Combining Adaptive Noise and Look-Ahead in Local Search for SAT***

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Abstract. The adaptive noise mechanism was introduced in Novelty+ to automatically adapt noise settings during the search [4]. The local search algorithm G^2WSAT deterministically exploits promising decreasing variables to reduce randomness and consequently the dependence on noise parameters. In this paper, we first integrate the adaptive noise mechanism in G^2WSAT to obtain an algorithm $adaptG^2WSAT$, whose performance suggests that the deterministic exploitation of promising decreasing variables cooperates well with this mechanism. Then, we propose an approach that uses look-ahead for promising decreasing variables to further reinforce this cooperation. We implement this approach in $adaptG^2WSAT$, resulting in a new local search algorithm called $adaptG^2WSAT_P$. Without any manual noise or other parameter tuning, $adaptG^2WSAT_P$ shows generally good performance, compared with G^2WSAT with approximately optimal static noise settings, or is sometimes even better than G^2WSAT . In addition, $adaptG^2WSAT_P$ is favorably compared with state-of-the-art local search algorithms such as R+adaptNovelty+ and VW.

1 Introduction

The performance of a *Walksat* family algorithm crucially depends on noise p and sometimes wp (random walk probability) or dp (diversification probability). For example, it is reported in [9] that running *R*-*Novelty* [9] with p = 0.4 instead of p = 0.6 degrades its performance by more than 50% for random 3-SAT instances. However, to

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find the optimal noise settings for each heuristic, extensive experiments on various values of p and sometimes wp or dp are needed because the optimal noise settings vary widely and depend on the types and sizes of the instances.

To avoid manual noise tuning, two approaches were proposed. Auto-Walksat [10] exploits the invariants observed in [9] to estimate the optimal noise settings for an algorithm on a given problem, based on several preliminary unsuccessful runs of the algorithm on this problem. This algorithm then rigorously applies the estimated optimal noise setting to the problem. The adaptive noise mechanism [4] was introduced in Novelty+ [3] to automatically adapt noise settings during the search, yielding the algorithm adaptNovelty+. This algorithm does not need any manual noise tuning and is effective for a broad range of problems.

One way to diminish the dependence of problem solving on noise settings is to reduce randomness in local search. The local search algorithm G^2WSAT deterministically selects the best promising decreasing variable to flip, if such variables exist [5]. Nevertheless, the performance of G^2WSAT still depends on static noise settings, since when there is no promising decreasing variable, a heuristic, such as Novelty++, is used to select a variable to flip, depending on two probabilities, p and dp. Furthermore, G^2WSAT does not favor those flips that will generate promising decreasing variables to minimize its dependence on noise settings.

In this paper, we first incorporate the adaptive noise mechanism of adaptNovelty+in G^2WSAT to obtain an algorithm $adaptG^2WSAT$. Experimental results suggest that the deterministic exploitation of promising decreasing variables in $adaptG^2WSAT$ enhances this mechanism. Then, we integrate a look-ahead approach in $adaptG^2WSAT$ to favor those flips that can generate promising decreasing variables, resulting in a new local search algorithm called $adaptG^2WSAT_P$. Without any manual noise or other parameter tuning, $adaptG^2WSAT_P$ shows generally good performance, compared with G^2WSAT with approximately optimal static noise settings, or is sometimes even better than G^2WSAT . Moreover, $adaptG^2WSAT_P$ compares favorably with state-of-the-art algorithms such as R+adaptNovelty+[1] and VW [11].

2 G^2WSAT and $adaptG^2WSAT$

2.1 G^2WSAT

Given a CNF formula \mathcal{F} and an assignment A, the objective function that local search for SAT attempts to minimize is usually the total number of unsatisfied clauses in \mathcal{F} under A. Let x be a variable. The break of x, break(x), is the number of clauses in \mathcal{F} that are currently satisfied but will be unsatisfied if x is flipped. The make of x, make(x), is the number of clauses in \mathcal{F} that are currently unsatisfied but will be satisfied if x is flipped. The score of x with respect to A, $score_A(x)$, is the improvement of the objective function if x is flipped. The score of x should be the difference between make(x)and break(x). We write $score_A(x)$ as score(x) if A is clear from the context. Heuristics Novelty [9] and Novelty++ [5] select a variable to flip from a randomly selected unsatisfied clause c as follows.

- Novelty(p): Sort the variables in c by their scores, breaking ties in favor of the least recently flipped variable. Consider the best and second best variables from the sorted variables. If the best variable is not the most recently flipped one in c, then pick it. Otherwise, with probability p, pick the second best variable, and with probability 1-p, pick the best variable.
- *Novelty*++(p, dp): With probability dp (diversification probability), pick the least recently flipped variable in c, and with probability 1-dp, do as *Novelty*.

Given a CNF formula \mathcal{F} and an assignment A, a variable x is said to be *decreasing* with respect to A if $score_A(x) > 0$. Promising decreasing variables are defined in [5] as follows:

- 1. Before any flip, i.e., when A is an initial random assignment, all decreasing variables with respect to A are promising.
- 2. Let x and y be two different variables and x be not decreasing with respect to A. If, after y is flipped, x becomes decreasing with respect to the new assignment, then x is a promising decreasing variable with respect to the new assignment.
- 3. A promising decreasing variable remains promising with respect to subsequent assignments in local search until it is no longer decreasing.

 G^2WSAT [5] deterministically picks the promising decreasing variable with the highest score to flip, if such variables exist. If there is no promising decreasing variable, G^2WSAT uses a heuristic, such as *Novelty* [9], *Novelty*+[3], or *Novelty*++[5], to pick a variable to flip from a randomly selected unsatisfied clause.

Promising decreasing variables might be considered as the opposite of tabu variables defined in [8, 9]; the flips of tabu variables are refused in a number of subsequent steps. Promising decreasing variables are chosen to flip since they probably allow local search to explore new promising regions in the search space, while tabu variables are forbidden since they probably make local search repeat or cancel earlier moves.

2.2 Algorithm $adaptG^2WSAT$

The adaptive noise mechanism [4] in adaptNovelty+ can be described as follows. At the beginning of a run, noise p is set to 0. Then, if no improvement in the objective function value has been observed over the last $\theta \times m$ search steps, where m is the number of the clauses of the input formula, and θ is a parameter whose default value in adaptNovelty+ is 1/6, noise p is increased by $p := p + (1 - p) \times \phi$, where ϕ is another parameter whose default value in adaptNovelty+ is 0.2. Every time the objective function value is improved, noise p is decreased by $p := p - p \times \phi/2$.

We implement this adaptive noise mechanism of adaptNovelty+ in G^2WSAT to obtain an algorithm $adaptG^2WSAT$, and confirm that ϕ and θ need not be tuned

for each problem instance or instance type to achieve good performances. That is, like adaptNovelty+, $adaptG^2WSAT$ is an algorithm in which no parameter has to be manually tuned to solve a new problem.

2.3 Performances of the Adaptive Noise Mechanism for $adaptG^2WSAT$ and for adaptNovelty+

We evaluate the performance of the adaptive noise mechanism for $adaptG^2WSAT$ on 9 groups of benchmark SAT problems.³ Structured problems come from the SATLIB repository⁴ and Miroslav Velev's SAT Benchmarks.⁵ These structured problems include bw_large.c and bw_large.d in Blocksworld, 3bit*31, 3bit*32, e0ddr2*1, e0ddr2*4, enddr2*1, enddr2*8, ewddr2*1, and ewddr2*8 in Beijing, the first 5 instances in Flat200-479, logistics.c and logistics.d in logistics, par16-1, par16-2, par16-3, par16-4, and par16-5 in parity, the 10 satisfiable instances in QG, and all satisfiable formulas in Superscalar Suite 1.0a (SSS.1.0a) except for *bug54.⁶ Since these 10 QG instances contain unit clauses, we simplify them using *my_compact*⁷ before running every algorithm. Random problems consist of unif04-52, unif04-62, unif04-65, unif04-80, unif04-83, unif04-86, unif04-91, and unif04-99, from the random category in the SAT 2004 competition benchmark.⁸ Industrial problems comprise v*1912, v*1915, v*1923, v*1924, v*1944, v*1955, v*1956, and v*1959, from the industrial category in the SAT 2005 competition benchmark.⁹

Table 1 shows the performances of $adaptG^2WSAT$ and G^2WSAT , both using heuristic Novelty+, compared with those of adaptNovelty+ and Novelty+. This table presents the results of these algorithms for only one instance from each group. The random walk probability (wp) is not adjusted and takes the default value 0.01 for the original Novelty+, in each algorithm for each instance. G^2WSAT (version 2005) is downloaded from http://www.laria.u-picardie.fr/~cli. Novelty+ and adaptNovelty+are from UBCSAT [13]. The static noise p of G^2WSAT is approximately optimal for G^2WSAT on each instance, and is obtained by comparing p = 0.10, 0.11, ...,0.89, and 0.90 for each instance. The static noise p of Novelty+ is different from that of G^2WSAT because Novelty+ with its own noise p can perform better than Novelty+ with the noise p of G^2WSAT . Each instance is executed 250 times. The

³ All experiments reported in this paper are conducted in Chorus, which consists of 2 dual processor master nodes (Sun V65) with hyperthreading enabled and 80 dual processor compute nodes (Sun V60). Each compute node has two 2.8GHz Intel Xeon processors with 2 to 3 Gigabytes of memory.

⁴ http://www.satlib.org/

⁵ http://www.ece.cmu.edu/~mvelev/sat_benchmarks.html

⁶ The instance *bug54 is hard for every algorithm discussed in this paper.

⁷ available at http://www.laria.u-picardie.fr/~cli

⁸ http://www.lri.fr/~simon/contest04/results/

⁹ http://www.lri.fr/~simon/contest/results/

algorithm	cutoff	N	ovelty+	adaptNovelty+		G^{2}	² WSAT	$adaptG^2WSAT$	
heuristic						N	ovelty+	Novelty+	
parameters		1	w p=0.01	$\theta = 1/6, \phi = 0.2$		1	wp=0.01	$\theta = 1/6, \phi = 0.2$	
		p	suc	suc	suc degr	p	suc	suc	suc degr
bw_large.d	10^{8}	.17	100%	92.80%	7.20%	.20	100%	100%	0%
ewddr2*8	10^{7}	.78	100%	5.20%	94.80%	.52	100%	100%	0%
flat200-5	10^{8}	.54	99.60%	99.20%	0.40%	.60	100%	100%	0%
logistics.c	10^{5}	.41	58.00%	43.20%	25.52%	.52	81.20%	73.20%	9.85%
par16-1	10^{9}	.80	98.00%	42.80%	56.33%	.63	100%	100%	0%
qg5-11	10^{6}	.29	100%	97.20%	2.80%	.32	100%	92.40%	7.60%
*bug17	10^{7}	.82	100%	32.80%	67.20%	.29	66.00%	66.00%	0%
unif04-52	10^{8}	.51	99.60%	94.40%	5.22%	.52	100%	99.20%	0.80%
v*1912	10^{7}	.16	56.00%	50.80%	9.29%	.22	84.00%	81.20%	3.33%

Table 1. Performance of the adaptive noise mechanism for $adaptG^2WSAT$ using Novelty+ and for adaptNovelty+. Results in bold indicate the lower degradation in success rate.

success rate of an algorithm for an instance is the number of successful runs divided by 250, and the success rate is intended to be the empirical probability with which the algorithm finds a solution for the instance within the cutoff. For each algorithm on each instance, we report the cutoff ("cutoff") and success rate ("suc"). Let *sr* be the success rate of G^2WSAT or *Novelty*+ with static noise for an instance, and *ar* the success rate of $adaptG^2WSAT$ or adaptNovelty+ for the same instance. For each instance, we also report the degradation ("suc degr") in success rate of $adaptG^2WSAT$, ((*srar*)/*sr*)*100, compared with that of G^2WSAT , and the degradation ("suc degr") in success rate of adaptNovelty+, ((*sr-ar*)/*sr*)*100, compared with that of *Novelty*+.

According to Table 1, without manual noise tuning, $adaptG^2WSAT$ and adaptNovelty+, with the adaptive noise mechanism, achieve good performances, θ and ϕ taking the same fixed values for all problems. Nevertheless, with instance specific noise settings, G^2WSAT and Novelty+ achieve success rates the same as or higher than $adaptG^2WSAT$ and adaptNovelty+, respectively, for all instances. For all instances except for qg5-11, the degradation in success rate of $adaptG^2WSAT$ compared with that of G^2WSAT is lower than the degradation in success rate of $adaptG^2WSAT$ compared with that of Novelty+. Especially, for bw_large.d, ewddr2*8, par16-1, and *bug17, the degradation in success rate of $adaptG^2WSAT$ compared with that of G^2WSAT is significantly lower than the degradation in success rate of $adaptG^2WSAT$ compared with that of G^2WSAT is significantly lower than the degradation in success rate of $adaptG^2WSAT$ compared with that of MOVELTW.

In Table 1, both $adaptG^2WSAT$ and G^2WSAT use Novelty+ to select a variable to flip when there is no promising decreasing variable. Furthermore, $adaptG^2WSAT$ uses the same default values for parameters θ and ϕ as adaptNovelty+, to adapt noise. So, it appears that, apart from the implementation details, the only difference between G^2WSAT and Novelty+, and between $adaptG^2WSAT$ and adaptNovelty+, in Ta-

ble 1, is the deterministic exploitation of promising decreasing variables in G^2WSAT and $adaptG^2WSAT$. From this table, we observe that the degradation in performance of $adaptG^2WSAT$ compared with that of G^2WSAT is lower than the degradation in performance of adaptNovelty+ compared with that of Novelty+. This observation suggests that the deterministic exploitation of promising decreasing variables enhances the adaptive noise mechanism. We then expect that better exploitation of promising decreasing variables will further enhance this mechanism.

3 Look-Ahead for Promising Decreasing Variables

3.1 Promising Score of a Variable

Given a CNF formula \mathcal{F} and an assignment A, let x be a variable, let B be obtained from A by flipping x, and let x' be the best promising decreasing variable with respect to B. We define the promising score of x with respect to A as

$$pscore_A(x) = score_A(x) + score_B(x')$$

where $score_A(x)$ is the score of x with respect to A and $score_B(x')$ is the score of x' with respect to B.¹⁰

If there are promising decreasing variables with respect to B, the promising score of x with respect to A represents the improvement in the number of unsatisfied clauses under A by flipping x and then x'. In this case, $pscore_A(x) > score_A(x)$.

If there is no promising decreasing variable with respect to B,

$$pscore_A(x) = score_A(x)$$

since $adaptG^2WSAT$ does not know in advance which variable will be flipped for B (the choice of the variable to flip is made randomly by using Novelty++).

Given \mathcal{F} and two variables x and y in \mathcal{F} , y is said to be a neighbor of x with respect to \mathcal{F} if y occurs in some clause containing x in \mathcal{F} . According to Equation 6 in [5], the flipping of x can only change the scores of the neighbors of x. Given an initial assignment, G^2WSAT or $adaptG^2WSAT$ computes the scores for all variables, and then uses Equation 6 in [5] to update the scores of the neighbors of the flipped variable after each step and maintains a list of promising decreasing variables. This update takes time O(L), where L is the upper bound for the sum of the lengths of all clauses containing the flipped variable and is almost a constant for a random 3-SAT problem when the ratio of the number of clauses to the number of variables is a constant. The computation of $pscore_A(x)$ involves the simulation of flipping x and the searching for the largest score of the promising decreasing variables after flipping x. This computation takes time $O(L + \gamma)$, where γ is the upper bound for the number of all the promising decreasing variables in \mathcal{F} after flipping x.

```
1: with probability wp do y \leftarrow randomly choose a variable in c;
 2: otherwise
      Determine best and second, breaking ties in favor of the least recently flipped variable;
 3:
      /*best and second are the best and second best variables in c according to the scores*/
 4.
      if best is the most recently flipped variable in c
 5:
      then
          with probability p do y \leftarrow second;
 6:
 7:
          otherwise if pscore(second) > = pscore(best) then y \leftarrow second else y \leftarrow best;
 8:
      else
 9:
          if best is more recently flipped than second
10:
          then if pscore(second) > = pscore(best) then y \leftarrow second else y \leftarrow best;
11:
          else y \leftarrow best;
12: return y;
```



3.2 Integrating Limited Look-Ahead in $adaptG^2WSAT$

We improve $adaptG^2WSAT$ in two ways. The algorithm $adaptG^2WSAT$ maintains a stack, DecVar, to store all promising decreasing variables in each step. When there are promising decreasing variables, the improved $adaptG^2WSAT$ chooses the least recently flipped promising decreasing variable among all promising decreasing variables in |DecVar| to flip. Otherwise, the improved $adaptG^2WSAT$ selects a variable to flip from a randomly chosen unsatisfied clause c, using heuristic $Novelty+_P$ (see Fig. 1), which extends Novelty+ [3], to exploit limited look-ahead.

Let best and second denote the best and second best variables respectively, measured by the scores of variables in c. Novelty+_P computes the promising scores for only best and second, only when best is more recently flipped than second (including the case in which best is the most recently flipped variable, where the computation is performed with probability 1 - p), in order to favor the less recently flipped second. In this case, score(second) < score(best). As is suggested by the success of HSAT [2] and Novelty [9], a less recently flipped variable is generally better if it can improve the objective function at least as well as a more recently flipped variable does. Accordingly, Novelty+_P prefers second if second is less recently flipped than best and if $pscore(second) \ge pscore(best)$.

The improved $adaptG^2WSAT$ is called $adaptG^2WSAT_P$ and is sketched in Fig. 2. Note that wp (random walk probability) is also automatically adjusted and wp =

¹⁰ x' has the highest $score_B(x')$ among all promising decreasing variables with respect to B.

p/10. The reason for adjusting wp this way is that, when noise needs to be high, local search should also be well randomized, and when low noise is sufficient, random walks are often not needed. The setting wp = p/10 comes from the fact that p = 0.5 and dp = 0.05 give the best results for random 3-SAT instances in G^2WSAT .

Algorithm: $adaptG^2WSAT_P(\text{SAT-formula }\mathcal{F})$

1:	for try=1 to Maxtries do
2:	$A \leftarrow$ randomly generated truth assignment; $p=0$; $wp=0$;
3:	Store all decreasing variables in stack DecVar;
4:	for flip=1 to Maxsteps do
5:	if A satisfies \mathcal{F} then return A;
6:	$\mathbf{if} \left DecVar \right > 0$
7:	then
8:	$y \leftarrow$ the least recently flipped promising decreasing variable among
9:	all promising decreasing variables in DecVar ;
10:	else
11:	$c \leftarrow$ randomly selected unsatisfied clause under A;
12:	$y \leftarrow Novelty+_P(p, wp, c);$
13:	$A \leftarrow A$ with y flipped;
14:	Adapt p and wp ;
15:	Delete variables that are no longer decreasing from <i>DecVar</i> ;
16:	Push new decreasing variables into DecVar which are different from
17:	y and were not decreasing before y is flipped;
18:	return Solution not found;

Fig. 2. Algorithm $adaptG^2WSAT_P$

Given a CNF formula \mathcal{F} and an assignment A, the set of assignments obtained by flipping one variable of \mathcal{F} is called the *1-flip neighborhood* of A, and the set of assignments obtained by flipping two variables of \mathcal{F} is called the *2-flip neighborhood* of A. The algorithm $adaptG^2WSAT_P$ exploits only the 1-flip neighborhoods, since the limited look-ahead is just used as a heuristic to select the next variable to flip.

We find that in $adaptG^2WSAT$ and $adaptG^2WSAT_P$, which use heuristics Novelty++ and $Novelty+_P$, respectively, $\theta = 1/5$ and $\phi = 0.1$ give slightly better results on the 9 groups of instances presented in Section 2.3 than $\theta = 1/6$ and $\phi = 0.2$, their original default values in adaptNovelty+. So, in $adaptG^2WSAT_P$, $\theta = 1/5$ and $\phi = 0.1$.

In this paper, $adaptG^2WSAT_P$ is improved in two ways, based on the preliminary $adaptG^2WSAT_P$ described in the preliminary version of this paper [6, 7]. The first

improvement is that, when promising decreasing variables exist, $adaptG^2WSAT_P$ no longer computes the promising scores for the δ promising decreasing variables with higher scores in |DecVar|, where δ is a parameter, but chooses the least recently flipped promising decreasing variable among all promising decreasing variables in |DecVar| to flip. As a result, $adaptG^2WSAT_P$ no longer needs parameter δ . The reasons for this first improvement are that, usually the scores of promising decreasing variables are close and so such variables can improve the objective function roughly the same, and that flipping the least recently flipped promising decreasing variable can increase the mobility and coverage [12] of a local search algorithm in the search space. The second improvement is that, when there is no promising decreasing variable, $adaptG^2WSAT_P$ uses $Novelty_{+P}$ instead of $Novelty_{+P}$ [6,7], to select a variable to flip from a randomly chosen unsatisfied clause c. The difference between Novelty+_P and Novelty+_P is that, with wp (random walk probability), Novelty+_P randomly chooses a variable to flip from c, but with dp (diversification probability), Novelty++_P chooses a variable in c, whose flip will falsify the least recently satisfied clause. Considering that $adaptG^2WSAT_P$ deterministically uses both promising decreasing variables and promising scores, adding a small amount of randomness¹¹ to the search may help find a solution.

4 Evaluation

We evaluate $adaptG^2WSAT_P$ on the 9 groups of instances, or the 56 instances, presented in Section 2.3. For an instance and an algorithm, we report the median flip number ("#flips") and the median run time ("time") in seconds, for this algorithm to find a solution for this instance. Each instance is executed 250 times. If an algorithm can successfully find a solution for an instance in at least 126 runs, the median flip number and median run time are calculated based on these 250 runs. If an algorithm cannot achieve a success rate greater than 50% on an instance even if the cutoff is greater than or equal to the maximum value among the cutoffs of all other algorithms, the median flip number and median run time cannot be calculated; we use "> Maxsteps" (greater than Maxsteps) to denote the median flip number and use "n/a" to denote the median run time, where Maxsteps is the cutoff for this algorithm on this instance. If the median flip number and median run time of G^2WSAT with any noise settings for an instance cannot be calculated, we also use n/a to denote the optimal noise setting. Results in bold indicate the best performance for an instance.

4.1 Comparison of Performances of $adaptG^2WSAT_P$, G^2WSAT , and $adaptG^2WSAT$

We compare the performances of $adaptG^2WSAT_P$, G^2WSAT with approximately optimal noise settings, and $adaptG^2WSAT$ in Table 2, where $adaptG^2WSAT_P$ uses

 $^{^{11}}$ In general, wp ranges from 0% to 10%.

Novelty+_P, and G^2WSAT and $adaptG^2WSAT$ use Novelty++, to pick a variable to flip, when there is no promising decreasing variable. On the instances that G^2WSAT can solve in reasonable time, except for qg7-13, the performance of $adaptG^2WSAT_P$ is comparable to that of G^2WSAT with approximately optimal noise settings. Moreover, $adaptG^2WSAT_P$ can solve 3bit*31, 3bit*32, *bug5, *bug38, *bug39, and *bug40, which are hard for G^2WSAT with any static noise settings. More importantly, $adaptG^2WSAT_P$ does not need any manual tuning of p and wp for each instance while G^2WSAT needs manual tuning of p and dp for each instance. In other words, G^2WSAT cannot achieve the performance shown in this table by using the same p and dp for the broad range of instances.

On the instances that $adaptG^2WSAT$ can solve in reasonable time, the performance of $adaptG^2WSAT_P$ is comparable to that of $adaptG^2WSAT$. Furthermore, $adaptG^2WSAT_P$ can solve 3bit*31, 3bit*32, *bug5, *bug38, *bug39, and *bug40, which are hard for $adaptG^2WSAT$. In addition, among the 56 instances presented in this table, $adaptG^2WSAT_P$ exhibits the best run time performance and/or the best flip number performance on the 13 instances among $adaptG^2WSAT_P$, G^2WSAT with approximately optimal noise settings, and $adaptG^2WSAT$, while $adaptG^2WSAT$ is never the best.

4.2 Comparison of Performances of $adaptG^2WSAT_P$, R+adaptNovelty+, and VW

R+adaptNovelty+ is adaptNovelty+ with preprocessing to add a set of resolvents of length ≤ 3 into the input formula [1]. VW [11] is an extension of Walksat. VWadjusts and smoothes variable weights, and takes variable weights into account when selecting a variable to flip. R+adaptNovelty+, G^2WSAT with p=0.50 and dp=0.05, and VW won the gold, silver, and bronze medals, respectively, in the satisfiable random formula category in the SAT 2005 competition.¹²

Table 3 compares the performance of $adaptG^2WSAT_P$ with the performances of R+adaptNovelty+ and VW. We download R+adaptNovelty+ and VW from http://www.satcompetition.org/. We use the default value 0.01 for the random walk probability in R+adaptNovelty+, when running this algorithm. In this table, instances with \dagger on the right constitute the entire set of instances that were used to originally evaluate R+adaptNovelty+ in [1]. Among the 56 instances presented in this table, in terms of run time, $adaptG^2WSAT_P$, R+adaptNovelty+, and VW are the best algorithms on the 32, 16, and 13 instances, respectively. Also, among the 56 instances, in terms of run time, $adaptG^2WSAT_P$ outperforms R+adaptNovelty+ and VW on the 38 and 42 instances, respectively.

¹² http://www.satcompetition.org/

	$adaptG^2$	WSAT _P	$adaptG^2$	WSAT	0	G^2WSAT	,
	#flips	time	#flips	time	optimal	#flips	time
bw_large.c	1083947	3.650	3553694	10.175	(.21, 0)	2119497	3.699
bw_large.d	1542898	8.590	9626411	49.635	(.16, 0)	3237895	7.180
3bit*31	87158	0.780	$> 10^{7}$	n/a	n/a	$> 10^{7}$	n/a
3bit*32	60518	0.565	$> 10^{7}$	n/a	n/a	$> 10^{7}$	n/a
e0ddr2*1	4520164	19.275	831073	2.595	(.14, .09)	254182	0.910
e0ddr2*4	641587	2.855	208815	0.805	(.23, .1)	117266	0.540
enddr2*1	982540	4.570	153905	0.640	(.18, .1)	97451	0.535
enddr2*8	412624	2.385	135332	0.585	(.16, .09)	90076	0.480
ewddr2*1	492907	2.470	137430	0.600	(.18, .1)	89420	0.505
ewddr2*8	262177	1.385	116917	0.535	(.16, .1)	67854	0.425
flat200-1	36764	0.025	42053	0.020	(.49, .08)	25358	0.010
flat200-2	288521	0.160	303515	0.135	(.49, .07)	171487	0.085
flat200-3	71324	0.045	89515	0.040	(.51, .05)	51037	0.025
flat200-4	314273	0.180	323353	0.145	(.49, .05)	178842	0.095
flat200-5	4963846	2.675	4173580	1.810	(.49, .08)	3008035	1.455
logistics.c	54777	0.075	46875	0.060	(.24, .07)	38177	0.040
logistics.d	83894	0.185	102575	0.165	(.2, .08)	78013	0.105
par16-1	58937999	27.955	76985828	29.870	(.51, .01)	48342381	20.835
par16-2	130634181	64.300	140615726	57.170	(.59, .01)	73324801	32.460
par16-3	104764223	50.865	112297525	44.885	(.58, .01)	80700698	33.223
par16-4	133899858	63.595	174053106	68.735	(.5, .02)	89662042	39.256
par16-5	124873168	59.865	133250726	53.385	(.54, .02)	83818097	35.688
qg1-07	6413	0.025	7370	0.020	(.38, 0)	4599	0.010
qg1-08	361229	4.740	448660	3.635	(.11, .03)	339312	1.350
qg2-07	3869	0.020	4708	0.025	(.33, .01)	2648	0.005
qg2-08	1262398	8.960	1473258	9.565	(.22, 0)	1449931	6.270
qg3-08	36322	0.125	36046	0.040	(.44, .05)	20517	0.015
qg4-09	68472	0.310	70659	0.100	(.37, 0)	48741	0.075
qg5-11	20598	0.210	23431	0.275	(.38, .01)	12559	0.080
qg6-09	414	0.005	441	0.005	(.41, .08)	340	0.000
qg7-09	392	0.005	318	0.005	(.41, .1)	316	0.015
qg7-13	$> 10^{\circ}$	n/a	$> 10^{\circ}$	n/a	(.33, 0)	4768987	50.809
*bug3	$> 10^{8}$	n/a	$> 10^{8}$	n/a	n/a	$> 10^{8}$	n/a
*bug4	$ >10^{\circ}$	n/a	$> 10^{\circ}$	n/a	n/a	$> 10^{\circ}$	n/a
*bug5	1460519	6.050	$> 10^{\circ}$	n/a	n/a	$> 10^{\circ}$	n/a
*bug17	107501	1.170	425730	5.130	(.15, .15)	63582	1.355
*bug38	181666	0.745	$> 10^{\circ}$	n/a	n/a	$> 10^{\circ}$	n/a
*bug39	75743	0.390	$> 10^{\circ}$	n/a	n/a	$> 10^{\circ}$	n/a
*bug40	182279	0.890	$> 10^{\circ}$	n/a	n/a	$> 10^{\circ}$	n/a
*bug59	102853	1.080	268332	2.475	(.62, .06)	52276	0.408
unif04-52	5588325	6.065	6763462	5.570	(.4, .07)	4991465	4.295
unif04-62	530432	0.590	768215	0.640	(.49, .03)	386031	0.335
unif04-65	1406786	1.560	1566427	1.315	(.48, .06)	1289658	0.918
unif04-80	3059121	3.575	3751125	3.300	(.45, .1)	1908125	1.760
unif04-83	83/0126	9.930	6589739	5.860	(.43, .09)	4370302	3.112
unit04-86	6288398	/.450	5817258	5.250	(.43, .09)	5429233	2.442
unif04-91	059313	0.780	/89/17	0.730	(.5, .05)	414399	0.324
un1104-99	4054201	4.985	//46102	7.205	(.45, .02)	4931360	4.530
v*1912	3454184	84.115	3683237	/8.625	(.16, 0)	3554771	05.509
v*1915	12928287	409.480	14636382	528.450	(.19, .02)	12510065	288.966
v*1923	1200896	25.030	1358055	16.630	(.42, 0)	1065848	13.386
v*1924	1389813	28.040	1/56/79	29.855	(.21, .04)	1013496	23.019
v*1944	4248279	216.700	4386535	150.67	(.20, 0)	300/138	120.398
V*1955	1404357	56.240	141/356	52.195	(.29, .01)	1152586	28.669
v*1950	1/02389	71.100	1849339	08.303	(.20, .02)	1399232	40.434
v*1959	012589	27.985	180925	32.815	[(.37, .01)]	498563	10.276

Table 2. Performance of $adaptG^2WSAT_P$, $adaptG^2WSAT$, and G^2WSAT with approximately optimal noise settings.

	R+adapt1	Novelty+	$adaptG^2$	VSAT _P	V	W
	#flips	time	#flips	time	#flips	time
bw_large.c†	9489817	29.140	1083947	3.650	1868393	5.960
bw_large.d	27179763	152.160	1542898	8.590	2963500	18.120
3bit*31	152565	1.645	87158	0.780	37487	0.290
3bit*32	133945	1.640	60518	0.565	21858	0.160
e0ddr2*1†	2488226	10.630	4520164	19.275	6549282	22.530
e0ddr2*4†	355044	1.530	641587	2.855	1894243	7.850
enddr2*1†	331420	1.555	982540	4.570	4484178	17.605
enddr2*8†	11753	0.020	412624	2.385	3493986	15.505
ewddr2*1†	154825	0.675	492907	2.470	4714786	18.410
ewddr2*8†	32527	0.100	262177	1.385	4956356	21.785
flat200-1	50600	0.030	36764	0.025	187053	0.085
flat200-2	535300	0.280	288521	0.160	1318485	0.650
flat200-3	161169	0.085	71324	0.045	664550	0.330
flat200-4	577180	0.290	314273	0.180	2747696	1.345
flat200-5	15841761	8.366	4963846	2.675	26137279	13.119
logistics.c†	57693	0.075	54777	0.075	70446	0.085
logistics.d	162737	0.220	83894	0.185	340379	0.395
par16-1†	80339283	37 645	58937999	27.955	$> 10^9$	n/a
par16-2†	324826713	157 455	130634181	64 300	$> 10^9$	n/a
par16-3+	224140856	107.410	104764223	50 865	510^{9}	n/a
par16-4†	274054172	129 660	133899858	63 595	$> 10^{9}$	n/a
par16.5+	264871071	125.000	124873168	50 865	$> 10^{9}$	n/a
ag1 07+	0882	0.015	6/13	0.025	21304	0.055
qg1-07	676122	2 200	261220	4.740	21304	60 225
qg1-08	6147	2.500	301229	4.740	2346200	09.525
qg2-07	2200276	0.010 8 440	1262208	0.020 8.060	9101	0.035
qg2-081	5200270	0.440	1202390	0.125	127254	0.195
qg5-081	105296	0.070	50522	0.125	15/554	0.165
qg4-091	103580	0.105	004/2	0.310	204297	0.303
qg5-11†	50850	0.215	20598	0.210	39907	0.410
qg6-09†	542	0.000	414	0.000	1014	0.000
qg7-09†	551	0.000	392	0.000	1057	207 (20
qg/-13†	5113772	00.080	$> 10^{\circ}$	n/a	8843466	307.620
*bug3	62148492	360.920	$> 10^{\circ}$	n/a	1974994	4.875
*bug4	> 10°	n/a	$> 10^{\circ}$	n/a	177511	0.460
*bug5	66283256	431.395	1460519	6.050	280071	0.735
*bug17	6020734	141.875	107501	1.170	32999	0.275
*bug38	4699436	32.735	181666	0.745	157834	0.385
*bug39	9693455	54.345	75743	0.390	83287	0.220
*bug40	17465338	125.010	182279	0.890	98834	0.290
*bug59	389865	4.150	102853	1.080	66090	0.345
unif04-52†	24720067	21.335	5588325	6.065	22594215	17.115
unif04-62†	1484946	1.280	530432	0.590	3321105	2.605
unif04-65†	9043996	7.885	1406786	1.560	4505318	3.520
unif04-80†	5432957	4.780	3059121	3.575	20083928	16.515
unif04-83†	291310536	255.685	8370126	9.930	25897048	21.590
unif04-86†	38667651	34.045	6288398	7.450	8536496	7.170
unif04-91†	1581843	1.370	659313	0.780	3097695	2.725
unif04-99†	16856278	14.850	4054201	4.985	17422353	15.400
v*1912	6812718	148.735	3454184	84.115	61152892	3037.695
v*1915	78909897	2208.900	12928287	409.480	$> 10^{8}$	n/a
v*1923	2736569	51.662	1200896	25.030	9820793	340.430
v*1924	2931225	60.319	1389813	28.040	13744232	515.720
v*1944	6153990	373.905	4248279	216.700	58541545	7971.731
v*1955	2755333	89.455	1404357	56.240	10396220	1073.960
*1050	2865074	114 685	1762589	71 100	13419375	1437 035
v*1956	2005074	114.005	1702507	/1.100	15117575	1 10 / 10000

Table 3. Experimental results for R+*adaptNovelty*+, *adaptG*²*WSAT*_P, and *VW*.

	prelimi	nary $adaptG^2WSAT_P$	$adaptG^2$	$^{2}WSAT_{P}$
	#flips	time	#flips	time
*bug5	$> 10^8$	n/a	1460519	6.050
*bug17	133691	2.820	107501	1.170
*bug38	$> 10^{8}$	n/a	181666	0.745
*bug39	$> 10^{8}$	n/a	75743	0.390
*bug40	$> 10^{8}$	n/a	182279	0.890
*bug59	179091	4.965	102853	1.080

4.3 Comparison of Performances of $adaptG^2WSAT_P$ and Preliminary $adaptG^2WSAT_P$

Table 4. Experimental results for the preliminary $adaptG^2WSAT_P$ and $adaptG^2WSAT_P$

Our experimental results show that $adaptG^2WSAT_P$ exhibits better performance than the preliminary $adaptG^2WSAT_P$ on some instances from SSS.1.0a presented in Section 2.3. According to our experimental results, on the remaining instances presented in Section 2.3, the overall performance of $adaptG^2WSAT_P$ is close to that of the preliminary $adaptG^2WSAT_P$. Table 4 indicates that $adaptG^2WSAT_P$ exhibits good performance on the 6 instances from SSS.1.0a while the preliminary $adaptG^2WSAT_P$ has difficulty on 4 out of these 6.

5 Conclusion

We have found that the deterministic exploitation of promising decreasing variables can enhance the adaptive noise mechanism in local search for SAT, and thus integrated this adaptive noise mechanism in G^2WSAT to obtain the algorithm $adaptG^2WSAT$. We then have proposed a limited look-ahead approach to favor those flips generating promising decreasing variables to further improve the adaptive noise mechanism. The look-ahead approach is based on the promising scores of variables, meaning that after flipping a variable x, the score of the best promising decreasing variable should be added to the score of x to improve the objective function. The resulting algorithm is called $adaptG^2WSAT_P$.

There are two new parameters in $adaptG^2WSAT_P$, θ and ϕ , which are from adaptNovelty+ and are used to implement the adaptive noise mechanism. However, noise p and random walk probability wp are entirely automatically adapted. Our experimental results confirm that, like θ and ϕ in adaptNovelty+, θ and ϕ in $adaptG^2WSAT_P$ are substantially less sensitive to problem instances and problem types than are p and wp [4], and our results also show that the same fixed default values of θ and ϕ allow $adaptG^2WSAT_P$ to achieve good performances for a broad range of SAT problems. Moreover, our experimental results show that, without any manual noise or other parameter tuning, $adaptG^2WSAT_P$ shows generally good performance, compared with G^2WSAT with approximately optimal static noise settings, or is sometimes even better than G^2WSAT , and that $adaptG^2WSAT_P$ compares favorably with state-of-the-art algorithms such as R+adaptNovelty+ and VW.

We plan to optimize the computation of promising scores, which actually is not incremental. In addition, the efficient implementation techniques of UBCSAT, the variable weight smoothing technique proposed in VW, and the preprocessing used in R+adaptNovelty+ could be integrated into $adaptG^2WSAT_P$.

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