

# DECIDABILITY OF SECOND-ORDER THEORIES AND AUTOMATA ON INFINITE TREES<sup>1</sup>

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Communicated by Dana Scott, March 21, 1968

**1. Introduction.** In this note we announce the solvability of the decision problem of the (monadic) second-order theory of two successor functions (S2S). This answers a question raised by Büchi [1].

The above decidability result turns out to be very powerful in that many difficult, often seemingly unrelated, decision problems are reducible to it. Thus we are able to deduce: the decidability of the first-order theory of the lattice of closed subsets of the real line (in answer to Grzegorzczuk [6]); the decidability of the second-order theory of countable linearly ordered sets; decidability of theory of countable Boolean algebras with quantification permitted over ideals; and many other results. All the decidability procedures obtained here are elementary recursive in the sense of Kalmar. Due to the fact that we use reductions to a second-order theory, our decidability proofs are very direct. Through appropriate interpretations, the set variables of S2S allow us to talk about all structures in a certain class.

The method of solution involves the development of a theory of finite automata operating on infinite trees. Complete details will be published elsewhere.

**1. Theory of  $n$  successor functions.** Let  $T = \{0, 1\}^*$  be the set of all finite words on  $\{0, 1\}$ . The functions  $r_0(x) = x0$ ,  $r_1(x) = x1$ ,  $x \in T$ , are called the *successor functions*. On  $T$  define the relation  $x \leq y \equiv \exists z [y = xz]$ ; and the lexicographic total ordering  $x \preceq y \equiv x \leq y \vee \exists z \exists u \exists v [x = z0u \wedge y = z1v]$ .

Let  $\Lambda$  denote the empty sequence. A *path*  $\pi$  of  $T$  is a subset  $\pi \subset T$  such that (1)  $\Lambda \in \pi$ ; (2) for each  $x \in \pi$ , either  $x0 \in \pi$  or  $x1 \in \pi$ ; (3) for each  $\Lambda \neq x \in \pi$ , the predecessor node  $y$  of  $x$  is in  $\pi$ .

For  $\mathfrak{M}$  a structure and  $L$  a formal language,  $\text{Th}(\mathfrak{M}, L)$  will denote the theory of  $\mathfrak{M}$  in the language  $L$ . If  $\mathcal{K}$  is a class of similar structures, then  $\text{Th}(\mathcal{K}, L) = \bigcap_{\mathfrak{M} \in \mathcal{K}} \text{Th}(\mathfrak{M}, L)$ . If  $L$  is (monadic) second-order, then we denote  $\text{Th}(\mathfrak{M}, L)$  by  $\text{Th}_2(\mathfrak{M})$ . If  $L'$  is second-order and the set variables are restricted to range over finite subsets of the domain, then  $\text{Th}(\mathfrak{M}, L')$  is called the *weak second-order theory* of  $\mathfrak{M}$ .

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<sup>1</sup> Presented to the American Mathematical Society, July 5, 1967.

$\text{Th}_2(\mathfrak{N}_2)$ , where  $\mathfrak{N}_2 = \langle T, r_0, r_1, \leq, \preceq \rangle$ , is denoted by S2S and called the *second-order theory of two successor functions*. In a similar way we define  $\text{SnS}$ —the second-order theory of  $n$  successor functions, for any  $1 \leq n \leq \omega$ .

**THEOREM 1.1.** *The second-order theory of two successor functions (S2S) is decidable.*

By direct interpretations we get

**COROLLARY 1.2.**  *$\text{SnS}$  is decidable for every  $1 \leq n \leq \omega$ .*

The proof of the decidability of S2S employs automata on infinite trees in a manner to be explained in §3.

**2. Applications.** Let  $\mathfrak{K}_{\leq}^{\omega}$  be the class of all linearly ordered sets  $\langle \bar{A}, \leq \rangle$  such that  $c(\bar{A}) \leq \omega$ .

**THEOREM 2.1.**  *$\text{Th}_2(\mathfrak{K}_{\leq}^{\omega})$ , the second-order theory of countable linearly ordered sets, is decidable.*

**PROOF.** It is readily seen that for every  $\langle \bar{A}, \leq \rangle \in \mathfrak{K}_{\leq}^{\omega}$  there exists a set  $A \subseteq T$  so that  $\langle \bar{A}, \leq \rangle \simeq \langle A, \_ | A \rangle$ . This directly implies decidability of  $\text{Th}_2(\mathfrak{K}_{\leq}^{\omega})$ .

The notion of a subset  $A \subseteq T$  being finite is definable in S2S by a formula  $\text{Fn}(A)$ . It follows that S2S remains decidable upon inclusion of set variables ranging over finite sets. We get as a corollary the following result of Laüchli [7] which strengthens Ehrenfeucht's result [4]. In contrast with the treatment in [4], [7], we get here elementary recursive decision procedures.

**COROLLARY 2.2.** *The weak second-order theory of linearly ordered sets is decidable.*

The following result is related to Büchi's Theorem 1' of [2].

**COROLLARY 2.3.** *The second-order theory of countable well-ordered sets is decidable.*

Let  $\mathfrak{K}_f$  be the class of all structures  $\langle A, f \rangle$ , where  $f: A \rightarrow A$ ; and  $\mathfrak{K}_f^{\omega}$  be the class of all  $\langle A, f \rangle \in \mathfrak{K}_f$  with  $c(A) \leq \omega$ .

**THEOREM 2.4.**  *$\text{Th}_2(\mathfrak{K}_f^{\omega})$ , the second-order theory of a unary function with a countable domain, is decidable.*

The proof is accomplished by reproducing in  $\mathfrak{N}_2$ , through appropriate definitions, the general structure  $\langle A, f \rangle \in \mathfrak{K}_f^{\omega}$ .

COROLLARY 2.5. *The weak second-order theory of a unary function is decidable.*

This is a strengthened version of Ehrenfeucht's result [3], where he announced the decidability of the first-order theory of a unary function.

Let  $CD = \{0, 1\}^\omega$  with product topology. Each path  $\pi \subset T$  is the set of all finite initials of a unique element  $\phi: \omega \rightarrow \{0, 1\}$  of  $CD$ . Thus, we shall view the paths as elements of  $CD$ , and sets of paths as subsets of  $CD$ .

THEOREM 2.6. *Let  $Cl(\mathbf{B}, \mathbf{A})$  be  $[B \subseteq A] \wedge \text{Path}(\mathbf{B})$ , and  $F_\sigma(\mathbf{B}, \mathbf{A})$  be  $\text{Fn}(\mathbf{A} \cap \mathbf{B}) \wedge \text{Path}(\mathbf{B})$ .  $\{\pi \mid \mathfrak{N}_2 \models Cl(\pi, A)\}$  ranges, with  $A \subseteq T$ , over all closed subsets of  $CD$ , and  $\{\pi \mid \mathfrak{N}_2 \models F_\sigma(\pi, A)\}$  ranges over all  $F_\sigma$  subsets of  $CD$ .*

THEOREM 2.7. *Let  $\mathfrak{C} = \langle CD, \leq \rangle$  be Cantor's discontinuum with the usual ordering. Let  $L$  be a language appropriate to  $\mathfrak{C}$  which has (besides the individual variables) set variables,  $C_1, C_2, \dots$ , ranging over closed subsets of  $CD$ , and set variables  $D_1, D_2, \dots$ , ranging over  $F_\sigma$  subsets of  $CD$ .  $\text{Th}(\mathfrak{C}, L)$  is decidable.*

The above result carries over from  $CD$  to the segment  $[0, 1]$  with the usual topology and order. This implies an affirmative answer to Grzegorzczuk's question [6] whether the first-order theory of the lattice of all closed subsets of the real line is decidable.

Denote the class of all Boolean algebras by  $\mathfrak{K}_B$ , and the class of countable Boolean algebras by  $\mathfrak{K}_B^\omega$ . Let  $L_I$  be the language appropriate for  $\mathfrak{K}_B$ , which has set variables ranging over *ideals* of the Boolean algebras.

THEOREM 2.8.  *$\text{Th}(\mathfrak{K}_B^\omega, L_I)$ , the theory of countable Boolean algebras with quantification over ideals, is decidable.*

This follows from Theorem 2.7 and the fact that  $CD$  is the Stone space of the free Boolean algebra with a denumerable number of generators.

As a corollary we get the following improvement of Tarski's result [8]; and of Ershov's result [5, Theorem 9] to the effect that the first-order theory of Boolean algebras with a distinguished *maximal* ideal is decidable.

THEOREM 2.9. *The first-order theory of Boolean algebras with a sequence of distinguished ideals is decidable.*

**3. Automata on infinite trees.** For a mapping  $\phi: A \rightarrow B$ , define  $In(\phi) = \{b \mid b \in B, c(\phi^{-1}(b)) \geq \omega\}$ . In the following,  $\Sigma$  denotes a finite set called the *alphabet*.

**DEFINITION.** A  $\Sigma$ -valued tree is a pair  $(v, T)$  such that  $v: T \rightarrow \Sigma$ . The set of all  $\Sigma$ -trees will be denoted by  $V_\Sigma$ .

**DEFINITION.** A  $\Sigma$ -automaton is a system  $\mathfrak{A} = \langle S, M, S_0, F \rangle$  where  $S$  is a finite set;  $M: S \times \Sigma \rightarrow P(S \times S)$  ( $P(A)$  denotes the set of all subsets of  $A$ );  $S_0 \subseteq S$ ; and  $F \subseteq P(S)$ .

**DEFINITION.** A run of  $\mathfrak{A}$  on the  $\Sigma$ -tree  $t = (v, T)$  is a mapping  $r: T \rightarrow S$  such that for  $y \in T$ ,  $(r(y_0), r(y_1)) \in M(r(y), v(y))$ .

The automaton  $\mathfrak{A}$  accepts  $t$  if there exists an  $\mathfrak{A}$ -run  $r$  on  $t$  such that  $r(\Lambda) \in S_0$ , and for every path  $\pi$  of  $T$ ,  $In(r \upharpoonright \pi) \in F$ . The set  $T(\mathfrak{A})$  of  $\Sigma$ -trees defined by  $\mathfrak{A}$  is  $T(\mathfrak{A}) = \{t \mid t \in V_\Sigma, t \text{ accepted by } \mathfrak{A}\}$ . A set  $A \subseteq V_\Sigma$  is automaton definable if for some  $\mathfrak{A}$ ,  $A = T(\mathfrak{A})$ .

Let  $t = (v, T)$  be a  $\Sigma \times \Sigma_1$ -tree and let  $p(x, y) = x$ . The projection  $p(t)$ , by definition, is the  $\Sigma$ -tree  $(pv, T)$ .

**THEOREM 3.1.** *If  $A, B \subseteq V_\Sigma$  and  $C \subseteq V_{\Sigma \times \Sigma_1}$  are automaton definable, then so are  $A \cup B$ ,  $V_\Sigma - A$ , and  $p(C)$ . Automata defining the latter sets can be effectively obtained from automata defining  $A, B$  and  $C$ .*

**THEOREM 3.2.** *There exists an effective (even elementary-recursive) procedure for deciding for every automaton  $\mathfrak{A}$  whether  $T(\mathfrak{A}) = \emptyset$ .*

For a set  $A \subseteq T$ , let  $\chi_A: T \rightarrow \{0, 1\}$  be the characteristic function of  $A$ . Denote  $\{0, 1\}^n$  by  $\Sigma^n$ ,  $n < \omega$ . With  $\vec{A} = (A_1, \dots, A_n)$ , associate the  $\Sigma^n$ -tree  $(v_{\vec{A}}, T)$  defined by  $v_{\vec{A}}(x) = (\chi_{A_1}(x), \dots, \chi_{A_n}(x))$ ,  $x \in T$ . The mapping  $\tau: \vec{A} \rightarrow (v_{\vec{A}}, T)$  sets up a one-to-one correspondence between  $P(T)^n$  and  $V_{\Sigma^n}$ .

**THEOREM 3.3.** *There exists an (elementary recursive) effective procedure for assigning to every formula  $F(A_1, \dots, A_n)$  of S2S a  $\Sigma^n$ -automaton  $\mathfrak{A}_F$  so that*

$$T(\mathfrak{A}_F) = \tau(\{(A_1, \dots, A_n) \mid \mathfrak{M}_2 \models F(A_1, \dots, A_n)\}).$$

The combination of Theorems 3.2 and 3.3 at once implies the decidability of S2S. In fact, Theorem 3.3 gives us a complete picture of the relations definable in S2S. Through the interpretations used, we also get information about definability in all the theories proved decidable in §2.

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