## Analytical Study on Thermal and Mechanical Design of Printed Circuit Heat Exchanger

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#### **ABSTRACT**

The analytical methodologies for the thermal design, mechanical design, and cost estimation of printed circuit heat exchanger are presented in this study. Three flow arrangements for PCHE of parallel flow, countercurrent flow and crossflow are taken into account. For each flow arrangement, the analytical solution of temperature profile of heat exchanger is introduced. The size and cost of printed circuit heat exchangers for advanced small modular reactors are also presented using various coolants such as sodium, molten salts, helium, and water.



#### **SUMMARY**

Printed Circuit Heat Exchanger (PCHE) is one of the candidate designs of Very High Temperature Reactor (VHTR) or Advanced High Temperature Reactor (AHTR) heat exchanger (HX). Fine grooves in the plate of PCHE are made by using the technique that is employed for making printed circuit board. This heat exchanger is formed by the diffusion bonding of stacked plates whose grooved surfaces are the flow paths. Thermal design of heat exchanger is required to determine the size and effectiveness of heat exchanger. To evaluate the structural integrity, mechanical design of heat exchanger must be investigated. In a previous study, the parallel/counter flow PCHE analysis code was developed. The methodologies for the thermal and mechanical design of parallel/counter flow PCHE used in previous study are also summarized in this report.

The objective of this work is to develop the analysis code for the crossflow PCHE to determine the size and cost of crossflow PCHE for AHTR. The size of the crossflow PCHE is determined through thermal design process of heat exchanger. Two dimensional temperature profiles in primary and secondary sides of crossflow PCHE are obtained from the solution of analytical model of crossflow PCHE assuming a single pass, both with unmixed fluid, and no contribution from longitudinal heat conduction. The mechanical design of crossflow PCHE is to determine the criteria of geometric parameters of structure for maintaining the integrity of the heat exchanger. The method for mechanical design of crossflow PCHE is developed based on that of parallel/counter flow PCHE.

To verify the developed code, the grid sensitivity test and effectiveness- number of transfer units (NTU) analysis were carried out. The grid sensitivity test for the developed code was performed to evaluate the effect of grid number on the result. The result of grid sensitivity test shows that the effect of grid number is negligible. The effectiveness-NTU analysis was carried out to verify the developed code. The calculated effectiveness by the code and  $\epsilon$ -NTU correlation for crossflow heat exchanger shows a good agreement with each other.

As a parametric study, uncertainty analyses for fluid properties and heat transfer correlation were performed. The uncertainty of fluid properties was investigated by assuming  $\pm 30\%$  of uncertainty in fluid material properties. The result of uncertainty analysis shows that the uncertainty of fluid property was negligible in the thermal design of crossflow PCHE. Geometric parameters of crossflow PCHE was assessed by criteria of mechanical design for each coolant.

Cost estimation of heat exchanger is one of the important factors in the nuclear plant design. Operation cost per year decreased as the operation period increased. Total cost of the heat exchanger using Alloy 617 was cheaper than the other structural materials except for the molten salt heat exchanger. In the molten salt heat exchanger, the total cost was minimized by using Alloy 800H.



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#### **ACRONYMS**

AHTR Advanced High Temperature Reactor

HX Heat Exchanger

LMTD Log Mean Temperature Difference

MTD Mean Temperature Difference

PCHE Printed Circuit Heat Exchanger

PFHE Plate Fin Heat Exchanger SMR Small Modular Reactor

VHTR Very High Temperature Reactor

#### **NOMENCLATURE**

A Area or Overall heat transfer surface area, m<sup>2</sup>

C Flow stream heat capacity  $(=\dot{m}\cdot c_p)$  or Cost, USD

 $C^*$  The ratio of heat capacity rate (= $C_{min}/C_{max}$ )

C<sub>M</sub> Material cost factor, USD/kg

C<sub>op</sub> Operating cost factor, USD/Wh

CP Capital cost (material cost), USD

 $c_p$  Heat capacity,  $J/(kg \cdot K)$ 

D Diameter, m

F LMTD correction factor

f Friction factor

h Convective heat transfer coefficient, W/(m<sup>2</sup>·K)

i Directional index, +1 for same direction, -1 for opposite direction

I<sub>0</sub> Modified Bessel function of the first kind and zero order

k Thermal conductivity,  $W/(m \cdot K)$ 

L Length, m

m Mass flow rate, kg/s

N Number of channel

NTU Number of transfer unit

Nu Nusselt number

OP Operating cost, USD

P Pressure, Pa or Pitch, m

p The order of scheme

Pe Peclet number

Pr	Prandtl number
Q	Heat duty, W
q	Heat transfer rate, W
R	Thermal resistance
R	Heat capacity rate ratio
Re	Reynolds number
T	Temperature, K
$\overline{T}$	Averaged (mean) temperature, K
t	Thickness, m
U	Overall heat transfer coefficient, W/(m <sup>2</sup> ·K)
u	Fluid velocity, m/s
V	Fluid velocity, m/s
X	Normalized location in x-coordinate $(=x/L_1 \cdot NTU_1)$
X	X-axial location, m
Y	Normalized location in y-coordinate (= $y/L_2 \cdot NTU_2$ )
У	Y-axial location, m
0	GREEK AND SYMBOLS
β	Heat transfer surface area density, m <sup>2</sup> /m <sup>3</sup>
Δ	Difference
$\Delta$ $\delta$	Difference Wall thickness, m
δ η	Difference Wall thickness, m Surface efficiency
δ	Difference Wall thickness, m Surface efficiency Dimensionless temperature
δ η θ μ	Difference Wall thickness, m Surface efficiency Dimensionless temperature Viscosity, Pa·s
δ η θ μ	Difference Wall thickness, m Surface efficiency Dimensionless temperature Viscosity, Pa·s Density, kg/m³
δ η θ μ ρ	Difference Wall thickness, m Surface efficiency Dimensionless temperature Viscosity, Pa·s Density, kg/m³ Stress
δ η θ μ ρ σ	Difference Wall thickness, m Surface efficiency Dimensionless temperature Viscosity, Pa·s Density, kg/m³ Stress Richardson solution
δ η θ μ ρ σ Φ	Difference Wall thickness, m Surface efficiency Dimensionless temperature Viscosity, Pa·s Density, kg/m³ Stress Richardson solution Numerical solution by particular grid
δ η θ μ ρ σ	Difference Wall thickness, m Surface efficiency Dimensionless temperature Viscosity, Pa·s Density, kg/m³ Stress Richardson solution
δ η θ μ ρ σ Φ φ	Difference Wall thickness, m Surface efficiency Dimensionless temperature Viscosity, Pa·s Density, kg/m³ Stress Richardson solution Numerical solution by particular grid Pumping power
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δ η θ μ ρ σ Φ φ $\mathcal{P}$	Difference Wall thickness, m Surface efficiency Dimensionless temperature Viscosity, Pa·s Density, kg/m³ Stress Richardson solution Numerical solution by particular grid Pumping power

h

Hydraulic

max Maximum min Minimum

p Primary or plate

s Secondary

tot Total
w Wall
1 Primary
2 Secondary



## Analytical Study on Thermal and Mechanical Design of Printed Circuit Heat Exchanger

#### 1. INTRODUCTION

#### 1.1 Objective

The work reported herein represents the analytical methodology for the printed circuit heat exchanger (PCHE) with various flow configurations. Analytical methodologies for thermal design of parallel and/or counter flow PCHEs that have been developed in a previous study are summarized. The objective of this study is to develop the analytical method for thermal and mechanical designs of crossflow PCHE. Thermal design method is used to determine the size and thermal-hydraulic characteristics of crossflow PCHE. For a given design of the heat exchanger, the mechanical design method is applied to evaluate the structural integrity of heat exchanger.

#### 1.2 Background

Heat exchangers are the device for the energy transfer between two or more mediums that have different temperatures. The heat exchanger can be classified according to the various criteria. Figure 1 shows the criteria used in the classification of heat exchanger by Hewitt et al. [1].

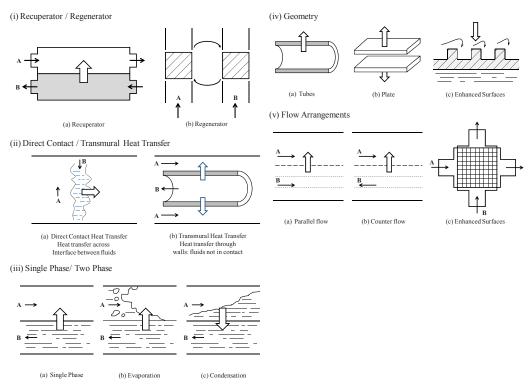


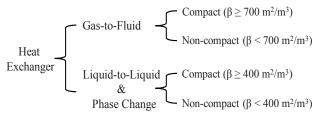
Figure 1. Criteria used in the classification of heat exchangers [1].

In a recuperator, the heat of hot stream transferred to the cold stream through a separating wall or through the interface between the streams. The concept of a recuperator is a well-known heat exchanger.

In a regenerator, heat from hot stream is first stored in a thermal mass and later extracted (or regenerated) from that mass by the cold stream. Thus, the concept of a regenerator is similar with the thermal storage. A heat exchanger can be classified by the heat transfer mechanism, geometry of the heat exchanger, flow arrangement, etc. Tubular heat exchangers, such as double-pipe type, shell-and-tube type, spiral tube type, etc., have been used widely in various engineering fields. For example, a U-tube-type steam generator in the commercial nuclear power plant is one of shell and tube-type heat exchangers.

The heat exchanger can be classified by the surface compactness. Figure 2 shows the heat exchanger classification criteria according to the surface compactness [2]. The one of major characteristics of compact heat exchanger is the large heat transfer surface area per unit volume of the heat exchanger, resulting in the reduced size, weight, and cost. According to Shah's classification [2], a gas-to-fluid heat exchanger can be referred as a compact heat exchanger when its surface area density is greater than about  $700 \text{ m}^2/\text{m}^3$  (213 ft²/ft³) or hydraulic diameter  $D_h$  is less than 6 mm (1/4 in.) for operating in a gas stream and greater than  $400 \text{ m}^2/\text{m}^3$  (122 ft²/ft³) in a liquid or phase-change stream. The liquid, two-phase heat exchanger is classified as the compact heat exchanger when the surface area density on any one fluid side is greater than  $400 \text{ m}^2/\text{m}^3$ .

Heat transfer surface area density spectrum is shown in Figure 3.



\* \$\beta\$ is the heat transfer surface area density

Figure 2. Classification of heat exchanger according to the surface compactness [2].

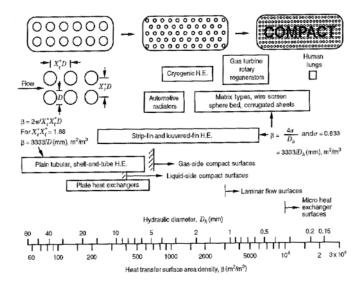


Figure 3. Heat transfer surface area density spectrum of heat exchanger surfaces [2].

#### 1.3 Printed Circuit Heat Exchanger

PCHE is one of the candidate designs of Very High Temperature Reactor (VHTR) or Advanced High Temperature Reactor (AHTR) heat exchanger (HX). Fine grooves in the plate of PCHE are made by using the technique that is employed for making printed circuit board. This heat exchanger is formed by the diffusion bonding of stacked plates whose grooved surfaces are the flow paths. The process of diffusion bonding is depicted in Figure 4. If the separated surfaces are atomically clean and perfectly flat, they can be bonded by interaction of the valence electrons of the separated pieces that forms a single crystal or a grain boundary without heating. However, the real surfaces are typically rough on the atomic scale and not atomically clean. In the diffusion bonding process, the pressure, which does not cause macro deformation, is applied to deform the interfacial boundary as shown in Figure 4(a). Then, the surface contaminants diffused away through the micro structure with a heating, typically in excess of 60% of the melting temperature, since the diffusion process strongly depends on the temperature. Figure 5 shows the microscopic view of the diffusion-bonded interface.

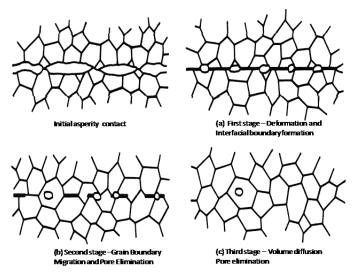


Figure 4. Diffusion bonding process [3].

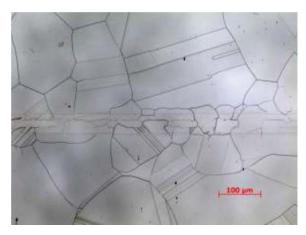


Figure 5. Microscopic structure of diffusion-bonded interface [4].

The PCHE has been commercially manufactured by Heatric [5], a division of Meggitt Ltd. Figure 6 shows the PCHE manufactured by Heatric. The cross-sectional shape of flow channel is typically a semicircle. Heatric recommends the channel diameter of 2.0 mm to maximize thermal performance and economic efficiency [6].

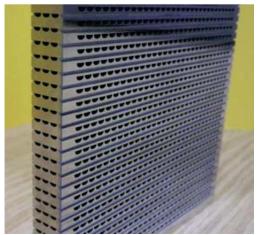


Figure 6. Section of PCHE [7].

As a structural material of PCHE, the nickel-based alloys such as Alloy 800H, Alloy 617, and Hastelloy N, are under development. The thermo-physical properties of structural material have also an influence on the sizing and cost estimation of heat exchanger. According to the previous studies on the cost of heat exchangers [8,9], the material costs of Alloy 800H and Alloy 617 are assumed to be 120 USD/kg conservatively. The material cost of Hastelloy N is approximately 124 USD/kg [4]. The operating cost is 0.0000612 USD/Wh, which is based on the consumer price index average price data [8]. For high-temperature condition of 700°C, the thermo physical properties and material costs of PCHE structural materials are summarized in Table 1.

Table 1. Thermo-physical properties and cost of structural materials of PCHE.

Structural Material	Density (kg/m³)	Thermal Conductivity (W/[m·K])	Heat Capacity (J/[kg·K])	Cost (USD/kg)
Alloy 617 [8]	8,360	23.9	586	120
Alloy 800H [9]	7,940	22.8	460	120
Hastelloy N [4]	8,860	23.6	523	124

## 2. THERMAL AND MECHANICAL DESIGN OF PRINTED CIRCUIT HEAT EXCHANGER

In this work, the thermal design and mechanical designs of the printed-circuit heat exchanger have been investigated. For the PCHE, three flow configurations can be considered: (1) parallel-flow HX, (2) counter-flow HX, and (3) crossflow HX.

The temperature distribution of PCHE is obtained by the analytical modeling and solution. The analytical models of parallel and counter flow configuration are relatively simpler than that of crossflow since the heat transfer in the crossflow heat exchanger is two-dimensional problem. In this report, thermal design and mechanical design methods of the PCHE have been summarized.

## 2.1 Thermal and Mechanical Design of Crossflow Printed-Circuit Heat Exchanger

#### 2.1.1 Analytical Modeling of Crossflow Printed-Circuit Heat Exchanger

For the one-pass crossflow design, a solution to the problem of both fluids unmixed in the heat exchanger and the longitudinal conduction was obtained first by Nusselt [10] in the form of analytical series expansions by assuming the longitudinal conduction can be neglected. The analytical model of crossflow PCHE can be analyzed from the energy balance between the hot and cold fluid sides as shown in Figure 7.

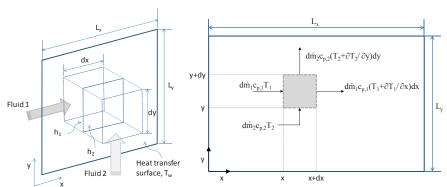


Figure 7. Energy balance control volume for crossflow heat exchanger.

The energy balance equations as shown in Figure 7 could be written as:

#### Fluid 1:

$$\frac{\underbrace{\text{dm}_{1}c_{p,1}T_{1}}_{\text{out of the C. V.}} - \underbrace{\text{dm}_{1}c_{p,1}\left[T_{1} + \frac{\partial T_{1}}{\partial x}\,\text{dx}\right]}_{\text{out of the C. V.}} - \underbrace{\text{dg}}_{\text{from fluid to wall}} = 0$$
 (2-1)

#### Fluid 2:

$$\frac{\underbrace{\dim_{2} c_{p,2} T_{2}}_{\text{from fluid to wall}}}{\left(\underset{\text{into the C. V.}}{\text{Fluid enthalpy rate}}\right)^{+} \left(\underset{\text{from fluid to wall}}{\text{Heat transfer rate}}\right)^{-} \underbrace{\frac{\dim_{2} c_{p,2} \left[T_{2} + \frac{\partial T_{2}}{\partial y} \, dy\right]}{\left(\underset{\text{out of the C. V.}}{\text{Fluid enthalpy rate}}\right)}} = 0 \tag{2-2}$$

In the above energy balance equations, the heat transfer from the hot fluid to the cold fluid can be calculated by the term dq that can be expressed by using the rate equations for convection and conduction as follow:

$$dq = \underbrace{\frac{\eta_{0,1}h_1(T_1 - T_{w,1})dxdy}{Convection}}_{from hot fluid to wall} = \underbrace{\frac{k_w(\frac{T_{w,1} - T_{w,2}}{\delta_w})dxdy}{(Conduction within the wall)}}_{(Conduction within the wall)} = \underbrace{\frac{\eta_{0,2}h_2(T_{w,2} - T_2)dxdy}{Convection}}_{from wall to cold fluid}$$
 (2-3)

where  $\eta_{0.1}$  and  $\eta_{0.2}$  are surface efficiencies on fluid 1 and 2 sides, respectively.

By employing the definition of the overall heat transfer coefficient  $U = \frac{dq}{dA\Delta T}$ , but neglecting the fouling thermal resistances, the heat transfer rate dq can be given by:

$$dq = UdA(T_1 - T_2) \tag{2-4}$$

where dA = dxdy.

By substituting Equation (2-4) into Equations (1-1) and (1-2), and simplifying, the following differential equations for the crossflow heat exchanger are obtained:

$$\frac{\partial \theta_1(X,Y)}{\partial X} + \theta_1(X,Y) = \theta_2(X,Y) \tag{2-5}$$

$$\frac{\partial \theta_2(X,Y)}{\partial Y} + \theta_2(X,Y) = \theta_1(X,Y) \tag{2-6}$$

$$\theta_{j} = (T_{j} - T_{2,in})/(T_{1,in} - T_{2,in}) \text{ with } j=1, 2$$
 (2-7)

where  $X = x/L_1 NTU_1$ ,  $Y = y/L_2 NTU_2$ .

The number of heat transfer unit, NTU, is a ratio of the overall thermal conductance to the smaller heat capacity rate. NTU is given by:

$$NTU_{j} = \frac{UA}{C_{j}} = \frac{1}{C_{j}} \int UdA \text{ with } j=1,2$$
 (2-8)

where C<sub>j</sub> is a flow stream heat capacity rates of fluid j.

If the inlet temperature distributions are assumed to be uniform, the following two boundary conditions could be applied:

$$\theta_1(0, Y) = 1, \theta_2(X, 0) = 0$$
 (2-9)

#### 2.1.2 Analytical Solution of Crossflow Printed-Circuit Heat Exchanger

The solution of above systems of partial differential equations can be obtained by implementing the Laplace transform and inverse transform. Exact solutions of this problem had been reported by Nusselt [10, 11]. There are various crossflow heat exchanger models [12–19], but it is proven that those all models are alternative expression of Nusselt's model [20]. Thus, in this section, the crossflow heat exchanger model has been introduced based on the Nusselt model. First, the Laplace transforms for each variable can be defined as follows:

$$\theta_{iL} = \theta_{iL}(X, p) = \mathcal{L}\{\theta_1(X, Y)\}_{Y \to p}, i = 1, 2$$
(2-10)

$$\tilde{\theta}_{iL} = \tilde{\theta}_{iL}(s, p) = \mathcal{L}\{\theta_{1L}(X, p)\}_{X \to s}, i = 1, 2$$
(2-11)

$$\mathcal{L}\{\mathcal{L}\{f(X,Y)\}_{X\to s}\}_{Y\to p} = \mathcal{L}\{\mathcal{L}\{f(X,Y)\}_{Y\to p}\}_{X\to s}$$
 (2-12)

To obtain the solution of the partial differential equations, first, the Laplace transform for variable Y is applied to Equations (2-5) and (2-6).

$$\frac{\mathrm{d}\theta_{1L}}{\mathrm{d}X} + \theta_{1L} = \theta_{2L} \tag{2-13}$$

$$\frac{\mathrm{d}\theta_{2L}}{\mathrm{d}Y} + \theta_{2L} = \theta_{1L} \tag{2-14}$$

Since the Laplace transform of the derivative of function is  $\mathcal{L}\left\{\frac{dF(\xi)}{d\xi}\right\}_{\xi \to s} = s\mathcal{L}\{F(\xi)\}_{\xi \to s} - F(0),$ 

Equation (2-14) can be expressed as follows:

$$p\theta_{2L} + \theta_2(X, 0) + \theta_{2L} = \theta_{1L}$$

$$\Rightarrow (p+1)\theta_{2L} - \theta_{1L} = 0$$
(1-15)

By applying Laplace transform for variable X to Equation (2-13), the following expression can be obtained with the boundary condition of  $\theta_1$  in Equation (2-9):

$$\mathcal{L}\left\{\mathcal{L}\left\{\frac{d\theta_{1}}{dX}\right\}_{X\to s}\right\}_{Y\to p} + \mathcal{L}\left\{\theta_{1L}\right\}_{X\to s} = \mathcal{L}\left\{\theta_{2L}\right\}_{X\to s} \Longrightarrow (s+1)\tilde{\theta}_{1L} = \tilde{\theta}_{2L} + \frac{1}{p} \tag{2-16}$$

From algebraic Equations (2-15) and (2-16),  $\tilde{\theta}_{1L}$  and  $\tilde{\theta}_{2L}$  are given by

$$\tilde{\theta}_{1L} = \left(\frac{p+1}{p}\right) \left(\frac{1}{ps+s+p}\right) = \frac{1}{p} \left(\frac{1}{s+\frac{p}{p+1}}\right) \tag{2-17}$$

$$\tilde{\theta}_{2L} = \left(\frac{1}{p}\right) \left(\frac{1}{ps + s + p}\right) = \left(\frac{1}{p(p+1)}\right) \left(\frac{1}{s + \frac{p}{p+1}}\right) = \left(\frac{1}{p} - \frac{1}{p+1}\right) \left(\frac{1}{s + \frac{p}{p+1}}\right) \tag{2-18}$$

The following Laplace transform pairs and their relationship are used to obtain the solutions of Equations (2-17) and (2-18).

$$V_{1,0}(X,Y) \equiv e^{-(X+Y)} I_0(2\sqrt{XY}) = \mathcal{L}^{-1} \left\{ \frac{\exp(-\frac{p}{p+1}X)}{(p+1)} \right\}_{p \to Y}$$
 (2-19)

$$V_{1}(X,Y) \equiv 1 - \int_{0}^{X} e^{-(u+Y)} I_{0}(2\sqrt{Yu}) du = \mathcal{L}^{-1} \left\{ \frac{\exp\left(-\frac{p}{p+1}X\right)}{p} \right\}_{p \to Y} \tag{2-20}$$

$$V_1(X,Y) - V_{1,0}(X,Y) = 1 - V_1(Y,X)$$
 (2-21)

where, I<sub>0</sub>(X) is the modified Bessel function of the first kind and zero order.

Thus, by applying the inverse Laplace transform of Equation (2-17) and (2-18), the final solutions are obtained:

$$\theta_{1}(X,Y) = \mathcal{L}^{-1} \left\{ \mathcal{L}^{-1} \left\{ \frac{1}{p} \left( \frac{1}{s + \frac{p}{p+1}} \right) \right\}_{s \to X} \right\}_{p \to Y} = \mathcal{L}^{-1} \left\{ \frac{1}{p} \exp \left( -\frac{p}{p+1} X \right) \right\}_{p \to Y} = V_{1}(X,Y)$$
 (2-22)

$$\theta_2(X,Y) = \mathcal{L}^{-1}\left\{\mathcal{L}^{-1}\left\{\left(\frac{1}{p} - \frac{1}{p+1}\right)\left(\frac{1}{s + \frac{p}{p+1}}\right)\right\}_{s \to X}\right\}_{p \to Y} = \mathcal{L}^{-1}\left\{\left(\frac{1}{p} - \frac{1}{p+1}\right)\exp\left(-\frac{p}{p+1}X\right)\right\}_{p \to Y}$$

$$= V_1(X,Y) - V_{1,0}(X,Y) = 1 - V_1(Y,X)$$
(2-23)

Figure 8 shows the temperature distributions of  $\theta_1(X, Y)$  and  $\theta_2(X, Y)$ .

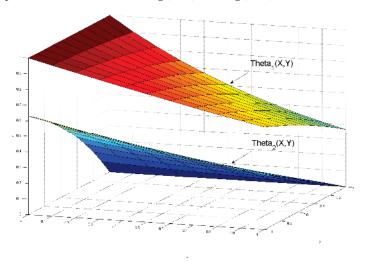


Figure 8. Fluid temperature fields in a crossflow heat exchanger.

#### 2.1.3 Thermal Design Method of Crossflow Printed-Circuit Heat Exchanger

Figure 9 shows the schematic diagram of the crossflow PCHE. The overall heat transfer coefficient, U, and heat transfer surface area,  $A_s$  can be calculated by the number of transfer units (NTU) method and the LMTD method [21].

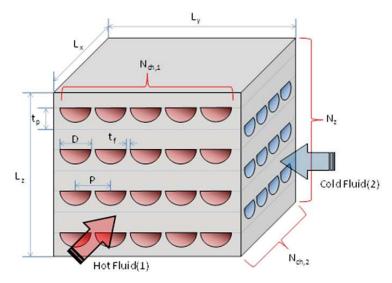


Figure 9. Schematic diagram of crossflow PCHE.

First, the mass flow rate through each fluid side is calculated from the heat duty and the given temperature conditions by using following heat balance equations:

$$Q = \dot{m}_1 c_{p,1} (T_{1,in} - T_{1,out}) = \dot{m}_2 c_{p,2} (T_{2,out} - T_{2,in})$$
(2-24)

thus

$$\dot{m}_{1} = \frac{Q}{c_{p,1}(T_{1,in} - T_{1,out})}$$

$$\dot{m}_{2} = \frac{Q}{c_{p,2}(T_{2,out} - T_{2,in})}$$
(2-25)

Also, the log-mean temperature difference,  $\Delta T_{LMTD}$ , is given by:

$$\Delta T_{LMTD} = \frac{(T_{1,in} - T_{2,out}) - (T_{1,out} - T_{2,in})}{\ln \left| \frac{(T_{1,in} - T_{2,out})}{(T_{1,out} - T_{2,in})} \right|}$$
(2-26)

In LMTD method, the heat transfer rate in the heat exchanger is given by:

$$Q = UA\Delta T_{m} = FUA\Delta T_{LMTD}$$
 (2-27)

Where:

A = is the overall heat transfer surface area

F = is the LMTD correction factor

 $\Delta T_m$  = is the true mean temperature difference (MTD)

U = the overall heat transfer coefficient.

In this work, the value of LMTD correction factor is determined by the iterative method. At first, the value of F is assumed to be from 0.8 to 1. The geometry information such as the sizes of heat exchanger,  $L_x$ ,  $L_y$ , etc., are assumed. From the assumed geometry information, the overall heat transfer surface area A is calculated as follows:

$$A = \left(\frac{\pi}{2}D + D\right)L_x N_1 N_z = \left(\frac{\pi}{2}D + D\right)L_y N_2 N_z$$
(2-28)

where  $N_{c,1}$  and  $N_{c,2}$  are the number of flow channels in Fluid Sides 1 and 2, respectively. The number of flow channels in each fluid side is determined as follow:

$$N_{c,1}D + (N_1 - 1)t_f = L_v$$
 (2-29)

$$N_{c,2}D + (N_2 - 1)t_f = L_x$$
 (2-30)

$$N_z = L_z/(2t_f) \tag{2-31}$$

Simplifying Equations (2-29)–(2-31) and substituting them in Equation (2-28) yield:

$$A = \left(\frac{\pi}{2}D + D\right)L_{x}L_{z}\frac{(L_{y}+t_{f})}{2t_{f}(t_{f}+D)} = \left(\frac{\pi}{2}D + D\right)L_{y}L_{z}\frac{(L_{x}+t_{f})}{2t_{f}(t_{f}+D)}$$
(2-32)

The mass flow rate through each fluid side can be obtained by Equation (2-24). The fluid velocity of each fluid side is calculated as follow:

$$V_j = \frac{\dot{m}_j}{\rho_i A_j}$$
 with j=1, 2 (2-33)

where A<sub>i</sub> is total cross-sectional area of the fluid j.

The Reynolds number and Prandtl number of each fluid side are calculated as follow:

$$Re_{j} = \frac{\rho_{j} V_{j} D_{h,j}}{\mu_{i}} \text{ with } j=1, 2$$
 (2-34)

$$Pr_{j} = \frac{c_{p,j}\mu_{j}}{k_{i}} \text{ with } j=1, 2$$
 (2-35)

where  $k_j$  is the thermal conductivity of the fluid j, and  $D_{h,j}$  is the hydraulic diameter of fluid j side.

If the channel is assumed to be straight through the flow paths, the heat transfer can be estimated by the following heat transfer correlations [22]:

$$Nu_{j} = \begin{cases} 3.657 & \text{Re}_{j} < 2,300 \\ 0.023 \times \text{Re}_{i}^{0.8} \text{Pr}_{i}^{0.33} & \text{Re}_{i} \geq 2,300 \end{cases} \text{ with } j=1, 2$$
 (2-36)

Above equation is known as Dittus-Boelter correlation. In this study, various Nusselt correlations were implemented to evaluate the effect of heat transfer correlation on the temperature profile of heat exchanger. Implemented heat transfer correlations are summarized in Table 2.

Table 2. Summary of single-phase heat transfer coefficient correlations.

Authors	Channel Shape	Working Fluid	Nusselt Number Correlation	Valid Ranges
Berbish [23]	Semi-circular	Air	0.0228Re <sup>0.8</sup>	$8,200 < \text{Re} < 5.83 \times 10^4$
Kim et al. [24]	Semi-circular	Не	3.255 + 0.00729(Re - 350)	350 < Re < 800, Pr = 0.66
Dittus-Boelter [28]	Circular	Any fluid	0.0243Re <sup>0.8</sup> Pr <sup>0.4</sup> for heating 0.0265Re <sup>0.8</sup> Pr <sup>0.3</sup> for cooling	$10^4 < Re < 1.2 \times 10^5,$ 0.7 < Pr < 120, L/D > 60
Gnielinski (Nu <sub>G</sub> ) [26]	Circular	Any fluid	$\frac{\binom{f}{8}(Re-1000)Pr}{1+12.7\sqrt{\frac{f}{8}}(Pr^{2/3}-1)}$	2,300 < Re < 5 × 10 <sup>6</sup> , 0.5 < Pr < 2,000
Lyon [27]	Circular	Liquid Metal	$7.0 + 0.025 Pe^{0.8}$	$0 \le Pr \le 0.1,$ $300 < Pe < 10^4$
Lubarsky and Kaufman [28]	Circular, Annular	Liquid Metal	0.625Pe <sup>0.4</sup>	$0 \le Pr \le 0.1,$ $200 < Pe < 10^4$
Reed [29]	Circular	Liquid Metal	3.3 + 0.02Pe <sup>0.8</sup>	100 < Pe
Taylor and Kirchgessner [29], Wieland [30]	Circular	Не	0.021Re <sup>0.8</sup> Pr <sup>0.4</sup>	$3.2 \times 10^3 < \text{Re} < 6 \times 10^4,$ 60 < L/D
Wu and Little [31]	Rectangular	N <sub>2</sub> gas	0.00222Re <sup>1.09</sup> Pr <sup>0.4</sup>	3,000 < Re
Wang and Peng [32]	Rectangular	Water, Methanol	0.00805Re <sup>0.8</sup> Pr <sup>0.33</sup>	2,300 < Re

From the Nusselt number correlation, the heat transfer coefficient in each fluid side can be estimated as follow:

$$h_j = Nu_j \frac{k_j}{D_{h,j}}$$
 with j=1, 2 (2-37)

Finally, the overall heat transfer coefficient for crossflow heat exchanger is given by:

$$U = \frac{1}{\frac{1}{h_1} + R_w + \frac{1}{h_2}} = \frac{1}{\frac{1}{h_1} + \frac{\delta_w}{k_w} + \frac{1}{h_2}}$$
(2-38)

To evaluate the temperature distribution in the crossflow heat exchanger, the analytical solution discussed in Section 2.1.2 is used and the NTU is determined. By using the overall heat transfer surface area in Equation (2-32), overall heat transfer coefficient in Equation (2-38), and the definition of the NTU from Equation (2-8), the value of NTU in each fluid side is determined as follow:

$$NTU_{j} = \frac{UA}{C_{j}} = \frac{UA}{\dot{m}_{j}c_{p,j}} = \frac{Q}{\dot{m}_{j}c_{p,j}F\Delta T_{LMTD}} \text{ with } j=1, 2$$
 (2-39)

Temperature distribution of the crossflow heat exchanger can be calculated by the analytical solutions in Equations (2-22) and (2-23). In this work, the crossflow heat exchanger analysis code has been developed in the MATLAB. Solution equation of each fluid is solved by using the built-in-function of MATLAB code. Since Equations (2-22) and (2-23) are the normalized form of the temperature distribution, the actual temperature distribution is calculated by applying the required conditions of heat exchanger such as inlet and outlet temperatures of heat exchanger, the duty of heat transfer rate, etc. The actual temperature distribution can be obtained by converting the dimensionless temperature  $\theta_j(X,Y)$  to  $T_j(x,y)$  as shown below:

$$\theta_{j}(x,y) = 1 - \int_{0}^{\frac{NTU_{1}}{L_{x}}} \exp\left(-\left(\frac{NTU_{2}}{L_{y}}y + u\right)\right) I_{o}\left(2\sqrt{\frac{NTU_{2}}{L_{y}}}yu\right) du \tag{2-40}$$

Substituting Equation (2-40) to (2-7) yields

$$T_{j}(x,y) = \left(T_{1,in} - T_{2,in}\right) \left(1 - \int_{0}^{\frac{NTU_{1}}{L_{x}}x} \exp\left(-\left(\frac{NTU_{2}}{L_{y}}y + u\right)\right) I_{o}\left(2\sqrt{\frac{NTU_{2}}{L_{y}}}yu\right) du\right) + T_{2,in}$$
(2-2-41)

where  $0 \le x \le L_x$ ,  $0 \le y \le L_y$ .

From the analytical solution of temperature distribution, the true mean temperature difference (MTD) is determined as follow:

$$\Delta T_{\rm m} = \frac{(T_{1,\rm in} - \overline{T}_{2,\rm out}) - (\overline{T}_{1,\rm out} - T_{2,\rm in})}{\ln \left[ \frac{(T_{1,\rm in} - \overline{T}_{2,\rm out})}{(\overline{T}_{1,\rm out} - T_{2,\rm in})} \right]}$$
(2-42)

The mean outlet temperatures of Fluid 1 and 2 can be determined by averaging each temperature distribution function as follows:

$$\overline{T}_{1,\text{out}} = \frac{1}{L_y} \int_0^{L_2} T_1(L_x, y) dy$$
 (2-43)

$$\overline{T}_{2,\text{out}} = \frac{1}{L_{y}} \int_{0}^{L_{1}} T_{2}(x, L_{y}) dx$$
 (2-44)

Substituting Equation (2-41) in Equation (2-43) and Equation (2-44) yields:

$$\overline{T}_{1,\text{out}} = \frac{1}{L_y} \int_0^{L_y} T_1(L_1, y) dy = \frac{1}{L_y} \int_0^{L_y} \left[ \left( T_{1,\text{in}} - T_{2,\text{in}} \right) \theta_j(L_x, y) + T_{2,\text{in}} \right] dy$$
 (2-45)

$$\overline{T}_{2,\text{out}} = \frac{1}{L_{\text{tr}}} \int_{0}^{L_{x}} T_{2}(x, L_{y}) dx = \frac{1}{L_{\text{tr}}} \int_{0}^{L_{x}} \left[ \left( T_{1,\text{in}} - T_{2,\text{in}} \right) \theta_{j}(x, L_{y}) + T_{2,\text{in}} \right] dx$$
(2-46)

Mean outlet temperatures in Equations (2-45) and (2-46) is compared to the required outlet temperature conditions. If the mean outlet temperatures disagree with the required outlet temperature, then the size of the heat exchanger is adjusted and the process is repeated from Equation (2-28) to Equation (2-46). When the calculated outlet temperature and requirements are converged, the value of LMTD correction factor can be obtained by substituting the calculated value of MTD to Equation (2-27). If the calculated value of correction factor is equal to assumed one, then the correction factor is finally determined. If not, change the assumed value and repeat the above process until the assumed and calculated correction factors are converged sufficiently. The overall thermal conductance of the heat exchanger, UA, can be calculated from the given heat duty and LMTD as follows:

$$UA = \frac{Q}{F\Delta T_{LMTD}} \tag{2-47}$$

Now, the pressure loss through the heat exchanger can be estimated by the given geometric information and estimated sizes of the heat exchanger. The pressure loss of the straight pipe can be estimated by following equation:

$$\Delta P_{j} = 4f_{j} \frac{L_{j}}{D_{h,j}} \rho_{j} u_{m,j}^{2} \text{ with } j=1, 2$$
 (2-48)

where

 $\Delta P$  = pressure drop

f = friction factor

L = length of channel

 $D_h$  = hydraulic diameter of the channel

 $u_m$  = mean flow velocity in the channel

i = index of fluid side.

Since the channel shape of PCHE is a semicircle, the pressure loss calculation using the friction factor correlation for a circular pipe can lead to an incorrect result. The flow channel of typical PCHE manufactured by Heatric is wavy (zigzag shaped). If the flow channel is wavy or zigzag shaped, the correlations for wavy or zigzag shaped channel should be employed. However, the straight pipe is assumed in this study so that the friction factor correlation by Berbish et al. [23] is employed to calculate the turbulent friction factor of semicircular straight pipe. The fully developed laminar friction factor [33] and turbulent friction factor of semicircular straight pipe are given by:

$$f = \begin{cases} \frac{15.78}{Re} & Re < 2300\\ f = 0.478Re^{-0.26} & 2300 \le Re \end{cases}$$
 (2-49)

#### 2.1.4 Mechanical Design of Crossflow Printed-Circuit Heat Exchanger

To prevent the mechanical failure of the heat exchanger, the dimensions of the channel pitch and the plate thickness should be larger than design criteria. The stress  $\sigma_D$  for both the plate-fin (PFHE) and printed-circuit heat exchangers (PCHE) is given by [33]:

$$\sigma_{\rm D} = \Delta p \left( \frac{1}{N_{\rm f} t_{\rm f}} - 1 \right) \tag{2-50}$$

where

 $\Delta p$  = the absolute value of pressure difference between the two fluids

 $N_f$  = is fin density

 $t_f$  = is fin thickness.

The fin thickness in PFHE means the wall thickness between the flow channels in PCHE, since PCHE does not have typical fins. Equation (2-50) gives a maximum allowable pressure difference between the hot and cold fluid sides since the stress in Equation (2-50) should be lower than allowable stress of the structure. In order words, this equation gives the criterion of the minimum wall thickness for a given pressure difference. Thus, the minimum wall thickness is given by:

$$t_f \ge \frac{1}{\left(\frac{\sigma_D}{\Delta p} + 1\right)N_f} \tag{2-51}$$

The fin density in PCHE, which is the number of channel walls per meter, is given by:

$$N_f = (N_{c,j} - 1)/L_j \text{ with } j=1,2$$
 (2-52)

The above fin density can be approximately expressed as a function of pitch as follow:

$$N_f = (N_{c,j} - 1)/L_j \approx (N_{c,j} - 1)/((N_{c,j} - 1) \times P) = \frac{1}{P}$$
 (2-53)

Therefore, the minimum wall thickness between the channels can be approximated as [34]:

$$t_f \ge \frac{P}{\left(\frac{\sigma_D}{\Delta p} + 1\right)} \tag{2-54}$$

Thus, the minimum pitch (P) of the channels can be calculated as:

$$P = D + t_f \ge \left(1 + \frac{\Delta p}{\sigma_D}\right) D \tag{2-55}$$

In the PCHE, the plate can be assumed to be a thick-walled cylinder with an inner radius of D/2 and the outer radius of  $t_p$ . Thus, the thickness of the plate [34] can be estimated by:

$$\frac{t_{p}}{D_{j}/2} \ge \begin{cases} \sqrt{\frac{\sigma_{max} + P_{p}}{\sigma_{max} + 2P_{s} - P_{p}}} & \text{where } P_{p} \ge P_{s} \\ \sqrt{\frac{\sigma_{max} - P_{p}}{\sigma_{max} - 2P_{s} - P_{p}}} & \text{where } P_{p} < P_{s} \end{cases}$$

$$(2-56)$$

## 2.2 Thermal and Mechanical Design of Parallel/ Counter Flow Printed-Circuit Heat Exchanger

## 2.2.1 Analytical Modeling of Parallel/Counter Flow Printed-Circuit Heat Exchanger

Figure 10 shows the schematic diagram of channel configuration and arrangement of the parallel/counter flow PCHE. The definitions of the terms in the parallel/counter flow PCHE and the crossflow PCHE are basically the same.

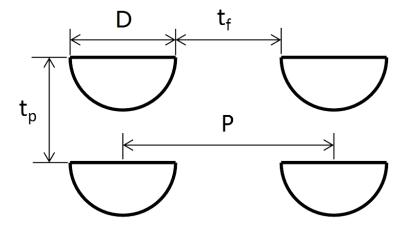


Figure 10. Channel configuration and arrangement of PCHE.

Figure 11 shows the schematic diagram of energy balance of counter flow PCHE. The energy balance of the parallel flow PCHE is basically the same as the counter flow-type flow.

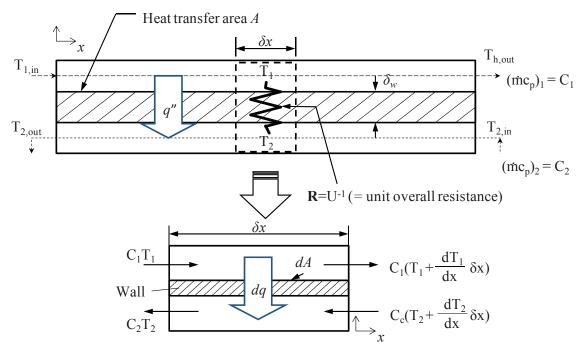


Figure 11. Energy balance of counter flow heat exchanger [21].

The energy balance equations in Equations (2-1)–(2-3) can be applied to the parallel/counter flow PCHE in the same manner. Thus, the energy balance equations of parallel/counter flow PCHE [21] are given by:

#### Fluid 1:

$$i_1(\dot{m}c_p)_1 T_1 + i_1(\dot{m}c_p)_1 \left(T_1 + \frac{dT_1}{dx}dx\right) - U(T_1 - T_2)dA = 0$$
 (2-57)

#### Fluid 2:

$$i_2 \left( \dot{m} c_p \right)_2 T_2 + i_2 \left( \dot{m} c_p \right)_2 \left( T_2 + \frac{dT_2}{dx} dx \right) + U(T_1 - T_2) dA = 0 \tag{2-58}$$

where  $i_1$  is +1 or -1 for the same or opposite direction of the fluid 1 with respect to the positive direction of the x axis, respectively. In the same manner,  $i_2$  is +1 or -1 for the same or opposite direction of the fluid 2, respectively, with respect to the positive direction of the x-axis.

If it is assumed that the distribution of the total heat transfer surface area A along the channel length L is uniform, a differential term  $\frac{dA}{dx}$  is equal to  $\frac{A}{L}$ . Thus, Equations (2-57) and (2-58) can be simplified as:

$$\left(\dot{m}c_{p}\right)_{1}\frac{dT_{1}}{dx} = \frac{UA}{L}\left(T_{2} - T_{1}\right)$$
 (2-59)

$$\left(\dot{m}c_{\rm p}\right)_2 \frac{dT_2}{dx} = \frac{UA}{L} (T_1 - T_2)$$
 (2-60)

To make a dimensionless form of above equations, the following dimensionless variables are defined by:

$$\theta = \frac{T - T_{1,in}}{T_{2,in} - T_{1,in}}$$
 (Dimensionless temperature) (2-61)

$$X = \frac{x}{L}$$
 (Dimensionless distance) (2-62)

Heat Capacity Rate Ratio is defined by:

$$R_1 = \frac{C_1}{C_2} = \frac{T_{2,in} - T_{2,out}}{T_{1,out} - T_{1,in}}$$
(2-63)

The boundary conditions are given by:

$$T_1 = T_{1,in}$$
 at  $x = 0$  (2-64)

$$T_2 = T_{2,in}$$
  $\begin{cases} x = 0 \text{ for parallel flow} \\ x = L \text{ for counter flow} \end{cases}$  (2-65)

Using the dimensionless variables from Equations (2-61) and (2-62) and NTU definition from Equation (2-39), the dimensionless forms of Equations (2-59) and (2-60) can be written as:

$$\frac{\mathrm{d}\theta_1}{\mathrm{d}X} + \mathrm{NTU}_1(\theta_1 - \theta_2) = 0 \tag{2-66}$$

$$\frac{d\theta_2}{dX} - i_2 NTU_1 R_1 (\theta_1 - \theta_2) = 0$$
 (2-67)

The dimensionless boundary conditions are given by:

$$\theta_1 = 0 \text{ at } X = 0$$
 (2-68)

$$\theta_2 = 1$$
  $\begin{cases} X = 0 \text{ for parallel flow} \\ X = 1 \text{ for counter flow} \end{cases}$  (2-69)

### 2.2.2 Analytical Solution of Parallel/Counter Flow Printed-Circuit Heat Exchanger

The general solutions of the dimensionless temperature of parallel and counter flow PCHEs can be obtained by the Laplace transform method. The detailed solving procedure of the parallel/counter flow PCHE is similar to that of crossflow HX. The solution of each flow arrangement [21] is given by:

#### Parallel flow:

$$\theta_1(X) = \frac{1 - \exp(-NTU_1(1 + R_1)X)}{1 + R_1} \tag{2-70}$$

$$\theta_2(X) = \frac{1 + R_1 \exp(-NTU_1(1 + R_1)X)}{1 + R_1}$$
 (2-71)

#### Counter flow:

$$\theta_1(X) = \frac{1 - \exp(-NTU_1(1 - R_1)X)}{1 - R_1 \exp(-NTU_1(1 - R_1))}$$
(2-72)

$$\theta_2(X) = \frac{1 - R_1 \exp(-NTU_1(1 - R_1)X)}{1 - R_1 \exp(-NTU_1(1 - R_1))}$$
(2-73)

#### 2.2.3 Thermal Design of Parallel/Counter Flow Printed-Circuit Heat Exchanger

Basically, the thermal design process of parallel/counter flow PCHE is similar to that of crossflow PCHE. However, the overall heat transfer coefficient is obtained from the thermal resistance circuit shown in Figure 11 as follows:

$$U = \frac{1}{\frac{1}{h_1} + R_W + \frac{1}{h_2}} \tag{2-74}$$

where  $h_1$  and  $h_2$  are the heat transfer coefficients of Fluid 1 and 2 sides, respectively, and  $R_w (= \delta_w/k_w)$  is the thermal resistance of the wall.

The mass flow rate through each fluid side can be obtained by Equation (2-24). The fluid velocity of each fluid side is calculated as follows:

$$V_j = \frac{\dot{m}_j}{\rho_j A_j}$$
 with j=1, 2 (2-75)

where A<sub>i</sub> is total cross-sectional area of the fluid j.

The Reynolds number and Prandtl number of each fluid side are calculated as follows:

$$Re_{j} = \frac{\rho_{j} V_{j} D_{h,j}}{\mu_{j}} \text{ with } j=1, 2$$
 (2-76)

$$Pr_j = \frac{c_{p,j}\mu_j}{k_j}$$
 with j=1, 2 (2-77)

where

 $k_i$  = thermal conductivity of the fluid j

 $D_{h,j}$  = hydraulic diameter of fluid j side.

If the channel is assumed to be straight through the flow paths, the heat transfer can be estimated by the following heat transfer correlations [35]:

$$Nu_{j} = \begin{cases} 3.657 & \text{Re}_{j} < 2,300 \\ 0.023 \times \text{Re}_{j}^{0.8} \text{Pr}_{j}^{0.33} & \text{Re}_{j} \geq 2,300 \end{cases} \text{ with } j=1, 2$$
 (2-78)

From the above Nusselt number correlation, the heat transfer coefficient in each fluid side can be estimated as follow:

$$h_j = Nu_j \frac{k_j}{D_{h,i}}$$
 with j=1, 2 (2-79)

The LMTDs of the parallel and counter flow configuration can be estimated by:

$$\Delta T_{\text{LMTD}} = \frac{(T_{1,\text{in}} - T_{2,\text{out}}) - (T_{1,\text{out}} - T_{2,\text{in}})}{\ln\left[\frac{(T_{1,\text{in}} - T_{2,\text{out}})}{(T_{1,\text{out}} - T_{2,\text{in}})}\right]}$$
(2-80)

The overall heat transfer surface area is calculated as follow:

$$A = \frac{Q}{UF\Delta T_{LMTD}}$$
 (2-81)

Note that the LMTD correction factor F is 1 for both the parallel and counter flow heat exchangers.

The numbers of flow channel in each side is calculated as follow:

$$N_{c,j} = \frac{A_j}{\frac{1}{2}(\frac{\pi}{4}D^2)}$$
 with j=1, 2 (2-82)

The heat exchanger channel length can be estimated as follow:

$$L_{j} = \frac{A}{(\frac{\pi}{2}D + D)N_{c,j}} \text{ with } j=1, 2$$
 (2-83)

The friction factor and pressure drop in the parallel/counter flow PCHE can be estimated by the same method used in the crossflow heat exchanger. Equations (2-48) and (2-49) are applied to estimate the pressure drop and friction factor of the flow channel, respectively. The result of thermal design of parallel/counter flow PCHE is summarized in Appendix A.

## 2.2.4 Mechanical Design of Parallel/Counter Flow Printed-Circuit Heat Exchanger

The mechanical design methodology of the crossflow heat exchanger can be applied to the parallel/counter flow PCHE. Thus, Equations (2-54), (2-55), and (2-56) can be applied to determine the minimum values of wall thickness between the channels, pitch, and plate thickness, respectively. The result of mechanical design of parallel/counter flow PCHE is summarized in Appendix B.

#### 3. THERMAL-HYDRAULIC ANALYSIS OF CROSSFLOW PCHE

Thermal design of heat exchanger is carried out to determine the size of heat exchanger that would provide us the needed temperature at the outlet for the given inlet condition. This report focuses on the thermal-hydraulic analysis of crossflow PCHE. Temperature profile of parallel and counter flow PCHE is provided in Appendix A. The basic input parameters of PCHE used in this analysis is summarized in Table 3. Table 4 describes the typical temperature and pressure conditions of advanced small modular reactors (SMRs) according to the reactor coolants. Inlet and outlet temperatures of primary and secondary sides are determined based on the intermediate heat exchanger. Thus, the inlet temperature of the primary side shown in Table 4 is actually the outlet temperature of the reactor core. Thermal-hydraulic analysis of crossflow PCHE was carried out based on the values in Tables 3 and 4.

Table 3. Basic design parameters of PCHE.

Geometric Parameters	Value
Channel diameter D, (m)	0.003
Channel pitch P, (m)	0.0033
Plate thickness t <sub>p</sub> , (m)	0.00317
Fin thickness, t <sub>f</sub> , (m)	0.00013

Table 4. Typical temperature and pressure condition of heat exchanger for advanced SMRs.

	Coolants	Operation Conditions			
			Temperature (C)	Primary/Secondary Pressure	
Coolant Type	Primary/Secondary	Primary	Secondary	(MPa)	
Water-cooled [36]	Water/Water	323/295	200/293	15.0/5.0	
Gas-cooled [37]	Не/Не	950/637	351/925	7.0/7.0	
Liquid Metal-cooled [38]	Na/Na	545/390	320/526	0.1/0.1	
Molten Salt-cooled [39]	FLiBe/FLiNaK	700/650	600/690	0.1/0.1	

#### 3.1 Grid Sensitivity Test

In this study, the temperature profile of crossflow PCHE is obtained by solving the system of differential equations as described in Section 2. Since the temperature profile of crossflow PCHE is two-dimensional, two-dimensional grid are required to analyze the crossflow PCHE. In numerical simulation, the result is generally influenced by the grid. Thus, the outlet temperature of each channel can be varied due to the number of grid. In developed code, the mean outlet temperature of each fluid side is calculated by averaging the temperature at the outlet. Consequently, the number of grids can influence the mean outlet temperature. To investigate the grid effect, the grid sensitivity test was performed. Tested numbers of grid and results are summarized in Table 5. In grid sensitivity test, x and y-axial dimensions of heat exchanger, NTUs of primary and secondary sides are assumed to be a unity. The size of reference grid was  $40 \times 40$ .

Table 5. Grid sensitivity test results.

	Dimensionless Mean Outlet Temperature						
Numbers of Grids	5 × 5	10 × 10	20 × 20	40 × 40	$80 \times 80$	160 × 160	320 × 320
Primary Side	0.52124	0.52251	0.52314	0.52346	0.52362	0.52370	0.52374
Secondary Side	0.47876	0.47749	0.47686	0.47654	0.47638	0.47630	0.47626

The grid sensitivity analysis by the Richardson extrapolation [40] was performed to estimate the numerical error due to the grid number. The approximation of exact solution  $\Phi$  is given by:

$$\Phi = \phi_h + \frac{\phi_h - \phi_{2h}}{2^p - 1} \tag{3-1}$$

where  $\phi$  is a numerical solution and the order of the scheme p is defined by:

$$p = \frac{\log\left(\frac{\phi_{2h} - \phi_{4h}}{\phi_h - \phi_{2h}}\right)}{\log 2} \tag{3-2}$$

Figure 12 shows the dimensionless mean outlet temperatures of the primary and secondary sides. The dimensionless temperature in the grid sensitivity test was defined in Equation (2-7). The Richardson solutions of primary and secondary fluids were 0.5238 and 0.4762, respectively. The maximum relative errors between the reference grid ( $40 \times 40$ ) and Richardson solution of primary and secondary fluids were 0.48% and 0.53%, respectively. Consequently, the grid sensitivity test results show that the effect of grid number is negligible.

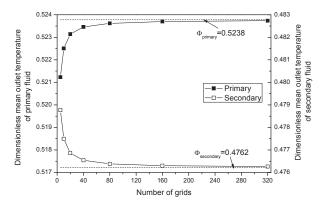


Figure 12. Effect of grid number on dimensionless mean temperature profile of crossflow heat exchanger.

#### 3.2 Effectiveness-NTU (ε-NTU) Method Analysis

The effectiveness of the heat exchanger,  $\varepsilon$ , is the ratio of the actual heat transfer rate to the maximum possible heat transfer rate of the exchanger and is defined by:

$$\varepsilon = \frac{Q}{Q_{\text{max}}} = \frac{(T_{1,\text{in}} - T_{1,\text{out}})}{(T_{1,\text{in}} - T_{2,\text{in}})}$$
(3-3)

The  $\epsilon$ -NTU method [10] is one of general methods applied for the thermal design of heat exchanger. In this method, the effectiveness of crossflow heat exchanger is a function of NTU. The relationship between the effectiveness and NTU of both unmixed fluids crossflow heat exchanger [41] is given by:

$$\varepsilon = 1 - \exp\left[\frac{1}{C^*}(NTU)^{0.22}(\exp[-C^*(NTU)^{0.78}] - 1)\right]$$
(3-4)

where  $C^* (= C_{min}/C_{max})$  is the ratio of minimum to maximum heat capacity rate of fluid.

The effectiveness of crossflow PCHE calculated by the developed code is compared with that of the  $\epsilon$ -NTU method. Figure 13 shows the effectiveness-NTU plots by the developed code and  $\epsilon$ -NTU method. The effectiveness of a heat exchanger increases as the NTU increases. The effectiveness increases rapidly as the ratio of heat capacity rate decreases.

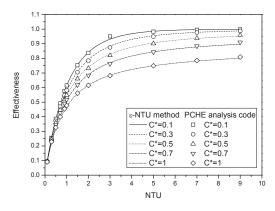


Figure 13. Effectiveness-NTU comparison between ε -NTU method and crossflow PCHE analysis code.

### 3.3 Effect of Fluid Property Uncertainty

The uncertainty of fluid property can be propagated into the calculated temperature profile of the heat exchanger. To evaluate the effect of uncertainty of fluid property, the uncertainty of fluid property was assumed to be  $\pm 30\%$ . In this sensitivity test, the fluid properties in both primary and secondary side are changed at the same time. Tested variables are thermal conductivity, heat capacity and viscosity. In this calculation, the heat duty, the temperatures, and the pressures in Table 4 were employed. Hastelloy N is employed as the structural material. Gnielinski heat transfer correlation was used to calculate the heat transfer coefficient. The dimensions in x, y, and z axial directions of heat exchanger were assumed to be 0.9897 m, 0.9897 m, and 0.634 m, respectively. Corresponding numbers of flow channels are 300, 300, and 100, respectively.

Figures 14–21 show the average temperature profiles according to the uncertainty of thermo-physical property for each coolant. The density change did not have an effect on the temperature profile. In the developed code, when the heat duty is given, the mass flow rate is determined from Equation (2-24). Then, the density is used to calculate the fluid velocity and Reynolds number. Since the product of density and fluid velocity is constant by Equation (2-33), the Reynolds number is not changed by the density. Consequently, the uncertainty of fluid density does not have an effect on the temperature. Uncertainties of heat capacity and dynamic viscosity resulted in the same temperature profile. The temperature profile of the crossflow analytical model is determined by the size of heat exchanger and NTU value. In this crossflow model, NTU can be approximated as a function of the product of heat capacity and dynamic viscosity so that the changes of these two parameters resulted in the same value of NTU. Uncertainty of thermal conductivity led to the maximum deviation of temperature profile except the sodium case. The effect of thermal conductivity was relatively smaller than heat capacity and dynamic viscosity for the fluid of low Prandtl number. Overall, the relative deviation of the temperature profile according to the uncertainty of fluid property was very small. Maximum deviation was 2.38%, which occurred by the thermal conductivity in the primary side of helium flow. Consequently, it is concluded that the effect of fluid property on the analytical solution of crossflow heat exchanger was not as critical as expected.

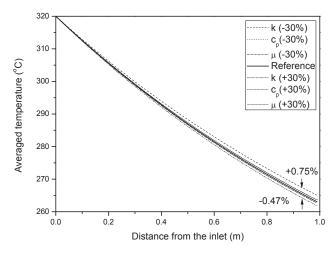


Figure 14. Average temperature profile of primary fluid according to uncertainty of material property (Water).

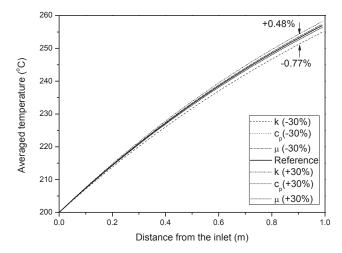


Figure 15. Average temperature profile of secondary fluid according to uncertainty of material property (Water).

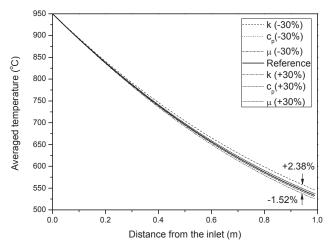


Figure 16. Average temperature profile of primary fluid according to uncertainty of material property (Helium).

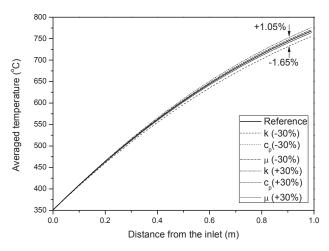


Figure 17. Average temperature profile of secondary fluid according to uncertainty of material property (Helium).

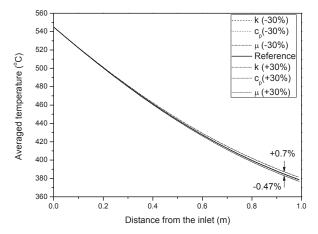


Figure 18. Average temperature profile in primary side according to uncertainty of material property (Sodium).

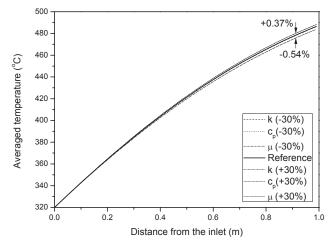


Figure 19. Average temperature profile in secondary side according to uncertainty of material property (Sodium).

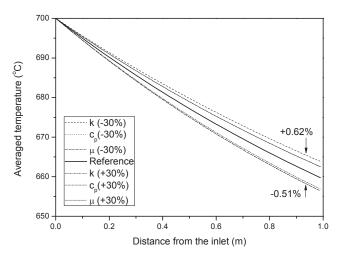


Figure 20. Average temperature profile in primary side according to uncertainty of material property (FLiBe).

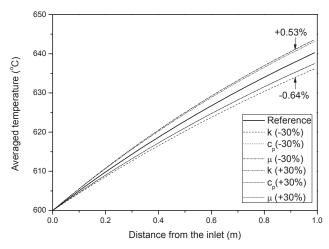


Figure 21. Average temperature profile in secondary side according to uncertainty of material property (FLiNaK).

#### 3.4 Effect of Heat Transfer Coefficient Correlations

Comparative analyses were carried out to evaluate the effect of heat transfer correlations on the temperature profile. In this analysis, the heat duty, the temperatures and pressures in Table 4 were employed. Hastelloy N was employed as the structural material. The number of channel in x, y and z axial directions were assumed to be 300, 300 and 100, and corresponding dimensions are 0.9897 m, 0.9897 m, and 0.634 m, respectively.

Figures 22 and 23 show the temperature profiles in the primary and secondary side with water as coolant, respectively. The Lubarsky and Kaufman's correlation showed the highest temperature of primary side and lowest temperature of secondary side. Wu and Little's and Kim et al.'s correlations showed the lowest temperature of primary side and highest temperature of secondary side. These two correlations predicted the heat transfer coefficients similarly for Prandtl number in the range of  $0.5\sim1.0$ . Thus, the same temperature profile trend was observed in the water and helium flows of which Prandtl numbers were approximately 1.0 and 0.66, respectively. The maximum deviation among the averaged outlet temperature was 39.45 K, which was caused by the Lubarsky and Kaufman's correlation and Kim et al.'s correlation. Figures 24 and 25 show the temperature profiles with helium flows which showed

similar trends as observed in the case with water. The maximum deviation among the averaged outlet temperature was approximately 196.01 K, which was caused by the Lubarsky and Kaufman's correlation and Kim et al.'s correlation.

Figures 26 and 27 show the temperature profiles with sodium. In this case, the effect of heat transfer correlation was smaller than the other cases. For the fluids with very low Prandtl numbers, most of empirical correlations predicted a low-heat transfer coefficient, and the difference between them was also small. Maximum deviation of averaged outlet temperature was 15.34 K, which was caused by Gnielinski's correlation and Kim et al.'s correlation. Figures 28 and 29 show the temperature profiles of molten salt flows. The Prandtl number for molten salt is approximately 10.0. Contrary to the sodium flow, the molten salt is a fluid with a high Prandtl number. Not only the empirical correlations developed for liquid metals but also Dittus-Boelter correlation and Gnielinski's correlations predicted a higher heat transfer coefficient. Consequently, these correlations predicted similar temperature profiles. Maximum deviation of averaged outlet temperature was 31.04 K, by using Wang and Peng's correlation and Lyon's correlation.

By comparing heat transfer correlations for each fluid, it is found that the effect of heat transfer correlations was largest in the helium flow. The deviation of temperature profiles by the heat transfer correlation decreased for very low or very high Prandtl number fluids. It was not easy to determine a heat transfer correlation that can be applied generally irrespective of coolant types. Consequently, the experimental and computational validations are deemed to be required for the design of crossflow PCHE. In addition, the appropriate heat transfer correlation for each fluid type should be applied.

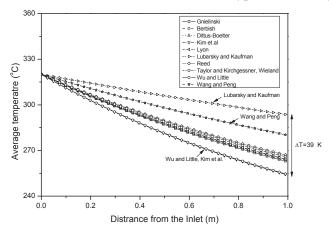


Figure 22. Temperature profile in primary side by the heat transfer correlations (Water).

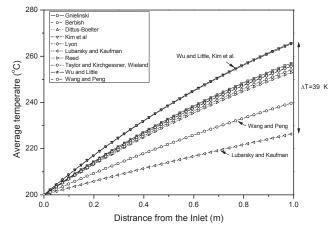


Figure 23. Temperature profile in secondary side by the heat transfer correlations (Water).

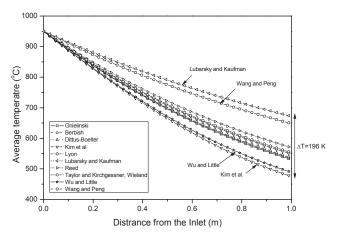


Figure 24. Temperature profile in primary side by the heat transfer correlations (Helium).

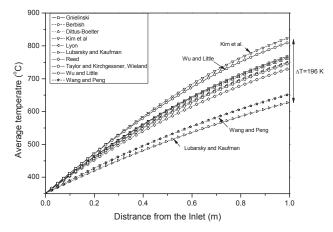


Figure 25. Temperature profile in secondary side by the heat transfer correlations (Helium).

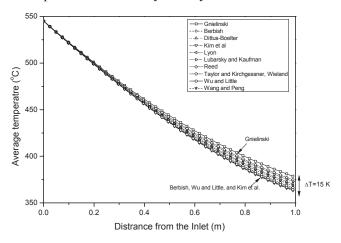


Figure 26. Temperature profile in primary side by the heat transfer correlations (Sodium).

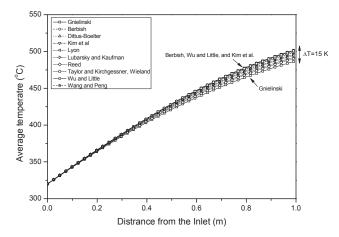


Figure 27. Temperature profile in secondary side by the heat transfer correlations (Sodium).

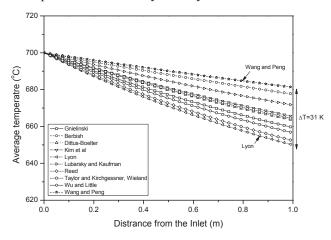


Figure 28. Temperature profile in primary side by the heat transfer correlations (Molten Salt).

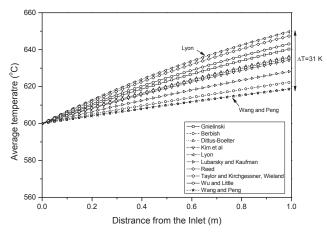


Figure 29. Temperature profile in secondary side by the heat transfer correlations (Molten Salt).

### 4. MECHANICAL DESIGN OF CROSSFLOW PCHEs

The assumptions and basic parameters of crossflow PCHE for mechanical design are summarized in Table 6.

Table 6. Assumptions and basic parameters of crossflow PCHE for mechanical design.

Parameter	Water/Water	Sodium/Sodium	M-S/M-S	Не/Не
Primary side pressure(P <sub>p</sub> ), (Pa)	$1.5 \times 10^{7}$	$1.01 \times 10^{5}$	$1.01 \times 10^{5}$	$7.0 \times 10^{6}$
Secondary side pressure(P <sub>s</sub> ), (Pa)	$5.0 \times 10^{6}$	$1.01 \times 10^{5}$	$1.01 \times 10^{5}$	$7.0 \times 10^{6}$
Channel diameter (D), (m)	0.003			
Channel pitch (P), (m)	0.0033			
Plate thickness (t <sub>p</sub> ), (m)	0.00317			
Maximum allowable stress( $\sigma_{max}$ ), (Pa)	$2.18 \times 10^{8}$			

Equations (2-55) and (2-56) are applied to determine the minimum values of pitch of channels and plate thickness, respectively. Calculated pitch of channels and plate thickness of each coolant are summarized in Table 7. The calculated pitch of channels and plate thickness of each coolant satisfied the criteria of mechanical design.

Table 7. Calculated pitch of channels and plate thickness of each coolant.

Parameter	Water/Water	Sodium/Sodium	M-S/M-S	Не/Не
Channel pitch (P), (m)	0.0031	0.003	0.003	0.003
Plate thickness (t <sub>p</sub> ), (m)	0.0016	0.0015	0.0015	0.0015

#### 5. ECONOMIC ANALYSIS OF CROSSFLOW PCHES

#### 5.1 Cost Estimation Method

The cost of heat exchanger is one of the important factors for development of heat exchanger. The total cost of a heat exchanger consists of capital cost and operating cost. The capital cost is related to the material cost of the heat exchanger so that it can be estimated based on its weight. Therefore, the capital cost depends on the structural material and size of the heat exchanger. The total mass of heat exchanger is given by:

$$M_{HX} = \rho_{HX} V_{HX} \tag{5-1}$$

The volume of the heat exchanger can be approximated as follow:

$$V_{HX} = L_x L_y L_z \tag{5-2}$$

The capital cost (CP) can be calculated by multiplying the cost factor of material ( $C_M$ ) and the total mass of heat exchanger ( $M_{HX}$ ) as follow:

$$CP = C_{M}M_{HX}$$
 (5-3)

On the other hand, the operating cost is estimated based on the thermal hydraulic condition of the heat exchanger. Since the operating cost is defined as the cost to operate the circulation pump of the heat exchanger, it is important to optimize the design of heat exchanger to reduce the pressure loss, and in turn, reducing the operating cost. To estimate the operating cost, the pumping power of the heat exchanger is used. The pumping powers of the heat exchanger in hot and cold fluid sides can be defined by [8]:

$$\mathcal{P}_{h} = \frac{\dot{m}_{h} \Delta P_{h}}{\rho_{h}} \tag{5-4}$$

$$\mathcal{P}_{c} = \frac{\dot{m}_{c} \Delta P_{c}}{\rho_{c}} \tag{5-5}$$

where

m = is a mass flow rate

 $\Delta P$  = pressure loss, and  $\rho$  is a density of fluid.

Thus, the operating cost can be approximated as follow [8]:

$$OP = C_{OP}Y(\mathcal{P}_h + \mathcal{P}_c)$$
 (5-6)

where

 $C_{OP} = cost per time (e.g., electricity cost per time)$ 

Y = the total duration of operation.

Therefore, the total cost of heat exchanger becomes:

$$C_{\text{total}} = CP + OP = C_{\text{M}}M_{\text{HX}} + C_{OP}Y(\mathcal{P}_{\text{h}} + \mathcal{P}_{\text{c}})$$
(5-7)

### 5.2 Results of Economic Analysis

In this crossflow PCHE analysis code, the size of heat exchanger is determined by iterative calculation to meet the given heat duty and temperature requirements. In this economic analysis, the heat duty and temperature requirements as shown in Table 4 and three nickel based structural alloys as shown in Table 1 were used. The maximum operating period of heat exchanger is assumed to be 20 years. In this analysis, the height of heat exchanger, L<sub>z</sub>, was fixed to 0.634 m to reduce the number of cases. If the height of the heat exchanger can be varied, the length and width of the heat exchanger are determined for each height so that various heat exchanger sizes can be generated. Economic analysis results are summarized in Table 8. For the given requirements of each coolant, the size of heat exchanger, average outlet temperature, capital cost and operation cost were determined.

Table 8. The result of economic analysis of crossflow PCHE.

	Heat	exchanger (m)	size	Average outlet temperature (°C)		Cost, (USD) (Operation period: 20 year)				
Coolants	L <sub>x</sub>	L <sub>y</sub>	$\rm L_z$	Primary	Secondary	Structural Material	Capital	Operation		
						Alloy 617	$3.82 \cdot 10^5$	1.40·10 <sup>9</sup>		
Water	0.396	1.518		295.3	293.6	Alloy 800H	$3.62 \cdot 10^5$	$1.44 \cdot 10^9$		
						Hastelloy N	$4.18 \cdot 10^5$	$1.41 \cdot 10^9$		
						Alloy 617	$1.50 \cdot 10^6$	9.48·10 <sup>9</sup>		
Helium	m 1.128 2.095 637.8	637.8	925.3	Alloy 800H	$1.43 \cdot 10^6$	9.49·10 <sup>9</sup>				
			0.624	_		2.4		Hastelloy N	$1.65 \cdot 10^6$	9.48·10 <sup>9</sup>
			0.634	390.2		Alloy 617	$1.25 \cdot 10^6$	$1.27 \cdot 10^8$		
Sodium	1.214	1.613			526.0	Alloy 800H	$1.18 \cdot 10^6$	$1.28 \cdot 10^8$		
						Hastelloy N	$1.36 \cdot 10^6$	$1.27 \cdot 10^8$		
				Alloy 617	$4.80 \cdot 10^7$	$9.12 \cdot 10^6$				
Molten Salt 6.352 11.880 651.0	6.352	5.352   11.880	651.0	690.2	Alloy 800H	$4.56 \cdot 10^7$	$9.12 \cdot 10^6$			
		Hastelloy N	$5.26 \cdot 10^7$	$9.12 \cdot 10^6$						

The capital cost of crossflow PCHE was relatively smaller than the operation cost except for molten salt heat exchanger. Due to the large size of the molten salt heat exchanger, its capital cost was estimated to be larger than operation cost. The capital cost of the molten salt heat exchanger was higher than the others, but the operation cost was much lower. The operation cost of the helium heat exchanger was the highest. Figures 30–33 show the total cost per year of the heat exchangers according to the operation period. Operation cost per year decreased as the operation period increased. Total cost of the heat exchanger using Alloy 617 was cheaper than the other structural materials except for the molten salt heat exchanger. In the molten salt heat exchanger, the total cost was minimized by using Alloy 800H. The total cost per year of molten salt heat exchanger decreased rapidly as the operation period increased.

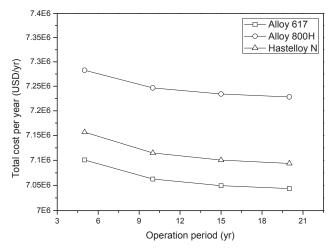


Figure 30. Total cost per year of crossflow PCHE (Water/Water).

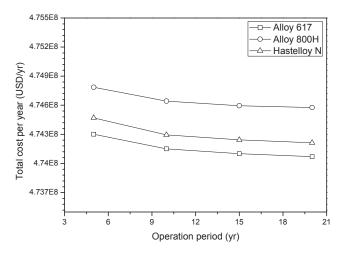


Figure 31. Total cost per year of crossflow PCHE (Helium/Helium).

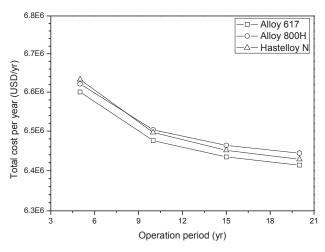


Figure 32. Total cost per year of crossflow PCHE (Sodium/Sodium).

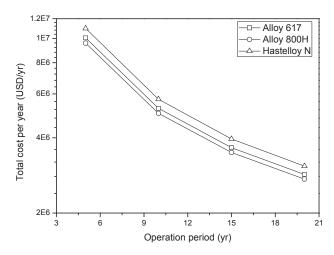


Figure 33. Total cost per year of crossflow PCHE (FLiBe/FLiNaK).

#### 6. CONCLUSION

In this study, the methodologies for thermal and mechanical designs of printed circuit heat exchanger with parallel, counter, and crossflow configuration were reported. The analytical solutions for temperature profiles in primary and secondary sides were described for each flow configuration. This work focused on the crossflow PCHE because parallel and counter flow PCHEs were studied previously (INL/EXT-11-23076). Thus, in this study, the crossflow PCHE analysis code has been developed to evaluate the size and cost of heat exchangers by implementing the analytical solution of single pass, both unmixed fluids crossflow heat exchanger model. Two-dimensional temperature distribution of crossflow PCHE was calculated by the analytical solution. General methods for thermal design and cost estimation of heat exchangers were employed to determine the size and cost of heat exchanger, respectively.

The grid sensitivity test of the code showed that the effect of grid on the temperature profile was negligible. The effectiveness calculated by the code showed a good agreement with that by well-known ε-NTU method. The uncertainty of fluid property was propagated into the temperature distribution, but its effect was small enough to be inconsequential. The heat transfer correlations had a considerable influence on the temperature profile. The temperature profile of crossflow PCHE using helium gases showed the largest deviation by the heat transfer correlations. The deviation of temperature profiles by the heat transfer correlation decreased for a very low or a very high Prandtl number of fluids. However, it was not easy to determine the most accurate heat transfer correlation for the heat exchangers using various combinations of coolants. Consequently, experimental and computational validations are required to determine the best heat transfer correlation for each coolant.

Costs of crossflow PCHE for the high temperature reactor designs were investigated. Capital costs of PCHE for water, helium, and sodium flows were lower than their operation costs, whereas capital cost of molten salt heat exchanger was higher than its operation cost. Total cost of heat exchanger using Alloy 617 was cheaper than the other structural materials except for the molten salt heat exchanger. In the molten salt heat exchanger, the total cost was minimized by using Alloy 800H, and in future potential Hastelloy N linear could be used to enhance corrosion resistance.

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## Appendix A

# Thermal Design of Parallel/Counter Flow PCHE

Thermal design of parallel/counter flow PCHE was performed in previous study [4]. In this report, thus, the results of previous study will be introduced.

Heat exchanger operating conditions are summarized in Table A-1.

Table A-1. Heat exchanger operating conditions.

Parameters	Primary Side	Secondary Side	
Heat Duty, MW <sub>th</sub>	3400		
Fluid Material	Molten Salt	Steam/water	
Inlet Temperature, °C	679	251	
Outlet Temperature, °C	587	593	
Pressure, MPa	0.1	25	

The geometric parameters of parallel/counter flow PCHE are summarized in Table A-2.

Table A-2. Basic geometry parameters of parallel/counter flow PCHE.

	I
Parameters	Value
Channel Diameter, m	0.003
Channel Pitch, m	0.0033
Channel Thickness, m	0.00317
Channel Horizontal Distance, m	3×10 <sup>-4</sup>
Surface Area Density, 1/m	737.252
Ratio of Free Flow Area to Frontal Area	0.338
Effective Diameter, m	1.833×10 <sup>-3</sup>

The primary coolant was molten-salt (KF-ZrF<sub>4</sub>) and the secondary coolant was water/steam. The basic properties of the coolants and structural material are summarized in Table A-3.

Table A-3. Thermo-physical properties of coolants.

Parameters	Molten-Salt (KF-ZrF <sub>4</sub> )	Water (Average)	
Density, kg/m <sup>3</sup>	2800	337	
Thermal Conductivity, W/(m·K)	0.45	0.29	
Heat Capacity, J/(kg·K)	1046.7	6510	
Viscosity, Poise	0.051	5.23×10 <sup>-4</sup>	
	Structural Material (Hastelloy N)		
Thermal Conductivity, W/(m·K)	23.5		

The flow parameters for the parallel and counter flow PCHE are summarized in Table A-4. The values of flow parameters of parallel and counter flow PCHE are equal to each other.

Table A-4. Flow parameters of parallel and counter flow PCHE.

Parameters	Value
Mass Flow in the Primary Side (Hot Channel), kg/s	35307.65
Mass Flow in the Secondary Side (Cold Channel), kg/s	1640.89
Coolant Velocity in Primary Side, m/s	0.95
Coolant Velocity in Secondary Side, m/s	0.75
Reynolds Number in Primary Side	1020.57
Reynolds Number in Secondary Side	8764.60
Prandtl Number in Primary Side	11.35
Prandtl Number in Secondary Side	1.14
Nusselt Number in Primary Side	3.66
Nusselt Number in Secondary Side	34.52
Colburn Factor in Primary Side	1.59×10 <sup>-3</sup>
Colburn Factor in Secondary Side	3.77×10 <sup>-3</sup>

The overall heat transfer characteristics of parallel and counter flow PCHE are summarized in Table A-5.

Table A-5. Overall heat transfer characteristics of parallel and counter flow PCHE.

Parameters	Value
Overall Heat Transfer Coefficient, W/(m <sup>2</sup> ·K)	760.34
Heat Transfer Surface Area, m <sup>2</sup>	24375.31
Log Mean Temperature Difference, K	0.86
Heat Exchanger Channel Length, m	0.86

Figures A-1 and A-2 show the temperature profiles of parallel and counter flow PCHE.

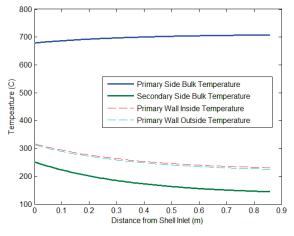


Figure A-1. Temperature profile of parallel flow PCHE.

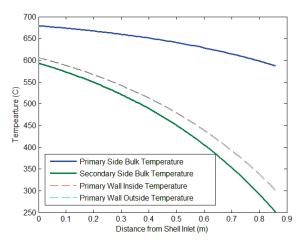


Figure A-2. Temperature profile of counter flow PCHE.

## Appendix B

## Mechanical Design of Parallel /Counter Flow PCHE

The basic assumptions and input parameters of parallel and counter flow PCHEs are summarized in Table B-1. The working fluids of primary and secondary sides in this analysis were molten salt and steam/water, respectively.

Table B-1. Assumptions and input parameters of parallel/counter flow PCHE for mechanical design.

Parameter	Value	Note
Channel diameter (D), m	0.003	Assumption
Channel pitch (P), m	0.0033	Assumption
Plate thickness (t <sub>p</sub> ), m	0.00317	Assumption
Primary side pressure(P <sub>p</sub> ), Pa	$2.5 \times 10^{7}$	Based on supercritical Rankine cycle
Secondary side pressure(P <sub>s</sub> ), Pa	$1.01 \times 10^{5}$	Based on molten salt intermediate loop
Maximum allowable stress( $\sigma_{max}$ ), Pa	$2.18 \times 10^{8}$	Yield stress for Alloy N at 700°C

The pitch of the channels can be estimated by:

$$P \ge D\left(1 + \frac{(P_p - P_s)}{\sigma_{max}}\right) = 0.003\left(1 + \frac{(2.5 \times 10^7 - 1.01 \times 10^5)}{2.18 \times 10^8}\right) = 0.0033 \tag{B-1}$$

In the PCHE, the plate can be assumed to be a thick-walled cylinder with an inner radius of d/2 and an outer radius of  $t_p$ . Therefore, the thickness of the plate,  $t_p$  can be estimated by:

$$t_{p} \ge \frac{D}{2} \sqrt{\frac{\sigma_{max} + P_{p}}{\sigma_{max} + 2P_{s} - P_{p}}} = \frac{0.003}{2} \sqrt{\frac{2.18 \times 10^{8} + 2.5 \times 10^{7}}{2.18 \times 10^{8} + 2 \times 1.01 \times 10^{5} - 2.5 \times 10^{7}}} = 0.0017$$
 (B-2)

In conclusion, the assumed pitch of channels and plate thickness satisfied the criteria of mechanical design.