

**An Improved Trusted On-Demand Multicast Routing with QoS for Wireless Networks**Jagadeesh Gopal<sup>1</sup>, Vellingiri J<sup>2</sup>, Gitanjali J<sup>3</sup>, Arivuselvan K<sup>4</sup>, Sudhakar S<sup>5</sup><sup>1234</sup>School of Information Technology and Engineering, Vellore Institute of Technology, Vellore, Tamil Nadu-632 014, India.

vellingirijayagopal@gmail.com

<sup>5</sup>Dept. of CSE, Sree Sakthi Engineering College, Coimbatore, Tamil Nadu– 641 104, India.sudhasengan@gmail.com<sup>5</sup>**ABSTRACT**

Usage of Wireless networks increasing rapidly due to an increase in the usage of IoT devices. For the better utilization of wireless networks, Ad Hoc networks prepared than Infrastructure based networks. Quality of Service is the primary concern in Ad Hoc networks. QoS in a Multicast routing strategy is needed to adapt to provide better services in Ad Hoc networks. For network group communication On-Demand Multicast Routing Protocol (ODMRP) has a low control overhead. Many schemes have worked on the development of ODMRP, but very few have provided an aware quality mechanism. We propose a new method for reducing the control overhead and also a technique for supporting QoS routing in ODMRP by making an acceptable estimation of available bandwidth.

**Key words:** Ad hoc Networks, Infrastructure Networks, Multicast Routing Protocols, Control Overhead, Bandwidth.

**1. INTRODUCTION**

The disadvantages of wireless networks are, the need to set up an entire base station, centralized routing, and their static nature, i.e., they require the establishment of a connection for communication purposes. Ad hoc networks are a category of infrastructure-less wireless networks. They don't follow any centralized (cellular) structure, thereby exhibiting distributed routing. These networks enable the nodes to move around freely, resulting in frequent changes in the topology. This dynamic nature of Ad hoc networks makes them suitable for critical applications (military, collaborative, and distributed computing, emergency operations) where we can carry out our tasks without the need to set up an entire base station (centralized). Due to frequent topology changes, they fall under mesh topology. Mesh topology is nothing but the existence of multiple paths between the source and the destination. This method, in turn, results in multi-hop links between the sender and the receiver [1]. This, however, is an excellent advantage over the wired networks, but these do lead to certain critical disadvantages. These disadvantageous natures of Adhoc networks result in security issues, loss of packets due to path breakage, and QoS metrics aren't satisfied.

The advantage is that Ad hoc networks are more comfortable to deploy and are highly cost-effective, whereas wired networks

are comparatively costlier. It is necessary to satisfy the quality parameters and make them highly efficient. We are concerned about the quality factors and are here to address a few issues. Since Ad hoc networks are truly infrastructure-less, they need control packets to broadcasted to know whether a link exists or not. Due to their change in topology, they will face link breaks quite often. This increases the control overhead in a network. The On-Demand-Multicast-Routing-Protocol reduces the control overhead as in [2]. This protocol performs multicasting. Multicasting is the sending of packets to many nodes. This protocol floods the network with Query packets. The ODMRP includes sending a join request to all the nodes by the source. The nodes will save the details and rebroadcast the join message until it reaches the receiver(s). The receiver, in turn, sends a join reply packet to the neighboring nodes. If there is an ID match, the intermediate node becomes a forwarding group member and rebroadcasts until the reply packet reaches the source. Taking the hop count as a parameter, the control overhead can be reduced even further. Due to the nature of these networks, we take into consideration the packet loss issue. This issue is minimized by calculating the available bandwidth in a network, and depending on this as well as the packet's data size, the packets will be transmitted.

Using the above two mechanisms (control overhead and bandwidth estimation), we improve efficiency by identifying the robust route, leading to the effectiveness of the packets being sent. We perform a comparison between the existing basic ODMRP and the proposed technique.

**2. RELATED WORKS**

Naveen Reddy et al. proposed a back-off mechanism is devised, which grants node access to the channel based on the rank of its highest priority packets. The source node is prioritizing the packets, and depending on its priority, packets [3] sent. The packets with minimum priority are submitted only at last. The disadvantage is that the receiver might want to receive packets in a different order. Xin Ming Zhang et al. found the EstD-Estimated Distance using two mechanisms: ETD-Estimated Topological Distance & EGD-Estimated Geographical Distance in the route discovery phase of the ODMRP protocol [4], EGD calculates the quality of a link and avoids weak links, and ETD is taken into consideration while EGD is inaccurate thereby reducing the control overhead in the

network and improving accuracy. Alsheakhali *et al.* calculated the hop count is and compared it in [5] with the values in the routing table, and the route with minimum hop count is taken as the shortest route, and then packets are transmitted efficiently in the identified route resulting in low control overhead. Yuanhui Ning *et al.* identified when a primary path is being over-utilized and is at its breakage point, the candidate paths are being maintained in a table, and the central path is given up well ahead of its breakage, and a new alternate path is made as primary path taking the quality of the alternative path considered. Only the paths which satisfy the QoS constraints [6] will be made as to the primary path, thereby creating a new TALORP protocol. Zhenhui Yuan *et al.* used two techniques the probing and the cross-layer for calculating the additional traffic [7] in a network. A combination of TCP & DCF models is taken, thereby reducing packet loss, and the available bandwidth is calculated efficiently. First, the size of the data to be sent is calculated, and then a path of required bandwidth for that particular data size of a packet is identified, and then that packet is transmitted. Barzuza *et al.* calculated the overutilization of Bandwidth in a network, and the real-time monitoring of the delay [8] is performed. Based on delay detection, bandwidth adaption is done to allocate bandwidth dynamically as and when needed. Yinzhe *et al.* proposed two approaches:

Testing the packets periodically ensuring that packets are not lost and maintaining the history of bandwidth in a table enabling the choosing of the candidate paths, which is, in turn, taken into consideration [9], when there is a breakage in the primary path resulting in a better estimation approach. Mingzhe *et al.* proposed a search algorithm used to detect the available bandwidth by statistically detecting the available fraction of the adequate capacity to mitigate estimation delay [10] and the impact of random wireless channel errors.

### 3. PROPOSED QOS MODEL

The disadvantage of existing ODMRP is that the packets are sent without knowing the capacity of the network (ABEST), which might lead to the loss of critical information. Prioritizing of packets will be of no use in case the chosen link doesn't meet the user's requirements, namely the size of data packets and traffic. The papers [10] [11] [12] take ABEST into consideration, but it also has certain disadvantages like for knowing the traffic in a network, the network is flooded with the probing packets thereby resulting increasing the cost incurred in a network. It is difficult to know whether a network is already being used by another set of nodes. So, to understand the AB in a network, we will have to forego the above control conditions.

The mechanism which we propose reduces the control overhead, and an estimation of the AB is also done, thereby increasing the efficiency of the network. The ODMRP protocol, which we use, has 2 phases: Route discovery and Route maintenance. In the Route discovery phase, the source will send JOIN\_REQ packets to all the neighboring nodes. The adjacent nodes save the *lastHop\_ID* and re-broadcasts to their neighbors. If the receiver's ID and the destination ID in the control packet sent matches, then broadcasting of the

JOIN\_REQ packet is suspended, and the receiving node creates a ROUTING\_TABLE, which includes its *ID*, *nextHopAddr*, *sourceID*, *queueLength*, *hopCounter* and forwards to the neighboring nodes as JOIN\_REQ message. The nodes which receive the JOIN\_REQ message will crosscheck if it's ID and the *nextHopAddr* parameter matches or not. If it's a match, then the node will update the packet with its *queueLength*, *nodeID*, *nextHopAddr*, and increments the *hopCounter* by 1 and then forward it after setting the FG\_FLAG to true. All the intermediate nodes which receive the JOIN\_REQ message will perform the same actions until it reaches the source node. Along with the hob count, the network congestion also takes into consideration to estimate the best available path.

After receiving the JOIN\_REQ message through multiple paths, the source finds the route with minimum *hopCount*. The Available Bandwidth Estimation (ABEST) in that particular route is done following which the transmission of data packets is performed. The algorithm for calculating the Available Bandwidth [13] is as given in Algorithm1. For calculating traffic in a link; we send back-to-back probe packets which estimate the load in a loop. The probeGap can be found out depending on the cross-traffic. Packet probing is done to perform capacity measurements. Taking the average of the return time of probes will be helpful in analyzing the Available Bandwidth of the particular link. We get accurate Available Bandwidth by sending of the probe packets with re-adjusted probeGaps. The returning speed and accuracy of the Gap search technique are modified by means of alpha, beta parameters.

$$availBandwidth = \frac{(probeSize * (trainLength - 1))}{sum(probe Returntime[])}$$

Where *probeSize* is the size of the probing packet that we send, and *train length* is the length of the sequences of the packets.

The bandwidth available is hence calculated, and this is effective because there will be no data packet loss, which would incur more cost. As we now know, the available bandwidth of the link, the transmission of data packets is done without any bottleneck issue.

The problem we may face next is the path or link breakage. We address this issue by maintaining active neighbors of the primary path. The member node sends NEIGH\_REQ to its neighbors. The neighbors will reply with their *nodeID* and *nodeTyp*, which will, in turn, be updated in the NEIGH\_ROUTE\_TABLE. The member sends its *group\_ID* to the neighbor nodes. The FG\_node gets to know if its neighbors are active or not depending on NEIGHBOR\_CHECKOUT\_TIME. If they are alive, they reply with their *group\_ID*.

In case there is a path breakage detected in the primary path, then we perform checking of whether there exist active neighbors for source, FGnode, and receivers or not. If they are, then we broadcast JOIN\_REQ packets asking the nodes to become the members of the primary path following which data transmission is carried out. The algorithm for detecting and recovering from link breakage [14] is as given in Algorithm 2.

### 3.1. Algorithm of Improved ABEST with ODMRP

Join Msg

A source sends JOIN\_REQ message to neighbors  
 Nodes create ROUTING\_INFO\_TABLE and save last hop\_ID  
 Nodes broadcast JOIN\_REQ till it reaches receivers

Case Originator:

```

    On receiving JOIN_REP message
    Find minimum hopCount;
    Find maximum hopCount;
    Perform
        ProbeGap=probe Size/(2*Capacity);
        Beta = probeGap/4;
        Alpha = 0.01;
    Perform
    Perform
        SendprobePackets;
        Wait for probeGap;
    tilltrainLength is sent;
    readprobeReturntime[];
        err=(avg(probeReturntime[])-probeGap)/
        probeGap;
    probeGap = probeGap + beta;
    till |err|<alpha;
    availBandwidth=(probeSize*(trainLength-1))
    sum(probeReturntime[]);
    Send Data
    End
    End Case
    End
    
```

Case group\_member:

```

    On receiving JOIN_REQ message
    Update the routing table and
        inform all other nodes in the network.
    
```

Case other nodes:

```

    On receiving JOIN-REP message
    Cross-check if (its ID==nextHopAddr)
    ThenUpdate QueueLength
    ++hopcounter
    Include ID, nextAddr,traffic_rateand forward
    Set FG_FLAG to TRUE
    
```

Case Receiver:

```

    On receiving JOIN_REQ message
    Perform
    Create ROUTING_TABLE
    Include its ID, nextHopAddr,node traffic,sourceID,
    queue length, Hopcounter
    Forward to neighbors as JOIN_REP
    
```

### 3.2. Algorithm of multicast routing with Path Breakage Recovery

LOCAL RECOVERY:

Each node:

```

    Send NEIGH_REQ to neighbor nodes and all
        reachable nodes of the network
    Neighbor nodes reply ID, node type and traffic
        information to the source
    Member node change ID, Type and update the traffic
        information along with its group address
    Store values in NEIGH_ROUTE_TABLE
    Send group_ID to neighbor nodes
    Send traffic information to neighbor nodes
    FG node sends HELLO PACKET to neighbor nodes
    Every NEIGHBOR_CHECKOUT_TIME seconds
    If(neighbor node available)
    Then
        replygroup_ID to FG node
    End
    
```

Case Traffic \_Congestion nodes:

```

    If (Number of packets is > 1) or
        (Number of source neighbors>1) or
        (Number of packets>1)&&(Number of sender
        packet>1) then Do packets+1
    Else
        Send traffic_REQ to other nodes.
    
```

Case FG node:

```

    If (number of FG neighbors>1) or
        (Number of source neighbors>1)
    Or (number of FG neighbors>1 &&
        Number of receiver neighbors>1)
    Then do nothing
    Else
        Send JOIN_REQ to neighbor nodes
    
```

End Case

Case group\_member:

```

    If (number of FG neighbors>1)
        Or (number of source neighbors>1)
    Then
        Do nothing
    Else
        Send JOIN_REQ to neighbors
    
```

End Case

End Switch

The overall system design of the proposed mechanism is given in Fig.1. The system design clearly portrays the overall

mechanisms such as control overhead, which includes minimum hop count calculation and then discovering the route. Bandwidth is estimated for the route, and then the data packets are sent accordingly. The recovery mechanism is also mentioned in the case of link breakage.

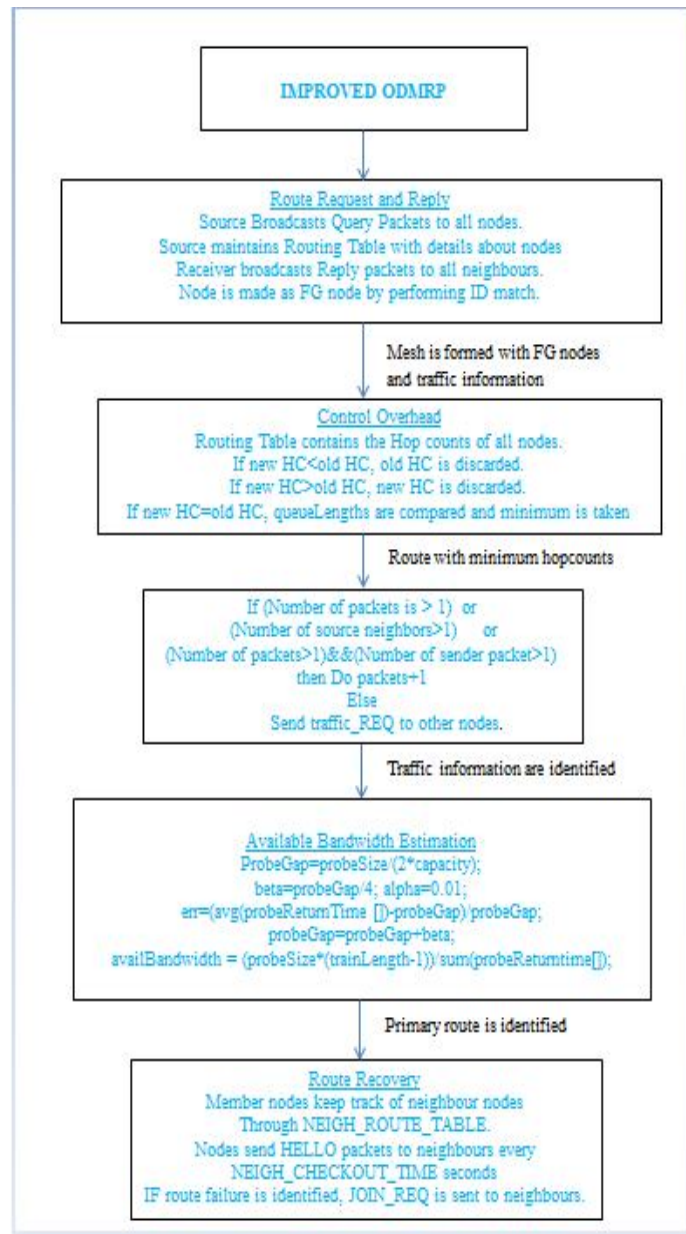


Figure 1: QoS Design for Multicast Routing

#### 4. PERFORMANCE EVALUATION

We performed the simulation in C language, keeping some parameters constant, such as network traffic and the number of nodes in the network. When a source node wants to send data to some particular nodes in the mesh, it will send the JOIN\_REQ packets through all identified paths and finds out the suitable way to the destination, and the data is sent. We performed our evaluation for various sets of nodes, and the respective values are made as graphs Fig 2 and Fig 3.

#### 4.1. Packet Delivery Ratio

It is the ratio of the number of data packets delivered to the receivers versus the number of data packets that are to be received. It is used to find out the rate of loss of data packets. The higher the ratio is, the better is the delivery ratio.

In Fig 2, we have performed a comparison between the delivery ratio of the packets and the network size. The packet delivery ratio lets us know how reliable the network is for the delivery of the packet. From the graph, we can analyze that the delivery ratio of the enhanced system is comparatively higher than the basic ODMRP system. And we also find that the delivery ratio increases with an increase in the number of nodes in the group.

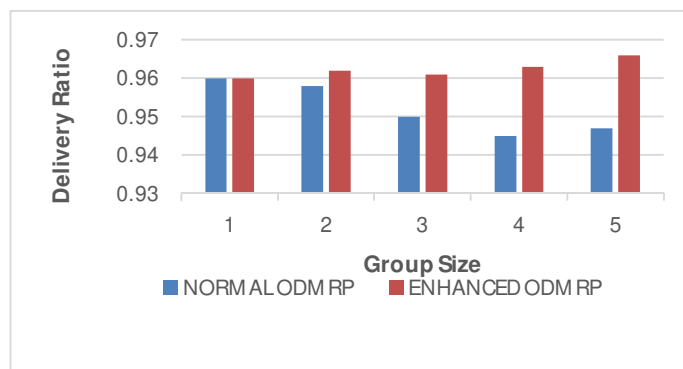


Figure 2: Packet Delivery Ratio vs. Network Size

#### 4.2. Control Overhead

It is the ratio of the number of control bytes transmitted per delivered data byte. This ratio is evaluated to find out how many control packets are required to provide the data packets.

Fig 3 shows the overhead control metric of the enhanced system and the basic ODMRP. This ratio is evaluated to find out how many control packets are required to deliver the data packets. We can find that the overhead is reduced to minimal as compared with the underlying system. It is to be noted that the overhead is comparatively reduced as the group size increases.

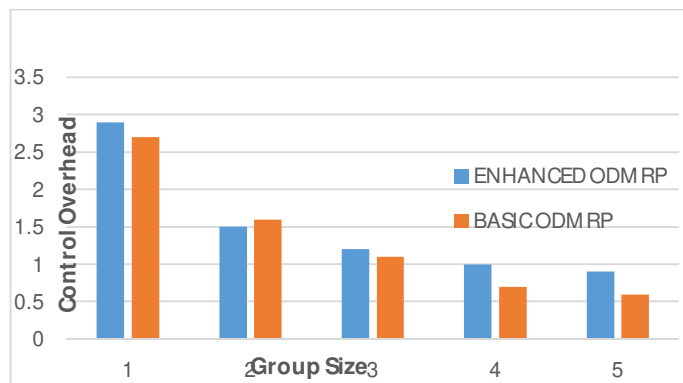


Figure 3: Control Overhead vs. Network Size

## 5. CONCLUSION

The proposed work supports QoS routing in ODMRP by appraising the available bandwidth of the paths and the congestion in the network nodes. The packet loss is reduced significantly by estimating the hop count, bandwidth, and congestion. In the proposed work, we have chosen the best route with minimum hop count and less congestion path. Reliable transmission of data packets supported by efficient recovery mechanism. According to user requirements, the Primary network path is identified among a group of feasible paths.

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