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Design of Momentum Fractional Stochastic Gradient Descent for Recommender Systems

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ABSTRACT The demand for recommender systems in E-commerce industry has increased tremendously. Efficient recommender systems are being proposed by different E-business companies with the intention to give users accurate and most relevant recommendation of products from huge amount of information. To improve the performance of recommender systems, various stochastic variants of gradient descent based algorithms have been reported. The scalability requirement of recommender systems needs algorithms with fast convergence to generate recommendations of specific items. Using the concepts of fractional calculus, an efficient variant of the stochastic gradient descent (SGD) was developed for fast convergence. Such fractional SGD (F-SGD) is further accelerated by adding a momentum term, thus termed as momentum fractional stochastic gradient descent (mF-SGD). The proposed mF-SGD method is shown to offer improved estimation accuracy and convergence rate, as compared to F-SGD and standard momentum SGD for different proportions of previous gradients, fractional orders, learning rates and number of features.

INDEX TERMS Recommender systems, e-commerce, momentum, fractional calculus, stochastic gradient descent.

I. INTRODUCTION

Nowadays, the need of e-commerce has increased rapidly and captured the businesses' interests in a short time span. At present, people are becoming habitual of using e-commerce applications and e-systems. Variety of available products pose challenges for businesses to full fill users' diverse demands. E-systems provide ease in users' taste management and allow users to explore a variety of options before taking a decision for a specific product. However, it is somehow difficult to get the useful data (information) about products for millions of users from enormous amount of data. To solve this problem, automated recommender systems are used by e-businesses with the intension to give users a precise and relevant recommendation of products.

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Recommender systems are programs and procedures giving useful suggestions to users according to their liking for different products [1], [2]. An important feature of recommender systems is to predict user's interest and liking by analyzing the buying behavior of particular users, in order to give useful recommendations [3]. Recommender system plays a significant role for the customers as well as for service providers. For customers, it is used to find interesting items, to locate appropriate news content [4], discover new products and to explore new options matched with their interests. On the other hand, for service providers, recommender systems are used to promote their products, develop customer trust, obtain more knowledge about customers and enhance sales. Recommender systems have been commonly used in applications such as entertainment (e.g. music and movie recommendations), content (e.g. recommendations for documents, news and e-applications), e-commerce (e.g. recommendation for items to buy such as camera and

books) and services (e.g. travel and houses for rent service recommendations) [5]–[7].

There are different types of recommender systems based on different methods [8]-[13] such as collaborative filtering (CF), content based filtering (CB), demographic, knowledgebased, community-based and hybrid recommender systems. Widely applied techniques among those are CF [14]-[18] and CB [19]–[21]. In CB filtering approach, a system learns to recommend to users the same products that the user preferred in the past [22]. CF has scalability, sparseness and cold start issues whereas CB may provide overspecialized recommendations. In case of CF, recommendation of items for the specific users are based on those items which are mutually liked by other users. CF is also referred to as "people-to-people correlation" in [23]. There are mainly two types of methods applied under CF, memory based (neighborhood) method and model based (latent factor based) method. User to user and item to item relations are identified using neighborhood methods [22].

One of the important methods to determine latent factors is matrix factorization [24], [25]. A rating matrix consisting of user ratings for items is factorized to get latent user and item factors. Since not all users rate all the items, hence the rating matrix is sparse. For a large data set with hundreds of items and millions of users, a large rating-matrix factorization for extraction of latent factors becomes a computationally challenging task. Stochastic gradient descent (SGD) [24] and its variants [26]–[28] are commonly used for matrix factorization of such a large and sparse matrix. SGD has effectively been used for many recommender system problems and challenges [29].

With constantly increasing data sets, new techniques for matrix factorization are required that could increase the convergence speed and estimation accuracy of the recommender systems. For this purpose, fractional calculus based SGD (F-SGD) has been proposed [30]. The performance of the F-SGD can be enhanced through efficient utilization of gradient information. Therefore, in this paper, we propose a momentum version of the F-SGD for matrix factorization in which proportion of previous gradient is used to calculate the current gradient of objective function and thus yield better performance.

A. RELATED WORK

Matrix factorization based methods are one of the most popular methods for dealing with recommender system problems [31]–[33]. These techniques include singular value decomposition [34], probabilistic latent semantic analysis [35], maximum margin matrix factorization [36], [37], alternating least squares [38] and probabilistic matrix factorization [39]. For recommender systems, matrix factorization based algorithms such as stochastic gradient descent (SGD) and alternating least squares (ALS) [29], [40] became much popular due to their performance. For fast matrix factorization coordinate descent techniques [41] based on ALS and momentum based SGD method [26] were suggested.

To enhance convergence speed and estimation accuracy, several variations of SGD [24] and simple gradient descent [42] were proposed. To deal with large datasets, various SGD based scalable methods for matrix factorization were suggested in [26], where performance of SGD based approaches was demonstrated in terms of accuracy of predictions and training time. Asymmetric factor models and biased MF based efficient methods were proposed in [27]. Another SGD based strategy for matrix factorization was proposed in [43], where a learning rate schedule was presented to improve the convergence. Importance of SGD based techniques for large scale matrix factorization for recommender systems was also emphasized in [44]. The SGD based algorithms were also used for matrix completion in [45], based on non-convex matrix factorization. A nonconvex SGD method was proposed in [46] for online matrix completion. An algorithm for the parallelization of SGD by MF was proposed in [47] such as distributed SGD (DSGD). However, as discussed in [48], SGD has not been parallelized for huge datasets yet. Although it is more efficient than ALS with respect to time complexity for a single iteration, it also requires more iterations for achieving a desired model. Another method was also proposed in [28] to parallelize SGD.

The weight update relations for different variants of SGD as mentioned above are based on integer order gradient. To improve the convergence speed further, fractional calculus [49]–[53] based fractional order gradient for the weight update relations of SGD have been developed in [30]. Fractional calculus based adaptive algorithms have been widely applied in diverse domains [54]–[57]. Additionally, momentum fractional least mean square algorithm has recently been developed and applied to solve parameter estimation problems [58, [59] and it has been shown that momentum based adaptive method provide better results than its standard counter-parts.

The superior performance of fractional gradient based adaptive algorithms in terms of accuracy and convergence is well proven in above referenced literature, which motivates the use of momentum fractional adaptive algorithms for recommender systems. With this motivation, in our previous work, we extended SGD to its fractional version based upon fractional calculus and named it fractional stochastic gradient descent (F-SGD) [30]. In standard SGD, integer order gradients are used while in fractional SGD (F-SGD) [30], fractional order gradient of the objective function is calculated in addition to integer order gradient. In this paper, based upon our previous work in [30], we further extend F-SGD for matrix factorization of recommender system rating matrix by incorporating momentum term and compare it with standard F-SGD and momentum SGD (mSGD).

B. OUR CONTRIBUTION

Based on the recent development [59], [30], we propose a new efficient fractional SGD algorithm by adding a momentum term to the standard F-SGD update equation termed as momentum F-SGD (mF-SGD). This variation in the F-SGD offers improvement in the estimation accuracy and convergence behavior of the recommender systems. The weights update procedure for mF-SGD includes percentage of previously calculated gradients in the weight update relation, which improves the convergence speed of mF-SGD relative to standard F-SGD for same learning rate parameters. We show that the proposed algorithm has higher convergence speed as compared to its counter-parts and achieves required estimation accuracy for lesser number of iterations as compared to the mSGD and F-SGD. The main contribution in terms of salient features of the proposed study are:

- The momentum term based F-SGD (mF-SGD) algorithm is presented for future generation recommender systems problem through efficient matrix factorization.
- The mF-SGD effectively exploits the gradient information by utilizing the proportion of previous gradients, α, in current update.
- The proposed scheme provides faster convergence for large value of *α*, while for lower values of *α*, mF-SGD provides better steady state performance.
- The correctness of the proposed approach is verified for small as well as, large datasets by testing it on ML-100K and ML-1M, respectively.
- The effectiveness of the method is validated through comparison with the standard counterparts for different learning rates, momentum weights (α) and fractional order (f_r) values.

C. PAPER OUTLINE

Rest of the paper is organized as follows: brief explanation of recommender systems problem is given in Section II. Section III defines three adaptive strategies along with their derivations and explains specifically the proposed method mF-SGD for dealing with recommender systems. Results and simulations are discussed in Section IV. Section V concludes the paper.

II. PROBLEM STATEMENT

Let $C \in R^{p \times q}$ be a partially filled input rating matrix for recommender systems holding *p* users and *q* items. The objective function for resolving recommender system problem through matrix factorization is

$$G(\boldsymbol{a}, \boldsymbol{b}) = \min_{\substack{\boldsymbol{A} \in R^{k \times p} \\ \boldsymbol{B} \in R^{k \times p}}} \sum_{\substack{(u,i) \in \Omega}} \left(\boldsymbol{C}_{ui} - \boldsymbol{a}_{u}^{T} \boldsymbol{b}_{i} \right)^{2}$$
$$= \min_{\substack{\boldsymbol{A} \in R^{k \times p} \\ \boldsymbol{B} \in R^{k \times p}}} \sum_{\substack{(u,i) \in \Omega}} E_{ui}^{2}$$
(1)

where the error between observed and estimated rating is $E_{ui} = (C_{ui} - a_u^T b_i)$, *a* and *b* are the u^{th} user and i^{th} item column vectors of user features matrix $A(A \in R^{k \times p})$ and the item feature matrix $B(B \in R^{k \times q})$ respectively, *k* denotes number of features for both users and items and Ω represents the specific indices for given ratings.



FIGURE 1. Graphical abstract of the proposed study.

The goal of objective function (1) is to discover factorized matrices A and B from sparse matrix C. The missing rating entries of C are generated through the dot product of A and B, i.e. AB^{T} . Factors of a_{u} for a specific user u, define the amount of interest of a user for a variety of features of an item whereas, factors of b_{i} for a particular item i hold the features for that specific item. Liking of user u for item i is represented by C_{ui} . In subsection A of section III, matrix factorization methods are used to find the matrices A and B using SGD and F-SGD. We propose a new mF-SGD method, which performs matrix factorization for recommender systems based upon momentum F-SGD.

III. ADAPTIVE METHODS FOR RECOMMENDER SYSTEMS

This section describes three adaptive strategies for dealing with recommender systems. The following subsections present the derivations for the standard SGD, fractional SGD and the proposed mF-SGD algorithms.

A. FRACTIONAL SGD

The alternative and recursive weight update expressions using SGD for both user and item feature vectors for the n-th iteration are written as

$$\boldsymbol{a}_{u}(n+1) = \boldsymbol{a}_{u}(n) - \frac{\mu}{2} \frac{\partial G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{a}_{u}}$$
(2)

$$\boldsymbol{b}_{i}(n+1) = \boldsymbol{b}_{i}(n) - \frac{\mu}{2} \frac{\partial G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{b}_{i}}$$
(3)

where μ represents the learning rate parameter.









FIGURE 3. Convergence curves of mSGD for various parametric values.

By taking the gradient of objective function (1) w.r.t user feature vector a_u , we get

$$\frac{\partial G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{a}_{\boldsymbol{u}}} = -2E_{\boldsymbol{u}\boldsymbol{i}}\boldsymbol{b}_{\boldsymbol{i}} \tag{4}$$

Likewise, by calculating the gradient of (1) with respect to item feature vector \boldsymbol{b}_i , we achieve

$$\frac{\partial G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{b}_i} = -2E_{ui}\boldsymbol{a}_u \tag{5}$$

At iteration n, the user and item feature weight update equations are evaluated by putting equations (4) and (5) in (2) and (3) respectively:

$$\boldsymbol{a}_{u}(n+1) = \boldsymbol{a}_{u}(n) + \mu E_{ui}\boldsymbol{b}_{i}(n) \tag{6}$$

$$\boldsymbol{b}_i(n+1) = \boldsymbol{b}_i(n) + \mu E_{ui}\boldsymbol{a}_u(n) \tag{7}$$

The above update equations are derived on the basis of integer order gradient and are standard SGD updates. The SGD updates can be extended to fractional calculus based SGD by incorporating fractional order gradient, in addition to the integer order gradients. This achieves better



convergence rate and estimation accuracy as compared to the standard SGD [30].

In the FSGD method, user feature and item feature vectors are updated as:

$$\boldsymbol{a}_{u}(n+1) = \boldsymbol{a}_{u}(n) + \mu E_{ui}\boldsymbol{b}_{i}(n) - \frac{\mu_{f_{r}}}{2} \frac{\partial^{f_{r}} G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{a}_{u}^{f_{r}}} \quad (8)$$

$$\boldsymbol{b}_{i}(n+1) = \boldsymbol{b}_{i}(n) + \mu E_{ui}\boldsymbol{a}_{u}(n) - \frac{\mu_{f_{r}}}{2} \frac{\partial^{f_{r}} G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{b}_{i}^{f_{r}}} \quad (9)$$

where μ and μ_{f_r} denote the integer and fractional order learning rate parameters of the F-SGD algorithm respectively and f_r is the fractional order such that $0 < f_r < 1$.

For a function $y(t) = t^m$ the fractional derivative with order f_r is declared generally as [60]:

$$\mathcal{D}^{f_r} y(t) = \frac{\Gamma(m+1)}{\Gamma(m-f_r+1)} t^{m-f_r}$$
(10)

where, the fractional (f_r) order gradient is represented by \mathcal{D}^{f_r} operator and Γ denotes a gamma function, represented as:

$$\Gamma(t) = (t-1)! \tag{11}$$



FIGURE 4. Convergence curves of mF-SGD for different f_r and α with k = 10, $\mu = 0.0001$.

by assuming the fractional order gradient of a constant value to be zero. Calculating the fractional order gradient of (1)with respect to the user feature vector and item feature vector respectively and using (10) and (11), we obtain:

$$\frac{\partial^{f_r} G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{a}_u^{f_r}} \cong -2E_{ui} \boldsymbol{b}_i \frac{1}{\Gamma(2-f_r)} \boldsymbol{a}_u^{1-f_r}$$
(12)

$$\frac{\partial^{f_r} G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{b}_i^{f_r}} \cong -2E_{ui}\boldsymbol{a}_u \frac{1}{\Gamma(2-f_r)} \boldsymbol{b}_i^{1-f_r}$$
(13)

After applying expressions (12) and (13) in (8) and (9) we get the F-SGD weight update rules for user features and items features vectors as:

$$a_{u}(n+1) = a_{u}(n) + \mu E_{ui}b_{i}(n) + \frac{\mu_{f_{r}}}{\Gamma(2-f_{r})}E_{ui}b_{i}(n) \odot |a_{u}(n)|^{1-f_{r}}$$
(14)

$$\boldsymbol{b}_{i}(n+1) = \boldsymbol{b}_{i}(n) + \mu E_{ui}\boldsymbol{a}_{u}(n) + \frac{\mu_{f_{r}}}{\Gamma\left(2 - f_{r}\right)} E_{ui}\boldsymbol{a}_{u}(n) \otimes |\boldsymbol{b}_{i}(n)|^{1 - f_{r}}$$
(15)

where the sign \odot denotes element-wise multiplication of two vectors, and to ignore complex entries, absolute value of the vectors is considered. Equations (14) and (15) represent the F-SGD update relations for user and item feature vectors, respectively.

1) MOMENTUM FRACTIONAL SGD

Above mentioned F-SGD can be extended to a faster converging algorithm by introducing a momentum term in the update equation of the F-SGD. We call this proposed algorithm as momentum F-SGD. The momentum term exhibits the percentage of prior gradients instead of merely the current gradients, which is added to the existing weights. Accumulated proportions of preceding gradients help in making convergence and optimal search process faster and avoid trapping in local minima. The weight update expression for the proposed mF-SGD is given as:

$$\hat{w}(n+1) = \hat{w}(n) - v(n+1)$$
 (16)

where \hat{w} are the weights that need to be updated and the term v(n + 1) in known as velocity term which holds the earlier gradients. The velocity vector is equal in dimension



FIGURE 5. Convergence curves of mF-SGD for different f_r and α with k = 30, $\mu = 0.0001$.

as the weight vector and can be calculated as:

$$\mathbf{v}(n+1) = \alpha \mathbf{v}(n) + \mu \mathbf{g}(n) \tag{17}$$

Here in (17), the range of α is between 0 and 1 and it determines the percentage of previous gradients that is used for the current update of expression, μ is learning rate such that $\mu = \mu_{fr}$. g(n) shows the gradient (integer order and fractional order gradient) part of the expression at current iteration and is given as:

$$\boldsymbol{g}(n) = \frac{\partial G\left(\hat{\boldsymbol{w}}\right)}{\partial \hat{\boldsymbol{w}}} + \frac{\partial^{f_r} G\left(\hat{\boldsymbol{w}}\right)}{\partial \hat{\boldsymbol{w}}^{f_r}}$$
(18)

Using Equations. (16), (17) and (18), the updated weight update equations for the proposed mF-SGD for user and item vectors are:

$$a_u(n+1) = a_u(n) - v_1(n+1)$$
 (19)

$$\boldsymbol{b}_{i}(n+1) = \boldsymbol{b}_{i}(n) - \boldsymbol{v}_{2}(n+1)$$
(20)

where $v_1(n + 1)$ and $v_2(n + 1)$ are velocity terms holding previous gradient proportions of a_u and b_i respectively:

$$\mathbf{v_1}(n+1) = \alpha \mathbf{v_1}(n) + \mu \mathbf{g_1}(n) \tag{21}$$

$$\mathbf{v_2}(n+1) = \alpha \mathbf{v_2}(n) + \mu \mathbf{g_2}(n)$$
(22)

While initially $v_1(0) = v_2(0) = 0$ and $g_1(n)$ denote the gradient (integer order and fractional order) of $G w.r.t a_u$ and $g_2(n)$ represent gradient of $G w.r.t b_i$ given in (4), (12) and (5), (13) respectively.

$$\boldsymbol{g_1}(n) = \frac{\partial G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{a}_u} + \frac{\partial^{f_r} G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{a}_u^{f_r}}$$
(23)

$$\boldsymbol{g_2}(n) = \frac{\partial G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{b}_i} + \frac{\partial^{f_r} G(\boldsymbol{a}, \boldsymbol{b})}{\partial \boldsymbol{b}_i^{f_r}}$$
(24)

The procedural steps for implementation of the proposed algorithm to solve recommender systems problem are provided in terms of the pseudo code in Algorithm 1. In case of standard momentum SGD algorithm, fractional gradient is not used. Thus, only integer gradient terms in (23) and (24) are considered. The overall graphical flow of the proposed study is given in Fig. 1.

IV. SIMULATIONS AND RESULTS

This section comprises of simulation parameters and results and discussion sections. Simulation parameters subsection holds dataset particulars and details of parameters involved in the simulation of F-SGD, standard mSGD and proposed



FIGURE 6. Convergence curves of mF-SGD vs F-SGD and mSGD for various α and k = 10.

mF-SGD algorithms. The graphical representation of results and convergence tables are given in Results and Discussion subsection to highlight the performance of the standard and proposed algorithms. This section also includes simulation results of all three methods.

A. SIMULATION PARAMETERS

In this section, simulation parameters used for standard methods like mSGD, F-SGD and the proposed mF-SGD algorithm are presented. The popular dataset, MovieLens 100K [61], is used for testing the performance of recommender systems. The MovieLens 100K dataset includes 100k movie ratings given by 943 users for choosing 1682 movies. Each user has given feedback (ratings) for at least 20 movies. The dataset also contains users' demographic information.

According to the rating matrix of the users and items from the dataset, the column density corresponds to the average rating given for individual item by a set of users and row density corresponds to the average rating given by individual user for a set of items which are given as 59.45 and 106.04, respectively. The rated entries by users for movies are from 1 to 5. The density of the dataset is 6.30%, which is calculated as:

Density = Ratings Given/(No of Users \times No of Items).

In addition to the ML-100K (943 \times 1682) dataset, a larger dataset ML-1M (6040 \times 3952) is also used to verify the viability of the proposed algorithm. Different hyper-parameters are tested for F-SGD, mSGD and mF-SGD algorithms, and their performance is compared in terms of root mean square error (RMSE).

The input rating matrix, which is sparse in nature and factorized into two matrices, is created using the above dataset. The factorized user and item matrices contain latent factors possessed by users and items respectively and are calculated by each method individually. Performance of the methods is analyzed by reconstructing the rating matrix (estimated rating matrix) by means of the dot product of factor matrices and then calculating the RMSE between the original rating matrix and the reconstructed one. The estimated rating matrix



FIGURE 7. Convergence curves of mF-SGD vs F-SGD and mSGD for various α and k = 20.

is dense, which also gives recommendations for the movies not rated in the original matrix. RMSE is represented as:

$$RMSE_{test} = \sqrt{mean\left(\sum_{(u,i)\in\Omega_{test}} E_{ui}^2\right)}$$

For fair comparison of the proposed mF-SGD with F-SGD and mSGD, the parameters for each method are selected empirically after plotting error curves for 200 iterations and choosing the best parameter values in each case. The error curves (Figs 2-9) are obtained by randomly splitting the rating matrix in training and testing sub-matrices and calculating RMSE for each iteration. Different hyper-parameters used by each method are given in Table 1.

1) TUNING OF OPTIMAL LEARNING RATE (μ, μ_{f_r})

The learning rate μ value i.e., 10^{-4} for the given algorithms is empirically chosen after performing a number of experiments

TABLE 1. Tuning parameters for different algorithms.

Name	Symbol	Usage	Algorithms		
Learning rate	μ	Step size for	F-SGD, mF-		
		integer order	SGD, mSGD		
		gradient			
Fractional	μ_{f_r}	Step size for	F-SGD, mF-		
learning rate		fractional order	SGD		
_		gradient			
Fractional	f_r	Fractional order	F-SGD, mF-		
order		of the gradient	SGD		
Features	k	Size of user/item	F-SGD, mF-		
		feature vector	SGD, mSGD		

for different learning rate (μ) values i.e. [0.0001, 0.0005, 0.001, 0.005 and 0.01], using four different values of α i.e. [0.3, 0.5, 0.7 and 0.9] and fractional orders (f_r) i.e. [0.25, 0.5, 0.75 and 0.9] against different (k) features, to accomplish appropriate RMSE value. The values of two learning rate parameters i.e. [fractional order and integer order] are same



FIGURE 8. Convergence curves of mF-SGD vs F-SGD and mSGD for various α and k = 30.



FIGURE 9. RMSE Convergence of mF-SGD, F-SGD and mSGD for ML-1M Dataset.

for fractional order methods, i.e. $\mu_{f_r} = \mu = \mu$. It is observed that a large value of RMSE is obtained when higher values of μ are used, i.e. [0.0005, 0.001, 0.005, and 0.01] or they did not show smooth convergence behavior for various (*k*) values.

2) FEATURE DIMENSION (k) SELECTION

Computational efficiency of the proposed method (mF-SGD) is examined for variations in latent features (k), i.e., [10, 20, 30]. It is observed that the computational complexity increases with the increase in number of features because time consumed by an algorithm primarily depends on the selection of the optimal number of runs and features (k). Algorithms are examined for 200 iterations to estimate the data matrix and to obtain the RMSE. It is also found that all the algorithms perform better when more features e.g., 30 features are used. In Figs 2-5, error curves for k = 10 and 30 are given to show the behavior of the algorithms due to variations in k.

3) SELECTING THE MOMENTUM TERM (α)

Two algorithms i.e. mSGD and mF-SGD involve the momentum term α . Therefore, for both methods, four different values of α are tested, i.e. [0.3, 0.5, 0.7 and 0.9]. The proposed mF-SGD algorithm is evaluated by considering four different values of α i.e. [0.3, 0.5, 0.7 and 0.9] against four fractional orders (f_r) i.e., [0.25, 0.5, 0.75, and 0.9] and learning rates (μ) i.e., [0.0001, 0.0005, 0.001, 0.005 and 0.01]. It is seen

						$\mu = 0.$	0001					
chs		<i>k</i> =	= 10			<i>k</i> =	= 20			<i>k</i> =	= 30	
Epo	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$
	0.25	0.50	0.75	0.90	0.25	0.50	0.75	0.90	0.25	0.50	0.75	0.90
10	3.769	3.769	3.769	3.770	3.770	3.769	3.769	3.769	3.769	3.769	3.769	3.769
20	3.769	3.769	3.766	3.769	3.769	3.769	3.769	3.768	3.769	3.769	3.769	3.768
30	3.767	3.764	3.744	3.759	3.769	3.767	3.764	3.761	3.768	3.768	3.768	3.761
40	3.758	3.738	3.603	3.673	3.767	3.758	3.737	3.696	3.765	3.765	3.760	3.703
50	3.716	3.600	3.136	3.251	3.758	3.714	3.571	3.335	3.753	3.750	3.706	3.369
60	3.532	3.177	2.673	2.714	3.721	3.516	3.093	2.788	3.705	3.678	3.423	2.818
70	3.105	2.747	2.345	2.346	3.562	3.072	2.656	2.405	3.523	3.401	2.910	2.427
80	2.722	2.433	2.102	2.083	3.159	2.684	2.343	2.132	3.135	2.961	2.522	2.149
90	2.436	2.195	1.915	1.885	2.766	2.396	2.109	1.927	2.772	2.614	2.240	1.942
100	2.215	2.008	1.767	1.733	2.471	2.174	1.926	1.769	2.495	2.352	2.027	1.781
110	2.038	1.857	1.647	1.612	2.242	1.997	1.780	1.643	2.278	2.146	1.859	1.654
120	1.893	1.732	1.549	1.514	2.060	1.854	1.662	1.541	2.103	1.980	1.725	1.551
130	1.773	1.629	1.468	1.434	1.911	1.735	1.564	1.458	1.958	1.844	1.616	1.467
140	1.671	1.542	1.400	1.368	1.787	1.635	1.483	1.389	1.837	1.731	1.525	1.397
150	1.585	1.468	1.343	1.314	1.683	1.550	1.415	1.331	1.734	1.635	1.450	1.340
160	1.511	1.405	1.295	1.268	1.594	1.478	1.357	1.283	1.645	1.553	1.386	1.291
170	1.447	1.352	1.254	1.229	1.518	1.416	1.308	1.242	1.569	1.484	1.332	1.250
180	1.391	1.305	1.219	1.196	1.452	1.362	1.266	1.207	1.502	1.423	1.286	1.215
190	1.342	1.265	1.188	1.169	1.396	1.315	1.230	1.178	1.444	1.371	1.247	1.185
200	1.300	1.231	1.163	1.145	1.346	1.275	1.198	1.152	1.393	1.326	1.214	1.159

that faster convergence of mF-SGD is accomplished with the increase in the value of α i.e., 0.7 but at the cost of steady state performance i.e. better steady state is achieved for lower value of α and fast convergence is achieved for higher value of α .

4) SELECTION OF THE FRACTIONAL ORDER (f_r)

The proposed method mF-SGD and FSGD are evaluated for four different values of fractional orders (f_r) i.e., [0.25, 0.5, 0.75, and 0.9], chosen from the range (0, 1). It is noticed that the rate of convergence and the steady state error increases for higher fractional orders e.g., 0.9. The impact of fractional order on the convergence speed and accuracy was explored in [62] using the fractional order in the range of (1, 1.5).

5) SIMULATION ENVIRONMENT

Experiments are executed on a laptop with (Core-i3-4005U @ 1.70 GHz) Processor and 4.00 GB DDR2 RAM. Simulations are carried out in Spyder 2.3.8, release 2015 using Python 2.7.13 (64 bit) on Windows 10 Pro Education (64 bit) operating system.

B. RESULTS AND DISCUSSION

The update rules in the standard SGD based algorithms are based on integer order gradient of the cost function. It is seen that by incorporating the fractional order gradient, the performance of mF-SGD is improved with respect to estimation accuracy and convergence at the cost of a small increase in computational complexity. For the proposed method (mF-SGD), the convergence behaviour is estimated to demonstrate its performance. The fitness achieved in terms of RMSE for three methods (F-SGD, mSGD and mF-SGD) is presented in Tables 2-6 and graphically shown in Figs 2-5 for 200 iterations with different number of features (k), fractional order (f_r) values and previous gradient values (α) using selected learning rate i.e., $\mu = 0.0001$. It is observed from the Tables 2-6 and the learning curves in Figs 2-5 that (mSGD) and (mF-SGD) exhibit faster convergence than F-SGD. Moreover, the convergence rate of momentum based methods increase with the increase in the percentage of previous gradients (α). It is also noticed that in terms of convergence, the proposed mF-SGD method outperforms other algorithms (mSGD and F-SGD) against different parameter values.

It is also demonstrated in Tables 4-6 and depicted in Figs 4-5 that RMSE for mF-SGD decreases significantly for large values of f_r against different values of α and the number of latent features (k). The best RMSE of mF-SGD (0.962) is achieved with $\alpha = 0.7$, $f_r = 0.9$ and for k = 30, which clearly shows its advantage over other counterparts. It is observed that for all the algorithms (mSGD, F-SGD and mF-SGD), RMSE decreases with an increase in the number of features for different parameter values of f_r and α . It is seen from the Figs 2-5 that mF-SGD and mSGD outperform F-SGD in terms of RMSE for various parameter setting.

For comparison purpose, the error curves for the three algorithms for different values of f_r , k and α with optimal

hs	$\mu = 0.0001$												
200		k =	10			<i>k</i> =	= 20			k =	30		
E	$\alpha = 0.3$	$\alpha = 0.5$	$\alpha = 0.7$	$\alpha = 0.9$	$\alpha = 0.3$	$\alpha = 0.5$	$\alpha = 0.7$	$\alpha = 0.9$	$\alpha = 0.3$	$\alpha = 0.5$	$\alpha = 0.7$	$\alpha = 0.9$	
10	3.769	3.769	3.764	3.104	3.769	3.769	3.768	3.118	3.769	3.769	3.769	3.116	
20	3.768	3.763	3.555	1.677	3.769	3.765	3.699	1.684	3.769	3.768	3.741	1.682	
30	3.762	3.696	2.649	1.282	3.767	3.727	2.913	1.284	3.765	3.749	3.139	1.284	
40	3.728	3.298	2.103	1.127	3.755	3.438	2.249	1.125	3.747	3.577	2.360	1.128	
50	3.573	2.725	1.779	1.057	3.693	2.841	1.872	1.053	3.653	3.015	1.938	1.056	
60	3.187	2.337	1.568	1.023	3.454	2.412	1.631	1.016	3.346	2.527	1.674	1.020	
70	2.776	2.065	1.423	1.004	3.020	2.118	1.468	0.996	2.910	2.200	1.497	1.000	
80	2.471	1.864	1.319	0.993	2.647	1.904	1.352	0.985	2.568	1.964	1.373	0.987	
90	2.239	1.709	1.243	0.986	2.372	1.741	1.267	0.977	2.314	1.787	1.283	0.979	
100	2.056	1.588	1.186	0.981	2.160	1.614	1.203	0.972	2.116	1.649	1.216	0.972	
110	1.908	1.492	1.143	0.978	1.992	1.512	1.155	0.969	1.957	1.541	1.165	0.968	
120	1.787	1.413	1.110	0.976	1.855	1.430	1.119	0.968	1.827	1.453	1.127	0.965	
130	1.686	1.349	1.084	0.975	1.742	1.363	1.090	0.967	1.719	1.382	1.097	0.964	
140	1.600	1.295	1.064	0.975	1.647	1.308	1.068	0.968	1.629	1.324	1.074	0.963	
150	1.527	1.251	1.048	0.975	1.567	1.262	1.050	0.969	1.552	1.275	1.055	0.963	
160	1.465	1.214	1.035	0.976	1.499	1.223	1.036	0.972	1.486	1.234	1.040	0.965	
170	1.411	1.182	1.025	0.977	1.440	1.190	1.024	0.974	1.430	1.200	1.028	0.967	
180	1.364	1.156	1.016	0.978	1.389	1.163	1.015	0.977	1.381	1.170	1.018	0.969	
190	1.323	1.133	1.009	0.979	1.345	1.139	1.007	0.980	1.338	1.146	1.010	0.973	
200	1.287	1.113	1.004	0.980	1.306	1.119	1.001	0.984	1.300	1.124	1.003	0.977	

TABLE 3. Convergence comparison of mSGD w.r.t RMSE attained for particular iterations.

learning rate $\mu = 0.0001$ are given in Figs 6-8. The improved performance of proposed method i.e., mF-SGD is visibly shown in Figs 6-8 for different α and f_r values. A RMSE convergence of mF-SGD against F-SGD and mSGD with $(\mu = 0.0001, k = 10 \text{ and } \alpha = 0.3, 0.5, 0.7 \text{ and } 0.9)$ and $f_r = 0.9$ is presented in Figures 6a, 6b, 6c and 6d respectively, the finest convergence can be seen in Figure 6c in which mF-SGD for $\alpha = 0.7$ and $f_r = 0.9$ converge significantly fast and achieved minimum RMSE (0.973) after 200 iterations. Similarly, it is shown in Figures 7a - 7d that mF-SGD also accomplished fast convergence for k = 20 with $(\mu = 0.0001 \text{ and } \alpha = 0.3, 0.5, 0.7 \text{ and } 0.9)$ with fractional order ($f_r = 0.9$) but mF-SGD optimal convergence in terms of RMSE (0.963) for k = 20 is achieved at $\alpha = 0.7$ and $f_r = 0.9$. Likewise, Figures 8a – 8d illustrate the better convergence offered by mF-SGD over F-SGD and mSGD for k = 30 with ($\mu = 0.0001$ and $\alpha = 0.3, 0.5, 0.7$ and 0.9) using fractional order ($f_r = 0.9$), while the minimum convergence in terms of RMSE (0.962) for 30 features is achieved for $\alpha = 0.7$ and $f_r = 0.9$. In Figures 6d, 7d and 8d RMSE curves for the proposed mF-SGD are early stopped at about 100 iterations to avoid over-fitting.

Furthermore, it is observed that for different features (k = 10, 20, 30), F-SGD and mSGD achieved the minimum RMSE after about 200 iterations, while mF-SGD takes a smaller number of iterations. It is also seen that the momentum based algorithms have shown improved performance in terms of RMSE for a large k. It is observed that after 200 iterations, bigger value of α and a large f_r leads to a smaller

RMSE except for $\alpha = 0.9$. It is also observed that for the proposed method (mF-SGD), a large value of f_r with higher value of α speeds up the convergence. In addition, increasing the f_r value leads to a small increase in the accuracy.

A Comprehensive set of investigations of the algorithms (mF-SGD, mSGD and F-SGD) are carried out for bigger dataset i.e., ML-1M (1-million), for different values of α i.e. [0.3, 0.5, 0.7 and 0.9], fractional order (f_r) i.e., [0.3, 0.5, 0.75, and 0.9] and learning rates (μ) i.e., [0.0001, 0.0005, 0.001, 0.005 and 0.01] against 30 features. The results achieved by mF-SGD, mSGD and F-SGD based on optimal parameters for the ML-1M dataset are given in the Fig 9.

Similar behavior (as that for the ML-100k dataset) in terms of convergence is observed for the ML-1M dataset. The optimal learning rate (0.0001) chosen for the bigger dataset is the same as that for the smaller dataset. It was noticed that all the compared methods show divergence or increasing trend in terms of RMSE for bigger values of learning rate μ i.e. [0.0005, 0.001, 0.005, and 0.01] against different features. The proposed algorithm performs better for higher values of both the fractional order f_r and weight α . It is shown that fast convergence of mFSGD is achieved for a large value of α but with the compromise of steady state performance. The best RMSE value achieved by the proposed algorithm for the ML-1M dataset is 0.887 for $\alpha = 0.7, f_r = 0.9$ after 150 iterations, whereas, the optimal RMSE values accomplished by mSGD and F-SGD after 200 iterations are 0.897 for $\alpha = 0.7$ and 0.930 for $f_r = 0.9$ respectively. However, for $\alpha = 0.9$, mF-SGD has fastest initial convergence than mSGD

IS		<i>α</i> =	0.3			<i>α</i> =	0.5			<i>α</i> =	0.7			<i>α</i> =	0.9	
poct	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$
E	0.25	0.50	0.75	0.90	0.25	0.50	0.75	0.90	0.25	0.50	0.75	0.90	0.25	0.50	0.75	0.90
10	3.769	3.769	3.768	3.770	3.769	3.769	3.768	3.767	3.761	3.764	3.747	3.707	2.427	2.068	1.928	1.797
20	3.767	3.765	3.750	3.762	3.766	3.755	3.685	3.576	3.116	3.083	2.556	2.305	1.364	1.252	1.186	1.152
30	3.752	3.718	3.503	3.600	3.700	3.419	2.801	2.576	2.163	2.090	1.808	1.673	1.101	1.064	1.035	1.027
40	3.612	3.320	2.790	2.850	3.042	2.589	2.163	2.015	1.718	1.642	1.463	1.382	1.024	1.012	0.993	0.991
50	3.044	2.697	2.307	2.304	2.396	2.107	1.803	1.692	1.463	1.393	1.276	1.227	0.998	0.993	0.979	0.980
60	2.551	2.290	1.990	1.964	2.006	1.803	1.573	1.488	1.303	1.244	1.167	1.137	0.987	0.986	0.974	0.976
70	2.216	2.008	1.767	1.733	1.746	1.594	1.417	1.350	1.200	1.153	1.100	1.083	0.982	0.982	0.972	0.975
80	1.973	1.801	1.603	1.568	1.562	1.445	1.307	1.255	1.132	1.097	1.059	1.049	0.980	0.981	0.972	0.976
90	1.789	1.643	1.479	1.445	1.428	1.336	1.228	1.186	1.087	1.061	1.033	1.027	0.980	0.981	0.973	0.978
100	1.646	1.520	1.383	1.352	1.327	1.255	1.170	1.137	1.056	1.038	1.016	1.012	0.981	0.983	0.976	0.981
110	1.531	1.423	1.308	1.280	1.250	1.194	1.128	1.100	1.036	1.023	1.004	1.001	0.981	0.985	0.978	0.983
120	1.438	1.345	1.248	1.224	1.191	1.149	1.096	1.073	1.021	1.012	0.996	0.993	0.982	0.987	0.980	0.986
130	1.363	1.282	1.201	1.180	1.147	1.114	1.072	1.053	1.010	1.005	0.990	0.987	0.984	0.990	0.983	0.989
140	1.300	1.231	1.163	1.145	1.112	1.088	1.053	1.037	1.003	0.999	0.986	0.983	0.986	0.992	0.986	0.992
150	1.249	1.189	1.132	1.117	1.085	1.068	1.039	1.025	0.997	0.995	0.983	0.979	0.988	0.995	0.989	0.996
160	1.206	1.155	1.107	1.094	1.064	1.052	1.027	1.015	0.993	0.992	0.980	0.977	0.990	0.998	0.992	0.999
170	1.171	1.127	1.086	1.075	1.048	1.040	1.019	1.007	0.990	0.990	0.979	0.975	0.992	1.000	0.995	1.002
180	1.142	1.103	1.070	1.060	1.035	1.030	1.012	1.001	0.987	0.988	0.978	0.974	0.994	1.003	0.997	1.006
190	1.117	1.084	1.056	1.048	1.025	1.022	1.006	0.996	0.985	0.987	0.977	0.974	0.996	1.006	1.000	1.009
200	1.097	1.068	1.044	1.038	1.017	1.016	1.001	0.992	0.984	0.985	0.977	0.973	0.998	1.009	1.003	1.012

TABLE 4. Convergence comparison of mF -SGD w.r.t RMSE attained for particular iterations with $k = 10, \mu = 0.0001$.

TABLE 5. Convergence comparison of mF-SGD w.r.t RMSE attained for particular iterations with k = 20, $\mu = 0.0001$.

IS	$\alpha = 0.3$				$\alpha = 0.5$					$\alpha =$	0.7		$\alpha = 0.9$			
poct	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$	$f_r =$
El	0.25	0.50	0.75	0.90	0.25	0.50	0.75	0.90	0.25	0.50	0.75	0.90	0.25	0.50	0.75	0.90
10	3.769	3.769	3.769	3.769	3.769	3.768	3.769	3.769	3.767	3.764	3.760	3.737	2.442	2.301	2.024	1.805
20	3.768	3.768	3.767	3.761	3.764	3.751	3.727	3.712	3.514	3.193	2.783	2.427	1.333	1.308	1.206	1.153
30	3.758	3.754	3.734	3.609	3.674	3.408	3.005	2.840	2.408	2.177	1.908	1.731	1.079	1.079	1.044	1.027
40	3.680	3.618	3.357	2.874	2.938	2.601	2.285	2.153	1.870	1.711	1.518	1.414	1.011	1.014	0.998	0.989
50	3.255	3.039	2.674	2.328	2.329	2.131	1.887	1.778	1.567	1.449	1.309	1.245	0.988	0.990	0.980	0.974
60	2.721	2.530	2.242	1.987	1.960	1.829	1.634	1.545	1.378	1.289	1.187	1.147	0.977	0.978	0.972	0.967
70	2.353	2.190	1.951	1.754	1.712	1.621	1.463	1.390	1.254	1.187	1.114	1.088	0.970	0.973	0.969	0.965
80	2.087	1.945	1.743	1.586	1.535	1.470	1.343	1.283	1.171	1.120	1.068	1.051	0.966	0.972	0.970	0.968
90	1.885	1.761	1.588	1.461	1.405	1.359	1.255	1.207	1.114	1.075	1.038	1.026	0.964	0.973	0.973	0.973
100	1.728	1.619	1.469	1.366	1.308	1.275	1.191	1.151	1.075	1.046	1.018	1.009	0.963	0.976	0.978	0.979
110	1.602	1.506	1.377	1.292	1.234	1.211	1.143	1.110	1.048	1.025	1.004	0.997	0.964	0.981	0.984	0.987
120	1.500	1.416	1.304	1.234	1.178	1.162	1.107	1.080	1.028	1.010	0.994	0.988	0.966	0.986	0.991	0.994
130	1.417	1.342	1.246	1.188	1.135	1.124	1.079	1.056	1.014	0.999	0.987	0.981	0.969	0.992	0.997	1.002
140	1.348	1.282	1.200	1.151	1.102	1.095	1.058	1.038	1.003	0.991	0.982	0.976	0.973	0.998	1.004	1.010
150	1.290	1.233	1.162	1.121	1.077	1.072	1.041	1.025	0.996	0.986	0.978	0.972	0.977	1.004	1.011	1.017
160	1.242	1.192	1.131	1.097	1.057	1.054	1.028	1.014	0.990	0.981	0.975	0.969	0.981	1.010	1.017	1.024
170	1.203	1.158	1.106	1.077	1.042	1.039	1.018	1.005	0.985	0.978	0.973	0.967	0.985	1.016	1.024	1.032
180	1.169	1.130	1.085	1.061	1.030	1.027	1.009	0.998	0.982	0.975	0.971	0.965	0.990	1.021	1.030	1.039
190	1.141	1.107	1.068	1.047	1.020	1.018	1.002	0.992	0.979	0.974	0.970	0.964	0.994	1.027	1.036	1.045
200	1.117	1.088	1.054	1.036	1.012	1.010	0.997	0.987	0.977	0.972	0.969	0.963	0.999	1.033	1.042	1.052

and F-SGD. For about 55 early iterations mF-SGD remained convergent but it starts diverging for subsequent iterations. Whereas, mSDG achieved minimum convergence for

 $\alpha = 0.9$, which is attained 30 iterations later than mF-SGD but starts diverging after around 100 iterations. On the other hand mF-SGD exhibits slow initial convergent for $\alpha = 0.7$

S		α =	0.3			α =	0.5			α =	0.7		$\alpha = 0.9$			
Epoch	$f_r = 0.25$	$f_r = 0.50$	$f_r = 0.75$	<i>f_r</i> = 0.90	$f_r = 0.25$	$f_r = 0.50$	$f_r = 0.75$	$f_r = 0.90$	$f_r = 0.25$	$f_r = 0.50$	$f_r = 0.75$	<i>f</i> _{<i>r</i>} = 0.90	$f_r = 0.25$	$f_r = 0.50$	$f_r = 0.75$	$f_r = 0.90$
10	3.769	3.769	3.769	3.769	3.769	3.769	3.769	3.768	3.768	3.768	3.765	3.752	2.755	2.360	2.094	1.903
20	3.769	3.768	3.766	3.764	3.767	3.765	3.749	3.683	3.685	3.562	2.983	2.533	1.446	1.303	1.227	1.172
30	3.765	3.759	3.728	3.658	3.736	3.672	3.216	2.761	2.619	2.363	2.014	1.776	1.129	1.073	1.051	1.033
40	3.736	3.677	3.321	2.979	3.319	2.946	2.402	2.123	1.973	1.801	1.585	1.439	1.032	1.007	0.999	0.993
50	3.539	3.206	2.648	2.392	2.602	2.345	1.960	1.766	1.622	1.499	1.353	1.260	0.997	0.983	0.978	0.975
60	2.984	2.655	2.227	2.030	2.164	1.978	1.683	1.541	1.407	1.318	1.217	1.157	0.982	0.971	0.967	0.966
70	2.539	2.287	1.942	1.785	1.872	1.731	1.497	1.390	1.269	1.205	1.134	1.094	0.975	0.964	0.962	0.962
80	2.228	2.024	1.738	1.609	1.666	1.555	1.366	1.286	1.177	1.132	1.081	1.055	0.970	0.960	0.961	0.962
90	1.998	1.827	1.586	1.479	1.513	1.426	1.272	1.211	1.116	1.084	1.047	1.030	0.968	0.959	0.963	0.966
100	1.821	1.675	1.469	1.381	1.397	1.329	1.203	1.156	1.075	1.052	1.025	1.012	0.968	0.959	0.967	0.972
110	1.681	1.555	1.378	1.304	1.308	1.255	1.152	1.116	1.047	1.030	1.009	0.999	0.969	0.962	0.972	0.979
120	1.568	1.458	1.306	1.244	1.238	1.197	1.114	1.085	1.027	1.014	0.998	0.990	0.973	0.966	0.979	0.987
130	1.475	1.379	1.249	1.197	1.184	1.153	1.085	1.062	1.014	1.002	0.990	0.983	0.977	0.971	0.986	0.995
140	1.399	1.315	1.203	1.159	1.142	1.118	1.062	1.044	1.004	0.993	0.983	0.977	0.982	0.977	0.994	1.003
150	1.335	1.262	1.165	1.128	1.109	1.091	1.045	1.030	0.996	0.986	0.979	0.973	0.987	0.984	1.000	1.011
160	1.281	1.218	1.135	1.103	1.083	1.069	1.031	1.019	0.990	0.981	0.975	0.969	0.993	0.991	1.008	1.019
170	1.236	1.181	1.110	1.083	1.063	1.051	1.020	1.010	0.986	0.977	0.972	0.966	0.999	0.998	1.015	1.026
180	1.199	1.150	1.089	1.066	1.046	1.037	1.012	1.002	0.982	0.974	0.969	0.965	1.005	1.005	1.022	1.034
190	1.167	1.125	1.072	1.052	1.034	1.025	1.004	0.996	0.979	0.971	0.968	0.963	1.011	1.012	1.030	1.041
200	1.140	1.103	1.058	1.040	1.023	1.016	0.998	0.991	0.976	0.969	0.966	0.962	1.017	1.020	1.037	1.048

TABLE 6. Convergence comparison of mF-SGD w.r.t RMSE attained for particular iterations with k = 30, $\mu = 0.0001$.

 TABLE 7. Performance comparison of mF-SGD with deep learning based

 Matrix Factorization methods.

DATASETS	METHODS	RMSE		
	ConvMF	1.000		
NAL 100K	DBPMF	0.990		
IVIL-100K	DCBPMF	0.985		
	mF-SGD	0.962		
	ConvMF	0.980		
	DBPMF	0.945		
	DCBPMF	0.943		
	mF-SGD	0.887		

and achieved minimum RMSE = 0.887 after 150 iterations and maintains stable steady state behavior for almost 180 iterations, which is not shown by mSGD for $\alpha = 0.9$.

C. PERFORMANCE COMPARISON WITH DEEP LEARNING BASED MATRIX FACTORIZATION MODELS

Apart from competing methods presented in this paper i.e., mSGD and F-SGD, the effectiveness of the proposed mF-SGD is also proved by comparing it with recent deep learning based matrix factorization methods using **ML-100K** and **ML-1M datasets.** The performance in terms of RMSE of deep learning based models is reported with optimum parameter values. Overview of the deep learning based MF models given in [63] is as follows.

- **ConvMF** [63] To improve the prediction accuracy of ratings, a context-aware recommendation model ConvMF) is proposed. For achieving high prediction accuracy, ConvMF integrates CNN with PMF to capture contextual information of documents as stated in [64].
- **DBPMF** [63]: Deep Bias Probabilistic Matrix Factorization model (DBPMF) uses CNN to extract hidden user/item characteristics. Moreover, DBPMF also adds bias into PMF to tract user ratings behavior and item reputation.
- **DCBPMF** [63]: Deep Constrain Bias PMF method is used to further improve the performance of standard DBPMF by adding constrain to the user specific and item specific vectors.

The performance comparison between proposed mF-SGD and deep learning based MF methods for recommender systems [63] is demonstrated in Table 7 for both ML-100K and ML-1M datasets. It is noticed from the results given in Table 7 that mF-SGD achieved improved results than **ConvMF, DBPMF** and **DCBPMF** for both datasets. The best performance (RMSE = 0.962) accomplished by mF-SGD against counterparts for ML-100K is with $\alpha = 0.7$, $f_r = 0.7$ and k = 30. Whereas, for ML-1M dataset mF-SGD also achieved finest RMSE = 0.887 against competing methods with similar parameters setting i.e., $\alpha = 0.7$, $f_r = 0.9$ and k = 30. The significant performance with regard to

or Recon	nmender Systems
Input:	$C \in \mathbb{R}^{p \times q}$: Sparse rating matrix. μ : Integer order
learnin	g rate, f_r : Fractional order and μ_{f_r} : Fractional order
learnin	g rate, α : Percentage of previous gradients, k: Num-
ber of f	eatures, Epochs
Output	t: $\hat{C} \in R^{p \times q}$: Rebuilt rating matrix, $A \in R^{k \times p}$:
Learne	d user factor matrix, $\boldsymbol{B} \in R^{k \times q}$: Learned item factor
matrix	
1)	Divide C into Train (<i>Train</i> $\in \mathbb{R}^{p \times q}$) and Test
/	$(Test \in R^{p \times q})$
2)	Initialize factorized matrices $A \in \mathbb{R}^{k \times p}$ and B
,	$\in \mathbb{R}^{k \times q}$ randomly
3)	Find position indices $\wp = (u, i)$ of all non-zero
	entries in Train
4)	While <i>epoch</i> < <i>epochs</i> do
5)	for all $(u, i) \in \wp$ do
6)	Compute $E_{ui} = (\boldsymbol{C}_{ui} - \boldsymbol{a}_u^T \boldsymbol{b}_i)$
7)	Compute Gradients w.r.t a_u via
	Eq. (23)
8)	Compute Gradients w.r.t \boldsymbol{b}_i via
	Eq. (24)
9)	Compute weights vector
	holding previous gradients of
	<i>a_u</i> via Eq. (21)
10)	Compute weights vector
	holding previous gradients of
	b_i via Eq. (22)
11)	Learn \boldsymbol{a}_u, u^{th} factor vector of
	A through Eq. (19)
12)	Learn \boldsymbol{b}_i , i^{in} factor vector of
	\boldsymbol{B} through Eq. (20)
13)	end for \hat{T}
14)	Reconstruct $C = AB^{T}$ via learned
	factor matrices A and B
15)	Calculate RMSE using Test
16)	epoch = epoch + 1
17)	end while

deep learning based MF methods confirms the usefulness of the proposed mF-SGD for proposing accurate and fast recommendations.

V. CONCLUSION

The momentum fractional stochastic gradient descent paradigm has been presented for solving the recommender systems problem. The algorithm is designed for making matrix factorization more efficient to solve future generation complex recommender systems. The correctness of the proposed mF-SGD is established by testing it on ML-100K and ML-1M datasets. The usefulness of the presented scheme mF-SGD is confirmed by comparing with standard mSGD and F-SGD for different learning rates, momentum weights (α) and fractional order (f_r) values. It is observed that increase

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in α value (i.e. the percentage of previous gradients) has directly proportional to the convergence rate. It is also witnessed that faster convergence in the mF-SGD is achieved for large values of α and f_r . However, a smaller value of α with small value of f_r results in slower convergence. It is noticed that by incorporating large value of α , initial convergence for momentum-based algorithms, i.e., mF-SGD and mSGD, is much faster than F-SGD without momentum term, while for lower values of α , mF-SGD provides better steady state performance. It is also witnessed that with the increase in number of features (k), the proposed algorithm gives better results. Moreover, the proposed mF-SGD provides superior results to other methods for all k variants.

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