# Compact embeddings, eigenvalue problems, and subelliptic Brezis-Nirenberg equations involving singularity on stratified Lie groups 

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#### Abstract

The purpose of this paper is twofold: first we study an eigenvalue problem for the fractional $p$-sub-Laplacian over the fractional Folland-Stein-Sobolev spaces on stratified Lie groups. We apply variational methods to investigate the eigenvalue problems. We conclude the positivity of the first eigenfunction via the strong minimum principle for the fractional $p$-sub-Laplacian. Moreover, we deduce that the first eigenvalue is simple and isolated. Secondly, utilising established properties, we prove the existence of at least two weak solutions via the Nehari manifold technique to a class of subelliptic singular problems associated with the fractional p-sub-Laplacian on stratified Lie groups. We also investigate the boundedness of positive weak solutions to the considered problem via the Moser iteration technique. The results obtained here are also new even for the case $p=2$ with $\mathbb{G}$ being the Heisenberg group.


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## 1 Introduction

The study of nonlocal elliptic partial differential equations (PDEs) and developments of the corresponding tools have been well explored in the Euclidean setting during the last few decades. Apart from the mathematical point of view, the theory of PDEs associated with nonlocal (or fractional) operators witnessed vast applications in different fields of applied sciences. We list a few (in fact a tiny fraction of them) of such applications involving fractional models like the Lévy processes in probability theory, in finance, image processing, in anomalous equations, porous medium equations, Cahn-Hilliard equations and Allen-Cahn equations, etc. Interested readers may refer to $[4,7,73,95]$ and the references therein. These models have been one of the primary context to study nonlocal PDEs both theoretically and numerically.

One of the most important tools to study PDEs over bounded domains is the embeddings of Sobolev spaces into Lebesgue spaces. It says, "If $\Omega \subset \mathbb{R}^{N}$ is open, then for $0<s<1<p<\infty$ with $N>p s$, the fractional Sobolev space $W^{s, p}(\Omega)$ is continuously embedded into $L^{q}(\Omega)$ for all $q \in[1, N p /(N-p s)]$. In addition, if $\Omega$ is bounded and is an extension domain, then the embedding is compact for all $q \in[1, N p /(N-p s))$." The compact embedding plays a crucial role for obtaining the existence of solutions of some PDEs. We refer the readers to see [79] for a well presented study of the fractional Sobolev spaces and the properties of the fractional $p$-Laplacian and its applications to PDEs. One can also consult [19, 39] for the theory and tools developed for the classical Sobolev spaces.

The Sobolev spaces (also known as Folland-Stein spaces) on stratified Lie groups were first considered by Folland [46] and then several further properties have been obtained in the book by Folland and Stein [48]. The reader may refer to several monographs devoted to the study of such spaces and the corresponding subelliptic operators [14, 45, 88]. For Sobolev embeddings of Folland-Stein spaces over bounded domains of stratified Lie groups, we refer to [23]. Recently, the fractional Sobolev type inequality and the corresponding Sobolev embeddings were investigated in [1] for weighted fractional Sobolev spaces on the Heisenberg group $\mathbb{H}^{N}$, whereas in [65], the authors established the fractional Sobolev type inequalities on stratified Lie groups (or homogeneous Carnot groups). In [1], the authors established the compact embeddings of Sobolev spaces $W_{0}^{s, p, \alpha}(\Omega)$ into Lebesgue spaces $L^{p}(\Omega)$ over a bounded extension domain $\Omega \subset \mathbb{H}^{N}$. We recall here the definition of an extension domain: A domain
$\Omega \subset \mathbb{G}$ is said to be an extension domain of $W_{0}^{s, p}(\Omega)$ (see Sect. 2 for the definition) if for every $f \in W_{0}^{s, p}(\Omega)$ there exist a $\tilde{f} \in W_{0}^{s, p}(\mathbb{G})$ such that $\left.\tilde{f}\right|_{\Omega}=f$ and $\|\tilde{f}\|_{W_{0}^{s, p}(\mathbb{G})} \leq C_{Q, s, p, \Omega}\|f\|_{W_{0}^{s, p}(\Omega)}$, where $C_{Q, s, p, \Omega}$ is a positive constant depending only on $Q, s, p, \Omega$. The extension property of a domain plays a crucial role in establishing such compact embeddings of the Sobolev spaces into Lebesgue spaces (cf. Theorem 2.4, Lemma 5.1 in [79]). Recently, Zhou [102] studied the characterizations of $(s, p)$-extension domains and embedding domains for the fractional Sobolev space on $\mathbb{R}^{N}$. To the best of our knowledge, we do not have such characterization for an arbitrary bounded domain in the case of stratified Lie groups. In fact, because of the existence of characteristic points, the problem of finding classes of extension domains in stratified Lie groups is highly non-trival and there are essentially no examples for step 3 and higher (see [24]). Thus, to overcome this issue, we will work with the fractional Sobolev space $X_{0}^{s, p}(\Omega)$ with vanishing trace (See Sect. 2 for the definition).

We first state the following embedding result for the fractional Sobolev space $X_{0}^{s, p}(\Omega)$.
Theorem 1 Let $\mathbb{G}$ be a stratified Lie group of homogeneous dimension $Q$. Let $0<$ $s<1 \leq p<\infty$ and $Q>s p$. Let $\Omega \subset \mathbb{G}$ be an open subset. Then the fractional Sobolev space $X_{0}^{s, p}(\Omega)$ is continuously embedded in $L^{r}(\Omega)$ for $p \leq r \leq p_{s}^{*}$, where $p_{s}^{*}:=\frac{Q p}{Q-s p}$, that is, there exists a positive constant $C=C(Q, s, p, \Omega)$ such that for all $u \in X_{0}^{s, p}(\Omega)$, we have

$$
\|u\|_{L^{r}(\Omega)} \leq C\|u\|_{X_{0}^{s, p}(\Omega)}
$$

Moreover, if $\Omega$ is bounded, then the embedding

$$
\begin{equation*}
X_{0}^{s, p}(\Omega) \hookrightarrow L^{r}(\Omega) \tag{1.1}
\end{equation*}
$$

is continuous for all $r \in\left[1, p_{s}^{*}\right]$ and is compact for all $r \in\left[1, p_{s}^{*}\right)$.
It was pointed out to us by the referee of this paper that there may be a relation between Theorem 1 and the results in the recent paper [12] combined with [68] dealing the fractional Sobolev spaces defined on metric measure spaces satisfying various conditions (typically, but not always, a Poincaré inequality and doubling condition), see also [57] and [56]. One such example of a metric measure space is a stratified Lie group. However, it is not completely clear how the result in [12] applies to our spaces $X_{0}^{s, p}$ since the definition of this space is different. Therefore, for the benefit of readers, we include a simple and direct proof of embedding theorems in Appendix A (Sect. 1) which makes use of group structures such as the group translation and regularisation process via group convolution and dilations for this particular setting of stratified Lie groups. We follow the ideas of [79] to establish the continuous embedding whereas the compact embedding will be proved based on the idea originated by [52]. We also refer $[2,5]$ for embedding results on function spaces defined on spaces of homogeneous type.

In this paper, we now aim to apply Theorem 1 to study the nonlinear Dirichlet eigenvalue problem on stratified Lie groups. The earliest known study of Dirichlet
eigenvalue problems involving the $p$-Laplacian on $\mathbb{R}^{N}$ is due to Lindqvist [72], where the author investigated the simplicity and isolatedness of the first eigenvalue of the following problem:

$$
\begin{gather*}
\Delta_{p} u+v|u|^{p-2} u=0, \text { in } \Omega, \\
u=0 \text { on } \partial \Omega . \tag{1.2}
\end{gather*}
$$

Lindqvist further showed that the first eigenfunction of the problem (1.2) is strictly positive on any arbitrary bounded domain $\Omega$. This study is directly related to the corresponding Rayleigh quotient of the energy given by the following expression:

$$
\begin{equation*}
\mathcal{R}(u):=\frac{\int_{\Omega}|\nabla u|^{p} d x}{\int_{\Omega}|u(x)|^{p} d x}, u \in C_{c}^{\infty}(\Omega) . \tag{1.3}
\end{equation*}
$$

The nonlocal counterpart of the above problem (1.2) was explored by Lindgren and Lindqvist [71], and Franzina and Palatucci [50]. After that, this topic received an extensive attention. For instance, we cite [3, 17, 50, 70, 71] just to mention a few of names toward the development of the eigenvalue problem.

As per our knowledge, the study of eigenvalue problems for the subelliptic setting is very limited in the literature. The earliest traces of such studies are due to [42, 77]. Thereafter, there has been some progress in this direction involving the $p$-subLaplacian on the Heisenberg group, for instance, see [59, 99]. Recently, there is an elevation of interest in the study of eigenvalue problems involving subelliptic operators on stratified Lie groups. We refer to $[27,49,59]$ and the references therein.

In this paper, we study the following nonlinear nonlocal Dirichlet eigenvalue problem involving the fractional $p$-sub-Laplacian on stratified Lie groups,

$$
\begin{align*}
\left(-\Delta_{p, \mathbb{G}}\right)^{s} u & =v|u|^{p-2} u, \text { in } \Omega, \\
u & =0 \text { in } \mathbb{G} \backslash \Omega . \tag{1.4}
\end{align*}
$$

In this direction, we first establish the existence of a minimizer for the Rayleigh quotient, namely, the existence of the first eigenfunction. Then, similar to the classical case, we prove some important properties of the first eigenfunction and the first eigenvalue of the problem (1.4), which are listed below in the form of the following result.

Theorem 2 Let $0<s<1<p<\infty$ and let $\Omega \subset \mathbb{G}$ be a bounded domain of a stratified Lie group $\mathbb{G}$ of homogeneous dimension $Q$. Then for $Q>s p$, we have the following properties.
(i) The first eigenfunction of the problem (1.4) is strictly positive.
(ii) The first eigenvalue $\lambda_{1}$ of the problem (1.4) is simple and the corresponding eigenfunction $\phi_{1}$ is the only eigenfunction of constant sign, that is, if u is an eigenfunction associated to an eigenvalue $v>\lambda_{1}(\Omega)$, then $u$ must be sign-changing.
(iii) The first eigenvalue $\lambda_{1}$ of the problem (1.4) is isolated.

Among the key ingredients to prove Theorem 2 are a strong minimum principle (Theorem 6) and logarithmic estimates (Lemma 4).

Now, as a combined application of Theorem 1 and Theorem 2, we turn our attention to the following problem involving the fractional $p$-sub-Laplacian on the stratified Lie group $\mathbb{G}$ :

$$
\begin{align*}
\left(-\Delta_{p, \mathbb{G}}\right)^{s} u & =\frac{\lambda f(x)}{u^{\delta}}+g(x) u^{q} \text { in } \Omega, \\
u & >0 \text { in } \Omega, \\
u & =0 \text { in } \mathbb{G} \backslash \Omega, \tag{1.5}
\end{align*}
$$

where $\Omega$ is a bounded domain in $\mathbb{G}, \lambda>0,1<p<Q, 0<s, \delta<1<p<$ $q+1<p_{s}^{*}$. Here $Q$ denotes the homogeneous dimension of $\mathbb{G}, p_{s}^{*}:=\frac{Q p}{Q-s p}$ denotes the critical Sobolev exponent, and $\left(-\Delta_{p, \mathbb{G}}\right)^{s}$ is the fractional $p$-sub-Laplacian (ref. Sect. 2). The weight functions $f, g \in L^{\infty}(\Omega)$ are strictly positive.

The problem of the type (1.5) is usually referred to as the Brezis-Nirenberg type problem [21] in the literature. Before we briefly recall some studies done in the Euclidean case, let us first discuss the motivation to consider Brezis-Nirenberg type problem on stratified Lie groups setting. The primary motivation to investigate the Brezis-Nirenberg problem in the classical Euclidean setting (i.e., $p=2$ and $s=1$ ) comes from the fact that it resembles variation problems in differential geometry and physics. One such celebrated example is the Yamabe problem on a Riemannian manifolds. There are many other examples that are directly related to the Brezis-Nirenberg problem; for example, existences of extremal functions for functional inequalities and existence of non-minimal solutions for Yang-Mills functions and $H$-system (see [21]). The pioneering investigation of CR Yamabe problem was started by Jerison and Lee in their seminal work [63]. It is well-known that the Heisenberg group (simplest example of a stratified Lie group) plays the same role in the CR geometry as the Euclidean space in conformal geometry. Naturally, the analysis on stratified Lie groups proved to be a fundamental tool in the resolution of the CR Yamabe problem. Therefore, a great deal of interest has been shown to studying subelliptic PDEs on stratified Lie groups. Recently, several researchers have considered the fractional CR Yamabe problem and problems around it; see [28, 40, 55, 66, 67, 90] and references therein. These aforementioned developments naturally encourage one for studying the Brezis-Nirenberg type problem (1.5) on stratified Lie groups. Apart from this, it is also worth mentioning that the investigation of problems of type (1.5) is closely related to the existence of best constant in functional inequalities, e.g. see [51] and references therein.

On the other hand, it was noted in the celebrated paper [84] by Rothschild and Stein that nilpotent Lie groups play an important role in deriving sharp subelliptic estimates for differential operators on manifolds. In view of the Rothschild-Stein lifting theorem, a general Hörmander's sums of squares of vector fields on manifolds can be approximated by a sup-Laplacian on some stratified Lie group (see also, [47] and [85]). This makes it crucial to study partial differential equations on stratified Lie groups and led to several interesting and promising works amalgamating the Lie group theory with the analysis on partial differential equations. Moreover, in recent
decades, there is a rapidly growing interest for sub-Laplacians on stratified Lie groups because these operators appear not only in theoretical settings (see e.g. Gromov [54] or Danielli, Garofalo and Nhieu [33] for general expositions from different points of view), but also in application settings such as mathematical models of crystal material and human vision (see, [31, 32]).

It is almost impossible to enlist all such studies dealing with existence, multiplicity and regularity of solutions but we will mention some of the pivotal studies that motivated us to consider this problem (1.5) in the subelliptic setting on stratified Lie groups. These studies are primarily divided into two cases, namely, $\lambda=0$ and $\lambda>0$. For $\lambda>0, g=0, p=2, s=1$ and $\delta>0$, i.e., the purely singular problem involving Laplacian was initially tossed up by Crandall et al. [30] following a pseudo-plastic model in the bounded domain $\Omega \subset \mathbb{R}^{N}$ with the Dirichlet boundary condition. Moving forward with the same setting, Lazer and McKenna [69] observed that one can expect a $W_{0}^{1,2}(\Omega)$ solution if and only if $0<\delta<3$. Later, in [100] it was proved that the exponent $\delta=3$ proposed in [69] is optimal to obtain a $W_{0}^{1,2}(\Omega)$ solution. The nonlocal counterparts of these type of PDEs were studied in Canino et al. [22] for all $p \in(1, \infty)$ and $s \in(0,1)$. For further references on the study of purely singular problems we refer to $[13,22]$ and the references therein. It is noteworthy to mention that the problem (1.5) with $g=0$ always possess a unique solution for $\lambda, \delta>0$. The study of the multiplicity and regularity of solutions was widely considered for $\lambda \geq 0$, see $[8,11,37,62,78]$ and the references therein.

We now emphasize the study of the existence of solutions to PDEs associated with subelliptic operators. In [6], the authors established the existence of solutions to the following problem involving the sub-Laplacian on the Heisenberg group:

$$
\begin{align*}
-\Delta_{\mathbb{H}^{N}} u & =\frac{\lambda f(x)}{u^{\delta}} \text { in } \Omega, \\
u & >0 \text { in } \Omega, \\
u & =0 \text { in } \partial \Omega, \tag{1.6}
\end{align*}
$$

They applied the fixed point theorem argument and a weak convergence method to deduce existence of solutions. The nonlinear extension of the aforementioned problem, that is, the singular problem with the $p$-sub-Laplacian was investigated in [51] in the setting of stratified Lie groups for $0<\delta<1$. In both of these studies, the authors used the weak convergence method to establish the existence of solution. In [96], the author considered subelliptic problem associated with sub-Laplacian on the Heisenberg group with mixed singular and power type nonlinearity. They established the existence of solution using the moving plane method. The authors [101] extended this to the Carnot groups. In [58], Han studied existence and nonexistence results for positive solutions to an integral type Brezis-Nirenberg type problem on the Heisenberg groups. Ruzhansky et al. [86] established the global existence and blow-up of the positive solutions to a nonlinear porous medium equation over stratified Lie groups. In [9] the authors characterised the existence of unique positive weak solution for subelliptic Dirichlet problems. A few more results dealing with the existence and multiplicity of solutions over the Heisenberg groups and stratified Lie groups can be found in [10, 15, 41, 44,
$74-76,81-83]$ and references listed therein. Finally, we cite [26,38] and references therein for the study of non-homogeneous fractional $p$-Laplacian on metric measure spaces. The study of existence and multiplicity of weak solutions mainly uses the variational tools, such as mountain pass theorem, Nehari manifold techniques, etc.

In this study we employ the Nehari manifold method [61, 94] to establish the multiplicity of solutions to the problem (1.5). The result is stated as follows.

Theorem 3 Let $\Omega$ be a bounded domain of a stratified Lie group $\mathbb{G}$ of homogeneous dimension $Q$, and let $0<s, \delta<1<p<q+1<p_{s}^{*}:=\frac{Q p}{Q-p s}, Q>p s$. Then there exists $\Lambda>0$ such that for all $\lambda \in(0, \Lambda)$ the problem (1.5) admits at least two non-negative solutions in $X_{0}^{s, p}(\Omega)$.

Let us make a few more comments on results of this paper before concluding the introduction. In this paper, our main focus is to study subelliptic eigenvalue problem and the Brezis-Nirenberg type problem on stratified Lie groups. But, we emphasise that the proofs and statements of Theorems 2 and 3 can easily be adopted with suitable modifications in the case of metric measure space, at least, in case when the metric measure space is doubling and satisfies a Poincaré inequality.

The paper is organized as follows: In the next section we present basics of the analysis on stratified Lie groups along with function spaces defined on them. In Sect. 3, we study the fractional $p$-sub-Laplacian eigenvalue problem on stratified Lie groups. The existence of (at least) two solutions of the nonlocal singular problem by using Nehari manifold technique is analysed in Sect.4. The last section consists of showing the boundedness of solution by employing the Moser iteration followed by a comparison principle.

## 2 Preliminaries: stratified Lie groups and Sobolev spaces

This section is devoted to recapitulating some basic notations and concepts related to stratified Lie groups and the fractional Sobolev spaces defined on them. There are many ways to introduce the notion of stratified Lie groups, for instance one may refer to books and monographs [14, 45, 48, 88]. In his seminal paper [46], Folland extensively investigated the properties of function spaces on these groups. The monographs [45] deals with the theory associated to higher order invariant operators, namely, the Rockland operators on graded Lie groups. For precise studies and properties on stratified Lie group, we refer [14, 45, 46, 48, 52].

Definition 1 A Lie group $\mathbb{G}\left(\right.$ on $\left.\mathbb{R}^{N}\right)$ is said to be homogeneous if, for each $\lambda>0$, there exists an automorphism $D_{\lambda}: \mathbb{G} \rightarrow \mathbb{G}$ defined by $D_{\lambda}(x)=\left(\lambda^{r_{1}} x_{1}, \lambda^{r_{2}} x_{2}, \ldots, \lambda^{r_{N}} x_{N}\right)$ for $r_{i}>0, \forall i=1,2, \ldots, N$. The map $D_{\lambda}$ is called a dilation on $\mathbb{G}$.

For simplicity, we sometimes prefer to use the notation $\lambda x$ to denote the dilation $D_{\lambda} x$. Note that, if $\lambda x$ is a dilation then $\lambda^{r} x$ is also a dilation. The number $Q=r_{1}+r_{2}+\ldots+r_{N}$ is called the homogeneous dimension of the homogeneous Lie group $\mathbb{G}$ and the natural number $N$ represents the topological dimension of $\mathbb{G}$. The Haar measure on $\mathbb{G}$ is denoted by $d x$ and it is nothing but the usual Lebesgue measure on $\mathbb{R}^{N}$.

Definition 2 A homogeneous Lie group $\mathbb{G}=\left(\mathbb{R}^{N}, \circ\right)$ is called a stratified Lie group (or a homogeneous Carnot group) if the following two conditions are fulfilled:
(i) For some natural numbers $N_{1}+N_{2}+\ldots+N_{k}=N$ the decomposition $\mathbb{R}^{N}=$ $\mathbb{R}^{N_{1}} \times \mathbb{R}^{N_{2}} \times \ldots \times \mathbb{R}^{N_{k}}$ holds, and for each $\lambda>0$ there exists a dilation of the form $D_{\lambda}(x)=\left(\lambda x^{(1)}, \lambda^{2} x^{(2)}, \ldots, \lambda^{k} x^{(k)}\right)$ which is an automorphism of the group $\mathbb{G}$. Here $x^{(i)} \in \mathbb{R}^{N_{i}}$ for $i=1,2, \ldots, k$.
(ii) With $N_{1}$ the same as in the above decomposition of $\mathbb{R}^{N}$, let $X_{1}, \ldots, X_{N_{1}}$ be the left invariant vector fields on $\mathbb{G}$ such that $X_{k}(0)=\left.\frac{\partial}{\partial x_{k}}\right|_{0}$ for $k=1, \ldots, N_{1}$. Then the Hörmander condition $\operatorname{rank}\left(\operatorname{Lie}\left\{X_{1}, \ldots, X_{N_{1}}\right\}\right)=N$ holds for every $x \in \mathbb{R}^{N}$. In other words, the Lie algebra corresponding to the Lie group $\mathbb{G}$ is spanned by the iterated commutators of $X_{1}, \ldots, X_{N_{1}}$.

Here $k$ is called the step of the homogeneous Carnot group. Note that, in the case of stratified Lie groups, the homogeneous dimension becomes $Q=\sum_{i=1}^{i=k} i N_{i}$. Furthermore, the left-invariant vector fields $X_{j}$ satisfy the divergence theorem and they can be written explicitly as

$$
\begin{equation*}
X_{i}=\frac{\partial}{\partial x_{i}^{(1)}}+\sum_{j=2}^{k} \sum_{l=1}^{N_{1}} a_{i, l}^{(j)}\left(x^{1}, x^{2}, \ldots, x^{j-1}\right) \frac{\partial}{\partial x_{l}^{(j)}} \tag{2.1}
\end{equation*}
$$

For simplicity, we set $n=N_{1}$ in the above Definition 2.
An absolutely continuous curve $\gamma:[0,1] \rightarrow \mathbb{R}$ is said to be admissible, if there exist functions $c_{i}:[0,1]: \rightarrow \mathbb{R}$, for $i=1,2 \ldots, n$ such that

$$
\dot{\gamma}(t)=\sum_{i=1}^{i=n} c_{i}(t) X_{i}(\gamma(t)) \text { and } \sum_{i=1}^{i=n} c_{i}(t)^{2} \leq 1 .
$$

Observe that the functions $c_{i}$ may not be unique as the vector fields $X_{i}$ may not be linearly independent. For any $x, y \in \mathbb{G}$ the Carnot-Carathéodory distance is defined as

$$
\begin{aligned}
& \rho_{c c}(x, y)=\inf \left\{l>0: \text { there exists an admissible } \gamma:[0, l]^{\prime}\right. \\
& \quad \rightarrow \mathbb{G} \text { with } \gamma(0)=x \& \gamma(l)=y\} .
\end{aligned}
$$

We define $\rho_{c c}(x, y)=0$, if no such curve exists. This $\rho_{c c}$ is not a metric in general but the Hörmander condition for the vector fields $X_{1}, X_{2}, \ldots X_{N_{1}}$ ensures that $\rho_{c c}$ is a metric. The space ( $\mathbb{G}, \rho_{c c}$ ) is is known as a Carnot-Carathéodory space.

Let us now define the quasi-norm on the homogeneous Carnot group $\mathbb{G}$.
Definition 3 A continuous function $|\cdot|: \mathbb{G} \rightarrow \mathbb{R}^{+}$is said to be a homogeneous quasi-norm on a homogeneous Lie group $\mathbb{G}$ if it satisfies the following conditions:
(i) (definiteness): $|x|=0$ if and only if $x=0$.
(ii) (symmetric): $\left|x^{-1}\right|=|x|$ for all $x \in \mathbb{G}$, and
(iii) (1-homogeneous): $|\lambda x|=\lambda|x|$ for all $x \in \mathbb{G}$ and $\lambda>0$.

An example of a quasi-norm on $\mathbb{G}$ is the norm defined as $d(x):=\rho_{c c}(x, 0), x \in \mathbb{G}$, where $\rho$ is a Carnot-Carathéodory distance related to Hörmander vector fields on $\mathbb{G}$. It is known that all homogeneous quasi-norms are equivalent on $\mathbb{G}$. In this paper we will work with a left-invariant homogeneous distance $d(x, y):=\left|y^{-1} \circ x\right|$ for all $x, y \in \mathbb{G}$ induced by the homogeneous quasi-norm of $\mathbb{G}$.

The sub-Laplacian (or Horizontal Laplacian) on $\mathbb{G}$ is defined as

$$
\begin{equation*}
\mathcal{L}:=X_{1}^{2}+\cdots+X_{N_{1}}^{2} . \tag{2.2}
\end{equation*}
$$

The horizontal gradient on $\mathbb{G}$ is defined as

$$
\begin{equation*}
\nabla_{\mathbb{G}}:=\left(X_{1}, X_{2}, \ldots, X_{N_{1}}\right) . \tag{2.3}
\end{equation*}
$$

The horizontal divergence on $\mathbb{G}$ is defined by

$$
\begin{equation*}
\operatorname{div}_{\mathbb{G}} v:=\nabla_{\mathbb{G}} \cdot v \tag{2.4}
\end{equation*}
$$

For $p \in(1,+\infty)$, we define the $p$-sub-Laplacian on the stratified Lie group $\mathbb{G}$ as

$$
\begin{equation*}
\Delta_{\mathbb{G}, p} u:=\operatorname{div}_{\mathbb{G}}\left(\left|\nabla_{\mathbb{G}} u\right|^{p-2} \nabla_{\mathbb{G}} u\right) . \tag{2.5}
\end{equation*}
$$

Let $\Omega$ be a Haar measurable subset of $\mathbb{G}$. Then $\mu\left(D_{\lambda}(\Omega)\right)=\lambda Q^{Q} \mu(\Omega)$ where $\mu(\Omega)$ is the Haar measure of $\Omega$. The quasi-ball of radius $r$ centered at $x \in \mathbb{G}$ with respect to the quasi-norm $|\cdot|$ is defined as

$$
\begin{equation*}
B(x, r)=\left\{y \in \mathbb{G}:\left|y^{-1} \circ x\right|<r\right\} . \tag{2.6}
\end{equation*}
$$

Observe that $B(x, r)$ can be obtained by the left-translation by $x$ of the ball $B(0, r)$. Furthermore, $B(0, r)$ is the image under the dilation $D_{r}$ of $B(0,1)$. Thus, we have $\mu(B(x, r))=r^{Q}$ for all $x \in \mathbb{G}$.

We are now in a position to define the notion of fractional Sobolev-Folland-Stein type spaces related to our study.

Let $\Omega \subset \mathbb{G}$ be an open subset. Then for $0<s<1<p<\infty$, the fractional Sobolev space $W^{s, p}(\Omega)$ on stratified groups is defined as

$$
\begin{equation*}
W^{s, p}(\Omega)=\left\{u \in L^{p}(\Omega):[u]_{s, p, \Omega}<\infty\right\}, \tag{2.7}
\end{equation*}
$$

endowed with the norm

$$
\begin{equation*}
\|u\|_{W^{s, p}(\Omega)}=\|u\|_{L^{p}(\Omega)}+[u]_{s, p, \Omega} \tag{2.8}
\end{equation*}
$$

where $[u]_{s, p, \Omega}$ denotes the Gagliardo semi-norm defined by

$$
\begin{equation*}
[u]_{s, p, \Omega}:=\left(\int_{\Omega} \int_{\Omega} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y\right)^{\frac{1}{p}}<\infty \tag{2.9}
\end{equation*}
$$

Observe that for all $\phi \in C_{c}^{\infty}(\Omega)$, we have $[u]_{s, p, \Omega}<\infty$. We define the space $W_{0}^{s, p}(\Omega)$ as the closure of $C_{c}^{\infty}(\Omega)$ with respect to the norm $\|u\|_{W^{s, p}(\Omega)}$. We would like to point out that $W_{0}^{s, p}(\mathbb{G})=W^{s, p}(\mathbb{G})$.

Now for an open bounded subset $\Omega \subset \mathbb{G}$, define the space $X_{0}^{s, p}(\Omega)$ as the closure of $C_{c}^{\infty}(\Omega)$ with respect to the norm $\|u\|_{L^{p}(\Omega)}+[u]_{s, p, \mathbb{G}}$. Note that the spaces $X_{0}^{s, p}(\Omega)$ and $W_{0}^{s, p}(\Omega)$ are different even in the Euclidean case unless $\Omega$ is an extension domain (see [79]).

Lemma 1 The space $X_{0}^{s, p}(\Omega)$ is a reflexive Banach space for $1<p<\infty$.
The space $X_{0}^{s, p}(\Omega)$ can be equivalently defined with respect to the homogeneous norm $[u]_{s, p, \mathbb{G}}$. Indeed, for $u \in C_{c}^{\infty}(\Omega)$ and $B_{r} \subset \mathbb{G} \backslash \Omega$, we have

$$
\begin{equation*}
|u(x)|^{p}=\left|y^{-1} x\right|^{Q+p s} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} \tag{2.10}
\end{equation*}
$$

for all $x \in \Omega$ and $y \in B_{r}$. Integrating first with respect to $y$ and then with respect to $x$, we obtain,

$$
\begin{equation*}
\int_{\Omega}|u(x)|^{p} d x \leq \frac{\operatorname{diam}\left(\Omega \cup B_{r}\right)^{Q+p s}}{\left|B_{r}\right|} \int_{\Omega} \int_{B_{r}} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y . \tag{2.11}
\end{equation*}
$$

Now define

$$
C=C(Q, s, p, \Omega)=\inf \left\{\frac{\operatorname{diam}(\Omega \cup B)^{Q+p s}}{|B|}: B \subset \mathbb{G} \backslash \Omega \text { is a ball }\right\}
$$

Then we have the following Poincaré type inequality,

$$
\begin{equation*}
\|u\|_{L^{p}(\Omega)}^{p} \leq C[u]_{s, p, \mathbb{G}}^{p} . \tag{2.12}
\end{equation*}
$$

This confirms that the space $X_{0}^{s, p}(\Omega)$ can be defined as a closure of $C_{c}^{\infty}(\Omega)$ with respect to the homogeneous norm $[u]_{s, p, \mathbb{G}}$. That is

$$
\|u\|_{X_{0}^{s, p}(\Omega)} \cong[u]_{s, p, \mathbb{G}} \text { for all } u \in X_{0}^{s, p}(\Omega)
$$

Moreover, the construction of the space $X_{0}^{s, p}(\Omega)$ suggests that by assigning $u=0$ in $\mathbb{G} \backslash \Omega$ for $u \in X_{0}^{s, p}(\Omega)$, we conclude that the inclusion map $i: X_{0}^{s, p}(\Omega) \rightarrow W^{s, p}(\mathbb{G})$ is well-defined and continuous.

Note that, in general $X_{0}^{s, p}(\Omega) \subset\left\{u \in W^{s, p}(\mathbb{G}): u=0\right.$ in $\left.\mathbb{G} \backslash \Omega\right\}$. From the equivalence of the norms and being the closure of $C_{c}^{\infty}(\Omega)$ with respect to the norm $\|\cdot\|_{L^{p}(\Omega)}+[u]_{s, p, \mathbb{G}}$, we can represent $X_{0}^{s, p}(\Omega)$ as follows:

$$
X_{0}^{s, p}(\Omega)=\left\{u \in W^{s, p}(\mathbb{G}): u=0 \text { in } \mathbb{G} \backslash \Omega\right\},
$$

whenever $\Omega$ is bounded with at least continuous boundary $\partial \Omega$. For $u \in X_{0}^{s, p}(\Omega)$,

$$
[u]_{s, p, \mathbb{G}}=\iint_{\mathbb{G} \times \mathbb{G}} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y=\iint_{\mathbb{G} \times \mathbb{G} \backslash\left(\Omega^{c} \times \Omega^{c}\right)} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y .
$$

We conclude this section with the following two definitions. For $s \in(0,1)$ and $p \in(1, \infty)$, we define the fractional $p$-sub-Laplacian as

$$
\begin{equation*}
\left(-\Delta_{p, \mathbb{G}}\right)^{s} u(x):=C_{Q, s, p} P . V \cdot \int_{\mathbb{G}} \frac{|u(x)-u(y)|^{p-2}(u(x)-u(y))}{\left|y^{-1} x\right|^{Q+p s}} d y, \quad x \in \mathbb{G} . \tag{2.13}
\end{equation*}
$$

For any $\varphi \in X_{0}^{s, p}(\Omega)$, we have

$$
\begin{equation*}
\left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u, \varphi\right\rangle=\iint_{\mathbb{G} \times \mathbb{G}} \frac{|u(x)-u(y)|^{p-2}(u(x)-u(y))(\varphi(x)-\varphi(y))}{\left|y^{-1} x\right|^{Q+p s}} d x d y . \tag{2.14}
\end{equation*}
$$

The simplest example of a stratified Lie group is the Heisenberg group $\mathbb{H}^{N}$ with the underlying manifold $\mathbb{R}^{2 N+1}:=\mathbb{R}^{N} \times \mathbb{R}^{N} \times \mathbb{R}$ for $N \in \mathbb{N}$. For $(x, y, t),\left(x^{\prime}, y^{\prime}, t^{\prime}\right) \in$ $\mathbb{H}^{N}$ the multiplication in $\mathbb{H}^{N}$ is given by

$$
(x, y, t) \circ\left(x^{\prime}, y^{\prime}, t^{\prime}\right)=\left(x+x^{\prime}, y+y^{\prime}, t+t^{\prime}+2\left(\left\langle x^{\prime}, y\right\rangle\right)-\left\langle x, y^{\prime}\right\rangle\right)
$$

where $(x, y, t),\left(x^{\prime}, y^{\prime}, t^{\prime}\right) \in \mathbb{R}^{N} \times \mathbb{R}^{N} \times \mathbb{R}$ and $\langle\cdot, \cdot\rangle$ represents the inner product on $\mathbb{R}^{N}$. The homogeneous structure of the Heisenberg group $\mathbb{H}^{N}$ is provided by the following dilation, for $\lambda>0$,

$$
D_{\lambda}(x, y, t)=\left(\lambda x, \lambda y, \lambda^{2} t\right)
$$

the homogeneous dimension $Q$ of $\mathbb{H}^{N}$ is given by $2 N+2:=N+N+2$ while the topological dimension of $\mathbb{H}^{N}$ is $2 N+1$. The left-invariant vector fields $\left\{X_{i}, Y_{i}\right\}_{i=1}^{N}$ defined below form a basis for the Lie algebra corresponding to the Heisenberg group $\mathbb{H}^{N}$ :

$$
\begin{equation*}
X_{i}=\frac{\partial}{\partial x_{i}}+2 y_{i} \frac{\partial}{\partial t} ; Y_{i}=\frac{\partial}{\partial y_{i}}-2 x_{i} \frac{\partial}{\partial t} \text { and } T=\frac{\partial}{\partial t}, \text { for } i=1,2, \ldots, N . \tag{2.15}
\end{equation*}
$$

It is easy to see that $\left[X_{i}, Y_{i}\right]=-4 T$ for $i=1,2, \ldots, N$ and

$$
\left[X_{i}, X_{j}\right]=\left[Y_{i}, Y_{j}\right]=\left[X_{i}, Y_{j}\right]=\left[X_{i}, T\right]=\left[Y_{j}, T\right]=0
$$

for all $i \neq j$ and these vector fields satisfy the Hörmander rank condition. Consequently, the sub-Laplacian on $\mathbb{H}^{N}$ is given by

$$
\mathfrak{L}_{\mathbb{H}^{N}}:=\sum_{i=1}^{N}\left(X_{i}^{2}+Y_{i}^{2}\right) .
$$

## 3 Fractional p-sub-Laplacian eigenvalue problem on stratified Lie groups

This section is devoted to the study of eigenvalue problems associated to the fractional $p$-sub-Laplacian on stratified Lie groups. Let us consider the following PDE on a stratified Lie group $\mathbb{G}$ :

$$
\begin{align*}
\left(-\Delta_{p, \mathbb{G}}\right)^{s} u & =v|u|^{p-2} u, \text { in } \Omega, \\
u & =0 \text { in } \mathbb{G} \backslash \Omega, \tag{3.1}
\end{align*}
$$

where $\nu \in \mathbb{R}$ and $\Omega$ is bounded domain in $\mathbb{G}$. The problem (3.1) is usually referred to as the fractional $p$-sub-Laplacian (or $(s, p)$-sub-Laplacian) eigenvalue problem.

Definition 4 We say that $u \in X_{0}^{s, p}(\Omega)$ is a weak solution to (3.1) if, for each $\phi \in$ $C_{c}^{\infty}(\Omega)$, we have

$$
\begin{equation*}
\left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u, \phi\right\rangle=v \int_{\Omega}|u|^{p-2} u \phi d x . \tag{3.2}
\end{equation*}
$$

A nontrivial solution to (3.2) is known as the ( $s, p$ )-sub-Laplacian eigenfunctions corresponding to an ( $s, p$ )-sub-Laplacian eigenvalue $\nu$.

Such eigenfunctions are directly related to the following minimization problem of the Rayleigh quotient $\mathcal{R}$ defined by

$$
\begin{equation*}
\mathcal{R}(u):=\frac{\iint_{\mathbb{G} \times \mathbb{G}} \frac{|u(x)-u(y)|^{p}}{\left|y y^{-1} x\right| Q+p s} d x d y}{\int_{\Omega}|u(x)|^{p} d x}, u \in C_{c}^{\infty}(\Omega) . \tag{3.3}
\end{equation*}
$$

Observe that a minimizer for the Rayleigh quotient does not change its sign. This follows immediately from the triangle inequality

$$
|u(x)-u(y)|>||u(x)|-| u(y) \| \text { whenever } u(x) u(y)<0 .
$$

Consider the space $\mathcal{S}$ defined as

$$
\begin{equation*}
\mathcal{S}=\left\{u \in X_{0}^{s, p}(\Omega):\|u\|_{p}=1\right\} . \tag{3.4}
\end{equation*}
$$

Then the eigenfunctions of (3.1) are the minimizers of the following energy functional on $\mathcal{S}$ :

$$
\begin{equation*}
I(u)=\iint_{\mathbb{G} \times \mathbb{G}} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y . \tag{3.5}
\end{equation*}
$$

In particular, the eigenfunctions of the problem (3.1) coincides with the critical points of $I$ on the space $\mathcal{S}$.

We define the first eigenvalue or the least eigenvalue $\lambda_{1}(\Omega)$ over $\Omega$ as

$$
\begin{align*}
\lambda_{1}(\Omega)= & \inf \left\{\mathcal{R}(\phi): \phi \in C_{c}^{\infty}(\Omega)\right\}  \tag{3.6}\\
& \text { or } \\
\lambda_{1}(\Omega)= & \inf \{I(u): u \in \mathcal{S}\} . \tag{3.7}
\end{align*}
$$

Recall the Sobolev inequality (6.3) which is given by

$$
\left(\int_{\Omega}|u(x)|^{p^{*}} d x\right)^{\frac{1}{p_{s}^{*}}} \leq C(Q, p, s)\left(\int_{\mathbb{G}} \int_{\mathbb{G}} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y\right)^{\frac{1}{p}}
$$

From the Hölder inequality with the exponent $\frac{p_{s}^{*}}{p}$ and $\frac{p_{s}^{*}}{p_{s}^{*}-p}$ we obtain the following inequality which assures that the first eigenvalue $\lambda_{1}(\Omega)$ of (3.1) is positive:

$$
\begin{equation*}
C(Q, p, s)^{-p}|\Omega|^{-\frac{p s}{Q}} \int_{\Omega}|u(x)|^{p} d x \leq \int_{\mathbb{G}} \int_{\mathbb{G}} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y . \tag{3.8}
\end{equation*}
$$

Thus, by definition all eigenvalues of (3.1) are positive. The weak solution of (3.1) corresponding to $v=\lambda_{1}$ is called the first eigenfunction of (3.1).

We now state the following existence result for the problem (3.1).
Theorem 4 Let $0<s<1<p<\infty$ and let $\Omega$ be a bounded domain of a stratified Lie group $\mathbb{G}$ of homogeneous dimension $Q$. Then for $Q>p s$, there exists a nonnegative minimizer $\phi_{1}$ of (3.5) in $X_{0}^{s, p}(\Omega)$ and $\phi_{1}$ is a weak solution to the problem (3.1) for $\nu=\lambda_{1}(\Omega)$. Moreover, $\phi_{1} \in L^{\infty}(\Omega)$. Furthermore, there exists $C=C(Q, p, s)$ such that $\lambda_{1}(\Omega) \geq C|\Omega|^{-\frac{p s}{Q}}$.

Proof The proof for existence is straightforward from the direct method of the calculus of variations. Suppose $\left\{u_{n}\right\}$ is a minimizing sequence for $I$. Then, by the Sobolev inequality, we have that $\left\{u_{n}\right\}$ is bounded in $X_{0}^{s, p}(\Omega)$. Thanks to the reflexivity of $X_{0}^{s, p}(\Omega)$, we get $\phi_{1} \in X_{0}^{s, p}(\Omega)$ such that up to a subsequence $u_{n} \rightharpoonup \phi_{1}$ weakly in $X_{0}^{s, p}(\Omega)$ and therefore, $u_{n} \rightarrow \phi_{1}$ strongly in $\left(X_{0}^{s, p}(\Omega)\right)^{\prime}:=X_{0}^{-s, p^{\prime}}(\Omega)$. Thus, Theorem 1 implies that $u_{n} \rightarrow \phi_{1}$ strongly in $L^{p}(\Omega)$ and $u_{n} \rightarrow \phi_{1}$ a.e. in $\Omega$ and $u_{n} \rightarrow \phi_{1}$ strongly in $L^{p^{\prime}}(\Omega)$, where $p^{\prime}=\frac{p}{p-1}$. To prove the strong convergence, we show that $\left\|u_{n}\right\|_{X_{0}^{s, p}(\Omega)} \rightarrow\left\|\phi_{1}\right\|_{X_{0}^{s, p}(\Omega)}$. The weak convergence implies that

$$
\begin{equation*}
\left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{n}-\left(-\Delta_{p, \mathbb{G}}\right)^{s} \phi_{1}, u_{n}-\phi_{1}\right\rangle \rightarrow 0 . \tag{3.9}
\end{equation*}
$$

We will use the following inequality from (7.1):

$$
\left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{1}-\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{2}, u_{1}-u_{2}\right\rangle \geq C_{p} \begin{cases}{\left[u_{1}-u_{2}\right]_{s, p}^{p},} & \text { if } p \geq 2  \tag{3.10}\\ \frac{\left[u_{1}-u_{2}\right]_{s, p}^{2}}{\left(\left[u_{1}\right]_{s, p}^{p}+\left[u_{2}\right]_{s, p}^{p}\right)^{\frac{2-p}{p}}}, & \text { if } 1<p<2 .\end{cases}
$$

Thus, by combining these two inequalities (3.9) and (3.10), we obtain $\left\|u_{n}\right\|_{X_{0}^{s, p}(\Omega)} \rightarrow$ $\left\|\phi_{1}\right\|_{X_{0}^{s, p}(\Omega)}$ and therefore, by using the uniform convexity, we conclude $u_{n} \rightarrow \phi_{1}$ strongly in $X_{0}^{s, p}(\Omega)$. In addition to this, we also observe that $I\left(\left|\phi_{1}\right|\right)=I\left(\phi_{1}\right)$. Thus we conclude that the solutions are nonnegative. Indeed, we have

$$
\begin{aligned}
\lambda_{1}(\Omega) & =\inf _{u \in \mathcal{S}} \int_{\mathbb{G}} \int_{\mathbb{G}} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \leq \int_{\mathbb{G}} \int_{\mathbb{G}} \frac{| | \phi_{1}(x)\left|-\left|\phi_{1}(y)\right|^{p}\right.}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \leq \int_{\mathbb{G}} \int_{\mathbb{G}} \frac{\left|\phi_{1}(x)-\phi_{1}(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} \\
& =\lambda_{1}(\Omega) .
\end{aligned}
$$

Thus, $\left|\phi_{1}\right|$ is also minimizes $I$ over $\mathcal{S}$. Therefore, we may conclude that the first eigenfunction of (3.1) can be chosen to be non-negative.

By taking $\lambda=0, g(x)=v$ and $q=p$ in the problem (1.5) and from the Lemma 14 (see Sect.5), we deduce that every solutions of the eigenvalue problem (3.6) are uniformly bounded.

Theorem 5 Let $0<s<1<p<\infty$. Assume that $\Omega \subset \mathbb{G}$ is a bounded domain of a stratified Lie group $\mathbb{G}$. Let $v \in X_{0}^{s, p}(\Omega)$ solve (3.1) and assume that $v>0$, and let $v$ be the corresponding eigenvalue of $v$. Then we have

$$
\begin{equation*}
v=\lambda_{1}(\Omega), \tag{3.11}
\end{equation*}
$$

where $\lambda_{1}(\Omega)=\inf \left\{I(\phi): \phi \in X_{0}^{s, p}(\Omega)\right\}$. In particular, any eigenfunction corresponding to an eigenvalue $\nu>\lambda_{1}(\Omega)$ must be sign-changing.

Proof For every nonnegative $u, v \in X_{0}^{s, p}(\Omega)$, we claim that

$$
\begin{equation*}
I(z(t)) \leq(1-t) I(v)+t I(u), \forall t \in[0,1] \tag{3.12}
\end{equation*}
$$

where $z(t)=\left((1-t) v^{p}(x)+t u^{p}(x)\right)^{1 / p}, \forall t \in[0,1]$. Let us first establish the above inequality. The estimate follows immediately by considering the $\ell_{p}$-norm of $z(t)$ over $\mathbb{R}^{2}$. Observe that

$$
z(t)=\left\|\left(t^{\frac{1}{p}} u,(1-t)^{\frac{1}{p}} v\right)\right\|_{\ell_{p}}
$$

For any $x, y \in \Omega \subset \mathbb{G}$, we first put

$$
a=\left(t^{1 / p} u(y),(1-t)^{1 / p} v(y)\right)
$$

and

$$
b=\left(t^{1 / p} u(x),(1-t)^{1 / p} v(y)\right)
$$

in the following triangle inequality

$$
\left|\|a\|_{\ell_{p}}-\|b\|_{\ell_{p}}\right| \leq\|a-b\|_{\ell_{p}}
$$

and then divide it by the fractional $p$-kernel $\left|y^{-1} x\right|^{Q+p s}$ on both sides followed by integration to obtain the desired inequality (3.12).

We now proceed to prove the main claim of this theorem. Suppose $v \in X_{0}^{s, p}(\Omega)$ and $v>0$ in $\Omega$ is a weak solution of (3.1). Further, by normalizing, if necessary, we may assume that $\|v\|_{p}=1$. Suppose that $u \in X_{0}^{s, p}(\Omega)$ minimizes the problem (3.6). In other words

$$
\lambda_{1}(\Omega)=\min \left\{I(u): u \in X_{0}^{s, p}(\Omega), \int_{\Omega}|u(x)|^{p} d x=1\right\}
$$

is minimized at $u$. Define, $u_{\epsilon}=u+\epsilon, v_{\epsilon}=v+\epsilon$ and for all $x \in \Omega$

$$
z(t, \epsilon)(x)=\left(t u_{\epsilon}(x)^{p}+(1-t) v_{\epsilon}(x)^{p}\right)^{\frac{1}{p}}, t \in[0,1] .
$$

Thanks to the inequality (3.12), the image of $t \mapsto z(t, \epsilon)$ is a family of curves in $X_{0}^{s, p}(\Omega)$ along which the energy $I$ is convex. Thus we have

$$
\begin{align*}
\iint_{\mathbb{G} \times \mathbb{G}} & \frac{|z(t, \epsilon)(x)-z(t, \epsilon)(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y-\iint_{\mathbb{G} \times \mathbb{G}} \frac{|v(x)-v(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \leq t\left(\iint_{\mathbb{G} \times \mathbb{G}} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y-\iint_{\mathbb{G} \times \mathbb{G}} \frac{|v(x)-v(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y\right) \\
& =t\left(\lambda_{1}(\Omega)-v\right), \forall t \in[0,1] \text { and } \forall \epsilon \ll 1 . \tag{3.13}
\end{align*}
$$

Now, using the convexity of $\tau \mapsto|\tau|^{p}$, that is, $\left(|a|^{p}-|b|^{p} \geq p|b|^{p-2} b(a-b)\right)$, we estimate the left hand side of (3.13) from below as follows:

$$
\begin{gather*}
\iint_{\mathbb{G} \times \mathbb{G}} \frac{|z(t, \epsilon)(x)-z(t, \epsilon)(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y-\iint_{\mathbb{G} \times \mathbb{G}} \frac{|v(x)-v(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
\geq p \iint_{\mathbb{G} \times \mathbb{G}} \frac{|v(x)-v(y)|^{p-2}(v(y)-v(x))}{\left|y^{-1} x\right|^{Q+p s}} \\
\quad \times(z(t, \epsilon)(y)-z(t, \epsilon)(x)-(v(y)-v(x))) d x d y \tag{3.14}
\end{gather*}
$$

for all $t \in[0,1]$ and for all $\epsilon \ll 1$.

Observe that, the fact $u, v \in X_{0}^{s, p}(\Omega)$ implies that

$$
z(t, \epsilon) \in X_{0}^{s, p}(\Omega) \text { and } v(y)-v(x)=v_{\epsilon}(y)-v_{\epsilon}(x) .
$$

Thus, on testing (3.2) with $\phi=\left(z(t, \epsilon)-v_{\epsilon}\right)$ corresponding to the eigenfunction $v$, we get, for all $\epsilon \ll 1$,

$$
\begin{align*}
& \iint_{\mathbb{G} \times \mathbb{G}} \frac{|v(x)-v(y)|^{p-2}(v(y)-v(x))}{\left|y^{-1} x\right|^{Q+p s}} \\
& \quad\left(z(t, \epsilon)(y)-z(t, \epsilon)(x)-\left(v_{\epsilon}(y)-v_{\epsilon}(x)\right)\right) d x d y \\
& \quad=v \int_{\Omega} v(\tau)^{p-1}\left(z(t, \epsilon)(\tau)-v_{\epsilon}(\tau)\right) d \tau . \tag{3.15}
\end{align*}
$$

Therefore, from (3.13), (3.14) and (3.15), we obtain

$$
\begin{equation*}
v \int_{\Omega} v(\tau)^{p-1}\left(z(t, \epsilon)(\tau)-v_{\epsilon}(\tau)\right) d \tau \leq t\left(\lambda_{1}(\Omega)-v\right), \tag{3.16}
\end{equation*}
$$

for all $t \in[0,1]$ and for all $\epsilon \ll 1$.
Now, by the concavity $\tau \mapsto|\tau|^{\frac{1}{p}}$ and by recalling that $z(t, \epsilon)(x)=\left(t u_{\epsilon}(x)^{p}\right.$ $\left.+(1-t) v_{\epsilon}(x)^{p}\right)^{\frac{1}{p}}$ we get the following point-wise boundedness a.e. in $\Omega$

$$
\begin{equation*}
v(\tau)^{p-1}\left(z(t, \epsilon)(\tau)-v_{\epsilon}(\tau)\right) \geq t v(\tau)^{p-1}\left(u_{\epsilon}(\tau)-v_{\epsilon}(\tau)\right) \tag{3.17}
\end{equation*}
$$

and

$$
v(\tau)^{p-1}\left(u_{\epsilon}(\tau)-v_{\epsilon}(\tau)\right) \in L^{1}(\Omega) .
$$

Therefore, from Fatou's lemma we obtain

$$
\begin{align*}
& v \int_{\Omega}\left(\frac{v(\tau)}{v_{\epsilon}(\tau)}\right)^{p-1}\left(\left(u_{\epsilon}(\tau)\right)^{p}-\left(v_{\epsilon}(\tau)\right)^{p}\right) d \tau \\
& \quad \leq v \liminf _{t \rightarrow 0^{+}} \int_{\Omega} v(\tau)^{p-1} \frac{z(t, \epsilon)(\tau)-v_{\epsilon}(\tau)}{t} d \tau \\
& \quad \leq \lambda_{1}(\Omega)-v \tag{3.18}
\end{align*}
$$

for sufficiently small $\epsilon>0$.
Finally, recalling that $v>0$ and applying the Lebesgue dominated convergence theorem and then passing the limit $\epsilon \rightarrow 0^{+}$, we get

$$
\begin{equation*}
0 \leq \lambda_{1}(\Omega)-v . \tag{3.19}
\end{equation*}
$$

Since, $\lambda_{1}(\Omega)$ is the least eigenvalue and $\lambda_{1}(\Omega) \geq \nu$, we conclude that $\lambda_{1}(\Omega)=\nu$. Hence, the proof is complete.

Lemma 2 Let $0<s<1<p<\infty$ and let $\Omega \subset \mathbb{G}$ be a bounded domain. Suppose that $u$ and $v$ are two positive eigenfunctions corresponding to $\lambda_{1}(\Omega)$. Then $u=c v$ for some $c>0$, that means, $u$ and $v$ are proportional. This says that the first eigenfunction $\lambda_{1}(\Omega)$ is simple.

Proof Let $u, v \in X_{0}^{s, p}(\Omega)$ be such that $\|u\|_{p}=\|v\|_{p}=1$ and $u, v \geq 0$. Recall the inequality (3.12) for $t=1 / 2$. Then, we have

$$
\begin{equation*}
I\left(\left(\frac{v^{p}+u^{p}}{2}\right)^{1 / p}\right) \leq \frac{I(v)+I(u)}{2} \tag{3.20}
\end{equation*}
$$

Observe that $w=\left(\frac{v^{p}+u^{p}}{2}\right)^{1 / p} \in \mathcal{S}$. Consider the convex function

$$
B(l, m)=\left|l^{\frac{1}{p}}-m^{\frac{1}{p}}\right|^{p} \text { for all } l>0, m>0
$$

Recall from [71, Lemma 13] that

$$
B\left(\frac{l_{1}+l_{2}}{2}, \frac{m_{1}+m_{2}}{2}\right) \leq \frac{1}{2} B\left(l_{1}, m_{1}\right)+\frac{1}{2} B\left(l_{2}, m_{2}\right)
$$

and equality holds only if $l_{1} m_{2}=l_{2} m_{1}$. Thus, using the fact that $u, v, w \in \mathcal{S}$ and (3.20), we obtain

$$
\begin{aligned}
\lambda_{1}(\Omega) & \leq \int_{\mathbb{G}} \int_{\mathbb{G}} \frac{|w(x)-w(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \leq \frac{1}{2} \int_{\mathbb{G}} \int_{\mathbb{G}} \frac{|u(x)-u(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y+\frac{1}{2} \int_{\mathbb{G}} \int_{\mathbb{G}} \frac{|v(x)-v(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y=\lambda_{1}(\Omega) .
\end{aligned}
$$

Therefore, the inequality becomes equality and thus we get

$$
u(x) v(y)=v(x) u(y)
$$

This implies

$$
\frac{u(y)}{v(y)}=\frac{u(x)}{v(x)}=c,(s a y)
$$

Hence, $u=c v$ a.e. in $\Omega$.
Consider the problem

$$
\begin{gather*}
\left(-\Delta_{p, \mathbb{G}}\right)^{s} u=0 \text { in } \Omega \\
u=0 \text { in } \mathbb{G} \backslash \Omega . \tag{3.21}
\end{gather*}
$$

We say a function $u \in X_{0}^{S, p}(\Omega)$ is a weak subsolution (or supersolution) of (3.21), if for every nonnegative $\phi \in X_{0}^{s, p}(\Omega)$, we have

$$
\begin{equation*}
\int_{\mathbb{G}} \int_{\mathbb{G}} \frac{|u(x)-u(y)|^{p-2}(u(x)-u(y))(\phi(x)-\phi(y))}{\left|y^{-1} x\right|^{Q+p s}} d x d y \leq(\text { or } \geq) 0 . \tag{3.22}
\end{equation*}
$$

A function $u \in X_{0}^{s, p}(\Omega)$ is a weak solution of (3.21), if it is a weak subsolution as well as a weak supersolution of (3.22). In particular, for every $\phi \in X_{0}^{s, p}(\Omega), u$ satisfies

$$
\begin{equation*}
\int_{\mathbb{G}} \int_{\mathbb{G}} \frac{|u(x)-u(y)|^{p-2}(u(x)-u(y))(\phi(x)-\phi(y))}{\left|y^{-1} x\right|^{Q+p s}} d x d y=0 . \tag{3.23}
\end{equation*}
$$

We define the nonlocal tail of a function $v \in X_{0}^{s, p}(\Omega)$ in a quasi-ball $B_{R}\left(x_{0}\right) \subset \mathbb{G}$ given by

$$
\begin{equation*}
\operatorname{Tail}\left(v, x_{0}, R\right)=\left[R^{s p} \int_{\mathbb{G} \backslash B_{R}\left(x_{0}\right)} \frac{|v(x)|^{p-1}}{\left|x_{0}^{-1} x\right|^{Q+p s}} d x\right]^{\frac{1}{p-1}} \tag{3.24}
\end{equation*}
$$

Clearly, for any $v \in L^{r}(\mathbb{G}), r \geq p-1$ and $R>0$, we have $\operatorname{Tail}\left(v, x_{0}, R\right)$ is finite, by using the Hölder inequality. For the definitions of the nonlocal tail in the Euclidean space and the Heisenberg group, we refer [35] and [80], respectively.

We state the following comparison principle for fractional $p$-sub-Laplacian on stratified Lie groups. We refer to $[25,29]$ for the strong maximal principle for the subellipic $p$-Laplacian for families of Hörmander vector fields and to [87, 89, 92] for a comparison principle for higher order invariant hypoelliptic operators on graded Lie groups.

Lemma 3 Let $\lambda>0,0<s<1<p<\infty$ and $u, v \in X_{0}^{s, p}(\Omega)$. Suppose that

$$
\left(-\Delta_{p, \mathbb{G}}\right)^{s} v \geq\left(-\Delta_{p, \mathbb{G}}\right)^{s} u
$$

weakly with $v=u=0$ in $\mathbb{G} \backslash \Omega$. Then $v \geq u$ in $\mathbb{G}$.
Proof It immediately follows from the proof of Lemma 13 later on with $\lambda=0$.
The next aim is to establish a minimum principle for the problem (3.21). Prior to that we will prove the following logarithmic estimate which will be used to prove the minimum principle.

Lemma 4 Let $0<s<1<p<\infty$ and let $u \in X_{0}^{s, p}(\Omega)$ be a weak supersolution of (3.21) such that $u \geq 0$ in $B_{R}:=B_{R}\left(x_{0}\right) \subset \Omega$. Then for any $B_{r}:=B_{r}\left(x_{0}\right) \subset B_{\frac{R}{2}}\left(x_{0}\right)$ and for any $d>0$, the following estimate holds:

$$
\begin{align*}
& \int_{B_{r}} \int_{B_{r}}\left|\log \frac{u(x)+d}{u(y)+d}\right|^{p} \frac{d x d y}{\left|y^{-1} x\right|^{Q+p s}} \\
& \quad \leq C r^{Q-p s}\left(d^{1-p}\left(\frac{r}{R}\right)^{s p}\left[\operatorname{Tail}\left(u_{-}, x_{0}, R\right)\right]^{p-1}+1\right), \tag{3.25}
\end{align*}
$$

where $C=C(N, p, s), u_{-}$is the negative part of $u$.
Proof We follow the idea from [36] which is proved for the Euclidean case. Let us first prove an inequality similar to Lemma 3.1 of [36].

Let $p \geq 1$ and $\epsilon \in(0,1]$. Then for any $a, b \in \mathbb{R}$, we have

$$
\begin{equation*}
|a| \leq(|b|+|a-b|) . \tag{3.26}
\end{equation*}
$$

Now, using this triangle inequality and the convexity of $t^{p}$, we obtain

$$
\begin{align*}
|a|^{p} \leq(|b|+|a-b|)^{p} & =(1+\epsilon)^{p}\left[\frac{1}{1+\epsilon}|b|+\frac{\epsilon}{1+\epsilon} \frac{|a-b|}{\epsilon}\right]^{p} \\
& \leq(1+\epsilon)^{p-1}|b|^{p}+\left(\frac{1+\epsilon}{\epsilon}\right)^{p-1}|a-b|^{p} \\
& \leq|b|^{p}+c_{p} \epsilon|b|^{p}+c^{p}\left(1+c_{p} \epsilon\right) \epsilon^{1-p}|a-b|^{p}, \tag{3.27}
\end{align*}
$$

where $c_{p}=(p-1) \Gamma(\max \{1, p-2\})$ is obtained by iterating the last term of the following estimate

$$
(1+\epsilon)^{p-1}=1+(p-1) \int_{1}^{1+\epsilon} t^{p-2} d t \leq 1+\epsilon(p-1) \max \left\{1,(1+\epsilon)^{p-2}\right\}
$$

We will now proceed to prove the main estimate of this lemma. Let $d>0$ and $\eta \in C_{c}^{\infty}(\mathbb{G})$ be such that

$$
\begin{equation*}
0 \leq \eta \leq 1, \quad \eta \equiv 1 \text { in } B_{r}, \quad \eta \equiv 0 \text { in } \mathbb{G} \backslash B_{2 r} \quad \text { and }\left|\nabla_{H} \eta\right|<C r^{-1} \tag{3.28}
\end{equation*}
$$

Since $u(x) \geq 0$ for all $x \in \operatorname{supp}(\eta), \psi=(u+d)^{1-p} \eta^{p}$ is a well-defined test function for (3.23). Thus, we get

$$
\begin{align*}
& \int_{B_{2 r}} \int_{B_{2 r}} \frac{|u(x)-u(y)|^{p-2}(u(x)-u(y))}{\left|y^{-1} x\right|^{Q+p s}}\left[\frac{\eta^{p}(x)}{(u(x)+d)^{p-1}}-\frac{\eta^{p}(y)}{(u(y)+d)^{p-1}}\right] d x d y \\
& +2 \int_{\mathbb{G} \backslash B_{2 r}} \int_{B_{2 r}} \frac{|u(x)-u(y)|^{p-2}(u(x)-u(y))}{\left|y^{-1} x\right|^{Q+p s}} \frac{\eta^{p}(x)}{(u(x)+d)^{p-1}} d x d y=0 . \tag{3.29}
\end{align*}
$$

We will estimate both the terms individually. Set

$$
I_{1}=\int_{B_{2 r}} \int_{B_{2 r}} \frac{|u(x)-u(y)|^{p-2}(u(x)-u(y))}{\left|y^{-1} x\right|^{Q+p s}}
$$

$$
\begin{align*}
& {\left[\frac{\eta^{p}(x)}{(u(x)+d)^{p-1}}-\frac{\eta^{p}(y)}{(u(y)+d)^{p-1}}\right] d x d y }  \tag{3.30}\\
I_{2}= & 2 \int_{\mathbb{G} \backslash B_{2 r}} \int_{B_{2 r}} \frac{|u(x)-u(y)|^{p-2}(u(x)-u(y))}{\left|y^{-1} x\right|^{Q+p s}} \frac{\eta^{p}(x)}{(u(x)+d)^{p-1}} d x d y . \tag{3.31}
\end{align*}
$$

We will first estimate $I_{1}$. Let us assume that $u(x)>u(y)$. Observe that $u(y) \geq 0$ for all $y \in B_{2 r} \subset B_{R}$ using the support of $\eta$. Then on choosing

$$
\begin{equation*}
a=\eta(x), b=\eta(y) \text { and } \epsilon=l \frac{u(x)-u(y)}{u(x)+d} \in(0,1) \text { with } l \in(0,1) \tag{3.32}
\end{equation*}
$$

in the inequality (3.27), it can be estimated that

$$
\begin{align*}
& \frac{|u(x)-u(y)|^{p-2}(u(x)-u(y))}{\left|y^{-1} x\right|^{Q+p s}}\left[\frac{\eta^{p}(x)}{(u(x)+d)^{p-1}}-\frac{\eta^{p}(y)}{(u(y)+d)^{p-1}}\right] \\
& \quad \leq \frac{(u(x)-u(y))^{p-1}}{(u(x)+d)^{p-1}} \frac{\eta^{p}(y)}{\left|y^{-1} x\right|^{Q+p s}}\left[1+c_{p} \frac{u(x)-u(y)}{u(x)+d}-\left(\frac{u(x)+d}{u(y)+d}\right)^{p-1}\right] \\
& \quad+c_{p} l^{1-p} \frac{|\eta(x)-\eta(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} \\
& =\left(\frac{u(x)-u(y)}{u(x)+d}\right)^{p} \frac{\eta^{p}(y)}{\left|y^{-1} x\right|^{Q+p s}}\left[\frac{1-\left(\frac{u(y)+d}{u(x)+d}\right)^{1-p}}{1-\frac{u(y)+d}{u(x)+d}}+c_{p} l\right] \\
& \quad+c_{p} l^{1-p} \frac{|\eta(x)-\eta(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} \\
& :=J_{1}+c_{p} l^{1-p} \frac{|\eta(x)-\eta(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} . \tag{3.33}
\end{align*}
$$

We now aim to estimate $J_{1}$. Consider the following function

$$
h(t):=\frac{1-t^{1-p}}{1-t}=-\frac{p-1}{1-t} \int_{t}^{1} \tau^{-p} d \tau, \quad \forall t \in(0,1) .
$$

Since, the function $h_{1}(t)=\frac{1}{1-t} \int_{t}^{1} \tau^{-p} d \tau$ is decreasing in $t \in(0,1)$, we have $h$ is increasing in $t \in(0,1)$. Thus, we have

$$
h(t) \leq-(p-1), \forall t \in(0,1)
$$

Case-1: $0<t \leq \frac{1}{2}$.
In this case,

$$
h(t) \leq-\frac{p-1}{2^{p}} \frac{t^{1-p}}{1-t} .
$$

For $t=\frac{u(y)+d}{u(x)+d} \in(0,1 / 2]$, i.e. for $u(y)+d \leq \frac{u(x)+d}{2}$, we get

$$
\begin{equation*}
J_{1} \leq\left(c_{p} l-\frac{p-1}{2^{p}}\right)\left[\frac{u(x)-u(y)}{u(y)+d}\right]^{p-1} \frac{\eta^{p}(y)}{\left|y^{-1} x\right|^{Q+p s}}, \tag{3.34}
\end{equation*}
$$

since

$$
(u(x)-u(y))\left(\frac{(u(y)+d)^{p-1}}{(u(x)+d)^{p}}\right)=\left(\frac{u(y)+d}{u(x)+d}\right)^{p-1}-\left(\frac{u(y)+d}{u(x)+d}\right)^{p} \leq 1 .
$$

On choosing $l$ as

$$
\begin{equation*}
l=\frac{p-1}{2^{p+1} c_{p}}\left(=\frac{1}{2^{p+1} \Gamma(\max \{1, p-2\})}<1\right) \tag{3.35}
\end{equation*}
$$

we obtain

$$
J_{1} \leq-\frac{p-1}{2^{p+1}}\left[\frac{u(x)-u(y)}{u(y)+d}\right]^{p-1} \frac{\eta^{p}(y)}{\left|y^{-1} x\right|^{Q+p s}} .
$$

Case-2: $\frac{1}{2}<t<1$.
Again choosing, $t=\frac{u(y)+d}{u(x)+d} \in(1 / 2,1)$, i.e. $u(y)+d>\frac{u(x)+d}{2}$, we obtain

$$
\begin{align*}
J_{1} \leq & {\left[c_{p} l-(p-1)\right]\left[\frac{u(x)-u(y)}{u(x)+d}\right]^{p} \frac{\eta^{p}(y)}{\left|y^{-1} x\right|^{Q+p s}} } \\
& -\frac{\left(2^{p+1}-1\right)(p-1)}{2^{p+1}}\left[\frac{u(x)-u(y)}{u(x)+d}\right]^{p} \frac{\eta^{p}(y)}{\left|y^{-1} x\right|^{Q+p s}} \tag{3.36}
\end{align*}
$$

for the choice of $l$ as in (3.35).
We note that, for $2(u(y)+d)<u(x)+d$, we have

$$
\begin{equation*}
\left[\log \left(\frac{u(x)+d}{u(y)+d}\right)\right]^{p} \leq c_{p}\left[\frac{u(x)-u(y)}{u(y)+d}\right]^{p-1}, \tag{3.37}
\end{equation*}
$$

and, for $2(u(y)+d) \geq u(x)+d$, we derive

$$
\begin{equation*}
\left[\log \left(\frac{u(x)+d}{u(y)+d}\right)\right]^{p}=\left[\log \left(1+\frac{u(x)-u(y)}{u(y)+d}\right)\right]^{p} \leq 2^{p}\left(\frac{u(x)-u(y)}{u(x)+d}\right)^{p} \tag{3.38}
\end{equation*}
$$

by using $u(x)>u(y)$ and $\log (1+x) \leq x, \forall x \geq 0$.
Thus, from the estimates (3.33), (3.34), (3.36), (3.37) and (3.38), we obtain

$$
\frac{|u(x)-u(y)|^{p-2}(u(x)-u(y))}{\left|y^{-1} x\right|^{Q+p s}}\left[\frac{\eta^{p}(x)}{(u(x)+d)^{p-1}}-\frac{\eta^{p}(y)}{(u(y)+d)^{p-1}}\right]
$$

$$
\leq-\frac{1}{c_{p}}\left[\log \left(\frac{u(x)+d}{u(y)+d}\right)\right]^{p} \frac{\eta^{p}(y)}{\left|y^{-1} x\right|^{Q+p s}}+c_{p} l^{1-p} \frac{|\eta(x)-\eta(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}}
$$

This is true also for $u(y)>u(x)$ by exchanging $x$ and $y$. The case $u(x)=u(y)$ holds trivially. Thus, we can estimate $I_{1}$ in (3.30) as

$$
\begin{align*}
I_{1} \leq & -\frac{1}{c(p)} \int_{B_{2 r}} \int_{B_{2 r}}\left|\log \left(\frac{u(x)+d}{u(y)+d}\right)\right|^{p} \frac{\eta^{p}(y)}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& +c(p) \int_{B_{2 r}} \int_{B_{2 r}} \frac{|\eta(x)-\eta(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \tag{3.39}
\end{align*}
$$

for some constant $c(p)$ depending on the choice of $l$.
We will now estimate the term $I_{2}$ in (3.31). Observe that $u(y) \geq 0$ for all $y \in B_{R}$. Thus, using $(u(x)-u(y))_{+} \leq u(x)$, we get

$$
\begin{equation*}
\frac{(u(x)-u(y))_{+}^{p-1}}{(d+u(x))^{p-1}} \leq 1, \forall x \in B_{2 r}, y \in B_{R} \tag{3.40}
\end{equation*}
$$

On the other hand for $y \in \Omega \backslash B_{R}$, we have

$$
\begin{equation*}
(u(x)-u(y))_{+}^{p-1} \leq 2^{p-1}\left[u^{p-1}(x)+(u(y))_{-}^{p-1}\right], \forall x \in B_{2 r} . \tag{3.41}
\end{equation*}
$$

Then using the inequalities (3.40) and (3.41), we obtain

$$
\begin{align*}
I_{2} & \leq 2 \int_{B_{R} \backslash B_{2 r}} \int_{B_{2 r}}(u(x)-u(y))_{+}^{p-1}(d+u(x))^{1-p} \frac{\eta^{p}(x)}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& +2 \int_{\mathbb{G} \backslash B_{R}} \int_{B_{2 r}}(u(x)-u(y))_{+}^{p-1}(d+u(x))^{1-p} \frac{\eta^{p}(x)}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
\leq & C(p) \int_{\mathbb{G} \backslash B_{2 r}} \int_{B_{2 r}} \frac{\eta^{p}(x)}{\left|y^{-1} x\right|^{Q+p s}} d x d y+C^{\prime}(p) d^{1-p} \int_{\mathbb{G} \backslash B_{R}} \int_{B_{2 r}} \frac{(u(y))_{-}^{p-1}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \leq C(p) \sup _{x \in B_{2 r}} r^{Q} \int_{\mathbb{G} \backslash B_{2 r}} \frac{d y}{\left|y^{-1} x\right|^{Q+p s}}+C^{\prime}(p) d^{1-p}\left|B_{r}\right| \int_{\mathbb{G} \backslash B_{R}} \frac{(u(y))_{-}^{p-1}}{\left|y^{-1} x_{0}\right|^{Q+p s}} d y \\
& \leq C(p) r r^{Q-p s}+C^{\prime}(p) d^{1-p} \frac{r^{Q}}{R^{s p}}\left[\text { Tail }\left(u_{-} ; x_{0}, R\right)\right]^{p-1} \\
& \leq C(p) \int_{B_{2 r}} \int_{B_{2 r}} \frac{|\eta(x)-\eta(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y+C(p) r^{Q-p s} \\
& +C^{\prime}(p) d^{1-p} \frac{r^{Q}}{R^{s p}}\left[\text { Tail }\left(u-; x_{0}, R\right)\right]^{p-1}, \tag{3.42}
\end{align*}
$$

for some constants $C(p), C^{\prime}(p)$ depending on $p$.

Therefore, by using (3.39) and (3.42) in (3.29), we get

$$
\begin{align*}
& \int_{B_{2 r}} \int_{B_{2 r}}\left|\log \left(\frac{u(x)+d}{u(y)+d}\right)\right|^{p} \frac{\eta^{p}(y)}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \quad \leq C \int_{B_{2 r}} \int_{B_{2 r}} \frac{|\eta(x)-\eta(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \quad+C d^{1-p_{r} Q} R^{-p s}\left[\text { Tail }\left(u_{-} ; x_{0}, R\right)\right]^{p-1}+C r^{Q-p s} \tag{3.43}
\end{align*}
$$

Again, by using $\left|\nabla_{H} \eta\right| \leq C r^{-1}$, we have

$$
\begin{align*}
& \int_{B_{2 r}} \int_{B_{2 r}} \frac{|\eta(x)-\eta(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \leq C r^{-p} \int_{B_{2 r}} \int_{B_{2 r}}\left|y^{-1} x\right|^{-Q+p(1-s)} d x d y \\
& \quad \leq \frac{C}{p(1-s)} r^{-s p}\left|B_{2 r}\right| \tag{3.44}
\end{align*}
$$

Therefore, the logarithmic estimate (3.25) follows from (3.43) and (3.44).
We have now all the ingredients to state the following strong minimum principle.
Theorem 6 (Strong minimum principle) Let $0<s<1<p<\infty$ and let $\Omega \subset \mathbb{G}$ be an open, connected and bounded subset of a stratified Lie group $\mathbb{G}$. Assume that $u \in X_{0}^{s, p}(\Omega)$ is a weak supersolution of (3.21) such that $u \geq 0$ in $\Omega$ and $u \not \equiv 0$ in $\Omega$. Then $u>0$ a.e. in $\Omega$.

Proof Suppose for a moment that $u>0$ a.e. in $K$ for every connected and compact subset of $\Omega$. Since $\Omega$ is connected and $u \not \equiv 0$ in $\Omega$, there exists a sequence of compact and connected sets $K_{j} \subset \Omega$ such that

$$
\left|\Omega \backslash K_{j}\right|<\frac{1}{j} \text { and } u \not \equiv 0 \text { in } K_{j} .
$$

Thus $u>0$ a.e. in $K_{j}$ for all $j$. Now passing to the limit as $j \rightarrow \infty$, we get that $u>0$ a.e. $\Omega$. Thus it enough to prove the result stated in the lemma for compact and connected subsets of $\Omega$. Since $K \subset \Omega$ is compact and connected, then there exists $r>0$ such that $K \subset\left\{x \in \Omega: \operatorname{dist}_{c c}(x, \partial \Omega)>2 r\right\}$. Again, using the compactness, there exist $x_{i} \in K, i=1,2, \ldots, k$, such that the quasi-balls $B_{r / 2}\left(x_{1}\right), \ldots B_{r / 2}\left(x_{k}\right)$ cover $K$ and

$$
\begin{equation*}
\left|B_{r / 2}\left(x_{i}\right) \cap B_{r / 2}\left(x_{i+1}\right)\right|>0, \quad i=1, \ldots, k-1 . \tag{3.45}
\end{equation*}
$$

Suppose that $u$ vanishes on a subset of $K$ with positive measure. Then with the help of (3.45), we conclude that there exists $i \in\{1, \ldots, k-1\}$ such that

$$
|Z|:=\left|\left\{x \in B_{r / 2}\left(x_{i}\right): u(x)=0\right\}\right|>0 .
$$

For $d>0$ and $x \in B_{r / 2}\left(x_{i}\right)$, define

$$
F_{d}(x)=\log \left(1+\frac{u(x)}{d}\right) .
$$

Observe that for every $x \in Z$ we have

$$
F_{d}(x)=0 .
$$

Thus for every $x \in B_{r / 2}\left(x_{i}\right)$ and $y \in Z$ with $x \neq y$ we get

$$
\left|F_{d}(x)\right|^{p}=\frac{\left|F_{d}(x)-F_{d}(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}}\left|y^{-1} x\right|^{Q+p s} .
$$

Integrating with respect to $y \in Z$, we get

$$
|Z|\left|F_{d}(x)\right|^{p} \leq\left(\max _{x, y \in B_{r / 2}\left(x_{i}\right)}\left|y^{-1} x\right|^{Q+p s}\right) \int_{B_{r / 2}\left(x_{i}\right)} \frac{\left|F_{d}(x)-F_{d}(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d y .
$$

Again integrating with respect to $x \in B_{r / 2}\left(x_{i}\right)$ we deduce the following local Poincaré inequality:

$$
\begin{equation*}
\int_{B_{r / 2}\left(x_{i}\right)}\left|F_{d}\right|^{p} d x \leq \frac{r^{Q+p s}}{|Z|} \int_{B_{r / 2}\left(x_{i}\right)} \int_{B_{r / 2}\left(x_{i}\right)} \frac{\left|F_{d}(x)-F_{d}(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y . \tag{3.46}
\end{equation*}
$$

Observe that

$$
\left|\log \left(\frac{d+u(x)}{d+u(y)}\right)\right|^{p}=\left|F_{d}(x)-F_{d}(y)\right|^{p} .
$$

Plugging the logarithmic estimate (3.25) into the above Poincaré inequality (3.46) by using the fact that $u_{-}=0$ (hence $\operatorname{Tail}\left(u_{-}, x_{i}, R\right)=0$ ), we get

$$
\begin{equation*}
\int_{B_{r / 2}\left(x_{i}\right)}\left|\log \left(1+\frac{u(x)}{d}\right)\right|^{p} d x \leq C \frac{r^{2 Q}}{|Z|} . \tag{3.47}
\end{equation*}
$$

Now taking limit $d \rightarrow 0$ in (3.47), we obtain $u=0$ a.e. in $B_{r / 2}\left(x_{i}\right)$. Thanks to (3.45), by repeating this arguments in the quasi-balls $B_{r / 2}\left(x_{i-1}\right)$ and $B_{r / 2}\left(x_{i+1}\right)$ and so on we obtain that $u \equiv 0$ a.e. on $K$. This is a contradiction and hence $u>0$ a.e. in $K$. This completes the proof.

Lemma 5 Let $0<s<1<p<\infty$. Assume that $\Omega \subset \mathbb{G}$ is a bounded domain. Let $u$ be an eigenfunction of (3.1) corresponding to $v \neq \lambda_{1}(\Omega)$. Then we have $\nu(\Omega)>$ $\lambda_{1}\left(\Omega_{+}\right)$and $\nu\left(\Omega_{)}>\lambda_{1}\left(\Omega_{-}\right)\right.$, where $\Omega_{+}=\{u>0\}$ and $\Omega_{-}=\{u<0\}$. In particular,

$$
\begin{equation*}
v \geq C(N, p, s)\left|\Omega_{+}\right|^{-\frac{p s}{Q}} \text { and } v \geq C(Q, p, s)\left|\Omega_{-}\right|^{-\frac{p s}{Q}} . \tag{3.48}
\end{equation*}
$$

Proof Since $v \neq \lambda_{1}(\Omega)$, then $u$ must be sign-changing. On testing the equation (3.2) with $\phi=u_{+}$we obtain

$$
\begin{aligned}
v \int_{\Omega_{+}}\left|u_{+}\right|^{p} d x \geq & \iint_{\mathbb{G} \times \mathbb{G}} \frac{\left|u_{+}(x)-u_{+}(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& +2^{p / 2} \iint_{\mathbb{G} \times \mathbb{G}} \frac{\left(u_{+}(y) u_{-}(x)\right)^{\frac{p}{2}}}{\left|y^{-1} x\right|^{Q+p s}} d x d y .
\end{aligned}
$$

Dividing both sides by $\int_{\Omega_{+}}\left|u_{+}(x)\right|^{p} d x$, we have

$$
\nu \geq \lambda_{1}\left(\Omega_{+}\right)+2^{p / 2} \frac{\iint_{\mathbb{G} \times \mathbb{G}} \frac{\left(u_{+}(y) u_{-}(x)\right)^{\frac{p}{2}}}{\left|y^{-1} x\right|^{Q+p s}} d x d y}{\int_{\Omega_{+}}\left|u_{+}(x)\right|^{p} d x}
$$

Therefore, we get $v>\lambda_{1}\left(\Omega_{+}\right)$. Inequality (3.8) yields that

$$
\begin{equation*}
v \int_{\Omega_{+}}\left|u_{+}\right|^{p} d x \geq \iint_{\mathbb{G} \times \mathbb{G}} \frac{\left|u_{+}(x)-u_{+}(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \geq C\left|\Omega_{+}\right|^{-\frac{p s}{Q}} \int_{\Omega_{+}}\left|u_{+}(x)\right|^{p} d x \tag{3.49}
\end{equation*}
$$

and dividing by $\int_{\Omega_{+}}\left|u_{+}(x)\right|^{p} d x$ we deduce $v \geq C(N, p, s)\left|\Omega_{+}\right|^{-\frac{p s}{Q}}$.
Similarly, we can deduce $v>\lambda_{1}\left(\Omega_{-}\right)$and $v \geq C\left|\Omega_{-}\right|^{-\frac{p s}{Q}}$. This completes the proof.

Lemma 6 Let $0<s<1<p<\infty$. Assume that $\Omega \subset \mathbb{G}$ is bounded. Then the first eigenvalue $\lambda_{1}(\Omega)$ of (3.1) is isolated.

Proof We will prove it by contradiction. Let $\left\{v_{k}\right\}$ be a sequence of eigenvalues converging to $\lambda_{1}$ such that $v_{k} \neq \lambda_{1}$. Suppose that $u_{k}$ is the eigenfunction corresponding to $v_{k}$. Without loss of generality, we may assume that $\left\|u_{k}\right\|_{p}=1$. Then we have

$$
v_{k}=\int_{\Omega \times \Omega} \frac{\left|u_{k}(x)-u_{k}(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y .
$$

By Theorem 1, there exists $u \in X_{0}^{s, p}(\Omega)$ such that, up to a subsequence

$$
u_{k} \rightarrow u \text { strongly in } L^{p}(\Omega) \text { and } u_{k}(x) \rightarrow u(x) \text { point-wise a.e. in } \Omega .
$$

Then by applying Fatou's lemma, we get

$$
\frac{\iint_{\mathbb{G} \times \mathbb{G}} \frac{|u(y)-u(x)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y}{\int_{\Omega}|u(x)|^{p} d x} \leq \lim _{k \rightarrow \infty} v_{k}=\lambda_{1}(\Omega)
$$

Hence we can conclude that $u$ coincides with the first eigenfunction. Theorem 3 infers that $u$ cannot change sign. Thus either $u>0$ in $\Omega$ or $u<0$ in $\Omega$. Thanks to Theorem 5, we conclude that $u_{k}$ must change signs in $\Omega$, since $\nu_{k}>\lambda_{1}(\Omega)$. Therefore, the sets $\Omega_{ \pm}^{k} \neq \emptyset$ are with positive measure, where

$$
\Omega_{+}^{k}=\left\{x \in \Omega: u_{k}(x)>0\right\} \text { and } \Omega_{-}^{k}=\left\{x \in \Omega: u_{k}(x)<0\right\} .
$$

From the estimate (3.48), we have

$$
v_{k} \geq \lambda_{1}\left(\Omega_{+}^{k}\right) \geq C\left|\Omega_{+}^{k}\right|^{-\frac{p s}{Q}} \text { and } v_{k} \geq \lambda_{1}\left(\Omega_{-}^{k}\right) \geq C\left|\Omega_{-}^{k}\right|^{-\frac{p s}{Q}}
$$

This implies that

$$
\left|\Omega_{ \pm}\right|=\left|\lim \sup \Omega_{ \pm}^{k}\right|>0
$$

Therefore, letting $k \rightarrow \infty$, we get that $u \geq 0$ in $\Omega_{+}$and $u \leq 0$ in $\Omega_{-}$. Thus we arrive at a contradiction that $u$ is a first eigenfunction.

Proof of Theorem 2 The proof immediately follows from the Theorem 2, Lemmas 5 and 6.

## 4 Nehari manifold, weak formulation and multiplicity result

In this section, we use the results established in the previous two sections to study the existence and multiplicity of weak solutions to the nonlocal singular subelliptic problem (1.5). We employ the Nehari manifold technique to establish the multiplicity of solutions. The following subsection is devoted to defining the notion of weak solutions, fibering maps, Nehari manifold and some preliminary results.

### 4.1 Weak solution and geometry of Nehari manifold

Let us now present the notion of a positive weak solution to the problem (1.5).
Definition 5 We say that $u \in X_{0}^{s, p}(\Omega)$ is a positive weak solution of (1.5) if $u>0$ on $\Omega$ (i.e. essinf ${ }_{K} u \geq C_{K}>0$ for all compact subsets $K \subset \Omega$ ) and

$$
\begin{equation*}
\left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u, \psi\right\rangle-\lambda \int_{\Omega} f(x) u^{-\delta} \psi d x-\int_{\Omega} g(x) u^{q} \psi d x=0 \tag{4.1}
\end{equation*}
$$

for all $\psi \in C_{c}^{\infty}(\Omega)$
The energy functional $I_{\lambda}: X_{0}^{s, p}(\Omega) \rightarrow \mathbb{R}$ associated with the problem (1.5) is defined as

$$
\begin{equation*}
I_{\lambda}(u)=\frac{1}{p}\|u\|_{X_{0}^{s, p}(\Omega)}^{p}-\frac{\lambda}{1-\delta} \int_{\Omega} f(x)|u|^{1-\delta} d x-\frac{1}{q+1} \int_{\Omega} g(x)|u|^{q+1} d x . \tag{4.2}
\end{equation*}
$$

We note here that due to the presence of the singular exponent $\delta \in(0,1)$, the functional $I_{\lambda}$ is not Fréchet differentiable. Also, it is not bounded from below in $X_{0}^{s, p}(\Omega)$ as $q>p-1$. The method of Nehari manifold plays an important role to extract critical points of this type of energy functional. We define the Nehari manifold $\mathcal{N}$ for $\lambda>0$ as

$$
\begin{equation*}
\mathcal{N}_{\lambda}:=\left\{u \in X_{0}^{s, p}(\Omega) \backslash\{0\}:\left\langle I_{\lambda}^{\prime}(u), u\right\rangle=0\right\} . \tag{4.3}
\end{equation*}
$$

We set

$$
\begin{equation*}
c_{\lambda}=\inf \left\{I_{\lambda}(u): u \in \mathcal{N}_{\lambda}\right\} . \tag{4.4}
\end{equation*}
$$

It is obvious that $u \in \mathcal{N}_{\lambda}$ if and only if

$$
\begin{equation*}
\|u\|_{X_{0}^{s, p}(\Omega)}^{p}-\lambda \int_{\Omega} f(x)|u|^{1-\delta} d x-\int_{\Omega} g(x)|u|^{q+1} d x=0 . \tag{4.5}
\end{equation*}
$$

In the next result we establish the coerciveness and boundedness of the functional $I_{\lambda}$.
Lemma 7 For each $\lambda>0$, the energy $I_{\lambda}$ is coercive and bounded from below on $\mathcal{N}_{\lambda}$.
Proof By referring to the equations (4.2) and (4.5), we obtain

$$
\begin{align*}
I_{\lambda}(u) & =\frac{1}{p}\|u\|_{X_{0}^{s, p}(\Omega)}^{p}-\frac{\lambda}{1-\delta} \int_{\Omega} f(x)|u|^{1-\delta} d x-\frac{1}{q+1} \int_{\Omega} g(x)|u|^{q+1} d x \\
& =\left(\frac{1}{p}-\frac{1}{q+1}\right)\|u\|_{X_{0}^{s, p}(\Omega)}^{p}-\lambda\left(\frac{1}{1-\delta}-\frac{1}{q+1}\right) \int_{\Omega} f(x)|u|^{1-\delta} d x \\
& \geq\left(\frac{1}{p}-\frac{1}{q+1}\right)\|u\|_{X_{0}^{s, p}(\Omega)}^{p}-c \lambda\|f\|_{\infty}\left(\frac{1}{1-\delta}-\frac{1}{q+1}\right)\|u\|_{X_{0}^{s, p}(\Omega)}^{1-\delta} . \tag{4.6}
\end{align*}
$$

Since $0<1-\delta<1$ and $q+1>p>1$, we conclude that that $I_{\lambda}$ is coercive and bounded from below on $\mathcal{N}_{\lambda}$.

Now, we prove the following lemma proceeding as in the proof given in [62].
Lemma 8 For every non-negative $u \in X_{0}^{s, p}(\Omega)$ there exists a non-negative, increasing sequence $\left\{u_{n}\right\}$ in $X_{0}^{s, p}(\Omega)$ with each $u_{n}$ having compact support in $\Omega$ such that $u_{n} \rightarrow u$ strongly in $X_{0}^{s, p}(\Omega)$.

Proof Take $u \in X_{0}^{s, p}(\Omega)$ and $u \geq 0$. By invoking the density of $C_{c}^{\infty}(\Omega)$ in $X_{0}^{s, p}(\Omega)$, we can choose a sequence $\left\{v_{n}\right\} \subset C_{c}^{\infty}(\Omega)$ converging strongly to $u$ in $X_{0}^{s, p}(\Omega)$ such that $v_{n} \geq 0$ for all $n \in \mathbb{N}$. We now construct another sequence $\left\{w_{n}\right\}$ by $w_{n}=$
$\min \left\{v_{n}, u\right\}$. Then $w_{n} \rightarrow u$ strongly in $X_{0}^{s, p}(\Omega)$. Let $\epsilon>0$. Choose $n_{1}>0$ such that $\left\|w_{n_{1}}-u\right\|<\epsilon$, then $\left\|\max \left\{u_{1}, w_{n}\right\}-u\right\| \rightarrow 0$, where $u_{1}:=w_{n_{1}}$. Again choose, $n_{2}$ such that $\left\|\max \left\{u_{1}, w_{n_{2}}\right\}-u\right\|<\frac{\epsilon}{2}$, then for $u_{2}:=\max \left\{u_{1}, w_{n_{2}}\right\}$ we have $\left\|\max \left\{u_{2}, w_{n}\right\}-u\right\| \rightarrow 0$. Continuing in this way, set $u_{k}=\max \left\{u_{k-1}, w_{n_{k}}\right\}$. Note that each $u_{k}$ is compactly supported and $\left\|u_{k}-u\right\| \leq \frac{\epsilon}{k}$. Thus we can deduce that $\left\|u_{n}-u\right\| \rightarrow 0$ and this is the desired sequence.

For each $u \in X_{0}^{s, p}(\Omega)$, the fiber map $\phi_{u}:(0, \infty) \rightarrow \mathbb{R}$ is defined by $\phi_{u}(t)=$ $I_{\lambda}(t u)$. This fibering map is an important tool to extract the critical points of the energy functional $I_{\lambda}$ which was first coined by Drábek and Pohozaev [37]. Clearly, for $t>0$, we have

$$
\begin{align*}
& \phi_{u}(t)=\frac{t^{p}}{p}\|u\|^{p}-\lambda \frac{t^{1-\delta}}{1-\delta} \int_{\Omega} f(x)|u|^{1-\delta} d x-\frac{t^{q+1}}{q+1} \int_{\Omega} g(x)|u|^{q+1} d x,  \tag{4.7}\\
& \phi_{u}^{\prime}(t)=t^{p-1}\|u\|^{p}-\lambda t^{-\delta} \int_{\Omega} f(x)|u|^{1-\delta} d x-t^{q} \int_{\Omega} g(x)|u|^{q+1} d x, \tag{4.8}
\end{align*}
$$

and

$$
\begin{equation*}
\phi_{u}^{\prime \prime}(t)=(p-1) t^{p-2}\|u\|^{p}+\delta \lambda t^{-\delta-1} \int_{\Omega} f(x)|u|^{1-\delta} d x-q t^{q-1} \int_{\Omega} g(x)|u|^{q+1} d x . \tag{4.9}
\end{equation*}
$$

Observe that $\phi_{u}^{\prime}(t)=\frac{1}{t}\left\langle I_{\lambda}^{\prime}(t u), t u\right\rangle$. Thus $\phi_{u}^{\prime}(t)=0$ if and only if $t u \in \mathcal{N}_{\lambda}$ for some $t>0$ and $u$ is a critical point of $I_{\lambda}$ if and only if $\phi_{u}^{\prime}(1)=0$. Thus it is natural to split $\mathcal{N}_{\lambda}$ into three essential subsets corresponding to local minima, local maxima and points of inflexion.

For this purpose, we define the following three sets

$$
\begin{align*}
\mathcal{N}_{\lambda}^{+} & =\left\{u \in \mathcal{N}_{\lambda}: \phi_{u}^{\prime}(1)=0, \phi_{u}^{\prime \prime}(1)>0\right\} \\
& =\left\{t_{0} u \in \mathcal{N}_{\lambda}: t_{0}>0, \phi_{u}^{\prime}\left(t_{0}\right)=0, \phi_{u}^{\prime \prime}\left(t_{0}\right)>0\right\},  \tag{4.10}\\
\mathcal{N}_{\lambda}^{-} & =\left\{u \in \mathcal{N}_{\lambda}: \phi_{u}^{\prime}(1)=0, \phi_{u}^{\prime \prime}(1)<0\right\} \\
& =\left\{t_{0} u \in \mathcal{N}_{\lambda}: t_{0}>0, \phi_{u}^{\prime}\left(t_{0}\right)=0, \phi_{u}^{\prime \prime}\left(t_{0}\right)<0\right\}, \tag{4.11}
\end{align*}
$$

and

$$
\begin{equation*}
\mathcal{N}_{\lambda}^{0}=\left\{u \in \mathcal{N}_{\lambda}: \phi_{u}^{\prime}(1)=0, \phi_{u}^{\prime \prime}(1)=0\right\} \tag{4.12}
\end{equation*}
$$

Therefore, it is enough to find two members $u \in \mathcal{N}_{\lambda}^{+} \backslash \mathcal{N}_{\lambda}^{0}$ and $v \in \mathcal{N}_{\lambda}^{-} \backslash \mathcal{N}_{\lambda}^{0}$ to establish our result. It is easy to see that only members of the sets $\mathcal{N}_{\lambda}^{ \pm} \backslash \mathcal{N}_{\lambda}^{0}$ are critical points of the energy functional $I_{\lambda}$.

We first introduce the following quantity

$$
\Lambda_{1}=\sup _{u \in X_{0}^{s, p}(\Omega)}\left\{\lambda>0: \phi_{u}(t)(\text { ref. (4.7)) has two critical points in }(0, \infty)\} .\right.
$$

Proposition 1 Under the assumptions on the problem (1.5), we have $0<\Lambda_{1}<\infty$.
To prove Proposition 1 we first prove the following result which ensure that $\Lambda_{1}>0$. We first define the function $m_{u}: \mathbb{R}^{+} \rightarrow \mathbb{R}$ by

$$
\begin{equation*}
m_{u}(t)=t^{p-1+\delta}\|u\|_{X_{0}^{s, p}(\Omega)}^{p}-t^{q+\delta} \int_{\Omega} g(x)|u|^{q+1} d x . \tag{4.13}
\end{equation*}
$$

The function $m_{u}$ will play a crucial role to find a $\lambda_{*}>0$ in the following lemma.
Lemma 9 Under the assumptions on the problem (1.5), there exists $\lambda_{*}>0$ such that, for every $0<\lambda<\lambda_{*}$, we have $\mathcal{N}_{\lambda}^{ \pm} \neq \emptyset$, i.e., there exist unique $t_{1}$ and $t_{2}$ in $(0, \infty)$ with $t_{1}<t_{2}$ such that $t_{1} u \in \mathcal{N}_{\lambda}^{+}$and $t_{2} u \in \mathcal{N}_{\lambda}^{-}$. Moreover, for any $\lambda \in\left(0, \Lambda_{1}\right)$, we have $\mathcal{N}_{\lambda}^{0}=\emptyset$.

Furthermore, $\sup _{u \in \mathcal{N}_{\lambda}^{+}}\|u\|_{X_{0}^{s, p}(\Omega)}<\infty$ and $\inf _{v \in \mathcal{N}_{\lambda}^{-}}\|v\|_{X_{0}^{s, p}(\Omega)}>0$.
Proof Using (4.8) and (4.13) we first deduce that, for $t>0$, we have

$$
\begin{equation*}
\phi_{u}^{\prime}(t)=t^{-\delta}\left(m_{u}(t)-\lambda \int_{\Omega} f(x)|u|^{1-\delta} d x\right) . \tag{4.14}
\end{equation*}
$$

This implies that $\phi_{u}^{\prime}(t)=0$ if and only if $m_{u}(t)-\lambda \int_{\Omega} f(x)|u|^{1-\delta} d x=0$. Referring to (4.13) and $q>p-1$, we note that for $u \neq 0, m_{u}(0)=0$ and $\lim _{t \rightarrow \infty} m_{u}(t)=-\infty$. Thus, one can verify that the function $m_{u}(t)$ attains its maximum at $t=t_{\mathrm{max}}$ given by

$$
\begin{equation*}
t_{\max }=\left[\frac{(p-1+\delta)\|u\|_{X_{0}^{s, p}(\Omega)}^{p}}{(q+\delta) \int_{\Omega} g(x)|u|^{q+1} d x}\right]^{\frac{1}{q+1-p}} . \tag{4.15}
\end{equation*}
$$

The value of $m_{u}$ at $t=t_{\text {max }}$ is given by

$$
\begin{equation*}
m_{u}\left(t_{\max }\right)=\left(\frac{q+2-p}{p-1+\delta}\right)\left(\frac{p-1+\delta}{q+\delta}\right)^{\frac{\delta+q}{q+1-p}} \frac{\|u\|_{X_{0}^{s, p}(\Omega)}^{\frac{p(q+\delta)}{q+1}}}{\left(\int_{\Omega} g(x)|u|^{q+1} d x\right)^{\frac{p-1+\delta}{q+1-p}}} \tag{4.16}
\end{equation*}
$$

In addition, by using the fact that $\lim _{t \rightarrow 0^{+}} m_{u}^{\prime}(t)>0$, we conclude that $m_{u}$ is increasing function on $\left(0, t_{\max }\right)$ and is decreasing function on $\left(t_{\max }, \infty\right)$. Indeed, we have

$$
\begin{aligned}
\frac{m_{u}\left(t_{\max }\right)}{\int_{\Omega} f(x)|u|^{1-\delta} d x}= & \left(\frac{q+2-p}{p-1+\delta}\right)\left(\frac{p-1+\delta}{q+\delta}\right)^{\frac{\delta+q}{\delta+1-p}} \\
& \frac{\|u\|^{\frac{p(q+\delta)}{\delta+1-p}}{ }^{X_{0}^{s, p}(\Omega)}}{\left(\int_{\Omega} g|u|^{q+1} d x\right)^{\frac{p-1+\delta}{q+1-p}}\left(\int_{\Omega} f|u|^{1-\delta} d x\right)}
\end{aligned}
$$

$$
\begin{equation*}
\geq\left(\frac{q+2-p}{p-1+\delta}\right)\left(\frac{p-1+\delta}{q+\delta}\right)^{\frac{\delta+q}{\delta+1-p}} \frac{S_{q+1}^{-\frac{p-1+\delta}{q+1-p}} S_{1-\delta}^{-1}}{\|f\|_{\infty}\|g\|_{\infty}^{\frac{p-1+\delta}{q+1}}}, \tag{4.17}
\end{equation*}
$$

where $S_{\alpha}=\sup \left\{\|u\|_{\alpha}^{\alpha}: u \in X_{0}^{s, p}(\Omega),\|u\|_{X_{0}^{s, p}(\Omega)}=1\right\}$ for $\alpha \geq 0$, i.e. $\int_{\Omega}|u|^{\alpha} d x \leq$ $S_{\alpha}\|u\|_{X_{0}^{s, p}(\Omega)}^{\alpha}$.

Now we set

$$
\begin{equation*}
\lambda_{*}=\left(\frac{q+2-p}{p-1+\delta}\right)\left(\frac{p-1+\delta}{q+\delta}\right)^{\frac{\delta+q}{\delta+1-p}} \frac{S_{q+1}^{-\frac{p-1+\delta}{q+1-p}} S_{1-\delta}^{-1}}{\|f\|_{\infty}\|g\|_{\infty}^{\frac{p-1+\delta}{q+p}}} \tag{4.18}
\end{equation*}
$$

Then, for every $\lambda \in\left(0, \lambda_{*}\right)$, we have

$$
\begin{equation*}
0<\lambda \int_{\Omega} f(x)|u|^{1-\delta} d x \leq m_{u}\left(t_{\max }\right) \tag{4.19}
\end{equation*}
$$

Thus, there exist $t_{1}$ and $t_{2}$ with $0<t_{1}<t_{\max }<t_{2}$ such that

$$
\begin{equation*}
m_{u}\left(t_{1}\right)=m_{u}\left(t_{2}\right)=\lambda \int_{\Omega} f(x)|u|^{1-\delta} d x \tag{4.20}
\end{equation*}
$$

Therefore, we deduce that $\phi_{u}$ decreasing on the set $\left(0, t_{1}\right)$, increasing on $\left(t_{1}, t_{2}\right)$ and again decreasing on $\left(t_{2}, \infty\right)$. So, $\phi_{u}$ has a local maxima at $t=t_{2}$ and a local minima at $t=t_{1}$ such that $t_{2} u \in \mathcal{N}_{\lambda}^{-}$and $t_{1} u \in \mathcal{N}_{\lambda}^{+}$. In particular, we have

$$
\begin{equation*}
I_{\lambda}\left(t_{1}\right)(u)=\min _{0 \leq t \leq t_{\max }} I_{\lambda}(u) \text { and } I_{\lambda}\left(t_{2}\right)(u)=\max _{t \geq 0} I_{\lambda}(u) \tag{4.21}
\end{equation*}
$$

We now intend to prove that $\mathcal{N}_{\lambda}^{0}=\emptyset$. For a moment, we suppose that $u \not \equiv 0$ and $u \in \mathcal{N}_{\lambda}^{0}$, then $u \in \mathcal{N}_{\lambda}$. Therefore, by using the definition of the fibering map $\phi_{u}(t)$, we see that $t=1$ is a critical point. Now, the above arguments imply that the critical points of $\phi_{u}$ are corresponding to a local minima or a local maxima. Thus, we get either $u \in \mathcal{N}_{\lambda}^{+}$or $u \in \mathcal{N}_{\lambda}^{-}$. This contradicts the fact that $u \in \mathcal{N}_{\lambda}^{0}$ and therefore we conclude that $\mathcal{N}_{\lambda}^{0}=\emptyset$.

Finally, we assume that $u \in \mathcal{N}_{\lambda}^{+}$. From (4.9) and $\phi_{u}^{\prime \prime}(1)>0$ we get

$$
(q+1-p)\|u\|_{X_{0}^{s, p}(\Omega)}^{p} \leq \lambda(q+\delta) c_{1}\|f\|_{\infty}\|u\|_{X_{0}^{s, p}(\Omega)}^{1-\delta},
$$

which implies that

$$
\begin{equation*}
\|u\|_{X_{0}^{s, p}(\Omega)} \leq\left(\frac{\lambda(q+\delta) c_{1}\|f\|_{\infty}}{q+1-p}\right)^{\frac{1}{p-1+\delta}} \tag{4.22}
\end{equation*}
$$

Similarly, for $v \in \mathcal{N}_{\lambda}^{-}$, from (4.9) and the fact $\phi_{v}^{\prime \prime}(1)<0$ we obtain

$$
(p-1+\delta)\|v\|_{X_{0}^{s, p}(\Omega)}^{p} \geq(q+\delta) c_{2}\|g\|_{\infty}\|v\|_{X_{0}^{s, p}(\Omega)}^{q+1}
$$

which eventually gives

$$
\begin{equation*}
\|v\|_{X_{0}^{s, p}(\Omega)} \geq\left(\frac{p-1+\delta}{(q+\delta) c_{1}\|g\|_{\infty}}\right)^{\frac{1}{q+1-p}} \tag{4.23}
\end{equation*}
$$

From (4.22) and (4.23), we conclude that

$$
\sup _{u \in \mathcal{N}_{\lambda}^{+}}\|u\|_{X_{0}^{s, p}(\Omega)}<\infty \text { and } \inf _{v \in \mathcal{N}_{\lambda}^{-}}\|v\|_{X_{0}^{s, p}(\Omega)}>0
$$

Lemma 10 Let $u$ be a local minimizer for $I_{\lambda}$ on $\mathcal{N}_{\lambda}^{-}$or $\mathcal{N}_{\lambda}^{+}$such that $u \notin \mathcal{N}_{\lambda}^{0}$. Then $u$ is a critical point of $I_{\lambda}$.

Proof We first introduce the functional $J_{\lambda}(u)=\left\langle I_{\lambda}^{\prime}(u), u\right\rangle$. Then, one can easily verify that $\mathcal{N}_{\lambda}=J_{\lambda}^{-1}(0) \backslash\{0\}$ and

$$
\begin{aligned}
\left\langle J_{\lambda}^{\prime}(u), u\right\rangle & =p\|u\|_{X_{0}^{s, p}(\Omega)}^{p}-\lambda(1-\delta) \int_{\Omega} f(x)|u|_{X_{0}^{s, p}(\Omega)}^{1-\delta} d x-q \int_{\Omega} g(x)|u|^{q+1} d x \\
& =(p-1+\delta)\|u\|^{p}-(q-\delta) \int_{\Omega} h(x)|u|^{q+1} d x, \quad \forall u \in \mathcal{N}_{\lambda}
\end{aligned}
$$

Since $u$ is a local minimizer for $I_{\lambda}$ on $\mathcal{N}_{\lambda}$ we can redefine the minimization problem under the following constrained equation

$$
\begin{equation*}
J_{\lambda}(u)=\left\langle I_{\lambda}^{\prime}(u), u\right\rangle=0 \tag{4.24}
\end{equation*}
$$

Therefore, the method of Lagrange multipliers guarantees the existence of a constant $\kappa \in \mathbb{R}$ such that

$$
J_{\lambda}^{\prime}(u)=\kappa I_{\lambda}^{\prime}(u) .
$$

Thus, we obtain

$$
\left\langle I_{\lambda}^{\prime}(u), u\right\rangle=\kappa\left\langle J_{\lambda}^{\prime}(u), u\right\rangle=\kappa \phi^{\prime \prime}(1)=0 .
$$

Therefore, we conclude that $\kappa=0$ as $u \notin \mathcal{N}_{\lambda}^{0}$. Hence, $u$ is a critical point of $I_{\lambda}$.

### 4.2 Existence of minimizers on $\mathcal{N}_{\lambda}^{+}$and $\mathcal{N}_{\lambda}^{-}$

In this subsection, we will prove the existence of minimizers $u_{\lambda}$ and $v_{\lambda}$ of $I_{\lambda}$ on $\mathcal{N}_{\lambda}^{+}$and $\mathcal{N}_{\lambda}^{-}$which is attained in $\mathcal{N}_{\lambda}^{+}$and $\mathcal{N}_{\lambda}^{-}$respectively. Also, we show that these minimizers are solutions of (1.5) and $u_{\lambda} \neq v_{\lambda}$. We have the following lemma.

Lemma 11 For all $\lambda \in\left(0, \Lambda_{1}\right)$, there exists $u_{\lambda} \in \mathcal{N}_{\lambda}^{+}$such that $I_{\lambda}\left(u_{\lambda}\right)=\inf I_{\lambda}\left(\mathcal{N}_{\lambda}^{+}\right)$. Moreover, $u_{\lambda}$ is a non-negative weak solution to the problem (1.5).

Proof Since the functional $I_{\lambda}$ is bounded below on $\mathcal{N}_{\lambda}$ (hence bounded below on $\mathcal{N}_{\lambda}^{+}$), there exists a sequence $\left\{u_{n}\right\} \subset \mathcal{N}_{\lambda}^{+}$such that $I_{\lambda}\left(u_{n}\right) \rightarrow \inf I_{\lambda}\left(\mathcal{N}_{\lambda}^{+}\right)$as $n \rightarrow+\infty$. Moreover, by using the coercivity of $I_{\lambda}$ and Lemma 9, we have that $\left\{u_{n}\right\}$ is bounded in $X_{0}^{s, p}(\Omega)$ and hence by the reflexiveness of $X_{0}^{s, p}(\Omega)$, there exists $u_{\lambda} \in X_{0}^{s, p}(\Omega)$ such that $u_{n} \rightharpoonup u_{\lambda}$ weakly in $X_{0}^{s, p}(\Omega)$. Thus, by the compact embedding (ref. Theorem 1), we get $u_{n} \rightarrow u_{\lambda}$ strongly in $L^{r}(\Omega)$ for $1 \leq r<p_{s}^{*}$ and $u_{n} \rightarrow u_{\lambda}$ pointwise a.e. in $\Omega$. Our aim is to show $u_{n} \rightarrow u_{\lambda}$ strongly in $X_{0}^{s, p}(\Omega)$. Prior to that we prove that $\inf I_{\lambda}\left(\mathcal{N}_{\lambda}^{+}\right)<0$. Indeed, for $w \in \mathcal{N}_{\lambda}^{+}$, the fiber map $\phi$ has a local minima in $\mathcal{N}_{\lambda}^{+}$and $\phi^{\prime \prime}(1)>0$. Thus, from (4.9), we get

$$
\begin{equation*}
\left(\frac{p-1+\delta}{\delta+q}\right)\|w\|_{X_{0}^{s, p}(\Omega)}^{p}>\int_{\Omega}|w|^{q+1} d x . \tag{4.25}
\end{equation*}
$$

The above inequality (4.25) with the fact that $q>p-1$ retrieves the required claim. In fact, we have

$$
\begin{aligned}
I_{\lambda}(w) & =\left(\frac{1}{p}-\frac{1}{1-\delta}\right)\|w\|_{X_{0}^{s, p}(\Omega)}^{p}+\left(\frac{1}{1-\delta}-\frac{1}{q+1}\right) \int_{\Omega}|w|^{q+1} d x \\
& \leq \frac{(1-\delta-p)}{p(1-\delta)}\|w\|_{X_{0}^{s, p}(\Omega)}^{p}+\frac{(p-1+\delta)}{(q+1)(1-\delta)}\|w\|_{X_{0}^{s, p}(\Omega)}^{p} \\
& =\left(-\frac{1}{p}+\frac{1}{q+1}\right)\left(\frac{p-1+\delta}{1-\delta}\right)\|w\|_{X_{0}^{s, p}(\Omega)}^{p} \\
& =\left(\frac{p-(q+1)}{p(q+1)}\right)\left(\frac{p-1+\delta}{1-\delta}\right)\|w\|_{X_{0}^{s, p}(\Omega)}^{p} \\
& <0
\end{aligned}
$$

We now prove the strong convergence by contradiction. Suppose the strong convergence $u_{n} \rightarrow u_{\lambda}$ in $X_{0}^{s, p}(\Omega)$ fails. Then we have

$$
\begin{equation*}
\left\|u_{\lambda}\right\|_{X_{0}^{s, p}(\Omega)}<\lim \inf _{n \rightarrow \infty}\left\|u_{n}\right\|_{X_{0}^{s, p}(\Omega)} \tag{4.26}
\end{equation*}
$$

Further, by the compact embedding (see Theorem 1), we have

$$
\begin{align*}
& \int_{\Omega} g(x)\left|u_{\lambda}\right|^{q+1} d x=\lim \inf _{n \rightarrow \infty} \int_{\Omega} g(x)\left|u_{n}\right|^{q+1} d x  \tag{4.27}\\
& \int_{\Omega} f(x)\left|u_{\lambda}\right|^{1-\delta} d x=\lim \inf _{n \rightarrow \infty} \int_{\Omega} f(x)\left|u_{n}\right|^{1-\delta} d x \tag{4.28}
\end{align*}
$$

Since $\left\{u_{n}\right\} \subset \mathcal{N}_{\lambda}^{+}$then $\phi^{\prime}(1)=\left\langle I_{\lambda}^{\prime}\left(u_{n}\right), u_{n}\right\rangle=0$. Thus, we get from (4.6) that

$$
\begin{equation*}
I_{\lambda}\left(u_{n}\right) \geq\left(\frac{1}{p}-\frac{1}{q+1}\right)\left\|u_{n}\right\|_{X_{0}^{s, p}(\Omega)}^{p}-c \lambda\|f\|_{\infty}\left(\frac{1}{1-\delta}-\frac{1}{q+1}\right)\left\|u_{n}\right\|_{X_{0}^{s, p}(\Omega)}^{1-\delta} \tag{4.29}
\end{equation*}
$$

Therefore, passing to the limit as $n \rightarrow \infty$, we deduce

$$
\begin{align*}
\inf I_{\lambda}\left(\mathcal{N}_{\lambda}^{+}\right) \geq & \lim _{n \rightarrow \infty}\left(\frac{1}{p}-\frac{1}{q+1}\right)\left\|u_{n}\right\|_{X_{0}^{s, p}(\Omega)}^{p} \\
& -\lim _{n \rightarrow \infty} c \lambda\|f\|_{\infty}\left(\frac{1}{1-\delta}-\frac{1}{q+1}\right)\left\|u_{n}\right\|_{X_{0}^{s, p}(\Omega)}^{1-\delta} \\
> & \left(\frac{1}{p}-\frac{1}{q+1}\right)\left\|u_{\lambda}\right\|_{X_{0}^{s, p}(\Omega)}^{p}-c \lambda\|f\|_{\infty}\left(\frac{1}{1-\delta}-\frac{1}{q+1}\right)\left\|u_{\lambda}\right\|_{X_{0}^{s, p}(\Omega)}^{1-\delta} \\
> & 0, \tag{4.30}
\end{align*}
$$

which is impossible since $\inf I_{\lambda}\left(\mathcal{N}_{\lambda}^{+}\right)<0$. Thus, $u_{n} \rightarrow u_{\lambda}$ strongly in $X_{0}^{s, p}(\Omega)$. Finally, we get $\phi_{u_{\lambda}}^{\prime \prime}(1)>0$ for all $\lambda \in\left(0, \Lambda_{1}\right)$. Hence, we have $u_{\lambda} \in \mathcal{N}_{\lambda}^{+}$and $I_{\lambda}\left(u_{\lambda}\right)=I_{\lambda}\left(\mathcal{N}_{\lambda}^{+}\right)$. Since, $I_{\lambda}\left(u_{\lambda}\right)=I_{\lambda}\left(\left|u_{\lambda}\right|\right)$, we can assume that $u_{\lambda}$ is non-negative. Finally, by the Lemma 10, we deduce that $u_{\lambda}$ is a critical point of $I_{\lambda}\left(u_{\lambda}\right)$ and hence a weak solution to the problem (1.5).

The next lemma guarantees the existence of a minimizer in $\mathcal{N}_{\lambda}^{-}$.
Lemma 12 For all $\lambda \in\left(0, \Lambda_{1}\right)$, there exists $v_{\lambda} \in \mathcal{N}_{\lambda}^{-}$such that $I_{\lambda}\left(v_{\lambda}\right)=\inf I_{\lambda}\left(\mathcal{N}_{\lambda}^{-}\right)$. Moreover, $v_{\lambda}$ is a non-negative weak solution to the problem (1.5).

Proof Proceeding as in the previous Lemma 11, we can assume that there exists a sequence $\left\{v_{n}\right\} \subset \mathcal{N}_{\lambda}^{-}$such that $I_{\lambda}\left(v_{n}\right) \rightarrow \inf I_{\lambda}\left(\mathcal{N}_{\lambda}^{-}\right)$as $n \rightarrow+\infty$ and there exists $v_{\lambda} \in X_{0}^{s, p}(\Omega)$ such that $v_{n} \rightharpoonup v_{\lambda}$ weakly in $X_{0}^{s, p}(\Omega)$. Therefore, the compact embedding (see Theorem 1) guarantees that $v_{n} \rightarrow v_{\lambda}$ strongly in $L^{r}(\Omega)$ for $1 \leq r<p_{s}^{*}$ and $v_{n} \rightarrow v_{\lambda}$ pointwise a.e. in $\Omega$. Let us first prove that inf $I_{\lambda}\left(\mathcal{N}_{\lambda}^{-}\right)>0$. Suppose $z \in \mathcal{N}_{\lambda}$. Therefore, using (4.6), we get

$$
\begin{align*}
I_{\lambda}(z) & \geq\left(\frac{1}{p}-\frac{1}{q+1}\right)\|z\|_{X_{0}^{s, p}(\Omega)}^{p}-c \lambda\|f\|_{\infty}\left(\frac{1}{1-\delta}-\frac{1}{q+1}\right)\|z\|_{X_{0}^{s, p}(\Omega)}^{1-\delta} \\
& =\|z\|_{X_{0}^{s, p}(\Omega)}^{1-\delta}\left(\frac{q+1-p}{p(q+1)}\right)\|z\|_{X_{0}^{s, p}(\Omega)}^{p-1+\delta}-c \lambda\|f\|_{\infty}\left(\frac{q+\delta}{(1-\delta)(q+1)}\right) . \tag{4.31}
\end{align*}
$$

Now, for any $\lambda<\frac{(q+1-p)(1-\delta)}{c p\|f\|_{\infty}}$ in (4.31), we get $I_{\lambda}(z)>0$. Since, $\mathcal{N}_{\lambda}^{+} \cap \mathcal{N}_{\lambda}^{-}=\emptyset$ and $\mathcal{N}_{\lambda}^{+} \cup \mathcal{N}_{\lambda}^{-}=\mathcal{N}_{\lambda}$ (ref. Lemma 9), then we must have $z \in \mathcal{N}_{\lambda}^{-}$. Again, for $z \in \mathcal{N}_{\lambda}^{-}$, there exists $t>0$ such that $\phi_{z}^{\prime}(t z)=I_{\lambda}^{\prime}(t z)<0$, since $1-\delta<1<p<q+1$. This implies $t z \in \mathcal{N}_{\lambda}^{-}$. This is also true for $v_{\lambda}$. We are now in a state to prove the
strong convergence. Suppose the strong convergence $v_{n} \rightarrow v_{\lambda}$ in $X_{0}^{s, p}(\Omega)$ fails. Then proceeding as Lemma 11, we obtain

$$
\begin{equation*}
I_{\lambda}\left(t v_{\lambda}\right) \leq \lim _{n \rightarrow \infty} I_{\lambda}\left(t v_{n}\right) \leq \lim _{n \rightarrow \infty} I_{\lambda}\left(v_{n}\right)=\inf I_{\lambda}\left(\mathcal{N}_{\lambda}^{-}\right) . \tag{4.32}
\end{equation*}
$$

This estimate gives the equality $I_{\lambda}\left(t v_{\lambda}\right)=\inf I_{\lambda}\left(\mathcal{N}_{\lambda}^{-}\right)$, which is a contradiction. Thus, $v_{n} \rightarrow v_{\lambda}$ strongly in $X_{0}^{s, p}(\Omega)$ and $I_{\lambda}\left(v_{\lambda}\right)=I_{\lambda}\left(\mathcal{N}_{\lambda}^{-}\right)$. Since, $I_{\lambda}\left(u_{\lambda}\right)=I_{\lambda}\left(\left|u_{\lambda}\right|\right)$, we can assume that $u_{\lambda}$ is non-negative. Finally, by the Lemma 10 , we deduce that $u_{\lambda}$ is a critical point of $I_{\lambda}\left(u_{\lambda}\right)$ and hence a weak solution to the problem (1.5).

Proof of Proposition 1 Clearly, from Lemma 9, we get $\Lambda_{1}>0$. We will prove the boundedness of $\Lambda_{1}$ by contradiction. Suppose $\Lambda_{1}=+\infty$. Let $\lambda_{1}$ be the first eigenvalue of the problem (3.21) and let $\phi_{1}$ be the corresponding first eigenfunction. Choose $\bar{\lambda}>0$ such that

$$
\begin{equation*}
\frac{\bar{\lambda} f(x)}{t^{\delta}}+g(x) t^{q}>\left(\lambda_{1}+\epsilon\right) t^{p-1} \tag{4.33}
\end{equation*}
$$

for all $t \in(0, \infty), x \in \Omega$ and for some $\epsilon \in(0,1)$. Recall the weak solution $u_{\lambda} \in \mathcal{N}_{\lambda}^{+}$. Then for the above choice of $\bar{\lambda}, \bar{u}:=u_{\bar{\lambda}} \in X_{0}^{s, p}(\Omega)$ is weak supersolution to

$$
\begin{align*}
\left(-\Delta_{p, \mathbb{G}}\right)^{s} u & =\left(\lambda_{1}+\epsilon\right)|u|^{p-2} u \text { in } \Omega, \\
u & =0 \text { in } \mathbb{G} \backslash \Omega . \tag{4.34}
\end{align*}
$$

Then we can choose $r>0$ such that $\underline{u}=r \phi_{1}$ becomes a subsolution to the problem (4.34). Now by using the boundedness of $\phi_{1}$, we can choose a smaller $r>0$ (this choice is possible since $r \phi_{1}$ is a subsolution) such that $\underline{u} \leq \bar{u}$. Now define $w=r \phi_{1}$ and $w_{n} \in X_{0}^{s, p}(\Omega)$ such that

$$
\left(-\Delta_{p, \mathbb{G}}\right)^{s} w_{k}=\left(\lambda_{1}+\epsilon\right)\left|w_{k-1}\right|^{p-2} w_{k-1} \text { in } \Omega .
$$

From Lemma 3, for all $x \in \Omega$ we have

$$
r \phi_{1}=w_{0} \leq w_{1} \leq \ldots \leq w_{k} \leq \ldots \leq u_{\bar{\lambda}}
$$

This shows that $\left\{w_{k}\right\}$ is bounded in $X_{0}^{s, p}(\Omega)$ and hence from the reflexivity, we conclude that $w_{k} \rightharpoonup w$ in $X_{0}^{s, p}(\Omega)$, up to a subsequence. Thus $w$ becomes a weak solution to (4.34). Since $\lambda_{1}+\epsilon>\lambda_{1}$, we arrive at a contradiction to the fact that $\lambda_{1}$ is simple and isolated. Hence, $\Lambda_{1}<\infty$.

Having developed all the necessary tools now we are ready to prove our main result.
Proof of Theorem 3 Set $\Lambda=\min \left\{\lambda_{*}, \Lambda_{1}\right\}$. Then, by using the fact $\mathcal{N}_{\lambda}^{+} \cap \mathcal{N}_{\lambda}^{-}=\emptyset$ and $\mathcal{N}_{\lambda}^{+} \cup \mathcal{N}_{\lambda}^{-}=\mathcal{N}_{\lambda}$ together with Lemma 11 and Lemma 12, we get two solutions $u_{\lambda} \neq v_{\lambda}$ in $\hat{X}_{0}^{s, p}(\Omega)$. In other words, it shows that the problem (1.5) has at least two non-negative solutions for every $\lambda \in(0, \Lambda)$.

## 5 Regularity results for the obtained solutions

In this section we prove that all nonnegative solutions to the problem (1.5) are uniformly bounded. Let us begin with the following weak comparison principle.

Lemma 13 (Weak Comparison Principle) Let $\lambda>0,0<\delta, s<1<p<\infty$ and $u, v \in X_{0}^{s, p}(\Omega)$. Suppose that

$$
\left(-\Delta_{p, \mathbb{G}}\right)^{s} v-\frac{\lambda f(x)}{v^{\delta}} \geq\left(-\Delta_{p, \mathbb{G}}\right)^{s} u-\frac{\lambda f(x)}{u^{\delta}}
$$

weakly with $v=u=0$ in $\mathbb{G} \backslash \Omega$. Then $v \geq u$ in $\mathbb{G}$.
Proof It follows from the statement of the lemma that

$$
\begin{equation*}
\left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} v, \phi\right\rangle-\int_{\Omega} \frac{\lambda \phi}{v} d x \geq\left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u, \phi\right\rangle-\int_{\Omega} \frac{\lambda \phi}{u} d x, \tag{5.1}
\end{equation*}
$$

for all non-negative $\phi \in X_{0}^{s, p}(\Omega)$.
Recall the identity

$$
\begin{equation*}
|b|^{p-2} b-|a|^{p-2} a=(p-1)(b-a) \int_{0}^{1}|a+t(b-a)|^{p-2} d t \tag{5.2}
\end{equation*}
$$

and define,

$$
\begin{equation*}
Q(x, y)=\int_{0}^{1}|(u(x)-u(y))+t((v(x)-v(y))-(u(x)-u(y)))|^{p-2} d t . \tag{5.3}
\end{equation*}
$$

Then, by choosing $a=v(x)-v(y), b=u(x)-u(y)$ we have

$$
\begin{align*}
& |u(x)-u(y)|^{p-2}(u(x)-u(y))-|v(x)-v(y)|^{p-2}(u(x)-u(y)) \\
& \quad=(p-1)\{(u(y)-v(y))-(u(x)-v(x))\} Q(x, y) . \tag{5.4}
\end{align*}
$$

Set $\psi=u-v=(u-v)_{+}-(u-v)_{-}$, where $(u-v)_{ \pm}=\max \{ \pm(u-v), 0\}$. Then, for $\phi=(u-v)^{+}$we obtain

$$
\begin{equation*}
[\psi(x)-\psi(y)][\phi(x)-\phi(y)]=\left(\psi^{+}(x)-\psi^{+}(y)\right)^{2} \geq 0 \tag{5.5}
\end{equation*}
$$

Therefore, the inequality (5.5) together with the test function $\phi=\left(u-v_{+}\right)$yields that

$$
\begin{aligned}
0 & \geq \int_{\Omega} \lambda(u-v)_{+}\left[\frac{1}{v^{\delta}}-\frac{1}{u^{\delta}}\right] \\
& \geq\left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u-\left(-\Delta_{p, \mathbb{G}}\right)^{s} v,(u-v)_{+}\right\rangle \\
& =(p-1) \iint_{\mathbb{G} \times \mathbb{G}} \frac{Q(x, y)\left(\psi^{+}(x)-\psi^{+}(y)\right)^{2}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \geq 0 .
\end{aligned}
$$

Hence, we have $v \geq u$ a.e. in $\mathbb{G}$.
Remark 1 It is worth noting that the result of Lemma 13 also holds for more general nonlocal operator of subelliptic type on homogeneous Lie groups.

We recall the following three results from [17] which will be useful for establishing subsequent results.

Proposition 2 [[17]] For every $\beta>0$ and $1 \leq p<\infty$ we have the following inequality

$$
\left(\frac{1}{\beta}\right)^{\frac{1}{p}}\left(\frac{p+\beta-1}{p}\right) \geq 1 .
$$

Proposition 3 [ [17]] Let $1<p<\infty$ and let $f: \mathbb{R} \rightarrow \mathbb{R}$ to be a $C^{1}$ convex function and $J_{p}(t):=|t|^{p-2} t$. Then, the following inequality

$$
\begin{equation*}
J_{p}(a-b)\left[A J_{p}\left(f^{\prime}(a)\right)-B J_{p}\left(f^{\prime}(b)\right)\right] \geq(f(a)-f(b))^{p-2}(f(a)-f(b))(A-B), \tag{5.6}
\end{equation*}
$$

holds for every $a, b \in \mathbb{R}$ and every $A, B \geq 0$.
Proposition 4 ([17]) Let $1<p<\infty$ and let $h: \mathbb{R} \rightarrow \mathbb{R}$ to be an increasing function. Define

$$
G(t)=\int_{0}^{t} h^{\prime}(\tau)^{\frac{1}{p}} \mathrm{~d} \tau, t \in \mathbb{R}
$$

Then, we have

$$
\begin{equation*}
J_{p}(a-b)(h(a)-h(b)) \geq|h(a)-h(b)|^{p} . \tag{5.7}
\end{equation*}
$$

The next lemma concludes the boundedness of solutions of the problem (1.5). We will employ a Moser type iteration to establish our result.
Lemma 14 Suppose $u \in X_{0}^{s, p}(\Omega)$ is a nonnegative weak solution to the problem (1.5), then we have $u \in L^{\infty}(\Omega)$.

Proof Let $\epsilon>0$ be given. Consider the smooth, Lipschitz function $g_{\epsilon}(t)=\left(\epsilon^{2}+t^{2}\right)^{\frac{1}{2}}$, which is convex and $g_{\epsilon}(t) \rightarrow|t|$ as $\epsilon \rightarrow 0$. In addition, we also have $\left|g_{\epsilon}^{\prime}(t)\right| \leq 1$. For each strictly positive $\psi \in C_{c}^{\infty}(\Omega)$, test the weak formulation (5) with the test function $\varphi=\left|g_{\epsilon}^{\prime}(u)\right|^{p-2} g_{\epsilon}^{\prime}(u) \psi$ to obtain the following estimate

$$
\begin{equation*}
\left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} g_{\epsilon}(u), \psi\right\rangle \leq \int_{\Omega}\left(\left|\frac{\lambda f(x)}{u^{\delta}}+g(x) u^{q}\right|\right)\left|g_{\epsilon}^{\prime}(u)\right|^{p-1} \psi d x, \tag{5.8}
\end{equation*}
$$

for all $\psi \in C_{c}^{\infty}(\Omega) \cap \mathbb{R}^{+}$. This is immediate from Proposition 3 by setting $a=$ $u(x), b=u(y), A=\psi(x)$ and $B=\psi(y)$.

Thanks to Fatou's Lemma, by passing to the limit $\epsilon \rightarrow 0$, we deduce

$$
\begin{equation*}
\left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s}(|u|), \psi\right\rangle \leq \int_{\Omega}\left(\left|\frac{\lambda f(x)}{u^{\delta}}+g(x) u^{q}\right|\right) \psi d x . \tag{5.9}
\end{equation*}
$$

The density result guarantees that (5.9) holds also for $\psi \in X_{0}^{s, p}(\Omega)$.
For each $k>0$, consider $u_{k}=\min \left\{(u-1)^{+}, k\right\} \in X_{0}^{s, p}(\Omega)$. Then, for fixed $\beta>0$ and $\eta>0$, by testing (5.9) with the test function $\psi=\left(u_{k}+\eta\right)^{\beta}-\eta^{\beta}$ we get

$$
\begin{aligned}
& \iint_{\mathbb{G} \times \mathbb{G}} \frac{| | u(x)\left|-|u(y)|^{p-2}(|u(x)|-|u(y)|)\left(\left(u_{k}(x)+\eta\right)^{\beta}-\left(u_{k}(y)+\eta\right)^{\beta}\right)\right.}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \quad \leq \int_{\Omega}\left|\frac{\lambda f(x)}{u^{\delta}}+g(x) u^{q}\right|\left(\left(u_{k}+\eta\right)^{\beta}-\eta^{\beta}\right) d x .
\end{aligned}
$$

We apply Proposition 4 with $h(u)=\left(u_{k}+\eta\right)^{\beta}$ to deduce the following estimate:

$$
\begin{align*}
& \iint_{\mathbb{G} \times \mathbb{G}} \frac{\left|\left(\left(u_{k}(x)+\eta\right)^{\frac{\beta+p-1}{p}}-\left(u_{k}(y)+\eta\right)^{\frac{\beta+p-1}{p}}\right)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \leq \frac{(\beta+p-1)^{p}}{\beta p^{p}} \\
& \quad \times \iint_{\mathbb{G} \times \mathbb{G}} \frac{\| u(x)|-|u(y)||^{p-2}(|u(x)|-|u(y)|)\left(\left(u_{k}(x)+\eta\right)^{\beta}-\left(u_{k}(y)+\eta\right)^{\beta}\right)}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \leq \frac{(\beta+p-1)^{p}}{\beta p^{p}} \int_{\Omega}\left(\left|\frac{\lambda f(x)}{u^{\delta}}\right|+\left|g(x) u^{q}\right|\right)\left(\left(u_{k}+\eta\right)^{\beta}-\eta^{\beta}\right) d x \\
& \quad=\frac{(\beta+p-1)^{p}}{\beta p^{p}} \\
& \quad \times\left[\int_{\{u \geq 1\}} \lambda|f(x)||u|^{-\delta}\left(\left(u_{k}+\eta\right)^{\beta}-\eta^{\beta}\right)+\int_{\{u \geq 1\}}|g(x) \| u|^{q}\left(\left(u_{k}+\eta\right)^{\beta}-\eta^{\beta}\right) d x\right] \\
& \leq \frac{(\beta+p-1)^{p}}{\beta p^{p}}\left[\int_{\{u \geq 1\}}\left(\lambda|f(x)|+|g(x) \| u|^{q}\right)\left(\left(u_{k}+\eta\right)^{\beta}-\eta^{\beta}\right) d x\right] \\
& \leq 2 C\left(\lambda,\|f\|_{\infty},\|g\|_{\infty}\right)\left(\frac{(\beta+p-1)^{p}}{\beta p^{p}}\right)\left[\int_{\Omega}|u|^{q}\left(\left(u_{k}+\eta\right)^{\beta}-\eta^{\beta}\right) d x\right] \\
& \leq C^{\prime}\left(\frac{(\beta+p-1)^{p}}{\beta p^{p}}\right)\|u\|_{p_{s}^{*}\left\|\left(u_{k}+\eta\right)^{\beta}\right\|_{\kappa},} \tag{5.10}
\end{align*}
$$

where $\kappa=\frac{p_{s}^{*}}{p_{s}^{*}-q}$. By recalling the fractional Sobolev inequality for fractional $p$-subLaplacian (6.3), we obtain

$$
\begin{align*}
& \iint_{\mathbb{G} \times \mathbb{G}} \frac{\left|\left(\left(u_{k}(x)+\eta\right)^{\frac{\beta+p-1}{p}}-\left(u_{k}(y)+\eta\right)^{\frac{\beta+p-1}{p}}\right)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \quad \geq C\left\|\left(u_{k}+\eta\right)^{\frac{\beta+p-1}{p}}-\eta^{\frac{\beta+p-1}{p}}\right\|_{p_{s}^{*}}^{p} \tag{5.11}
\end{align*}
$$

for some $C>0$.
By using triangle inequality with $\left(u_{k}+\eta\right)^{\beta+p-1} \geq \eta^{p-1}\left(u_{k}+\eta\right)^{\beta}$, we have

$$
\begin{align*}
& {\left[\int_{\Omega}\left(\left(u_{k}+\eta\right)^{\frac{\beta+p-1}{p}}-\eta^{\frac{\beta+p-1}{p}}\right)^{p_{s}^{*}} d x\right]^{\frac{p}{p_{s}^{*}}}} \\
& \quad \geq\left(\frac{\eta}{2}\right)^{p-1}\left[\int_{\Omega}\left(u_{k}+\eta\right)^{\frac{p_{s}^{*} \beta}{p}}\right]^{\frac{p}{p_{s}^{*}}}-\eta^{\beta+p-1}|\Omega| \frac{p}{p_{s}^{*}} . \tag{5.12}
\end{align*}
$$

Thus, plugging (5.12) into (5.11) and finally from (5.10), we obtain

$$
\begin{align*}
& \left\|\left(u_{k}+\eta\right)^{\frac{\beta}{p}}\right\|_{p_{s}^{*}}^{p} \\
& \quad \leq C^{\prime}\left[C\left(\frac{2}{\eta}\right)^{p-1}\left(\frac{(\beta+p-1)^{p}}{\beta p^{p}}\right)\|u\|_{p_{s}^{*}}^{q}\left\|\left(u_{k}+\eta\right)^{\beta}\right\|_{\kappa}+\eta^{\beta}|\Omega| \frac{p}{\frac{p}{p_{s}^{*}}}\right] . \tag{5.13}
\end{align*}
$$

Now, Proposition 2, estimates (5.10) and (5.13) imply that

$$
\begin{equation*}
\left\|\left(u_{k}+\eta\right)^{\frac{\beta}{p}}\right\|_{p_{s}^{*}}^{p} \leq C^{\prime}\left[\frac{1}{\beta}\left(\frac{\beta+p-1}{p}\right)^{p}\left\|\left(u_{k}+\eta\right)^{\beta}\right\|_{\kappa}\left(\frac{C\|u\|_{p_{s}^{*}}^{q}+|\Omega|^{\frac{p}{p_{s}^{*}}-\frac{1}{\kappa}}}{\eta^{p-1}}\right)\right] . \tag{5.14}
\end{equation*}
$$

We are now in a position to employ a Moser type bootstrap argument to establish our claim. For this, choose $\eta>0$ such that $\eta^{p-1}=C\|u\|_{p_{s}^{*}}^{r-1}\left(|\Omega|^{\frac{p}{p_{s}^{*}}-\frac{1}{\kappa}}\right)^{-1}$. We observe that for $\beta \geq 1$, we have $\beta^{p} \geq\left(\frac{\beta+p-1}{p}\right)^{p}$.

Let us now rewrite the estimate (5.14) by plugging $\chi=\frac{p_{s}^{*}}{p \kappa}>1$ and $\tau=\beta \kappa$ as follows:

$$
\begin{equation*}
\left\|\left(u_{k}+\eta\right)\right\|_{\chi \tau} \leq\left(C|\Omega|^{\frac{p}{p_{s}^{*}}-\frac{1}{\kappa}}\right)^{\frac{\kappa}{\tau}}\left(\frac{\tau}{\kappa}\right)^{\frac{\kappa}{\tau}}\left\|\left(u_{k}+\eta\right)\right\|_{\tau} . \tag{5.15}
\end{equation*}
$$

We perform $m$ iterations with $\tau_{0}=\kappa$ and $\tau_{m+1}=\chi \tau_{m}=\chi^{m+1} \kappa$ on (5.15) to have

$$
\left\|\left(u_{k}+\eta\right)\right\|_{\tau_{m+1}} \leq\left(C|\Omega|^{\frac{p}{p_{s}^{*}}-\frac{1}{\kappa}}\right)^{\left(\sum_{i=0}^{m} \frac{\kappa}{\tau_{i}}\right.}\left(\prod_{i=0}^{m}\left(\frac{\tau_{i}}{\kappa}\right)^{\frac{\kappa}{\tau_{i}}}\right)^{p-1}\left\|\left(u_{k}+\eta\right)\right\|_{\kappa}
$$

$$
\begin{equation*}
=\left(C|\Omega|^{\frac{p}{p_{s}^{*}}-\frac{1}{\kappa}}\right)^{\frac{\chi}{\chi-1}}\left(\chi^{\frac{\chi}{(\chi-1)^{2}}}\right)^{p-1}\left\|\left(u_{k}+\eta\right)\right\|_{\kappa} . \tag{5.16}
\end{equation*}
$$

Now, taking the limit as $m \rightarrow \infty$, we obtain

$$
\begin{equation*}
\left\|u_{k}\right\|_{\infty} \leq\left(C|\Omega|^{\frac{p}{p_{s}^{*}}-\frac{1}{q}}\right)^{\frac{\chi}{x-1}}\left(C^{\prime} \chi^{\frac{\chi}{(x-1)^{2}}}\right)^{p-1}\left\|\left(u_{k}+\eta\right)\right\|_{q} . \tag{5.17}
\end{equation*}
$$

Finally, we use $u_{k} \leq(u-1)^{+}$in (5.17) combined with the triangle inequality and pass the limit $k \rightarrow \infty$, to obtain

$$
\begin{gather*}
\left\|(u-1)^{+}\right\|_{\infty} \leq\left\|u_{k}\right\|_{\infty} \leq C\left(\chi^{\frac{x}{(x-1)^{2}}}\right)^{p-1}\left(|\Omega|^{\frac{p}{p_{s}^{*}}-\frac{1}{\kappa}}\right)^{\frac{x}{x^{-1}}} \\
\left(\left\|(u-1)^{+}\right\|_{\kappa}+\eta|\Omega|^{\frac{1}{\kappa}}\right) . \tag{5.18}
\end{gather*}
$$

Therefore, we have $u \in L^{\infty}(\Omega)$ and hence the proof.
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## Appendix A: Sobolev-Rellich-Kondrachov type embedding on stratified Lie groups

The purpose of this section to prove continuity and compactness of the Sobolev embedding for $X_{0}^{s, p}(\Omega)$ where $\Omega$ is any open subset of a stratified Lie group $\mathbb{G}$. We follow the ideas of [79] to establish the continuous embedding whereas the compact embedding will be proved based on the idea originated by [52]. Recently, a similar embedding result is obtained for the Rockland operator on graded Lie groups [91]. The embedding
results for the fractional Sobolev space $X_{0}^{s, p}(\Omega)$ over $\mathbb{R}^{N}$ can be found in [34, 43]. We note here that in [1] the authors studied weighted compact embeddings for the fractional Sobolev spaces on bounded extension domains of the Heisenberg group using an approach similar to [79]. Recently, the fractional Sobolev inequality on stratified Lie groups was shown in [65, Theorem 2] (see [64] for fractional logarithmic inequalities on homogeneous Lie groups). Motivated by the above mentioned investigations we prove the continuous and compact embeddings of $X_{0}^{s, p}(\Omega)$ into the Lebesgue space $L^{r}(\Omega)$ for an appropriate range of $r \geq 1$. We now state the embedding result for the space $X_{0}^{s, p}(\Omega)$ on stratified Lie groups.

Theorem 7 Let $\mathbb{G}$ be a stratified Lie group of homogeneous dimension Q, and let $\Omega \subset$ $\mathbb{G}$ be an open set. Let $0<s<1 \leq p<\infty$ and $Q>s p$. Then the fractional Sobolev space $X_{0}^{s, p}(\Omega)$ is continuously embedded in $L^{r}(\Omega)$ for $p \leq r \leq p_{s}^{*}:=\frac{Q p}{Q-s p}$, that is, there exists a positive constant $C=C(Q, s, p, \Omega)$ such that for all $u \in X_{0}^{s, p}(\Omega)$, we have

$$
\|u\|_{L^{r}(\Omega)} \leq C\|u\|_{X_{0}^{s, p}(\Omega)}
$$

Moreover, if $\Omega$ is bounded, then the following embedding

$$
\begin{equation*}
X_{0}^{s, p}(\Omega) \hookrightarrow L^{r}(\Omega) \tag{6.1}
\end{equation*}
$$

is continuous for all $r \in\left[1, p_{s}^{*}\right]$ and is compact for all $r \in\left[1, p_{s}^{*}\right)$.
Proof Let us recall the fractional Sobolev inequality on stratified Lie groups [65], given by

$$
\begin{equation*}
\|u\|_{L^{p_{s}^{*}}(\mathbb{G})} \leq C\|u\|_{W^{s, p}(\mathbb{G})} . \tag{6.2}
\end{equation*}
$$

Thus, the space $W^{s, p}(\mathbb{G})$ is continuously embedded in $L^{p_{s}^{*}}(\mathbb{G})$. Let $r \in\left(p, p_{s}^{*}\right)$ be such that $\frac{1}{r}=\frac{\theta}{p}+\frac{1-\theta}{p_{s}^{*}}$ for some $\theta \in(0,1)$. Then by the interpolation inequality of Lebesgue spaces we have

$$
\|u\|_{L^{r}(\mathbb{G})} \leq\|u\|_{L^{p}(\mathbb{G})}^{\theta}\|u\|_{L^{p_{s}^{*}}(\mathbb{G})}^{1-\theta} .
$$

Therefore, using Young's inequality with the exponent $\frac{1}{\theta}$ and $\frac{1}{1-\theta}$ we obtain

$$
\begin{aligned}
\|u\|_{L^{r}(\mathbb{G})} & \leq\|u\|_{L^{p}(\mathbb{G})}+\|u\|_{L^{p_{s}^{*}}(\mathbb{G})} \\
& \leq\|u\|_{L^{p}(\mathbb{G})}+C\|u\|_{W^{s, p}(\mathbb{G})} .
\end{aligned}
$$

Thus, we get that the space $W^{s, p}(\mathbb{G})$ is continuously embedded in $L^{r}(\mathbb{G})$ for all $r \in\left[p, p_{s}^{*}\right]$.

Let $\Omega$ be an open subset of $\mathbb{G}$. Then, for each $u \in X_{0}^{s, p}(\Omega)$, we have from (6.2), as $u=0$ in $\mathbb{G} \backslash \Omega$, that

$$
\begin{equation*}
\|u\|_{L^{p_{s}^{*}}(\Omega)} \leq C\|u\|_{X_{0}^{s, p}(\Omega)} . \tag{6.3}
\end{equation*}
$$

Thus the space $X_{0}^{s, p}(\Omega)$ is continuously embedded in $L^{p_{s}^{*}}(\Omega)$. Proceeding as above we conclude that the embedding $X_{0}^{s, p}(\Omega) \hookrightarrow L^{r}(\Omega)$ is continuous for all $r \in\left[p, p_{s}^{*}\right]$. That is, for all $u \in X_{0}^{s, p}(\Omega)$ there exists a $C=C(Q, p, s, \Omega)>0$ such that

$$
\begin{equation*}
\|u\|_{L^{r}(\Omega)} \leq C\|u\|_{X_{0}^{s, p}(\Omega)} \text { for all } p \leq r \leq p_{s}^{*} \tag{6.4}
\end{equation*}
$$

In particular, if $\Omega$ is bounded that is $|\Omega|<\infty$, then applying the Hölder inequality to the inequality (6.4), we get the continuous embedding for all $r \in\left[1, p_{s}^{*}\right]$. This concludes the proof of the first part of the theorem.

Now, we choose $\eta \in C_{c}^{\infty}(\mathbb{G})$ such that supp $\eta \subset \bar{B}_{1}(0), 0 \leq \eta \leq 1$ and $\|\eta\|_{L^{1}(\mathbb{G})}=$ 1. For each $\epsilon>0$ and $f \in L_{\mathrm{loc}}^{1}(\mathbb{G})$, let us define

$$
\eta_{\epsilon}(x)=\frac{1}{\epsilon Q} \eta\left(\epsilon^{-1} x\right)
$$

and

$$
\begin{equation*}
T_{\epsilon} f(x):=f * \eta_{\epsilon}(x):=\int_{\mathbb{G}} f(x) \eta_{\epsilon}\left(x^{-1} y\right) d y . \tag{6.5}
\end{equation*}
$$

Prior to proceeding to show the compactness of the embedding, we first we prove the following lemma.

Lemma 15 Let $\Omega$ be a open bounded subset of $\mathbb{G}$. Then, for $1 \leq r<\infty$, the set $\mathcal{F} \subset L^{r}(\Omega)$ is relatively compact in $L^{r}(\Omega)$ if and only if $\mathcal{F}$ is bounded and $\| T_{\epsilon} f-$ $f \|_{L^{r}(\Omega)} \rightarrow 0$ uniformly in $f \in \mathcal{F}$ as $\epsilon \rightarrow 0$.

Proof Suppose that $\mathcal{F}$ is relatively compact in $L^{r}(\Omega)$. We agree to extend any function $L^{r}(\Omega)$ to $L^{r}(\mathbb{G})$ by assigning zero out of $\Omega$. Let $R>0$ and let $f_{1}, f_{2}, \ldots, f_{l} \in \mathcal{F}$ be such that $\mathcal{F} \subset \cup_{j=1}^{l} B_{R}\left(f_{j}\right) \subset L^{r}(\Omega)$. Then we have

$$
\begin{equation*}
\left\|f-T_{\epsilon} f\right\|_{L^{r}(\Omega)} \leq\left\|f-f_{j}\right\|_{L^{r}(\Omega)}+\left\|f_{j}-T_{\epsilon} f_{j}\right\|_{L^{r}(\Omega)}+\left\|T_{\epsilon} f_{j}-T_{\epsilon} f\right\|_{L^{r}(\Omega)} \tag{6.6}
\end{equation*}
$$

Since $T_{\epsilon} f \rightarrow f$ in $L^{r}(\Omega)$ as $\epsilon \rightarrow 0$ and $\left\|T_{\epsilon} f\right\|_{r} \leq\|f\|_{r}$, we have uniform convergence $\left\|T_{\epsilon} f-f\right\|_{L^{r}(\Omega)} \rightarrow 0$ by passing $\epsilon \rightarrow 0$.

Conversely, we assume that $\mathcal{F}$ is bounded and $\left\|T_{\epsilon} f-f\right\|_{L^{r}(\Omega)} \rightarrow 0$ uniformly in $f \in \mathcal{F}$ as $\epsilon \rightarrow 0$. Choose a bounded sequence $\left(f_{n}\right)$ in $\mathcal{F}$. Thanks to the BanachAlouglu theorem we can extract a subsequence (again denoted by $\left(f_{n}\right)$ ) such that $f_{n} \rightharpoonup f$ weakly in $L^{r}(\Omega)$. We now aim to prove strong convergence. For that we first observe that

$$
\begin{equation*}
\left\|f_{n}-f\right\|_{L^{r}(\Omega)} \leq\left\|f-T_{\epsilon} f_{n}\right\|_{L^{r}(\Omega)}+\left\|T_{\epsilon} f_{n}-T_{\epsilon} f\right\|_{L^{r}(\Omega)}+\left\|T_{\epsilon} f-f\right\|_{L^{r}(\Omega)} \tag{6.7}
\end{equation*}
$$

It follows from the weak convergence of $f_{n} \rightharpoonup f$ that, for all $x \in \mathbb{G}$ and for $\epsilon>0$, we have $\lim _{n \rightarrow \infty} T_{\epsilon}\left(f_{n}-f\right)(x) \rightarrow 0$. Again, by Hölder inequality we have

$$
\begin{equation*}
\left\|T_{\epsilon}\left(f_{n}-f\right)\right\|_{L^{r}(\Omega)}^{r} \leq\left\|\eta_{\epsilon}\right\|_{L^{1}(\mathbb{G})}^{r}\left\|f_{n}-f\right\|_{L^{r}(\Omega)}^{r}<\infty \tag{6.8}
\end{equation*}
$$

and therefore by the Lebesgue dominated convergence theorem we get

$$
\begin{equation*}
\int_{\mathbb{G}}\left|T_{\epsilon}\left(f_{n}-f\right)(x)\right|^{r} d x \rightarrow 0 \quad n \rightarrow \infty \tag{6.9}
\end{equation*}
$$

Thus, as $\epsilon \rightarrow 0$, all three terms on right hand side of (6.7) go to zero with the use of assumption $\left\|T_{\epsilon} f-f\right\|_{L^{r}(\Omega)} \rightarrow 0$ uniformly in $f \in \mathcal{F}$ as $\epsilon \rightarrow 0$. Thus, $f_{n} \rightarrow f$ converges strongly in $L^{r}(\Omega)$. Hence, $\mathcal{F}$ is relative compact in $L^{r}(\Omega)$ for all $1 \leq r<\infty$.

Now, we continue the proof of Theorem 1. We emphasise that by assigning $f=0$ in $\mathbb{G} \backslash \Omega$ we have $f \in W^{s, p}(\mathbb{G})$ for every $f \in X_{0}^{s, p}(\Omega)$. Now, with the help of Lemma 15 we prove the relative compactness of a bounded set $\mathcal{F}$ in $X_{0}^{s, p}(\Omega)$. Recall that $\left|B_{R}(x)\right|=R^{Q}\left|B_{1}(0)\right|$ (see [45, p. 140]). Therefore, the boundedness of $\mathcal{F}$ in $L^{r}(\Omega)$ is immediate from the fractional Gagliardo-Nirenberg inequality [88, Theorem 4.4.1],

$$
\begin{equation*}
\|f\|_{L^{r}(\mathbb{G})} \leq C[f]_{s, p}^{b}\|f\|_{L^{q}(\mathbb{G})}^{1-b}, \tag{6.10}
\end{equation*}
$$

where $p>1, q \geq 1, r>0, b \in(0,1]$ satisfy $\frac{1}{r}=b\left(\frac{1}{p}-\frac{s}{Q}\right)+\frac{1-b}{q}$.
Setting,

$$
K_{\epsilon}:=T_{\epsilon} f-f \text { for all } f \in \mathcal{F},
$$

we get from the fractional Gagliardo-Nirenberg inequality (6.10), as $f \in X_{0}^{s, p}(\Omega)$ and thus $K_{\epsilon}(x)=0$ for all $x \in \mathbb{G} \backslash \Omega$, that

$$
\begin{equation*}
\left\|K_{\epsilon}\right\|_{L^{r}(\Omega)} \leq C\left[K_{\epsilon}\right]_{s, p}^{b}\left\|K_{\epsilon}\right\|_{L^{q}(\Omega)}^{1-b}, \tag{6.11}
\end{equation*}
$$

where $\frac{1}{r}=b\left(\frac{1}{p}-\frac{s}{Q}\right)+\frac{1-b}{q}$. Thus, it is sufficient to show that

$$
\begin{equation*}
\left[K_{\epsilon}\right]_{s, p} \leq\left\|T_{\epsilon} f-f\right\|_{X_{0}^{s, p}(\Omega)} \rightarrow 0 . \tag{6.12}
\end{equation*}
$$

This means that

$$
\begin{equation*}
\lim _{\epsilon \rightarrow 0} \int_{\mathbb{G}} \int_{\mathbb{G}} \frac{\left|\left(T_{\epsilon} f-f\right)(x)-\left(T_{\epsilon} f-f\right)(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y=0 . \tag{6.13}
\end{equation*}
$$

Using $\operatorname{supp}\left(\eta_{\epsilon}\right) \subset B_{\epsilon}(0)$, the Hölder inequality, Tonelli's and Fubini's theorem we obtain

$$
\int_{\mathbb{G}} \int_{\mathbb{G}} \frac{\left|\left(T_{\epsilon} f-f\right)(x)-\left(T_{\epsilon} f-f\right)(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y
$$

$$
\begin{align*}
& =\int_{\mathbb{G}} \int_{\mathbb{G}} \frac{1}{\left|y^{-1} x\right|^{Q+p s}}\left|\int_{\mathbb{G}} \eta_{\epsilon}(z)\left(f\left(z^{-1} x\right)-f\left(z^{-1} y\right)\right) d z-f(x)+f(y)\right|^{p} d x d y \\
& =\int_{\mathbb{G}} \int_{\mathbb{G}} \frac{1}{\left|y^{-1} x\right|^{Q+p s}}\left|\epsilon^{-Q} \int_{B_{\epsilon}(0)} \eta\left(\epsilon^{-1} z\right)\left(f\left(z^{-1} x\right)-f\left(z^{-1} y\right)\right) d z-f(x)+f(y)\right|^{p} d x d y \\
& =\int_{\mathbb{G}} \int_{\mathbb{G}} \frac{1}{\left|y^{-1} x\right|^{Q+p s}}\left|\int_{B_{1}(0)} \eta\left(z^{\prime}\right)\left(f\left(\left(\epsilon z^{\prime}\right)^{-1} x\right)-f\left(\left(\epsilon z^{\prime}\right)^{-1} y\right)-f(x)+f(y)\right) d z^{\prime}\right|^{p} d x d y \\
& \leq\left|B_{1}(0)\right|^{p-1} \int_{\mathbb{G}} \int_{\mathbb{G}}\left(\int_{B_{1}(0)} \eta^{p}(z) \frac{\left|f\left((\epsilon z)^{-1} x\right)-f\left((\epsilon z)^{-1} y\right)-f(x)+f(y)\right|^{p}}{\left|y^{-1} x\right|} d z\right) d x d y \\
& =\left|B_{1}(0)\right|^{p-1} \int_{B_{1}(0)} \int_{\mathbb{G} \times \mathbb{G}} \frac{\left|f\left((\epsilon z)^{-1} x\right)-f\left((\epsilon z)^{-1} y\right)-f(x)+f(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} \eta^{p}(z) d x d y d z \quad(6 . \tag{6.14}
\end{align*}
$$

Now, we note that for the Lie group $\mathbb{G} \times \mathbb{G}$ with the Haar measure $d x d y$ using the continuity of translations on $L^{p}(\mathbb{G} \times \mathbb{G})$ (see [60, Theorem 20.15]) we obtain, for $v \in L^{p}(\mathbb{G} \times \mathbb{G})$ and $(z, z) \in \mathbb{G} \times \mathbb{G}$, that

$$
\begin{equation*}
\lim _{\epsilon \rightarrow 0} \int_{\mathbb{G} \times \mathbb{G}}\left|v\left((\epsilon z, \epsilon z)^{-1}(x, y)\right)-v(x, y)\right|^{p} d x d y=0 \tag{6.15}
\end{equation*}
$$

Now, fix $z \in B_{1}(0)$ and set

$$
v(x, y):=\frac{f(x)-f(y)}{\left|y^{-1} x\right|^{\frac{Q+p s}{p}}} .
$$

Observe that $v \in L^{p}(\mathbb{G} \times \mathbb{G})$ as $f \in X_{0}^{s, p}(\Omega)$. Therefore, the property (6.15) yields

$$
\begin{equation*}
\lim _{\epsilon \rightarrow 0} \int_{\mathbb{G} \times \mathbb{G}} \frac{\left|f\left((\epsilon z)^{-1} x\right)-f\left((\epsilon z)^{-1} y\right)-f(x)+f(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y=0 . \tag{6.16}
\end{equation*}
$$

Thus,

$$
\begin{equation*}
\rho_{\epsilon}(z):=\eta^{p}(z) \int_{\mathbb{G} \times \mathbb{G}} \frac{\left|f\left((\epsilon z)^{-1} x\right)-f\left((\epsilon z)^{-1} y\right)-f(x)+f(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \rightarrow 0 \tag{6.17}
\end{equation*}
$$

as $\epsilon \rightarrow 0$. Now for a.e. $z \in B_{1}(0)$, using the fact that $f \in X_{0}^{s, p}(\Omega)$ we have

$$
\begin{align*}
\left|\rho_{\epsilon}(z)\right| \leq 2^{p-1} \eta^{p}(z)( & \int_{\mathbb{G} \times \mathbb{G}} \frac{\left|f\left((\epsilon z)^{-1} x\right)-f\left((\epsilon z)^{-1} y\right)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \left.+\int_{\mathbb{G} \times \mathbb{G}} \frac{|f(x)-f(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y\right) \\
& =2^{p} \eta^{p}(z) \int_{\mathbb{G} \times \mathbb{G}} \frac{|f(x)-f(y)|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y . \tag{6.18}
\end{align*}
$$

Observe that the last estimate shows $\rho_{\epsilon} \in L^{\infty}\left(B_{1}(0)\right)$ uniformly as $\epsilon \rightarrow 0$. Therefore, by the Lebesgue dominated convergence theorem we conclude that

$$
\begin{align*}
\int_{B_{1}(0)} \int_{\mathbb{G} \times \mathbb{G}} & \frac{\left|f\left((\epsilon z)^{-1} x\right)-f\left((\epsilon z)^{-1} y\right) d z-f(x)+f(y)\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} \eta^{p}(z) d x d y d z \\
& =\int_{B_{1}(0)} \rho_{\epsilon}(z) d z \rightarrow 0 \tag{6.19}
\end{align*}
$$

as $\epsilon \rightarrow 0$. This fact along with (6.14) gives (6.13) and so (6.12). Finally, by Lemma 15 we conclude that $\mathfrak{F}$ is relatively compact in $L^{r}(\Omega)$. Thus we conclude that the space $X_{0}^{s, p}(\Omega)$ is compactly embedded in $L^{r}(\Omega)$ for all $r \in\left[1, p_{s}^{*}\right)$.

## Appendix B

In this section we prove the following important lemma.
Lemma 16 Let $u_{1}, u_{2} \in X_{0}^{s, p}(\Omega) \backslash\{0\}$. Then there exists a positive constant $C=C_{p}$, depending only on $p$, such that

$$
\begin{align*}
& \left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{1}-\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{2},\right. \\
& \left.\quad \geq u_{1}-u_{2}\right\rangle  \tag{7.1}\\
& \quad \begin{array}{ll}
{\left[u_{1}-u_{2}\right]_{s, p}^{p},} & \text { if } p \geq 2 \\
\frac{\left[u_{1}-u_{2}\right]_{s, p}^{2}}{\left(\left[u_{1}\right]_{s, p}^{p}+\left[u_{2}\right]_{s, p}^{p}\right)^{\frac{2-p}{p}},}, & \text { if } 1<p<2
\end{array}
\end{align*}
$$

Proof Let us recall the well-known Simmon's inequality

$$
\left(|a|^{p-2} a-|b|^{p-2} b\right) \cdot(a-b) \geq C(p)\left\{\begin{array}{lll}
\frac{|a-b|^{2}}{(|a|+|b|)^{2-p}} & \text { if } & 1<p<2  \tag{7.2}\\
|a-b|^{p} & \text { if } \quad p \geq 2
\end{array}\right.
$$

where $a, b \in \mathbb{R}^{N} \backslash\{0\}$ and $C(p)$ is a positive constant depending only on $p$.
For simplicity we denote

$$
w_{i}(x, y)=u_{i}(x)-u_{i}(y), \quad i=1,2 .
$$

Therefore,

$$
\begin{aligned}
& \left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{1}-\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{2}, u_{1}-u_{2}\right\rangle \\
& \quad=\iint_{\mathbb{G} \times \mathbb{G}} \frac{\left|w_{1}\right|^{p-2} w_{1}-\left|w_{2}\right|^{p-2} w_{2}}{\left|y^{-1} x\right|^{Q+p s}}\left(w_{1}-w_{2}\right) d x d y .
\end{aligned}
$$

Observe that for $p \geq 2$ the inequality (7.1) immediately follows from the inequality (7.2). Thus we are left to establish the inequality (7.1) for the range $1<p<2$.

From (7.2), we have

$$
\begin{align*}
& \left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{1}-\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{2}, u_{1}-u_{2}\right\rangle \\
& \quad \geq C(p) \iint_{\mathbb{G} \times \mathbb{G}} \frac{\left|w_{1}-w_{2}\right|^{2}}{\left(\left|w_{1}\right|+\left|w_{2}\right|\right)^{2-p}\left|y^{-1} x\right|^{Q+p s}} d x d y . \tag{7.3}
\end{align*}
$$

Now from the Hölder's inequality, we get

$$
\begin{align*}
{\left[u_{1}-u_{2}\right]_{s, p}^{p} } & =\iint_{\mathbb{G} \times \mathbb{G}} \frac{\left|w_{1}-w_{2}\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
= & \iint_{\mathbb{G} \times \mathbb{G}} \frac{\left|w_{1}-w_{2}\right|^{p}}{\left(\left|w_{1}\right|+\left|w_{2}\right|\right)^{\frac{p(2-p)}{2}}\left|y^{-1} x\right|^{(Q+p s) \frac{p}{2}}} \frac{\left(\left|w_{1}\right|+\left|w_{2}\right|\right)^{\frac{p(2-p)}{2}}}{\left|y^{-1} x\right|^{(Q+p s) \frac{2-p}{2}}} d x d y \\
& \leq A^{\frac{p}{2}} B^{\frac{2-p}{2}}, \tag{7.4}
\end{align*}
$$

where

$$
A=\iint_{\mathbb{G} \times \mathbb{G}} \frac{\left|w_{1}-w_{2}\right|^{2}}{\left(\left|w_{1}\right|+\left|w_{2}\right|\right)^{2-p}\left|y^{-1} x\right|^{Q+p s}} d x d y
$$

and

$$
\begin{aligned}
B & =\iint_{\mathbb{G} \times \mathbb{G}} \frac{\left(\left|w_{1}\right|+\left|w_{2}\right|\right)^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y \\
& \leq 2^{p} \iint_{\mathbb{G} \times \mathbb{G}} \frac{\left|w_{1}\right|^{p}+\left|w_{2}\right|^{p}}{\left|y^{-1} x\right|^{Q+p s}} d x d y=2^{p}\left(\left[u_{1}\right]_{s, p}^{p}+\left[u_{2}\right]_{s, p}^{p}\right) .
\end{aligned}
$$

From (7.3), we deduce

$$
\begin{align*}
& \left\langle\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{1}-\left(-\Delta_{p, \mathbb{G}}\right)^{s} u_{2}, u_{1}-u_{2}\right\rangle \\
& \quad \geq C(p) A \geq C(p)\left(\left[u_{1}-u_{2}\right]_{s, p}^{p} B^{-\frac{2-p}{2}}\right)^{\frac{2}{p}} \\
& \quad \geq C(p)\left[u_{1}-u_{2}\right]_{s, p}^{2}\left(2^{p}\left(\left[u_{1}\right]_{s, p}^{p}+\left[u_{2}\right]_{s, p}^{p}\right)\right)^{-\frac{2-p}{p}} \\
& \quad=2^{p-2} C(p) \frac{\left[u_{1}-u_{2}\right]_{s, p}^{2}}{\left(\left[u_{2}\right]_{s, p}^{p}+\left[u_{2}\right]_{s, p}^{p}\right)^{\frac{2-p}{p}}} \tag{7.5}
\end{align*}
$$

completing the proof.

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