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Contactless mode-selective resonance ultrasound spectroscopy: Electromagnetic acoustic resonance

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A noncontacting resonant-ultrasound-spectroscopy (RUS) method for measuring elastic constants and internal friction of conducting materials is described, and applied to monocrystalline copper. This method is called electromagnetic acoustic resonance (EMAR). Contactless acoustic coupling is achieved by energy transduction between the electromagnetic field and the ultrasonic vibrations. A solenoidal coil and static magnetic field induce Lorentz forces on specimen surfaces without using a coupling agent. By changing the field direction, a particular set of vibration modes can be selectively excited and detected, an advantage in identifying the vibration modes of the observed resonance peaks. Contactless coupling allows the measure of intrinsic internal friction free from energy loss associated with contact coupling. The elastic constants and internal friction measured by EMAR are compared with those by the usual RUS method for a rectangular-parallelepiped copper monocrystal. Both methods yielded the same elastic constants despite fewer resonant peaks in the EMAR case. The two methods gave essentially the same shear-mode internal friction, but the RUS method gave higher volume-mode internal friction. © 1999 Acoustical Society of America. [S0001-4966(99)05208-X]

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INTRODUCTION

Resonant ultrasound spectroscopy (RUS) is recognized as a useful method to determine elastic constants of solids, even for a crystal of lower symmetry. The usual RUS configuration uses a sphere, cylinder, or rectangular-parallelepiped specimen, whose dimensions are typically 10 to 1 mm, and two sandwiching transducers that touch the specimen at opposite corners. One transducer generates a continuous wave (cw) oscillation and the other detects ultrasonic oscillation. Sweeping through frequency, one obtains the frequency response of the received amplitude, which consists of a spectrum of resonance peaks. The resonance frequencies are then used in an inverse calculation to find the complete set of elastic constants. Good overviews of RUS were given by Maynard¹ and Migliori and Sarrao.²

To make full use of the attractive feature of RUS that one can obtain all independent elastic constants with a single frequency scan on a single specimen, many efforts have been made both for measurement development and numerical calculation of the resonance frequencies. Concerning technical study and application, Migliori and his co-workers³ made large contributions. They developed instrumentation for acquiring the resonance spectrum of very small specimens ($\sim 0.001 \text{ cm}^3$) as a function of temperature (20–400 K). Kuokkala and Schwarz⁴ used a deposited nickel film for non-contact ultrasonic transduction and measured internal friction of an $\text{Ni}_{80}\text{P}_{20}$ alloy up to 520 K. Ledbetter *et al.*⁵ applied

RUS to measure elastic constants of a boron–aluminum fiber-reinforced composite. More recently, Tanaka *et al.*^{6–8} measured elastic constants of monocrystals of intermetallic compounds, including $\gamma\text{-TiAl}$. Isaak *et al.*⁹ used it to measure the shear-modulus pressure derivative of fused silica and discussed the effect of mass density of pressurizing gases. Concerning numerical calculation, Holland¹⁰ used a Fourier series to approximate deformation in a cubic specimen. Demarest¹¹ used Legendre polynomials and obtained a good solution with a smaller number of harmonic functions. Ohno¹² also used Legendre functions and established an effective method for obtaining free-vibration resonant frequencies.

A key to the successful determination of elastic constants is the correct correspondence between the observed and calculated resonance frequencies. Because the identification of the observed resonance modes is not straightforward, one needs to know beforehand a set of elastic constants near real values. Otherwise, the inversion fails to converge or converges to a false minimum. This forces us to supplement RUS with other methods such as a pulse–echo or rod resonance. To reduce these troubles, several efforts have been made for resonance-peak mode identification. Ohno¹² used different rates of changes of resonant frequencies by varying the specimen size. Maynard¹³ switched assignments of frequencies during the iteration calculation for finding the best fit. Migliori *et al.*³ changed the sample orientation relative to

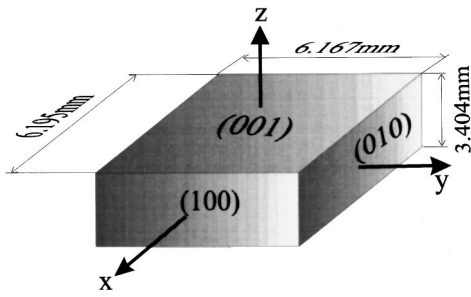


FIG. 1. Rectangular-parallelepiped specimen of copper monocrystal ($6.159 \times 6.167 \times 3.404 \text{ mm}^3$).

the transducers and monitored the signal amplitude. Okamoto *et al.*¹⁴ used multiple detectors attached to different points on the surface to evaluate the vibration symmetry using the multiple outputs. These methods are laborious and sometimes inapplicable for a solid having larger internal friction because broad resonant peaks usually overlap one another. The best way to identify the mode is to independently produce only one group of vibrations, filtering others out. No one reported a method realizing this goal for RUS method.

In the present study, we present a new noncontacting RUS method to selectively excite and detect only one group of vibrations; electromagnetic acoustic resonance (EMAR).^{15–19} A specimen is inserted in a solenoidal coil where a uniform static magnetic field is applied. By driving the coil with a high-power rf burst, electromagnetic body forces occur directly on the specimen surfaces. The same coil works as a receiver. Because the direction and symmetry of the body forces can be easily controlled by changing the geometrical configuration of the static field and the coil, we can generate and detect only a selected subgroup of resonances. The acoustically contactless coupling has an especially important advantage in measuring internal friction. Little energy loss to transducers occurs, which helps us measure intrinsic internal friction. Another outstanding aspect of EMAR is its contactless feasibility at elevated temperatures. The authors¹⁹ made a noncontact monitoring of internal friction evolution in an SiC/Ti composite up to 1000 K. The present study demonstrates the usefulness of EMAR to determine elastic constants and internal friction with a rectangular-parallelepiped copper monocrystal.

I. MODE-SELECTION METHOD

Figure 1 shows the shape and size of the copper monocrystal used in the present study. The x , y , and z axes are defined as shown. Archimedes-method mass density was 8.94 g/cm^3 . The dimension fluctuation was within 0.3%. Measurements were made at ambient temperature.

Figure 2 shows a typical measurement setup. The specimen was inserted into a thin plastic sheet in a solenoidal coil fixed between two permanent-magnet blocks. The solenoidal coil is loose and the specimen is unconstrained. Mechanical specimen-plastic coupling is weak because of no applied force, just specimen mass, and because of large acoustic-impedance mismatch. Thus, this situation can be considered as acoustically noncontacting. The permanent magnets provide the static magnetic field needed for Lorentz-force cou-

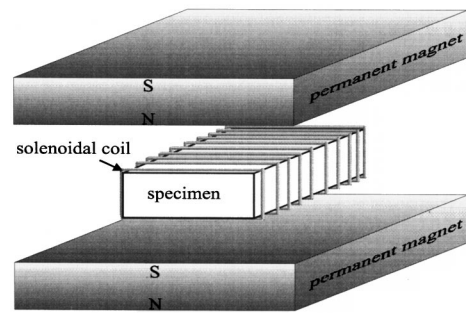


FIG. 2. Typical setup for electromagnetic-acoustic transduction.

pling. The magnetic field was 0.15 T. Driving the coil with a high-power rf burst causes eddy currents on the surfaces, which interact with the magnetic field and generate Lorentz forces. These forces are the sources of the ultrasonic vibration. The reverse mechanism works in the receiving process. Details of the electromagnetic coupling into the acoustic wave can be found elsewhere.^{17–20}

We measured the three configurations shown in Fig. 3: magnetic field parallel to x axis and the resultant Lorentz forces normal to x axis (case I); magnetic field parallel to z axis and Lorentz forces parallel to x axis (case II); and magnetic field parallel to z axis and Lorentz forces parallel to y axis (case III). Considering x -, y -, and z -components of displacement on the surfaces, u , v , and w , respectively, we notice that in case I w on x - y faces can be detected by the reversed-Lorentz-force mechanism only when it is an odd function about z and an even function about x and y , and also v on z - x faces can be detected only when it is an odd function about y and an even function about x and z . Similarly, in case II and case III, the Lorentz-force mechanism

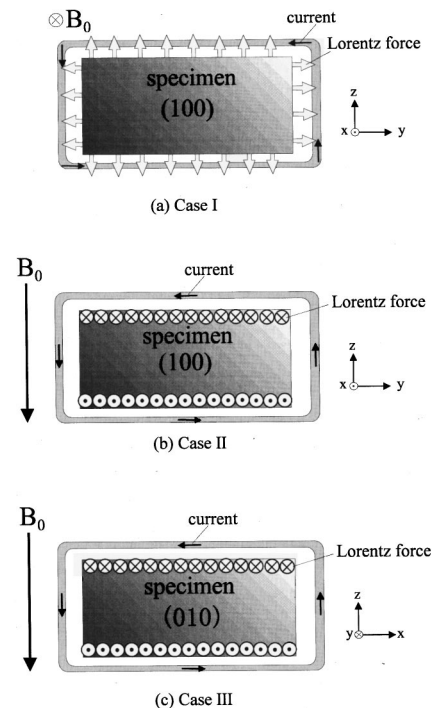


FIG. 3. Three configurations of the coil and static field for generating (a) OD group, (b) OY group, and (c) OX group.

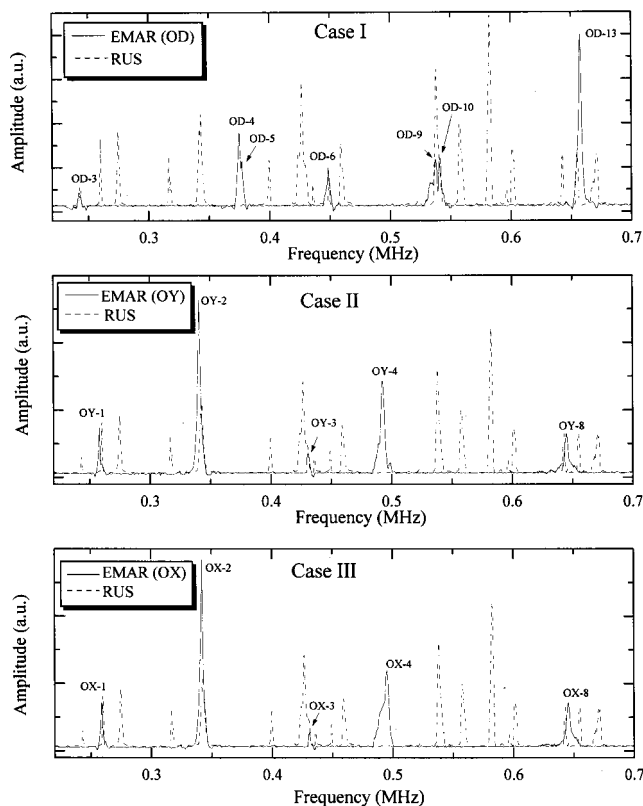


FIG. 4. Resonance spectrum for the three cases. RUS results are shown as a broken line.

works responding to u and w on x - y faces, respectively. To detect them with the same coil, they must be odd functions about z and even functions about x and y . For a rectangular-parallelepiped crystal with symmetry orthorhombic or higher, the vibration modes fall into eight groups, depending on the deformation symmetry.^{11,12} Among them, only the OD group (breathing vibration) satisfies the condition of the deformation symmetry of case I. Similar analysis shows that only the OY group (torsional vibration about the y -axis) can be detected in case II, and the OX group (torsional vibration about the x -axis) in case III. Thus, we can easily select the vibration group by changing the configuration of the measurement setup.

II. THE ELASTIC CONSTANTS

We show the resonance spectra in Fig. 4 for the three cases. For comparison, we made the usual RUS measurement using the same specimen. The detailed configuration of the RUS measurement in the present study is found in Ref. 5. The RUS result is shown in Fig. 4 with a dashed line, which demonstrates detection of many groups of vibration other than the above three. Different EMAR configurations led to different spectra, as expected. We determined the resonance frequencies by fitting the Lorentzian function to a peak and calculating its center. Although the number of the resonant peaks observed with EMAR is fewer than that with RUS, the determination of a set of elastic constants is straightforward. This is because mode identification is much easier in EMAR. For example, the OX-2 and OY-2 resonances occur at close frequencies, and they overlap in RUS measurement as shown

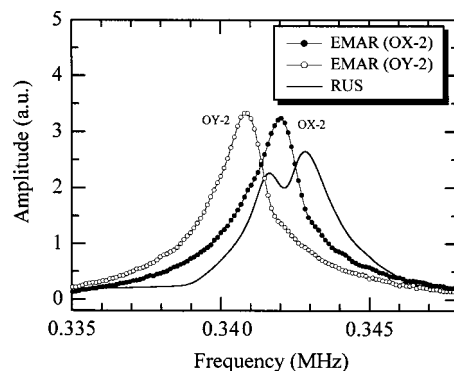


FIG. 5. Resonance spectra measured by EMAR and RUS.

in Fig. 5. However, because EMAR can select either of them, the distinction is easy, giving no ambiguity. We made the inverse calculation developed in previous studies,^{5,12} using the EMAR resonance frequencies, and we obtained the three cubic-symmetry elastic constants. Measured and calculated resonance frequencies are shown in Table I. (Equipment limitations prevented our detecting the lower-frequency modes OD-1 and OD-2.) Measured and calculated frequencies agreed within 0.4%, which is comparable with the fractional error of the specimen dimensions. This iterative calculation needs a first guess of elastic constants. We started the iteration with several sets of elastic constants covering a wide range (C_{11} : 100–230 GPa, C_{12} : 70–150 GPa, C_{44} : 50–150 GPa) and we obtained the same results. We also deduced the elastic constants with the RUS frequencies using a larger number of resonances. In this case, to get correct convergence, we needed better guesses (C_{11} = 168 GPa, C_{12} = 120 GPa, C_{44} = 74 GPa). The measured and calculated frequencies also showed a difference of 0.4%.

Table II shows the elastic constants deduced from the

TABLE I. Measured (f_{meas}) and calculated (f_{calc}) resonance frequencies for EMAR case.

Mode	f_{meas} (MHz)	f_{calc} (MHz)	Difference (%)
OD-1	...	0.183 706	...
OD-2	...	0.211 36	...
OD-3	0.242 323	0.242 549	0.09
OD-4	0.374 916	0.373 805	-0.3
OD-5	0.375 139	0.374 833	-0.08
OD-6	0.448 678	0.450 268	0.35
OD-7	...	0.472 787	...
OD-8	...	0.494 272	...
OD-9	0.535 587	0.533 39	-0.41
OD-10	0.542 134	0.543 198	0.2
OD-11	...	0.567 346	...
OD-12	...	0.643 16	...
OD-13	0.657 429	0.657 74	0.05
OX-1	0.258 849	0.258 944	0.04
OX-2	0.341 657	0.341 765	0.03
OX-3	0.429 726	0.428 519	-0.28
OX-4	0.492 967	0.494 452	0.3
OY-1	0.257 887	0.258 572	0.27
OY-2	0.340 418	0.340 449	0.01
OY-3	0.430 686	0.429 46	-0.28
OY-4	0.492 49	0.493 67	0.24

TABLE II. Elastic constants and internal friction of a copper monocrystal determined by EMAR and RUS.

	C_{ij} (GPa)				$Q_{ij}^{-1} (\times 10^{-3})$	
	EMAR	RUS	Ref. 21	Ref. 22	EMAR	RUS
C_{11}	167.0	168.7	169.7	168.4	1.14	1.74
C_{12}	120.9	121.6	122.6	121.4	0.30	1.34
C_{44}	74.64	75.46	74.49	75.40	2.59	2.46
$B = (C_{11} + 2C_{12})/3$	136.2	137.3	137.3	137.1	0.64	1.50
$C' = (C_{11} - C_{12})/2$	23.05	23.52	23.35	23.50	3.34	2.80
$C_{110,110} = (C_{11} + C_{12} + 2C_{44})/2$	218.6	220.6	220.6	220.3	1.40	1.87
$C_{111,111} = (C_{11} + 2C_{12} + 4C_{44})/3$	235.7	237.9	237.6	237.7	1.47	1.90
$C_{111, \text{arb}} = (C_{11} - C_{12} + C_{44})/3$	40.25	40.84	40.54	40.80	2.88	2.59
C_L	199.6	201.6	1.34	1.84
G	47.54	48.22	2.83	2.57
E	127.8	129.5	2.60	2.46
ν	0.3437	0.3428

two methods and those obtained previously,^{21,22} including other useful elastic-constant combinations obtained from C_{11} , C_{12} , and C_{44} . Using Kröner's method,²³ we calculated the usual isotropic-material averaged-over-direction elastic constants: shear modulus G , longitudinal modulus C_L , Young's modulus E , and Poisson ratio ν . EMAR provided slightly smaller stiffness constants than those measured by the RUS method. This may be caused by the mechanical coupling of RUS, even if it is weak; that is, RUS does not achieve ideal free vibration. To obtain the resonance frequencies of free vibration with RUS, one should minimize the forces from the sandwiching piezoelectric transducers. Applied load partially constrains the sample deformation and increases the resonant frequencies (see Fig. 5), leading to larger elastic constants in general.²⁴ We noticed this influence during measurements when the force was changed. However, since we did our best to minimize the force in the RUS measurement (it may be slightly larger than the sample mass), the influence on the elastic constants should be insignificant.

EMAR does not detect all vibration modes expected for a given configuration (see Fig. 3). For example, OD-11 and OD-12 were missing in case I. These absences occur because the solenoidal coil detects the integral displacement over the specimen faces. If this value is too small, EMAR fails to detect that mode. It would be most useful to develop a model that predicts vibration-mode amplitudes. Then, we could predict low-amplitude modes and further facilitate mode identification.

Another configuration between the coil and static field will make it possible to generate other vibration groups. For example, designing a solenoidal coil where the direction of the driving current is reversed at the center of the sample, one can change the deformation symmetry that can be detected by the coil. Considering that the axial direction of such a coil is along the x axis and the static field is applied along the x axis, displacement w on x - y faces can be detected only if it is an odd function about z , an even function about y , and an odd function about x . This is known as the EX mode¹² (symmetric flexure vibration along the x axis). In principle, one can select one of seven classes of vibration modes with the present method. Not excitable is the EV mode (asymmetric flexure mode).

III. THE INTERNAL FRICTION

EMAR has the important advantage that no energy loss occurs from mechanical contact. Thus, it is ideal for measuring internal friction. The measurement is never affected by uncertain changes of mechanical-coupling conditions, which are accompanied by varying temperature and pressure (or stress). Thus, together with the applicability to *in situ* monitoring, intensive studies have been made using EMAR to detect the evolution of internal friction at elevated temperatures,^{18,19} during deformation,²⁵ recovery,²⁶ and fatigue.²⁷

Here, we compare the internal friction measured by EMAR and RUS. In RUS measurements, internal friction is usually obtained from the resonance peak width: $Q^{-1} = \Delta f/f_r$, where Δf denotes the peak width at the half-power amplitude and f_r resonance frequency. We determined Q^{-1} by fitting a Lorentzian function to the resonance peak and calculating Δf . In EMAR, internal friction can be measured from the resonance ringdown.¹⁶ After an excitation with a burst signal at a resonance frequency, the reverberation exponentially decays with time. This ringdown curve provides the attenuation coefficient α by fitting an exponential function. Figure 6 shows an example of the measured ringdown curve and the fitted exponential function for the OX-2 mode. We show the same measurements on a logarithmic scale. Departure from the fitted curve at low-amplitude region is caused by the background noise. Q^{-1} and α are related by

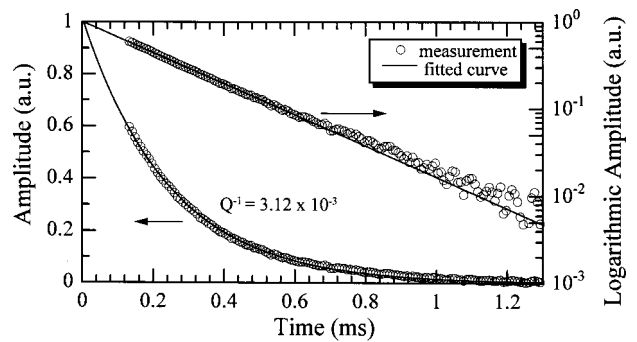


FIG. 6. Measured ringdown curve of OX-2 mode with EMAR. Solid line is a fitted exponential function. Logarithmic-scale amplitude for the same data is also shown.

TABLE III. Internal friction measured by EMAR (Q_{EMAR}^{-1}) and RUS (Q_{RUS}^{-1}).

Mode	$Q_{\text{EMAR}}^{-1}(\times 10^{-3})$	$Q_{\text{RUS}}^{-1}(\times 10^{-3})$	Difference (%)
OD-1	...	2.63	...
OD-2	...	1.36	...
OD-3	2.73	3.52	-29
OD-4	4.46	2.68	39
OD-5	4.33	2.80	35
OD-6	2.10	3.00	-43
OD-7
OD-8
OD-9	3.01	3.04	-1
OD-10	1.44	1.51	-5
OD-11	...	3.38	...
OD-12	...	1.71	...
OD-13	1.55	1.74	-12
OX-1	2.20	2.38	-8
OX-2	3.12	3.78	-21
OX-3	1.94	1.83	6
OX-4	4.01
OY-1	2.42	2.82	-17
OY-2	3.16	3.43	-9
OY-3	2.03	2.06	-1
OY-4	3.87

$Q^{-1} = \alpha / (f_r \pi)$. In the EMAR case, $\Delta f / f_r$ should not be used for Q^{-1} because at a slightly off-resonance frequency the burst wave cannot cancel the ringdown signal adequately, unlike the cw signal, resulting in a broader resonance peak width.

Table III compares Q^{-1} measured by RUS and EMAR. For most modes, Q^{-1} from RUS exceeded that from EMAR. OD-4 and OD-5 modes showed larger Q^{-1} in the EMAR measurement. RUS Q^{-1} values for these modes are not reliable because of the very low resonance intensity (see Fig. 4). Because we can calculate the contribution of each elastic constant to the resonant frequencies, we can also calculate the internal friction for each elastic constant; that is, the internal friction tensor Q_{ij}^{-1} .^{28,29} Q_{ij}^{-1} is useful because one can calculate the internal friction of any oscillation mode. We show Q_{ij}^{-1} thus calculated in Table II. Internal friction for the bulk modulus B was considerably smaller. Because in monocrystal copper a large part of the internal friction is caused by dislocation damping, this observation is easily understood because of the lower mobility of dislocations during hydrostatic loading. The larger internal friction of shear waves (internal friction for C_{44} , C' , $C_{111, \text{arb}}$, and G) than those of longitudinal waves (C_{11} , $C_{110, 110}$, $C_{111, 111}$, and C_L) indicates that shear waves more effectively cause dislocation vibration about their pinning points than do longitudinal waves. This is supported by a simultaneous measurement of shear wave and longitudinal wave internal friction on deforming polycrystalline copper.²⁵ The ratio of internal friction for longitudinal modulus (C_L) and shear modulus (G) was 2.1 for EMAR. The ratio for RUS was 1.4, which is comparable with a ratio 1.6 found by Ledbetter and co-workers²⁸ in studying polycrystalline copper using RUS. Comparing EMAR and RUS, we find a larger RUS Q_{ij}^{-1} for longitudinal waves and, especially, for the bulk modulus; the

Q_{ij}^{-1} for shear waves were comparable. This indicates that vibration modes accompanying volume change cause energy losses into the sandwiching transducers in an RUS measurement, even when the loading force is minimized.

The only possible extra energy loss in EMAR is eddy-current loss in the specimen. Ultrasonic vibration in a uniform magnetic field generates eddy currents within the specimen. This loss is estimated by¹⁶

$$Q_{\text{ed}}^{-1} = \frac{\sigma B_0^2}{\omega \rho}. \quad (1)$$

Here, σ denotes electric conductivity, B_0 flux density of the static field, ω angular frequency, and ρ mass density. Taking $\sigma = 6 \times 10^7$ S/m, $\rho = 8.94$ g/cm³, $f = 0.2$ MHz, and $B_0 = 0.15$ T, we have $Q_{\text{ed}}^{-1} = 1.2 \times 10^{-4}$, which is small compared with the measured Q^{-1} . One may consider that Q_{ed}^{-1} has to be compensated for a material of low Q^{-1} and high conductivity. Fortunately, such a material shows good electromagnetic-acoustic transduction efficiency and we can lower the static magnetic field and thus also Q_{ed}^{-1} .

IV. CONCLUSIONS

- (1) Electromagnetic acoustic resonance (EMAR) works well in measuring elastic constants, even with a smaller number of resonant peaks than in RUS. By changing the geometrical configuration of the coil and static field, one can selectively generate and detect a particular group of vibration modes. This helps identify vibration modes for the elastic-constant determination.
- (2) The inverse calculation using the mode-identified resonant frequencies with EMAR provided one set of elastic constants, being independent of the initial guessed values for iteration. The RUS method can be extremely sensitive to the first guess.
- (3) Elastic constants measured by EMAR were generally smaller than those by RUS with contacting transducers by approximately 1%.
- (4) Except for the pure-shear modes, internal friction measured by EMAR was lower than that by RUS for all useful elastic constant combinations. The difference was substantial for the breathing modes because the RUS method involves energy loss into the transducers, even for minimum coupling load.

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