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# AN INVESTIGATION OF STRIP LINES AND FIN LINES WITH PERIODIC STUBS

TOSHIHIDE KITAZAWA RAJ MITTRA

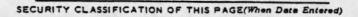
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# AN INVESTIGATION OF STRIP LINES AND FIN LINES WITH PERIODIC STUBS

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\* Dr. Kitazawa is on leave from Kitami Institute of Technology, Kitami, Japan.

# ABSTRACT

In this paper a technique based on the network analytical formalism of electromagnetic fields is used to analyze the strip and fin lines with periodic stubs. Numerical results for the dispersion characteristics of the periodically loaded lines are presented. The effect of the loading stubs on the passband and stopband characteristics is investigated.

#### I. INTRODUCTION

Propagation characteristics of planar transmission lines for microwave and millimeter-wave integrated circuits have been investigated in the past by many authors. Two of the frequently used transmission media in the microwave frequency range are the strip and slot lines while the fin-line is known to find applications in the millimeter-wave range. Hybrid-mode analyses of uniform lines of the above types [1] have been reported in the literature [2]. However, the periodic-loaded version of these lines finds useful applications in many devices, such as filters [3].

In this paper an approach for analyzing periodically loaded strip lines and fin lines is presented. The network-analytical method is employed for the formulation of an integral equation for the unknown electromagnetic fields [4] and Galerkin's procedure is used to derive a numerical solution of this equation. Numerical results present the passband and stopband properties.

#### II. THE NETWORK FORMULATION OF THE PROBLEM

In this section we illustrate the network-analytical method of formulation by analyzing the problem of fin lines with periodic stubs (see Fig. 1a), although the method itself is applicable to the strip-line configuration (Fig. 1b). The numerical results for both cases will be presented in the next section.

As a first step, we express the transverse (to z) fields in each region by using the Fourier transformation in the x-direction and Floquet harmonic representation in the y-direction as follows:

$$\begin{cases} {}^{(i)}_{t}(x,y,z) \\ {}^{(i)}_{t}(x,y,z) \end{cases} = \begin{cases} 2 & \infty & \infty \\ \sum & \sum \\ \ell = 1 \\ m = 0 \\ m = 0 \\ m = -\infty \end{cases} \begin{cases} V_{\ell mn}^{(i)}(z) & e_{\ell mn}^{(x,y)} \\ I_{\ell mn}^{(i)}(z) & h_{\ell mn}^{(x,y)} \\ i = 1, 2, 3 \quad (regions) \end{cases}$$
(1)

where

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$$e_{1mn}(x,y) = \sqrt{\frac{\eta_m}{2Ap}} \frac{1}{K} \{x_0 \gamma_m \cos \gamma_m(x+A) - y_0 j\beta_n \sin \gamma_m(x+A)\} e^{-j\beta_n y}$$

$$e_{2mn}(x,y) = \sqrt{\frac{\eta_m}{2Ap}} \frac{1}{K} \{x_0 j \beta_n \cos \gamma_m (x+A) - y_0 \gamma_m \sin \gamma_m (x+A)\} e^{-j \beta_n y}$$

 $h_{lmn}(x,y) = z_0 \times e_{lmn}(x,y)$  (l = 1, 2)

$$\kappa^2 = \gamma_m^2 + \beta_n^2$$
,  $\gamma_m = \frac{m\pi}{2A}$ ,  $\beta_n = \beta_0 + \frac{2n\pi}{p}$ 

 $n_{\rm m} = 0$ Neumann's number . 2 (m \neq 0)

(2)

Here  $\beta_0$  is the propagation constant of the dominant harmonic in the Floquet representation, and the vector mode functions  $e_{lmn}$ ,  $h_{lmn}$  satisfy the boundary conditions at  $x = \pm A$  as well as the following orthonormal properties:

$$A P/2 = \int_{-A} \int_{-P/2} e_{\ell mn}(x,y) \cdot e_{\ell'm'n}^{*}(x,y) dxdy = \delta_{\ell\ell'} \delta_{mn'} \delta_{nn'}$$
(3)

where  $\delta_{ll}$  is Kronecker's delta and the symbol \* signifies complex conjugate. Substituting (1) into Maxwell's field equations and applying the orthonormal properties (3), we obtain the differential equations for  $V_{lmn}^{(i)}$  and  $I_{lmn}^{(i)}$ :

$$\begin{cases} -\frac{dV_{lmn}^{(i)}}{dz} = j\kappa_{mn}^{(i)} z_{lmn}^{(i)} I_{lmn}^{(i)} \\ -\frac{dI_{lmn}^{(i)}}{dz} = j\kappa_{mn}^{(i)} y_{lmn}^{(i)} V_{lmn}^{(i)} \end{cases}$$

where

$$z_{1mn}^{(i)} = \frac{\kappa_{mn}^{(i)}}{\omega \varepsilon_0 \varepsilon_r^{(i)}} , \qquad z_{2mn}^{(i)} = \frac{\omega \mu_0}{\kappa_{mn}^{(i)}}$$

$$Y_{lmn}^{(i)} = \frac{1}{Z_{lmn}^{(i)}} , \quad \kappa_{mn}^{(i)} = \sqrt{k^2 \varepsilon_r^{(i)} - \kappa^2}$$

$$k = \omega \sqrt{\varepsilon_0 \mu_0}$$
,  $\varepsilon_r^{(i)} = \begin{cases} \varepsilon_r & (region (2)) \\ 1 & (otherwise) \end{cases}$ 

The boundary conditions to be satisfied are expressed as follows:

(4)

(5)

$$V_{lmn}^{(1)}(d_1) = 0$$
 (6)

$$V_{lmn}^{(1)}(+0) = V_{lmn}^{(2)}(-0) = v_{lmn}$$
 (7)

$$v_{\ell mn}^{(2)}(-d_2 + 0) = v_{\ell mn}^{(3)}(-d_2 - 0)$$
 (8a)

$$I_{lmn}^{(2)}(-d_2 + 0) = I_{lmn}^{(3)}(-d_2 - 0)$$
(8b)

$$v_{lmn}^{(3)}(-d_2 - d_3) = 0$$
<sup>(9)</sup>

and

$$H_{t}^{(i)}(x,y,+0) = H_{t}^{(2)}(x,y,-0)$$
(10)  
(in the aperture of z = 0)

where

1

1

$$\mathbf{v}_{lmn} = \int_{-A}^{A} \int_{-P/2}^{P/2} e_{lmn(x',y') \cdot \epsilon(x',y') \, dx' dy'}^{*}$$
(11)

and  $\varepsilon(x,y)$  is the transverse electric field in the aperture at z = 0.

Solution of the differential equations (4) and imposition of the boundary conditions (6) - (9) yield the unknowns  $V_{lmn}^{(i)}$  and  $I_{lmn}^{(i)}$  in each region. The electromagnetic fields, in turn, can be obtained by substituting  $V_{lmn}^{(i)}$  and  $I_{lmn}^{(i)}$  into Equation (1). Finally, applying the remaining boundary conditions (10), we may obtain the integral equation for the aperture field  $\varepsilon(x,y)$ , and implicitly for the unknown propagation constant  $\beta_0$ :

$$\sum_{m n}^{A} \frac{P/2}{\int} \int_{1mn}^{P/2} \{Y_{1mn} h_{1mn}(x,y) e_{1mn}^{*}(x',y') + Y_{2mn} h_{2mn}(x,y) e_{2mn}^{*}(x',y')\}$$

•  $\varepsilon(x',y') dx'dy' = 0$ 

(12)

where (x,y) lies in the aperture at z = 0 and

ļ

$$Y_{1mn} = \omega \varepsilon_0 \left\{ \frac{1}{\kappa_{mn}^{(1)}} \cot \left(\kappa_{mn}^{(1)} d_1\right) + \frac{\varepsilon_r}{\kappa_{mn}^{(2)}} \frac{\kappa_{mn}^{(2)} - \varepsilon_r}{\kappa_{mn}^{(2)}} \frac{\kappa_{mn}^{(3)}}{\kappa_{mn}^{(2)}} \frac{\tan \left(\kappa_{mn}^{(2)} d_2\right) \tan \left(\kappa_{mn}^{(2)} d_2\right)}{\kappa_{mn}^{(2)}} \frac{\tan \left(\kappa_{mn}^{(2)} d_2\right) + \varepsilon_r}{\kappa_{mn}^{(3)}} \frac{\kappa_{mn}^{(3)}}{\tan \left(\kappa_{mn}^{(3)} d_3\right)} \right\}$$

$$Y_{2mn} = \frac{1}{\omega \mu_0} \left\{ \kappa_{mn}^{(1)} \cot \left(\kappa_{mn}^{(1)} d_1\right) + \kappa_{mn}^{(2)} \frac{\frac{1}{\kappa_{mn}^{(2)}} - \frac{1}{\kappa_{mn}^{(3)}} \tan \left(\kappa_{mn}^{(2)} d_2\right) \tan \left(\kappa_{mn}^{(3)} d_3\right)}{\kappa_{mn}^{(2)}} + \kappa_{mn}^{(2)} \frac{\frac{1}{\kappa_{mn}^{(2)}} - \frac{1}{\kappa_{mn}^{(3)}} \tan \left(\kappa_{mn}^{(2)} d_2\right) \tan \left(\kappa_{mn}^{(3)} d_3\right)}{\frac{1}{\kappa_{mn}^{(2)}} \tan \left(\kappa_{mn}^{(2)} d_2\right) + \frac{1}{\kappa_{mn}^{(3)}} \tan \left(\kappa_{mn}^{(3)} d_3\right)} \right\}$$
(13)

'The formulation is rigorous up to this stage. The numerical computation for the above equation is explained in the next section.

### III. NUMERICAL COMPUTATION AND RESULTS

Equation (12) can be expressed in an operator form as

$$\mathbf{F}(\mathbf{x},\mathbf{y}|\mathbf{x}',\mathbf{y}') \cdot \boldsymbol{\varepsilon}(\mathbf{x}',\mathbf{y}') = 0 \tag{14}$$

where the dyadic operator  $F \cdot$  is given by

$$F(x,y|x',y') = \sum_{m n} \sum_{n}^{A} \int_{-P/2}^{P/2} \{Y_{1mn} h_{1mn}(x,y) e_{1mn}^{*}(x',y')\}$$

+ 
$$Y_{2mn} h_{2mn}(x,y) e_{2mn}^{*}(x',y') dx'dy'$$
 (15)

The determinantal equation for the dispersion relation can be obtained by applying Galerkin's procedure to Eq. (14). In this procedure, the unknown aperture field  $\varepsilon(x,y)$  is expanded in terms of the appropriate basis functions  $f_{\mu}(x,y)$  as follows:

$$\varepsilon(\mathbf{x},\mathbf{y}) = \sum_{k=1}^{N} a_k f_k(\mathbf{x},\mathbf{y})$$
(16)

where  $a_k$  are the unknown coefficients. Substituting (16) into (14), using  $f_m^*(x,y)$  as test functions and taking inner products, we obtain a set of simultaneous equations for the unknown coefficients  $a_k$ :

$$[M] [a] = 0$$
 (17a)

That is,

$$\begin{bmatrix} M_{11} & M_{12} & \cdots & M_{1N} \\ M_{21} & & & \\ & & \ddots & \\ & & & \ddots & \\ & & & \ddots & \\ M_{N1} & & M_{NN} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ \vdots \\ a_N \end{bmatrix} = 0$$

(17b)

where

1

1

$$M_{mk} = \int_{-A}^{A} \int_{-P/2}^{P/2} Z_0 \times f_m^*(x,y) \cdot \{F(x,y|x',y') \cdot f_k(x',y')\} dxdy$$
(18)

The determinantal equation for the propagation constant  $\beta_0$  can be obtained by setting the determinant of the coefficient matrix of Eq. (17) equal to zero, i.e.,

$$det[M(\beta_0)] = 0 \quad . \tag{19}$$

It remains only to select the basis functions  $f_k(x,y)$ . Before defining the basis functions, we introduce three auxiliary functions:

$$S_1(x,y) = \begin{cases} 1 & (|x| \leq W \text{ and } |y| \leq \frac{P}{2}) \\ 0 & (\text{otherwise}) \end{cases}$$

$$S_{2}(x,y) = \begin{cases} 1 & (|x| \leq W \text{ and } W_{1} \leq |y| \leq \frac{P}{2}) \\ 0 & (\text{otherwise}) \end{cases}$$

$$S_{3}(x,y) = \begin{cases} 1 & (W \leq |x| \leq W + \ell \text{ and } |y| \leq W_{1}) \\ 0 & (\text{otherwise}) \end{cases}$$
(20)

The regions represented by these functions are shown in Fig. 2. The basis functions to be used are defined by employing these auxiliary functions:

$$f_1(x,y) = x_0 X(x) e^{-j\beta_0 y} S_1(x,y)$$
 (21a)

$$f_2(x,y) = x_0 X(x) e^{-j\beta_{-1}y} S_1(x,y)$$
 (21b)

$$f_{3}(x,y) = x_{0} \operatorname{sgn}(y) X(x) e^{-j\beta_{0}y} S_{2}(x,y) + y_{0} \operatorname{sgn}(x) \cos \left\{ \frac{\pi}{2(\ell + W)} x \right\} Y(y) S_{3}(x,y)$$
(21c)

$$f_{4}(x,y) = x_{0} \operatorname{sgn}(y) X(x) e^{-j\beta_{-1}y} S_{2}(x,y) + y_{0} \operatorname{sgn}(x) \cos \left\{ \frac{\pi}{2(\ell + W)} x \right\} Y(y) S_{3}(x,y)$$
(21d)

where

$$\beta_{-1} = \beta_0 - \frac{2\pi}{p}$$

and X(x) and Y(y) represent the x- and y-variations in the main- and stub-fin lines, respectively. Three different functions are used for X(x) and Y(y), viz.,

i) 
$$X(x) = \frac{C}{W}$$
,  $Y(y) = \frac{C}{W_1}$  C: constant  
ii)  $X(x) = \frac{|x|}{W}$ ,  $Y(y) = \frac{|y|}{W_1}$   
iii)  $X(x) = \frac{1}{W} \left\{ 1 + \left| \frac{x}{W} \right|^3 \right\}$ ,  $Y(y) = \frac{1}{W_1} \left\{ 1 + \left| \frac{y}{W_1} \right|^3 \right\}$ . (22)

We mention that the functions in (21c) and (21d) are quite similar in character to the junction basis functions that have been employed in scattering problems [5].

Figure 3 shows the k -  $\beta_0$  diagram for a fin line with periodic stubs. Computations have been performed for three different sets of basis functions given in (22), but the deviations were found to be rather small because Galerkin's procedure was used in the numerical computations. The curve for the periodically loaded fin line (solid line) is lower than for the uniform fin line without stubs (broken line) because of the inductive reactance of the series stubs. The passband and stopband regions, which are common in the dispersion diagrams in periodic structures [6] and are applicable to filters, are clearly evident in Fig. 3. The first passband occurs in the frequency range when kp satisfies 1.038 < kp < 2.800 and the first stopband 2.800 < kp < 2.931. It should be noted that the higher-order stopbands will appear in the higher-frequency range; however, since the higher-order (even) mode of the uniform fin line (without stubs) can propagate in the range kp > 4.315, these higher stopbands have little significance.

Figure 4 shows the relative amplitude of the coefficients of basis functions  $f_1$  and  $f_2$ , which represent the n = 0 and n = -1 harmonics, respectively, at each point indicated in Fig. 3. These results show that the first stopband is caused by the coupling between the n = 0 and n = -1 harmonics.

Figure 5 shows the effect of the loading stubs on the normalized stopband width  $\Delta k/k_c$ , where  $\Delta k$  is the stopband width and  $k_c$  is the center frequency. The stub length  $\ell$  is smaller than the quarter wavelength of the stub fin line, so the series stubs have an inductive reactance; therefore, the longer the stub, the wider the stopband. The characteristic impedance of the fin line becomes larger as the gap becomes wider [2]; therefore, the stopband becomes wider with wider stubs, although the dependence on the stub width is relatively small.

Figure 6 shows the k -  $\beta_0$  diagram of the strip line with periodic stubs. Again, the passband and stopband properties are observed in this case, with the first passband occurring when 0 < kp < 1.228 and the first stopband when 1.228 < kp <1.286. The first higher-order mode of the main strip line appears when kp = 2.289; therefore, the higher-order stopbands have no meaning in the same way as the case of fin line.

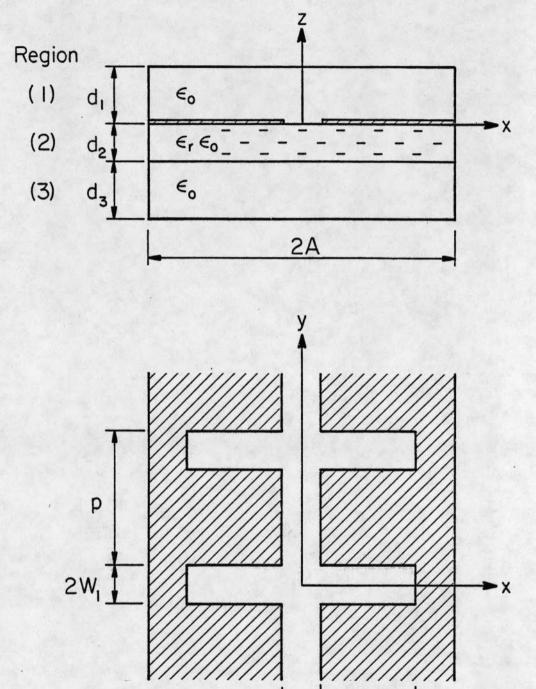
Figure 7 shows the effect of the loading stubs. The characteristic impedance of the strip line becomes smaller as the strip becomes wider [4], but the stubs are shunt-connected in this case. Therefore, the stopband, again, becomes wider with wider stubs.

## IV. CONCLUSIONS

A method of analysis for the strip line and the fin line with periodic stubs has been presented, and the  $k - \beta_0$  diagrams for these structures have been computed. It is found that the passband and stopband properties are generated from the coupling between the n = 0 and n = -1 harmonics. The effects of the loading stubs have been determined numerically.

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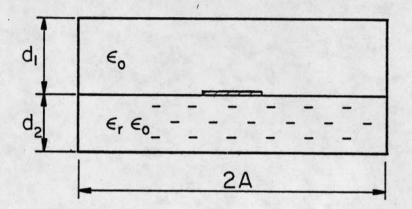
(C) Planar transmission lines with stubs - periodicloaded fin line.

Figure la:

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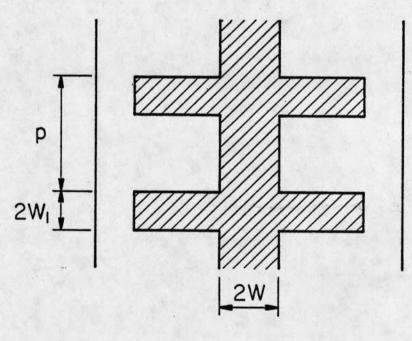


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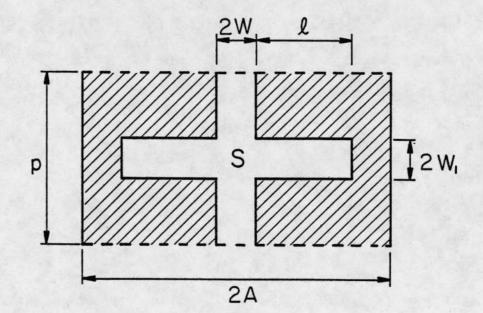
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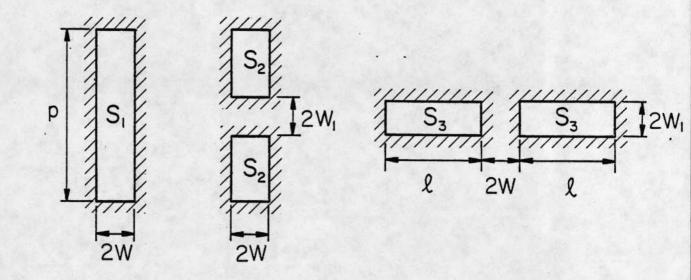
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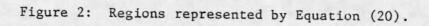


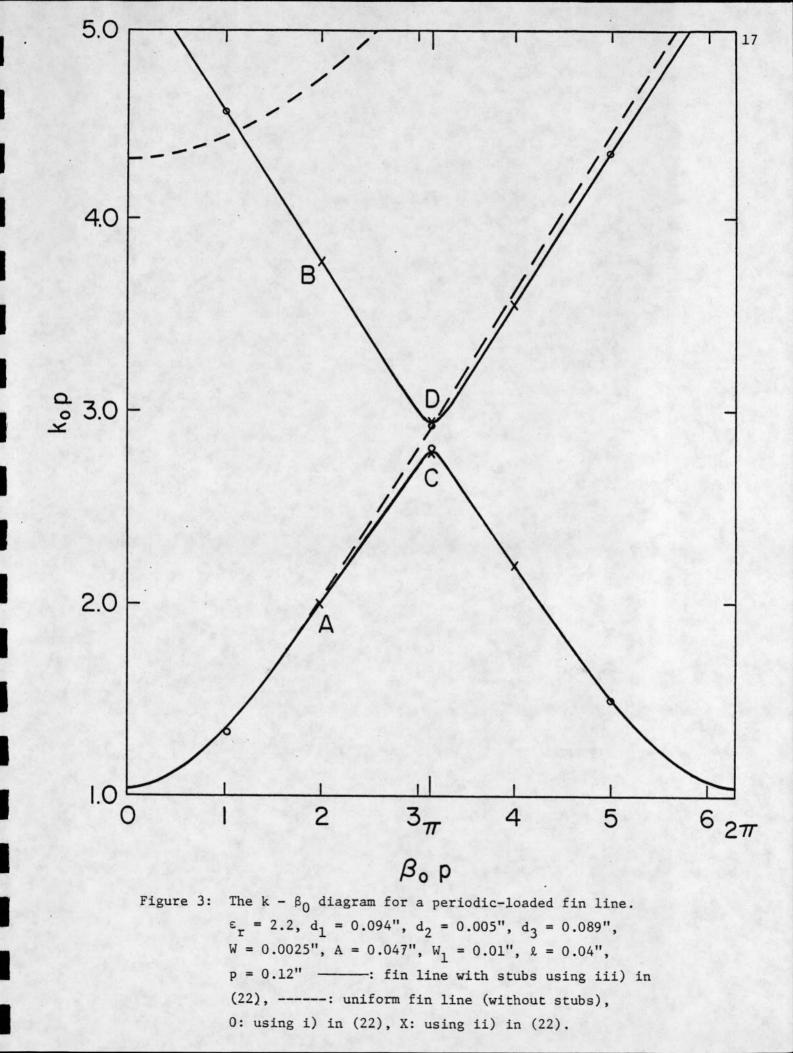
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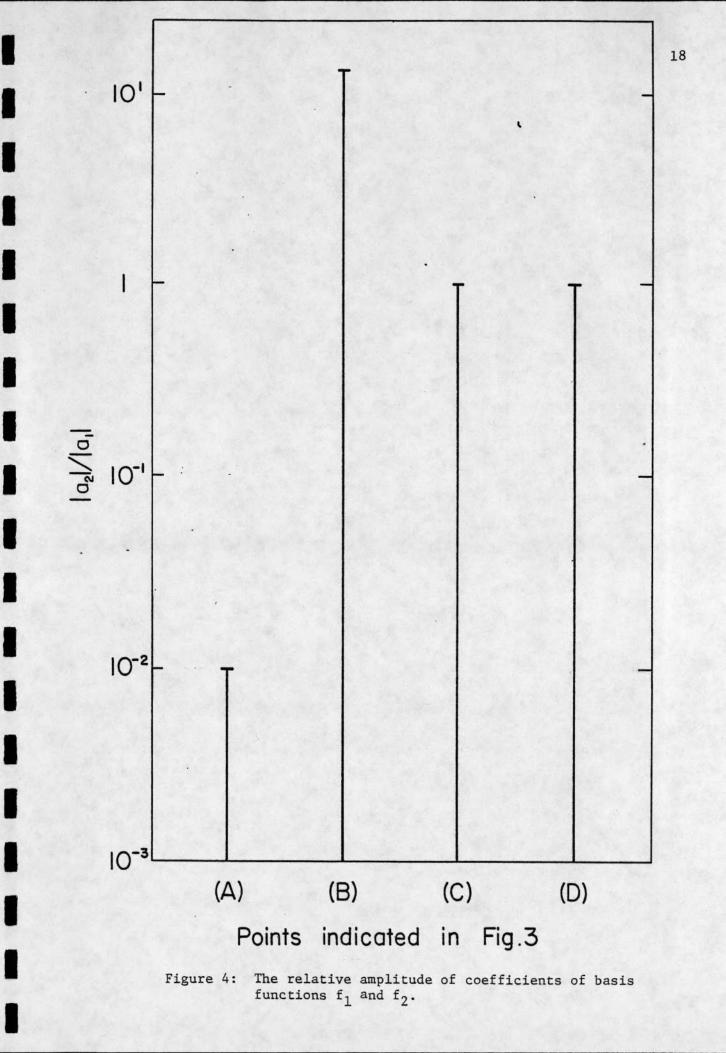
Figure 1b: Planar transmission lines with stubs - periodicloaded strip line.

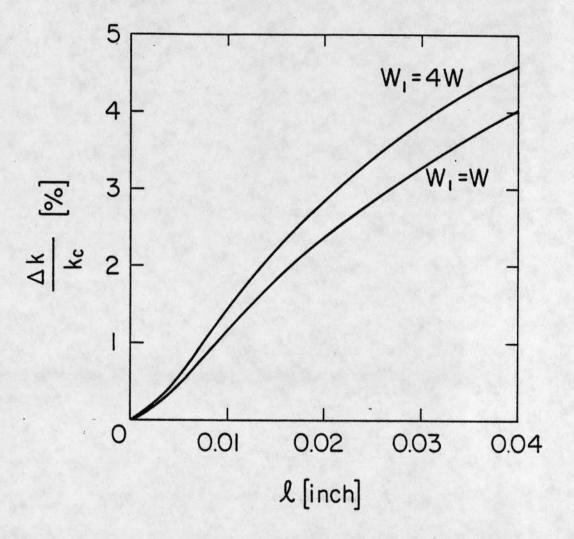


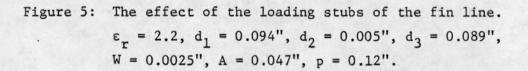












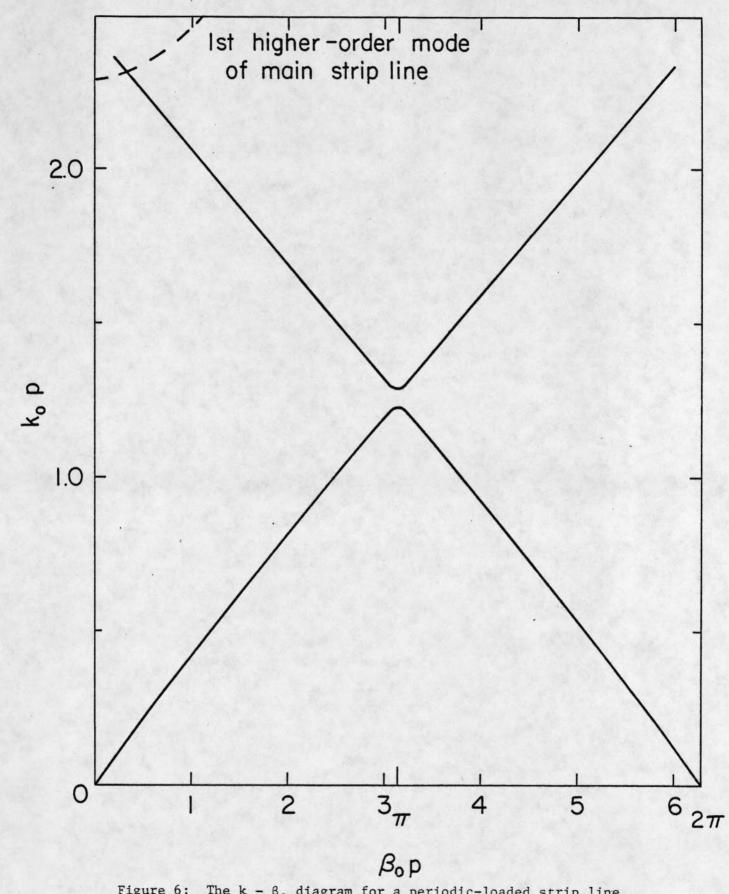


Figure 6: The k -  $\beta_0$  diagram for a periodic-loaded strip line.  $\epsilon_r = 8.875$ ,  $d_1 = 11.43 (mm)$ ,  $d_2 = 1.27 (mm)$ , W = 0.3175(mm), A = 6.35(mm), W<sub>1</sub> = 0.3175(mm), 1 = 4(mm), p = 10(mm).

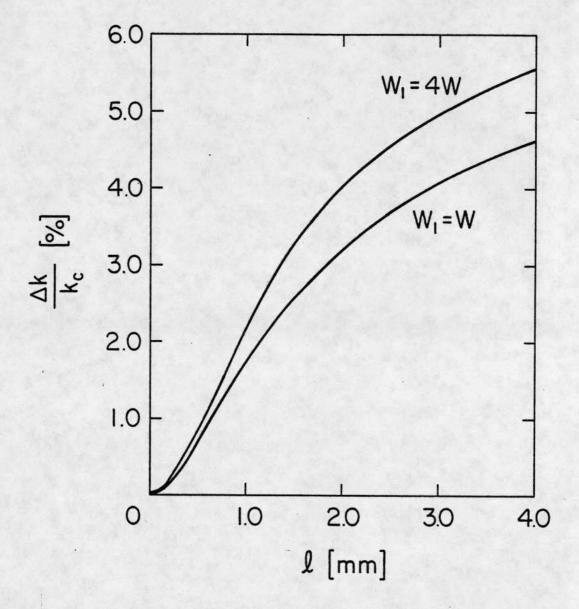


Figure 7: The effect of the loading stubs of the strip line.  $\varepsilon_r = 8.875$ ,  $d_1 = 11.43(mm)$ ,  $d_2 = 1.27(mm)$ , W = 0.3175(mm), A = 6.35(mm), p = 10(mm).