes. Therefore, assaying landscapes of this size or larger will typically involve experimental measurement of a (random) sub-sample of genotypes, corresponding to distinct rows in $A_{n}$. In other words, it is usually unnecessary to construct full $A_{n}$ matrices when modeling real experimental data. Finally, there is evidence of extreme sparsity in the epistatic architecture of biomolecules where only a small fraction of theoretically possible genetic interactions are non-zero [7]. The feasibility of sampling very large background-averaged epistatic coefficient spaces may improve methods to infer accurate genotype-phenotype models.

Using results from the analysis of a near combinatorially complete multiallelic fitness landscape of a tRNA, we have shown that sparse regression models relying on a background-averaged definition of epistasis can efficiently capture salient features of the underlying biological system - namely direct physical interactions - even in situations of sparse sampling of phenotypes. This behaviour, which we speculate is due to a richer representation of the sequence feature space compared to one-hot models (i.e. higher level of constraint during model fitting; Fig 2 d ), is particularly desirable in the case of very large genetic landscapes where comprehensive phenotyping is infeasible. However, more work is needed to determine whether this result holds more generally. One difficulty in such comparisons between approaches is the requirement for a set of interactions or landscape features that are known to be critical for biomolecular function. Here we rely on Watson-Crick base pairing interactions whose importance for RNA secondary structure and function is well-established.

More broadly, this work opens the door to investigations of the biological properties of background-averaged epistasis in empirical genetic landscapes of arbitrary shape and complexity. Beyond applications within the field of DMS, we believe our theory extensions have the potential to influence research in evolutionary and synthetic biology including protein engineering. In future it will be important to compare the performance and properties of models relying on this definition of epistasis to those of other recently proposed models that incorporate higher-order genetic interactions for phenotypic prediction [27, 28].

## Methods

Raw sequencing (FASTQ) files obtained from the $\mathrm{tRNA}-\operatorname{Arg}(\mathrm{CCU})$ DMS experiment in [6] were re-processed with DiMSum v1.3 [29] using default parameters with minor adjustments. We obtained fitness estimates for 5,059 out of a total of 5,184 possible variants $(97.6 \%)$ in the combinatorially complete genetic landscape. We restricted the data to a high quality subset by requiring fitness estimates in all six biological replicates as well as at least 10 input read counts in all input samples. This resulted in a total of 3,847 retained variants (74.2\%) for downstream analysis.

We trained Lasso regression models to predict variant fitness estimates from nucleotide sequences using the 'scikit-learn' Python package. Training data comprised random subsets of $1,2,4,8,16,32$ and $64 \%$ of retained variants of all mutation orders. All remaining held out variants comprised the 'test' data which was unseen during model training in each case.

To train models inferring background-averaged epistatic coefficients we used feature matrices of the form $H_{n}^{-1} \cdot V_{n}^{-1}$ (see equation (4)). For comparison, one-hot encoded matrices of sequence features were used. Linear regression was performed using 10 -fold cross validation to determine the optimal value of the L1 regularization parameter $\lambda$ in the range [0.005, 0.25] ('LassoCV' and 'RepeatedKFold' functions). Final models were fit to all training data. In order to estimate model-related statistics and performance results we fit 100 models to different random subsets of the training data for each model type and training data fraction. In Fig 2 and S1 Fig we plot the mean or median of the indicated measures over all models, where $95 \%$ confidence intervals were obtained using a nonparametric bootstrap approach and 1000 bootstrap samples. For performance estimates in Fig 2 f we estimated the maximum explainable variance by taking the square of the mean Pearson correlation between replicate fitness estimates over all 15 pairwise combinations.

To test enrichment of physical interactions in Lasso model coefficients we used the strategy illustrated in Fig 2 h . For each model, all position pairs represented in non-zero epistatic coefficients of at least second order were determined. The number of position pairs corresponding to direct physical interactions was counted and an associated enrichment score (odds ratio) and P-value calculated using Fisher's Exact Test. The background set consisted of all position pairs in all possible epistatic coefficients. To test the appropriateness of the null hypothesis we also repeated enrichment analyses using random models i.e. randomly chosen sets of epistatic coefficients matching the numbers of non-zero coefficients in Lasso models and their distribution over different epistatic orders.

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## Supporting information captions

## S1 Fig. Supplementary figure related to Fig 2.

S1 Text. Supplementary Methods.


Figure S1: Supplementary figure related to Fig 2. a, P-value from Fisher's Exact Test for enrichment of direct physical interactions in non-zero epistatic coefficients (related to Fig 2g). b, Enrichment of direct physical interactions in non-zero epistatic coefficients of random models with matching numbers of epistatic coefficients of different orders (related to Fig 2g). P-value from Fisher's Exact Test for enrichment of direct physical interactions in non-zero epistatic coefficients of random models with matching numbers of epistatic coefficients of different order (related to panel b). d, Median number of epistatic terms in Lasso models (related to Fig 2f). f, P-value from Fisher's Exact Test for enrichment of direct physical interactions in non-zero epistatic shown separately for epistatic coefficients of different orders (realted to Fig 2i). Error bars indicate nonparametric bootstrap $95 \%$ confidence intervals of the mean in all panels, except in panel d where these correspond to the median.

## Supporting Information 1 - Supplementary Methods

## Here we provide the proofs of the mathematical results shown in the main text.

Proposition 1. Let us define the matrices $A_{n}$ recursively as

$$
A_{n+1}=\frac{1}{s}\left(\begin{array}{ccccc}
A_{n} & A_{n} & A_{n} & \cdots & A_{n}  \tag{5}\\
A_{n} & (1-s) A_{n} & A_{n} & \cdots & A_{n} \\
A_{n} & A_{n} & (1-s) A_{n} & \ddots & \vdots \\
\vdots & \vdots & \ddots & \ddots & A_{n} \\
A_{n} & A_{n} & \cdots & A_{n} & (1-s) A_{n}
\end{array}\right) \quad A_{0}=1 \quad \text { and } \quad A_{n} \text { is } s^{n} \times s^{n} \text {. }
$$

For $n \in \mathbb{N}, A_{n}$ is the inverse of the matrix $H_{n}$ defined in equation (2).

Proof. Let us prove this by induction. For $n=1$ we have

$$
H_{1}=\left(\begin{array}{ccccc}
1 & 1 & 1 & \ldots & 1  \tag{11}\\
1 & -1 & 0 & \ldots & 0 \\
1 & 0 & -1 & \ddots & \vdots \\
\vdots & \vdots & \ddots & \ddots & 0 \\
1 & 0 & \ldots & 0 & -1
\end{array}\right)
$$

$$
A_{1}=\frac{1}{s}\left(\begin{array}{ccccc}
1 & 1 & 1 & \ldots & 1  \tag{12}\\
1 & 1-s & 1 & \ldots & 1 \\
1 & 1 & 1-s & \ddots & \vdots \\
\vdots & \vdots & \ddots & \ddots & 1 \\
1 & 1 & \ldots & 1 & 1-s
\end{array}\right) .
$$

The rows and columns of these two matrices can be described as follows:

$$
\begin{gathered}
\left(\boldsymbol{H}_{1}\right)_{i}= \begin{cases}(1,1, \ldots, 1) & \text { if } i=1 \\
\left(1,0, \ldots, 0, h_{i}, 0, \ldots, 0\right) & \text { if } i \neq 1,\end{cases} \\
\left(A_{1}\right)_{\cdot j}=\frac{1}{S} \begin{cases}(1,1, \ldots, 1)^{T} & \text { if } j=1 \\
\left(1,1, \ldots, 1, a_{j}, 1, \ldots, 1\right)^{T} & \text { if } j \neq 1,\end{cases}
\end{gathered}
$$

where $h_{i}:=\left(H_{1}\right)_{i i}=-1 \forall i>1$ and $a_{j}:=\left(A_{1}\right)_{j j}=1-s \forall j>1$.

Therefore,

$$
\begin{gathered}
\left(H_{1} \cdot A_{1}\right)_{i j}=\left(H_{1}\right)_{i \cdot} \cdot\left(A_{1}\right)_{\cdot j}=\frac{1}{s} \begin{cases}s & \text { if } i=j \\
0 & \text { if } i \neq j\end{cases} \\
H_{1} \cdot A_{1}=\frac{1}{s}\left(\begin{array}{cccc}
s & 0 & \ldots & 0 \\
0 & s & \ddots & \vdots \\
\vdots & \ddots & \ddots & 0 \\
0 & \ldots & 0 & s
\end{array}\right)=I_{s \times s},
\end{gathered}
$$

where $I_{s \times s}$ is the identity matrix of size $s \times s$. Since both $H_{1}$ and $A_{1}$ are symmetric, it is also true that $A_{1} \cdot H_{1}=I_{s \times s}$. Therefore, $A_{1}$ is the inverse of $H_{1}$.

Assume that the hypothesis is true for a fixed $n \in \mathbb{N}$. Let us now prove that it is also true for $n+1$. Following the recursive definitions of $H_{n+1}$ and $A_{n+1}$ in equations (2) and (5), we can write the blocks of these matrices as follows:

$$
\left(H_{n+1}\right)_{[i] \cdot]}= \begin{cases}\left(H_{n}, H_{n}, \ldots, H_{n}\right) & \text { if } i=1  \tag{13}\\ \left(H_{n}, 0, \ldots, 0, \tilde{h}_{i}, 0, \ldots, 0\right) & \text { if } i \neq 1,\end{cases}
$$

where $\left(H_{n+1}\right)_{[i][j]}$ denotes the block at position $i, j$ in $H_{n+1}$ and $\tilde{h}_{i}:=\left(H_{n+1}\right)_{[i][i]}=-H_{n} \forall i>1$;

$$
\left(A_{n+1}\right)_{[\cdot \mathrm{I}[j]}=\frac{1}{s} \begin{cases}\left(A_{n}, A_{n}, \ldots, A_{n}\right)^{T} & \text { if } j=1  \tag{14}\\ \left(A_{n}, A_{n}, \ldots, A_{n}, \tilde{a}_{j}, A_{n}, \ldots, A_{n}\right)^{T} & \text { if } j \neq 1\end{cases}
$$

where $\left(A_{n+1}\right)_{[i][j]}$ denotes the block at position $i, j$ in $A_{n+1}$ and $\tilde{a}_{j}:=s\left(A_{n+1}\right)_{[j][j]}=(1-s) A_{n} \forall j>1$. We can therefore write the block at position $i, j$ of the product of these matrices as follows:

$$
\left(H_{n+1} \cdot A_{n+1}\right)_{[i][j]}=\left(H_{n+1}\right)_{[i][\cdot]} \cdot\left(A_{n+1}\right)_{[\cdot][j]}=\frac{1}{s} \begin{cases}s H_{n} \cdot A_{n} & \text { if } i=j \\ 0 & \text { if } i \neq j\end{cases}
$$

According to the induction hypothesis we know that $H_{n}$ and $A_{n}$ are inverse matrices i.e. $H_{n} \cdot A_{n}=I_{s^{n} \times s^{n}}$. Therefore, the blocks on the diagonal are identity matrices and the blocks outside the diagonal are zeros. This means that $H_{n+1} \cdot A_{n+1}=I_{s^{n+1} \times s^{n+1}}$. Similarly, due to the symmetry of the matrices we can also prove that $A_{n+1} \cdot H_{n+1}=I_{s^{n+1} \times s^{n+1}}$.

We can then conclude that $A_{n}=H_{n}^{-1}$ for every $n \in \mathbb{N}$.
Proposition 2. The elements of $H_{n}$ can be written as

$$
\left(H_{n}\right)_{i j}= \begin{cases}(-1)^{\left(E_{n}\right)_{i j}} & \text { if }\left(M_{n}\right)_{i j}=n \\ 0 & \text { otherwise, }\end{cases}
$$

where $M$ and $E$ are $s^{n} \times s^{n}$ matrices whose elements are

$$
\begin{gather*}
\left(E_{n}\right)_{i j}=\sum_{\substack{k=1 \\
i_{k} \cdot j_{k}>0}}^{n} \delta_{i_{k} j_{k}}  \tag{6}\\
\left(M_{n}\right)_{i j}=\sum_{\substack{k=1 \\
i_{k} \cdot j_{k}>0}}^{n} \delta_{i_{k} j_{k}}+\sum_{\substack{k=1 \\
i_{k} \cdot j_{k}=0}}^{n} 1=\left(E_{n}\right)_{i j}+\sum_{\substack{k=1 \\
i_{k} \cdot j_{k}=0}}^{n} 1,
\end{gather*}
$$

where $\delta_{i j}$ denotes the Kronecker delta of $i, j$.

Proof. Let us prove the formula by induction. For $n=1$ and any given $s, H_{n}$ is given by equation (11). Therefore, we can write $\left(E_{1}\right)_{i j}$ and $\left(M_{1}\right)_{i j}$ as follows:

$$
\begin{gather*}
\left(M_{1}\right)_{i j}= \begin{cases}1 & \text { if } i=1 \text { or } j=1 \\
1 & \text { if } i=j \\
0 & \text { if } i \neq j \neq 1\end{cases} \\
\left(E_{1}\right)_{i j}= \begin{cases}1 & \text { if } i=j \neq 1 \\
0 & \text { otherwise }\end{cases} \tag{15}
\end{gather*}
$$

Therefore, since $n=1,\left(M_{1}\right)_{i j}=n=1$ only when either $i=1, j=1$ or $i=j$. In the rest of the cases $\left(M_{1}\right)_{i j} \neq n=1$ and, according to the formula, the elements of the matrix will be 0 . Now, for the cases where $\left(M_{1}\right)_{i j}=n=1$, we need to check the value of $\left(E_{1}\right)_{i j}$. We can see how $\left(E_{1}\right)_{i j}=1$ only when $i=j$ and they are different from 1 . This means that all the elements of the diagonal of $H_{1}$, except the first one, will be $(-1)^{1}=-1$ and the first row and first columns will have $(-1)^{0}=1$. The rest of the elements correspond to $\left(M_{1}\right)_{i j} \neq n=1$ so they will be filled with zeros. Putting all this together, we find the expression as $H_{1}$ from equation (11).

Assume now that the expression is true for a fixed $n \in \mathbb{N}$ and let us prove it for $n+1$. In this case, the matrix of $H_{n+1}$ is defined by blocks (see equation (2)). We first define the indices $P \in\{1, \ldots, s\}$ and $Q \in\{1, \ldots, s\}$ for row and column blocks, respectively. The first matrix block of $H_{n+1}$ corresponds to $P=1$ and $Q=1$. The corresponding blocks of the matrices $M_{n+1}$ and $E_{n+1}$, which are necessary for the derivation of the block in $H_{n+1}$, are computed by comparing the genotype sequences $\vec{p}, \vec{q} \in S^{n+1}$ for which $\vec{p}=\left(0, i_{1}, \ldots, i_{n}\right):=0 \frown \vec{i}$
for $\vec{i} \in S^{n}$ and $\vec{q}=0 \frown \vec{j}, \vec{j} \in S^{n}$. More generally, the block in the $P^{t h}$ position with respect to the rows and $Q^{t h}$ position with respect to the columns can be obtained by comparing the genotype sequences $\vec{p}, \vec{q} \in S^{n+1}$ for which $\vec{p}=(P-1) \frown \vec{i}, \vec{i} \in S^{n}$ and $\vec{q}=(Q-1) \frown \vec{j}, \vec{j} \in S^{n}$. See below for a visual description of the notation.

From these observations, it can easily be deduced that for any $\vec{p}=(P-1) \frown \vec{i}, \vec{q}=(Q-1) \frown \vec{j}$ with $\vec{i}, \vec{j} \in S^{n}, P-1, Q-1 \in S$,

$$
\begin{gather*}
\left(M_{n+1}\right)_{p q}= \begin{cases}\left(M_{n}\right)_{i j}+1 & \text { if } P=1 \text { or } Q=1 \\
\left(M_{n}\right)_{i j}+1 & \text { if } P=Q \\
\left(M_{n}\right)_{i j} & \text { if } P \neq Q \neq 1\end{cases}  \tag{16}\\
\left(E_{n+1}\right)_{p q}= \begin{cases}\left(E_{n}\right)_{i j}+1 & \text { if } P=Q \neq 1 \\
\left(E_{n}\right)_{i j} & \text { otherwise },\end{cases} \tag{17}
\end{gather*}
$$

where $i=p-s^{n}(P-1), j=q-s^{n}(Q-1), P=\left\lceil p / s^{n}\right\rceil$ and $Q=\left\lceil q / s^{n}\right\rceil$, with $\lceil$.$\rceil denoting the ceiling$ function. A visual description of the notation of the block structure of the matrices is given by

$$
X_{n+1}=\text { row block } P\left\{\left(\begin{array}{ccccc}
X_{n}^{11} & \ldots & \overbrace{n}^{1 Q} \\
\vdots & \ddots & \vdots & & X_{n}^{1 s} \\
X_{n}^{P 1} & \ldots & X_{n}^{P Q} & \ldots & X_{n}^{P s} \\
\vdots & & \vdots & \ddots & \vdots \\
X_{n}^{s 1} & \ldots & X_{n}^{s Q} & \ldots & X_{n}^{s s}
\end{array}\right) \text { row } p\right.
$$

Here $X_{n+1}$ denotes any generic matrix following the structure of the matrices in equations (2), (3), (5), (16) and (17).

Now, similar to the case $n=1$, we have that $\left(M_{n+1}\right)_{p q}=n+1$ only when $\left(M_{n}\right)_{i j}=n$ and either $P=1$, $Q=1$ or $P=Q$, which corresponds to the newly added state being $p_{1}=P-1=0, q_{1}=Q-1=0$ or $p_{1}=q_{1}$. In the rest of the cases $\left(M_{n+1}\right)_{p q} \neq n+1$ and the elements of the matrix $H_{n+1}$ will be 0 . Now, for the cases where $\left(M_{n+1}\right)_{p q}=n+1$, we will have that $\left(E_{n+1}\right)_{p q}$ has either the same value of the corresponding entry in $E_{n}$ or it will be increased by 1 . This means, that when $P=Q \neq 1$, the sign of the entry in $H_{n+1}$ will be inverted. Otherwise, the sign of the element of the matrix stays the same. With this we prove the formula for $H_{n+1}$, since we have shown how we can find the same block structure as in equation (2). By induction, we can conclude that the formula holds for every $n \in \mathbb{N}$.

Proposition 3. The elements of $A_{n}$ can be written as

$$
\begin{equation*}
\left(A_{n}\right)_{i j}=\frac{1}{s^{n}}(1-s)^{\left(E_{n}\right)_{i j}} \tag{7}
\end{equation*}
$$

where $E_{n}$ is defined as in equation (6).

Proof. Let us prove the formula by induction.
For any given $s, A_{1}$ is defined in equation 12 Its diagonal elements are equal to $(1-s) / s$ for $i>1,1 / s$ for $i=1$ and its off-diagonal elements are equal to $1 / s$. It can easily be observed from equation (15) that the RHS of equation (7) is equal to $(1-s) / s$ for $i=j \neq 1$ and to $1 / s$ otherwise, so equation (7) is true for $n=1$.

Assume now that equation (7) is true for a fixed $n \in \mathbb{N}$ and let us prove it for $n+1$. We use the recursive definition of $A_{n+1}$ in equation (5) and the block representation of the genotype sequences as in the proof of (2).

Let us start with the first block in the diagonal of $A_{n+1}$, i.e. $P=1$ and $Q=1$, where the entries of the corresponding block in $E_{n+1}$ are derived from comparisons of pairs of genotype sequences of the form $\vec{p}=$ $0 \frown \vec{i}, \vec{q}=0 \frown \vec{j}$ for $\vec{i}, \vec{j} \in S^{n}$. From equation (5), this block is equal to $\frac{1}{s} A_{n}$, so writing $i=p \bmod s^{n}$ and $j=q \bmod s^{n}$, we have

$$
\left(A_{n+1}\right)_{p q}=\frac{1}{s}\left(A_{n}\right)_{i j}=\frac{1}{s^{n+1}}(1-s)^{\left(E_{n}\right)_{i j}} .
$$

From equation (17), $\left(E_{n+1}\right)_{p q}=\left(E_{n}\right)_{i j}$, which yields the desired result.
Now let us consider the elements in the other diagonal blocks of $A_{n+1}$, where the entries correspond to pairs of genotype sequences of the form $\vec{p}=(P-1) \frown \vec{i}, \vec{q}=(Q-1) \frown \vec{j}$ with $P=Q \neq 1$ and $\vec{i}, \vec{j} \in S^{n}$. From equation (5), this block is equal to $\frac{1}{s}(1-s) A_{n}$, i.e.

$$
\left(A_{n+1}\right)_{p q}=\frac{1}{s}(1-s)\left(A_{n}\right)_{i j}=\frac{1}{s^{n+1}}(1-s)^{\left(E_{n}\right)_{i j}+1} .
$$

From equation (17), $\left(E_{n+1}\right)_{p q}=\left(E_{n}\right)_{i j}+1$, which yields the desired result.
Finally, let us consider the elements in the off-diagonal blocks of $A_{n+1}$, where the entries correspond to pairs of genotype sequences of the form $\vec{p}=(P-1) \frown \vec{i}, \vec{q}=(Q-1) \frown \vec{j}$ with $P \neq Q$ and $\vec{i}, \vec{j} \in S^{n}$. From equation (5), this block is equal to $\frac{1}{s} A_{n}$, so we have

$$
\left(A_{n+1}\right)_{p q}=\frac{1}{s}\left(A_{n}\right)_{i j}=\frac{1}{s^{n+1}}(1-s)^{\left(E_{n}\right)_{i j}} .
$$

From equation (17), $\left(E_{n+1}\right)_{p q}=\left(E_{n}\right)_{i j}$, which completes the proof.
Proposition 4. The matrices $V_{n}$ and $V_{n}^{-1}$ are diagonal matrices whose diagonal elements can be written as

$$
\begin{equation*}
\left(V_{n}\right)_{i i}=(-1)^{n-W_{n}(\vec{i}} \frac{1}{s^{W_{n}(\vec{i})}} \tag{8}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(V_{n}^{-1}\right)_{i i}=(-1)^{n-W_{n}(\vec{i})} s^{W_{n}(\vec{i})}, \tag{9}
\end{equation*}
$$

where

$$
W_{n}(\vec{i}):=\sum_{k=1}^{n} w_{k} \text {, with } w_{k}:=\delta_{i_{k} 0}
$$

and $\vec{i}$ again denotes the $i^{\text {th }}$ element in $S^{n}$ when ordered by the base $s$ representation of integers.

Proof. Let us prove equation (8) by induction, equation (9) follows directly.
One can easily check from equation (3) that the formula holds for $n=1$. Let us now assume that equation (8) is true for a fixed $n \in \mathbb{N}$ and let us prove it for $n+1$. We use the recursive definition of $V_{n+1}$ in equation (3). Let us consider the element $\left(V_{n+1}\right)_{p p}$. If $\vec{p}=0 \frown \vec{i}$, this corresponds to the first block of $V_{n+1}$, i.e. $P=1$, where the elements are multiplied by $1 / s$ and $W_{n+1}(\vec{p})=W_{n}(\vec{i})+1$, so

$$
\left(V_{n+1}\right)_{p p}=\frac{1}{s}\left(V_{n}\right)_{i i}=(-1)^{n-W_{n}(\vec{i})} \frac{1}{s^{W_{n}(\vec{i})+1}}=(-1)^{n+1-W_{n+1}(\vec{p})} \frac{1}{s^{W_{n+1}(\vec{p})}} .
$$

Similarly, if $\vec{p}=(P-1) \frown \vec{i}$ and $P>1$, i.e. for the other diagonal blocks, from the recursive formula the elements are multiplied by -1 and $W_{n+1}(\vec{p})=W_{n}(\vec{i})$, so by writing again $i=p-s^{n}(P-1)$, where $P=\left\lceil p / s^{n}\right\rceil$, we have

$$
\left(V_{n+1}\right)_{p p}=-\left(V_{n}\right)_{i i}=(-1)^{1+n-W_{n}(\vec{i})} \frac{1}{s^{W_{n}(\vec{i})}}=(-1)^{n+1-W_{n+1}(\vec{p})} \frac{1}{s^{W_{n+1}(\vec{p})}},
$$

which completes the proof.
Proposition 5. The matrix $A_{n}$ defined in equation (10) is the inverse of the matrix $H_{n}$ in the general case where each position can have a different number of states.

Proof. Let us prove by induction that $H_{n} \cdot A_{n}=I$ where $I$ is the identity matrix of the corresponding size. Since $H_{n}$ and $A_{n}$ are symmetric, this would imply that $A_{n} \cdot H_{n}=I$ as well, and therefore, $A_{n}=H_{n}^{-1}$.

The case $n=1$ corresponds exactly to the case $n=1$ of the proof of Proposition 1 by setting $s=s_{1}$. Therefore, $H_{1} A_{1}=I_{s_{1} \times s_{1}}$, and $A_{1}$ is the inverse of $H_{1}$.

Now, assume the hypothesis is true for a fixed $n \in \mathbb{N}$ and let us prove that this is also true for $n+1$. We can write the rows and columns of the matrices $H_{n+1}$ and $A_{n+1}$ as equation (13) and equation (14), respectively. The only difference is that we need to replace $s$ by $s_{n+1}$ and the size of the matrices is different. Following exactly the same derivation as in Proposition 1 we can conclude that $H_{n+1} A_{n+1}=I$ and this proves by induction that $A_{n}=H_{n}^{-1}$.

Proposition 6. In this general case, the elements of $H_{n}$ and $A_{n}$ can be written as

$$
\begin{gathered}
\left(H_{n}\right)_{i j}= \begin{cases}(-1)^{\left(E_{n}\right)_{i j}} & \text { if }\left(M_{n}\right)_{i j}=n \\
0 & \text { otherwise }\end{cases} \\
\left(A_{n}\right)_{i j}=\frac{\prod_{k=1}^{n}\left(1-s_{k}\right)^{e_{k}}}{\prod_{k=1}^{n} s_{k}},
\end{gathered}
$$

536 where $E_{n}$ and $M_{n}$ are defined as in equation (6) and $e_{k}=\left\{\begin{array}{ll}1 & \text { if } i_{k}=j_{k} \neq 1 \\ 0 & \text { otherwise }\end{array}\right.$.
where

$$
W_{n}(\vec{i}):=\sum_{k=1}^{n} w_{k}, \text { with } w_{k}:=\delta_{i_{k} 0} .
$$

Proof. The proof follows the same steps as the proof of Proposition 4 The only difference in the induction step is that $s$ is replaced by $s_{n+1}$.

