

AN OPERATIONAL HAAR WAVELET METHOD FOR SOLVING FRACTIONAL VOLTERRA INTEGRAL EQUATIONS

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A Haar wavelet operational matrix is applied to fractional integration, which has not been undertaken before. The Haar wavelet approximating method is used to reduce the fractional Volterra and Abel integral equations to a system of algebraic equations. A global error bound is estimated and some numerical examples with smooth, nonsmooth, and singular solutions are considered to demonstrate the validity and applicability of the developed method.

Keywords: fractional Volterra integral equation, Abel integral equation, fractional calculus, Haar wavelet method, operational matrices.

1. Introduction

The development of the theory of fractional integrals and derivatives starts with Euler, Liouville and Abel (1823). However, during the last ten years, fractional calculus has attracted much more attention of physicists and mathematicians. In fact, real problems in scientific fields such as physics, mechanics, chemistry and biology are formulated as partial differential equations or integral equations. Many authors have demonstrated applications of fractional calculus to coelastic materials (Bagley and Torvik, 1985), continuum and statistical mechanics (Mainardi, 1997), colored noise (Mandelbrot, 1967), economics (Baillie, 1996), bioengineering (Magin, 2004), anomalous diffusion and transport (Chena *et al.*, 2010), the dynamics of interfaces between nanoparticles and substrates (Chow, 2005), complex viscoelasticity (Meral *et al.*, 2010), rheology (Metzler, 2003) and others. There are also several methods for solving fractional integral equations like He's homotopy (Pandey *et al.*, 2009), Adomian

decomposition (Li and Wang, 2009), collocation method (Lepik, 2009) and power spectral density (Zaman and Yu, 1995).

The aim of this paper is to introduce a new operational wavelet method for approximating the solution of a fractional Volterra integral equation in the following form:

$$f(x) - \frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} k(x,t) f(t) dt = g(x), \quad (1)$$
$$0 \leq x \leq 1.$$

The kernel $k(x,t)$ and the right-hand-side function $g(x)$ are given, and $\alpha > 0$ is a real number. This equation is also referred to as the weakly-singular linear Volterra integral equation (see Hachbusch, 1995). The value $\alpha = 1$ corresponds to the ordinary (non-fractional) Volterra integral equation. Particularly, if $k(x,t) = 1$ and $0 < \alpha < 1$ in Eqn. (1), we have an Abel integral equation in the form

$$f(x) - \lambda \int_0^x \frac{f(t)}{(x-t)^\beta} dt = g(x), \quad 0 < \beta < 1, \quad (2)$$

where $\lambda = 1/\Gamma(\alpha)$ and $\beta = 1 - \alpha$.

The treatment of Eqn. (1) is not simple because, as is well known, the solutions of weakly singular Volterra integral equations usually have a weak singularity at $x = 0$, even when the inhomogeneous term $g(x)$ is smooth. Miller and Feldstein (1971) proved that the solution of (1) is unique and continuous in $[0, 1]$ if $g \in L^1(0, 1)$ and $k \in L^\infty$. A deeper insight into this problem is provided by many differentiability results for $f(x)$ obtained by various authors under specific hypotheses on $g(x)$ and $k(x, t)$ (Miller and Feldstein, 1971).

A possibility of nonsmooth solution complicates the numerical investigation of Eqn. (2). Various numerical techniques have been developed to treat such nonsmooth solutions (Baratella and Orsi, 2004; Brunner, 1984; Dixon, 1985). In general, the numerical solution of Eqn. (1) is often quite complicated, so we are looking for simplifications. For this reason we use an operational Haar wavelet method, since Haar wavelets are the simplest ones (Lepik, 2003; 2004, Maleknejad, 2005; Hsiao, 2007), and it has not received much attention so far. Only Lepik (2009) has used Haar wavelets to solve such equations. He has utilized these wavelets as a collocation method and introduced a local error estimate, but we use Haar wavelets to obtain an operational method which yields an operational matrix of fractional integration.

The main characteristic of an operational method is to convert a differential equation into an algebraic one. This not only simplifies the problem but also speeds up the computation. However, the interest in the wavelet treatment of various integral equations has recently increased due to promising applications of this method in computational chemistry (Chuev and Fedorov, 2004a; 2004b; 2004c; Fedorov, 2004; Fedorov and Khoromskij, 2007; Fedorov and Chuev, 2005).

In the present paper we first introduce Haar wavelets and their properties, then construct a new operational matrix of fractional integration via Haar wavelets. After that the method is described and its convergence is discussed. A global error estimate is also evaluated and several representative examples are considered. We should remark that, despite numerous examples of numerical evaluations of the fractional Volterra integral equation, a general theory guaranteeing the convergence of the solution for this equation is still incomplete (Baratella and Orsi, 2004; Brunner, 1984; Dixon, 1985; Miller and Feldstein, 1971). Therefore, to consider the conditions under which the method will fail, we shall apply our approach not only to smooth solutions, but also to those revealing nonsmooth behavior.

2. Function approximation

The orthogonal set of the Haar wavelets $h_n(x)$ is a group of square waves defined as follows:

$$h_0(x) = \begin{cases} 1, & 0 \leq x < 1, \\ 0, & \text{elsewhere,} \end{cases}$$

$$h_1(x) = \begin{cases} 1, & 0 \leq x < \frac{1}{2}, \\ -1, & \frac{1}{2} \leq x < 1, \\ 0, & \text{elsewhere,} \end{cases}$$

$$h_n(x) = h_1(2^j x - k),$$

$$n = 2^j + k, \quad j, k \in \mathbb{N} \cup \{0\}, \quad 0 \leq k < 2^j, \tag{3}$$

such that

$$\int_0^1 h_n(x)h_m(x) dx = 2^{-j}\delta_{nm},$$

where δ_{nm} is the Kronecker delta. For more details, see the works of Akansu and Haddad (1981), Vetterli and Kovacevic (1995), or Strang (1989).

The Heaviside step function is defined as

$$u(x) = \begin{cases} 1, & x \geq 0, \\ 0, & x < 0. \end{cases}$$

A useful property of this function is

$$u(x - a)u(x - b) = u(x - \max\{a, b\}), \quad a, b \in \mathbb{R}. \tag{4}$$

Note that we can write Eqn. (3) by using the Heaviside step function as

$$h_0(x) = u(x) - u(x - 1),$$

$$h_n(x) = u\left(x - \frac{k}{2^j}\right) - 2u\left(x - \frac{k + 1/2}{2^j}\right) + u\left(x - \frac{k + 1}{2^j}\right), \tag{5}$$

$$n = 2^j + k, \quad j, k \in \mathbb{N} \cup \{0\}, \quad 0 \leq k < 2^j.$$

Each square integrable function $f(x)$ in the interval $[0, 1]$ can be expanded into a Haar series of infinite terms:

$$f(x) = c_0h_0(x) + \sum_{j=0}^{\infty} \sum_{k=0}^{2^j-1} c_{2^j+k}h_{2^j+k}(x), \quad x \in [0, 1], \tag{6}$$

where the Haar coefficients are determined as

$$c_i = 2^j \int_0^1 f(x)h_i(x) dx, \tag{7}$$

$$i = 0, 2^j + k, \quad j, k \in \mathbb{N} \cup \{0\}, \quad 0 \leq k < 2^j,$$

such that the following integral square error ϵ_m is minimized:

$$\epsilon_m = \int_0^1 \left[f(x) - \sum_{i=0}^{m-1} c_i h_i(x) \right]^2 dx, \quad m = 2^{J+1}, \quad J \in \mathbb{N} \cup \{0\}.$$

By using Eqn. (5), the above Haar coefficients can be rewritten as

$$c_i = 2^j \left[\int_{\frac{k}{2^j}}^{\frac{k+1/2}{2^j}} f(x) dx - \int_{\frac{k+1/2}{2^j}}^{\frac{k+1}{2^j}} f(x) dx \right], \quad i = 2^j + k, \quad j, k \in \mathbb{N} \cup \{0\}, \quad 0 \leq k < 2^j. \quad (8)$$

If $f(x)$ is piecewise constant or may be approximated by a piecewise constant function during each subinterval, the series sum in Eqn. (6) can be truncated after m terms ($m = 2^{J+1}$, $J \geq 0$ being the resolution level of the wavelet), that is

$$f(x) \cong c_0 h_0(x) + \sum_{j=0}^J \sum_{k=0}^{2^j-1} c_{2^j+k} h_{2^j+k}(x) = \mathbf{c}^T \mathbf{h}(x) = f_m(x), \quad x \in [0, 1], \quad (9)$$

where $\mathbf{c} = \mathbf{c}_{m \times 1} = [c_0, c_1, \dots, c_{m-1}]^T$, $\mathbf{h}(x) = \mathbf{h}_{m \times 1}(x) = [h_0(x), h_1(x), \dots, h_{m-1}(x)]^T$.

3. Haar wavelet operational matrix of fractional integration

In this section we obtain an operational matrix of fractional integration, based on Haar wavelets, which is novel. The Riemann–Liouville fractional integral operator of order $\alpha > 0$ of the function $f(x)$ is defined as (Podlubny, 1999; Miller and Ross, 1993)

$$I^\alpha f(x) = \frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} f(t) dt, \quad \alpha > 0, \quad x > 0, \quad (10)$$

where $\Gamma(\cdot)$ is the Gamma function with the property $\Gamma(x+1) = x\Gamma(x)$, $x \in \mathbb{R}$. Some properties of the operator I^α can be found in the research by Podlubny (1999). We mention only the following: For $\alpha \geq 0$ and $\gamma > -1$, we have

$$I^\alpha x^\gamma = \frac{\Gamma(\gamma+1)}{\Gamma(\alpha+\gamma+1)} x^{\alpha+\gamma}. \quad (11)$$

The integration of $\mathbf{h}(x)$ can be expanded into a Haar series with a Haar coefficient matrix \mathbf{P}_m (Chen and Hsiao, 1997) as

$$\int_0^x \mathbf{h}(x) dx \cong \mathbf{P}_m \mathbf{h}(x).$$

The $m \times m$ matrix \mathbf{P}_m is called the operational matrix of integration and is given by Hsiao and Wu (2007) as

$$\mathbf{P}_m = \frac{1}{2m} \begin{bmatrix} 2m\mathbf{P}_{m/2} & -\mathbf{H}_{m/2 \times m/2} \\ \mathbf{H}_{m/2 \times m/2}^{-1} & \mathbf{0} \end{bmatrix}, \quad (12)$$

where $\mathbf{H}_{1 \times 1} = [1]$, $\mathbf{P}_1 = [1/2]$ and

$$\mathbf{H}_{m \times m} = \left[\mathbf{h}\left(\frac{1}{2m}\right), \mathbf{h}\left(\frac{3}{2m}\right), \dots, \mathbf{h}\left(\frac{2m-1}{2m}\right) \right].$$

Three basic multiplication properties of Haar wavelets are as follows (Hsiao and Wu, 2007):

- (i) $h_n(x)h_0(x) = h_n(x)$ for any $n \in \mathbb{N} \cup \{0\}$.
- (ii) For any two Haar wavelets $h_n(x)$ and $h_l(x)$ with $n < l$, we have

$$h_n(x)h_l(x) = \rho_{nl}h_l(x),$$

where

$$\rho_{nl} = h_n(2^{-i}(q+1/2)) = \begin{cases} 1, & 2^{i-j}k \leq q < 2^{i-j}(k+1/2), \\ -1, & 2^{i-j}(k+1/2) \leq q < 2^{i-j}(k+1), \\ 0, & \text{elsewhere,} \end{cases} \quad (13)$$

for $n = 2^j + k$, $j \geq 0$, $0 \leq k < 2^j$ and $l = 2^i + q$, $i \geq 0$, $0 \leq q < 2^i$.

- (iii) The square of any Haar wavelet is a block pulse with a magnitude of 1 during both positive and negative half waves.

The product of $\mathbf{h}(x)$, $\mathbf{h}^T(x)$ and \mathbf{c} can also be expanded into a Haar series with a Haar coefficient matrix \mathbf{M}_m as follows:

$$\mathbf{h}(x)\mathbf{h}^T(x)\mathbf{c} = \mathbf{M}_m\mathbf{h}(x),$$

where \mathbf{M}_m is an $m \times m$ matrix referred to as the product operational matrix and given by Hsiao and Wu (2007):

$$\mathbf{M}_m = \begin{bmatrix} \mathbf{M}_{m/2} & \mathbf{H}_{m/2} \text{diag}(\tilde{\mathbf{c}}_b) \\ \text{diag}(\tilde{\mathbf{c}}_b)\mathbf{H}_{m/2}^{-1} & \text{diag}(\tilde{\mathbf{c}}_a^T \mathbf{H}_{m/2}) \end{bmatrix}, \quad (14)$$

such that $\mathbf{M}_1 = c_0$ and

$$\tilde{\mathbf{c}}_a = [c_0, \dots, c_{m/2-1}]^T, \quad \tilde{\mathbf{c}}_b = [c_{m/2}, \dots, c_{m-1}]^T.$$

Now we want to obtain the operational matrix of fractional integration for Haar wavelets, which is a generalized form of \mathbf{P}_m in (12). The fractional integration of

order α of $\mathbf{h}(x)$ can be expanded into a Haar series with a Haar coefficient matrix \mathbf{P}_m^α as follows:

$$\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} \mathbf{h}(t) dt = \mathbf{P}_m^\alpha \mathbf{h}(x). \quad (15)$$

We call this $m \times m$ square matrix \mathbf{P}_m^α the (generalized) operational matrix of fractional integration. Thus for expanding the Riemann–Liouville integral, it is enough to expand

$$\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} h_n(t) dt,$$

for $n = 0, 1, \dots, m-1$, in a Haar series. We know that

$$\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} h_n(t) dt = \frac{1}{\Gamma(\alpha)} \{x^{\alpha-1} * h_n(x)\},$$

where $*$ is the convolution operator of two functions. By taking the Laplace transform of the above equation, we have

$$\begin{aligned} \mathcal{L}\left\{\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} h_n(t) dt\right\} \\ = \frac{1}{\Gamma(\alpha)} \mathcal{L}\{x^{\alpha-1}\} \mathcal{L}\{h_n(x)\}, \end{aligned} \quad (16)$$

where

$$\begin{aligned} \mathcal{L}\{x^{\alpha-1}\} &= \frac{\Gamma(\alpha)}{s^\alpha}, \\ \mathcal{L}\{h_n(x)\} &= \mathcal{L}\left\{u\left(x - \frac{k}{2^j}\right) - 2u\left(x - \frac{k+1/2}{2^j}\right) \right. \\ &\quad \left. + u\left(x - \frac{k+1}{2^j}\right)\right\} \\ &= \frac{1}{s} \left\{e^{-\frac{k}{2^j}s} - 2e^{-\frac{k+1/2}{2^j}s} + e^{-\frac{k+1}{2^j}s}\right\}. \end{aligned}$$

The last two equalities are obtained using the properties of the Laplace transform. Therefore, (16) can be rewritten as

$$\begin{aligned} \mathcal{L}\left\{\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} h_n(t) dt\right\} \\ = \frac{1}{\Gamma(\alpha+1)} \cdot \frac{\Gamma(\alpha+1)}{s^{\alpha+1}} \\ \cdot \left\{e^{-\frac{k}{2^j}s} - 2e^{-\frac{k+1/2}{2^j}s} + e^{-\frac{k+1}{2^j}s}\right\}. \end{aligned}$$

Now, taking the inverse Laplace transform of the

above equation, we find

$$\begin{aligned} &\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} h_n(t) dt \\ &= \frac{1}{\Gamma(\alpha+1)} \left\{ \underbrace{\left(x - \frac{k}{2^j}\right)^\alpha u\left(x - \frac{k}{2^j}\right)}_{X(x)} \right. \\ &\quad \left. - 2 \underbrace{\left(x - \frac{k+1/2}{2^j}\right)^\alpha u\left(x - \frac{k+1/2}{2^j}\right)}_{Y(x)} \right. \\ &\quad \left. \cdot \underbrace{\left(x - \frac{k+1}{2^j}\right)^\alpha u\left(x - \frac{k+1}{2^j}\right)}_{Z(x)} \right\} \\ &= \frac{1}{\Gamma(\alpha+1)} \{X(x) - 2Y(x) + Z(x)\}. \end{aligned} \quad (17)$$

Specifically, for $n = 0$, we have

$$\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} h_0(t) dt = \frac{1}{\Gamma(\alpha+1)} W(x), \quad (18)$$

where

$$W(x) = x^\alpha u(x) - (x-1)^\alpha u(x-1).$$

Equations (17) and (18) can be expanded into Haar wavelets as

$$I^\alpha h_n(x) = c_{n0} h_0(x) + \sum_{p=0}^J \sum_{q=0}^{2^p-1} c_{n2^p+q} h_{2^p+q}(x) \quad (19)$$

for $n = 0, 1, \dots, m-1$.

Now we want to obtain the coefficients c_{nl} , $n, l = 0, 1, \dots, m-1$ in the above equation. According to (4) and (5), we have

$$\begin{aligned} c_{00} &= \frac{1}{\Gamma(\alpha+1)} \int_0^1 W(t) h_0(t) dt = \frac{1}{\Gamma(\alpha+2)}, \\ c_{02^p+q} &= \frac{2^p}{\Gamma(\alpha+1)} \int_0^1 W(t) h_{2^p+q}(t) dt \\ &= \frac{2^p}{\Gamma(\alpha+1)} \int_0^1 W(t) \left\{ u\left(t - \frac{q}{2^p}\right) \right. \\ &\quad \left. - 2u\left(t - \frac{q+1/2}{2^p}\right) + u\left(t - \frac{q+1}{2^p}\right) \right\} dt \\ &= \frac{2^p}{\Gamma(\alpha+1)} \left[\int_{\frac{q}{2^p}}^1 t^\alpha dt - 2 \int_{\frac{q+1/2}{2^p}}^1 t^\alpha dt \right. \\ &\quad \left. + \int_{\frac{q+1}{2^p}}^1 t^\alpha dt \right]. \end{aligned}$$

Thus

$$c_{02^p+q} = -\frac{2^p}{\Gamma(\alpha+2)} \cdot \left[\left(\frac{q}{2^p}\right)^{\alpha+1} - 2\left(\frac{q+1/2}{2^p}\right)^{\alpha+1} + \left(\frac{q+1}{2^p}\right)^{\alpha+1} \right], \tag{20}$$

where $p = 0, 1, \dots, J$ and $q = 0, 1, \dots, 2^p - 1$.

Similarly, to calculate c_{n0} and c_{n2^p+q} for $n = 1, 2, \dots, m-1, p = 0, 1, \dots, J$ and $q = 0, 1, \dots, 2^p - 1$ (in Eqn. (19)), we have

$$\begin{aligned} c_{n0} &= \frac{1}{\Gamma(\alpha+1)} \int_0^1 [X(t) - 2Y(t) + Z(t)] h_0(t) dt \\ &= \frac{1}{\Gamma(\alpha+1)} \int_0^1 [X(t) - 2Y(t) + Z(t)] \cdot [u(t) - u(t-1)] dt \\ &= \frac{1}{\Gamma(\alpha+1)} \left[\int_{\frac{k}{2^j}}^1 \left(t - \frac{k}{2^j}\right)^\alpha dt - 2 \int_{\frac{k+1/2}{2^j}}^1 \left(t - \frac{k+1/2}{2^j}\right)^\alpha dt + \int_{\frac{k+1}{2^j}}^1 \left(t - \frac{k+1}{2^j}\right)^\alpha dt \right]. \end{aligned}$$

Consequently,

$$\begin{aligned} c_{n0} &= \frac{1}{\Gamma(\alpha+2)} \left[\left(1 - \frac{k}{2^j}\right)^{\alpha+1} - 2\left(1 - \frac{k+1/2}{2^j}\right)^{\alpha+1} + \left(1 - \frac{k+1}{2^j}\right)^{\alpha+1} \right]. \tag{21} \end{aligned}$$

and

$$\begin{aligned} c_{n2^p+q} &= \frac{2^p}{\Gamma(\alpha+1)} \int_0^1 [X(t) - 2Y(t) + Z(t)] h_{2^p+q}(t) dt \\ &= \frac{2^p}{\Gamma(\alpha+1)} \int_0^1 [X(t) - 2Y(t) + Z(t)] \left[u\left(t - \frac{q}{2^p}\right) - 2u\left(t - \frac{q+1/2}{2^p}\right) + u\left(t - \frac{q+1}{2^p}\right) \right] dt \\ &= \frac{2^p}{\Gamma(\alpha+1)} \left[\int_{\eta_0}^1 \left(t - \frac{k}{2^j}\right)^\alpha dt - 2 \int_{\theta_{1/2}}^1 \left(t - \frac{k+1/2}{2^j}\right)^\alpha dt + \int_{\theta_1}^1 \left(t - \frac{k+1/2}{2^j}\right)^\alpha dt + \frac{2^p}{\Gamma(\alpha+1)} \left[\int_{\xi_0}^1 \left(t - \frac{k+1}{2^j}\right)^\alpha dt - 2 \int_{\xi_{1/2}}^1 \left(t - \frac{k+1}{2^j}\right)^\alpha dt + \int_{\xi_1}^1 \left(t - \frac{k+1}{2^j}\right)^\alpha dt \right] \right], \end{aligned}$$

$$\begin{aligned} &- 2 \int_{\eta_{1/2}}^1 \left(t - \frac{k}{2^j}\right)^\alpha dt + \int_{\eta_1}^1 \left(t - \frac{k}{2^j}\right)^\alpha dt \\ &- 2 \frac{2^p}{\Gamma(\alpha+1)} \left[\int_{\theta_0}^1 \left(t - \frac{k+1/2}{2^j}\right)^\alpha dt - 2 \int_{\theta_{1/2}}^1 \left(t - \frac{k+1/2}{2^j}\right)^\alpha dt + \int_{\theta_1}^1 \left(t - \frac{k+1/2}{2^j}\right)^\alpha dt + \frac{2^p}{\Gamma(\alpha+1)} \left[\int_{\xi_0}^1 \left(t - \frac{k+1}{2^j}\right)^\alpha dt - 2 \int_{\xi_{1/2}}^1 \left(t - \frac{k+1}{2^j}\right)^\alpha dt + \int_{\xi_1}^1 \left(t - \frac{k+1}{2^j}\right)^\alpha dt \right] \right], \end{aligned}$$

where

$$\begin{aligned} \eta_i &= \max \left\{ \frac{k}{2^j}, \frac{q+i}{2^p} \right\}, & i = 0, 1/2, 1, \\ \theta_i &= \max \left\{ \frac{k+1/2}{2^j}, \frac{q+i}{2^p} \right\}, & i = 0, 1/2, 1, \\ \xi_i &= \max \left\{ \frac{k+1}{2^j}, \frac{q+i}{2^p} \right\}, & i = 0, 1/2, 1. \end{aligned}$$

Therefore

$$\begin{aligned} c_{n2^p+q} &= -\frac{2^p}{\Gamma(\alpha+2)} \left[\left(\eta_0 - \frac{k}{2^j}\right)^{\alpha+1} - 2\left(\eta_{1/2} - \frac{k}{2^j}\right)^{\alpha+1} + \left(\eta_1 - \frac{k}{2^j}\right)^{\alpha+1} \right] \\ &+ 2 \frac{2^p}{\Gamma(\alpha+2)} \left[\left(\theta_0 - \frac{k+1/2}{2^j}\right)^{\alpha+1} - 2\left(\theta_{1/2} - \frac{k+1/2}{2^j}\right)^{\alpha+1} + \left(\theta_1 - \frac{k+1/2}{2^j}\right)^{\alpha+1} \right] \\ &- \frac{2^p}{\Gamma(\alpha+2)} \left[\left(\xi_0 - \frac{k+1}{2^j}\right)^{\alpha+1} - 2\left(\xi_{1/2} - \frac{k+1}{2^j}\right)^{\alpha+1} + \left(\xi_1 - \frac{k+1}{2^j}\right)^{\alpha+1} \right], \end{aligned}$$

for $n = 1, 2, \dots, m-1, p = 0, 1, \dots, J$ and $q = 0, 1, \dots, 2^p - 1$. Thus, we can write the operational matrix of fractional integration as

$$\mathbf{P}_m^\alpha = \begin{bmatrix} \mathbf{P}_{m/2}^\alpha & \mathbf{R}_{m/2 \times m/2} \\ \mathbf{S}_{m/2 \times m/2} & \mathbf{U}_{m/2 \times m/2} \end{bmatrix},$$

where

$$\mathbf{R}_{m/2 \times m/2} = [c_{n2^j+q}],$$

for $n = 0, 1, \dots, m/2 - 1, q = 0, 1, \dots, 2^j - 1$ and $\mathbf{S}_{m/2 \times m/2} = [c_{nl}]$, $n = m/2, \dots, m-1$, and $l = 0, 1, \dots, m/2 - 1$ are calculated easily by (20), (22) and (21), (22), respectively, and $\mathbf{U}_{m/2 \times m/2}$ is an upper triangular matrix in the form

$$\mathbf{U}_{m/2 \times m/2} = u_1 \mathbf{I} + u_2 \mu + u_3 \mu^2 + \dots + u_{m/2} \mu^{m/2-1},$$

such that

$$u_i = \begin{cases} \frac{2^J}{\Gamma(\alpha + 2)} \left(\frac{1}{2^J}\right)^{\alpha+1} [4(1/2)^{\alpha+1} - 1], & \text{if } i = 1, \\ \frac{2^J}{\Gamma(\alpha + 2)} \left(\frac{1}{2^J}\right)^{\alpha+1} \left[-i^{\alpha+1} + 4(i - 1/2)^{\alpha+1} - 6(i - 1)^{\alpha+1} + 4(i - 3/2)^{\alpha+1} - (i - 2)^{\alpha+1} \right], & \text{if } i = 2, \dots, m/2, \end{cases}$$

$\mathbf{I}_{m/2}$ is an $(m/2) \times (m/2)$ identity matrix and

$$\mu_{m/2} = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \ddots & \vdots \\ \vdots & & \ddots & \ddots & 0 \\ & & & & 1 \\ 0 & & \dots & & 0 \end{bmatrix}_{m/2 \times m/2}$$

It is essential that, for $\alpha = 1$, the fractional integration (10) is the ordinary integration and the generalized operational matrix of fractional integration \mathbf{P}_m^α is the same as \mathbf{P}_m , which is introduced in (12). Here we present $\mathbf{P}_m^{1/3}$ for $J = 0, 1$:

$$\mathbf{P}_2^{1/3} = \begin{bmatrix} 0.8399 & -0.1733 \\ 0.1733 & 0.4933 \end{bmatrix},$$

$$\mathbf{P}_4^{1/3} = \begin{bmatrix} 0.8399 & -0.1733 & -0.1375 & -0.0571 \\ 0.1733 & 0.4933 & -0.1375 & 0.2179 \\ 0.0286 & 0.1090 & 0.3916 & -0.0428 \\ 0.0688 & -0.0688 & 0 & 0.3916 \end{bmatrix},$$

4. Application of the method

According to Section (2), the right-hand side of Eqn. (1) is approximated as

$$g(x) \cong g_0 h_0(x) + \sum_{j=0}^J \sum_{k=0}^{2^j-1} g_{2^j+k} h_{2^j+k}(x) = \mathbf{g}^T \mathbf{h}(x). \tag{22}$$

Similarly, $K(x, t) \in L^2([0, 1) \times [0, 1))$ can be approximated as

$$k(x, t) \cong \sum_{i=0}^{m-1} \sum_{j=0}^{m-1} k_{ij} h_i(x) h_j(t),$$

or, in matrix form,

$$k(x, t) \cong \mathbf{h}^T(x) \mathbf{K} \mathbf{h}(t), \tag{23}$$

where $\mathbf{K} = [k_{ij}]_{m \times m}$, such that

$$k_{ij} = 2^{i+j} \int_0^1 \int_0^1 k(x, t) h_i(x) h_j(t) dt dx, \quad i, j = 0, 1, \dots, m - 1.$$

Also, the fractional integral part of (1) is written as

$$\frac{1}{\Gamma(\alpha)} \int_0^x (x - t)^{\alpha-1} k(x, t) f(t) dt \cong \tilde{\mathbf{v}} \mathbf{h}(x). \tag{24}$$

The details of calculating $\tilde{\mathbf{v}}$ are shown in Appendix. By substituting the approximations (9), (33) and (22) into (1), we obtain

$$\mathbf{h}^T(x) \mathbf{c} - \mathbf{h}^T(x) \tilde{\mathbf{v}} = \mathbf{h}^T(x) \mathbf{g}.$$

Therefore,

$$\mathbf{c} - \tilde{\mathbf{v}} = \mathbf{g}. \tag{25}$$

Equation (25) is a system of linear equations and can be easily solved for the unknown vector \mathbf{c} . Note that the entries of the vector $\tilde{\mathbf{v}}$ are related to the entries of \mathbf{c} . Similarly, the Abel integral equation (2) can be written as

$$\mathbf{h}^T(x) \mathbf{c} - \mathbf{h}^T(x) (\mathbf{P}_m^\alpha)^T \mathbf{c} = \mathbf{h}^T(x) \mathbf{g}.$$

Therefore,

$$\mathbf{c} - (\mathbf{P}_m^\alpha)^T \mathbf{c} = \mathbf{g}. \tag{26}$$

Equation (26) is a system of linear equations and can be easily solved for the unknown vector \mathbf{c} :

$$\mathbf{c} = (I - (\mathbf{P}_m^\alpha)^T)^{-1} \mathbf{g}.$$

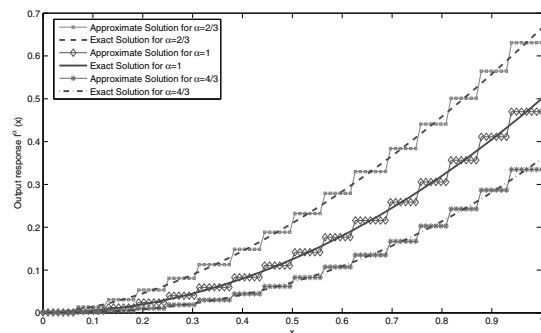


Fig. 1. Fractional integration of $f(x) = x$ and its approximation ($I^\alpha f_{16}(x)$) for $\alpha = 2/3, 1, 4/3$.

5. Error analysis

Let us consider the following integral equation:

$$f(x) - \frac{1}{\Gamma(\alpha)} \int_0^x (x - t)^{\alpha-1} k(x, t) f(t) dt = g(x), \quad 0 \leq x \leq 1. \tag{27}$$

Suppose that $f(x)$ is the exact solution of the above integral equation. In order to analyze the convergence of our method, we will define the following error function and show that the method is convergent for a special class of functions in the sense that the corresponding error tends to zero as m tends to infinity.

Definition 1. If $f(x)$ and $f_m(x) = \mathbf{c}^T \mathbf{h}(x)$ are the exact and approximate solutions of (27), respectively, then the corresponding error is defined as follows:

$$e_m(x) = f(x) - f_m(x).$$

It is clear that

$$e_m(x) = \sum_{j=J+1}^{\infty} \sum_{k=0}^{2^j-1} c_{2^j+k} h_{2^j+k}(x).$$

Now we will prove the following convergence theorem.

Theorem 1. Suppose that $f(x)$ satisfies a Lipschitz condition on $[0, 1]$, that is,

$$\exists M > 0, \forall x, y \in [0, 1] : |f(x) - f(y)| \leq M|x - y|. \tag{28}$$

Then the Haar wavelet method will be convergent in the sense that $e_m(x)$ goes to zero as m goes to infinity. Moreover, the convergence is of order one, that is,

$$\|e_m(x)\|_2 = O\left(\frac{1}{m}\right).$$

Proof. We have

$$\begin{aligned} \|e_m(x)\|_2^2 &= \int_0^1 \left(\sum_{j=J+1}^{\infty} \sum_{k=0}^{2^j-1} c_{2^j+k} h_{2^j+k}(x) \right)^2 dx \\ &= \sum_{j=J+1}^{\infty} \sum_{k=0}^{2^j-1} c_{2^j+k}^2 \int_0^1 h_{2^j+k}^2(x) dx \\ &\quad + \sum_{j=J+1}^{\infty} \sum_{k=0}^{2^j-1} \sum_{p=J+1}^{\infty} \sum_{q=0, q \neq k}^{2^p-1} \left\{ c_{2^j+k} \right. \\ &\quad \cdot \left. c_{2^p+q} \int_0^1 h_{2^j+k}(x) h_{2^p+q}(x) dx \right\} \\ &= \sum_{j=J+1}^{\infty} \sum_{k=0}^{2^j-1} c_{2^j+k}^2 \left(\frac{1}{2^j} \right). \end{aligned}$$

Since $c_{2^j+k} = 2^j \int_0^1 f(x) h_i(x) dx$, by (8) and using the mean value theorem, we have

$$\exists x_1^{jk} \in \left[\frac{k}{2^j}, \frac{k+1/2}{2^j} \right], x_2^{jk} \in \left[\frac{k+1/2}{2^j}, \frac{k+1}{2^j} \right],$$

such that

$$\begin{aligned} c_{2^j+k} &= 2^j \left[\left(\frac{k+1/2}{2^j} - \frac{k}{2^j} \right) f(x_1^{jk}) \right. \\ &\quad \left. - \left(\frac{k+1}{2^j} - \frac{k+1/2}{2^j} \right) f(x_2^{jk}) \right] \\ &= \frac{1}{2} [f(x_1^{jk}) - f(x_2^{jk})] \\ &\leq \frac{1}{2} M(x_1^{jk} - x_2^{jk}) \\ &\leq \frac{1}{2} M \frac{1}{2^j} = M \frac{1}{2^{j+1}}. \end{aligned}$$

The first inequality is obtained by (28). Therefore, $c_{2^j+k}^2 \leq M^2 \frac{1}{2^{2j+2}}$ and

$$\begin{aligned} \|e_m(x)\|_2^2 &= \sum_{j=J+1}^{\infty} \sum_{k=0}^{2^j-1} c_{2^j+k}^2 \left(\frac{1}{2^j} \right) \\ &\leq \sum_{j=J+1}^{\infty} \sum_{k=0}^{2^j-1} M^2 \frac{1}{2^{2j+2}} \left(\frac{1}{2^j} \right) \\ &= \frac{M^2}{4} \sum_{j=J+1}^{\infty} 2^j \frac{1}{2^{3j}} \\ &= \frac{M^2}{3} \left(\frac{1}{2^{J+1}} \right)^2. \end{aligned}$$

Since $m = 2^{J+1}$, we have

$$\|e_m(x)\|_2^2 \leq \frac{M^2}{3} \left(\frac{1}{m} \right)^2$$

or, in other words,

$$\|e_m(x)\|_2 = O\left(\frac{1}{m}\right).$$

■

By the above proof, we can obtain a bound for $\|e_m(x)\|_2$

$$\|e_m(x)\|_2 \leq \frac{M}{m\sqrt{3}}. \tag{29}$$

At the end of this section, we discuss the conditions under which our method will fail or will not give us an acceptable approximation. The solution $f(x)$ of Eqn. (27) is generally not differentiable at the initial point (Vainikko and Pedas, 1981). On the other hand, the Lipschitz continuity of functions on the real line is closely related to differentiability, i.e., an everywhere differentiable function $f : \mathbb{R} \rightarrow \mathbb{R}$ is Lipschitz continuous (with $M = \sup |f'(x)|$) if and only if it has the first derivative bounded (one direction follows from the mean value theorem). So due to the non-smoothness of $f(x)$ at the initial point, the Lipschitz constant M may not exist or may be too large. Therefore, the error bound (29) will increase and we will not have a good approximation.

5.1. Estimation of the error function. In real problems, we often tend to solve equations with unknown exact solutions. These unknown exact solutions may be singular, smooth or not. Hence, when we apply our method to these problems, we cannot say that this approximate solution is good or bad unless we are able to calculate the error function $e_m(x)$. Therefore, it is necessary to introduce a process for estimating the error function when the exact solution is unknown.

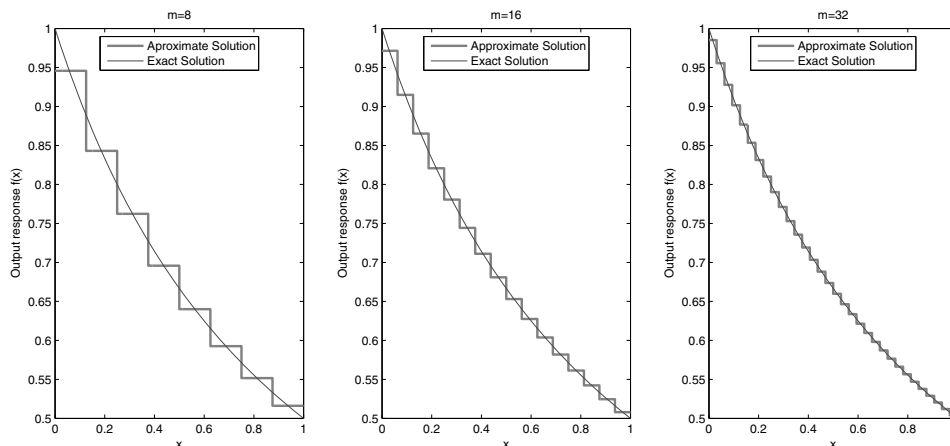


Fig. 2. Approximate solutions of Example 2 for selected values of m .

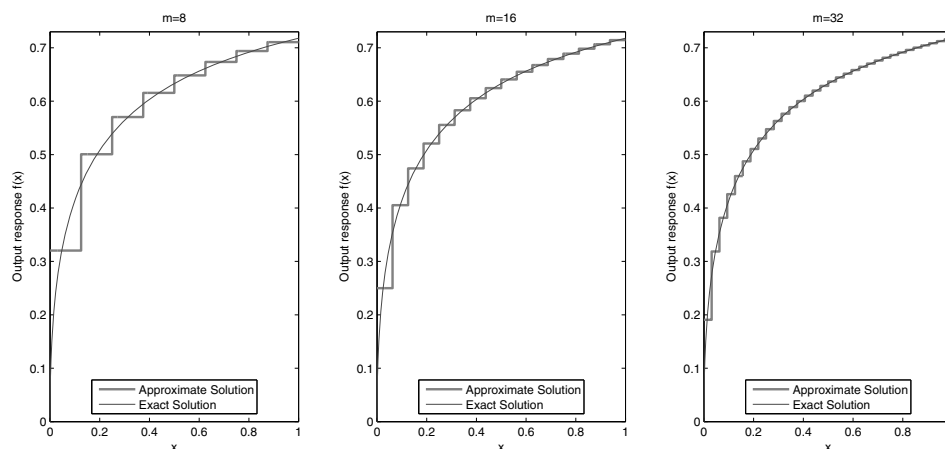


Fig. 3. Approximate solutions of Example 3 for selected values of m .

Here we introduce a method to estimate the error function. Since $f_m(x)$ is considered an approximate solution of Eqn. (1), it satisfies the following equation:

$$f_m(x) - \frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} k(x,t) f_m(t) dt = g(x) + r_m(x), \quad (30)$$

The perturbation term $r_m(x)$ can be obtained by substituting the estimated solution $f_m(x)$ into the equation

$$r_m(x) = f_m(x) - \frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} k(x,t) f_m(t) dt - g(x). \quad (31)$$

Subtracting (30) from (1), we get the following equation:

$$e_m(x) - \frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} k(x,t) e_m(t) dt = -r_m(x). \quad (32)$$

Obviously, the above is a fractional Volterra integral equation in which the error function, $e_m(x)$, is unknown. We can easily apply our method to the above equation to find an approximation of the error function $e_m(x)$.

6. Numerical examples

To show the efficiency of the proposed method, we will apply our method to obtain the approximate solution of the following examples. All of the computations have been performed using MATLAB 7.8. Note that

$$\|e_m(x)\|_2 = \left(\int_0^1 e_m^2(x) dx \right)^{1/2} \cong \left(\frac{1}{N} \sum_{i=0}^N e_m^2(x_i) \right)^{1/2},$$

where $f(x)$ is the exact solution and $f_m(x)$ is the approximate solution obtained by Eqn. (9).

Example 1. Let $f(x) = x$. Here we approximate $I^\alpha f(x)$ by \mathbf{P}_m^α for $\alpha = 2/3, 1, 4/3$ and compare it with the exact fractional integration of the function $f(x) = x$, which is easily obtained by (11). If we write $x \cong \mathbf{c}^T \mathbf{h}(x)$, we will have $I^\alpha x \cong \mathbf{c}^T I^\alpha \mathbf{h}(x) \cong \mathbf{c}^T \mathbf{P}_m^\alpha \mathbf{h}(x)$. Numerical results for $m = 16$ are shown in Fig. 1. ♦

Example 2. (Pandey *et al.*, 2009) Consider the following Abel integral equation of the second kind:

$$f(x) = \frac{1}{1+x} + \frac{2\operatorname{arcsinh}(\sqrt{x})}{\sqrt{1+x}} - \int_0^x \frac{f(t)}{\sqrt{x-t}} dt = x, \quad 0 \leq x \leq 1,$$

which has the exact solution $f(x) = 1/(1+x)$. Numerical results are shown in Table 1 and Fig. 2.

Example 3. (Yousefi, 2006) Consider the following Abel integral equation of the second kind:

$$f(x) = 2\sqrt{x} - \int_0^x \frac{f(t)}{\sqrt{x-t}} dt = x, \quad 0 \leq x \leq 1,$$

which has $f(x) = 1 - e^{-\pi x} \operatorname{erfc}(\sqrt{\pi x})$ as the exact solution, where the complementary error function $\operatorname{erfc}(x)$ is defined as

$$\operatorname{erfc}(x) = \frac{2}{\sqrt{\pi}} \int_x^\infty e^{-t^2} dt.$$

Here $\alpha = 1/2$. Numerical results are shown in Table 1 and Fig. 3. ♦

Example 4. Consider the following fractional Volterra integral equation:

$$f(x) + \int_0^x \frac{xt}{\sqrt{x-t}} f(t) dt = g(x), \quad 0 \leq x \leq 1,$$

where

$$g(x) = x(1-x) + \frac{16}{105} x^{\frac{7}{2}} (7-6x)$$

and $f(x) = x(1-x)$ is the exact solution. The numerical results are shown in Table 1 and Fig. 4. ♦

Let us consider examples with nonsmooth and singular solutions.

Example 5. (Pandey, 2009) Consider the fractional Volterra integral equation:

$$f(x) = \frac{1}{\sqrt{x}} + \pi - \int_0^x \frac{f(t)}{\sqrt{x-t}} dt = x, \quad 0 \leq x \leq 1,$$

which has $f(x) = 1/\sqrt{x}$ as the exact solution. In this case there is a singularity at the point $x = 0$. As discussed in Section 5, the solution around this point is not so good (see Fig. 5). Hence the numerical results in Table 1 have been calculated in $[0.1, 1]$. As can be seen, our method provides reasonable estimates even in this case with a singular solution. ♦

Example 6. Consider the following Abel integral equation of the first kind:

$$\int_0^x \frac{f(t)}{\sqrt{x-t}} dt = x,$$

with the exact solution $f(x) = \frac{2}{\pi} \sqrt{x}$. Numerical results are shown in Fig. 6 and Table 1, for some selected values of m . ♦

Example 7. (Abdalkhania, 1990; Dixon, 1985) Consider the following fractional Volterra integral equation:

$$f(x) + \int_0^x \frac{f(t)}{\sqrt{x-t}} dt = \frac{1}{2} \pi x + \sqrt{x}, \quad 0 \leq x \leq 1,$$

which has $f(x) = \sqrt{x}$ as the exact solution. Numerical results are shown in Table 1 and Fig. 7. ♦

As can be seen, in contrast to the singular solution (Example 6), the method provides rather accurate results for nonsmooth solutions (Examples 6 and 7).

7. Conclusion

Haar wavelets have been applied to study integral equations with a nonsingular kernel (Lepik, 2004; Maleknejad and Mirzaee, 2005). In this paper we use them to solve the fractional Volterra integral equation which has a weakly singular kernel. For this purpose, we generalized the operational matrix of integration to the case of fractional integration. We considered various types of solutions, with smooth, nonsmooth and even singular behaviors. In all the cases considered, the method provides reasonable estimates. Numerical examples and their error analysis show that more accurate results are obtained when finer resolutions are used. We hope the method to be generalized to the case of fractional Fredholm integral equations, which is the interest of current applications in computational chemistry (Chiodo, 2007; Chuev, 2006; 2007; 2008).

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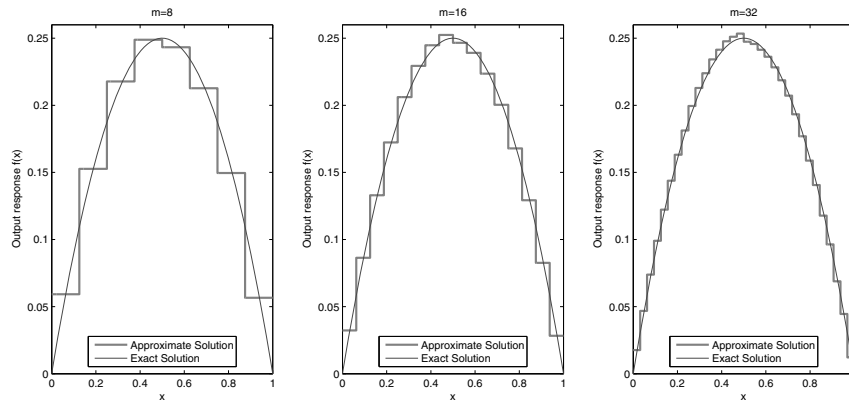


Fig. 4. Approximate solutions of Example 4 for selected values of m .

Table 1. Approximate norm-2 of the absolute error, $\|e_m(x)\|_2$, for $m = 8, 16, 32, 64, 128$.

Examples	$\ e_8(x)\ _2$	$\ e_{16}(x)\ _2$	$\ e_{32}(x)\ _2$	$\ e_{64}(x)\ _2$	$\ e_{128}(x)\ _2$
Example 2	3.7602e+000	9.5290e-005	2.3838e-005	5.9609e-006	1.4936e-006
Example 3	1.3111e-003	4.8933e-004	1.7606e-004	6.1280e-005	2.1571e-005
Example 4	4.3628e-004	1.1572e-004	3.4342e-005	1.4039e-005	9.0411e-006
Example 5	1.2696e+001	3.7150e-003	1.0089e-003	2.6852e-004	8.4154e-005
Example 6	6.9314e-004	1.9918e-004	5.7015e-005	1.6171e-005	4.6829e-006
Example 7	1.5713e-003	4.5647e-004	1.3244e-004	3.8332e-005	1.1353e-005

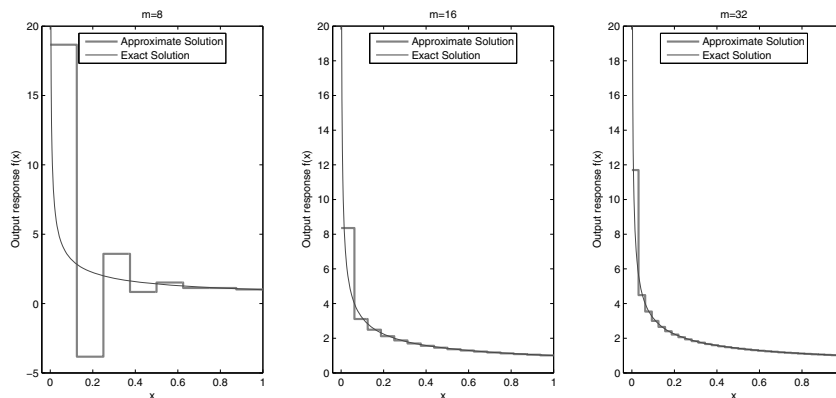


Fig. 5. Approximate solutions of Example 5 for selected values of m .

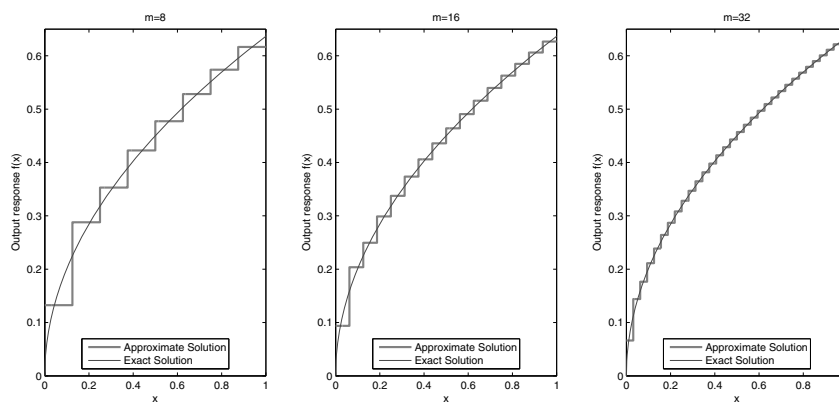


Fig. 6. Approximate solutions of Example 6 for selected values of m .

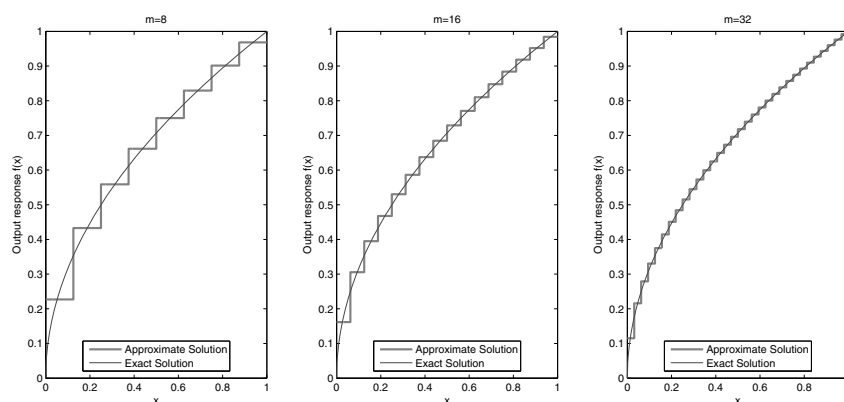


Fig. 7. Approximate solutions of Example 7 for selected values of m .

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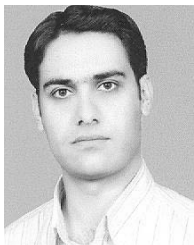
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Appendix

Evaluating $\tilde{\mathbf{v}}$

The fractional integral part of (1) can be written as

$$\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} k(x,t) f(t) dt \cong \tilde{\mathbf{v}} \mathbf{h}(x), \quad (33)$$

where $\tilde{\mathbf{v}} = [\tilde{v}_0, \tilde{v}_1, \dots, \tilde{v}_{m-1}]^T$. According to Eqn. (7), we have

$$\begin{aligned} \tilde{v}_i &= 2^j \int_0^1 \left[\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} k(x,t) f(t) dt \right] h_i(x) dx, \end{aligned} \quad (34)$$

for $i = 2^j + k$. Substituting $f(t) \cong \mathbf{h}^T(t) \mathbf{c}$ and (23) into Eqn. (34), we obtain

$$\begin{aligned} \tilde{v}_i &\cong 2^j \int_0^1 \left[\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} \mathbf{h}^T(x) \mathbf{K} \mathbf{h}(t) \mathbf{h}^T(t) \mathbf{c} dt \right] \\ &\quad \cdot h_i(x) dx \\ &= 2^j \int_0^1 \mathbf{h}^T(x) \mathbf{K} \mathbf{M} \left[\frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} \mathbf{h}(t) dt \right] \\ &\quad \cdot h_i(x) dx, \end{aligned}$$

where the $m \times m$ matrix \mathbf{M} is introduced in (14). Now, by using (15), we have

$$\begin{aligned} \tilde{v}_i &\cong 2^j \int_0^1 \mathbf{h}^T(x) \mathbf{K} \mathbf{M} \mathbf{P}_m^\alpha \mathbf{h}(x) h_i(x) dx \\ &= 2^j \int_0^1 \mathbf{h}^T(x) \mathbf{A} \mathbf{h}(x) h_i(x) dx, \end{aligned}$$

where $\mathbf{A} = \mathbf{K} \mathbf{M} \mathbf{P}_m^\alpha = [a_{ij}]_{m \times m}$. It is obvious that $\mathbf{h}^T(x) \mathbf{A} \mathbf{h}(x)$ is a 1×1 matrix, and:

$$\begin{aligned} & \mathbf{h}^T(x) \mathbf{A} \mathbf{h}(x) h_i(x) \\ &= \sum_{m_1=2}^m \sum_{n_1=m_1}^m (a_{n_1(m_1-1)} + a_{(m_1-1)n_1}) \\ & \quad \cdot h_{n_1-1}(x) h_{m_1-2}(x) + \sum_{i_1=1}^m a_{i_1 i_1} h_{i_1-1}^2(x) \\ &= \sum_{n_1=2}^m (a_{1n_1} + a_{n_1 1}) h_{n_1-1}(x) h_0(x) \\ & \quad + \sum_{m_1=3}^m \sum_{n_1=m_1}^m (a_{n_1(m_1-1)} \\ & \quad + a_{(m_1-1)n_1}) h_{n_1-1}(x) h_{m_1-2}(x) \\ & \quad + \sum_{i_1=1}^m a_{i_1 i_1} h_{i_1-1}^2(x) \\ &= \sum_{n_1=2}^m (a_{1n_1} + a_{n_1 1}) h_{n_1-1}(x) \\ & \quad + \sum_{m_1=3}^m \sum_{n_1=m_1}^m (a_{n_1(m_1-1)} + a_{(m_1-1)n_1}) \\ & \quad \cdot \rho_{n_1-1 m_1-2} h_{n_1-1}(x) \\ & \quad + \sum_{i_1=1}^m a_{i_1 i_1} h_{i_1-1}^2(x), \end{aligned}$$

where $\rho_{n_1 m_1}$ is defined in (13). Therefore

$$\begin{aligned} \tilde{v}_i &\cong 2^j \left[\sum_{n_1=2}^m (a_{1n_1} + a_{n_1 1}) \int_0^1 h_{n_1-1}(x) h_i(x) dx \right. \\ & \quad + \sum_{m_1=3}^m \sum_{n_1=m_1}^m (a_{n_1(m_1-1)} + a_{(m_1-1)n_1}) \\ & \quad \cdot \rho_{n_1-1 m_1-2} \int_0^1 h_{n_1-1}(x) h_i(x) dx \\ & \quad \left. + \sum_{i_1=1}^m a_{i_1 i_1} \int_0^1 h_{i_1-1}^2(x) h_i(x) dx \right] \\ &= (a_{1(i+1)} + a_{(i+1)1}) \\ & \quad + \sum_{m_1=2}^i (a_{m_1(i+1)} + a_{(i+1)m_1}) \rho_{i(m_1-1)} \\ & \quad + 2^j \sum_{i_1=i+2}^m a_{i_1 i_1} \rho_{i_1 i} \frac{1}{2^{i_1}}, \end{aligned}$$

where $i_1 = 2^l + w$ for $l, w \in \{0\} \cup \mathbb{N}$ and $0 \leq w < 2^l$. Specifically,

$$\tilde{v}_0 = a_{11} + \sum_{i_1=2}^m a_{i_1 i_1} \frac{1}{2^{i_1}},$$

for $i_1 - 1 = 2^{l_1} + z$, where $l_1, z \in \{0\} \cup \mathbb{N}$ and $0 \leq z < 2^{l_1}$.

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