

Development of an open sensorized platform in a smart agriculture context: A vineyard support system for monitoring mildew disease

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Abstract

In recent years, some official reports, to produce best products regarding quality, quantity and economic conditions, recommend that the farming sector should benefit with new tools and techniques coming from Information and Communications Technology (ICT) realm. In this way, during last decade the deployment of sensing devices has increased considerably in the field of agriculture. This fact has led to a new concept called smart agriculture, and it contemplates activities such as field monitoring, which offer support to make decisions or perform actions, such as irrigation or fertilization.

Apart from sensing devices, which use the Internet protocol to transfer data (Internet of Things), there are the so-called crop models, which are able to provide added value over the data provided by the sensors, with the aim of providing recommendations to farmers in decision-making and thus, increase the quality and quantity of their production.

In this scenario, the current work uses a low-cost sensorized platform, capable of monitoring meteorological phenomena following the Internet of Things paradigm, with the goal to apply an alert disease model on the cultivation of the vine. The edge computing paradigm is used to achieve this objective; also

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our work follows some advances from GIScience to increase interoperability. An example of this platform has been deployed in a vineyard parcel located in the municipality of Vilafamés (Castelló, Spain).

Keywords: Wireless Sensor Networks, Internet of Things, edge computing, open sensorized platform, precision agriculture, vineyard, downy mildew, Goidanich

1. Introduction

The Food and Agricultural Organization (FAO) predicts that the global population will reach 8 billion people by 2025 and 9.6 billion people by 2050 [1]. To keep pace, food production must increase 70% by 2050. There are some
5 obstacles to increase food production and produce such amount of food. Some of them are climate change; restricted availability of arable land; reduced productivity growth; water necessity; the impact of urbanization over agricultural labour; high price and low availability of energy, mainly from fossil fuels; among many others. Moreover, the average age of farmers is increasing because young
10 people prefer going into the industry [2].

A report from the Intergovernmental Panel on Climate Change (IPCC) [3] enumerates all effects of climate change on agriculture. They are: 1) changes in extreme weather with severe flooding and acute water shortages areas will increase around the globe; 2) Since agriculture consumes 70% of the world's
15 fresh water supply, water management should be an adequate and controlled process.

To mitigate these challenges, the FAO [4] recommends that all farming sectors should be equipped with new tools and techniques coming from the Information and Communications Technology (ICT). During the last decade, a
20 new movement to implant digital technology on agriculture was born, which is known as precision agriculture [5]. It aims to optimize the yield per unit of farming land by using ICT tools and technologies [6]. The objective of precision agriculture is to achieve the best products concerning quality, quantity and

economic conditions.

25 Traditionally, precision agriculture makes use of sensors to monitor environmental conditions. To attain this objective, networks of these sensors are created to cover larger areas. Precision agriculture is not only attached to deploying on-site sensors but involving many areas related to robotics, computer science, and remote sensing. An example of this is the use of smartphones,
30 which have been used to visualize on the field the data provided by sensors and offer the possibility to apply different strategies to improve productivity [7]. The works presented in [8, 9] exploit the use of advances in neural networks for weed detection and plant species identification with the purpose of optimizing the herbicide application. Finally, the review introduced in [10] showed the
35 improvements of the spatial resolution in aerial and satellite imagery for precision agriculture since the late 80s, which now allows fine-grained analysis at the expense of high data storage and computational resources.

In the last decade, a new approach to connect everything (sensors or actuators), as well as to monitor and act [11] using the Internet, was implanted in
40 every aspect of our daily lives; this process has come to be called the Internet of Things (IoT). IoT describes how in the real world, physical things are integrated into the digital world of bits and bytes [12]. In general, it involves the integration of each object, such as a sensor or device that is connected via wired or wireless networks using the Internet. To connect things, the Internet
45 Protocol (IP) is used, in which each device has an IP address.

The IoT devices need a mechanism to communicate with the cloud side, which is called Machine to Machine (M2M) communications. M2M will work with new developments and contributes to the future of Internet [13]. Nowadays, the future of the Internet will not only consist of connecting people but also to
50 the approach of a digital world where, ideally, everything will be connected.

Every day farmers are producing large amounts of data that are published on the cloud, with the aim of delivering benefits concerning data access, synchronization storage and to apply some analysis, the so-called Cloud Computing (CC), to make decisions. New trends that appeared after CC move the com-

55 putation towards the smart devices; the benefit is to distribute the computing between different things. This paradigm is called Edge Computing (EC) [14].

The connection between the IoT and M2M with precision agriculture have produced a new concept called “smart agriculture” following other M2M based implementations such as smart cities. One of the realms in which more great
60 adaptation of such technologies has been incorporated is the viticulture. Viticulture has historically been characterized by obtaining a high-quality product. This has been made possible by many factors: the selection of suitable soil and climatic zones, the varietal vineyards and the work of the winegrowers in managing their vineyards.

65 Many threats can affect quantity and quality of the wine. Concretely, there are some well-known plagues attacking vineyards, and they produce substantial losses. The vine is exposed to different types of diseases or harmful agents; these are classified into four types [15]. The first category, physiological damage or disorders in the vine that are not caused by pest and diseases, are generated
70 by lack or excess of irrigation, extreme conditions due to meteorological factors, natural ageing, deficiencies or excesses of nutrients in the vine, lousy soil, irrigation with saline water, among many others. The second category, fungus, they can even grow in both wet and dry regions. Some examples of this disease are powdery mildew, downy mildew, and bunch rot and they can even grow well in
75 both wet and dry regions. The third category, vine pests, and insects, the most damaging are those that feed on grapes, examples of them are: Tetranychus urticae, Meloidogyne, Heterodera, Ditylenchus, Lobesia botrana, Colomerus viti, Eriophyes vitis or Phylloxera vastatrix, among others. Finally, the last category is vine diseases generated by viruses and bacteria, like grapevine degeneration,
80 grapevine decline, leafroll complex or rugose wood complex. All these diseases impoverish the quality of the grape, and as a result, they might cause severe economic losses to farmers and people related to the wine industry.

Downy mildew is probably the most studied disease, as it produces critical

economic losses in vineyards and, consequently, in wineries¹. Within this con-
85 text, this paper introduces the *SEnviro* platform for vineyards, which integrates
the downy mildew model [16] for detecting the most suitable moment to treat
the downy mildew disease.

In summary, the main contributions of this work are:

1. to apply a model to alert when would be the suitable moment to treat the
90 downy mildew disease in the vineyard context;
2. to monitor vineyard fields through a new version of the *SEnviro* platform
following the IoT paradigm and;
3. to follow the edge computing paradigm and to mitigate the communication
between ends.

95 The remainder of the paper is organized as follows. Section 2 presents the
background of the IoT in edge computing, open hardware and smart agriculture.
Section 3 presents the *SEnviro* Platform. Section 4 details the Goidanich model
used to detect the suitable moment to apply treatment for the downy mildew
disease. Section 5 shows the experimentation done to test the platform. Section
100 6 reviews the related work. The paper concludes in Section 7 with conclusions
and future work.

2. Background

This section is devoted to showing the background of the IoT, Edge Com-
puting, and Open Hardware paradigms. Also, their relation with precision
105 agriculture through GIS is detailed.

2.1. IoT in the edge

Cisco's report anticipates that 50 million smart objects will be connected to
the Internet by 2020 [17]. This situation will cause data tsunami which refers

¹See <http://westernfarmpress.com/grapes/powdery-mildew-always-vineyard-concern> (last
accessed: April 2018)

to the use of the IP to achieve connectivity between these smart objects. This
110 trend produces streams of potential information, which challenge today's data
analysis systems in a centralized server in the Cloud [18, 19, 20]. IoT movement
has been successfully applied in healthcare [21, 22, 23, 24] (ambient-assisted
living and telemedicine), smart home and smart metering [25, 26] (devices that
enable the automation of common in-house activities), video surveillance [27]
115 (intelligent video systems), automotive and smart mobility [27, 28] (intelligent
transportation systems) and smart energy and smart grid (intelligent manage-
ment of energy distribution and consumption) [29].

All these applications have boosted up the popularity of "smart things"
connected to the Internet, and the networks created with them. In this way, the
120 traditional WSNs have been updated to follow an IP protocol to apply all the
benefits that it entails. The new paradigm, namely cloud computing, has been
added to improve and provide more advantages over the IoT [30].

The low bandwidth lags between the producer (smart objects) and con-
sumer parts (cloud server) and the improved performance at both computing
125 and consumer of smart objects, has led to a new paradigm called edge comput-
ing. The main feature of edge computing is that data can be processed locally
in smart devices, rather than being sent to the cloud for being processed.

The edge computing essentially means that instead of staying and working
from a centralized cloud, edge nodes work at the ends of the networks. Edge
130 computing puts some of the transactions and resources on the edge of the cloud;
instead of establishing channels for storage and use in the cloud, it reduces the
need for bandwidth by not sending every bit of information through channels
to the cloud and instead adds it in specific access points. By using this type
of distributed strategy, we can reduce costs and increase efficiency and reduce
135 bandwidth consumption.

Edge computing arose from the need to address three issues: 1) being able to
act in real-time with the incoming data; 2) working within the limits of available
bandwidth; and 3) distributing the computing between the nodes, to relieve the
centralized server.

140 Edge computing address applications and services that do not fit the paradigm
of the cloud, such as applications that require very low latency and being
predictable; geospatial distributed applications; fast mobile applications; dis-
tributed control systems on a large scale.

Figure 1 details the work-flow for connecting sensor nodes to users using a
145 cloud and edge computing infrastructure. On the one hand, this figure divides
the physical and cyber worlds and the IoT part with traditional IT. The Gateway
GPRS Support Node (GGSN) is used to pass the barrier between the IoT device
cloud and the IT cloud [31]. It is responsible for the interworking between the
GPRS network and Internet. On the other hand, the figure shows where the
150 edge computing is located. The results offered by the edge computing can be
sent to the cloud or directly to the clients without using any cloud infrastructure.

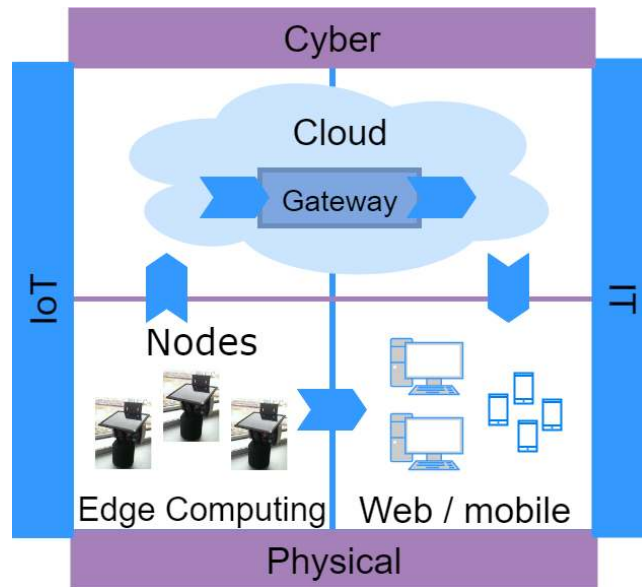


Figure 1: Representation of the cycle provided by IoT and IT, that it is divided between the physical and cyber world.

2.2. Open-hardware to make smart objects

Nowadays, the open movement has gained attention [32]. Traditionally, this idea was applied with more acceptance over source code and provoked the

155 open-source movement. More recently, the same idea has been applied to the
hardware (open-hardware). This situation has permitted to offer complete open
systems, where both source and hardware are open. The users can contribute
to improve the system and propose improvements.

One of these improvements is the ability to offer more interoperability be-
160 tween components because they can be adapted for each usage. In this way,
it reduces compatibility issues. This advantage can establish a standard IoT
approach. In this work, we apply different Geographic Information Systems
(GIS) standards to communicate with each IoT device; these standards will be
explained in following paragraphs.

165 Another advantage is the low cost of these devices compared with commercial
solutions. As concluded by [33], open initiatives are cheaper, but they have
also shown that open hardware is more powerful and has better performance
than commercial solutions. Also, the same work demonstrates that the open
hardware project can be considered reliable.

170 Currently, there are several different alternatives regarding the micro-controller
based platform, and the most remarkable platforms are Arduino², Raspberry
Pi³, BeagleBone⁴ or MSP430 Launchpad⁵. All these platforms can be expanded
easily, and used for other applications. Using these platforms different applica-
tions have been developed thanks to the acceptance of the IoT movement above
175 described.

²Official Arduino Website. Available online: <https://www.arduino.cc/> (accessed on 2 June 2018)

³Official RaspBerry Pi Website. Available online: <http://www.raspberrypi.org> (accessed on 2 June 2018).

⁴Official BeagleBoard Website. Available online: <http://beagleboard.org> (accessed on 2 June 2018).

⁵Official MSP430 Launchpad Website. Available online: <http://www.ti.com/launchpad> (accessed on 2 June 2018).

2.3. GIS role in smart agriculture

As commented in the Section 1, one way to address these issues and increase the quality and quantity of agricultural production is by using ICT to make farms more “intelligent” and more connected through the so-called “precision
180 agriculture” also known as “smart agriculture”.

Nowadays, there is a high quantity of proprietary IT solutions to help farmers manage their farms more effectively [34]. More advanced systems track geospatial zones, weather patterns and perform expert predictions [35]. These kinds of systems are called Farm Management Information Systems [36], and fo-
185 cus on specific tasks and use their specifications to implement the functionality provided.

Currently, this field is slowly moving to use the Internet and is starting to use some of the networking solutions to improve what they offer to the end users. However, it is widely accepted that the Internet faces some shortcomings, es-
190 pecially in handling vast numbers of networked devices (IoT) or stakeholders. Moreover, there is still no standardized solution to enable cohesive and straight-forward interoperability among services and stakeholders.

To solve this issue, we look at GIScience. It can offer an excellent opportunity to standardize the ways of connecting different “things”, offering an interopera-
195 ble connection; and it should help to deploy the new smart cities. GIScience can be defined as “the discipline that uses GIS as tools to understand the world” [37]. It can contribute by offering a crucial essential component for the IoT movement, which is interoperability using the use of standards.

The Open Geospatial Consortium (OGC)⁶ is a non-profit international or-
200 ganization which develops open standards for the global geospatial community. OGC defines standards in a wide variety of domains including environment, defense, health, agriculture, meteorology, sustainable development, and smart cities. The OGC has standardized Sensor Web Enablement (SWE) as a set of specifications related to sensors, sensor data models, and sensor web services

⁶See <http://www.opengeospatial.org/> (last accessed: April 2018)

205 that will enable sensors to be accessible and controllable via the web [38]. It is composed of a set of standards; the most popular are: Observations and Measurements (O&M), SensorML, Sensor Observation Service (SOS), Transducer Model Language (TransducerML), Sensor Planning Service (SPS), Sensor Alert Service (SAS) or Web Notification Service (WNS).

210 Another proposal is OGC SensorThings API⁷. It is a new candidate standard that provides open access built on web protocols, based on the current SWE standard and following the architectural REST style. The aim is to provide a standardized a way to expose the IoT world to the real world, where things have limited resources.

215 3. *SEnviro* platform

This section presents the sensorized platform used in a smart agricultural context. As commented in the above sections, the platform *Sense Our Environment* (*SEnviro*) [39] follows the IoT and Web of Things (WoT) [40] paradigms by means of a low-cost, open-hardware and open-software, energetically efficient and autonomous and interoperable solution. The *SEnviro* platform uses the IP protocol to establish the connection. With these features, it can be considered that each *SEnviro Thing* is a smart object. A network is formed by joining several *SEnviro Things*. This platform makes use of standards when publishing data. It guarantees the interoperability of the services provided by the platform.

225 Another important feature of this platform is that it is energetically efficient and autonomous through a battery cell, which is charged with the energy provided by a solar panel attached to it. To save as much energy as possible, we are using a sleep mode, in which during this period the micro-controller and connectivity module consume as little as possible.

⁷See <http://ogc-iot.github.io/ogc-iot-api/> (last accessed: April 2018)

230 *3.1. How is SEnviro made of?*

At the hardware level, the sensorized platform has been designed to be a node acting as a smart object, which provides measures of environmental variables. Each *SEnviro Thing* is composed of different components, which are organized into four groups depending on their function: Core, Sensors, Power Supply and
235 Communication. At the same time, the Core is formed by four parts: Micro-controller, Connectors, Clock, and Memory.

For this work, we developed an enhanced *SEnviro* using the LinkIt One development board. The LinkIt ONE board is an open source, high performance, Arduino footprint board for prototyping IoT devices. The board is based around
240 a powerful ARM7 EJ-S processor but has onboard GSM, GPRS, Wi-Fi, Bluetooth BR/EDR/BLE, GPS, Audio codec, and SD card connector. Pin-out similar to Arduino boards, including Digital I/O, Analog I/O, PWM, I2C, SPI, UART and power supply, compatible with Grove 4-pin interface. In Section 5, we detail all components used to develop the *SEnviro node* for monitoring
245 vineyards.

3.2. How does SEnviro work?

At an operational level, *SEnviro Thing* can change its behaviour, updating the information about what sensor is active and the frequency at which measures are taken. The *SEnviro Thing's* behaviour has two stages, initial and repetitive
250 periodic. In the initial stage, a set of procedures are executed when it is initiated, for instance, one procedure could initialize the clock using the current time. The repetitive periodic stage defines the procedures that are repeated during the *SEnviro Thing's* life cycle before going to sleep.

Figure 4 shows the design of the complete infrastructure with all of the system's components, and describes each of them in different layers. If we
255 analyze *SEnviro* from a GIS context and specify what is happening in each of its layers, we obtain the Figure 2, which we are going to detail below. In the content layer, there are different *SEnviro Things* to cover an area to measure

the phenomena by the included sensors in each sensorized platform. In this figure, we can see the two functionalities mentioned above.

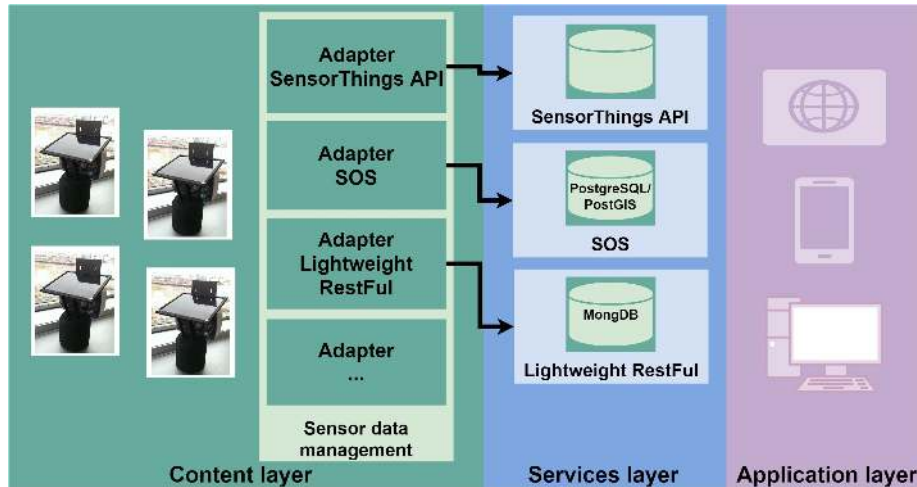


Figure 2: General overview about the *SEnviro* work-flow following three layers architecture.

As detailed in [39], different observations are periodically taken from the installed sensors to monitor the environment. When the *SEnviro Thing* takes a new observation, it invokes the Sensor Data Management (SDM) module. This component is implemented as a RESTful web service.

The SDM module is responsible for publishing observations in different services that we want to offer, such as SensorThings API, SOS or others. Thus, it offers the same content using different interfaces; depending on the context it may be more or less appropriate. Different adapters for each of these services are offered. If we want to support new services/standards, we only need to add a new adapter for the service. We use the adapter software pattern to implement this feature.

The service layer offers the services described above. One of the objectives of the *SEnviro* platform is to offer a standard service, to provide connectivity in an interoperable way. To meet this challenge, a candidate OGC standard, SensorThings API, has been used to offer an interoperable service to access the *SEnviro* platform. The most remarkable thing about this standard is that

it breaks away from all “standard topics” [41] and offers access to restrictive devices, such as smartphones. Also, it offers the SOS interface to increase the interoperability, because this standard is widely used [42]. Finally, a lightweight
280 RestFul service is created to connect this service in a more agile way [43].

The last layer, the application layer has been designed for different clients, mobile, web-based or desktop.

The *SEnviro Thing* can adapt its behavior, updating the information about which sensor is active and the frequency at which measurements are taken.
285 At regular intervals, the platform requests a new behavior to a server using a RestFul service. Then, the *SEnviro Thing* will get a new behavior following the new configuration received.

The sensorized platform sends the taken observations to a server. A sensor collector service has been created to achieve this integration. Different oper-
290 ations are available to collect the observations measured. When one *SEnviro Thing* takes a new observation it invokes these operations to send data to the server using SDM module.

When the SDM receives a new observation, it connects with the different adapters to send the data for each available service. To accomplish this ob-
295 jective, we have followed previous work [43, 39] to connect with different OGC instances, such as SOS and candidate standard SensorThings API. Also, we provide a lighter solution for data sensors access using RestFul interface used in [43].

To offer all these interfaces, we provide different adapters to publish the sen-
300 sor data in different services or databases. To offer a SensorThings interface, we use an external server to test this API, which is offered by the SensorThings API candidate proposal. For SOS, the 52° North implementation (SOS version 2.0) is used. In this case, the server is deployed using an Apache Tomcat server and sensor data are stored in a PostgreSQL/PostGIS database⁸ following
305 the documented standard installation guides. Finally, for the last interface, a

⁸See <http://postgis.net/> (last accessed: April 2018)

Lightweight RestFul service is implemented using JAX-RS⁹, Jersey¹⁰ and one MongoDB database¹¹ is used to store the observations.

4. Goidanich model to detect downy mildew disease

Downy mildew is a fungal disease caused by the *plasmopara viticola oomycete*.
310 It is one of the worst diseases of vine cultivation under specific weather conditions. Downy mildew is the most studied disease, as it produces critical economic losses in vineyards and, consequently, in wineries [44]. Downy mildew is the result of the presence of a fungus in the green elements of the vines, and its life cycle is well established [44].

315 Its biological cycle is developed in four phases: contamination, incubation, and sporulation and propagation phase.

- Contamination phase: in spring, the oospores reach maturity and germinate as zoospores. These may be transported by rain and wind, reaching the vine green parts and colonizing them. The needed conditions for contamination are: an air temperature around 10 °C, a young plant of at least 10 cm, and a rain rate of at least 10 mm/day.
320
- Incubation phase: it takes from 4 to 21 days, depending on the temperatures and relative humidity.
- Sporulation phase: during this step, the fungus is propagated along the vine.
325
- Propagation phase: dissemination to nearby plants with the help of rebounding raindrops and wind. The optimal condition for ambient temperature is between 20 and 25 degrees, with the help of rain during the night.

⁹See <http://jax-rs-spec.java.net/> (last accessed: April, 2018)

¹⁰See <https://jersey.java.net/> (last accessed: April, 2018)

¹¹See <https://www.mongodb.org/> (last accessed: April, 2018)

330 There are some models with more complexity and better precision than
Goldanich [45] such as MILVIT [46, 47]. Some other works simulate only a
particular phase of the epidemic cycle [48, 49]. Moreover, some other works
simulate only the first date of primary infection followed by the second cycle
with quantitative outputs [50, 51]. More recently, new models are presented
335 which use exploratory simulations based on newly available computing power
[52].

Our work, unlike the ones found in the bibliography, is the pioneer in using
devices of IoT for monitoring this kind of models. Although Goldanichs model
has been improved over time, it is an ideal candidate for testing our platform.
340 As a future work, we intend to use other more complete models to improve the
predictions of this type of disease.

The Goidanich model is used to follow the evolution of the downy mildew
fungus [16]. It takes into account three different phenomena: relative humid-
ity, temperature, and rainfall. The model starts when a traditional method is
reached, the “rule of the three ten”, which predicts that primary infections will
345 occur once the average temperature has exceeded 10 degrees, the sprouting ex-
ceed 10 cm and on a day when there is at least 10 mm of rainfall. This rule,
though simple, gives a rough idea of when to start looking for these primary
infections.

350 To follow the evolution of the fungus, it is necessary to know the aver-
age temperature (T_m), the average relative humidity (H_m) and daily rainfall.
Goidanich presents a daily table (Table 1) in which, for each temperature, the
daily growth of the fungus is set according to whether the H_m is high or low.
The author defines each T_m in two columns, one when the H_m is lower than 75%
355 and the other when it is higher than 75%, providing, therefore, two numerical
values of daily development for each case.

When the sensor records 10 or more mm of rain, starting from the next
day, the estimation of the daily growth is recorded, and the model is calculated
by adding every day until reaching the value of 100. At this moment, the
360 theoretical incubation period ends, and the fungus contamination is evident

Tm(C)	Hm<75%	Hm>75%	Tm(C)	Hm<75%	Hm>75%	Tm(C)	Hm<75%	Hm>75%
12,	00 0,00	5,25	17,	00 10	12,25	22,	00 16,60	22,20
	25 4,40	5,75		25 10,30	16,60		25 17	22,60
	50 4,70	6,20		50 10,50	14,30		50 17,30	23,50
	75 5	6,70		75 10,75	14,75		75 17,70	24,40
13,	00 5,30	7,10	18	00 11,10	15,30	23	00 18,10	25
	25 5,70	7,70		25 11,48	15,20		25 18,10	25
	50 6	8		50 11,70	16		50 18,10	25
	75 6,30	8,50		75 12,10	16,30		75 18,10	25
14,	00 6,6	9	19,	00 12,50	16,60	24,	00 18,10	25
	25 6,8	9,40		25 12,90	17,50		25 17,70	24,30
	50 7,10	9,70		50 13,40	18,30		50 17,30	23,60
	75 7,30	10,20		75 13,70	19,30		75 16,60	23,20
15,	00 7,60	10,60	20,	00 14,20	20	25,	00 16,60	22,20
	25 7,80	10,80		25 14,50	20,50			
	50 8,10	11,10		50 14,80	21			
	75 8,30	11,30		75 15	21,51			
16,	00 8,50	11,70	21,	00 15,30	22,20			
	25 9	12		25 15,70	22,20			
	50 9,30	12,50		50 16	22,20			
	75 9,60	12,90		75 16,30	22,20			

Table 1: Daily cumulative percentage of downy mildew incubation.

due to the appearance of stains of oil and the asexual fruiting.

The model works in that if the sum of the daily development accumulated is over 70%, the risk is high, so treatment is needed as soon as possible. If a fungicide product is applied, the development of the fungus restarts and remains
365 in suspension for a certain number of days, or until the product has been washed away by rain.

5. Case study: *SEnviro* for agriculture

This section details how we have developed the sensorized platform in a smart agricultural context.

370 5.1. Building a *SEnviro* Thing for Smart Agriculture

For this work, we have developed a new version of the sensorized platform presented in [39]. For the current case study, we only need three different phenomenon sensors, such as temperature, humidity sensor and rain gauge (Figure

3). Also, for this case, the new sensorized platform uses a GPRS connection
375 to offer easy installation and wireless connection in the field. The *LinkIt One*
board offers an integrated GPRS module. Table 2 shows a general description.
Figure 3 shows a *SEnviro Thing* assembled with all components used to follow
the Goidanich model.

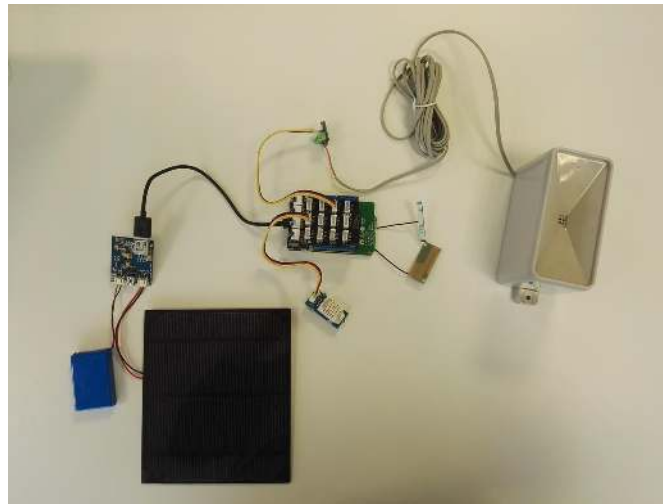


Figure 3: *SEnviro Thing* assembly to monitor vineyards.

To offer an energetically efficient and autonomous platform, we use a lithium
380 battery of 2200 mAh¹² that supplies an output voltage of 3.7 V and is charged
with the power generated with a 3W solar panel¹³ that supplies an output
voltage of 5.2 V. Those two elements and the microcontroller are attached to
a board (Lipo Rider V1.1¹⁴) that handles the power ow between the various
components.

385 Finally, to protect all parts of the *SEnviro Thing*, two boxes have been used.

¹² http://www.seeedstudio.com/wiki/images/e/e5/PL805050P2200mAh_3.7V_1S1P_V_1.0.pdf (last accessed: April 2018)

¹³See http://www.seeedstudio.com/wiki/3W_Solar_Panel_138*160 (last accessed: April, 2018)

¹⁴See http://www.seeedstudio.com/wiki/Lipo_Rider_V1.1 (last accessed: April, 2018)

<i>Category</i>	<i>Component</i>	<i>Description</i>
Core	Microcontroller board	Linkit One
	Shield Grove	Base Shield V2
	MicroSD card	MicroSD card 2Gb
	Screw connectors (x1)	Screw Terminal for Grove
	Box for arduino	RETEX serie 102
	Box for sensors	3D printed box
Communication	GPRS module	Included in LinkIt One
	SIM card	SIM card
Sensors	Temperature and humidity sensor	Grove temperature and humidity sensor
	Rainfall sensors	Weather Meters
Power Supply	Power module	Li-po Rider
	Battery	Polymer Lithium Ion Battery 2200mAh 3.7V
	Solar panel	3W Solar Panel 138X160

Table 2: Components list included in the *SEnviro Thing* for smart agriculture.

A waterproof box¹⁵ to protect the Core, Communication and Power supply and a pagoda box to protect the sensors.

5.2. Applying Goidanich model

This section describes the behavior that follows the developed *SEnviro node* for monitoring the downy mildew. The *SEnviro* has two different objectives: 1) 390 to take and send observations at a defined rate, which by default is every ten minutes. 2) to calculate the Goidanich model, and if an alert state happens, the *SEnviro node* will send an alert via SMS. The Figure 4 shows these two functionalities as general overview following different layers.

395 The first functionality was explained in [39], but in this work, some changes have been introduced. The first functionality has been the connectivity used. We have selected GPRS connectivity due to lack of other connectivity in the context in which it is experienced.

The sensorized platform sends the observations to a server (Section 3). A 400 sensor collector service has been created to achieve this integration. Different operations are available to collect the observations measured. When one *SEnviro Thing* catches a new observation, it invokes these operations and sends the data to the server using the SDM module.

When the SDM receives a new observation, it connects with the different 405 adapters to send the data for each service available. To accomplish this objective, we have followed our previous work [43, 39] to connect with different OGC instances, such as SOS and candidate standard SensorThings API. Also, we provide a lighter solution for data sensors access using RestFul interface used in [43].

410 To complete the *SEnviro Thing* integration, we proposed a *SEnviro* application to access sensor data provided by each *SEnviro Thing*. The *SEnviro* APP is a web-application in charge of integrating the sensor data provided by

¹⁵See <http://www.retex.es/es/Cajas/Cajas-universales/Serie-102.axd> (last accessed: April 2018)

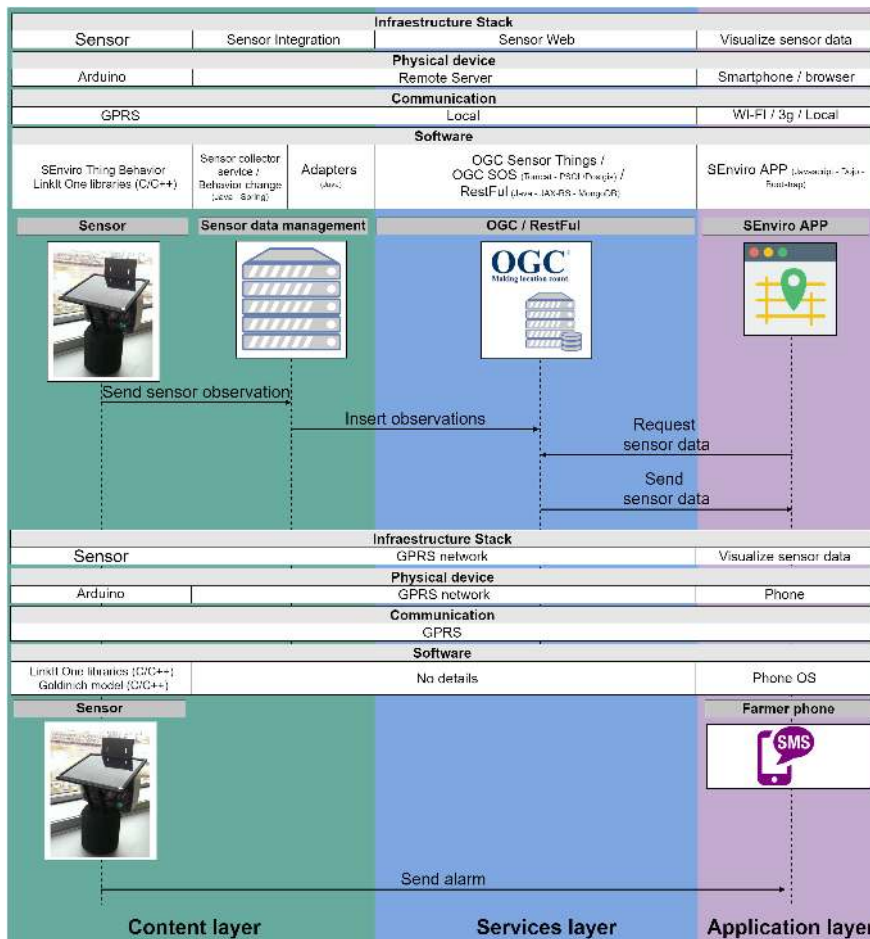


Figure 4: On top) the figure gives information about the realization of the different components of the infrastructure and the sequence diagram of an exemplary usage to send *SEnviro*'s observations; on bottom) it gives a sequence diagram of an alarm.

the installed *SEnviro Things*. Furthermore, the application is built using the mobile-first approach. In this way, it can be easily tested on a mobile device.

415 The second functionality, which is of high importance for this work, is the possibility to apply the Goidanich model in each *SEnviro node*. We follow the fog computing paradigm to distribute the computation between the devices, in this case, *SEnviro nodes*.

To calculate the Goidanich model, we need to know the temperature and

420 humidity averages per day and the amount of rainfall accumulated. Each plat-
 form will have the capability to execute a method as depicted in Figure 5.
 The Pseudocode 1 shows how each *SEnviro Thing* can calculate the Goidanich
 model.

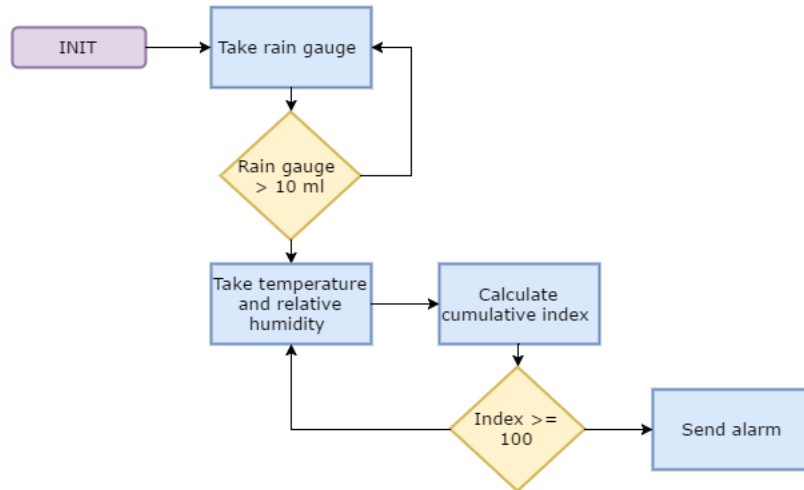


Figure 5: Goidanich model workflow.

The first step is to accumulate the rain gauge. When it starts to rain, the
 algorithm will calculate the rain quantitative uninterruptedly while it is raining.
 425 The accumulative value will be reset when in one-day rainfall has been recorded.

When the accumulative rainfall exceeds 10 mm, the *SEnviro* starts to calcu-
 late the temperature and humidity means. To offer these means, we will add
 up all of the observations taken in one day and divide them by the number of
 430 observations.

These means will be used to determine the percentage of downy mildew
 incubation, and the selected value will be accumulated. When this value reaches
 100, an alarm will be sent to the farmer to inform him/her about the downy
 mildew incubation level, and the specialized treatment can begin.

435 We have selected SMS-based services as the way to connect with the farm-
 ers. It is due to the high penetration of mobile phones used by the stakeholders.
 Also, using SMS notifications, we can guarantee that the notification will ar-

Data: Temperature, humidity and rainfall sensors

Result: Send alarm to notify downy mildew risk

accumulateGoidanich = 0;

while *true* **do**

 RainAcum = RainAcum + RainValue;

if *RainAcum* > 10 **then**

 | riskMildew = true (active downy mildew risk);

end

if *riskMildew* **then**

 | accumulateGoidanich += CalculateMildewPercent ;

if *accumulateGoidanich* > 100 **then**

 | sendAlarm ;

 | resent all values ;

end

end

end

Algorithm 1: Applying the Goidanich model

rive at the farmer. Other mobile technologies that use Internet connection do not guarantee the notification delivery, because the receiver needs permanent
440 Inter-net connection. It involves farmers having a smartphone with an Internet connection data plan that will also receive the alarm.

It is important to remark the potential of the developed *SEnviro node*. Although this subsection has described the behavior that it followed for a particular disease, its development could be modified to follow other models using
445 the meteorological data collected by the node. Therefore, we consider that the *SEnviro node* could also be useful for detecting different diseases in vineyards or other crops.

5.3. Results

In a first phase, the platform has been tested in a lab environment. It
450 was working correctly without huge losses. The sensors obtained measurements
between predictable values. The rain gauge has also been tested with rain
recreation, and it was working correctly. These tests were carried out both
indoors and outdoors.

In a second phase, we have been deployed within a vineyard parcel located
455 in the municipality of Vilafamés (Castelló, Spain). The parcel has a 23633.4
m². Figure 6 shows the location of each *SEnviro Thing*. A *SEnviro node* was
deployed in this vineyard parcel during May 2016 (Figure 7), the month when
downy mildew can begin to arise at the chosen location. As mentioned, this
platform is capable of measuring three different phenomena which are tempera-
460 ture, humidity and the amount of rainfall that are all involved in the Goidanich's
model. During this month, observations were taken every 10 minutes and were
sent to the central server. Each platform can calculate the temperature and
minimum humidity, in addition to calculating cumulative rainfall every day.

In this test, the platform registered correct observations. During this period,
465 the rain gauge did not reach 10mm to activate the alert, so our system does
not detect downy mildew. During the 30 days that it was running almost all
observations (96,9% successful deliveries) have been measured and sent in real-
time although there were some that were undetected due to the loss of the signal
in the area. These lost observations were sent in following deliveries.

470 6. A comparative between some similar works

In the literature, some approaches are similar to our proposal. The following
items describe the works that have been analyzed. All of them talk about IoT
in the smart agriculture context, more concretely on monitoring vineyards.

- In [53], the authors propose a WSN where each node takes images from
475 the field and internally uses image processing techniques to detect any
unusual status in the leaves.

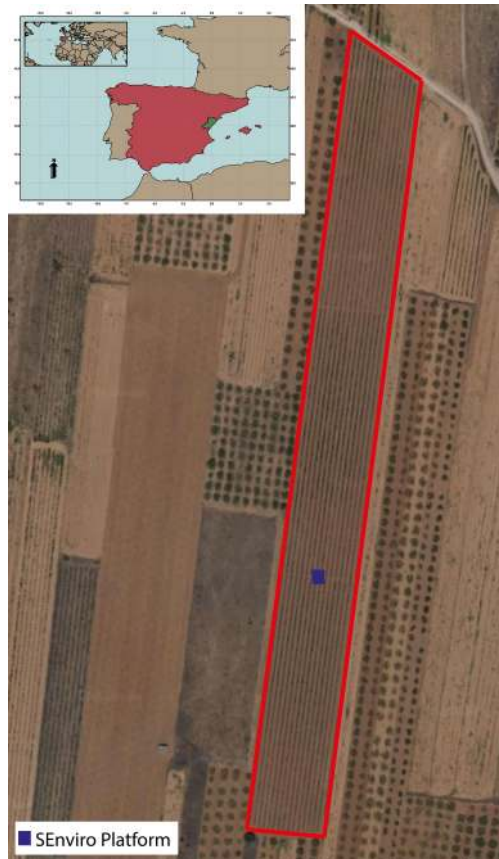


Figure 6: Location of the *SEnviro* Platform in a vineyard parcel located in Vilafamés (Castelló, Spain).

- The paper [54] presents a smart embedded system that will aid vineyards and which is cost-effective and flexible. They monitor ambient temperature and humidity and send an SMS with the values.
- 480 • Authors in [55] do not describe a single platform, they show a variety of sensor network configurations and applications that can address different priorities in the vineyard.
- Authors in [56] present the results from an operational sensor network. The network is based on the Berkeley mote (Mica II mote). The basic
485 sensor board is equipped with a temperature sensor. The network con-



Figure 7: Picture of the *SEnviro* unit in the field.

sisted of sixty-five motes distributed in a grid-like pattern ten to twenty meters apart covering about two acres.

- Authors in [57] present a general sensor network designed to connect agriculture to the IoT. A customized sensor node and developed the application for agriculture on top of TinyOS 2.x are detailed. A common access interface of the sensor networks for agricultural applications was created to enable further integration of the sensor networks on the IoT.
- A sensor network built using TelosB platforms is presented in [58]. They show the experience of matured during the design and deployment of a prototypal WSN-based system for monitoring the productive cycle of high-quality wine in a Sicilian winery. They propose two networks, one for the vineyard, and another for the wine cellar. The objective is to provide some of the basic functionalities that may be extended to obtain

complete product traceability, from the grapes to the bottle.

500 To compare the formerly reviewed works, Table 3 shows a comparison between the detailed works. The following features to characterize each one have been proposed:

- *Platform*: it refers to the microcontroller model that the system uses.
- *Real-Time*: it indicates if the system works in real-time. Possible values:
505 Yes/No.
- *Connection*: it refers to the wireless connections available for the system. Possible values: Wi-Fi, Bluetooth, GPRS, others.
- *Phenomena*: it refers to the phenomena that the system can measure. Possible values: Temp., Hum., Dust, Bar., Noise, others.
- 510 • *IoT-WoT*: it indicates if the system follows the IoT and WoT paradigms. Possible values: Yes/No.
- *Analyze*: it shows if the system offers a RESTful interface. Possible values: Yes/No.
- *Client*: it indicates if the system provides a client for visualizing the sensors and observations. Possible values: Yes (what kind) /No.
515
- *OGC standards*: it shows if the system offers OGC standards. Possible values: Yes (what kind) /No.

In the following, we compare the analyzed works and our work using the characteristics listed at the beginning of this section, and the results are shown
520 in Table 3. As indicated, most of the analyzed works use different platforms to build the different nodes. In our case, we use *LinkIt ONE*, because it has different ways to connect, GPRS, Wi-Fi or Bluetooth. It also includes useful operations to use the different features.

Like some other works analyzed, our work offers sensor data in real-time. It is
525 possible because our *SEnviro node*, to monitor vineyards, is provided with GPRS

Work Reference	Platform	Real-Time	Connection	Phenomena	IoT-WoT Analyze	Client	OGC standards
[53]	OpenWrt Router	No	Wi-Fi	Photos	✗	✗	✗
[54]	Arduino	✓	GPRS	Temp. and Hum.	✗	✗	✗
[55]	Motes	✓	RF	Temp.	✗	✓	✗
[56]	TSmarT IoT platform	Yes	GPRS	Temp., Humd. Soil Temp., Soil Water, Leaf wetness dielectric and Davis Vantage Pro2	✓	✓	✓
[57]	eKo Pro	✓	GPRS	Temp. (air), Hum. (air), Temp.(soil), Hum(soil), light and CO2	✓	✗	✗
[58]	TelosB	✓	Wi-Fi	Temp. (air), Hum. (air), light and Wind Speed and Dir.	✓	✗	✗
Current work	LinkIt One	Yes	GPRS	Temp., Hum. and Rain	✓	✓	HTML5 OGC SensorThing API

Table 3: Comparison between different sensorized platforms.

connection to the Internet. *SEnviro*, as we show in [39], it can include a huge variety of phenomena. For this proof of concept, to detect downy mildew disease, we adopt the nodes to offer only three phenomena: temperature, humidity and rain gauge.

530 Only three analyzed projects [56, 57, 58] follow the IoT and WoT paradigms. *SEnviro* follows these paradigms and offers a RESTful interface. Finally, our project aims to be interoperable, and for this purpose, an OGC standard has

been chosen, such as the OGC SensorThings API.

If you look at the works that apply some analysis over the observations from
535 the sensors, only two works, apart from *SEnviro*, apply some analysis to increase
the value of the observations and offer decision-making models. Our work, as
we detailed in the previous work [39], provides a client to these paradigms and
offers a RESTful interface using the OGC SensorThings API.

7. Conclusions

540 The primary concern of this work is to apply the new improvements in the
ICT area, within the smart agriculture context. In this way, the applied model
to detect the suitable moment to treat downy mildew disease can help the farmer
in different ways. The first improvement is the reduction of costs of chemical
products. The proposed support system detects the best moment to apply the
545 downy mildew control treatments, which are only applied when they are strictly
necessary. At the same time, it reduces the chemicals in the soil. It redounds
in less external elements in the environment, improving the ecological footprint
of the crop. Also, it reduces costs concerning person-hours; each treatment
that is not needed represents some working hours that could be used for other
550 tasks. Consequently, the farmer does not need to visit the vineyards to know
the status.

Our work applied a sensorized platform called *SEnviro* detailed in [39], whose
objective was to monitor vineyards. For this purpose, we have designed a new
version of the sensorized platform to measure different phenomena to provide
555 follow up models to detect the best moment to treat downy mildew.

To achieve this, we propose an improved version of the *SEnviro* platform that
follows different computer science paradigms, such as IoT or edge computing.
In this way, our platform can process and apply short algorithms to compute
the information at the same moment when the data are collected.

560 The objective of the work is not to evaluate or validate the Goldanich model
since there are different works in the bibliography related to that. Our work only

shows a single experimentation to test the presented IoT platform. It has offered good results during the month that the *SEnviro* platform has been installed and has correctly reported the observations to the central server, the platform had
565 some isolated losses caused by coverage problems to send the observation in real-time. Temperatures and humidities average for the monitoring of the Goidanich model have also been calculated.

As future work, new fungal disease models in the field of viticulture could be included, such as Powdery mildew, Black rot or Botrytis. All of these diseases
570 are based on meteorological phenomena, and they are included in the *SEnviro* node. New kinds of crop could be supported if the disease models are based on these meteorological phenomena. Support other crops with other phenomena require to add these sensors, in this case, more efforts are needed.

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