## CHARACTERIZATION OF (r, s)-ADJACENCY GRAPHS OF COMPLEXES

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ABSTRACT. The (r, s)-adjacency graph of a simplicial complex K has been defined as the graph whose nodes are the r-cells of K with adjacency whenever there is incidence with a common s-cell. The (r, s)-adjacency graphs for r > s have been characterized by graph coverings by Dewdney and Harary generalizing the result of Krausz for line-graphs (r = 1, s = 0). We now complete the characterization by handling the case r < s.

**1. Introduction.** Let S be a collection of distinct subsets called *simplexes* of a nonempty finite set V whose elements are called *nodes*. Then K = (V, S) is a (*simplicial*) complex if it satisfies the condition that every nonempty subset of a simplex  $x \in S$  is also a simplex.

The dimension of a simplex x in K is r = |x| - 1 and x is called an *r*-simplex or sometimes an *r*-cell. The dimension of a complex K is the maximum dimension of a simplex in it. A complex of dimension r is called an *r*-complex. Thus a 1-complex is a graph which has at least one line. If the graph is totally disconnected, it is, of course, a 0-complex. A pure *r*-complex is one in which every maximal simplex has dimension r.

Every complex K has an associated hypergraph whose edges are its maximal simplexes. Conversely given any hypergraph, we can construct its complex by including every nonempty subset of an edge as a simplex. Thus an r-complex is known as an hereditary rank-r hypergraph.

The (r, s)-adjacency graph,  $r \neq s$ , of a complex K denoted by  $L_{rs}(K)$ , in analogy with the standard notation for the line-graph L(G), is the graph whose nodes are the r-simplexes of K, with two of these nodes adjacent whenever their r-simplexes are incident with a common s-simplex. Thus if K is a 1-complex, then  $L_{10}(K)$  is its line-graph.

This concept was first suggested by Grünbaum [6] for s = r - 1 and has been investigated for r > s by Dewdney and Harary [3], by Bermond, Sotteau, Heydemann, Germa in a series [1], [2], [8], and for s = 0 and s = r - 1 by Gardner [4], [5] and others.

Let  $x_1, \ldots, x_i$  be simplexes of K, with no  $x_i$  contained in  $x_j$  for any  $i \neq j$ . Their *induced complex* is the subcomplex K' whose maximal simplexes are the  $x_i$ .

2. Structural characterization of adjacency graphs. Krausz [9] characterized linegraphs of 1-complexes by a suitable partition of the edges into complete subgraphs.

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In this statement, condition (i) is redundant because of the partition requirement, but it is useful for later generalization.

THEOREM A (KRAUSZ). The graph G is a (1, 0)-adjacency graph if and only if the edges can be partitioned into a family of complete subgraphs  $G_i$  satisfying:

(i) Each edge is in exactly one  $G_i$ .

(ii) Each vertex is in no more than two  $G_i$ .

Grünbaum [6] conjectured that this characterization could be extended to graphs which are (r, r - 1)-adjacency graphs. Necessary conditions which are not sufficient are given in [2]. When r > s, necessary and sufficient conditions for (r, s)-adjacency graphs were developed in [3].

THEOREM B (DEWDNEY AND HARARY). The graph G is an (r, s)-adjacency graph with r > s if and only if there is a family  $G_i$  of subgraphs of G satisfying the following three conditions.

(i) Each edge lies in at most r and at least s + 1 of the graphs  $G_i$ .

(ii) Each vertex lies in at most r + 1 of the graphs  $G_i$ .

(iii) The intersection of any s + 1 of the graphs  $G_i$  is either empty or a complete graph.

The proof, in analogy with that of Krausz for line-graphs, constructs a complex whose nodes (0-simplexes) are the  $G_i$  and which has one *r*-simplex for each node v of G. The *r*-simplex corresponding to v contains the 0-simplex  $G_i$  whenever node v of G is in subgraph  $G_i$ .

A few comments are in order. The complete bipartite graph  $G = K(2, \binom{2r}{r})$  is the (2r - 1, r - 1)-adjacency graph of some complex K. Such a complex K can be constructed by taking 4r nodes, partitioning them into two sets x and y of size 2r each and defining the (2r - 1)-simplexes to be x, y and all sets consisting of r nodes from each of x and y. It is not possible however to cover the edges of G with a set of complete graphs which satisfies condition (i) of Theorem B. Therefore we cannot expect a characterization of the Krausz type which contains among the  $G_i$  a subset consisting of complete graphs which covers the edges of G.

Bermond, Heydemann and Sotteau [1] defined the *s*-line-graph of a hypergraph H, denoted  $L_s(H)$ , as the graph whose nodes are the edges of H with two edges adjacent if their intersection contains at least *s* nodes. Theorem B characterizes the (s + 1)-line-graphs of rank-(r + 1) hypergraphs.

In an exact (r, s)-adjacency graph, two adjacent simplexes have a common s-simplex but not a common (s + 1)-simplex. If (i) is replaced by

(i') Each edge lies in exactly s + 1 of the graphs  $G_i$ , then Theorem B characterizes the exact (r, s)-adjacency graphs.

We now finish the characterization of all (r, s)-adjacency graphs by deriving conditions for r < s.

THEOREM 1. A graph G is the (r, s)-adjacency graph of a simplicial complex with r < s if and only if the edges of G are covered by a set of complete subgraphs  $G_i$  of

order  $\binom{s+1}{r+1}$  which are grouped into subsets  $S_1, \ldots, S_p$  such that the  $G_i$  and  $S_j$  satisfy the following conditions.

(i) The intersection of every subset of the  $G_i$ 's has the form  $K_b$  where b is a binomial coefficient of the form  $\binom{n+1}{r+1}$  for some  $n \ge r$ . In this case there are exactly n + 1 sets  $S_i$  containing this subset of  $G_i$ 's.

(ii) Each  $G_i$  is in at most s + 1 sets  $S_i$ .

**PROOF.** Let G be any graph with isolated nodes  $u_1, \ldots, u_n$ . Represent the  $u_j$  by node-disjoint r-simplexes, one for each  $u_j$ . Then G is an (r, s)-adjacency graph if and only if  $G - \{u_1, \ldots, u_n\}$  is. Assume without loss of generality that G is connected.

We will first show that the conditions of the theorem are sufficient. We do this by constructing a complex K with a maximal simplex  $x_i$  for each graph  $G_i$ . For each  $G_i$  define disjoint sets  $T_i$  of cardinality  $s + 1 - |\{S_j: G_i \in S_j\}|$ . Set  $x_i = \{S_j: G_i \in S_i\} \cup T_i$ . Let K be the complex induced by the maximal simplexes  $x_i$ .

We prove that  $L_{rs}(K) \cong G$  by induction on t - m, where t is the number of  $G_i$ 's. For the induction hypothesis, suppose that there is a one-to-one map from the nodes that lie in at least m + 1  $G_i$ 's onto the r-simplexes of K incident with at least m + 1 maximal simplexes, that is, s-simplexes. In addition suppose that the map has the property that a node u is mapped to an r-simplex x, with  $x = \{S_1, \ldots, S_{r+1}\}$  or  $x = \{S_1, \ldots, S_j, t_{j+1}, \ldots, t_{r+1}\}$  with  $t_{j+1}, \ldots, t_r \in T_i$  for some i, only if  $S_1 \cap \cdots \cap S_{r+1} = \{G_i: u \in G_i\}$ .

Let m = 0. The intersection of all the  $G_i$ 's is  $K_b$  with  $b = \binom{n+1}{r+1}$ . By condition (i), there are exactly n + 1  $S_j$ 's containing all the graphs  $G_i$  and there are therefore exactly  $\binom{n+1}{r+1}$  r-simplexes lying in the intersection of all the  $x_i$ 's. Fix any one-to-one map between the nodes of the  $K_b$  and these r-simplexes.

Now let m > 0 be given. Fix an *m*-set  $\{G_{i_1}, \ldots, G_{i_m}\}$  with  $H = G_{i_1} \cap \cdots \cap G_{i_m}$ =  $K_b$ ,  $b = \binom{n+1}{r+1}$ . Using condition (i) again, there are exactly n + 1 S<sub>j</sub>'s containing this subset of  $G_i$ 's and therefore exactly  $\binom{n+1}{r+1}$  r-simplexes in  $x_{i_1} \cap \cdots \cap x_{i_m} =$  $\{S_{j_1}, \ldots, S_{j_{n+1}}\}$ . Some of these r-simplexes are already the image of a node of G under the map defined by the induction hypothesis. The number of such rsimplexes is equal to the number of nodes in the union of the graphs  $H \cap G_{i_{m+1}}$ taken over all  $i_{m+1} \neq i_1, \ldots, i_m$ . As this is just the number of r-simplexes in the corresponding union of the  $x_{i_1} \cap \cdots \cap x_{i_m} \cap x_{i_{m+1}}$  the map can be extended in a one-to-one fashion to map the nodes of  $H = G_{i_1} \cap \cdots \cap G_{i_m}$  to the r-simplexes of  $x_{i_1} \cap \cdots \cap x_{i_n}$ .

Observe that no unassigned node is in two distinct intersections of m graphs  $G_i$ . Thus the map will be well-defined if it is extended in this way and will cover all nodes in any intersection of m graphs  $G_i$ . The map is one-to-one by definition and onto by construction.

Finally we verify that two r-simplexes are the image of adjacent nodes of G if and only if the simplexes are incident with a common s-simplex. Let x and y be two r-simplexes whose preimages in G are u and v. If u and v are adjacent, then the edge uv is in some  $G_i$  and x and y are both incident with the s-simplex  $x_i$ . Conversely, if x and y are incident with an s-simplex  $x_i$  then their preimages must be contained in  $G_i$ .

To prove the necessity of the conditions, suppose that G is the (r, s)-adjacency graph of a complex K. Let  $x_i$  be an s-simplex of K. Then there are  $\binom{s+1}{r+1}$  r-simplexes in  $x_i$  and the image of  $x_i$  in G is

$$K\left(\frac{s+1}{v+1}\right) = G_i$$

If *m* distinct *r*-simplexes overlap on n + 1 points, their images in *G* will be a complete graph on  $\binom{n+1}{r+1}$  nodes.

For each 0-simplex j of K, define the set  $S_j = \{G_i: x_i \text{ is an } s \text{-simplex with } j \in x_i\}$ . Clearly the  $S_i$  satisfy conditions (i) and (ii).

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