## Bisimulation minimisation mostly speeds up probabilistic model checking

Joost-Pieter Katoen ${ }^{1,2}$, Tim Kemna ${ }^{1}$, Ivan Zapreev ${ }^{1,2}$ and David N. Jansen ${ }^{1,2}$

University of Twente ${ }^{1}$

RWTH-Aachen ${ }^{2}$
March 28, 2007

## Probabilistic model checking

(1) Enjoys a rapid increase of interest
(3) Formalisms that use probabilistic model checking - Probabilistic extension of Promela (Baier et al., 2005a) - Stochastic process algebra PEPA (Hillston, 1996) - Stochastic Petri nets (D'Aprile et al., 2004) - Statemate (Bode et al.. 2006)

## Probabilistic model checking

(1) Enjoys a rapid increase of interest
(2) Case studies:

- Biological process modeling
- Communication protocols
- Randomised algorithms
- Quantum computing
- Planning and AI
- Security


## Probabilistic model checking

(1) Enjoys a rapid increase of interest
(2) Case studies:

- Biological process modeling
- Communication protocols
- Randomised algorithms
- Quantum computing
- Planning and AI
- Security
(3) Formalisms that use probabilistic model checking:
- Probabilistic extension of Promela (Baier et al., 2005a)
- Stochastic process algebra PEPA (Hillston, 1996)
- Stochastic Petri nets (D'Aprile et al., 2004)
- Statemate (Bode et al., 2006)


## Probabilistic model checking

(1) Enjoys a rapid increase of interest
(2) Case studies:

- Biological process modeling
- Communication protocols
- Randomised algorithms
- Quantum computing
- Planning and AI
- Security
(3) Formalisms that use probabilistic model checking:
- Probabilistic extension of Promela (Baier et al., 2005a)
- Stochastic process algebra PEPA (Hillston, 1996)
- Stochastic Petri nets (D'Aprile et al., 2004)
- Statemate (Bode et al., 2006)
(3) Model checking tools:
- LiQuor (Baier et al., 2005a)
- PRISM (Kwiatkowska et al., 2004)
- MRMC (Katoen et al., 2005)


## Motivation

## Probabilistic model checking

(1) State-space explosion
(2) State-space reduction techniques - Symmetry reduction (Kwiatkowska et al., 2006) - Binary decision diagrams (Kwiatkowska et al., 200 - Abstraction refinement (D'Argenio et al., 2001) - Bisimulation equivalences (Baier et al., 2005b)

[^0]
## Motivation

## Probabilistic model checking

(1) State-space explosion
(2) State-space reduction techniques:

- Symmetry reduction (Kwiatkowska et al., 2006)
- Binary decision diagrams (Kwiatkowska et al., 2004)
- Abstraction refinement (D'Argenio et al., 2001)
- Bisimulation equivalences (Baier et al., 2005b)


## Motivation

## Probabilistic model checking

(1) State-space explosion
(2) State-space reduction techniques:

- Symmetry reduction (Kwiatkowska et al., 2006)
- Binary decision diagrams (Kwiatkowska et al., 2004)
- Abstraction refinement (D'Argenio et al., 2001)
- Bisimulation equivalences (Baier et al., 2005b)


## Bisimulation minimization

- Huge state-space reduction
- Is fully automated
- Drastic time penalty for LTL model checking (Fisler and Vardi, 1998; Fisler and Vardi, 1999; Fisler and Vardi, 2002)


## Motivation

## Probabilistic model checking

(1) State-space explosion
(2) State-space reduction techniques:

- Symmetry reduction (Kwiatkowska et al., 2006)
- Binary decision diagrams (Kwiatkowska et al., 2004)
- Abstraction refinement (D'Argenio et al., 2001)
- Bisimulation equivalences (Baier et al., 2005b)


## Bisimulation minimization

- Huge state-space reduction
- Is fully automated
- Drastic time penalty for LTL model checking (Fisler and Vardi, 1998; Fisler and Vardi, 1999; Fisler and Vardi, 2002)


## Motivation

## Probabilistic model checking

(1) State-space explosion
(2) State-space reduction techniques:

- Symmetry reduction (Kwiatkowska et al., 2006)
- Binary decision diagrams (Kwiatkowska et al., 2004)
- Abstraction refinement (D'Argenio et al., 2001)
- Bisimulation equivalences (Baier et al., 2005b)


## Bisimulation minimization

- Huge state-space reduction
- Is fully automated
- Drastic time penalty for LTL model checking (Fisler and Vardi, 1998; Fisler and Vardi, 1999; Fisler and Vardi, 2002)


## Motivation

## Probabilistic model checking

(1) State-space explosion
(2) State-space reduction techniques:

- Symmetry reduction (Kwiatkowska et al., 2006)
- Binary decision diagrams (Kwiatkowska et al., 2004)
- Abstraction refinement (D'Argenio et al., 2001)
- Bisimulation equivalences (Baier et al., 2005b)


## Bisimulation minimization

- Huge state-space reduction
- Is fully automated
- Drastic time penalty for LTL model checking
(Fisler and Vardi, 1998; Fisler and Vardi, 1999; Fisler and Vardi, 2002)


## What is our contribution?

## An empirical study

We did an empirical study on the effect of bisimulation minimization on probabilistic model checking.

## What is our contribution?

## An empirical study

We did an empirical study on the effect of bisimulation minimization on probabilistic model checking.

## Our main result

Bisimulation minimization often pays off.

## What is our contribution?

## Consider

- Known theory
- Discrete and continuous time Markov Chains
- Reward extensions


## An empirical study

- Use benchmark problems in the field (Kwiatkowska et al., 2007)
- Investigate 7 case studies
- Perform about 1870 experiments


## Focus on

- The state-space reduction
- Time of lumping + verification
- Peak-memory consumption


## What is our contribution?

## Consider

- Known theory
- Discrete and continuous time Markov Chains
- Reward extensions


## An empirical study

- Use benchmark problems in the field (Kwiatkowska et al., 2007)
- Investigate 7 case studies
- Perform about 1870 experiments


## Focus on

- The state-space reduction
- Time of lumping + verification
- Peak-memory consumption


## What is our contribution?

## Consider

- Known theory
- Discrete and continuous time Markov Chains
- Reward extensions


## An empirical study

- Use benchmark problems in the field (Kwiatkowska et al., 2007)
- Investigate 7 case studies
- Perform about 1870 experiments


## Focus on

- The state-space reduction
- Time of lumping + verification
- Peak-memory consumption


## What is our contribution?

## Consider

- Known theory
- Discrete and continuous time Markov Chains
- Reward extensions


## An empirical study

- Use benchmark problems in the field (Kwiatkowska et al., 2007)
- Investigate 7 case studies
- Perform about 1870 experiments


## Focus on

- The state-space reduction
- Time of lumping + verification
- Peak-memory consumption


## What is our contribution?

## Consider

- Known theory
- Discrete and continuous time Markov Chains
- Reward extensions


## An empirical study

- Use benchmark problems in the field (Kwiatkowska et al., 2007)
- Investigate 7 case studies
- Perform about 1870 experiments


## Focus on

- The state-space reduction
- Time of lumping + verification
- Peak-memory consumption


## What is our contribution?

## Consider

- Known theory
- Discrete and continuous time Markov Chains
- Reward extensions


## An empirical study

- Use benchmark problems in the field (Kwiatkowska et al., 2007)
- Investigate 7 case studies
- Perform about 1870 experiments


## Focus on

- The state-space reduction
- Time of lumping + verification
- Peak-memory consumption


## What is our contribution?

## Consider

- Known theory
- Discrete and continuous time Markov Chains
- Reward extensions


## An empirical study

- Use benchmark problems in the field (Kwiatkowska et al., 2007)
- Investigate 7 case studies
- Perform about 1870 experiments


## Focus on

- The state-space reduction
- Time of lumping + verification
- Peak-memory consumption


## What is our contribution?

## Consider

- Known theory
- Discrete and continuous time Markov Chains
- Reward extensions


## An empirical study

- Use benchmark problems in the field (Kwiatkowska et al., 2007)
- Investigate 7 case studies
- Perform about 1870 experiments


## Focus on

- The state-space reduction
- Time of lumping + verification
- Peak-memory consumption


## What is our contribution?

## Consider

- Known theory
- Discrete and continuous time Markov Chains
- Reward extensions


## An empirical study

- Use benchmark problems in the field (Kwiatkowska et al., 2007)
- Investigate 7 case studies
- Perform about 1870 experiments


## Focus on

- The state-space reduction
- Time of lumping + verification
- Peak-memory consumption
(2) Preliminaries
(3) Bisimulation minimization

4 Experimental results
(5) Conclusions and future works

## The considered models

## Definition ( Discrete time Markov chain)

A (labelled) DTMC is a tuple $(S, \mathcal{P}, A P, L)$ :

- $S$ - a finite set of states,
- AP - a finite set of atomic propositions,
- $L: S \rightarrow 2^{A P}$ - a labelling function,
- $\mathcal{P}: S \times S \rightarrow[0,1]$ - a probability matrix,

$$
\sum_{s^{\prime} \in S} \mathcal{P}\left(s, s^{\prime}\right)=1 \text { for all } s \in S
$$



[^1]
## The considered models

Definition ( Discrete time Markov chain)
A (labelled) DTMC is a tuple $(S, \mathcal{P}, A P, L)$ :

- S - a finite set of states,
- AP - a finite set of atomic propositions,
- $L: S \rightarrow 2^{A P}$ - a labelling function,
- $\mathcal{P}: S \times S \rightarrow[0,1]$ - a probability matrix,

$$
\sum_{s^{\prime} \in S} \mathcal{P}\left(s, s^{\prime}\right)=1 \text { for all } s \in S
$$

## Plus

- Continuous time Markov chains
- Reward extentions of both



## Probabilistic time-bounded reachability

## Example

Determine states from which win states may be reached with a probability at least 0.9, within 10 time steps.

$$
\mathcal{P}_{\geq 0.9}\left(\diamond^{\leq 10} \text { win }\right)
$$



## Probabilistic time-bounded reachability

## Example

Determine states from which win states may be reached with a probability at least 0.9, within 10 time steps.

$$
\mathcal{P}_{\geq 0.9}\left(\diamond^{\leq 10} \text { win }\right)
$$



## Probabilistic time-bounded reachability

## Example

Determine states from which win states may be reached with a probability at least 0.9, within 10 time steps.

$$
\mathcal{P}_{\geq 0.9}\left(\diamond^{\leq 10} \text { win }\right)
$$



## Probabilistic time-bounded reachability

## Example

Determine states from which win states may be reached with a probability at least 0.9, within 10 time steps.

$$
\mathcal{P}_{\geq 0.9}\left(\diamond^{\leq 10} \text { win }\right)
$$



## Probabilistic time-bounded reachability

## Example

Determine states from which win states may be reached with a probability at least 0.9, within 10 time steps.

$$
\mathcal{P}_{\geq 0.9}\left(\diamond^{\leq 10} \text { win }\right)
$$

| Model | Example |
| :---: | :---: |
| DTMC | $\mathcal{P}_{\geq 0.9}(\diamond \leq 10$ win $)$ |
| CTMC | $\mathcal{P}_{\geq 0.9}(\triangle \leq 3.5$ win $)$ |
| Rewards | $\mathcal{P}_{\geq 0.9}\left(\diamond_{\leq 13.7}^{\leq 15}\right.$ win $)$ |



## Probabilistic time-bounded reachability

## Example

Determine states from which win states may be reached with a probability at least 0.9 , within 10 time steps.

$$
\mathcal{P}_{\geq 0.9}(\diamond \leq 10 \text { win })
$$

| Model | Logic |
| :---: | :---: |
| DTMC | PCTL |
|  | (Hansson and Jonsson, 1994) |
| CTMC | CSL |
| Rewards | PRCTL/CSRL |
|  | (Andova et al., 2003; Baier et al., 2000) |

## (1) Outline

## (2) Preliminaries

(3) Bisimulation minimization

4 Experimental results
(5) Conclusions and future works

## Bisimulation minimization

Definition (Strong bisimulation
(Buchholz, 1994; Hillston, 1996))

- Let $D=(S, \mathcal{P}, A P, L)$ be a DTMC.
- $\Delta$ an equivalence relation on $S$.
- $S / \Delta$ is the quotient of $S$ under $\Delta$.
- $\Delta$ is a strong bisimulation, if $s_{1} \Delta s_{2} \Rightarrow$

$$
\begin{array}{r}
L\left(s_{1}\right)=L\left(s_{2}\right) \\
\forall B \in S / \Delta: \mathcal{P}\left(s_{1}, B\right)=\mathcal{P}\left(s_{2}, B\right)
\end{array}
$$



## Bisimulation minimization

Definition (Strong bisimulation (Buchholz, 1994; Hillston, 1996))

- Let $D=(S, \mathcal{P}, A P, L)$ be a DTMC.
- $\Delta$ an equivalence relation on $S$.
- $S / \Delta$ is the quotient of $S$ under $\Delta$.
- $\Delta$ is a strong bisimulation, if $s_{1} \Delta s_{2} \Rightarrow$

$$
\begin{array}{r}
L\left(s_{1}\right)=L\left(s_{2}\right) \\
\forall B \in S / \Delta: \mathcal{P}\left(s_{1}, B\right)=\mathcal{P}\left(s_{2}, B\right)
\end{array}
$$



## Preservation results

## Theorem (1, (Aziz et al., 1995))

Let $D$ be a DTMC, $\Delta$ a bisimulation and $s \in S$. Then $\forall \Phi \in P C T L^{*}$

$$
s \models_{D} \Phi \Longleftrightarrow[s]_{\Delta} \models_{D / \Delta} \Phi
$$

## Preservation results

## Theorem (1, (Aziz et al., 1995))

Let $D$ be a DTMC, $\Delta$ a bisimulation and $s \in S$. Then $\forall \Phi \in P C T L^{*}$

$$
s \models_{D} \Phi \Longleftrightarrow[s]_{\Delta} \models_{D / \Delta} \Phi
$$

## Note

- Probabilistic bisimulation is the coarsest relation for Theor. 1.
- Since $s \sim[s]_{\Delta}$, verify properties on a bisimulation quotient.


## Preservation results

## Theorem (1, (Aziz et al., 1995))

Let $D$ be a DTMC, $\Delta$ a bisimulation and $s \in S$. Then $\forall \Phi \in P C T L^{*}$

$$
s \models_{D} \Phi \Longleftrightarrow[s]_{\Delta} \models_{D / \Delta} \Phi
$$

## Note

- Probabilistic bisimulation is the coarsest relation for Theor. 1.
- Since $s \sim[s]_{\Delta}$, verify properties on a bisimulation quotient.


## Preservation results

## Theorem (1, (Aziz et al., 1995))

Let $D$ be a DTMC, $\Delta$ a bisimulation and $s \in S$. Then $\forall \Phi \in P C T L^{*}$

$$
s \models_{D} \Phi \Longleftrightarrow[s]_{\Delta} \models_{D / \Delta} \Phi
$$

## Note

- Probabilistic bisimulation is the coarsest relation for Theor. 1.
- Since $s \sim[s]_{\Delta}$, verify properties on a bisimulation quotient.


## Measure-driven bisimulation

Definition ( $F$-bisimulation (Baier et al., 2000))

- Let $D=(S, \mathcal{P}, A P, L)$ be a DTMC.
- $F$ is a subset of PCTL formulas.
- $\Delta$ an equivalence relation on $S$.
- $S / \Delta$ is the quotient of $S$ under $\Delta$.
- $\Delta$ is an $F$-bisimulation on $S$, if $s_{1} \Delta s_{2}$ :

$$
\begin{array}{r}
\forall \Phi \in F: s_{1} \models \Phi \Longleftrightarrow s_{2} \models \Phi \\
\forall B \in S / \Delta: \mathcal{P}\left(s_{1}, B\right)=\mathcal{P}\left(s_{2}, B\right)
\end{array}
$$

## Measure-driven bisimulation

Definition ( $F$-bisimulation (Baier et al., 2000))

- Let $D=(S, \mathcal{P}, A P, L)$ be a DTMC.
- $F$ is a subset of PCTL formulas.
- $\Delta$ an equivalence relation on $S$.
- $S / \Delta$ is the quotient of $S$ under $\Delta$.
- $\Delta$ is an $F$-bisimulation on $S$, if $s_{1} \Delta s_{2}$ :

$$
\begin{array}{r}
\forall \Phi \in F: s_{1} \models \Phi \Longleftrightarrow s_{2} \models \Phi \\
\forall B \in S / \Delta: \mathcal{P}\left(s_{1}, B\right)=\mathcal{P}\left(s_{2}, B\right)
\end{array}
$$

## Example ( $F$-bisimulation)

Let us take $F=\{$ win $\}$.


## Measure-driven bisimulation

Definition ( $F$-bisimulation (Baier et al., 2000))

- Let $D=(S, \mathcal{P}, A P, L)$ be a DTMC.
- $F$ is a subset of PCTL formulas.
- $\Delta$ an equivalence relation on $S$.
- $S / \Delta$ is the quotient of $S$ under $\Delta$.
- $\Delta$ is an $F$-bisimulation on $S$, if $s_{1} \Delta s_{2}$ :

$$
\begin{array}{r}
\forall \Phi \in F: s_{1} \models \Phi \Longleftrightarrow s_{2} \models \Phi \\
\forall B \in S / \Delta: \mathcal{P}\left(s_{1}, B\right)=\mathcal{P}\left(s_{2}, B\right)
\end{array}
$$

## Example ( $F$-bisimulation)

Let us take $F=\{$ win $\}$.


## Preservation results

## Theorem ((Baier et al., 2003))

Let $D$ be a DTMC, $\Delta$ an $F$-bisimulation and $s \in S$. Then $\forall \Phi \in P C T L_{F}$

$$
s \models_{D} \Phi \Longleftrightarrow[s]_{\Delta} \models_{D / \Delta} \Phi
$$

## Preservation results

## Theorem ((Baier et al., 2003))

Let $D$ be a DTMC, $\Delta$ an $F$-bisimulation and $s \in S$. Then $\forall \Phi \in P C T L_{F}$

$$
s \models_{D} \Phi \Longleftrightarrow[s]_{\Delta} \models_{D / \Delta} \Phi
$$

Strong bisimulation vs. F-bisimulation

- Strong bisimilarity is $F$-bisimilarity for $F=A P$
- $F$-bisimulation is coarser than strong bisimulation
- Verify properties on F-bisimulation quotient


## Obtaining bisimulation quotient

## Strong bisimulation (Derisavi et al., 2003)

- Partition refinement algorithm
- The worst-time complexity is $O(|P| \log |S|)$


## Obtaining bisimulation quotient

## Strong bisimulation (Derisavi et al., 2003)

- Partition refinement algorithm
- The worst-time complexity is $O(|P| \log |S|)$


## $F$-bisimulation

- A slight modification of the partition refinement algorithm.


## Initial partitioning for $\mathcal{P}_{\unlhd p}(\Phi \mathrm{U} \Psi)$ and $\mathcal{P}_{\unlhd p}\left(\Phi \mathrm{U}^{[0, t]} \Psi\right)$

## Note

- Strong bisimulation: Atomic propositions
- $F$ - bisimulation:

Formulas $\Phi, \Psi$

## Initial partitioning for $\mathcal{P}_{\unlhd p}(\Phi \mathrm{U} \Psi)$ and $\mathcal{P}_{\unlhd p}\left(\Phi \mathrm{U}^{[0, t]} \Psi\right)$

## Note

- Strong bisimulation: Atomic propositions
- $F$ - bisimulation:

Formulas $\Phi, \Psi$

## Initial partitioning for $\mathcal{P}_{\unlhd p}(\Phi \mathrm{U} \Psi)$ and $\mathcal{P}_{\unlhd p}\left(\Phi \mathrm{U}^{[0, t]} \Psi\right)$

## Note

- Strong bisimulation: Atomic propositions
- $F$ - bisimulation:

Formulas $\Phi, \Psi$
$\mathcal{P}_{\unlhd p}(\Phi \mathrm{U} \Psi)$

- Define $U_{0}=\operatorname{Sat}\left(\mathcal{P}_{\leq 0}(\Phi \mathrm{U} \Psi)\right)$.
- Define $U_{1}=\operatorname{Sat}\left(\mathcal{P}_{\geq 1}(\Phi \mathrm{U} \Psi)\right)$.
- Choose $F=\left\{U_{0}, U_{1}, S \backslash\left(U_{0} \cup U_{1}\right)\right\}$.
- Apply F-bisimulation.


## Initial partitioning for $\mathcal{P}_{\unlhd p}(\Phi \mathrm{U} \Psi)$ and $\mathcal{P}_{\unlhd p}\left(\Phi \mathrm{U}^{[0, t]} \Psi\right)$

## Note

- Strong bisimulation:

Atomic propositions

- $F$-bisimulation:

Formulas $\Phi, \Psi$
$\mathcal{P}_{\unlhd p}(\Phi \mathrm{U} \Psi)$

- Define $U_{0}=\operatorname{Sat}\left(\mathcal{P}_{\leq 0}(\Phi U \Psi)\right)$.
- Define $U_{1}=\operatorname{Sat}\left(\mathcal{P}_{\geq 1}(\Phi \mathrm{U} \Psi)\right)$.
- Choose $F=\left\{U_{0}, U_{1}, S \backslash\left(U_{0} \cup U_{1}\right)\right\}$.
- Apply F-bisimulation.


## $\mathcal{P}_{\unlhd p}\left(\Phi \mathrm{U}^{[0, t]} \Psi\right)$

- Define $U_{0}=\operatorname{Sat}\left(\mathcal{P}_{\leq 0}(\Phi \mathrm{U} \Psi)\right)$.
- Define $S_{1}=\operatorname{Sat}(\Psi)$.
- Choose $F=\left\{U_{0}, S_{1}, S \backslash\left(U_{0} \cup S_{1}\right)\right\}$.
- Apply F-bisimulation.


## Initial partitioning for $\mathcal{P}_{\unlhd p}(\Phi \mathrm{U} \Psi)$ and $\mathcal{P}_{\unlhd p}\left(\Phi \mathrm{U}^{[0, t]} \Psi\right)$

## Note

- Strong bisimulation:

Atomic propositions

- $F$-bisimulation:

Formulas $\Phi, \Psi$

## $S_{1}$ vs. $U_{1}$

A finer initial partitioning
$\mathcal{P}_{\unlhd p}(\Phi \mathrm{U} \Psi)$

- Define $U_{0}=\operatorname{Sat}\left(\mathcal{P}_{\leq 0}(\Phi \mathrm{U} \Psi)\right)$.
- Define $U_{1}=\operatorname{Sat}\left(\mathcal{P}_{\geq 1}(\Phi \mathrm{U} \Psi)\right)$.
- Choose $F=\left\{U_{0}, U_{1}, S \backslash\left(U_{0} \cup U_{1}\right)\right\}$.
- Apply F-bisimulation.
$\mathcal{P}_{\unlhd p}\left(\Phi \mathrm{U}^{[0, t]} \Psi\right)$
- Define $U_{0}=\operatorname{Sat}\left(\mathcal{P}_{\leq 0}(\Phi \mathrm{U} \Psi)\right)$.
- Define $S_{1}=\operatorname{Sat}(\Psi)$.
- Choose $F=\left\{U_{0}, S_{1}, S \backslash\left(U_{0} \cup S_{1}\right)\right\}$.
- Apply F-bisimulation.
(2) Preliminaries
(3) Bisimulation minimization

4 Experimental results
(5) Conclusions and future works

## Cyclic polling server (Ibe and Trivedi, 1990)



State-space reductions for $\mathcal{P}_{\leq q}\left(\neg\right.$ serve $_{1} \mathrm{U}^{[0,1010]}$ serve $\left._{1}\right)$ and

$$
\mathcal{P}_{\leq q}\left(\neg \text { serve }_{1} \mathrm{U} \text { serve }_{1}\right)
$$

Bisimulation minimisation mostly speeds up probabilistic model checking
Experimental results

## Cyclic polling server (Ibe and Trivedi, 1990)



Original $\Phi \mathrm{U}^{[0, t]} \Psi$
Original $\Phi \mathrm{U} \Psi$
$\Phi \mathrm{U}^{[0, t]} \psi$
$\phi U \Psi$

Run times for $\mathcal{P}_{\leq q}\left(\neg\right.$ serve $_{1} \mathrm{U}^{[0,1010]}$ serve $\left._{1}\right)$ and $\mathcal{P}_{\leq q}\left(\neg\right.$ serve $_{1} \mathrm{U}$ serve $\left.{ }_{1}\right)$

## Crowds protocol (Reiter and Rubin, 1998)



State-space reductions for eventually observing the real sender more than once

## Crowds protocol (Reiter and Rubin, 1998)

verification (+ lumping) time (in ms )


Run times for eventually observing the real sender more than once

## Simple P2P protocol (Kwiatkowska et al., 2006)

|  |  |  | symmetry reduction (Kwiatkowska et al., 2006) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| original CTMC |  |  | reduced CTMC |  |  | red. factor |  |
| $N$ | states | ver. time | states | red. time | ver. time | states | time |
| 2 | 1024 | 5.6 | 528 | 12 | 2.9 | 1.93 | 0.38 |
| 3 | 32768 | 410 | 5984 | 100 | 59 | 5.48 | 2.58 |
| 4 | 1048576 | 22000 | 52360 | 360 | 820 | 20.0 | 18.3 |


|  |  | bisimulation minimisation |  |  |  |  |  |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| original CTMC |  | lumped CTMC |  |  | red. factor |  |  |
| $N$ | states | ver. time | blocks | lump time | ver. time | states | time |
| 2 | 1024 | 5.6 | 56 | 1.4 | 0.3 | 18.3 | 3.3 |
| 3 | 32768 | 410 | 252 | 170 | 1.3 | 130 | 2.4 |
| 4 | 1048576 | 22000 | 792 | 10200 | 4.8 | 1324 | 2.2 |

## Simple P2P protocol (Kwiatkowska et al., 2006)

|  |  |  | symmetry reduction (Kwiatkowska et al., 2006) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| original CTMC |  |  | reduced CTMC |  |  | red. factor |  |
| $N$ | states | ver. time | states | red. time | ver. time | states | time |
| 2 | 1024 | 5.6 | 528 | 12 | 2.9 | 1.93 | 0.38 |
| 3 | 32768 | 410 | 5984 | 100 | 59 | 5.48 | 2.58 |
| 4 | 1048576 | 22000 | 52360 | 360 | 820 | 20.0 | 18.3 |


|  |  | bisimulation minimisation |  |  |  |  |  |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| original CTMC |  | lumped CTMC |  |  | red. factor |  |  |
| $N$ | states | ver. time | blocks | lump time | ver. time | states | time |
| 2 | 1024 | 5.6 | 56 | 1.4 | 0.3 | 18.3 | 3.3 |
| 3 | 32768 | 410 | 252 | 170 | 1.3 | 130 | 2.4 |
| 4 | 1048576 | 22000 | 792 | 10200 | 4.8 | 1324 | 2.2 |

## Simple P2P protocol (Kwiatkowska et al., 2006)

|  |  |  | symmetry reduction (Kwiatkowska et al., 2006) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| original CTMC |  |  | reduced CTMC |  |  | red. factor |  |
| $N$ | states | ver. time | states | red. time | ver. time | states | time |
| 2 | 1024 | 5.6 | 528 | 12 | 2.9 | 1.93 | 0.38 |
| 3 | 32768 | 410 | 5984 | 100 | 59 | 5.48 | 2.58 |
| 4 | 1048576 | 22000 | 52360 | 360 | 820 | 20.0 | 18.3 |


|  |  | bisimulation minimisation |  |  |  |  |  |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| original CTMC |  | lumped CTMC |  |  | red. factor |  |  |
| $N$ | states | ver. time | blocks | lump time | ver. time | states | time |
| 2 | 1024 | 5.6 | 56 | 1.4 | 0.3 | 18.3 | 3.3 |
| 3 | 32768 | 410 | 252 | 170 | 1.3 | 130 | 2.4 |
| 4 | 1048576 | 22000 | 792 | 10200 | 4.8 | 1324 | 2.2 |

## Simple P2P protocol (Kwiatkowska et al., 2006)

|  |  | symmetry reduction (Kwiatkowska et al., 2006) |  |  |  |  |  |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: | :---: |
| original CTMC |  | reduced CTMC |  |  | red. factor |  |  |
| $N$ | states | ver. time | states | red. time | ver. time | states | time |
| 2 | 1024 | 5.6 | 528 | 12 | 2.9 | 1.93 | 0.38 |
| 3 | 32768 | 410 | 5984 | 100 | 59 | 5.48 | 2.58 |
| 4 | 1048576 | 22000 | 52360 | 360 | 820 | 20.0 | 18.3 |


|  |  | bisimulation minimisation |  |  |  |  |  |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| original CTMC |  | lumped CTMC |  |  | red. factor |  |  |
| $N$ | states | ver. time | blocks | lump time | ver. time | states | time |
| 2 | 1024 | 5.6 | 56 | 1.4 | 0.3 | 18.3 | 3.3 |
| 3 | 32768 | 410 | 252 | 170 | 1.3 | 130 | 2.4 |
| 4 | 1048576 | 22000 | 792 | 10200 | 4.8 | 1324 | 2.2 |

## (1) Outline

(2) Preliminaries
(3) Bisimulation minimization

4 Experimental results
(5) Conclusions and future works

## The end

## Concluding remarks

- Significant, up to logarithmic, state-space reduction.
- The abstraction technique is fully automated.
- Strong bisimulation:
- Sometimes, a substantial model-checking time reduction.
- Sometimes, an increase of peak memory (by $50 \%$ ).
- F-bisimulation:
- Sometimes, a substantial model-checking time reduction.
- The peak memory use is typically unchanged.
- For reward case a decrease of peak memory (by 20-40\%).


## Future work

- Combine symmetry reduction with bisimulation.
- Extend experiments towards MDPs and simulation preorders.

Andova, S., Hermanns, H., and Katoen, J.-P.: 2003,
in Formal Modeling and Analysis of Timed Systems (FORMATS), LNCS, Marseille, France
Aziz, A., Sanwal, K., Singhal, V., Brayton, R. K., and Sangiovanni-Vincentelli: 1995,
in Computer Aided Verification (CAV), pp 155-165, Berlin, Germany
Baier, C., Ciesinski, F., and Gr\&\#246;\&\#223;er, M.: 2005a,
SIGMETRICS Perform. Eval. Rev. 32(4), 22
Baier, C., Haverkort, B., Hermanns, H., and Katoen, J.-P.: 2003,
IEEE Trans. on Softw. Eng. 29(6), 524
Baier, C., Haverkort, B. R., Hermanns, H., and Katoen, J.-P.: 2000, in International Colloquium on Automata, Languages and Programming (ICALP), pp 780-792, London, UK

Baier, C., Katoen, J.-P., Hermanns, H., and Wolf, V.: 2005b, Inf. Comput. 200(2), 149

Bode, E., Herbstritt, M., Hermanns, H., Johr, S., Peikenkamp, T., Pulungan, R., Wimmer, R., and Becker, B.: 2006,
in QEST '06: Proceedings of the Third International Conference on the Quantitative Evaluation of Systems (QEST'06), pp 167-178, IEEE Computer Society, Washington, DC, USA

Buchholz, P.: 1994,
Journal of Applied Probability 31, 59
D'Aprile, D., Donatelli, S., and Sproston, J.: 2004, in Int. Symp. on Computer and Information Sciences, Vol. 3280 of LNCS, pp 543-552

D'Argenio, P. R., Jeannet, B., Jensen, H. E., and Larsen, K. G.: 2001, in PAPM-PROBMIV '01: Proceedings of the Joint International Workshop on Process Algebra and Probabilistic Methods, Performance Modeling and Verification, pp 39-56, Springer-Verlag, London, UK

Derisavi, S., Hermanns, H., and Sanders, W. H.: 2003, Inf. Process. Lett. 87(6), 309

Fisler, K. and Vardi, M. Y.: 1998,
in FMCAD, Vol. 1522 of LNCS, pp 115-132
Fisler, K. and Vardi, M. Y.: 1999,
in CHARME, Vol. 1703 of LNCS, pp 338-342
Fisler, K. and Vardi, M. Y.: 2002,
in Formal Methods in System Design, Vol. 21, pp 39-78
Hansson, N. and Jonsson, B.: 1994,
Formal Aspects of Computing 6, 512
Hillston, J.: 1996,
A compositional approach to performance modelling,
Cambridge University Press, New York, NY, USA
Ibe, O. C. and Trivedi, K. S.: 1990,
in IEEE J. on Selected Areas in Communications, Vol. 8, pp 1649-1657
Katoen, J.-P., Khattri, M., and Zapreev, I. S.: 2005,
in Quantitative Evaluation of Systems (QEST), pp 243-244
Kwiatkowska, M., Norman, G., and Parker, D.: 2004,
International Journal on Software Tools for Technology Transfer (STTT) 6(2), 128
Kwiatkowska, M., Norman, G., and Parker, D.: 2006,
in T. Ball and R. Jones (eds.), Proc. 18th International Conference on Computer Aided Verification (CAV'06), Vol. 4114 of LNCS, pp 234-248, Springer-Verlag

Kwiatkowska, M., Norman, G., and Parker, D.: 2007,
http:www.cs.bham.ac.uk dxpprismcasestudies
Reiter, M. K. and Rubin, A.: 1998,
in ACM Transactions on Information and System Security, Vol. 1, pp 66-92


[^0]:    Bisimulation minimization

    - Huge state-space reduction
    - Is fully automated
    - Drastic time penalty for LTL model checking (Fisler and Vardi, 1998; Fisler and Vardi, 1999; Fisler and Vardi, 2002)

[^1]:    - Reward extentions of both

