

APPLICATIONS OF RESAMPLING METHODS IN ACTUARIAL PRACTICE

RICHARD A. DERRIG, KRZYSZTOF M. OSTASZEWSKI,
AND GRZEGORZ A. REMPALA

Abstract

Actuarial analysis can be viewed as the process of studying profitability and solvency of an insurance firm under a realistic and integrated model of key input random variables such as loss frequency and severity, expenses, reinsurance, interest and inflation rates, and asset defaults. Traditional models of input variables have generally fitted parameters for a predetermined family of probability distributions. In this paper we discuss applications of some modern methods of non-parametric statistics to modeling loss distributions, and possibilities of using them for modeling other input variables for the purpose of arriving at an integrated company model. Several examples of inference about the severity of loss, loss distributions percentiles and other related quantities based on data smoothing, bootstrap estimates of standard error and bootstrap confidence intervals are presented. The examples are based on real-life auto injury claim data and the accuracy of our methods is compared with that of standard techniques. Model adjustment for inflation and bootstrap techniques based on the Kaplan–Meier estimator, useful in the presence of policies limits (censored losses), are also considered.

ACKNOWLEDGEMENT

The last two authors graciously acknowledge support from the Actuarial Education and Research Fund.

1. INTRODUCTION

In modern analysis of the financial models of property-casualty companies the input variables can be typically classified into financial variables and underwriting variables (e.g., see D'Arcy, Gorvett, Herbers and Hettinger [6]). The financial variables generally refer to asset-side generated cash flows of the business, and the underwriting variables relate to the cash flows of the liabilities side. The process of developing any actuarial model begins with the creation of probability distributions of these input variables, including the establishment of the proper range of values of input parameters. The use of parameters is generally determined by the use of parametric families of distributions. Fitting of those parameters is generally followed either by Monte Carlo simulation together with integration of all inputs for profit testing and optimization, or by the study of the effect of varying the parameters on output variables in sensitivity analysis and basic cash flow testing. Thus traditional actuarial methodologies are rooted in parametric approaches, which fit prescribed distributions of losses and other random phenomena studied (e.g., interest rate or other asset return variables) to the data. The experience of the last two decades has shown greater interdependence of basic loss variables (severity, frequency, exposures) with asset variables (interest rates, asset defaults, etc.), and sensitivity of the firm to all input variables. Increased complexity has been accompanied by increased competitive pressures, and more frequent insolvencies. In our opinion, in order to properly address these issues one must carefully address the weaknesses of traditional methodologies. These weaknesses can be summarized as originating from either ignoring the uncertainties of inputs, or mismanaging those uncertainties. While early problems of actuarial modeling could be attributed mostly to ignoring uncertainty, we believe at this point the uncertain nature of model inputs is generally acknowledged. Note that Derrig and Ostaszewski [9] used fuzzy set techniques to handle the mixture of probabilistic and non-probabilistic uncertainties in asset/

liability considerations for property-casualty claims. In our opinion it is now time to proceed to deeper issues concerning the actual forms of uncertainty. The Central Limit Theorem and its stochastic process counterpart provide clear guidance for practical uses of the normal distribution and all distributions derived from it. But one cannot justify similarly fitting convenient distributions to, for instance, loss data and expect to easily survive the next significant change in the marketplace. What does work in practice, but not in theory, may be merely an illusion of applicability provided by powerful tools of modern technology. If one cannot provide a justification for the use of a parametric distribution, then a nonparametric alternative should be studied, at least for the purpose of understanding the firm's exposures. In this work, we will show such a study of nonparametric methodologies applied to loss data, and will advocate the development of an integrated company model with the use of nonparametric approaches.

1.1. Loss Distributions

We begin by addressing the most basic questions concerning loss distributions. The first two parameters generally fitted to the data are average claim size and the number of claim occurrences per unit of exposure. Can we improve upon these estimates by using nonparametric methods?

Consider the problem of estimating the severity of a claim, which is, in its most general setting, equivalent to modeling the probability distribution of a single claim size. Traditionally, this has been done by means of fitting some parametric models from a particular continuous family of distributions (e.g., see Daykin, Pentikainen, and Pesonen [7, Chapter 3]). While this standard approach has several obvious advantages, we should also realize that occasionally it may suffer some serious drawbacks:

- Some loss data has a tendency to cluster about round numbers like \$1,000, \$10,000, etc., due to rounding off the claim

amount and thus in practice follows a mixture of continuous and discrete distributions. Usually, parametric models simply ignore the discrete component in such cases.

- The data is often truncated from below or censored from above due to deductibles and/or limits on different policies. In particular, the presence of censoring, if not accounted for, may seriously compromise the goodness-of-fit of a fitted parametric distribution. On the other hand, trying to incorporate the censoring mechanism (which is often random in its nature, especially when we consider losses falling under several insurance policies with different limits) often leads to a creation of a very complex model which is difficult to work with.
- The loss data may come from a mixture of distributions depending upon some known or unknown classification of claim types.
- Finally, it may happen that the data simply does not fit any of the available distributions in a satisfactory way.

It seems, therefore, that there are many situations of practical importance where the traditional approach cannot be utilized, and one must look beyond parametric models. In this work we point out an alternative, nonparametric approach to modeling losses and other random parameters of financial analysis, originating from the modern methodology of nonparametric statistics based on *the bootstrap* or *resampling* method.

To keep things in focus we will be concerned here only with applications to modeling the severity of loss, but the methods discussed may be easily applied to other problems such as loss frequencies, asset returns, asset defaults, and the combination of variables into models of Risk Based Capital, Value at Risk, and general Dynamic Financial Analysis (DFA), including Cash Flow Testing and Asset Adequacy Analysis.

1.2. The Concept of Bootstrap

The concept of bootstrap was first introduced in the seminal piece of Efron [10], and relies on the consideration of the discrete empirical distribution generated by a random sample of size n from an unknown distribution F . This empirical distribution assigns equal probability to each sample item. In the discussion which follows, we will write \hat{F}_n for that distribution. By generating an independent, identically distributed (IID) random sequence (resample) from the distribution \hat{F}_n or its appropriately smoothed version, we can arrive at new estimates of various parameters and nonparametric characteristics of the original distribution F . This idea is at the very root of the bootstrap methodology. In particular, Efron [10] points out that the bootstrap gives a reasonable estimate of standard error for any estimator, and it can be extended to statistical error assessments and to inferences beyond biases and standard errors.

1.3. Overview of the Article

In this paper, we apply bootstrap methods to two data sets as illustrations of the advantages of resampling techniques, especially when dealing with empirical loss data. The basics of bootstrap theory are covered in Section 2, where we show its applications in estimating standard errors and calculating confidence intervals. In Section 3, we compare bootstrap and traditional estimators for quantiles and excess losses using some truncated wind loss data. The important concept of smoothing the bootstrap estimator is also covered in that section. Applications of bootstrap to auto bodily injury liability claims in Section 4 show loss elimination ratio estimates together with their standard errors in a case of lumpy and clustered data (the data set is enclosed in Appendix B). More complicated designs that incorporate data censoring and adjustment for inflation appear in Section 5. Sections 6 and 7 provide some final remarks and conclusions. The Mathematica 3.0 programs used to perform bootstrap calculations are provided in Appendix A.

2. BOOTSTRAP STANDARD ERRORS AND CONFIDENCE INTERVALS

As we have already mentioned in the previous section, the central idea of bootstrap lies in sampling the empirical cumulative distribution function (CDF) \hat{F}_n . This idea is closely related to the following, well-known statistical principle, henceforth referred to as the “plug-in” principle. Given a parameter of interest $\theta(F)$ depending upon an unknown population CDF F , we estimate this parameter by $\hat{\theta} = \theta(\hat{F}_n)$. That is, we simply replace F in the formula for θ by its empirical counterpart \hat{F}_n obtained from the observed data. The plug-in principle will not provide good results if \hat{F}_n poorly approximates F , or if there is information about F other than that provided by the sample. For instance, in some cases we might know (or be willing to assume) that F belongs to some parametric family of distributions. However, the plug-in principle and the bootstrap may be adapted to this latter situation as well. To illustrate the idea, let us consider a parametric family of CDF’s $\{F_\mu\}$ indexed by a parameter μ (possibly a vector), and for some given μ_0 , let $\hat{\mu}_0$ denote its estimate calculated from the sample. The plug-in principle in this case states that we should estimate $\theta(F_{\mu_0})$ by $\theta(F_{\hat{\mu}_0})$. In this case, bootstrap is often called parametric, since a resample is now collected from $F_{\hat{\mu}_0}$. Here and elsewhere in this work, we refer to any replica of θ calculated from a resample as “a bootstrap estimate of $\theta(F)$ ” and denote it by $\hat{\theta}^*$.

2.1. *The Bootstrap Methodology*

Bickel and Freedman [2] formulated conditions for consistency of bootstrap, which resulted in further extensions of Efron’s [10] methodology to a broad range of standard applications, including quantile processes, multiple regression and stratified sampling. They also argued that the use of bootstrap did not require theoretical derivations such as function derivatives, influence functions, asymptotic variances, the Edgeworth expansion, etc.

Singh [19] made a further point that the bootstrap estimator of the sampling distribution of a given statistic may be more accurate than the traditional normal approximation. In fact, it turns out that for many commonly used statistics the bootstrap is asymptotically equivalent to the one-term Edgeworth expansion estimator, usually having the same convergence rate, which is faster than the normal approximation. In many more recent statistical texts the bootstrap is recommended for estimating sampling distributions and finding standard errors and confidence sets. The extension of the bootstrap method to the case of dependent data was considered for instance by Künsch [15], who suggested a *moving block bootstrap* procedure which takes into account the dependence structure of the data by resampling blocks of adjacent observations rather than individual data points. More recently, Politis and Romano [16] suggested a method based on circular blocks (i.e., on wrapping the observed time series values around the circle and then generating the blocks of the bootstrap data from the circle's "arcs"). In the case of the sample mean this method, which is known as *circular bootstrap*, again was shown to accomplish the Edgeworth correction for dependent, stationary data.

The bootstrap methods can be applied to both parametric and non-parametric models, although most of the published research in the area is concerned with the non-parametric case since that is where the most immediate practical gains might be expected. Let us note though that a simple, non-parametric bootstrap may often be improved by other bootstrap methods taking into account the special nature of the model. In the IID non-parametric models, for instance, the smoothed bootstrap (bootstrap based on some smoothed version of \hat{F}_n) often improves the simple bootstrap (bootstrap based solely on \hat{F}_n). Since in recent years several excellent books on the subject of resampling and related techniques have become available, we will not be particularly concerned here with providing all the details of the presented techniques, contenting ourselves with making appropriate ref-

erences to more technically detailed works. Readers interested in gaining some basic background in resampling are referred to Efron and Tibisharani [11]. For a more mathematically advanced treatment of the subject, we recommend Shao and Tu [17].

2.2. Bootstrap Standard Error Estimate

Arguably, one of the most important applications of bootstrap is to provide an estimate of the standard error of $\hat{\theta}$ ($se_F(\hat{\theta})$). It is rarely practical to calculate it exactly; instead, one usually approximates $se_F(\hat{\theta})$ with the help of multiple resamples. The approximation to the bootstrap estimate of standard error of $\hat{\theta}$ (or BESE) suggested by Efron [10] is given by

$$\hat{se}_B = \left\{ \sum_{b=1}^B [\hat{\theta}^*(b) - \hat{\theta}^*(\cdot)]^2 / (B - 1) \right\}^{1/2}, \tag{2.1}$$

where $\theta^*(\cdot) = \sum_{b=1}^B \hat{\theta}^*(b) / B$, B is the total number of resamples (each of size n) collected with replacement from the plug-in estimate of F (in the parametric or non-parametric setting), and $\hat{\theta}^*(b)$ is the original statistic $\hat{\theta}$ calculated from the b th resample ($b = 1, \dots, B$). By the law of large numbers

$$\lim_{B \rightarrow \infty} \hat{se}_B = \text{BESE}(\hat{\theta}),$$

and, for sufficiently large n , we expect

$$\text{BESE}(\hat{\theta}) \approx se_F(\hat{\theta}).$$

Let us note that B , the total number of resamples, may be as large as we wish since we are in complete control of the resampling process. It has been shown that for estimating the standard error, one should take B to be about 250, whereas for different resampled statistics this number may have to be significantly increased in order to reach the desired accuracy (see [11]).

2.3. *The Method of Percentiles*

Let us now turn to the problem of using the bootstrap methodology to construct confidence intervals. This area has been a major focus of theoretical work on the bootstrap, and several different methods of approaching the problem have been suggested. The “naive” procedure described below is not the most efficient one and can be significantly improved in both rate of convergence and accuracy. It is, however, intuitively obvious and easy to justify, and seems to be working well enough for the cases considered here. For a complete review of available approaches to bootstrap confidence intervals, see [11].

Let us consider $\hat{\theta}^*$, a bootstrap estimate of θ based on a re-sample of size n from the original sample X_1, \dots, X_n , and let G_* be its distribution function given the observed sample values

$$G_*(x) = P\{\hat{\theta}^* \leq x \mid X_1 = x_1, \dots, X_n = x_n\}.$$

Recall that for any distribution function F and $p \in (0, 1)$ we define the p th quantile of F (sometimes also called p th percentile) as $F^{-1}(p) = \inf\{x : F(x) \geq p\}$. The *bootstrap percentiles method* gives $G_*^{-1}(\alpha)$ and $G_*^{-1}(1 - \alpha)$ as, respectively, lower and upper bounds for the $(1 - 2\alpha)$ confidence interval for θ . Let us note that for most statistics $\hat{\theta}$, the distribution function of the bootstrap estimator $\hat{\theta}^*$ is not available. In practice, $G_*^{-1}(\alpha)$ and $G_*^{-1}(1 - \alpha)$ are approximated by taking multiple resamples and then calculating the empirical percentiles. In this case the number of resamples B is usually much larger than for estimating BESE; in most cases $B \geq 1000$ is recommended.

3. BOOTSTRAP AND SMOOTHED BOOTSTRAP ESTIMATORS VS TRADITIONAL METHODS

In making the case for the usefulness of bootstrap methodology in modeling loss distributions, we would first like to compare its performance with that of the standard methods of inference as presented in actuarial textbooks.

3.1. Application to Wind Losses: Quantiles

Let us consider the following set of 40 losses due to wind-related catastrophes that occurred in 1977. These data are taken from Hogg and Klugman [12], where they are discussed in detail in Chapter 3. The losses were recorded only to the nearest \$1,000,000 and data included only those losses of \$2,000,000 or more. For convenience they have been ordered and recorded below.

2, 2, 2, 2, 2, 2, 2, 2, 2, 2
 2, 2, 3, 3, 3, 3, 4, 4, 4, 5
 5, 5, 5, 6, 6, 6, 6, 8, 8, 9
 15, 17, 22, 23, 24, 24, 25, 27, 32, 43

Using this data set we shall give two examples illustrating the advantages of applying the bootstrap approach to modeling losses. The problem at hand is a typical one: assuming that all the losses recorded above have come from a single unknown distribution F , we would like to use the data to obtain some good approximation for F and its various parameters.

First, let us look at an important problem of finding the approximate confidence intervals for the quantiles of F . The standard approach to this problem relies on the normal approximation to the sample quantiles (order statistics). Applying this method, Hogg and Klugman [12] have found the approximate 95% confidence interval for the 0.85th quantile of F to be between X_{30} and X_{39} , which for the wind data translates into the observed interval (9,32). They also have noted that “this is a wide interval but without additional assumptions this is the best we can do.” Is that really true? To answer this question let us first note that in this particular case the highly skewed binomial distribution of the 0.85th sample quantile is approximated by a symmetric normal curve. Thus, it seems reasonable to expect that normal approximation could be improved here upon introducing some form of correction for skewness. In the standard normal

approximation theory this is usually accomplished by considering, in addition to the normal term, the first non-normal term in the asymptotic Edgeworth expansion of the binomial distribution. The resulting formula is messy and requires the calculation of a sample skewness coefficient, as well as some refined form of the continuity correction (e.g., see Singh [19]). On the other hand, the bootstrap has been known to make such a correction automatically (Singh [19]) and hence we could expect that a bootstrap approximation would perform better here.¹ Indeed, in this case (in the notation of Section 2) we have $\theta(F) = F^{-1}(0.85)$ and $\hat{\theta} = \widehat{F}_n^{-1}(0.85) \approx X_{(34)}$, the 34th order statistic, which for the wind data equals 23. For sample quantiles the bootstrap distribution G_* can be calculated exactly (Shao and Tu [17, p.10]) or approximated by an empirical distribution obtained from B resamples as described in Section 2. Using either method, the $(1 - 2\alpha)$ confidence interval calculated using the percentile method is found to be between $X_{(28)}$ and $X_{(38)}$ (which is also in this case the exact confidence interval obtained by using binomial tables). For the wind data this translates into the interval (8, 27), which is considerably shorter than the one obtained by Hogg and Klugman [12].

3.2. *The Smoothed Bootstrap and its Application to Excess Wind Losses*

As our second example, let us consider the estimation of the probability that a wind loss will exceed a \$29,500,000 threshold. In our notation that means that we wish to estimate the unknown parameter $(1 - F(29.5))$. A direct application of the plug-in principle gives the value 0.05, the nonparametric estimate based on relative frequencies. However, note that the same number is also an estimate for $(1 - F(29))$ and $(1 - F(31.5))$, since the relative

¹This turns out to be true only for a moderate sample size (here, 40); for a binomial distribution with large n (i.e., large sample size) the effect of the bootstrap correction is negligible. In general, the bootstrap approximation performs better than the normal approximation for large sample sizes only for continuous distributions.

frequency changes only at the threshold values present in reported data. In particular, since the wind data were rounded off to the nearest unit, the nonparametric method does not give a good estimate for any non-integer threshold. This problem with the same threshold value of \$29,000,000 was also considered in [12, Example 4 on p. 94 and Example 1 on p. 116]. As indicated therein, one reasonable way to deal with the non-integer threshold difficulty is to first fit some continuous curve to the data. The idea seems justified since the clustering effect in the wind data has most likely occurred due to rounding off the records. In their book Hogg and Klugman [12] have used standard techniques based on method of moments and maximum likelihood estimation to fit two different parametric models to the wind data: the truncated exponential with CDF

$$F_{\mu}(x) = 1 - e^{-(x-1.5)/\mu}, \quad 1.5 < x < \infty \quad (3.1)$$

for $\mu > 0$, and the truncated Pareto with CDF

$$F_{\alpha,\lambda}(x) = 1 - \left(\frac{\lambda}{\lambda + x - 1.5} \right)^{\alpha}, \quad 1.5 < x < \infty \quad (3.2)$$

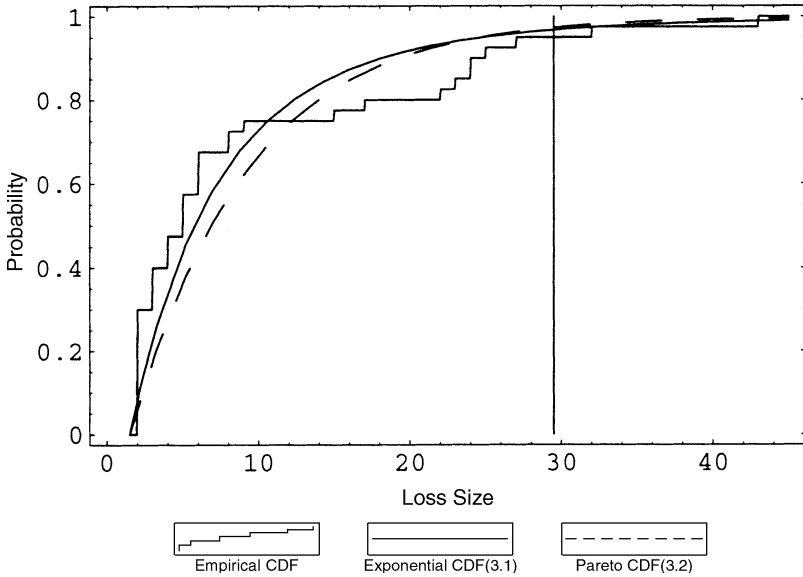
for $\alpha > 0, \lambda > 0$.

For the exponential distribution the method of moments estimator as well as maximum likelihood estimator (MLE) of μ was found to be $\hat{\mu} = 7.725$. The MLE's for the Pareto distribution parameters were $\hat{\lambda} = 28.998$ and $\hat{\alpha} = 5.084$; similar values were obtained using the method of moments.

The empirical distribution function for the wind data along with two fitted maximum likelihood models are presented in Figure 1. The solid smooth line represents the curve fitted from the exponential family (3.1), the dashed line represents the curve fitted from the Pareto family (3.2), and a vertical line is drawn for reference at $x = 29.5$. It is clear that the fit is not good at all, especially around the interval (16,24). The reason for the bad fit is the fact that both fitted curves are consistently concave down

FIGURE 1

EMPIRICAL AND FITTED CDF'S FOR WIND LOSS DATA



for all the x 's and F seems to be concave up in this area.² The fit in the tail seems to be much better.

Once we determine the values of the unknown model parameters, MLE estimators for $(1 - F(29.5))$ may be obtained from (3.1) and (3.2). The numerical values of these estimates, their respective variances and their 95% confidence intervals are summarized in the second and third row of Table 1. All the confidence intervals and variances for the first three estimates shown in the table are calculated using the normal theory approximation. The variance and confidence intervals for the fourth estimate based on the moving-average smoother are calculated by

²In practice, this drawback could be possibly remedied by fitting a mixture of the distributions shown in (3.1) and (3.2). However, this approach could considerably complicate the parametric model and seems unlikely to provide much improvement in the tail fit, which is of primary interest here.

TABLE 1
 COMPARISON OF THE PERFORMANCE OF ESTIMATORS FOR
 $(1 - F(29.5))$ FOR THE WIND DATA

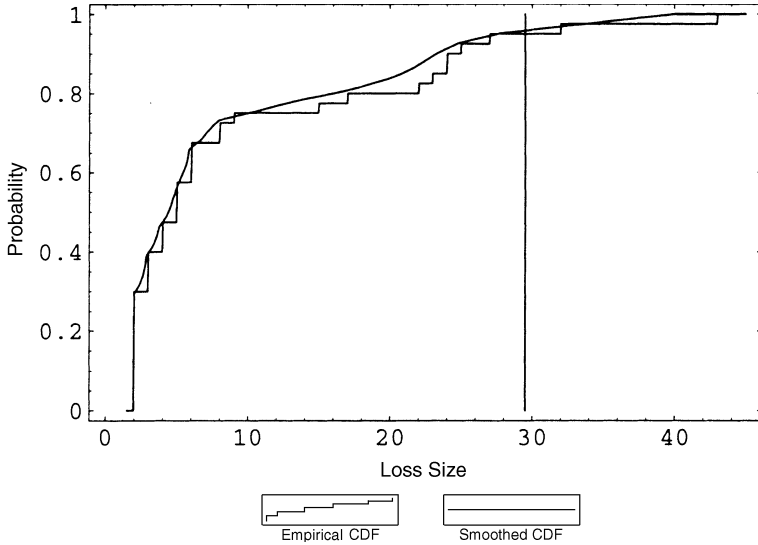
Fitted Model	Estimate of $(1 - F(29.5))$	Approx. s.e.	Approx. 95% c.i. (two sided)
Non-parametric (Plug-in)	0.05	0.034	(-0.019,0.119)
Exponential	0.027	0.015	(-0.003,0.057)
Pareto	0.036	0.024	(-0.012,0.084)
3-Step Moving Average Smoother	0.045	0.016	(0.013,0.079)

means of the approximate BESE and bootstrap percentile methods described in Section 2. In the first row the same characteristics are calculated for the standard non-parametric estimate based on relative frequencies. As we may well see, the respective values of the point estimators differ considerably from model to model and, in particular, both MLE's are quite far away from the relative frequency estimator. Another thing worth noticing is that the confidence intervals for all three models have negative lower bounds—they are obviously too long, at least on one side. This also indicates that their true coverage probability may in fact be greater than 95%.

In order to provide a better estimate of $(1 - F(29.5))$ for the wind data, we will first need to construct a smoothed version of the empirical CDF. In order to do so we employ the following data transformation widely used in image and signal processing theory, where a series of raw data $\{x_1, x_2, \dots, x_n\}$ is often transformed to a new series of data before it is analyzed. The purpose of this transformation is to smooth out local fluctuations in the raw data, so the transformation is called *data smoothing* or a *smoother*. One common type of smoother employs a linear transformation and is called a linear filter. A linear filter with weights $\{c_0, c_1, \dots, c_{r-1}\}$ transforms the given data to weighted averages $\sum_{j=0}^{r-1} c_j x_{t-j}$ for $t = r, r + 1, \dots, n$. Notice that the new data set has

FIGURE 2

EMPIRICAL AND SMOOTHED CDF'S FOR WIND LOSS DATA



length $(n - r - 1)$. If all the weights c_k are equal and they sum to unity, the linear filter is called an r -term moving average. For an overview of this interesting technique and its various applications, see Simonoff [18]. To create a smoothed version of the empirical CDF for the wind data, we have first used a three-term moving average smoother and then linearized in between any two consecutive data points.

The plot of this linearized smoother along with the original empirical CDF is presented in Figure 2. A vertical line is once again drawn for reference at $x = 29.5$. Let us note that the smoother follows the “concave-up-down-up” pattern of the data, which was not the case with the parametric distributions fitted from the families (3.1) and (3.2).

Once we have constructed the smoothed empirical CDF for the wind data, we may simply read the approximate value of

$(1 - F(29.5))$ off the graph (or better yet, ask the computer to do it for us). The resulting numerical value is 0.045. What is the standard error for that estimate? We again may use the bootstrap to answer that question without messy calculations. An approximate value for BESE (with $B = 1000$, but the result is virtually the same for $B = 100$) is found to be 0.016, which is only slightly worse than that of the exponential model MLE and much better than the standard error for the Pareto and empirical models. Equivalently, the same result may be obtained by numerical integration. Finally, the 95% confidence interval for $(1 - F(29.5))$ is found by means of the bootstrap percentile method with the number of replications set at $B = 1000$. Here the superiority of the bootstrap is obvious, as it gives an interval which is the second shortest (again exponential MLE model gives a shorter interval) but, most importantly, is bounded away from zero. The results are summarized in Table 1. Let us note that the result based on a smoothed empirical CDF and bootstrap dramatically improves that based on the relative frequency (plug-in) estimator and standard normal theory. It is perhaps of interest to note also that the MLE estimator of $(1 - F(29.5))$ in the exponential model is simply a parametric bootstrap estimator. For more details on the connection between MLE estimators and bootstrap, see [11].

4. CLUSTERED DATA

In the previous section we have assumed that the wind data were distributed according to some continuous CDF F . Clearly this is not always the case with loss data, and in general we may expect our theoretical loss distribution to follow some mixture of discrete and continuous CDF's.

4.1. *Massachusetts Auto Bodily Injury Liability Data*

In Appendix B we present the set of 432 closed losses due to bodily injuries in car accidents, under bodily injury liability (BI) policies reported in the Boston Territory (19) for calendar year

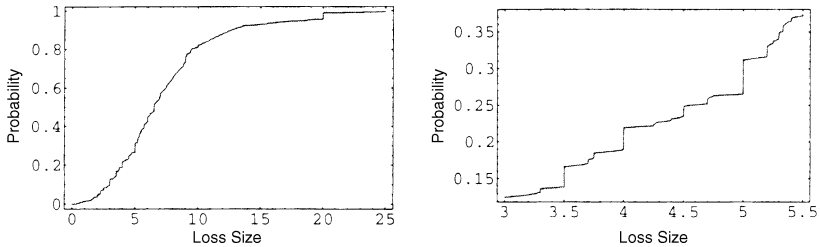
1995 (as of mid-1997). The losses are recorded in thousands and are subject to various policy limits but have no deductible. Policy limits capped 16 out of 432 losses which are therefore considered right-censored. The problem of bootstrapping censored data will be discussed in the next section; here we would like to concentrate on another interesting feature of the data. Massachusetts BI claim data are of interest because the underlying behavioral processes have been analyzed extensively. Weisberg and Derrig [20] and Derrig, Weisberg and Chen [8] describe the Massachusetts claiming environment after a tort reform as a “lottery” with general damages for non-economic loss (pain and suffering) as the prize. Cummins and Tennyson [5] showed signs of similar patterns countrywide, while Carroll, Abrahamse and Vaiana [3] and the Insurance Research Council [13] documented the pervasiveness of the lottery claims in both tort and no-fault state injury claim payment systems. The overwhelming presence of suspected fraud and buildup claims³ allow for distorted relationships between the underlying economic loss and the liability settlement. Claim negotiators can greatly reduce the “usual” non-economic damages when exaggerated injury and/or excessive treatment are claimed as legitimate losses. Claim payments in such a negotiated process with discretionary injuries tend to be clustered at some usual mutually-acceptable amounts, especially for the run-of-the-mill strain and sprain claims. Conners and Feldblum [4] suggest that the claim environment, rather than the usual rating variables, are the key elements needed to understand and estimate relationships in injury claim data. All the data characteristics above tend to favor empirical methods over analytical ones.

Looking at the frequencies of occurrences of the particular values of losses in Massachusetts BI claim data, we may see that several numerical values have especially high frequency. The loss

³In auto insurance, fraudulent claims are those in which there was no injury or the injury was unrelated to the accident, whereas buildup claims are those in which the injury is exaggerated and/or the treatment is excessive.

FIGURE 3

APPROXIMATION TO THE EMPIRICAL CDF FOR THE BI DATA ADJUSTED FOR THE CLUSTERING EFFECT



of \$5,000 was reported 21 times (nearly 5% of all the occurrences), the loss of \$20,000 was reported 15 times, \$6,500 and \$4,000 losses were reported 14 times, a \$3,500 loss was only slightly less common (13 times), and losses of size \$6,000 and \$9,000 occurred 10 times each. There were also several other numerical values that have occurred at least five times. The clustering effect is obvious here and it seems that we should incorporate it into our model. This may be accomplished for instance by constructing an approximation to the empirical CDF, which is linearized in between the observed data values except for the ones with high frequency, where it behaves like the original, discrete CDF. In Figure 3 we present such an approximate CDF for the BI data. We have allowed our adjusted CDF to have discontinuities at the observed values which occurred with frequencies of five or greater. The left panel of Figure 3 shows the graph plotted for the entire range of observed loss values (0,25). The right panel zooms in on the values from 3.5 to 5.5. Discontinuities can be seen here as the graph’s “jumps” at the observed loss values of high frequency: 3.5, 4, 4.5, 5.

4.2. *Bootstrap Estimates for Loss Elimination Ratios*

To give an example of statistical inference under this model, let us consider a problem of eliminating part of the BI losses

by purchasing a reinsurance policy that would cap the losses at some level d . Since the BI data is censored at \$20,000, we would consider here only values of d not exceeding \$20,000. One of the most important problems for the insurance company considering purchasing reinsurance is an accurate prediction of whether such a purchase would indeed reduce the experienced severity of loss and if so, by what amount. Typically this type of analysis is done by considering the loss elimination ratio (LER) defined as

$$\text{LER}(d) = \frac{E_F(X, d)}{E_F X}, \quad (4.1)$$

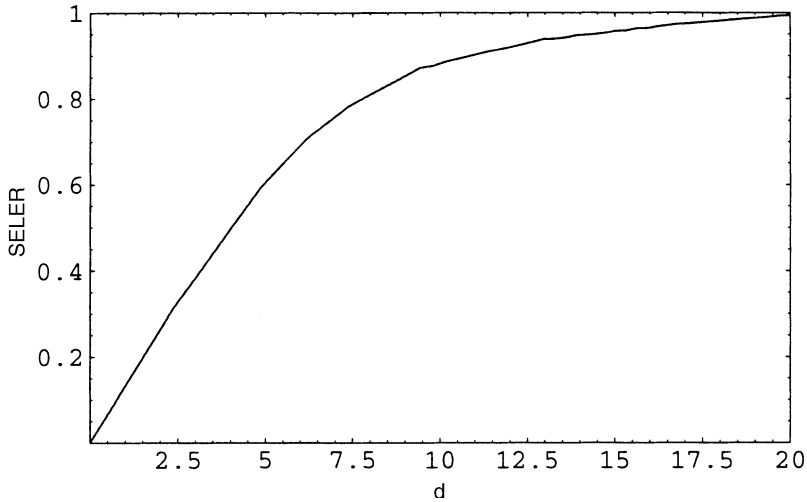
where $E_F X$ and $E_F(X, d)$ are, respectively, expected value and limited expected value functions for a random variable X following a true distribution of loss F . Since LER is only a theoretical quantity unobservable in practice, its estimate calculated from the data is needed. Usually, one considers the empirical loss elimination ratio (ELER) given by the obvious plug-in estimate

$$\text{ELER}(d) = \frac{E_{\widehat{F}_n}(X, d)}{E_{\widehat{F}_n} X} = \frac{\sum_{i=1}^n \min(X_i, d)}{\sum_{i=1}^n X_i}, \quad (4.2)$$

where X_1, \dots, X_n is a sample.

The drawback of ELER is in the fact that (unlike LER) it changes only at the values of d equal to the observed values of X_1, \dots, X_n . It seems, therefore, that in order to calculate an approximate LER at different values of d , some smoothed version of ELER (SELER) should be considered. SELER may be obtained from Equation 4.2 by replacing the empirical CDF \widehat{F}_n with its smoothed version, obtained for instance by applying a linear smoother (as for the wind data considered in Section 3) or a cluster-adjusted linearization. Obviously, the SELER formula may become quite complicated and its explicit derivation may be tedious (as would be the derivation of its standard error). Again, the bootstrap methodology can be applied here to facilitate the

FIGURE 4
 APPROXIMATE GRAPH OF SELER(d)



computation of an approximate value of SELER(d), its standard error and confidence interval for any given value of d . In Figure 4 we present the graph of the SELER estimate for the BI data calculated for the values of d ranging from 0 to 20 (lowest censoring point) by means of a bootstrap approximation. This approximation was obtained by resampling the cluster-adjusted, linearized version of the empirical CDF (presented in the left panel of Figure 3) a large number of times ($B = 300$) and replicating $\hat{\theta} = \text{SELER}$ each time. The resulting sequence of bootstrap estimates $\hat{\theta}^*(b)$ for $b = 1, \dots, B$ was then averaged to give the desired approximation of SELER. The calculation of standard errors and confidence intervals for SELER was done by means of BESE and the method of percentiles, as described in Section 2. The standard errors and 95% confidence intervals of SELER for several different values of d are presented in Table 2. The approximate BESE and bootstrap percentile methods

TABLE 2
VALUES OF SELER(d)

d	SELER(d)	Standard Error	95% Confidence Interval (two-sided)
4	0.505	0.0185	(0.488, 0.544)
5	0.607	0.0210	(0.597, 0.626)
10.5	0.892	0.0188	(0.888, 0.911)
11.5	0.913	0.0173	(0.912, 0.917)
14	0.947	0.0127	(0.933, 0.953)
18.5	0.985	0.00556	(0.98, 0.988)

described in Section 2 were used to calculate the standard errors and confidence intervals for the BI data in Table 2.

5. EXTENSIONS TO MORE COMPLICATED DESIGNS

So far in our account we have not considered any problems related to the fact that often in practice we may have to deal with truncated (e.g., due to deductible) or censored (e.g., due to policy limit) data. Another frequently encountered difficulty is the need for inflation adjustment, especially with data observed over a long period of time. We will address these important issues now.

5.1. Bootstrapping Censored Data for Policy Limits and Deductibles

Let us consider again the BI data presented in Section 4. There were 432 losses reported, of which 16 were at the policy limits.⁴ These 16 losses may therefore be considered censored from above (or right-censored), and the appropriate adjustment for this fact should be made in our approach to estimating the loss distribution F . Whereas 16 is less than 4% of the total number of observed losses for the BI data, these censored observations are crucial in order to obtain a good estimate of F for the large loss values.

⁴Fifteen losses were truncated at \$20,000 and one loss was truncated at \$25,000.

Since the problem of censored data arises naturally in many medical, engineering, and other settings, it has received considerable attention in statistical literature. For the sake of brevity we will limit ourselves to the discussion of only one of the several commonly used techniques, the so-called Kaplan–Meier (or product-limit) estimator.

The typical statistical model for right-censored observations replaces the usual observed sample X_1, \dots, X_n with the set of ordered pairs $(X_1, \delta_1), \dots, (X_n, \delta_n)$, where

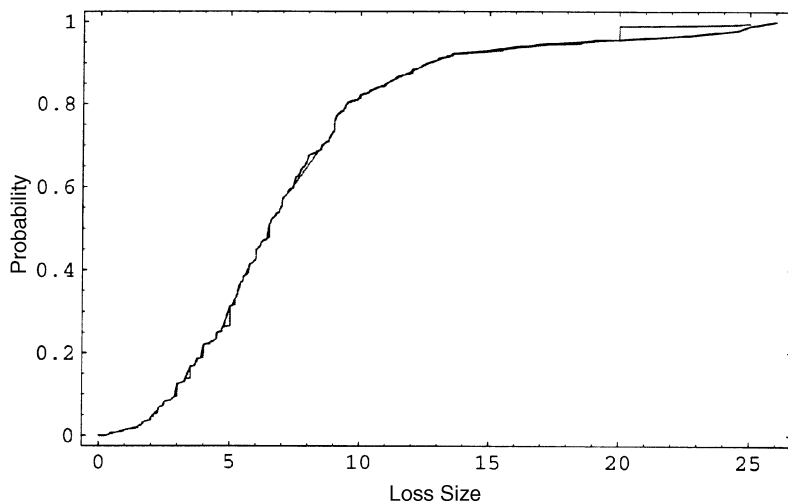
$$\delta_i = \begin{cases} 0 & \text{if } X_i \text{ is censored,} \\ 1 & \text{if } X_i \text{ is not censored} \end{cases}$$

and the recorded losses are ordered $X_1 = x_1 \leq X_2 = x_2 \leq \dots \leq X_n = x_n$ (with the usual convention that in the case of ties the uncensored values x_i ($\delta_i = 1$) precede the censored ones ($\delta_i = 0$)). The Kaplan–Meier estimator of $1 - F(x)$ is given by

$$\widehat{S}(x) = \prod_{i: x_i \leq x} \left(\frac{n-i}{n-i+1} \right)^{\delta_i}. \tag{5.1}$$

The product in the above formula is that of i terms, where i is the smallest positive integer less than or equal to n (the number of reported losses) and such that $x_i \leq x$. The Kaplan–Meier estimator, like the empirical CDF, is a step function with jumps at those values x_i that are uncensored. In fact, if $\delta_i = 1$ for all i , $i = 1, \dots, n$ (i.e., no censoring occurs), it is easy to see that Equation 5.1 reduces to the complement of the usual empirical CDF. If the highest observed loss x_n is censored, Equation 5.1 is not defined for the values of x greater than x_n . The usual practice is to then add one uncensored data point (loss value) x_{n+1} such that $x_n < x_{n+1}$, and to define $\widehat{S}(x) = 0$ for $x \geq x_{n+1}$. For instance, for the BI data the largest reported loss was censored at 25 and we had to add one artificial “loss” at 26 to define the Kaplan–Meier curve for the losses exceeding 25. The number 26 was picked quite arbitrarily; in actuarial practice a more precise guess of

FIGURE 5
THE KAPLAN–MEIER ESTIMATOR



the maximum possible value of loss (e.g., based on past experience) should be easily available. The Kaplan–Meier estimator enjoys several optimal statistical properties and can be viewed as a generalization of the usual empirical CDF adjusted for the case of censored losses. Moreover, truncated losses or truncated and censored losses may be easily handled by some simple modifications of Equation 5.1. For more details and some examples, see Klugman, Panjer and Willmot [14, Chapter 2].

In the case of loss data coming from a mixture of discrete and continuous CDF's as, for instance, the BI data, the linearization of the Kaplan–Meier estimator with adjustment for clustering seems to be appropriate. In Figure 5 we present the plots of a linearized Kaplan–Meier estimator for the BI data and the approximate empirical CDF function (which was discussed in Section 4), not corrected for the censoring effect. It is interesting to note that the two curves agree very well up to the first censoring point (20), where the Kaplan–Meier estimator starts to correct

for the effect of censoring. It is thus reasonable to believe that, for instance, the values of SELER calculated in Table 2 should be close to the values obtained by bootstrapping the Kaplan–Meier estimator. This, however, does not have to be the case in general. The agreement between the Kaplan–Meier curve and the smoothed CDF of the BI data is mostly due to the relatively small number of censored values. The estimation of other parameters of interest under the Kaplan–Meier model (e.g. quantiles, probability of exceedance, etc.) as well as their standard errors may be performed using the bootstrap methodology outlined in the previous sections. For more details on the problem of bootstrapping censored data, see Akritas [1].

5.2. Inflation Adjustment

An adjustment for the effect of inflation can be handled quite easily in our setting. If X is the random variable modeling the loss which follows CDF F , when adjusting for inflation we are interested in obtaining an estimate of the distribution of $Z = (1 + r)X$, where r is the uniform inflation rate over the period of concern. If Z follows a CDF G , then obviously

$$G(z) = F\left(\frac{z}{1+r}\right) \quad (5.1)$$

and the same relation holds when we replace G and F with the usual empirical CDF's or their smoothed versions.⁵ In this setting, bootstrap techniques described earlier should be applied to the empirical approximation of G .

6. SOME FINAL REMARKS

Although we have limited the discussion of resampling methods to the narrow scope of modeling losses, we have presented

⁵Subclasses of losses may inflate at different rates (soft tissue versus hard injuries for the BI data is an example). The theoretical CDF G may be then derived using multiple inflation rates as well.

only some examples of modern statistical methods relevant to the topic. Other important areas of application which have been purposely left out here include kernel estimation and the use of resampling in non-parametric regression and auto-regression models. The latter includes, for instance, such important problems as bootstrapping time-series data, modeling time-correlated losses and other time-dependent variables. Over the past several years some of these techniques, like non-parametric density estimation, have already found their way into actuarial practice (e.g., Klugman, Panjer and Willmot [14]). Others, like bootstrap, are still waiting. The purpose of this article was not to give a complete account of the most recent developments in non-parametric statistical methods, but rather to show by example how easily they may be adapted to real-life situations and how often they may, in fact, outperform the traditional approach.

7. CONCLUSIONS

Several examples of the practical advantages of the bootstrap methodology were presented. We have shown by example that in many cases the bootstrap technique provides a better approximation to the true parameters of the underlying distribution of interest than the traditional, textbook approach relying on the MLE and normal approximation theory. It seems that bootstrap may be especially useful in the statistical analysis of data which do not follow any obvious continuous parametric model (or mixture of models) or/and contain a discrete component (like the BI data presented in Section 4). The presence of censoring and truncation in the data does not present a problem for the bootstrap which, as seen in Section 5, may be easily incorporated into a standard non-parametric analysis of censored or truncated data. Of course, most of the bootstrap analysis is typically done approximately using a Monte Carlo simulation (generating resamples), which makes the computer an indispensable tool in the bootstrap world. Even more, according to some leading bootstrap theorists, automation is the goal

[11, p. 393]:

One can describe the ideal computer-based statistical inference machine of the future. The statistician enters the data...the machine answers the questions in a way that is optimal according to statistical theory. For standard errors and confidence intervals, the ideal is in sight if not in hand.

The resampling methods described in this paper can be used (possibly after correcting for time-dependence) to handle the empirical data concerning all DFA model input variables, including interest rates and capital market returns. The methodologies also apply to any financial intermediary, such as a bank or a life insurance company. It would be interesting, indeed it is imperative, to make bootstrap-based inferences in such settings and compare their effectiveness and applicability with classical parametric, trend-based, Bayesian, and other methods of analysis. The bootstrap computer program (using Mathematica 3.0 programming language; see Appendix A) that we have developed here to provide smooth estimates of an empirical CDF, BESE, and bootstrap confidence intervals could be easily adapted to produce appropriate estimates in DFA, including regulatory calculations for Value at Risk and Asset Adequacy Analysis. It would also be interesting to investigate further all areas of financial management where our methodologies may hold a promise of future applications. For instance, by modeling both the assets side (interest rates and capital market returns) and the liabilities side (losses, mortality, etc.), as well as their interactions (crediting strategies, investment strategies of the firm), one might create nonparametric models of the firm and use such a whole-company model to analyze value optimization and solvency protection in an integrated framework. Such whole company models are more and more commonly used by financial intermediaries, but we propose an additional level of complexity by adding the bootstrap estimation of their underlying random structures. This methodology is

immensely computationally intensive, but it holds great promise not just for internal company models but also for regulatory supervision, hopefully allowing for better oversight and avoiding problems such as the insolvencies of savings and loans institutions in the late 1980s, the insolvencies of life insurance firms such as Executive Life and Mutual Benefit, or the catastrophe-related problems of property-casualty insurers.

REFERENCES

- [1] Akritas, Michael G., "Bootstrapping the Kaplan–Meier Estimator," *Journal of the American Statistical Association* 81, 396, 1986, pp. 1032–1038.
- [2] Bickel, Peter J. and David A. Freedman, "Some Asymptotic Theory for the Bootstrap," *Annals of Statistics* 9, 6, 1981, pp. 1196–1217.
- [3] Carroll, Stephen J., Allan Abrahamse, and Mary Vaiana, *The Costs of Excess Medical Claims for Automobile Personal Injuries*, RAND, The Institute for Civil Justice, 1995.
- [4] Conners, John and Sholom Feldblum, "Personal Automobile: Cost, Drivers, Pricing, and Public Policy," *Casualty Actuarial Society Forum*, Winter 1997, pp. 317–341.
- [5] Cummins, J. David and Sharon Tennyson, "Controlling Automobile Insurance Costs," *Journal of Economic Perspectives* 6, 2, 1992, pp. 95–115.
- [6] D'Arcy, Stephen P., Richard W. Gorvett, Joseph A. Herbers, and T. E. Hettinger, "Building a Dynamic Financial Analysis Model that Flies," *Contingencies*, November/December 1997, pp. 40–45.
- [7] Daykin, Chris D., Teivo Pentikainen, and Martti Pesonen, *Practical Risk Theory for Actuaries*, London: Chapman and Hall, 1994.
- [8] Derrig, Richard A., Herbert I. Weisberg, and Xiu Chen, "Behavioral Factors and Lotteries Under No-Fault with a Monetary Threshold: A Study of Massachusetts Automobile Claims," *Journal of Risk and Insurance* 61, 2, 1994, pp. 245–275.
- [9] Derrig, Richard A. and Krzysztof M. Ostaszewski, "Managing the Tax Liability of a Property-Liability Insurer," *Journal of Risk and Insurance* 64, 1997, pp. 695–711.
- [10] Efron, Bradley, "Bootstrap: Another Look at Jackknife," *Annals of Statistics* 7, 1, 1979, pp. 1–26.

- [11] Efron, Bradley and Robert J. Tibshirani, *An Introduction to the Bootstrap*, New York: Chapman and Hall, 1993.
- [12] Hogg, Robert V. and Stuart A. Klugman, *Loss Distributions*, New York: John Wiley & Sons, Inc., 1984.
- [13] Insurance Research Council, *Fraud and Buildup in Auto Injury Claims—Pushing the Limits of the Auto Insurance System*, Wheaton, FL, 1996.
- [14] Klugman, Stuart A., Harry H. Panjer, and Gordon E. Willmot, *Loss Models: From Data to Decisions*, New York: John Wiley & Sons, Inc., 1998.
- [15] Künsch, Hans R., “The Jackknife and the Bootstrap for General Stationary Observations,” *Annals of Statistics* 17, 3, 1989, pp. 1217–1241.
- [16] Politis, D. and J. Romano, “A Circular Block-Resampling Procedure for Stationary Data,” *Exploring the Limits of Bootstrap (East Lansing, MI, 1990)*, New York: John Wiley & Sons, Inc., 1992, pp. 263–270.
- [17] Shao, Jian and Dong Sheng Tu, *The Jackknife and Bootstrap*, New York: Springer-Verlag, 1995.
- [18] Simonoff, Jeffrey S., *Smoothing Methods in Statistics*, New York: Springer-Verlag, 1997.
- [19] Singh, Kesar, “On the Asymptotic Accuracy of Efron’s Bootstrap,” *Annals of Statistics* 9, 6, 1981, pp. 1187–1195.
- [20] Weisberg, Herbert I. and Richard A. Derrig, “Massachusetts Automobile Bodily Injury Tort Reform,” *Journal of Insurance Regulation* 10, 1992, pp. 384–440.

APPENDIX A

MATHEMATICA BOOTSTRAP FUNCTIONS

The following computer program written in Mathematica 3.0 programming language was used to calculate bootstrap replications, bootstrap standard errors estimates (BESE) and bootstrap 95% confidence intervals using the method of percentiles.

(* Here we include the standard statistical libraries to be used in our bootstrapping program *)

```
<<Statistics'DataManipulation'
<<Statistics'ContinuousDistributions'
```

(* Here we define resampling procedure “boot” as well as empirical cdf functions: usual empirical cdf “empcdf” and its smoothed version “cntcdf”. Procedure “inv” is used by “boot” *)

(* Arguments for the procedures are as follows:

“boot” has two arguments: “lst” (any data list of numerical values) and , “nosam” (number of resamples, usually nosam=Length[lst]

“empcdf” and “cntcdf” both have two arguments “lst” (any data list of numerical values) and “x” -the numerical argument of function *)

```
inv[x_, lstx_] :=
Module[{nlx=Length[lstx]},
  If [x == 0 , lstx[[1]],
    If[x == 1, lstx[[nlx]], k=Floor[(nlx - 1) x];
      ((nlx - 1) x - k ) (lstx[[k+2]] -
lstx[[k+1]])+lstx[[k+1]]
    ]
  ]
];
```

```

boot[lx_, nosam_] := Module[{tt, i, a, n, lstx},
  lstx=Sort[lx]; n=Length[lx];
  lstx=Flatten[{{2 lstx[[1]] - lstx[[2]]},
  lstx, {2 lstx[[n]] - lstx[[n - 1]]}}];
  tt=RandomArray[UniformDistribution [0, 1], nosam];
  For[i=1, i <= nosam , i++, a[i] = inv[tt[[i]],
  lstx]];
  Table[a[i], {i, 1, nosam}]
  ];

cntcdf[lst_, x_] := Module[{ll=Sort[lst],
  n=Length[lst], i=1},
  ll=Flatten[{{2 ll[[1]] - ll[[2]]}, ll, {2 ll[[n]] -
  ll[[n - 1]]}}];
  While[i <= n+2 && x > ll[[i]], i++];
  If[i == 1, 0,
  If[i == n+3,
  1, ((x - ll[[i - 1]])/(ll[[i]] - ll[[i - 1]])+(i -
  2))/(n+1)]]
  ];

empcdf[lst_, x_] :=Module[{ll=Sort[lst], n=Length[lst],
  i=1},
  While[i <= n && x > ll[[i]], i++];
  If[i == 1, 0, (i - 1)/ n]
  ];

```

(* Here we define the bootstrap replications of statistic theta. Procedure “theta” calculates a statistic from the list of data “lst”. Procedure “replicate” replicates the statistic “theta” “norep” number of times using procedure “boot “ with parameters “lst” and “nosam”. As a result of this procedure we obtain a list of replicated values of “theta” *)

```
theta[lst_] := 1; (* define your Theta statistic here*)
```

```

replicate[lst_, norep_, nosam_] := Module[{i, ll = {}},
For [i=1, i <= norep, i++,
  ll = Flatten[{ll, theta[boot[lst, nosam]]}]
]; ll
];

```

(*Here we calculate BESE and 95% confidence interval based on the method of percentiles for 1000 replications *)

(* run “replicate” procedure, store the results in variable “listofrep” *)

```
listofrep=replicate[lst, norep, nosam];
```

```
(* BESE*)
```

```
Variance[listofrep]
```

```
(* 95% confidence interval for number of replications (norep)=
1000 *)
```

```
95ci = {listofrep[[25]], listofrep[[975]]}
```

Mathematica is a registered trademark of Wolfram Research, Inc.

APPENDIX B

MASSACHUSETTS BI DATA

The table below presents a set of 432 closed auto BI losses in Boston Territory (19) for calendar year 1995 (as of mid-1997). For each loss we have provided the injury type classification code along with the actual payment amount, as well as the corresponding policy limit. A description of the injury codes is provided on the last page of the appendix.

No.	Injury Type	Total Amount Paid	Policy Limit
1	5	\$393	\$20,000
2	1	\$500	\$20,000
3	6	\$500	\$20,000
4	8	\$900	\$20,000
5	6	\$1,000	\$20,000
6	5	\$1,000	\$20,000
7	5	\$1,250	\$20,000
8	5	\$1,500	\$20,000
9	5	\$1,500	\$20,000
10	5	\$1,525	\$20,000
11	5	\$1,631	\$100,000
12	4	\$1,650	\$20,000
13	5	\$1,700	\$20,000
14	5	\$1,700	\$20,000
15	5	\$1,800	\$20,000
16	5	\$1,950	\$20,000
17	5	\$2,000	\$20,000
18	5	\$2,000	\$25,000
19	5	\$2,007	\$20,000
20	5	\$2,100	\$20,000
21	5	\$2,100	\$20,000
22	5	\$2,100	\$20,000
23	5	\$2,250	\$20,000
24	5	\$2,250	\$20,000
25	5	\$2,250	\$20,000
26	5	\$2,250	\$20,000
27	5	\$2,270	\$20,000
28	5	\$2,300	\$20,000
29	6	\$2,300	\$20,000
30	5	\$2,375	\$20,000
31	5	\$2,450	\$20,000

No.	Injury Type	Total Amount Paid	Policy Limit
32	5	\$2,500	\$20,000
33	5	\$2,500	\$100,000
34	5	\$2,500	\$20,000
35	6	\$2,500	\$20,000
36	1	\$2,600	\$20,000
37	5	\$2,750	\$20,000
38	5	\$2,800	\$20,000
39	5	\$2,813	\$20,000
40	5	\$2,900	\$20,000
41	5	\$3,000	\$20,000
42	5	\$3,000	\$20,000
43	5	\$3,000	\$20,000
44	5	\$3,000	\$20,000
45	5	\$3,000	\$20,000
46	5	\$3,000	\$20,000
47	5	\$3,000	\$20,000
48	6	\$3,000	\$20,000
49	6	\$3,000	\$50,000
50	99	\$3,000	\$20,000
51	6	\$3,000	\$20,000
52	5	\$3,000	\$20,000
53	5	\$3,000	\$20,000
54	4	\$3,000	\$20,000
55	5	\$3,150	\$20,000
56	5	\$3,250	\$20,000
57	5	\$3,300	\$20,000
58	5	\$3,300	\$20,000
59	5	\$3,300	\$20,000
60	4	\$3,500	\$20,000
61	4	\$3,500	\$1,000,000
62	5	\$3,500	\$20,000
63	1	\$3,500	\$20,000
64	5	\$3,500	\$20,000
65	5	\$3,500	\$20,000
66	5	\$3,500	\$20,000
67	5	\$3,500	\$20,000
68	5	\$3,500	\$20,000
69	4	\$3,500	\$20,000
70	5	\$3,500	\$20,000
71	5	\$3,500	\$50,000
72	99	\$3,500	\$20,000
73	5	\$3,650	\$20,000
74	5	\$3,700	\$20,000
75	5	\$3,700	\$20,000
76	5	\$3,700	\$20,000

No.	Injury Type	Total Amount Paid	Policy Limit
77	5	\$3,750	\$20,000
78	5	\$3,750	\$20,000
79	5	\$3,750	\$20,000
80	5	\$3,750	\$20,000
81	6	\$3,900	\$20,000
82	5	\$4,000	\$20,000
83	5	\$4,000	\$1,000,000
84	5	\$4,000	\$20,000
85	5	\$4,000	\$20,000
86	5	\$4,000	\$20,000
87	4	\$4,000	\$20,000
88	6	\$4,000	\$20,000
89	5	\$4,000	\$20,000
90	5	\$4,000	\$20,000
91	5	\$4,000	\$20,000
92	5	\$4,000	\$20,000
93	5	\$4,000	\$20,000
94	1	\$4,000	\$20,000
95	5	\$4,000	\$25,000
96	5	\$4,250	\$20,000
97	6	\$4,250	\$20,000
98	6	\$4,278	\$50,000
99	5	\$4,396	\$25,000
100	5	\$4,400	\$20,000
101	5	\$4,476	\$20,000
102	5	\$4,500	\$20,000
103	5	\$4,500	\$20,000
104	5	\$4,500	\$25,000
105	5	\$4,500	\$20,000
106	10	\$4,500	\$20,000
107	5	\$4,500	\$20,000
108	5	\$4,521	\$20,000
109	5	\$4,697	\$20,000
110	5	\$4,700	\$20,000
111	5	\$4,700	\$20,000
112	5	\$4,700	\$20,000
113	4	\$4,725	\$20,000
114	5	\$4,750	\$20,000
115	5	\$5,000	\$20,000
116	5	\$5,000	\$100,000
117	5	\$5,000	\$20,000
118	5	\$5,000	\$20,000
119	5	\$5,000	\$20,000
120	5	\$5,000	\$20,000
121	5	\$5,000	\$20,000

No.	Injury Type	Total Amount Paid	Policy Limit
122	4	\$5,000	\$20,000
123	5	\$5,000	\$20,000
124	5	\$5,000	\$20,000
125	5	\$5,000	\$20,000
126	5	\$5,000	\$20,000
127	5	\$5,000	\$20,000
128	6	\$5,000	\$20,000
129	4	\$5,000	\$20,000
130	1	\$5,000	\$20,000
131	5	\$5,000	\$20,000
132	5	\$5,000	\$20,000
133	5	\$5,000	\$20,000
134	5	\$5,000	\$100,000
135	5	\$5,000	\$20,000
136	6	\$5,100	\$20,000
137	5	\$5,200	\$20,000
138	5	\$5,200	\$20,000
139	5	\$5,200	\$20,000
140	5	\$5,200	\$20,000
141	5	\$5,200	\$20,000
142	5	\$5,200	\$20,000
143	5	\$5,200	\$20,000
144	5	\$5,225	\$20,000
145	5	\$5,250	\$20,000
146	5	\$5,250	\$20,000
147	5	\$5,292	\$20,000
148	5	\$5,296	\$20,000
149	5	\$5,300	\$20,000
150	5	\$5,300	\$20,000
151	4	\$5,300	\$20,000
152	5	\$5,333	\$20,000
153	5	\$5,333	\$20,000
154	5	\$5,333	\$20,000
155	5	\$5,333	\$20,000
156	4	\$5,344	\$20,000
157	5	\$5,366	\$20,000
158	4	\$5,400	\$30,000
159	5	\$5,400	\$20,000
160	5	\$5,415	\$20,000
161	5	\$5,497	\$100,000
162	4	\$5,500	\$20,000
163	5	\$5,500	\$20,000
164	5	\$5,500	\$20,000
165	5	\$5,500	\$20,000
166	6	\$5,500	\$20,000

No.	Injury Type	Total Amount Paid	Policy Limit
167	5	\$5,566	\$20,000
168	5	\$5,600	\$25,000
169	5	\$5,714	\$20,000
170	5	\$5,714	\$20,000
171	5	\$5,714	\$20,000
172	5	\$5,714	\$20,000
173	5	\$5,714	\$20,000
174	5	\$5,714	\$20,000
175	5	\$5,714	\$20,000
176	5	\$5,725	\$20,000
177	6	\$5,750	\$20,000
178	5	\$5,750	\$100,000
179	5	\$5,750	\$20,000
180	5	\$5,852	\$20,000
181	6	\$5,898	\$20,000
182	5	\$5,900	\$20,000
183	5	\$5,964	\$20,000
184	6	\$5,990	\$20,000
185	5	\$6,000	\$25,000
186	5	\$6,000	\$20,000
187	5	\$6,000	\$20,000
188	5	\$6,000	\$20,000
189	1	\$6,000	\$20,000
190	5	\$6,000	\$20,000
191	5	\$6,000	\$20,000
192	5	\$6,000	\$20,000
193	5	\$6,000	\$20,000
194	5	\$6,000	\$20,000
195	4	\$6,077	\$20,000
196	5	\$6,078	\$20,000
197	5	\$6,131	\$20,000
198	5	\$6,166	\$20,000
199	5	\$6,166	\$20,000
200	5	\$6,169	\$20,000
201	5	\$6,171	\$20,000
202	5	\$6,208	\$20,000
203	5	\$6,243	\$20,000
204	5	\$6,318	\$20,000
205	5	\$6,399	\$20,000
206	5	\$6,413	\$20,000
207	5	\$6,500	\$20,000
208	5	\$6,500	\$20,000
209	5	\$6,500	\$20,000
210	5	\$6,500	\$20,000
211	5	\$6,500	\$20,000

No.	Injury Type	Total Amount Paid	Policy Limit
212	5	\$6,500	\$20,000
213	5	\$6,500	\$20,000
214	5	\$6,500	\$20,000
215	99	\$6,500	\$20,000
216	5	\$6,500	\$20,000
217	5	\$6,500	\$50,000
218	5	\$6,500	\$25,000
219	5	\$6,500	\$20,000
220	5	\$6,500	\$50,000
221	5	\$6,519	\$20,000
222	4	\$6,536	\$20,000
223	5	\$6,549	\$20,000
224	1	\$6,558	\$25,000
225	6	\$6,600	\$20,000
226	5	\$6,600	\$20,000
227	6	\$6,620	\$20,000
228	5	\$6,700	\$20,000
229	6	\$6,703	\$20,000
230	1	\$6,743	\$25,000
231	5	\$6,750	\$20,000
232	5	\$6,800	\$20,000
233	4	\$6,870	\$20,000
234	5	\$6,893	\$50,000
235	5	\$6,898	\$50,000
236	5	\$6,907	\$20,000
237	5	\$6,933	\$20,000
238	5	\$6,935	\$100,000
239	5	\$6,977	\$100,000
240	5	\$7,000	\$100,000
241	5	\$7,000	\$20,000
242	5	\$7,000	\$20,000
243	5	\$7,000	\$20,000
244	5	\$7,000	\$20,000
245	5	\$7,000	\$20,000
246	5	\$7,000	\$20,000
247	5	\$7,014	\$20,000
248	4	\$7,043	\$20,000
249	5	\$7,079	\$20,000
250	5	\$7,118	\$20,000
251	5	\$7,163	\$20,000
252	5	\$7,191	\$20,000
253	5	\$7,200	\$20,000
254	5	\$7,200	\$20,000
255	5	\$7,250	\$20,000
256	4	\$7,252	\$20,000

No.	Injury Type	Total Amount Paid	Policy Limit
257	5	\$7,304	\$20,000
258	1	\$7,412	\$25,000
259	1	\$7,425	\$100,000
260	5	\$7,432	\$20,000
261	5	\$7,444	\$50,000
262	5	\$7,447	\$20,000
263	5	\$7,500	\$20,000
264	5	\$7,500	\$20,000
265	5	\$7,500	\$25,000
266	5	\$7,500	\$20,000
267	5	\$7,500	\$20,000
268	5	\$7,500	\$20,000
269	99	\$7,500	\$20,000
270	1	\$7,564	\$20,000
271	5	\$7,620	\$20,000
272	18	\$7,629	\$20,000
273	5	\$7,657	\$20,000
274	1	\$7,670	\$20,000
275	5	\$7,671	\$20,000
276	4	\$7,696	\$100,000
277	4	\$7,700	\$100,000
278	5	\$7,750	\$20,000
279	5	\$7,754	\$20,000
280	5	\$7,820	\$20,000
281	4	\$7,859	\$20,000
282	5	\$7,868	\$20,000
283	1	\$7,873	\$25,000
284	5	\$7,920	\$100,000
285	5	\$7,922	\$20,000
286	5	\$7,945	\$20,000
287	5	\$7,954	\$20,000
288	5	\$7,961	\$20,000
289	5	\$8,000	\$100,000
290	5	\$8,000	\$100,000
291	5	\$8,000	\$20,000
292	10	\$8,013	\$50,000
293	5	\$8,073	\$20,000
294	5	\$8,200	\$20,000
295	1	\$8,298	\$25,000
296	6	\$8,300	\$20,000
297	1	\$8,420	\$20,000
298	5	\$8,485	\$20,000
299	5	\$8,500	\$50,000
300	5	\$8,500	\$20,000
301	99	\$8,500	\$20,000

No.	Injury Type	Total Amount Paid	Policy Limit
302	5	\$8,500	\$20,000
303	5	\$8,515	\$20,000
304	5	\$8,612	\$20,000
305	5	\$8,634	\$100,000
306	5	\$8,686	\$20,000
307	5	\$8,785	\$20,000
308	5	\$8,786	\$20,000
309	5	\$8,794	\$20,000
310	5	\$8,805	\$20,000
311	5	\$8,815	\$20,000
312	5	\$8,856	\$20,000
313	5	\$8,861	\$20,000
314	6	\$8,882	\$20,000
315	5	\$8,911	\$20,000
316	5	\$8,914	\$20,000
317	5	\$8,988	\$20,000
318	5	\$9,000	\$100,000
319	5	\$9,000	\$20,000
320	5	\$9,000	\$20,000
321	5	\$9,000	\$20,000
322	5	\$9,000	\$20,000
323	5	\$9,000	\$0
324	5	\$9,000	\$20,000
325	5	\$9,000	\$20,000
326	5	\$9,000	\$20,000
327	5	\$9,000	\$20,000
328	5	\$9,009	\$20,000
329	5	\$9,020	\$20,000
330	5	\$9,030	\$25,000
331	5	\$9,051	\$20,000
332	5	\$9,053	\$20,000
333	5	\$9,073	\$100,000
334	5	\$9,100	\$20,000
335	1	\$9,129	\$20,000
336	5	\$9,200	\$20,000
337	5	\$9,208	\$20,000
338	5	\$9,300	\$20,000
339	5	\$9,355	\$20,000
340	5	\$9,356	\$20,000
341	5	\$9,392	\$20,000
342	5	\$9,395	\$100,000
343	5	\$9,423	\$20,000
344	5	\$9,428	\$20,000
345	5	\$9,451	\$100,000
346	5	\$9,500	\$20,000

No.	Injury Type	Total Amount Paid	Policy Limit
347	5	\$9,500	\$20,000
348	5	\$9,602	\$20,000
349	5	\$9,710	\$20,000
350	4	\$9,881	\$25,000
351	5	\$9,909	\$20,000
352	8	\$10,000	\$20,000
353	6	\$10,000	\$20,000
354	5	\$10,000	\$100,000
355	6	\$10,000	\$20,000
356	4	\$10,106	\$20,000
357	5	\$10,229	\$20,000
358	5	\$10,330	\$20,000
359	5	\$10,331	\$20,000
360	5	\$10,400	\$20,000
361	5	\$10,505	\$100,000
362	4	\$10,555	\$20,000
363	1	\$10,645	\$20,000
364	8	\$10,861	\$20,000
365	5	\$10,968	\$20,000
366	5	\$11,000	\$50,000
367	4	\$11,000	\$100,000
368	5	\$11,032	\$20,000
369	5	\$11,144	\$20,000
370	5	\$11,166	\$20,000
371	1	\$11,262	\$25,000
372	5	\$11,344	\$50,000
373	99	\$11,353	\$20,000
374	5	\$11,385	\$20,000
375	1	\$11,500	\$20,000
376	5	\$11,626	\$20,000
377	5	\$11,835	\$20,000
378	99	\$11,986	\$20,000
379	5	\$11,991	\$20,000
380	4	\$12,000	\$20,000
381	5	\$12,000	\$20,000
382	5	\$12,000	\$20,000
383	5	\$12,214	\$100,000
384	5	\$12,274	\$20,000
385	5	\$12,374	\$20,000
386	99	\$12,380	\$20,000
387	3	\$12,500	\$20,000
388	5	\$12,509	\$20,000
389	5	\$12,621	\$100,000
390	5	\$12,756	\$20,000
391	5	\$12,859	\$20,000

No.	Injury Type	Total Amount Paid	Policy Limit
392	5	\$12,988	\$20,000
393	7	\$13,000	\$20,000
394	5	\$13,009	\$20,000
395	5	\$13,299	\$50,000
396	4	\$13,347	\$20,000
397	5	\$13,500	\$20,000
398	5	\$13,570	\$20,000
399	99	\$13,572	\$100,000
400	4	\$14,181	\$20,000
401	5	\$14,700	\$20,000
402	5	\$14,953	\$20,000
403	5	\$15,500	\$20,000
404	5	\$15,500	\$100,000
405	5	\$15,765	\$20,000
406	18	\$16,000	\$20,000
407	5	\$16,668	\$20,000
408	5	\$16,794	\$20,000
409	4	\$17,267	\$100,000
410	99	\$18,500	\$20,000
411	99	\$18,500	\$20,000
412	18	\$19,000	\$20,000
413	5	\$19,012	\$20,000
414	99	\$20,000	\$20,000
415	5	\$20,000	\$20,000
416	7	\$20,000	\$20,000
417	8	\$20,000	\$20,000
418	8	\$20,000	\$20,000
419	7	\$20,000	\$20,000
420	7	\$20,000	\$20,000
421	3	\$20,000	\$20,000
422	6	\$20,000	\$20,000
423	16	\$20,000	\$20,000
424	5	\$20,000	\$20,000
425	6	\$20,000	\$20,000
426	5	\$20,000	\$20,000
427	9	\$20,000	\$20,000
428	5	\$20,000	\$20,000
429	1	\$22,692	\$100,000
430	5	\$24,500	\$50,000
431	99	\$25,000	\$25,000
432	2	\$25,000	\$100,000

INJURY CODE DESCRIPTION

Injury Type	Description	Injury Type	Description
1	MINOR LACERATIONS/ CONTUSIONS	13	PARALYSIS/PARESIS
2	SERIOUS LACERATION	14	JAW JOINT DYSFUNCTION
3	SCARRING OR PERMANENT DISFIGUREMENT	15	LOSS OF A SENSE
4	NECK ONLY SPRAIN STRAIN	16	FATALITY
5	BACK OR NECK & BACK SPRAIN/STRAIN	17	DENTAL
6	OTHER SPRAIN/STRAIN	18	CARTILAGE/MUSCLE/TENDON/ LIGAMENT INJURY
7	FRACTURE OR WEIGHT BEARING BONE	19	DISC HERNIATION
8	OTHER FRACTURE	20	PREGNANCY RELATED
9	INTERNAL ORGAN INJURY	21	PRE-EXISTING CONDITION
10	CONCUSSION	22	PSYCHOLOGICAL CONDITION
11	PERMANENT BRAIN INJURY	30	NO VISIBLE INJURY
12	LOSS OF BODY PART	99	OTHER