

COMMON FIXED POINTS OF GENERALIZED ALMOST NONEXPANSIVE MAPPINGS

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Abstract

The concept of a generalized almost nonexpansive mappings is introduced and the existence of common fixed points for this new class of mappings is proved. As an application, an invariant approximation result is obtained.

1 Introduction and preliminaries

In 1968, Kannan [12] proved a fixed point theorem for a map satisfying a contractive condition that did not require continuity at each point. This paper was a genesis for a multitude of fixed point papers over the next two decades. Sessa [13] coined the term weakly commuting maps. Jungck [8] generalized the notion of weak commutativity by introducing compatible maps and then weakly compatible maps [10].

The concept of almost contraction property was extended to a pair of selfmaps as follows:

Definition 1.1. Let T and f be two selfmaps of a metric space (X, d) . A map T is called an *almost f -contraction* if there exist a constant $\delta \in]0, 1[$ and some $L \geq 0$ such that

$$d(Tx, Ty) \leq \delta d(fx, fy) + L d(fy, Tx), \quad (1)$$

for all $x, y \in X$. If we choose $f = I_X$, I_X is the identity map on X , we obtain the definition of *almost contraction*, the concept introduced by Berinde ([5], [6]).

This concept was introduced by Berinde as ‘weak contraction’ in [5]. But in [6], Berinde renamed ‘weak contraction’ as ‘almost contraction’ which is appropriate.

It was shown in [5] that any strict contraction, the Kannan [12] and Zamfirescu [14] mappings, as well as a large class of quasi-contractions, are all almost contractions.

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Let T and f be two selfmaps of a metric space (X, d) . T is said to be f -contraction if there exists $k \in [0, 1)$ such that $d(Tx, Ty) \leq kd(fx, fy)$ for all $x, y \in X$. This definition can be obtained directly from (1) if we take $L = 0$.

In 2006, Al-Thagafi and Shahzad [2] proved the following theorem which is a generalization of many known results.

Theorem 1.2 (Al-Thagafi and Shahzad ([2], Theorem 2.1)). Let E be a subset of a metric space (X, d) and f and T be selfmaps of E and $T(E) \subseteq f(E)$. Suppose that f and T are weakly compatible, T is f -contraction and $T(E)$ is complete. Then f and T have a unique common fixed point in E .

Babu, Sandhya and Kameswari [3] considered the class of mappings that satisfy ‘condition (B)’.

Let (X, d) be a metric space. A map $T : X \rightarrow X$ is said to satisfy ‘condition (B)’ if there exist a constant $\delta \in]0, 1[$ and some $L \geq 0$ such that

$$d(Tx, Ty) \leq \delta d(x, y) + L \min\{d(x, Tx), d(y, Ty), d(x, Ty), d(y, Tx)\},$$

for all $x, y \in X$.

Recently, Berinde established the following fixed point result.

Theorem 1.3 (Berinde ([6], Theorem 3.4)). Let (X, d) be a complete metric space and $T : X \rightarrow X$ a mapping for which there exist $\alpha \in]0, 1[$ and some $L \geq 0$ such that for all $x, y \in X$

$$d(Tx, Ty) \leq \alpha M(x, y) + L \min\{d(x, Tx), d(y, Ty), d(x, Ty), d(y, Tx)\}, \quad (2)$$

where, $M(x, y) = \max\{d(x, y), d(x, Tx), d(y, Ty), d(x, Ty), d(y, Tx)\}$. Then

- (1) T has a unique fixed point, i.e., $F(T) = \{x^*\}$;
- (2) for any $x_0 \in X$, the Picard iteration $\{x_n\}_{n=0}^{\infty}$ defined by (1.1) converges to some $x^* \in F(T)$
- (3) the prior estimate

$$d(x_n, x^*) \leq \frac{\alpha^n}{(1 - \alpha)^2} d(x_0, x_1)$$

holds, for $n = 1, 2, \dots$,

- (4) the rate of convergence of Picard iteration is given by

$$d(x_n, x^*) \leq \theta d(x_{n-1}, x^*)$$

for $n = 0, 1, 2, \dots$.

The contractive condition (2) is termed as generalized condition B . We introduce the following definition as follows:

Definition 1.4. Let T and f be two selfmaps of a metric space (X, d) . A map T is called *generalized almost f -contraction* if there exists $\delta \in]0, 1[$ and $L \geq 0$ such that

$$d(Tx, Ty) \leq \delta M(x, y) + L \min\{d(fx, Tx), d(fy, Ty), d(fx, Ty), d(fy, Tx)\} \quad (3)$$

for all $x, y \in X$, where

$$M(x, y) = \max\{d(fx, fy), d(fx, Tx), d(fy, Ty), \frac{d(fx, Ty) + d(fy, Tx)}{2}\}.$$

If $f = I_X$, then we say that T satisfies ‘generalized condition (B)’.

Example 1.5. Let $X = [0, 1)$ with usual metric. Define $T, f : X \rightarrow X$ as

$$T(x) = \begin{cases} \frac{1}{2} & \text{if } 0 \leq x < \frac{2}{3} \\ \frac{2}{3} & \text{if } \frac{2}{3} \leq x < 1 \end{cases}$$

and

$$f(x) = \begin{cases} \frac{5}{6} & \text{if } 0 \leq x < \frac{2}{3} \\ \frac{4}{3} - x & \text{if } \frac{2}{3} \leq x < 1. \end{cases}$$

Here T is generalized almost f -contraction with $\delta = \frac{1}{2}$ and $L = 0$.

But, when $x \in [0, \frac{2}{3})$ and $y = \frac{2}{3}$, we have $d(Tx, Ty) = \frac{1}{6}$; and $d(fx, fy) = \frac{1}{6}$ so that for any $\alpha \in [0, 1)$, T fails to be an f -contraction.

Let Y be a subset of a normed space $(X, \|\cdot\|)$. The set $P_Y(u) = \{x \in Y : \|x - u\| = \text{dist}(u, Y)\}$ is called the *set of best approximants* to $u \in X$ out of Y , where $\text{dist}(u, Y) = \inf\{\|y - u\| : y \in Y\}$. We shall use \mathbb{N} to denote the set of positive integers, $\text{cl}(Y)$ to denote the closure of a set Y and $\text{wcl}(Y)$ to denote the weak closure of a set Y . Let $f : Y \rightarrow Y$ be a mapping. The set of fixed points of T (resp. f) is denoted by $F(T)$ (resp. $F(f)$). A point $x \in Y$ is a *coincidence point* (*common fixed point*) of f and T if $fx = Tx$ ($x = fx = Tx$). The set of coincidence points of f and T is denoted by $C(f, T)$. A pair (f, T) of self-mappings on X is said to be *weakly compatible* if f and T commute at their coincidence point (i.e. $fTx = Tf x$, $x \in X$ whenever $fx = Tx$). A point $y \in X$ is called a *point of coincidence* of two self-mappings f and T on X if there exists a point $x \in X$ such that $y = Tx = fx$.

The set Y is called *q-starshaped* with $q \in Y$, if the segment $[q, x] = \{(1 - k)q + kx : 0 \leq k \leq 1\}$ joining q to x is contained in Y for all $x \in Y$. For further details we refer to [4], [7], [9], [11] and referenced mentioned therein.

Definition 1.6. Let X be a normed space and M be a q -starshaped subset of X . Then a selfmap T of X is said to be generalized almost f -nonexpansive if

$$\begin{aligned} d(Tx, Ty) \leq & \max\{d(fx, fy), \text{dist}(fx, [q, Tx]), \text{dist}(fy, [q, Ty]), \\ & \frac{\text{dist}(fx, [q, Ty]) + \text{dist}(fy, [q, Tx])}{2}\} \\ & + L \min\{\text{dist}(fx, [q, Tx]), \text{dist}(fy, [q, Ty]), \text{dist}(fx, [q, Ty]), \\ & \text{dist}(fy, [q, Tx])\} \end{aligned} \quad (4)$$

for all $x, y \in X$, $L \geq 0$.

Definition 1.7. Let (X, d) be a metric space, T and f be self-mappings on X , with $T(X) \subset f(X)$, and $x_0 \in X$. Choose a point x_1 in X such that $fx_1 = Tx_0$. This can be done since $T(X) \subset f(X)$. Continuing this process having chosen x_1, \dots, x_k , we choose x_{k+1} in X such that

$$fx_{k+1} = Tx_k, \quad k = 0, 1, 2, \dots$$

The sequence $\{fx_n\}$ is called a T -sequence with initial point x_0 .

2 Common fixed point theorems

First, we establish a result on the existence of points of coincidence and common fixed points for two weakly compatible maps. We then, apply this result to obtain common fixed point of generalized almost f -nonexpansive mapping.

Theorem 2.1. Let Y be a nonempty subset of a metric space (X, d) , and f and T be weakly compatible self-maps of Y . Assume that $clT(Y) \subset f(Y)$, $clT(Y)$ is complete, and T is generalized almost f -contraction. Then $Y \cap F(f) \cap F(T)$ is singleton.

Proof As $T(Y) \subseteq f(Y)$, one can choose $\{fx_n\}$ which is a T -sequence with initial point x_0 . For each n , using (3), we have

$$d(Tx_n, Tx_{n+1}) \leq \delta M(x_n, x_{n+1}) + L \min\{d(fx_n, Tx_n), d(fx_{n+1}, Tx_{n+1}), d(fx_n, Tx_{n+1}), d(fx_{n+1}, Tx_n)\} \quad (5)$$

where

$$M(x_n, x_{n+1}) = \max\{d(fx_n, fx_{n+1}), d(fx_n, Tx_n), d(fx_{n+1}, Tx_{n+1}), \frac{d(fx_n, Tx_{n+1}) + d(fx_{n+1}, Tx_n)}{2}\}.$$

Using $Tx_n = fx_{n+1}$ in (5), we obtain

$$\begin{aligned} d(Tx_n, Tx_{n+1}) &\leq \delta \max\{d(Tx_{n-1}, Tx_n), d(Tx_n, Tx_{n+1}), \frac{d(Tx_{n-1}, Tx_{n+1})}{2}\} \\ &= \delta \max\{d(Tx_{n-1}, Tx_n), d(Tx_n, Tx_{n+1})\}. \end{aligned}$$

If for some n , $\max\{d(Tx_{n-1}, Tx_n), d(Tx_n, Tx_{n+1})\} = d(Tx_n, Tx_{n+1})$, then from above inequality we have

$$d(Tx_n, Tx_{n+1}) \leq \delta d(Tx_n, Tx_{n+1}),$$

a contradiction. Therefore

$$d(Tx_n, Tx_{n+1}) \leq \delta d(Tx_{n-1}, Tx_n). \quad (6)$$

From (6), we obtain

$$d(Tx_n, Tx_{n+1}) \leq \delta d_0$$

where $d_0 = d(Tx_0, Tx_1)$. Thus for $m, n \in N$ with $m > n$,

$$\begin{aligned} d(Tx_n, Tx_{m+n}) &\leq d(Tx_n, Tx_{n+1}) + d(Tx_{n+1}, Tx_{n+2}) + \dots + d(Tx_{n+m-1}, Tx_{m+n}) \\ &\quad + (\delta)^n d_0 + (\delta)^{n+1} d_0 + \dots + (\delta)^{n+m-1} d_0. \end{aligned}$$

So

$$d(Tx_n, Tx_{m+n}) \leq \sum_{i=n}^{n+m-1} (\delta)^i d_0.$$

Therefore $\{Tx_n\}$ is a Cauchy sequences in $T(Y)$. It follows from completeness of $clT(Y)$ that $Tx_n \rightarrow w \in clT(Y)$ and hence $fx_n \rightarrow w$ as $n \rightarrow \infty$. Consequently, $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} Tx_n = w \in clT(Y)$. Thus $w = fy$ for some $y \in Y$. Now we show that $fy = Ty$. If not, then for $n \geq 1$, we have

$$d(w, Ty) \leq d(w, Tx_n) + d(Tx_n, Ty) \leq d(w, Tx_n) + \delta M(x_n, y) + L \min\{d(fx_n, Tx_n), d(fy, Ty), d(fx_n, Ty), d(fy, Tx_n)\}, \quad (7)$$

where

$$M(x_n, y) = \max\{d(fx_n, fy), d(fx_n, Tx_n), d(fy, Ty), \frac{d(fx_n, Ty) + d(fy, Tx_n)}{2}\}.$$

Letting $n \rightarrow \infty$, on both side of (7), we obtain

$$d(w, Ty) \leq \delta d(w, Ty)$$

a contradiction. Hence $Ty = w = fy$. We now show the point of coincidence is unique. Suppose that for some $z \in Y$, $fz = Tz$. Then by inequality (3), we get

$$d(fy, fz) = d(Ty, Tz) \leq \delta M(y, z) + L \min\{d(fy, Ty), d(fz, Tz), d(fy, Tz), d(fz, Ty)\}, \quad (8)$$

where

$$M(x, y) = \max\{d(fy, fz), d(fy, Ty), d(fz, Tz), \frac{d(fy, Tz) + d(fz, Ty)}{2}\}.$$

By (8), we have

$$d(fy, fz) \leq \delta d(fy, fz).$$

Hence $fz = fy = Ty$ as $\delta \in (0, 1)$. This implies that the point of coincidence of f and T is unique. Since f and T are weakly compatible and $fy = Ty$, we obtain $TTy = fTy = Tfy$, thereby showing that TTy is a point of coincidence of f and T . By the uniqueness of point of coincidence, we have $TTy = fTy = Ty$; thus Ty is a common fixed point of f and T . Consequently Ty is unique common fixed point of f and T .

Lemma 2.2. Let f and T be self-maps on a nonempty q -starshaped subset Y of a normed space X , f and T are weakly compatible, and T is generalized almost f -nonexpansive with $clT(Y) \subset f(Y)$, define a mapping T_n on Y by

$$T_n x = (1 - \mu_n)q + \mu_n T x,$$

where $\{\mu_n\}$ is a sequence of numbers in $(0, 1)$ such that $\lim_{n \rightarrow \infty} \mu_n = 1$. Then for each $n \geq 1$, T_n and f have exactly one common fixed point x_n in Y such that

$$fx_n = x_n = (1 - \mu_n)q + \mu_n T x_n,$$

provided one of the following conditions hold;

- (i) $cl(T_n(Y))$ is complete for each n ,
- (ii) for each n , $wcl(T_n(Y))$ is complete.

Proof. By definition,

$$T_n x = (1 - \mu_n)q + \mu_n T x.$$

Note that T_n is a self mapping on Y and $clT_n(Y) \subset f(Y)$. Also by (4),

$$\begin{aligned} \|T_n x - T_n y\| &= \mu_n \|T x - T y\| \\ &\leq \mu_n \max\{\|f x - f y\|, \text{dist}(f x, [q, T x]), \text{dist}(f y, [q, T y]), \\ &\quad \frac{\text{dist}(f x, [q, T y]) + \text{dist}(f y, [q, T x])}{2}\} \\ &\quad + \mu_n L \min\{\text{dist}(f x, [q, T x]), \text{dist}(f y, [q, T y]), \text{dist}(f x, [q, T y]), \\ &\quad \text{dist}(f y, [q, T x])\} \\ &\leq \mu_n \max\{\|f x - f y\|, \|f x - T_n x\|, \|f y - T_n y\|, \\ &\quad \frac{\|f x - T_n y\| + \|f y - T_n x\|}{2}\} + \mu_n L \{\|f x - T_n x\|, \|f y - T_n y\|, \\ &\quad \|f x - T_n y\|, \|f y - T_n x\|\} \end{aligned}$$

for each $x, y \in Y$. By Theorem 2.1, for each $n \geq 1$, there exists a unique $x_n \in Y$ such that $x_n = f x_n = T_n x_n$. Thus for each $n \geq 1$, $F(T_n) \cap F(f) \neq \phi$.

(ii) Conclusion follows from Theorem 2.1.

Theorem 2.3. Let f and T be self-maps on a q -starshaped subset Y of a normed space X . Assume that f and T are weakly compatible, T is a generalized almost f -nonexpansive mapping with $clT(Y) \subset f(Y)$. Then $F(T) \cap F(f) \neq \phi$, provided one of the following conditions holds;

- (i) $cl(T(Y))$ is compact and T is continuous;
- (ii) X is complete, f is weakly continuous, $wcl(T(Y))$ is weakly compact and $f - T$ is demiclosed at 0.

Proof.

- (i) Define a mapping T_n on Y by

$$T_n x = (1 - \mu_n)q + \mu_n T x,$$

where $\{\mu_n\}$ is a sequence of numbers in $(0, 1)$ such that $\lim_{n \rightarrow \infty} \mu_n = 1$. Notice that compactness of $cl(T(Y))$ implies that $clT_n(Y)$ is compact and thus complete. From Lemma 2.2, for each $n \geq 1$, there exists $x_n \in Y$ such that $x_n = f x_n = (1 - \mu_n)q + \mu_n T x_n$. Also,

$$\begin{aligned} \|x_n - T x_n\| &= \|(1 - \mu_n)q + \mu_n T x_n - T x_n\| \\ &= (1 - \mu_n)\|q - T x_n\| \rightarrow 0 \end{aligned}$$

as $n \rightarrow \infty$. Since $cl(T(Y))$ is compact, there exists a subsequence $\{Tx_m\}$ of $\{Tx_n\}$ such that $Tx_m \rightarrow y$ as $m \rightarrow \infty$. Now, $x_m = (1 - \mu_m)q + \mu_m Tx_m$ implies that $x_m \rightarrow y$ as $m \rightarrow \infty$. By the continuity of f and T and the fact $\|x_m - Tx_m\| \rightarrow 0$, we have $y \in F(T) \cap F(f)$. Thus $F(T) \cap F(f) \neq \phi$.

- (ii) The weak compactness of $wclT(Y)$ implies that $wclT_n(Y)$ is weakly compact and hence complete due to completeness of X . From Lemma 2.2, for each $n \geq 1$, there exists $x_n \in Y$ such that $x_n = fx_n = T_n x_n = (1 - \mu_n)q + \mu_n Tx_n$. The analysis in (i), implies that $\|x_n - Tx_n\| \rightarrow 0$ as $n \rightarrow \infty$. The weak compactness of $wclT(Y)$ implies that there is a subsequence $\{x_m\}$ of $\{x_n\}$ converging weakly to $y \in Y$ as $m \rightarrow \infty$. Weak continuity of f implies that $fy = y$. Also we have, $fx_m - Tx_m = x_m - Tx_m \rightarrow 0$ as $m \rightarrow \infty$. If $f - T$ is demiclosed at 0, then $fy = Ty$ and hence $F(T) \cap F(f) \neq \phi$.

Following is an invariant approximation result.

Theorem 2.4. Let Y be a subset of a normed space X and $f, T : X \rightarrow X$ be mappings such that $u \in F(f) \cap F(T)$ for some $u \in X$ and $T(\partial Y \cap Y) \subseteq Y$. Suppose that $P_Y(u)$ is nonempty and q -starshaped, f is continuous on $P_Y(u)$, $\|Tx - Tu\| \leq \|fx - fu\|$ for each $x \in P_Y(u)$ and $f(P_Y(u)) \subseteq P_Y(u)$. If T and f are weakly compatible, $F(f)$ is nonempty and q -starshaped for $q \in F(f)$, T is almost generalized f -nonexpansive type then $P_Y(u) \cap F(f) \cap F(T) \neq \phi$, provided one of the following conditions is satisfied;

- (i) T is continuous and $cl(T(P_Y(u)))$ is compact;
- (ii) X is complete, $wcl(T(P_Y(u)))$ is weakly compact, f is weakly continuous and either $f - T$ is demiclosed at $\mathbf{0}$.

Proof. Let $x \in P_Y(u)$. Then for any $h \in (0, 1)$, $\|hu + (1-h)x - u\| = (1-h)\|x - u\| < dist(u, C)$. It follows that the line segment $\{hu + (1-h)x : 0 < h < 1\}$ and the set Y are disjoint. Thus x is not in the interior of Y and so $x \in \partial Y \cap Y$. Since $T(\partial Y \cap Y) \subseteq Y$, Tx must be in Y . Also $fx \in P_Y(u)$, $u \in F(f) \cap F(T)$ and f and T satisfy $\|Tx - Tu\| \leq \|fx - fu\|$, thus we have

$$\|Tx - u\| = \|Tx - Tu\| \leq \|fx - fu\| = \|fx - u\| = dist(u, Y).$$

It further implies that $Tx \in P_Y(u)$. Therefore T is a self map of $P_Y(u)$. The result now follows from Theorem 2.3.

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