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# An isoperimetric inequality in the plane with a log-convex density

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**Abstract** Given a positive lower semi-continuous density  $f$  on  $\mathbb{R}^2$  the weighted volume  $V_f := \int f \mathcal{L}^2$  is defined on the  $\mathcal{L}^2$ -measurable sets in  $\mathbb{R}^2$ . The  $f$ -weighted perimeter of a set of finite perimeter  $E$  in  $\mathbb{R}^2$  is written  $P_f(E)$ . We study minimisers for the weighted isoperimetric problem

$$I_f(v) := \inf \left\{ P_f(E) : E \text{ is a set of finite perimeter in } \mathbb{R}^2 \text{ and } V_f(E) = v \right\}$$

for  $v > 0$ . Suppose  $f$  takes the form  $f : \mathbb{R}^2 \rightarrow (0, +\infty); x \mapsto e^{h(|x|)}$  where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Let  $v > 0$  and  $B$  a centred ball in  $\mathbb{R}^2$  with  $V_f(B) = v$ . We show that  $B$  is a minimiser for the above variational problem and obtain a uniqueness result.

**Keywords** Isoperimetric problem · Log-convex density · Generalised mean curvature

**Mathematics Subject Classification** 49Q20

## 1 Introduction

Let  $f$  be a positive lower semi-continuous density on  $\mathbb{R}^2$ . The weighted volume  $V_f := \int f \mathcal{L}^2$  is defined on the  $\mathcal{L}^2$ -measurable sets in  $\mathbb{R}^2$ . Let  $E$  be a set of finite perimeter in  $\mathbb{R}^2$ . The weighted perimeter of  $E$  is defined by

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$$P_f(E) := \int_{\mathbb{R}^2} f \, d|D\chi_E| \in [0, +\infty]. \quad (1.1)$$

We study minimisers for the weighted isoperimetric problem

$$I_f(v) := \inf \left\{ P_f(E) : E \text{ is a set of finite perimeter in } \mathbb{R}^2 \text{ and } V_f(E) = v \right\} \quad (1.2)$$

for  $v > 0$ . To be more specific we suppose that  $f$  takes the form

$$f : \mathbb{R}^2 \rightarrow (0, +\infty); x \mapsto e^{h(|x|)} \quad (1.3)$$

where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Our first main result is the following. It contains the classical isoperimetric inequality (cf. [9, 12]) as a special case; namely, when  $h$  is constant on  $[0, +\infty)$ .

**Theorem 1.1** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Let  $v > 0$  and  $B$  a centred ball in  $\mathbb{R}^2$  with  $V_f(B) = v$ . Then  $B$  is a minimiser for (1.2).*

For  $x \geq 0$  and  $v \geq 0$  define the directional derivative of  $h$  in direction  $v$  by

$$h'_+(x, v) := \lim_{t \downarrow 0} \frac{h(x + tv) - h(x)}{t} \in \mathbb{R}$$

and define  $h'_-(x, v)$  similarly for  $x > 0$  and  $v \leq 0$ . We introduce the notation

$$\rho_+ := h'_+(\cdot, +1), \rho_- := -h'_+(\cdot, -1) \text{ and } \rho := (1/2)(\rho_+ + \rho_-)$$

on  $(0, +\infty)$ . The function  $h$  is locally of bounded variation and is differentiable a.e. with  $h' = \rho$  a.e. on  $(0, +\infty)$ . Our second main result is a uniqueness theorem.

**Theorem 1.2** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Suppose that  $R := \inf\{\rho > 0\} \in [0, +\infty)$  and set  $v_0 := V(B(0, R))$ . Let  $v > 0$  and  $E$  a minimiser for (1.2). The following hold:*

- (i) if  $v \leq v_0$  then  $E$  is a.e. equivalent to a ball  $B$  in  $\overline{B}(0, R)$  with  $V(B) = V(E)$ ;
- (ii) if  $v > v_0$  then  $E$  is a.e. equivalent to a centred ball  $B$  with  $V(B) = V(E)$ .

Theorem 1.1 is a generalisation of Conjecture 3.12 in [24] (due to K. Brakke) in the sense that less regularity is required of the density  $f$ : in the latter,  $h$  is supposed to be smooth on  $(0, +\infty)$  as well as convex and non-decreasing. This conjecture springs in part from the observation that the weighted perimeter of a local volume-preserving perturbation of a centred ball is non-decreasing ([24] Theorem 3.10). In addition, the conjecture holds for log-convex Gaussian densities of the form  $h : [0, +\infty) \rightarrow \mathbb{R}; t \mapsto e^{ct^2}$  with  $c > 0$  ([3, 24] Theorem 5.2). In subsequent work partial forms of the conjecture were proved in the literature. In [19] it is shown to hold for large  $v$  provided that  $h$  is uniformly convex in the sense that  $h'' \geq 1$  on  $(0, +\infty)$  (see [19] Corollary

6.8). A complementary result is contained in [11] Theorem 1.1 which establishes the conjecture for small  $v$  on condition that  $h''$  is locally uniformly bounded away from zero on  $[0, +\infty)$ . The above-mentioned conjecture is proved in large part in [7] (see Theorem 1.1) in dimension  $n \geq 2$  (see also [4]). There it is assumed that the function  $h$  is of class  $C^3$  on  $(0, +\infty)$  and is convex and even (meaning that  $h$  is the restriction of an even function on  $\mathbb{R}$  to  $[0, +\infty)$ ). A uniqueness result is also obtained ([7] Theorem 1.2). We obtain these results under weaker hypotheses in the 2-dimensional case and our proofs proceed along different lines.

We give a brief outline of the article. In Sect. 2 we discuss some preliminary material. In Sect. 3 we show that (1.2) admits an open minimiser  $E$  with  $C^1$  boundary  $M$  (Theorem 3.8). The argument draws upon the regularity theory for almost minimal sets (cf. [27]) and includes an adaptation of [21] Proposition 3.1. In Sect. 4 it is shown that the boundary  $M$  is of class  $C^{1,1}$  (and has weakly bounded curvature). This result is contained in [21] Corollary 3.7 (see also [8]) but we include a proof for completeness. This Section also includes the result that  $E$  may be supposed to possess spherical cap symmetry (Theorem 4.5). Section 5 contains further results on spherical cap symmetric sets useful in the sequel. The main result of Sect. 6 is Theorem 6.5 which shows that the generalised (mean) curvature is conserved along  $M$  in a weak sense. In Sect. 7 it is shown that there exist convex minimisers of (1.2). Sections 8 and 9 comprise an analytic interlude and are devoted to the study of solutions of the first-order differential equation that appears in Theorem 6.6 subject to Dirichlet boundary conditions. Section 9 for example contains a comparison theorem for solutions to a Riccati equation (Theorem 9.15 and Corollary 9.16). These are new as far as the author is aware. Section 10 concludes the proof of our main theorems.

## 2 Some preliminaries

*Geometric measure theory.* We use  $|\cdot|$  to signify the Lebesgue measure on  $\mathbb{R}^2$  (or occasionally  $\mathcal{L}^2$ ). Let  $E$  be a  $\mathcal{L}^2$ -measurable set in  $\mathbb{R}^2$ . The set of points in  $E$  with density  $t \in [0, 1]$  is given by

$$E^t := \left\{ x \in \mathbb{R}^2 : \lim_{\rho \downarrow 0} \frac{|E \cap B(x, \rho)|}{|B(x, \rho)|} = t \right\}.$$

As usual  $B(x, \rho)$  denotes the open ball in  $\mathbb{R}^2$  with centre  $x \in \mathbb{R}^2$  and radius  $\rho > 0$ . The set  $E^1$  is the measure-theoretic interior of  $E$  while  $E^0$  is the measure-theoretic exterior of  $E$ . The essential boundary of  $E$  is the set  $\partial^* E := \mathbb{R}^2 \setminus (E^0 \cup E^1)$ .

Recall that an integrable function  $u$  on  $\mathbb{R}^2$  is said to have bounded variation if the distributional derivative of  $u$  is representable by a finite Radon measure  $Du$  (cf. [1] Definition 3.1 for example) with total variation  $|Du|$ ; in this case, we write  $u \in \text{BV}(\mathbb{R}^2)$ . The set  $E$  has finite perimeter if  $\chi_E$  belongs to  $\text{BV}_{\text{loc}}(\mathbb{R}^2)$ . The reduced boundary  $\mathcal{F}E$  of  $E$  is defined by

$$\mathcal{F}E := \left\{ x \in \text{supp}|D\chi_E| : \nu^E(x) := \lim_{\rho \downarrow 0} \frac{D\chi_E(B(x, \rho))}{|D\chi_E|(B(x, \rho))} \text{ exists in } \mathbb{R}^2 \text{ and } |\nu^E(x)| = 1 \right\}$$

(cf. [1] Definition 3.54) and is a Borel set (cf. [1] Theorem 2.22 for example). We use  $\mathcal{H}^k$  ( $k \in [0, +\infty)$ ) to stand for  $k$ -dimensional Hausdorff measure. If  $E$  is a set of finite perimeter in  $\mathbb{R}^2$  then

$$\mathcal{F}E \subset E^{1/2} \subset \partial^*E \text{ and } \mathcal{H}^1(\partial^*E \setminus \mathcal{F}E) = 0 \quad (2.1)$$

by [1] Theorem 3.61.

Let  $f$  be a positive locally Lipschitz density on  $\mathbb{R}^2$ . Let  $E$  be a set of finite perimeter and  $U$  a bounded open set in  $\mathbb{R}^2$ . The weighted perimeter of  $E$  relative to  $U$  is defined by

$$P_f(E, U) := \sup \left\{ \int_U \operatorname{div}(fX) \, dx : X \in C_c^\infty(U, \mathbb{R}^2), \|X\|_\infty \leq 1 \right\}.$$

By the Gauss–Green formula ([1] Theorem 3.36 for example) and a convolution argument,

$$\begin{aligned} P_f(E, U) &= \sup \left\{ \int_{\mathbb{R}^2} f \langle \nu^E, X \rangle \, d|D\chi_E| : X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2), \right. \\ &\quad \left. \operatorname{supp}[X] \subset U, \|X\|_\infty \leq 1 \right\} \\ &= \sup \left\{ \int_{\mathbb{R}^2} f \langle \nu^E, X \rangle \, d|D\chi_E| : X \in C_c(\mathbb{R}^2, \mathbb{R}^2), \right. \\ &\quad \left. \operatorname{supp}[X] \subset U, \|X\|_\infty \leq 1 \right\} \\ &= \int_U f \, d|D\chi_E| \end{aligned} \quad (2.2)$$

where we have also used [1] Propositions 1.47 and 1.23.

**Lemma 2.1** *Let  $\varphi$  be a  $C^1$  diffeomorphism of  $\mathbb{R}^2$  which coincides with the identity map on the complement of a compact set and  $E \subset \mathbb{R}^2$  with  $\chi_E \in \operatorname{BV}(\mathbb{R}^2)$ . Then*

- (i)  $\chi_{\varphi(E)} \in \operatorname{BV}(\mathbb{R}^2)$ ;
- (ii)  $\partial^*\varphi(E) = \varphi(\partial^*E)$ ;
- (iii)  $\mathcal{H}^1(\mathcal{F}\varphi(E) \Delta \varphi(\mathcal{F}E)) = 0$ .

*Proof* Part (i) follows from [1] Theorem 3.16 as  $\varphi$  is a proper Lipschitz function. Given  $x \in E^0$  we claim that  $y := \varphi(x) \in \varphi(E)^0$ . Let  $M$  stand for the Lipschitz constant of  $\varphi$  and  $L$  stand for the Lipschitz constant of  $\varphi^{-1}$ . Note that  $B(y, r) \subset \varphi(B(x, Lr))$  for each  $r > 0$ . As  $\varphi$  is a bijection and using [1] Proposition 2.49,

$$\begin{aligned} |\varphi(E) \cap B(y, r)| &\leq |\varphi(E) \cap \varphi(B(x, Lr))| \\ &= |\varphi(E \cap B(x, Lr))| \leq M^2 |E \cap B(x, Lr)|. \end{aligned}$$

This means that

$$\frac{|\varphi(E) \cap B(y, r)|}{|B(y, r)|} \leq (LM)^2 \frac{|E \cap B(x, Lr)|}{|B(x, Lr)|}$$

for  $r > 0$  and this proves the claim. This entails that  $\varphi(E^0) \subset [\varphi(E)]^0$ . The reverse inclusion can be seen using the fact that  $\varphi$  is a bijection. In summary  $\varphi(E^0) = [\varphi(E)]^0$ . The corresponding identity for  $E^1$  can be seen in a similar way. These identities entail (ii). From (2.1) and (ii) we may write  $\mathcal{F}\varphi(E) \cup N_1 = \varphi(\mathcal{F}E) \cup \varphi(N_2)$  for  $\mathcal{H}^1$ -null sets  $N_1, N_2$  in  $\mathbb{R}^2$ . Item (iii) follows.  $\square$

*Curves with weakly bounded curvature.* Suppose the open set  $E$  in  $\mathbb{R}^2$  has  $C^1$  boundary  $M$ . Denote by  $n : M \rightarrow \mathbb{S}^1$  the inner unit normal vector field. Given  $p \in M$  we choose a tangent vector  $t(p) \in \mathbb{S}^1$  in such a way that the pair  $\{t(p), n(p)\}$  forms a positively oriented basis for  $\mathbb{R}^2$ . There exists a local parametrisation  $\gamma_1 : I \rightarrow M$  where  $I = (-\delta, \delta)$  for some  $\delta > 0$  of class  $C^1$  with  $\gamma_1(0) = p$ . We always assume that  $\gamma_1$  is parametrised by arc-length and that  $\dot{\gamma}_1(0) = t(p)$  where the dot signifies differentiation with respect to arc-length. Let  $X$  be a vector field defined in some neighbourhood of  $p$  in  $M$ . Then

$$(D_t X)(p) := \left. \frac{d}{ds} \right|_{s=0} (X \circ \gamma_1)(s) \tag{2.3}$$

if this limit exists and the divergence  $\operatorname{div}^M X$  of  $X$  along  $M$  at  $p$  is defined by

$$\operatorname{div}^M X := \langle D_t X, t \rangle \tag{2.4}$$

evaluated at  $p$ . Suppose that  $X$  is a vector field in  $C^1(U, \mathbb{R}^2)$  where  $U$  is an open neighbourhood of  $p$  in  $\mathbb{R}^2$ . Then

$$\operatorname{div} X = \operatorname{div}^M X + \langle D_n X, n \rangle \tag{2.5}$$

at  $p$ . If  $p \in M \setminus \{0\}$  let  $\sigma(p)$  stand for the angle measured anti-clockwise from the position vector  $p$  to the tangent vector  $t(p)$ ;  $\sigma(p)$  is uniquely determined up to integer multiples of  $2\pi$ .

Let  $E$  be an open set in  $\mathbb{R}^2$  with  $C^{1,1}$  boundary  $M$ . Let  $x \in M$  and  $\gamma_1 : I \rightarrow M$  a local parametrisation of  $M$  in a neighbourhood of  $x$ . There exists a constant  $c > 0$  such that

$$|\dot{\gamma}_1(s_2) - \dot{\gamma}_1(s_1)| \leq c|s_2 - s_1|$$

for  $s_1, s_2 \in I$ ; a constraint on average curvature (cf. [10, 18]). That is,  $\dot{\gamma}_1$  is Lipschitz on  $I$ . So  $\dot{\gamma}_1$  is absolutely continuous and differentiable a.e. on  $I$  with

$$\dot{\gamma}_1(s_2) - \dot{\gamma}_1(s_1) = \int_{s_1}^{s_2} \ddot{\gamma}_1 ds \tag{2.6}$$

for any  $s_1, s_2 \in I$  with  $s_1 < s_2$ . Moreover,  $|\ddot{\gamma}_1| \leq c$  a.e. on  $I$  (cf. [1] Corollary 2.23). As  $\langle \dot{\gamma}_1, \dot{\gamma}_1 \rangle = 1$  on  $I$  we see that  $\langle \dot{\gamma}_1, \ddot{\gamma}_1 \rangle = 0$  a.e. on  $I$ . The (geodesic) curvature  $k_1$  is then defined a.e. on  $I$  via the relation

$$\ddot{\gamma}_1 = k_1 n_1 \tag{2.7}$$

as in [18]. The curvature  $k$  of  $M$  is defined  $\mathcal{H}^1$ -a.e. on  $M$  by

$$k(x) := k_1(s) \tag{2.8}$$

whenever  $x = \gamma_1(s)$  for some  $s \in I$  and  $k_1(s)$  exists. We sometimes write  $H(\cdot, E) = k$ .

Let  $E$  be an open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$ . Let  $x \in M$  and  $\gamma_1 : I \rightarrow M$  a local parametrisation of  $M$  in a neighbourhood of  $x$ . In case  $\gamma_1 \neq 0$  let  $\theta_1$  stand for the angle measured anti-clockwise from  $e_1$  to the position vector  $\gamma_1$  and  $\sigma_1$  stand for the angle measured anti-clockwise from the position vector  $\gamma_1$  to the tangent vector  $t_1 = \dot{\gamma}_1$ . Put  $r_1 := |\gamma_1|$  on  $I$ . Then  $r_1, \theta_1 \in C^1(I)$  and

$$\dot{r}_1 = \cos \sigma_1; \tag{2.9}$$

$$r_1 \dot{\theta}_1 = \sin \sigma_1; \tag{2.10}$$

on  $I$  provided that  $\gamma_1 \neq 0$ . Now suppose that  $M$  is of class  $C^{1,1}$ . Let  $\alpha_1$  stand for the angle measured anti-clockwise from the fixed vector  $e_1$  to the tangent vector  $t_1$  (uniquely determined up to integer multiples of  $2\pi$ ). Then  $t_1 = (\cos \alpha_1, \sin \alpha_1)$  on  $I$  so  $\alpha_1$  is absolutely continuous on  $I$ . In particular,  $\alpha_1$  is differentiable a.e. on  $I$  with  $\dot{\alpha}_1 = k_1$  a.e. on  $I$ . This means that  $\alpha_1 \in C^{0,1}(I)$ . In virtue of the identities  $r_1 \cos \sigma_1 = \langle \gamma_1, t_1 \rangle$  and  $r_1 \sin \sigma_1 = -\langle \gamma_1, n_1 \rangle$  we see that  $\sigma_1$  is absolutely continuous on  $I$  and  $\sigma_1 \in C^{0,1}(I)$ . By choosing an appropriate branch we may assume that

$$\alpha_1 = \theta_1 + \sigma_1 \tag{2.11}$$

on  $I$ . We may choose  $\sigma$  in such a way that  $\sigma \circ \gamma_1 = \sigma_1$  on  $I$ .

*Flows.* Recall that a diffeomorphism  $\varphi : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is said to be proper if  $\varphi^{-1}(K)$  is compact whenever  $K \subset \mathbb{R}^2$  is compact. Given  $X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  there exists a 1-parameter group of proper  $C^\infty$  diffeomorphisms  $\varphi : \mathbb{R} \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$  as in [20] Lemma 2.99 that satisfy

$$\begin{aligned} \partial_t \varphi(t, x) &= X(\varphi(t, x)) \text{ for each } (t, x) \in \mathbb{R} \times \mathbb{R}^2; \\ \varphi(0, x) &= x \text{ for each } x \in \mathbb{R}^2. \end{aligned} \tag{2.12}$$

We often use  $\varphi_t$  to refer to the diffeomorphism  $\varphi(t, \cdot) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ .

**Lemma 2.2** *Let  $X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  and  $\varphi$  be the corresponding flow as above. Then*

(i) *there exists  $R \in C^\infty(\mathbb{R} \times \mathbb{R}^2, \mathbb{R}^2)$  and  $K > 0$  such that*

$$\varphi(t, x) = \begin{cases} x + tX(x) + R(t, x) & \text{for } x \in \text{supp}[X]; \\ x & \text{for } x \notin \text{supp}[X]; \end{cases}$$

where  $|R(t, x)| \leq Kt^2$  for  $(t, x) \in \mathbb{R} \times \mathbb{R}^2$ ;

(ii) there exists  $R^{(1)} \in C^\infty(\mathbb{R} \times \mathbb{R}^2, M_2(\mathbb{R}))$  and  $K_1 > 0$  such that

$$d\varphi(t, x) = \begin{cases} I + t dX(x) + R^{(1)}(t, x) & \text{for } x \in \text{supp}[X]; \\ I & \text{for } x \notin \text{supp}[X]; \end{cases}$$

where  $|R^{(1)}(t, x)| \leq K_1 t^2$  for  $(t, x) \in \mathbb{R} \times \mathbb{R}^2$ ;

(iii) there exists  $R^{(2)} \in C^\infty(\mathbb{R} \times \mathbb{R}^2, \mathbb{R})$  and  $K_2 > 0$  such that

$$J_2 d\varphi(t, x) = \begin{cases} 1 + t \operatorname{div} X(x) + R^{(2)}(t, x) & \text{for } x \in \text{supp}[X]; \\ 1 & \text{for } x \notin \text{supp}[X]; \end{cases}$$

where  $|R^{(2)}(t, x)| \leq K_2 t^2$  for  $(t, x) \in \mathbb{R} \times \mathbb{R}^2$ .

Let  $x \in \mathbb{R}^2$ ,  $v$  a unit vector in  $\mathbb{R}^2$  and  $M$  the line through  $x$  perpendicular to  $v$ . Then

(iv) there exists  $R^{(3)} \in C^\infty(\mathbb{R} \times \mathbb{R}^2, \mathbb{R})$  and  $K_3 > 0$  such that

$$J_1 d^M \varphi(t, x) = \begin{cases} 1 + t (\operatorname{div}^M X)(x) + R^{(3)}(t, x) & \text{for } x \in \text{supp}[X]; \\ 1 & \text{for } x \notin \text{supp}[X]; \end{cases}$$

where  $|R^{(3)}(t, x)| \leq K_3 t^2$  for  $(t, x) \in \mathbb{R} \times \mathbb{R}^2$ .

*Proof* (i) First notice that  $\varphi \in C^\infty(\mathbb{R} \times \mathbb{R}^2)$  by [16] Theorem 3.3 and Exercise 3.4. The statement for  $x \notin \text{supp}[X]$  follows by uniqueness (cf. [16] Theorem 3.1); the assertion for  $x \in \text{supp}[X]$  follows from Taylor's theorem. (ii) follows likewise: note, for example, that

$$[\partial_{t_i} d\varphi]_{\alpha\beta}|_{t=0} = X_{,\beta\delta}^\alpha X^\delta + X_{,\gamma}^\alpha X_{,\beta}^\gamma$$

where the subscript  $\cdot$  signifies partial differentiation. (iii) follows from (ii) and the definition of the 2-dimensional Jacobian (cf. [1] Definition 2.68). (iv) Using [1] Definition 2.68 together with the Cauchy–Binet formula [1] Proposition 2.69,  $J_1 d^M \varphi(t, x) = |d\varphi(t, x)v|$  for  $t \in \mathbb{R}$  and the result follows from (ii).  $\square$

Let  $I$  be an open interval in  $\mathbb{R}$  containing 0. Let  $Z : I \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$ ;  $(t, x) \mapsto Z(t, x)$  be a continuous time-dependent vector field on  $\mathbb{R}^2$  with the properties

(Z.1)  $Z(t, \cdot) \in C_c^1(\mathbb{R}^2, \mathbb{R}^2)$  for each  $t \in I$ ;

(Z.2)  $\text{supp}[Z(t, \cdot)] \subset K$  for each  $t \in I$  for some compact set  $K \subset \mathbb{R}^2$ .

By [16] Theorems I.1.1, I.2.1, I.3.1, I.3.3 there exists a unique flow  $\varphi : I \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$  such that

(F.1)  $\varphi : I \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is of class  $C^1$ ;

(F.2)  $\varphi(0, x) = x$  for each  $x \in \mathbb{R}^2$ ;

(F.3)  $\partial_t \varphi(t, x) = Z(t, \varphi(x, t))$  for each  $(t, x) \in I \times \mathbb{R}^2$ ;

(F.4)  $\varphi_t := \varphi(t, \cdot) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is a proper diffeomorphism for each  $t \in I$ .



**Lemma 2.3** *Let  $Z$  be a time-dependent vector field with the properties (Z.1)–(Z.2) and  $\varphi$  be the corresponding flow. Then*

(i) *for  $(t, x) \in I \times \mathbb{R}^2$ ,*

$$d\varphi(t, x) = \begin{cases} I + t dZ_0(x) + tR(t, x) & \text{for } x \in K; \\ I & \text{for } x \notin K; \end{cases}$$

*where  $\sup_K |R(t, \cdot)| \rightarrow 0$  as  $t \rightarrow 0$ .*

*Let  $x \in \mathbb{R}^2$ ,  $v$  a unit vector in  $\mathbb{R}^2$  and  $M$  the line through  $x$  perpendicular to  $v$ . Then*

(ii) *for  $(t, x) \in I \times \mathbb{R}^2$ ,*

$$J_1 d^M \varphi(t, x) = \begin{cases} 1 + t(\operatorname{div}^M Z_0)(x) + tR^{(1)}(t, x) & \text{for } x \in K; \\ 1 & \text{for } x \notin K. \end{cases}$$

*where  $\sup_K |R^{(1)}(t, \cdot)| \rightarrow 0$  as  $t \rightarrow 0$ .*

*Proof (i)* We first remark that the flow  $\varphi : I \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$  associated to  $Z$  is continuously differentiable in  $t, x$  in virtue of (Z.1) by [16] Theorem I.3.3. Put  $y(t, x) := d\varphi(t, x)$  for  $(t, x) \in I \times \mathbb{R}^2$ . By [16] Theorem I.3.3,

$$\dot{y}(t, x) = dZ(t, \varphi(t, x))y(t, x)$$

for each  $(t, x) \in I \times \mathbb{R}^2$  and  $y(0, x) = I$  for each  $x \in \mathbb{R}^2$  where  $I$  stands for the  $2 \times 2$ -identity matrix. For  $x \in K$  and  $t \in I$ ,

$$\begin{aligned} d\varphi(t, x) &= I + d\varphi(t, x) - d\varphi(0, x) \\ &= I + t\dot{y}(0, x) + t \left\{ \frac{d\varphi(t, x) - d\varphi(0, x)}{t} - \dot{y}(0, x) \right\} \\ &= I + t dZ(0, x) + t \left\{ \frac{y(t, x) - y(0, x)}{t} - \dot{y}(0, x) \right\} \\ &= I + t dZ_0(x) + t \left\{ \frac{y(t, x) - y(0, x)}{t} - \dot{y}(0, x) \right\}. \end{aligned}$$

Applying the mean-value theorem component-wise and using uniform continuity of the matrix  $\dot{y}$  in its arguments we see that

$$\frac{y(t, \cdot) - y(0, \cdot)}{t} - \dot{y}(0, \cdot) \rightarrow 0$$

uniformly on  $K$  as  $t \rightarrow 0$ . This leads to (i). Part (ii) follows as in Lemma 2.2. □

Let  $E$  be a set of finite perimeter in  $\mathbb{R}^2$  with  $V_f(E) < +\infty$ . The first variation of weighted volume resp. perimeter along  $X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  is defined by

$$\delta V_f(X) := \left. \frac{d}{dt} \right|_{t=0} V_f(\varphi_t(E)), \tag{2.13}$$

$$\delta P_f^+(X) := \lim_{t \downarrow 0} \frac{P_f(\varphi_t(E)) - P_f(E)}{t}, \tag{2.14}$$

whenever the limit exists. By Lemma 2.1 the  $f$ -perimeter in (2.14) is well-defined. *Convex functions.* Suppose that  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a convex function. For  $x \geq 0$  and  $v \geq 0$  define

$$h'_+(x, v) := \lim_{t \downarrow 0} \frac{h(x + tv) - h(x)}{t} \in \mathbb{R}$$

and define  $h'_-(x, v)$  similarly for  $x > 0$  and  $v \leq 0$ . For future use we introduce the notation

$$\rho_+ := h'(\cdot, +1), \rho_- := -h'(\cdot, -1) \text{ and } \rho := (1/2)(\rho_+ + \rho_-)$$

on  $(0, +\infty)$ . It holds that  $h$  is differentiable a.e. and  $h' = \rho$  a.e. on  $(0, +\infty)$ . Define  $[\rho] := \rho_+ - \rho_-$ . Then  $[\rho] \geq 0$  and vanishes a.e. on  $(0, +\infty)$ .

**Lemma 2.4** *Suppose that the function  $f$  takes the form (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a convex function. Then*

- (i) *the directional derivative  $f'_+(x, v)$  exists in  $\mathbb{R}$  for each  $x \in \mathbb{R}^2$  and  $v \in \mathbb{R}^2$ ;*
- (ii) *for  $v \in \mathbb{R}^2$ ,*

$$f'_+(x, v) = \begin{cases} f(x)h'_+(|x|, \operatorname{sgn}(x, v)) \frac{|(x,v)|}{|x|} & \text{for } x \in \mathbb{R}^2 \setminus \{0\}; \\ f(0)h'_+(0, +1)|v| & \text{for } x = 0; \end{cases}$$

- (iii) *if  $M$  is a  $C^1$  hypersurface in  $\mathbb{R}^2$  such that  $\cos \sigma \neq 0$  on  $M$  then  $f$  is differentiable  $\mathcal{H}^1$ -a.e. on  $M$  and*

$$(\nabla f)(x) = f(x)\rho(|x|) \frac{(x, \cdot)}{|x|}$$

*for  $\mathcal{H}^1$ -a.e.  $x \in M$ .*

*Proof* The assertion in (i) follows from the monotonicity of chords property while (ii) is straightforward. (iii) Let  $x \in M$  and  $\gamma_1 : I \rightarrow M$  be a  $C^1$ -parametrisation of  $M$  near  $x$  as above. Now  $r_1 \in C^1(I)$  and  $r'_1(0) = \cos \sigma(x) \neq 0$  so we may assume that  $r_1 : I \rightarrow r_1(I) \subset (0, +\infty)$  is a  $C^1$  diffeomorphism. The differentiability set  $D(h)$  of  $h$  has full Lebesgue measure in  $[0, +\infty)$ . It follows by [1] Proposition 2.49 that  $r_1^{-1}(D(h))$  has full measure in  $I$ . This entails that  $f$  is differentiable  $\mathcal{H}^1$ -a.e. on  $\gamma_1(I) \subset M$ . □

### 3 Existence and $C^1$ regularity

We start with an existence theorem.

**Theorem 3.1** Assume that  $f$  is a positive radial lower-semicontinuous non-decreasing density on  $\mathbb{R}^2$  which diverges to infinity. Then for each  $v > 0$ ,

- (i) (1.2) admits a minimiser;
- (ii) any minimiser of (1.2) is essentially bounded.

*Proof* See [22] Theorems 3.3 and 5.9. □

But the bulk of this section will be devoted to a discussion of  $C^1$  regularity.

**Proposition 3.2** Let  $f$  be a positive locally Lipschitz density on  $\mathbb{R}^2$ . Let  $E \subset \mathbb{R}^2$  be a bounded set with finite perimeter. Let  $X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$ . Then

$$\delta V_f(X) = \int_E \operatorname{div}(fX) \, dx = - \int_{\mathcal{F}E} f \langle \nu^E, X \rangle \, d\mathcal{H}^1.$$

*Proof* Let  $t \in \mathbb{R}$ . By the area formula ([1] Theorem 2.71 and (2.74)),

$$V_f(\varphi_t(E)) = \int_{\varphi_t(E)} f \, dx = \int_E (f \circ \varphi_t) J_2 d(\varphi_t)_x \, dx \quad (3.1)$$

and

$$\begin{aligned} V_f(\varphi_t(E)) - V_f(E) &= \int_E (f \circ \varphi_t) J_2 d\varphi_t - f \, dx \\ &= \int_E (f \circ \varphi_t)(J_2 d\varphi_t - 1) \, dx + \int_E f \circ \varphi_t - f \, dx. \end{aligned}$$

The density  $f$  is locally Lipschitz and in particular differentiable a.e. on  $\mathbb{R}^2$  (see [1] 2.3 for example). By the dominated convergence theorem and Lemma 2.2,

$$\begin{aligned} \delta V_f(X) &= \int_E \left\{ f \operatorname{div}(X) + \langle \nabla f, X \rangle \right\} \, dx = \int_E \operatorname{div}(fX) \, dx \\ &= - \int_{\mathcal{F}E} f \langle \nu^E, X \rangle \, d\mathcal{H}^1 \end{aligned}$$

by the generalised Gauss–Green formula [1] Theorem 3.36. □

**Proposition 3.3** Let  $f$  be a positive locally Lipschitz density on  $\mathbb{R}^2$ . Let  $E \subset \mathbb{R}^2$  be a bounded set with finite perimeter. Let  $X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$ . Then there exist constants  $C > 0$  and  $\delta > 0$  such that

$$|P_f(\varphi_t(E)) - P_f(E)| \leq C|t|$$

for  $|t| < \delta$ .

*Proof* Let  $t \in \mathbb{R}$ . By Lemma 2.1 and [1] Theorem 3.59,

$$P_f(\varphi_t(E)) = \int_{\mathbb{R}^2} f \, d|D\chi_{\varphi_t(E)}| = \int_{\mathcal{F}\varphi_t(E)} f \, d\mathcal{H}^1 = \int_{\varphi_t(\mathcal{F}E)} f \, d\mathcal{H}^1.$$

As  $\mathcal{F}E$  is countably 1-rectifiable ([1] Theorem 3.59) we may use the generalised area formula [1] Theorem 2.91 to write

$$P_f(\varphi_t(E)) = \int_{\mathcal{F}E} (f \circ \varphi_t) J_1 d^{\mathcal{F}E}(\varphi_t)_x \, d\mathcal{H}^1.$$

For each  $x \in \mathcal{F}E$  and any  $t \in \mathbb{R}$ ,

$$|(f \circ \varphi_t)(x) - f(x)| \leq K|\varphi(t, x) - x| \leq K\|X\|_\infty|t|$$

where  $K$  is the Lipschitz constant of  $f$  on  $\text{supp}[X]$ . The result follows upon writing

$$\begin{aligned} P_f(\varphi_t(E)) - P_f(E) &= \int_{\mathcal{F}E} (f \circ \varphi_t)(J_1 d^{\mathcal{F}E}(\varphi_t)_x - 1) \\ &\quad + [f \circ \varphi_t - f] \, d\mathcal{H}^1 \end{aligned} \tag{3.2}$$

and using Lemma 2.2. □

**Lemma 3.4** *Let  $f$  be a positive locally Lipschitz density on  $\mathbb{R}^2$ . Let  $E \subset \mathbb{R}^2$  be a bounded set with finite perimeter and  $p \in \mathcal{F}E$ . For any  $r > 0$  there exists  $X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  with  $\text{supp}[X] \subset B(p, r)$  such that  $\delta V_f(X) = 1$ .*

*Proof* By (2.2) and [1] Theorem 3.59 and (3.57) in particular,

$$P_f(E, B(p, r)) = \int_{B(p,r) \cap \mathcal{F}E} f \, d\mathcal{H}^1 > 0$$

for any  $r > 0$ . By the variational characterisation of the  $f$ -perimeter relative to  $B(p, r)$  we can find  $Y \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  with  $\text{supp}[Y] \subset B(p, r)$  such that

$$0 < \int_{E \cap B(p,r)} \text{div}(fY) \, dx = - \int_{\mathcal{F}E \cap B(p,r)} f \langle \nu^E, Y \rangle \, d\mathcal{H}^1 =: c$$

where we make use of the generalised Gauss–Green formula (cf. [1] Theorem 3.36). Put  $X := (1/c)Y$ . Then  $X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  with  $\text{supp}[X] \subset B(p, r)$  and  $\delta V_f(X) = 1$  according to Proposition 3.2. □

**Proposition 3.5** *Let  $f$  be a positive lower semi-continuous density on  $\mathbb{R}^2$ . Let  $U$  be a bounded open set in  $\mathbb{R}^2$  with Lipschitz boundary. Let  $E, F_1, F_2$  be bounded sets in  $\mathbb{R}^2$  with finite perimeter. Assume that  $E \Delta F_1 \subset\subset U$  and  $E \Delta F_2 \subset\subset \mathbb{R}^2 \setminus \bar{U}$ . Define*

$$F := [F_1 \cap U] \cup [F_2 \setminus U].$$

Then  $F$  is a set of finite perimeter in  $\mathbb{R}^2$  and

$$P_f(E) + P_f(F) = P_f(F_1) + P_f(F_2).$$

*Proof* The function  $\chi_E|_U \in \text{BV}(U)$  and  $D(\chi_E|_U) = (D\chi_E)|_U$ . We write  $\chi_E^U$  for the boundary trace of  $\chi_E|_U$  (see [1] Theorem 3.87); then  $\chi_E^U \in L^1(\partial U, \mathcal{H}^1 \llcorner \partial U)$  (cf. [1] Theorem 3.88). We use similar notation elsewhere. By [1] Corollary 3.89,

$$\begin{aligned} D\chi_E &= D\chi_E \llcorner U + (\chi_E^U - \chi_E^{\mathbb{R}^2 \setminus \bar{U}})_v^U \mathcal{H}^1 \llcorner \partial U + D\chi_E \llcorner (\mathbb{R}^2 \setminus \bar{U}); \\ D\chi_F &= D\chi_{F_1} \llcorner U + (\chi_{F_1}^U - \chi_{F_2}^{\mathbb{R}^2 \setminus \bar{U}})_v^U \mathcal{H}^1 \llcorner \partial U + D\chi_{F_2} \llcorner (\mathbb{R}^2 \setminus \bar{U}); \\ D\chi_{F_1} &= D\chi_{F_1} \llcorner U + (\chi_{F_1}^U - \chi_E^{\mathbb{R}^2 \setminus \bar{U}})_v^U \mathcal{H}^1 \llcorner \partial U + D\chi_E \llcorner (\mathbb{R}^2 \setminus \bar{U}); \\ D\chi_{F_2} &= D\chi_E \llcorner U + (\chi_E^U - \chi_{F_2}^{\mathbb{R}^2 \setminus \bar{U}})_v^U \mathcal{H}^1 \llcorner \partial U + D\chi_{F_2} \llcorner (\mathbb{R}^2 \setminus \bar{U}). \end{aligned}$$

From the definition of the total variation measure ([1] Definition 1.4),

$$\begin{aligned} |D\chi_E| &= |D\chi_E \llcorner U + (\chi_E^U - \chi_E^{\mathbb{R}^2 \setminus \bar{U}})_v^U \mathcal{H}^1 \llcorner \partial U + D\chi_E \llcorner (\mathbb{R}^2 \setminus \bar{U})|; \\ |D\chi_F| &= |D\chi_{F_1} \llcorner U + (\chi_{F_1}^U - \chi_{F_2}^{\mathbb{R}^2 \setminus \bar{U}})_v^U \mathcal{H}^1 \llcorner \partial U + D\chi_{F_2} \llcorner (\mathbb{R}^2 \setminus \bar{U})|; \\ |D\chi_{F_1}| &= |D\chi_{F_1} \llcorner U + (\chi_{F_1}^U - \chi_E^{\mathbb{R}^2 \setminus \bar{U}})_v^U \mathcal{H}^1 \llcorner \partial U + D\chi_E \llcorner (\mathbb{R}^2 \setminus \bar{U})|; \\ |D\chi_{F_2}| &= |D\chi_E \llcorner U + (\chi_E^U - \chi_{F_2}^{\mathbb{R}^2 \setminus \bar{U}})_v^U \mathcal{H}^1 \llcorner \partial U + D\chi_{F_2} \llcorner (\mathbb{R}^2 \setminus \bar{U})|; \end{aligned}$$

where we also use the fact that  $\chi_{F_1}^U = \chi_E^U$  as  $E \Delta F_1 \subset\subset U$  and similarly for  $F_2$ . The result now follows.  $\square$

**Proposition 3.6** *Assume that  $f$  is a positive locally Lipschitz density on  $\mathbb{R}^2$ . Let  $v > 0$  and suppose that the set  $E$  is a bounded minimiser of (1.2). Let  $U$  be a bounded open set in  $\mathbb{R}^2$ . There exist constants  $C > 0$  and  $\delta > 0$  with the following property. For any  $x \in U$  and  $0 < r < \delta$ ,*

$$P_f(E) - P_f(F) \leq C |V_f(E) - V_f(F)| \tag{3.3}$$

where  $F$  is any set with finite perimeter in  $\mathbb{R}^2$  such that  $E \Delta F \subset\subset B(x, r)$ .

*Proof* The proof follows that of [21] Proposition 3.1. We assume to the contrary that

$$\begin{aligned} (\forall C > 0)(\forall \delta > 0)(\exists x \in U)(\exists r \in (0, \delta))(\exists F \subset \mathbb{R}^2) \\ [F \Delta E \subset\subset B(x, r) \wedge \Delta P_f > C |\Delta V_f|] \end{aligned} \tag{3.4}$$

in the language of quantifiers where we have taken some liberties with notation.

Choose  $p_1, p_2 \in \mathcal{F}E$  with  $p_1 \neq p_2$ . Choose  $r_0 > 0$  such that the open balls  $B(p_1, r_0)$  and  $B(p_2, r_0)$  are disjoint. Choose vector fields  $X_j \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  with  $\text{supp}[X_j] \subset B(p_j, r_0)$  such that

$$\delta V_f(X_j) = 1 \text{ and } |P_f(\varphi_t^{(j)}(E)) - P_f(E)| \leq a_j |t| \text{ for } |t| < \delta_j \text{ and } j = 1, 2 \tag{3.5}$$

as in Lemma 3.4 and Proposition 3.3. Put  $a := \max\{a_1, a_2\}$ . By (3.5),

$$V_f(\varphi_t^{(j)}(E)) - V_f(E) = t + o(t) \text{ as } t \rightarrow 0 \text{ for } j = 1, 2.$$

So there exist  $\varepsilon > 0$  and  $1 > \eta > 0$  such that

$$\begin{aligned} t - \eta |t| < V_f(\varphi_t^{(j)}(E)) - V_f(E) < t + \eta |t|; \\ |P_f(\varphi_t^{(j)}(E)) - P_f(E)| < (a + 1) |t|; \end{aligned} \tag{3.6}$$

for  $|t| < \varepsilon$  and  $j = 1, 2$ . In particular,

$$\begin{aligned} |V_f(\varphi_t^{(j)}(E)) - V_f(E)| > (1 - \eta) |t|; \\ |P_f(\varphi_t^{(j)}(E)) - P_f(E)| < \frac{1 + a}{1 - \eta} |V_f(\varphi_t^{(j)}(E)) - V_f(E)| \text{ for } |t| < \varepsilon; \end{aligned} \tag{3.7}$$

for  $|t| < \varepsilon$  and  $j = 1, 2$ .

In (3.4) choose  $C = (1 + a)/(1 - \eta)$  and  $\delta > 0$  such that

- (a)  $0 < 2\delta < \text{dist}(B(p_1, r_0), B(p_2, r_0))$ ,
- (b)  $\sup\{V_f(B(x, \delta)) : x \in U\} < (1 - \eta) \varepsilon$ .

Choose  $x, r$  and  $F_1$  as in (3.4). In light of (a) we may assume that  $B(x, r) \cap B(p_1, r_0) = \emptyset$ . By (b),

$$|V_f(F_1) - V_f(E)| \leq V_f(B(x, r)) \leq V_f(B(x, \delta)) < (1 - \eta) \varepsilon. \tag{3.8}$$

From (3.6) and (3.8) we can find  $t \in (-\varepsilon, \varepsilon)$  such that with  $F_2 := \varphi_t^{(1)}(E)$ ,

$$V_f(F_2) - V_f(E) = - \left\{ V_f(F_1) - V_f(E) \right\} \tag{3.9}$$

by the intermediate value theorem. From (3.4),

$$P_f(F_1) < P_f(E) - C |V_f(F_1) - V_f(E)| \tag{3.10}$$

while from (3.7),

$$P_f(F_2) < P_f(E) + C |V_f(F_2) - V_f(E)|. \tag{3.11}$$

Let  $F$  be the set

$$F := \left[ F_1 \setminus B(p_1, r_0) \right] \cup \left[ B(p_1, r_0) \cap F_2 \right].$$

Note that  $E \Delta F_2 \subset\subset B(p_1, r_0)$ . By Proposition 3.5,  $F$  is a bounded set of finite perimeter in  $\mathbb{R}^2$  and

$$P_f(E) + P_f(F) = P_f(F_1) + P_f(F_2).$$

We then infer from (3.10), (3.11) and (3.9) that

$$\begin{aligned} P_f(F) &= P_f(F_1) + P_f(F_2) - P_f(E) \\ &< P_f(E) - C|V_f(F_1) - V_f(E)| + P_f(E) \\ &\quad + C|V_f(F_2) - V_f(E)| - P_f(E) = P_f(E). \end{aligned}$$

On the other hand,  $V_f(F) = V_f(F_1) + V_f(F_2) - V_f(E) = V_f(E)$  by (3.9). We therefore obtain a contradiction to the  $f$ -isoperimetric property of  $E$ .  $\square$

Let  $E$  be a set of finite perimeter in  $\mathbb{R}^2$  and  $U$  a bounded open set in  $\mathbb{R}^2$ . The minimality excess is the function  $\psi$  defined by

$$\psi(E, U) := P(E, U) - v(E, U) \tag{3.12}$$

where

$$v(E, U) := \inf\{P(F, U) : F \text{ is a set of finite perimeter with } F \Delta E \subset\subset U\}$$

as in [27] (1.9). We recall that the boundary of  $E$  is said to be almost minimal in  $\mathbb{R}^2$  if for each bounded open set  $U$  in  $\mathbb{R}^2$  there exists  $T > 0$  and a positive constant  $K$  such that for every  $x \in U$  and  $r \in (0, T)$ ,

$$\psi(E, B(x, r)) \leq Kr^2. \tag{3.13}$$

This definition corresponds to [27] Definition 1.5.

**Theorem 3.7** *Assume that  $f$  is a positive locally Lipschitz density on  $\mathbb{R}^2$ . Let  $v > 0$  and assume that  $E$  is a bounded minimiser of (1.2). Then the boundary of  $E$  is almost minimal in  $\mathbb{R}^2$ .*

*Proof* Let  $U$  be a bounded open set in  $\mathbb{R}^2$  and  $C > 0$  and  $\delta > 0$  as in Proposition 3.6. The open  $\delta$ -neighbourhood of  $U$  is denoted  $I_\delta(U)$ . Let  $x \in U$  and  $r \in (0, \delta)$ . Put  $V := I_{2\delta}(U)$ . For the sake of brevity write  $m := \inf_{B(x,r)} f$  and  $M := \sup_{B(x,r)} f$ . Let  $F$  be a set of finite perimeter in  $\mathbb{R}^2$  such that  $F \Delta E \subset\subset B(x, r)$ . By Proposition 3.6,

$$\begin{aligned}
 & P(E, B(x, r)) - P(F, B(x, r)) \\
 & \leq \frac{1}{m} P_f(E, B(x, r)) - \frac{1}{M} P_f(F, B(x, r)) \\
 & = \frac{1}{m} (P_f(E, B(x, r)) - P_f(F, B(x, r))) + \left(\frac{1}{m} - \frac{1}{M}\right) P_f(F, B(x, r)) \\
 & \leq \frac{1}{m} (P_f(E, B(x, r)) - P_f(F, B(x, r))) + \frac{M - m}{m^2} P_f(F, B(x, r)) \\
 & \leq \frac{C}{\inf_V f} |V_f(E) - V_f(F)| + (2Lr) \frac{\sup_V f}{(\inf_V f)^2} P(F, B(x, r)) \\
 & \leq C\pi r^2 \frac{\sup_V f}{\inf_V f} + (2Lr) \frac{\sup_V f}{(\inf_V f)^2} P(F, B(x, r))
 \end{aligned}$$

where  $L$  stands for the Lipschitz constant of the restriction of  $f$  to  $V$ . We then derive that

$$\psi(E, B(x, r)) \leq C\pi r^2 \frac{\sup_V f}{\inf_V f} + (2Lr) \frac{\sup_V f}{(\inf_V f)^2} \nu(E, B(x, r)).$$

By [13] (5.14),  $\nu(E, B(x, r)) \leq \pi r$ . The inequality in (3.13) now follows. □

**Theorem 3.8** *Assume that  $f$  is a positive locally Lipschitz density on  $\mathbb{R}^2$ . Let  $v > 0$  and suppose that  $E$  is a bounded minimiser of (1.2). Then there exists a set  $\tilde{E} \subset \mathbb{R}^2$  such that*

- (i)  $\tilde{E}$  is a bounded minimiser of (1.2);
- (ii)  $\tilde{E}$  is equivalent to  $E$ ;
- (iii)  $\tilde{E}$  is open and  $\partial\tilde{E}$  is a  $C^1$  hypersurface in  $\mathbb{R}^2$ .

*Proof* By [13] Proposition 3.1 there exists a Borel set  $F$  equivalent to  $E$  with the property that

$$\partial F = \{x \in \mathbb{R}^2 : 0 < |F \cap B(x, \rho)| < \pi\rho^2 \text{ for each } \rho > 0\}.$$

By Theorem 3.7 and [27] Theorem 1.9,  $\partial F$  is a  $C^1$  hypersurface in  $\mathbb{R}^2$  (taking note of differences in notation). The set

$$\tilde{E} := \{x \in \mathbb{R}^2 : |F \cap B(x, \rho)| = \pi\rho^2 \text{ for some } \rho > 0\}$$

satisfies (i)–(iii). □

### 4 Weakly bounded curvature and spherical cap symmetry

**Theorem 4.1** *Assume that  $f$  is a positive locally Lipschitz density on  $\mathbb{R}^2$ . Let  $v > 0$  and suppose that  $E$  is a bounded minimiser of (1.2). Then there exists a set  $\tilde{E} \subset \mathbb{R}^2$  such that*

- (i)  $\tilde{E}$  is a bounded minimiser of (1.2);
- (ii)  $\tilde{E}$  is equivalent to  $E$ ;



(iii)  $\tilde{E}$  is open and  $\partial\tilde{E}$  is a  $C^{1,1}$  hypersurface in  $\mathbb{R}^2$ .

*Proof* We may assume that  $E$  has the properties listed in Theorem 3.8. Put  $M := \partial E$ . Let  $x \in M$  and  $U$  a bounded open set containing  $x$ . Choose  $C > 0$  and  $\delta > 0$  as in Proposition 3.6. Let  $0 < r < \delta$  and  $X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  with  $\text{supp}[X] \subset B(x, r)$ . Then

$$P_f(E) - P_f(\varphi_t(E)) \leq C|V_f(E) - V_f(\varphi_t(E))|$$

for each  $t \in \mathbb{R}$ . From the identity (3.2),

$$\begin{aligned} - \int_M (f \circ \varphi_t)(J_1 d^M(\varphi_t)_x - 1) d\mathcal{H}^1 &\leq C|V_f(E) - V_f(\varphi_t(E))| \\ &+ \int_M [f \circ \varphi_t - f] d\mathcal{H}^1 \\ &\leq C|V_f(E) - V_f(\varphi_t(E))| + \sqrt{2}K \|X\|_\infty \mathcal{H}^1(M \cap \text{supp}[X])t \end{aligned}$$

where  $K$  stands for the Lipschitz constant of  $f$  restricted to  $U$ . On dividing by  $t$  and taking the limit  $t \rightarrow 0$  we obtain

$$\begin{aligned} - \int_M f \text{div}^M X d\mathcal{H}^1 &\leq C \left| \int_M f \langle n, X \rangle d\mathcal{H}^1 \right| \\ &+ \sqrt{2}K \|X\|_\infty \mathcal{H}^1(M \cap \text{supp}[X]) \end{aligned}$$

upon using Lemma 2.2 and Proposition 3.2. Replacing  $X$  by  $-X$  we derive that

$$\left| \int_M f \text{div}^M X d\mathcal{H}^1 \right| \leq C_1 \|X\|_\infty \mathcal{H}^1(M \cap \text{supp}[X])$$

where  $C_1 = C\|f\|_{L^\infty(U)} + \sqrt{2}K$ . Let  $\gamma_1 : I \rightarrow M$  be a local  $C^1$  parametrisation of  $M$  near  $x$ . Suppose that  $Y \in C_c^1(I, \mathbb{R}^2)$  with  $\text{supp}[Y] \subset I$  and that  $\gamma_1(I) \subset M \cap B(x, r)$ . Note that there exists  $X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  with  $\text{supp}[X] \subset B(x, r)$  such that  $X \circ \gamma_1 = Y$  on  $I$ . The above estimate entails that

$$\left| \int_I (f \circ \gamma_1) \langle \dot{Y}, t \rangle ds \right| \leq C_1 |\text{supp}[Y]| \|Y\|_\infty.$$

This means that the function  $(f \circ \gamma_1)t$  belongs to  $\text{BV}(I)$  and this implies in turn that  $t \in \text{BV}(I)$ . For  $s_1, s_2 \in I$  with  $s_1 < s_2$ ,

$$\begin{aligned} |t(s_2) - t(s_1)| &= |Dt((s_1, s_2))| \leq |Dt((s_1, s_2))| \\ &= \sup \left\{ \int_{(s_1, s_2)} \langle t, \dot{Y} \rangle ds : Y \in C_c^1((s_1, s_2)) \text{ and } \|Y\|_\infty \leq 1 \right\} \\ &\leq c \sup \left\{ \int_{(s_1, s_2)} (f \circ \gamma_1) \langle t, \dot{Y} \rangle ds : Y \in C_c^1((s_1, s_2)) \text{ and } \|Y\|_\infty \leq 1 \right\} \\ &\leq cC_1 |s_2 - s_1| \end{aligned}$$

where  $1/c = \inf_{\overline{J}} f > 0$ . It follows that  $M$  is of class  $C^{1,1}$ . □

We turn to the topic of spherical cap symmetrisation. Denote by  $\mathbb{S}_\tau^1$  the centred circle in  $\mathbb{R}^2$  with radius  $\tau > 0$ . We sometimes write  $\mathbb{S}^1$  for  $\mathbb{S}_1^1$ . Given  $x \in \mathbb{R}^2$ ,  $v \in \mathbb{S}^1$  and  $\alpha \in (0, \pi]$  the open cone with vertex  $x$ , axis  $v$  and opening angle  $2\alpha$  is the set

$$C(x, v, \alpha) := \left\{ y \in \mathbb{R}^2 : \langle y - x, v \rangle > |y - x| \cos \alpha \right\}.$$

Let  $E$  be an  $\mathcal{L}^2$ -measurable set in  $\mathbb{R}^2$  and  $\tau > 0$ . The  $\tau$ -section  $E_\tau$  of  $E$  is the set  $E_\tau := E \cap \mathbb{S}_\tau^1$ . Put

$$L(\tau) = L_E(\tau) := \mathcal{H}^1(E_\tau) \text{ for } \tau > 0 \tag{4.1}$$

and  $p(E) := \{\tau > 0 : L(\tau) > 0\}$ . The function  $L$  is  $\mathcal{L}^1$ -measurable by [1] Theorem 2.93. Given  $\tau > 0$  and  $0 < \alpha \leq \pi$  the spherical cap  $C(\tau, \alpha)$  is the set

$$C(\tau, \alpha) := \begin{cases} \mathbb{S}_\tau^1 \cap C(0, e_1, \alpha) & \text{if } 0 < \alpha < \pi; \\ \mathbb{S}_\tau^1 & \text{if } \alpha = \pi; \end{cases}$$

and has  $\mathcal{H}^1$ -measure  $s(\tau, \alpha) := 2\alpha\tau$ . The spherical cap symmetral  $E^{sc}$  of the set  $E$  is defined by

$$E^{sc} := \bigcup_{\tau \in p(E)} C(\tau, \alpha) \tag{4.2}$$

where  $\alpha \in (0, \pi]$  is determined by  $s(\tau, \alpha) = L(\tau)$ . Observe that  $E^{sc}$  is a  $\mathcal{L}^2$ -measurable set in  $\mathbb{R}^2$  and  $V_f(E^{sc}) = V_f(E)$ . Note also that if  $B$  is a centred open ball then  $B^{sc} = B \setminus \{0\}$ . We say that  $E$  is spherical cap symmetric if  $\mathcal{H}^1((E \Delta E^{sc})_\tau) = 0$  for each  $\tau > 0$ . This definition is broad but suits our purposes.

The result below is stated in [22] Theorem 6.2 and a sketch proof given. A proof along the lines of [2] Theorem 1.1 can be found in [23]. First, let  $B$  be a Borel set in  $(0, +\infty)$ ; then the annulus  $A(B)$  over  $B$  is the set  $A(B) := \{x \in \mathbb{R}^2 : |x| \in B\}$ .

**Theorem 4.2** *Let  $E$  be a set of finite perimeter in  $\mathbb{R}^2$ . Then  $E^{sc}$  is a set of finite perimeter and*

$$P(E^{sc}, A(B)) \leq P(E, A(B)) \tag{4.3}$$

for any Borel set  $B \subset (0, \infty)$  and the same inequality holds with  $E^{sc}$  replaced by any set  $F$  that is  $\mathcal{L}^2$ -equivalent to  $E^{sc}$ .

**Corollary 4.3** *Let  $f$  be a positive lower semi-continuous radial function on  $\mathbb{R}^2$ . Let  $E$  be a set of finite perimeter in  $\mathbb{R}^2$ . Then  $P_f(E^{sc}) \leq P_f(E)$ .*

*Proof* Assume that  $P_f(E) < +\infty$ . We remark that  $f$  is Borel measurable as  $f$  is lower semi-continuous. Let  $(f_h)$  be a sequence of simple Borel measurable radial

functions on  $\mathbb{R}^2$  such that  $0 \leq f_h \leq f$  and  $f_h \uparrow f$  on  $\mathbb{R}^2$  as  $h \rightarrow \infty$ . By Theorem 4.2,

$$P_{f_h}(E^{sc}) = \int_{\mathbb{R}^2} f_h d|D\chi_{E^{sc}}| \leq \int_{\mathbb{R}^2} f_h d|D\chi_E| = P_{f_h}(E)$$

for each  $h$ . Taking the limit  $h \rightarrow \infty$  the monotone convergence theorem gives  $P_f(E^{sc}) \leq P_f(E)$ .  $\square$

**Lemma 4.4** *Let  $E$  be an  $\mathcal{L}^2$ -measurable set in  $\mathbb{R}^2$  such that  $E \setminus \{0\} = E^{sc}$ . Then there exists an  $\mathcal{L}^2$ -measurable set  $F$  equivalent to  $E$  such that*

- (i)  $\partial F = \{x \in \mathbb{R}^2 : 0 < |F \cap B(x, \rho)| < |B(x, \rho)| \text{ for any } \rho > 0\}$ ;
- (ii)  $F$  is spherical cap symmetric.

*Proof* Put

$$E_1 := \{x \in \mathbb{R}^2 : |E \cap B(x, \rho)| = |B(x, \rho)| \text{ for some } \rho > 0\};$$

$$E_0 := \{x \in \mathbb{R}^2 : |E \cap B(x, \rho)| = 0 \text{ for some } \rho > 0\}.$$

We claim that  $E_1$  is spherical cap symmetric. For take  $x \in E_1$  with  $\tau = |x| > 0$  and  $|\theta(x)| \in (0, \pi]$ . Now  $|E \cap B(x, \rho)| = |B(x, \rho)|$  for some  $\rho > 0$ . Let  $y \in \mathbb{R}^2$  with  $|y| = \tau$  and  $|\theta(y)| < |\theta(x)|$ . Choose a rotation  $O \in \text{SO}(2)$  such that  $OB(x, \rho) = B(y, \rho)$ . As  $E \setminus \{0\} = E^{sc}$ ,  $|E \cap B(y, \rho)| = |O(E \cap B(x, \rho))| = |E \cap B(x, \rho)| = |B(x, \rho)| = |B(y, \rho)|$ . The claim follows. It follows in a similar way that  $\mathbb{R}^2 \setminus E_0$  is spherical cap symmetric. It can then be seen that the set  $F := (E_1 \cup E) \setminus E_0$  inherits this property. As in [13] Proposition 3.1 the set  $F$  is equivalent to  $E$  and enjoys the property in (i).  $\square$

**Theorem 4.5** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Given  $v > 0$  let  $E$  be a bounded minimiser of (1.2). Then there exists an  $\mathcal{L}^2$ -measurable set  $\tilde{E}$  with the properties*

- (i)  $\tilde{E}$  is a minimiser of (1.2);
- (ii)  $L_{\tilde{E}} = L$  a.e. on  $(0, +\infty)$ ;
- (iii)  $\tilde{E}$  is open, bounded and has  $C^{1,1}$  boundary;
- (iv)  $\tilde{E} \setminus \{0\} = \tilde{E}^{sc}$ .

*Proof* Let  $E$  be a bounded minimiser for (1.2). Then  $E_1 := E^{sc}$  is a bounded minimiser of (1.2) by Corollary 4.3 and  $L_E = L_{E_1}$  on  $(0, +\infty)$ . Now put  $E_2 := F$  with  $F$  as in Lemma 4.4. Then  $L_{E_2} = L$  a.e. on  $(0, +\infty)$  as  $E_2$  is equivalent to  $E_1$ ,  $E_2$  is a bounded minimiser of (1.2) and  $E_2$  is spherical cap symmetric. Moreover,  $\partial E_2 = \{x \in \mathbb{R}^2 : 0 < |E_2 \cap B(x, \rho)| < |B(x, \rho)| \text{ for any } \rho > 0\}$ . As in the proof of Theorem 3.8,  $\partial E_2$  is a  $C^1$  hypersurface in  $\mathbb{R}^2$ . Put

$$\tilde{E} := \{x \in \mathbb{R}^2 : |E_2 \cap B(x, \rho)| = |B(x, \rho)| \text{ for some } \rho > 0\}.$$

Then  $\tilde{E}$  is equivalent to  $E_2$  so that (ii) holds, and is a bounded minimiser of (1.2);  $\tilde{E}$  is open and  $\partial \tilde{E} = \partial E_2$  is  $C^1$ . In fact,  $\partial \tilde{E}$  is of class  $C^{1,1}$  by Theorem 4.1. As  $E_2$

is spherical cap symmetric the same is true of  $\tilde{E}$ . But  $\tilde{E}$  is open which entails that  $\tilde{E} \setminus \{0\} = \tilde{E}^{sc}$ . □

### 5 More on spherical cap symmetry

Let

$$H := \{x = (x_1, x_2) \in \mathbb{R}^2 : x_2 > 0\}$$

stand for the open upper half-plane in  $\mathbb{R}^2$  and

$$S : \mathbb{R}^2 \rightarrow \mathbb{R}^2; x = (x_1, x_2) \mapsto (x_1, -x_2)$$

for reflection in the  $x_1$ -axis. Let  $O \in \text{SO}(2)$  represent rotation anti-clockwise through  $\pi/2$ .

**Lemma 5.1** *Let  $E$  be an open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$  and assume that  $E \setminus \{0\} = E^{sc}$ . Let  $x \in M \setminus \{0\}$ . Then*

- (i)  $Sx \in M \setminus \{0\}$ ;
- (ii)  $n(Sx) = Sn(x)$ ;
- (iii)  $\cos \sigma(Sx) = -\cos \sigma(x)$ .

*Proof* (i) The closure  $\bar{E}$  of  $E$  is spherical cap symmetric. The spherical cap symmetrals  $\bar{E}$  is invariant under  $S$  from the representation (4.2). (ii) is a consequence of this last observation. (iii) Note that  $t(Sx) = O^*n(Sx) = O^*Sn(x)$ . Then

$$\begin{aligned} \cos \sigma(Sx) &= \langle Sx, t(Sx) \rangle = \langle Sx, O^*Sn(x) \rangle = \langle x, SO^*Sn(x) \rangle \\ &= \langle x, On(x) \rangle = -\langle x, O^*n(x) \rangle = \cos \sigma(x) \end{aligned}$$

as  $SO^*S = O$  and  $O = -O^*$ . □

We introduce the projection  $\pi : \mathbb{R}^2 \rightarrow [0, +\infty)$ ;  $x \mapsto |x|$ .

**Lemma 5.2** *Let  $E$  be an open set in  $\mathbb{R}^2$  with boundary  $M$  and assume that  $E \setminus \{0\} = E^{sc}$ .*

- (i) *Suppose  $0 \neq x \in \mathbb{R}^2 \setminus \bar{E}$  and  $\theta(x) \in (0, \pi]$ . Then there exists an open interval  $I$  in  $(0, +\infty)$  containing  $\tau$  and  $\alpha \in (0, \theta(x))$  such that  $A(I) \setminus \bar{S}(\alpha) \subset \mathbb{R}^2 \setminus \bar{E}$ .*
- (ii) *Suppose  $0 \neq x \in E$  and  $\theta(x) \in [0, \pi)$ . Then there exists an open interval  $I$  in  $(0, +\infty)$  containing  $\tau$  and  $\alpha \in (\theta(x), \pi)$  such that  $A(I) \cap S(\alpha) \subset E$ .*
- (iii) *For each  $0 < \tau \in \pi(M)$ ,  $M_\tau$  is the union of two closed spherical arcs in  $\mathbb{S}_\tau^1$  symmetric about the  $x_1$ -axis.*

*Proof* (i) We can find  $\alpha \in (0, \theta(x))$  such that  $\mathbb{S}_\tau^1 \setminus S(\alpha) \subset \mathbb{R}^2 \setminus \bar{E}$  as can be seen from definition (4.2). This latter set is compact so  $\text{dist}(\mathbb{S}_\tau^1 \setminus S(\alpha), \bar{E}) > 0$ . This means that the  $\varepsilon$ -neighbourhood of  $\mathbb{S}_\tau^1 \setminus S(\alpha)$  is contained in  $\mathbb{R}^2 \setminus \bar{E}$  for  $\varepsilon > 0$  small. The claim

follows. (ii) Again from (4.2) we can find  $\alpha \in (\theta(x), \pi)$  such that  $\overline{\mathbb{S}_\tau^1 \cap S(\alpha)} \subset E$  and the assertion follows as before.

(iii) Suppose  $x_1, x_2$  are distinct points in  $M_\tau$  with  $0 \leq \theta(x_1) < \theta(x_2) \leq \pi$ . Suppose  $y$  lies in the interior of the spherical arc joining  $x_1$  and  $x_2$ . If  $y \in \mathbb{R}^2 \setminus \overline{E}$  then  $x_2 \in \mathbb{R}^2 \setminus \overline{E}$  by (i) and hence  $x_2 \notin M$ . If  $y \in E$  we obtain the contradiction that  $x_1 \in E$  by (ii). Therefore  $y \in M$ . We infer that the closed spherical arc joining  $x_1$  and  $x_2$  lies in  $M_\tau$ . The claim follows noting that  $M_\tau$  is closed.  $\square$

**Lemma 5.3** *Let  $E$  be an open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$ . Let  $x \in M$ . Then*

$$\liminf_{E \ni y \rightarrow x} \left\langle \frac{y - x}{|y - x|}, n(x) \right\rangle \geq 0.$$

*Proof* Assume for a contradiction that

$$\liminf_{E \ni y \rightarrow x} \left\langle \frac{y - x}{|y - x|}, n(x) \right\rangle \in [-1, 0).$$

There exists  $\eta \in (0, 1)$  and a sequence  $(y_h)$  in  $E$  such that  $y_h \rightarrow x$  as  $h \rightarrow \infty$  and

$$\left\langle \frac{y_h - x}{|y_h - x|}, n(x) \right\rangle < -\eta \tag{5.1}$$

for each  $h \in \mathbb{N}$ . Choose  $\alpha \in (0, \pi/2)$  such that  $\cos \alpha = \eta$ . As  $M$  is  $C^1$  there exists  $r > 0$  such that

$$B(x, r) \cap C(x, -n(x), \alpha) \cap E = \emptyset.$$

By choosing  $h$  sufficiently large we can find  $y_h \in B(x, r)$  with the additional property that  $y_h \in C(x, -n(x), \alpha)$  by (5.1). We are thus led to a contradiction.  $\square$

**Lemma 5.4** *Let  $E$  be an open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$  and assume that  $E \setminus \{0\} = E^{sc}$ . For each  $0 < \tau \in \pi(M)$ ,*

- (i)  $|\cos \sigma|$  is constant on  $M_\tau$ ;
- (ii)  $\cos \sigma = 0$  on  $M_\tau \cap \{x_2 = 0\}$ ;
- (iii)  $\langle Ox, n(x) \rangle \leq 0$  for  $x \in M_\tau \cap H$
- (iv)  $\cos \sigma \leq 0$  on  $M_\tau \cap H$ ;

and if  $\cos \sigma \neq 0$  on  $M_\tau$  then

- (v)  $\tau \in p(E)$ ;
- (vi)  $M_\tau$  consists of two disjoint singletons in  $\mathbb{S}_\tau^1$  symmetric about the  $x_1$ -axis;
- (vii)  $L(\tau) \in (0, 2\pi\tau)$ ;
- (viii)  $M_\tau = \{(\tau \cos(L(\tau)/2\tau), \pm\tau \sin(L(\tau)/2\tau)\}$ .

*Proof* (i) By Lemma 5.2,  $M_\tau$  is the union of two closed spherical arcs in  $\mathbb{S}_\tau^1$  symmetric about the  $x_1$ -axis. In case  $M_\tau \cap \overline{H}$  consists of a singleton the assertion follows from Lemma 5.1. Now suppose that  $M_\tau \cap \overline{H}$  consists of a spherical arc in  $\mathbb{S}_\tau^1$  with non-empty

interior. It can be seen that  $\cos \sigma$  vanishes on the interior of this arc as  $0 = r'_1 = \cos \sigma_1$  in a local parametrisation by (2.9). By continuity  $\cos \sigma = 0$  on  $M_\tau$ . (ii) follows from Lemma 5.1. (iii) Let  $x \in M_\tau \cap H$  so  $\theta(x) \in (0, \pi)$ . Then  $S(\theta(x)) \cap \mathbb{S}^1_\tau \subset \bar{E}$  as  $\bar{E}$  is spherical cap symmetric. Then

$$0 \leq \lim_{S(\theta(x)) \cap \mathbb{S}^1_\tau \ni y \rightarrow x} \left\langle \frac{y-x}{|y-x|}, n(x) \right\rangle = -\langle Ox, n(x) \rangle$$

by Lemma 5.3. (iv) The adjoint transformation  $O^*$  represents rotation clockwise through  $\pi/2$ . Let  $x \in M_\tau \cap H$ . By (iii),

$$0 \geq \langle Ox, n(x) \rangle = \langle x, O^*n(x) \rangle = \langle x, t(x) \rangle = \tau \cos \sigma(x)$$

and this leads to the result. (v) As  $\cos \sigma \neq 0$  on  $M_\tau$  we can find  $x \in M_\tau \cap H$ . We claim that  $\mathbb{S}^1_\tau \cap S(\theta(x)) \subset E$ . For suppose that  $y \in \mathbb{S}^1_\tau \cap S(\theta(x))$  but  $y \notin E$ . We may suppose that  $0 \leq \theta(y) < \theta(x) < \pi$ . If  $y \in \mathbb{R}^2 \setminus \bar{E}$  then  $x \in \mathbb{R}^2 \setminus \bar{E}$  by Lemma 5.2. On the other hand, if  $y \in M$  then the spherical arc in  $H$  joining  $y$  to  $x$  is contained in  $M$  again by Lemma 5.2. This arc also has non-empty interior in  $\mathbb{S}^1_\tau$ . Now  $\cos \sigma = 0$  on its interior so  $\cos(\sigma(x)) = 0$  by (i) contradicting the hypothesis. A similar argument deals with (vi) and this together with (v) in turn entails (vii) and (viii).  $\square$

**Lemma 5.5** *Let  $E$  be an open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$  and assume that  $E \setminus \{0\} = E^{sc}$ . Suppose that  $0 \in M$ . Then*

- (i)  $(\sin \sigma)(0+) = 0$ ;
- (ii)  $(\cos \sigma)(0+) = -1$ .

*Proof* (i) Let  $\gamma_1$  be a  $C^1$  parametrisation of  $M$  in a neighbourhood of 0 with  $\gamma_1(0) = 0$  as above. Then  $n(0) = n_1(0) = e_1$  and hence  $t(0) = t_1(0) = -e_2$ . By Taylor's Theorem  $\gamma_1(s) = \gamma_1(0) + t_1(0)s + o(s) = -e_2s + o(s)$  for  $s \in I$ . This means that  $r_1(s) = |\gamma_1(s)| = s + o(s)$  and

$$\cos \theta_1 = \frac{\langle e_1, \gamma_1 \rangle}{r_1} = \frac{\langle e_1, \gamma_1 \rangle}{s} \frac{s}{r_1} \rightarrow 0$$

as  $s \rightarrow 0$  which entails that  $(\cos \theta_1)(0-) = 0$ . Now  $t_1$  is continuous on  $I$  so  $t_1 = -e_2 + o(1)$  and  $\cos \alpha_1 = \langle e_1, t_1 \rangle = o(1)$ . We infer that  $(\cos \alpha_1)(0-) = 0$ . By (2.11),  $\cos \alpha_1 = \cos \sigma_1 \cos \theta_1 - \sin \sigma_1 \sin \theta_1$  on  $I$  and hence  $(\sin \sigma_1)(0-) = 0$ . We deduce that  $(\sin \sigma)(0+) = 0$ . Item (ii) follows from (i) and Lemma 5.4.  $\square$

The set

$$\Omega := \pi \left[ (M \setminus \{0\}) \cap \{\cos \sigma \neq 0\} \right] \tag{5.2}$$

plays an important rôle in the proof of Theorem 1.1.

**Lemma 5.6** *Let  $E$  be an open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$  and assume that  $E \setminus \{0\} = E^{sc}$ . Then  $\Omega$  is an open set in  $(0, +\infty)$ .*

*Proof* Suppose  $0 < \tau \in \Omega$ . Choose  $x \in M_\tau \cap \{\cos \sigma \neq 0\}$ . Let  $\gamma_1 : I \rightarrow M$  be a local  $C^1$  parametrisation of  $M$  in a neighbourhood of  $x$  such that  $\gamma_1(0) = x$  as before. By shrinking  $I$  if necessary we may assume that  $r_1 \neq 0$  and  $\cos \sigma_1 \neq 0$  on  $I$ . Then the set  $\{r_1(s) : s \in I\} \subset \Omega$  is connected and so an interval in  $\mathbb{R}$  (see for example [25] Theorems 6.A and 6.B). By (2.9),  $r'_1(0) = \cos \sigma_1(0) = \cos \sigma(p) \neq 0$ . This means that the set  $\{r_1(s) : s \in I\}$  contains an open interval about  $\tau$ .  $\square$

### 6 Generalised (mean) curvature

Given a set  $E$  of finite perimeter in  $\mathbb{R}^2$  the first variation  $\delta V_f(Z)$  resp.  $\delta P_f^+(Z)$  of weighted volume and perimeter along a time-dependent vector field  $Z$  are defined as in (2.13) and (2.14).

**Proposition 6.1** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Let  $E$  be a bounded open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$ . Let  $Z$  be a time-dependent vector field. Then*

$$\delta P_f^+(Z) = \int_M f'_+(\cdot, Z_0) + f \operatorname{div}^M Z_0 \, d\mathcal{H}^1$$

where  $Z_0 := Z(0, \cdot) \in C_c^1(\mathbb{R}^2, \mathbb{R}^2)$ .

*Proof* The identity (3.2) holds for each  $t \in I$  with  $M$  in place of  $\mathcal{F}E$ . The assertion follows on appealing to Lemma 2.3 and Lemma 2.4 with the help of the dominated convergence theorem.  $\square$

Given  $X, Y \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  let  $\psi$  resp.  $\chi$  stand for the 1-parameter group of  $C^\infty$  diffeomorphisms of  $\mathbb{R}^2$  associated to the vector fields  $X$  resp.  $Y$  as in (2.12). Let  $I$  be an open interval in  $\mathbb{R}$  containing the point 0. Suppose that the function  $\sigma : I \rightarrow \mathbb{R}$  is  $C^1$ . Define a flow via

$$\varphi : I \times \mathbb{R}^2 \rightarrow \mathbb{R}^2; (t, x) \mapsto \chi(\sigma(t), \psi(t, x)).$$

**Lemma 6.2** *The time-dependent vector field  $Z$  associated with the flow  $\varphi$  is given by*

$$Z(t, x) = \sigma'(t)Y(\chi(\sigma(t), \psi(t, x))) + d\chi(\sigma(t), \psi(t, x))X(\psi(t, x)) \tag{6.1}$$

for  $(t, x) \in I \times \mathbb{R}^2$  and satisfies (Z.1) and (Z.2).

*Proof* For  $t \in I$  and  $x \in \mathbb{R}^2$  we compute using (2.12),

$$\partial_t \varphi(t, x) = (\partial_t \chi)(\sigma(t), \psi(t, x))\sigma'(t) + d\chi(\sigma(t), \psi(t, x))\partial_t \psi(t, x)$$

and this gives (6.1). Put  $K_1 := \operatorname{supp}[X]$ ,  $K_2 := \operatorname{supp}[Y]$  and  $K := K_1 \cup K_2$ . Then (Z.2) holds with this choice of  $K$ .  $\square$

Let  $E$  be a bounded open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$ . Define  $\Lambda := (M \setminus \{0\}) \cap \{\cos \sigma = 0\}$  and

$$\Lambda_1 := \{x \in M : \mathcal{H}^1(\Lambda \cap B(x, \rho)) = \mathcal{H}^1(M \cap B(x, \rho)) \text{ for some } \rho > 0\}. \quad (6.2)$$

For future reference put  $\Lambda_1^\pm := \Lambda_1 \cap \{x \in M : \pm \langle x, n \rangle > 0\}$ .

**Lemma 6.3** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Let  $E$  be a bounded open set in  $\mathbb{R}^2$  with  $C^{1,1}$  boundary  $M$  and suppose that  $E \setminus \{0\} = E^{sc}$ . Then*

- (i)  $\Lambda_1$  is a countable disjoint union of well-separated open circular arcs centred at 0;
- (ii)  $\mathcal{H}^1(\overline{\Lambda_1} \setminus \Lambda_1) = 0$ ;
- (iii)  $f$  is differentiable  $\mathcal{H}^1$ -a.e. on  $M \setminus \overline{\Lambda_1}$ .

The term well-separated in (i) means the following: if  $\Gamma$  is an open circular arc in  $\Lambda_1$  with  $\Gamma \cap (\Lambda_1 \setminus \Gamma) = \emptyset$  then  $d(\Gamma, \Lambda_1 \setminus \Gamma) > 0$ .

*Proof* (i) Let  $x \in \Lambda_1$  and  $\gamma_1 : I \rightarrow M$  a  $C^{1,1}$  parametrisation of  $M$  near  $x$ . By shrinking  $I$  if necessary we may assume that  $\gamma_1(I) \subset M \cap B(x, \rho)$  with  $\rho$  as in (6.2). So  $\cos \sigma = 0$   $\mathcal{H}^1$ -a.e. on  $\gamma_1(I)$  and hence  $\cos \sigma_1 = 0$  a.e. on  $I$ . This means that  $\cos \sigma_1 = 0$  on  $I$  as  $\sigma_1 \in C^{0,1}(I)$  and that  $r_1$  is constant on  $I$  by (2.9). Using (2.10) it can be seen that  $\gamma_1(I)$  is an open circular arc centred at 0. By compactness of  $M$  it follows that  $\Lambda_1$  is a countable disjoint union of open circular arcs centred on 0. The well-separated property flows from the fact that  $M$  is  $C^1$ . (ii) follows as a consequence of this property. (iii) Let  $x \in M \setminus \overline{\Lambda_1}$  and  $\gamma_1 : I \rightarrow M$  a  $C^{1,1}$  parametrisation of  $M$  near  $x$  with properties as before. We assume that  $x$  lies in the upper half-plane  $H$ . By shrinking  $I$  if necessary we may assume that  $\gamma_1(I) \subset (M \setminus \overline{\Lambda_1}) \cap H$ . Let  $s_1, s_2, s_3 \in I$  with  $s_1 < s_2 < s_3$ . Then  $y := \gamma_1(s_2) \in M \setminus \overline{\Lambda_1}$ . So  $\mathcal{H}^1(M \cap \{\cos \sigma \neq 0\} \cap B(y, \rho)) > 0$  for each  $\rho > 0$ . This means that for small  $\eta > 0$  the set  $\gamma_1((s_2 - \eta, s_2 + \eta)) \cap \{\cos \sigma \neq 0\}$  has positive  $\mathcal{H}^1$ -measure. Consequently,  $r_1(s_3) - r_1(s_1) = \int_{s_1}^{s_3} \cos \sigma_1 ds < 0$  bearing in mind Lemma 5.4. This shows that  $r_1$  is strictly decreasing on  $I$ . So  $h$  is differentiable a.e. on  $r_1(I) \subset (0, +\infty)$  in virtue of the fact that  $h$  is convex and hence locally Lipschitz. This entails (iii). □

**Proposition 6.4** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Given  $v > 0$  let  $E$  be a minimiser of (1.2). Assume that  $E$  is a bounded open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$  and suppose that  $E \setminus \{0\} = E^{sc}$ . Suppose that  $M \setminus \overline{\Lambda_1} \neq \emptyset$ . Then there exists  $\lambda \in \mathbb{R}$  such that for any  $X \in C_c^1(\mathbb{R}^2, \mathbb{R}^2)$ ,*

$$0 \leq \int_M \left\{ f'_+(\cdot, X) + f \operatorname{div}^M X - \lambda f \langle n, X \rangle \right\} d\mathcal{H}^1.$$

*Proof* Let  $X \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$ . Let  $x \in M$  and  $r > 0$  such that  $M \cap B(x, r) \subset M \setminus \overline{\Lambda_1}$ . Choose  $Y \in C_c^\infty(\mathbb{R}^2, \mathbb{R}^2)$  with  $\operatorname{supp}[Y] \subset B(x, r)$  as in Lemma 3.4. Let  $\psi$  resp.  $\chi$  stand for the 1-parameter group of  $C^\infty$  diffeomorphisms of  $\mathbb{R}^2$  associated to the vector



fields  $X$  resp.  $Y$  as in (2.12). For each  $(s, t) \in \mathbb{R}^2$  the set  $\chi_s(\psi_t(E))$  is an open set in  $\mathbb{R}^2$  with  $C^1$  boundary and  $\partial(\chi_s \circ \psi_t)(E) = (\chi_s \circ \psi_t)(M)$  by Lemma 2.1. Define

$$\begin{aligned} V(s, t) &:= V_f(\chi_t(\psi_s(E))) - V_f(E), \\ P(s, t) &:= P_f(\chi_t(\psi_s(E))), \end{aligned}$$

for  $(s, t) \in \mathbb{R}^2$ . We write  $F = (\chi_t \circ \psi_s)(E)$ . Arguing as in Proposition 3.2,

$$\begin{aligned} \partial_t V(s, t) &= \lim_{h \rightarrow 0} (1/h) \{V_f(\chi_h(F)) - V_f(F)\} = \int_F \operatorname{div}(fY) dx \\ &= \int_E (\operatorname{div}(fY) \circ \chi_t \circ \psi_s) J_2 d(\chi_t \circ \psi_s)_x dx \end{aligned}$$

with an application of the area formula (cf. [1] Theorem 2.71). This last varies continuously in  $(s, t)$ . The same holds for partial differentiation with respect to  $s$ . Indeed, put  $\eta := \chi_t \circ \psi_s$ . Then noting that  $J_2 d(\eta \circ \psi_h) = (J_2 d\eta) \circ \psi_h J_2 d\psi_h$  and using the dominated convergence theorem,

$$\begin{aligned} \partial_s V(s, t) &= \lim_{h \rightarrow 0} (1/h) \left\{ V_f(\eta(\psi_h(E))) - V_f(\eta(E)) \right\} \\ &= \lim_{h \rightarrow 0} (1/h) \left\{ \int_E (f \circ \eta \circ \psi_h) J_2 d(\eta \circ \psi_h)_x dx - \int_E (f \circ \eta) J_2 d\eta_x dx \right\} \\ &= \lim_{h \rightarrow 0} (1/h) \left\{ \int_E [(f \circ \eta \circ \psi_h) - (f \circ \eta)] J_2 d(\eta \circ \psi_h)_x dx \right. \\ &\quad \left. + \int_E (f \circ \eta) [(J_2 d\eta \circ \psi_h - J_2 d\eta)] J_2 d\psi_h dx \right. \\ &\quad \left. + \int_E (f \circ \eta) J_2 d\eta [J_2 d\psi_h - 1] dx \right\} \\ &= \int_E \langle \nabla(f \circ \eta), X \rangle J_2 d\eta_x dx + \int_E (f \circ \eta) \langle \nabla J_2 d\eta, X \rangle dx \\ &\quad + \int_E (f \circ \eta) J_2 d\eta \operatorname{div} X dx \end{aligned}$$

where the explanation for the last term can be found in the proof of Proposition 3.2. In this regard we note that  $d(d\chi_t)$  (for example) is continuous on  $I \times \mathbb{R}^2$  (cf. [1] Theorem 3.3 and Exercise 3.2) and in particular  $\nabla J_2 d\chi_t$  is continuous on  $I \times \mathbb{R}^2$ . The expression above also varies continuously in  $(s, t)$  as can be seen with the help of the dominated convergence theorem. This means that  $V(\cdot, \cdot)$  is continuously differentiable on  $\mathbb{R}^2$ . Note that

$$\partial_t V(0, 0) = \int_E \operatorname{div}(fY) dx = 1$$

by choice of  $Y$ . By the implicit function theorem there exists  $\eta > 0$  and a  $C^1$  function  $\sigma : (-\eta, \eta) \rightarrow \mathbb{R}$  such that  $\sigma(0) = 0$  and  $V(s, \sigma(s)) = 0$  for  $s \in (-\eta, \eta)$ ; moreover,

$$\begin{aligned} \sigma'(0) &= -\partial_s V(0, 0) = -\int_E \left\{ \langle \nabla f, X \rangle + f \operatorname{div} X \right\} dx \\ &= -\int_E \operatorname{div}(fX) dx = \int_M f \langle n, X \rangle d\mathcal{H}^1 \end{aligned}$$

by the Gauss–Green formula (cf. [1] Theorem 3.36).

The mapping

$$\varphi : (-\eta, \eta) \times \mathbb{R}^2 \rightarrow \mathbb{R}^2; t \mapsto \chi(\sigma(t), \psi(t, x))$$

satisfies conditions (F.1)–(F.4) above with  $I = (-\eta, \eta)$  where the associated time-dependent vector field  $Z$  is given as in (6.1) and satisfies (Z.1) and (Z.2); moreover,  $Z_0 = Z(0, \cdot) = \sigma'(0)Y + X$ . Note that  $Z_0 = X$  on  $M \setminus B(x, r)$ .

The mapping  $I \rightarrow \mathbb{R}; t \mapsto P_f(\varphi_t(E))$  is right-differentiable at  $t = 0$  as can be seen from Proposition 6.1 and has non-negative right-derivative there. By Proposition 6.1 and Lemma 6.3,

$$\begin{aligned} 0 \leq \delta P_f^+(Z) &= \int_M f'_+(\cdot, Z_0) + f \operatorname{div}^M Z_0 d\mathcal{H}^1 \\ &= \int_{M \setminus \overline{\Lambda_1}} f'_+(\cdot, Z_0) + f \operatorname{div}^M Z_0 d\mathcal{H}^1 \\ &\quad + \int_{\overline{\Lambda_1}} f'_+(\cdot, X) + f \operatorname{div}^M X d\mathcal{H}^1 \\ &= \int_{M \setminus \overline{\Lambda_1}} \sigma'(0) \langle \nabla f, Y \rangle + \langle \nabla f, X \rangle \\ &\quad + \sigma'(0) f \operatorname{div}^M Y + f \operatorname{div}^M X d\mathcal{H}^1 \\ &\quad + \int_{\overline{\Lambda_1}} f'_+(\cdot, X) + f \operatorname{div}^M X d\mathcal{H}^1 \\ &= \int_M f'_+(\cdot, X) + f \operatorname{div}^M X d\mathcal{H}^1 \\ &\quad + \sigma'(0) \int_M f'_+(\cdot, Y) + f \operatorname{div}^M Y d\mathcal{H}^1. \end{aligned} \tag{6.3}$$

The identity then follows upon inserting the expression for  $\sigma'(0)$  above with  $\lambda = -\int_M f'_+(\cdot, Y) + f \operatorname{div}^M Y d\mathcal{H}^1$ . The claim follows for  $X \in C_c^1(\mathbb{R}^2, \mathbb{R}^2)$  by a density argument.  $\square$

**Theorem 6.5** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Given  $v > 0$  let  $E$  be a minimiser of (1.2). Assume that  $E$  is a bounded open set in  $\mathbb{R}^2$  with  $C^{1,1}$  boundary  $M$  and suppose that  $E \setminus \{0\} = E^{sc}$ . Suppose that  $M \setminus \overline{\Lambda_1} \neq \emptyset$ . Then there exists  $\lambda \in \mathbb{R}$  such that*

- (i)  $k + \rho \sin \sigma + \lambda = 0$   $\mathcal{H}^1$ -a.e. on  $M \setminus \overline{\Lambda_1}$ ;
- (ii)  $\rho_- - \lambda \leq k \leq \rho_+ - \lambda$  on  $\Lambda_1^+$ ;
- (iii)  $-\rho_+ - \lambda \leq k \leq -\rho_- - \lambda$  on  $\Lambda_1^-$ .

The expression  $k + \rho \sin \sigma$  is called the generalised (mean) curvature of  $M$ .

*Proof (i)* Let  $x \in M$  and  $r > 0$  such that  $M \cap B(x, r) \subset M \setminus \overline{\Lambda_1}$ . Choose  $X \in C_c^1(\mathbb{R}^2, \mathbb{R}^2)$  with  $\text{supp}[X] \subset B(x, r)$ . We know from Lemma 6.3 that  $f$  is differentiable  $\mathcal{H}^1$ -a.e. on  $\text{supp}[X]$ . Let  $\lambda$  be as in Proposition 6.4. Replacing  $X$  by  $-X$  we deduce from Proposition 6.4 that

$$0 = \int_M \left\{ \langle \nabla f, X \rangle + f \operatorname{div}^M X - \lambda f \langle n, X \rangle \right\} d\mathcal{H}^1.$$

The divergence theorem on manifolds (cf. [1] Theorem 7.34) holds also for  $C^{1,1}$  manifolds. So

$$\begin{aligned} \int_M \langle \nabla f, X \rangle + f \operatorname{div}^M X d\mathcal{H}^1 &= \int_M \partial_n f \langle n, X \rangle + \langle \nabla^M f, X \rangle + f \operatorname{div}^M X d\mathcal{H}^1 \\ &= \int_M \partial_n f \langle n, X \rangle + \operatorname{div}^M(fX) d\mathcal{H}^1 \\ &= \int_M \partial_n f \langle n, X \rangle - Hf \langle n, X \rangle d\mathcal{H}^1 \\ &= \int_M fu \{ \partial_n \log f - H \} d\mathcal{H}^1 \end{aligned}$$

where  $u = \langle n, X \rangle$ . Combining this with the equality above we see that

$$\int_M uf \{ \partial_n \log f - H - \lambda \} d\mathcal{H}^1 = 0$$

for all  $X \in C_c^1(\mathbb{R}^2, \mathbb{R}^2)$ . This leads to the result.

(ii) Let  $x \in M$  and  $r > 0$  such that  $M \cap B(x, r) \subset \Lambda_1^+$ . Let  $\phi \in C^1(\mathbb{S}_r^1)$  with support in  $\mathbb{S}_r^1 \cap B(x, r)$ . We can construct  $X \in C_c^1(\mathbb{R}^2, \mathbb{R}^2)$  with the property that  $X = \phi n$  on  $M \cap B(x, r)$ . By Lemma 2.4,

$$f'_+(\cdot, X) = fh'_+(|x|, \operatorname{sgn}\langle x, X \rangle)|\langle n, X \rangle| = fh'_+(|x|, \operatorname{sgn}\phi(x, n))|\phi|$$

on  $\Lambda_1$ . Let us assume that  $\phi \geq 0$ . As  $\langle \cdot, n \rangle > 0$  on  $\Lambda_1^+$  we have that  $f'_+(\cdot, X) = f\phi h'_+(|x|, +1) = f\phi\rho_+$  so by Proposition 6.4,

$$\begin{aligned} 0 &\leq \int_M \left\{ f'_+(\cdot, X) + f \operatorname{div}^M X - \lambda f \langle n, X \rangle \right\} d\mathcal{H}^1 \\ &= \int_M f\phi \{ \rho_+ - k - \lambda \} d\mathcal{H}^1. \end{aligned}$$

We conclude that  $\rho_+ - k - \lambda \geq 0$  on  $M \cap B(x, r)$ . Now assume that  $\phi \leq 0$ . Then  $f'_+(\cdot, X) = -f\phi h'_+(|x|, -1) = f\phi\rho_-$  so

$$0 \leq \int_M f\phi \{ \rho_- - k - \lambda \} d\mathcal{H}^1$$

and hence  $\rho_- - k - \lambda \leq 0$  on  $M \cap B(x, r)$ . This shows (ii).

(iii) The argument is similar. Assume in the first instance that  $\phi \geq 0$ . Then  $f'_+(\cdot, X) = f\phi h'_+(|x|, -1) = -f\phi\rho_-$  so

$$0 \leq \int_M f\phi \{ -\rho_- - k - \lambda \} d\mathcal{H}^1.$$

We conclude that  $-\rho_- - k - \lambda \geq 0$  on  $M \cap B(x, r)$ . Next suppose that  $\phi \leq 0$ . Then  $f'_+(\cdot, X) = -f\phi h'_+(|x|, +1) = -f\phi\rho_+$  so

$$0 \leq \int_M f\phi \{ -\rho_+ - k - \lambda \} d\mathcal{H}^1$$

and  $-\rho_+ - k - \lambda \leq 0$  on  $M \cap B(x, r)$ . □

Let  $E$  be an open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$  and assume that  $E \setminus \{0\} = E^{sc}$  and that  $\Omega$  is as in (5.2). Bearing in mind Lemma 5.4 we may define

$$\theta_2 : \Omega \rightarrow (0, \pi); \tau \mapsto L(\tau)/2\tau; \tag{6.4}$$

$$\gamma : \Omega \rightarrow M; \tau \mapsto (\tau \cos \theta_2(\tau), \tau \sin \theta_2(\tau)). \tag{6.5}$$

The function

$$u : \Omega \rightarrow [-1, 1]; \tau \mapsto \sin(\sigma(\gamma(\tau))). \tag{6.6}$$

plays a key role.

**Theorem 6.6** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Given  $v > 0$  let  $E$  be a bounded minimiser of (1.2). Assume that  $E$  is open with  $C^{1,1}$  boundary  $M$  and that  $E \setminus \{0\} = E^{sc}$ . Suppose that  $M \setminus \overline{\Delta_1} \neq \emptyset$  and let  $\lambda$  be as in Theorem 6.5. Then  $u \in C^{0,1}(\Omega)$  and*

$$u' + (1/\tau + \rho)u + \lambda = 0$$

a.e. on  $\Omega$ .

*Proof* Let  $\tau \in \Omega$  and  $x$  a point in the open upper half-plane such that  $x \in M_\tau$ . There exists a  $C^{1,1}$  parametrisation  $\gamma_1 : I \rightarrow M$  of  $M$  in a neighbourhood of  $x$  with  $\gamma_1(0) = x$  as above. Put  $u_1 := \sin \sigma_1$  on  $I$ . By shrinking the open interval  $I$  if necessary we may assume that  $r_1 : I \rightarrow r_1(I)$  is a diffeomorphism and that  $r_1(I) \subset\subset \Omega$ . Note that  $\gamma = \gamma_1 \circ r_1^{-1}$  and  $u = u_1 \circ r_1^{-1}$  on  $r_1(I)$ . It follows that  $u \in C^{0,1}(\Omega)$ . By (2.9),

$$u' = \frac{\dot{u}_1}{\dot{r}_1} \circ r_1^{-1} = \dot{\sigma}_1 \circ r_1^{-1}$$

a.e. on  $r_1(I)$ . As  $\dot{\alpha}_1 = k_1$  a.e. on  $I$  and using the identity (2.10) we see that  $\dot{\sigma}_1 = \dot{\alpha}_1 - \dot{\theta}_1 = k_1 - (1/r_1) \sin \sigma_1$  a.e. on  $I$ . Thus,

$$u' = k - (1/\tau) \sin(\sigma \circ \gamma) = k - (1/\tau)u$$

a.e. on  $r_1(I)$ . By Theorem 6.5 there exists  $\lambda \in \mathbb{R}$  such that  $k + \rho \sin \sigma + \lambda = 0$   $\mathcal{H}^1$ -a.e. on  $M$ . So

$$u' = -\rho(\tau)u - \lambda - (1/\tau)u = -(1/\tau + \rho(\tau))u - \lambda$$

a.e. on  $r_1(I)$ . The result follows.  $\square$

**Lemma 6.7** *Suppose that  $E$  is a bounded open set in  $\mathbb{R}^2$  with  $C^1$  boundary  $M$  and that  $E \setminus \{0\} = E^{sc}$ . Then*

- (i)  $\theta_2 \in C^1(\Omega)$ ;
- (ii)  $\theta'_2 = -\frac{1}{\tau} \frac{u}{\sqrt{1-u^2}}$  on  $\Omega$ .

*Proof* Let  $\tau \in \Omega$  and  $x$  a point in the open upper half-plane such that  $x \in M_\tau$ . There exists a  $C^1$  parametrisation  $\gamma_1 : I \rightarrow M$  of  $M$  in a neighbourhood of  $x$  with  $\gamma_1(0) = x$  as above. By shrinking the open interval  $I$  if necessary we may assume that  $r_1 : I \rightarrow r_1(I)$  is a diffeomorphism and that  $r_1(I) \subset \subset \Omega$ . It then holds that

$$\theta_2 = \theta_1 \circ r_1^{-1} \text{ and } \sigma \circ \gamma = \sigma_1 \circ r_1^{-1}$$

on  $r_1(I)$  by choosing an appropriate branch of  $\theta_1$ . It follows that  $\theta_2 \in C^1(\Omega)$ . By the chain-rule, (2.10) and (2.9),

$$\begin{aligned} \theta'_2 &= \frac{\dot{\theta}_1}{\dot{r}_1} \circ r_1^{-1} = \left( \frac{1}{r_1} \tan \sigma_1 \right) \circ r_1^{-1} \\ &= (1/\tau) \tan(\sigma \circ \gamma) \end{aligned}$$

on  $r_1(I)$ . By Lemma 5.4,  $\cos(\sigma \circ \gamma) = -\sqrt{1-u^2}$  on  $\Omega$ . This entails (ii).  $\square$

## 7 Convexity

**Lemma 7.1** *Let  $E$  be a bounded open set in  $\mathbb{R}^2$  with  $C^{1,1}$  boundary  $M$  and assume that  $E \setminus \{0\} = E^{sc}$ . Put  $d := \sup\{|x| : x \in M\} > 0$  and  $b := (d, 0)$ . Let  $\gamma_1 : I \rightarrow M$  be a  $C^{1,1}$  parametrisation of  $M$  near  $b$  with  $\gamma_1(0) = b$ . Then*

$$\lim_{\delta \downarrow 0} \left\{ \text{ess sup}_{[-\delta, \delta]} k_1 \right\} \geq 1/d.$$

*Proof* For  $s \in I$ ,

$$\gamma_1(s) = de_1 + se_2 + \int_0^s \left\{ \dot{\gamma}_1(u) - \dot{\gamma}_1(0) \right\} du$$

and

$$\dot{\gamma}_1(u) - \dot{\gamma}_1(0) = \int_0^u k_1 n_1 dv$$

by (2.6). By the Fubini–Tonelli Theorem,

$$\gamma_1(s) = de_1 + se_2 + \int_0^s (s - u)k_1(u)n_1(u) du = de_1 + se_2 + R(s)$$

for  $s \in I$ . Assume for a contradiction that

$$\lim_{\delta \downarrow 0} \left\{ \text{ess sup}_{[-\delta, \delta]} k_1 \right\} < l < 1/d$$

for some  $l \in \mathbb{R}$ . Then we can find  $\delta > 0$  such that  $k_1 < l$  a.e. on  $[-\delta, \delta]$ . So

$$\langle R(s), e_1 \rangle = \int_0^s (s - u)k_1(u)\langle n_1(u), e_1 \rangle du > -(1/2)s^2l(1 + o(1))$$

as  $s \downarrow 0$  and

$$\begin{aligned} r_1(s)^2 - d^2 &= 2d\langle R(s), e_1 \rangle + s^2 + o(s^2) \\ &> -dls^2(1 + o(1)) + s^2 + o(s^2) \end{aligned}$$

as  $s \downarrow 0$ . Alternatively,

$$\frac{r_1(s)^2 - d^2}{s^2} > 1 - dl + o(1).$$

As  $1 - dl > 0$  we can find  $s \in I$  with  $r_1(s) > d$ , contradicting the definition of  $d$ .  $\square$

**Lemma 7.2** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Given  $v > 0$  let  $E$  be a bounded minimiser of (1.2). Assume that  $E$  is open with  $C^{1,1}$  boundary  $M$  and that  $E \setminus \{0\} = E^{sc}$ . Suppose that  $M \setminus \overline{\Lambda_1} \neq \emptyset$ . Then  $\lambda \leq -1/d - \rho_-(d) < 0$  with  $\lambda$  as in Theorem 6.5.*

*Proof* We write  $M$  as the disjoint union  $M = (M \setminus \overline{\Lambda_1}) \cup \overline{\Lambda_1}$ . Let  $b$  be as above. Suppose that  $b \in \overline{\Lambda_1}$ . Then  $b \in \Lambda_1$ ; in fact,  $b \in \Lambda_1^-$ . By Theorem 6.5,  $\lambda \leq -\rho_- - k$  at  $b$ . By Lemma 7.1,  $\lambda \leq -1/d - \rho_-(d)$  upon considering an appropriate sequence in  $M$  converging to  $b$ . Now suppose that  $b$  lies in the open set  $M \setminus \overline{\Lambda_1}$  in  $M$ . Let  $\gamma_1 : I \rightarrow M$  be a  $C^{1,1}$  parametrisation of  $M$  near  $b$  with  $\gamma_1(I) \subset M \setminus \overline{\Lambda_1}$ . By Theorem 6.5,  $k_1 + \rho(r_1) \sin \sigma_1 + \lambda = 0$  a.e. on  $I$ . Now  $\sin \sigma_1(s) \rightarrow 1$  as  $s \rightarrow 0$ . In light of Lemma 7.1,  $1/d + \rho(d^-) + \lambda \leq 0$  and  $\lambda \leq -1/d - \rho_-(d)$ .  $\square$

**Theorem 7.3** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Given  $v > 0$  let  $E$  be a bounded minimiser of (1.2). Assume that  $E$  is open with  $C^{1,1}$  boundary  $M$  and that  $E \setminus \{0\} = E^{sc}$ . Suppose that  $M \setminus \overline{\Lambda_1} \neq \emptyset$ . Then  $E$  is convex.*

*Proof* The proof runs along similar lines as [22] Theorem 6.5. By Theorem 6.5,  $k + \rho \sin \sigma + \lambda = 0$   $\mathcal{H}^1$ -a.e. on  $M \setminus \overline{\Lambda_1}$ . By Lemma 7.2,

$$0 \leq k + \rho_-(d) + \lambda \leq k - 1/d$$

and  $k \geq 1/d$   $\mathcal{H}^1$ -a.e. on  $M \setminus \overline{\Lambda_1}$ . On  $\Lambda_1^+$ ,  $k \geq \rho_- - \lambda \geq \rho_- + \rho_-(d) + 1/d > 0$ ; on the other hand,  $k < 0$  on  $\Lambda_1^+$ . So in fact  $\Lambda_1^+ = \emptyset$ . If  $b \in \Lambda_1^-$  then  $k = 1/d$ . On  $\Lambda_1^- \cap B(0, d)$ ,  $k \geq -\rho_+ - \lambda \geq -\rho_+ + \rho_-(d) + 1/d \geq 1/d$ . Therefore  $k \geq 1/d > 0$   $\mathcal{H}^1$ -a.e. on  $M$ . The set  $E$  is then convex by a modification of [26] Theorem 1.8 and Proposition 1.4. It is sufficient that the function  $f$  (here  $\alpha_1$ ) in the proof of the former theorem is non-decreasing. □

### 8 A reverse Hermite–Hadamard inequality

Let  $0 \leq a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Let  $h$  be a primitive of  $\rho$  on  $[a, b]$  so that  $h \in C^{0,1}([a, b])$  and introduce the functions

$$f : [a, b] \rightarrow \mathbb{R}; x \mapsto e^{h(x)}; \tag{8.1}$$

$$g : [a, b] \rightarrow \mathbb{R}; x \mapsto xf(x). \tag{8.2}$$

Then

$$g' = (1/x + \rho)g = f + g\rho \tag{8.3}$$

a.e. on  $(a, b)$ . Define

$$m = m(\rho, a, b) := \frac{g(b) - g(a)}{\int_a^b g dt}. \tag{8.4}$$

If  $\rho$  takes the constant value  $\mathbb{R} \ni \lambda \geq 0$  on  $[a, b]$  we use the notation  $m(\lambda, a, b)$  and we write  $m_0 = m(0, a, b)$ . A computation gives

$$m_0 = m(0, a, b) = A(a, b)^{-1} \tag{8.5}$$

where  $A(a, b) := (a + b)/2$  stands for the arithmetic mean of  $a$  and  $b$ .

**Lemma 8.1** *Let  $0 \leq a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Then  $m_0 \leq m$ .*

*Proof* Note that  $g$  is convex on  $[a, b]$  as can be seen from (8.3). By the Hermite-Hadamard inequality (cf. [15, 17]),

$$\frac{1}{b-a} \int_a^b g \, dt \leq \frac{g(a) + g(b)}{2}. \tag{8.6}$$

The inequality  $(b-a)(g(a) + g(b)) \leq (a+b)(g(b) - g(a))$  entails

$$\int_a^b g \, dt \leq \frac{a+b}{2}(g(b) - g(a))$$

and the result follows on rearrangement. □

**Lemma 8.2** *Let  $0 \leq a < b < +\infty$  and  $\lambda > 0$ . Then  $m(\lambda, a, b) < \lambda + A(a, b)^{-1}$ .*

*Proof* First suppose that  $\lambda = 1$  and take  $h : [a, b] \rightarrow \mathbb{R}; t \mapsto t$ . In this case,

$$\int_a^b g \, dt = \int_a^b t e^t \, dt = (b-1)e^b - (a-1)e^a$$

and

$$m(1, a, b) = \frac{be^b - ae^a}{(b-1)e^b - (a-1)e^a}.$$

The inequality in the statement is equivalent to

$$(a+b)(be^b - ae^a) < ((b-1)e^b - (a-1)e^a)(2+a+b)$$

which in turn is equivalent to the statement  $\tanh[(b-a)/2] < (b-a)/2$  which holds for any  $b > a$ .

For  $\lambda > 0$  take  $h : [a, b] \rightarrow \mathbb{R}; t \mapsto \lambda t$ . Substitution gives

$$\int_a^b g \, dt = (1/\lambda)^2 [(\lambda b - 1)e^{\lambda b} - (\lambda a - 1)e^{\lambda a}] \text{ and}$$

$$g(b) - g(a) = (1/\lambda)[\lambda b e^{\lambda b} - \lambda a e^{\lambda a}]$$

so from above

$$m(\lambda, a, b) = \lambda m(1, \lambda a, \lambda b) < \lambda \left\{ 1 + A(\lambda a, \lambda b)^{-1} \right\} = \lambda + A(a, b)^{-1}.$$

□

**Theorem 8.3** *Let  $0 \leq a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Then*

(i)  $m(\rho, a, b) \leq \rho(b-) + A(a, b)^{-1}$ ;



(ii) equality holds if and only if  $\rho \equiv 0$  on  $[a, b]$ .

*Proof* (i) Define  $h := \int_a^\cdot \rho \, d\tau$  on  $[a, b]$  so that  $h' = \rho$  a.e. on  $(a, b)$ . Define  $h_1 : [a, b] \rightarrow \mathbb{R}; t \mapsto h(b) - \rho(b-)(b-t)$ . Then  $h_1(b) = h(b)$ ,  $h_1' = \rho(b-) \geq \rho = h'$  a.e. on  $(a, b)$  and hence  $h \geq h_1$  on  $[a, b]$ . We derive

$$\int_a^b g \, dt = \int_a^b t e^{h(t)} \, dt \geq \int_a^b t e^{h_1(t)} \, dt = \int_a^b g_1 \, dt$$

and

$$\begin{aligned} g(b) - g(a) &= b e^{h(b)} - a e^{h(a)} = b e^{h_1(b)} - a e^{h(a)} \\ &\leq b e^{h_1(b)} - a e^{h_1(a)} = g_1(b) - g_1(a) \end{aligned}$$

with obvious notation. This entails that  $m(\rho, a, b) \leq m(\rho(b-), a, b)$  and the result follows with the help of Lemma 8.2.

(ii) Suppose that  $\rho \not\equiv 0$  on  $[a, b]$ . If  $\rho$  is constant on  $[a, b]$  the assertion follows from Lemma 8.2. Assume then that  $\rho$  is not constant on  $[a, b]$ . Then  $h \not\equiv h_1$  on  $[a, b]$  in the above notation and  $\int_a^b t e^{h(t)} \, dt > \int_a^b t e^{h_1(t)} \, dt$  which entails strict inequality in (i).  $\square$

With the above notation define

$$\hat{m} = \hat{m}(\rho, a, b) := \frac{g(a) + g(b)}{\int_a^b g \, dt}. \quad (8.7)$$

A computation gives

$$\hat{m}_0 := \hat{m}(0, a, b) = \frac{2}{b-a}. \quad (8.8)$$

**Lemma 8.4** *Let  $0 \leq a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Then  $\hat{m} \geq \hat{m}_0$ .*

*Proof* This follows by the Hermite-Hadamard inequality (8.6).  $\square$

We prove a reverse Hermite-Hadamard inequality.

**Theorem 8.5** *Let  $0 \leq a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Then*

- (i)  $(b-a)\hat{m}(\rho, a, b) \leq 2 + a\rho(a+) + b\rho(b-)$ ;
- (ii) equality holds if and only if  $\rho \equiv 0$  on  $[a, b]$ .

This last inequality can be written in the form

$$\frac{g(a) + g(b)}{2 + a\rho(a+) + b\rho(b-)} \leq \frac{1}{b-a} \int_a^b g \, dt;$$

comparing with (8.6) justifies naming this a reverse Hermite-Hadamard inequality.

*Proof (i)* We assume in the first instance that  $\rho \in C^1((a, b))$ . We prove the above result in the form

$$\int_a^b g \, dt \geq (b - a) \frac{g(a) + g(b)}{2 + a\rho(a) + b\rho(b)}. \tag{8.9}$$

Put

$$w := \frac{(t - a)(g(a) + g)}{2 + a\rho(a) + t\rho}$$

for  $t \in [a, b]$  so that

$$\int_a^b w' \, dt = (b - a) \frac{g(a) + g(b)}{2 + a\rho(a) + b\rho(b)}.$$

Then using (8.3),

$$\begin{aligned} w' &= \frac{(g(a) + g + (t - a)g')(2 + a\rho(a) + t\rho) - (t - a)(g(a) + g)(\rho + t\rho')}{(2 + a\rho(a) + t\rho)^2} \\ &= \frac{(g(a) - ag' + (2 + t\rho)g)(2 + a\rho(a) + t\rho) - (t - a)(g(a) + g)(\rho + t\rho')}{(2 + a\rho(a) + t\rho)^2} \\ &= \frac{(2 + t\rho)(2 + a\rho(a) + t\rho)}{(2 + a\rho(a) + t\rho)^2} g \\ &\quad + \frac{(g(a) - ag')(2 + a\rho(a) + t\rho) - (t - a)(g(a) + g)(\rho + t\rho')}{(2 + a\rho(a) + t\rho)^2} \\ &\leq g - \frac{2g(a)}{(2 + a\rho(a) + b\rho(b))^2} (t - a)\rho \\ &\leq g \end{aligned} \tag{8.10}$$

on  $(a, b)$  as

$$g(a) - ag' = a(\mathfrak{f}(a) - (1/t + \rho)g) = a(\mathfrak{f}(a) - \mathfrak{f} - \rho g) \leq 0.$$

An integration over  $[a, b]$  gives the result.

Let us now assume that  $\rho \geq 0$  is a non-decreasing bounded function on  $[a, b]$ . Extend  $\rho$  to  $\mathbb{R}$  via

$$\tilde{\rho}(t) := \begin{cases} \rho(a+) & \text{for } t \in (-\infty, a]; \\ \rho(t) & \text{for } t \in (a, b]; \\ \rho(b-) & \text{for } t \in (b, +\infty); \end{cases}$$

for  $t \in \mathbb{R}$ . Let  $(\psi_\varepsilon)_{\varepsilon>0}$  be a family of mollifiers (see e.g. [1] 2.1) and set  $\tilde{\rho}_\varepsilon := \tilde{\rho} \star \psi_\varepsilon$  on  $\mathbb{R}$  for each  $\varepsilon > 0$ . Then  $\tilde{\rho}_\varepsilon \in C^\infty(\mathbb{R})$  and is non-decreasing on  $\mathbb{R}$  for each  $\varepsilon > 0$ . Put  $\rho_\varepsilon := \tilde{\rho}_\varepsilon|_{[a,b]}$  for each  $\varepsilon > 0$ . Then  $(\rho_\varepsilon)_{\varepsilon>0}$  converges to  $\rho$  in  $L^1((a, b))$  by [1]

2.1 for example. Note that  $h_\varepsilon := \int_a^\cdot \rho_\varepsilon dt \rightarrow h$  pointwise on  $[a, b]$  as  $\varepsilon \downarrow 0$  and that  $(h_\varepsilon)$  is uniformly bounded on  $[a, b]$ . Moreover,  $\rho_\varepsilon(a) \rightarrow \rho(a+)$  and  $\rho_\varepsilon(b) \rightarrow \rho(b-)$  as  $\varepsilon \downarrow 0$ . By the above result,

$$(b - a)\hat{m}(\rho_\varepsilon, a, b) \leq 2 + a\rho_\varepsilon(a) + b\rho_\varepsilon(b)$$

for each  $\varepsilon > 0$ . The inequality follows on taking the limit  $\varepsilon \downarrow 0$  with the help of the dominated convergence theorem.

(ii) We now consider the equality case. We claim that

$$(b - a) \frac{g(a) + g(b)}{2 + a\rho(a+) + b\rho(b-)} \leq \int_a^b g dt - \frac{2g(a)}{(2 + a\rho(a+) + b\rho(b-))^2} \int_a^b (t - a)\rho dt; \tag{8.11}$$

this entails the equality condition in (ii). First suppose that  $\rho \in C^1((a, b))$ . In this case the inequality in (8.10) implies (8.11) upon integration. Now suppose that  $\rho \geq 0$  is a non-decreasing bounded function on  $[a, b]$ . Then (8.11) holds with  $\rho_\varepsilon$  in place of  $\rho$  for each  $\varepsilon > 0$ . The inequality for  $\rho$  follows by the dominated convergence theorem. □

### 9 Comparison theorems for first-order differential equations

Let  $\mathcal{L}$  stand for the collection of Lebesgue measurable sets in  $[0, +\infty)$ . Define a measure  $\mu$  on  $([0, +\infty), \mathcal{L})$  by  $\mu(dx) := (1/x) dx$ . Let  $0 \leq a < b < +\infty$ . Suppose that  $u : [a, b] \rightarrow \mathbb{R}$  is an  $\mathcal{L}^1$ -measurable function with the property that

$$\mu(\{u > t\}) < +\infty \text{ for each } t > 0. \tag{9.1}$$

The distribution function  $\mu_u : (0, +\infty) \rightarrow [0, +\infty)$  of  $u$  with respect to  $\mu$  is given by

$$\mu_u(t) := \mu(\{u > t\}) \text{ for } t > 0.$$

Note that  $\mu_u$  is right-continuous and non-increasing on  $(0, \infty)$  and  $\mu_u(t) \rightarrow 0$  as  $t \rightarrow \infty$ .

Let  $u$  be a Lipschitz function on  $[a, b]$ . Define

$$Z_1 := \{u \text{ differentiable and } u' = 0\}, Z_2 := \{u \text{ not differentiable}\} \text{ and } Z := Z_1 \cup Z_2.$$

By [1] Lemma 2.96,  $Z \cap \{u = t\} = \emptyset$  for  $\mathcal{L}^1$ -a.e.  $t \in \mathbb{R}$  and hence  $N := u(Z) \subset \mathbb{R}$  is  $\mathcal{L}^1$ -negligible. We make use of the coarea formula ([1] Theorem 2.93 and (2.74)),

$$\int_{[a,b]} \phi |u'| dx = \int_{-\infty}^{\infty} \int_{\{u=t\}} \phi d\mathcal{H}^0 dt \tag{9.2}$$

for any  $\mathcal{L}^1$ -measurable function  $\phi : [a, b] \rightarrow [0, \infty]$ .

**Lemma 9.1** *Let  $0 \leq a < b < +\infty$  and  $u$  a Lipschitz function on  $[a, b]$ . Then*

- (i)  $\mu_u \in \text{BV}_{\text{loc}}((0, +\infty))$ ;
- (ii)  $D\mu_u = -u_{\#}\mu$ ;
- (iii)  $D\mu_u^a = D\mu_u \llcorner ((0, +\infty) \setminus N)$ ;
- (iv)  $D\mu_u^s = D\mu_u \llcorner N$ ;
- (v)  $A := \left\{ t \in (0, +\infty) : \mathcal{L}^1(Z \cap \{u = t\}) > 0 \right\}$  is the set of atoms of  $D\mu_u$  and  $D\mu_u^j = D\mu_u \llcorner A$ ;
- (vi)  $\mu_u$  is differentiable  $\mathcal{L}^1$ -a.e. on  $(0, +\infty)$  with derivative given by

$$\mu'_u(t) = - \int_{\{u=t\} \setminus Z} \frac{1}{|u'|} \frac{d\mathcal{H}^0}{\tau}$$

for  $\mathcal{L}^1$ -a.e.  $t \in (0, +\infty)$ ;

- (vii)  $\text{Ran}(u) \cap [0, +\infty) = \text{supp}(D\mu_u)$ .

The notation above  $D\mu_u^a, D\mu_u^s, D\mu_u^j$  stands for the absolutely continuous resp. singular resp. jump part of the measure  $D\mu_u$  (see [1] 3.2 for example).

*Proof* For any  $\varphi \in C_c^\infty((0, +\infty))$  with  $\text{supp}[\varphi] \subset (\tau, +\infty)$  for some  $\tau > 0$ ,

$$\begin{aligned} \int_0^\infty \mu_u \varphi' dt &= \int_{[a,b]} \varphi \circ u d\mu \\ &= \int_{[a,b]} \chi_{\{u>\tau\}} \varphi \circ u d\mu \end{aligned} \tag{9.3}$$

by Fubini's theorem; so  $\mu_u \in \text{BV}_{\text{loc}}((0, +\infty))$  and  $D\mu_u$  is the push-forward of  $\mu$  under  $u$ ,  $D\mu_u = -u_{\#}\mu$  (cf. [1] 1.70). By (9.2),

$$\begin{aligned} D\mu_u \llcorner ((0, +\infty) \setminus N)(A) &= -\mu(\{u \in A\} \setminus Z) \\ &= - \int_A \int_{\{u=t\} \setminus Z} \frac{1}{|u'|} \frac{d\mathcal{H}^0}{\tau} dt \end{aligned}$$

for any  $\mathcal{L}^1$ -measurable set  $A$  in  $(0, +\infty)$ . In light of the above, we may identify  $D\mu_u^a = D\mu_u \llcorner ((0, +\infty) \setminus N)$  and  $D\mu_u^s = D\mu_u \llcorner N$ . The set of atoms of  $D\mu_u$  is defined by  $A := \{t \in (0, +\infty) : D\mu_u(\{t\}) \neq 0\}$ . For  $t > 0$ ,

$$\begin{aligned} D\mu_u(\{t\}) &= D\mu_u^s(\{t\}) = (D\mu_u \llcorner N)(\{t\}) \\ &= -u_{\#}\mu(N \cap \{t\}) = -\mu(Z \cap \{u = t\}) \end{aligned}$$

and this entails (v). The monotone function  $\mu_u$  is a good representative within its equivalence class and is differentiable  $\mathcal{L}^1$ -a.e. on  $(0, +\infty)$  with derivative given by the density of  $D\mu_u$  with respect to  $\mathcal{L}^1$  by [1] Theorem 3.28. Item (vi) follows from (9.2) and (iii). Item (vii) follows from (ii). □

Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Let  $\eta \in \{\pm 1\}^2$ . We study solutions to the first-order linear ordinary differential equation

$$u' + (1/x + \rho)u + \lambda = 0 \text{ a.e. on } (a, b) \text{ with } u(a) = \eta_1 \text{ and } u(b) = \eta_2 \tag{9.4}$$

where  $u \in C^{0,1}([a, b])$  and  $\lambda \in \mathbb{R}$ . In case  $\rho \equiv 0$  on  $[a, b]$  we use the notation  $u_0$ .

**Lemma 9.2** *Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Let  $\eta \in \{\pm 1\}^2$ . Then*

- (i) *there exists a solution  $(u, \lambda)$  of (9.4) with  $u \in C^{0,1}([a, b])$  and  $\lambda = \lambda_\eta \in \mathbb{R}$ ;*
- (ii) *the pair  $(u, \lambda)$  in (i) is unique;*
- (iii)  *$\lambda_\eta$  is given by*

$$-\lambda_{(1,1)} = \lambda_{(-1,-1)} = m; \quad \lambda_{(1,-1)} = -\lambda_{(-1,1)} = \hat{m};$$

- (iv) *if  $\eta = (1, 1)$  or  $\eta = (-1, -1)$  then  $u$  is uniformly bounded away from zero on  $[a, b]$ .*

*Proof (i)* For  $\eta = (1, 1)$  define  $u : [a, b] \rightarrow \mathbb{R}$  by

$$u(t) := \frac{m \int_a^t g \, ds + g(a)}{g(t)} \text{ for } t \in [a, b] \tag{9.5}$$

with  $m$  as in (8.4). Then  $u \in C^{0,1}([a, b])$  and satisfies (9.4) with  $\lambda = -m$ . For  $\eta = (1, -1)$  set  $u = (-\hat{m} \int_a^t g \, ds + g(a))/g$  with  $\lambda = \hat{m}$ . The cases  $\eta = (-1, -1)$  and  $\eta = (-1, 1)$  can be dealt with using linearity. (ii) We consider the case  $\eta = (1, 1)$ . Suppose that  $(u_1, \lambda_1)$  resp.  $(u_2, \lambda_2)$  solve (9.4). By linearity  $u := u_1 - u_2$  solves

$$u' + (1/x + \rho)u + \lambda = 0 \text{ a.e. on } (a, b) \text{ with } u(a) = u(b) = 0$$

where  $\lambda = \lambda_1 - \lambda_2$ . An integration gives that  $u = (-\lambda \int_a^t g \, ds + c)/g$  for some constant  $c \in \mathbb{R}$  and the boundary conditions entail that  $\lambda = c = 0$ . The other cases are similar. (iii) follows as in (i). (iv) If  $\eta = (1, 1)$  then  $u > 0$  on  $[a, b]$  from (9.5) as  $m > 0$ . □

*The boundary condition  $\eta_1 \eta_2 = -1$ .*

**Lemma 9.3** *Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Let  $(u, \lambda)$  solve (9.4) with  $\eta = (1, -1)$ . Then*

- (i) *there exists a unique  $c \in (a, b)$  with  $u(c) = 0$ ;*
- (ii)  *$u' < 0$  a.e. on  $[a, c]$  and  $u$  is strictly decreasing on  $[a, c]$ ;*
- (iii)  *$D\mu_u^s = 0$ .*

*Proof* (i) We first observe that  $u' \leq -\hat{m} < 0$  a.e. on  $\{u \geq 0\}$  in view of (9.4). Suppose  $u(c_1) = u(c_2) = 0$  for some  $c_1, c_2 \in (a, b)$  with  $c_1 < c_2$ . We may assume that  $u \geq 0$  on  $[c_1, c_2]$ . This contradicts the above observation. Item (ii) is plain. For any  $\mathcal{L}^1$ -measurable set  $B$  in  $(0, +\infty)$ ,  $D\mu_u^s(B) = \mu(\{u \in B\} \cap Z) = 0$  using Lemma 9.1 and (ii).  $\square$

**Lemma 9.4** *Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Let  $(u, \lambda)$  solve (9.4) with  $\eta = (1, -1)$ . Assume that*

- (a)  $u$  is differentiable at both  $a$  and  $b$  and that (9.4) holds there;
- (b)  $u'(a) < 0$  and  $u'(b) < 0$ ;
- (c)  $\rho$  is differentiable at  $a$  and  $b$ .

Put  $v := -u$ . Then

- (i)  $\int_{\{v=1\} \setminus Z_v} \frac{1}{|v'|} \frac{d\mathcal{H}^0}{\tau} \geq \int_{\{u=1\} \setminus Z_u} \frac{1}{|u'|} \frac{d\mathcal{H}^0}{\tau}$ ;
- (ii) equality holds if and only if  $\rho \equiv 0$  on  $[a, b]$ .

*Proof* First,  $\{u = 1\} = \{a\}$  by Lemma 9.3. Further  $0 < -au'(a) = 1 + a[\hat{m} + \rho(a)]$  from (9.4). On the other hand  $\{v = 1\} \supset \{b\}$  and  $0 < bv'(b) = -1 + b[\hat{m} - \rho(b)]$ . Thus

$$\begin{aligned} & \int_{\{v=1\} \setminus Z_v} \frac{1}{|v'|} \frac{d\mathcal{H}^0}{\tau} - \int_{\{u=1\} \setminus Z_u} \frac{1}{|u'|} \frac{d\mathcal{H}^0}{\tau} \\ & \geq \frac{1}{-1 + b[\hat{m} - \rho(b)]} - \frac{1}{1 + a[\hat{m} + \rho(a)]}. \end{aligned}$$

By Theorem 8.5,  $0 \leq 2 + (a - b)\hat{m} + a\rho(a) + b\rho(b)$ , noting that  $\rho(a) = \rho(a+)$  in virtue of (c) and similarly at  $b$ . A rearrangement leads to the inequality. The equality assertion follows from Theorem 8.5.  $\square$

**Theorem 9.5** *Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Suppose that  $(u, \lambda)$  solves (9.4) with  $\eta = (1, -1)$  and set  $v := -u$ . Assume that  $u > -1$  on  $[a, b]$ . Then*

- (i)  $-\mu'_v \geq -\mu'_u$  for  $\mathcal{L}^1$ -a.e.  $t \in (0, 1)$ ;
- (ii) if  $\rho \not\equiv 0$  on  $[a, b]$  then there exists  $t_0 \in (0, 1)$  such that  $-\mu'_v > -\mu'_u$  for  $\mathcal{L}^1$ -a.e.  $t \in (t_0, 1)$ ;
- (iii) for  $t \in [-1, 1]$ ,

$$\mu_{u_0}(t) = \log \left\{ \frac{-(b-a)t + \sqrt{(b-a)^2 t^2 + 4ab}}{2a} \right\}$$

and  $\mu_{v_0} = \mu_{u_0}$  on  $[-1, 1]$ ;

in obvious notation.

*Proof* (i) The set

$$Y_u := Z_{2,u} \cup \left( \{u' + (1/x + \rho)u + \lambda \neq 0\} \setminus Z_{2,u} \right) \cup \{\rho \text{ not differentiable}\} \subset [a, b]$$

(in obvious notation) is a null set in  $[a, b]$  and likewise for  $Y_v$ . By [1] Lemma 2.95 and Lemma 2.96,  $\{u = t\} \cap (Y_u \cup Z_{1,u}) = \emptyset$  for a.e.  $t \in (0, 1)$  and likewise for the function  $v$ . Let  $t \in (0, 1)$  and assume that  $\{u = t\} \cap (Y_u \cup Z_{1,u}) = \emptyset$  and  $\{v = t\} \cap (Y_v \cup Z_{1,v}) = \emptyset$ . Put  $c := \max\{u \geq t\}$ . Then  $c \in (a, b)$ ,  $\{u > t\} = [a, c)$  by Lemma 9.3 and  $u$  is differentiable at  $c$  with  $u'(c) < 0$ . Put  $d := \max\{v \leq t\} = \max\{u \geq -t\}$ . As  $u$  is continuous on  $[a, b]$  it holds that  $a < c < d < b$ . Moreover,  $u'(d) < 0$  as  $v(d) = t$  and  $d \notin Z_v$ . Put  $\tilde{u} := u/t$  and  $\tilde{v} := v/t$  on  $[c, d]$ . Then

$$\begin{aligned} \tilde{u}' + (1/\tau + \rho)\tilde{u} + \hat{m}/t &= 0 \text{ a.e. on } (c, d) \text{ and } \tilde{u}(c) = -\tilde{u}(d) = 1; \\ \tilde{v}' + (1/\tau + \rho)\tilde{v} - \hat{m}/t &= 0 \text{ a.e. on } (c, d) \text{ and } -\tilde{v}(c) = \tilde{v}(d) = 1. \end{aligned}$$

By Lemma 9.4,

$$\begin{aligned} \int_{\{v=t\} \setminus Z_v} \frac{1}{|v'|} \frac{d\mathcal{H}^0}{\tau} &\geq \int_{[c,d] \cap \{v=t\} \setminus Z_v} \frac{1}{|v'|} \frac{d\mathcal{H}^0}{\tau} \\ &= (1/t) \int_{[c,d] \cap \{\tilde{v}=1\} \setminus Z_v} \frac{1}{|\tilde{v}'|} \frac{d\mathcal{H}^0}{\tau} \\ &\geq (1/t) \int_{[c,d] \cap \{\tilde{u}=1\} \setminus Z_u} \frac{1}{|\tilde{u}'|} \frac{d\mathcal{H}^0}{\tau} \\ &= \int_{\{u=t\} \setminus Z_u} \frac{1}{|u'|} \frac{d\mathcal{H}^0}{\tau}. \end{aligned}$$

By Lemma 9.1,

$$-\mu'_u(t) = \int_{\{u=t\} \setminus Z_u} \frac{1}{|u'|} \frac{d\mathcal{H}^0}{\tau}$$

for  $\mathcal{L}^1$ -a.e.  $t \in (0, 1)$  and a similar formula holds for  $v$ . The assertion in (i) follows. (ii) Assume that  $\rho \not\equiv 0$  on  $[a, b)$ . Put  $\alpha := \inf\{\rho > 0\} \in [a, b)$ . Note that  $\max\{v \leq t\} \rightarrow b$  as  $t \uparrow 1$  as  $v < 1$  on  $[a, b)$  by assumption. Choose  $t_0 \in (0, 1)$  such that  $\max\{v \leq t_0\} > \alpha$ . Then for  $t > t_0$ ,

$$a < \max\{u \geq t\} < \max\{u \geq -t_0\} = \max\{v \leq t_0\} < \max\{v \leq t\} < d;$$

that is, the interval  $[c, d]$  with  $c, d$  as described above intersects  $(\alpha, b)$ . So for  $\mathcal{L}^1$ -a.e.  $t \in (t_0, 1)$ ,

$$\int_{\{v=t\} \setminus Z_v} \frac{1}{|v'|} \frac{d\mathcal{H}^0}{\tau} > \int_{\{u=t\} \setminus Z_u} \frac{1}{|u'|} \frac{d\mathcal{H}^0}{\tau}.$$

by the equality condition in Lemma 9.4. The conclusion follows from the representation of  $\mu_u$  resp.  $\mu_v$  in Lemma 9.1.

(iii) A direct computation gives

$$u_0(\tau) = \frac{1}{b-a} \left\{ -\tau + \frac{ab}{\tau} \right\}$$

for  $\tau \in [a, b]$ ;  $u_0$  is strictly decreasing on its domain. This leads to the formula in (iii). A similar computation gives

$$\mu_{v_0}(t) = \log \left\{ \frac{2b}{(b-a)t + \sqrt{(b-a)^2 t^2 + 4ab}} \right\}$$

for  $t \in [-1, 1]$ . Rationalising the denominator results in the stated equality. □

**Corollary 9.6** *Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Suppose that  $(u, \lambda)$  solves (9.4) with  $\eta = (1, -1)$  and set  $v := -u$ . Assume that  $u > -1$  on  $[a, b]$ . Then*

- (i)  $\mu_u(t) \leq \mu_v(t)$  for each  $t \in (0, 1)$ ;
- (ii) if  $\rho \not\equiv 0$  on  $[a, b]$  then  $\mu_u(t) < \mu_v(t)$  for each  $t \in (0, 1)$ .

*Proof* (i) By [1] Theorem 3.28 and Lemma 9.3,

$$\begin{aligned} \mu_u(t) &= \mu_u(t) - \mu_u(1) = -D\mu_u((t, 1)) \\ &= -D\mu_u^a((t, 1)) - D\mu_u^s((t, 1)) \\ &= - \int_{(t,1)} \mu'_u ds \end{aligned}$$

for each  $t \in (0, 1)$  as  $\mu_u(1) = 0$ . On the other hand,

$$\begin{aligned} \mu_v(t) &= \mu_v(1) + (\mu_v(t) - \mu_v(1)) = \mu_v(1) - D\mu_v((t, 1)) \\ &= \mu_v(1) - \int_{(t,1)} \mu'_v ds - D\mu_v^s((t, 1)) \end{aligned}$$

for each  $t \in (0, 1)$ . The claim follows from Theorem 9.5 noting that  $D\mu_v^s((t, 1)) \leq 0$  as can be seen from Lemma 9.1. Item (ii) follows from Theorem 9.5 (ii). □

**Corollary 9.7** *Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Suppose that  $(u, \lambda)$  solves (9.4) with  $\eta = (1, -1)$ . Assume that  $u > -1$  on  $[a, b]$ . Let  $\varphi \in C^1((-1, 1))$  be an odd strictly increasing function with  $\varphi \in L^1((-1, 1))$ . Then*

- (i)  $\int_{\{u>0\}} \varphi(u) d\mu < +\infty$ ;
- (ii)  $\int_a^b \varphi(u) d\mu \leq 0$ ;
- (iii) equality holds in (ii) if and only if  $\rho \equiv 0$  on  $[a, b]$ .

*In particular,*

- (iv)  $\int_a^b \frac{u}{\sqrt{1-u^2}} d\mu \leq 0$  with equality if and only if  $\rho \equiv 0$  on  $[a, b]$ .



*Proof* (i) Put  $I := \{1 > u > 0\}$ . The function  $u : I \rightarrow (0, 1)$  is  $C^{0,1}$  and  $u' \leq -\hat{m}$  a.e. on  $I$  by Lemma 9.3. It has  $C^{0,1}$  inverse  $v : (0, 1) \rightarrow I$ ,  $v' = 1/(u' \circ v)$  and  $|v'| \leq 1/\hat{m}$  a.e. on  $(0, 1)$ . By a change of variables,

$$\int_{\{u>0\}} \varphi(u) d\mu = \int_0^1 \varphi(v'/v) dt$$

from which the claim is apparent. (ii) The integral is well-defined because  $\varphi(u)^+ = \varphi(u)\chi_{\{u>0\}} \in L^1((a, b), \mu)$  by (i). By Lemma 9.3 the set  $\{u = 0\}$  consists of a singleton and has  $\mu$ -measure zero. So

$$\begin{aligned} \int_a^b \varphi(u) d\mu &= \int_{\{u>0\}} \varphi(u) d\mu + \int_{\{u<0\}} \varphi(u) d\mu \\ &= \int_{\{u>0\}} \varphi(u) d\mu - \int_{\{v>0\}} \varphi(v) d\mu \end{aligned}$$

where  $v := -u$  as  $\varphi$  is an odd function. We remark that in a similar way to (9.3),

$$\begin{aligned} \int_0^1 \varphi' \mu_u dt &= \int_{\{u>0\}} \{\varphi(u) - \varphi(0)\} \\ d\mu &= \int_{\{u>0\}} \varphi(u) d\mu \end{aligned}$$

using oddness of  $\varphi$  and an analogous formula holds with  $v$  in place of  $u$ . Thus we may write

$$\begin{aligned} \int_a^b \varphi(u) d\mu &= \int_0^1 \varphi' \mu_u dt - \int_0^1 \varphi' \mu_v dt \\ &= \int_0^1 \varphi' \{\mu_u - \mu_v\} dt \leq 0 \end{aligned}$$

by Corollary 9.6 as  $\varphi' > 0$  on  $(0, 1)$ . (iii) Suppose that  $\rho \not\equiv 0$  on  $[a, b)$ . Then strict inequality holds in the above by Corollary 9.6. If  $\rho \equiv 0$  on  $[a, b)$  the equality follows from Theorem 9.5. (iv) follows from (ii) and (iii) with the particular choice  $\varphi : (-1, 1) \rightarrow \mathbb{R}; t \mapsto t/\sqrt{1-t^2}$ .  $\square$

*The boundary condition  $\eta_1\eta_2 = 1$ .* Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . We study solutions of the auxilliary Riccati equation

$$w' + \lambda w^2 = (1/x + \rho)w \text{ a.e. on } (a, b) \text{ with } w(a) = w(b) = 1; \tag{9.6}$$

with  $w \in C^{0,1}([a, b])$  and  $\lambda \in \mathbb{R}$ . If  $\rho \equiv 0$  on  $[a, b]$  then we write  $w_0$  instead of  $w$ . Suppose  $(u, \lambda)$  solves (9.4) with  $\eta = (1, 1)$ . Then  $u > 0$  on  $[a, b]$  by Lemma 9.2 and we may set  $w := 1/u$ . Then  $(w, -\lambda)$  satisfies (9.6).

**Lemma 9.8** *Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Then*

- (i) *there exists a solution  $(w, \lambda)$  of (9.6) with  $w \in C^{0,1}([a, b])$  and  $\lambda \in \mathbb{R}$ ;*
- (ii) *the pair  $(w, \lambda)$  in (i) is unique;*
- (iii)  *$\lambda = m$ .*

*Proof* (i) Define  $w : [a, b] \rightarrow \mathbb{R}$  by

$$w(t) := \frac{g(t)}{m \int_a^t g \, ds + g(a)} \text{ for } t \in [a, b].$$

Then  $w \in C^{0,1}([a, b])$  and  $(w, m)$  satisfies (9.6). (ii) We claim that  $w > 0$  on  $[a, b]$  for any solution  $(w, \lambda)$  of (9.6). For otherwise,  $c := \min\{w = 0\} \in (a, b)$ . Then  $u := 1/w$  on  $[a, c)$  satisfies

$$u' + \left(\frac{1}{\tau} + \rho\right)u - \lambda = 0 \text{ a.e. on } (a, c) \text{ and } u(a) = 1, u(c-) = +\infty.$$

Integrating, we obtain

$$gu - g(a) - \lambda \int_a^{\cdot} g \, dt = 0 \text{ on } [a, c)$$

and this entails the contradiction that  $u(c-) < +\infty$ . We may now use the uniqueness statement in Lemma 9.2. (iii) follows from (ii) and the particular solution given in (i). □

We introduce the mapping

$$\omega : (0, \infty) \times (0, \infty) \rightarrow \mathbb{R}; (t, x) \mapsto -(2/t) \coth(x/2).$$

For  $\xi > 0$ ,

$$|\omega(t, x) - \omega(t, y)| \leq \operatorname{cosech}^2[\xi/2](1/t)|x - y| \tag{9.7}$$

for  $(t, x), (t, y) \in (0, \infty) \times (\xi, \infty)$  and  $\omega$  is locally Lipschitzian in  $x$  on  $(0, \infty) \times (0, \infty)$  in the sense of [16] I.3. Let  $0 < a < b < +\infty$  and set  $\lambda := A/G > 1$ . Here,  $A = A(a, b)$  stands for the arithmetic mean of  $a, b$  as introduced in the previous Section while  $G = G(a, b) := \sqrt{ab}$  stands for their geometric mean. We refer to the initial value problem

$$z' = \omega(t, z) \text{ on } (0, \lambda) \text{ and } z(1) = \mu((a, b)). \tag{9.8}$$

Define

$$z_0 : (0, \lambda) \rightarrow \mathbb{R}; t \mapsto 2 \log \left\{ \frac{\lambda + \sqrt{\lambda^2 - t^2}}{t} \right\}.$$

**Lemma 9.9** Let  $0 < a < b < +\infty$ . Then

- (i)  $w_0(\tau) = \frac{2A\tau}{G^2 + \tau^2}$  for  $\tau \in [a, b]$ ;
- (ii)  $\|w_0\|_\infty = \lambda$ ;
- (iii)  $\mu_{w_0} = z_0$  on  $[1, \lambda]$ ;
- (iv)  $z_0$  satisfies (9.8) and this solution is unique;
- (v)  $\int_{\{w_0=1\}} \frac{1}{|w'_0|} \frac{d\mathcal{H}^0}{\tau} = 2 \coth(\mu((a, b))/2)$ ;
- (vi)  $\int_a^b \frac{1}{\sqrt{w_0^2 - 1}} \frac{dx}{x} = \pi$ .

*Proof* (i) follows as in the proof of Lemma 9.8 with  $g(t) = t$  while (ii) follows by calculus. (iii) follows by solving the quadratic equation  $t\tau^2 - 2A\tau + G^2t = 0$  for  $\tau$  with  $t \in (0, \lambda)$ . Uniqueness in (iv) follows from [16] Theorem 3.1 as  $\omega$  is locally Lipschitzian with respect to  $x$  in  $(0, \infty) \times (0, \infty)$ . For (v) note that  $|aw'_0(a)| = 1 - a/A$  and  $|bw'_0(b)| = b/A - 1$  and

$$2 \coth(\mu((a, b))/2) = 2(a + b)/(b - a).$$

(vi) We may write

$$\begin{aligned} \int_a^b \frac{1}{\sqrt{w_0^2 - 1}} \frac{d\tau}{\tau} &= \int_a^b \frac{ab + \tau^2}{\sqrt{(a + b)^2\tau^2 - (ab + \tau^2)^2}} \frac{d\tau}{\tau} \\ &= \int_a^b \frac{ab + \tau^2}{\sqrt{(\tau^2 - a^2)(b^2 - \tau^2)}} \frac{d\tau}{\tau}. \end{aligned}$$

The substitution  $s = \tau^2$  followed by the Euler substitution (cf. [14] 2.251)

$$\sqrt{(s - a^2)(b^2 - s)} = t(s - a^2)$$

gives

$$\int_a^b \frac{1}{\sqrt{w_0^2 - 1}} \frac{d\tau}{\tau} = \int_0^\infty \frac{1}{1 + t^2} + \frac{ab}{b^2 + a^2t^2} dt = \pi.$$

□

**Lemma 9.10** Let  $0 < a < b < +\infty$ . Then

- (i) for  $y > a$  the function  $x \mapsto \frac{by - ax}{(y - a)(b - x)}$  is strictly increasing on  $(-\infty, b]$ ;
- (ii) the function  $y \mapsto \frac{(b - a)y}{(y - a)(b - y)}$  is strictly increasing on  $[G, b]$ ;
- (iii) for  $x < b$  the function  $y \mapsto \frac{by - ax}{(y - a)(b - x)}$  is strictly decreasing on  $[a, +\infty)$

*Proof* The proof is an exercise in calculus. □

**Lemma 9.11** Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Let  $(w, \lambda)$  solve (9.6). Assume

- (i)  $w$  is differentiable at both  $a$  and  $b$  and that (9.6) holds there;
- (ii)  $w'(a) > 0$  and  $w'(b) < 0$ ;
- (iii)  $w > 1$  on  $(a, b)$ ;
- (iv)  $\rho$  is differentiable at  $a$  and  $b$ .

Then

$$\int_{\{w=1\} \setminus Z_w} \frac{1}{|w'|} \frac{d\mathcal{H}^0}{\tau} \geq 2 \coth(\mu((a, b))/2)$$

with equality if and only if  $\rho \equiv 0$  on  $[a, b]$ .

*Proof* At the end-points  $x = a, b$  the condition (i) entails that  $w' + m - \rho = 1/x = w'_0 + m_0$  so that

$$w' - w'_0 = m_0 - m + \rho \text{ at } x = a, b. \tag{9.9}$$

We consider the four cases

- (a)  $w'(a) \geq w'_0(a)$  and  $w'(b) \geq w'_0(b)$ ;
- (b)  $w'(a) \geq w'_0(a)$  and  $w'(b) \leq w'_0(b)$ ;
- (c)  $w'(a) \leq w'_0(a)$  and  $w'(b) \geq w'_0(b)$ ;
- (d)  $w'(a) \leq w'_0(a)$  and  $w'(b) \leq w'_0(b)$ ;

in turn.

- (a) Condition (a) together with (9.9) means that  $m_0 - m + \rho(a) \geq 0$ ; that is,  $m - \rho(a) \leq m_0$ . By (i) and (ii),  $bm - b\rho(b) - 1 = -bw'(b) > 0$ ; or  $m - \rho(b) > 1/b$ . Therefore,

$$0 < 1/b < m - \rho(b) \leq m - \rho(a) \leq 1/A$$

by (8.5). Put  $x := 1/(m - \rho(b))$  and  $y := 1/(m - \rho(a))$ . Then

$$a < A \leq y \leq x < b.$$

We write

$$\begin{aligned} aw'(a) &= -(m - \rho(a))a + 1 = -(1/y)a + 1 > 0; \\ bw'(b) &= -(m - \rho(b))b + 1 = -(1/x)b + 1 < 0. \end{aligned}$$

Making use of assumption (iii),

$$\begin{aligned} \int_{\{w=1\} \setminus Z_w} \frac{1}{|w'|} \frac{d\mathcal{H}^0}{x} &= \frac{1}{-(1/y)a + 1} - \frac{1}{-(1/x)b + 1} \\ &= \frac{by - ax}{(y - a)(b - x)}. \end{aligned}$$

By Lemma 9.10 (i) then (ii),

$$\int_{\{w=1\}} \frac{1}{|w'|} \frac{d\mathcal{H}^0}{x} \geq \frac{(b-a)y}{(y-a)(b-y)} \geq \frac{(b-a)A}{(A-a)(b-A)}$$

$$= 2 \frac{a+b}{b-a} = 2 \coth(\mu((a, b))/2).$$

If equality holds then  $\rho(a) = \rho(b)$  and  $\rho$  is constant on  $[a, b]$ . By Theorem 8.3 we conclude that  $\rho \equiv 0$  on  $[a, b]$ .

- (b) Condition (b) together with (9.9) entails that  $0 \leq m_0 - m + \rho(a)$  and  $0 \leq -m_0 + m - \rho(b)$  whence  $0 \leq \rho(a) - \rho(b)$  upon adding; so  $\rho$  is constant on the interval  $[a, b]$  by monotonicity. Define  $x$  and  $y$  as above. Then  $x = y$  and  $y \geq A$ . The result now follows in a similar way to case (a).
- (c) In this case,

$$\frac{1}{aw'(a)} - \frac{1}{bw'(b)} \geq \frac{1}{aw'_0(a)} - \frac{1}{bw'_0(b)}$$

$$= 2 \coth(\mu((a, b))/2)$$

by Lemma 9.9. If equality holds then  $w'(b) = w'_0(b)$  so that  $m_0 - m + \rho(b) = 0$  and  $\rho$  vanishes on  $[a, b]$  by Theorem 8.3.

- (d) Condition (d) together with (9.9) means that  $m_0 - m + \rho(b) \leq 0$ ; that is,  $m \geq \rho(b) + m_0$ . On the other hand, by Theorem 8.3,  $m \leq \rho(b) + m_0$ . In consequence,  $m = \rho(b) + m_0$ . It then follows that  $\rho \equiv 0$  on  $[a, b]$  by Theorem 8.3. Now use Lemma 9.9.

□

**Lemma 9.12** *Let  $\phi : (0, +\infty) \rightarrow (0, +\infty)$  be a convex non-increasing function with  $\inf_{(0,+\infty)} \phi > 0$ . Let  $\Lambda$  be an at most countably infinite index set and  $(x_h)_{h \in \Lambda}$  a sequence of points in  $(0, +\infty)$  with  $\sum_{h \in \Lambda} x_h < +\infty$ . Then*

$$\sum_{h \in \Lambda} \phi(x_h) \geq \phi\left(\sum_{h \in \Lambda} x_h\right)$$

and the left-hand side takes the value  $+\infty$  in case  $\Lambda$  is countably infinite and is otherwise finite.

*Proof* Suppose  $0 < x_1 < x_2 < +\infty$ . By convexity  $\phi(x_1) + \phi(x_2) \geq 2\phi(\frac{x_1+x_2}{2}) \geq \phi(x_1 + x_2)$  as  $\phi$  is non-increasing. The result for finite  $\Lambda$  follows by induction. □

**Theorem 9.13** *Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Let  $(w, \lambda)$  solve (9.6). Assume that  $w > 1$  on  $(a, b)$ . Then*

(i) for  $\mathcal{L}^1$ -a.e.  $t \in (1, \|w\|_\infty)$ ,

$$- \mu'_w \geq (2/t) \coth((1/2)\mu_w); \tag{9.10}$$

(ii) if  $\rho \neq 0$  on  $[a, b)$  then there exists  $t_0 \in (1, \|w\|_\infty)$  such that strict inequality holds in (9.10) for  $\mathcal{L}^1$ -a.e.  $t \in (1, t_0)$ .

*Proof* (i) The set

$$Y_w := Z_{2,w} \cup \left( \{w' + mw^2 \neq (1/x + \rho)w\} \setminus Z_{2,w} \right) \cup \{\rho \text{ not differentiable}\} \subset [a, b]$$

is a null set in  $[a, b]$ . By [1] Lemma 2.95 and Lemma 2.96,  $\{w = t\} \cap (Y_w \cap Z_{1,w}) = \emptyset$  for a.e.  $t > 1$ . Let  $t \in (1, \|w\|_\infty)$  and assume that  $\{w = t\} \cap (Y_w \cap Z_{1,w}) = \emptyset$ . We write  $\{w > t\} = \bigcup_{h \in \Lambda} I_h$  where  $\Lambda$  is an at most countably infinite index set and  $(I_h)_{h \in \Lambda}$  are disjoint non-empty well-separated open intervals in  $(a, b)$ . The term well-separated means that for each  $h \in \Lambda$ ,  $\inf_{k \in \Lambda \setminus \{h\}} d(I_h, I_k) > 0$ . This follows from the fact that  $w' \neq 0$  on  $\partial I_h$  for each  $h \in \Lambda$ . Put  $\tilde{w} := w/t$  on  $\{w > t\}$  so

$$\tilde{w}' + (mt)\tilde{w}^2 = (1/x + \rho)\tilde{w} \text{ a.e. on } \{w > t\} \text{ and } \tilde{w} = 1 \text{ on } \{w = t\}.$$

We use the fact that the mapping  $\phi : (0, +\infty) \rightarrow (0, +\infty); t \mapsto \coth t$  satisfies the hypotheses of Lemma 9.12. By Lemmas 9.11 and 9.12,

$$\begin{aligned} (0, +\infty) &\ni \int_{\{w=t\} \setminus Z_w} \frac{1}{|w'|} \frac{d\mathcal{H}^0}{x} = (1/t) \int_{\{\tilde{w}=1\}} \frac{1}{|\tilde{w}'|} \frac{d\mathcal{H}^0}{\tau} \\ &= (1/t) \sum_{h \in \Lambda} \int_{\partial I_h} \frac{1}{|\tilde{w}'|} \frac{d\mathcal{H}^0}{\tau} \\ &\geq (2/t) \sum_{h \in \Lambda} \coth((1/2)\mu(I_h)) \\ &\geq (2/t) \coth\left( (1/2) \sum_{h \in \Lambda} \mu(I_h) \right) \\ &= (2/t) \coth((1/2)\mu(\{w > t\})) \\ &= (2/t) \coth((1/2)\mu_w(t)). \end{aligned}$$

The statement now follows from Lemma 9.1.

(ii) Suppose that  $\rho \neq 0$  on  $[a, b)$ . Put  $\alpha := \min\{\rho > 0\} \in [a, b)$ . Now that  $\{w > t\} \uparrow (a, b)$  as  $t \downarrow 1$  as  $w > 1$  on  $(a, b)$ . Choose  $t_0 \in (1, \|w\|_\infty)$  such that  $\{w > t_0\} \cap (\alpha, b) \neq \emptyset$ . Then for each  $t \in (1, t_0)$  there exists  $h \in \Lambda$  such that  $\rho \neq 0$  on  $I_h$ . The statement then follows by Lemma 9.11.  $\square$

**Lemma 9.14** *Let  $\emptyset \neq S \subset \mathbb{R}$  be bounded and suppose  $S$  has the property that for each  $s \in S$  there exists  $\delta > 0$  such that  $[s, s + \delta) \subset S$ . Then  $S$  is  $\mathcal{L}^1$ -measurable and  $|S| > 0$ .*

*Proof* For each  $s \in S$  put  $t_s := \inf\{t > s : t \notin S\}$ . Then  $s < t_s < +\infty$ ,  $[s, t_s) \subset S$  and  $t_s \notin S$ . Define

$$\mathcal{C} := \left\{ [s, t] : s \in S \text{ and } t \in (s, t_s) \right\}.$$

Then  $\mathcal{C}$  is a Vitali cover of  $S$  (see [6] Chapter 16 for example). By Vitali’s Covering Theorem (cf. [6] Theorem 16.27) there exists an at most countably infinite subset  $\Lambda \subset \mathcal{C}$  consisting of pairwise disjoint intervals such that

$$\left| S \setminus \bigcup_{I \in \Lambda} I \right| = 0.$$

Note that  $I \subset S$  for each  $I \in \Lambda$ . Consequently,  $S = \bigcup_{I \in \Lambda} I \cup N$  where  $N$  is an  $\mathcal{L}^1$ -null set and hence  $S$  is  $\mathcal{L}^1$ -measurable. The positivity assertion is clear.  $\square$

**Theorem 9.15** *Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Let  $(w, \lambda)$  solve (9.6). Assume that  $w > 1$  on  $(a, b)$ . Put  $T := \min\{\|w_0\|_\infty, \|w\|_\infty\} > 1$ . Then*

- (i)  $\mu_w(t) \leq \mu_{w_0}(t)$  for each  $t \in [1, T)$ ;
- (ii)  $\|w\|_\infty \leq \|w_0\|_\infty$ ;
- (iii) if  $\rho \not\equiv 0$  on  $[a, b]$  then there exists  $t_0 \in (1, \|w\|_\infty)$  such that  $\mu_w(t) < \mu_{w_0}(t)$  for each  $t \in (1, t_0)$ .

*Proof* (i) We adapt the proof of [16] Theorem I.6.1. The assumption entails that  $\mu_w(1) = \mu_{w_0}(1) = \mu((a, b))$ . Suppose for a contradiction that  $\mu_w(t) > \mu_{w_0}(t)$  for some  $t \in (1, T)$ .

For  $\varepsilon > 0$  consider the initial value problem

$$z' = \omega(t, z) + \varepsilon \text{ and } z(1) = \mu((a, b)) + \varepsilon \tag{9.11}$$

on  $(0, T)$ . Choose  $\nu \in (0, 1)$  and  $\tau \in (t, T)$ . By [16] Lemma I.3.1 there exists  $\varepsilon_0 > 0$  such that for each  $0 \leq \varepsilon < \varepsilon_0$  (9.11) has a continuously differentiable solution  $z_\varepsilon$  defined on  $[\nu, \tau]$  and this solution is unique by [16] Theorem I.3.1. Moreover, the sequence  $(z_\varepsilon)_{0 < \varepsilon < \varepsilon_0}$  converges uniformly to  $z_0$  on  $[\nu, \tau]$ .

Given  $0 < \varepsilon < \eta < \varepsilon_0$  it holds that  $z_0 \leq z_\varepsilon \leq z_\eta$  on  $[1, \tau]$  by [16] Theorem I.6.1. Note for example that  $z'_0 \leq \omega(\cdot, z_0) + \varepsilon$  on  $(1, \tau)$ . In fact,  $(z_\varepsilon)_{0 < \varepsilon < \varepsilon_0}$  decreases strictly to  $z_0$  on  $(1, \tau)$ . For if, say,  $z_0(s) = z_\varepsilon(s)$  for some  $s \in (1, \tau)$  then  $z'_\varepsilon(s) = \omega(s, z_\varepsilon(s)) + \varepsilon > \omega(s, z_0(s)) = z'_0(s)$  by (9.11); while on the other hand  $z'_\varepsilon(s) \leq z'_0(s)$  by considering the left-derivative at  $s$  and using the fact that  $z_\varepsilon \geq z_0$  on  $[1, \tau]$ . This contradicts the strict inequality.

Choose  $\varepsilon_1 \in (0, \varepsilon_0)$  such that  $z_\varepsilon(t) < \mu_w(t)$  for each  $0 < \varepsilon < \varepsilon_1$ . Now  $\mu_w$  is right-continuous and strictly decreasing as  $\mu_w(t) - \mu_w(s) = -\mu(\{s < w \leq t\}) < 0$  for  $1 \leq s < t < \|w\|_\infty$  by continuity of  $w$ . So the set  $\{z_\varepsilon < \mu_w\} \cap (1, t)$  is open and non-empty in  $(0, +\infty)$  for each  $\varepsilon \in (0, \varepsilon_1)$ . Thus there exists a unique  $s_\varepsilon \in [1, t)$  such that

$$\mu_w > z_\varepsilon \text{ on } (s_\varepsilon, t] \text{ and } \mu_w(s_\varepsilon) = z_\varepsilon(s_\varepsilon)$$

for each  $\varepsilon \in (0, \varepsilon_1)$ . As  $z_\varepsilon(1) > \mu((a, b))$  it holds that each  $s_\varepsilon > 1$ . Note that  $1 < s_\varepsilon < s_\eta$  whenever  $0 < \varepsilon < \eta$  as  $(z_\varepsilon)_{0 < \varepsilon < \varepsilon_0}$  decreases strictly to  $z_0$  as  $\varepsilon \downarrow 0$ .

Define

$$S := \left\{ s_\varepsilon : 0 < \varepsilon < \varepsilon_1 \right\} \subset (1, t).$$

We claim that for each  $s \in S$  there exists  $\delta > 0$  such that  $[s, s + \delta) \subset S$ . This entails that  $S$  is  $\mathcal{L}^1$ -measurable with positive  $\mathcal{L}^1$ -measure by Lemma 9.14.

Suppose  $s = s_\varepsilon \in S$  for some  $\varepsilon \in (0, \varepsilon_1)$  and put  $z := z_\varepsilon(s) = \mu_w(s)$ . Put  $k := \operatorname{cosech}^2(z_0(t)/2)$ . For  $0 \leq \zeta < \eta < \varepsilon_1$  define

$$\Omega_{\zeta, \eta} := \left\{ (u, y) \in \mathbb{R}^2 : u \in (0, t) \text{ and } z_\zeta(u) < y < z_\eta(u) \right\}$$

and note that this is an open set in  $\mathbb{R}^2$ . We remark that for each  $(u, y) \in \Omega_{\zeta, \eta}$  there exists a unique  $v \in (\zeta, \eta)$  such that  $y = z_v(u)$ . Given  $r > 0$  with  $s + r < t$  set

$$Q = Q_r := \left\{ (u, y) \in \mathbb{R}^2 : s \leq u < s + r \text{ and } |y - z| < \|z_\varepsilon - z\|_{C([s, s+r])} \right\}.$$

Choose  $r \in (0, t - s)$  and  $\varepsilon_2 \in (\varepsilon, \varepsilon_1)$  such that

- (a)  $Q_r \subset \Omega_{0, \varepsilon_1}$ ;
- (b)  $\|z_\varepsilon - z\|_{C([s, s+r])} < s\varepsilon/(2k)$ ;
- (c)  $\sup_{\eta \in (\varepsilon, \varepsilon_2)} \|z_\eta - z\|_{C([s, s+r])} \leq \|z_\varepsilon - z\|_{C([s, s+r])}$ ;
- (d)  $z_\eta < \mu_w$  on  $[s + r, t]$  for each  $\eta \in (\varepsilon, \varepsilon_2)$ .

We can find  $\delta \in (0, r)$  such that  $z_\varepsilon < \mu_w < z_{\varepsilon_2}$  on  $(s, s + \delta)$  as  $z_{\varepsilon_2}(s) > z$ ; in other words, the graph of  $\mu_w$  restricted to  $(s, s + \delta)$  is contained in  $\Omega_{\varepsilon, \varepsilon_2}$ .

Let  $u \in (s, s + \delta)$ . Then  $\mu_w(u) = z_\eta(u)$  for some  $\eta \in (\varepsilon, \varepsilon_2)$  as above. We claim that  $u = s_\eta$  so that  $u \in S$ . This implies in turn that  $[s, s + \delta) \subset S$ . Suppose for a contradiction that  $z_\eta \not\leq \mu_w$  on  $(u, t]$ . Then there exists  $v \in (u, t]$  such that  $\mu_w(v) = z_\eta(v)$ . In view of condition (d),  $v \in (u, s + r)$ . By [1] Theorem 3.28 and Theorem 9.13,

$$\begin{aligned} \mu_w(v) - \mu_w(u) &= D\mu_w((u, v)) = D\mu_w^a((u, v)) + D\mu_w^s((u, v)) \\ &\leq D\mu_w^a((u, v)) = \int_u^v \mu'_w \, d\tau \leq \int_u^v \omega(\cdot, \mu_w) \, d\tau. \end{aligned}$$

On the other hand,

$$z_\eta(v) - z_\eta(u) = \int_u^v z'_\eta \, d\tau = \int_u^v \omega(\cdot, z_\eta) \, d\tau + \eta(v - u).$$



We derive that

$$\begin{aligned}\varepsilon(v-u) &\leq \eta(v-u) \leq \int_u^v \left\{ \omega(\cdot, \mu_w) - \omega(\cdot, z_\eta) \right\} d\tau \\ &\leq k \int_u^v |\mu_w - z_\eta| d\mu\end{aligned}$$

using the estimate (9.7). Thus

$$\begin{aligned}\varepsilon &\leq k \frac{1}{v-u} \int_u^v |\mu_w - z_\eta| d\mu \\ &\leq (k/s) \|\mu_w - z_\eta\|_{C([u,v])} \\ &\leq (k/s) \left\{ \|\mu_w - z\|_{C([s,s+r])} + \|z_\eta - z\|_{C([s,s+r])} \right\} \\ &\leq (2k/s) \|z_\varepsilon - z\|_{C([s,s+r])} < \varepsilon\end{aligned}$$

by (b) and (c) giving rise to the desired contradiction.

By Theorem 9.13,  $\mu'_w \leq \omega(\cdot, \mu_w)$  for  $\mathcal{L}^1$ -a.e.  $t \in S$ . Choose  $s \in S$  such that  $\mu_w$  is differentiable at  $s$  and the latter inequality holds at  $s$ . Let  $\varepsilon \in (0, \varepsilon_1)$  such that  $s = s_\varepsilon$ . For any  $u \in (s, t)$ ,

$$\mu_w(u) - \mu_w(s) > z_\varepsilon(u) - z_\varepsilon(s).$$

We deduce that  $\mu'_w(s) \geq z'_\varepsilon(s)$ . But then

$$\mu'_w(s) \geq z'_\varepsilon(s) = \omega(s, z_\varepsilon(s)) + \varepsilon > \omega(s, \mu_w(s)).$$

This strict inequality holds on a set of full measure in  $S$ . This contradicts Theorem 9.13.

(ii) Use the fact that  $\|w\|_\infty = \sup\{t > 0 : \mu_w(t) > 0\}$ .

(iii) Assume that  $\rho \not\equiv 0$  on  $[a, b)$ . Let  $t_0 \in (1, \|w\|_\infty)$  be as in Lemma 9.13. Then for  $t \in (1, t_0)$ ,

$$\begin{aligned}\mu_w(t) - \mu_w(1) &= D\mu_w((1, t]) = D\mu_w^a((1, t]) \\ &\quad + D\mu_w^s((1, t]) \leq D\mu_w^a((1, t]) \\ &= \int_{(1,t]} \mu'_w ds < \int_{(1,t]} \omega(s, \mu_w) ds \\ &\leq \int_{(1,t]} \omega(s, \mu_{w_0}) ds = \mu_{w_0}(t) - \mu_{w_0}(1)\end{aligned}$$

by Theorem 9.13, Lemma 9.9 and the inequality in (i).

□

**Corollary 9.16** *Let  $0 < a < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[a, b]$ . Suppose that  $(w, \lambda)$  solves (9.6). Assume that  $w > 1$  on  $(a, b)$ . Let  $0 \leq \varphi \in C^1((1, +\infty))$  be strictly decreasing with  $\int_a^b \varphi(w_0) d\mu < +\infty$ . Then*

- (i)  $\int_a^b \varphi(w) d\mu \geq \int_a^b \varphi(w_0) d\mu$ ;
- (ii) equality holds in (i) if and only if  $\rho \equiv 0$  on  $[a, b]$ .

*In particular,*

- (iii)  $\int_a^b \frac{1}{\sqrt{w^2-1}} d\mu \geq \pi$  with equality if and only if  $\rho \equiv 0$  on  $[a, b]$ .

*Proof* (i) Let  $\varphi \geq 0$  be a decreasing function on  $(1, +\infty)$  which is piecewise  $C^1$ . Suppose that  $\varphi(1+) < +\infty$ . By Tonelli’s Theorem,

$$\begin{aligned} \int_{[1,+\infty)} \varphi' \mu_w ds &= \int_{[1,+\infty)} \varphi' \left\{ \int_{(a,b)} \chi_{\{w>s\}} d\mu \right\} ds \\ &= \int_{(a,b)} \left\{ \int_{[1,+\infty)} \varphi' \chi_{\{w>s\}} ds \right\} d\mu \\ &= \int_{(a,b)} \left\{ \varphi(w) - \varphi(1) \right\} d\mu \\ &= \int_{(a,b)} \varphi(w) d\mu - \varphi(1)\mu((a, b)) \end{aligned}$$

and a similar identity holds for  $\mu_{w_0}$ . By Theorem 9.15,  $\int_a^b \varphi(w) d\mu \geq \int_a^b \varphi(w_0) d\mu$ . Now suppose that  $0 \leq \varphi \in C^1((1, +\infty))$  is strictly decreasing with  $\int_a^b \varphi(w_0) d\mu < +\infty$ . The inequality holds for the truncated function  $\varphi \wedge n$  for each  $n \in \mathbb{N}$ . An application of the monotone convergence theorem establishes the result for  $\varphi$ .

(ii) Suppose that equality holds in (i). For  $c \in (1, +\infty)$  put  $\varphi_1 := \varphi \vee \varphi(c) - \varphi(c)$  and  $\varphi_2 := \varphi \wedge \varphi(c)$ . By (i) we deduce

$$\int_a^b \varphi_2(w) d\mu = \int_a^b \varphi_2(w_0) d\mu;$$

and hence by the above that

$$\int_{[c,+\infty)} \varphi' \left\{ \mu_w - \mu_{w_0} \right\} ds = 0.$$

This means that  $\mu_w = \mu_{w_0}$  on  $(c, +\infty)$  and hence on  $(1, +\infty)$ . By Theorem 9.15 we conclude that  $\rho \equiv 0$  on  $[a, b]$ . (iii) flows from (i) and (ii) noting that the function  $\varphi : (1, +\infty) \rightarrow \mathbb{R}; t \mapsto 1/\sqrt{t^2 - 1}$  satisfies the integral condition by Lemma 9.9.  $\square$

*The case  $a = 0$ .* Let  $0 < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[0, b]$ . We study solutions to the first-order linear ordinary differential equation

$$u' + (1/x + \rho)u + \lambda = 0 \text{ a.e. on } (0, b) \text{ with } u(0) = 0 \text{ and } u(b) = 1 \tag{9.12}$$

where  $u \in C^{0,1}([0, b])$  and  $\lambda \in \mathbb{R}$ . If  $\rho \equiv 0$  on  $[0, b]$  then we write  $u_0$  instead of  $u$ .

**Lemma 9.17** *Let  $0 < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[0, b]$ . Then*

- (i) *there exists a solution  $(u, \lambda)$  of (9.12) with  $u \in C^{0,1}([0, b])$  and  $\lambda \in \mathbb{R}$ ;*
- (ii)  *$\lambda$  is given by  $\lambda = -g(b)/G(b)$  where  $G := \int_0^b g \, ds$ ;*
- (iii) *the pair  $(u, \lambda)$  in (i) is unique;*
- (iv)  *$u > 0$  on  $(0, b]$ .*

*Proof* (i) The function  $u : [a, b] \rightarrow \mathbb{R}$  given by

$$u = \frac{g(b)}{G(b)} \frac{G}{g} \quad (9.13)$$

on  $[0, b]$  solves (9.12) with  $\lambda$  as in (ii). (iii) Suppose that  $(u_1, \lambda_1)$  resp.  $(u_2, \lambda_2)$  solve (9.12). By linearity  $u := u_1 - u_2$  solves

$$u' + (1/x + \rho)u + \lambda = 0 \text{ a.e. on } (0, b) \text{ with } u(0) = u(b) = 0$$

where  $\lambda = \lambda_1 - \lambda_2$ . An integration gives that  $u = (-\lambda G + c)/g$  for some constant  $c \in \mathbb{R}$  and the boundary conditions entail that  $\lambda = c = 0$ . (iv) follows from the formula (9.13) and unicity.  $\square$

**Lemma 9.18** *Suppose  $-\infty < a < b < +\infty$  and that  $\phi : [a, b] \rightarrow \mathbb{R}$  is convex. Suppose that there exists  $\xi \in (a, b)$  such that*

$$\phi(\xi) = \frac{b - \xi}{b - a} \phi(a) + \frac{\xi - a}{b - a} \phi(b).$$

*Then*

$$\phi(c) = \frac{b - c}{b - a} \phi(a) + \frac{c - a}{b - a} \phi(b)$$

*for each  $c \in [a, b]$ .*

*Proof* Let  $c \in (\xi, b)$ . By monotonicity of chords,

$$\frac{\phi(\xi) - \phi(a)}{\xi - a} \leq \frac{\phi(c) - \phi(\xi)}{c - \xi}$$

so

$$\begin{aligned} \phi(c) &\geq \frac{c - a}{\xi - a} \phi(\xi) - \frac{c - \xi}{\xi - a} \phi(a) \\ &= \frac{c - a}{\xi - a} \left\{ \frac{b - \xi}{b - a} \phi(a) + \frac{\xi - a}{b - a} \phi(b) \right\} - \frac{c - \xi}{\xi - a} \phi(a) \end{aligned}$$

$$= \frac{b - c}{b - a} \phi(a) + \frac{c - a}{b - a} \phi(b)$$

and equality follows. The case  $c \in (a, \xi)$  is similar. □

**Lemma 9.19** *Let  $0 < b < +\infty$  and  $\rho \geq 0$  be a non-decreasing bounded function on  $[0, b]$ . Let  $(u, \lambda)$  satisfy (9.12). Then*

- (i)  $u \geq u_0$  on  $[0, b]$ ;
- (ii) if  $\rho \not\equiv 0$  on  $[0, b)$  then  $u > u_0$  on  $(0, b)$ .

*Proof* (i) The mapping  $G : [0, b] \rightarrow [0, G(b)]$  is a bijection with inverse  $G^{-1}$ . Define  $\eta : [0, G(b)] \rightarrow \mathbb{R}$  via  $\eta := (tg) \circ G^{-1}$ . Then

$$\eta' = \frac{(tg)'}{g} \circ G^{-1} = (2 + t\rho) \circ G^{-1}$$

a.e. on  $(0, G(b))$  so  $\eta'$  is non-decreasing there. This means that  $\eta$  is convex on  $[0, G(b)]$ . In particular,  $\eta(s) \leq [\eta(G(b))/G(b)]s$  for each  $s \in [0, G(b)]$ . For  $t \in [0, b]$  put  $s := G(t)$  to obtain  $tg(t) \leq (bg(b)/G(b))G(t)$ . A rearrangement gives  $u \geq u_0$  on  $[0, b]$  noting that  $u_0 : [0, b] \rightarrow \mathbb{R}; t \mapsto t/b$ . (ii) Assume  $\rho \not\equiv 0$  on  $[0, b)$ . Suppose that  $u(c) = u_0(c)$  for some  $c \in (0, b)$ . Then  $\eta(G(c)) = [\eta(G(b))/G(b)]G(c)$ . By Lemma 9.18,  $\eta' = 0$  on  $(0, G(b))$ . This implies that  $\rho \equiv 0$  on  $[0, b)$ . □

**Lemma 9.20** *Let  $0 < b < +\infty$ . Then  $\int_0^b \frac{u_0}{\sqrt{1-u_0^2}} d\mu = \pi/2$ .*

*Proof* The integral is elementary as  $u_0(t) = t/b$  for  $t \in [0, b]$ . □

### 10 Proof of main results

**Lemma 10.1** *Let  $x \in H$  and  $v$  be a unit vector in  $\mathbb{R}^2$  such that the pair  $\{x, v\}$  forms a positively oriented orthogonal basis for  $\mathbb{R}^2$ . Put  $b := (\tau, 0)$  where  $|x| = \tau$  and  $\gamma := \theta(x) \in (0, \pi)$ . Let  $\alpha \in (0, \pi/2)$  such that*

$$\frac{\langle v, x - b \rangle}{|x - b|} = \cos \alpha.$$

Then

- (i)  $C(x, v, \alpha) \cap H \cap \overline{C}(0, e_1, \gamma) = \emptyset$ ;
- (ii) for any  $y \in C(x, v, \alpha) \cap H \setminus \overline{B}(0, \tau)$  the line segment  $[b, y]$  intersects  $\mathbb{S}_\tau^1$  outside the closed cone  $\overline{C}(0, e_1, \gamma)$ .

We point out that  $C(0, e_1, \gamma)$  is the open cone with vertex 0 and axis  $e_1$  which contains the point  $x$  on its boundary. We note that  $\cos \alpha \in (0, 1)$  because

$$\begin{aligned} \langle v, x - b \rangle &= -\langle v, b \rangle = -\langle (1/\tau)Ox, b \rangle \\ &= -\langle Op, e_1 \rangle = \langle x, O^*e_1 \rangle = \langle x, e_2 \rangle > 0 \end{aligned} \tag{10.1}$$

and if  $|x - b| = \langle v, x - b \rangle$  then  $b = x - \lambda v$  for some  $\lambda \in \mathbb{R}$  and hence  $x_1 = \langle e_1, x \rangle = \tau$  and  $x_2 = 0$ .

*Proof (i)* For  $\omega \in \mathbb{S}^1$  define the open half-space

$$H_\omega := \{y \in \mathbb{R}^2 : \langle y, \omega \rangle > 0\}.$$

We claim that  $C(x, v, \alpha) \subset H_v$ . For given  $y \in C(x, v, \alpha)$ ,

$$\langle y, v \rangle = \langle y - x, v \rangle > |y - x| \cos \alpha > 0.$$

On the other hand, it holds that  $\overline{C}(0, e_1, \gamma) \cap H \subset \overline{H}_{-v}$ . This establishes (i).

(ii) By some trigonometry  $\gamma = 2\alpha$ . Suppose that  $\omega$  is a unit vector in  $C(b, -e_1, \pi/2 - \alpha)$ . Then  $\lambda := \langle \omega, e_1 \rangle < \cos \alpha$  since upon rewriting the membership condition for  $C(b, -e_1, \pi/2 - \alpha)$  we obtain the quadratic inequality

$$\lambda^2 - 2 \cos^2 \alpha \lambda + \cos \gamma > 0.$$

For  $\omega$  a unit vector in  $\overline{C}(0, e_1, \gamma)$  the opposite inequality  $\langle \omega, e_1 \rangle \geq \cos \alpha$  holds. This shows that

$$C(b, -e_1, \pi/2 - \alpha) \cap \overline{C}(0, e_1, \gamma) \cap \mathbb{S}_\tau^1 = \emptyset.$$

The set  $C(x, v, \alpha) \cap H$  is contained in the open convex cone  $C(b, -e_1, \pi/2 - \alpha)$ . Suppose  $y \in C(x, v, \alpha) \cap H \setminus \overline{B}(0, \tau)$ . Then the line segment  $[b, y]$  is contained in  $C(b, -e_1, \pi/2 - \alpha) \cup \{b\}$ . Now the set  $C(b, -e_1, \pi/2 - \alpha) \cap \mathbb{S}_\tau^1$  disconnects  $C(b, -e_1, \pi/2 - \alpha) \cup \{b\}$ . This entails that  $(b, y] \cap C(b, -e_1, \pi/2 - \alpha) \cap \mathbb{S}_\tau^1 \neq \emptyset$ . The foregoing paragraph entails that  $(b, y] \cap \overline{C}(0, e_1, \gamma) \cap \mathbb{S}_\tau^1 = \emptyset$ . This establishes the result.  $\square$

**Lemma 10.2** *Let  $E$  be an open set in  $\mathbb{R}^2$  such that  $M := \partial E$  is a  $C^{1,1}$  hypersurface in  $\mathbb{R}^2$ . Assume that  $E \setminus \{0\} = E^{sc}$ . Suppose*

- (i)  $x \in (M \setminus \{0\}) \cap H$ ;
- (ii)  $\sin(\sigma(x)) = -1$ .

*Then  $E$  is not convex.*

*Proof* Let  $\gamma_1 : I \rightarrow M$  be a  $C^{1,1}$  parametrisation of  $M$  in a neighbourhood of  $x$  with  $\gamma_1(0) = x$  as above. As  $\sin(\sigma(x)) = -1, n(x)$  and hence  $n_1(0)$  point in the direction of  $x$ . Put  $v := -t_1(0) = -t(x)$ . We may write

$$\gamma_1(s) = \gamma_1(0) + st_1(0) + R_1(s) = x - sv + R_1(s)$$

for  $s \in I$  where  $R_1(s) = s \int_0^1 \dot{\gamma}_1(ts) - \dot{\gamma}_1(0) dt$  and we can find a finite positive constant  $K$  such that  $|R_1(s)| \leq Ks^2$  on a symmetric open interval  $I_0$  about 0 with  $I_0 \subset\subset I$ . Then

$$\begin{aligned} \frac{\langle \gamma_1(s) - x, v \rangle}{|\gamma_1(s) - x|} &= \frac{\langle -sv + R_1, v \rangle}{|-sv + R_1|} \\ &= \frac{1 - \langle (R_1/s), v \rangle}{|v - R_1/s|} \rightarrow 1 \end{aligned}$$

as  $s \uparrow 0$ . Let  $\alpha$  be as in Lemma 10.1 with  $x$  and  $v$  as just mentioned. The above estimate entails that  $\gamma_1(s) \in C(x, v, \alpha)$  for small  $s < 0$ . By (2.9) and Lemma 5.4 the function  $r_1$  is non-increasing on  $I$ . In particular,  $r_1(s) \geq r_1(0) = |x| =: \tau$  for  $I \ni s < 0$  and  $\gamma_1(s) \notin B(0, \tau)$ .

Choose  $\delta_1 > 0$  such that  $\gamma_1(s) \in C(x, v, \alpha) \cap H$  for each  $s \in [-\delta_1, 0)$ . Put  $\beta := \inf\{s \in [-\delta_1, 0] : r_1(s) = \tau\}$ . Suppose first that  $\beta \in [-\delta_1, 0)$ . Then  $E$  is not convex (see Lemma 5.2). Now suppose that  $\beta = 0$ . Let  $\gamma$  be as in Lemma 10.1. Then the open circular arc  $\mathbb{S}_\tau^1 \setminus \overline{C}(0, e_1, \gamma)$  does not intersect  $\overline{E}$ : for otherwise,  $M$  intersects  $\mathbb{S}_\tau^1 \setminus \overline{C}(0, e_1, \gamma)$  and  $\beta < 0$  bearing in mind Lemma 5.2. Choose  $s \in [-\delta_1, 0)$ . Then the points  $b$  and  $\gamma_1(s)$  lie in  $\overline{E}$ . But by Lemma 10.1 the line segment  $[b, \gamma_1(s)]$  intersects  $\mathbb{S}_\tau^1$  in  $\mathbb{S}_\tau^1 \setminus \overline{C}(0, e_1, \gamma)$ . Let  $c \in [b, \gamma_1(s)] \cap \mathbb{S}_\tau^1$ . Then  $c \notin \overline{E}$ . This shows that  $\overline{E}$  is not convex. But if  $E$  is convex then  $\overline{E}$  is convex. Therefore  $E$  is not convex.  $\square$

**Theorem 10.3** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Given  $v > 0$  let  $E$  be a bounded minimiser of (1.2). Assume that  $E$  is open,  $M := \partial E$  is a  $C^{1,1}$  hypersurface in  $\mathbb{R}^2$  and  $E \setminus \{0\} = E^{sc}$ . Put*

$$R := \inf\{\rho > 0\} \in [0, +\infty). \tag{10.2}$$

Then  $\Omega \cap (R, +\infty) = \emptyset$  with  $\Omega$  as in (5.2).

*Proof* Suppose that  $\Omega \cap (R, +\infty) \neq \emptyset$ . As  $\Omega$  is open in  $(0, +\infty)$  by Lemma 5.6 we may write  $\Omega$  as a countable union of disjoint open intervals in  $(0, +\infty)$ . By a suitable choice of one of these intervals we may assume that  $\Omega = (a, b)$  for some  $0 \leq a < b < +\infty$  and that  $\Omega \cap (R, +\infty) \neq \emptyset$ . Let us assume for the time being that  $a > 0$ . Note that  $[a, b] \subset \pi(M)$  and  $\cos \sigma$  vanishes on  $M_a \cup M_b$ .

Let  $u : \Omega \rightarrow [-1, 1]$  be as in (6.6). Then  $u$  has a continuous extension to  $[a, b]$  and  $u = \pm 1$  at  $\tau = a, b$ . This may be seen as follows. For  $\tau \in (a, b)$  the set  $M_\tau \cap \overline{H}$  consists of a singleton by Lemma 5.4. The limit  $x := \lim_{\tau \downarrow a} M_\tau \cap \overline{H} \in \mathbb{S}_a^1 \cap \overline{H}$  exists as  $M$  is  $C^1$ . There exists a  $C^{1,1}$  parametrisation  $\gamma_1 : I \rightarrow M$  with  $\gamma_1(0) = x$  as above. By (2.9) and Lemma 5.4,  $r_1$  is decreasing on  $I$ . So  $r_1 > a$  on  $I \cap \{s < 0\}$  for otherwise the  $C^1$  property fails at  $x$ . It follows that  $\gamma_1 = \gamma \circ r_1$  and  $\sigma_1 = \sigma \circ \gamma \circ r_1$  on  $I \cap \{s < 0\}$ . Thus  $\sin(\sigma \circ \gamma) \circ r_1 = \sin \sigma_1$  on  $I \cap \{s < 0\}$ . Now the function  $\sin \sigma_1$  is continuous on  $I$ . So  $u \rightarrow \sin \sigma_1(0) \in \{\pm 1\}$  as  $\tau \downarrow a$ . Put  $\eta_1 := u(a)$  and  $\eta_2 := u(b)$ .

Let us consider the case  $\eta = (\eta_1, \eta_2) = (1, 1)$ . According to Theorem 6.5 the generalised (mean) curvature is constant  $\mathcal{H}^1$ -a.e. on  $M$  with value  $-\lambda$ , say. Note that  $u < 1$  on  $(a, b)$  for otherwise  $\cos(\sigma \circ \gamma)$  vanishes at some point in  $(a, b)$  bearing in

mind Lemma 5.4. By Theorem 6.6 the pair  $(u, \lambda)$  satisfies (9.4) with  $\eta = (1, 1)$ . By Lemma 9.2,  $u > 0$  on  $[a, b]$ . Put  $w := 1/u$ . Then  $(w, -\lambda)$  satisfies (9.6) and  $w > 1$  on  $(a, b)$ . By Lemma 6.7,

$$\begin{aligned} \theta_2(b) - \theta_2(a) &= \int_a^b \theta_2' d\tau = - \int_a^b \frac{u}{\sqrt{1-u^2}} \frac{d\tau}{\tau} \\ &= - \int_a^b \frac{1}{\sqrt{w^2-1}} \frac{d\tau}{\tau}. \end{aligned}$$

By Corollary 9.16,  $|\theta_2(b) - \theta_2(a)| > \pi$ . But this contradicts the definition of  $\theta_2$  in (6.4) as  $\theta_2$  takes values in  $(0, \pi)$  on  $(a, b)$ . If  $\eta = (-1, -1)$  then  $\lambda > 0$  by Lemma 9.2; this contradicts Lemma 7.2.

Now let us consider the case  $\eta = (-1, 1)$ . Using the same formula as above,  $\theta_2(b) - \theta_2(a) < 0$  by Corollary 9.7. This means that  $\theta_2(a) \in (0, \pi]$ . As before the limit  $x := \lim_{\tau \downarrow a} M_\tau \cap \overline{H} \in \mathbb{S}_a^1 \cap \overline{H}$  exists as  $M$  is  $C^1$ . Using a local parametrisation it can be seen that  $\theta_2(a) = \theta(x)$  and  $\sin(\sigma(x)) = -1$ . If  $\theta_2(a) \in (0, \pi)$  then  $E$  is not convex by Lemma 10.2. This contradicts Theorem 7.3. Note that we may assume that  $\theta_2(a) \in (0, \pi)$ . For otherwise,  $\langle \gamma, e_2 \rangle < 0$  for  $\tau > a$  near  $a$ , contradicting the definition of  $\gamma$  (6.5). If  $\eta = (1, -1)$  then  $\lambda > 0$  by Lemma 9.2 and this contradicts Lemma 7.2 as before.

Suppose finally that  $a = 0$ . By Lemma 5.5,  $u(0) = 0$  and  $u(b) = \pm 1$ . Suppose  $u(b) = 1$ . Again employing the formula above,  $\theta_2(b) - \theta_2(0) < -\pi/2$  by Lemma 9.19, the fact that the function  $\phi : (0, 1) \rightarrow \mathbb{R}; t \mapsto t/\sqrt{1-t^2}$  is strictly increasing and Lemma 9.20. This means that  $\theta_2(0) > \pi/2$ . This contradicts the  $C^1$  property at  $0 \in M$ . If  $u(b) = -1$  then then  $\lambda > 0$  by Lemma 9.2 giving a contradiction.  $\square$

**Lemma 10.4** *Let  $f$  be as in (1.3) where  $h : [0, +\infty) \rightarrow \mathbb{R}$  is a non-decreasing convex function. Let  $v > 0$ .*

- (i) *Let  $E$  be a bounded minimiser of (1.2). Assume that  $E$  is open,  $M := \partial E$  is a  $C^{1,1}$  hypersurface in  $\mathbb{R}^2$  and  $E \setminus \{0\} = E^{sc}$ . Then for any  $r > 0$  with  $r \geq R$ ,  $M \setminus \overline{B}(0, r)$  consists of a finite union of disjoint centred circles.*
- (ii) *There exists a minimiser  $E$  of (1.2) such that  $\partial E$  consists of a finite union of disjoint centred circles.*

*Proof* (i) First observe that

$$\emptyset \neq \pi(M) = \left[ \pi(M) \cap [0, r] \right] \cup \left[ \pi(M) \cap (r, +\infty) \right] \setminus \Omega$$

by Lemma 10.3. We assume that the latter member is non-empty. By definition of  $\Omega$ ,  $\cos \sigma = 0$  on  $M \cap A((r, +\infty))$ . Let  $\tau \in \pi(M) \cap (r, +\infty)$ . We claim that  $M_\tau = \mathbb{S}_\tau^1$ . Suppose for a contradiction that  $M_\tau \neq \mathbb{S}_\tau^1$ . By Lemma 5.2,  $M_\tau$  is the union of two closed spherical arcs in  $\mathbb{S}_\tau^1$ . Let  $x$  be a point on the boundary of one of these spherical arcs relative to  $\mathbb{S}_\tau^1$ . There exists a  $C^{1,1}$  parametrisation  $\gamma_1 : I \rightarrow M$  of  $M$  in a neighbourhood of  $x$  with  $\gamma_1(0) = x$  as before. By shrinking  $I$  if necessary we may assume that  $\gamma_1(I) \subset A((r, +\infty))$  as  $\tau > r$ . By (2.9),  $\dot{r}_1 = 0$  on  $I$  as  $\cos \sigma_1 = 0$  on  $I$

because  $\cos \sigma = 0$  on  $M \cap A((r, +\infty))$ ; that is,  $r_1$  is constant on  $I$ . This means that  $\gamma_1(I) \subset \mathbb{S}_r^1$ . As the function  $\sin \sigma_1$  is continuous on  $I$  it takes the value  $\pm 1$  there. By (2.10),  $r_1 \theta_1 = \sin \sigma_1 = \pm 1$  on  $I$ . This means that  $\theta_1$  is either strictly decreasing or strictly increasing on  $I$ . This entails that the point  $x$  is not a boundary point of  $M_\tau$  in  $\mathbb{S}_\tau^1$  and this proves the claim.

It follows from these considerations that  $M \setminus \overline{B}(0, r)$  consists of a finite union of disjoint centred circles. Note that  $f \geq e^{h(0)} =: c > 0$  on  $\mathbb{R}^2$ . As a result,  $+\infty > P_f(E) \geq cP(E)$  and in particular the relative perimeter  $P(E, \mathbb{R}^2 \setminus \overline{B}(0, r)) < +\infty$ . This explains why  $M \setminus \overline{B}(0, r)$  comprises only finitely many circles.

(ii) Let  $E$  be a bounded minimiser of (1.2) such that  $E$  is open,  $M := \partial E$  is a  $C^{1,1}$  hypersurface in  $\mathbb{R}^2$  and  $E \setminus \{0\} = E^{sc}$  as in Theorem 4.5. Assume that  $R > 0$ . By (i),  $M \setminus \overline{B}(0, R)$  consists of a finite union of disjoint centred circles. We claim that only one of the possibilities

$$M_R = \emptyset, M_R = \mathbb{S}_R^1, M_R = \{Re_1\} \text{ or } M_R = \{-Re_1\} \tag{10.3}$$

holds. To prove this suppose that  $M_R \neq \emptyset$  and  $M_R \neq \mathbb{S}_R^1$ . Bearing in mind Lemma 5.2 we may choose  $x \in M_R$  such that  $x$  lies on the boundary of  $M_R$  relative to  $\mathbb{S}_R^1$ . Assume that  $x \in H$ . Let  $\gamma_1 : I \rightarrow M$  be a local parametrisation of  $M$  with  $\gamma_1(0) = x$  with the usual conventions. We first notice that  $\cos(\sigma(x)) = 0$  for otherwise we obtain a contradiction to Theorem 10.3. As  $r_1$  is decreasing on  $I$  and  $x$  is a relative boundary point it holds that  $r_1 < R$  on  $I^+ := I \cap \{s > 0\}$ . As  $M \setminus \overline{A}_1$  is open in  $M$  we may suppose that  $\gamma_1(I^+) \subset M \setminus \overline{A}_1$ . According to Theorem 6.5 the curvature  $k$  of  $\gamma_1(I^+) \cap B(0, R)$  is a.e. constant as  $\rho$  vanishes on  $(0, R)$ . Hence  $\gamma_1(I^+) \cap B(0, R)$  consists of a line or circular arc. The fact that  $\cos(\sigma(x)) = 0$  means that  $\gamma_1(I^+) \cap B(0, R)$  cannot be a line. So  $\gamma_1(I^+) \cap B(0, R)$  is an open arc of a circle  $C$  containing  $x$  in its closure with centre on the line-segment  $[0, x]$  and radius  $r \in (0, R)$ . By considering a local parametrisation, it can be seen that  $C \cap B(0, R) \subset M$ . But this contradicts the fact that  $E \setminus \{0\} = E^{sc}$ . In summary,  $M_R \subset \{\pm Re_1\}$ . Finally note that if  $M_R = \{\pm Re_1\}$  then  $M_R = \mathbb{S}_R^1$  by Lemma 5.2. This establishes (10.3).

Suppose that  $M_R = \emptyset$ . As both sets  $M$  and  $\mathbb{S}_R^1$  are compact,  $d(M, \mathbb{S}_R^1) > 0$ . Assume first that  $\mathbb{S}_R^1 \subset E$ . Put  $F := B(0, R) \setminus E$  and suppose  $F \neq \emptyset$ . Then  $F$  is a set of finite perimeter,  $F \subset \subset B(0, R)$  and  $P(F) = P(E, B(0, R))$ . Let  $B$  be a centred ball with  $|B| = |F|$ . By the classical isoperimetric inequality,  $P(B) \leq P(F)$ . Define  $E_1 := (\mathbb{R}^2 \setminus B) \cap (B(0, R) \cup E)$ . Then  $V_f(E_1) = V_f(E)$  and  $P_f(E_1) \leq P_f(E)$ . That is,  $E_1$  is a minimiser of (1.2) such that  $\partial E_1$  consists of a finite union of disjoint centred circles. Now suppose that  $\mathbb{S}_R^1 \subset \mathbb{R}^2 \setminus E$ . In like fashion we may redefine  $E$  via  $E_1 := B \cup (E \setminus \overline{B}(0, R))$  with  $B$  a centred ball in  $B(0, R)$ . The remaining cases in (10.3) can be dealt with in a similar way. The upshot of this argument is that there exists a minimiser of (1.2) whose boundary  $M$  consists of a finite union of disjoint centred circles in case  $R > 0$ .

Now suppose that  $R = 0$ . By (i),  $M \setminus \overline{B}(0, r)$  consists of a finite union of disjoint centred circles for any  $r \in (0, 1)$ . If these accumulate at 0 then  $M$  fails to be  $C^1$  at the origin. The assertion follows.  $\square$



**Lemma 10.5** *Suppose that the function  $J : [0, +\infty) \rightarrow [0, +\infty)$  is continuous non-decreasing and  $J(0) = 0$ . Let  $N \in \mathbb{N} \cup \{+\infty\}$  and  $\{t_h : h = 0, \dots, 2N + 1\}$  a sequence of points in  $[0, +\infty)$  with*

$$t_0 > t_1 > \dots > t_{2h} > t_{2h+1} > \dots \geq 0.$$

Then

$$+\infty \geq \sum_{h=0}^{2N+1} J(t_h) \geq J\left(\sum_{h=0}^{2N+1} (-1)^h t_h\right).$$

*Proof* We suppose that  $N = +\infty$ . The series  $\sum_{h=0}^{\infty} (-1)^h t_h$  converges by the alternating series test. For each  $n \in \mathbb{N}$ ,

$$\sum_{h=0}^{2n+1} (-1)^h t_h \leq t_0$$

and the same inequality holds for the infinite sum. As in Step 2 in [5] Theorem 2.1,

$$+\infty \geq \sum_{h=0}^{\infty} J(t_h) \geq J(t_0) \geq J\left(\sum_{h=0}^{\infty} (-1)^h t_h\right)$$

as  $J$  is non-decreasing. □

*Proof of Theorem 1.1* There exists a minimiser  $E$  of (1.2) with the property that  $\partial E$  consists of a finite union of disjoint centred circles according to Lemma 10.4. As such we may write

$$E = \bigcup_{h=0}^N A((a_{2h+1}, a_{2h}))$$

where  $N \in \mathbb{N}$  and  $+\infty > a_0 > a_1 > \dots > a_{2N} > a_{2N+1} > 0$ . Define

$$\begin{aligned} f &: [0, +\infty) \rightarrow \mathbb{R}; t \mapsto e^{h(t)}; \\ g &: [0, +\infty) \rightarrow \mathbb{R}; t \mapsto t f(t); \\ G &: [0, +\infty) \rightarrow \mathbb{R}; t \mapsto \int_0^t g \, d\tau. \end{aligned}$$

Then  $G : [0, +\infty) \rightarrow [0, +\infty)$  is a bijection with inverse  $G^{-1}$ . Define the strictly increasing function

$$J : [0, +\infty) \rightarrow \mathbb{R}; t \mapsto g \circ G^{-1}.$$

Put  $t_h := G(a_h)$  for  $h = 0, \dots, 2N + 1$ . Then  $+\infty > t_0 > t_1 > \dots > t_{2N} > t_{2N+1} >> 0$ . Put  $B := B(0, r)$  where  $r := G^{-1}(v/2\pi)$  so that  $V_f(B) = v$ . Note that

$$\begin{aligned}
 v &= V_f(E) = 2\pi \sum_{h=0}^N \left\{ G(a_{2h}) - G(a_{2h+1}) \right\} \\
 &= 2\pi \sum_{h=0}^{2N+1} (-1)^h t_h.
 \end{aligned}$$

By Lemma 10.5,

$$\begin{aligned}
 P_f(E) &= 2\pi \sum_{h=0}^{2N+1} g(a_h) = 2\pi \sum_{h=0}^{2N+1} J(t_h) \\
 &\geq 2\pi J \left( \sum_{h=0}^{2N+1} (-1)^h t_h \right) \\
 &= 2\pi J(v/2\pi) = P_f(B).
 \end{aligned}$$

□

*Proof of Theorem 1.2* Let  $v > 0$  and  $E$  be a minimiser for (1.2). Then  $E$  is essentially bounded by Theorem 3.1. By Theorem 4.5 there exists an  $\mathcal{L}^2$ -measurable set  $\tilde{E}$  with the properties

- (a)  $\tilde{E}$  is a minimiser of (1.2);
- (b)  $L_{\tilde{E}} = L_E$  a.e. on  $(0, +\infty)$ ;
- (c)  $\tilde{E}$  is open, bounded and has  $C^{1,1}$  boundary;
- (d)  $\tilde{E} \setminus \{0\} = \tilde{E}^{sc}$ .

(i) Suppose that  $0 < v \leq v_0$  so that  $R > 0$ . Choose  $r \in (0, R]$  such that  $V(B(0, r)) = V(E) = v$ . Suppose that  $\tilde{E} \setminus \overline{B}(0, R) \neq \emptyset$ . By Lemma 10.4 there exists  $t > R$  such that  $\mathbb{S}_t^1 \subset M$ . As  $g$  is strictly increasing,  $g(t) > g(r)$ . So  $P_f(E) = P_f(\tilde{E}) \geq \pi g(t) > \pi g(r) = P_f(B(0, r))$ . This contradicts the fact that  $E$  is a minimiser for (1.2). So  $\tilde{E} \subset \overline{B}(0, R)$  and  $L_{\tilde{E}} = 0$  on  $(R, +\infty)$ . By property (b),  $|\tilde{E} \setminus \overline{B}(0, R)| = 0$ . By the uniqueness property in the classical isoperimetric theorem (see for example [12] Theorem 4.11) the set  $E$  is equivalent to a ball  $B$  in  $\overline{B}(0, R)$ .

(ii) With  $r > 0$  as before,  $V(B(0, r)) = V(E) = v > v_0 = V(B(0, R))$  so  $r > R$ . If  $\tilde{E} \setminus \overline{B}(0, r) \neq \emptyset$  we derive a contradiction in the same way as above. Consequently,  $\tilde{E} = B := B(0, r)$ . Thus,  $L_E = L_B$  a.e. on  $(0, +\infty)$ ; in particular,  $|E \setminus B| = 0$ . This entails that  $E$  is equivalent to  $B$ . □

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