

Bounded elements of C^* -inductive locally convex spaces

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Abstract The notion of bounded element of C^* -inductive locally convex spaces (or C^* -inductive partial $*$ -algebras) is introduced and discussed in two ways: The first one takes into account the inductive structure provided by certain families of C^* -algebras; the second one is linked to the natural order of these spaces. A particular attention is devoted to the relevant instance provided by the space of continuous linear maps acting in a rigged Hilbert space.

Keywords Bounded elements · Inductive limit of C^* -algebras · Partial $*$ -algebras

Mathematics Subject Classification 47L60 · 47L40

1 Introduction

Some locally convex spaces exhibit an interesting feature: They contain a large number of C^* -algebras that often contribute to their topological structure, in the sense that these spaces can be thought as *generalized* inductive limits of C^* -algebras. These objects were called *C^* -inductive locally convex spaces* in [8] and their structure was examined in detail, also taking in mind that they arise naturally when one considers the operators acting in the *joint topological limit* of an inductive family of Hilbert spaces as described in [9]. Indeed, a typical instance of this structure is obtained by considering the space $\mathcal{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^{\times})$ of operators acting in the rigged Hilbert space canonically associated with an O^* -algebra of unbounded operators acting on a dense domain \mathcal{D} of Hilbert space \mathcal{H} . In [8], a series of features of this structure was studied giving a particular attention to the order structure, positive linear functionals

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and representation theory. The space $\mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)$ contains a subspace isomorphic to the $*$ -algebra $\mathfrak{B}(\mathcal{H})$ of bounded operators in \mathcal{H} whose elements can be in natural way considered as the *bounded elements* of $\mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)$. The notion of bounded element of a locally convex $*$ -algebra \mathfrak{A} was first introduced by Allan [1] with the aim of developing a spectral theory for topological $*$ -algebras: An element x of the topological $*$ -algebra $\mathfrak{A}[\tau]$ is *Allan bounded* if there exists $\lambda \neq 0$ such that the set $\{(\lambda^{-1}x)^n; n = 1, 2, \dots\}$ is a bounded subset of $\mathfrak{A}[\tau]$. This definition was suggested by the successful spectral analysis for closed operators in Hilbert space \mathcal{H} : A complex number λ is in the resolvent set $\rho(T)$ of a closed operator T if $T - \lambda I$ has an inverse in the $*$ -algebra $\mathfrak{B}(\mathcal{H})$ of bounded operators.

There are, however, several other possibilities for defining bounded elements. For instance, one may say that x is bounded if $\pi(x)$ is a bounded operator, for every (continuous, in a certain sense) $*$ -representation π defined on a dense domain \mathcal{D}_π of some Hilbert space \mathcal{H}_π . This could be a reasonable definition in itself, provided that \mathfrak{A} possesses sufficiently many $*$ -representations in Hilbert space.

Moreover some attempts to extend this notion to the larger setup of locally convex quasi $*$ -algebras [10, 17–20] or locally convex partial $*$ -algebras [2, 5, 6] have been done. But in these cases, Allan’s notion cannot be adopted, since powers of a given element x need not be defined.

In the case of $*$ -algebras, bounded elements in purely algebraic terms have been considered by Vidav [22] and Schmüdgen [15] with respect to some (positive) wedge.

The aim of this paper is to extend the notion of bounded element to the case of C^* -inductive locally convex spaces \mathfrak{A} with defining family of C^* -algebras $\{\mathfrak{B}_\alpha; \alpha \in \mathbb{F}\}$ (\mathbb{F} is an index set directed upward). There are also in this case several possibilities: The first one consists in taking elements that have *representatives* in every C^* -algebra \mathfrak{B}_α of the family whose norms are uniformly bounded; the second one consists into taking into account the order structure of \mathfrak{A} , in the same spirit of the quoted papers of Vidav and Schmüdgen.

The paper is organized as follows. After some preliminaries (Sect. 2), we study, in Sect. 3, how *bounded elements* of $\mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)$ can be derived from its C^* -inductive structure and from its order structure. We show that these two notions are equivalent and that an element X is bounded if and only if X maps \mathcal{D} into \mathcal{H} and $\overline{X} \in \mathfrak{B}(\mathcal{H})$. Finally, in Sect. 4, we consider the same problem for abstract C^* -inductive locally convex spaces and give conditions for some of the characterizations proved for $\mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)$ maintain their validity. Some of these results are then specialized to the case where \mathfrak{A} is a C^* -inductive locally convex partial $*$ -algebra.

2 Notations and preliminaries

For general aspects of the theory of partial $*$ -algebras and of their representations, we refer to the monograph [3]. For the convenience of the reader, however, we repeat here the essential definitions.

A partial $*$ -algebra \mathfrak{A} is a complex vector space with conjugate linear involution $*$ and a distributive partial multiplication \cdot , defined on a subset $\Gamma \subset \mathfrak{A} \times \mathfrak{A}$, satisfying the property that $(x, y) \in \Gamma$ if, and only if, $(y^*, x^*) \in \Gamma$ and $(x \cdot y)^* = y^* \cdot x^*$. From now on, we will write simply xy instead of $x \cdot y$ whenever $(x, y) \in \Gamma$. For every $y \in \mathfrak{A}$, the set of left (resp. right) multipliers of y is denoted by $L(y)$ (resp. $R(y)$), i.e., $L(y) = \{x \in \mathfrak{A} : (x, y) \in \Gamma\}$, (resp. $R(y) = \{x \in \mathfrak{A} : (y, x) \in \Gamma\}$). We denote by $L\mathfrak{A}$ (resp. $R\mathfrak{A}$) the space of universal left (resp. right) multipliers of \mathfrak{A} . In general, a partial $*$ -algebra is not associative.

The *unit* of partial $*$ -algebra \mathfrak{A} , if any, is an element $e \in \mathfrak{A}$ such that $e = e^*$, $e \in R\mathfrak{A} \cap L\mathfrak{A}$ and $xe = ex = x$, for every $x \in \mathfrak{A}$.

Let \mathcal{H} be a complex Hilbert space and \mathcal{D} a dense subspace of \mathcal{H} . We denote by $\mathcal{L}^\dagger(\mathcal{D}, \mathcal{H})$ the set of all (closable) linear operators X such that $D(X) = \mathcal{D}$, $D(X^*) \supseteq \mathcal{D}$. The map $X \rightarrow X^\dagger = X^*_{|\mathcal{D}}$ defines an involution on $\mathcal{L}^\dagger(\mathcal{D}, \mathcal{H})$, which can be made into a partial $*$ -algebra with respect to the *weak* multiplication [3]; however, this fact will not be used in this paper.

Let $\mathcal{L}^\dagger(\mathcal{D})$ be the subspace of $\mathcal{L}^\dagger(\mathcal{D}, \mathcal{H})$ consisting of all its elements which leave, together with their adjoints, the domain \mathcal{D} invariant. Then $\mathcal{L}^\dagger(\mathcal{D})$ is a $*$ -algebra with respect to the usual operations. A $*$ -subalgebra \mathfrak{M} of $\mathcal{L}^\dagger(\mathcal{D})$, containing the identity I of \mathcal{D} , is called an O^* -algebra.

Let \mathfrak{M} be an O^* -algebra. The *graph topology* $t_{\mathfrak{M}}$ on \mathcal{D} is the locally convex topology defined by the family $\{\|\cdot\|_A\}_{A \in \mathfrak{M}}$, where

$$\|\xi\|_A = \sqrt{\|\xi\|^2 + \|A\xi\|^2} = \|(I + A^*\bar{A})^{1/2}\xi\|, \quad \xi \in \mathcal{D}.$$

For $A = 0$, the null operator of $\mathcal{L}^\dagger(\mathcal{D})$, $\|\cdot\|_0$ is exactly the norm of \mathcal{H} , thus we will omit the 0 in the notation of the norm.

The topology $t_{\mathfrak{M}}$ is finer than the norm topology, unless \mathfrak{M} does consist of bounded operators only.

If \mathfrak{M} is an O^* -algebra, we write $A \leq B$ if $\|A\xi\| \leq \|B\xi\|$, for every $\xi \in \mathcal{D}$. Then, \mathfrak{M} is directed upward with respect to this order relation.

If $A \in \mathfrak{M}$, we denote by \mathcal{H}_A the Hilbert space obtained by endowing $D(\bar{A})$ with the graph norm $\|\cdot\|_A$.

If $A, B \in \mathfrak{M}$ and $A \leq B$, then $U_{BA} = (I + B^*\bar{B})^{-1/2}(I + A^*\bar{A})^{1/2}$ is a contractive map of \mathcal{H}_A into \mathcal{H}_B ; i.e., $\|U_{BA}\xi\|_B \leq \|\xi\|_A$, for every $\xi \in \mathcal{H}_A$.

If the locally convex space $\mathcal{D}[t_{\mathfrak{M}}]$ is complete, then \mathfrak{M} is said to be *closed*.

If $\mathfrak{M} = \mathcal{L}^\dagger(\mathcal{D})$ then the corresponding graph topology denoted by t_\dagger instead of $t_{\mathcal{L}^\dagger(\mathcal{D})}$.

As is known, a locally convex topology t on \mathcal{D} is finer than the topology induced by the Hilbert norm defines, in standard fashion, a *rigged Hilbert space* (RHS)

$$\mathcal{D}[t] \hookrightarrow \mathcal{H} \hookrightarrow \mathcal{D}^\times[t^\times],$$

where \mathcal{D}^\times is the vector space of all continuous conjugate linear functionals on $\mathcal{D}[t]$, i.e., the conjugate dual of $\mathcal{D}[t]$, endowed with the *strong dual topology* $t^\times = \beta(\mathcal{D}^\times, \mathcal{D})$, and \hookrightarrow denotes a continuous embedding with dense range. The Hilbert space \mathcal{H} is identified (by considering the form which puts \mathcal{D} and \mathcal{D}^\times into conjugate duality as an extension of the inner product of \mathcal{D}) with a dense subspace of $\mathcal{D}^\times[t^\times]$.

Let $\mathfrak{L}(\mathcal{D}, \mathcal{D}^\times)$ denote the vector space of all continuous linear maps from $\mathcal{D}[t]$ into $\mathcal{D}^\times[t^\times]$. In $\mathfrak{L}(\mathcal{D}, \mathcal{D}^\times)$, an involution $X \mapsto X^\dagger$ can be introduced by the equality

$$\langle X\xi | \eta \rangle = \overline{\langle X^\dagger \eta | \xi \rangle}, \quad \forall \xi, \eta \in \mathcal{D}.$$

Hence, $\mathfrak{L}(\mathcal{D}, \mathcal{D}^\times)$ is a $*$ -invariant vector space.

To every $X \in \mathfrak{L}(\mathcal{D}, \mathcal{D}^\times)$, there corresponds a separately continuous sesquilinear form θ_X on $\mathcal{D} \times \mathcal{D}$ defined by

$$\theta_X(\xi, \eta) = \langle X\xi | \eta \rangle, \quad \xi, \eta \in \mathcal{D}.$$

The vector space of all *jointly* continuous sesquilinear forms on $\mathcal{D} \times \mathcal{D}$ will be denoted with $\mathbf{B}(\mathcal{D}, \mathcal{D})$. We denote by $\mathfrak{L}_{\mathbf{B}}(\mathcal{D}, \mathcal{D}^\times)$ the subspace of all $X \in \mathfrak{L}(\mathcal{D}, \mathcal{D}^\times)$ such that $\theta_X \in \mathbf{B}(\mathcal{D}, \mathcal{D})$ and by $\mathfrak{L}^\dagger(\mathcal{D})$ the $*$ -algebra consisting of all operators of $\mathcal{L}^\dagger(\mathcal{D})$, which together with their adjoints are continuous from $\mathcal{D}[t]$ into $\mathcal{D}[t]$. If $t = t_\dagger$, then $\mathfrak{L}^\dagger(\mathcal{D}) = \mathcal{L}^\dagger(\mathcal{D})$. We will refer to the rigged Hilbert space defined by endowing \mathcal{D} with the topology t_\dagger as to the

canonical rigged Hilbert space defined by $\mathcal{L}^\dagger(\mathcal{D})$ on \mathcal{D} . In this case $(\mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times), \mathcal{L}^\dagger(\mathcal{D}))$ is a quasi $*$ -algebra [3].

The spaces $\mathfrak{L}(\mathcal{D}, \mathcal{D}^\times)$ and $\mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$ have been studied at length by several authors (see, e.g., [11–13, 21]) and several pathologies concerning their multiplicative structure have been considered (see also [3, 4] and references therein). Recently some spectral properties of operators of these classes have also been studied [7].

3 Bounded elements of $\mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$

The inductive structure of $\mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$, with \mathcal{D} endowed with the graph topology t_\dagger , has been discussed in [8, Section 5]. To keep the paper reasonably self-contained, we sum the main features up.

By the definition itself, $X \in \mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$ if, and only if, there exists $\gamma_X > 0$ and $A \in \mathcal{L}^\dagger(\mathcal{D})$ such that

$$|\theta_X(\xi, \eta)| = |\langle X\xi \mid \eta \rangle| \leq \gamma_X \|\xi\|_A \|\eta\|_A, \quad \forall \xi, \eta \in \mathcal{D}. \tag{1}$$

Conversely, if $\theta \in \mathbf{B}(\mathcal{D}, \mathcal{D})$, there exists a unique $X \in \mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$ such that $\theta = \theta_X$.

Thus, the map

$$\mathbb{I} : X \in \mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times) \mapsto \theta_X \in \mathbf{B}(\mathcal{D}, \mathcal{D})$$

is an isomorphism of vector spaces and $\mathbb{I}(\theta^*) = X^\dagger$, where $\theta^*(\xi, \eta) = \overline{\theta(\eta, \xi)}$, for every $\xi, \eta \in \mathcal{D}$.

We denote by $\mathbf{B}^A(\mathcal{D}, \mathcal{D})$ the subspace of $\mathbf{B}(\mathcal{D}, \mathcal{D})$ consisting of all $\theta \in \mathbf{B}(\mathcal{D}, \mathcal{D})$ such that (1) holds for fixed $A \in \mathcal{L}^\dagger(\mathcal{D})$.

If $\theta \in \mathbf{B}^A(\mathcal{D}, \mathcal{D})$, it extends to a bounded sesquilinear form on $\mathcal{H}_A \times \mathcal{H}_A$ (we use the same symbol for this extension). Hence, there exists a unique operator $X_A^\theta \in \mathfrak{B}(\mathcal{H}_A)$ such that

$$\theta(\xi, \eta) = \langle X_A^\theta \xi \mid \eta \rangle_A, \quad \forall \xi, \eta \in \mathcal{H}_A.$$

On the other hand, if $X_A \in \mathfrak{B}(\mathcal{H}_A)$, then the sesquilinear form θ_{X_A} defined by

$$\theta_{X_A}(\xi, \eta) = \langle X_A \xi \mid \eta \rangle_A, \quad \xi, \eta \in \mathcal{D},$$

is an element of $\mathbf{B}^A(\mathcal{D}, \mathcal{D})$ and the map

$$\Phi_A : X_A \in \mathfrak{B}(\mathcal{H}_A) \rightarrow \theta_{X_A} \in \mathbf{B}^A(\mathcal{D}, \mathcal{D})$$

is a $*$ -isomorphism of vector spaces with involution.

If $B \succeq A$, then, for $\xi, \eta \in \mathcal{D}$,

$$|\theta_{X_A}(\xi, \eta)| = |\langle X_A \xi \mid \eta \rangle_A| \leq \|X_A\|_{A,A} \|\xi\|_A \|\eta\|_A \leq \|X_A\|_{A,A} \|\xi\|_B \|\eta\|_B,$$

where $\|\cdot\|_{A,A}$ denotes the operator norm in $\mathfrak{B}(\mathcal{H}_A)$. Hence, there exists a unique $X_B \in \mathfrak{B}(\mathcal{H}_B)$ such that

$$\langle X_A \xi \mid \eta \rangle_A = \langle X_B \xi \mid \eta \rangle_B, \quad \forall \xi, \eta \in \mathcal{D}.$$

So it is natural to define

$$J_{BA}(X_A) = X_B, \quad \forall X_A \in \mathfrak{B}(\mathcal{H}_A).$$

It is easily seen that $J_{BA} = \Phi_B^{-1} \Phi_A$.

The space $\mathfrak{L}_B^A(\mathcal{D}, \mathcal{D}^\times) := \mathbb{I}^{-1}\mathbf{B}^A(\mathcal{D}, \mathcal{D})$ is a Banach space, with norm

$$\|X\|^A := \sup_{\|\xi\|_A, \|\eta\|_A \leq 1} |\theta_X(\xi, \eta)|$$

and $\mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$ can be endowed with the inductive topology τ_{ind} defined by the family of subspaces $\{\mathfrak{L}_B^A(\mathcal{D}, \mathcal{D}^\times); A \in \mathcal{L}^\dagger(\mathcal{D})\}$ as in [16, Section 1.2.III].

In conclusion,

$$X_A \in \mathfrak{B}(\mathcal{H}_A) \leftrightarrow \theta_{X_A} \in \mathbf{B}^A(\mathcal{D}, \mathcal{D}) \leftrightarrow X \in \mathfrak{L}_B^A(\mathcal{D}, \mathcal{D}^\times)$$

are isometric $*$ -isomorphisms of Banach spaces.

Hence, to every $X \in \mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$ one can associate the net $\{X_B; B \in \mathcal{L}^\dagger(\mathcal{D}); B \succeq A\}$ of its representatives in each of the spaces \mathcal{H}_B .

Definition 3.1 We say that $X \in \mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$ is a *bounded element* of $\mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$ if X has a representative X_A in every $\mathfrak{B}(\mathcal{H}_A)$ and

$$\|X\|_b := \sup_{A \in \mathcal{L}^\dagger(\mathcal{D})} \|X_A\|_{A,A} < +\infty.$$

The space $\mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)_b$ of all bounded elements of $\mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$ is a Banach space with norm $\|\cdot\|_b$.

Proposition 3.2 $\mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)_b$ is $*$ -isomorphic (as Banach space) to a C^* -algebra of operators.

Proof Let \mathcal{H}_\oplus denote the Hilbert space direct sum of the $\mathcal{H}_A, A \in \mathcal{L}^\dagger(\mathcal{D})$; i.e.,

$$\begin{aligned} \mathcal{H}_\oplus &:= \bigoplus_{A \in \mathcal{L}^\dagger(\mathcal{D})} \mathcal{H}_A \\ &= \left\{ \xi_\oplus = (\xi_A); \xi_A \in \mathcal{H}_A, \forall A \in \mathcal{L}^\dagger(\mathcal{D}) \text{ and } \sum_A \|\xi_A\|_A^2 < +\infty \right\}. \end{aligned}$$

If $\{X_A\}_{A \in \mathcal{L}^\dagger(\mathcal{D})}$ is a net of operators $X_A \in \mathfrak{B}(\mathcal{H}_A), A \in \mathcal{L}^\dagger(\mathcal{D})$, we define $X_\oplus \xi_\oplus = \{X_A \xi_A\}$ provided that $\sum_A \|X_A \xi_A\|^2 < +\infty, \xi_A \in \mathcal{H}_A$.

The operator $X_\oplus = \{X_A\}$ is bounded if and only if $\sup_A \|X_A\|_{A,A} < +\infty$. The space constructed in this way is $\prod_A \mathfrak{B}(\mathcal{H}_A) = \mathfrak{B}(\mathcal{H}_\oplus)$. To every $X \in \mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)_b$, we can associate the net $\{X_A\}$ which we have defined above. Clearly, $\{X_A\} \in \mathfrak{B}(\mathcal{H}_\oplus)$. It is easily seen that the map

$$\tau : X \in \mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)_b \mapsto \{X_A\} \in \mathfrak{B}(\mathcal{H}_\oplus)$$

is isometric. Thus, the statement is proved. □

Remark 3.3 An element $X \in \mathfrak{L}_B(\mathcal{D}, \mathcal{D}^\times)$ having a representative X_A for every $A \in \mathcal{L}^\dagger(\mathcal{D})$ need not be bounded in the sense of Definition 3.1. The spaces $\{\mathcal{H}_A; A \in \mathcal{L}^\dagger(\mathcal{D})\}$, together with their conjugate duals, make \mathcal{D}^\times into an indexed PIP-space [4, Chap. 2]. In that language, operators having representatives in every \mathcal{H}_A are called totally regular operators. For more details on their behavior see [4, Section 3.3.3] where also a C^* -agebra corresponding to our bounded elements has been studied.

Our next goal is to characterize bounded elements of $\mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)$ in several different ways. For doing this, we need to consider the natural order structure of $\mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)$.

We say that $X \in \mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)$ is *positive*, and write $X \geq 0$, if $\langle X\xi | \xi \rangle \geq 0$, for every $\xi \in \mathcal{D}$.

It is easy to see that if X is positive, then it is *symmetric*; i.e., $X = X^\dagger$.

Proposition 3.4 *The following conditions are equivalent.*

- (i) $X \geq 0$.
- (ii) *There exists $A \in \mathcal{L}^\dagger(\mathcal{D})$ such that $X_B \geq 0, \forall B \geq A$.*

Proof (i) \Rightarrow (ii): Since $X \in \mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)$, there exists $A \in \mathcal{L}^\dagger(\mathcal{D})$ and $\gamma > 0$ such that

$$|\langle X\xi | \eta \rangle| \leq \gamma \|\xi\|_B \|\eta\|_B, \quad B \geq A.$$

If $X \geq 0$, then, for every $\xi \in \mathcal{D}$,

$$\langle X_B \xi | \xi \rangle_B = \langle X\xi | \xi \rangle \geq 0, \quad \forall B \geq A.$$

Since \mathcal{D} is dense in \mathcal{H}_B , we have $\langle X_B \xi | \xi \rangle_B \geq 0, \forall \xi \in \mathcal{H}_B$.

(ii) \Rightarrow (i): Let $X_B \geq 0$ for every $B \geq A$. Then, for every $\xi \in \mathcal{D}, \langle X\xi | \xi \rangle = \langle X_B \xi | \xi \rangle_B \geq 0$. □

Theorem 3.5 *Let $X \in \mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)$. The following statements are equivalent.*

- (i) $X : \mathcal{D} \rightarrow \mathcal{H}$ and $\overline{X} \in \mathcal{B}(\mathcal{H})$.
- (ii) $X \in \mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)_b$.
- (iii) *There exists $\lambda > 0$ such that*

$$-\lambda I \leq \Re(X) \leq \lambda I, \quad -\lambda I \leq \Im(X) \leq \lambda I$$

where $\Re(X) = \frac{X+X^\dagger}{2}$ and $\Im(X) = \frac{X-X^\dagger}{2i}$.

Proof (i) \Rightarrow (ii): If $X : \mathcal{D} \rightarrow \mathcal{H}$ and X is bounded, then, for every $A \in \mathcal{L}^\dagger(\mathcal{D})$,

$$|\langle X\xi | \eta \rangle| \leq \|\overline{X}\| \|\xi\| \|\eta\| \leq \|\overline{X}\| \|\xi\|_A \|\eta\|_A. \tag{2}$$

This means that X has a bounded representative X_A in every $\mathcal{B}(\mathcal{H}_A)$. By (2), $\|X_A\|_{A,A} \leq \|\overline{X}\|$, for every $A \in \mathcal{L}^\dagger(\mathcal{D})$, so $\sup_{A \in \mathcal{L}^\dagger(\mathcal{D})} \|X_A\|_{A,A} < +\infty$.

(ii) \Rightarrow (i) Let $X \in \mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)_b$. Then, for every $A \in \mathcal{L}^\dagger(\mathcal{D})$

$$|\langle X\xi | \eta \rangle| \leq \|X_A\|_{A,A} \|\xi\|_A \|\eta\|_A, \quad \forall \xi, \eta \in \mathcal{D}.$$

In particular, for $A = 0$,

$$|\langle X\xi | \eta \rangle| \leq \|X_0\| \|\xi\| \|\eta\|, \quad \forall \xi, \eta \in \mathcal{D}. \tag{3}$$

By (3), for every $\xi \in \mathcal{D}, F(\eta) = \langle X\xi | \eta \rangle$ is a bounded conjugate linear functional on \mathcal{D} , so by Riesz’s lemma $X\xi \in \mathcal{H}$. It is finally easily seen that $\overline{X} \in \mathcal{B}(\mathcal{H})$.

(iii) \Rightarrow (i) Suppose first that $X = X^\dagger$. Note that the operator X satisfies the following: $0 \leq \frac{X+\lambda I}{2\lambda} \leq I$; so $\frac{X+\lambda I}{2\lambda}$ is a positive operator and $\langle \frac{X+\lambda I}{2\lambda} \xi | \xi \rangle \leq \langle \xi | \xi \rangle, \forall \xi \in \mathcal{D}$; this implies that

$$\left| \left\langle \frac{X + \lambda I}{2\lambda} \xi \middle| \eta \right\rangle \right| \leq \|\xi\| \|\eta\|, \quad \forall \xi, \eta \in \mathcal{D} \tag{4}$$

and by Riesz’s lemma there exists $\zeta \in \mathcal{H}$ such that

$$\left\langle \frac{X + \lambda I}{2\lambda} \xi \mid \eta \right\rangle = \langle \zeta \mid \eta \rangle, \quad \forall \xi, \eta \in \mathcal{D} \tag{5}$$

and then $\frac{X + \lambda I}{2\lambda} \xi \in \mathcal{H}$. This implies that $X\xi \in \mathcal{H}$ too. Moreover, X has a representative for every $A \in \mathcal{L}^\dagger(\mathcal{D})$. Indeed,

$$|\langle X\xi \mid \eta \rangle| \leq \gamma \|\xi\| \|\eta\| \leq \gamma \|\xi\|_A \|\eta\|_A \quad \forall A \in \mathcal{L}^\dagger(\mathcal{D}),$$

where $\gamma > 0$. From (4), it follows that X is bounded and $\bar{X} \in \mathcal{B}(\mathcal{H})$. In the very same way, one can prove the boundedness of X if $X^\dagger = -X$. The result for a general X follows easily.

(i) \Rightarrow (iii): This is a standard result of the C^* -algebras theory. □

4 Bounded elements of C^* -inductive locally convex spaces

The results obtained in Sect. 3 have an abstract generalization to locally convex spaces that are inductive limits of C^* -algebras in a generalized sense. These spaces were called *C^* -inductive locally convex spaces* in [8]. We begin with recalling the basic definitions.

Let \mathfrak{A} be a vector space over \mathbb{C} . Let \mathbb{F} be a set of indices directed upward and consider, for every $\alpha \in \mathbb{F}$, a space $\mathfrak{A}_\alpha \subset \mathfrak{A}$ such that:

- (I.1) $\mathfrak{A}_\alpha \subseteq \mathfrak{A}_\beta$, if $\alpha \leq \beta$;
- (I.2) $\mathfrak{A} = \bigcup_{\alpha \in \mathbb{F}} \mathfrak{A}_\alpha$;
- (I.3) $\forall \alpha \in \mathbb{F}$, there exists a C^* -algebra \mathfrak{B}_α (with unit e_α and norm $\|\cdot\|_\alpha$) and an isomorphism of vector spaces $\phi_\alpha : \mathfrak{B}_\alpha \rightarrow \mathfrak{A}_\alpha$ which makes of \mathfrak{A}_α a Banach space under the norm $\|x\|^\alpha := \|x_\alpha\|_\alpha$, if $x \in \mathfrak{A}_\alpha, x = \phi_\alpha(x_\alpha)$;
- (I.4) $x_\alpha \in \mathfrak{B}_\alpha^+ \Rightarrow x_\beta = (\phi_\beta^{-1} \phi_\alpha)(x_\alpha) \in \mathfrak{B}_\beta^+$, for every $\alpha, \beta \in \mathbb{F}$ with $\beta \geq \alpha$.

We put $j_{\beta\alpha} = \phi_\beta^{-1} \phi_\alpha$, if $\alpha, \beta \in \mathbb{F}, \beta \geq \alpha$.

If $x \in \mathfrak{A}$, there exists $\alpha \in \mathbb{F}$ such that $x \in \mathfrak{A}_\alpha$ and, for every $\beta \geq \alpha$, a unique $x_\beta \in \mathfrak{B}_\beta$ such that $x = \phi_\beta(x_\beta)$.

Then, we put

$$j_{\beta\alpha}(x_\alpha) := x_\beta \text{ if } \alpha \leq \beta.$$

By (I.4), it follows easily that $j_{\beta\alpha}$ preserves the involution; i.e., $j_{\beta\alpha}(x_\alpha^*) = (j_{\beta\alpha}(x_\alpha))^*$.

Remark 4.1 From the previous discussion, it follows that to every $x \in \mathfrak{A}$ there corresponds a family of *representatives* $\{x_\beta; x_\beta \in \mathfrak{B}_\beta, \beta \geq \alpha\}$. We write, for short, $x = (x_\beta)$. If $x = (x_\beta), y = (y_\beta)$ and $x_\beta = y_\beta$, for every β larger than a certain $\gamma \in \mathbb{F}$, then $x = y$. With this identification, the mentioned correspondence is one-to-one.

The family $\{\mathfrak{B}_\alpha, j_{\beta\alpha}, \beta \geq \alpha\}$ is a *directed system of C^* -algebras*, in the sense that:

- (J.1) for every $\alpha, \beta \in \mathbb{F}$, with $\beta \geq \alpha$, $j_{\beta\alpha} : \mathfrak{B}_\alpha \rightarrow \mathfrak{B}_\beta$ is a linear and injective map; $j_{\alpha\alpha}$ is the identity of \mathfrak{B}_α ,
- (J.2) for every $\alpha, \beta \in \mathbb{F}$, with $\alpha \leq \beta$, $\phi_\alpha = \phi_\beta j_{\beta\alpha}$,
- (J.3) $j_{\gamma\beta} j_{\beta\alpha} = j_{\gamma\alpha}, \alpha \leq \beta \leq \gamma$.

We assume that, in addition, the $j_{\beta\alpha}$ s are Schwarz maps (see, e.g., [14]); i.e.,

(sch) $j_{\beta\alpha}(x_\alpha)^* j_{\beta\alpha}(x_\alpha) \leq j_{\beta\alpha}(x_\alpha^* x_\alpha), \quad \forall x_\alpha \in \mathfrak{B}_\alpha, \alpha \leq \beta.$

For every $\alpha, \beta \in \mathbb{F}$, with $\alpha \leq \beta$, $j_{\beta\alpha}$ is continuous [14] and, moreover,

$$\|j_{\beta\alpha}(x_\alpha)\|_\beta \leq \|x_\alpha\|_\alpha, \quad \forall x_\alpha \in \mathfrak{B}_\alpha.$$

An involution in \mathfrak{A} is defined as follows. Let $x \in \mathfrak{A}$. Then $x \in \mathfrak{A}_\alpha$, for some $\alpha \in \mathbb{F}$, i.e., $x = \phi_\alpha(x_\alpha)$, for a unique $x_\alpha \in \mathfrak{B}_\alpha$. Put $x^* := \phi_\alpha(x_\alpha^*)$. Then if $\beta \geq \alpha$, we have

$$\phi_\beta^{-1}(x^*) = \phi_\beta^{-1}(\phi_\alpha(x_\alpha^*)) = j_{\beta\alpha}(x_\alpha^*) = (j_{\beta\alpha}(x_\alpha))^* = x_\beta^*.$$

It is easily seen that the map $x \mapsto x^*$ is an involution in \mathfrak{A} . Moreover, by the definition itself, it follows that every map ϕ_α preserves the involution; i.e., $\phi_\alpha(x_\alpha^*) = (\phi_\alpha(x_\alpha))^*$, for all $x_\alpha \in \mathfrak{B}_\alpha, \alpha \in \mathbb{F}$.

Definition 4.2 Let \mathfrak{A} be a vector space with involution $*$ and \mathbb{F} a directed (upward) set.

- A *defining system* for \mathfrak{A} consists of a family $\{\{\mathfrak{B}_\alpha, \phi_\alpha\}, \alpha \in \mathbb{F}\}$, where, for every $\alpha \in \mathbb{F}$, \mathfrak{B}_α is a C^* -algebra and ϕ_α is a linear injective map of \mathfrak{B}_α into \mathfrak{A} , satisfying the above conditions (I.1)–(I.4) and (sch), with $\mathfrak{A}_\alpha = \phi_\alpha(\mathfrak{B}_\alpha), \alpha \in \mathbb{F}$.
- If \mathfrak{A} is endowed with the locally convex inductive topology τ_{ind} generated by the family $\{\{\mathfrak{B}_\alpha, \phi_\alpha\}, \alpha \in \mathbb{F}\}$, then we say that \mathfrak{A} is a *C^* -inductive locally convex space*.

We notice that the involution is automatically continuous in $\mathfrak{A}[\tau_{\text{ind}}]$.

A C^* -inductive locally convex space has a natural positive cone.

An element $x \in \mathfrak{A}$ is called *positive* if there exists $\gamma \in \mathbb{F}$ such that $\phi_\alpha^{-1}(x) \in \mathfrak{B}_\alpha^+, \forall \alpha \geq \gamma$.

We denote by \mathfrak{A}^+ the set of all positive elements of \mathfrak{A} .

Then,

- (i) Every positive element $x \in \mathfrak{A}$ is hermitian; i.e., $x \in \mathfrak{A}_h := \{y \in \mathfrak{A} : y^* = y\}$.
- (ii) \mathfrak{A}^+ is a non empty convex pointed cone; i.e., $\mathfrak{A}^+ \cap (-\mathfrak{A}^+) = \{0\}$.
- (iii) If $\alpha \in \mathbb{F}$ and $x_\alpha \in \mathfrak{B}_\alpha^+, \phi_\alpha(x_\alpha)$ is positive.

Moreover, every hermitian element $x = x^*$ is the difference of two positive elements, i.e., there exist $x^+, x^- \in \mathfrak{A}^+$ such that $x = x^+ - x^-$.

A linear functional ω is said to be *positive* if $\omega(x) \geq 0$ for every $x = (x_\alpha) \in \mathfrak{A}^+$. As shown in [8, Prop. 3.9, 3.10], ω is positive if, and only if, $\omega_\alpha(x_\alpha) := \omega(\phi_\alpha(x_\alpha)) \geq 0$ for every $\alpha \in \mathbb{F}$. We write, in this case, $\omega = \lim_{\rightarrow} \omega_\alpha$.

4.1 Bounded elements

Definition 4.3 Let \mathfrak{A} be a C^* -inductive locally convex space. An element $x = (x_\alpha) \in \mathfrak{A}$, with $x_\alpha \in \mathfrak{B}_\alpha$, is called *bounded* if $x \in \mathfrak{A}_\alpha$, for every $\alpha \in \mathbb{F}$ and $\sup_{\alpha \in \mathbb{F}} \|x_\alpha\|_\alpha < \infty$. The set of bounded elements of \mathfrak{A} is denoted by \mathfrak{A}_b .

Proposition 4.4 The set \mathfrak{A}_b is a Banach space under the norm $\|x\|_b := \sup_{\alpha \in \mathbb{F}} \|x_\alpha\|_\alpha$.

Proof We only prove the completeness. Let $\{x_n\}$ be a Cauchy sequence in \mathfrak{A}_b . Then, for every $\alpha \in \mathbb{F}$ the sequence $\{x_n^\alpha\}$, with $x_n^\alpha := (x_n)_\alpha$, is Cauchy in \mathfrak{B}_α , so it converges to some $x_\alpha \in \mathfrak{B}_\alpha$. Since the $j_{\beta\alpha}$'s are continuous, one easily proves that the family $\{x_\alpha\}$ defines an element $x = (x_\alpha)$ of \mathfrak{A} . From the Cauchy condition, for every $\epsilon > 0$, there exists $n_\epsilon \in \mathbb{N}$ such that

$$\sup_{\alpha \in \mathbb{F}} \|x_n^\alpha - x_m^\alpha\|_\alpha < \epsilon \tag{6}$$

If $m > n_\epsilon$,

$$\|x_\alpha\|_\alpha \leq \|x_\alpha - x_m^\alpha\|_\alpha + \|x_m^\alpha\|_\alpha \leq \epsilon + \|x_m^\alpha\|_\alpha.$$

Hence,

$$\sup_{\alpha \in \mathbb{F}} \|x_\alpha\|_\alpha \leq \epsilon + \sup_{\alpha \in \mathbb{F}} \|x_m^\alpha\|_\alpha < \infty.$$

Thus $x \in \mathfrak{A}_b$.

Fix now $n > n_\epsilon$ and let $m \rightarrow \infty$ in (6). Then,

$$\sup_{\alpha \in \mathbb{F}} \|x_n^\alpha - x_\alpha\|_\alpha \leq \epsilon.$$

This proves that $x_n \rightarrow x$. □

In what follows, we will consider $*$ -representations of a C^* -inductive locally convex space. We recall the basic definitions.

Let \mathbb{F} be a set directed upward by \leq . A family $\{\mathcal{H}_\alpha, U_{\beta\alpha}, \alpha, \beta \in \mathbb{F}, \beta \geq \alpha\}$, where each \mathcal{H}_α is a Hilbert space (with inner product $\langle \cdot | \cdot \rangle_{(\alpha)}$ and norm $\| \cdot \|_{(\alpha)}$) and, for every $\alpha, \beta \in \mathbb{F}$, with $\beta \geq \alpha$, $U_{\beta\alpha}$ is a linear map from \mathcal{H}_α into \mathcal{H}_β , is called a *directed contractive system of Hilbert spaces* if the following conditions are satisfied

- (i) $U_{\beta\alpha}$ is injective;
- (ii) $\|U_{\beta\alpha}\xi_\alpha\|_{(\beta)} \leq \|\xi_\alpha\|_{(\alpha)}$, $\forall \xi_\alpha \in \mathcal{H}_\alpha$;
- (iii) $U_{\alpha\alpha} = I_\alpha$, the identity of \mathcal{H}_α ;
- (iv) $U_{\gamma\alpha} = U_{\gamma\beta}U_{\beta\alpha}$, $\alpha \leq \beta \leq \gamma$.

A directed contractive system of Hilbert spaces defines a conjugate dual pair $(\mathcal{D}^\times, \mathcal{D})$ which is called the *joint topological limit* [9] of the directed contractive system $\{\mathcal{H}_\alpha, U_{\beta\alpha}, \alpha, \beta \in \mathbb{F}, \beta \geq \alpha\}$ of Hilbert spaces.

Definition 4.5 Let \mathfrak{A} be the C^* -inductive locally convex space defined by the system $\{\{\mathfrak{B}_\alpha, \Phi_\alpha\}, \alpha \in \mathbb{F}\}$ as in Definition 4.2.

For each $\alpha \in \mathbb{F}$, let π_α be a $*$ -representation of \mathfrak{B}_α in Hilbert space \mathcal{H}_α . The collection $\pi := \{\pi_\alpha\}$ is said to be a $*$ -representation of \mathfrak{A} if

- (i) for every $\alpha, \beta \in \mathbb{F}$, there exists a linear map $U_{\beta\alpha} : \mathcal{H}_\alpha \rightarrow \mathcal{H}_\beta$ such that the family $\{\mathcal{H}_\alpha, U_{\beta\alpha}, \alpha, \beta \in \mathbb{F}, \beta \geq \alpha\}$ is a directed contractive system of Hilbert spaces;
- (ii) the following equality holds

$$\pi_\beta(j_{\beta\alpha}(x_\alpha)) = U_{\beta\alpha}\pi_\alpha(x_\alpha)U_{\beta\alpha}^*, \quad \forall x_\alpha \in \mathfrak{B}_\alpha, \beta \geq \alpha. \tag{7}$$

In this case, we write $\pi(x) = \varinjlim \pi_\alpha(x_\alpha)$ for every $x = (x_\alpha) \in \mathfrak{A}$ or, for short, $\pi = \varinjlim \pi_\alpha$.

The $*$ -representation π is said to be *faithful* if $x \in \mathfrak{A}^+$ and $\pi(x) = 0$ imply $x = 0$ (of course, $\pi(x) = 0$ means that there exists $\gamma \in \mathbb{F}$ such that $\pi_\alpha(x_\alpha) = 0$, for $\alpha \geq \gamma$).

Remark 4.6 With this definition (which is formally different from that given in [8] but fully equivalent), $\pi(x)$, $x \in \mathfrak{A}$, is not an operator but rather a collection of operators. But as shown in [8], $\pi(x)$ can be regarded as an operator acting on the joint topological limit $(\mathcal{D}^\times, \mathcal{D})$ of $\{\mathcal{H}_\alpha, U_{\beta\alpha}, \alpha, \beta \in \mathbb{F}, \beta \geq \alpha\}$. The corresponding space of operators was denoted by $\mathcal{L}_{\mathfrak{B}}(\mathcal{D}, \mathcal{D}^\times)$; it behaves in the very same way as the space $\mathcal{L}_{\mathfrak{B}}(\mathcal{D}, \mathcal{D}^\times)$ studied in Sect. 3 and reduces to it when the family of Hilbert spaces is exactly $\{\mathcal{H}_A; A \in \mathcal{L}^\dagger(\mathcal{D})\}$. The main difference consists in the fact that the \mathcal{H}_α 's need not be all subspaces of a certain Hilbert space \mathcal{H} .

Lemma 4.7 Let $\pi = \varinjlim \pi_\alpha$ be a faithful $*$ -representation of \mathfrak{A} . Then, for every $\alpha \in \mathbb{F}$, π_α is a faithful $*$ -representation of \mathfrak{B}_α .

Proof Let $x_\alpha \in \mathfrak{B}_\alpha^+$ with $\pi_\alpha(x_\alpha) = 0$. Let $x \in \mathfrak{A}$ be the unique element of \mathfrak{A} such that $x = \phi_\alpha(x_\alpha)$. Then $\pi_\beta(x_\beta) = \pi_\beta(j_{\beta\alpha}(x_\alpha)) = U_{\beta\alpha}\pi_\alpha(x_\alpha)U_{\beta\alpha}^* = 0$. Hence $\pi(x) = 0$, and therefore, $x = 0$. Thus there exists $\bar{\gamma} \in \mathbb{F}$ such that $x_\gamma = 0$, for $\gamma \geq \bar{\gamma}$. Let $\beta \geq \alpha, \bar{\gamma}$. Then $0 = x_\beta = j_{\beta\alpha}(x_\alpha)$. Hence, by the injectivity of $j_{\beta\alpha}$, $x_\alpha = 0$. \square

As shown in [8, Proposition 3.16], if a C^* -inductive locally convex space \mathfrak{A} fulfills the following conditions

- (r₁) if $x_\alpha \in \mathfrak{B}_\alpha$ and $j_{\beta\alpha}(x_\alpha) \geq 0$ for some $\beta \geq \alpha$, then $x_\alpha \geq 0$;
- (r₂) $e_\beta \in j_{\beta\alpha}(\mathfrak{B}_\alpha)$, $\forall \alpha, \beta \in \mathbb{F}, \beta \geq \alpha$;
- (r₃) every positive linear functional $\omega = \varinjlim \omega_\alpha$ on \mathfrak{A} satisfies the following property

- if $\alpha \in \mathbb{F}$ and $\omega_\beta(j_{\beta\alpha}(x_\alpha^*)j_{\beta\alpha}(x_\alpha)) = 0$, for some $\beta > \alpha$ and $x_\alpha \in \mathfrak{B}_\alpha$, then $\omega_\alpha(x_\alpha^*x_\alpha) = 0$;

then, \mathfrak{A} admits a faithful representation. The conditions (r₁), (r₂), in fact, guarantee that \mathfrak{A} possesses sufficiently many positive linear functionals, in the sense that for every $x \in \mathfrak{A}^+, x \neq 0$ there exists a positive linear functional ω on \mathfrak{A} such that $\omega(x) > 0$ [8, Theorem 3.14].

Theorem 4.8 *Let \mathfrak{A} be a C^* -inductive locally convex space and $x = (x_\alpha) \in \mathfrak{A}$. The following statements hold.*

- (i) *If $x \in \mathfrak{A}_b$, then, for every $*$ -representation $\pi = \varinjlim \pi_\alpha$ of \mathfrak{A} , one has*

$$\sup_{\alpha \in \mathbb{F}} \|\pi_\alpha(x_\alpha)\|_{\alpha\alpha} < \infty,$$

where $\|\cdot\|_{\alpha\alpha}$ denotes the norm of $\mathfrak{B}(\mathcal{H}_\alpha)$.

- (ii) *Conversely, if \mathfrak{A} admits a faithful $*$ -representation $\pi^f = \varinjlim \pi_\alpha^f$ and*

$$\sup_{\alpha \in \mathbb{F}} \|\pi_\alpha^f(x_\alpha)\|_{\alpha\alpha} < \infty,$$

then $x \in \mathfrak{A}_b$.

Proof (i): For every $\alpha \in \mathbb{F}$, π_α is a $*$ -representation of the C^* -algebra \mathfrak{B}_α . Hence

$$\|\pi_\alpha(x_\alpha)\|_{\alpha\alpha} \leq \|x_\alpha\|_\alpha.$$

Thus if $x \in \mathfrak{A}_b$ the statement follows immediately from the definition.

- (ii): Let $\pi^f(x) = \varinjlim \pi_\alpha^f(x_\alpha)$. Then, by Lemma 4.7, for every $\alpha \in \mathbb{F}$, π_α^f is a faithful representation of \mathfrak{B}_α . The $*$ -representation π_α^f is an isometric isomorphism of C^* -algebras, for all $\alpha \in \mathbb{F}$; hence

$$\sup_{\alpha \in \mathbb{F}} \|x_\alpha\|_\alpha = \sup_{\alpha \in \mathbb{F}} \|\pi_\alpha^f(x_\alpha)\|_{\alpha\alpha} < \infty.$$

This proves that x is a bounded element of \mathfrak{A} . \square

4.2 Order bounded elements

Let \mathfrak{A} be a C^* -inductive locally convex space. If $x \in \mathfrak{A}$, we put

$$\Re(x) = \frac{x + x^*}{2} \quad \text{and} \quad \Im(x) = \frac{x - x^*}{2i}.$$

Both $\Re(x)$ and $\Im(x)$ are symmetric elements of \mathfrak{A} .

Assume that \mathfrak{A} has an element $u = u^*$ such that $\|u_\alpha\|_\alpha \leq 1$, for every $\alpha \in \mathbb{F}$, and there exists $\gamma \in \mathbb{F}$ such that $u_\beta = j_{\beta\gamma}(e_\gamma) \forall \beta \geq \gamma$, (e_γ is the unit of \mathfrak{B}_γ). For shortness, we call the element u a *pre-unit* of \mathfrak{A} .

Remark 4.9 The pre-unit $u \in \mathfrak{A}$, if any, is unique. Indeed, let suppose there is another $v \in \mathfrak{A}$ satisfying the same properties as u . Then,

$$\exists \gamma, \gamma' \in \mathbb{F}; u_\beta = j_{\beta\gamma}(e_\gamma), v_{\beta'} = j_{\beta'\gamma'}(e_{\gamma'}), \quad \forall \beta \geq \gamma, \beta' \geq \gamma'$$

so, if $\delta \geq \gamma, \gamma'$, one has $u_\delta = v_\delta, \forall \delta \geq \delta$. The statement then follows from Remark 4.1.

Definition 4.10 Let \mathfrak{A} be a C^* -inductive locally convex space with pre-unit u . We say that $x \in \mathfrak{A}$ is *order bounded* (with respect to u) if there exists $\lambda > 0$ such that

$$-\lambda u \leq \Re(x) \leq \lambda u \quad -\lambda u \leq \Im(x) \leq \lambda u.$$

Theorem 4.11 Let \mathfrak{A} be a C^* -inductive locally convex space satisfying condition (r_1) . Assume that \mathfrak{A} has a pre-unit u .

Then, $x \in \mathfrak{A}_b$ if, and only if, x has a representative for every $\alpha \in \mathbb{F}$ (i.e., for every $\alpha \in \mathbb{F}$, there exists $x_\alpha \in \mathfrak{B}_\alpha$ such that $x = \phi_\alpha(x_\alpha)$) and x is order bounded with respect to u .

Proof Let us assume that $x = x^* \in \mathfrak{A}_b$. Then, x has a representative x_α , with $x_\alpha^* = x_\alpha$, in every \mathfrak{B}_α and $\lambda := \sup_{\alpha \in \mathbb{F}} \|x_\alpha\|_\alpha < \infty$. Hence, we have

$$-\lambda e_\alpha \leq x_\alpha \leq \lambda e_\alpha, \quad \forall \alpha \in \mathbb{F},$$

where e_α denotes the unit of \mathfrak{B}_α . By the definition of u , there exists $\gamma \in \mathbb{F}$ such that $u_\beta = j_{\beta\gamma}(e_\gamma)$ for $\beta \geq \gamma$. Hence, taking into account that the maps $j_{\beta\alpha}$ preserve the order, we have

$$-\lambda u_\beta \leq x_\beta \leq \lambda u_\beta, \quad \forall \beta \geq \gamma.$$

This implies that $-\lambda u \leq x \leq \lambda u$.

Now, let us suppose that for some $\lambda > 0, -\lambda u \leq x \leq \lambda u$. Then, there exists $\gamma \in \mathbb{F}$ such that

$$-\lambda u_\beta \leq x_\beta \leq \lambda u_\beta, \quad \forall \beta \geq \gamma. \tag{8}$$

Let now $\alpha \in \mathbb{F}$. Then, there is $\delta \geq \alpha, \gamma$ such that (8) holds. Hence, using (r_1) , we conclude that

$$-\lambda u_\alpha \leq x_\alpha \leq \lambda u_\alpha, \quad \forall \alpha \in \mathbb{F}.$$

This implies that $\|x_\alpha\|_\alpha \leq \lambda$, for every $\alpha \in \mathbb{F}$. Thus, $x \in \mathfrak{A}_b$. □

From the proof of the previous theorem, it follows easily that

Proposition 4.12 Assume that the assumptions of Theorem 4.11 hold and let $x = x^* \in \mathfrak{A}_b$. Put

$$p(x) = \inf\{\lambda > 0; -\lambda u \leq x \leq \lambda u\}.$$

Then, $p(x) = \|x\|_b$.

5 C*-inductive partial *-algebras

As shown in [8], a partial multiplication in \mathfrak{A} can be defined by a family $w = \{w_\alpha\}$, $w_\alpha \in \mathfrak{B}_\alpha$. Let $w = \{w_\alpha\}$ be a family of elements, such that each $w_\alpha \in \mathfrak{B}_\alpha^+$ and $j_{\beta\alpha}(w_\alpha) = w_\beta$, for all $\alpha, \beta \in \mathbb{F}$ with $\beta \geq \alpha$.

Let $x, y \in \mathfrak{A}$. The partial multiplication $x \cdot y$ is defined by the conditions:

$$\begin{aligned} \exists \gamma \in \mathbb{F} : \phi_\beta(\phi_\beta^{-1}(x)w_\beta\phi_\beta^{-1}(y)) &= \phi_{\beta'}(\phi_{\beta'}^{-1}(x)w_{\beta'}\phi_{\beta'}^{-1}(y)), \quad \forall \beta, \beta' \geq \gamma \\ x \cdot y &= \phi_\beta(\phi_\beta^{-1}(x)w_\beta\phi_\beta^{-1}(y)), \quad \beta \geq \gamma. \end{aligned}$$

Then, \mathfrak{A} is an *associative* partial *-algebra with respect to the usual operations and the above-defined multiplication (see [3, Section 2.1.1] for the definitions) and we will call it a *C*-inductive partial *-algebra*.

The partial *-algebra \mathfrak{A} has a unit e (that is, an element e which is a left- and right universal multiplier such that $x \cdot e = e \cdot x = x$, for every $x \in \mathfrak{A}$) if, and only if, every element w_α of the family $\{w_\alpha\}$ defining the multiplication is invertible and

$$j_{\beta\alpha}(w_\alpha^{-1}) = w_\beta^{-1}, \quad \forall \alpha, \beta \in \mathbb{F}, \beta \geq \alpha. \tag{9}$$

In this case, $e = \phi_\alpha(w_\alpha^{-1})$, independently of $\alpha \in \mathbb{F}$.

The element e is called a *bounded unit* if it is a bounded element of \mathfrak{A} and $\|e\|_b = 1$.

Proposition 5.1 *Let \mathfrak{A} be a C*-inductive partial *-algebra with the multiplication defined by a family $\{w_\alpha\}$. Assume that $e = (w_\alpha^{-1})$ is a bounded unit of \mathfrak{A} . Then \mathfrak{A}_b is a Banach partial *-algebra; that is, $\mathfrak{A}_b[\|\cdot\|_b]$ is a Banach space with isometric involution $*$ and there exists $C \geq 1$ such that the following inequality holds*

$$\|x \cdot y\|_b \leq C \|x\|_b \|y\|_b, \quad \forall x, y \in \mathfrak{A}_b \quad \text{with } x \cdot y \text{ well-defined.} \tag{10}$$

Remark 5.2 The constant C in (10) can be taken equal to 1 if $w_\alpha^{-1} = e_\alpha$, for each $\alpha \in \mathbb{F}$, where e_α is the unit of the C*-algebra \mathfrak{B}_α . Under the same assumption, the norm of \mathfrak{A}_b satisfies the C*-property, which in our case reads

$$\|x^* \cdot x\|_b = \|x\|_b^2, \quad \forall x \in \mathfrak{A}_b \quad \text{with } x^* \cdot x \text{ well-defined.}$$

This is no longer true in the general case.

Remark 5.3 In Example 5.3 of [8], two of us tried to construct a family $\{W_A \in \mathfrak{B}(\mathcal{H}_A); A \in \mathcal{L}^\dagger(\mathcal{D})\}$ so that the partial multiplication defined in $\mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times)$ by the method mentioned above would reproduce the quasi *-algebra structure of $(\mathfrak{L}_{\mathbb{B}}(\mathcal{D}, \mathcal{D}^\times), \mathcal{L}^\dagger(\mathcal{D}))$ (see Sect. 2). Unfortunately, the conclusion of that discussion is incorrect (see [8, Erratum/Addendum] for more details).

Let \mathfrak{A} be a C*-inductive partial *-algebra with the multiplication defined by a family $\{w_\alpha\}$ as above. The spaces $R\mathfrak{A}$ and $L\mathfrak{A}$ of the right-, respectively, left universal multipliers (with respect to w) of \mathfrak{A} are algebras. Hence, $\mathfrak{A}_0 := L\mathfrak{A} \cap R\mathfrak{A}$ is a *-algebra and, thus,

- (i) $(\mathfrak{A}, \mathfrak{A}_0)$ is a quasi *-algebra.
- (ii) If \mathfrak{A} is endowed with τ_{ind} , then the maps $x \mapsto x^*$, $x \mapsto a \cdot x$, $x \mapsto x \cdot b$, $a, b \in \mathfrak{A}_0$ are continuous.

It is easily seen from the very definition that if $a \in R\mathfrak{A}$ and $x \in \mathfrak{A}^+$, then $a^*xa \in \mathfrak{A}^+$. Hence, if $\mathcal{P}(\mathfrak{A})$ denotes the family of all positive linear functionals on \mathfrak{A} , we have in particular $\omega(a^*xa) \geq 0$, for every $\omega \in \mathcal{P}(\mathfrak{A})$.

Theorem 5.4 *Let \mathfrak{A} be a C^* -inductive partial $*$ -algebra with the multiplication defined by a family $\{w_\alpha\}$ and with pre-unit u . Assume, moreover, that the following condition (P) holds:*

$$(P) \ y \in \mathfrak{A}, \omega(a^*ya) \geq 0, \forall \omega \in \mathcal{P}(\mathfrak{A}) \text{ and } a \in R\mathfrak{A} \Rightarrow y \in \mathfrak{A}^+;$$

then, for $x \in \mathfrak{A}$, the following conditions are equivalent.

- (i) x is order bounded with respect to u .
- (ii) There exists $\gamma_x > 0$ such that

$$|\omega(a^*xa)| \leq \gamma_x \omega(a^*ua), \quad \forall \omega \in \mathcal{P}(\mathfrak{A}), \quad \forall a \in R\mathfrak{A}.$$

- (iii) There exists $\gamma_x > 0$ such that

$$|\omega(b^*xa)|^2 \leq \gamma_x \omega(a^*ua)\omega(b^*ub), \quad \forall \omega \in \mathcal{P}(\mathfrak{A}), \quad \forall a, b \in R\mathfrak{A}.$$

Proof It is sufficient to consider the case $x = x^*$;

(i) \Rightarrow (ii): Let $\omega \in \mathcal{P}(\mathfrak{A})$. By the hypothesis, $-\gamma u \leq x \leq \gamma u$, for some $\gamma > 0$; then $\omega(\gamma u - x) \geq 0$ and $\omega(a^*(\gamma u - x)a) \geq 0, \forall a \in R\mathfrak{A}$. On the other hand, similarly, one can show that $\omega(a^*(x - \gamma u)a) \geq 0$.

- (ii) \Rightarrow (i): Assume now that u is a pre-unit and there exists $\gamma_x > 0$ such that

$$|\omega(a^*xa)| \leq \gamma_x \omega(a^*ua), \quad \forall \omega \in \mathcal{P}(\mathfrak{A}), \quad a \in R\mathfrak{A}.$$

Then

$$\gamma_x \omega(a^*ua) \pm \omega(a^*xa) \geq 0 \Rightarrow \omega(a^*(\gamma_x u \pm x)a) \geq 0, \quad \forall \omega \in \mathcal{P}(\mathfrak{A}), a \in R\mathfrak{A}.$$

So, by (P), $\gamma_x u \pm x \geq 0$.

(i) \Rightarrow (iii): By the assumption, there exists $\gamma > 0$ such that $-\gamma u \leq x \leq \gamma u$. Let $\omega \in \mathcal{P}(\mathfrak{A})$. Then, the linear functional ω_a on \mathfrak{A} , defined by $\omega_a(x) := \omega(a^*xa)$, is positive. Hence, if $x = x^*$

$$-\gamma \omega_a(u) \leq \omega_a(x) \leq \gamma \omega_a(u);$$

i.e.,

$$|\omega(a^*xa)| \leq \gamma \omega(a^*ua).$$

Now, let $x \in \mathfrak{A}^+, a, b \in R\mathfrak{A}$. Let us define $\Omega_\omega^x(a, b) := \omega(b^*xa)$. Then, it is easily checked that Ω_ω^x is a positive sesquilinear form on $R\mathfrak{A} \times R\mathfrak{A}$. Using the Cauchy–Schwartz inequality, we obtain

$$\begin{aligned} |\omega(b^*xa)| &\leq \omega(a^*xa)^{1/2} \omega(b^*xb)^{1/2} \\ &\leq \gamma \omega(a^*ua)^{1/2} \omega(b^*ub)^{1/2}. \end{aligned}$$

The extension to arbitrary $x \in \mathfrak{A}$ goes through as in the proof of Proposition 4.3 of [8].

- (iii) \Rightarrow (ii) It is trivial. □

The previous proof shows that if $x = x^* \in \mathfrak{A}$ is order bounded with respect to u then

$$p(x) \leq \sup\{|\omega(b^*xa)|; \omega \in \mathcal{P}(\mathfrak{A}); a, b \in R\mathfrak{A}; \omega(a^*ua) = \omega(b^*ub) = 1\}.$$

where $p(x)$ is the quantity defined in Proposition 4.12.

The following statement is an easy consequence of Proposition 4.12 and Theorem 5.4.

Theorem 5.5 *Let \mathfrak{A} be a C^* -inductive partial $*$ -algebra with the multiplication defined by a family $\{w_\alpha\}$ and pre-unit u . Assume that conditions (r₁) and (P) are satisfied. For an element $x \in \mathfrak{A}$, having a representative in every $\mathfrak{B}_\alpha, \alpha \in \mathbb{F}$, the following statements are equivalent.*

- (i) $x \in \mathfrak{A}_b$.
(ii) x is order bounded with respect to u .
(iii) For every $\omega \in \mathcal{P}(\mathfrak{A})$

$$|\omega(b^*xa)|^2 \leq \gamma_x \omega(a^*ua)\omega(b^*ub), \quad \forall a, b \in R\mathfrak{A}.$$

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