

# **Answer Sets and the Language of Answer Set Programming**

**Vladimir Lifschitz**

Answer set programming is a declarative programming paradigm based on the answer set semantics of logic programs. This introductory article provides the mathematical background for the discussion of answer set programming in other contributions to this special issue.

## Introduction

Answer set programming (ASP) is a declarative programming paradigm introduced by Marek & Truszczynski (1999) and Niemelä (1999). It grew out of research on knowledge representation (van Harmelen, Lifschitz, & Porter 2008), nonmonotonic reasoning (Ginsberg & Smith 1988), and Prolog programming (Sterling & Shapiro 1986). Its main ideas are described in the article by Janhunen & Niemelä (2016) and in other contributions to this special issue.

In this introductory article our goal is to discuss the concept of an answer set, or stable model, which defines the semantics of ASP languages. The answer sets of a logic program are sets of atomic formulas without variables (“ground atoms”), and they were introduced in the course of research on the semantics of negation in Prolog. For this reason, we start with examples illustrating the relationship between answer sets and Prolog and the relationship between answer set solvers and Prolog systems. Then we review the mathematical definition of an answer set and discuss some extensions of the basic language of ASP.

## Prolog and Negation as Failure

Simple Prolog rules can be understood as rules for generating new facts, expressed as ground atoms, from facts that are given or have been generated earlier. For example, the Prolog program

```
p(1) . p(2) . p(3) .
q(2) . q(3) . q(4) .
r(X) :- p(X), q(X) .
```

consists of 6 facts (“1, 2, and 3 have property  $p$ ; 2, 3, and 4 have property  $q$ ”) and a rule: for any value of  $X$ ,  $r(X)$  can be generated if  $p(X)$  and  $q(X)$  are given or have been generated earlier.<sup>1</sup> In response to the query  $?- r(X)$  a typical Prolog system will return two answers, first  $X = 2$  and then  $X = 3$ .

Let us call this program  $\Pi_1$  and consider its modification  $\Pi_2$ , in which the “negation as failure” symbol  $\backslash+$  is inserted in front of the second atom in the body of the rule:

```
p(1) . p(2) . p(3) .
q(2) . q(3) . q(4) .
r(X) :- p(X), \+ q(X) .
```

The modified rule allows us, informally speaking, to generate  $r(X)$  if  $p(X)$  has been generated, assuming that any attempt to generate  $q(X)$  using the rules of the program would fail. Given the modified program and the query  $?- r(X)$  Prolog returns one answer,  $X = 1$ .

What is the precise meaning of conditions of this kind, “any attempt to generate ... using the rules of the program would fail”? This is not an easy question, because the condition is circular: it attempts to describe when a rule  $R$  “fires” (can be used to generate a new fact) in terms of the set of facts that can be generated using all rules of the program, including  $R$  itself. Even though this formulation is vague, it often allows us to decide when a rule with negation is supposed to fire. It is clear, for instance, that there is no way to use the rules of  $\Pi_2$  to generate  $q(1)$ , because this atom is not among the given facts and it does not match the head of any rule of  $\Pi_2$ . We conclude that the last rule of  $\Pi_2$  can be used to generate  $r(1)$ .

But there are cases when the circularity of the above description of negation as failure makes it confusing. Consider the following program  $\Pi_3$ , obtained from  $\Pi_2$  by replacing the facts in the second line with a rule:

```
p(1) . p(2) . p(3) .
q(3) :- \+ r(3) .
r(X) :- p(X), \+ q(X) .
```

The last rule justifies generating  $r(1)$  and  $r(2)$ , there can be no disagreement about this. But what about  $r(3)$ ? The answer is yes if any attempt to use the rules of the program to generate  $q(3)$  fails. In other words, the answer is yes if the second rule of the program does not fire. But does it? It depends on whether the last rule can be used to generate  $r(3)$ ---the question that we started with.

The first precise semantics for negation as failure was proposed by Clark (1978), who defined the process of program completion---a syntactic transformation that turns Prolog programs into first-order theories. The definition of a stable model, or answer set, proposed ten years later (Gelfond & Lifschitz 1988), is an alternative explanation of the meaning of Prolog rules with negation. It grew out of the view that an answer set of a logic program describes a possible set of beliefs of an agent associated with this program; see the paper by Erdem, Gelfond, & Leone (2016) in this special issue. Logic programs are similar, in this sense, to autoepistemic theories (Moore 1985) and default theories (Reiter 1980).<sup>2</sup> The definition of an answer set, reproduced below, adapts the semantics of default logic to the syntax of Prolog.

We will see that program  $\Pi_3$ , unlike  $\Pi_1$  and  $\Pi_2$ , has two answer sets. One answer set authorizes including  $X=3$  as an answer to the query  $?- q(X)$  but not as an answer to the query  $?- r(X)$ ; according to the other answer set, it is the other way around. In this sense, program  $\Pi_3$  does not give an unambiguous specification for query answering. Programs with several answer sets are "bad" Prolog programs.

In answer set programming, on the other hand, programs with several answer sets (or without answer sets) are quite usual and play an important role, like equations with several roots (or without roots) in algebra.

## Answer Set Solvers

How does the functionality of answer set solvers compare with Prolog?

Each of the programs  $\Pi_1$ ,  $\Pi_2$ , and  $\Pi_3$  will be accepted as a valid input by an answer set solver, except that the symbol  $\backslash+$  for negation as failure should be written as `not`. Thus  $\Pi_2$  becomes, in the language of answer set programming,

```
p(1). p(2). p(3).
q(2). q(3). q(4).
r(X) :- p(X), not q(X).
```

and  $\Pi_3$  will be written as

```
p(1). p(2). p(3).
q(3) :- not r(3).
r(X) :- p(X), not q(X).
```

Unlike Prolog systems, an answer set solver does not require a query as part of the input. The only input it expects is a program, and it outputs the program's answer sets. For instance, given program  $\Pi_1$ , it will find the answer set

```
p(1) p(2) p(3) q(2) q(3) q(4) r(2) r(3)
```

From the perspective of Prolog, this is the list of all ground queries that would generate the answer `yes` for this program. For program  $\Pi_2$ , the answer set

```
p(1) p(2) p(3) q(2) q(3) q(4) r(1)
```

will be calculated. Given  $\Pi_3$  as input, an answer set solver will find two answer sets:

```
Answer: 1
p(1) p(2) p(3) q(3) r(1) r(2)
Answer: 2
p(1) p(2) p(3) r(3) r(1) r(2)
```

## Definition of an Answer Set: Positive Programs

We will review now the definition of an answer set, beginning with the case when the rules of the program do not contain negation, as in program  $\Pi_1$  above. By definition, such a program has a unique answer set, which is formed as follows.

First we *ground* the program by substituting specific values for variables in its rules in all possible ways. The result will be a set of rules of the form

$$A_0 :- A_1, \dots, A_n. \quad (1)$$

where each  $A_i$  is a ground atom. (We think of “facts,” such as  $p(1)$  in  $\Pi_1$ , as rules of form (1) with  $n = 0$  and with the symbol  $:-$  dropped.) For instance, grounding turns  $\Pi_1$  into

```
p(1) . p(2) . p(3) .
q(2) . q(3) . q(4) .
r(1) :- p(1) , q(1) .
r(2) :- p(2) , q(2) .
r(3) :- p(3) , q(3) .
r(4) :- p(4) , q(4) .
```

The answer set of the program is the smallest set  $S$  of ground atoms such that for every rule (1) obtained by grounding, if the atoms  $A_1, \dots, A_n$  belong to  $S$  then the head  $A_0$  belongs to  $S$  too.

For instance, in the case of program  $\Pi_1$  this set  $S$  includes

- the facts in the first two lines of the grounded program,
- the atom  $r(2)$ , because both atoms in the body of the rule with the head  $r(2)$  belong to  $S$ , and
- the atom  $r(3)$ , because both atoms in the body of the rule with the head  $r(3)$  belong to  $S$ .

The following program contains two symbolic constants, `block` and `table`:

```
number(1) . number(2) . number(3) .
location(block(N)) :- number(N) .
location(table) .
```

Grounding turns the second rule into

```
location(block(1)) :- number(1) .
location(block(2)) :- number(2) .
location(block(3)) :- number(3) .
```

The answer set of this program consists of the atoms

```
number(1) number(2) number(3) location(block(1))
location(block(2)) location(block(3)) location(table)
```

### Definition of an Answer Set: Programs with Negation

In the general case, when the rules of the given program may contain negation, grounding gives a set of rules of the form

$$A_0 :- A_1, \dots, A_m, \text{ not } A_{m+1}, \dots, \text{ not } A_n. \quad (2)$$

where each  $A_i$  is a ground atom. (To simplify notation, we showed all negated atoms at the end.) For instance, the result of grounding  $\Pi_2$  is

```
p(1) . p(2) . p(3) .
q(2) . q(3) . q(4) .
r(1) :- p(1) , not q(1) .
r(2) :- p(2) , not q(2) .
r(3) :- p(3) , not q(3) .
r(4) :- p(4) , not q(4) .
```

To decide whether a set  $S$  of ground atoms is an answer set, we form the *reduct* of the grounded program with respect to  $S$ , as follows. For every rule (2) of the grounded program such that  $S$  does not contain any of the atoms  $A_{m+1}, \dots, A_n$ , we drop the negated atoms from (2) and include the “positive part” (1) of the rule in the reduct. All other rules are dropped from the grounded program altogether. Since the reduct consists of rules of form (1), we already know how to calculate its

answer set. If the answer set of the reduct coincides with the set  $S$  that we started with then we say  $S$  is an answer set of the given program.

For instance, to check that the set

$$\{p(1), p(2), p(3), q(2), q(3), q(4), r(1)\} \quad (3)$$

is an answer set of  $\Pi_2$ , we calculate the reduct of the grounded program with respect to this set. The reduct is

$$\begin{aligned} & p(1) . p(2) . p(3) . \\ & q(2) . q(3) . q(4) . \\ & r(1) :- p(1) . \end{aligned}$$

(The last three rules of the grounded program are not included in the reduct because set (3) includes  $q(2)$ ,  $q(3)$ , and  $q(4)$ .) The answer set of the reduct is indeed the set (3) that we started with. If we repeat this computation for any set  $S$  of ground atoms other than (3) then the result may be a subset of  $S$ , or a superset of  $S$ , or it may partially overlap with  $S$ , but it will never coincide with  $S$ .

Consequently (3) is the only answer set of  $\Pi_2$ .

Intuitively, the reduct of a program with respect to  $S$  consists of the rules of the program that “fire” assuming that  $S$  is exactly the set of atoms that can be generated using the rules of the program. If the answer set of the reduct happens to be exactly  $S$  then we conclude that  $S$  was a “good guess.”

The concept of an answer set can be defined in many other, equivalent ways (Lifschitz 2010).

## Extensions of the Basic Language

*Arithmetic.* Rules may contain symbols for arithmetic operations and comparisons, for instance:

$$\begin{aligned} & p(1) . p(2) . \\ & q(1) . q(2) . \\ & r(X+Y) :- p(X), q(Y), X < Y . \end{aligned}$$

The answer set of this program is

$$p(1) \ p(2) \ q(1) \ q(2) \ r(3)$$

(In view of the condition  $X < Y$  in the body, the only values substituted for the variables in the process of grounding are  $X=1, Y=2$ .)

*Disjunctive rules* (Gelfond & Lifschitz 1991). The head of a rule may be a disjunction of several atoms (often separated by bars or semicolons), rather than a single atom. For instance, the rule

$$p(1) \ | \ p(2) .$$

instructs the solver to include  $p(1)$  or  $p(2)$  in each answer set. The answer sets of this one-rule program are

$$\begin{aligned} \text{Answer: } & 1 \\ & p(1) \\ \text{Answer: } & 2 \\ & p(2) \end{aligned}$$

*Choice rules* (Niemelä & Simons 2000). Enclosing the list of atoms in the head in curly braces represents the “choice” construct: choose in all possible ways which atoms from the list will be included in the answer set. For instance, the one-rule program

$$\{ p(1) \ ; \ p(2) \} .$$

has 4 answer sets:

$$\begin{aligned} \text{Answer: } & 1 \\ & p(1) \\ \text{Answer: } & 2 \\ & p(1) \end{aligned}$$

Answer: 3  
 p(2)  
 Answer: 4  
 p(1) p(2)

A choice rule may specify bounds on the number of atoms that are included. The lower bound is shown to the left of the expression in braces, and the upper bound to the right. For instance, the one-rule program

$1 \{ p(1) ; p(2) \}.$

has 3 answer sets---answers 2--4 from the previous example. The one-rule program

$\{ p(1) ; p(2) \} 1.$

has 3 answer sets as well---answers 1--3.

*Constraints.* A constraint is a disjunctive rule that has 0 disjuncts in the head, so that it starts with the symbol  $:-$ . Adding a constraint to a program eliminates the answer sets that satisfy the body of the constraint. For instance, the answer sets of the program

$\{ p(1) ; p(2) \}.$   
 $:- p(1), \text{ not } p(2).$

are answers 1, 3 and 4 from the list above. Answer 2 violates the constraint, because it includes  $p(1)$  and does not include  $p(2)$ .

*Classical negation* (Gelfond & Lifschitz 1991). Atoms in programs and in answer sets can be preceded by the “classical negation” sign ( $-$ ) that should be distinguished from the negation as failure symbol ( $\text{not}$ ). This is useful for representing incomplete information. For instance, the answer set

$p(a) \ p(b) \ -p(c) \ q(a) \ -q(c)$

can be interpreted as follows:  $a$  and  $b$  have property  $p$ , and  $c$  does not;  $a$  has property  $q$ , and  $c$  does not; whether  $b$  has property  $q$  we do not know. A rule of the form

$- A :- \text{ not } A.$

containing classical negation in the head and negation as failure in the body expresses the “closed world assumption” for the atom  $A$ :  $A$  is false if there is no evidence that  $A$  is true. The rule

$p(T+1) :- p(T), \text{ not } -p(T+1).$

expresses the “frame default” (Reiter 1980) in the language of answer set programming: if  $p$  was true at time  $T$  and there is no evidence that  $p$  became false at time  $T+1$  then  $p$  was true at time  $T+1$ .

Input languages of many answer set solvers include other useful extensions of the basic language, such as aggregates (Faber, Leone, & Pfeifer 2004), weak constraints (Buccafuri, Leone, & Rullo 1997), consistency-restoring rules (Balduccini & Gelfond 2003), and P-log rules (Chitta, Gelfond, & Rushton 2009).

## Extending the Definition of an Answer Set

The problem of extending the definition of an answer set to additional constructs, such as those reviewed in the previous section, can be approached in several ways. One useful idea is to treat expressions in the bodies and heads of rules as logical formulas written in alternative notation. For instance, we can think of the list in the body of (2) as a conjunction of literals:

$$A_1 \wedge \cdots \wedge A_m \wedge \neg A_{m+1} \wedge \cdots \wedge \neg A_n.$$

A choice expression  $\{A_1; \dots; A_n\}$  can be treated as a conjunction of “excluded middle” formulas:

$$(A_1 \vee \neg A_1) \wedge \cdots \wedge (A_n \vee \neg A_n)$$

(Ferraris & Lifschitz 2005). Under this approach, the rules of a grounded program are expressions of the form  $F \leftarrow G$ , where  $F$  and  $G$  are formulas built from ground atoms using conjunction, disjunction, and negation.<sup>3</sup>

The definition of the reduct was extended to such rules by Lifschitz, Tang, & Turner [1999]. In the process of constructing the reduct of a rule  $F \leftarrow G$  with respect to a set  $S$  of ground atoms, every subformula that begins with negation is replaced by a logical constant: by *true* if it is satisfied by  $S$ , and by *false* otherwise.

Gebser *et al.* [2015] defined the syntax and semantics of many constructs implemented in the solver CLINGO using a generalization of this approach that allows the formulas  $F$  and  $G$  to contain implication, and that allows conjunctions and disjunctions in  $F$  and  $G$  to be infinitely long.

## Acknowledgements

Thanks to Gerhard Brewka, Martin Gebser, Michael Gelfond, Tomi Janhunnen, Amelia Harrison, Amanda Lacy, Yuliya Lierler, Nicola Leone, and Mirek Truszczynski for comments on a draft of this article. This research was partially supported by the National Science Foundation under Grant IIS-1422455.

## Notes

<sup>1</sup>In Prolog programs, a period indicates the end of a rule. Capitalized identifiers are used as variables. The symbol  $:-$  reads “if”; it separates the “head” of the rule (in this case, the atom  $r(x)$ ) from its “body” (the pair of atoms  $p(x), q(x)$ ). Answer set programming inherited from Prolog these syntactic conventions and terminology.

<sup>2</sup>The relationship between Prolog and autoepistemic logic was described by Gelfond (1987).

<sup>3</sup>A more radical version of this view is to think of the whole rule  $F \leftarrow G$  as a propositional formula—as the implication  $G \rightarrow F$  “written backwards” (Ferraris 2005). It is also possible to avoid the reference to grounding in the definition of an answer set and to treat rules with variables as first-order formulas (Ferraris, Lee, & Lifschitz 2011).

## References

- Balduccini, M., and Gelfond, M. 2003. Logic programs with consistency-restoring rules<sup>4</sup>. In *Working Notes of the AAAI Spring Symposium on Logical Formalizations of Commonsense Reasoning*.
- Buccafuri, F.; Leone, N.; and Rullo, P. 1997. Enhancing disjunctive Datalog by constraints. *IEEE Transactions on Knowledge and Data Engineering* 12:845--860.
- Chitta, B.; Gelfond, M.; and Rushton, N. 2009. Probabilistic reasoning with answer sets. *Theory and Practice of Logic Programming* 9:57--144.
- Clark, K. 1978. Negation as failure. In Gallaire, H., and Minker, J., eds., *Logic and Data Bases*. New York: Plenum Press. 293--322.
- Erdem, E.; Gelfond, M.; and Leone, N. 2016. Applications of ASP. *AI Magazine*.
- Faber, W.; Leone, N.; and Pfeifer, G. 2004. Recursive aggregates in disjunctive logic programs: Semantics and complexity. In *Proceedings of European Conference on Logics in Artificial Intelligence (JELIA)*.
- Ferraris, P., and Lifschitz, V. 2005. Weight constraints as nested expressions. *Theory and Practice of Logic Programming* 5(1--2):45--74.
- Ferraris, P.; Lee, J.; and Lifschitz, V. 2011. Stable models and circumscription. *Artificial Intelligence* 175:236--263.

- Ferraris, P. 2005. Answer sets for propositional theories. In *Proceedings of International Conference on Logic Programming and Nonmonotonic Reasoning (LPNMR)*, 119--131.
- Gebser, M.; Harrison, A.; Kaminski, R.; Lifschitz, V.; and Schaub, T. 2015. Abstract Gringo. *Theory and Practice of Logic Programming* 15:449--463.
- Gelfond, M., and Lifschitz, V. 1988. The stable model semantics for logic programming. In Kowalski, R., and Bowen, K., eds., *Proceedings of International Logic Programming Conference and Symposium*, 1070--1080. MIT Press.
- Gelfond, M., and Lifschitz, V. 1991. Classical negation in logic programs and disjunctive databases. *New Generation Computing* 9:365--385.
- Gelfond, M. 1987. On stratified autoepistemic theories. In *Proceedings of National Conference on Artificial Intelligence (AAAI)*, 207--211.
- Ginsberg, M., and Smith, D. 1988. Reasoning about action I: a possible world approach. *Artificial Intelligence* 35:165--195.
- Janhunen, T., and Niemelä, I. 2016. The answer set programming paradigm. *AI Magazine*.
- Lifschitz, V.; Tang, L. R.; and Turner, H. 1999. Nested expressions in logic programs. *Annals of Mathematics and Artificial Intelligence* 25:369--389.
- Lifschitz, V. 2010. Thirteen definitions of a stable model. In *Fields of Logic and Computation: Essays Dedicated to Yuri Gurevich on the Occasion of his 70th Birthday*. Springer. 488--503.
- Marek, V., and Truszczyński, M. 1999. Stable models and an alternative logic programming paradigm. In *The Logic Programming Paradigm: a 25-Year Perspective*. Springer Verlag. 375--398.
- Moore, R. 1985. Semantical considerations on nonmonotonic logic. *Artificial Intelligence* 25(1):75--94.
- Niemelä, I., and Simons, P. 2000. Extending the Smodels system with cardinality and weight constraints. In Minker, J., ed., *Logic-Based Artificial Intelligence*. Kluwer. 491--521.
- Niemelä, I. 1999. Logic programs with stable model semantics as a constraint programming paradigm. *Annals of Mathematics and Artificial Intelligence* 25:241--273.
- Reiter, R. 1980. A logic for default reasoning. *Artificial Intelligence* 13:81--132.
- Sterling, L., and Shapiro, E. 1986. *The Art of Prolog: Advanced Programming Techniques*. MIT Press.
- van Harmelen, F.; Lifschitz, V.; and Porter, B., eds. 2008. *Handbook of Knowledge Representation*. Elsevier.