# Ginzburg-Landau Vortices for Thin Ferromagnetic Films 

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## 1 Introduction

In this paper, we consider ferromagnetic bodies, represented by a bounded, open domain $\Omega \subset \mathbb{R}^{3}$. The magnetization of $\Omega$ is described by a vector field $m: \Omega \rightarrow \mathbb{R}^{3}$ which satisfies the saturation constraint $|m|=1$ almost everywhere. In the absence of an external magnetic field, and with the contribution of a crystalline anisotropy neglected, the energy of this configuration, as derived in the theory of micromagnetics, is given by the expression

$$
\begin{equation*}
\mathcal{E}(\mathrm{m})=\frac{\epsilon^{2}}{2} \int_{\Omega}|\nabla \mathrm{m}|^{2} \mathrm{~d} x+\frac{1}{2} \int_{\mathbb{R}^{3}}|\nabla u|^{2} \mathrm{~d} x \tag{1.1}
\end{equation*}
$$

where $u \in H^{1}\left(\mathbb{R}^{3}\right)$ is determined by the static Maxwell equations, written in the form

$$
\begin{equation*}
\Delta u=\operatorname{div} m \quad \text { in } \mathbb{R}^{3} \tag{1.2}
\end{equation*}
$$

Here $m$ is extended by 0 outside of $\Omega$.
The first term on the right-hand side of (1.1), called the exchange energy, penalizes spatial variations of $m$. It models the tendency for parallel alignment of the magnetization vectors of the underlying atomic structure. The parameter $\epsilon$ is a material constant. The second term is the so-called magnetostatic energy. It corresponds to the energy of the magnetic field induced by $m$. For more details, see, for example, Hubert and Schäfer [15].

Our aim is to study minimizers of $\mathcal{E}$ for ferromagnetic samples in the shape of very thin films. That is, we assume that $\Omega$ is of the form $\Omega=\Omega^{\prime} \times(0, \delta)$ for a small
number $\delta>0$. We want to find the limiting behaviour for this variational problem in a special asymptotic regime, defined by certain relations between the thickness $\delta$ of the film, the length scale $L$ of the cross section $\Omega^{\prime}$, and the parameter $\epsilon$. Namely, we study the limit $\delta / \mathrm{L} \rightarrow 0$ under the condition $\epsilon^{2} / \mathrm{L} \delta=1$. With respect to polynomial order, this is the border case of the situation studied by DeSimone, Kohn, Müller, and Otto [8]. In that paper, the limiting behaviour for $\delta / \mathrm{L} \rightarrow 0$ and $\left(\epsilon^{2} / \mathrm{L} \delta\right) \log (\mathrm{L} / \delta) \rightarrow 0$ was established.

For simplicity, we set $\mathrm{L}=1$ in the rest of the paper. Thus the condition above yields $\delta=\epsilon^{2}$. We assume that $\Omega^{\prime} \subset \mathbb{R}^{2}$ is a bounded, open, simply connected domain with smooth boundary. For $0<\epsilon \leq 1$, we define $\Omega_{\epsilon}=\Omega^{\prime} \times\left(0, \epsilon^{2}\right)$. For a vector field $m \in L^{2}\left(\Omega_{\epsilon}, \mathbb{R}^{3}\right)$, we denote by $u_{\epsilon}(\mathfrak{m})$ the unique distributional solution of equation (1.2) for $\Omega=\Omega_{\epsilon}$ in the space $H^{1}\left(\mathbb{R}^{3}\right)$. That is, $u_{\epsilon}(\mathfrak{m}) \in H^{1}\left(\mathbb{R}^{3}\right)$ is to satisfy

$$
\begin{equation*}
\int_{\mathbb{R}^{3}} \nabla \mathfrak{u}_{\epsilon}(\mathfrak{m}) \cdot \nabla \phi \mathrm{dx}=\int_{\Omega_{e}} m \cdot \nabla \phi \mathrm{dx} \tag{1.3}
\end{equation*}
$$

for all $\phi \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{3}\right)$. For $k \geq 1$, let $\mathbb{S}^{k}$ denote the unit sphere in $\mathbb{R}^{k+1}$. Divide $\mathcal{E}$ by $\epsilon^{4}$ to obtain the functionals

$$
\begin{equation*}
\mathrm{E}_{\epsilon}(\mathfrak{m})=\frac{1}{2 \epsilon^{2}}\left(\int_{\Omega_{\epsilon}}|\nabla \mathfrak{m}|^{2} \mathrm{~d} x+\frac{1}{\epsilon^{2}} \int_{\mathbb{R}^{3}}\left|\nabla \mathfrak{u}_{\epsilon}(\mathfrak{m})\right|^{2} \mathrm{~d} x\right) \tag{1.4}
\end{equation*}
$$

on the spaces

$$
\begin{equation*}
\mathrm{H}^{1}\left(\Omega_{\epsilon}, \mathbb{S}^{2}\right)=\left\{m \in \mathrm{H}^{1}\left(\Omega_{\epsilon}, \mathbb{R}^{3}\right):|m|=1 \text { almost everywhere }\right\} . \tag{1.5}
\end{equation*}
$$

Note that one of the properties of the magnetostatic energy is that it favours a magnetization which is tangential on the boundary $\partial \Omega_{\epsilon}$. Thus for minimizers of $E_{\epsilon}$, the third component of $m$ tends to be small on the surfaces $\Omega^{\prime} \times\left\{0, \epsilon^{2}\right\}$ (cf. Section 2 ).

We now consider the limit $\epsilon \searrow 0$. We first note that we have necessarily

$$
\begin{equation*}
\lim _{\epsilon \searrow 0} E_{\varepsilon}\left(m_{\varepsilon}\right)=\infty \tag{1.6}
\end{equation*}
$$

for any choice of $\mathfrak{m}_{\epsilon} \in H^{1}\left(\Omega_{\epsilon}, \mathbb{S}^{2}\right)$. Indeed, suppose this were not true. Then one could find a sequence $\epsilon_{k} \searrow 0$ such that the maps

$$
\begin{equation*}
\bar{m}_{k}\left(x^{\prime}\right)=\frac{1}{\epsilon_{\mathrm{k}}^{2}} \int_{0}^{\epsilon_{\mathrm{k}}^{2}} m_{\epsilon_{\mathrm{k}}}\left(x^{\prime}, s\right) \mathrm{d} s, \quad x^{\prime} \in \Omega^{\prime}, \tag{1.7}
\end{equation*}
$$

would converge weakly in $H^{1}\left(\Omega^{\prime}, \mathbb{R}^{3}\right)$. For the limit map $m \in H^{1}\left(\Omega^{\prime}, \mathbb{S}^{2}\right)$, write $m=\left(m^{\prime}\right.$, $\left.m^{3}\right)$, where $m^{\prime} \in H^{1}\left(\Omega^{\prime}, \mathbb{R}^{2}\right)$ and $m^{3} \in H^{1}\left(\Omega^{\prime}\right)$. Then it must satisfy $\left|m^{\prime}\right|=1$ and $m^{3}=0$
almost everywhere in $\Omega^{\prime}$, and $m^{\prime} \cdot v^{\prime}=0$ almost everywhere on $\partial \Omega^{\prime}$, where $v^{\prime}$ is the outer normal vector to $\partial \Omega^{\prime}$. (The arguments to prove this are given in the proof of Proposition 4.2.) But there is no map in $H^{1}\left(\Omega^{\prime}, \mathbb{R}^{3}\right)$ with these properties, hence (1.6) holds true. This rules out the "naive" approach of trying to establish weak $\mathrm{H}^{1}$-convergence for minimizers of $E_{\epsilon}$, or even $\Gamma$-convergence of the functionals.

What kind of limiting behaviour can one expect instead for $\epsilon \searrow 0$ ? Consider for the moment a simplification of $E_{\epsilon}$. Assume that the magnetization $m=\left(\mathfrak{m}^{\prime}, m^{3}\right)$ is independent of the third argument, and model the penalization of $m^{3}$ by the $L^{2}$-norm (instead of the magnetostatic energy). Owing to the constraint $|\mathrm{m}|=1$ almost everywhere, this leads to the functionals

$$
\begin{equation*}
\mathrm{F}_{\epsilon}(\mathfrak{m})=\frac{1}{2} \int_{\Omega^{\prime}}\left(\left|\nabla^{\prime} m\right|^{2}+\frac{1-\left|\mathfrak{m}^{\prime}\right|^{2}}{\epsilon^{2}}\right) \mathrm{d} x^{\prime}, \quad m=\left(\mathfrak{m}^{\prime}, \mathfrak{m}^{3}\right) \in H^{1}\left(\Omega^{\prime}, \mathbb{S}^{2}\right), \tag{1.8}
\end{equation*}
$$

where $\nabla^{\prime}=\left(\partial / \partial x^{1}, \partial / \partial x^{2}\right)$. This, on the other hand, is reminiscent of the GinzburgLandau functionals

$$
\begin{equation*}
I_{\epsilon}(f)=\frac{1}{2} \int_{\Omega^{\prime}}\left(\left|\nabla^{\prime} f\right|^{2}+\frac{1}{2 \epsilon^{2}}\left(|f|^{2}-1\right)^{2}\right) d x^{\prime}, \quad f \in H^{1}\left(\Omega^{\prime}, \mathbb{R}^{2}\right) . \tag{1.9}
\end{equation*}
$$

The limiting problem for $\epsilon \searrow 0$ for minimizers of $I_{\epsilon}$ was first studied by Bethuel, Brezis, and Hélein $[3,4]$, and by many other authors since then. One of the main results (which was proven in [4] for star-shaped domains, and extended by Struwe [25, 26] to arbitrary bounded domains with smooth boundaries) can be summarized as follows. Suppose that for $0<\epsilon \leq 1$, certain maps $f_{\epsilon} \in H^{1}\left(\Omega^{\prime}, \mathbb{R}^{2}\right)$ are given, which minimize $I_{\epsilon}$ for fixed Dirichlet boundary data $\mathrm{g}: \partial \Omega^{\prime} \rightarrow \mathbb{S}^{1}$. Then there exist finitely many points $x_{1}^{\prime}, \ldots, x_{\mathrm{N}}^{\prime} \in$ $\Omega^{\prime}$ (their number depending on the topological degree of $g$ ) and a sequence $\epsilon_{\mathrm{k}} \searrow 0$, such that the sequence $\left\{f_{\epsilon_{k}}\right\}$ converges in $C_{\text {loc }}^{\infty}\left(\Omega^{\prime} \backslash\left\{x_{1}^{\prime}, \ldots, x_{N}^{\prime}\right\}, \mathbb{R}^{2}\right)$ to a harmonic map $f$ : $\Omega \backslash\left\{x_{1}^{\prime}, \ldots, x_{N}^{\prime}\right\} \rightarrow \mathbb{S}^{1}$. Identifying $\mathbb{R}^{2}$ with the complex plane $\mathbb{C}$, we can write $f$ in the form

$$
\begin{equation*}
f(z)=\left(\prod_{j=1}^{N} \frac{z-z_{j}}{\left|z-z_{j}\right|}\right) e^{i \theta(z)}, \tag{1.10}
\end{equation*}
$$

or the complex conjugate of this, where $z_{j}=x_{j}^{1}+i x_{j}^{2}$ for $x_{j}^{\prime}=\left(x_{j}^{1}, x_{j}^{2}\right)$. The function $\theta$ satisfies $\Delta^{\prime} \theta=0$ in $\Omega^{\prime}$, where $\Delta^{\prime}$ is the Laplace operator in $\mathbb{R}^{2}$. This (and more) has been generalized to the corresponding problem for the functionals $F_{\varepsilon}$ by André and Shafrir [1] and Hang and Lin [11].

Our aim is to prove a similar result for minimizers of $\mathrm{E}_{\epsilon}$. For technical reasons, we impose Dirichlet boundary data on $\partial \Omega^{\prime} \times\left(0, \epsilon^{2}\right)$. It turns out (cf. Proposition 4.2) that only two choices for the boundary data are reasonable, namely,

$$
\begin{equation*}
m=\left(-v^{2}, \nu^{1}, 0\right) \quad \text { on } \partial \Omega^{\prime} \times\left(0, \epsilon^{2}\right) \tag{1.11}
\end{equation*}
$$

(where we write $\nu^{\prime}=\left(\nu^{1}, \nu^{2}\right)$ for the normal vector to $\partial \Omega^{\prime}$ ), and the same with $\nu^{\prime}$ replaced by $-v^{\prime}$. Moreover, the second case is reduced to the first one by reflection. Thus, we define $\bar{H}^{1}\left(\Omega_{\epsilon}, \mathbb{S}^{2}\right)$ to be the space of all maps $\mathfrak{m} \in \mathrm{H}^{1}\left(\Omega_{\epsilon}, \mathbb{S}^{2}\right)$ satisfying (1.11), and consider only maps therein. For every $\epsilon \in(0,1]$, we fix a map $m_{\epsilon}$ which minimizes $E_{\epsilon}$ in $\bar{H}^{1}\left(\Omega_{\epsilon}, \mathbb{S}^{2}\right)$.

The Euler-Lagrange equation for this variational problem is

$$
\begin{equation*}
\epsilon^{2}\left(\Delta \mathfrak{m}_{\epsilon}+\left|\nabla \mathfrak{m}_{\epsilon}\right|^{2} \mathfrak{m}_{\epsilon}\right)-\nabla \mathfrak{u}_{\epsilon}\left(\mathfrak{m}_{\epsilon}\right)+\left(\mathfrak{m}_{\epsilon} \cdot \nabla \mathfrak{u}_{\epsilon}\left(\mathfrak{m}_{\epsilon}\right)\right) \mathfrak{m}_{\epsilon}=0 \quad \text { in } \Omega_{\epsilon} \tag{1.12}
\end{equation*}
$$

and we have the homogeneous Neumann boundary conditions

$$
\begin{equation*}
\frac{\partial m_{\epsilon}}{\partial x^{3}}=0 \quad \text { on } \Omega^{\prime} \times\left\{0, \epsilon^{2}\right\} . \tag{1.13}
\end{equation*}
$$

There exists another form of (1.12) which will prove useful. Namely, denoting by $\wedge$ the exterior product $\wedge: \mathbb{R}^{n} \times \mathbb{R}^{n} \rightarrow \Lambda_{2} \mathbb{R}^{n}$, it is easily checked that (1.12) is equivalent to

$$
\begin{equation*}
\epsilon^{2} \operatorname{div}\left(\mathfrak{m}_{\epsilon} \wedge \nabla \mathfrak{m}_{\epsilon}\right)=\mathfrak{m}_{\epsilon} \wedge \nabla \mathfrak{u}_{\epsilon}\left(\mathfrak{m}_{\epsilon}\right) \quad \text { in } \Omega_{\epsilon} . \tag{1.14}
\end{equation*}
$$

Both (1.12) and (1.14) are to be understood in the distribution sense.
Before we state our first main result, we define the operator which is to play the role of a limit of $\epsilon^{-2} u_{\epsilon}$ for $\epsilon \searrow 0$. Suppose $m^{\prime} \in W^{1,4 / 3}\left(\Omega^{\prime}, \mathbb{R}^{2}\right)$ is a map with the property $m^{\prime} \cdot v^{\prime}=0$ almost everywhere on $\partial \Omega^{\prime}$. Then for any $\phi \in C_{0}^{\infty}\left(\mathbb{R}^{3}\right)$, we have

$$
\begin{align*}
\left|\int_{\Omega^{\prime}} m^{\prime}\left(x^{\prime}\right) \cdot \nabla^{\prime} \phi\left(x^{\prime}, 0\right) \mathrm{d} x^{\prime}\right| & =\left|\int_{\Omega^{\prime}} \operatorname{div}^{\prime} m^{\prime}\left(x^{\prime}\right)\left(\phi\left(x^{\prime}, 0\right)-f_{\Omega^{\prime}} \phi\left(y^{\prime}, 0\right) d y^{\prime}\right) d x^{\prime}\right| \\
& \leq C\left\|\operatorname{div}^{\prime} m^{\prime}\right\|_{L^{4 / 3}\left(\Omega^{\prime}\right)}\|\nabla \phi\|_{L^{2}\left(\mathbb{R}^{3}\right)} \tag{1.15}
\end{align*}
$$

for a constant $C=C\left(\Omega^{\prime}\right)$, owing to the continuity of the trace operator $T: H^{1}\left(\Omega_{1}\right) \rightarrow$ $L^{4}\left(\Omega^{\prime}\right)$, which is given by $\operatorname{Tv}\left(x^{\prime}\right)=v\left(x^{\prime}, 0\right)$. (Here div' denotes the divergence in $\mathbb{R}^{2}$.) Hence there exists a unique function $u\left(m^{\prime}\right) \in H_{\mathrm{loc}}^{1}\left(\mathbb{R}^{3}\right)$ with $\left\|\nabla u\left(\mathfrak{m}^{\prime}\right)\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{3}\right)}+\left\|u\left(m^{\prime}\right)\right\|_{\mathrm{L}^{6}\left(\mathbb{R}^{3}\right)}<\infty$,
such that

$$
\begin{equation*}
\int_{\Omega^{\prime}} \mathfrak{m}^{\prime}\left(x^{\prime}\right) \cdot \nabla^{\prime} \phi\left(x^{\prime}, 0\right) d x^{\prime}=\int_{\mathbb{R}^{3}} \nabla \mathfrak{u}\left(\mathfrak{m}^{\prime}\right) \cdot \nabla \phi d x \tag{1.16}
\end{equation*}
$$

for every $\phi \in C_{0}^{\infty}\left(\mathbb{R}^{3}\right)$. We furthermore define $u^{\prime}\left(m^{\prime}\right)=T u\left(m^{\prime}\right)$. By standard results from the theory of singular integrals (see [24]), it follows that $\mathfrak{u}^{\prime}\left(\mathrm{m}^{\prime}\right) \in W_{\mathrm{loc}}^{1,4 / 3}\left(\Omega^{\prime}\right)$.

We have the following result (cf. [4, 11, 25, 26]).
Theorem 1.1. (i) There exist a sequence $\epsilon_{\mathrm{k}} \searrow 0$ and a point $x_{0}^{\prime} \in \Omega^{\prime}$, such that the maps $\bar{m}_{\mathrm{k}}$, defined as in (1.7), converge weakly in $\mathcal{H}_{\mathrm{loc}}^{1}\left(\overline{\Omega^{\prime}} \backslash\left\{x_{0}^{\prime}\right\}, \mathbb{R}^{3}\right)$, and weakly in $W^{1, p}\left(\Omega^{\prime}, \mathbb{R}^{3}\right)$ for any $p<2$, to a map of the form $\bar{m}=\left(m^{\prime}, 0\right)$ with $\left|m^{\prime}\right|=1$ almost everywhere.
(ii) The limit map $m^{\prime}$ satisfies the equations

$$
\begin{align*}
& \operatorname{div}^{\prime}\left(\mathfrak{m}^{\prime} \wedge \nabla^{\prime} \mathfrak{m}^{\prime}\right)=\mathfrak{m}^{\prime} \wedge \nabla^{\prime} u^{\prime}\left(\mathfrak{m}^{\prime}\right) \quad \text { in } \Omega^{\prime},  \tag{1.17}\\
& \Delta^{\prime} \mathfrak{m}^{\prime}+\left|\nabla^{\prime} \mathfrak{m}^{\prime}\right|^{2} \mathfrak{m}^{\prime}-\nabla^{\prime} u^{\prime}\left(\mathfrak{m}^{\prime}\right)+\left(\mathfrak{m}^{\prime} \cdot \nabla^{\prime} u^{\prime}\left(\mathfrak{m}^{\prime}\right)\right) \mathfrak{m}^{\prime}=0 \quad \text { in } \Omega^{\prime} \backslash\left\{x_{0}^{\prime}\right\} \tag{1.18}
\end{align*}
$$

in the distribution sense.
(iii) If $\mathbb{R}^{2}$ is identified with $\mathbb{C}$, then $m^{\prime}$ is of the form

$$
\begin{equation*}
m^{\prime}(z)=\frac{z-z_{0}}{\left|z-z_{0}\right|} e^{i \theta(z)}, \quad z \in \Omega^{\prime} \backslash\left\{z_{0}\right\}, \tag{1.19}
\end{equation*}
$$

where $z_{0}=x_{0}^{1}+i x_{0}^{2}$ for $x_{0}^{\prime}=\left(x_{0}^{1}, x_{0}^{2}\right)$ and $\theta: \Omega^{\prime} \rightarrow \mathbb{R}$ is a solution of

$$
\begin{equation*}
\Delta^{\prime} \theta=m^{\prime} \wedge \nabla^{\prime} u^{\prime}\left(m^{\prime}\right) \quad \text { in } \Omega^{\prime} . \tag{1.20}
\end{equation*}
$$

The proof of Theorem 1.1 will follow roughly the outline of the arguments in [4], and it will also use some arguments from [11]. The problem considered here has a few additional difficulties however. For instance, the nonlinear constraint $|\mathrm{m}|=1$ almost everywhere generates nonlinearities in the Euler-Lagrange equation which involve first derivatives. It has been shown in [11] how this problem itself may be overcome; but in conjunction with the fact that the $\Omega_{\epsilon}$ 's are three-dimensional domains, the situation is even more difficult. We cannot expect that minimizers of $E_{\epsilon}$ are smooth here (cf. Brezis, Coron, and Lieb [6], and Lin [17]), and in particular we do not have certain pointwise estimates for the gradient, as we have in two dimensions. For variational problems of this kind, regularity can usually be obtained only if the energy is small. But we have seen in (1.6) that this is not the case if $\epsilon$ becomes small. What we will prove instead is that suitable estimates for the gradients hold except in small, controllable sets.

Another difference to the situation of [11] is the fact that the functionals $E_{\epsilon}$ contain the nonlocal operator $\mathfrak{u}_{\epsilon}$. However, it turns out that this only causes minor difficulties for this problem.

The result of Theorem 1.1 has the disadvantage that it requires Dirichlet boundary data on $\partial \Omega^{\prime} \times\left(0, \epsilon^{2}\right)$. It would be more natural to consider minimizers of $E_{\epsilon}$ among all maps in $H^{1}\left(\Omega_{\epsilon}, \mathbb{S}^{2}\right)$. However, we need the boundary conditions for technical reasons. To obtain an idea of the thin film limiting behaviour for free boundary data, we consider a model problem, based on a generalization of the Ginzburg-Landau functionals $I_{\epsilon}$, in Section 5. We will find a similar result as Theorem 1.1, but instead of one vortex in the interior of the domain $\Omega^{\prime}$, we will rather have two "half-vortices" at the boundary.

Vortices at the boundary have also been studied by Kurzke [16] for a slightly different model (with the Ginzburg-Landau penalizing term replaced by a constraint). Similar results as those presented in Section 5 are proven in Kurzke's work, among other things.

Notation. As we have already done above, we will systematically mark objects belonging to $\mathbb{R}^{2}$ with a prime to distinguish them clearly from their three-dimensional equivalents. For $x_{0}^{\prime} \in \mathbb{R}^{2}$ and $r>0$, we write $B_{r}^{\prime}\left(x_{0}^{\prime}\right)$ for the open ball in $\mathbb{R}^{2}$ with centre $x_{0}^{\prime}$ and radius $r$. Moreover, we define $D_{r}^{\prime}\left(x_{0}^{\prime}\right)=\Omega^{\prime} \cap B_{r}^{\prime}\left(x_{0}^{\prime}\right)$ and $D_{r, \epsilon}\left(x_{0}^{\prime}\right)=D_{r}^{\prime}\left(x_{0}^{\prime}\right) \times\left(0, \epsilon^{2}\right)$ for $\epsilon \in(0,1]$.

## 2 Preliminaries

In this section, we will prove certain estimates that will be needed later. In particular, we will find an upper bound for the terms in $E_{\epsilon}\left(\mathfrak{m}_{\epsilon}\right)$ of the type as expected from the theory of $[3,4]$. Moreover, we will obtain certain relations between the magnetostatic energy and the $\mathrm{L}^{2}$-norm of the third component of the magnetization.

Lemma 2.1. Suppose that c is the smallest constant satisfying the inequality

$$
\begin{equation*}
\|v(\cdot, 0)\|_{\mathrm{L}^{4}\left(\Omega^{\prime}\right)} \leq \mathrm{c}\|\nabla v\|_{\mathrm{L}^{2}\left(\mathbb{R}^{3}\right)} \tag{2.1}
\end{equation*}
$$

for all $v \in \mathrm{H}^{1}\left(\mathbb{R}^{3}\right)$. (Such a constant exists by the trace theorem for Sobolev spaces.) Then for any $\epsilon \in(0,1]$, any map $\mathfrak{m}=\left(\mathfrak{m}^{\prime}, \mathfrak{m}^{3}\right) \in \bar{H}^{1}\left(\Omega_{\epsilon}, \mathbb{S}^{2}\right)$ satisfies the inequality

$$
\begin{equation*}
\left\|\nabla \mathfrak{u}_{\epsilon}(\mathfrak{m})\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{3}\right)} \leq c\left(4 \sqrt{\epsilon}\|\nabla \mathfrak{m}\|_{\mathrm{L}^{4 / 3}\left(\Omega_{e}\right)}+2\left\|\mathfrak{m}^{3}(\cdot, 0)\right\|_{\mathrm{L}^{4 / 3}\left(\Omega^{\prime}\right)}\right) . \tag{2.2}
\end{equation*}
$$

Proof. Note that

$$
\begin{align*}
& \int_{\mathbb{R}^{3}}\left|\nabla u_{\epsilon}(m)\right|^{2} d x \\
&=\int_{\Omega_{\epsilon}} m \cdot \nabla u_{\epsilon}(m) d x \\
&=\int_{\Omega^{\prime} \times\left\{\epsilon^{2}\right\}} m^{3} u_{\epsilon}(m) d x^{\prime}-\int_{\Omega^{\prime} \times\{0\}} m^{3} u_{\epsilon}(m) d x^{\prime}-\int_{\Omega_{\epsilon}} \operatorname{div} m u_{\epsilon}(m) d x  \tag{2.3}\\
& \leq c\left\|\nabla u_{\epsilon}(m)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}\left(\left\|m^{3}(\cdot, 0)\right\|_{L^{4 / 3}\left(\Omega^{\prime}\right)}+\left\|m^{3}\left(\cdot, \epsilon^{2}\right)\right\|_{L^{4 / 3}\left(\Omega^{\prime}\right)}\right. \\
&\left.\quad+3 \int_{0}^{\epsilon^{2}}\|\nabla m(\cdot, s)\|_{L^{4 / 3}\left(\Omega^{\prime}\right)} d s\right)
\end{align*}
$$

We have

$$
\begin{align*}
& \int_{0}^{\epsilon^{2}}\|\nabla \mathrm{~m}(\cdot, s)\|_{\mathrm{L}^{4 / 3}\left(\Omega^{\prime}\right)} \mathrm{d} s \leq \sqrt{\epsilon}\|\nabla \mathrm{m}\|_{\mathrm{L}^{4 / 3}\left(\Omega_{\epsilon}\right)} \\
& \begin{aligned}
\left\|\mathrm{m}^{3}\left(\cdot, \epsilon^{2}\right)-\mathrm{m}^{3}(\cdot, 0)\right\|_{\mathrm{L}^{4 / 3}\left(\Omega^{\prime}\right)}^{4 / 3} & =\int_{\Omega^{\prime}}\left|\int_{0}^{\epsilon^{2}} \frac{\partial m^{3}}{\partial x^{3}}\left(x^{\prime}, s\right) \mathrm{d} s\right|^{4 / 3} \mathrm{~d} x^{\prime} \\
& \leq \epsilon^{2 / 3}\|\nabla \mathrm{~m}\|_{\mathrm{L}^{4 / 3}\left(\Omega_{\epsilon}\right)}^{4 / 3}
\end{aligned} \tag{2.4}
\end{align*}
$$

by the Hölder inequality. The claim now follows immediately.
Lemma 2.2. There exists a constant C, depending only on $\Omega^{\prime}$, such that

$$
\begin{equation*}
\mathrm{E}_{\epsilon}\left(\mathrm{m}_{\epsilon}\right) \leq \mathrm{C}-\pi \log \epsilon \tag{2.5}
\end{equation*}
$$

for any $\epsilon \in(0,1]$.
Proof. Since $m_{\epsilon}$ is $E_{\epsilon}$-minimizing, it suffices to construct any map which satisfies the inequality. We assume for simplicity that the closed unit ball $\overline{\mathrm{B}_{1}^{\prime}(0)}$ is contained in $\Omega^{\prime}$. (Otherwise we scale and translate everything.)

Choose a map $n_{0} \in H^{1}\left(B_{1}^{\prime}(0), \mathbb{S}^{2}\right)$ with

$$
\begin{equation*}
n_{0}\left(x^{1}, x^{2}\right)=\left(-x^{2}, x^{1}, 0\right) \quad \text { on } \partial B_{1}^{\prime}(0) \tag{2.6}
\end{equation*}
$$

and another map $n_{1}^{\prime} \in H^{1}\left(\Omega^{\prime} \backslash B_{1}^{\prime}(0), \mathbb{S}^{1}\right)$ such that $n_{1}^{\prime}=\left(-v^{2}, v^{1}\right)$ on $\partial \Omega^{\prime}$ and $n_{1}^{\prime}\left(x^{1}, x^{2}\right)=$ $\left(-x^{2}, x^{1}\right)$ on $\partial B_{1}^{\prime}(0)$. Now define

$$
n_{\epsilon}\left(x^{1}, x^{2}, x^{3}\right)= \begin{cases}\left(n_{1}^{\prime}\left(x^{1}, x^{2}\right), 0\right), & \text { if }\left(x^{1}, x^{2}\right) \in \Omega^{\prime} \backslash B_{1}^{\prime}(0),  \tag{2.7}\\ \frac{\left(-x^{2}, x^{1}, 0\right)}{\sqrt{\left(x^{1}\right)^{2}+\left(x^{2}\right)^{2}},} & \text { if }\left(x^{1}, x^{2}\right) \in B_{1}^{\prime}(0) \backslash B_{\epsilon}^{\prime}(0), \\ n_{0}\left(\frac{x^{1}}{\epsilon}, \frac{x^{2}}{\epsilon}\right), & \text { if }\left(x^{1}, x^{2}\right) \in B_{\epsilon}^{\prime}(0) .\end{cases}
$$

It is readily checked that

$$
\begin{align*}
& \int_{\Omega_{e}}\left|\nabla \mathfrak{n}_{\epsilon}\right|^{2} \mathrm{~d} x \leq\left(\mathrm{C}_{1}-2 \pi \log \epsilon\right) \epsilon^{2},  \tag{2.8}\\
& \int_{\Omega_{\epsilon}}\left|\nabla \mathfrak{n}_{\epsilon}\right|^{4 / 3} \mathrm{~d} x \leq \mathrm{C}_{2} \epsilon^{2},
\end{align*}
$$

for constants $C_{1}$ and $C_{2}$ which depend only on $\Omega^{\prime}$ and the choice of $n_{0}$ and $n_{1}^{\prime}$. Write $n_{\epsilon}=\left(n_{\epsilon}^{\prime}, n_{\epsilon}^{3}\right)$. Then Lemma 2.1 implies that

$$
\begin{equation*}
\left\|\nabla \mathfrak{u}_{\epsilon}\left(\mathfrak{n}_{\epsilon}^{\prime}, 0\right)\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{3}\right)} \leq \mathrm{C}_{3} \epsilon^{2} \tag{2.9}
\end{equation*}
$$

where $C_{3}=C_{3}\left(\Omega^{\prime}, n_{0}, n_{1}^{\prime}\right)$. Finally, we have

$$
\begin{align*}
\left\|\nabla \mathfrak{u}_{\epsilon}\left(\mathrm{n}_{\epsilon}\right)-\nabla \mathfrak{u}_{\epsilon}\left(\mathrm{n}_{\epsilon}^{\prime}, 0\right)\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{3}\right)} & =\left\|\nabla \mathfrak{u}_{\epsilon}\left(0, \mathrm{n}_{\epsilon}^{3}\right)\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{3}\right)} \\
& \leq\left\|\left(0, \mathrm{n}_{\epsilon}^{3}\right)\right\|_{\mathrm{L}^{2}\left(\Omega_{\epsilon}\right)}  \tag{2.10}\\
& \leq \sqrt{\pi} \epsilon^{2},
\end{align*}
$$

because $n_{\epsilon}^{3}$ is supported in $\overline{D_{\epsilon, \epsilon}(0)}$. Combining these inequalities, the lemma is proven.

Lemma 2.3. For $\epsilon \in(0,1]$, suppose that $m=\left(m^{\prime}, m^{3}\right) \in H^{1}\left(\Omega_{\varepsilon}, \mathbb{R}^{3}\right)$ is a map which satisfies $\mathfrak{m}^{3}=0$ almost everywhere on $\partial \Omega^{\prime} \times\left(0, \epsilon^{2}\right)$. Then

$$
\begin{equation*}
\int_{\Omega_{e}}\left(\mathfrak{m}^{3}\right)^{2} \mathrm{~d} x \leq\left(1+\epsilon^{2}\right) \epsilon^{2} \int_{\Omega_{e}}\left|\nabla \mathfrak{m}^{3}\right|^{2} \mathrm{~d} x+2 \int_{\mathbb{R}^{3}}\left|\nabla \mathfrak{u}_{\epsilon}(\mathfrak{m})\right|^{2} \mathrm{~d} x+\epsilon^{4}\left|\Omega^{\prime}\right| . \tag{2.11}
\end{equation*}
$$

Proof. The basic idea for the following argument is due to Gioia and James [10].
Define the function $\phi \in \mathrm{H}^{1}\left(\mathbb{R}^{3}\right)$ by $\phi \equiv 0$ in $\left(\mathbb{R}^{2} \backslash \Omega^{\prime}\right) \times \mathbb{R}$, and

$$
\phi\left(x^{\prime}, x^{3}\right)= \begin{cases}0, & \text { if } x^{3} \leq 0  \tag{2.12}\\ \int_{0}^{x^{3}} m^{3}\left(x^{\prime}, s\right) d s, & \text { if } 0<x^{3} \leq \epsilon^{2}, \\ \left(2-\frac{x^{3}}{\epsilon^{2}}\right) \int_{0}^{\epsilon^{2}} m^{3}\left(x^{\prime}, s\right) d s, & \text { if } \epsilon^{2}<x^{3} \leq 2 \epsilon^{2}, \\ 0, & \text { if } x^{3}>2 \epsilon^{2},\end{cases}
$$

for $x^{\prime} \in \Omega^{\prime}$. Then we have

$$
\begin{equation*}
\left|\nabla^{\prime} \phi\left(x^{\prime}, x^{3}\right)\right| \leq \int_{0}^{e^{2}}\left|\nabla^{\prime} m^{3}\left(x^{\prime}, s\right)\right| \mathrm{ds} \tag{2.13}
\end{equation*}
$$

in $\Omega^{\prime} \times\left(0,2 \epsilon^{2}\right)$, and $\nabla^{\prime} \phi=0$ elsewhere. Thus

$$
\begin{equation*}
\int_{\Omega_{\epsilon}}\left|\nabla^{\prime} \phi\right|^{2} \mathrm{~d} x \leq \epsilon^{4} \int_{\Omega_{\epsilon}}\left|\nabla \mathrm{m}^{3}\right|^{2} \mathrm{~d} x \tag{2.14}
\end{equation*}
$$

Furthermore, since $\partial \phi / \partial x^{3}=m^{3}$ in $\Omega^{\prime} \times\left(0, \epsilon^{2}\right)$,

$$
\begin{equation*}
\frac{\partial \phi}{\partial x^{3}}\left(x^{\prime}, x^{3}\right)=-\frac{1}{\epsilon^{2}} \int_{0}^{\epsilon^{2}} m^{3}\left(x^{\prime}, s\right) d s \quad \text { in } \Omega^{\prime} \times\left(\epsilon^{2}, 2 \epsilon^{2}\right) \tag{2.15}
\end{equation*}
$$

and $\partial \phi / \partial x^{3}=0$ elsewhere, we have

$$
\begin{equation*}
\int_{\mathbb{R}^{3}}|\nabla \phi|^{2} \mathrm{~d} x \leq 2 \int_{\Omega_{\epsilon}}\left(\epsilon^{4}\left|\nabla \mathrm{~m}^{3}\right|^{2}+\left(\mathrm{m}^{3}\right)^{2}\right) \mathrm{dx} \tag{2.16}
\end{equation*}
$$

Testing (1.3) with $\phi$ yields

$$
\begin{align*}
\int_{\Omega_{\epsilon}}\left(m^{3}\right)^{2} d x= & \int_{\Omega_{\epsilon}} m \cdot \nabla \phi d x-\int_{\Omega_{\epsilon}} m^{\prime} \cdot \nabla^{\prime} \phi d x \\
= & \int_{\mathbb{R}^{3}} \nabla u_{\epsilon}(m) \cdot \nabla \phi d x-\int_{\Omega_{\epsilon}} m^{\prime} \cdot \nabla^{\prime} \phi d x \\
\leq & \int_{\mathbb{R}^{3}}\left|\nabla u_{\epsilon}(m)\right|^{2} d x+\frac{1}{2} \int_{\Omega_{\epsilon}}\left(\epsilon^{4}\left|\nabla m^{3}\right|^{2}+\left(m^{3}\right)^{2}\right) d x  \tag{2.17}\\
& +\frac{\epsilon^{4}}{2}\left|\Omega^{\prime}\right|+\frac{\epsilon^{2}}{2} \int_{\Omega_{\epsilon}}\left|\nabla m^{3}\right|^{2} d x
\end{align*}
$$

and the lemma follows.

Lemma 2.4. There exists a constant C, depending only on $\Omega^{\prime}$, such that for $0<\epsilon \leq 1$, the inequality

$$
\begin{equation*}
\frac{1}{\epsilon^{2}} \int_{\Omega_{\epsilon}}\left(\left|\nabla m_{\epsilon}^{3}\right|^{2}+\left|\frac{\partial m_{\epsilon}}{\partial x^{3}}\right|^{2}+\frac{\left(m_{\epsilon}^{3}\right)^{2}}{\epsilon^{2}}\right) d x+\frac{1}{\epsilon^{4}} \int_{\mathbb{R}^{3}}\left|\nabla u_{\epsilon}\left(m_{\epsilon}\right)\right|^{2} d x \leq C \tag{2.18}
\end{equation*}
$$

is satisfied.

Proof. We combine an argument from [11] with Lemmas 2.2 and 2.3.
For almost every $x^{3} \in\left(0, \epsilon^{2}\right)$, we have

$$
\begin{align*}
\int_{\Omega^{\prime}} & \left(\left|\nabla^{\prime} m_{\epsilon}^{\prime}\left(x^{\prime}, x^{3}\right)\right|^{2}+\frac{1}{4 \epsilon^{2}}\left(m_{\epsilon}^{3}\left(x^{\prime}, x^{3}\right)\right)^{2}\right) d x^{\prime} \\
& =\int_{\Omega^{\prime}}\left(\left|\nabla^{\prime} m_{\epsilon}^{\prime}\left(x^{\prime}, x^{3}\right)\right|^{2}+\frac{1}{4 \epsilon^{2}}\left(1-\left|m_{\epsilon}^{\prime}\left(x^{\prime}, x^{3}\right)\right|^{2}\right)\right) d x^{\prime}  \tag{2.19}\\
& \geq \int_{\Omega^{\prime}}\left(\left|\nabla^{\prime} m_{\epsilon}^{\prime}\left(x^{\prime}, x^{3}\right)\right|^{2}+\frac{1}{4 \epsilon^{2}}\left(1-\left|m_{\epsilon}^{\prime}\left(x^{\prime}, x^{3}\right)\right|^{2}\right)^{2}\right) d x^{\prime} \\
& \geq-2 \pi \log \epsilon-C_{1}
\end{align*}
$$

for a constant $C_{1}=C_{1}\left(\Omega^{\prime}\right)$. For the last step, we have used results from [25, 26]. Together with Lemma 2.2, this yields

$$
\begin{align*}
\frac{1}{\epsilon^{2}} \int_{\Omega_{\epsilon}}\left(\left|\nabla m_{\epsilon}^{3}\right|^{2}+\right. & \left.\left|\frac{\partial m_{\epsilon}}{\partial x^{3}}\right|^{2}-\frac{\left(m_{\epsilon}^{3}\right)^{2}}{4 \epsilon^{2}}\right) d x+\frac{1}{\epsilon^{4}} \int_{\mathbb{R}^{3}}\left|\nabla u_{\epsilon}\left(m_{\epsilon}\right)\right|^{2} d x \\
& =2 E_{\epsilon}\left(m_{\epsilon}\right)-\frac{1}{\epsilon^{2}} \int_{\Omega_{\epsilon}}\left(\left|\nabla^{\prime} m_{\epsilon}^{\prime}\right|^{2}+\frac{1}{4 \epsilon^{2}}\left(m_{\epsilon}^{3}\right)^{2}\right) d x  \tag{2.20}\\
& \leq C_{2}=C_{2}\left(\Omega^{\prime}\right)
\end{align*}
$$

Finally, we use Lemma 2.3 to end the proof.

## 3 Regularity and a gradient estimate

We now want to find a pointwise estimate for $\nabla m_{\epsilon}$ of the form $\left|\nabla m_{\epsilon}\right| \leq C / \epsilon$ for an appropriate constant $C$. Such estimates were used, for example, in [3] or [11]. As pointed out in the introduction, however, this can only be expected to be true under additional assumptions.

First, we observe that regularity and a gradient estimate are implied by a small energy condition.

Lemma 3.1. There exist constants $\epsilon_{0}, \lambda_{0}>0$, depending only on $\Omega^{\prime}$, such that for any $\epsilon \in\left(0, \epsilon_{0}\right]$ and for any $x_{0}^{\prime} \in \Omega^{\prime}$ and $r \geq \epsilon^{2}$ with the property

$$
\begin{equation*}
\frac{1}{\epsilon^{2}} \int_{D_{r, \epsilon}\left(x_{0}^{\prime}\right)}\left(\left|\nabla m_{\epsilon}\right|^{2}+\frac{r^{2}}{\epsilon^{4}}\left|\nabla u_{\epsilon}\left(m_{\epsilon}\right)\right|^{2}\right) d x \leq \lambda_{0} \tag{3.1}
\end{equation*}
$$

the map $m_{\epsilon}$ is smooth in $D_{r / 2, \epsilon}\left(x_{0}^{\prime}\right)$ and $\nabla m_{\epsilon}$ is continuous in $\overline{D_{r / 2, \epsilon}\left(x_{0}^{\prime}\right)}$.

Proof. In the case $B_{r}^{\prime}\left(x_{0}^{\prime}\right) \subset \Omega^{\prime}$, the Hölder continuity of $m_{\epsilon}$ in $\overline{D_{r / 2, \epsilon}\left(x_{0}^{\prime}\right)}$ was proven in [18, Proposition 2.1]. Higher regularity then follows by well-known arguments (cf. Borchers and Garber [5], and Simon [23]). If $B_{r}^{\prime}\left(x_{0}^{\prime}\right) \not \subset \Omega^{\prime}$, it is not difficult to modify the arguments so that they prove the claim also in this situation (combining them, e.g., with methods from Schoen and Uhlenbeck [22]).

For an alternative proof, different arguments to prove regularity for minima of functionals of the form of $E_{\epsilon}$ can be found in papers of Hardt and Kinderlehrer [12] and Carbou [7]. (If they are to be applied here, however, they first have to be adapted to the situation of thin films.) All of these arguments use well-known methods from the regularity theory for harmonic maps (cf. Schoen and Uhlenbeck [21, 22], Hélein [13, 14], Evans [9], and Bethuel [2]).

Lemma 3.2. There exist numbers $\epsilon_{1}, \lambda_{1}, c_{1}>0$, depending only on $\Omega^{\prime}$, with the following property. Suppose that for $\epsilon \in\left(0, \epsilon_{1}\right]$, there exist a point $x_{0}^{\prime} \in \Omega^{\prime}$ and a radius $r \in\left[\epsilon^{2}, \epsilon\right]$, such that

$$
\begin{equation*}
\frac{1}{\epsilon^{2}} \int_{D_{2 r, \epsilon}\left(x_{0}^{\prime}\right)}\left(\left|\nabla m_{\epsilon}\right|^{2}+\frac{r^{2}}{\epsilon^{4}}\left|\nabla u_{\epsilon}\left(m_{\epsilon}\right)\right|^{2}\right) d x \leq \lambda_{1} \tag{3.2}
\end{equation*}
$$

Then

$$
\begin{equation*}
\sup _{\mathrm{D}_{\mathrm{r} / 2, \epsilon}\left(x_{o}^{\prime}\right)}\left|\nabla \mathrm{m}_{\epsilon}\right| \leq \frac{\mathrm{c}_{1}}{\mathrm{r}} \tag{3.3}
\end{equation*}
$$

Proof. We use a modified version of an argument due to Schoen [20].
Assume the statement is false. Then there exist a sequence $\epsilon_{k} \searrow 0$ and minimizers $m_{k} \in \bar{H}^{1}\left(\Omega_{\epsilon_{k}}, \mathbb{S}^{2}\right)$ of $E_{\epsilon_{k}}$ such that

$$
\begin{equation*}
m_{k} \in C^{1}\left(\overline{D_{r_{k}, \epsilon_{k}}\left(x_{k}^{\prime}\right)}, \mathbb{S}^{2}\right) \tag{3.4}
\end{equation*}
$$

(cf. Lemma 3.1) for certain points $x_{k}^{\prime} \in \Omega^{\prime}$ and certain numbers $r_{k} \in\left[\epsilon_{k}^{2}, \epsilon_{k}\right]$, and

$$
\begin{equation*}
\frac{1}{\epsilon_{k}^{2}} \int_{D_{2 r_{k}, \epsilon_{k}}\left(x_{k}^{\prime}\right)}\left(\left|\nabla m_{k}\right|^{2}+\frac{r_{k}^{2}}{\epsilon_{k}^{4}}\left|\nabla u_{\epsilon_{k}}\left(m_{k}\right)\right|^{2}\right) d x=: \mu_{k} \longrightarrow 0 \tag{3.5}
\end{equation*}
$$

but

$$
\begin{equation*}
\sup _{\mathrm{D}_{\mathrm{r}_{\mathrm{k}} / 2, \epsilon_{\mathrm{k}}\left(x_{k}^{\prime}\right)}\left|\nabla m_{k}\right|>\frac{\mathrm{d}_{\mathrm{k}}}{\mathrm{r}_{\mathrm{k}}}, ., ~}^{\text {, }} \tag{3.6}
\end{equation*}
$$

where $d_{k} \rightarrow \infty$ for $k \rightarrow \infty$.

For each k, set

$$
\begin{align*}
& \Phi_{k}(\sigma)=\left(r_{k}-\sigma\right)^{2} \sup _{D_{\sigma, \epsilon_{k}}\left(x_{k}^{\prime}\right)}\left|\nabla \mathfrak{m}_{k}\right|^{2}, \quad 0<\sigma \leq r_{k}, \\
& \Phi_{k}(0)=r_{k}^{2} \sup _{0<s<\epsilon_{k}^{2}}\left|\nabla \mathfrak{m}_{k}\left(x_{k}^{\prime}, s\right)\right|^{2} . \tag{3.7}
\end{align*}
$$

Choose $\rho_{k} \in\left[0, r_{k}\right)$ such that

$$
\begin{equation*}
\Phi_{k}\left(\rho_{k}\right)=\max _{0 \leq \sigma \leq r_{k}} \Phi_{k}(\sigma) . \tag{3.8}
\end{equation*}
$$

Moreover, choose $y_{k}=\left(y_{k}^{\prime}, y_{k}^{3}\right) \in \overline{D_{\rho_{k}, \epsilon_{k}}\left(x_{k}^{\prime}\right)}$ with the property

$$
\begin{equation*}
\left|\nabla \mathfrak{m}_{k}\left(y_{k}\right)\right|=\sup _{\mathrm{D}_{\rho_{k}, e_{k}}\left(x_{k}^{\prime}\right)}\left|\nabla \mathfrak{m}_{k}\right| \tag{3.9}
\end{equation*}
$$

if $\rho_{\mathrm{k}}>0$, and $y_{k}=\left(y_{k}^{\prime}, y_{k}^{3}\right) \in\left\{x_{k}^{\prime}\right\} \times\left[0, \epsilon_{k}^{2}\right]$ with

$$
\begin{equation*}
\left|\nabla \mathfrak{m}_{k}\left(y_{k}\right)\right|=\sup _{\left\{x_{k}^{\prime}\right\} \times\left(0, \epsilon_{k}^{2}\right)}\left|\nabla \mathfrak{m}_{k}\right| \tag{3.10}
\end{equation*}
$$

if $\rho_{k}=0$. Set $e_{k}=\left|\nabla \mathfrak{m}_{k}\left(y_{k}\right)\right|$. Note that

$$
\begin{equation*}
\mathrm{d}_{\mathrm{k}}^{2}<4 \Phi\left(\frac{\mathrm{r}_{\mathrm{k}}}{2}\right) \leq 4 \Phi_{\mathrm{k}}\left(\rho_{\mathrm{k}}\right)=4\left(\mathrm{r}_{\mathrm{k}}-\rho_{\mathrm{k}}\right)^{2} e_{\mathrm{k}}^{2} \tag{3.11}
\end{equation*}
$$

that is, $e_{k}^{-1}<2\left(\left(r_{k}-\rho_{k}\right) / d_{k}\right)$. The rescaled maps

$$
\begin{equation*}
\widehat{\mathfrak{m}}_{k}(x)=\mathfrak{m}_{k}\left(\frac{x}{e_{k}}+y_{k}\right) \tag{3.12}
\end{equation*}
$$

are thus defined and smooth at least in the set

$$
\begin{equation*}
D_{k}=\left(B_{d_{k} / 4}^{\prime}(0) \cap \Omega_{k}^{\prime}\right) \times\left(-e_{k} y_{k}^{3}, e_{k}\left(\epsilon_{k}^{2}-y_{k}^{3}\right)\right), \tag{3.13}
\end{equation*}
$$

where $\Omega_{\mathrm{k}}^{\prime}=e_{\mathrm{k}}\left(\Omega^{\prime}-y_{\mathrm{k}}^{\prime}\right)$. Moreover, they have the properties

$$
\begin{align*}
\left|\nabla \widehat{\mathfrak{m}}_{k}(0)\right|= & 1,  \tag{3.14}\\
\sup _{D_{k}}\left|\nabla \widehat{\mathfrak{m}}_{k}\right|^{2} & \leq e_{k}^{-2} \sup _{D_{\left(r_{k}+\rho_{k}\right) / 2, e_{k}}\left(x_{k}^{\prime}\right)}\left|\nabla \mathfrak{m}_{k}\right|^{2} \\
& \leq \frac{4}{e_{k}^{2}\left(r_{k}-\rho_{k}\right)^{2}} \Phi_{k}\left(\frac{r_{k}+\rho_{k}}{2}\right)  \tag{3.15}\\
& \leq \frac{4}{e_{k}^{2}\left(r_{k}-\rho_{k}\right)^{2}} \Phi\left(\rho_{k}\right)=4 .
\end{align*}
$$

We have

$$
\begin{equation*}
\int_{\Omega_{e_{k} \cap B_{s}\left(x_{1}\right)}}\left|\nabla \mathfrak{m}_{k}\right|^{2} \mathrm{~d} x \leq \mathrm{C}_{1}\left(\mu_{\mathrm{k}}+\mathrm{r}_{\mathrm{k}}\right) \min \left\{s, \epsilon_{\mathrm{k}}^{2}\right\} \tag{3.16}
\end{equation*}
$$

for all $x_{1} \in D_{r_{k}, \epsilon_{k}}\left(x_{k}^{\prime}\right)$ and $s \leq r_{k}$, for a constant $C_{1}=C_{1}\left(\Omega^{\prime}\right)$. This is proven in [18, Lemma 2.2] for the case $B_{2 r_{k}}\left(x_{k}^{\prime}\right) \subset \Omega^{\prime}$. If $B_{2 r_{k}}\left(x_{k}^{\prime}\right)$ intersects the boundary of $\Omega^{\prime}$, then one can use the same arguments, combined with methods from [22], to prove inequality (3.3). In particular, we have

$$
\begin{equation*}
\int_{\mathrm{D}_{\mathrm{k} \cap \mathrm{~B}_{1}(0)}}\left|\nabla \widehat{\mathfrak{m}}_{\mathrm{k}}\right|^{2} \mathrm{~d} x \leq \mathrm{C}_{1}\left(\mu_{\mathrm{k}}+\epsilon_{\mathrm{k}}\right) \min \left\{1, e_{k} \epsilon_{\mathrm{k}}^{2}\right\} . \tag{3.17}
\end{equation*}
$$

Remember that $m_{k}$ satisfies the equation

$$
\begin{equation*}
\epsilon_{k}^{2}\left(\Delta \mathfrak{m}_{k}+\left|\nabla \mathfrak{m}_{k}\right|^{2} \mathfrak{m}_{k}\right)=\nabla u_{\epsilon_{k}}\left(m_{k}\right)-\left(\mathfrak{m}_{k} \cdot \nabla \mathfrak{u}_{\epsilon_{k}}\left(\mathfrak{m}_{k}\right)\right) \mathfrak{m}_{k} \quad \text { in } \Omega_{\epsilon_{k}} . \tag{3.18}
\end{equation*}
$$

Let $\widehat{v}_{k} \in H^{1}\left(\mathbb{R}^{3}\right)$ be the unique solutions of

$$
\begin{equation*}
\Delta \widehat{v}_{k}=\operatorname{div} \widehat{\mathfrak{m}}_{k} . \tag{3.19}
\end{equation*}
$$

Then it follows that $\widehat{m}_{k}$ satisfies

$$
\begin{equation*}
e_{k}^{2} \epsilon_{k}^{2}\left(\Delta \widehat{m}_{k}+\left|\nabla \widehat{m}_{k}\right|^{2} \widehat{m}_{k}\right)=\nabla \widehat{v}_{k}-\left(\widehat{m}_{k} \cdot \nabla \widehat{v}_{k}\right) \widehat{m}_{k} \quad \text { in } D_{k} . \tag{3.20}
\end{equation*}
$$

Note that $e_{k}^{2} \epsilon_{k}^{2} \geq d_{k}^{2} / 4 \rightarrow \infty$ for $k \rightarrow \infty$.
By standard estimates, we have $\left\|\nabla \widehat{v}_{k}\right\|_{L^{p}\left(B_{2}(0)\right)} \leq C_{2}=C_{2}(p)$ for any $p<\infty$. We conclude that there exist $\mathrm{C}_{3}=\mathrm{C}_{3}\left(\Omega^{\prime}\right)$ and $\gamma=\gamma\left(\Omega^{\prime}\right)>0$, such that

$$
\begin{equation*}
\left\|\nabla \widehat{\mathfrak{m}}_{\mathrm{k}}\right\|_{\mathrm{C}^{0, \gamma\left(\mathrm{~B}_{1}(0) \cap \mathrm{D}_{\mathrm{k}}\right)}} \leq \mathrm{C}_{3} . \tag{3.21}
\end{equation*}
$$

But this is clearly a contradiction to (3.14) and (3.17).
Lemma 3.2 is not yet good enough for our purpose. The next lemma will give an improvement.

Lemma 3.3. For every $C_{0}>0$, there exist numbers $\epsilon_{2}, \lambda_{2}, c_{2}>0$, depending only on $C_{0}$ and $\Omega^{\prime}$, with the following property. Suppose that for $\epsilon \in\left(0, \epsilon_{2}\right]$, there is a point $x_{0}^{\prime} \in \Omega^{\prime}$, such that $\nabla \mathfrak{m}_{\varepsilon}$ is continuous in $\overline{\bar{D}_{\epsilon, \epsilon}\left(x_{0}^{\prime}\right)}$ and satisfies

$$
\begin{align*}
& \sup _{\mathrm{D}_{e, \epsilon}\left(x_{0}^{\prime}\right)}\left|\nabla \mathfrak{m}_{\epsilon}\right| \leq \frac{\mathrm{C}_{0}}{\epsilon^{2}},  \tag{3.22}\\
& \frac{1}{\epsilon^{2}} \int_{\mathrm{D}_{e, e}\left(x_{0}^{\prime}\right)}\left|\nabla \mathfrak{m}_{\epsilon}^{3}\right|^{2} \mathrm{~d} x \leq \lambda_{2} . \tag{3.23}
\end{align*}
$$

Then

$$
\begin{equation*}
\sup _{\mathrm{D}_{\epsilon / 2, \mathrm{e}}\left(x_{\mathrm{o}}^{\prime}\right)}\left|\nabla \mathrm{m}_{\epsilon}\right| \leq \frac{\mathrm{c}_{2}}{\epsilon} . \tag{3.24}
\end{equation*}
$$

Proof. We use similar arguments as in the proof of Lemma 3.2, and we combine them with arguments due to Hang and Lin [11].

Assume that the statement is false. Then we construct the sequence $\left\{\widehat{m}_{k}\right\}$ as in the proof of Lemma 3.2. In this case, $\widehat{m}_{k}$ has the properties (3.14), (3.15), (3.21), and

$$
\begin{equation*}
\frac{1}{e_{\mathrm{k}} \epsilon_{\mathrm{k}}^{2}} \int_{\mathrm{D}_{\mathrm{k}}}\left|\nabla \widehat{\mathfrak{m}}_{\mathrm{k}}^{3}\right|^{2} \mathrm{~d} x=\mu_{\mathrm{k}} \longrightarrow 0 . \tag{3.25}
\end{equation*}
$$

Furthermore, condition (3.22) guarantees that $e_{k} \epsilon_{k}^{2} \leq C_{0}$.
We choose a subsequence (without changing notation), such that both $e_{k} y_{k}^{3}$ and $e_{k}\left(\epsilon_{k}^{2}-y_{k}^{3}\right)$ converge to a number in $\left[0, C_{0}\right]$. Assume first that $\lim _{k \rightarrow \infty} e_{k} y_{k}^{3}=$ $\lim _{k \rightarrow \infty} e_{k}\left(\epsilon_{k}^{2}-y_{k}^{3}\right)=0$. Define the maps

$$
\begin{equation*}
\bar{m}_{k}\left(x^{\prime}\right)=\frac{1}{\epsilon_{k}^{2}} \int_{-e_{k} y_{k}^{3}}^{e_{k}\left(\epsilon_{k}^{2}-y_{k}^{3}\right)} \widehat{m}_{k}\left(x^{\prime}, s\right) \mathrm{ds}, \quad x^{\prime} \in \Omega_{k}^{\prime} . \tag{3.26}
\end{equation*}
$$

We may assume that $\Omega_{k}^{\prime}$ converges to a set $\Sigma^{\prime} \subset \mathbb{R}^{2}$ of the form

$$
\begin{equation*}
\Sigma^{\prime}=\left\{x^{\prime} \in \mathbb{R}^{2}: a^{\prime} \cdot x^{\prime}<\alpha\right\}, \tag{3.27}
\end{equation*}
$$

for some $a^{\prime}=\left(a^{1}, a^{2}\right) \in \mathbb{S}^{1}$ and $0 \leq \alpha \leq \infty$. Moreover, by (3.21), we may assume that $\bar{m}_{k}$ converges to a map $\bar{m}: \Sigma^{\prime} \rightarrow \mathbb{S}^{2}$ in the $C^{1}$-sense.

We want to show that $\bar{m}$ is a locally energy minimizing map for the Dirichlet energy, that is, for any ball $\overline{B_{R}^{\prime}\left(x^{\prime}\right)} \subset \Sigma^{\prime}$ and any map $\bar{n} \in H_{\text {loc }}^{1}\left(\Sigma^{\prime}, \mathbb{S}^{2}\right)$ with $\bar{n}=\bar{m}$ outside of $B_{R}^{\prime}\left(x^{\prime}\right)$, we have

$$
\begin{equation*}
\int_{B_{R}^{\prime}\left(x^{\prime}\right)}\left|\nabla^{\prime} \overline{\mathrm{n}}\right| \mathrm{d} x^{\prime} \geq \int_{\mathrm{B}_{\mathrm{R}}^{\prime}\left(x^{\prime}\right)}\left|\nabla^{\prime} \overline{\mathrm{m}}\right| d x^{\prime} . \tag{3.28}
\end{equation*}
$$

To this end, suppose there existed such a map $\bar{n}$ which did not satisfy (3.28), that is,

$$
\begin{equation*}
\int_{B_{\mathrm{R}}^{\prime}\left(x^{\prime}\right)}\left|\nabla^{\prime} \overline{\mathrm{n}}\right| \mathrm{d} x^{\prime} \leq \int_{B_{\mathrm{R}}^{\prime}\left(x^{\prime}\right)}\left|\nabla^{\prime} \overline{\mathrm{m}}\right| \mathrm{d} x^{\prime}-\sigma \tag{3.29}
\end{equation*}
$$

for a positive number $\sigma$. Then clearly for any sufficiently large $k$, one could construct a map $n_{k} \in H^{1}\left(\Omega_{\varepsilon_{k}}, \mathbb{S}^{2}\right)$ with $n_{k}=m_{k}$ outside of $D_{R / e_{k}, e_{k}}^{\prime}\left(x^{\prime} / e_{k}+y_{k}^{\prime}\right)$, such that

$$
\begin{equation*}
\int_{D_{k / e_{k}, e_{k}}^{\prime}\left(x^{\prime} / e_{k}+y_{k}^{\prime}\right)}\left|\nabla \mathfrak{n}_{k}\right|^{2} \mathrm{~d} x \leq \int_{D_{k / e_{k}, e_{k}}^{\prime}\left(x^{\prime} / e_{k}+y_{k}^{\prime}\right)}\left|\nabla m_{k}\right|^{2} \mathrm{~d} x-\frac{\sigma \epsilon_{k}^{2}}{2} . \tag{3.30}
\end{equation*}
$$

Moreover,

$$
\begin{align*}
\frac{1}{\epsilon_{k}^{2}}\left\|\nabla u_{\epsilon_{k}}\left(m_{k}\right)-\nabla u_{\epsilon_{k}}\left(n_{k}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)} & =\frac{1}{\epsilon_{k}^{2}}\left\|\nabla u_{\epsilon_{k}}\left(m_{k}-n_{k}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)} \\
& \leq \frac{1}{\epsilon_{k}^{2}}\left\|m_{k}-n_{k}\right\|_{L^{2}\left(\Omega_{e_{k}}\right)}  \tag{3.31}\\
& \leq \frac{\sqrt{2 \pi} R}{e_{k} \epsilon_{k}} \leq \frac{\sqrt{8 \pi} R}{d_{k}} \longrightarrow 0
\end{align*}
$$

This would give a contradiction to the minimality of $E_{\epsilon_{k}}\left(m_{k}\right)$.
Hence $\bar{m}: \Sigma^{\prime} \rightarrow \mathbb{S}^{2}$ is a locally energy minimizing map. It satisfies $\nabla \bar{m}^{3}=0$ and $|\nabla \bar{m}| \leq 2$ in $\Sigma^{\prime}$, and $|\nabla \bar{m}(0)|=1$. If $\alpha<\infty$ in the representation (3.27) of $\Sigma^{\prime}$, then $\bar{m} \equiv$ $\left(-a^{2}, a^{1}, 0\right)$ on $\partial \Sigma^{\prime}$. All this follows easily from the construction of $\bar{m}$ and inequalities (3.14), (3.15), and (3.25). It is readily concluded that $\bar{m}$ is of the form

$$
\begin{equation*}
\bar{m}\left(x^{\prime}\right)=\left(e^{i\left(b^{\prime} \cdot x^{\prime}+\beta\right)}, 0\right), \quad x^{\prime} \in \Sigma^{\prime} \tag{3.32}
\end{equation*}
$$

for some $b^{\prime} \in \mathbb{S}^{1}$ and $\beta \in \mathbb{R}$. But Hang and Lin [11] proved that this is not a locally energy minimizing map. Thus in this case, we have a contradiction.

If either $\lim _{k \rightarrow \infty} e_{k} y_{k}^{3}>0$ or $\lim _{k \rightarrow \infty} e_{k}\left(\epsilon_{k}^{2}-y_{k}^{3}\right)>0$, we use similar arguments. In this case, a subsequence of $\left\{\hat{m}_{k}\right\}$ converges to a locally energy minimizing map $\widehat{m}$ : $\Sigma^{\prime} \times(s, t) \rightarrow \mathbb{S}^{2}$, where $\Sigma^{\prime}$ is as before and $s<t$. Moreover, $\partial \widehat{m} / \partial x^{3}=0$ on $\Sigma^{\prime} \times\{s, t\}$. We conclude that

$$
\begin{equation*}
\widehat{m}\left(x^{\prime}, x^{3}\right)=\left(e^{i\left(b^{\prime} \cdot x^{\prime}+\beta\right)}, 0\right), \quad x^{\prime} \in \Sigma^{\prime}, s<x^{3}<t \tag{3.33}
\end{equation*}
$$

as before. Again we can use the arguments of [11] to obtain a contradiction and thus conclude the proof.

## 4 Proof of Theorem 1.1

The following is the key lemma for the proof of Theorem 1.1. It will enable us to apply certain arguments from [4] and from [25, 26].

Lemma 4.1. There exist $\epsilon_{3}, \lambda_{3}, c_{3}>0$, depending only on $\Omega^{\prime}$, such that the following holds true. For $\epsilon \in\left(0, \epsilon_{3}\right]$, suppose there exists $x_{0}^{\prime} \in \Omega^{\prime}$ with the property

$$
\begin{equation*}
\int_{D_{2 \epsilon, \epsilon}\left(x_{0}^{\prime}\right)}\left(\frac{\left|\nabla m_{\epsilon}^{3}\right|^{2}}{\epsilon^{2}}-\frac{\left|\nabla m_{\epsilon}\right|^{2}}{\epsilon^{2} \log \epsilon}+\frac{\left(m_{\epsilon}^{3}\right)^{2}+\left|\nabla u_{\epsilon}\left(m_{\epsilon}\right)\right|^{2}}{\epsilon^{4}}\right) d x \leq \lambda_{3} \tag{4.1}
\end{equation*}
$$

Then $m_{\epsilon}$ is smooth in $D_{\varepsilon / 2, \epsilon}\left(x_{0}^{\prime}\right)$ with

$$
\begin{align*}
& \sup _{\mathrm{D}_{\epsilon / 2, \epsilon}\left(x_{0}^{\prime}\right)}\left|\mathrm{m}_{\epsilon}^{3}\right| \leq \frac{1}{2},  \tag{4.2}\\
& \sup _{\mathrm{D}_{\epsilon / 2, \epsilon}\left(x_{0}^{\prime}\right)}\left|\nabla m_{\epsilon}\right| \leq \frac{\mathrm{c}_{3}}{\epsilon} . \tag{4.3}
\end{align*}
$$

Proof. Choose a number $\gamma \in(1,2)$. We can find a radius $r \in\left(\epsilon^{2}, \epsilon^{\gamma}\right)$ such that

$$
\begin{equation*}
r \int_{\left(\partial B_{r}^{\prime}\left(x_{o}^{\prime}\right) \cap \Omega^{\prime}\right) \times\left(0, \epsilon^{2}\right)}\left|\nabla \mathfrak{m}_{\epsilon}\right|^{2} \text { do } \leq \frac{2 \lambda_{3} \epsilon^{2}}{2-\gamma} . \tag{4.4}
\end{equation*}
$$

(Otherwise we would have

$$
\begin{align*}
\int_{D_{\epsilon, e}\left(x_{0}^{\prime}\right)}\left|\nabla \mathfrak{m}_{\epsilon}\right|^{2} \mathrm{~d} x & \geq \frac{2 \lambda_{3} \epsilon^{2}}{2-\gamma} \int_{\epsilon^{2}}^{\epsilon^{\gamma}} \frac{d r}{r}  \tag{4.5}\\
& =-2 \lambda_{3} \epsilon^{2} \log \epsilon,
\end{align*}
$$

in contradiction to (4.1).) Moreover, there exists a number $s \in\left(0, \epsilon^{2}\right)$ such that

$$
\begin{equation*}
\mathrm{r} \int_{\left(\partial \mathrm{B}_{r}^{\prime}\left(x_{0}^{\prime}\right) \cap \Omega^{\prime}\right) \times\{s\}}\left|\nabla \mathfrak{m}_{\epsilon}\right|^{2} \mathrm{do}^{\prime} \leq \frac{4 \lambda_{3}}{2-\gamma}, \tag{4.6}
\end{equation*}
$$

where do' indicates the arc length measure.
If $\epsilon \leq \epsilon_{3} \leq r_{0}$ for a certain number $r_{0}$ which depends only on $\Omega^{\prime}$, then $\partial B_{r}^{\prime}\left(x_{0}^{\prime}\right) \cap \Omega^{\prime}$ is connected. Hence for $x^{\prime}, y^{\prime} \in \partial B_{r}^{\prime}\left(x_{0}^{\prime}\right) \cap \Omega^{\prime}$, we have in this case

$$
\begin{align*}
\left|m_{\epsilon}\left(x^{\prime}, s\right)-\mathfrak{m}_{\epsilon}\left(y^{\prime}, s\right)\right| & \leq \int_{\left(\partial D_{r}^{\prime}\left(x_{0}^{\prime}\right) \cap \Omega^{\prime}\right) \times\{s\}}\left|\nabla \mathfrak{m}_{\epsilon}\right| \mathrm{do}^{\prime} \\
& \leq \sqrt{\frac{8 \pi \lambda_{3}}{2-\gamma}} \tag{4.7}
\end{align*}
$$

If $\lambda_{3} \leq(2-\gamma) / 32 \pi$, then the right-hand side is at most $1 / 2$. If $\epsilon_{3}$ (and thus $r$ ) is also small enough, then $m_{\epsilon}\left(\partial D_{r}^{\prime}\left(x_{0}^{\prime}\right) \times\{s\}\right)$ is contained in a ball of radius 1 . Then it is easy to construct a map $n_{\varepsilon} \in H^{1}\left(D_{r}^{\prime}\left(x_{0}^{\prime}\right) \times\{s\}, \mathbb{S}^{2}\right)$ with $n_{\varepsilon}=m_{\epsilon}$ on $\partial D_{r}^{\prime}\left(x_{0}^{\prime}\right) \times\{s\}$, and

$$
\begin{equation*}
\int_{D_{r}^{\prime}\left(x_{o}^{\prime}\right)}\left|\nabla^{\prime} n_{\epsilon}(x, s)\right|^{2} d x^{\prime} \leq C_{1}\left(\lambda_{3}+\epsilon_{3}\right) \tag{4.8}
\end{equation*}
$$

for a constant $C_{1}=C_{1}\left(\gamma, \Omega^{\prime}\right)$. If $B_{r}^{\prime}\left(x_{0}^{\prime}\right) \subset \Omega^{\prime}$, we extend $n_{\epsilon}$ to $D_{r, \epsilon}\left(x_{0}^{\prime}\right)$ by

$$
n_{\epsilon}\left(x^{\prime}, x^{3}\right)= \begin{cases}n_{\epsilon}\left(\left(1-\left|x^{3}-s\right| / r\right)^{-1} x^{\prime}, s\right), & \text { if }\left|x^{3}-s\right| \leq r-\left|x^{\prime}\right|,  \tag{4.9}\\ m_{\epsilon}\left(r x^{\prime} /\left|x^{\prime}\right|, x^{3}-r+\left|x^{\prime}\right|\right), & \text { if } x^{3}>r-\left|x^{\prime}\right|+s, \\ m_{\epsilon}\left(r x^{\prime} /\left|x^{\prime}\right|, x^{3}+r-\left|x^{\prime}\right|\right), & \text { if } x^{3}<s-r+\left|x^{\prime}\right|,\end{cases}
$$

and to $\Omega_{\epsilon}$ by $n_{\epsilon}=m_{\epsilon}$ outside of $D_{r, \epsilon}\left(x_{0}^{\prime}\right)$. If $B_{r}^{\prime}\left(x_{0}^{\prime}\right) \not \subset \Omega^{\prime}$, we construct a similar extension. In both cases, we thus find a map $n_{\epsilon} \in \bar{H}^{1}\left(\Omega_{\epsilon}, \mathbb{S}^{2}\right)$ with $n_{\epsilon}=m_{\epsilon}$ in $\Omega_{\epsilon} \backslash D_{r, \epsilon}\left(x_{0}^{\prime}\right)$, and

$$
\begin{equation*}
\int_{\mathrm{D}_{\mathrm{r}, \mathrm{\epsilon}}\left(x_{0}^{\prime}\right)}\left|\nabla \mathfrak{n}_{\epsilon}\right|^{2} \mathrm{~d} x \leq \mathrm{C}_{2}\left(\lambda_{3}+\epsilon_{3}\right) \epsilon^{2} \tag{4.10}
\end{equation*}
$$

for a constant $C_{2}=C_{2}\left(\gamma, \Omega^{\prime}\right)$.
Note that

$$
\begin{align*}
\left\|\nabla u_{\epsilon}\left(m_{\epsilon}\right)-\nabla u_{\epsilon}\left(n_{\epsilon}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)} & =\left\|\nabla u_{\epsilon}\left(m_{\epsilon}-n_{\epsilon}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)} \\
& \leq\left\|m_{\epsilon}-n_{\epsilon}\right\|_{L^{2}\left(D_{r, \epsilon}\left(x_{o}^{\prime}\right)\right)}  \tag{4.11}\\
& \leq \sqrt{2 \pi} \epsilon^{1+\gamma}
\end{align*}
$$

By the minimizing property of $m_{\epsilon}$, we have

$$
\begin{align*}
& \frac{1}{\epsilon^{2}} \int_{\mathrm{D}_{r, \epsilon}\left(x_{0}^{\prime}\right)}\left|\nabla \mathrm{m}_{\epsilon}\right|^{2} \mathrm{~d} x \\
& \quad \leq \frac{1}{\epsilon^{2}} \int_{\mathrm{D}_{\mathrm{r}, \epsilon}\left(x_{0}^{\prime}\right)}\left|\nabla \mathrm{n}_{\epsilon}\right|^{2} \mathrm{~d} x+\frac{1}{\epsilon^{4}}\left(\left\|\nabla u_{\epsilon}\left(\mathrm{n}_{\epsilon}\right)\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{3}\right)}^{2}-\left\|\nabla u_{\epsilon}\left(\mathrm{m}_{\epsilon}\right)\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{3}\right)}^{2}\right)  \tag{4.12}\\
& \quad \leq \mathrm{C}_{2}\left(\lambda_{3}+\epsilon_{3}\right)+\mathrm{C}_{3} \epsilon_{3}^{\gamma-1}
\end{align*}
$$

for a constant $C_{3}=C_{3}\left(\Omega^{\prime}\right)$. For the last step, we have used Lemma 2.4 and inequality (4.11).

If $\lambda_{3}$ and $\epsilon_{3}$ are sufficiently small, we can now apply Lemma 3.1, and find that $m_{\epsilon}$ is smooth in $\overline{\mathrm{D}_{\mathrm{r} / 2, \epsilon}\left(\mathrm{x}_{0}^{\prime}\right)}$. Lemma 3.2 then even implies that $\left|\nabla \mathrm{m}_{\epsilon}\left(x_{0}^{\prime}\right)\right| \leq 2 \mathrm{c}_{2} / \mathrm{r}$. Furthermore, we can apply the same arguments for any point $x^{\prime} \in D_{\epsilon, \epsilon}\left(x_{0}^{\prime}\right)$ instead of $x_{0}^{\prime}$. Hence $m_{\epsilon}$ is even smooth in $\overline{D_{\epsilon, \epsilon}\left(x_{0}^{\prime}\right)}$, and $\left|\nabla m_{\epsilon}\right| \leq 2 c_{2} / \epsilon^{2}$ in this set.

Now, according to Lemma 3.3, we have (4.3) for a constant $c_{3}=c_{3}\left(\Omega^{\prime}\right)$ provided that $\lambda_{3}$ and $\epsilon_{3}$ are chosen appropriately. With this, inequality (4.2) follows easily from the inequality

$$
\begin{equation*}
\int_{D_{2 \epsilon, \varepsilon}\left(x_{0}^{\prime}\right)}\left(m_{\epsilon}^{3}\right)^{2} d x \leq \lambda_{3} \epsilon^{4} \tag{4.13}
\end{equation*}
$$

if $\lambda_{3}$ is sufficiently small.
For the proof of Theorem 1.1, we can now proceed as in [4].
For a fixed $\epsilon \in(0,1]$, cover $\Omega^{\prime}$ with a collection of balls $\left\{B_{\epsilon / 2}^{\prime}\left(x_{i}^{\prime}\right)\right\}_{1 \leq i \leq I}$ with the properties $x_{i}^{\prime} \in \Omega^{\prime}$ and

$$
\begin{equation*}
B_{\epsilon / 8}^{\prime}\left(x_{i}^{\prime}\right) \cap B_{\epsilon / 8}^{\prime}\left(x_{\mathfrak{j}}^{\prime}\right)=\varnothing \quad \text { for } i \neq \mathfrak{j} \tag{4.14}
\end{equation*}
$$

(For instance, a maximal collection of balls with centres in $\Omega^{\prime}$, such that (4.14) holds, will do.) Consider all balls in this collection which satisfy

$$
\begin{equation*}
\int_{D_{2 e, e}\left(x_{i}^{\prime}\right)}\left(\frac{\left|\nabla \mathfrak{m}_{\epsilon}^{3}\right|^{2}}{\epsilon^{2}}-\frac{\left|\nabla \mathfrak{m}_{\epsilon}\right|^{2}}{\epsilon^{2} \log \epsilon}+\frac{\left(\mathfrak{m}_{\epsilon}^{3}\right)^{2}+\left|\nabla \mathfrak{u}_{\epsilon}\left(\mathfrak{m}_{\epsilon}\right)\right|^{2}}{\epsilon^{4}}\right) \mathrm{d} x>\lambda_{3} \tag{4.15}
\end{equation*}
$$

for the constant $\lambda_{3}$ from Lemma 4.1. By Lemmas 2.2 and 2.4, the number of such balls is bounded by a number J which depends only on $\Omega^{\prime}$. Using Lemma 4.1, we conclude that there exists a constant $R=R(\Omega)$, such that for any sufficiently small $\epsilon$, we can construct a set of points $y_{\epsilon 1}^{\prime}, \ldots, y_{\epsilon J}^{\prime} \in \Omega^{\prime}$ with the properties

$$
\begin{align*}
& \left|y_{\epsilon i}^{\prime}-y_{\epsilon j}^{\prime}\right| \geq 8 R \epsilon \quad \text { or } \quad y_{\epsilon i}=y_{\epsilon j} \quad \text { for } 1 \leq i, j \leq J, \\
& \left|\mathfrak{m}_{\epsilon}^{3}\right| \leq \frac{1}{2}, \quad\left|\nabla \mathfrak{m}_{\epsilon}\right| \leq \frac{c_{3}}{\epsilon}, \quad \text { in } \Omega_{\epsilon} \backslash\left(\bigcup_{i=1}^{J} D_{R \epsilon, \epsilon}\left(y_{\epsilon i}^{\prime}\right)\right) \tag{4.16}
\end{align*}
$$

for the constant $c_{3}$ from Lemma 4.1. Now we pick a sequence $\epsilon_{k} \searrow 0$, such that for every $i=1, \ldots$, J, we have

$$
\begin{equation*}
y_{\epsilon_{k} i}^{\prime} \longrightarrow y_{i}^{\prime} \quad(k \longrightarrow \infty) \tag{4.17}
\end{equation*}
$$

for a certain point $y_{i}^{\prime} \in \overline{\Omega^{\prime}}$. Choose $\rho>0$ such that any two balls $B_{\rho}^{\prime}\left(y_{i}^{\prime}\right)$ and $B_{\rho}^{\prime}\left(y_{j}^{\prime}\right)$ are disjoint unless $y_{i}^{\prime}=y_{j}^{\prime}$. If $k$ is sufficiently large, then

$$
\begin{equation*}
\left|m_{\epsilon_{k}}^{3}\right| \leq \frac{1}{2}, \quad\left|\nabla m_{\epsilon_{k}}\right| \leq \frac{c_{3}}{\epsilon_{k}}, \quad \text { in } \Omega_{\epsilon_{k}} \backslash\left(\bigcup_{i=1}^{J} D_{\rho, \epsilon_{k}}\left(y_{i}^{\prime}\right)\right) . \tag{4.18}
\end{equation*}
$$

In particular, for any sufficiently large $k$, the topological degree of the restriction of $m_{\epsilon_{k}}$ to $\partial D_{\rho}^{\prime}\left(y_{i}^{\prime}\right) \times\{s\}$ is well defined for all $i=1, \ldots, J$ and all $s \in\left(0, \epsilon_{k}^{2}\right)$, and is independent of $s$. Clearly it must be nonzero for at least one of the points $y_{i}^{\prime}$. Without loss of generality, we may assume that this point is always the same; we denote it by $x_{0}^{\prime}$. It follows from the arguments in the proofs of [4, Theorem V.2] or [25, Proposition 3.4] (cf. also Proposition 5.6) that

$$
\begin{equation*}
\frac{1}{\epsilon_{\mathrm{k}}^{2}} \int_{D_{\rho, \epsilon_{\mathrm{k}}\left(x_{0}^{\prime}\right)}}\left|\nabla \mathrm{m}_{\epsilon_{\mathrm{k}}}\right|^{2} \mathrm{~d} x \geq 2 \pi \log \left(\frac{\rho}{\epsilon_{\mathrm{k}}}\right)-\mathrm{C}_{1} \tag{4.19}
\end{equation*}
$$

for a constant $C_{1}$ which is independent of $k$ and $\rho$, provided that $k$ is sufficiently large.
Comparing this with Lemma 2.2, we obtain uniform estimates for

$$
\begin{equation*}
\frac{1}{\epsilon_{\mathrm{k}}^{2}} \int_{\Omega^{\prime} \backslash \mathrm{D}_{\rho, \epsilon_{k}\left(x_{j}^{\prime}\right)}}\left|\nabla \mathrm{m}_{\epsilon_{k}}\right|^{2} \mathrm{~d} x \tag{4.20}
\end{equation*}
$$

for any $\rho>0$, and for

$$
\begin{equation*}
\frac{1}{\epsilon_{\mathrm{k}}^{2}} \int_{\Omega^{\prime}}\left|\nabla \mathfrak{m}_{\epsilon_{\mathrm{k}}}\right|^{\mathrm{p}} \mathrm{~d} x \tag{4.21}
\end{equation*}
$$

for any $p \in[1,2)$. After passing to a subsequence once more, we find a map

$$
\begin{equation*}
\overline{\mathfrak{m}} \in \mathcal{H}_{\mathrm{loc}}^{1}\left(\overline{\Omega^{\prime}} \backslash\left\{x_{0}^{\prime}\right\}, \mathbb{S}^{2}\right) \cap \bigcap_{1 \leq p<2} W^{1, p}\left(\Omega^{\prime}, \mathbb{S}^{2}\right) \tag{4.22}
\end{equation*}
$$

which is the limit of the maps $\bar{m}_{k}$ in the sense specified in Theorem 1.1. Now we use the following result.

Proposition 4.2. For $p>4 / 3$ and for a sequence $\epsilon_{k} \searrow 0$, suppose that $m_{k}=\left(m_{k}^{1}, m_{k}^{2}, m_{k}^{3}\right)$ $\in W^{1, p}\left(\Omega_{\epsilon_{k}}, \mathbb{S}^{2}\right)$ are distributional solutions of

$$
\begin{equation*}
\epsilon_{k}^{2} \operatorname{div}\left(\mathfrak{m}_{k} \wedge \nabla m_{k}\right)=\mathfrak{m}_{k} \wedge \nabla u_{\epsilon_{k}}\left(m_{k}\right) \quad \text { in } \Omega_{\epsilon_{k}}, \tag{4.23}
\end{equation*}
$$

satisfying the Neumann boundary conditions $\partial m_{k} / \partial x^{3}=0$ on $\Omega^{\prime} \times\left\{0, \epsilon_{k}^{2}\right\}$. Define $v_{k}=$ $\epsilon_{k}^{-2} u_{\epsilon_{k}}\left(\mathfrak{m}_{k}\right)$ and

$$
\begin{equation*}
\bar{m}_{\mathrm{k}}\left(x^{\prime}\right)=\frac{1}{\epsilon_{\mathrm{k}}^{2}} \int_{0}^{\epsilon_{\mathrm{k}}^{2}} m_{\mathrm{k}}\left(x^{\prime}, s\right) \mathrm{ds}, \quad x^{\prime} \in \Omega^{\prime} . \tag{4.24}
\end{equation*}
$$

Suppose that

$$
\begin{equation*}
\sup _{k \in \mathbb{N}}\left(\frac{1}{\epsilon_{\mathrm{k}}^{2}} \int_{\Omega_{\varepsilon_{k}}}\left|\nabla \mathfrak{m}_{k}\right|^{p} \mathrm{~d} x+\frac{1}{2} \int_{\mathbb{R}^{3}}\left|\nabla v_{k}\right|^{2} \mathrm{~d} x\right)<\infty . \tag{4.25}
\end{equation*}
$$

Then there exist a map $\bar{m}=\left(m^{\prime}, 0\right) \in W^{1, p}\left(\Omega^{\prime}, \mathbb{S}^{1} \times\{0\}\right)$ and subsequences $\left\{\bar{m}_{k_{j}}\right\}$ and $\left\{v_{k_{j}}\right\}$ such that

$$
\begin{align*}
& \overline{\mathrm{m}}_{\mathrm{k}_{j}} \rightharpoonup \overline{\mathrm{~m}} \quad \text { weakly in } W^{1, p}\left(\Omega^{\prime}, \mathbb{R}^{3}\right), \\
& \nabla v_{k_{j}} \rightharpoonup \nabla \mathfrak{u}\left(\mathrm{~m}^{\prime}\right) \quad \text { weakly in } \mathrm{L}^{2}\left(\mathbb{R}^{3}, \mathbb{R}^{3}\right) . \tag{4.26}
\end{align*}
$$

The limit map satisfies $m^{\prime} \cdot v^{\prime}=0$ almost everywhere on $\partial \Omega$, and equation (1.17) holds in the distribution sense.

We postpone the proof and finish first the proof of Theorem 1.1. We now know that $\bar{m}$ is of the form $\bar{m}=\left(\mathfrak{m}^{\prime}, 0\right)$, where $\mathfrak{m}^{\prime}$ satisfies (1.17). Then (1.18) follows from (1.17). Moreover, we see that

$$
\begin{equation*}
\int_{\Omega^{\prime} \backslash B_{\rho}\left(x_{0}^{\prime}\right)}\left|\nabla \mathrm{m}^{\prime}\right|^{2} \mathrm{~d} x^{\prime} \leq-2 \pi \log \rho+\mathrm{C}_{2} \tag{4.27}
\end{equation*}
$$

for a constant $C_{2}$ which is independent of $\rho$. We conclude that $x_{0}^{\prime} \in \Omega^{\prime}$, for otherwise we would have a contradiction to [4, Lemma VI.1]. This proves Theorem 1.1(i) and (ii).

For the proof of (iii), first note that $\bar{m}$ is smooth in $\Omega^{\prime} \backslash\left\{x_{0}^{\prime}\right\}$. This follows, for example, from [19, Theorem 1]. A simple generalization of those arguments proves that $\bar{m}$ is continuous in $\overline{\Omega^{\prime}} \backslash\left\{x_{0}^{\prime}\right\}$. In particular, there exists a continuous function $\theta: \Omega^{\prime} \backslash\left\{x_{0}^{\prime}\right\} \rightarrow \mathbb{R}$, such that $m^{\prime}$ has the representation (1.19), owing to the choice of the boundary data. We compute

$$
\begin{equation*}
m^{\prime}\left(x^{\prime}\right) \wedge \nabla^{\prime} \mathfrak{m}^{\prime}\left(x^{\prime}\right)=\nabla^{\prime} \theta\left(x^{\prime}\right)+\frac{\left(x_{0}^{2}-x^{2}, x^{1}-x_{0}^{1}\right)}{\left|x^{\prime}-x_{0}^{\prime}\right|^{2}}, \quad x^{\prime}=\left(x^{1}, x^{2}\right) \in \Omega^{\prime} \backslash\left\{x_{0}^{\prime}\right\} . \tag{4.28}
\end{equation*}
$$

The second term on the right-hand side is divergence free in $\Omega^{\prime}$ in the distribution sense. Hence, $\theta$ is a distributional solution of (1.20). This completes the proof of Theorem 1.1.

Proof of Proposition 4.2. It is clear that there exist $\bar{m}=\left(m^{\prime}, m^{3}\right) \in W^{1, p}\left(\Omega^{\prime}, \mathbb{S}^{2}\right)$ and $v \in$ $\mathrm{H}_{\mathrm{loc}}^{1}\left(\mathbb{R}^{3}\right)$, such that (4.26), for $v$ instead of $\mathfrak{u}\left(\mathrm{m}^{\prime}\right)$, hold for a certain subsequence. Since $\left|m_{k}\right|=1$ almost everywhere, we may assume that $\bar{m}_{k_{j}} \rightarrow \bar{m}$ strongly in $L^{q}\left(\Omega^{\prime}, \mathbb{R}^{3}\right)$ for any $\mathrm{q}<\infty$.

For any $\phi \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{3}\right)$, we have

$$
\begin{equation*}
\int_{\mathbb{R}^{3}} \nabla v_{\mathrm{k}} \cdot \nabla \phi \mathrm{~d} x=\frac{1}{\epsilon_{\mathrm{k}}^{2}} \int_{\Omega_{\varepsilon_{\mathrm{k}}}} m_{\mathrm{k}} \cdot \nabla \phi \mathrm{~d} x . \tag{4.29}
\end{equation*}
$$

In the limit, this yields

$$
\begin{align*}
\int_{\mathbb{R}^{3}} \nabla v \cdot \nabla \phi \mathrm{~d} x= & \int_{\Omega^{\prime}} \overline{\mathrm{m}}\left(x^{\prime}\right) \cdot \nabla \phi\left(x^{\prime}, 0\right) \mathrm{d} x^{\prime} \\
= & \int_{\Omega^{\prime}} m^{3}\left(x^{\prime}\right) \frac{\partial \phi}{\partial x^{3}}(x, 0) \mathrm{d} x^{\prime} \\
& -\int_{\Omega^{\prime}} \operatorname{div}^{\prime} m^{\prime}\left(x^{\prime}\right) \phi\left(x^{\prime}, 0\right) \mathrm{d} x^{\prime}  \tag{4.30}\\
& +\int_{\partial \Omega^{\prime}} v^{\prime}\left(x^{\prime}\right) \cdot m^{\prime}\left(x^{\prime}\right) \phi\left(x^{\prime}, 0\right) \operatorname{do}^{\prime}\left(x^{\prime}\right) .
\end{align*}
$$

If the third component of $\bar{m}$ did not vanish or if the trace of $\bar{m}$ on $\partial \Omega^{\prime}$ were not tangential to the boundary of $\Omega^{\prime}$, it would be easy to construct a sequence of test functions such that the left-hand side of (4.30) would be bounded and the right-hand side would diverge. Thus we have $m^{3}=0$ almost everywhere in $\Omega^{\prime}$, and $m^{\prime} \cdot v^{\prime}=0$ almost everywhere on $\partial \Omega^{\prime}$, as the proposition claims. Moreover, we see that $v=\mathfrak{u}\left(\mathrm{m}^{\prime}\right)$.

For $\psi^{\prime} \in C_{0}^{\infty}\left(\Omega^{\prime}\right)$, set $\psi\left(x^{\prime}, x^{3}\right)=\psi^{\prime}\left(x^{\prime}\right)$. Test (4.23) with $\psi$. An integration by parts in the third component yields

$$
\begin{align*}
\int_{\Omega_{e_{k}}} \nabla \psi \cdot\left(m_{k}^{1} \nabla m_{k}^{2}-m_{k}^{2} \nabla m_{k}^{1}\right) d x & +\int_{\Omega_{\varepsilon_{k}}} \psi v_{k}\left(\frac{\partial m_{k}^{2}}{\partial x^{1}}-\frac{\partial m_{k}^{1}}{\partial x^{2}}\right) d x  \tag{4.31}\\
& -\int_{\Omega_{e_{k}}} v_{\mathrm{k}}\left(m_{k}^{1} \frac{\partial \psi}{\partial x^{2}}-m_{k}^{2} \frac{\partial \psi}{\partial x^{1}}\right) d x=0
\end{align*}
$$

We have a continuous embedding $A: H^{1}\left(\mathbb{R}^{3}\right) \rightarrow C^{0, \alpha}\left([0,1], L^{p /(p-1)}\left(\Omega^{\prime}\right)\right)$ for $\alpha=1 / 2-$ $2 / 3 p>0$, given by the mapping

$$
\begin{equation*}
(A v)(t)=v(\cdot, t), \quad 0 \leq t \leq 1 \tag{4.32}
\end{equation*}
$$

Moreover, the trace operator $H^{1}\left(\mathbb{R}^{3}\right) \rightarrow L^{p /(p-1)}\left(\Omega^{\prime} \times\{0\}\right)$ is compact, and we may hence assume that $v_{k_{j}}(\cdot, 0) \rightarrow u^{\prime}\left(m^{\prime}\right)$ strongly in $L^{p /(p-1)}\left(\Omega^{\prime}\right)$. Hence (4.31) implies in the limit

$$
\begin{equation*}
\int_{\Omega^{\prime}}\left(\nabla^{\prime} \psi^{\prime} \cdot\left(m^{\prime} \wedge \nabla^{\prime} m^{\prime}\right)+\psi^{\prime} u^{\prime}\left(m^{\prime}\right) \operatorname{curl}^{\prime} m^{\prime}+v^{\prime} \nabla^{\prime} \psi^{\prime} \wedge m^{\prime}\right) d x^{\prime}=0 \tag{4.33}
\end{equation*}
$$

where curl' is the curl operator in $\mathbb{R}^{2}$. Now we can integrate by parts again and find that (1.17) holds true.

## 5 Free boundary data: a model problem

We would like to drop now the Dirichlet boundary conditions in Theorem 1.1, that is, to study the minimizers of $E_{\epsilon}$ among all maps in $H^{1}\left(\Omega_{\epsilon}, \mathbb{S}^{2}\right)$. The analysis is more difficult in this situation, however, therefore we consider only a simpler variational problem which may serve as a model for the more complex one.

We have already established certain connections between the magnetostatic energy and the $L^{2}$-norm of the third component of the magnetization in the previous sections. We may therefore regard the limiting problem for the functionals $F_{\epsilon}$ defined in the introduction as a model for the corresponding problem for $E_{\epsilon}$ under Dirichlet boundary conditions. The minimizers of $F_{\epsilon}$, on the other hand, show a similar behaviour as those of the Ginzburg-Landau functionals $I_{\epsilon}$.

For free boundary data, we need to penalize $m^{\prime} \cdot v^{\prime}$ on $\partial \Omega^{\prime} \times\left(0, \epsilon^{2}\right)$ as well. For this purpose, we consider a boundary integral of the form

$$
\begin{equation*}
\int_{\partial \Omega^{\prime} \times\left(0, \epsilon^{2}\right)}\left(m^{\prime} \cdot v^{\prime}\right)^{2} d o \tag{5.1}
\end{equation*}
$$

Throughout the rest of this section, we work in two dimensions. Therefore, we drop the prime marking two-dimensional objects. Hence from now on, $\Omega$ is a bounded, open, simply connected domain in $\mathbb{R}^{2}$ with smooth boundary, and $v=\left(v^{1}, v^{2}\right)$ denotes the outer normal vector to its boundary. We further set $\tau=\left(\tau^{1}, \tau^{2}\right)=\left(-\nu^{2}, \nu^{1}\right)$. For $x_{0} \in \bar{\Omega}$ and $r>0$, we denote $D_{r}\left(x_{0}\right)=\Omega \cap B_{r}\left(x_{0}\right)$ and $D_{r}^{*}\left(x_{0}\right)=\partial \Omega \cap B_{r}\left(x_{0}\right)$.

For a fixed $\alpha \in(0,1]$ and for $0<\epsilon \leq 1$, we consider the functionals

$$
\begin{equation*}
J_{\epsilon}(f)=\frac{1}{2} \int_{\Omega}\left(|\nabla f|^{2}+\frac{1}{2 \epsilon^{2}}\left(|f|^{2}-1\right)^{2}\right) d x+\frac{1}{2 \epsilon^{\alpha}} \int_{\partial \Omega}(f \cdot v)^{2} d o \tag{5.2}
\end{equation*}
$$

on $H^{1}\left(\Omega, \mathbb{R}^{2}\right)$. For any $\epsilon \in(0,1]$, we fix a minimizer $f_{\epsilon} \in H^{1}\left(\Omega, \mathbb{R}^{2}\right)$ of $J_{\epsilon}$.
Our aim is to prove a result similar to those in $[4,25,26]$ for the functionals $J_{\epsilon}$ in order to obtain an idea of the limiting behaviour for minimizers of $E_{\epsilon}$ without restrictions on the boundary data.

Theorem 5.1. There exist a sequence $\epsilon_{k} \searrow 0$ and a set $\Sigma \subset \bar{\Omega}$, which is either of the form $\Sigma=\left\{x_{0}\right\}$ for a point $x_{0} \in \Omega$, or $\Sigma=\left\{x_{1}, x_{2}\right\}$ for two different points $x_{1}, x_{2} \in \partial \Omega$, such that $\mathrm{f}_{\epsilon_{k}} \rightarrow \mathrm{f}$ weakly in $H_{\text {loc }}^{1}\left(\bar{\Omega} \backslash \Sigma, \mathbb{R}^{2}\right)$ and weakly in $W^{1, p}\left(\Omega, \mathbb{R}^{2}\right)$ for all $p<2$, where $\mathrm{f}: \bar{\Omega} \backslash \Sigma \rightarrow \mathbb{S}^{1}$ is a harmonic map. The case $\Sigma=\left\{x_{0}\right\}$ can only occur if $\alpha=1$.

The proof of Theorem 5.1 will follow roughly the outline of the arguments in [25, 26]. First we need an estimate for the energy of $f_{\epsilon}$.

Lemma 5.2. There exists a constant C , depending only on $\Omega$, such that

$$
\begin{equation*}
\mathrm{J}_{\epsilon}\left(\mathrm{f}_{\epsilon}\right) \leq \mathrm{C}-\alpha \pi \log \epsilon \tag{5.3}
\end{equation*}
$$

for $0<\epsilon \leq 1$.
Proof. We assume for simplicity that $\partial \Omega$ contains two points $x_{1}$ and $x_{2}$, such that

$$
\begin{equation*}
\partial \Omega \cap B_{1}\left(x_{i}\right)=\left\{x \in B_{1}\left(x_{i}\right):\left(x-x_{i}\right) \cdot v\left(x_{i}\right)=0\right\}, \quad i=1,2, \tag{5.4}
\end{equation*}
$$

and $B_{2}\left(x_{1}\right) \cap B_{2}\left(x_{2}\right)=\varnothing$. If this is not the case, we may map $\Omega$ onto a domain which has this property by a $C^{2}$-diffeomorphism. It is then easy to check that the following construction gives rise to a map which satisfies the estimate (5.3).

For $0<\epsilon \leq 1$, set $x_{i \epsilon}=x_{i}+\epsilon^{\alpha} v\left(x_{i}\right), i=1,2$. Define

$$
g_{\epsilon}(x)= \begin{cases}\frac{x-x_{1 \epsilon}}{\left|x-x_{1 \epsilon}\right|}, & \text { if } x \in B_{1}\left(x_{1}\right),  \tag{5.5}\\ \frac{x_{2 \epsilon}-x}{\left|x_{2 \epsilon}-x\right|}, & \text { if } x \in B_{1}\left(x_{2}\right) .\end{cases}
$$

This map satisfies

$$
\begin{align*}
& \int_{\Omega \cap \mathrm{B}_{1\left(\mathrm{x}_{\mathrm{i}}\right)}}\left|\nabla \mathrm{g}_{\epsilon}\right|^{2} \mathrm{~d} x \leq \pi \log \left(\frac{2}{\epsilon^{\alpha}}\right), \\
& \int_{\partial \Omega \cap B_{1}\left(x_{i}\right)}\left(g_{\epsilon} \cdot v\right)^{2} d o \leq \int_{-1}^{1} \frac{\epsilon^{2 \alpha}}{s^{2}+\epsilon^{2 \alpha}} \mathrm{ds}  \tag{5.6}\\
& \leq \epsilon^{\alpha} \int_{-\infty}^{\infty} \frac{\mathrm{ds}}{\mathrm{~s}^{2}+1} \\
& =\pi \epsilon^{\alpha}
\end{align*}
$$

for $i=1,2$. Obviously $g_{\epsilon}$ can be extended to $\Omega$ such that it satisfies (5.3). Hence also $f_{\epsilon}$ satisfies (5.3).

Lemma 5.3. The maps $f_{\epsilon}$ are smooth in $\Omega$ and satisfy $\left|f_{\epsilon}\right| \leq 1$ and $\left|\nabla f_{\epsilon}\right| \leq C / \epsilon$ for a constant C which depends only on $\Omega$.

Proof. The maps $f_{\epsilon}$ satisfy the equations

$$
\begin{equation*}
\Delta f_{\epsilon}=\frac{1}{\epsilon^{2}}\left(\left|f_{\epsilon}\right|^{2}-1\right) f_{\epsilon} \quad \text { in } \Omega, \tag{5.7}
\end{equation*}
$$

with the boundary conditions

$$
\begin{equation*}
\frac{\partial f_{\epsilon}}{\partial v}=-\frac{1}{\epsilon^{\alpha}}\left(f_{\epsilon} \cdot v\right) v \quad \text { on } \partial \Omega \text {. } \tag{5.8}
\end{equation*}
$$

The regularity thus follows from standard results in the theory of elliptic equations.
To prove $\left|f_{\epsilon}\right| \leq 1$, we apply the maximum principle, similarly as in [3] or [25]. More precisely, for any fixed $\epsilon$, we consider the function $g=\left|f_{\epsilon}\right|^{2}$ in the set $\Omega^{+}=\{x \in \Omega$ : $g(x)>1\}$. We have

$$
\begin{align*}
& \Delta g=\frac{2}{\epsilon^{2}}(g-1) g+2\left|\nabla f_{\epsilon}\right|^{2} \geq 0 \quad \text { in } \Omega^{+},  \tag{5.9}\\
& \frac{\partial g}{\partial v}=-\frac{2}{\epsilon^{\alpha}}\left(f_{\epsilon} \cdot v\right)^{2} \leq 0 \quad \text { on } \partial \Omega .
\end{align*}
$$

Hence g can take its maximum neither in $\Omega^{+}$nor on $\partial \Omega \cap \partial \Omega^{+}$unless it is constant in $\Omega^{+}$. It follows that $\mathrm{g} \leq 1$ and thus $\left|\mathrm{f}_{\epsilon}\right| \leq 1$.

For the gradient estimate, we first estimate the Dirichlet energy of $f_{\epsilon}$ on balls of radius $\epsilon$. For a given point $x \in \Omega$, choose a cutoff function $\eta \in C_{0}^{\infty}\left(B_{2 \epsilon}(x)\right)$ with the
properties $0 \leq \eta \leq 1, \eta \equiv 1$ in $B_{\epsilon}(x)$, and $|\nabla \eta| \leq 2 / \epsilon$. We have

$$
\begin{align*}
\int_{\Omega} \eta^{2}\left|\nabla f_{\epsilon}\right|^{2} d x= & \frac{1}{\epsilon^{2}} \int_{\Omega} \eta^{2}\left(1-\left|f_{\epsilon}\right|^{2}\right)\left|f_{\epsilon}\right|^{2} d x-2 \int_{\Omega} \eta \frac{\partial \eta}{\partial x^{i}} f_{\epsilon} \cdot \frac{\partial f_{\epsilon}}{\partial x^{i}} d x \\
& -\frac{1}{\epsilon^{\alpha}} \int_{\partial \Omega} \eta^{2}\left(f_{\epsilon} \cdot v\right)^{2} d o  \tag{5.10}\\
\leq & \frac{C_{1}}{2}+\frac{1}{2} \int_{\Omega} \eta^{2}\left|\nabla f_{\epsilon}\right|^{2} d x
\end{align*}
$$

for a constant $C_{1}=C_{1}(\Omega)$. Here and in the following, we use the summation convention, that is, we sum over repeated indices from 1 to 2 . We conclude that

$$
\begin{equation*}
\int_{\mathrm{B}_{e}(x)}\left|\nabla \mathrm{f}_{e}\right|^{2} \mathrm{~d} x \leq \mathrm{C}_{1} . \tag{5.11}
\end{equation*}
$$

We can now use a blowup argument similar to those in the proofs of Lemmas 3.2 and 3.3. If the estimate was not true, then we could find solutions $f_{k} \in C^{\infty}\left(\Omega, \mathbb{R}^{2}\right)$ of (5.7) and (5.8) for certain numbers $\epsilon_{k} \in(0,1]$, such that certain points $x_{k} \in \bar{\Omega}$ would exist with the property

$$
\begin{equation*}
e_{k}:=\left|\nabla f_{k}\left(x_{k}\right)\right|=\sup _{\Omega}\left|\nabla f_{k}\right|>\frac{c_{k}}{\epsilon_{\mathrm{k}}}, \tag{5.12}
\end{equation*}
$$

where $c_{k} \rightarrow \infty$ for $k \rightarrow \infty$. Define

$$
\begin{equation*}
\widehat{f}_{k}(x)=f_{k}\left(\frac{2 \sqrt{C_{1}} x}{e_{k}}+x_{k}\right) \tag{5.13}
\end{equation*}
$$

so that $\left|\nabla \widehat{f}_{k}(0)\right|=2 \sqrt{C_{1}}$ and $\left|\nabla \widehat{f}_{k}\right| \leq 2 \sqrt{C_{1}}$ wherever $\widehat{f}_{k}$ is defined. We see that a subsequence of $\left\{\widehat{f}_{k}\right\}$ converges to a solution $\widehat{f}: \Sigma \rightarrow \mathbb{R}^{2}$ of Laplace's equation $\Delta \widehat{f}=0$, with either $\Sigma=\mathbb{R}^{2}$ or $\Sigma=\left\{x \in \mathbb{R}^{2}: a \cdot x>\alpha\right\}$ for some $a \in \mathbb{S}^{1}$ and some $\alpha \geq 0$. In the latter case, we have homogeneous Neumann boundary conditions for $\widehat{f}$ on $\partial \Sigma$. Furthermore, we have $|\nabla \widehat{f}(0)|=2 \sqrt{C_{1}}$, but also

$$
\begin{align*}
|\nabla \widehat{\mathrm{f}}(0)| & \leq \frac{2}{\pi} \int_{\sum \cap B_{1}(0)}|\nabla \widehat{\mathrm{f}}| \mathrm{d} x \\
& \leq \frac{2}{\sqrt{\pi}}\left(\int_{\sum \cap B_{1}(0)}|\nabla \widehat{\mathrm{f}}|^{2} \mathrm{~d} x\right)^{1 / 2}  \tag{5.14}\\
& \leq 2 \sqrt{\frac{\mathrm{C}_{1}}{\pi}}
\end{align*}
$$

by the mean value theorem and the energy estimate above. Hence we have a contradiction, and the estimate is proven.

Lemma 5.4. There exist $C>0$ and $r_{0}>0$, depending only on $\Omega$, such that for $0<\epsilon \leq 1$, $x_{0} \in \partial \Omega$, and $0<r \leq r_{0}$,

$$
\begin{align*}
& \frac{1}{2 \epsilon^{2}} \int_{D_{r}\left(x_{0}\right)}\left(\left|f_{\epsilon}\right|^{2}-1\right)^{2} d x+\frac{1}{\epsilon^{\alpha}} \int_{D_{r}^{*}\left(x_{0}\right)}\left(f_{\epsilon} \cdot v\right)^{2} d o \\
& \leq C r\left[\int_{D_{r}\left(x_{0}\right)}\left|\nabla f_{\epsilon}\right|^{2} d x+\int_{\Omega \cap \partial B_{r}\left(x_{0}\right)}\left(\left|\nabla f_{\epsilon}\right|^{2}+\frac{1}{2 \epsilon^{2}}\left(\left|f_{\epsilon}\right|^{2}-1\right)^{2}\right) d o\right.  \tag{5.15}\\
& \left.\quad+\frac{1}{\epsilon^{\alpha}} \sum_{x \in \partial \Omega \cap \partial B_{r}\left(x_{0}\right)}\left(f_{\epsilon}(x) \cdot v(x)\right)^{2}+\frac{r}{\epsilon^{\alpha}}\right] .
\end{align*}
$$

Proof. Let $\psi \in C^{\infty}\left(\Omega, \mathbb{R}^{2}\right)$ be a vector field which satisfies $\psi \cdot v=0$ on $\partial \Omega$. Consider the 1-parameter family of diffeomorphisms $\Psi_{\mathrm{t}}: \Omega \rightarrow \Omega$, obtained as the solution to

$$
\begin{equation*}
\frac{\partial \Psi_{\mathrm{t}}}{\partial \mathrm{t}}=\psi \circ \Psi_{\mathrm{t}}, \quad \Psi_{0}=\mathrm{id} \tag{5.16}
\end{equation*}
$$

for $t$ in a neighbourhood of 0 . From the condition $d /\left.d t\right|_{t=0} J_{\epsilon}\left(f_{\epsilon} \circ \Psi_{t}\right)=0$, we derive by an integration by parts

$$
\begin{align*}
0= & \int_{\Omega}\left[\frac{\partial \psi^{i}}{\partial x^{j}} \frac{\partial f_{\epsilon}}{\partial x^{i}} \cdot \frac{\partial f_{\epsilon}}{\partial x^{j}}-\frac{1}{2} \operatorname{div} \psi\left(\left|\nabla f_{\epsilon}\right|^{2}+\frac{1}{2 \epsilon^{2}}\left(\left|f_{\epsilon}\right|^{2}-1\right)\right)\right] d x \\
& -\frac{1}{\epsilon^{\alpha}} \int_{\partial \Omega}\left[\frac{1}{2} \tau^{i} \frac{\partial}{\partial x^{i}}(\psi \cdot \tau)\left(f_{\epsilon} \cdot v\right)^{2}+\kappa(\psi \cdot \tau)\left(f_{\epsilon} \cdot v\right)\left(f_{\epsilon} \cdot \tau\right)\right] d o, \tag{5.17}
\end{align*}
$$

where $k=\tau^{i}\left(\partial \nu / \partial x_{i}\right) \cdot \tau$ is the curvature of $\partial \Omega$.
For an appropriate choice of $\mathrm{r}_{0}$, there exists a vector field $\phi=\left(\phi^{1}, \phi^{2}\right) \in$ $C^{\infty}\left(D_{r_{0}}\left(x_{0}\right), \mathbb{R}^{2}\right)$ with the properties
(i) $\phi \cdot v=0$ on $D_{r_{0}}^{*}\left(x_{0}\right)$,
(ii) $\left|\phi(x)-\left(x-x_{0}\right)\right| \leq C_{1}\left|x-x_{0}\right|^{2}$,
(iii) $\left|\left(\partial \phi^{i} / \partial x^{j}\right)(x)-\delta_{i j}\right| \leq C_{1}\left|x-x_{0}\right|$,
for a constant $C_{1}=C_{1}(\Omega)$. Choosing $\psi=\eta \phi$ as a test vector field in (5.17), where $\eta \in$ $C_{0}^{\infty}\left(B_{r}\left(x_{0}\right)\right)$, we see that

$$
\begin{align*}
& \frac{1}{4 \epsilon^{2}} \int_{\Omega}\left(\left|f_{\epsilon}\right|^{2}-1\right)^{2} \eta \mathrm{~d} x+\frac{1}{2 \epsilon^{\alpha}} \int_{\partial \Omega}\left(f_{\epsilon} \cdot v\right)^{2} \eta \mathrm{do} \\
& \leq \mathrm{C}_{3} r\left[\int_{\Omega}\left(\left|\nabla \mathrm{f}_{\epsilon}\right|^{2}+\frac{1}{2 \epsilon^{2}}\left(\left|\mathrm{f}_{\epsilon}\right|^{2}-1\right)^{2}\right) \eta \mathrm{d} x+\frac{1}{\epsilon^{\alpha}} \int_{\partial \Omega}\left(\left(\mathrm{f}_{\epsilon} \cdot v\right)^{2}+\left|\mathrm{f}_{\epsilon} \cdot v\right|\right) \eta \mathrm{do}\right] \\
&+\int_{\Omega}\left[\phi^{i} \frac{\partial \eta}{\partial x^{j}} \frac{\partial \mathrm{f}_{\epsilon}}{\partial x^{i}} \cdot \frac{\partial \mathrm{f}_{\epsilon}}{\partial x^{j}}-\frac{1}{2} \phi \cdot \nabla \eta\left(\left|\nabla \mathrm{f}_{\epsilon}\right|^{2}+\frac{1}{2 \epsilon^{2}}\left(\left|\mathrm{f}_{\epsilon}\right|^{2}-1\right)^{2}\right)\right] \mathrm{dx} \\
&-\frac{1}{\epsilon^{\alpha}} \int_{\partial \Omega}(\nabla \eta \cdot \tau)(\phi \cdot \tau)\left(\mathrm{f}_{\epsilon} \cdot v\right)^{2} \text { do, } \tag{5.18}
\end{align*}
$$

where $C_{3}=C_{3}(\Omega)$. Approximating the characteristic function of $B_{r}\left(x_{0}\right)$ by $\eta$, we conclude that (5.15) holds for a constant $C=C(\Omega)$ provided that $\mathrm{r}_{0} \leq 1 / 4 \mathrm{C}_{3}$.

Now, choose two numbers $\beta$ and $\gamma$ with $3 \alpha / 4 \leq \beta<\gamma<\alpha$.
Lemma 5.5. There exist constants $\epsilon_{0}, \lambda, C>0$, depending only on $\Omega, \beta$, and $\gamma$, such that for any $\epsilon \in\left(0, \epsilon_{0}\right]$ and any $x_{0} \in \bar{\Omega}$, the condition

$$
\begin{equation*}
\int_{D_{\epsilon} \beta\left(x_{0}\right)}\left(\left|\nabla f_{\epsilon}\right|^{2}+\frac{1}{2 \epsilon^{2}}\left(\left|f_{\epsilon}\right|^{2}-1\right)^{2}\right) d x+\frac{1}{\epsilon^{\alpha}} \int_{D_{\epsilon \beta}^{*}\left(x_{0}\right)}\left(f_{\epsilon} \cdot v\right)^{2} \text { do } \leq-\lambda \log \epsilon \tag{5.19}
\end{equation*}
$$

implies $\left|f_{\epsilon}\right| \geq 1 / 2$ in $D_{\epsilon \gamma}\left(x_{0}\right),\left|f_{\epsilon} \cdot v\right| \leq 1 / 4$ on $D_{\epsilon \gamma}^{*}\left(x_{0}\right)$, and

$$
\begin{equation*}
\frac{1}{2 \epsilon^{2}} \int_{D_{e \gamma}\left(x_{0}\right)}\left(\left|f_{\epsilon}\right|^{2}-1\right)^{2} d x+\frac{1}{\epsilon^{\alpha}} \int_{D_{\epsilon \gamma}^{*} \gamma\left(x_{0}\right)}\left(f_{\epsilon} \cdot v\right)^{2} d o \leq C\left(\lambda+\epsilon^{\alpha / 2}\right) . \tag{5.20}
\end{equation*}
$$

Proof. For $\mathrm{B}_{\epsilon^{\beta}}\left(\mathrm{x}_{0}\right) \subset \Omega$, this is proven in [25]. In the other case, we assume for simplicity that $x_{0} \in \partial \Omega$. The general case can be reduced to these two special cases.

There exists a radius $r \in\left(\epsilon^{\gamma}, \epsilon^{\beta}\right)$ with the property

$$
\begin{equation*}
r \int_{\Omega \cap \partial \mathrm{B}_{\mathrm{r}\left(x_{0}\right)}}\left(\left|\nabla \mathrm{f}_{\epsilon}\right|^{2}+\frac{1}{2 \epsilon^{2}}\left(\left|f_{\epsilon}\right|^{2}-1\right)^{2}\right) \mathrm{do}+\frac{r}{\epsilon^{\alpha}} \sum_{x \in \partial \Omega \cap \partial \mathrm{~B}_{r}\left(x_{0}\right)}\left(f_{\epsilon}(x) \cdot v(x)\right)^{2} \leq \frac{4 \lambda}{\gamma-\beta} . \tag{5.21}
\end{equation*}
$$

Estimate (5.20) then follows from Lemma 5.4.
Recall that $\left|\nabla f_{\epsilon}\right| \leq C_{1} / \varepsilon$ for a constant $C_{1}=C_{1}(\Omega)$ by Lemma 5.3. Hence, if we had a point $x \in D_{\epsilon^{\gamma}}\left(x_{0}\right)$ with $\left|f_{\epsilon}(x)\right|<1 / 2$, then we would conclude that $\left|f_{\epsilon}\right| \leq 3 / 4$ in $\mathrm{D}_{\mathrm{ce}}(\mathrm{x})$ for $\mathrm{c}=1 / 4 \mathrm{C}_{1}$, and we would thus find a contradiction to (5.20) provided that $\lambda$ and $\epsilon_{0}$ are sufficiently small. Hence $\left|f_{\epsilon}\right| \geq 1 / 2$ in $D_{\epsilon}\left(x_{0}\right)$.

We extend $v$ and $\tau$ to $\partial \mathrm{D}_{\mathrm{r}}\left(\mathrm{x}_{0}\right)$ such that they are normal and tangential, respectively, to that boundary. If $\epsilon_{0}$ is small enough, then $D_{r}\left(x_{0}\right)$ is strictly star-shaped in the sense that $\left(x-x_{1}\right) \cdot v(x) \geq r / 4$ on $\partial D_{r}\left(x_{0}\right)$ for some point $x_{1} \in D_{r}\left(x_{0}\right)$. Using the Pohožaev identity for solutions of (5.7) (cf. [4, 25]), we obtain

$$
\begin{align*}
& \int_{\partial \mathrm{D}_{\mathrm{r}}\left(x_{0}\right)}\left(x-x_{1}\right) \cdot v\left|\frac{\partial f_{\epsilon}}{\partial v}\right|^{2} d o+\frac{1}{\epsilon^{2}} \int_{\mathrm{D}_{\mathrm{r}\left(x_{0}\right)}}\left(\left|f_{\epsilon}\right|^{2}-1\right)^{2} \mathrm{dx} \\
& \quad=\int_{\partial \mathrm{D}_{\mathrm{r}}\left(x_{0}\right)}\left(\left(x-x_{1}\right) \cdot v\left|\frac{\partial f_{\epsilon}}{\partial \tau}\right|^{2}-2\left(x-x_{1}\right) \cdot \tau \frac{\partial f_{\epsilon}}{\partial v} \cdot \frac{\partial f_{\epsilon}}{\partial \tau}\right) \mathrm{do} . \tag{5.22}
\end{align*}
$$

Note that we have proven (5.20) actually for the radius $r$ instead of $\epsilon^{\gamma}$. Combining the identity above with this version of (5.20) and with (5.21), we conclude that

$$
\begin{equation*}
\int_{D_{r}^{*}\left(x_{0}\right)}\left|\frac{\partial f_{\epsilon}}{\partial \tau}\right|^{2} \text { do } \leq C_{2}\left[\int_{D_{r}^{*}\left(x_{0}\right)}\left|\frac{\partial f_{\epsilon}}{\partial v}\right|^{2} \text { do }+\lambda+\epsilon^{\alpha / 2}\right] \tag{5.23}
\end{equation*}
$$

for a constant $C_{2}=C_{2}(\Omega, \beta, \gamma)$. By the boundary conditions (5.8), we even have

$$
\begin{align*}
\int_{D_{r}^{*}\left(x_{0}\right)}\left|\frac{\partial f_{\epsilon}}{\partial \tau}\right|^{2} \text { do } & \leq C_{2}\left[\frac{1}{\epsilon^{2 \alpha}} \int_{D_{r}^{*}\left(x_{0}\right)}\left(f_{\epsilon} \cdot v\right)^{2} \text { do }+\lambda+\epsilon^{\alpha / 2}\right]  \tag{5.24}\\
& \leq \frac{C_{3}}{\epsilon^{\alpha}},
\end{align*}
$$

where $C_{3}=C_{3}(\Omega, \beta, \gamma)$. Here we have used again the version of (5.20) for the radius $r$. For $x, y \in D_{r}^{*}\left(x_{0}\right)$, it follows that

$$
\begin{equation*}
\left|f_{\epsilon}(x)-f_{\epsilon}(y)\right| \leq C_{4} \sqrt{|x-y|} e^{-\alpha / 2} \tag{5.25}
\end{equation*}
$$

where $C_{4}=C_{4}(\Omega, \beta, \gamma)$. The estimate for $\left|f_{\epsilon} \cdot \gamma\right|$ on $D_{\epsilon \gamma}^{*}\left(x_{0}\right)$ is now proven similarly as the one for $\left|\mathrm{f}_{\epsilon}\right|$ in $\mathrm{D}_{\epsilon^{\gamma}}\left(\mathrm{x}_{0}\right)$.

Now choose a number $r_{0}>0$, such that for each $x_{0} \in \bar{\Omega}$ and every $r \in\left(0, r_{0}\right]$, the sets $D_{r}\left(x_{0}\right)$ and $D_{r}^{*}\left(x_{0}\right)$ are connected. For $0<r \leq R \leq r_{0}$ and $x_{0} \in \bar{\Omega}$, define

$$
\begin{align*}
& A_{r, R}\left(x_{0}\right)=\Omega \cap B_{R}\left(x_{0}\right) \backslash B_{r}\left(x_{0}\right), \\
& A_{r, R}^{*}\left(x_{0}\right)=\partial \Omega \cap B_{R}\left(x_{0}\right) \backslash B_{r}\left(x_{0}\right) . \tag{5.26}
\end{align*}
$$

Suppose that a continuous map $f: \bar{\Omega} \rightarrow \mathbb{R}^{2}$ is given such that $|f| \geq 1 / 2$ in $A_{r, R}\left(x_{0}\right)$ and $|f \cdot v| \leq 1 / 4$ on $A_{r, R}^{*}\left(x_{0}\right)$. These conditions imply in particular $|f \cdot \tau| \geq \sqrt{3} / 4$ on $A_{r, R}^{*}\left(x_{0}\right)$. Hence the sign of $f \cdot \tau$ is constant on each connected component of $A_{r, R}^{*}\left(x_{0}\right)$ (of which there are exactly two). In the following, when we say that $f \cdot \tau$ changes sign in $D_{r}^{*}\left(x_{0}\right)$, we mean that it takes both signs on $A_{r, R}^{*}\left(x_{0}\right)$. If it does not change sign, we may extend the map $g=\left.f\right|_{\Omega \cap \partial B_{R}\left(x_{0}\right)}$ to $\partial D_{R}\left(x_{0}\right)$ in such a way that $|g| \geq 1 / 2$ and $|g \cdot v| \leq 1 / 4$ hold also on $D_{R}^{*}\left(x_{0}\right)$. We say that $g$ is topologically nontrivial if the topological degree of this extension (which maps $\partial D_{R}\left(x_{0}\right) \cong \mathbb{S}^{1}$ to $\mathbb{R}^{2} \backslash B_{1 / 2}(0)$ ) is nonzero.

The following is a generalization of [26, Proposition 3.4'].

Proposition 5.6. For $x_{0} \in \bar{\Omega}$ and $0<r<R \leq r_{0}$, suppose that $f \in C^{1}\left(\bar{\Omega}, \mathbb{R}^{2}\right)$ satisfies $1 / 2 \leq|f| \leq 1$ in $A_{r, R}\left(x_{0}\right)$ and $|f \cdot v| \leq 1 / 4$ on $A_{r, R}^{*}\left(x_{0}\right)$. Suppose furthermore that

$$
\begin{align*}
& J_{\epsilon}(f) \leq K(1-\log \epsilon), \\
& \frac{1}{2 \epsilon^{2}} \int_{D_{\epsilon \beta}\left(x_{0}\right)}\left(|f|^{2}-1\right)^{2} d x+\frac{1}{\epsilon^{\alpha}} \int_{D_{\epsilon \beta}^{*}\left(x_{0}\right)}(f \cdot v)^{2} d o \leq K, \tag{5.27}
\end{align*}
$$

for some number $K$. There exists a constant $C$, depending only on $\Omega$, $\beta$, and $K$, such that the following is true.
(i) Suppose $B_{R}\left(x_{0}\right) \subset \Omega$ and $r \geq \epsilon$. If the topological degree of the restriction of $f$ to $\partial B_{R}\left(x_{0}\right)$ is not 0 , then

$$
\begin{equation*}
\int_{\mathcal{A}_{r, R}\left(x_{0}\right)}|\nabla f|^{2} \mathrm{~d} x \geq 2 \pi \log \left(\frac{R}{r}\right)-C \tag{5.28}
\end{equation*}
$$

(ii) Suppose $x_{0} \in \partial \Omega$ and $r \geq \epsilon^{\alpha}$. If $f \cdot \tau$ changes $\operatorname{sign}$ in $D_{r}^{*}\left(x_{0}\right)$, then

$$
\begin{equation*}
\int_{A_{r, R}\left(x_{0}\right)}|\nabla f|^{2} \mathrm{~d} x \geq \pi \log \left(\frac{\mathrm{R}}{\mathrm{r}}\right)-\mathrm{C} \tag{5.29}
\end{equation*}
$$

(iii) Suppose $x_{0} \in \partial \Omega$ and $r \geq \epsilon^{\alpha}$. If $f \cdot \tau$ does not change sign in $D_{r}^{*}\left(x_{0}\right)$ and if $\left.f\right|_{\Omega \cap \partial B_{R}\left(x_{0}\right)}$ is topologically nontrivial, then

$$
\begin{equation*}
\int_{A_{r, R}\left(x_{0}\right)}|\nabla f|^{2} d x \geq 4 \pi \log \left(\frac{R}{r}\right)-C \tag{5.30}
\end{equation*}
$$

Proof. We only give a proof for (ii). Part (i) is proven in [25, 26], and the proof of (iii) is very similar to the proof of (ii). The following arguments are for the most part the same as in $[25,26]$.

We assume for simplicity that $x_{0}=0$ and $v(0)=(0,-1)$. Using polar coordinates $x=\rho e^{i \theta}$, we can write

$$
\begin{equation*}
f(x)=\sigma(x) e^{i(\theta+\phi(x))} \tag{5.31}
\end{equation*}
$$

where $\sigma, \phi \in C^{1}\left(A_{r, R}(0)\right)$ with $1 / 2 \leq \sigma \leq 1$. We can choose $\phi$ such that either $|\phi(x)| \leq$ $C_{1}(|f(x) \cdot v(x)|+\rho)$ or $|\phi(x)-\pi| \leq C_{1}(|f(x) \cdot v(x)|+\rho)$ on $A_{r, R}^{*}(0)$ for a constant $C_{1}=C_{1}(\Omega)$.

Note that

$$
\begin{align*}
|\nabla f|^{2} & \geq \sigma^{2}|\nabla \theta+\nabla \phi|^{2} \\
& =\frac{\sigma^{2}}{\rho^{2}}\left(1+2 \frac{\partial \phi}{\partial \theta}\right)+\sigma^{2}|\nabla \phi|^{2} \tag{5.32}
\end{align*}
$$

Furthermore,

$$
\begin{align*}
\int_{A_{r, R}(0)} \frac{\sigma^{2}}{\rho^{2}} d x & =\int_{A_{r, R}(0)} \frac{1}{\rho^{2}} d x+\int_{A_{r, R}(0)} \frac{\sigma^{2}-1}{\rho^{2}} \mathrm{~d} x  \tag{5.33}\\
& \geq \pi \log (R / r)-C_{2}+\int_{A_{r, R}(0)} \frac{\sigma^{2}-1}{\rho^{2}} d x
\end{align*}
$$

for a constant $C_{2}=C_{2}(\Omega)$. Note that for every $\rho \in[r, R]$, we have

$$
\begin{equation*}
-\int_{\Omega \cap \partial \mathrm{B}_{\rho}(0)} \frac{1}{\rho} \frac{\partial \phi}{\partial \theta} \mathrm{~d} \theta \leq \mathrm{C}_{1}\left(\sum_{x \in \partial \Omega \cap \partial \mathrm{~B}_{\rho}(0)}|f(x) \cdot v(x)|+2 \rho\right) \tag{5.34}
\end{equation*}
$$

Thus

$$
\begin{equation*}
2 \int_{\mathcal{A}_{r, R}(0)} \frac{\sigma^{2}}{\rho^{2}} \frac{\partial \phi}{\partial \theta} d x \geq 2 \int_{\mathcal{A}_{r, R}(0)} \frac{\sigma^{2}-1}{\rho^{2}} \frac{\partial \phi}{\partial \theta} d x-2 C_{1} \int_{\mathcal{A}_{r, R}^{*}(0)}\left(\frac{|f \cdot v|}{\rho}+1\right) d o . \tag{5.35}
\end{equation*}
$$

We write

$$
\begin{equation*}
\int_{A_{r, R}(0)} \frac{\sigma^{2}-1}{\rho^{2}} \frac{\partial \phi}{\partial \theta} d x=\int_{\mathcal{A}_{r, \epsilon \beta}(0)} \frac{\sigma^{2}-1}{\rho^{2}} \frac{\partial \phi}{\partial \theta} d x+\int_{\mathcal{A}_{\epsilon \beta, R}(0)} \frac{\sigma^{2}-1}{\rho^{2}} \frac{\partial \phi}{\partial \theta} d x \tag{5.36}
\end{equation*}
$$

(provided that $r<\epsilon^{\beta}<R$; otherwise we consider only one of these terms) and we estimate

$$
\begin{align*}
\left|\int_{\mathcal{A}_{r, e \beta}(0)} \frac{\sigma^{2}-1}{\rho^{2}} \frac{\partial \phi}{\partial \theta} d x\right| & \leq \frac{1}{\epsilon}\left(\int_{A_{r, \epsilon \beta}(0)}\left(\sigma^{2}-1\right)^{2} \mathrm{~d} x\right)^{1 / 2}\left(\int_{\mathcal{A}_{r, \epsilon \beta}(0)}|\nabla \phi|^{2} \mathrm{dx}\right)^{1 / 2} \\
& \leq 4 K+\frac{1}{8} \int_{\mathcal{A}_{r, \epsilon \beta}(0)}|\nabla \phi|^{2} \mathrm{~d} x, \\
\left|\int_{A_{\epsilon \beta, R}(0)} \frac{\sigma^{2}-1}{\rho^{2}} \frac{\partial \phi}{\partial \theta} d x\right| & \leq \frac{1}{\epsilon^{\beta}}\left(\int_{A_{\epsilon \beta, R}(0)}\left(\sigma^{2}-1\right)^{2} d x\right)^{1 / 2}\left(\int_{\mathcal{A}_{\epsilon \beta, R}(0)}|\nabla \phi|^{2} d x\right)^{1 / 2} \\
& \leq 8 K \epsilon^{2-2 \beta}(1-\log \epsilon)+\frac{1}{8} \int_{\mathcal{A}_{\epsilon \beta, R}(0)}|\nabla \phi|^{2} d x . \tag{5.37}
\end{align*}
$$

Similarly, we prove

$$
\begin{equation*}
\int_{A_{r, R}(0)} \frac{1-\sigma^{2}}{\rho^{2}} d x+\int_{A_{r, R}^{*}(0)}\left(\frac{|f \cdot v|}{\rho}+1\right) d o \leq C_{3}(\Omega, K, \beta) \tag{5.38}
\end{equation*}
$$

Finally,

$$
\begin{equation*}
\int_{A_{r, R}(0)} \sigma^{2}|\nabla \phi|^{2} \mathrm{~d} x \geq \frac{1}{4} \int_{A_{r, R}(0)}|\nabla \phi|^{2} \mathrm{~d} x \tag{5.39}
\end{equation*}
$$

To complete the proof, we only need to combine these estimates.
Proof of Theorem 5.1. For each $\epsilon \in(0,1]$, define the set

$$
\begin{equation*}
S_{\epsilon}=\left\{x \in \bar{\Omega}:\left|f_{\epsilon}(x)\right|<\frac{1}{2}\right\} \cup\left\{x \in \partial \Omega:\left|f_{\epsilon} \cdot v\right|>\frac{1}{4}\right\} . \tag{5.40}
\end{equation*}
$$

Choose a maximal collection of balls $B_{m}=B_{\epsilon^{\beta}}\left(x_{m}\right), m=1, \ldots, M$, such that $x_{m} \in S_{\epsilon}$ and $B_{\epsilon^{\beta} / 4}\left(x_{l}\right) \cap B_{\epsilon^{\beta} / 4}\left(x_{m}\right)=\varnothing$ for $l \neq m$. Then obviously this collection covers $S_{\epsilon}$. Moreover, Lemmas 5.2 and 5.5 imply that $M$ is bounded by a number which is independent of $\epsilon$. For each $m$, we use the arguments in the proof of Lemma 5.5 to show that

$$
\begin{equation*}
\frac{1}{2 \epsilon^{2}} \int_{D_{2 \epsilon \beta}\left(x_{m}\right)}\left(\left|f_{\epsilon}\right|^{2}-1\right)^{2} d x+\frac{1}{\epsilon^{\alpha}} \int_{D_{2 \epsilon \beta}^{*}\left(x_{m}\right)}\left(f_{\epsilon} \cdot v\right)^{2} d o \leq C_{1} \tag{5.41}
\end{equation*}
$$

where $C_{1}=C_{1}(\Omega, \beta)$.
With the arguments from $[4,25,26]$ (i.e., similarly as in the proof of Theorem 1.1), combined with the arguments from the proof of Lemma 5.5 , we can now find numbers $R>0$ and $N \in \mathbb{N}$, which are independent of $\epsilon$, and points

$$
\begin{equation*}
y_{\in 1}, \ldots, y_{\in N} \in \overline{\Omega \cap \bigcup_{m=1}^{N} B_{m}} \tag{5.42}
\end{equation*}
$$

such that

$$
\begin{align*}
& \left|y_{\epsilon i}-y_{\epsilon j}\right| \geq 8 R \epsilon^{\alpha} \quad \text { or } \quad y_{\epsilon i}=y_{\epsilon j} \quad \text { for } 1 \leq i, j \leq N, \\
& \left|f_{\epsilon}\right| \geq \frac{1}{2} \quad \text { in } \Omega \backslash\left(\bigcup_{i=1}^{N} B_{R \epsilon^{\alpha}}\left(y_{\epsilon i}\right)\right),  \tag{5.43}\\
& \left|f_{\epsilon} \cdot v\right| \leq \frac{1}{4} \quad \text { on } \partial \Omega \backslash\left(\bigcup_{i=1}^{N} B_{R \epsilon^{\alpha}}\left(y_{\epsilon i}\right)\right),
\end{align*}
$$

for any $\epsilon \in(0,1]$. Again we may pick $\epsilon_{k} \searrow 0$ such that $y_{\epsilon_{k} i} \rightarrow y_{i}$ for certain points $y_{i} \in \bar{\Omega}$. Choose $\rho>0$ such that $B_{\rho}\left(y_{i}\right) \cap B_{\rho}\left(y_{j}\right)=\varnothing$ unless $y_{i}=y_{j}$, and $B_{\rho}\left(y_{i}\right) \subset \Omega$ unless $y_{i} \in \partial \Omega$. Now we may pick a subsequence (without changing notation) and relabel the points $y_{i}$ such that either
(i) $y_{1} \in \Omega$ and $\left.f_{\epsilon_{k}}\right|_{\partial B_{\rho}\left(y_{1}\right)}$ is topologically nontrivial, or
(ii) $y_{2}, y_{3} \in \partial \Omega, y_{2} \neq y_{3}$, and $f_{\epsilon_{k}} \cdot \tau$ changes sign in $D_{\rho}^{*}\left(y_{2}\right)$ and in $D_{\rho}^{*}\left(y_{3}\right)$.
(The conditions of (iii) in Proposition 5.6 cannot be satisfied for large k's because there is not enough energy.) Setting either $\Sigma=\left\{y_{1}\right\}$ or $\Sigma=\left\{y_{2}, y_{3}\right\}$, we conclude, using Proposition 5.6, that a subsequence of $\left\{f_{\epsilon_{k}}\right\}$ converges weakly in $H_{\text {loc }}^{1}\left(\bar{\Omega} \backslash \Sigma, \mathbb{R}^{2}\right)$ and weakly in $W^{1, p}(\Omega$, $\mathbb{R}^{2}$ ) for all $p<2$. To see that the limit is a harmonic map from $\Omega \backslash \Sigma \rightarrow \mathbb{S}^{1}$, we use the form

$$
\begin{equation*}
\operatorname{div}\left(f_{\epsilon} \wedge \nabla f_{\epsilon}\right)=0 \quad \operatorname{in} \Omega \tag{5.44}
\end{equation*}
$$

of (5.7). In order to prove that $\Sigma \subset \Omega$ can only happen for $\alpha=1$, we repeat the arguments above with balls of radius $\epsilon$ instead of $\epsilon^{\alpha}$, and show thus that a vortex in the interior of $\Omega$ needs more energy than available for $\alpha<1$.

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