# An $L^{q}$-approach to Stokes and Navier-Stokes equations in general domains 

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## 1. Introduction

Throughout this paper, $\Omega \subseteq \mathbf{R}^{3}$ means a general 3-dimensional domain with uniform $C^{2}$-boundary $\partial \Omega \neq \varnothing$, where the main interest is focussed on domains with noncompact boundary $\partial \Omega$. As is well known, the standard approach to the Stokes equations in $L^{q_{-}}$ spaces, $1<q<\infty$, cannot be extended to general unbounded domains in $L^{q}, q \neq 2$; for counterexamples concerning the Helmholtz decomposition, see [7] and [24]. However, to develop a complete and analogous theory of the Stokes equations for arbitrary domains, we replace the space $L^{q}(\Omega)$ by

$$
\tilde{L}^{q}(\Omega)= \begin{cases}L^{2}(\Omega) \cap L^{q}(\Omega), & 2 \leqslant q<\infty \\ L^{2}(\Omega)+L^{q}(\Omega), & 1<q<2\end{cases}
$$

First we prove the existence of the Helmholtz projection $P$ for the space $\tilde{L}^{q}(\Omega)$ yielding the decomposition $f=f_{0}+\nabla p, f_{0}=P f$, with properties corresponding to those in $L^{q}(\Omega)$.

In the next step we consider in $\tilde{L}^{q}(\Omega)$ the usual resolvent equation

$$
\begin{equation*}
\lambda u-\Delta u+\nabla p=f, \quad \operatorname{div} u=0 \quad \text { in } \Omega,\left.\quad u\right|_{\partial \Omega}=0 \tag{1.1}
\end{equation*}
$$

with $\lambda$ in the sector $\mathcal{S}_{\varepsilon}:=\left\{0 \neq \lambda \in \mathbf{C}:|\arg \lambda|<\frac{1}{2} \pi+\varepsilon\right\}, 0<\varepsilon<\frac{1}{2} \pi$. We prove an $\tilde{L}^{q}$-estimate similar to that in $L^{q}(\Omega)$, i.e.,

$$
\begin{equation*}
|\lambda|\|u\|_{\tilde{L}^{q}}+\left\|\nabla^{2} u\right\|_{\tilde{L}^{q}}+\|\nabla p\|_{\tilde{L}^{q}} \leqslant C\|f\|_{\tilde{L}^{q}}, \quad 1<q<\infty \tag{1.2}
\end{equation*}
$$

at least when $|\lambda| \geqslant \delta>0$ and $C=C(\Omega, q, \varepsilon, \delta)>0$.
The Stokes operator $A=-P \Delta$ is well defined in $\tilde{L}_{\sigma}^{q}(\Omega), 1<q<\infty$, and the semigroup $\left\{e^{-A t}: t \geqslant 0\right\}$ is (locally in time) bounded and analytic in some sector $\{0 \neq t \in \mathbf{C}$ : $\left.|\arg t|<\varepsilon^{\prime}\right\}, 0<\varepsilon^{\prime}<\frac{1}{2} \pi$, of the complex plane.

Further, we prove the maximal regularity estimate of the nonstationary Stokes system

$$
\begin{gather*}
u_{t}-\Delta u+\nabla p=f, \quad \operatorname{div} u=0 \quad \text { in } \Omega \times(0, T)  \tag{1.3}\\
\left.u\right|_{\partial \Omega}=0, \quad u(0)=u_{0}
\end{gather*}
$$

with $0<T<\infty$. To be more precise, if $u_{0}=0$ for simplicity, then

$$
\begin{equation*}
\left\|u_{t}\right\|_{Y_{q}}+\|u\|_{Y_{q}}+\left\|\nabla^{2} u\right\|_{Y_{q}}+\|\nabla p\|_{Y_{q}} \leqslant C\|f\|_{Y_{q}} \tag{1.4}
\end{equation*}
$$

where $Y_{q}=L^{q}\left(0, T ; \tilde{L}^{q}(\Omega)\right)$ and $C=C(T, q, \alpha, \beta, K)>0$ depends on $T, q$ and the type $\alpha, \beta, K$ of $\Omega$, see $\S 2.3$.

As an application of these linear results we obtain the existence of a so-called suitable weak solution $u$ of the Navier-Stokes system

$$
\begin{gather*}
u_{t}-\Delta u+u \cdot \nabla u+\nabla p=f, \quad \operatorname{div} u=0 \quad \text { in } \Omega \times(0, T), \\
\left.u\right|_{\partial \Omega}=0, \quad u(0)=u_{0}, \tag{1.5}
\end{gather*}
$$

with special regularity properties which are new up to now for general domains, see the conjecture in [8, p. 780]. In particular, we get for general domains the regularity property

$$
\begin{equation*}
\nabla p \in L_{\mathrm{loc}}^{5 / 4}((0, T) \times \bar{\Omega}) \tag{1.6}
\end{equation*}
$$

which is needed in the partial regularity theory of the Navier--Stokes equations. Moreover, $u$ satisfies the local energy inequality, see (2.26) below and $[8,(2.5)]$, as well as the strong energy inequality

$$
\begin{equation*}
\frac{1}{2}\|u(t)\|_{2}^{2}+\int_{s}^{t}\|\nabla u\|_{2}^{2} d \tau \leqslant \frac{1}{2}\|u(s)\|_{2}^{2}+\int_{s}^{t}\langle f, u\rangle d \tau \tag{1.7}
\end{equation*}
$$

for a.a. $s \in[0, T)$ including $s=0$ and all $t$ with $s \leqslant t<T$, see [25]. This result is essentially known for domains with compact boundaries; see [32, Chapter V, Theorems 3.6.2 and 3.4.1] for bounded domains, and [14], [26], [29], [33] and [37] for exterior domains.

## 2. Preliminaries and main results

### 2.1. Sum and intersection spaces

We recall some properties of sum and intersection spaces known from interpolation theory, cf. [4], [5], [27] and [36].

Consider two (complex) Banach spaces $X_{1}$ and $X_{2}$ with norms $\|\cdot\|_{X_{1}}$ and $\|\cdot\| x_{2}$, respectively, and assume that both $X_{1}$ and $X_{2}$ are subspaces of a topological vector
space $V$ with continuous embeddings $X_{1} \subseteq V$ and $X_{2} \subseteq V$. Further, we assume that the intersection $X_{1} \cap X_{2}$ is a dense subspace of both $X_{1}$ and $X_{2}$ in the corresponding norms.

Then the sum space

$$
X_{1}+X_{2}:=\left\{u_{1}+u_{2}: u_{1} \in X_{1}, u_{2} \in X_{2}\right\} \subseteq V
$$

is a well-defined Banach space with the norm

$$
\|u\|_{X_{1}+X_{2}}:=\inf \left\{\left\|u_{1}\right\|_{X_{1}}+\left\|u_{2}\right\|_{X_{2}}: u=u_{1}+u_{2}, u_{1} \in X_{1}, u_{2} \in X_{2}\right\}
$$

Another formulation of that norm is given by

$$
\left\|u_{1}+u_{2}\right\|_{X_{1}+X_{2}}=\inf \left\{\left\|u_{1}-v\right\|_{X_{1}}+\left\|u_{2}+v\right\|_{X_{2}}: v \in X_{1} \cap X_{2}\right\} .
$$

The intersection space $X_{1} \cap X_{2}$ is a Banach space with norm

$$
\|u\|_{X_{1} \cap X_{2}}=\max \left\{\|u\|_{X_{1}},\|u\|_{X_{2}}\right\}
$$

which is equivalent to $\|u\|_{X_{1}}+\|u\|_{X_{2}}$. Note that the space $X_{1}+X_{2}$ can be identified isometrically with the quotient space $\left(X_{1} \times X_{2}\right) / D$, where $D=\left\{(-v, v): v \in X_{1} \cap X_{2}\right\}$, identifying $u=u_{1}+u_{2} \in X_{1}+X_{2}$ with the equivalence class $\left[\left(u_{1}, u_{2}\right)\right]=\left\{\left(u_{1}-v, u_{2}+v\right)\right.$ : $\left.v \in X_{1} \cap X_{2}\right\}$.

Next we consider the dual spaces $X_{1}^{\prime}$ and $X_{2}^{\prime}$ of $X_{1}$ and $X_{2}$, respectively, with norms

$$
\|f\|_{X_{i}^{\prime}}=\sup \left\{\frac{|\langle u, f\rangle|}{\|u\|_{X_{i}}}: 0 \neq u \in X_{i}\right\}, \quad i=1,2
$$

In both cases, $\langle u, f\rangle$ denotes the value of some functional $f$ at some element $u$, and $\langle\cdot, \cdot\rangle$ is called the natural pairing between the space $X_{i}$ and its dual space $X_{i}^{\prime}$. Note that $\|u\|_{X_{i}}=\sup \left\{|\langle u, f\rangle| /\|f\|_{X_{i}^{\prime}}: 0 \neq f \in X_{i}^{\prime}\right\}$.

Since $X_{1} \cap X_{2}$ is dense in $X_{1}$ and in $X_{2}$, we can identify two elements $f_{1} \in X_{1}^{\prime}$ and $f_{2} \in X_{2}^{\prime}$, writing $f_{1}=f_{2}$, if and only if $\left\langle u, f_{1}\right\rangle=\left\langle u, f_{2}\right\rangle$ holds for all $u \in X_{1} \cap X_{2}$. In this way the intersection $X_{1}^{\prime} \cap X_{2}^{\prime}$ is a well-defined Banach space with norm $\|f\|_{X_{1}^{\prime} \cap X_{2}^{\prime}}=$ $\max \left\{\|f\|_{X_{1}^{\prime}},\|f\|_{X_{2}^{\prime}}\right\}$. The dual space $\left(X_{1}+X_{2}\right)^{\prime}$ of $X_{1}+X_{2}$ is given by $X_{1}^{\prime} \cap X_{2}^{\prime}$, and we get

$$
\left(X_{1}+X_{2}\right)^{\prime}=X_{1}^{\prime} \cap X_{2}^{\prime}
$$

with the natural pairing

$$
\langle u, f\rangle=\left\langle u_{1}, f\right\rangle+\left\langle u_{2}, f\right\rangle
$$

for all $u=u_{1}+u_{2} \in X_{1}+X_{2}$ and $f \in X_{1}^{\prime} \cap X_{2}^{\prime}$. Thus it holds that

$$
\|u\|_{X_{1}+X_{2}}=\sup \left\{\frac{\left|\left\langle u_{1}, f\right\rangle+\left\langle u_{2}, f\right\rangle\right|}{\|f\|_{X_{1}^{\prime} \cap X_{2}^{\prime}}}: 0 \neq f \in X_{1}^{\prime} \cap X_{2}^{\prime}\right\}
$$

and

$$
\|f\|_{X_{1}^{\prime} \cap X_{2}^{\prime}}=\sup \left\{\frac{\left|\left\langle u_{1}, f\right\rangle+\left\langle u_{2}, f\right\rangle\right|}{\|u\|_{X_{1}+X_{2}}}: 0 \neq u=u_{1}+u_{2} \in X_{1}+X_{2}\right\}
$$

see [5, p. 32] and [36, p. 69]. Therefore, $|\langle u, f\rangle| \leqslant\|u\|_{X_{1}+X_{2}}\|f\|_{X_{1}^{\prime} \cap X_{2}^{\prime}}$.
By analogy, we obtain that

$$
\left(X_{1} \cap X_{2}\right)^{\prime}=X_{1}^{\prime}+X_{2}^{\prime}
$$

with the natural pairing $\left\langle u, f_{1}+f_{2}\right\rangle=\left\langle u, f_{1}\right\rangle+\left\langle u, f_{2}\right\rangle$.
Consider closed subspaces $L_{1} \subseteq X_{1}$ and $L_{2} \subseteq X_{2}$ equipped with norms $\|\cdot\|_{L_{1}}=\|\cdot\|_{X_{1}}$ and $\|\cdot\|_{L_{2}}=\|\cdot\|_{X_{2}}$, and assume that $L_{1} \cap L_{2}$ is dense in both $L_{1}$ and $L_{2}$ in the corresponding norms. Then $\|u\|_{L_{1} \cap L_{2}}=\|u\|_{X_{1} \cap X_{2}}, u \in L_{1} \cap L_{2}$, and an elementary argument, using the Hahn-Banach theorem, shows that also

$$
\begin{equation*}
\|u\|_{L_{1}+L_{2}}=\|u\|_{X_{1}+X_{2}}, \quad u \in L_{1}+L_{2} \tag{2.1}
\end{equation*}
$$

In particular, we need the following special case. Let $B_{1}: D\left(B_{1}\right) \rightarrow X_{1}$ and $B_{2}$ : $D\left(B_{2}\right) \rightarrow X_{2}$ be closed linear operators with dense domains $D\left(B_{1}\right) \subseteq X_{1}$ and $D\left(B_{2}\right) \subseteq X_{2}$ equipped with graph norms

$$
\|u\|_{D\left(B_{1}\right)}=\|u\|_{X_{1}}+\left\|B_{1} u\right\|_{X_{1}} \quad \text { and } \quad\|u\|_{D\left(B_{2}\right)}=\|u\|_{X_{2}}+\left\|B_{2} u\right\|_{X_{2}} .
$$

We assume that $D\left(B_{1}\right) \cap D\left(B_{2}\right)$ is dense in both $D\left(B_{1}\right)$ and $D\left(B_{2}\right)$ in the corresponding graph norms. Each functional $F \in D\left(B_{i}\right)^{\prime}, i=1,2$, is given by some pair $f, g \in X_{i}^{\prime}$ in the form $\langle u, F\rangle=\langle u, f\rangle+\left\langle B_{i} u, g\right\rangle$. Using (2.1) with $L_{i}=\left\{\left(u, B_{i} u\right): u \in D\left(B_{i}\right)\right\} \subseteq X_{i} \times X_{i}$, $i=1,2$, and the equality of norms $\|\cdot\|_{\left(X_{1} \times X_{1}\right)+\left(X_{2} \times X_{2}\right)}$ and $\|\cdot\|_{\left(X_{1}+X_{2}\right) \times\left(X_{1}+X_{2}\right)}$ on $\left(X_{1} \times X_{1}\right)+\left(X_{2} \times X_{2}\right)$, we conclude that for each $u \in D\left(B_{1}\right)+D\left(B_{2}\right)$ with decomposition $u=u_{1}+u_{2}, u_{1} \in D\left(B_{1}\right), u_{2} \in D\left(B_{2}\right)$,

$$
\begin{equation*}
\|u\|_{D\left(B_{1}\right)+D\left(B_{2}\right)}=\left\|u_{1}+u_{2}\right\|_{X_{1}+X_{2}}+\left\|B_{1} u_{1}+B_{2} u_{2}\right\|_{X_{1}+X_{2}} \tag{2.2}
\end{equation*}
$$

Suppose that $X_{1}$ and $X_{2}$ are reflexive Banach spaces implying that each bounded sequence in $X_{1}$ (and $X_{2}$ ) has a weakly convergent subsequence. This argument yields the following property: Given $u \in X_{1}+X_{2}$ there exist $u_{1} \in X_{1}$ and $u_{2} \in X_{2}$ with $u=u_{1}+u_{2}$ such that

$$
\begin{equation*}
\|u\|_{X_{1}+X_{2}}=\left\|u_{1}\right\|_{X_{1}}+\left\|u_{2}\right\|_{X_{2}} \tag{2.3}
\end{equation*}
$$

### 2.2. Function spaces

In the following let $D_{j}=\partial / \partial x_{j}, j=1,2,3, x=\left(x_{1}, x_{2}, x_{3}\right) \in \Omega \subset \mathbf{R}^{3}, \nabla=\left(D_{1}, D_{2}, D_{3}\right)$ and $\nabla^{2}=\left(D_{j} D_{k}\right)_{j, k=1,2,3}$. The spaces of smooth functions on $\Omega$ are denoted as usual by $C^{k}(\Omega), C^{k}(\bar{\Omega})$ and $C_{0}^{k}(\Omega)$ with $k \in \mathbf{N}_{0}=\mathbf{N} \cup\{0\}$ or $k=\infty$. We set

$$
C_{0, \sigma}^{\infty}(\Omega)=\left\{u=\left(u_{1}, u_{2}, u_{3}\right) \in C_{0}^{\infty}(\Omega): \operatorname{div} u=0\right\}
$$

Let $1<q<\infty$ and $q^{\prime}=q /(q-1)$ such that $1 / q+1 / q^{\prime}=1$. Then $L^{q}(\Omega)$ with norm $\|u\|_{L^{q}}=\|u\|_{q}=\|u\|_{q, \Omega}$ denotes the usual Lebesgue space for scalar or vector fields. Each $f=\left(f_{1}, f_{2}, f_{3}\right) \in L^{q^{\prime}}(\Omega)=L^{q}(\Omega)^{\prime}$ will be identified with the functional $\langle\cdot, f\rangle: u \mapsto\langle u, f\rangle=$ $\langle u, f\rangle_{\Omega}=\int_{\Omega} u \cdot f d x$ on $L^{q}(\Omega)$. Let $L_{\sigma}^{q}(\Omega)=\overline{C_{0, \sigma}(\Omega)}{ }^{\|\cdot\|_{q}} \subset L^{q}(\Omega)$ denote the subspace of divergence-free vector fields $u=\left(u_{1}, u_{2}, u_{3}\right)$ with normal component $\left.N \cdot u\right|_{\partial \Omega}=0$ at $\partial \Omega$; here $N$ means the outer normal at $\partial \Omega$. The usual Sobolev spaces $W^{k, q}(\Omega)$ are mainly used for $k=1,2$ with norms $\|u\|_{W^{1, q}}=\|u\|_{1, q}=\|u\|_{1, q, \Omega}=\|u\|_{q}+\|\nabla u\|_{q}$ and $\|u\|_{W^{2, q}}=\|u\|_{2, q}=$ $\|u\|_{2, q, \Omega}=\|u\|_{1, q}+\left\|\nabla^{2} u\right\|_{q}$, respectively. Further, we need the subspaces

$$
W_{0}^{1, q}(\Omega)=\overline{C_{0}^{\infty}(\Omega)}\|\cdot\|_{1, q} \subset W^{1, q}(\Omega) \quad \text { and } \quad W_{0, \sigma}^{1, q}(\Omega)={\overline{C_{0, \sigma}^{\infty}(\Omega)}}^{\|\cdot\|_{1, q}} \subset W^{1, q}(\Omega)
$$

For simplicity, we will write $C^{k}, L^{q}, W_{\sigma}^{1, q}$, etc. instead of $C^{k}(\Omega), L^{q}(\Omega), W_{\sigma}^{1, q}(\Omega)$, respectively, when the underlying domain is known from the context. Moreover, we will use the same notation for spaces of scalar-, vector- and matrix-valued functions.

The sum space $L^{2}+L^{q}$ is well defined when $V$ in $\S 2.1$ is the space of distributions with the usual topology. We obtain that

$$
\left(L^{2}+L^{q}\right)^{\prime}=L^{2} \cap L^{q^{\prime}} \quad \text { and } \quad\left(L^{2} \cap L^{q}\right)^{\prime}=L^{2}+L^{q^{\prime}}
$$

where $\|u\|_{L^{2} \cap L^{q}}=\max \left\{\|u\|_{2},\|u\|_{q}\right\}$ and

$$
\begin{aligned}
\|u\|_{L^{2}+L^{q}} & =\inf \left\{\left\|u_{1}\right\|_{2}+\left\|u_{2}\right\|_{q}: u=u_{1}+u_{2}, u_{1} \in L^{2}, u_{2} \in L^{q}\right\} \\
& =\sup \left\{\frac{\left|\left\langle u_{1}+u_{2}, f\right\rangle\right|}{\|f\|_{L^{2} \cap L^{q^{\prime}}}}: 0 \neq f \in L^{2} \cap L^{q^{\prime}}\right\}
\end{aligned}
$$

For the nonstationary problem on some time interval $[0, T), 0<T \leqslant \infty$, we need the usual Banach space $L^{s}(0, T ; X)$ of measurable $X$-valued (classes of) functions $u$ with norm

$$
\|u\|_{L^{s}(0, T ; X)}=\left(\int_{0}^{T}\|u(t)\|_{X}^{s} d t\right)^{1 / s}, \quad 1 \leqslant s<\infty
$$

where $X$ is a Banach space. For $s=\infty$ let

$$
\|u\|_{L^{\infty}(0, T ; X)}=\operatorname{ess} \sup \left\{\|u(t)\|_{X}: 0 \leqslant t<T\right\}
$$

If $X$ is reflexive and $1<s<\infty$, then the dual space of $L^{s}(0, T ; X)$ is given by $L^{s}(0, T ; X)^{\prime}=$ $L^{s^{\prime}}\left(0, T ; X^{\prime}\right), s^{\prime}=s /(s-1)$, with the natural pairing $\langle u, f\rangle_{T}=\int_{0}^{T}\langle u(t), f(t)\rangle d t$; see [20].

Let $X=L^{q}(\Omega), 1<q<\infty$. Then we use the notation

$$
\|u\|_{L^{s}\left(0, T ; L^{q}\right)}=\|u\|_{L^{s}\left(L^{q}\right)}=\left(\int_{0}^{T}\|u\|_{q}^{s} d t\right)^{1 / s}
$$

Moreover, the pairing of $L^{s}\left(0, T ; L^{q}\right)$ with its dual $L^{s^{\prime}}\left(0, T ; L^{q^{\prime}}\right)$ is given by $\langle u, f\rangle_{T}=$ $\langle u, f\rangle_{\Omega, T}=\int_{0}^{T} \int_{\Omega} u \cdot f d x d t$ if $1<s<\infty$.

Let $Y_{1}=L^{s}\left(0, T ; L^{2}\right)$ and $Y_{2}=L^{s}\left(0, T ; L^{q}\right)$ with $1<q, s<\infty$. Then we see that

$$
\left(Y_{1}+Y_{2}\right)^{\prime}=Y_{1}^{\prime} \cap Y_{2}^{\prime}=L^{s^{\prime}}\left(0, T ; L^{2} \cap L^{q^{\prime}}\right)=L^{s}\left(0, T ; L^{2}+L^{q}\right)^{\prime}
$$

and therefore $Y_{1}+Y_{2}=L^{s}\left(0, T ; L^{2}+L^{q}\right)$; the pairing between $Y_{1}+Y_{2}$ and $Y_{1}^{\prime} \cap Y_{2}^{\prime}$ is given by $\left\langle u_{1}+u_{2}, f\right\rangle_{T}=\left\langle u_{1}, f\right\rangle_{T}+\left\langle u_{2}, f\right\rangle_{T}$ for $u_{1} \in Y_{1}, u_{2} \in Y_{2}$ and $f \in Y_{1}^{\prime} \cap Y_{2}^{\prime}$. Furthermore, we can choose the decomposition $u=u_{1}+u_{2} \in L^{s}\left(0, T ; L^{2}+L^{q}\right)$ in such a way that

$$
\begin{equation*}
\|u\|_{Y_{1}+Y_{2}}=\left\|u_{1}\right\|_{Y_{1}}+\left\|u_{2}\right\|_{Y_{2}} \tag{2.4}
\end{equation*}
$$

We conclude that

$$
\begin{equation*}
\left\|u_{1}+u_{2}\right\|_{Y_{1}+Y_{2}}=\sup \left\{\frac{\left|\left\langle u_{1}+u_{2}, f\right\rangle_{T}\right|}{\|f\|_{Y_{1}^{\prime} \cap Y_{2}^{\prime}}}: 0 \neq f \in L^{s^{\prime}}\left(0, T ; L^{2} \cap L^{q^{\prime}}\right)\right\} \tag{2.5}
\end{equation*}
$$

### 2.3. Structure properties of the boundary $\partial \Omega$

We recall some well-known technical details on the uniform $C^{2}$-domain $\Omega \subseteq \mathbf{R}^{3}$, see, e.g., [1, p. 67], [18, p. 645] and [32, p. 26]. By definition, this means that there are constants $\alpha, \beta, K>0$ with the following properties:

For each $x_{0} \in \partial \Omega$ we can choose a Cartesian coordinate system with origin $x_{0}$ and coordinates $y=\left(y_{1}, y_{2}, y_{3}\right)=\left(y^{\prime}, y_{3}\right), y^{\prime}=\left(y_{1}, y_{2}\right)$, obtained by some translation and rotation, as well as some $C^{2}$-function $h\left(y^{\prime}\right),\left|y^{\prime}\right| \leqslant \alpha$, with $C^{2}$-norm $\|h\|_{C^{2}} \leqslant K$, such that the neighborhood

$$
U_{\alpha, \beta, h}\left(x_{0}\right):=\left\{\left(y^{\prime}, y_{3}\right): h\left(y^{\prime}\right)-\beta<y_{3}<h\left(y^{\prime}\right)+\beta,\left|y^{\prime}\right|<\alpha\right\}
$$

of $x_{0}$ satisfies

$$
U_{\alpha, \beta, h}^{-}\left(x_{0}\right):=\left\{\left(y^{\prime}, y_{3}\right): h\left(y^{\prime}\right)-\beta<y_{3}<h\left(y^{\prime}\right),\left|y^{\prime}\right|<\alpha\right\}=\Omega \cap U_{\alpha, \beta, h}\left(x_{0}\right)
$$

and

$$
\partial \Omega \cap U_{\alpha, \beta, h}\left(x_{0}\right)=\left\{\left(y^{\prime}, y_{3}\right): h\left(y^{\prime}\right)=y_{3},\left|y^{\prime}\right|<\alpha\right\}
$$

Without loss of generality we may assume that the axes of $y^{\prime}=\left(y_{1}, y_{2}\right)$ are contained in the tangential plane at $x_{0}$. Thus at $y^{\prime}=(0,0)$ we have $h\left(y^{\prime}\right)=0$ and $\nabla^{\prime} h\left(y^{\prime}\right)=$ $\left(\partial h / \partial y_{1}, \partial h / \partial y_{2}\right)=(0,0)$. Therefore, for any given constant $M_{0}>0$, we may choose $\alpha>0$ sufficiently small such that a smallness condition of the form

$$
\left\|\nabla^{\prime} h\right\|_{C^{0}}=\max \left\{\left|\nabla^{\prime} h\left(y^{\prime}\right)\right|:\left|y^{\prime}\right| \leqslant \alpha\right\} \leqslant M_{0}
$$

is satisfied. It is important to note that the constants $\alpha, \beta, K>0$ do not depend on $x_{0} \in \Omega$. We call $\alpha, \beta, K$ the type of $\Omega$.

Let $\bar{\Omega}$ be the closure of $\Omega$ and let $B_{r}(x)=\left\{w \in \mathbf{R}^{3}:|w-x|<r\right\}$ be the open ball with center $x \in \mathbf{R}^{3}$ and radius $r>0$. Then we can choose some fixed $r \in(0, \alpha)$ depending only on $\alpha, \beta, K$, balls $B_{j}=B_{r}\left(x_{j}\right)$ with centers $x_{j} \in \bar{\Omega}$, and $C^{2}$-functions $h_{j}\left(y^{\prime}\right),\left|y^{\prime}\right| \leqslant \alpha$, where $j=1,2, \ldots, N$ if $\Omega$ is bounded and $j \in \mathbf{N}$ if $\Omega$ is unbounded, such that

$$
\begin{gather*}
\bar{\Omega} \subseteq \bigcup_{j=1}^{N} B_{j} \quad \text { and } \quad \bar{\Omega} \subseteq \bigcup_{j=1}^{\infty} B_{j}, \quad \text { respectively }  \tag{2.6}\\
\bar{B}_{j} \subseteq U_{\alpha, \beta, h_{j}}\left(x_{j}\right) \text { if } x_{j} \in \partial \Omega, \quad \bar{B}_{j} \subseteq \Omega \text { if } x_{j} \in \Omega
\end{gather*}
$$

Moreover, we can construct this covering in such a way that not more than a fixed finite number $N_{0}=N_{0}(\alpha, \beta, K) \in \mathbf{N}$ of these balls $B_{1}, B_{2}, \ldots$ can have a nonempty intersection. Thus if we choose any $N_{0}+1$ different balls $B_{1}, B_{2}, \ldots$, then their common intersection is empty. If $\Omega$ is bounded, let $N_{0}=N$.

Concerning $\left\{B_{j}\right\}$, there exists a partition of unity $\varphi_{j} \in C_{0}^{\infty}\left(\mathbf{R}^{3}\right)$ with $0 \leqslant \varphi_{j} \leqslant 1$, $\operatorname{supp} \varphi_{j} \subseteq B_{j}, j=1, \ldots, N$ or $j \in \mathbf{N}$, satisfying

$$
\begin{equation*}
\sum_{j=1}^{N} \varphi_{j}(x)=1 \quad \text { and } \quad \sum_{j=1}^{\infty} \varphi_{j}(x)=1, \quad \text { respectively, for all } x \in \bar{\Omega} \tag{2.7}
\end{equation*}
$$

and the pointwise estimates $\left|\nabla \varphi_{j}(x)\right|,\left|\nabla^{2} \varphi_{j}(x)\right| \leqslant C$ uniformly with respect to $x$ and $j$, where $C=C(\alpha, \beta, K)$.

If $\Omega$ is unbounded, we can represent $\Omega$ as a union of countably many bounded $C^{2}$-subdomains $\Omega_{j} \subseteq \Omega, j \in \mathbf{N}$, such that

$$
\begin{equation*}
\Omega_{j} \subseteq \Omega_{j+1} \quad \text { for all } j \in \mathbf{N}, \quad \Omega=\bigcup_{j=1}^{\infty} \Omega_{j} \tag{2.8}
\end{equation*}
$$

and such that each $\Omega_{j}$ has some fixed type $\alpha^{\prime}, \beta^{\prime}, K^{\prime}>0$. Without loss of generality we may assume that $\alpha=\alpha^{\prime}, \beta=\beta^{\prime}$ and $K=K^{\prime}$ : each subdomain $\Omega_{j}, j \in \mathbf{N}$, has the same type $\alpha, \beta, K$ as $\Omega$, see [18, p. 665]. Obviously each compact subset $\Omega_{0} \subseteq \Omega$ is contained in some $\Omega_{j}$, and therefore in each $\Omega_{k}, k \geqslant j$; see [32, p. 56, Remark 1.4.2].

Finally we need a technical property in subsequent proofs. Given a ball $B_{r}(x) \subset \mathbf{R}^{3}$ consider some Cartesian coordinate system with origin $x$ and coordinates $y=\left(y^{\prime}, y_{3}\right)$. Then $B_{r}^{-}(x):=\left\{y=\left(y^{\prime}, y_{3}\right):|y|<r, y_{3}<0\right\}$ is called a half-ball with center $x$ and radius $r$. We may assume without loss of generality that there are appropriate half-balls $B_{j}^{-}=$ $B_{r}^{-}\left(x_{j}\right)$ of the balls $B_{j}$ in (2.6) and (2.7) such that

$$
\begin{equation*}
\operatorname{supp} \varphi_{j} \subseteq B_{j}^{-} \quad \text { if } x_{j} \in \Omega, \text { where } j=1, \ldots, N \text { or } j \in \mathbf{N} \tag{2.9}
\end{equation*}
$$

### 2.4. Main results on the Stokes equations

We can extend several important $L^{q}$-properties of the Stokes equations known for special domains, such as bounded or exterior domains, to general domains $\Omega$ if we replace the usual $L^{q}$-space by the space

$$
\tilde{L}^{q}=\tilde{L}^{q}(\Omega)=L^{2}(\Omega) \cap L^{q}(\Omega) \quad \text { for } 2 \leqslant q<\infty,
$$

and by the space

$$
\tilde{L}^{q}=\tilde{L}^{q}(\Omega)=L^{2}(\Omega)+L^{q}(\Omega) \quad \text { for } 1<q<2 .
$$

Note that $\tilde{L}^{q}$ is smaller than $L^{q}$ when $q>2$, and larger than $L^{q}$ when $1<q<2$, but that $\tilde{L}^{2}=L^{2}$. Analogously, we define the subspace $\tilde{L}_{\sigma}^{q}=\tilde{L}_{\sigma}^{q}(\Omega) \subset \tilde{L}^{q}(\Omega)$ by setting $\tilde{L}_{\sigma}^{q}=$ $L_{\sigma}^{2}(\Omega) \cap L_{\sigma}^{q}(\Omega)$ for $2 \leqslant q<\infty$, and $\tilde{L}_{\sigma}^{q}=L_{\sigma}^{2}(\Omega)+L_{\sigma}^{q}(\Omega)$ for $1<q<2$.

In the same way we modify the $L^{q}$-Sobolev spaces $W^{k, q}(\Omega)$ and the spaces

$$
\begin{array}{lr}
G^{q}(\Omega)=\left\{\nabla p \in L^{q}: p \in L_{\mathrm{loc}}^{q}(\Omega)\right\}, & \|\nabla p\|_{G^{q}}=\|\nabla p\|_{L^{q}}, \\
D^{q}(\Omega)=L_{\sigma}^{q}(\Omega) \cap W_{0}^{1, q}(\Omega) \cap W^{2, q}(\Omega), & \|u\|_{D^{q}}=\|u\|_{W^{2, q}},
\end{array}
$$

$1<q<\infty$, as follows: For $2 \leqslant q<\infty$ let

$$
\begin{aligned}
\widetilde{W}^{k, q}(\Omega) & =W^{k, 2}(\Omega) \cap W^{k, q}(\Omega), \\
\widetilde{G}^{q}(\Omega) & =G^{2}(\Omega) \cap G^{q}(\Omega), \\
\widetilde{D}^{q}(\Omega) & =D^{2}(\Omega) \cap D^{q}(\Omega),
\end{aligned}
$$

and for $1<q<2$ let

$$
\begin{aligned}
\widetilde{W}^{k, q}(\Omega) & =W^{k, 2}(\Omega)+W^{k, q}(\Omega), \\
\widetilde{G}^{q}(\Omega) & =G^{2}(\Omega)+G^{q}(\Omega) \\
\widetilde{D}^{q}(\Omega) & =D^{2}(\Omega)+D^{q}(\Omega),
\end{aligned}
$$

$k=1,2$. Then the norms $\|\cdot\|_{\widetilde{W}^{k, q}},\|\cdot\|_{\widetilde{G}^{q}}$ and $\|\cdot\|_{\tilde{D}^{q}}$ are well defined. If $\Omega$ is bounded, then $\tilde{L}^{q}=L^{q}, \tilde{L}_{\sigma}^{q}=L_{\sigma}^{q}, \widetilde{G}^{q}=G^{q}, \widetilde{D}^{q}=D^{q}$ and $\widetilde{W}^{k, q}=W^{k, q}$ hold with equivalent norms. Thus the introduction of " $\sim$ "-spaces is reasonable only for unbounded domains.

Our first result yields the existence of the Helmholtz projection in $\tilde{L}^{q}(\Omega)$. The counterexamples in [7] and [24] show that the usual $L^{q}$-theory for special domains cannot be extended to $\Omega$ for arbitrary $q \neq 2$. It is important to note that the constants $C=$ $C(q, \alpha, \beta, K)>0$ below only depend on $q$ and the type $\alpha, \beta, K$ of the domain $\Omega$.

Theorem 2.1. (Helmholtz decomposition.) Let $\Omega \subseteq \mathbf{R}^{3}$ be a uniform $C^{2}$-domain of type $\alpha, \beta, K>0$ and let $1<q<\infty, q^{\prime}=q /(q-1)$. Then for each $f \in \tilde{L}^{q}$ there exists a unique decomposition $f=f_{0}+\nabla p$ with $f_{0} \in \tilde{L}_{\sigma}^{q}$ and $\nabla p \in \widetilde{G}^{q}$ satisfying the estimate

$$
\begin{equation*}
\left\|f_{0}\right\|_{\tilde{L}^{q}}+\|\nabla p\|_{\tilde{L}^{q}} \leqslant C\|f\|_{\tilde{L}^{q}}, \quad C=C(q, \alpha, \beta, K)>0 . \tag{2.10}
\end{equation*}
$$

The Helmholtz projection $P=\widetilde{P}_{q}$ defined by $\widetilde{P}_{q} f=f_{0}$ is a bounded operator from $\tilde{L}^{q}$ onto $\tilde{L}_{\sigma}^{q}$ satisfying $\widetilde{P}_{q} f=f$ if $f \in \tilde{L}_{\sigma}^{q}$, and $\widetilde{P}_{q}(\nabla p)=0$ if $\nabla p \in \widetilde{G}^{q}$. Moreover, $\left\langle\widetilde{P}_{q} f, g\right\rangle=\left\langle f, \widetilde{P}_{q^{\prime}} g\right\rangle$ for all $f \in \tilde{L}^{q}$ and $g \in \tilde{L}^{q^{\prime}}$.

Remark 2.2. By Theorem 2.1 we conclude that $\widetilde{P}_{q}^{\prime}=\widetilde{P}_{q^{\prime}}$ for the dual operator $\widetilde{P}_{q}^{\prime}=\left(\widetilde{P}_{q}\right)^{\prime}$ of $\widetilde{P}_{q}, 1<q<\infty$, and $\left(\tilde{L}_{\sigma}^{q}\right)^{\prime}=\tilde{L}_{\sigma}^{q^{\prime}}$ with pairing $\langle\cdot, \cdot\rangle$. We also get that the norm defined by

$$
\begin{equation*}
\|u\|_{\tilde{L}_{\sigma}^{q}}^{*}=\sup \left\{\frac{|\langle u, f\rangle|}{\|f\|_{\tilde{L}_{\sigma}^{q^{\prime}}}}: 0 \neq f \in \tilde{L}_{\sigma}^{q^{\prime}}\right\}, \quad u \in \tilde{L}_{\sigma}^{q}, \tag{2.11}
\end{equation*}
$$

is equivalent to the norm $\|u\|_{\tilde{L}_{\sigma}^{g}}=\|u\|_{\tilde{L}^{q}}$ in the sense that $\|u\|_{\tilde{\mathcal{L}}_{\sigma}^{g}}^{*} \leqslant\|u\|_{\tilde{L}_{\sigma}} \leqslant C\|u\|_{\tilde{L}_{\sigma}^{g}}^{*}$ with $C=C(q, \alpha, \beta, K)>0$ from (2.10).

The usual $L^{q}$-Stokes operator $A=A_{q}$ with domain

$$
D\left(A_{q}\right)=D^{q}=L_{\sigma}^{q} \cap W_{0}^{1, q} \cap W^{2, q} \subset L_{\sigma}^{q}
$$

and range $R\left(A_{q}\right) \subseteq L_{\sigma}^{q}$ defined by $A_{q} u=-P_{q} \Delta u$ is meaningful if the Helmholtz projection $P_{q}: L^{q} \rightarrow L_{\sigma}^{q}$ is well defined. Thus, because of the counterexamples, see [7] and [24], we cannot expect that this theory is extendable to general domains $\Omega$ for $q \neq 2$ without modification of the $L^{q}$-space.

Next we will show that the usual Stokes estimate, at least for $|\lambda| \geqslant \delta>0$, remains valid for $\Omega$ when we replace the $L^{q}$-theory by the $\tilde{L}^{q}$-theory. More precisely, let the Stokes operator $A=\tilde{A}_{q}$ be defined as an operator with domain $D\left(\tilde{A}_{q}\right)=\widetilde{D}^{q} \subseteq \tilde{L}_{\sigma}^{q}$ into $\tilde{L}_{\sigma}^{q}$, by setting

$$
\tilde{A}_{q} u=-\widetilde{P}_{q} \Delta u, \quad u \in \widetilde{D}^{q} .
$$

Let $I$ be the identity and $\mathcal{S}_{\varepsilon}=\left\{0 \neq \lambda \in \mathbf{C}:|\arg \lambda|<\frac{1}{2} \pi+\varepsilon\right\}, 0<\varepsilon<\frac{1}{2} \pi$.
Theorem 2.3. (Stokes resolvent.) Let $\Omega \subseteq \mathbf{R}^{3}$ be a uniform $C^{2}$-domain of type $\alpha, \beta, K>0$ and let $1<q<\infty, q^{\prime}=q /(q-1), 0<\varepsilon<\frac{1}{2} \pi$ and $\delta>0$. Then

$$
\tilde{A}_{q}=-\widetilde{P}_{q} \Delta: D\left(\tilde{A}_{q}\right) \longrightarrow \tilde{L}_{\sigma}^{q}, \quad D\left(\tilde{A}_{q}\right) \subset \tilde{L}_{\sigma}^{q}
$$

is a densely defined closed operator, the resolvent $\left(\lambda I+\tilde{A}_{q}\right)^{-1}: \tilde{L}_{\sigma}^{q} \rightarrow \tilde{L}_{\sigma}^{q}$ is well defined for all $\lambda \in \mathcal{S}_{\varepsilon}$, and for $u=\left(\lambda I+\tilde{A}_{q}\right)^{-1} f, f \in \tilde{L}_{\sigma}^{q}$, the estimate

$$
\begin{equation*}
|\lambda|\|u\|_{\tilde{L}_{\sigma}^{q}}+\|u\|_{\widetilde{W}^{2, q}} \leqslant C\|f\|_{\tilde{\mathcal{L}}_{\sigma}^{q}}, \quad|\lambda| \geqslant \delta, \tag{2.12}
\end{equation*}
$$

with $C=C(q, \varepsilon, \delta, \alpha, \beta, K)>0$, is satisfied. Further, the following duality relation holds:

$$
\begin{equation*}
\left\langle\tilde{A}_{q} u, v\right\rangle=\left\langle u, \tilde{A}_{q^{\prime}} v\right\rangle, \quad u \in D\left(\tilde{A}_{q}\right), v \in D\left(\tilde{A}_{q^{\prime}}\right) . \tag{2.13}
\end{equation*}
$$

Remark 2.4. (a) From (2.12) we conclude that $-\tilde{A}_{q}$ generates a $C^{0}$-semigroup $\left\{e^{-t \tilde{A}_{q}}: t \geqslant 0\right\}$ which has an analytic extension to some sector $\left\{0 \neq t \in \mathbf{C}:|\arg t|<\varepsilon^{\prime}\right\}$, $0<\varepsilon^{\prime}<\frac{1}{2} \pi$, satisfying the estimate

$$
\begin{equation*}
\left\|e^{-t \tilde{A}_{q}} f\right\|_{\tilde{L}_{\sigma}^{q}} \leqslant M e^{\delta t}\|f\|_{\tilde{L}_{\sigma}^{q}}, \quad f \in \tilde{L}_{\sigma}^{q}, t \geqslant 0 \tag{2.14}
\end{equation*}
$$

with $M=M(q, \delta, \alpha, \beta, K)>0$. Note that $\delta>0$ may be chosen arbitrarily small, but we cannot prove up to now whether (2.14) holds with $\delta=0$ for the general domain $\Omega$.
(b) Let $f \in \tilde{L}^{q}, 1<q<\infty, \lambda \in \mathcal{S}_{\varepsilon}$ and $|\lambda|>\delta$, and set $u=\left(\lambda I+\tilde{A}_{q}\right)^{-1} \widetilde{P}_{q} f$ and $\nabla p=$ $\left(I-\widetilde{P}_{q}\right)(f+\Delta u)$. Then we get a unique solution pair $u \in D\left(\tilde{A}_{q}\right), \nabla p \in \widetilde{G}^{q}$ of the equation $\lambda u-\Delta u+\nabla p=f$, and by (2.12),

$$
\begin{equation*}
|\lambda|\|u\|_{\tilde{L}^{q}}+\left\|\nabla^{2} u\right\|_{\tilde{L}^{q}}+\|\nabla p\|_{\tilde{L}^{q}} \leqslant C\|f\|_{\tilde{L}^{q}} \tag{2.15}
\end{equation*}
$$

where $C=C(q, \varepsilon, \delta, \alpha, \beta, K)>0$.
(c) Due to (2.15) the graph norm $\|u\|_{D\left(\tilde{A}_{q}\right)}=\|u\|_{\tilde{L}_{\sigma}^{q}}+\left\|\tilde{A}_{q} u\right\|_{\tilde{L}_{\sigma}^{q}}$ on the Banach space $D\left(\tilde{A}_{q}\right)$ satisfies the estimate

$$
\begin{equation*}
C\|u\|_{\widetilde{W}^{2, q}} \leqslant\|u\|_{D\left(\tilde{A}_{q}\right)} \leqslant C^{\prime}\|u\|_{\widetilde{W}^{2, q}}, \quad u \in D\left(\tilde{A}_{q}\right) \tag{2.16}
\end{equation*}
$$

with constants $C=C(q, \alpha, \beta, K)>0$ and $C^{\prime}=C^{\prime}(q, \alpha, \beta, K)>0$. Hence the norms $\|u\|_{\widetilde{W}^{2, q}}$ and $\|u\|_{D\left(\tilde{A}_{q}\right)}$ are equivalent.

Another important property is the maximal regularity estimate of the nonstationary Stokes equation (1.3), which can be written, applying the Helmholtz projection, in the form

$$
\begin{equation*}
u_{t}+\tilde{A}_{q} u=f, \quad u(0)=u_{0} \tag{2.17}
\end{equation*}
$$

For simplicity, we do not use the weakest possible norm for the initial value $u_{0}$, see Remark 2.6 (a).

THEOREM 2.5. (Nonstationary Stokes system.) Let $\Omega \subseteq \mathbf{R}^{3}$ be a uniform $C^{2}$-domain of type $\alpha, \beta, K>0$, and let $0<T<\infty, Y_{q}=L^{q}\left(0, T ; \tilde{L}_{\sigma}^{q}\right), 1<q<\infty$.

Then for each $f \in Y_{q}$ and each $u_{0} \in D\left(\tilde{A}_{q}\right)$ there exists a unique solution

$$
u \in L^{q}\left(0, T ; D\left(\tilde{A}_{q}\right)\right), \quad u_{t} \in Y_{q}
$$

of the evolution system (2.17), satisfying the estimate

$$
\begin{equation*}
\left\|u_{t}\right\|_{Y_{q}}+\|u\|_{Y_{q}}+\left\|\tilde{A}_{q} u\right\|_{Y_{q}} \leqslant C\left(\left\|u_{0}\right\|_{D\left(\tilde{A}_{q}\right)}+\|f\|_{Y_{q}}\right) \tag{2.18}
\end{equation*}
$$

with $C=C(q, T, \alpha, \beta, K)>0$.

Remark 2.6. (a) The assumption $u_{0} \in D\left(\tilde{A}_{q}\right)$ in this theorem is not optimal and may be replaced by the weaker properties $u_{0} \in \tilde{L}_{\sigma}^{q}$ and $\int_{0}^{T}\left\|\tilde{A}_{q} e^{-t \tilde{A}_{q}} u_{0}\right\|_{\tilde{L}_{\sigma}^{q}}^{q} d t<\infty$. Then the term $\left\|u_{0}\right\|_{D\left(\tilde{A}_{q}\right)}$ in (2.18) may be substituted by the weaker norm

$$
\begin{equation*}
\left(\int_{0}^{T}\left\|\tilde{A}_{q} e^{-t \tilde{A}_{q}} u_{0}\right\|_{\tilde{L}_{\sigma}^{q}}^{q} d t\right)^{1 / q}, \quad 1<q<\infty \tag{2.19}
\end{equation*}
$$

Furthermore, by (2.16), the estimate (2.18) implies that

$$
\begin{equation*}
\left\|u_{t}\right\|_{Y_{q}}+\|u\|_{L^{q}\left(0, T ; \widetilde{W}^{2, q}\right)} \leqslant C\left(\left\|u_{0}\right\|_{D\left(\tilde{A}_{q}\right)}+\|f\|_{Y_{q}}\right) \tag{2.20}
\end{equation*}
$$

where $C=C(q, T, \alpha, \beta, K)>0$.
(b) Let $f \in Y_{q}=L^{q}\left(0, T ; \tilde{L}_{\sigma}^{q}\right)$ in Theorem 2.5 be replaced by $f \in \widehat{Y}_{q}=L^{q}\left(0, T ; \tilde{L}^{q}\right)$, $1<q<\infty$. Then $u \in L^{q}\left(0, T ; D\left(\tilde{A}_{q}\right)\right)$, defined by $u_{t}+\tilde{A}_{q} u=\widetilde{P}_{q} f$, and $\nabla p$, defined by $\nabla p(t)=\left(I-\widetilde{P}_{q}\right)(f+\Delta u)(t)$, is a unique solution pair of the system

$$
u_{t}-\Delta u+\nabla p=f, \quad u(0)=u_{0}
$$

satisfying

$$
\begin{equation*}
\left\|u_{t}\right\|_{Y_{q}}+\|u\|_{Y_{q}}+\left\|\nabla^{2} u\right\|_{\hat{Y}_{q}}+\|\nabla p\|_{\widehat{Y}_{q}} \leqslant C\left(\left\|u_{0}\right\|_{D\left(\tilde{A}_{q}\right)}+\|f\|_{\hat{Y}_{q}}\right) \tag{2.21}
\end{equation*}
$$

with $C=C(q, T, \alpha, \beta, K)>0$.
Using (2.3) we see that in the case $1<q<2$, the solution pair $u, \nabla p$ possesses a decomposition $u=u^{(1)}+u^{(2)}, \nabla p=\nabla p^{(1)}+\nabla p^{(2)}$ such that

$$
\begin{array}{rr}
u^{(1)} \in L^{q}\left(0, T ; W^{2,2}\right), & u_{t}^{(1)} \in L^{q}\left(0, T ; L_{\sigma}^{2}\right), \\
u^{(2)} \in L^{q}\left(0, T ; W^{2, q}\right), & u_{t}^{(2)} \in L^{q}\left(0, T ; L_{\sigma}^{q}\right),  \tag{2.22}\\
\nabla p^{(1)} \in L^{q}\left(0, T ; L^{2}\right), & \nabla p^{(2)} \in L^{q}\left(0, T ; L^{q}\right),
\end{array}
$$

and

$$
\begin{aligned}
\left\|u_{t}\right\|_{Y_{q}}+\|u\|_{Y_{q}}+\left\|\nabla^{2} u\right\|_{\widehat{Y}_{q}}+\|\nabla p\|_{\widehat{Y}_{q}}=\left\|u_{t}^{(1)}\right\|_{\widehat{Y}_{q}^{(1)}} & +\left\|u^{(1)}\right\|_{\hat{Y}_{q}^{(1)}}+\left\|\nabla^{2} u^{(1)}\right\|_{\hat{Y}_{q}^{(1)}}+\left\|\nabla p^{(1)}\right\|_{\widehat{Y}_{q}^{(1)}} \\
& +\left\|u_{t}^{(2)}\right\|_{\hat{Y}_{q}^{(2)}}+\left\|u^{(2)}\right\|_{\hat{Y}_{q}^{(2)}} \\
& +\left\|\nabla^{2} u^{(2)}\right\|_{\widehat{Y}_{q}^{(2)}}+\left\|\nabla p^{(2)}\right\|_{\hat{Y}_{q}^{(2)}}
\end{aligned}
$$

where $\widehat{Y}_{q}^{(1)}=L^{q}\left(0, T ; L^{2}\right)$ and $\widehat{Y}_{q}^{(2)}=L^{q}\left(0, T ; L^{q}\right)$.

### 2.5. Applications

As an application we construct a so-called suitable weak solution $u$ of the instationary Navier-Stokes system

$$
\begin{gather*}
u_{t}-\Delta u+u \cdot \nabla u+\nabla p=f, \quad \operatorname{div} u=0 \text { in } \Omega \times(0, T) \\
\left.u\right|_{\partial \Omega}=0, \quad u(0)=u_{0} \tag{2.23}
\end{gather*}
$$

for the general domain $\Omega \subset \mathbf{R}^{3}$ with important additional properties. In particular, we are interested in estimate (2.21) for $q=\frac{5}{4}$. The reason is that the energy properties $u \in L^{\infty}\left(0, T ; L_{\sigma}^{2}\right)$ and $\nabla u \in L^{2}\left(0, T ; L^{2}\right)$ imply that $u \cdot \nabla u \in L^{q}\left(0, T ; L^{q}\right)$ with $q=\frac{5}{4}$. Hence, shifting $u \cdot \nabla u$ in (2.23) to the right-hand side and considering for simplicity $u_{0}=0$, we get from (2.21) that $\nabla p \in L^{q}\left(0, T ; L^{2}+L^{q}\right)$ and $\nabla p \in L_{\mathrm{loc}}^{q}((0, T) \times \bar{\Omega})$. This property is needed in the local regularity theory as well as in the proof of the local energy estimate. It was conjectured in [8, p. 780], and open up to now for general domains.

Moreover, we prove that $u$ satisfies the strong energy inequality, see [14], [26], [32] and [33], which was open for general domains as well. A consequence is Leray's structure theorem [23] for general domains; note that the proof in [23] concerns the entire space $\mathbf{R}^{3}$ only.

We recall some definitions, see, e.g., [32] and [35]. The space $C_{0}^{\infty}\left([0, T) ; C_{0, \sigma}^{\infty}\right)$ consists of smooth solenoidal vector fields $v$ defined on $[0, T) \times \Omega$ with compact support $\operatorname{supp} v \subseteq[0, T) \times \Omega$.

Let $f \in L^{5 / 4}\left(0, T ; L^{2}\right), 0<T \leqslant \infty$, and $u_{0} \in L_{\sigma}^{2}$. Then a function

$$
u \in L^{\infty}\left(0, T ; L_{\sigma}^{2}\right) \cap L_{\mathrm{loc}}^{2}\left([0, T) ; W_{0, \sigma}^{1,2}\right)
$$

is called a weak solution of (2.23) if and only if

$$
\begin{equation*}
-\left\langle u, v_{t}\right\rangle_{\Omega, T}+\langle\nabla u, \nabla v\rangle_{\Omega, T}+\langle u \cdot \nabla u, v\rangle_{\Omega, T}=\left\langle u_{0}, v(0)\right\rangle_{\Omega}+\langle f, v\rangle_{\Omega, T} \tag{2.24}
\end{equation*}
$$

is satisfied for all $v \in C_{0}^{\infty}\left([0, T) ; C_{0, \sigma}^{\infty}\right)$. We may assume without loss of generality that $u$ is weakly continuous as a function from $[0, T)$ to $L_{\sigma}^{2}$.

We know that for each weak solution $u$ there exists a distribution $p$ in $(0, T) \times \Omega$ such that $u_{t}-\Delta u+u \cdot \nabla u+\nabla p=f$ holds in the sense of distributions, see [19], [28] and [32]; $p$ is called an associated pressure of $u$. However, for general $\Omega$ it is crucial whether $p$ is contained in any $L^{q}$-type space; the problem in this context is the validity of the maximal regularity estimate (2.21) for $q=\frac{5}{4}$.

The following result is essentially known for domains with compact boundaries; see [32, Chapter V, Theorem 3.6.2] for bounded domains, and [26] and [33] for exterior domains.

Theorem 2.7. (Suitable weak solution.) Let $\Omega \subseteq \mathbf{R}^{3}$ be a uniform $C^{2}$-domain of type $\alpha, \beta, K$, and let $0<T \leqslant \infty, q=\frac{5}{4}, f \in L^{q}\left(0, T ; L^{2}\right)$ and $u_{0} \in L_{\sigma}^{2}$. Then there exists a weak solution $u \in L^{\infty}\left(0, T ; L_{\sigma}^{2}\right) \cap L_{\mathrm{loc}}^{2}\left([0, T) ; W_{0, \sigma}^{1,2}\right)$ (called a suitable weak solution) of the system (2.23) and an associated pressure $p$ with the following additional properties:
(a) Regularity:

$$
\begin{equation*}
u_{t}, u, \nabla u, \nabla^{2} u, \nabla p \in L^{q}\left(\varepsilon, T^{\prime} ; L^{2}+L^{q}\right) \tag{2.25}
\end{equation*}
$$

for all $0<\varepsilon<T^{\prime}<T$. If $u_{0} \in D\left(\tilde{A}_{q}\right)$, then (2.25) holds for $\varepsilon=0$ and all $0<T^{\prime}<T$.
(b) Local energy inequality:

$$
\begin{align*}
\frac{1}{2}\|\phi u(t)\|_{2}^{2}+\int_{s}^{t}\|\phi \nabla u\|_{2}^{2} d \tau \leqslant & \frac{1}{2}\|\phi u(s)\|_{2}^{2}+\int_{s}^{t}\langle\phi f, \phi u\rangle d \tau  \tag{2.26}\\
& \left.\left.-\left.\frac{1}{2} \int_{s}^{t}\langle\nabla| u\right|^{2}, \nabla \phi^{2}\right\rangle d \tau+\left.\int_{s}^{t}\left\langle\frac{1}{2}\right| u\right|^{2}+p, u \cdot \nabla \phi^{2}\right\rangle d \tau
\end{align*}
$$

for a.a. $s \in[0, T)$, all $t \in[s, T)$ and all $\phi \in C_{0}^{\infty}\left(\mathbf{R}^{3}\right)$.
(c) Strong energy inequality:

$$
\begin{equation*}
\frac{1}{2}\|u(t)\|_{2}^{2}+\int_{s}^{t}\|\nabla u\|_{2}^{2} d \tau \leqslant \frac{1}{2}\|u(s)\|_{2}^{2}+\int_{s}^{t}\langle f, u\rangle d \tau \tag{2.27}
\end{equation*}
$$

for a.a. $s \in[0, T)$ including $s=0$, and all $t \in[s, T)$.
Remark 2.8. (a) From (2.25) we obtain the existence of some pressure $p$ satisfying

$$
\begin{equation*}
p \in L^{q}\left(\varepsilon, T^{\prime} ; L_{\mathrm{loc}}^{r}(\bar{\Omega})\right), \quad 0<\varepsilon<T^{\prime}<T, q=\frac{5}{4}, r=\frac{15}{7}, \tag{2.28}
\end{equation*}
$$

and we get that $u \in L^{2}\left(0, T^{\prime} ; L^{6}(\Omega)\right), 0<T^{\prime}<T$. This shows that (2.26) is well defined. As in (2.22) we obtain decompositions $u=u^{(1)}+u^{(2)}$ and $p=p^{(1)}+p^{(2)}$ satisfying

$$
\begin{equation*}
u_{t}^{(1)}, u^{(1)}, \nabla u^{(1)}, \nabla^{2} u^{(1)}, \nabla p^{(1)} \in L^{q}\left(\varepsilon, T^{\prime} ; L^{2}\right) \quad \text { for } 0<\varepsilon<T^{\prime}<T \tag{2.29}
\end{equation*}
$$

and

$$
\begin{equation*}
u_{t}^{(2)}, u^{(2)}, \nabla u^{(2)}, \nabla^{2} u^{(2)}, \nabla p^{(2)} \in L^{q}\left(\varepsilon, T^{\prime} ; L^{q}\right) \quad \text { for } 0<\varepsilon<T^{\prime}<T, \tag{2.30}
\end{equation*}
$$

which holds with $\varepsilon=0$ if additionally $u_{0} \in D\left(\tilde{A}_{q}\right)$. Note that we may choose $T^{\prime}=T$ in (2.25) if $T<\infty$.
(b) To obtain Leray's structure theorem for $\Omega$, see [23] for the case $\mathbf{R}^{3}$, let $T=\infty$ and assume for simplicity that $f=0$. Then $u$ in Theorem 2.7, also called a turbulent weak solution of (2.23), has the following properties: There exists a countable disjoint family $\left\{I_{k}\right\}_{k=0}^{\infty}$ of intervals in $(0, \infty)$ such that
(1) $I_{1}=\left(0, T_{1}\right)$ and $I_{0}=\left[T_{\infty}, \infty\right)$ with some $0<T_{1} \leqslant T_{\infty}<\infty$;
(2) $\left|(0, \infty) \backslash \bigcup_{k=0}^{\infty} I_{k}\right|=0$ and $\sum_{k=1}^{\infty}\left|I_{k}\right|^{1 / 2}<\infty$, where $|\cdot|$ denotes the Lebesgue measure;
(3) $u(\cdot, t) \in C^{\infty}(\Omega)$ for every $t \in I_{k}, k=0,1, \ldots$.

These properties imply that the $\frac{1}{2}$-dimensional Hausdorff measure of the singular set $\sigma=\left\{t \in(0, \infty): u(\cdot, t) \notin C^{\infty}(\Omega)\right\}$ is zero, see [8].

## 3. Proofs

### 3.1. Preliminary local results

Using the structure properties of the given uniform $C^{2}$-domain $\Omega \subseteq \mathbf{R}^{3}$ of type $\alpha, \beta, K>0$, see $\S 2.3$, we are able to reduce our results by the localization principle to a standard domain of the form

$$
\begin{equation*}
H=H_{\alpha, \beta, r, h}=\left\{\left(y^{\prime}, y_{3}\right): h\left(y^{\prime}\right)-\beta<y_{3}<h\left(y^{\prime}\right),\left|y^{\prime}\right|<\alpha\right\} \cap B_{r} \tag{3.1}
\end{equation*}
$$

here $h: y^{\prime} \mapsto h\left(y^{\prime}\right),\left|y^{\prime}\right| \leqslant \alpha$, is a $C^{2}$-function and $B_{r}=B_{r}(0)$ a ball with radius $0<r=$ $r(\alpha, \beta, K)<\alpha$ such that

$$
\bar{B}_{r} \subseteq\left\{\left(y^{\prime}, y_{3}\right): h\left(y^{\prime}\right)-\beta<y_{3}<h\left(y^{\prime}\right)+\beta,\left|y^{\prime}\right|<\alpha\right\} .
$$

Further, we may assume that $h(0)=0, \nabla^{\prime} h(0)=(0,0), h\left(y^{\prime}\right)=0$ for $r \leqslant\left|y^{\prime}\right| \leqslant \alpha$, and that $h$ satisfies the smallness condition

$$
\begin{equation*}
\left\|\nabla^{\prime} h\right\|_{C^{0}}=\max \left\{\left|\nabla^{\prime} h\left(y^{\prime}\right)\right|:\left|y^{\prime}\right| \leqslant \alpha\right\} \leqslant M_{0} \tag{3.2}
\end{equation*}
$$

where $M_{0}>0$ is a given constant. Recall that $\nabla^{\prime}=\left(D_{1}, D_{2}\right)$.
In the subsequent proofs we can treat each problem for the standard domain (3.1) as a problem in the domain

$$
H_{h}=\left\{\left(y^{\prime}, y_{3}\right) \in \mathbf{R}^{3}: y_{3}<h\left(y^{\prime}\right), y^{\prime} \in \mathbf{R}^{2}\right\}
$$

with $h \in C_{0}^{2}\left(\mathbf{R}^{2}\right) ; H_{h}$ is called a bent half-space, see [9]. Then, using the smallness condition (3.2), an equation in $H_{h}$ is considered as a perturbation of some equation in the half-space $H_{0}=\left\{\left(y^{\prime}, y_{3}\right) \in \mathbf{R}^{3}: y_{3}<0\right\}$.

The following estimates in $H=H_{\alpha, \beta, h, r}$ are well known. However, we have to check that the constants in these estimates depend only on $q, \alpha, \beta$ and $K$; here we need the smallness condition (3.2) on $h$.

Let $1<q<\infty$. First we consider the Helmholtz decomposition in $H$. Let $f \in L^{q}(H)$, $f_{0} \in L_{\sigma}^{q}(H)$ and $p \in W^{1, q}(H)$ satisfy $f=f_{0}+\nabla p$ and supp $f_{0} \cup \operatorname{supp} p \subseteq B_{r}$. Then

$$
\begin{equation*}
\left\|f_{0}\right\|_{L^{q}(H)}+\|\nabla p\|_{L^{q}(H)} \leqslant C\|f\|_{L^{q}(H)}, \quad C=C(q, \alpha, \beta, K)>0 \tag{3.3}
\end{equation*}
$$

cf. [30, p. 12 and Lemma 3.8 (a)].
Next let $f \in L^{q}(H), u \in L_{\sigma}^{q}(H) \cap W_{0}^{1, q}(H) \cap W^{2, q}(H)$ and $p \in W^{1, q}(H)$ satisfy

$$
\lambda u-\Delta u+\nabla p=f
$$

with $\lambda \in \mathcal{S}_{\mathcal{E}}$, see Theorem 2.3, and with supp $u \cup \operatorname{supp} p \subseteq B_{r}$. Then there are constants $\lambda_{0}=\lambda_{0}(q, \alpha, \beta, K)>0$ and $C=C(q, \alpha, \beta, K)>0$ such that

$$
\begin{equation*}
|\lambda|\|u\|_{L^{q}(H)}+\|u\|_{W^{2, q}(H)}+\|\nabla p\|_{L^{q}(H)} \leqslant C\|f\|_{L^{q}(H)} \tag{3.4}
\end{equation*}
$$

if $|\lambda| \geqslant \lambda_{0}$. To prove this estimate we use $[9$, p. 624] and apply [9, Theorem 3.1 (i) and (1.2)].

The next estimate concerns the nonstationary Stokes equation in $H$. As usual the Stokes operator is defined by $A_{q}=-P_{q} \Delta$ with domain

$$
D\left(A_{q}\right)=L_{\sigma}^{q}(H) \cap W_{0}^{1, q}(H) \cap W^{2, q}(H)
$$

Let $0<T<\infty, u_{0} \in D\left(A_{q}\right)$ and $f \in L^{q}\left(0, T ; L^{q}(H)\right)$, and let $u \in L^{q}\left(0, T, D\left(A_{q}\right)\right)$ and $p \in$ $L^{q}\left(0, T ; W^{\mathbf{1}, q}(H)\right)$ satisfy $\operatorname{supp} u_{0} \cup \operatorname{supp} u(t) \cup \operatorname{supp} p(t) \subseteq B_{r}$ for a.a. $t \in[0, T]$. Moreover, assume that

$$
u_{t}-\Delta u+\nabla p=f, \quad u(0)=u_{0} \quad \text { and } \quad-u_{t}-\Delta u+\nabla p=f, \quad u(T)=u_{0}
$$

respectively. Then there is a constant $C=C(q, \alpha, \beta, K, T)>0$ such that

$$
\begin{align*}
\left\|u_{t}\right\|_{L^{q}\left(0, T ; L^{q}(H)\right)}+\|u\|_{L^{q}\left(0, T ; W^{2, q}(H)\right)}+ & \|\nabla p\|_{L^{q}\left(0, T ; L^{q}(H)\right)}  \tag{3.5}\\
& \leqslant C\left(\left\|u_{0}\right\|_{W^{2, q}(H)}+\|f\|_{L^{q}\left(0, T ; L^{q}(H)\right)}\right)
\end{align*}
$$

In the case $u(0)=u_{0}$ this estimate follows from [34, Theorem 4.1, (4.2) and (4.21')]. The second case $-u_{t}-\Delta u+\nabla p=f, u(T)=u_{0}$, can be reduced to the first case by the transformation $\tilde{u}(t)=u(T-t), \tilde{f}(t)=f(T-t), \tilde{p}(t)=p(T-t)$. The relatively strong assumption $u_{0} \in D\left(A_{q}\right)$ is used for simplicity and can be weakened as in Remark 2.6 (a). Note that the conditions $u(0)=u_{0}$ and $u(T)=u_{0}$, respectively, are well defined since $u_{t} \in L^{q}\left(0, T ; L_{\sigma}^{q}\right)$.

Finally, we consider the divergence problem

$$
\operatorname{div} u=f \text { in } H,\left.\quad u\right|_{\partial H}=0
$$

and let $L_{0}^{q}(H)=\left\{f \in L^{q}(H): \int_{H} f d x=0\right\}$. Then from [6] and [12, III, Theorem 3.2], we obtain the existence of some linear operator $R: L_{0}^{q}(H) \rightarrow W_{0}^{1, q}(H)$ satisfying div $R f=f$ and

$$
\begin{array}{ll}
\|R f\|_{W^{1, q}(H)} \leqslant C\|f\|_{L^{q}(H)} & \text { if } f \in L_{0}^{q}(H) \\
\|R f\|_{W^{2, q}(H)} \leqslant C\|f\|_{W^{1, q}(H)} & \text { if } f \in L_{0}^{q}(H) \cap W_{0}^{1, q}(H) \tag{3.6}
\end{array}
$$

with $C=C(q, \alpha, \beta, K)>0$; moreover, $R f \in W_{0}^{2, q}(H)$ if $f \in L_{0}^{q}(H) \cap W_{0}^{1, q}(H)$.

The dual operator $R^{\prime}$ of $R$ maps $W^{-1, q^{\prime}}(H)$ into $L_{0}^{q^{\prime}}(H)$. Thus for each $p \in L^{q^{\prime}}(H)$ we find a unique constant $M=M(p)$ satisfying $p-M=R^{\prime}(\nabla p) \in L_{0}^{q^{\prime}}(H)$ and the estimate

$$
\begin{equation*}
\|p-M\|_{L^{q^{\prime}}(H)} \leqslant C\|\nabla p\|_{W^{-1 . q^{\prime}(H)}}=C \sup \left\{\frac{|\langle p, \operatorname{div} v\rangle|}{\|\nabla v\|_{q}}: 0 \neq v \in W_{0}^{1, q}(H)\right\} \tag{3.7}
\end{equation*}
$$

with $C=C(q, \alpha, \beta, K)>0$.
Now let $\Omega \subseteq \mathbf{R}^{3}$ be a bounded $C^{2}$-domain with boundary $\partial \Omega$. Obviously, such a domain is of type $\alpha, \beta, K$. We collect several results on the Helmholtz projection $P=P_{q}$ and the Stokes operator $A=A_{q}, 1<q<\infty$. In this case the constant $C$ below may depend also on $\Omega$ except for $q=2$ where Hilbert space arguments are applicable.

It is known, see [11], [30] and [34], that each $f \in L^{q}$ has a unique decomposition $f=f_{0}+\nabla p, f_{0} \in L_{\sigma}^{q}, \nabla p \in G^{q}$, and that $P_{q}: L^{q} \rightarrow L_{\sigma}^{q}$ defined by $P_{q} f=f_{0}$ satisfies the estimate $\left\|P_{q} f\right\|_{L^{q}}+\|\nabla p\|_{L^{q}} \leqslant C\|f\|_{L^{q}}$ with $C=C(q, \Omega)>0$; however, it is not clear whether $C$ depends only on the type $\alpha, \beta, K$. We obtain that $\left(P_{q}\right)^{\prime}=P_{q^{\prime}}$ and $\left\langle P_{q} f, g\right\rangle=\left\langle f, P_{q^{\prime}} g\right\rangle$ for all $f \in L^{q}$ and $g \in L^{q^{\prime}}$. If $q=2$, a Hilbert space argument yields the estimate

$$
\begin{equation*}
\left\|P_{2} f\right\|_{L^{2}}+\|\nabla p\|_{L^{2}} \leqslant 2\|f\|_{L^{2}}, \quad f \in L^{2}, \nabla p \in G^{2} \tag{3.8}
\end{equation*}
$$

with $C=C(2, \Omega)=2$ not depending on $\Omega$.
The Stokes operator $A_{q}=-P_{q} \Delta: D\left(A_{q}\right) \rightarrow L_{\sigma}^{q}$, where $D\left(A_{q}\right)=L_{\sigma}^{q} \cap W_{0}^{1, q} \cap W^{2, q}$, satisfies the resolvent estimate

$$
|\lambda|\|u\|_{L^{q}}+\left\|A_{q} u\right\|_{L^{q}} \leqslant C\|f\|_{L^{q}}, \quad C=C(\varepsilon, q, \Omega)>0
$$

where $u \in D\left(A_{q}\right), \lambda u+A_{q} u=f, \lambda \in \mathcal{S}_{\varepsilon}$ and $0<\varepsilon<\frac{1}{2} \pi$, and the estimate

$$
\|u\|_{W^{2, q}} \leqslant C\left\|A_{q} u\right\|_{L^{q}}, \quad C=C(q, \Omega)
$$

Furthermore, $A_{q}^{\prime}=A_{q^{\prime}}$ implying that $\left\langle A_{q} u, v\right\rangle=\left\langle u, A_{q^{\prime}} v\right\rangle$ for all $u \in D\left(A_{q}\right)$ and $v \in D\left(A_{q^{\prime}}\right)$; see [2], [3], [9], [13], [15], [16], [17], [21], [22] and [34]. If $q=2$, we obtain by a Hilbert space argument that $u \in D\left(A_{2}\right)$, with $\lambda u+A_{2} u=f \in L_{\sigma}^{2}, \lambda \in \mathcal{S}_{\varepsilon}$, satisfies the estimate

$$
\begin{equation*}
|\lambda|\|u\|_{L^{2}}+\left\|A_{2} u\right\|_{L^{2}} \leqslant C\|f\|_{L^{2}}, \quad C=1+\frac{2}{\cos \varepsilon} \tag{3.9}
\end{equation*}
$$

with $C$ independent of $\Omega$. Moreover, since $A_{2}$ is selfadjoint,

$$
\begin{equation*}
\left\langle A_{2} u, u\right\rangle=\left\|A_{2}^{1 / 2} u\right\|_{L^{2}}^{2}=\|\nabla u\|_{L^{2}}^{2}, \quad u \in D\left(A_{2}\right) \tag{3.10}
\end{equation*}
$$

Let $1<q, r<\infty, 0<T<\infty$ and $f \in L^{r}\left(0, T ; L_{\sigma}^{q}\right), u_{0} \in D\left(A_{q}\right)$. Then the semigroup operators $e^{-t A_{q}}$ and the operators $\mathcal{J}_{q, r}$ and $\mathcal{J}_{q, r}^{\prime}$ given by

$$
\left(\mathcal{J}_{q, r}\right) f(t)=\int_{0}^{t} e^{-(t-\tau) A_{q}} f(\tau) d \tau \quad \text { and } \quad\left(\mathcal{J}_{q, r}^{\prime} f\right)(t)=\int_{t}^{T} e^{-(\tau-t) A_{q}} f(\tau) d \tau
$$

are well defined for $0 \leqslant t \leqslant T$, see [9] and [15]. Setting $u(t)=e^{-t A_{q}} u_{0}+\left(\mathcal{J}_{q, r} f\right)(t)$ we obtain the unique solution $u \in L^{r}\left(0, T ; D\left(A_{q}\right)\right)$, $u_{t} \in L^{r}\left(0, T ; L_{\sigma}^{q}\right)$, of the nonstationary Stokes system $u_{t}+A_{q} u=f, u(0)=u_{0}$, satisfying the estimate

$$
\begin{equation*}
\left\|u_{t}\right\|_{L^{r}\left(L^{q}\right)}+\|u\|_{L^{r}\left(L^{q}\right)}+\left\|A_{q} u\right\|_{L^{r}\left(L^{q}\right)} \leqslant C\left(\left\|u_{0}\right\|_{D\left(A_{q}\right)}+\|f\|_{L^{r}\left(L^{q}\right)}\right) \tag{3.11}
\end{equation*}
$$

with $C=C(q, r, T, \Omega)>0$. For our application it is important that $C=C(2, r, T, \Omega)=$ $C(r, T)$ does not depend on $\Omega$ if $q=2$, see [31] and [32, IV.1.6]. Analogously, $u(t)=$ $e^{-(T-t) A_{q}} u_{0}+\left(\mathcal{J}_{q, r}^{\prime} f\right)(t)$ is the unique solution of the system $-u_{t}+A_{q} u=f, u(T)=u_{0}$, in $L^{r}\left(0, T ; D\left(A_{q}\right)\right)$ with $u_{t} \in L^{r}\left(0, T ; L_{\sigma}^{q}\right)$ satisfying the estimate (3.11) with the same constant $C$; this result follows from the transformation $\tilde{u}(t)=u(T-t), \tilde{f}(t)=f(T-t)$. Further, we obtain the duality relation

$$
\begin{equation*}
\left(\mathcal{J}_{q, r}\right)^{\prime}=\mathcal{J}_{q^{\prime}, r^{\prime}}^{\prime} \tag{3.12}
\end{equation*}
$$

Finally we mention some well-known embedding estimates for Sobolev spaces on bounded $C^{2}$-domains $\Omega$ of type $\alpha, \beta, K$, see [1, IV, Theorem 4.28], [10] and [32, II.1.3]. Given $1<q<\infty$ and $0<M \leqslant 1$, there exists some $C=C(q, M, \alpha, \beta, K)>0$ such that

$$
\begin{equation*}
\|\nabla u\|_{L^{q}} \leqslant M\left\|\nabla^{2} u\right\|_{L^{q}}+C\|u\|_{L^{q}} \tag{3.13}
\end{equation*}
$$

for all $u \in W^{2, q}$. If $2 \leqslant q<\infty$ and $0<M \leqslant 1$, then there exists some $C=C(q, M, \alpha, \beta, K)>0$ such that

$$
\begin{equation*}
\|u\|_{L^{q}} \leqslant M\left\|\nabla^{2} u\right\|_{L^{2}}+C\|u\|_{L^{2}} \tag{3.14}
\end{equation*}
$$

for all $u \in W^{2,2}$. Finally, let $1<q, \gamma<\infty, 1<r \leqslant 3$ and $0 \leqslant \alpha \leqslant 1$ such that

$$
\alpha\left(\frac{1}{r}-\frac{1}{3}\right)+(1-\alpha) \frac{1}{\gamma}=\frac{1}{q}
$$

Then

$$
\begin{equation*}
\|u\|_{L^{a}} \leqslant C\|\nabla u\|_{L^{r}}^{\alpha}\|u\|_{L^{\gamma}}^{1-\alpha} \tag{3.15}
\end{equation*}
$$

for all $u \in W_{0}^{1, r} \cap L^{\gamma}$ with $C=C(r, q, \gamma)>0$.

### 3.2. Helmholtz projection in $\tilde{L}^{q}$; Proof of Theorem 2.1

The proofs of the main theorems rest on the localization principle using the structure of the domain $\Omega$ of the type $\alpha, \beta, K>0$, see $\S 2.3$, and the local estimates in $\S 3.1$. In the first step of each proof we assume that $\Omega$ is bounded. In this case cover $\bar{\Omega}$ by domains of the form

$$
\begin{equation*}
U_{j}=U_{\alpha, \beta, h_{j}}^{-}\left(x_{j}\right) \cap B_{j}, \quad j=1,2, \ldots, N \tag{3.16}
\end{equation*}
$$

with $B_{j}=B_{r}\left(x_{j}\right), 0<r=r(\alpha, \beta, K)<\alpha, x_{j} \in \bar{\Omega}$ and functions $h_{j} \in C^{2}$, where $h_{j} \equiv 0$ if $x_{j} \in \Omega$, and use the cut-off functions $\varphi_{j}$ as in (2.6) and (2.7). We may assume that each $U_{j}$ has the standard form $H=H_{\alpha, \beta, r, h}$, see (3.1) and (2.9). In the second step of each proof we consider the sequence of bounded subdomains $\Omega_{j} \subseteq \Omega$ of the same type $\alpha, \beta, K$, see (2.8), and treat the limit $j \rightarrow \infty$.

Step 1. $\Omega$ bounded. Let $f \in L^{q}, 2 \leqslant q<\infty, f_{0}=P_{q} f \in L_{\sigma}^{q}$ and $\nabla p=f-f_{0} \in G^{q}$. Then $f \in L^{2}$, and we obtain, see $\S 3.1$, that

$$
\begin{equation*}
\left\|f_{0}\right\|_{L^{2} \cap L^{q}}+\|\nabla p\|_{L^{2} \cap L^{q}} \leqslant C\|f\|_{L^{2} \cap L^{q}} \tag{3.17}
\end{equation*}
$$

with $C=C(q, \Omega)>0$. First we show that the constant $C$ in (3.17) can be chosen depending only on $q, \alpha, \beta$ and $K$. For this purpose consider in $U_{j}$ the local equation

$$
\varphi_{j} f=\varphi_{j} f_{0}+\nabla\left(\varphi_{j}\left(p-M_{j}\right)\right)-\left(\nabla \varphi_{j}\right)\left(p-M_{j}\right)
$$

with the constant $M_{j}=M_{j}(p)$ such that $p-M_{j}=R^{\prime}(\nabla p) \in L_{0}^{q}\left(U_{j}\right)$, see (3.7). Furthermore, we use the solution $w=R\left(\left(\nabla \varphi_{j}\right) \cdot f_{0}\right) \in W_{0}^{1, q}\left(U_{j}\right)$ of the equation $\operatorname{div} w=\operatorname{div}\left(\varphi_{j} f_{0}\right)=$ $\left(\nabla \varphi_{j}\right) \cdot f_{0} \in L_{0}^{q}\left(U_{j}\right)$, see (3.6). Then

$$
\varphi_{j} f+\left(\nabla \varphi_{j}\right)\left(p-M_{j}\right)-w=\left(\varphi_{j} f_{0}-w\right)+\nabla\left(\varphi_{j}\left(p-M_{j}\right)\right)
$$

is the Helmholtz decomposition of $\varphi_{j} f+\left(\nabla \varphi_{j}\right)\left(p-M_{j}\right)-w$ in $L^{q}\left(U_{j}\right)$, and we may use estimate (3.3).

First let $2 \leqslant q \leqslant 6$. Then (3.6), (3.15) with $r=\gamma=2$, and Poincaré's inequality imply that $\|w\|_{L^{q}\left(U_{j}\right)} \leqslant C\left\|f_{0}\right\|_{L^{2}\left(U_{j}\right)}$ with $C=C(q, \alpha, \beta, K)>0$. Further, considering $p-M_{j}$, we apply (3.7), (3.15) and Poincaré's inequality to obtain with $\nabla p=f-f_{0}$ that

$$
\left\|p-M_{j}\right\|_{L^{q}\left(U_{j}\right)} \leqslant C\left(\|f\|_{L^{q}\left(U_{j}\right)}+\left\|f_{0}\right\|_{L^{2}\left(U_{j}\right)}\right)
$$

where $C=C(q, \alpha, \beta, K)>0$. Combining these estimates we get the inequality

$$
\begin{equation*}
\left\|\varphi_{j} f_{0}\right\|_{L^{q}\left(U_{j}\right)}^{q}+\left\|\varphi_{j} \nabla p\right\|_{L^{q}\left(U_{j}\right)}^{q} \leqslant C\left(\|f\|_{L^{q}\left(U_{j}\right)}^{q}+\left\|f_{0}\right\|_{L^{2}\left(U_{j}\right)}^{q}\right) \tag{3.18}
\end{equation*}
$$

with $C=C(q, \alpha, \beta, K)>0$. Next we will take the sum for $j=1, \ldots, N$, and use the number $N_{0}=N_{0}(\alpha, \beta, K) \in \mathbf{N}$ introduced in $\S 2.3$, Hölder's inequality and the reverse Hölder
inequality $\left(\sum_{j=1}^{N}\left|a_{j}\right|^{q}\right)^{1 / q} \leqslant\left(\sum_{j=1}^{N}\left|a_{j}\right|^{2}\right)^{1 / 2}$. This leads to the crucial estimate

$$
\begin{align*}
\left\|f_{0}\right\|_{L^{q}(\Omega)}^{q}+\|\nabla p\|_{L^{q}(\Omega)}^{q} & =\int_{\Omega}\left(\sum_{j=1}^{N} \varphi_{j}\left|f_{0}\right|\right)^{q} d x+\int_{\Omega}\left(\sum_{j=1}^{N} \varphi_{j}|\nabla p|\right)^{q} d x \\
& \leqslant \int_{\Omega} N_{0}^{q / q^{\prime}}\left(\sum_{j=1}^{N}\left|\varphi_{j} f_{0}\right|^{q}\right) d x+\int_{\Omega} N_{0}^{q / q^{\prime}}\left(\sum_{j=1}^{N}\left|\varphi_{j} \nabla p\right|^{q}\right) d x \\
& =N_{0}^{q / q^{\prime}}\left(\sum_{j=1}^{N}\left\|\varphi_{j} f_{0}\right\|_{L^{q}\left(U_{j}\right)}^{q}+\sum_{j=1}^{N}\left\|\varphi_{j} \nabla p\right\|_{L^{q}\left(U_{j}\right)}^{q}\right)  \tag{3.19}\\
& \leqslant C_{1}\left(\sum_{j=1}^{N}\|f\|_{L^{q}\left(U_{j}\right)}^{q}+\left(\sum_{j=1}^{N}\left\|f_{0}\right\|_{L^{2}\left(U_{j}\right)}^{2}\right)^{q / 2}\right) \\
& \leqslant C_{2}\left(\|f\|_{L^{q}(\Omega)}^{q}+\left\|f_{0}\right\|_{L^{2}(\Omega)}^{q}\right)
\end{align*}
$$

with $C_{i}=C_{i}(q, \alpha, \beta, K)>0, i=1,2$, and $2 \leqslant q \leqslant 6$; this kind of estimate will be used in an analogous way also in the subsequent proofs in $\S 3.3$ and $\S 3.4$.

In the case $6<q<\infty$ we obtain the estimate (3.19) in the same way as above with $\left\|f_{0}\right\|_{L^{2}(\Omega)}^{q}$ replaced by $\left\|f_{0}\right\|_{L^{6}(\Omega)}^{q}$. Now we use the elementary interpolation estimate

$$
\left\|f_{0}\right\|_{L^{6}(\Omega)} \leqslant \gamma\left(\frac{1}{\varepsilon}\right)^{1 / \gamma}\left\|f_{0}\right\|_{L^{2}(\Omega)}+(1-\gamma) \varepsilon^{1 /(1-\gamma)}\left\|f_{0}\right\|_{L^{q}(\Omega)}
$$

where $0<\gamma<1$ is defined by

$$
\frac{1}{6}=\frac{\gamma}{2}+\frac{1-\gamma}{q}
$$

and where $\varepsilon>0$ is chosen sufficiently small. Then the absorption principle yields the estimate

$$
\begin{equation*}
\left\|f_{0}\right\|_{L^{q}(\Omega)}+\|\nabla p\|_{L^{q}(\Omega)} \leqslant C\left(\|f\|_{L^{q}(\Omega)}+\left\|f_{0}\right\|_{L^{2}(\Omega)}\right), \quad C=C(q, \alpha, \beta, K)>0 \tag{3.20}
\end{equation*}
$$

also for $q>6$. Therefore, (3.20) holds for all $2 \leqslant q<\infty$. Combining (3.20) with (3.8) we get (3.17) with $C=C(q, \alpha, \beta, K)>0$ for all $2 \leqslant q<\infty$.

Next we consider the case $f \in L^{2}+L^{q}, 1<q<2$. Choose $f_{1} \in L^{2}$ and $f_{2} \in L^{q}$ with $f=f_{1}+f_{2},\|f\|_{L^{2}+L^{q}}=\left\|f_{1}\right\|_{L^{2}}+\left\|f_{2}\right\|_{L^{q}}$, and define

$$
f_{0}=P_{2} f_{1}+P_{q} f_{2} \in L_{\sigma}^{2}+L_{\sigma}^{q} \quad \text { and } \quad \nabla p=\left(I-P_{2}\right) f_{1}+\left(I-P_{q}\right) f_{2} \in G^{2}+G^{q}
$$

yielding $f=f_{0}+\nabla p$. Then we use the dual representation of the norm $\left\|f_{0}\right\|_{L^{2}+L^{q}}$, see $\S 2.2$, and obtain with (3.17), $q^{\prime}>2$, that

$$
\begin{align*}
\left\|f_{0}\right\|_{L^{2}+L^{q}} & =\sup \left\{\frac{\left|\left\langle P_{2} f_{1}+P_{q} f_{2}, g\right\rangle\right|}{\|g\|_{L^{2} \cap L^{q^{\prime}}}}: 0 \neq g \in L^{2} \cap L^{q^{\prime}}\right\} \\
& =\sup \left\{\frac{\left|\left\langle f_{1}+f_{2}, P_{q^{\prime}} g\right\rangle\right|}{\|g\|_{L^{2} \cap L^{q^{\prime}}}}: 0 \neq g \in L^{2} \cap L^{q^{\prime}}\right\}  \tag{3.21}\\
& \leqslant \sup \left\{\frac{\left(\left\|f_{1}\right\|_{L^{2}}+\left\|f_{2}\right\|_{L^{q}}\right)\left\|P_{q^{\prime}} g\right\|_{L^{2} \cap L^{q^{\prime}}}}{\|g\|_{L^{2} \cap L^{q^{\prime}}}}: 0 \neq g \in L^{2} \cap L^{q^{\prime}}\right\} \\
& \leqslant C\|f\|_{L^{2}+L^{q}}
\end{align*}
$$

with the same $C=C(q, \alpha, \beta, K)>0$ as valid for (3.17). It follows that

$$
\left\|f_{0}\right\|_{L^{2}+L^{q}}+\|\nabla p\|_{L^{2}+L^{q}} \leqslant C\|f\|_{L^{2}+L^{q}}
$$

with $C=C(q, \alpha, \beta, K)>0$.
Summarizing we obtain for every $1<q<\infty$ and $f \in \tilde{L}^{q}$ the estimate

$$
\begin{equation*}
\left\|f_{0}\right\|_{\tilde{L}^{q}}+\|\nabla p\|_{\tilde{L}^{q}} \leqslant C\|f\|_{\tilde{L}^{q}}, \quad C=C(q, \alpha, \beta, K)>0, \tag{3.22}
\end{equation*}
$$

where $\widetilde{P}_{q} f=f_{0}$ is defined by $f_{0}=P_{q} f$ if $f \in \tilde{L}^{q}=L^{2} \cap L^{q}, 2 \leqslant q<\infty$, and by $f_{0}=P_{2} f_{1}+P_{q} f_{2}$ if $f=f_{1}+f_{2} \in \tilde{L}^{q}=L^{2}+L^{q}, 1<q<2$. Moreover, $\nabla p=\left(I-\widetilde{P}_{q}\right) f \in \widetilde{G}^{q}=G^{2} \cap G^{q}$ if $2 \leqslant q<\infty$, and $\nabla p=\nabla p_{1}+\nabla p_{2}=\left(I-P_{2}\right) f_{1}+\left(I-P_{q}\right) f_{2} \in \widetilde{G}^{q}=G^{2}+G^{q}$ when $1<q<2$. Thus we proved (2.10) for bounded domains $\Omega$, and we may conclude that $\widetilde{P}_{q} f=P_{q} f$ holds for $1<q<\infty$. Therefore, the other assertions of Theorem 2.1 are obvious for bounded domains. Note that the choice of $C=C(q, \alpha, \beta, K)$ in (2.10) is the only new property in this case.

Step 2. $\Omega$ unbounded. Let $f \in \tilde{L}^{q}(\Omega), 1<q<\infty$, and let $f_{j}=\left.f\right|_{\Omega_{j}} \in \tilde{L}^{q}\left(\Omega_{j}\right), j \in \mathbf{N}$, be the restriction to the subdomain $\Omega_{j} \subseteq \Omega$, see (2.8). Our aim is to construct a unique solution pair $f_{0} \in \tilde{L}_{\sigma}^{q}(\Omega), \nabla p \in \widetilde{G}^{q}(\Omega)$ satisfying $f=f_{0}+\nabla p$. For this purpose we use Step 1 with the decomposition

$$
f_{j}=f_{j, 0}+\nabla p_{j}, \quad \text { where } f_{j, 0}=\widetilde{P}_{q} f_{j} \text { and } \nabla p_{j} \in \widetilde{G}^{q}\left(\Omega_{j}\right)
$$

and the uniform estimate

$$
\begin{equation*}
\left\|f_{j, 0}\right\|_{\tilde{L}^{q}\left(\Omega_{j}\right)}+\left\|\nabla p_{j}\right\|_{\tilde{L}^{q}\left(\Omega_{j}\right)} \leqslant C\left\|f_{j}\right\|_{\tilde{L}^{q}\left(\Omega_{j}\right)} \leqslant C\|f\|_{\tilde{L}^{q}(\Omega)} \tag{3.23}
\end{equation*}
$$

with $C>0$ as in (3.22). Here consider $\tilde{L}^{q}\left(\Omega_{j}\right)$ as a subspace of $\tilde{L}^{q}(\Omega)$ by extending each function on $\Omega_{j}$ by zero to get a function on $\Omega$. Since $\left(\tilde{L}^{q}\right)^{\prime}=\tilde{L}^{q^{\prime}}$ and $\left(\tilde{L}^{q^{\prime}}\right)^{\prime}=\tilde{L}^{q}$, cf. §2.2, we may assume, suppressing subsequences, that there exist weak limits

$$
f_{0}=\underset{j \rightarrow \infty}{\mathrm{w}-\lim _{j \rightarrow \infty}} f_{j, 0} \in \tilde{L}_{\sigma}^{q}(\Omega) \quad \text { and } \quad \nabla p=\underset{j \rightarrow \infty}{\mathrm{w}-\lim _{j} \nabla p_{j} \in \widetilde{G}^{q}(\Omega), ~}
$$

satisfying $f_{0}+\nabla p=f$. Note that $\nabla p_{j}$ treated as an element of $\tilde{L}^{q}(\Omega)$ when extended by zero need not be a gradient; however, by de Rham's argument, cf. [35, Chapter I, (1.29)] or [32, p. 73], we see that w- $\lim _{j \rightarrow \infty} \nabla p_{j}$ is indeed a gradient. From (3.23) we obtain the estimate

$$
\begin{equation*}
\left\|f_{0}\right\|_{\tilde{L}^{q}(\Omega)}+\|\nabla p\|_{\tilde{L}^{q}(\Omega)} \leqslant C\|f\|_{\tilde{L}^{q}(\Omega)} \tag{3.24}
\end{equation*}
$$

with $C$ as in (3.23). To prove the uniqueness of the decomposition $f=f_{0}+\nabla p$ assume that $f_{0}+\nabla p=0, f_{0} \in \tilde{L}_{\sigma}^{q}(\Omega), \nabla p \in \widetilde{G}^{q}(\Omega)$. Then we use the construction above for any $g=$ $g_{0}+\nabla h \in \tilde{L}^{q^{\prime}}(\Omega), g_{0} \in \tilde{L}_{\sigma}^{q^{\prime}}(\Omega), \nabla h \in \tilde{G}^{q^{\prime}}(\Omega)$, and obtain that $\left\langle f_{0}, g\right\rangle=-\left\langle\nabla p, g_{0}\right\rangle=0$. Hence $f_{0}=\nabla p=0$, and $\widetilde{P}_{q} f=f_{0} \in \tilde{L}_{\sigma}^{q}$ is well defined. Now the assertions of Theorem 2.1 and of Remark 2.2 are easy consequences. This completes the proof.

### 3.3. The Stokes operator in $\tilde{\boldsymbol{L}}^{q}$; Proof of Theorem 2.3

Step 1. $\Omega$ bounded. First we consider the Stokes equation $-\Delta u+\nabla p=f$ with $f \in L_{\sigma}^{q}$ and $u \in D\left(A_{q}\right)=L_{\sigma}^{q} \cap W_{0}^{1, q} \cap W^{2, q}, 1<q<\infty$, which is equivalent to the equation $A_{q} u=f$, and prove the preliminary estimate

$$
\begin{equation*}
\left\|\nabla^{2} u\right\|_{L^{q}(\Omega)}+\|\nabla p\|_{L^{p}(\Omega)} \leqslant C\left(\|f\|_{L^{q}(\Omega)}+\|u\|_{L^{q}(\Omega)}\right) \tag{3.25}
\end{equation*}
$$

with $C=C(q, \alpha, \beta, K)>0$ depending only on $q$ and the type $\alpha, \beta, K$.
This estimate has the important implication that the graph norm $\|u\|_{D\left(A_{q}\right)}=$ $\|u\|_{L^{q}}+\left\|A_{q} u\right\|_{L^{q}}$ is equivalent to the norm $\|u\|_{W^{2, q}}$ on $D\left(A_{q}\right)$ with constants only depending on $q, \alpha, \beta$ and $K$. More precisely,

$$
\begin{equation*}
C_{1}\|u\|_{W^{2, q}} \leqslant\|u\|_{D\left(A_{q}\right)} \leqslant C_{2}\|u\|_{W^{2, q}}, \quad u \in D\left(A_{q}\right) \tag{3.26}
\end{equation*}
$$

with $C_{1}=C_{1}(q, \alpha, \beta, K)>0$ and $C_{2}=C_{2}(q, \alpha, \beta, K)>0$.
To prove (3.25) we use $U_{j}$ and $\varphi_{j}, j=1, \ldots, N$, as in $\S 3.2$, and consider in $U_{j}$ the local equation

$$
\begin{aligned}
& \lambda_{0}\left(\varphi_{j} u-w\right)-\Delta\left(\varphi_{j} u-w\right)+\nabla\left(\varphi_{j}\left(p-M_{j}\right)\right) \\
& \quad=\varphi_{j} f+\Delta w-2 \nabla \varphi_{j} \cdot \nabla u-\left(\Delta \varphi_{j}\right) u+\left(\nabla \varphi_{j}\right)\left(p-M_{j}\right)+\lambda_{0}\left(\varphi_{j} u-w\right)
\end{aligned}
$$

Here $\lambda_{0}$ means the constant in (3.4), $M_{j}=M_{j}(p)$ is a constant such that $p-M_{j}=$ $R^{\prime}(\nabla p) \in L_{0}^{q}(\Omega)$, see $(3.7)$, and $w=R\left(\left(\nabla \varphi_{j}\right) \cdot u\right) \in W_{0}^{2, q}\left(U_{j}\right)$ is the solution of the equation $\operatorname{div} w=\operatorname{div}\left(\varphi_{j} u\right)=\left(\nabla \varphi_{j}\right) \cdot u$, see (3.6). Then we apply (3.4) with $\lambda=\lambda_{0}$, and use the estimates

$$
\begin{aligned}
\|w\|_{W^{1, q}\left(U_{j}\right)} & \leqslant C\|u\|_{L^{q}\left(U_{j}\right)} \\
\|w\|_{W^{2, q}\left(U_{j}\right)} & \leqslant C\|u\|_{W^{1, q}\left(U_{j}\right)} \\
\left\|p-M_{j}\right\|_{L^{q}\left(U_{j}\right)} & \leqslant C\left(\|f\|_{L^{q}\left(U_{j}\right)}+\|\nabla u\|_{L^{q}\left(U_{j}\right)}\right)
\end{aligned}
$$

with $C=C(q, \alpha, \beta, K)>0$, following from (3.6) and (3.7) applied to $\nabla p=f+\Delta u$ in $U_{j}$. Combining these estimates we are led to the local inequalities

$$
\begin{equation*}
\left\|\varphi_{j} \nabla^{2} u\right\|_{L^{q}\left(U_{j}\right)}^{q}+\left\|\varphi_{j} \nabla\left(p-M_{j}\right)\right\|_{L^{q}\left(U_{j}\right)}^{q} \leqslant C\left(\|f\|_{L^{q}\left(U_{j}\right)}^{q}+\|u\|_{W^{1, q}\left(U_{j}\right)}^{q}\right) \tag{3.27}
\end{equation*}
$$

with $C=C(q, \alpha, \beta, K)>0$. Taking the sum over $j=1, \ldots, N$ in the same way as in (3.19), and using the absorption argument to remove $\|\nabla u\|_{L^{q}(\Omega)}^{q}$ with (3.13), we obtain the desired inequality (3.25).

Next we consider the resolvent equation

$$
\lambda u+A_{q} u=\lambda u-\Delta u+\nabla p=f \quad \text { in } \Omega
$$

with $f \in L_{\sigma}^{q}$, where $1<q<\infty$ and $\lambda \in \mathcal{S}_{\varepsilon}, 0<\varepsilon<\frac{1}{2} \pi$. Our first purpose is to prove for $u \in D\left(A_{q}\right)$ and $\nabla p=\left(I-P_{q}\right) \Delta u, 2 \leqslant q<\infty$, the estimate

$$
\begin{equation*}
|\lambda|\|u\|_{L^{2} \cap L^{q}}+\left\|\nabla^{2} u\right\|_{L^{2} \cap L^{q}}+\|\nabla p\|_{L^{2} \cap L^{q}} \leqslant C\|f\|_{L^{2} \cap L^{q}} \tag{3.28}
\end{equation*}
$$

with $|\lambda| \geqslant \delta>0$, where $\delta>0$ is given, and $C=C(q, \varepsilon, \delta, \alpha, \beta, K)>0$. Note that this estimate is well known for bounded domains with $C=C(q, \varepsilon, \delta, \Omega)>0$, see $\S 3.1$. In this case we obtain the local equation

$$
\begin{align*}
& \lambda\left(\varphi_{j} u-w\right)-\Delta\left(\varphi_{j} u-w\right)+\nabla\left(\varphi_{j}\left(p-M_{j}\right)\right) \\
& \quad=\varphi_{j} f+\Delta w-2 \nabla \varphi_{j} \cdot \nabla u-\left(\Delta \varphi_{j}\right) u-\lambda w+\left(\nabla \varphi_{j}\right)\left(p-M_{j}\right) \tag{3.29}
\end{align*}
$$

with $p-M_{j}=R^{\prime}(\nabla p)$ and $w=R\left(\left(\nabla \varphi_{j}\right) \cdot u\right)$ as above.
First let $2 \leqslant q \leqslant 6$. Concerning $w$, we use the estimates above and the inequality

$$
\|w\|_{L^{q}\left(U_{j}\right)} \leqslant C_{1}\|w\|_{W^{1,2}\left(U_{j}\right)} \leqslant C_{2}\|u\|_{L^{2}\left(U_{j}\right)}
$$

$C_{i}=C_{i}(q, \alpha, \beta, K)>0, i=1,2$. For $p-M_{j}$ we use the above estimate and the inequality

$$
\left\|p-M_{j}\right\|_{L^{q}\left(U_{j}\right)} \leqslant C\left(\|f\|_{L^{q}\left(U_{j}\right)}+|\lambda|\|u\|_{L^{2}\left(U_{j}\right)}+\|\nabla u\|_{L^{q}\left(U_{j}\right)}\right)
$$

with $C=C(q, \alpha, \beta, K)>0$. Further, to the local resolvent equation (3.29) we apply the estimate (3.4) with $\lambda$ replaced by $\lambda+\lambda_{0}^{\prime}$, where $\lambda_{0}^{\prime} \geqslant 0$ is sufficiently large such that $\left|\lambda+\lambda_{0}^{\prime}\right| \geqslant \lambda_{0}$ for $|\lambda| \geqslant \delta$, and $\lambda_{0}$ is as in (3.4). Then we combine these estimates and are led to the local inequality

$$
\begin{align*}
& \left\|\lambda \varphi_{j} u\right\|_{L^{q}\left(U_{j}\right)}^{q}+\left\|\varphi_{j} u\right\|_{L^{q}\left(U_{j}\right)}^{q}+\left\|\varphi_{j} \nabla^{2} u\right\|_{L^{q}\left(U_{j}\right)}^{q}+\left\|\varphi_{j} \nabla p\right\|_{L^{q}\left(U_{j}\right)}^{q}  \tag{3.30}\\
& \quad \leqslant C\left(\|f\|_{L^{q}\left(U_{j}\right)}^{q}+\|u\|_{L^{q}\left(U_{j}\right)}^{q}+\|\nabla u\|_{L^{q}\left(U_{j}\right)}^{q}+\|\lambda u\|_{L^{2}\left(U_{j}\right)}^{q}\right)
\end{align*}
$$

with $C=C(q, \delta, \varepsilon, \alpha, \beta, K)>0$. Next we take the sum over $j=1, \ldots, N$ in the same way as in (3.19). This leads to the inequality

$$
\begin{align*}
|\lambda|\|u\|_{L^{q}(\Omega)}+\|u\|_{L^{q}(\Omega)} & +\left\|\nabla^{2} u\right\|_{L^{q}(\Omega)}+\|\nabla p\|_{L^{q}(\Omega)}  \tag{3.31}\\
& \leqslant C\left(\|f\|_{L^{q}(\Omega)}+\|u\|_{L^{q}(\Omega)}+\|\nabla u\|_{L^{q}(\Omega)}+|\lambda|\|u\|_{L^{2}(\Omega)}\right)
\end{align*}
$$

with $C=C(q, \delta, \varepsilon, \alpha, \beta, K)>0,|\lambda| \geqslant \delta$ and $2 \leqslant q \leqslant 6$. Applying (3.13) we remove the term $\|\nabla u\|_{L^{q}(\Omega)}$ in (3.31) by the absorption principle.

If $q>6$, estimate (3.31) holds in the same way with the term $|\lambda|\|u\|_{L^{2}(\Omega)}$ on the right-hand side replaced by $|\lambda|\|u\|_{L^{6}(\Omega)}$. Now use the elementary estimate

$$
|\lambda|\|u\|_{L^{6}(\Omega)} \leqslant \gamma\left(\frac{1}{\varepsilon}\right)^{1 / \gamma}|\lambda|\|u\|_{L^{2}(\Omega)}+(1-\gamma) \varepsilon^{1 /(1-\gamma)}|\lambda|\|u\|_{L^{q}(\Omega)}
$$

with $0<\gamma<1$ such that

$$
\frac{1}{6}=\frac{\gamma}{2}+\frac{1-\gamma}{q}
$$

with sufficiently small $\varepsilon>0$, and use the absorption principle. This proves (3.31) for all $q \geqslant 2$ without the term $\|\nabla u\|_{L^{q}(\Omega)}$. Moreover, due to (3.14), the term $\|u\|_{L^{q}(\Omega)}$ may be removed from the right-hand side of (3.31). Now we combine this improved inequality (3.31) with estimate (3.9) for $|\lambda| \geqslant \delta$, and we apply (3.25) with $q=2$. This proves the desired estimate (3.28) for $2 \leqslant q<\infty$.

Next let $1<q<2$ and consider in $\Omega$ the (well-defined) equation $\lambda u-\Delta u+\nabla p=f$ with $f \in L_{\sigma}^{2}+L_{\sigma}^{q}$, where $u \in D\left(A_{2}\right)+D\left(A_{q}\right), \nabla p=\left(I-\widetilde{P}_{q}\right) \Delta u$ and $\lambda \in \mathcal{S}_{\varepsilon},|\lambda| \geqslant \delta$. Using $f=\lambda u-\widetilde{P}_{q} \Delta u$ and (3.28) with $q^{\prime}>2$ we first obtain that

$$
\begin{align*}
\|f\|_{L_{\sigma}^{2}+L_{\sigma}^{q}} & =\sup \left\{\frac{\left|\left\langle\lambda u-\widetilde{P}_{q} \Delta u, v\right\rangle\right|}{\|v\|_{L_{\sigma}^{2} \cap L_{\sigma}^{g^{\prime}}}}: 0 \neq v \in L_{\sigma}^{2} \cap L_{\sigma}^{q^{\prime}}\right\} \\
& =\sup \left\{\frac{\left|\left\langle u, \lambda v-\widetilde{P}_{q^{\prime}} \Delta v\right\rangle\right|}{\|v\|_{L_{\sigma}^{2} \cap L_{\sigma}^{q^{\prime}}}}: 0 \neq v \in L_{\sigma}^{2} \cap L_{\sigma}^{q^{\prime^{\prime}}}\right\} \\
& =\sup \left\{\frac{|\langle u, g\rangle|}{\left\|\left(\lambda I-\widetilde{P}_{q^{\prime}} \Delta\right)^{-1} g\right\|_{L_{\sigma}^{2} \cap L_{\sigma}^{q^{\prime}}}}: 0 \neq g \in L_{\sigma}^{2} \cap L_{\sigma}^{q^{\prime}}\right\}  \tag{3.32}\\
& \geqslant \frac{|\lambda|}{C} \sup \left\{\frac{|\langle u, g\rangle|}{\|g\|_{L_{\sigma}^{2} \cap L_{\sigma}^{q^{\prime}}}}: 0 \neq g \in L_{\sigma}^{2} \cap L_{\sigma}^{q^{\prime}}\right\} \\
& =\frac{|\lambda|}{C}\|u\|_{L_{\sigma}^{2} \cap L_{\sigma}^{q}}^{*}
\end{align*}
$$

with $C$ as in (3.28); see (2.11) concerning $\|u\|_{L_{\sigma}^{2} \cap L_{\sigma}^{q}}^{*}$. Hence we also get $|\lambda|\|u\|_{L_{\sigma}^{2}+L_{\sigma}^{q}} \leqslant$ $C\|f\|_{L_{\sigma}^{2}+L_{\sigma}^{q}}$ and even

$$
\begin{equation*}
|\lambda|\|u\|_{L_{\sigma}^{2}+L_{\sigma}^{q}}+\|u\|_{L_{\sigma}^{2}+L_{\sigma}^{q}}+\left\|A_{q} u\right\|_{L_{\sigma}^{2}+L_{\sigma}^{q}} \leqslant C\|f\|_{L_{\sigma}^{2}+L_{\sigma}^{q}}, \quad \lambda \in \mathcal{S}_{\varepsilon},|\lambda| \geqslant \delta \tag{3.33}
\end{equation*}
$$

From the equivalence of the norms $\|\cdot\|_{D\left(A_{q}\right)}$ and $\|\cdot\|_{W^{2, q}}$, cf. (3.26), and from (2.2) with $B_{1}=A_{2}$ and $B_{2}=A_{q}$, we conclude that

$$
C_{1}\|u\|_{W^{2,2}+W^{2, q}} \leqslant\|u\|_{L_{\sigma}^{2}+L_{\sigma}^{q}}+\left\|A_{q} u\right\|_{L_{\sigma}^{2}+L_{\sigma}^{q}} \leqslant C_{2}\|u\|_{W^{2,2}+W^{2, q}}
$$

where $C_{i}=C_{i}(q, \varepsilon, \alpha, \beta, K), i=1,2$. Then (3.33) and the identity $\nabla p=f-\lambda u+\Delta u$ lead to the estimate

$$
\begin{equation*}
|\lambda|\|u\|_{L_{\sigma}^{2}+L_{\sigma}^{q}}+\|u\|_{W^{2,2}+W^{2, q}}+\|\nabla p\|_{L^{2}+L^{q}} \leqslant C\|f\|_{L_{\sigma}^{2}+L_{\sigma}^{q}} \tag{3.34}
\end{equation*}
$$

with $C=C(q, \delta, \varepsilon, \alpha, \beta, K)>0$.
Since $\Omega$ is bounded, we easily conclude that $\tilde{A}_{q} u=-\widetilde{P}_{q} \Delta u=A_{q} u$ for $u \in D\left(\tilde{A}_{q}\right)=$ $D\left(A_{q}\right), 1<q<\infty$. The only new result in this case is the validity of the estimate

$$
\begin{equation*}
|\lambda|\|u\|_{\tilde{L}_{\sigma}^{q}}+\|u\|_{\widetilde{W}^{2, q}}+\|\nabla p\|_{\tilde{L}^{q}} \leqslant C\|f\|_{\tilde{L}_{\sigma}^{q}}, \quad u \in D\left(\tilde{A}_{q}\right) \tag{3.35}
\end{equation*}
$$

with $C=C(q, \delta, \varepsilon, \alpha, \beta, K)>0$ when $|\lambda| \geqslant \delta>0$. Thus the proof of Theorem 2.3 is complete for bounded $\Omega$.

Step 2. $\Omega$ unbounded. In principle we use the same arguments as in Step 2 of $\S 3.2$ with the bounded subdomains $\Omega_{j} \subset \Omega, j \in \mathbf{N}$, see (2.8).

Let $f \in \tilde{L}_{\sigma}^{q}(\Omega), 1<q<\infty$, and $\lambda \in \mathcal{S}_{\varepsilon}, 0<\varepsilon<\frac{1}{2} \pi$. Our aim is to construct a unique solution $u \in \widetilde{D}^{q}(\Omega)$ of the equation

$$
\lambda u-\widetilde{P}_{q} \Delta u=\lambda u-\Delta u+\nabla p=f, \quad \nabla p=\left(I-\widetilde{P}_{q}\right) \Delta u \quad \text { in } \Omega
$$

satisfying estimate (2.12). For this purpose set $f_{j}=\left.\widetilde{P}_{q} f\right|_{\Omega_{j}}$ and consider the solution $u_{j} \in \widetilde{D}^{q}\left(\Omega_{j}\right)$ of the equation

$$
\lambda u_{j}+\tilde{A}_{q} u_{j}=\lambda u_{j}-\Delta u_{j}+\nabla p_{j}=f_{j}, \quad \nabla p_{j}=\left(I-\widetilde{P}_{q}\right) \Delta u_{j} \quad \text { in } \Omega_{j}
$$

From (3.35) we obtain the uniform estimate

$$
\begin{equation*}
|\lambda|\left\|u_{j}\right\|_{\tilde{L}_{\sigma}^{q}\left(\Omega_{j}\right)}+\left\|u_{j}\right\|_{\widetilde{W}^{2, q}\left(\Omega_{j}\right)}+\left\|\nabla p_{j}\right\|_{\tilde{L}^{q}\left(\Omega_{j}\right)} \leqslant C\|f\|_{\tilde{L}_{(\Omega)}^{q}(\Omega)} \tag{3.36}
\end{equation*}
$$

with $|\lambda| \geqslant \delta>0$ and $C=C(q, \delta, \varepsilon, \alpha, \beta, K)>0$. The same weak convergence argument as in Step 2 of $\S 3.2$ yields, suppressing subsequences, weak limits

$$
u=\underset{j \rightarrow \infty}{\mathrm{w}-\lim } u_{j} \text { in } \tilde{L}_{\sigma}^{q}(\Omega) \quad \text { and } \quad \nabla p=\underset{j \rightarrow \infty}{\mathrm{w}-\lim _{j}} \nabla p_{j} \text { in } \tilde{L}^{q}(\Omega)
$$

satisfying $u \in \widetilde{D}^{q}(\Omega), \lambda u-\Delta u+\nabla p=\lambda u-\widetilde{P}_{q} \Delta u=f$ in $\Omega$ and (2.12).
To prove the uniqueness of $u$ we assume that there is some $v \in \widetilde{D}^{q}(\Omega)$ and $\lambda \in \mathcal{S}_{\varepsilon}$ satisfying $\lambda v-\widetilde{P}_{q} \Delta v=0$. Given $f^{\prime} \in \tilde{L}^{q^{\prime}}(\Omega)$ let $u \in \widetilde{D}^{q^{\prime}}(\Omega)$ be a solution of $\lambda u-\widetilde{P}_{q^{\prime}} \Delta u=$ $\widetilde{P}_{q^{\prime}} f^{\prime}$. Then

$$
0=\left\langle\lambda v-\widetilde{P}_{q} \Delta v, u\right\rangle=\left\langle v,\left(\lambda-\widetilde{P}_{q^{\prime}} \Delta\right) u\right\rangle=\left\langle v, \widetilde{P}_{q^{\prime}} f^{\prime}\right\rangle=\left\langle v, f^{\prime}\right\rangle
$$

for all $f^{\prime} \in \tilde{L}^{q^{\prime}}(\Omega)$; hence, $v=0$. Thus we get that the equation $\lambda u+\tilde{A}_{q} u=f, \lambda \in \mathcal{S}_{\varepsilon}$, has a unique solution $u=\left(\lambda I+\tilde{A}_{q}\right)^{-1} f$ satisfying (2.12).

### 3.4. Maximal regularity in $\tilde{L}^{q}$ for the nonstationary Stokes system; Proof of

 Theorem 2.5Step 1. $\Omega$ bounded. In principle we use the same arguments as in the previous proofs. Given $0<T<\infty$ and $1<s, q<\infty$ let

$$
\|\cdot\|_{L^{s}(X(\Omega))}=\|\cdot\|_{L^{s}(0, T ; X(\Omega))}=\left(\int_{0}^{T}\|\cdot\|_{X}^{s} d t\right)^{1 / s}
$$

where $X(\Omega)$ is a Banach space of functions in $\Omega$; furthermore, we use the operators $\mathcal{J}_{q, s}$ and $\mathcal{J}_{q, s}^{\prime}$, see $\S 3.1$, and define $\tilde{\mathcal{J}}_{q, s}$ and $\tilde{\mathcal{J}}_{q, s}^{\prime}$ for $f \in L^{s}\left(0, T ; \tilde{L}_{\sigma}^{q}\right)$ by

$$
\left(\tilde{\mathcal{J}}_{q, s} f\right)(t)=\int_{0}^{t} e^{-(t-\tau) \tilde{A}_{q}} f(\tau) d \tau \quad \text { and } \quad\left(\tilde{\mathcal{J}}_{q, s}^{\prime} f\right)(t)=\int_{t}^{T} e^{-(\tau-t) \tilde{A}_{q}} f(\tau) d \tau
$$

$0 \leqslant t \leqslant T$. Since $\tilde{A}_{q}^{\prime}=\tilde{A}_{q^{\prime}}$, we obtain for all $f \in L^{s}\left(0, T ; \tilde{L}_{\sigma}^{q}\right)$ and $g \in L^{s^{\prime}}\left(0, T ; \tilde{L}_{\sigma}^{q^{\prime}}\right)$ that

$$
\left\langle\widetilde{\mathcal{J}}_{q, s} f, g\right\rangle_{T}=\left\langle f, \widetilde{\mathcal{J}}_{q^{\prime}, s^{\prime}}^{\prime} g\right\rangle_{T}
$$

First consider the case $u_{0}=0$ and let $s=q$. Then $u=\tilde{\mathcal{J}}_{q, q} f$ solves the evolution system $u_{t}+\tilde{A}_{q} u=f, u(0)=0$, and $u=\widetilde{\mathcal{J}}_{q, q}^{\prime} f$ is the solution of the system $-u_{t}+\tilde{A}_{q} u=f, u(T)=0$. Our aim is to prove in both cases the estimate

$$
\begin{equation*}
\left\|u_{t}\right\|_{L^{q}\left(\tilde{L}_{\sigma}^{q}(\Omega)\right)}+\|u\|_{L^{q}\left(\widetilde{W}^{2, q}(\Omega)\right)}+\|\nabla p\|_{L^{q}\left(\tilde{L}^{q}(\Omega)\right)} \leqslant C\|f\|_{L^{q}\left(\tilde{L}_{\sigma}^{q}(\Omega)\right)} \tag{3.37}
\end{equation*}
$$

with $\nabla p=\left(I-\widetilde{P}_{q}\right) \Delta u$ and $C=C(T, q, \alpha, \beta, K)>0$.
Observe that it is sufficient to prove (3.37) for the case $u=\tilde{\mathcal{J}}_{q, q} f$ only. The other case follows using the transformation $\tilde{u}(t)=u(T-t), \tilde{f}(t)=f(T-t)$. Further, it is sufficient to prove (3.37) when $2 \leqslant q<\infty$. For, using $\left(\widetilde{\mathcal{J}}_{q, q}^{\prime}\right)^{\prime}=\widetilde{\mathcal{J}}_{q^{\prime}, q^{\prime}}$ and the duality principle in the same way as in (3.32), the case $1<q<2$ is reduced to the case $2<q^{\prime}<\infty$. In this context we note that it is sufficient to prove instead of (3.37) the estimate $\left\|u_{t}\right\|_{L^{q}\left(\tilde{L}_{\sigma}^{q}(\Omega)\right)} \leqslant$ $C\|f\|_{L^{q}\left(\tilde{L}_{\sigma}^{q}(\Omega)\right)}$. Actually, (3.37) follows using $\tilde{A}_{q} u=f-u_{t}$, the simple identity $u(t)=$ $\int_{0}^{t} u_{t}(\tau) d \tau$ leading to the estimate $\|u\|_{L^{q}\left(\tilde{L}_{\sigma}^{q}(\Omega)\right)} \leqslant C\left\|u_{t}\right\|_{L^{q}\left(\tilde{L}_{\sigma}^{q}(\Omega)\right)}, C=C(T)>0$, and the equivalence relation (3.26).

Thus it remains to prove (3.37) with $2 \leqslant q<\infty$, where $u=\widetilde{\mathcal{J}}_{q, q} f$ solves

$$
u_{t}+\tilde{A}_{q} u=u_{t}-\Delta u+\nabla p=f \in L^{q}\left(0, T ; \tilde{L}_{\sigma}^{q}\right), \quad u(0)=0
$$

and $\nabla p=\left(I-\widetilde{P}_{q}\right) \Delta u$. Using the well-known estimate (3.11) for bounded domains we know that $u=\widetilde{\mathcal{J}}_{q, q} f$ satisfies $(3.37)$ with $C=C(T, q, \Omega)>0$. Thus it remains to prove that $C$ in (3.37) can be chosen depending only on $T, q, \alpha, \beta$ and $K$.

To prove this result consider the local equation

$$
\begin{aligned}
\left(\varphi_{j} u-w\right)_{t}-\Delta\left(\varphi_{j} u-w\right)+ & \nabla\left(\varphi_{j}\left(p-M_{j}\right)\right) \\
& =\varphi_{j} f-w_{t}+\Delta w-2 \nabla \varphi_{j} \cdot \nabla u-\left(\Delta \varphi_{j}\right) u+\left(\nabla \varphi_{j}\right)\left(p-M_{j}\right)
\end{aligned}
$$

in $U_{j}$, where $w=R\left(\left(\nabla \varphi_{j}\right) \cdot u\right) \in L^{q}\left(0, T ; W_{0}^{2, q}\left(U_{j}\right)\right)$ solves the equations $\operatorname{div} w=\left(\nabla \varphi_{j}\right) \cdot u$ and $\operatorname{div} w_{t}=\left(\nabla \varphi_{j}\right) \cdot u_{t}$ for a.a. $t \in(0, T)$. Here $U_{j}$ and $\varphi_{j}, 1 \leqslant j \leqslant N$, have the same meaning as in the previous proofs, and $M_{j}=M_{j}(p)$ is a constant depending on $t$ defined by $p-M_{j}=$ $R^{\prime}(\nabla p) \in L^{q}\left(0, T ; L_{0}^{q}\left(U_{j}\right)\right)$.

First let $2 \leqslant q \leqslant 6$. Then from (3.6) and (3.7) using $\nabla p=f-u_{t}+\Delta u$ we obtain the estimates

$$
\begin{align*}
\left\|w_{t}\right\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)} & \leqslant C\left\|u_{t}\right\|_{L^{q}\left(L^{2}\left(U_{j}\right)\right)} \\
\left\|\nabla^{2} w\right\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)} & \leqslant C\left(\|u\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}+\|\nabla u\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}\right)  \tag{3.38}\\
\left\|p-M_{j}\right\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)} & \leqslant C\left(\|f\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}+\left\|u_{t}\right\|_{L^{q}\left(L^{2}\left(U_{j}\right)\right)}+\|\nabla u\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}\right)
\end{align*}
$$

with $C=C(q, \alpha, \beta, K)>0$. Applying the local estimate (3.5) and using (3.38) we are led to the inequality

$$
\begin{gather*}
\left\|\varphi_{j} u_{t}\right\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}^{q}+\left\|\varphi_{j} u\right\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}^{q}+\left\|\varphi_{j} \nabla^{2} u\right\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}^{q}+\left\|\varphi_{j} \nabla p\right\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}^{q}  \tag{3.39}\\
\leqslant C\left(\|f\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}^{q}+\|u\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}^{q}+\|\nabla u\|_{L^{q}\left(L^{q}\left(U_{j}\right)\right)}^{q}+\left\|u_{t}\right\|_{L^{q}\left(L^{2}\left(U_{j}\right)\right)}^{q}\right)
\end{gather*}
$$

with $C=C(T, q, \alpha, \beta, K)>0$. Next we argue in principle in the same way as in Step 1 of §3.3: Take the sum over $j=1, \ldots, N$, remove the term $\|\nabla u\|_{L^{q}\left(L^{q}(\Omega)\right)}$ with the absorption argument using (3.13), then apply the estimate (3.11) to $\left\|u_{t}\right\|_{L^{q}\left(L^{2}(\Omega)\right)}$ with $C=$ $C(q, T)>0$. If $q>6$, we have to replace the term $\left\|u_{t}\right\|_{L^{q}\left(L^{2}(\Omega)\right)}$ by the term $\left\|u_{t}\right\|_{L^{q}\left(L^{6}(\Omega)\right)}$, and use the interpolation inequality

$$
\left\|u_{t}\right\|_{L^{q}\left(L^{6}(\Omega)\right)} \leqslant \gamma\left(\frac{1}{\varepsilon}\right)^{1 / \gamma}\left\|u_{t}\right\|_{L^{q}\left(L^{2}(\Omega)\right)}+(1-\gamma) \varepsilon^{1 /(1-\gamma)}\left\|u_{t}\right\|_{L^{q}\left(L^{q}(\Omega)\right)}
$$

with sufficiently small $\varepsilon>0$. This leads to the inequality

$$
\begin{aligned}
&\left\|u_{t}\right\|_{L^{q}\left(L_{\sigma}^{2}(\Omega) \cap L_{\sigma}^{q}(\Omega)\right)}+\|u\|_{L^{q}\left(W^{2,2}(\Omega) \cap W^{2, q}(\Omega)\right)}+\|\nabla p\|_{L^{q}\left(L^{2}(\Omega) \cap L^{q}(\Omega)\right)} \\
& \leqslant C\|f\|_{L^{q}\left(L_{\sigma}^{2}(\Omega) \cap L_{\sigma}^{q}(\Omega)\right)}
\end{aligned}
$$

for all $2 \leqslant q<\infty$ with $C=C(T, q, \alpha, \beta, K)>0$, and completes the proof of (3.37) for $1<q<\infty$. In particular, this proves inequality (2.18) for the bounded domain $\Omega$ when $u_{0}=0$. To prove (2.18) with $u_{0} \in D\left(\tilde{A}_{q}\right)$ we solve the system $\tilde{u}_{t}+\tilde{A}_{q} \tilde{u}=\tilde{f}, \tilde{u}(0)=0$, with $\tilde{f}=f-\tilde{A}_{q} u_{0}$. Then $u(t)=\tilde{u}(t)+u_{0}$ yields the desired solution with $u_{0} \in D\left(\tilde{A}_{q}\right)$. This proves Theorem 2.5 for bounded $\Omega$.

Step 2. $\Omega$ unbounded. Using the same arguments as in Step 2 of $\S 3.3$, let $f \in$ $L^{q}\left(0, T ; \tilde{L}_{\sigma}^{q}(\Omega)\right), 1<q<\infty$, and consider the solution $u_{j} \in L^{q}\left(0, T ; D\left(\tilde{A}_{q}\right)\right)$ of the system

$$
u_{j, t}+\tilde{A}_{q} u_{j}=f_{j}, \quad u_{j}(0)=0
$$

with $f_{j}=\left.\widetilde{P}_{q} f\right|_{\Omega_{j}}, j \in \mathbf{N}$, following Step 1. Then (3.37) applied to the domains $\Omega_{j}$ yields the uniform estimate

$$
\begin{equation*}
\left\|u_{j, t}\right\|_{L^{q}\left(\tilde{L}_{\sigma}^{q}\left(\Omega_{j}\right)\right)}+\left\|u_{j}\right\|_{L^{q}\left(\widetilde{W}^{2, q}\left(\Omega_{j}\right)\right)}+\left\|\nabla p_{j}\right\|_{L^{q}\left(\tilde{L}^{q}\left(\Omega_{j}\right)\right)} \leqslant C\|f\|_{L^{q}\left(\tilde{L}_{\sigma}^{q}(\Omega)\right)} \tag{3.40}
\end{equation*}
$$

with $\nabla p_{j}=\left(I-\widetilde{P}_{q}\right) \Delta u_{j}$ and $C=C(T, q, \alpha, \beta, K)>0$. Suppressing subsequences we obtain by the weak convergence argument the weak limits
satisfying $u \in L^{q}\left(0, T ; \widetilde{D}^{q}(\Omega)\right), u_{t}+\tilde{A}_{q} u=u_{t}-\Delta u+\nabla p=f, u(0)=0$, and the estimate

$$
\begin{equation*}
\left\|u_{t}\right\|_{L^{q}\left(\tilde{L}^{q}(\Omega)\right)}+\|u\|_{L^{q}\left(\widetilde{W}^{2, q}(\Omega)\right)}+\|\nabla p\|_{L^{q}\left(\tilde{L}^{q}(\Omega)\right)} \leqslant C\|f\|_{L^{q}\left(\tilde{L}_{\sigma}^{q}(\Omega)\right)} \tag{3.41}
\end{equation*}
$$

with $C$ as in (3.40), which is equivalent to inequality (2.18).
The uniqueness of $u$ follows in the same way as in Step 2 of $\S 3.3$, and the case $u(0)=u_{0} \in D\left(\tilde{A}_{q}\right)$ is treated as above in Step 1. The other properties in Theorem 2.5 are obvious. This completes the proof.

### 3.5. Suitable weak solutions, strong energy inequality and Leray's structure result for general domains; Proof of Theorem 2.7

To construct a suitable weak solution $u$ for the general uniform $C^{2}$-domain $\Omega$ of type $\alpha, \beta, K$, we use approximate solutions $u_{k}$ and the key estimate (2.18) in the formulation (2.21) with the exponent $q=\frac{5}{4}$; the reason for this exponent is the structure of the nonlinear term. Except for this estimate, all the other approximation arguments are well known in principle; here we follow the construction in [32, Chapter V]. However, it is easier first to consider a bounded domain $\Omega$ and then to treat the subdomains $\Omega_{j}$ with $j \rightarrow \infty$ as in the previous proofs. Furthermore, we may assume without loss of generality that $0<T<\infty$, and consequently that $T^{\prime}=T$ in (2.25); if $T=\infty$ we consider a sequence $0<T_{1}<T_{2}<\ldots$ with $\lim _{j \rightarrow \infty} T_{j}=\infty$, and continue the construction of $u$ step by step.

Moreover, we may assume that $u_{0}=0$ in the following proof. The case $u_{0} \neq 0$ can be reduced to this case in two steps: If $u_{0} \in D\left(\tilde{A}_{q}\right)$, we replace $u(t)$ by $\hat{u}(t)=u(t)-e^{-A_{2} t} u_{0}$ in the linear part of the equation (2.23). Hence $\hat{u}(0)=0$, and the argument for $u_{0}=0$ yields
(2.25) with $\varepsilon=0$ and $u$ replaced by $\hat{u}$. Since $u_{0} \in D\left(\tilde{A}_{q}\right)$, we conclude that (2.25) holds for $u$ with $\varepsilon=0$. If $u_{0} \in L_{\sigma}^{2}$ only, we choose any $0<\varepsilon<T$, use that $e^{-A_{2} t} u_{0}=e^{-A_{2}(t-\varepsilon)} u_{0, \varepsilon}$ with $u_{0, \varepsilon}=e^{-A_{2} \varepsilon} u_{0} \in D\left(A_{2}\right) \subset D\left(\tilde{A}_{q}\right), q=\frac{5}{4}$, and conclude from the validity of (2.25) for $\hat{u}$ and $\varepsilon=0$, that (2.25) holds for $u$ in the restricted interval $\left(\varepsilon, T^{\prime}\right)$. This information is sufficient to prove (2.26) and (2.27).

Thus we may assume that $u_{0}=0$ and $0<T^{\prime}=T<\infty$, and we prove (2.25) with $\varepsilon=0$. Further let $f \in L^{q}\left(0, T ; L^{2}(\Omega)\right)$ and $q=\frac{5}{4}$.

Step 1. $\Omega$ bounded. Following [32, V.3.3], we use the Yosida operators

$$
J_{k}=\left(I+k^{-1} A_{2}^{1 / 2}\right)^{-1}, \quad k \in \mathbf{N}
$$

and find solutions $u=u_{k}$ of the approximate Navier-Stokes system

$$
\begin{equation*}
u_{t}-\Delta u+\left(J_{k} u\right) \cdot \nabla u+\nabla p=f, \quad \operatorname{div} u=0,\left.u\right|_{\partial \Omega}=0, u(0)=0 \tag{3.42}
\end{equation*}
$$

on $(0, T)$. Further, we recall the estimates

$$
\begin{gather*}
\frac{1}{2}\left\|u_{k}\right\|_{L^{\infty}\left(L_{\sigma}^{2}(\Omega)\right)}^{2}+\left\|\nabla u_{k}\right\|_{L^{2}\left(L^{2}(\Omega)\right)}^{2} \leqslant C_{0}\|f\|_{L^{1}\left(L^{2}(\Omega)\right)}^{2}, \quad C_{0}>0  \tag{3.43}\\
\left\|u_{k}\right\|_{L^{\gamma}\left(L^{\delta}(\Omega)\right)} \leqslant C\|f\|_{L^{1}\left(L^{2}(\Omega)\right)},
\end{gather*}
$$

where $\delta \geqslant 2, \gamma \geqslant 2,2 / \gamma+3 / \delta=3 / 2, C=C(\gamma, \delta)>0$, and

$$
\left\|J_{k} u_{k} \cdot \nabla u_{k}\right\|_{L^{\gamma}\left(L^{\delta}(\Omega)\right)} \leqslant C\|f\|_{L^{1}\left(L^{2}(\Omega)\right)}^{2}
$$

where $1<\gamma, \delta<2,2 / \gamma+3 / \delta=4, C=C(\gamma, \delta)>0$; see [32, V.2.2, (2.2.5), and V.1.2] concerning these properties.

Moreover, due to (3.37),

$$
\begin{align*}
& \left\|u_{k, t}\right\|_{L^{q}\left(L^{q}(\Omega)\right)}+\left\|u_{k}\right\|_{L^{q}\left(W^{2, q}(\Omega)\right)}+\left\|\nabla p_{k}\right\|_{L^{q}\left(L^{q}(\Omega)\right)} \\
& \quad \leqslant C\left(\|f\|_{L^{q}\left(L^{2}(\Omega)\right)}+\|f\|_{L^{1}\left(L^{2}(\Omega)\right)}^{2}\right), \quad q=\frac{5}{4}, C=C(T, \alpha, \beta, K)>0 \tag{3.44}
\end{align*}
$$

Using these uniform boundedness properties we conclude letting $k \rightarrow \infty$ (and suppressing subsequences) that there exists a weak solution $u$ of the system (2.23) with the following weak (" $\Delta$ ") and strong (" $\rightarrow$ ") convergence properties, respectively:

$$
\begin{array}{cl}
u_{k} \rightharpoonup u & \text { in } L^{2}\left(0, T ; W_{0}^{1,2}(\Omega)\right) \\
u_{k} \rightarrow u & \text { in } L^{2}\left(0, T ; L^{2}(\Omega)\right) \quad(\text { since } \Omega \text { is bounded) }, \\
\nabla u_{k} \rightharpoonup \nabla u_{k} & \text { in } L^{2}\left(0, T ; L^{2}(\Omega)\right) \\
u_{k}(t) \rightarrow u(t) & \text { in } L_{\sigma}^{2}(\Omega) \text { for a.a. } t \in[0, T),
\end{array}
$$

and $\left(u_{k, t}, u_{k}, \nabla u_{k}, \nabla^{2} u_{k}, \nabla p_{k}\right) \rightarrow\left(u_{t}, u, \nabla u, \nabla^{2} u, \nabla p\right)$ in $L^{q}\left(0, T ; L^{q}(\Omega)\right)$, where $q=\frac{5}{4}$. Moreover, Poincaré's inequality shows that

$$
\begin{equation*}
\left\|p_{k}-M_{k}\right\|_{L^{q}\left(L^{r}(\Omega)\right)} \leqslant C\left\|\nabla p_{k}\right\|_{L^{q}\left(L^{q}(\Omega)\right)} \tag{3.45}
\end{equation*}
$$

where $q=\frac{5}{4}, r=\frac{15}{7}, M_{k}=M_{k}\left(p_{k}\right)=(1 /|\Omega|) \int_{\Omega} p_{k} d x$ and $C=C(T, \Omega)>0$.
Hence we conclude that the estimates (3.43) and (3.44) also hold with $u_{k}$ and $\nabla p_{k}$ replaced by $u$ and $\nabla p$, and that

$$
p_{k}-M_{k} \rightharpoonup \hat{p} \quad \text { in } L^{q}\left(0, T ; L^{r}(\Omega)\right)
$$

for some $\hat{p} \in L^{q}\left(0, T ; L^{r}(\Omega)\right)$ satisfying $\nabla \hat{p}=\nabla p$. Choosing $M=M(t)$ such that $\hat{p}=p-M$, (3.45) holds with $p_{k}-M_{k}$ and $\nabla p_{k}$ replaced by $p-M$ and $\nabla p$.

Let $\phi \in C_{0}^{\infty}\left(\mathbf{R}^{3}\right)$. An elementary calculation yields for all $0 \leqslant s \leqslant t \leqslant T$ the equality

$$
\begin{align*}
& \frac{1}{2}\left\|\phi u_{k}(t)\right\|_{L^{2}}^{2}+\int_{s}^{t}\left\|\phi \nabla u_{k}\right\|_{L^{2}}^{2} d \tau \\
& \left.=\frac{1}{2}\left\|\phi u_{k}(s)\right\|_{L^{2}}^{2}+\int_{s}^{t}\left\langle\phi f, \phi u_{k}\right\rangle d \tau-\left.\frac{1}{2} \int_{s}^{t}\langle\nabla| u_{k}\right|^{2}, \nabla \phi^{2}\right\rangle d \tau  \tag{3.46}\\
& \left.+\left.\int_{s}^{t}\left\langle\frac{1}{2}\right| u_{k}\right|^{2},\left(J_{k} u_{k}\right) \cdot \nabla \phi^{2}\right\rangle d \tau+\int_{s}^{t}\left\langle p_{k}, u_{k} \cdot \nabla \phi^{2}\right\rangle d \tau .
\end{align*}
$$

By the convergence properties above and writing the most problematic term in (3.46) in the form $\left\langle p_{k}, u_{k} \cdot \nabla \phi^{2}\right\rangle=\left\langle p_{k}-M_{k}, u_{k} \cdot \nabla \phi^{2}\right\rangle$, we may let $k$ converge to infinity in each term, using Lebesgue's dominated convergence theorem. Because of the weak convergence property concerning $\nabla u_{k}$, equality (3.46) yields (2.26) for a.a. $s \in[0, T)$ and all $t \in[s, T)$. Finally the strong energy inequality (2.27) is a consequence of (2.26) with $\phi \equiv 1$ on $\Omega$. Recall that the restriction concerning $\varepsilon$ in (2.25) is needed only for technical reasons if $0 \neq u_{0} \in L_{\sigma}^{2} \backslash D\left(\tilde{A}_{q}\right)$.

Step 2. $\Omega$ unbounded. Consider the bounded subdomains $\Omega_{j} \subseteq \Omega, j \in \mathbf{N}$, as in (2.8), and let $u_{j}$ be a weak solution in $\Omega_{j}$ according to Step 1 with associated pressure term $\nabla p_{j}$, satisfying

$$
\begin{equation*}
u_{j, t}-\Delta u_{j}+u_{j} \cdot \nabla u_{j}+\nabla p_{j}=f_{j}, \quad \operatorname{div} u_{j}=0, u_{j}(0)=0,\left.u_{j}\right|_{\partial \Omega_{j}}=0, \tag{3.47}
\end{equation*}
$$

where $f_{j}=\left.f\right|_{\Omega_{j}}$. Applying the diagonal principle in the same way as in [32, Chapter V , (3.3.17)], we find a subsequence $\left\{\tilde{u}_{j}\right\}_{j=1}^{\infty}$ of the sequence $\left\{u_{j}\right\}_{j=1}^{\infty}$ and a weak solution $u$ with pressure term $\nabla p$ of the system (2.23) with the following convergence properties as $j \rightarrow \infty$ (assuming for simplicity $\tilde{u}_{j}=u_{j}$ ):
(1) $u_{j}$ converges to $u$ weakly in $L^{2}\left(0, T ; W^{1,2}\left(\Omega_{j_{0}}\right)\right)$ and strongly in $L^{2}\left(0, T ; L^{2}\left(\Omega_{j_{0}}\right)\right)$ for each fixed $j_{0}$;
(2) $\nabla u_{j}$ converges to $\nabla u$ weakly in $L^{2}\left(0, T ; L^{2}\left(\Omega_{j_{0}}\right)\right)$;
(3) $u_{j}(t)$ converges to $u(t)$ strongly in $L^{2}\left(\Omega_{j_{0}}\right)$ for a.a. $t \in[0, T)$.

Furthermore, uniformly in $j \in \mathbf{N}$,

$$
\begin{align*}
\frac{1}{2}\left\|u_{j}\right\|_{L^{\infty}\left(L_{\sigma}^{2}\left(\Omega_{j}\right)\right)}^{2}+\left\|\nabla u_{j}\right\|_{L^{2}\left(L^{2}\left(\Omega_{j}\right)\right)}^{2} \leqslant C_{0}\|f\|_{L^{1}\left(L^{2}(\Omega)\right)}^{2}, \quad C_{0}>0  \tag{3.48}\\
\left\|u_{j}\right\|_{L^{\gamma}\left(L^{\delta}\left(\Omega_{j}\right)\right)} \leqslant C\|f\|_{L^{1}\left(L^{2}(\Omega)\right)}
\end{align*}
$$

where $\gamma \geqslant 2, \delta \geqslant 2,2 / \gamma+3 / \delta=3 / 2, C=C(\gamma, \delta)>0$, and

$$
\left\|u_{j} \cdot \nabla u_{j}\right\|_{L^{\gamma}\left(L^{\delta}\left(\Omega_{j}\right)\right)} \leqslant C\|f\|_{L^{1}\left(L^{2}(\Omega)\right)}^{2}
$$

where $1<\gamma, \delta<2,2 / \gamma+3 / \delta=4, C=C(\gamma, \delta)>0$.
Using the maximal regularity estimate (2.18) in the form (2.21) combined with the last estimate we are led to the inequality

$$
\begin{align*}
\left\|u_{j, t}\right\|_{L^{q}\left(L^{2}\left(\Omega_{j}\right)+L^{q}\left(\Omega_{j}\right)\right)}+\left\|u_{j}\right\|_{L^{q}\left(W^{2,2}\left(\Omega_{j}\right)+W^{2, q}\left(\Omega_{j}\right)\right)}+\left\|\nabla p_{j}\right\|_{L^{q}\left(L^{2}\left(\Omega_{j}\right)+L^{q}\left(\Omega_{j}\right)\right)} \\
\leqslant C\left(\|f\|_{L^{q}\left(L^{2}(\Omega)\right)}+\|f\|_{L^{1}\left(L^{2}(\Omega)\right)}^{2}\right) \tag{3.49}
\end{align*}
$$

with $q=\frac{5}{4}$ and $C=C(T, \alpha, \beta, K)>0$ not depending on $j \in \mathbf{N}$. Thus we may conclude without loss of generality, see the previous proofs, that

$$
\left(u_{j, t}, u_{j}, \nabla u_{j}, \nabla^{2} u_{j}, \nabla p_{j}\right) \rightharpoonup\left(u_{t}, u, \nabla u, \nabla^{2} u, \nabla p\right) \quad \text { in } L^{q}\left(0, T, L^{2}(\Omega)+L^{q}(\Omega)\right)
$$

as $j \rightarrow \infty$, and that (3.49) holds with $u_{j}$ and $\Omega_{j}$ replaced by $u$ and $\Omega$. This proves (2.25) for $u_{0}=0$.

To prove the local energy inequality (2.26) choose $j_{0}$ such that $\Omega \cap \operatorname{supp} \phi \subseteq \Omega_{j_{0}}$, use (2.26) from Step 1 for $\Omega_{j}$ and $u_{j}, j \geqslant j_{0}$, and let $j \rightarrow \infty$ using the convergence properties above. This proves (2.26) for $u$ and $\Omega$.

To prove (2.27) we choose a sequence $\phi_{j} \in C_{0}^{\infty}\left(\mathbf{R}^{3}\right), j \in \mathbf{N}$, satisfying $0 \leqslant \phi_{j} \leqslant 1$ and $\left|\nabla \phi_{j}^{2}\right| \leqslant C_{0}$ with some constant $C_{0}$, and with $\lim _{j \rightarrow \infty} \phi_{j}(x)=1$ and $\lim _{j \rightarrow \infty} \nabla \phi_{j}^{2}(x)=0$ for all $x \in \mathbf{R}^{3}$. Setting $\phi=\phi_{j}$ in (2.26) we obtain the desired inequality (2.27) by letting $j \rightarrow \infty$.

Now the proof of Theorem 2.7 is complete.

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