Autonomous Mental Development: A New Interdisciplinary Transactions for Natural and Artificial Intelligence

LTHOUGH some baby animals can get up and walk within hours after birth, what a human child learns during the first two years of life easily exceeds what those animals learn in their entire lifetime. Furthermore, besides the explosive growth that occurs during this period, it is now well documented that a human brain continues its life-long development and learning [1]. The human brain is one of the most complex systems we know of in the world, composed of about 100 billion strongly interconnected neurons. A single neuron may have more than 10 000 connections to other neurons. For thousands of years, the mind has been the center of myths and human beings have endeavored to understand our own brain and the mind arising from it.

With the recent advances in cognitive science and neuroscience, e.g., with the help of brain imaging technologies such as the fMRI, EEG and PET, and many other direct observation and intervention techniques, more and deeper details of the brain's inner workings are being revealed. Together with the advances in computational intelligence, computer science, and robotics, these discoveries have stimulated the birth and rapid growth of a new interdisciplinary research field known as Autonomous Mental Development (AMD) [2]. Mental development is a process during which a brain-like natural or artificial embodied system, under the control of its intrinsic species-specific developmental program, develops mental capabilities through its real-time interactions with its environment (including the brain's own internal environment) using its own sensors and effectors. The mental capabilities that develop in this way include perceptual, cognitive, behavioral, motivational, and all other mental capabilities that are exhibited by humans, higher animals, and artificial systems. The intrinsic developmental program and the interaction with the environment are both important for normal mental development: The environment affects how the developmental program in the genes works, which in turn regulates how the environment and experience give rise to the brain's internal representations, mental capabilities, and internal and external behaviors.

In recognition of the gains made in this field and to support its further development, the IEEE has approved this new IEEE TRANSACTIONS ON AUTONOMOUS MENTAL DEVELOPMENT (TAMD). Published four times a year, it will serve as an archival repository for significant work on this subject. The scope of TAMD includes:

- Computational modeling of mental development, including mental architecture, theories, algorithms, properties and experiments;
- Experimental investigations relevant to the goal of achieving a computational understanding of develop-

mental processes in humans and animals, especially those focusing on the role of experience and on the active exploration of the environment;

 Engineering applications of autonomous mental development such as mechanisms enabling highly complex capabilities by robots and other artificial systems.

Investigations in AMD are expected to improve our systematic understanding of the working of the wide variety of mental capabilities in humans, to help develop biotechnology solutions, such as drugs and neural implants, to brain disorders, and to build truly intelligent machines by enabling the machines' brains to autonomously develop. We expect big breakthroughs in all of these areas.

The TAMD encourages papers submitted from all areas related to mental development, including, but not limited to, computer science, engineering, robotics, neuroscience, psychology, biology, medicine, and philosophy. No one can be expected to be an expert in all these areas. By bringing researchers and practitioners from different areas together in this forum, we are exposed to knowledge from other areas. This process will facilitate interactions with experts in other areas and fertilize the development of this interdisciplinary field. I would like to offer an advice to the interested authors to submit their research works. To ensure a wide audience and a large impact, the authors should write papers that are as readable and interesting as possible, accessible to researchers who are not in your specific area. As far as appropriate, a paper will be reviewed by peers from natural as well as from artificial intelligence sides. Due to the existence of many empirically oriented journals in the field of developmental psychology, the TAMD will emphasize computational approaches to mental development and experimental studies that make contact with computational approaches. Of course, it will be free to evolve with the community it serves.

The publication of the TAMD is the fruit of the collective effort of the AMD community supported by the IEEE Computational Intelligence Society (CIS) and the Cognitive Science Society. IEEE CIS established the Technical Committee on Autonomous Mental Development (AMD TC) in 2004. The AMD TC members are actively involved in the organization of the annual *International Conference on Development and Learning* (ICDL), and the annual *International Conference on Epigenetic Robotics* (EpiRob). The AMD TC has also explored alternative publishing mechanisms, including five special issues in IEEE TRANSACTIONS ON EVOLUTIONARY COMPUTION (IEEE TEVC) [3], *Advanced Robotics* [4], *Neurocomputing* [5], *Adaptive Behavior* [6], and *International Journal of Humanoid Robotics* [7] in 2006 and 2007. With this publication, we expect the AMD community to grow bigger and stronger.

I would like to thank Juyang (John) Weng (Founding AMD TC Chair), James (Jay) L. McClelland (Former President of the Cognitive Science Society), David Fogel (CIS President), Jim

Digital Object Identifier 10.1109/TAMD.2009.2021201

Keller (Former CIS VP Publications), Vincenzo Piuri (Former CIS President), Brian Scassellati (Former AMD TC Chair), and Xin Yao (CIS VP Publications, Former Editor-in-Chief of IEEE TEVC) for their immense support and personal encouragement to start this TRANSACTIONS. Special thanks are also owed to the AMD community, and especially the AMD TC members, for helping me putting together a strong TAMD proposal. Finally, I would like to express my appreciation to all of the Associated Editors who are volunteering their time and effort to support this new publication. The quality of the TAMD depends critically on the quality of service of its editorial board and the vitality of its AMD research community. We are lucky to have so many dedicated volunteers and energetic researchers. I trust that our efforts together will serve the AMD community well in the years to come.

> ZHENGYOU ZHANG, *Editor-in-Chief* Microsoft Research, One Microsoft Way, Redmond, WA 98052 USA Phone: 425-703-3029 Fax: 425-706-7329 E-mail: zhang@microsoft.com

REFERENCES

- Handbook of Developmental Cognitive Neuroscience, C. A. Nelson and M. Luciana, Eds., 2nd ed. Cambridge, MA: The MIT Press, 2008.
- [2] J. Weng, J. McClelland, A. Pentland, O. Sporns, I. Stockman, M. Sur, and E. Thelen, "Autonomous mental development by robots and animals," *Science*, vol. 291, no. 5504, pp. 599–600, Jan. 26, 2001.
- [3] J. McClelland, K. Plunkett, and J. Weng, Eds., *IEEE Trans. Evol. Comput.*, vol. 11, no. 2, 2007.
- [4] K. Hosoda, Ed., Adv. Robot., vol. 20, no. 10, 2006.
- [5] G. Deak, M. S. Bartlett, and T. Jebara, Eds., *Neurocomputing*, vol. 70, no. 13–15, 2007.
- [6] O. Sporns, Ed., Adapt. Behav., vol. 15, no. 2, Jun. 2007.
- [7] J. Weng, B. Scassellati, and Z. Zhang, Eds., Int. J. Humanoid Robot., vol. 4, no. 2, Jun. 2007.



Zhengyou Zhang (SM'97–F'05) received the B.S. degree in electronic engineering from the University of Zhejiang, Hangzhou, China, in 1985, the M.S. degree in computer science from the University of Nancy, Nancy, France, in 1987, and the Ph.D. degree in computer science and the Doctor of Science (*Habilitation à diriger des recherches*) diploma from the University of Paris XI, Paris, France, in 1990 and 1994, respectively.

He is a Principal Researcher with Microsoft Research, Redmond, WA. He was with INRIA (French National Institute for Research in Computer Science and Control) for 11 years and was a Senior Research Scientist from 1991 until he joined Microsoft Research in March 1998. In 1996–1997, he spent a one-year sabbatical as an Invited Researcher with the Advanced Telecommunications Research Institute International (ATR), Kyoto, Japan. He is also an Affiliate Professor with the University of Washington, Seattle, WA, and an Adjunct Chair Professor with the University of Zhejiang, Hangzhou, China. He has published over 200 papers in refereed international journals and conferences, and has coauthored the following books: *3-D Dynamic*

Scene Analysis: A Stereo Based Approach (Springer-Verlag, 1992); Epipolar Geometry in Stereo, Motion and Object Recognition (Kluwer, 1996); and Computer Vision (Chinese Academy of Sciences, 1998, 2003, in Chinese). He has given a number of keynotes in international conferences.

Dr. Zhang is an Associate Editor of the IEEE TRANSACTIONS ON MULTIMEDIA, an Associate Editor of the *International Journal of Computer Vision*, an Associate Editor of the *International Journal of Pattern Recognition and Artificial Intelligence*, and an Associate Editor of *Machine Vision and Applications*. He served on the Editorial Board of the IEEE TRANSACTIONS ON PATTERN ANALYSIS AND MACHINE INTELLIGENCE from 2000 to 2004, among others. He has been on the program committees for numerous international conferences in the areas of autonomous mental development, computer vision, signal processing, multimedia, and human–computer interaction. He was an Area Chair and a Demo Chair of the International Conference on Computer Vision, October 2003, a Program Co-Chair of the Asian Conference on Computer Vision, January 2004, a Demo Chair of the International Conference of Multimedia Signal Processing (MMSP), October 2006, a Program Co-Chair of the International Workshop on Motion and Video Computing, November 2006, and a Program Co-Chair of the International Conference on Development and Learning, June 2009. He is a member of ACM.

Introduction of the TAMD Associate Editors



Minoru Asada (F'05) received the B.E., M.E., and Ph.D., degrees in control engineering from Osaka University, Osaka, Japan, in 1977, 1979, and 1982, respectively.

In April 1995, he became a Professor of the Osaka University. Since April 1997, he has been a Professor of the department of Adaptive Machine Systems at the Graduate School of Engineering, Osaka University. From August 1986 to October 1987, he was a Visiting Researcher of Center for Automation Research, University of Maryland, College Park.

Dr. Asada received many awards such as the best paper award of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS92) and the Commendation by the Minister of Education, Culture, Sports, Science and Technology, Japanese Government as Persons of distinguished services to enlightening people on science and technology. He was the president of the International RoboCup Federation (2002–2008). Since 2005, he has been the Research Director of "ASADA Synergistic Intelligence Project" of ERATO (Exploratory Research for Advanced Technology by Japan Science and Technology Agency).



Luc Berthouze received the M.Sc. degree in sciences for the Engineer (applied mathematics) from the University of Paris XII, France, in 1994, and the Ph.D. degree from the University of Evry in 1996.

Since 2007, he is a Senior Lecturer in evolutionary and adaptive systems at the University of Sussex, U.K., and a honorary Senior Lecturer in the developmental cognitive neuroscience unit of the UCL Institute of Child Health, U.K. From 1996 to 2001, he was a Research Scientist at the Electrotechnical Laboratory, Japan. In 2001, he joined the Neuroscience Research Institute (AIST), Japan, first as a Research Scientist, and from 2005 as a Senior Research Scientist. He has authored more than 50 refereed research articles in the fields of cognitive science, robotics, cognitive neuroscience, and developmental psychology. His current research interests include motor development in infants and in machines, clinical applications of a dynamical systems approach to characterizing infant early movements (particularly in cerebral palsy) and intelligent neuroprostheses.



Kerstin Dautenhahn received the Ph.D. degree from the Biological Cybernetics Department of the University of Bielefeld, Bielefeld, Germany, in 1993.

She is Research Professor in the School of Computer Science at University of Hertfordshire, U.K., where she coordinates the Adaptive Systems Research Group. She has published more than 200 research articles on social robotics, human-robot interaction, assistive technology and Artificial Life. She has edited several books and frequently gives invited keynote lectures at international meetings. She regularly organizes conferences, and was general Chair of IEEE RO-MAN 2006 with the theme of "Getting to Know Socially Intelligent Robots" and co-general chair of the ACM/IEEE conference HRI'08. She has been Principal Investigator in several European projects on developmental robotics (Robotcub), robot companions (Cogniron and LIREC), educational virtual environments (Victec and eCircus), and robotics and assistive technology (IROMEC, RoboSkin).

Prof. Dautenhahn is Editor-in-Chief of the journal Interaction Studies: Social Behaviour and Communication in Biological and Artificial Systems, as well as Associate Editor of Adaptive Be-

havior (Sage Publications), the International Journal of Social Robotics (Springer).



Gedeon Deak received the B.A. degree (*cum laude*), Vassar College, in 1990 and the Ph.D. degree from the University of Minnesota, 1995.

He is an Associate Professor of Cognitive Science and Human Development at the University of California at San Diego. From 1995 to 1999, he was on the faculty at Vanderbilt University (1995–1999). He and his colleagues investigate how young children learn and use language, and how they use changing verbal information to make inferences about complex objects and situations. They also investigate how infants learn social and communication skills, using experiments, naturalistic observation, physiological responses, and simulations with computers and robots. He teaches undergraduate and graduate classes on cognitive development, language learning, infancy, and education and cognition. He has received research grants from the National Science Foundation, National Academy of Education/Spencer Foundation, M.I.N.D. Institute, National Alliance for Autism Research, Nicholas Hobbs Foundation, and the Hellmans. He is on the executive council of the Center for Human Development at UCSD, is a co-investigator in the Temporal Dynamics

Learning Center, and is a co-editor of the Journal of Cognition and Development.



Marco Dorigo (S'92–M'93–SM'96–F'06) received the Laurea (Master of Technology) degree in industrial technologies engineering in 1986 and the doctoral degree in information and systems electronic engineering in 1992 from Politecnico di Milano, Milan, Italy.

He is a Research Director of the Belgian National Funds for Scientific Research and of IRIDIA, the artificial intelligence laboratory of the Université Libre de Bruxelles. He is the inventor of the ant colony optimization metaheuristic. His current research interests include swarm intelligence, swarm robotics, and metaheuristics for discrete optimization.

Dr. Dorigo is the Editor-in-Chief of the *Swarm Intelligence* journal, and an Associate Editor or member of the editorial board for many journals in computational intelligence and adaptive systems. He was awarded the Italian Prize for Artificial Intelligence in 1996, the Marie Curie Excellence Award in 2003, the Dr. A. De Leeuw-Damry-Bourlart award in applied sciences in 2005, and the Cajastur International Prize for Soft Computing in 2007. He is a Fellow of the ECCAI.



Wen Gao (S'87–M'88–SM'05–F'09) received the Ph.D. degree from the University of Tokyo, Japan.

He is a Professor in Peking University, China. He was a Professor in Harbin Institute of Technology from 1991 to 1995, and a Professor in Chinese Academy of Sciences (CAS) from 1996 to 2005. During his career in CAS, he also served as the Managing Director of the Institute of Computing Technology, the Executive Vice President of the Graduate School, and a Vice President of the University of Science and Technology of China. He is the Editor-in-Chief of *Journal of Computer* (a journal of Chinese Computer Federation), an Associate Editor of the IEEE TRANSACTIONS ON CIRCUITS AND SYSTEMS FOR VIDEO TECHNOLOGY and the IEEE TRANSACTIONS ON MULTIMEDIA, among others. He chaired a number of prestigious international conferences and served on the advisory and technical committees of numerous professional organizations. He has published four books and over 400 technical articles in refereed journals and conference proceedings in the areas of multimedia, image/video processing, face recognition, sign language recognition and synthesis,

multimedia information retrieval, multimodal interface, and bioinformatics.



Richard Granger received the Bachelor and Ph.D. degrees from the Massachusetts Institute of Technology (MIT), Cambridge, and Yale University, New Haven, CT.

He is Professor of Psychological and Brain Sciences at Dartmouth College, MA. He directs Dartmouth College's interdisciplinary Brain Engineering Laboratory, with research projects ranging from computation and robotics to cognitive neuroscience. He has authored more than 100 scientific papers and numerous patents, and is a recipient of many awards and honors, including election as a Fellow of the American Association for the Advancement of Science, and he serves on the boards of a number of technology corporations and government agencies. He is co-inventor of FDA-approved devices and drugs in clinical trials, and has been the principal architect of a series of advanced computational systems for military, commercial and medical applications.



conferences.





Tianzi Jiang received the B.Sc. degree from Lanzhou University, China, in 1984, and the M.Sc. and Ph.D. degrees from Zhejiang University, China, in 1992 and 1994, respectively.

He is a Professor of Brain Imaging and Cognitive Disorders at Institute of Automation of the Chinese Academy of Sciences (CASIA). From 1999 to 2000, he was a Visiting Scientist at the Max-Planck Institute of Cognitive Neuroscience, Leipzig, Germany. From 2000 to 2001, he was a Research Fellow at the Queen's University of Belfast, U.K. In 2001, he joined CASIA again as a full professor supported by the Hundred Talents Programs of the Chinese Academy of Sciences. He is the Chinese Director of the Sino-French Laboratory LIAMA since 2006. He has published over 110 reviewed journal papers. His current research interests include systems and computational neuroscience, brain imaging, complex brain networks, imaging genetics, and medical image analysis.

He is the Associate Editor of IEEE TRANSACTIONS ON MEDICAL IMAGING and on the editorial boards of *NeuroImage* and several other journals. He served/s as the chair for several international

Kazuhiko Kawamura (S'64–M'73–SM'90–LF'05) received the B.E. degree from Waseda University, Japan, the M.S. degree from the University of California, Berkeley, and Ph.D. degree from the University of Michigan, Ann Arbor, all in electrical engineering.

He is a Professor of electrical and computer engineering and engineering management and the Director of the Center for Intelligent Systems (CIS), Vanderbilt University, Nashville, TN. He has published over 170 research papers, a book, several book chapters in the fields of intelligent systems, intelligent robotics, cognitive robotics and control. He directs research projects at the CIS in humanoid robots, cognitive robotics and control.

Dr. Kawamura is a Founding Chair of the Technical Committee on Service Robots for the IEEE Robotics and Automation Society. He was the General Chair of the IEEE 14th International Workshop on Robot and Human interactive Communication in 2005. He is a member of the editorial board of *International Journal of Humanoid Robotics*, and the designated General Chair of the IEEE-RSJ International Conference on Humanoids in 2010.

Jeffrey L. Krichmar received the B.S. degree in 1983 from the University of Massachusetts at Amherst, the M.S. degree from the George Washington University, Washington, DC, in 1991, and the Ph.D. degree from George Mason University, Fairfax, VA, in 1997.

In 1997, he became an Assistant Professor at The Krasnow Institute for Advanced Study at George Mason University. From 1999 to 2007, he was a Senior Fellow in theoretical neurobiology at The Neurosciences Institute. He currently is an Assistant Professor in the Department of Cognitive Sciences at the University of California, Irvine. His research interests include neurorobotics, embodied cognition, biologically plausible models of learning and memory, and the effect of neural architecture on neural function. He and his colleagues have successfully constructed a series of Brain Based Devices, robotic devices whose behavior is controlled by a simulated nervous system, to test theories of the nervous system. He is author of over 40 scientific articles, has organized international conferences on brain-based robotics, and was chair of a Robotic Soccer league in which Segway robots interacted with humans.



Benjamin Kuipers (M'89–SM'97–F'99) received the B.A. degree from Swarthmore College, Swarthmore, PA, and the Ph.D. degree from the Massachusetts Institute of Technology (MIT), Cambridge.

He joined the University of Michigan, Ann Arbor, in January 2009 as Professor of Computer Science and Engineering. Prior to that, he held an endowed Professorship in computer sciences at the University of Texas at Austin. He investigates the representation of commonsense and expert knowledge, with particular emphasis on the effective use of incomplete knowledge. His research accomplishments include developing the TOUR model of spatial knowledge in the cognitive map, the QSIM algorithm for qualitative simulation, the Algernon system for knowledge representation, and the spatial semantic hierarchy model of knowledge for robot exploration and mapping.

Dr. Kuipers has served as Department Chair at University of Texas, Austin, and is a Fellow of AAAI.



Stephen E. Levinson (S'72–M'74–SM'82–F'05) received the B.A. degree from Harvard University, Cambridge, MA, in 1966, and the M.S. and Ph.D. degrees from the University of Rhode Island, Kingston, in 1972 and 1974, respectively.

In 1976, he joined the Technical Staff of Bell Laboratories, Murray Hill, NJ, where he conducted research in the areas of speech recognition and understanding. In 1990, he became head of the Linguistics Research Department at AT&T Bell Laboratories. In 1997, he joined the University of Illinois at Urbana-Champaign, where he leads research in speech synthesis and automatic language acquisition. He is also a full-time faculty member of the Beckman Institute for Advanced Science and Technology.

Dr. Levinson is a member of the ACM and a fellow of the Acoustical Society of America. He is a founding editor of the journal *Computer Speech and Language*. He is the author of more than 100 technical papers and holds seven patents. His book is entitled *Mathematical Models for Speech Technology* (2005: Wiley).



Denis Mareschal received the first degree in physics and theoretical physics from Cambridge University, Cambridge, MA. He then received the Master's degree in psychology from McGill University, Canada, before receiving the Ph.D. degree from Oxford University, Oxford, U.K.

Dr. Mareschal received the Marr prize from the Cognitive Science Society (USA), the Young Investigator Award from the International Society on Infant Studies (USA), and the Margaret Donaldson Prize from the British Psychological Society. His research centers on developing mechanistic models of perceptual and cognitive development in infancy and childhood. He is currently Professor at Birkbeck College, University of London.



James L. (Jay) McClelland received the Ph.D. degree in cognitive psychology from the University of Pennsylvania, Philadelphia, in 1975.

He served on the faculty of the University of California, San Diego and Carnegie Mellon, Pittsburgh, PA, where he became a University Professor and a founding Co-Director of the Center for the Neural Basis of Cognition. In 2006 he moved to Stanford University, where he is now Professor of Psychology and founding Director of the Center for Mind, Brain and Computation. He has contributed to the experimental and theoretical literatures in the application of connectionist/parallel distributed processing models to perception, cognitive development, language learning, and the neurobiology of memory. With David E. Rumelhart he led the effort leading to the publication in 1986 of the two-volume book, *Parallel Distributed Processing*, in which the parallel distributed processing framework was laid out and applied to a wide range of topics in cognitive psychology and cognitive neuroscience.

Dr. McClelland received the 1996 Distinguished Scientific Contribution Award from the Amer-

ican Psychological Association jointly with Dr. Rumelhart and the 2002 IEEE Neural Networks Pioneer Award for this work. He is President-Elect of the Federation of the Behavioral, Psychological, and Cognitive Sciences. He is a member of the National Academy of Sciences, and he received the APS William James Fellow Award for lifetime contributions to the basic science of psychology.

fornia, Los Angeles (UCLA) in 1990.



Giorgio Metta received the Ph.D. degree in electronic engineering in 2000.

He is Assistant Professor at the University of Genoa, Italy, where he teaches the courses of Anthropomorphic Robotics and Operating Systems for the bioengineering curricula. He is also Senior Research Scientist at the Italian Institute of Technology (IIT) in Genoa. He was Postdoctoral Associate at the Massachusetts Institute of Technology (MIT), AI-Lab, Cambridge, from 2001 to 2002. For more than ten years, he has been active in the field of developmental robotics. His goal has always been that of furthering the understanding of brain functions on one side and of building better artificial systems on the other. He has been collaborating with leading neuroscience and psychology scientists worldwide with a particular emphasis in aspects of manipulation and affordances. His research interests lay squarely in the field of artificial cognitive systems. He is one of the coordinators of the "RobotCub", an open source project, which has developed a child-size humanoid robot specifically dedicated to developmental and cognitive systems research by allowing sophisticate manipulation and human like kinematics.

Risto Miikkulainen received the M.S. degree in engineering from the Helsinki University of Technology, Finland, in 1986, and the Ph.D. degree in computer science from the University of Cali-

He is a Professor of Computer Sciences at the University of Texas at Austin. His current research includes models of natural language processing, self-organization of the visual cortex, and



(http://www.pyoudeyer.com).

evolving neural networks with genetic algorithms; he is an author of over 250 articles in these research areas. He is currently on the Board of Governors of the Neural Network Society, and in addition to the IEEE TRANSACTIONS ON AUTONOMOUS MENTAL DEVELOPMENT, an action editor of the IEEE TRANSACTIONS ON COMPUTATIONAL INTELLIGENCE AND AI IN GAMES (T-CIAIG), the Machine Learning Journal, Journal of Cognitive Systems Research, and the IEEE TRANSACTIONS ON NEURAL NETWORKS.

Pierre-Yves Oudeyer studied theoretical computer science at Ecole Normale Supérieure in Lyon, and received the Ph.D. degree in artificial intelligence from the University Paris VI, France.

He has been a permanent researcher in Sony Computer Science Laboratory for 8 years (1999–2007), working on developmental robotics and computational modeling of language acquisition and evolution. Since January 2008, he has been head of the INRIA research team FLOWERS at INRIA Bordeaux-Sud-Ouest, focused on developmental and social robotics. He is interested in the mechanisms that allow humans and robots to develop perceptual, motivational, behavioral, and social capabilities to become capable of sharing cultural representations. He also works on artificial curiosity, intrinsic motivation, and life-long learning. He has published a book, more than 60 papers in international journals and conferences, holds eight patents, and received several prizes for his work in developmental robotics and on the origins of language.

Dr. Oudeyer is Editor of the IEEE CIS Newsletter on Autonomous Mental Development, and Associate Editor of Frontiers in Neurorobotics and of the International Journal of Social Robotics



Kim Plunkett received the Bachelor's degree in physics at Imperial College, London, U.K., and then switched to Experimental Psychology at Sussex University, where he received the D.Phil. degree in 1979.

After holding faculty positions at Nottingham University and the Open University in the U.K., he moved to the Institute of Psychology, Aarhus University, Denmark, where he investigated children's acquisition of Scandinavian languages. In 1986, he became affiliated to the University of California, San Diego, to study the application of neural networks to modelling linguistic and cognitive development in young children. Since 1991, he has been a member of the faculty in the Department of Experimental Psychology, Oxford University, where he holds the position of Professor of Cognitive Neuroscience. He has been a Director of the International Association for the Study of Child Language and Executive Board member of the Cognitive Science Society. In 1993, he established the Oxford BabyLab which is a research facility for the experimental investigation of linguistic and cognitive development in babies and young children. His current research focuses

on early lexical development using experimental and neuro-imaging approaches and neural network modeling.



Tomaso A. Poggio (A'86) is the Eugene McDermott Professor at the Department of Brain and Cognitive Sciences and the McGovern Institute and a member of the Computer Science and Artificial Intelligence Laboratory at the Massachusetts Institute of Technology (MIT), Cambridge. He is author or coauthor of over 400 papers in the fields of learning theory, computer science, computational neuroscience, and nonlinear systems theory and he belongs to the editorial board of several scientific journals. He is an honorary member of the Neuroscience Research Program, a member of the American Academy of Arts and Sciences and a Founding Fellow of AAAI. He received several awards including the Otto-Hahn Award of the Max-Planck-Society, the Laurea Honoris Causa from the University of Pavia and the 2003 Gabor Award. His research has been interdisciplinary, between brains and computers. It is now focused on the mathematics of learning theory, on the applications of learning techniques to computer vision, bioinformatics, computer graphics and especially on the computational neuroscience of the visual cortex in close collaboration with several physiology labs. A former Corporate Fellow of Thinking Machines Corporation, he was involved

in starting several other high tech companies. For more information see http://cbcl.mit.edu.



Danil V. Prokhorov (SM'02) began his technical career in St. Petersburg, Russia, after graduating with Honors from Saint Petersburg State University of Aerospace Instrumentation in 1992 (M.S. degree in robotics). He worked as a research engineer in St. Petersburg Institute for Informatics and Automation of the Russian Academy of Sciences. He came to United States in late 1993 to study for the Ph.D. degree in neurocomputing.

Upon his graduation from the Electrical Engineering Department of Texas Tech University, Lubbock, in 1997, he joined Ford to pursue application-driven research on neural networks and other machine learning algorithms. At Ford, he took part in several production-bound projects including neural network based engine misfire detection. Since 2005, he has been with Toyota Research Institute NA, Toyota Technical Center, Ann Arbor, MI, overseeing important mid- and long-term research projects in computational intelligence. In addition to contributing with his numerous technical papers and patents, he has been helping research community with reviewing for many conferences, journals, and for the U.S. funding agencies.



Brian Scassellati received the Ph.D. degree in computer science from the Massachusetts Institute of Technology (MIT), Cambridge, in 2001. He received the Master of Engineering in computer science and electrical engineering in 1995, and the Bachelor degrees in computer science and electrical engineering in 1995, and brain and cognitive science in 1995, all from MIT.

He is an Associate Professor of Computer Science at Yale University, New Haven, CT. His research focuses on building embodied computational models of human social behavior, especially the developmental progression of early social skills. His other interests include humanoid robots, human-robot interaction, artificial intelligence, machine perception, and social learning.

Dr. Scassellati was the Chairman of the IEEE Autonomous Mental Development Technical Committee from 2006 to 2007. He is the Program Chair of the *IEEE International Conference on Development and Learning* (ICDL) in both 2007 and 2008 and the Program Chair for the *IEEE/ACM International Conference on Human-Robot Interaction* (HRI) in 2009.



Matthew Schlesinger received the B.A. degree in psychology (*summa cum laude*) from the University of California, San Diego, in 1989, and the Ph.D. degree in psychology from the University of California, Berkeley, in 1995.

After spending a year as a Visiting Lecturer in psychology at Berkeley, he received a Fulbright fellowship to study artificial life models of sensorimotor cognition with Domenico Parisi at the Italian National Research Council in Rome. He continued his postdoctoral work in 1998–2000 with a multidisciplinary team of researchers at the University of Massachusetts, Amherst, studying machine-learning approaches to adaptive motor control. He joined Southern Illinois University in 2000, where he is currently an associate professor of psychology. His research focuses on the development of attention, perceptual-motor skill, and memory in natural and artificial systems, and utilizes approaches from the fields of cognitive development, machine learning, and cognitive neuroscience.



Thomas R. Shultz received the Ph.D. degree is from Yale University, New Haven, CT, in psychology.

He is a Professor of Psychology and Associate Member of the School of Computer Science at McGill University, Canada. His current research interests include connectionism, cognitive science, cognitive development, cognitive consistency phenomena, constraint-satisfaction reasoning, evolution, agent-based modeling, and relations between knowledge and learning.

Dr. Schultz is a Member of the IEEE Computational Intelligence Society Autonomous Mental Development Technical Committee and the Chair of its Task Force on Developmental Psychology. He is the author of the book *Computational Developmental Psychology* (MIT Press, 2003). More information is available at http://www.psych.mcgill.ca/perpg/fac/shultz/personal/default.htm.



Vladimir Sloutsky is a Professor of Psychology at Ohio State University, Columbus. His research focuses on conceptual development, and on interrelationships between cognition and language. More information is available at http://faculty.psy.ohio-state.edu/1/sloutsky/.



Linda Smith received the B.S. degree in 1973 from the University of Wisconsin—Madison and the Ph.D. degree in psychology from the University of Pennsylvania, Philadelphia, in 1977.

She is a Distinguished Professor and the Chancellor's Professor of Psychological and Brain Sciences and Cognitive Science at Indiana University—Bloomington. She She joined the faculty at Indiana University in 1977. Her research is directed to understanding developmental processes especially at it applies to early cognitive development and to the interaction of perception, action and language in that developmental process. She has published over 100 research articles and is coauthor with Esther Thelen of A Dynamical Systems Approach to the Development of Cognition and Action. Her research is supported by grants from the National Institutes of Child Health and Development and the National Institute of Mental Health. You may find out more about her research and laboratory at www.iub.edu/~cogdev.



Olaf Sporns received the undergraduate degree in biochemistry from the University of Tübingen, Germany, and the Ph.D. degree in neuroscience from Rockefeller University, New York.

He then took a position as a Senior Fellow in Theoretical and Experimental Neurobiology at The Neurosciences Institute, first in New York and later in San Diego, CA. Since 2000, he has held a faculty position at the Department of Psychological and Brain Sciences at Indiana University in Bloomington, IN, where he is currently a Professor and Associate Chair. Sporns is also on the faculty of the Programs in Cognitive Science and Neuroscience, the School of Informatics, and the Indiana University Biocomplexity Institute. He directs the Computational Cognitive Neuroscience Laboratory (www.indiana.edu/~cortex/CCNL.html). Dr. Sporns' main research field is theoretical and computational neuroscience, with a strong emphasis on network complexity and neurorobotics.

Dr. Sporns is a member of the AAAS, the Society for Neuroscience, the International Society for Adaptive Behavior, and Sigma Xi. He is an associate editor or member of the editorial board of the journals *BioSystems, Adaptive Behavior*, the *International Journal of Humanoid Robotics, PLoS ONE, PLoS Computational Biology, Neural Networks*, and *Neuroinformatics*.



Mriganka Sur received the B.Tech. degree in electrical engineering from the Indian Institute of Technology, Kanpur, and the Ph.D. degree in electrical engineering from Vanderbilt University, Nashville.

He is the Newton Professor of Neuroscience and Head of the Department of Brain and Cognitive Sciences at the Massachusetts Institute of Technology (MIT), Cambridge. He studies the development, organization, and plasticity of the cerebral cortex of the brain using experimental and computational approaches. He has pioneered high-resolution imaging approaches to analyzing brain cells and circuits, and discovered fundamental principles by which networks of the cerebral cortex are wired and change.

Dr. Sur has received many awards and honors, delivered numerous lectures worldwide, and been elected a fellow of the American Academy of Arts and Sciences, the Third World Academy of Sciences, and the Royal Society of the United Kingdom.



Jun Tani received the B.S. degree in mechanical engineering from Waseda University, Japan, dual M.S. degrees in electrical engineering and mechanical engineering from University of Michigan, Ann Arbor, and the Dr.Eng. from Sophia University, Japan.

He started his research career in Sony Computer Science Laboratory in 1990. He has been appointed as a team leader in the Laboratory for Behavior and Dynamic Cognition, Brain Science Institute, RIKEN in Tokyo, Japan, since 2000. He was also appointed as a Visiting Associate Professor in University of Tokyo from 1997 to 2002. He is interested in neuroscience, psychology, phenomenology, complex adaptive systems, and robotics.



Jochen Triesch received the Diploma and Ph.D. degrees in physics from the Ruhr-Universität Bochum, Germany, in 1994 and 1999, respectively.

From 1999 to 2001, he was a Postdoctoral Fellow in the Department of Computer Science and the Center for Visual Science at the University of Rochester. In 2001, he joined the faculty of the University of California, San Diego, as an Assistant Professor of Cognitive Science. In 2005, he was elected a Fellow of the Frankfurt Institute for Advanced Studies (FIAS) and moved back to Germany. In 2006, he received a Marie Curie Excellence Center Award from the European Union. Since 2007, he has held the chair for Theoretical Life Sciences at FIAS. He has worked in a range of areas including computational neuroscience, computer vision, robotics, and visual psychophysics. Much of his current research focuses on modeling learning processes in the mammalian visual system.



Juyang (John) Weng (S'85–M'89–SM'05–F'09) received the M.S. and Ph.D. degrees from University of Illinois, Urbana-Champaign, 1985 and 1988, respectively.

He is a professor at the Department of Computer Science and Engineering, the Cognitive Science Program, and the Neuroscience Program, Michigan State University, East Lansing. His research interests include developmental systems, vision, audition, touch, and intelligent robots.

Dr. Weng is the Editor-in-Chief of International Journal of Humanoid Robotics, and the General Chair of 8th ICDL (2009). He was a Program Chairman of the NSF/DARPA funded Workshop on Development and Learning 2000 (1st ICDL), the Chairman of the ICDL Governing Board (2005–2007, http://cogsci.ucsd.edu/~triesch/icdl/), a member of the Executive Board of the International Neural Network Society, a general chairman of 7th ICDL, chairman of the Autonomous Mental Development Technical Committee of the IEEE Computational Intelligence Society (2004–2005), an Associate Editor of IEEE TRANSACTIONS ON PATTERN RECOGNITION AND MACHINE INTELLIGENCE, an Associate Editor of IEEE TRANSACTIONS ON

IMAGE PROCESSING. He and his colleagues developed the SAIL and Dav experimental robots.



Ming Xie received the B.Eng. degree in control and automation in 1984, the Master degree in industrial automation from the University of Valenciennes, France, in 1986, and the Ph.D. degree in informatics from the University of Rennes, France, in 1989.

He has been a Research Assistant at IRISA-INRIA Rennes, France, between 1986 and 1989. He has published one best-seller book in robotics, has won two scientific awards, and also has won two best conference paper awards. He has worked with Renault Automation (Paris/France) in 1986, INRIA Sophia-Antipolis (Nice/France) between 1990 and 1993, and Singapore-MIT Alliance between 2000 and 2004. In addition, he has served as technical consultants to Asia Electronics Pte. Ltd., in 1994, Port of Singapore Authority in 1994, Delphi Automotive Systems Pte. Ltd., in 2001, ST Aerospace Ltd., in 2006, Murata Electronics Pte. Ltd., in 2007, and Sony Electronics Pte. Ltd. in 2007. He has taught a number of university courses such as applied machine vision, robotics, computer graphics, statistical process control, and physics. His research strengths are in machine intelligence, humanoid robotics and autonomous vehicles.

Xiangyang Xue received the B.S., M.S., and Ph.D. degrees in communication engineering from Xidian University, Xi'an, China, in 1989, 1992, and 1995, respectively.

He is a Professor of computer science at Fudan University, Shanghai, China. From 1995 to 1996, he was a Postdoctoral Research Fellow at Fudan University. Since 1997, he has been with the Computer Science Department at Fudan University. He has authored more than 80 research articles in the area of image and video indexing, digital watermarking, pattern recognition, and neural network. His current research interests include multimedia information retrieval, machine learning, artificial neural network, and multimodal human-computer interactions.

