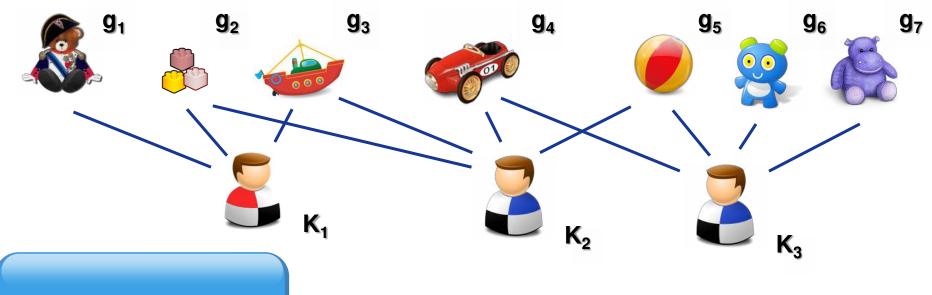
Constraint Satisfaction and Fair Multi-Objective Optimization Problems: Foundations, Complexity, and Islands of Tractability

Gianluigi Greco and Francesco Scarcello



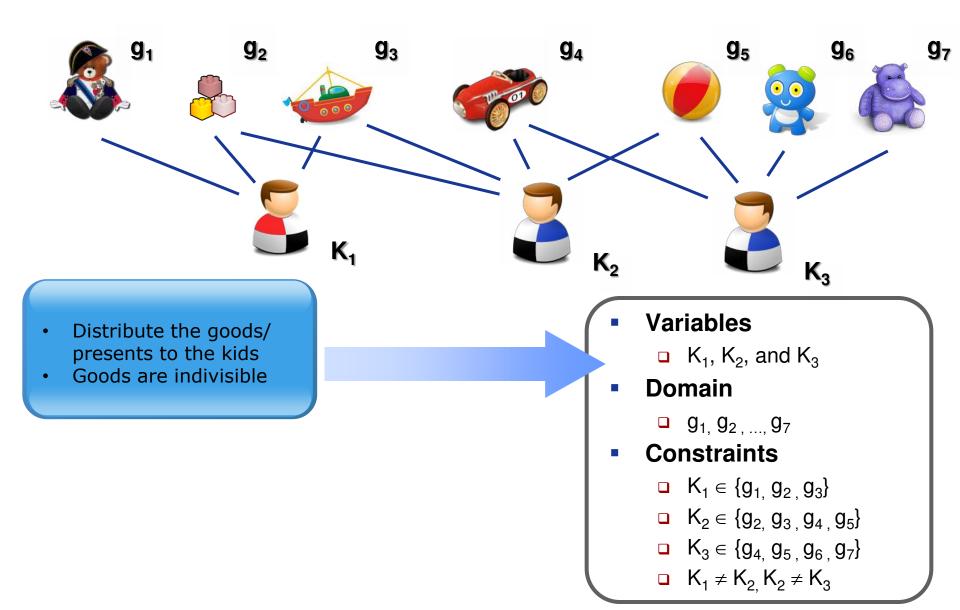


Constraint Satisfaction Problems

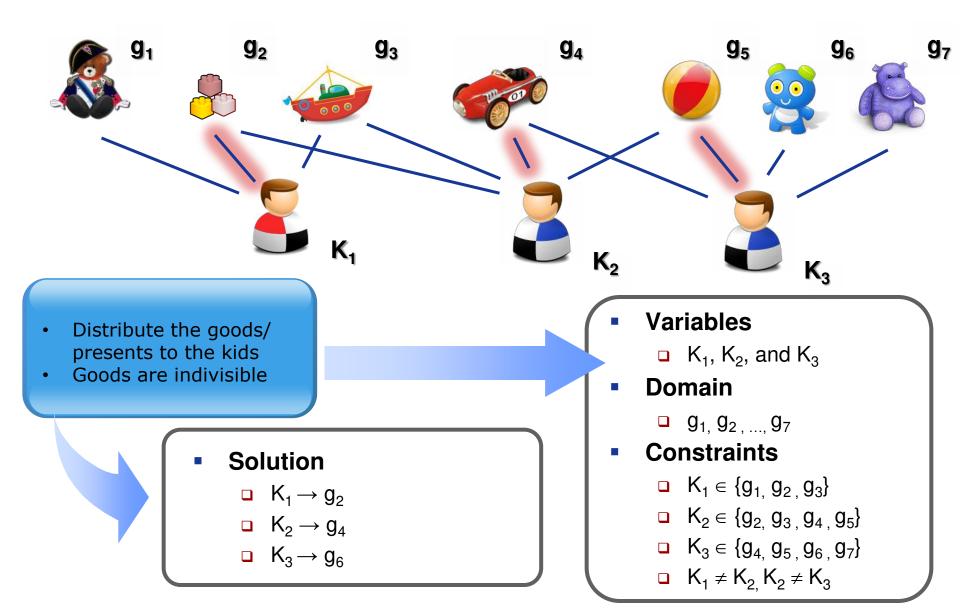


- Distribute the goods/ presents to the kids
- Goods are indivisible

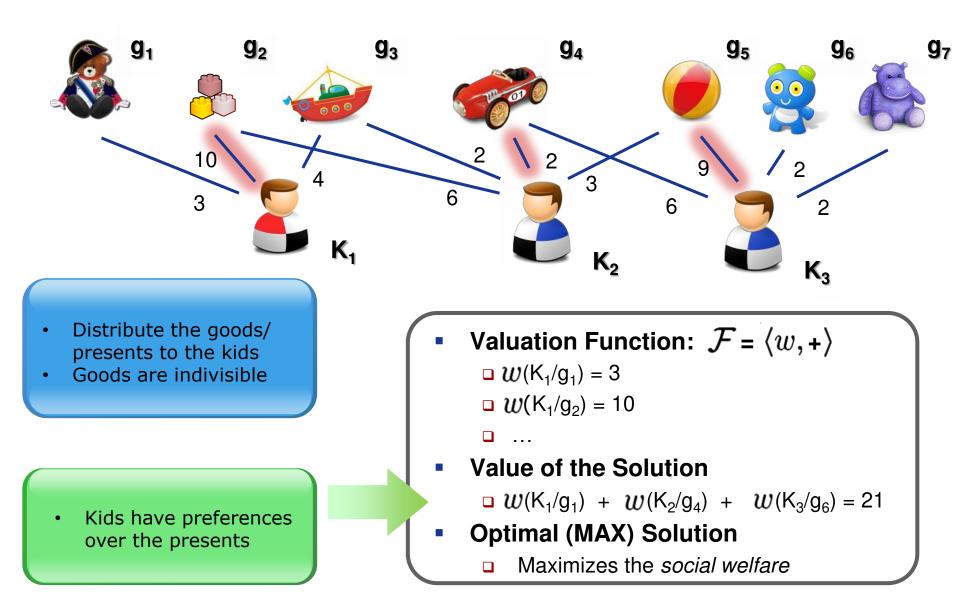
Constraint Satisfaction Problems

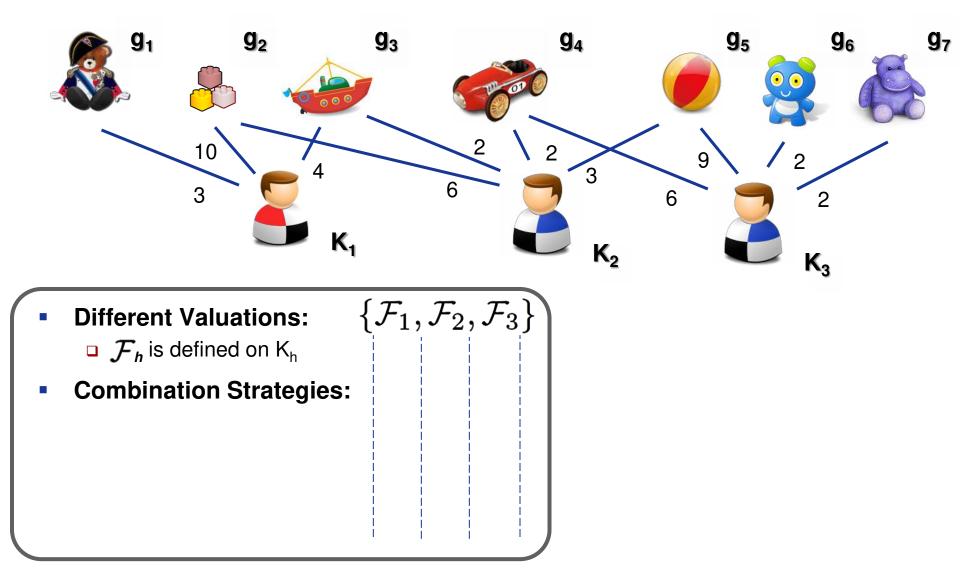


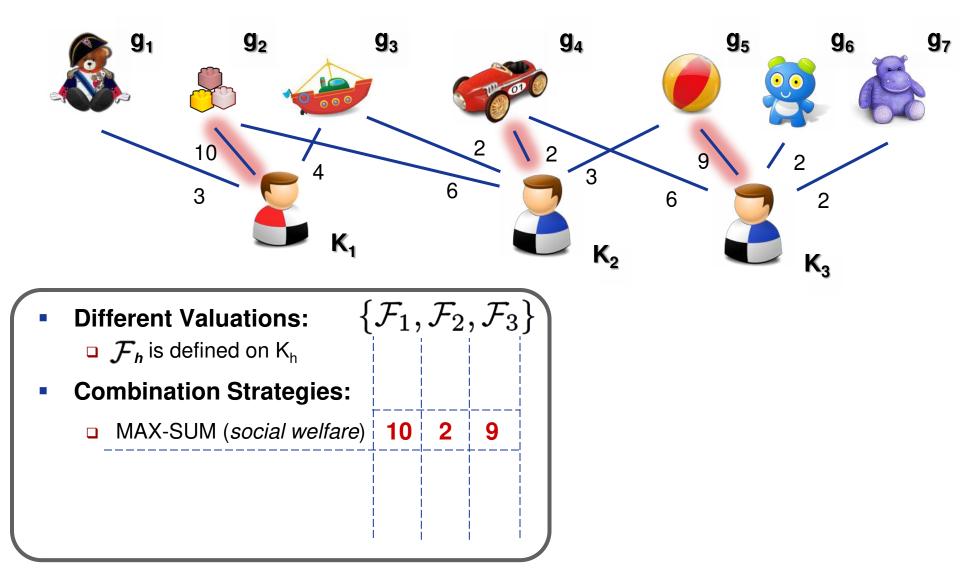
Constraint Satisfaction Problems

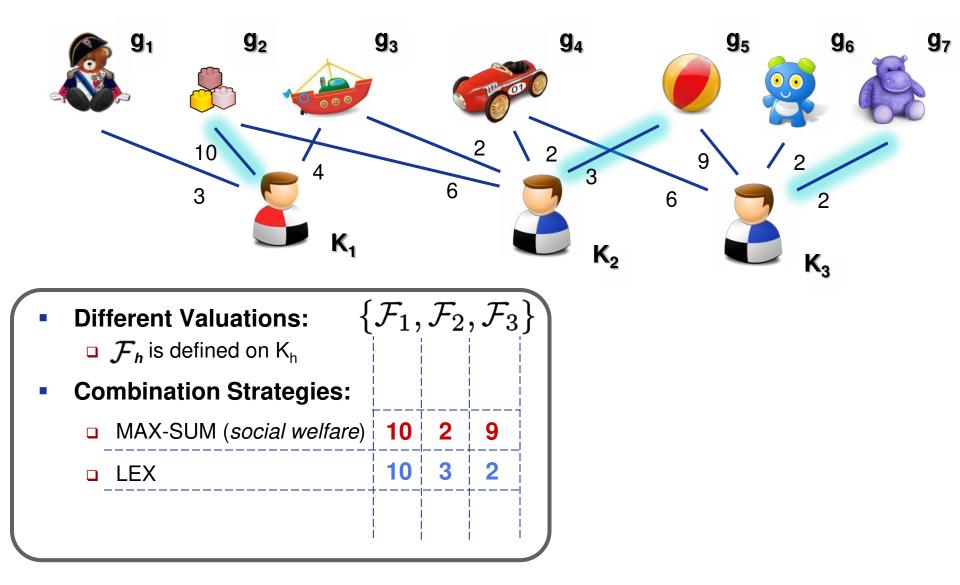


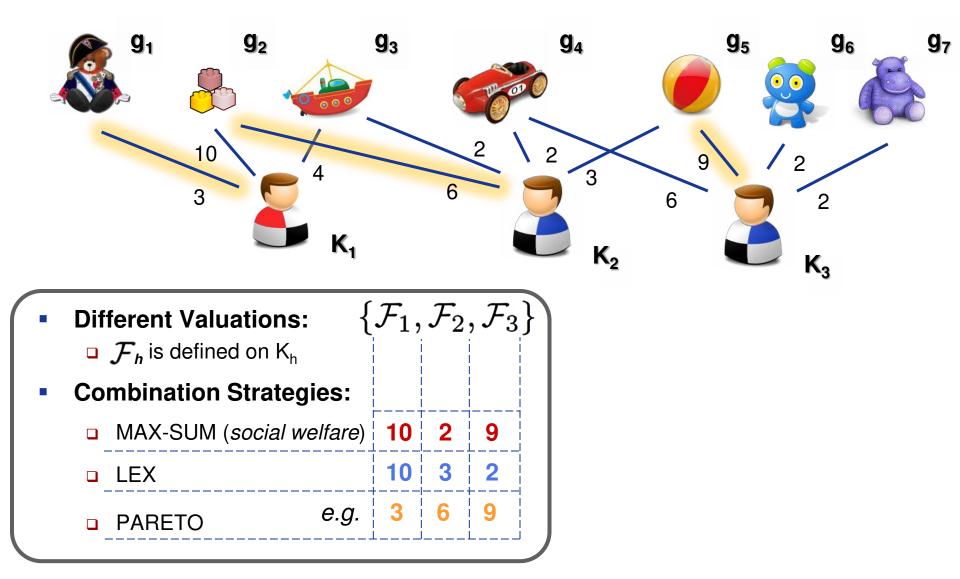
Optimization Functions in CSPs

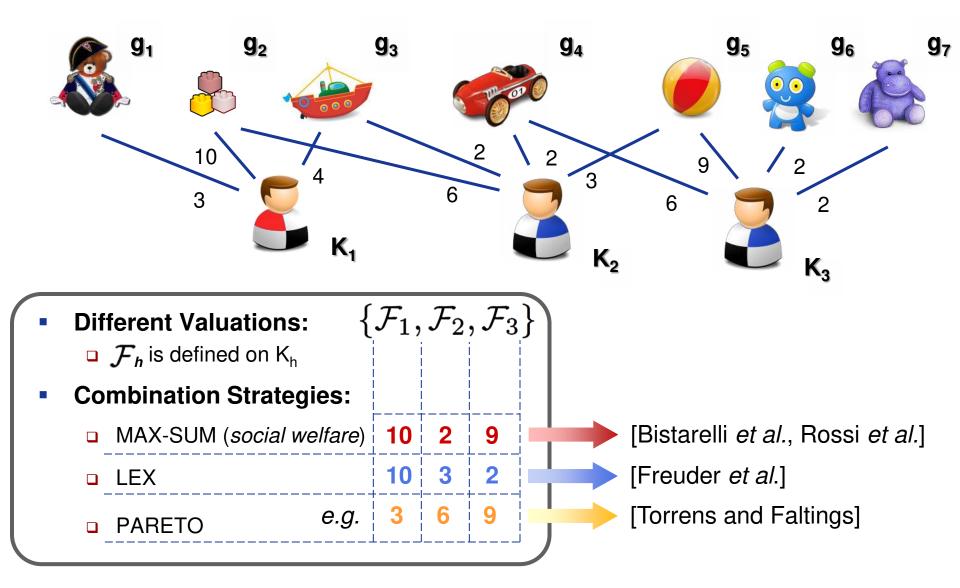


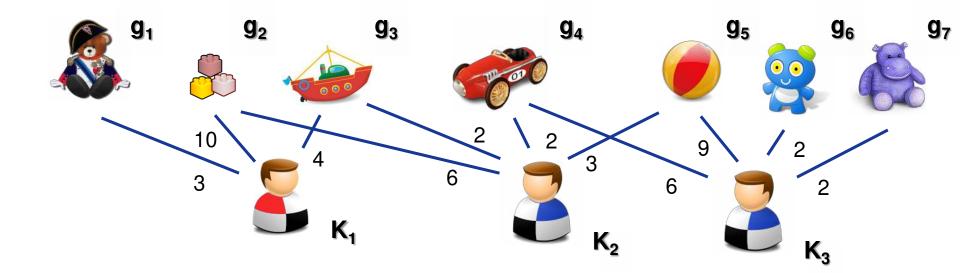






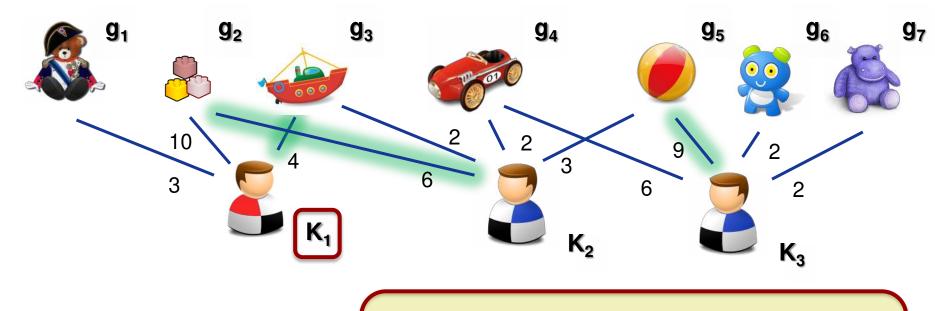






The Santa Claus Problem:

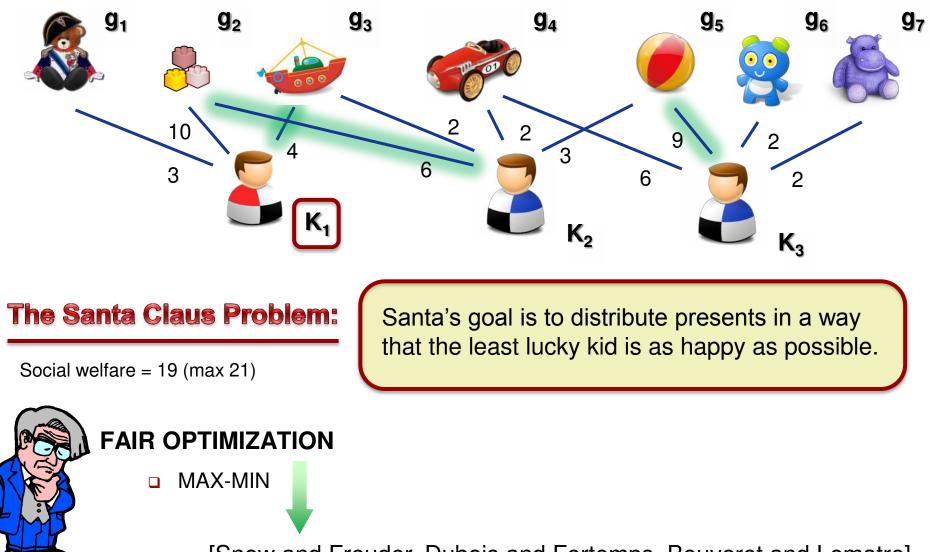
Santa's goal is to distribute presents in a way that the least lucky kid is as happy as possible.



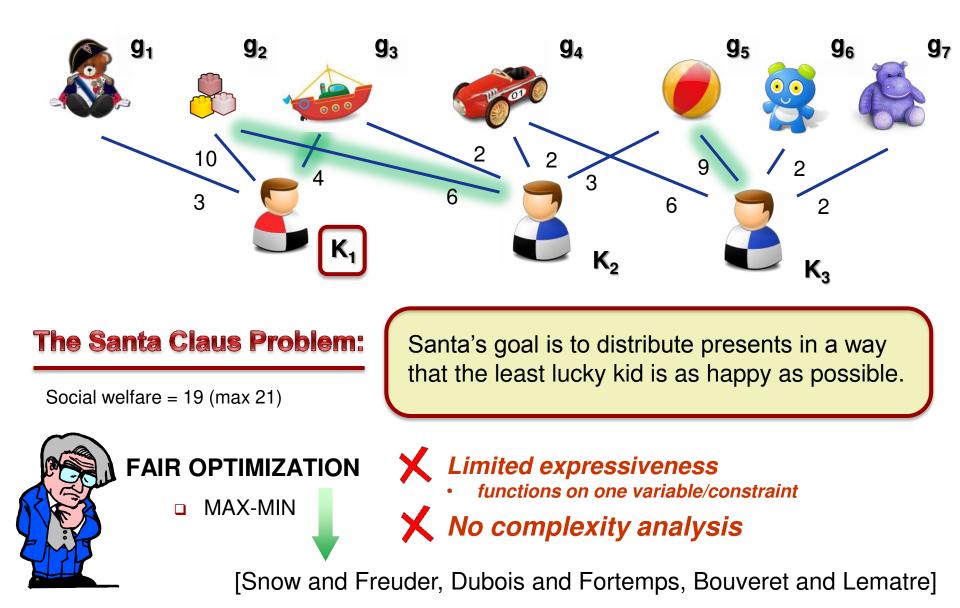
The Santa Claus Problem:

Social welfare = 19 (max 21)

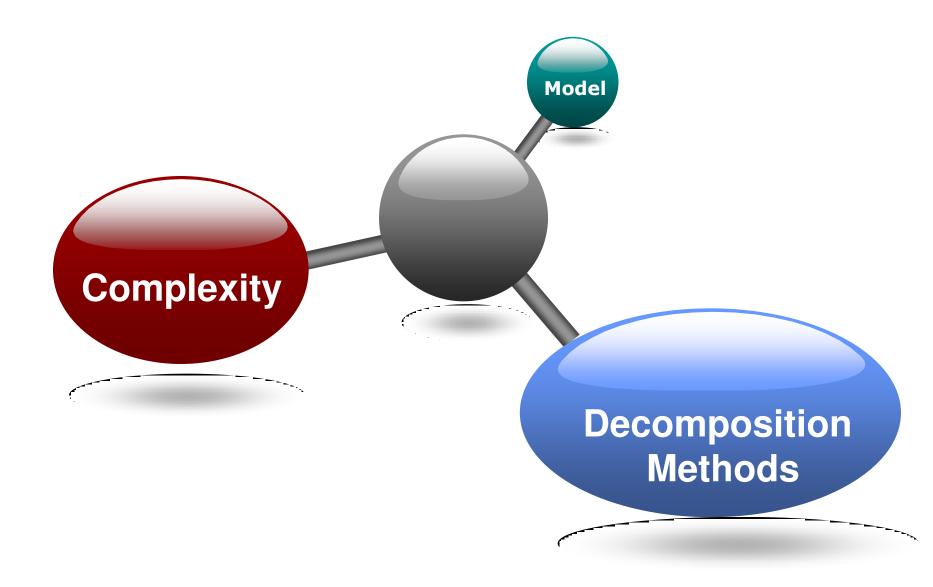
Santa's goal is to distribute presents in a way that the least lucky kid is as happy as possible.



[Snow and Freuder, Dubois and Fortemps, Bouveret and Lematre]



Overview



•
$$L = \{\mathcal{F}_1, ..., \mathcal{F}_n\}$$
 is a set of valuation functions
• $\mathcal{F}_i = \langle w_i, \bigoplus_i \rangle$ is such that
• $w_i : \bar{X}_i \times \mathcal{U} \mapsto \mathbb{R}$, with $\bar{X}_i \subseteq Var$
• \oplus_i is a *commutative*, *associative*, and *closed* binary operator
• $\mathcal{F}_i(\theta) = \bigoplus_{\{X/u \in \theta \mid X \in \bar{X}_i\}} w_i(X, u)$

$$\max_{\theta} \min_{\mathcal{F} \in L} \mathcal{F}(\theta)$$

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The Santa Claus Problem:

(possible solutions)

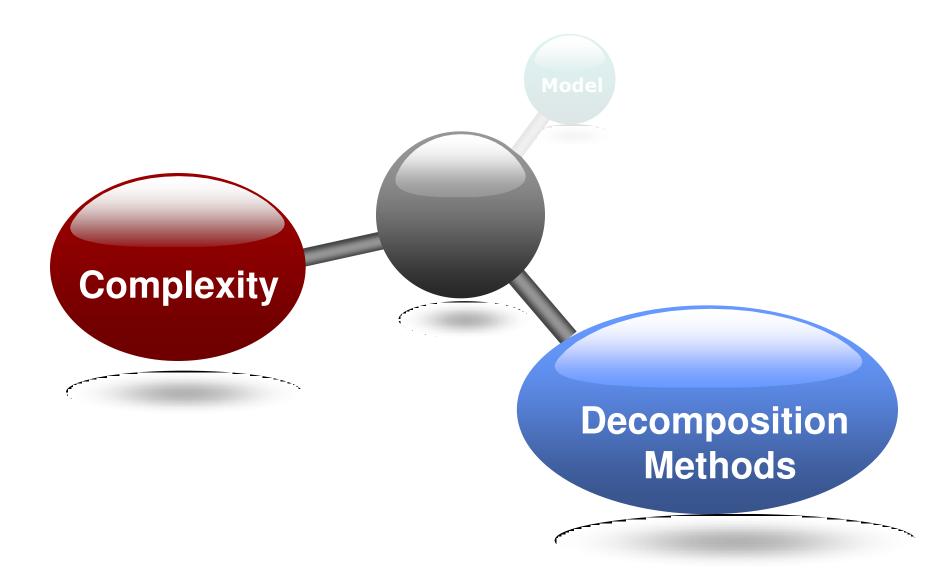
$$\{\mathcal{F}_1, \mathcal{F}_2, \mathcal{F}_3\}$$
10
2
9
10
3
2
3
6
9
4
6
6
4
6
9
 \vdots
 \vdots
 \vdots

$$\max_{\theta} \min_{\mathcal{F} \in L} \mathcal{F}(\theta)$$

4

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The Santa Claus Problem:
(possible solutions)
 $\{\mathcal{F}_1, \mathcal{F}_2, \mathcal{F}_3\}$
 $10 \ 2 \ 9$
 $10 \ 3 \ 2$
 $3 \ 6 \ 9$
 $4 \ 6 \ 6$
 $4 \ 6 \ 9$
 \vdots \vdots \vdots \vdots \vdots $ux_{\theta} \min_{\mathcal{F} \in L} \mathcal{F}(\theta)$
 $lexmax_{\theta} \min_{\mathcal{F} \in L} \mathcal{F}(\theta)$

Overview



Constraint satisfaction is NP-hard

Even without optimization functions...

Tractable classes of CSPs

- Based on the values in the constraint relations
- Based on the structure of the constraint scopes

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Tractable classes of CSPs

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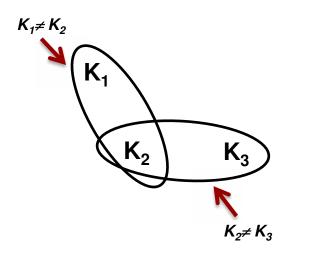
Treewidth [Dechter & Pearl]

Constraint satisfaction is NP-hard

Even without optimization functions...

Tractable classes of CSPs

- Based on the values in the constraint relations
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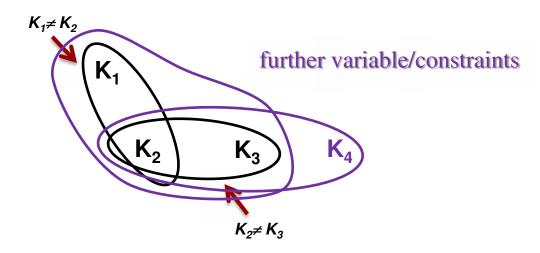


Constraint satisfaction is NP-hard

• Even without optimization functions...

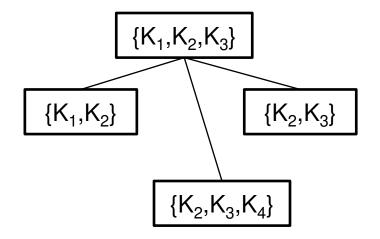
Tractable classes of CSPs

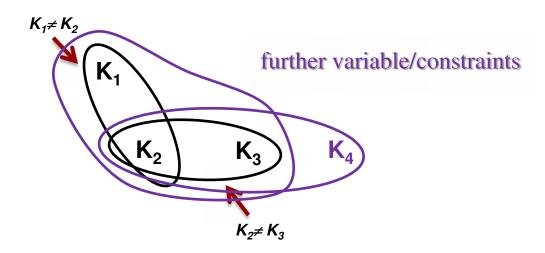
- Based on the values in the constraint relations
- Based on the structure of the constraint scopes



JOIN TREE

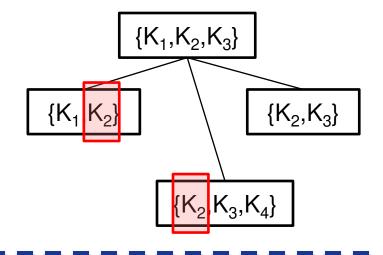
- Vertices correspond to the hyperedges
- Each variable induces a connected subtree

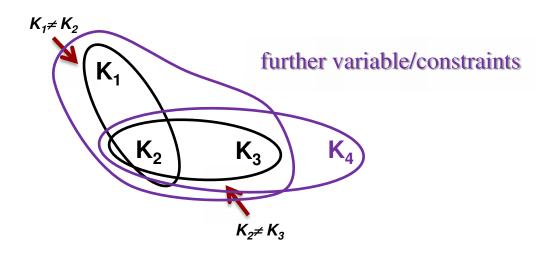


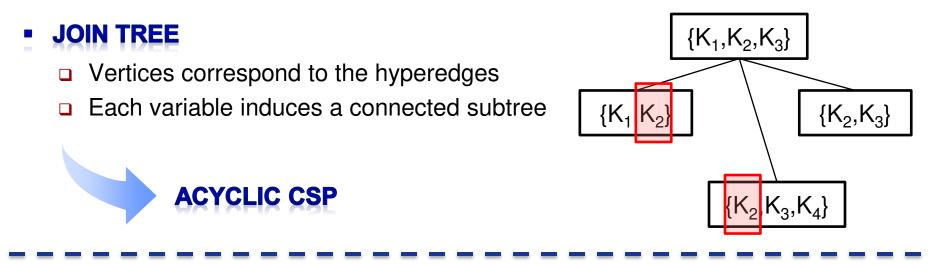


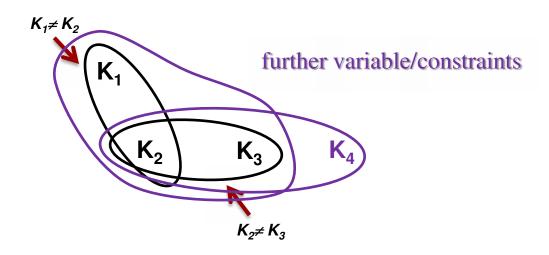
JOIN TREE

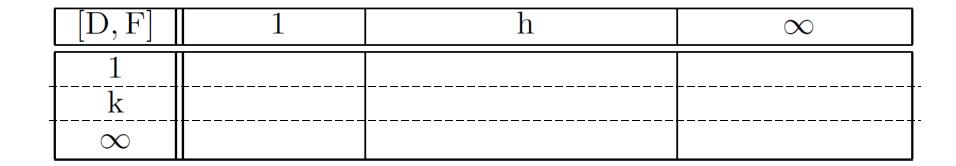
- Vertices correspond to the hyperedges
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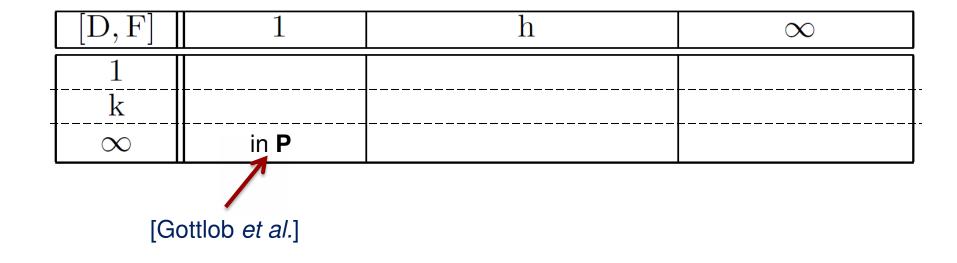






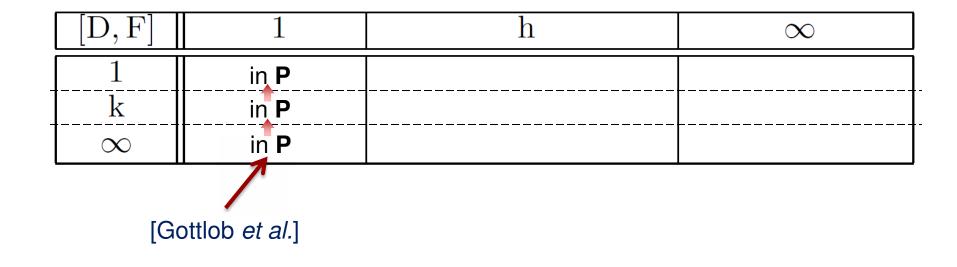
• Restrictions on
$$L = \{\mathcal{F}_1, ..., \mathcal{F}_n\}$$

• $\max_{\mathcal{F} \in L} |\operatorname{dom}(\mathcal{F})| \leq D$
• $|L| \leq F$



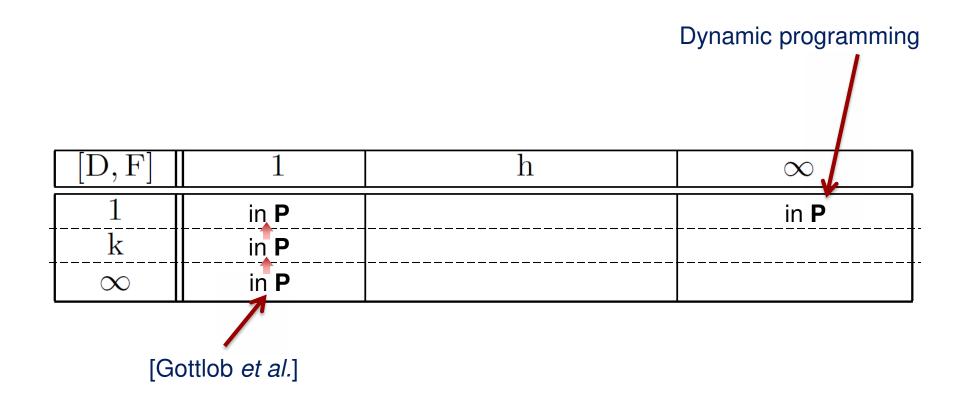
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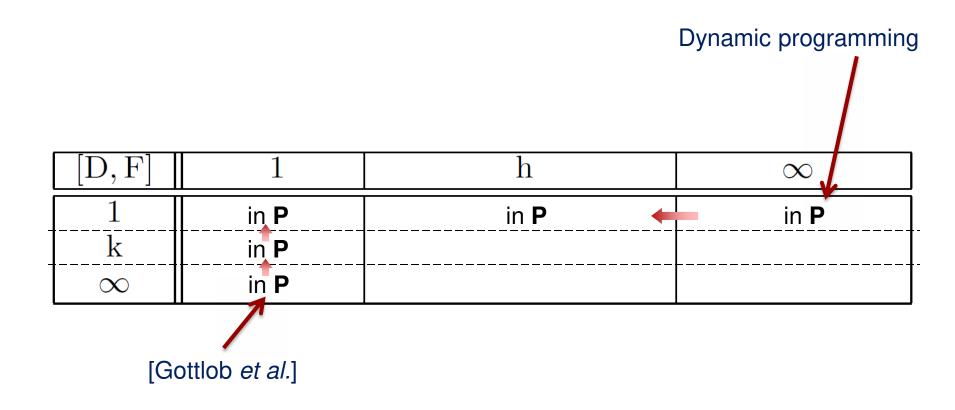
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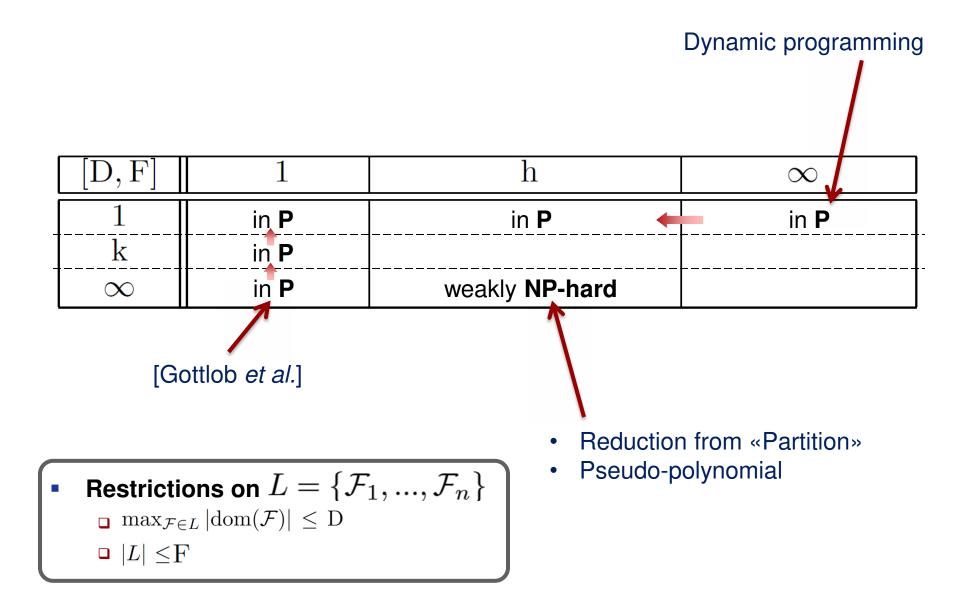
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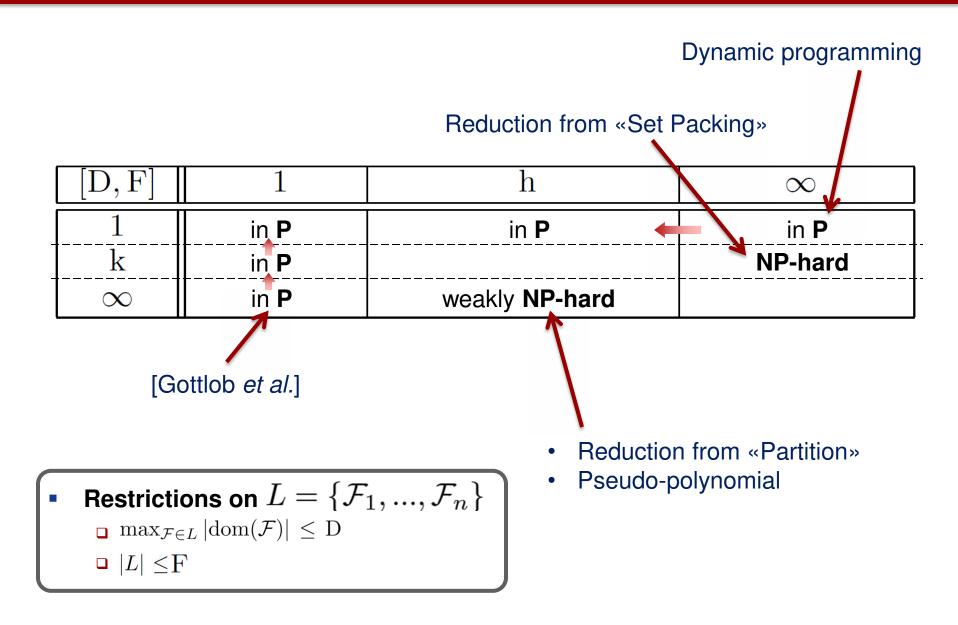
• $\max_{\mathcal{F} \in L} |\operatorname{dom}(\mathcal{F})| \leq D$
• $|L| \leq F$

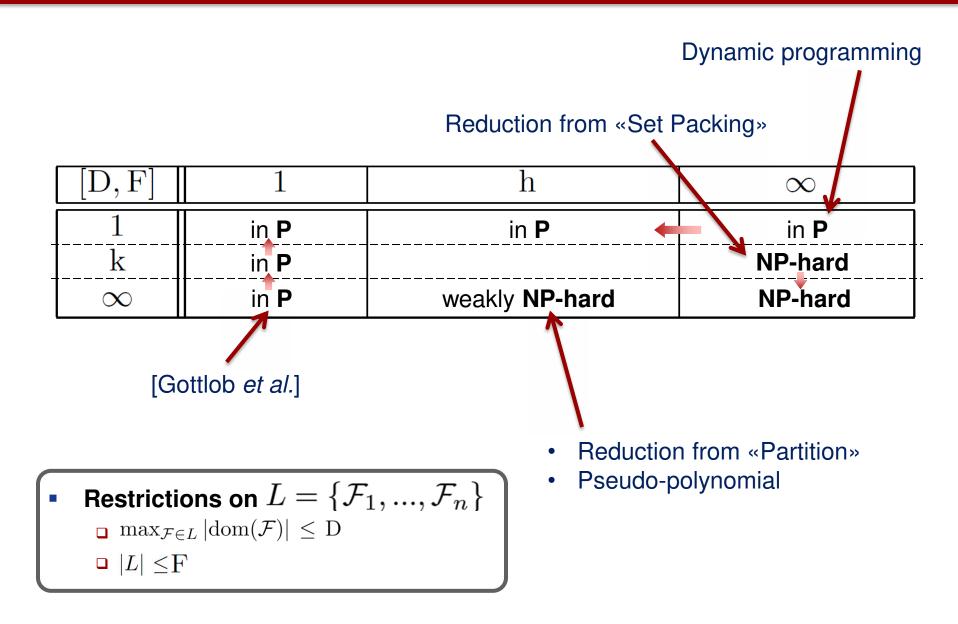


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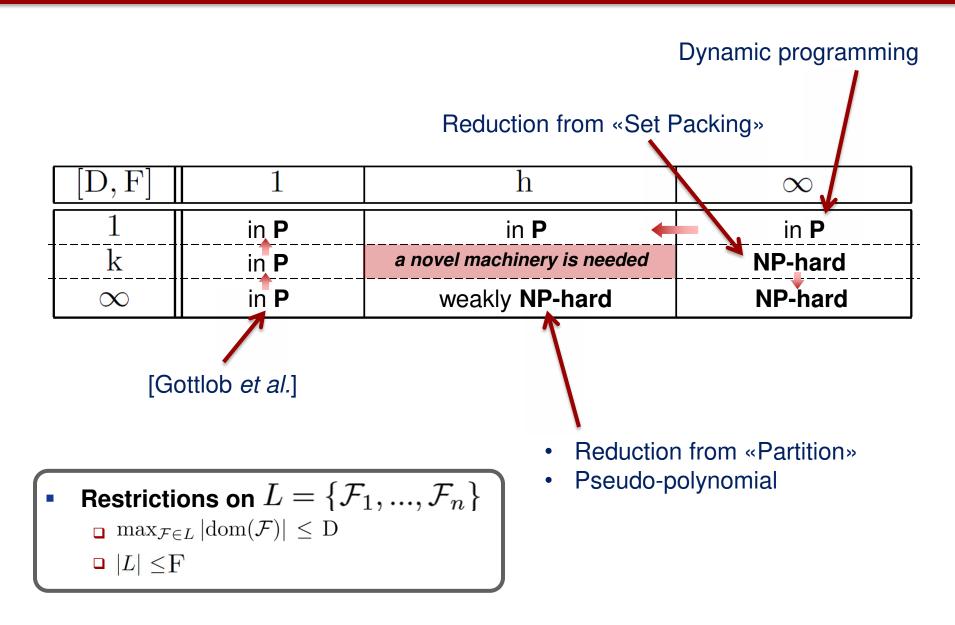
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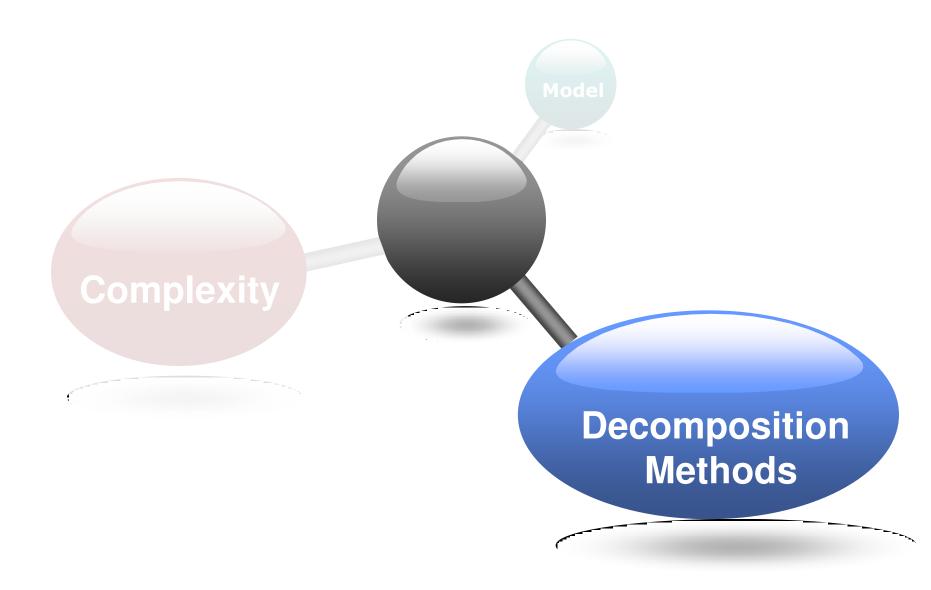




Complexity of Acyclic Instances



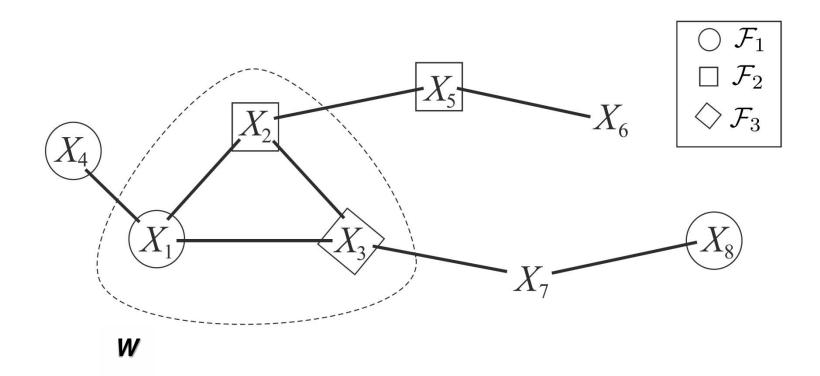
Overview



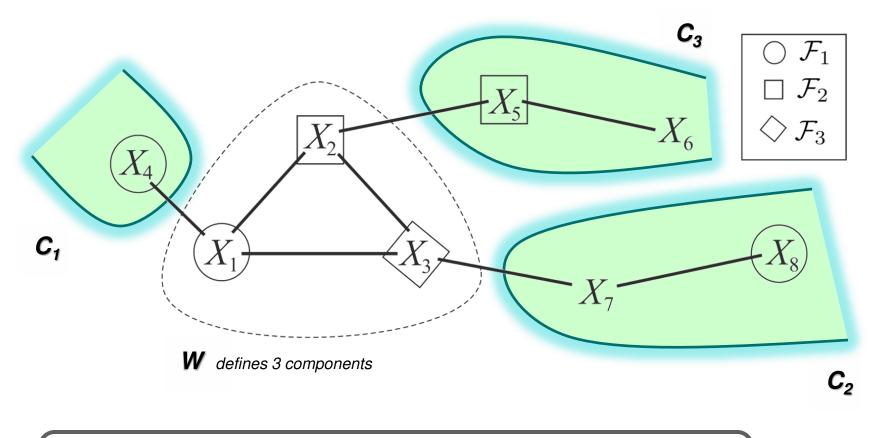
Key Ideas



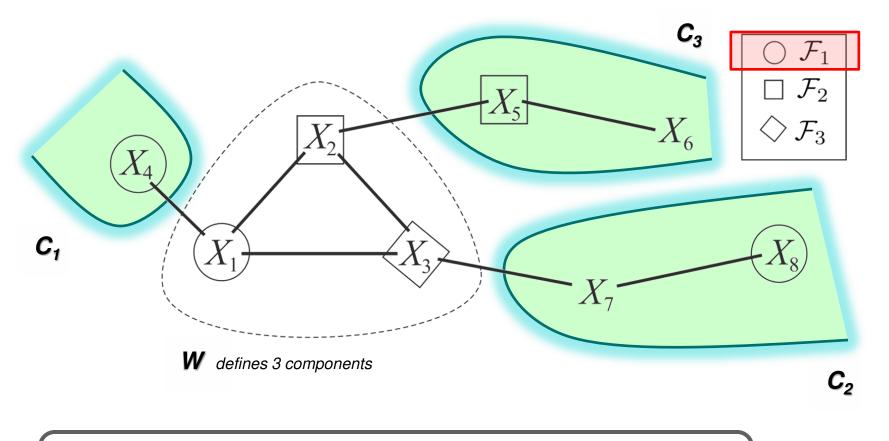
Decomposition Methods



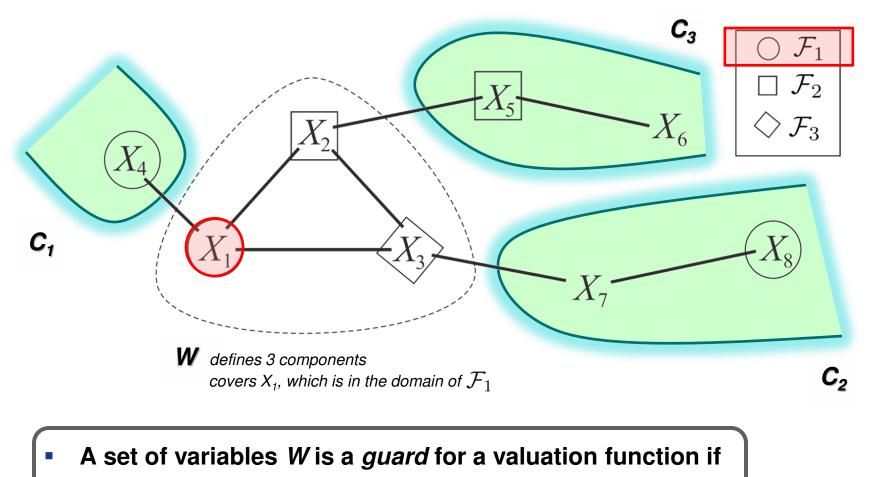
A set of variables W is a guard for a valuation function if

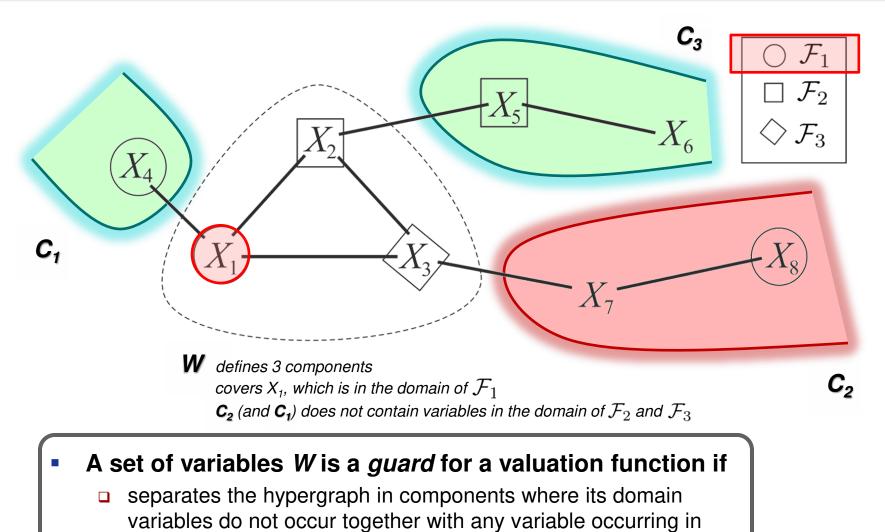


A set of variables *W* is a *guard* for a valuation function if

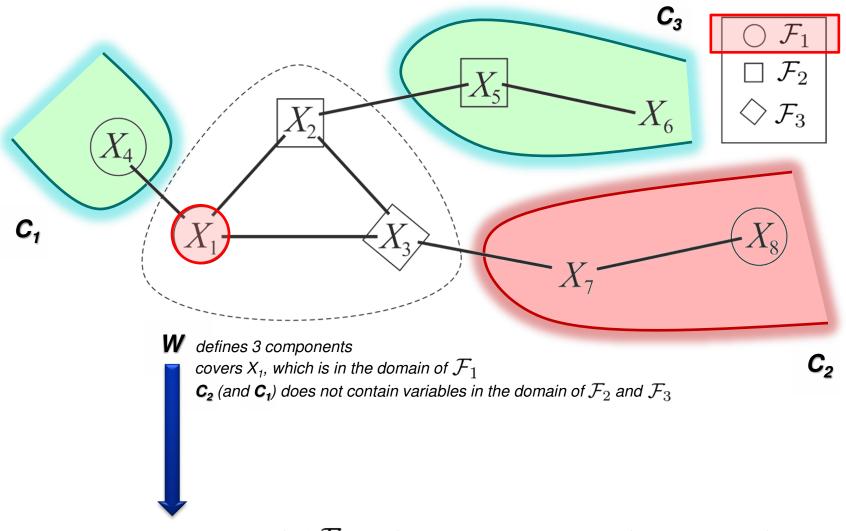


• A set of variables *W* is a *guard* for a valuation function if





other valuation functions



is a guard for \mathcal{F}_1 ; in fact, it is also a guard for the other functions

Key Ideas



Decomposition Methods

Decomposition Methods

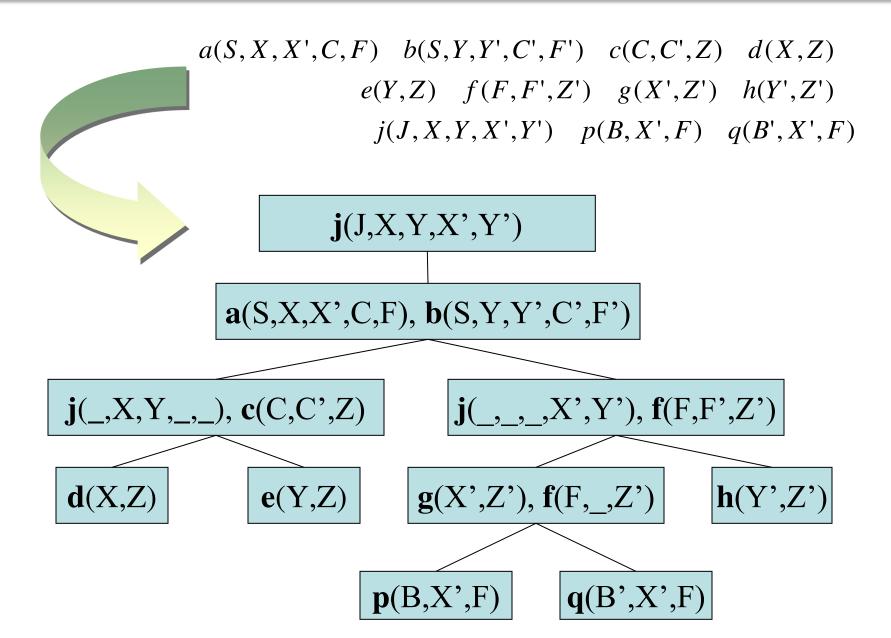
Common Ideas

- Generalize the notion of graph or hypergraph acyclicity
- Associate a width to each instance, expressing its degree of cyclicity
- Polynomial time algorithms for bounded-width CSP instances, running in O(n w+1· logn)
- Bounded-width CSP instances can be recognized in polynomial time
- Bounded-width decompositions can be computed in polynomial time

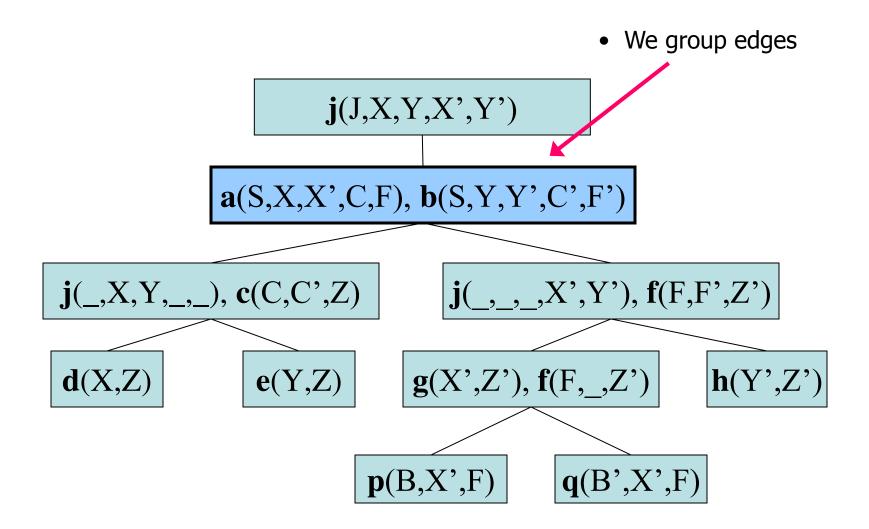
Noticeable Examples

- Tree decompositions
- Generalized) Hypertree decompositions

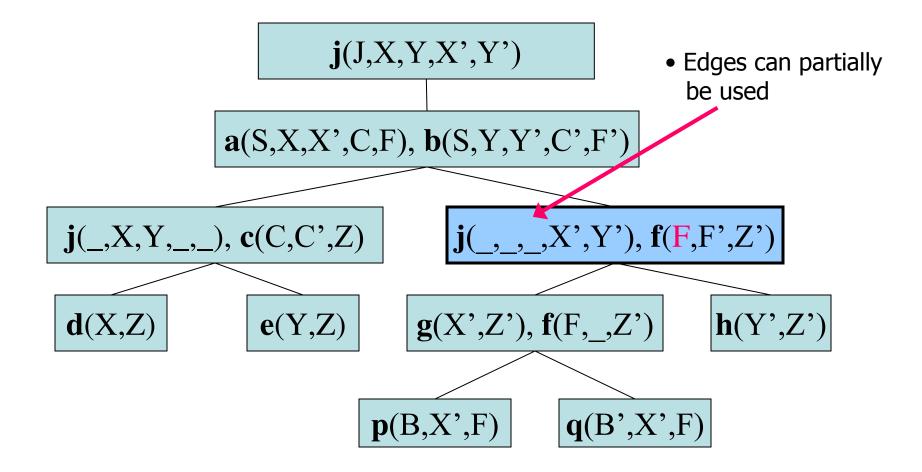
Generalized Hypertree Decompositions



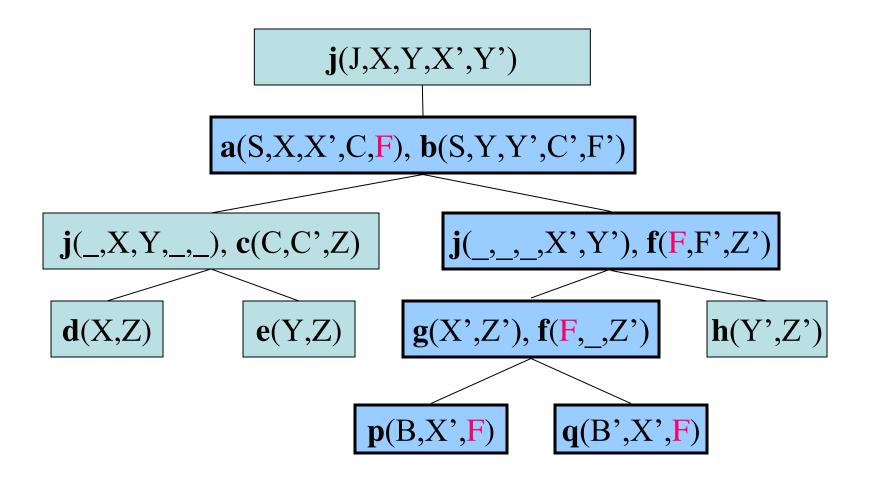
Basic Conditions_(1/2)



Basic Conditions_(2/2)

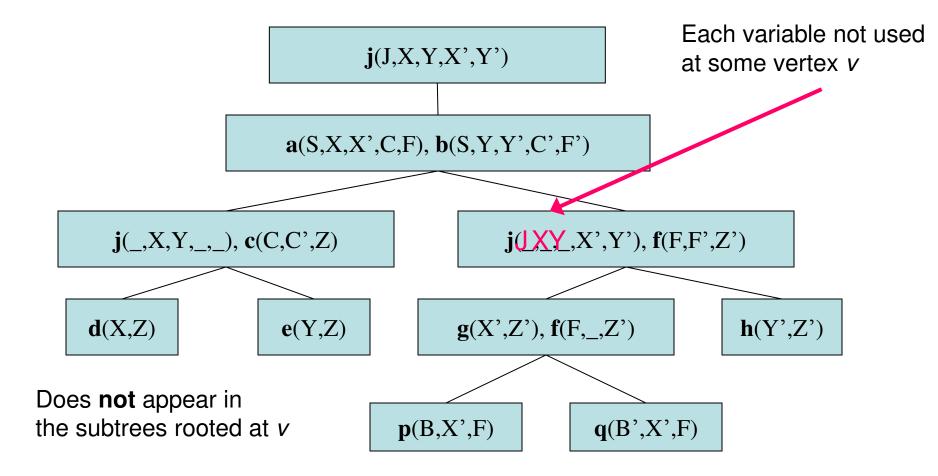


Connectdness Condition



Hypertree Decompositions (HTD)

HTD = Generalized HTD +Special Condition

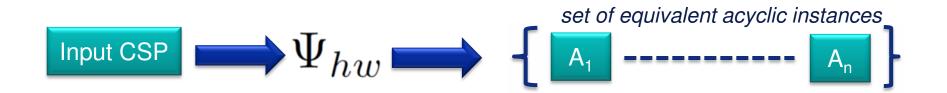


Key Ideas

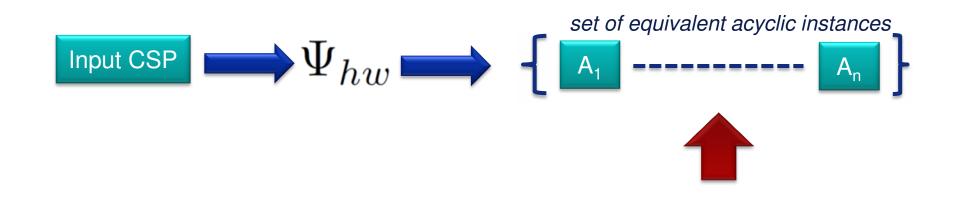


Decomposition Methods

Decomposition Methods and Guards

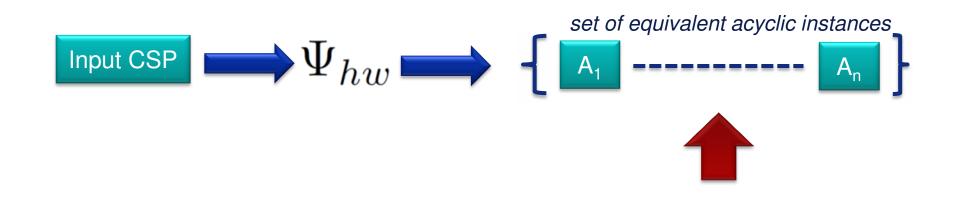


Decomposition Methods and Guards

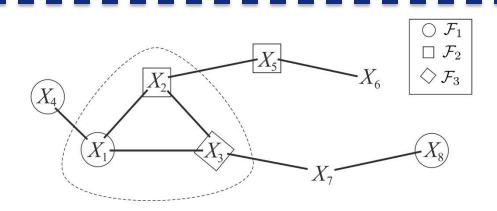


An instance is guarded via the given method if there is an output A_i such that each valution function is guarded by some hyperedge

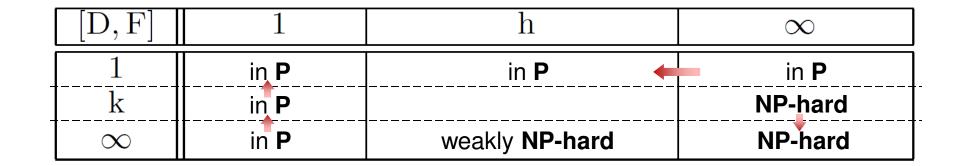
Decomposition Methods and Guards

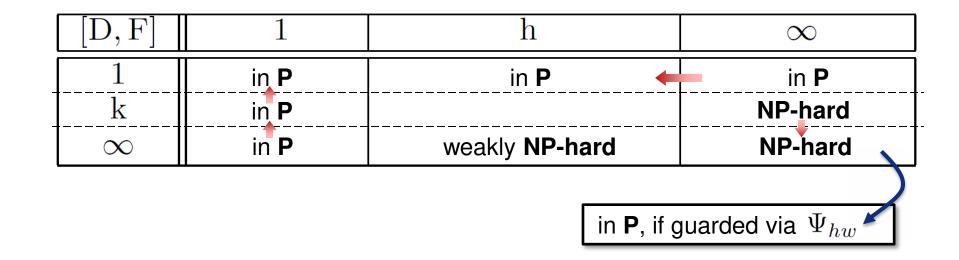


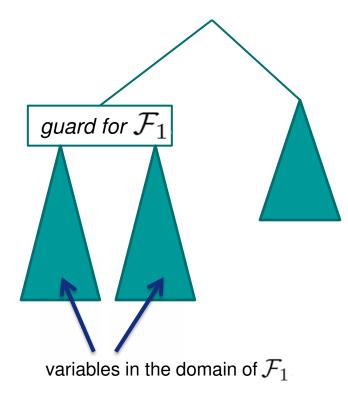
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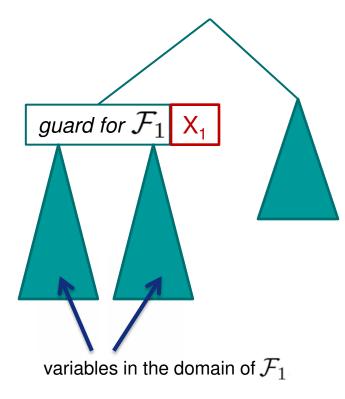
is guarded via hypertree decomposition (width k=3)



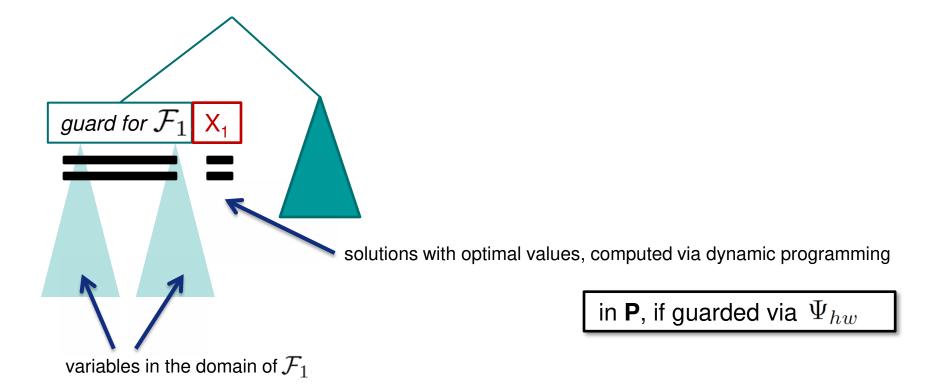


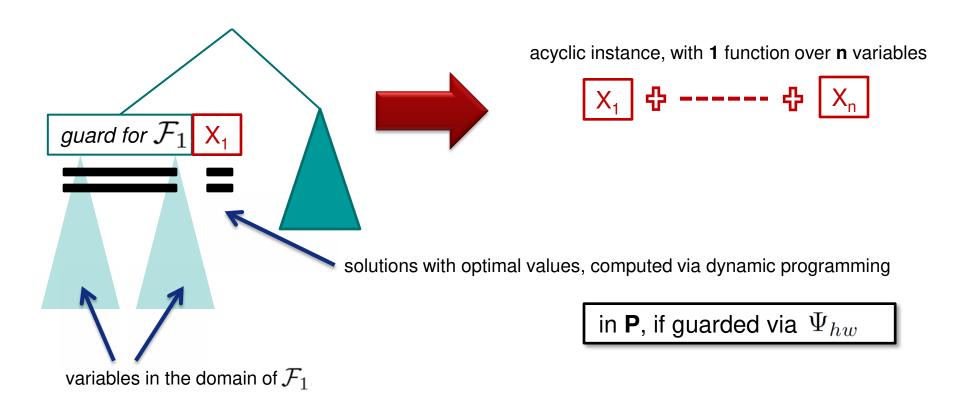


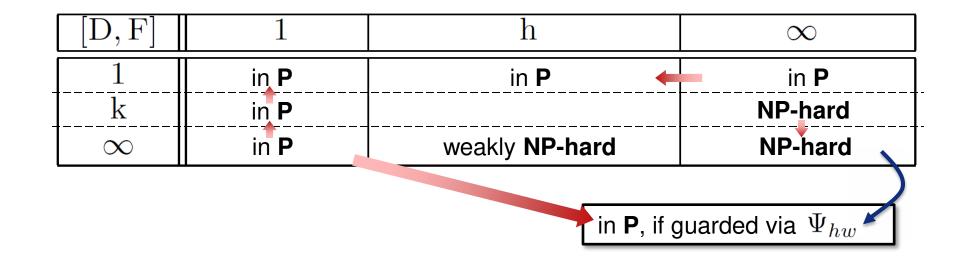
in **P**, if guarded via Ψ_{hw}

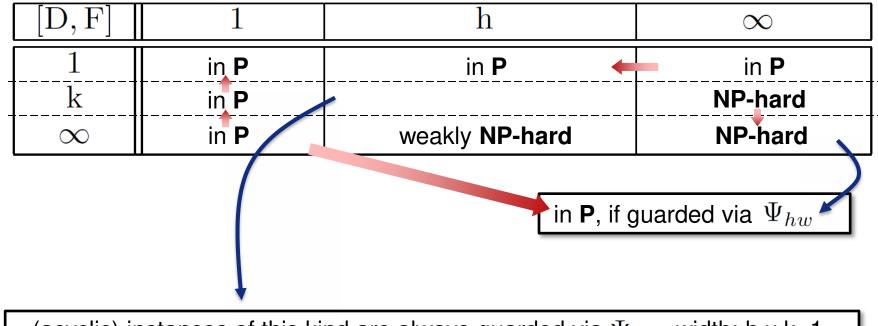


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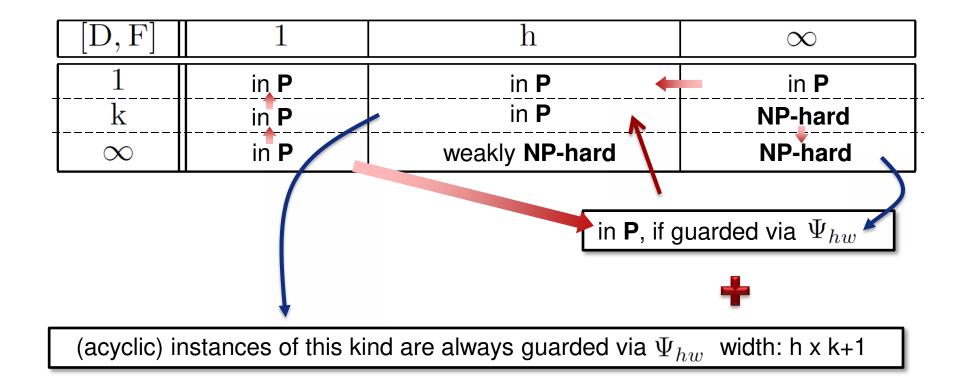








(acyclic) instances of this kind are always guarded via $\Psi_{hw}~$ width: h x k+1



Overview

