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3 **Attributing Minds to Triangles: Kinematics and**
4 **Observer-Animator Kinematic Similarity predict Mental**
5 **State Attribution in the Animations Task**

6 Bianca A. Schuster^{1*}, Dagmar S. Fraser¹, Jasper J.F. van den Bosch¹, Sophie Sowden¹,
7 Andrew S. Gordon², Dongsung Huh³, and Jennifer L. Cook¹

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9 ¹ University of Birmingham, School of Psychology, Birmingham, B15 2TT, United Kingdom

10 ² University of Southern California, Institute for Creative Technologies, Los Angeles, CA
11 90094, United States

12 ³ MIT-IBM Watson AI Lab, Cambridge, MA 02142, United States

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15 **Author Notes**

16 Bianca Schuster: Orchid ID <https://orcid.org/0000-0001-5584-2078>

17 Correspondence concerning this article should be directed to Bianca Schuster

18 biancaschuster05@gmail.com

19

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26

27 **ABSTRACT**

28 The ability to ascribe mental states, such as beliefs or desires to oneself and other individuals
29 forms an integral part of everyday social interaction. One task that has been extensively used
30 to test mental state attribution in a variety of clinical populations is the animations task, where
31 participants are asked to infer mental states from short videos of interacting triangles. In this
32 task, individuals with clinical conditions such as autism spectrum disorders typically offer
33 fewer and less appropriate mental state descriptions than controls, however little is currently
34 known about why they show these difficulties. Previous studies have hinted at the similarity
35 between an observer's and the triangles' movements as a key factor for the successful
36 interpretation of these animations. In this study we present a novel adaptation of the animations
37 task, suitable to track and compare animation generator and -observer kinematics. Using this
38 task and a population-derived stimulus database, we demonstrate that an animation's
39 kinematics and kinematic similarity between observer and generator are integral for the correct
40 identification of that animation. Our results shed light on why some clinical populations show
41 difficulties in this task and highlight the role of participants' own movement and specific
42 perceptual properties of the stimuli.

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52 **Introduction**

53 Seminal work by Heider and Simmel¹ demonstrated that humans readily attribute
54 mental states to two triangles moving around a rectangular enclosure. Since their inception in
55 1944 such “animations tasks” (also referred to as Frith-Happé Animations² and Social
56 Attribution Task³) have grown dramatically in popularity and have been used in a wide variety
57 of clinical populations, including autism spectrum disorder (ASD)^{2,4}, Schizophrenia⁵,
58 antisocial personality disorder⁶, Huntington’s disease⁷ and Tourette’s syndrome⁸. Though
59 animations tasks have been scored and administered in a number of ways (Some studies count
60 the number of mental state terms used to describe the movements of the triangles^{2,4}, other
61 studies have asked participants to rate the type of interaction or the mental state word depicted
62 in the animations^{9,10}) it is generally agreed that “poor performance” indicates a problem with
63 identifying the triangles as mentalistic agents and ascribing appropriate mental states to them.
64 We refer to these processes here as ‘mental state attribution’.

65 Though mental state attribution has been found to be atypical across a range of clinical
66 populations, little is known about *why* some individuals struggle to attribute appropriate mental
67 states to the triangles. One explanation is that individuals who struggle with the animations
68 task would exhibit atypicalities in other tests of mental state attribution because of a deficit in
69 the ability to attribute minds and ascribe appropriate mental states. However, animations tasks
70 tend to be more sensitive to mental state attribution difficulties compared to other tests, as
71 shown by Abell et al.².

72 A recent study highlights that kinematic similarities between the triangles’ movements
73 and the participant’s own movements may influence performance on the animations task⁹.
74 Edey and colleagues asked autistic (‘condition-first’ terminology is used in line with the
75 majority preference expressed in a survey of the autistic community¹¹) and non-autistic
76 participants to complete the animations task, and also to produce their own animations using

77 triangles that could be moved around an enclosure with magnetic levers. The authors found
78 that animations produced by autistic individuals were more jerky (i.e. exhibited greater changes
79 in acceleration and deceleration) than those produced by non-autistic individuals. Furthermore,
80 whereas non-autistic participants could readily attribute mental states to animations created by
81 other non-autistic participants, they had difficulties attributing mental states to the jerky
82 animations that had been produced by the autistic participants. The authors proposed that
83 *movement similarity* significantly contributes to performance in the animations task: that is,
84 non-autistic individuals were better able to correctly identify animations created by other non-
85 autistic participants because the movement kinematics in the videos were similar to the
86 kinematics that they themselves would use to move the triangles. Conversely, autistic
87 participants in in Edey's study did not show improved performance when rating their own
88 group's relative to the control group's animations. The authors concluded that the increased
89 variability in jerk present within this group lead to a reduced number of animations sufficiently
90 similar to facilitate mentalizing performance in their autistic participants.

91 The proposal that movement similarity may affect performance in the animations task
92 is bolstered by recent empirical work showing that observers more accurately estimate a human
93 actor's underlying intentions when the kinematics of the actor's movements closely
94 approximate the observer's own movement kinematics¹². Furthermore, a role for movement
95 similarity in mental state attribution is in line with theoretical accounts suggesting that
96 inferences about others' actions are facilitated by mapping visual representations of others'
97 actions onto our own visual/motoric representations of the same actions¹³⁻¹⁶. The movement
98 similarity hypothesis would propose that mental state attribution difficulties in classic
99 animations tasks may, at least in part, be explained by differences between the way the triangles
100 are animated and the way an observer would move the triangles if required to create their own
101 animation. This raises the possibility that clinical groups might exhibit accurate mental state

102 attribution for animations where kinematics are matched to a participant's own movement
103 kinematics. To better understand why some individuals struggle to attribute appropriate mental
104 states in the animations task, the first aim of the current study was to test the hypothesis that a
105 significant amount of variance in performance in the animations task would be accounted for
106 by the kinematic jerkiness of the animation and the *similarity* between the kinematics of the
107 animation and a participant's own movements.

108 Kinematic jerk and movement similarity are not the only factors which plausibly
109 influence performance on the animations task. Previous studies have highlighted potential roles
110 for stimulus features including the rotation of, and distance between, the triangles¹⁷, and the
111 shape of the triangles' trajectories¹⁸. For instance, Roux et al. documented highly
112 distinguishable trajectory paths for random, goal-directed and mental state animations, thus
113 suggesting that trajectory path may be an important cue in mental state attribution.
114 Correspondingly, the second aim of the current study was to explore the extent to which a range
115 of other stimulus features, including trajectory shape, influence the ease with which
116 participants correctly attribute a mental state to an animation. By doing so, we shed light on a
117 multiplicity of factors which may explain why some clinical groups find the animations task
118 so challenging.

119 For this latter analysis we made use of the fact that, similar to a sound wave, a triangle's
120 trajectory comprises a complex wave and thus can be decomposed with Fourier transform and
121 represented as spectral density in different frequency bands¹⁹. In other words, Fourier transform
122 can be used to characterize the shape of a trajectory. For example, a trajectory which
123 approximately follows an elliptical orbit oscillates in speed and curvature twice during every
124 full rotation and consequently would be characterized by high spectral density in a band
125 centered around an angular frequency of two. Adapting a method developed by Huh &
126 Sejnowski we explored whether there are particular angular frequency bands which

127 differentiate mocking, seducing, surprising, following and fighting animations and whether
128 spectral density in these bands was predictive of accuracy.

129 Currently available animation task datasets are not suitable to test our hypotheses for
130 two reasons: First, having been created by experimenters or graphic designers, the stimuli in
131 these tasks typically represent a narrow range of kinematics and thus lack the variation
132 necessary for quantifying the contribution of kinematics and other stimulus features to
133 performance. Second, tasks to date offer no option to track animator (or observer) kinematics
134 at sufficient sampling rates to reliably make inferences about the role of movement similarity.
135 Here we created a novel animations database (available upon request) by asking 51 members
136 of the general population to animate two triangles to depict mental- (mocking, seducing,
137 surprising) and non-mental- (following, fighting) state interactions on a 133 Hz touch screen
138 device. Subsequently an independent sample of 37 members of the general population watched
139 a selection of videos from our new database. To ensure that participants were exposed to a
140 wide range of kinematics they watched 8 exemplars, for each word, ranging from slow to fast
141 speed. Participants rated the extent to which each animation depicted the words mocking,
142 seducing, surprising, following and fighting, in addition to also creating their own animation
143 for each word (Fig. 1). In a three-step analysis procedure, we first used Bayesian mixed effects
144 models to test our hypotheses that kinematic jerk and the similarity in kinematics between
145 observer and animator are significant predictors of the accuracy of mental state attributions
146 (*confirmatory analysis*). In a second step, we used Fast Fourier Transform (FFT) combined
147 with bootstrapped F-tests to investigate whether mocking, seducing, surprising, following and
148 fighting animations could be reliably distinguished according to the profile of spectral density
149 across a range of frequency bands (*exploratory analysis 1*). Finally, we employed random
150 forest analysis to determine the relative contribution to accuracy of a multiplicity of factors
151 including speed, acceleration, jerk, the amount of simultaneous movement of both triangles,

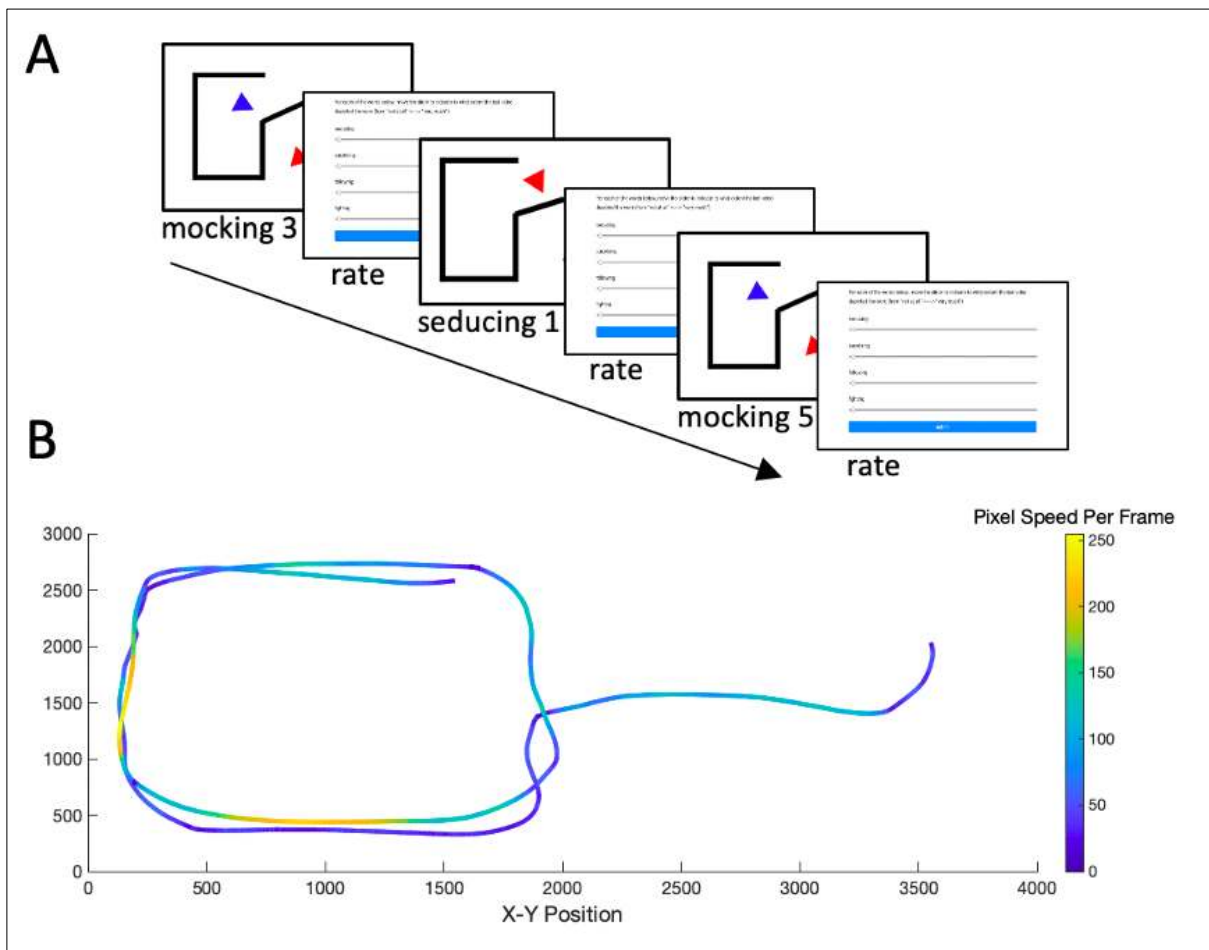
152 the relative distance between triangles, triangles' average rotation and the magnitude of
153 *spectral density* in the frequency bands identified in the second analysis step (*exploratory*
154 *analysis 2*).

155

156 **Figure 1**

157 (A) Schematic depiction of three successive trials in the animations task. (B) Example

158 trajectory of an animation stimulus.



159 *Note.* (A) 37 participants watched videos from the database and rated the extent to which each video depicted
160 mocking, seducing, surprising, following, or fighting. (B) Each participant used a touchscreen device to create
161 their own triangles animations. For each animation (both observed and generated by participants) we calculated
162 *jerk* as the mean of the third order non-null derivative of the raw positional data across all frames, movement
163 similarity was calculated as the difference in mean jerk between an animation stimulus and the participant's own
164 animation of the same word (*jerk difference*). Depicted is an example of a *following* animation (one triangle's
165 trajectory).

166

167

168 **Results**

169 Accuracy for each trial was calculated by subtracting the mean rating for all non-target
170 words from the rating for the target word (e.g., the target word was *seducing* on trials where
171 the participant watched a video wherein the original animator had attempted to depict the
172 triangles seducing each other). Consequently, a high, positive accuracy score for a seducing
173 animation indicates that an observer rated this animation as depicting seducing to a higher
174 extent than mocking, surprising, following or fighting. For a comparison of mean accuracy
175 scores for each word category see Supplementary Materials. For each video that participants
176 observed and for each animation that they created themselves, mean jerk magnitude (hereafter:
177 *jerk*) was obtained by taking the third order non-null derivatives of the raw positional data and
178 calculating the mean across all frames in the video. Movement similarity was calculated as the
179 difference in mean jerk between an animation stimulus and the participant's own animation of
180 the same word (hereafter: *jerk difference*), where lower difference values indicate higher
181 movement similarity (see **Methods: Data Analysis and Processing**).

182

183 **Mental state animations are rated less accurately than non-mental state animations**

184 The distinction between mental state and non-mental state, and the individual words to
185 depict these two conditions, are equivalent to the Theory of Mind and Goal-Directed conditions
186 used in the original paradigm by Abell et al.², and have since been widely used across the
187 literature^{4,9,10}. A Bayesian linear mixed effects model with the maximal random effects
188 structure allowed by the design²⁰ (random intercepts for *animation ID* (unique identifier for
189 each animation) and *subject ID*; random slopes for all fixed effects varying by *animation ID*
190 and *subject ID*) was fitted to jerk, jerk difference (lower values reflect higher movement
191 similarity) and the dummy-coded factor *mental state* (mental state [seducing, surprising,
192 mocking] versus non-mental state [following, fighting]) as well as their three-way interaction.

193 For all relevant model parameters, we report expected values (E_{μ}) under the posterior
194 distribution and their 95% credible intervals (CrIs)²¹, as well as the posterior probability that
195 an effect is different to zero ($P(E_{\mu} < 0) / P(E_{\mu} > 0)$). In line with Franke & Roettger²², if a
196 hypothesis states that an effect $E_{\mu} \neq 0$ (e.g. effect of movement similarity on accuracy), we
197 conclude there is compelling evidence for this effect if zero is not included in the 95% CrI of
198 E_{μ} and if the posterior probability $P(E_{\mu} \neq 0)$ is close to 1.

199 The model indicated that accuracy was higher in non-mental state videos relative to
200 mental state videos ($E\mu_{non-mental} = 2.54$, CrI= [1.81, 3.28]), with the posterior probability
201 that the effect is larger than zero being $P(E\mu_{non-mental} > 0) = 1$ (see Fig. 2 for prior and
202 posterior distributions of all estimated parameters).

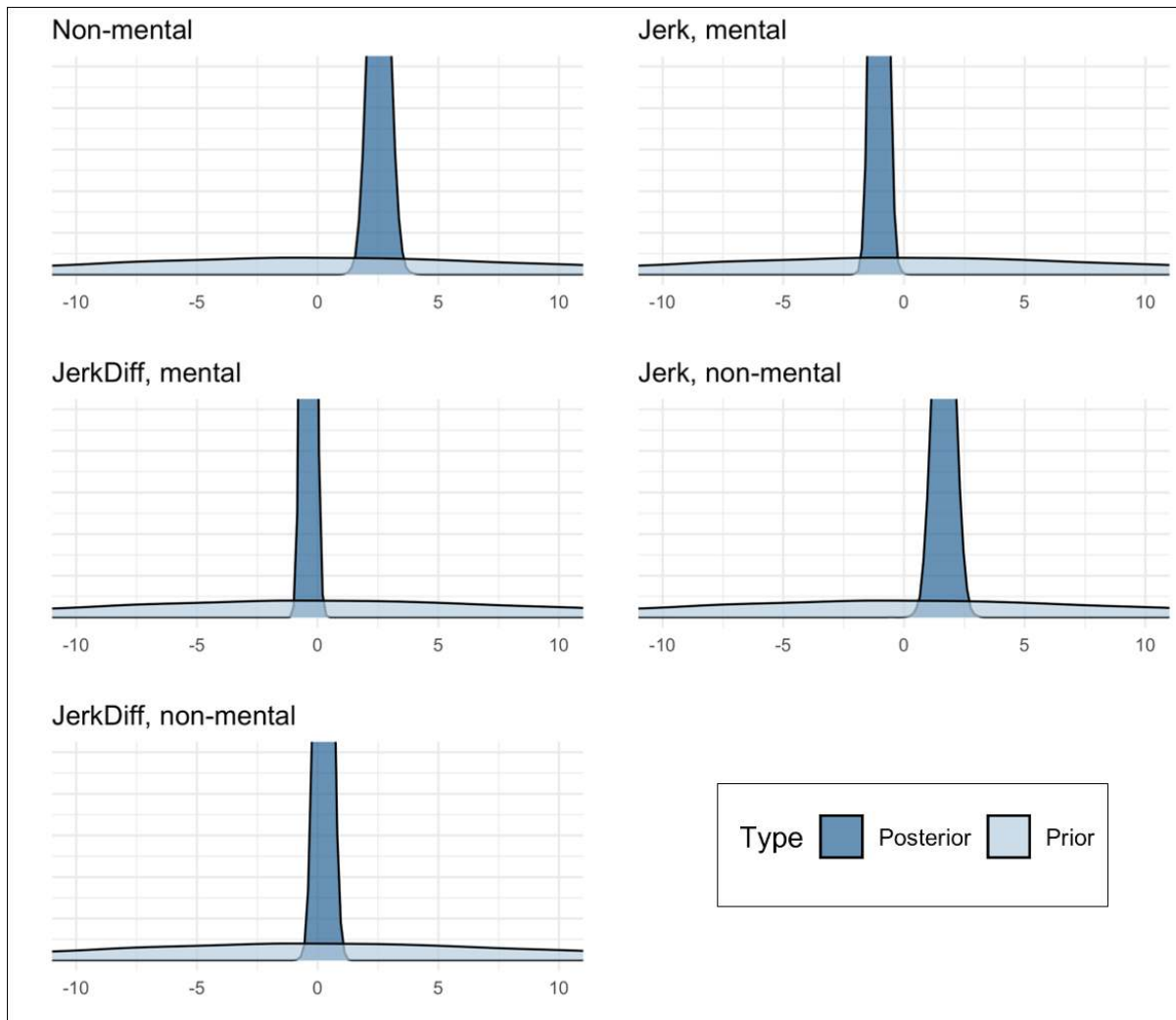
203

204 **Jerk affects performance differently for mental- and non-mental state animations**

205 In line with our hypothesis, accuracy was associated with mean jerk, furthermore jerk
206 interacted with mental state: For mental state animations, lower mean jerk was associated with
207 higher accuracy ($E\mu_{jerk,mental} = -1.03$, CrI = [-1.52, -0.53]), whereas in non-mental state
208 animations higher mean jerk led to higher accuracy scores ($E\mu_{jerk,non-mental} = 1.65$, CrI =
209 [0.88, 2.41]). Thus, while mental state animations with mean jerk values higher than 1 standard
210 deviation (SD) above the mean were rated 1.03 points less accurately, in non-mental state
211 animations higher jerk values increased accuracy by 1.65 points. Since the posterior
212 probabilities for both effects ($P(E\mu_{jerk,non-mental} > 0)$, $P(E\mu_{jerk,mental} < 0)$) were in fact 1,
213 we conclude that, given our model and the data, there is compelling evidence in favor of our
214 hypothesis that an animations' jerk impacts mental state attribution performance in the
215 animations task. To probe whether such effects varied as a function of the word depicted in the
216 video, we conducted separate exploratory models for non-mental state and mental state
217 animations for which we included *word category* (non-mental state: following, fighting; mental

218 **Figure 2**

219 *Prior and posterior probabilities of model parameters predicting accuracy*



220 *Note.* JerkDiff = *jerk difference*. For all regression coefficients, weakly informative priors were set as following
221 a normal distribution centered at 0 with an SD of 10.

222

223 state: mocking, seducing, surprising) as a predictor in addition to jerk and jerk difference.

224 These models revealed that, for non-mental state animations there was a strong negative effect

225 of jerk for fighting, but not following, animations ($E\mu_{jerk, fighting} = 1.88$, CrI = [0.67, 3.11],

226 $P(E\mu_{jerk, fighting} > 0) = 1$; $E\mu_{jerk, following} = 0.30$, CrI = [-0.30, 1.05]). For mental state

227 animations, the overall negative effect of jerk was driven by a tendency towards a negative

228 effect of jerk on accuracy in mocking and surprising animations ($E\mu_{jerk, mocking} =$

229 -0.58, CrI = [-1.56, 0.40]; $E\mu_{jerk,surprising} = -0.94$, CrI = [-2.69, 0.76]). There was no effect
230 of jerk in seducing animations ($E\mu_{jerk,seducing} = 0.26$, CrI = [-1.40, 1.85]).

231

232 **Higher observer-animator similarity in jerk is associated with higher accuracy only in** 233 **mental-state animations**

234 In line with our hypothesis, accuracy was also associated with jerk difference,
235 furthermore jerk difference interacted with mental state such that it was a significant predictor
236 for mental, but not non-mental, state videos. That is, for non-mental state animations the mean
237 of all posterior coefficients for jerk difference was centered near zero ($E\mu_{jerkDiff,non-mental}$
238 $= 0.25$, CrI = [-0.27, 0.76]). In contrast, for mental state animations the credible interval of jerk
239 difference did not include zero ($E\mu_{jerkDiff,mental} = -0.38$, CrI = [-0.72, -0.03]) and the
240 estimated probability of this effect being below zero ($P(E\mu_{jerkDiff,mental} < 0)$) was 0.98.
241 Thus, jerk difference had a negative effect on accuracy for mental state animations only.
242 Consequently, in mental state animations, *higher* movement similarity was associated with
243 higher accuracy. To probe whether such effects varied as a function of word category we
244 conducted an exploratory mixed model which included the word categories mocking, seducing
245 and surprising. This model revealed that jerk difference affected performance only in mocking
246 animations ($E\mu_{jerkDiff,mocking} = -0.70$, CrI = [-1.22, -0.18]; $P(E\mu_{jerkDiff,mocking} < 0) = 0.99$;
247 $E\mu_{jerkDiff,seducing} = 0.98$, CrI = [-0.49, 2.46]; $E\mu_{jerkDiff,surprising} = 0.63$, CrI = [-0.29, 1.52]).

248

249 **A combination of ten kinematic and spatial variables best predicts accuracy in the** 250 **animations task**

251 To investigate whether different triangle trajectories can reliably distinguish between
252 the five target words (i.e., mocking, seducing, surprising, following, fighting) we used FFT to
253 decompose the triangles' trajectories and represent them as an amplitude spectral density

254 profile across a range of angular frequencies. To test for differences, between the five target
255 words, in spectral density across the angular frequency range, bootstrapped F-tests (with 1000
256 boots) were performed (see **Methods: Data Analysis and Processing**). This analysis revealed
257 nine significant clusters, defined as clusters of difference that occurred in less than 5% of
258 comparisons with resampled distributions (see Figure 3A).

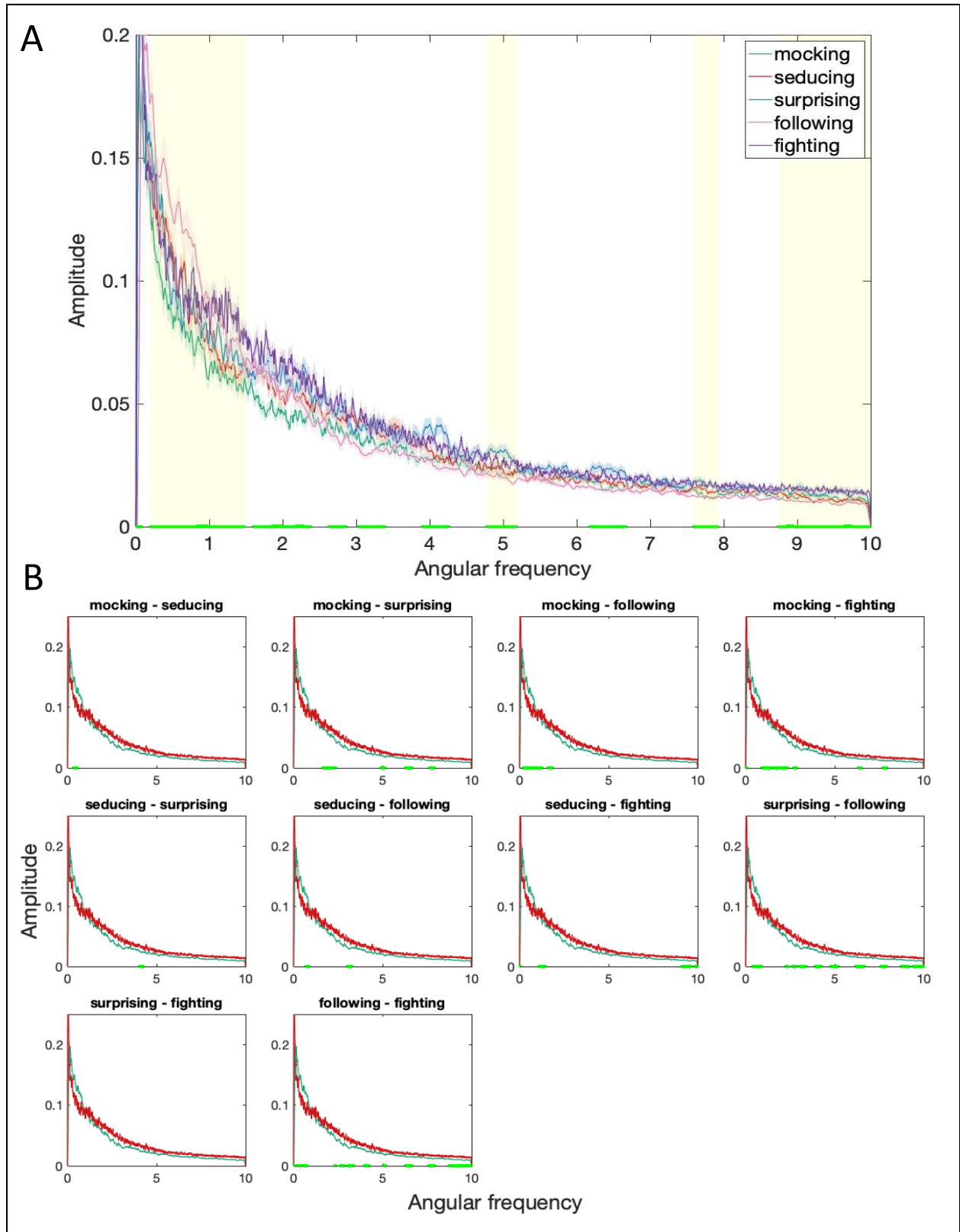
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260 To examine whether spectral density in these nine frequency clusters was predictive of
261 accuracy we used the maxima and minima of each significant cluster as bin edges and
262 calculated the *angular frequency spectral density (AFSD)* as the area under the curve between
263 the bin edges (cluster bin edges: 0.21 – 1.49, 1.61 – 2.39, 2.64 – 2.87, 3.04 – 3.40, 3.91 – 4.27,
264 4.79-5.19, 6.19-6.68, 7.6-7.93, 8.75-10). The relative contribution to accuracy of AFSD in bins
265 1-9 was assessed, alongside mental-state, speed, acceleration magnitude (hereafter:
266 *acceleration*), jerk, *simultaneous movement*, *relative distance* and *mean rotation*, by means of
267 a random forest model²³ using the *Boruta*²⁴ wrapper algorithm (version 7.7.0). Boruta trains a
268 random forest regression model on all variables as well as their permuted copies - so called
269 “shadow features” - and classes a variable as *important* when its permutation importance is
270 significantly higher than the highest permutation importance of a shadow feature (for more
271 details see **Methods: Exploratory analysis**). Note that because this analysis technique does
272 not account for random effects, values corresponding to the same animation were averaged
273 across participants, this permits indices such as jerk and acceleration which are features of a
274 particular animation but excludes jerk difference which depends on the relation between an
275 animation and an individual participant.

276 Out of all 16 variables tested, 10 were confirmed *important*, two were confirmed
277 *unimportant*, and four were classed as *tentative* on the basis that their permutation importance

278 was not significantly different from the maximal importance of a shadow feature (see Fig 4).
279 Fig 4 illustrates that the important role of mental-state and jerk in predicting accuracy is
280 confirmed by the random forest model, with mean importances of 16.0 and 7.82 respectively.
281 However, the model identifies a third variable as even more important than jerk: mean rotation
282 (mean importance = 11.78). In addition, an animation's acceleration and speed, AFSD in bins
283 1, 6, 9 and 8, as well as the amount of simultaneous movement of both triangles notably
284 contribute to explaining performance in the animations task (mean importances: acceleration
285 = 7.91; speed = 4.70; AFSD-bin 1 = 7.03, AFSD-bin 6 = 6.37, AFSD-bin 9 = 5.04, AFSD-bin
286 8 = 3.89; simultaneous movement = 4.74). A final model of all 10 important variables
287 predicting accuracy was evaluated by training a random forest on a subset of 70% of the data
288 (training set) and using it to predict the remaining 30% (test set). The regression model of the
289 training set predicting the test set was highly significant ($p < .001$) and indicated that the
290 selected variables explained 37% of accuracy values.

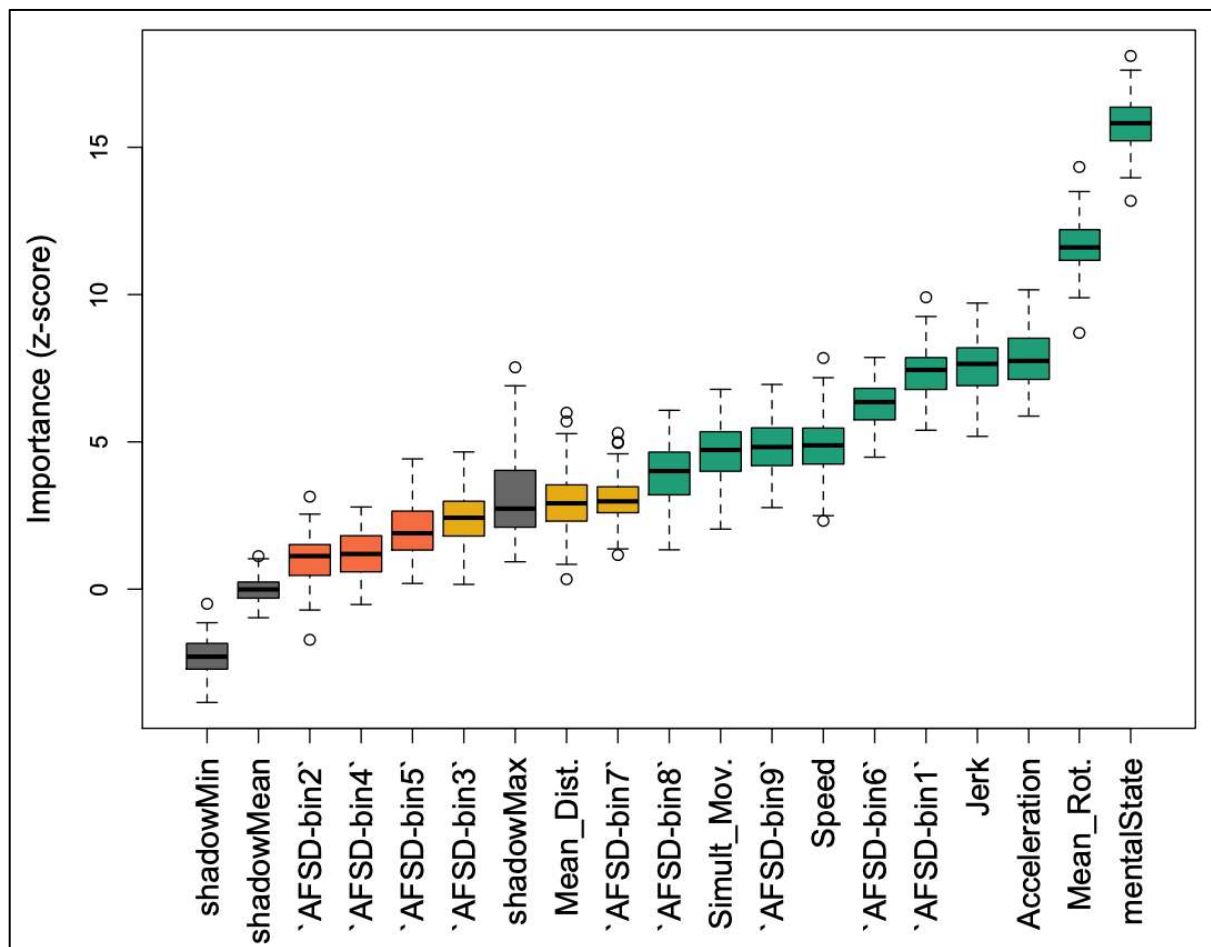
291 We subsequently conducted post hoc random forests separately for mental state- and
292 non-mental state animations. These post hoc analyses revealed that, in mental state animations,
293 five factors were predictive of accuracy, with jerk and acceleration being the most prominent
294 predictors, followed by speed, which was ranked third (see Supplementary Fig 2). In addition,
295 AFSD in bin 6 and simultaneous movement were classed as important in predicting accuracy.
296 In non-mental state animations, a total of eight predictors were identified as important
297 variables, with mean rotation being ranked highest by a considerable margin. In addition to
298 mean rotation, a combination of AFSD in bins 1, 6, 7 and 9, and acceleration, jerk and speed
299 were identified as important features of non-mental state animations.



Note. A) Solid colored lines represent spectral density as a function of angular frequency per word (=AFSD), the corresponding shaded areas represent 1 SEM (standard error of the mean) below and above the mean values. Yellow bars on x-axis represent clusters where AFSD significantly differs between mocking, seducing, surprising, following and fighting. Clusters that are predictive of accuracy are highlighted in yellow. Note that the lowest angular frequency derived from the data varied between 0.02 and 0.09, resulting in extrapolated values for some participants. For this reason, the first cluster of difference ranging from 0.02 to 0.09 was considered not representative of actual movements and disregarded. B) Post-hoc comparisons of AFSD.

302 **Figure 4**

303 *Random forest variable importances*



304 *Note.* Variable importances of all 16 features entered into the Boruta random forest, displayed as boxplots. Box
305 edges denote the interquartile range (IQR) between first and third quartile; whiskers denote 1.5 * IQR distance
306 from box edges; circles represent outliers outside of 1.5 * IQR above and below box edges. Box color denotes
307 decision: Green = confirmed, yellow = tentative, red = rejected; grey = meta-attributes shadowMin, shadowMax
308 and shadowMean (minimum, maximum and mean variable importance attained by a shadow feature).

309

310 **Discussion**

311 To better understand why some clinical groups find the animations task so challenging,
312 this study evaluated the relative contribution of jerk, jerk similarity and other stimulus
313 characteristics to mental state attribution performance. Our results confirm our hypothesis that
314 kinematic jerk and movement similarity are predictors of the accuracy of mental state
315 attribution. In addition, we highlight that stimulus features including the shape of the triangles'

316 trajectories and the amount of rotation of the triangles can also affect the ease with which
317 participants are able to appropriately label the target states.

318 In the first part of our three-step analysis, we found that mental state was the primary
319 predictor of animations task performance. Mental state videos were strongly associated with
320 lower accuracy, correspondingly non-mental state videos were rated more accurately. The
321 observation that our healthy participants performed worse when interpreting mental state
322 animations is inconsistent with previous findings. In Abell et al.'s and other studies, non-
323 autistic adult participants performed equally well on non-mental state and mental state
324 animations^{2,4,25}. It is possible that our findings illustrate a true difference in difficulty between
325 mental and non-mental state attribution that is revealed only when participants are presented
326 with a wide range of animation stimuli from a population-derived database. This difference
327 may have been overlooked because previous studies employed animations created by a single
328 graphic designer, or small group of experimenters and thus lack variation. However, this
329 possibility demands empirical testing. Indeed, a direct comparison between our paradigm and
330 previous studies is not possible due to task related differences (e.g., in indices of performance,
331 and number of words animated per condition).

332 In this first analysis step it was further revealed that the triangles' mean jerk in an
333 animation plays a substantial role in interpreting that animation. For mental state attributions
334 jerk was *negatively* predictive of accuracy, whereas for non-mental state animations jerk was
335 *positively* predictive of accuracy. Post hoc analyses revealed that this latter result was primarily
336 driven by fighting animations, and that the former was most notable with respect to mocking
337 and surprising animations (though caution is advised since credible intervals of coefficient
338 estimates did not exclude zero). In previous work, Edey and colleagues⁹ observed that non-
339 autistic participants were more accurate in their mental state attributions for animations
340 generated by non-autistic participants compared to those generated by autistic participants.

341 They also observed that animations generated by autistic participants were more jerky
342 compared to those generated by controls. However, in Edey et al.'s study there were a number
343 of additional dimensions along which the two groups' animations may have varied, making it
344 impossible to know whether the autistic participants' animations were difficult to interpret
345 *because of* the jerky kinematics. Our results show that jerk meaningfully contributes to the
346 accuracy of mental state attributions, thus our data supports the conclusion that jerk is highly
347 likely to be one of the driving factors in the group differences observed by Edey et al.

348 Our results also highlight kinematic similarity as a potential driving factor of the
349 differences observed by Edey et al.⁹. That is, we observed a positive relationship between
350 kinematic similarity and accuracy. Post hoc analyses revealed that evidence of this relationship
351 was particularly compelling in the case of mocking animations: The more closely a mocking
352 animation's mean jerk approximated the participant's own jerk when animating the same word
353 category, the more accurately that animation was rated. We speculate that Edey et al.'s non-
354 autistic participants performed poorly when attributing mental states to animations produced
355 by autistic individuals not only because these animations were jerky, but also because the
356 kinematics of the animations were *dissimilar* from the way in which the observer would have
357 produced the same animation.

358 The second aim of the current study was to explore the extent to which a range of other
359 stimulus features, including trajectory shape, influence mental state attribution accuracy. To
360 quantify trajectory shape we used FFT to decompose trajectories into spectral density in
361 angular frequency bins. Animation identity could be differentiated by AFSD in nine bins and
362 random forest analyses confirmed that four of these bins - bins 1, 6, 8 and 9 corresponding to
363 angular frequencies 0.2-1.5, 4.8-5.2, 7.6-7.9, 8.8-10 - were 'important' predictors of mental
364 state attribution accuracy. Relative to the other words, following animations had the highest
365 AFSD in the angular frequency range 0.2-1.5 (bin 1; Fig. 3). A high amount of AFSD in this

366 range indicates a trajectory characterized by complex doodle-like movements (See
367 Supplementary Fig. 3) with low angular-frequency oscillation in speed and curvature. Thus,
368 one may speculate that animations which are most easily identifiable as ‘following’ comprise
369 doodle-like triangle trajectories, with between 0.2 and 1.5 curvature oscillations per 2π radians.
370 In the angular frequency range 4.8-5.2 (bin 6), surprising animations had highest AFSD relative
371 to the other words (See Fig. 3). This angular frequency range centers around the pure-frequency
372 trajectory of a pentagon and thus is reflective of movements with around five speed-curvature
373 oscillations per 2π radians. Whilst our stimuli did not necessarily contain trajectories in the
374 shape of actual pentagons, high AFSD in bin 6 reflects curves and speed-curvature patterns
375 similar to those required to produce a closed-form pentagon. Finally, relative to the other
376 words, both surprising and fighting had high AFSD in angular frequency ranges 7.6-7.9 (bin
377 8) and 8.8-10 (bin 9). A high amount of AFSD in these ranges indicates trajectories
378 characterized by octagonal (bin 8) and decagonal shapes (See Fig. 4) with 8-10 speed-curvature
379 oscillations per rotation. Together these results clearly illustrate that trajectory shape comprises
380 an important cue with respect to the identity of the word that is depicted in an animation. At
381 present one can only speculate about why some shapes (e.g., pentagons) are more indicative of
382 particular mental/non-mental states (e.g., surprising).

383 For the third step in our three-part analysis, we employed random forests to ascertain
384 the relative contribution to accuracy of a range of stimulus features. The random forest
385 methodology was chosen for its robustness against (multi-)collinearity and suitability for
386 evaluating contributions of a large number of variables with limited data points²⁶. Our random
387 forest analysis confirmed ten features as important predictors of accuracy. In order of relative
388 importance these are: mental state, mean rotation, acceleration, jerk, trajectory shape (AFSD
389 in bins 1, 6, 8, 9), simultaneous movement of the triangles and speed. Post hoc analyses (see
390 Fig 3B) revealed that with respect to mental state attribution specifically, five of these features

391 were of confirmed importance: jerk, acceleration, speed, AFSD-bin 6 and simultaneous
392 movement. There was one feature which was uniquely important for mental state accuracy:
393 The amount of simultaneous movement of blue and red triangles. By decomposing the
394 animations task into features which predict accuracy, this random forest analysis deepens
395 understanding of individual differences in animations task performance and raises testable
396 empirical hypotheses for further research. For example, our analysis illustrates that
397 simultaneous movement of the triangles is a stimulus feature which predicts mental state
398 attribution accuracy. This observation raises the possibility that poor performance on the
399 animations task in some clinical groups may be related to differences in processing this
400 stimulus feature. That is, processing the simultaneous movement of the triangles requires
401 distributed attention to two objects simultaneously. It may be that individuals with some
402 clinical conditions exhibit a deficit in the perception of global relative to local motion stimuli
403 (e.g., autism²⁷) making it more difficult for them to process the simultaneous movement of two
404 triangles. Here we show that this perceptual processing style would impact selectively on the
405 accuracy of mental-, not non-mental-, state attributions.

406 Furthermore, our random forest analysis also raises interesting questions for further
407 study. Since the random forest technique does not account for random effects, values
408 corresponding to the same animation had to be averaged across participants, meaning that only
409 features of a particular animation (e.g., jerk, speed) could be included and indices such as
410 movement similarity, which depend on the *relation between* an animation and an individual
411 participant were excluded. Future experiments are therefore required to investigate whether,
412 similar to the jerk similarity effect we observed, there are also ‘similarity effects’ with respect
413 to features such as simultaneous movement and trajectory shape. One may hypothesize that
414 participants should be better able to infer mental states from animations which follow
415 trajectories that are similar to the shapes they would produce themselves. Such an analysis has

416 the potential to provide a clearer mechanistic understanding of atypical animations task
417 performance in clinical groups. For example, given differences in upper limb- and fine motor
418 control²⁸⁻³¹ autistic people may produce different trajectory shapes when creating their own
419 animations. It remains to be seen whether apparent mentalizing deficits in autism are
420 ameliorated when autistic people are provided with stimuli which match closely to features of
421 their own movement including trajectory shape as well as kinematics.

422 The present findings highlight particular kinematic- and trajectory features as being
423 critical for mental state attribution in the context of the animations task. This raises the
424 possibility that individual differences in mentalizing may be related to individual differences
425 in the perceptual processing of kinematics and trajectory information. Our findings further
426 show that kinematic similarity between observer and animator facilitates mental state
427 attribution. Consequently, individuals with certain clinical conditions might find the
428 animations task particularly difficult due to differences in perceptual processing and/or reduced
429 movement similarity. Our data paves the way for studies which empirically test whether
430 mentalizing deficits in clinical populations persist when participants are provided with stimuli
431 which closely match features (including kinematics, trajectory shape and amount of
432 simultaneous movement) of their own movements.

433

434 **Methods**

435 **Building the animations database**

436 *Animation Online Task*

437 We created a browser-based application that enables us to record and replay
438 participants' animations in the style of Heider & Simmel's original movies¹ while capturing
439 the triangles' positions at 133Hz. For this purpose, we adapted a web application developed by
440 Gordon & Roemmele (*The Heider-Simmel Interactive Theatre*³², <https://hsit.ict.usc.edu/>) to fit

441 our task design and allow instantaneous calculation of mean speed, acceleration and jerk
442 (change in acceleration), thus enabling the selection of stimuli according to predefined criteria
443 for replay. Gordon's web application employs scalable vector graphics (SVG) objects that
444 allow simultaneous translation and rotation of each object with input from a single finger per
445 object. To ensure object motion follows the direction of movement of the finger, and to
446 suppress sporadic rotations (which can occur if dragging is initiated too close to the object
447 center), object motion is suppressed until the pointer is dragged sufficiently far away from the
448 center point (see <https://asgordon.github.io/rotodrag-js/> for a more detailed description of the
449 library used for this application).

450

451 ***Participants***

452 We asked 51 healthy volunteers (46 females, mean (M) [SD] age = 20.23 [2.71]
453 years, range 18-34 years) to animate two triangles in order to depict three mental state
454 (mocking, seducing, surprising) and two non-mental state (following, fighting) words.
455 Participants were recruited from the University of Birmingham research participation
456 scheme, gave written informed consent and received either course credit or money (£8 per
457 hour) for their participation. All experimental procedures were conducted in line with the
458 WMA declaration of Helsinki³³ and approved by the University of Birmingham Research
459 Ethics Committee (ERN 16-0281AP5).

460

461 ***Procedure***

462 Data was collected at the University of Birmingham. Individuals were seated in front
463 of a WACOM Cintiq 22 HD touch screen, tilted at an angle of approximately 30 degrees
464 upon the desk. They were presented with the starting frame, comprising a black rectangular
465 enclosure and two equally sized equilateral triangles (one red and one blue) on a white

466 background (see Supplementary Figure 4). In a 45-second-long practice phase, participants
467 familiarized themselves with how to use their finger movements in order to navigate the
468 triangles around the screen. Participants were subsequently instructed to ‘*represent certain*
469 *words by moving the triangles around the screen*’, assured they could move the triangles in
470 any way they saw fit and encouraged to use their index fingers on both the left and right hand
471 to move the triangles simultaneously (for a complete transcript of task instructions see
472 Supplementary Materials). A dictionary was provided in case participants did not know the
473 word in question. No further explanations were given.

474 Following instructions, participants were presented with the first word and a 30-second-
475 long presentation of the stationary starting frame, allowing participants to plan their subsequent
476 animation of that word. Finally, individuals were given 45 seconds to animate the given word.
477 This process was repeated for the total of five words (mocking, seducing, surprising, following,
478 fighting) and on each trial participants were given the option to discard and repeat their
479 animations if they were unhappy with the result. Only the final animations were analyzed.

480

481 ***Stimulus Selection***

482 Our procedure resulted in a total of 255 animations (51 for each word), recorded at a
483 frame rate of 133 frames / second. Animations were then visually inspected for sufficient length
484 and movement coverage of more than two quadrants of the screen. 53 animations failed these
485 quality control checks. The final stimulus set comprised 202 animations (42 mocking, 38
486 seducing, 36 surprising, 44 following, 42 fighting).

487

488

489 **Ratings Collection**

490 ***Participants***

491 Thirty-seven healthy volunteers (31 females, M [SD] age = 21.30 [2.68] years, range =
492 18-32 years) were recruited from the University of Birmingham Research Participation Scheme
493 and gave written informed consent to participate in this study. Post-hoc power calculations
494 based on an online application by Judd et al.³⁴
495 (https://jakewestfall.shinyapps.io/two_factor_power/) confirmed that this study had 91.2 %
496 power to find an effect of size Cohen's d (d) = 0.4 for the main hypothesis (1). An a priori
497 power analysis of the complete study was not performed due to the lack of applications
498 available to estimate effect sizes for the present analyses (a mixed effects model with more
499 than one fixed effect). Participants received either course credit or money (£8 per hour) for
500 their participation. None of the participants had previously taken part in stimulus development.

501

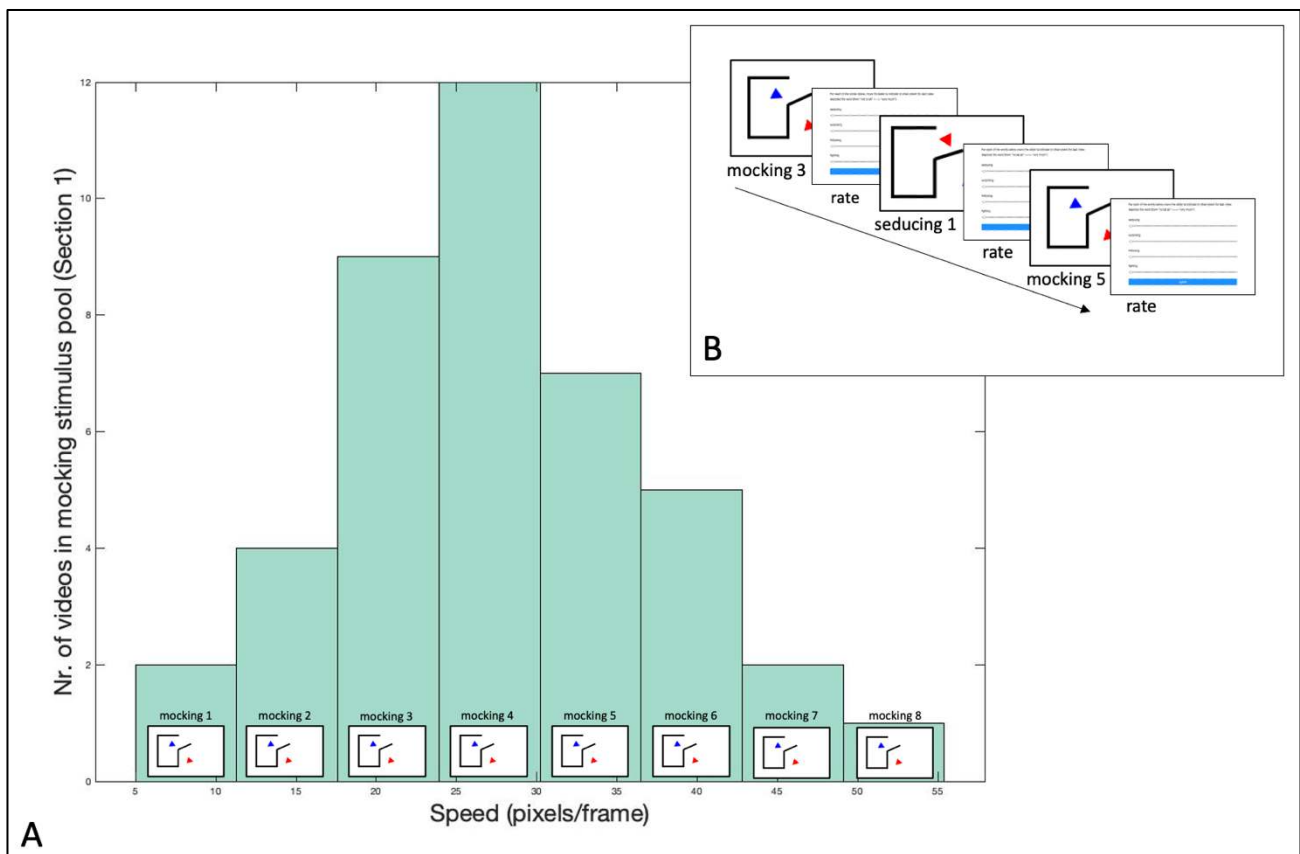
502 *Task*

503 The Ratings Collection phase comprised two tasks. First, all participants carried out a
504 **production task**, where they created one 45-second-long animation for each of the five target
505 words mocking, seducing, surprising, following and fighting, as described above. Following
506 this, participants completed a **perception task**, where they viewed 40 animations from the full
507 stimulus set and rated the extent to which the animations depicted each of the target words
508 (mocking, seducing, surprising, following, fighting). Participants viewed eight exemplars of
509 each of the five target words, presented in random order. The eight animations were selected
510 from the stimulus pool (N = 202, see **Building the animotions database**) such that the mean
511 speed of the triangles represented one of eight percentiles of the speed frequency distribution
512 for a word (see Figure 5). Thus, for each word, each participant viewed a selection of
513 animations such that they were exposed to the full range of kinematic variation in the
514 population used to create the stimulus pool.

515 Finally, after watching each animation, participants were asked to rate on a visual
 516 analogue scale ranging from one to ten the extent to which they perceived the video to display
 517 the target word (e.g., mocking) and each of the four non-target words (e.g., seducing,
 518 surprising, following and fighting). The whole process of creating five and viewing and rating
 519 40 45- second animations lasted between 40 and 50 minutes. Task order was fixed (production
 520

521 **Figure 5**

522 *Example of stimulus selection method.*



523 *Note.* A) Example of the stimulus selection method for the word mocking. The selection method was the same for
 524 all five word categories. From each of eight percentile bins of the speed frequency distribution for a word category,
 525 one animation was selected at random and replayed to the participant. B) Schematic depiction of 3 successive
 526 trials in the perception task: Each animation was followed by a separate screen with five visual analogue sliding
 527 scales (one for each of the five word categories), ranging from 1 to 10.
 528

529 task then perception task) to allow participants' animations to be unaffected by the animations
530 they would see in the perception task. Due to the upper limit on the WACOM monitor refresh
531 rate, videos were created with a 133 Hz sampling rate and displayed at 60Hz.

532

533 *Procedure*

534 Individuals sat in front of the WACOM Cintiq 22 HD touch screen, tilted at 30 degrees,
535 and first completed a practice phase in which they familiarized themselves with moving the
536 triangles around the screen. They were then instructed that they would first create an animation
537 for each of the five words themselves (instructions were the same as in **Building the**
538 **animotions database**; see Supplementary Materials) and subsequently would view and rate
539 animations which had been created by other people. Participants then completed the production
540 and perception tasks as described above.

541

542 **Data Analysis and Processing**

543 All data was processed in MATLAB R2020a³⁵ and analyzed in R³⁶. Code required to
544 reproduce data analysis and figures for this study will be freely available under
545 (<https://osf.io/pqn4u>).

546

547 *Accuracy Ratings*

548 Accuracy for each trial was calculated by subtracting the mean rating for all non-target
549 words from the rating for the target word. Thus, a positive score indicates that the target word
550 was rated higher than all non-target words, with higher accuracy scores reflecting better
551 discrimination between target and non-target words. See Appendix 1 for further analysis of
552 accuracy scores.

553

554 ***Spatial and Kinematic Predictors***

555 All variables were calculated from positional data derived from the center points of the
556 blue and red triangles. All steps of data processing mentioned below were performed on both
557 the animations created by participants (= production data) and the animations from the full
558 stimulus set used as perception task stimuli (= perception data).

559

560 ***Stimulus Kinematics***

561 Instantaneous speed, acceleration magnitude and jerk magnitude were obtained by
562 taking the first-, second- and third order non-null derivatives of the raw positional data,
563 respectively (see [1], [2] and [3], where x and y represent x - and y positions of red and blue
564 triangles in the cartesian coordinate system, v , a , and j denote instantaneous velocity,
565 acceleration and jerk, respectively, and t denotes time).

566

$$\vec{v} = \sqrt{(x_{t-1} - x_t)^2 + (y_{t-1} - y_t)^2} \quad [1]$$

$$\vec{a} = \frac{d\vec{v}}{dt} \quad [2]$$

$$\vec{j} = \frac{d\vec{a}}{dt} \quad [3]$$

567

568 As the ‘diff’ function in MATLAB amplifies the signal noise, which compounds
569 for higher derivatives, we employed a smooth differential filter to undertake each step of
570 differentiation (filter adopted from Huh & Sejnowski, 2015). The Euclidean norms of the x and
571 y vectors of velocity, acceleration and jerk were then calculated to give speed, acceleration
572 magnitude and jerk magnitude. That is, speed is calculated as the distance in pixels moved
573 from one frame to the next. Acceleration magnitude comprises the change in speed from one
574 frame to the next, and jerk magnitude comprises the change in acceleration. Mean speed, mean

575 acceleration magnitude and mean jerk magnitude were then calculated by taking the mean
576 across red and blue values, respectively. Lastly, kinematic values were converted from units of
577 pixels/frame to mm/s.

578

579 *Observer-Animator Kinematic Similarity*

580 In order to measure the kinematic similarity between participants' and stimulus
581 kinematics, absolute observer-animator jerk difference was calculated by first subtracting the
582 mean jerk of each video a person rated from their own jerk values when animating the same
583 word, and then taking the absolute magnitude of those values. Lower jerk difference values
584 indicate *higher* observer-animator kinematic similarity.

585

586 *Angular Frequency Spectral Density (AFSD)*

587 For the purpose of quantifying animation trajectories, we adapted a method developed
588 by Huh & Sejnowski (2015). Huh and Sejnowski have shown that the two-thirds power law
589 varies according to shape trajectory, such that the gradient of the relationship between angular
590 speed and curvature (in the Frenet-Serret frame^{37,38}) is a function of the shape's angular
591 frequency. Angular frequency here is defined as the number of curvature oscillations within
592 one full tracing (360° or 2π radians) of a closed-form shape. We extended the method to derive
593 the angular frequencies of arbitrary trajectories (i.e., not closed-form shapes) from the
594 frequencies of speed oscillations within every 2π radians of a triangle's angular displacement
595 in the Frenet-Serret frame.

596 First, absolute instantaneous curvature k was calculated (angular speed divided by
597 speed). This enables the calculation of Frenet-Serret speed v . Periodicity in v , in every 2π
598 radians, allows the determination of angular frequencies present in the triangles' movement.
599 Asymmetrical FFT was employed on $\log v$, which returned the amplitude spectral density of

600 all angular frequencies present for each triangle in each animation. Angular Frequency values
601 returned by the FFT were then interpolated to obtain uniformly sampled values at 1001 points.
602 Because the FFT assumes an infinite signal, when addressing a finite sample such as the log
603 angular speed here, the first and last values of each sample must be continuous to avoid
604 artefacts in the FFT results. We addressed this and any general drift in the signal (e.g., from
605 participants generally slowing their movements due to fatigue) by removing a second order
606 polynomial trend. The area under the amplitude spectral density curve was normalized to
607 allow like to like comparison between differing lengths of red and blue triangle movement
608 within and across participants. Across red and blue triangles' trajectories a weighted mean was
609 then taken by multiplying each AFSD value with a factor reflecting the proportion of curved
610 movement available for a triangle before averaging. See Figure 6 for an example of an
611 amplitude spectrum and the related trajectory path.

612

613 *Further Spatial Variables*

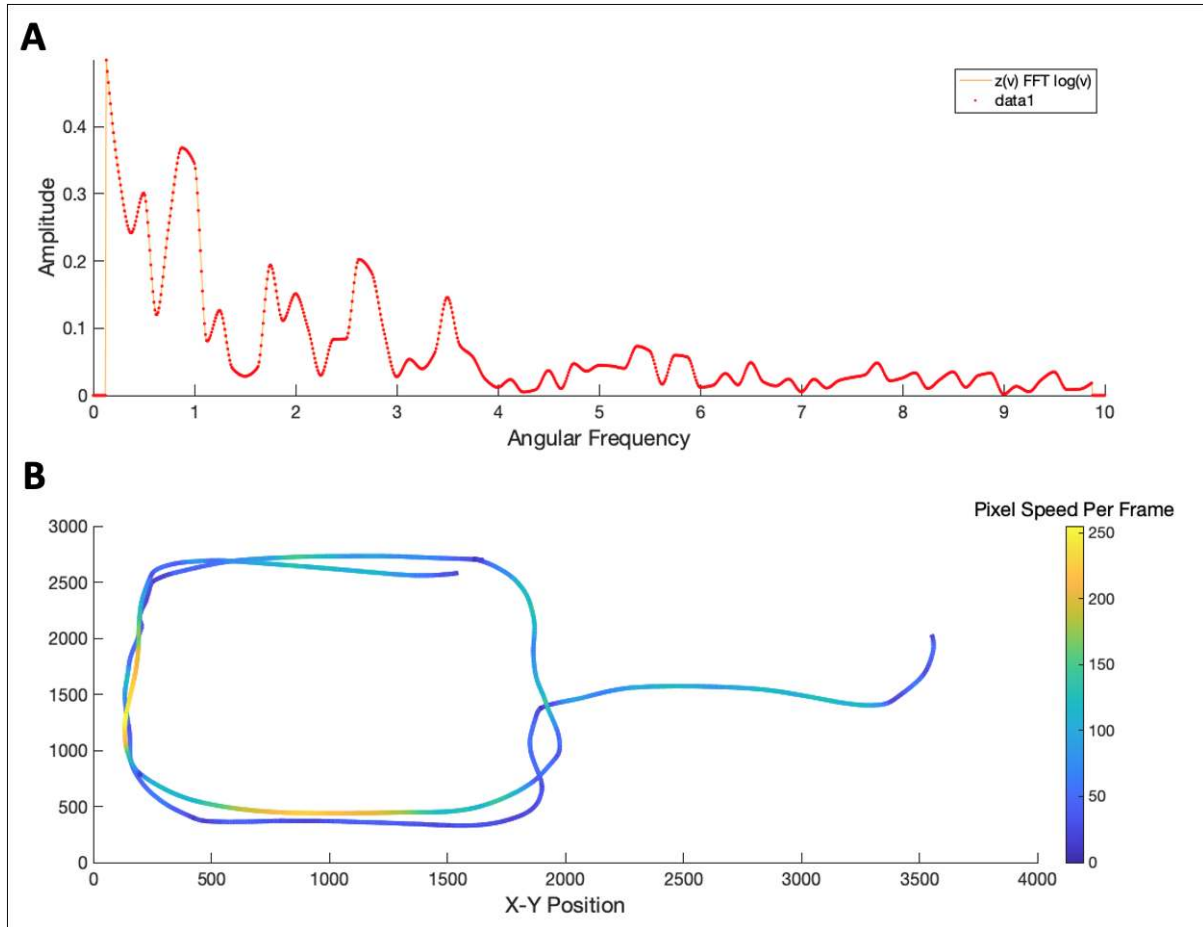
614 A variety of other variables were created to further quantify spatial aspects potentially
615 affecting inferences from the animations. First, simultaneous movement was calculated as the
616 proportion of all frames where both red and blue triangles' speed was greater than zero (as seen
617 in [4]), reflecting simultaneous movement of both triangles in a video. Furthermore, relative
618 distance - the average distance between red and blue triangles - was quantified by taking the
619 mean of the square root of the absolute distances between the triangles' x and y coordinates,
620 respectively (see [5]). Finally, mean rotation reflects the average rotation of blue and red
621 triangles around their own axis, measured in angle degrees and weighted by proportion of
622 movement present across all frames for each color ([6]).

623

624

625 **Figure 6**

626 *Example of trajectory shape and related angular frequency spectrum*



627 *Note.* (A) Example of angular frequency spectrum for following animation. (B) Related trajectory (of one of two
 628 triangles). Trajectory colors indicate speed (pixel/frame).

629

630

$$\frac{\sum(\text{speed}_{red} \& \text{speed}_{blue} > 0.01)}{\sum \text{all frames}} \quad [4]$$

$$\underline{x} \left(\sqrt{(\text{abs}(x_{red} - x_{blue}))^2 + (\text{abs}(y_{red} - y_{blue}))^2} \right) \quad [5]$$

$$\frac{(\underline{x}(\text{abs}(r_{blue\ t-1} - r_{blue\ t})) + (\underline{x}(\text{abs}(r_{red\ t-1} - r_{red\ t})))}{2} \quad [6]$$

631

632

633 **Statistical analysis**

634 ***Data Analysis Overview***

635 This study investigates the role of a large number of different predictor variables in
636 explaining accuracy in the animations task. For two of these variables we present specific
637 hypotheses (jerk, jerk difference); in addition, we wanted to investigate the role of a larger set
638 of variables on an exploratory basis. For this reason, analyses were conducted in two stages:
639 First, in a confirmatory stage, the roles of jerk and jerk difference were examined using
640 Bayesian mixed models. Second, in an exploratory stage, a random forest model was
641 performed, investigating the relative contribution of all predictor variables together.

642

643 ***Data Cleaning and Transformations***

644 For all analyses, variables that were not normally distributed were either log- or square-
645 root transformed to approximate normal distribution. Any outliers, as defined by values
646 exceeding three scaled absolute deviations from the median, were replaced with the respective
647 lower and upper threshold values. Finally, all predictor variables were z-scored.

648

649 ***Confirmatory analysis***

650 A Bayesian linear mixed effects model was fitted in R using the *brms* package³⁹ to
651 evaluate the relative contribution of jerk and jerk difference to accuracy as a function of word
652 category, as well as their three-way interaction. A maximal²⁰ random effects structure was
653 defined, allowing the intercept, the predictors of interest and their interactions to vary by
654 participants (subject ID) and items (animation ID). Jerk and jerk difference were entered as
655 covariates and word category was entered as dummy coded factor. We used *brms* default priors
656 for the intercept and the standard deviation of the likelihood function as well as weakly
657 informative priors (following a normal distribution centered at 0 and SD = 10) for all regression

658 coefficients. Each model was run for four sampling chains with 5000 iterations each (including
659 1000 warmup iterations). There was no indication of convergence issues for any of the models
660 (all Rhat values = 1.00, no divergent transitions).

661

662 *Exploratory analysis I*

663 Bootstrapped F-tests were performed to test for differences, between the five target
664 words, in the presence of angular frequencies at each of the 1001 points on the amplitude
665 spectrum. Bootstrapping amplitude spectrum values 1000 times revealed nine significant
666 clusters, defined as clusters of difference that occurred in less than 5% of comparisons with
667 resampled distributions (see Fig. 3A). The maxima and minima of each significant cluster were
668 then used as bin edges for calculating the amplitude spectral density as the area under the curve
669 within those nine bins, for both red and blue triangles' trajectories in each animation (cluster
670 bin edges: 0.21 – 1.49, 1.61 – 2.39, 2.64 – 2.87, 3.04 – 3.40, 3.91 – 4.27, 4.79-5.19, 6.19-6.68,
671 7.6-7.93, 8.75-10). Finally, the weighted mean (weighted by amount of curved movement
672 present in a triangle's full trajectory) was taken across red and blue triangles' spectral density
673 values to form a single value of mean AFSD for each of nine bins for each animation. The final
674 spectral density values are reflective of the relative proportion of curved movement available
675 in a video in each of the nine areas of interest. Thus, a video that had high spectral density in
676 bin 3 would be dominated by shapes with angular frequencies between 2.64 and 2.87. That is,
677 relative to all other animations, the triangles in this video would be predominately moving with
678 a speed and acceleration profile that lies between that of elliptical- and triangle trajectories.

679

680 *Exploratory analysis II*

681 Relative variable importance of 16 variables in predicting accuracy was assessed using
682 random forest models²³ and the feature selection wrapper algorithm *Boruta*²⁴. Random forests

683 are ensembles of decision trees, where each tree is grown from a pre-specified subset of
684 bootstrapped samples and where, for each tree, only a randomly selected subset of variables
685 are considered as splitting variables. Boruta makes use of the *ranger* package⁴⁰ to train a
686 random forest regression model on all variables as well as their permuted copies - so called
687 “shadow features”. First, *normalized permutation importance* (scaled by standard error, see²³)
688 of all features is assessed. Permutation importance of a given variable is the reduction in
689 prediction accuracy (mean decrease in accuracy, MDA) of the model when this variable is
690 randomly permuted. A variable is then classed as important when the Z-score of their
691 importance measure is significantly higher than the highest importance Z-score achieved by a
692 shadow feature. Overall performance of the model was evaluated by fitting a random forest
693 with the *ranger* package with 500 trees and 10 random variables per tree.

694 Due to the known correlational structure within the data and the present lack of random
695 forest models which can account for random effects, this analysis was performed items-based.
696 For this purpose, for every variable, values corresponding to the same item were averaged
697 across subjects, resulting in a total of 202 data points. Note that, due to the reliance on between-
698 subject variance of variables relating to own-stimulus kinematic difference, these variables
699 were excluded from this analysis.

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716 **References**

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864 **Author contributions statement:**

865 B.S., S.S. and J.C. conceived the experiments, B.S. and S.S. conducted the experiments, D.F.
866 and D.H. contributed analysis tools. A.G. and J.v.d.B. contributed the code for the online
867 task. B.S. analysed the results. B.S. and J.C. wrote the manuscript.

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869 **Additional Information:**

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871 The authors declare no competing interests.

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