# Application of the X-FEM to the fracture of piezoelectric materials

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# Outline

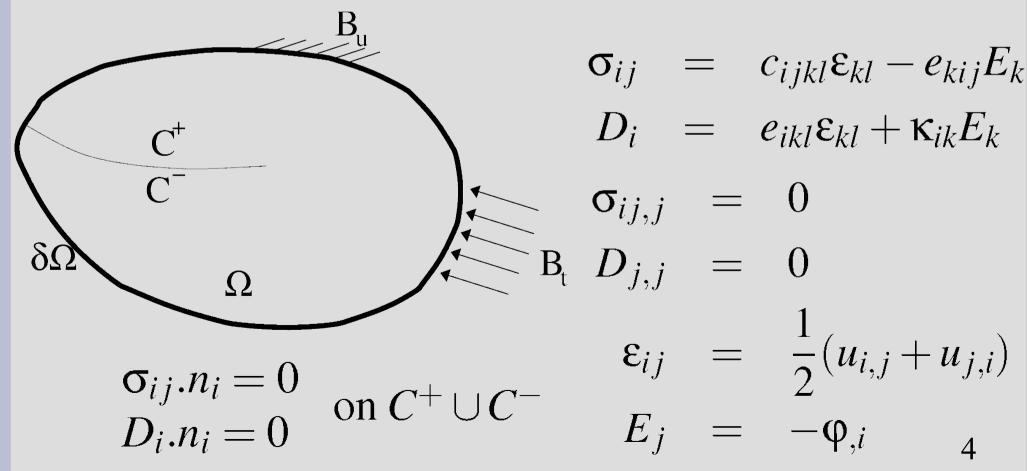
- Introduction
- Updated X-FEM formulation
  - New crack tip enrichment functions
  - Updated SIF computation scheme
  - Use of specific preconditionner
- Convergence study
- Conclusions

# Introduction

- Goal
  - Propose a updated enrichment scheme for a cracked anisotropic piezoelectric media
  - Convergence study of the method
    - Energy error
    - SIFS and energy release rate
  - Development of a SIF evaluation scheme based on interaction integrals specific to piezoelectric materials
  - Numerical crack propagation using empirical laws

#### Introduction

 Physical model : linear piezoelectric media, electrically impermeable crack

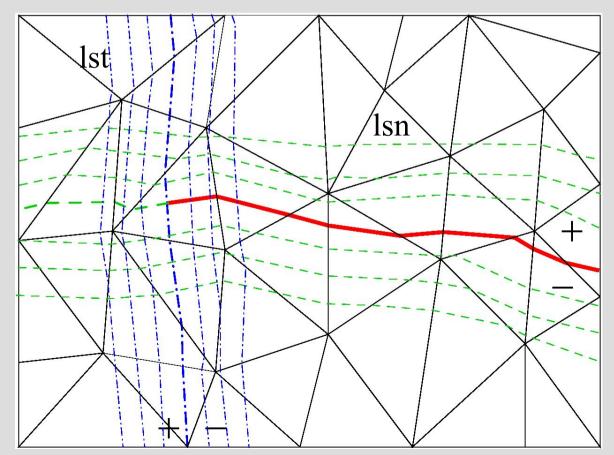


# Introduction

- Numerical Model
  - Xfem field approximation
  - No remeshing
  - Interaction integrals used to compute the SIFs

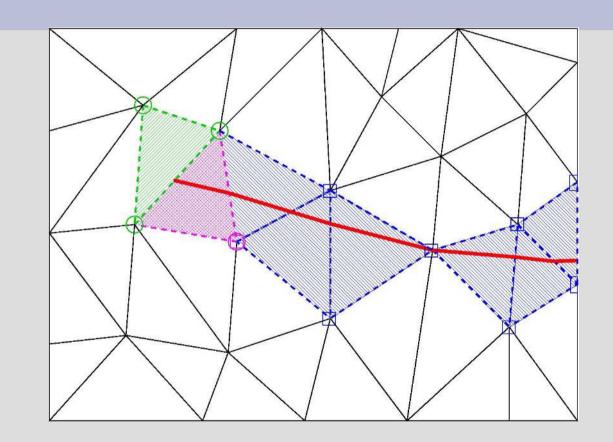
#### X-FEM

- Crack represented by level-sets
  - Local coodinates at the crack tip



# X-FEM

- Local partition of unity enrichment
  - Singular functions around crack tip
  - Heaviside along crack surface
  - Remaining dofs unenriched



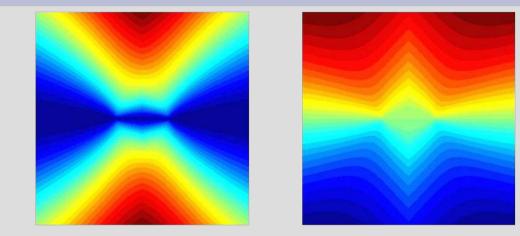
$$\mathbf{u}^{h} = \sum_{i \in R} \mathbf{N}_{i} a_{i} + \sum_{i \in R} \sum_{j=1...n} \mathbf{N}_{i} g_{j} b_{ij} + \sum_{i \in H} \mathbf{N}_{i} h c_{i}$$
$$\Phi^{h} = \sum_{i \in R} N_{i} \alpha_{i} + \sum_{i \in R} \sum_{j=1...n} N_{i} g_{j} \beta_{ij} + \sum_{i \in H} N_{i} h \gamma_{i}$$

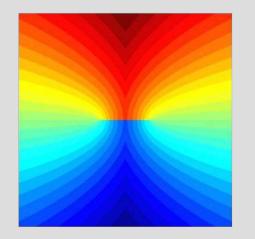
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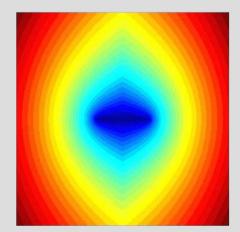
- Enrichment functions
  - Jump across the crack for displacements and potential :

$$h(\varphi) = \begin{cases} +1 & \text{if } \varphi \ge 0\\ -1 & \text{if } \varphi < 0 \end{cases}$$

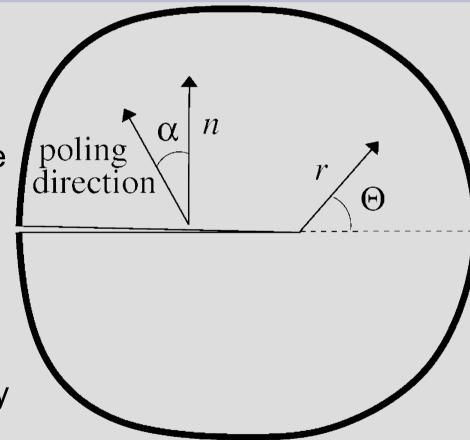
- Crack tip for in a pure mechanical setting  $g_i(r,\theta) = \left\{ \sqrt{r} \sin \frac{\theta}{2}, \sqrt{r} \cos \frac{\theta}{2}, \sqrt{r} \sin \frac{\theta}{2} \sin \theta, \sqrt{r} \cos \frac{\theta}{2} \sin \theta \right\}$ 







- Crack tip functions for a piezoelectrical setting
  - Must span the eigenfunction's space at the crack tip for displacements and potential
  - Depends on the material characteristics and the orientation
  - Depends on the permeability of the crack



 $g_i(r,\theta) = \left\{\sqrt{r}f_1(\theta), \sqrt{r}f_2(\theta), \sqrt{r}f_3(\theta), \sqrt{r}f_4(\theta), \sqrt{r}f_5(\theta), \sqrt{r}f_6(\theta)\right\}$ 

$$f_{i}(\theta) = \phi(\omega(\theta, \alpha), a_{i,re}, a_{i,im})$$

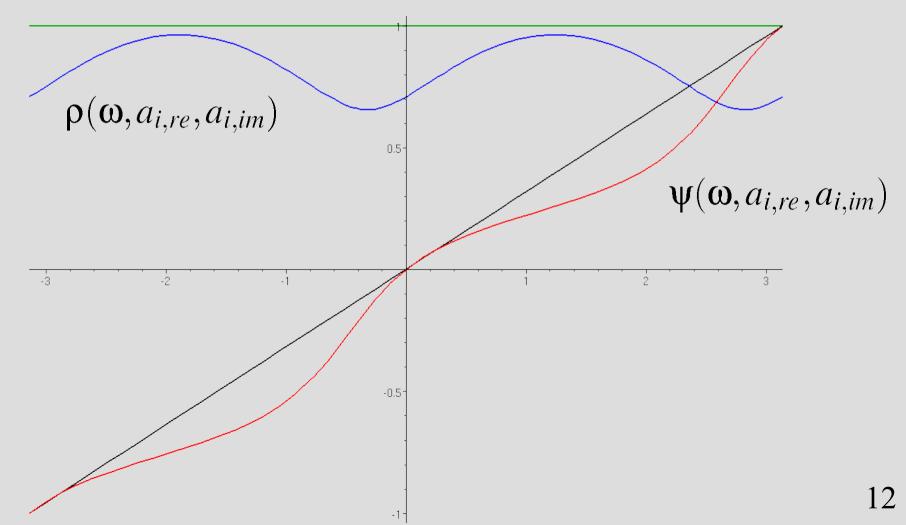
$$= \begin{cases} \rho(\omega, a_{i,re}, a_{i,im}) \cos \frac{\psi(\omega, a_{i,re}, a_{i,im})}{2} & \text{if } a_{i,im} > 0\\ \rho(\omega, a_{i,re}, a_{i,im}) \sin \frac{\psi(\omega, a_{i,re}, a_{i,im})}{2} & \text{if } a_{i,im} \le 0 \end{cases}$$

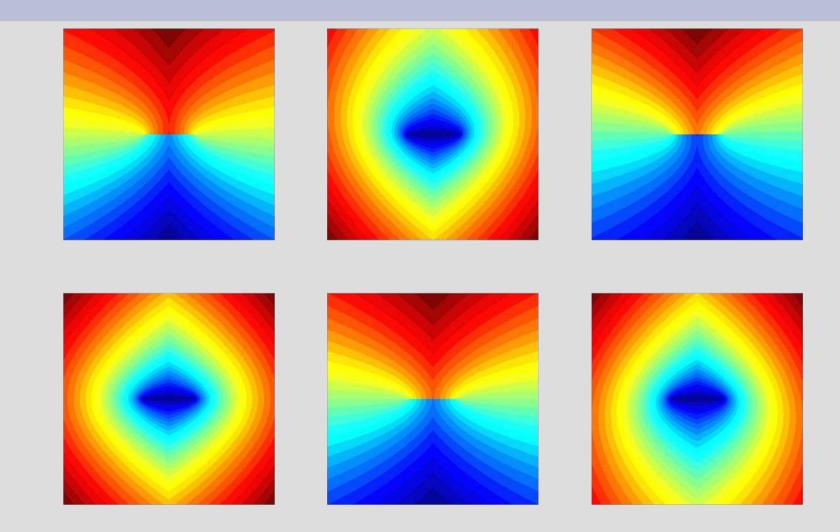
$$\boldsymbol{\omega} = \boldsymbol{\theta} - \boldsymbol{\alpha}$$
  
 $\boldsymbol{\rho}(\boldsymbol{\omega}, a_{i,re}, a_{i,im}) =$ 

$$\frac{1}{\sqrt{2}} \sqrt[4]{a_{i,re}^2 + a_{i,im}^2 + a_{i,re} \sin 2\omega - \left(a_{i,re}^2 + a_{i,im}^2 - 1\right) \cos 2\omega}$$
$$\psi(\omega, a_{i,re}, a_{i,im}) = \frac{\pi}{2} + \pi \operatorname{int}\left(\frac{\omega}{\pi}\right)$$
$$- \arctan\left(\frac{\cos\left(\omega - \pi \operatorname{int}\left(\frac{\omega}{\pi}\right)\right) + a_{i,re} \sin\left(\omega - \pi \operatorname{int}\left(\frac{\omega}{\pi}\right)\right)}{|a_{i,im}| \sin\left(\omega - \pi \operatorname{int}\left(\frac{\omega}{\pi}\right)\right)}\right)$$

11

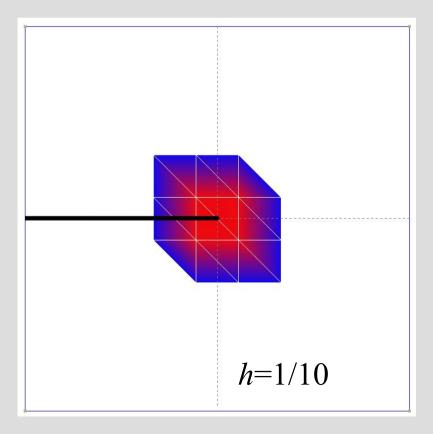
Modified functions

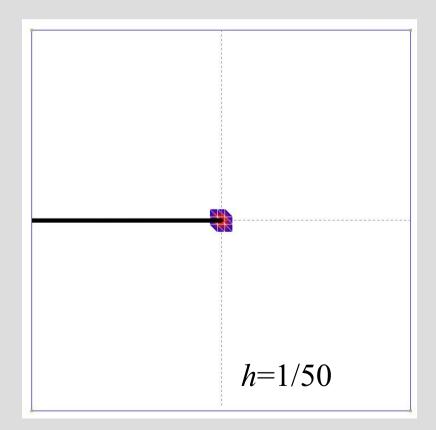




# **Updated enrichment scheme**

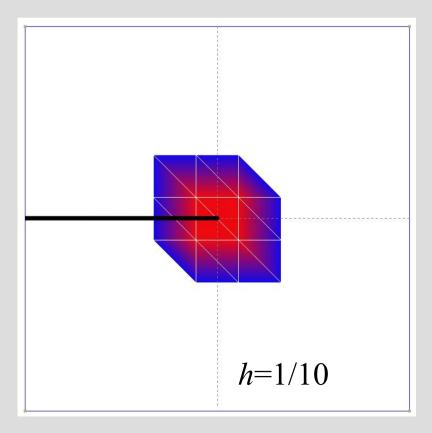
#### "topological" Enrichment

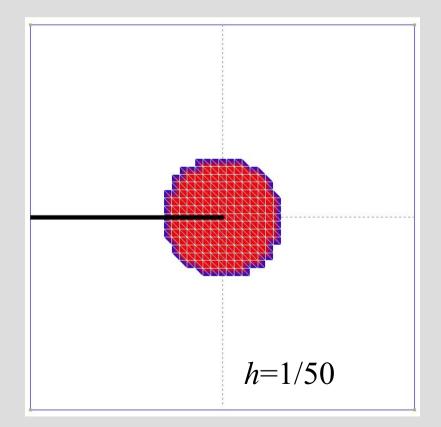




# **Updated enrichment scheme**

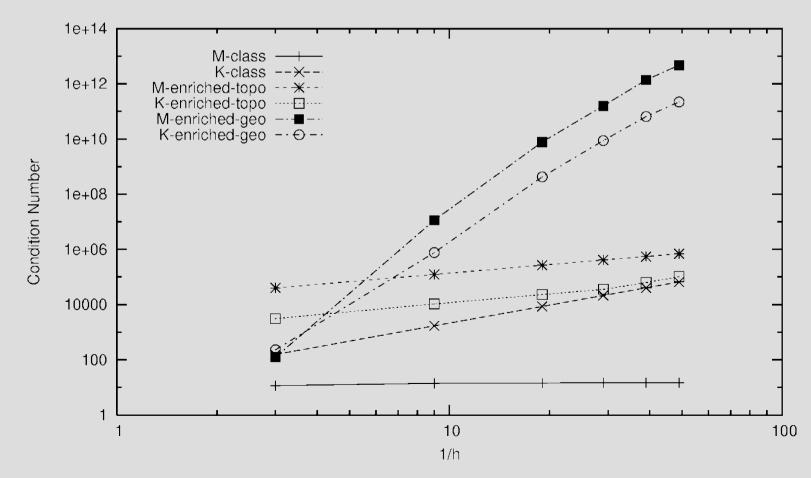
#### "Geometrical" Enrichment



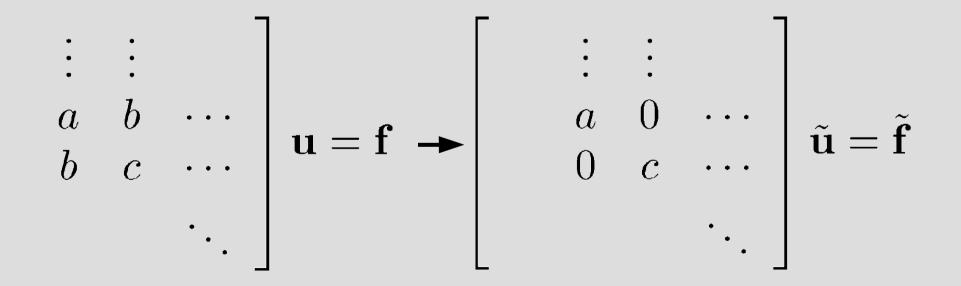


#### **Condition number**

 The enrichment may lead to almost-singular matrices — difficult to use iterative solvers



Orthogonalize each subset of enriched dofs



• Cholesky decomposition & scaling for node k :

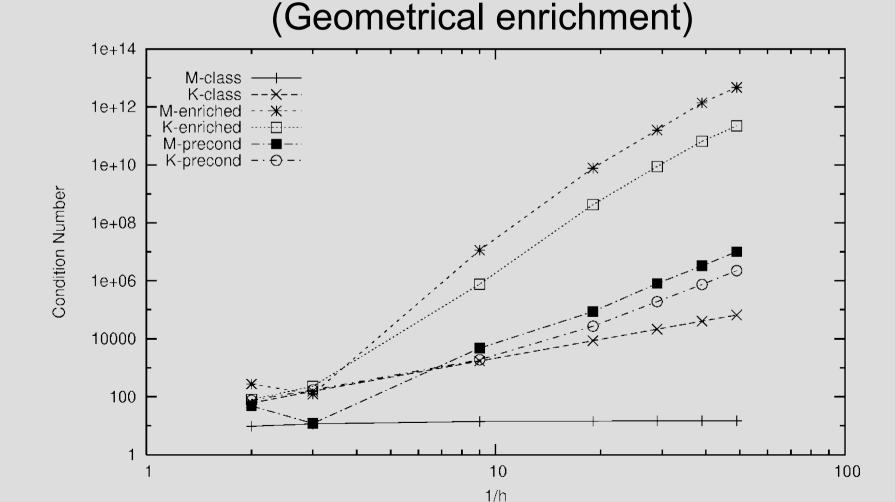
$$\mathbf{A} = \begin{bmatrix} a & b \\ b & c \end{bmatrix} \quad \mathbf{A} = \mathbf{G}\mathbf{G}^T$$

$$\mathbf{D}_{ij} = \sqrt{\mathbf{A}_{ij}\delta_{ij}}$$
 (no summation)  
 $\mathbf{R} = \mathbf{G}^{-1}\mathbf{D}$ 

"Assembly" of every submatrix R gives R\*  $\mathbf{R}^* \mathbf{K} \mathbf{R}^{*T} \tilde{\mathbf{u}} = \mathbf{R}^* \mathbf{f}$  with  $\mathbf{u} = \mathbf{R}^{*T} \tilde{\mathbf{u}}$ 

- Trick for handling non positive definite systems (but blockwise positive definite)
  - If the matrix A belongs to the electrostatic part:
    - *a*, *b* and *c* are negative
    - we need to take the opposite matrix (which is positive definite) in order to generate the preconditionner

#### Condition number of $\mathbf{R}^* \mathbf{K} \mathbf{R}^{*T}$ or $\mathbf{R}^* \mathbf{M} \mathbf{R}^{*T}$

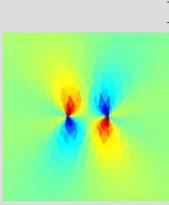


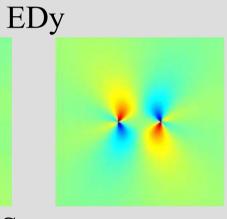
20

- Exact solution use of complex potentials
  - cf. H. Sosa, Plane problems in piezoelectric media with defects, Int. J. Sol. Struct. (1991)

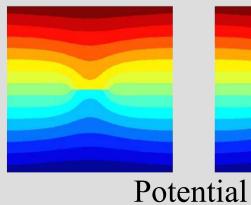
$$\begin{aligned} \varepsilon_{xx} &= 2\Re \left( \sum_{k=1}^{3} \left( a_{11}\tau_{k}^{2} + a_{12} - b_{12}\kappa_{k} \right) \phi_{k}(z_{k}) \right) & \kappa_{k} = -\frac{(b_{21} + b_{13})\tau_{k} + b_{22}}{\delta_{11}\tau_{k}^{2} + \delta_{22}} \\ \varepsilon_{xy} &= 2\Re \left( \sum_{k=1}^{3} \left( a_{12}\tau_{k}^{2} + a_{22} - b_{22}\kappa_{k} \right) \phi_{k}(z_{k}) \right) & z_{k} = x + \tau_{k}y \\ \varepsilon_{xy} &= \Re \left( \sum_{k=1}^{3} \left( -a_{33}\tau_{k} + b_{13}\tau_{k}\kappa_{k} \right) \phi_{k}(z_{k}) \right) & \phi_{k}(z_{k}) = \frac{A_{k}z_{k}}{\sqrt{z_{k}^{2} - a^{2}}} + B_{k} \\ E_{x} &= 2\Re \left( \sum_{k=1}^{3} \left( b_{13} + \delta_{11}\kappa_{k} \right) \tau_{k}\phi_{k}(z_{k}) \right) & \tau_{k} \text{ are roots of the characteristic equation} \\ E_{y} &= -2\Re \left( \sum_{k=1}^{3} \left( b_{21}\tau_{k}^{2} + b_{22} + \delta_{22}\kappa_{k} \right) \phi_{k}(z_{k}) \right) & 2 \end{aligned}$$



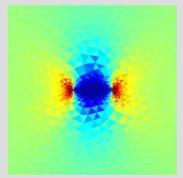


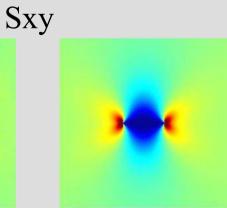


















Displacement

 Energy norm with respect to the internal energy

$$U = \int_{V} \left( \frac{1}{2} \varepsilon_{ij} c_{ijkl} \varepsilon_{kl} + \frac{1}{2} E_{i} \varepsilon_{ij} E_{j} \right) dV$$

 $E_U =$ 

$$\int_{V} \sqrt{\frac{1}{2} \left( \varepsilon_{ij} - \varepsilon_{ij}^{ex} \right) c_{ijkl} \left( \varepsilon_{kl} - \varepsilon_{kl}^{ex} \right) + \frac{1}{2} \left( E_i - E_i^{ex} \right) \varepsilon_{ij} \left( E_j - E_j^{ex} \right) dV}$$

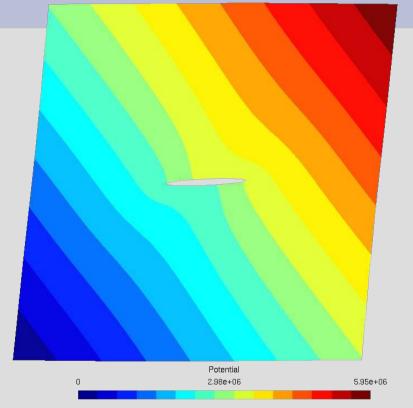
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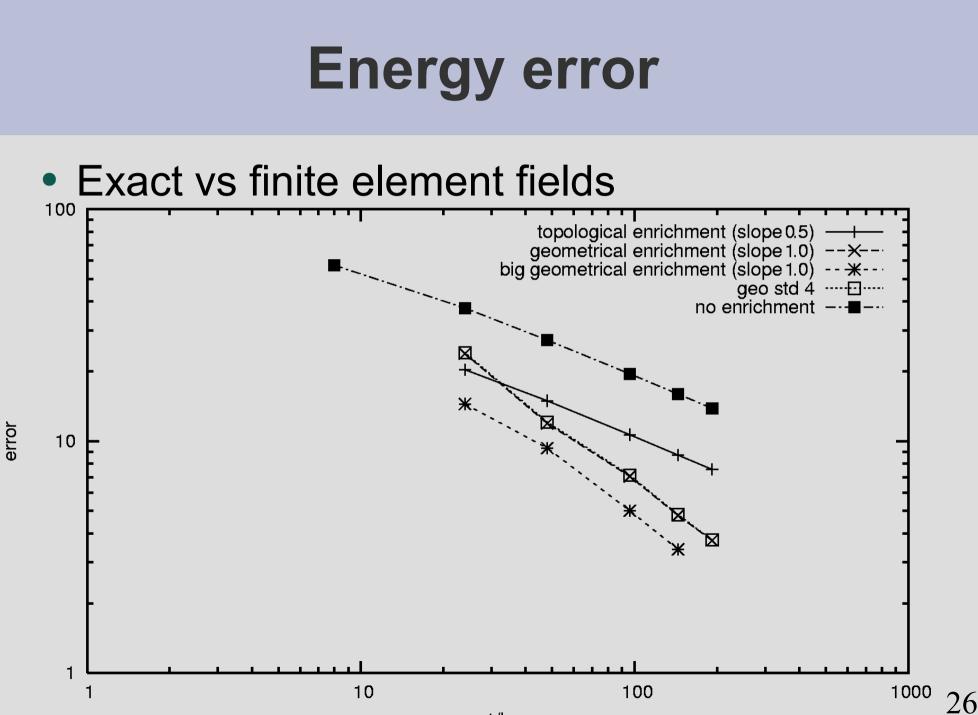
$$\int_{V} \sqrt{\frac{1}{2} (u_{i} - u_{i}^{ex})_{,j} c_{ijkl} (u_{k} - u_{k}^{ex})_{,l}} + \frac{1}{2} (\varphi - \varphi^{ex})_{,i} \varepsilon_{ij} (\varphi - \varphi^{ex})_{,j} dV$$

#### • Energy norm

- comparison with standard crack tip enrichment
- Infinite body with embedded crack
- inclined material axes (30°)
- PZT4 orthotropic material

$$c = 10^{10} \begin{bmatrix} 14.02 & 7.892 & 7.565 & 0 & 0 & 0 \\ 7.892 & 14.02 & 7.565 & 0 & 0 & 0 \\ 7.565 & 7.565 & 11.58 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2.527 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2.527 & 0 \\ 0 & 0 & 0 & 0 & 0 & 3.064 \end{bmatrix} \qquad e = 10^{0} \begin{bmatrix} 0 & 0 & 0 & 0 & 13.0 & 0 \\ 0 & 0 & 0 & 13.0 & 0 & 0 \\ -5.268 & -5.268 & 15.44 & 0 & 0 & 0 \end{bmatrix}$$



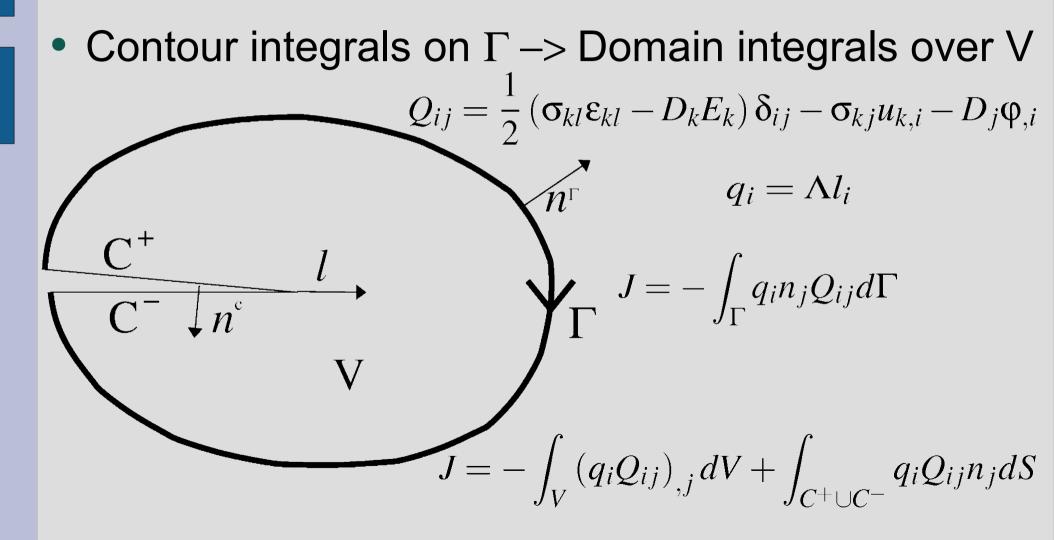


## **Energy error**

- The "classical" enrichment gives almost the same results as the specific enrichment, with less computational overhead.
- It is not clear whether different material laws (e.g. "more" anisotropic) lead to different results

$$g_i(r,\theta) = \left\{ \sqrt{r} \sin\frac{\theta}{2}, \sqrt{r} \cos\frac{\theta}{2}, \sqrt{r} \sin\frac{\theta}{2} \sin\theta, \sqrt{r} \cos\frac{\theta}{2} \sin\theta \right\}$$

## **SIFs computation**



# Interaction integrals

 Same procedure used to compute interaction integrals (no crack loading) :

$$I = \int_{V} q_{i,j} \left( \sigma_{kj} u_{k,i}^{aux} + \sigma_{kj}^{aux} u_{k,i} + D_{j} \varphi_{i,i}^{aux} + D_{j}^{aux} \varphi_{i,i} \right) dV$$
  
+ 
$$\int_{V} q_{i} \left( \sigma_{kj} u_{k,ij}^{aux} + \sigma_{kj,j}^{aux} u_{k,i} + D_{j} \varphi_{i,ij}^{aux} + D_{j,j}^{aux} \varphi_{i,i} \right) dV$$
  
- 
$$\int_{V} q_{i,j} \left( \sigma_{kl} \varepsilon_{kl}^{aux} - D_{k} E_{k}^{aux} \right) \delta_{ij} dV$$
  
- 
$$\int_{V} q_{i} \left( \sigma_{kl} \varepsilon_{kl,i}^{aux} - D_{k} E_{k,i}^{aux} \right) dV$$
  
$$I = \int_{\Gamma} G^{aux} \Lambda d\Gamma \quad G^{aux} = Y_{MN} K_{M} K_{N}^{aux} \qquad Y_{MN} K_{M} K_{N}^{aux} = \frac{I}{\int_{\Gamma} \Lambda d\Gamma}$$

# Interaction integrals

Relation between G and the K factors

- Simpler case of the isotropic elasticity well known

$$Y_{MN}K_{M}K_{N}^{aux} = \{K_{I}K_{II}K_{III}\} \begin{bmatrix} \frac{2(1-\nu^{2})}{E} & 0 & 0\\ 0 & \frac{2(1-\nu^{2})}{E} & 0\\ 0 & 0 & \frac{2(1+\nu)}{E} \end{bmatrix} \begin{cases} K_{I}^{aux}\\ K_{II}^{aux}\\ K_{III}^{aux} \end{cases} \}$$

- The Irwin matrix depends on the material orientation and is not explicitly known for piezos.

$$G^{aux1,aux2} = Y_{MN}K_M^{aux1}K_N^{aux2}$$
$$I^{aux1,aux2} = \int_{\Gamma} G^{aux1,aux2}\Lambda d\Gamma \quad Y_{MN}K_M^{aux1}K_N^{aux2} = \frac{I^{aux1,aux2}}{\int_{\Gamma}\Lambda d\Gamma}$$

# Interaction integrals

• By using the eigenfunction set, every term in the Irwin matrix can be determined

- for instance :  $\begin{cases} K_I^{aux1} = 1 K_{II}^{aux1} = 0 K_{III}^{aux1} = 0 K_{IV}^{aux1} = 0 \\ \{K_I^{aux2} = 0 K_{II}^{aux2} = 1 K_{III}^{aux2} = 0 K_{IV}^{aux2} = 0 \end{cases}$ 

I<sup>aux1,aux2</sup>

 $\int_{\Gamma} \Lambda d\Gamma =$ 

$$Y_{MN}K_M^{aux1}K_N^{aux2}$$

 $= Y_{12} = Y_{21}$ 

 No need of finite element support because the Irwin matrix is intrinsic (for a given material orientation)

$$I^{aux1,aux2} = \int_{\Gamma} q_{i}n_{j} \left( \sigma_{kj}^{aux1} u_{k,i}^{aux2} + \sigma_{kj}^{aux2} u_{k,i}^{aux1} + D_{j}^{aux1} \phi_{,i}^{aux2} + D_{j}^{aux2} \phi_{,i}^{aux1} \right) d\Gamma - \int_{\Gamma} q_{i}n_{j} \frac{1}{2} \left( \sigma_{kl}^{aux1} \varepsilon_{kl}^{aux2} + \sigma_{kl}^{aux2} \varepsilon_{kl}^{aux1} - D_{k}^{aux1} E_{k}^{aux2} - D_{k}^{aux2} E_{k}^{aux1} \right) \delta_{ij} d\Gamma$$
31

# Choice of $\Lambda$

The field  $\Lambda$  describes the geometry of the integration domain *S*.

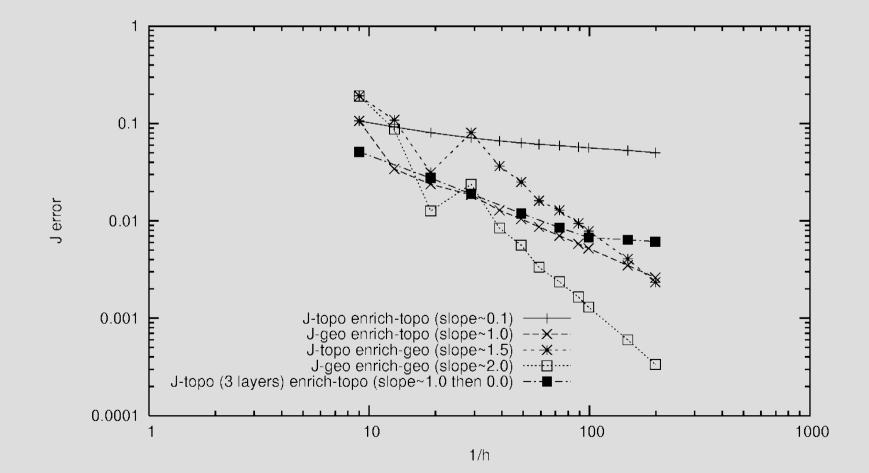
$$\Lambda = \sum_{i} N_i \Lambda_i \qquad \Lambda_i = \begin{cases} 1 & \text{if } support(N_i) \subset S \\ 0 & \text{otherwise} \end{cases}$$

Two choices of integration domain with regard to *h*:

- Topological
- Geometrical

#### J error

Exact J vs computed J-integral



# **Conclusion & future work**

- Application of the X-Fem for piezos
- The convergence study shows that the four classical enrichment functions are enough
- Use of equivalement volume integrals to compute the electromechanical J-integral
- Interaction integrals will be used to extract K factors
- Auxiliary fields can also be used to compute the local Irwin matrix

# **Conclusion & future work**

- Systematic investigations of J and the K factors's accuracy
- Propagation laws
- Investigation for a electrically permeable crack
- 3D extensions (esp. for the eigenfunctions needed for K extraction)