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# Discovery of the Nearly Zero Flux between Two Parallel Conductors in Planar Transformers

Mingxiao Li *Student Member, IEEE*, Ziwei Ouyang, *Senior Member, IEEE* and Michael A.E. Andersen, *Member IEEE*

**Abstract**-The momentum to achieve high efficiency, high frequency, and high power density in power supplies limits the use of conventional wire-wound transformers, but widely employs planar transformers. Planar transformers intrinsically benefit from low profile, predictable parasitic components, ease of manufacture and excellent repeatability of construction, which are generally applied to high frequency and high current applications, such as data centers and telecoms. Reducing the current density through parallel connections is becoming common practice in planar transformers. However, the current on every parallel conductor is usually unbalanced and hard to be predicted. Start from the motivation to predict parallel current distribution, a phenomenon is discovered in this paper that the parallel current distribution is constant from medium frequency and follows the same pattern in higher frequency range. Besides, this paper points out that the insulation thickness also affects the current distribution. Furthermore, the phenomenon that the magnetic flux in the space between two parallel conductors approaches zero when parallel currents are frequency independent is proved theoretically and demonstrated experimentally. Together with Ampere's circuital law which links the current to the magnetic field, the current distribution can be derived. No complex mathematical calculation or simulation tool is required. Any applications using planar transformers with parallel conductors at medium frequency or higher frequency can adopt this method to predict the parallel current distribution for design optimization.

## I. INTRODUCTION

Achieving high efficiency and high power density has become a general requirement for power electronic designs. Among many components in a power supply, the transformer usually takes 30%-50% of the total system volume and creates nearly half of the power loss. Thereby, the transformer design plays a key role in the power supply to satisfy the size and efficiency requirements.

High frequency operation offers a way to shrink the system volume by reducing the size of the passive components. Planar transformers are proved to have excellent performance at high frequency operation [1]-[6]. They are recognized by low profile, predictable parasitic components, ease of manufacture and excellent repeatability of construction. As opposed to conventional wire-wound transformers, planar transformers usually contain windings made of copper sheets etched on a printed circuit board (PCB) in a spiral form, as shown in Fig. 1. Primary and secondary windings can with relative ease be heavily interleaved in a manufacturing or automation environment.

In high current and high frequency (up to MHz) applications, there is a tendency that lower output voltage is required for many DC/DC power conversions, like data centers and

telecoms [7]-[13]. Connecting several conductors in parallel to reduce the large DC current density is commonly used in planar transformers. Furthermore, planar transformers allow the easy implementation of interleaving winding layouts to balance the current distribution on each parallel conductor at high frequency.

However, the current on each parallel conductor is usually unbalanced, as discussed in [14]. Previous research has been carried out to estimate the planar transformer AC resistance [15]-[19] and core losses [20]-[29]. Studies [24]-[26] utilize finite element analysis (FEA) to investigate several parallel winding layouts. However, this approach is time-consuming and not analytical for optimal design. A lumped circuit model is proposed in paper [27] to predict the AC resistance and leakage inductance. Literature [29] presents a method to derive the currents on parallel conductors. Nevertheless, solutions are hard to be derived for a planar transformer with complex structures and multiple turns in parallel. The investigation over the current distribution at high frequency is not discussed.

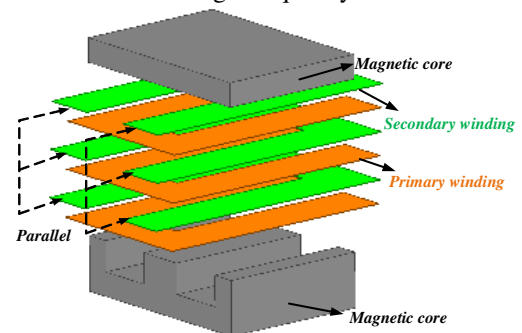


Fig. 1 3D view of the planar transformer

In this paper, a phenomenon is discovered that the currents on parallel conductors do not change with frequency from medium frequency and keeps constant at higher frequency. Additionally, previous research usually assumes the identical insulation thickness to analyze planar transformers. However, the insulation thickness usually varies from layer to layer in a practical PCB fabrication. This paper points out that the insulation thickness also affect the parallel current distribution through the comparison between Case I and Case II, as shown in Fig.3. In the worst scenario, the interleaving winding layout has lost its benefit of better current sharing.

The phenomenon that the magnetic flux between two parallel conductors approaches zero when parallel currents are frequency independent are proved theoretically and demonstrated experimentally. Together with Ampere's circuital law, the current distribution can be derived. No complex mathematical calculation or simulation tool is required. Dowell equations can be used to calculate the AC resistance afterward.

Any applications using planar transformers with parallel conductors operating at medium frequency or higher frequency can adopt this method to predict the parallel current distribution for design optimization.

## II. PARALLEL CURRENT DISTRIBUTION PRINCIPLE

The analyses given in section follows the “1-D” assumption: the electromagnetic field and current distribution within and around the conductor only vary along the thickness of the conductor (or insulation layer) [15][27]-[29]. The target winding layouts only have one conductor on each layer, and extremely small conductor-to-core clearances compared to the winding width. Besides, the 10% PCB manufacture tolerance, terminations using to measure parallel currents, and the accuracy of the measurement apparatus are not considered. The subsection A presents the theoretical support for the constant parallel current distribution and the cancelled flux at high frequency. The subsection B use simulations and the proposed method to predict parallel current distributions.

### A. Theoretical support for the cancelled flux between two parallel conductors

At high frequency operation, eddy current results in large power loss in winding conductors. It can be characterized by skin effect and proximity effect. The proximity effect in parallel conductors is introduced here. Fig.2 illustrates cross-section views of two planar windings. One primary conductor (P) carries high frequency sinusoidal current  $i_p(t)$ . Two secondary conductors ( $S_1$  and  $S_2$ ) are short circuited and connected in parallel. These conductors are closely spaced and the spacing between every conductor is identical for each layer. The transformer works in medium frequency or higher frequency. The skin depth is given by

$$\delta = \sqrt{\frac{\rho}{\pi \mu f}} \quad (1)$$

where  $f$  is the frequency;  $\mu$  and  $\rho$  are the permeability and the resistivity of the conductor, respectively. For a copper conductor,  $\mu$  is the same with the air permeability  $\mu_0$ .

In Fig.2 (a), a high frequency sinusoidal current  $i_p(t)$  in conductor P tends to the surface adjacent to conductor  $S_1$  due to the skin effect. A flux  $\Phi_1(t)$  is induced in the region between conductors P and  $S_1$ . This flux tends to penetrate conductor  $S_1$ . Based on Lenz’s law, there is a current induced on the upper part of conductor  $S_1$ . It attempts to cancel the flux  $\Phi_1(t)$ . As these conductors are closely spaced, the induced current in conductor  $S_1$  is identical with  $i_p(t)$  but in an opposite direction. Furthermore, the total current in secondary conductors is no larger than the primary current using Faraday’s law. Thus, no current runs through conductor  $S_2$ . Following Ampere’s circuital law which links the current to the magnetic field, the magnetic field  $H$  is plotted in Fig.2 (a).  $b$  is the window width of the magnetic core. It can be observed that there is no magnetic field  $H$  in the space between conductors  $S_1$  and  $S_2$ . This means magnetic flux  $\Phi_2(t)$  between two parallel conductors is zero. The phenomenon is also applied when the primary conductor P is sandwiched between two secondary conductors  $S_1$  and  $S_2$ , as shown in Fig.2 (b). The magnetic

fluxes induced by the conductor P,  $\Phi_1(t)$  and  $\Phi_2(t)$ , tend to penetrate conductors  $S_1$  and  $S_2$ , respectively.  $\Phi_1(t)$  and  $\Phi_2(t)$  are identical and opposite to each other. Thus, the current induced on the lower part of the conductor  $S_1$  is identical with the current induced on the upper part of the conductor  $S_2$ , which is half of the  $i_p(t)$ .

It can also be concluded that parallel currents are frequency-independent at high frequency from the above-mentioned analysis. For the winding layout shown in Fig.2 (a), the current flowing through conductor  $S_1$  is identical with  $i_p(t)$  but in an opposite direction. For the other winding layout shown in Fig.2 (b), each secondary conductor has  $i_p(t)/2$ .

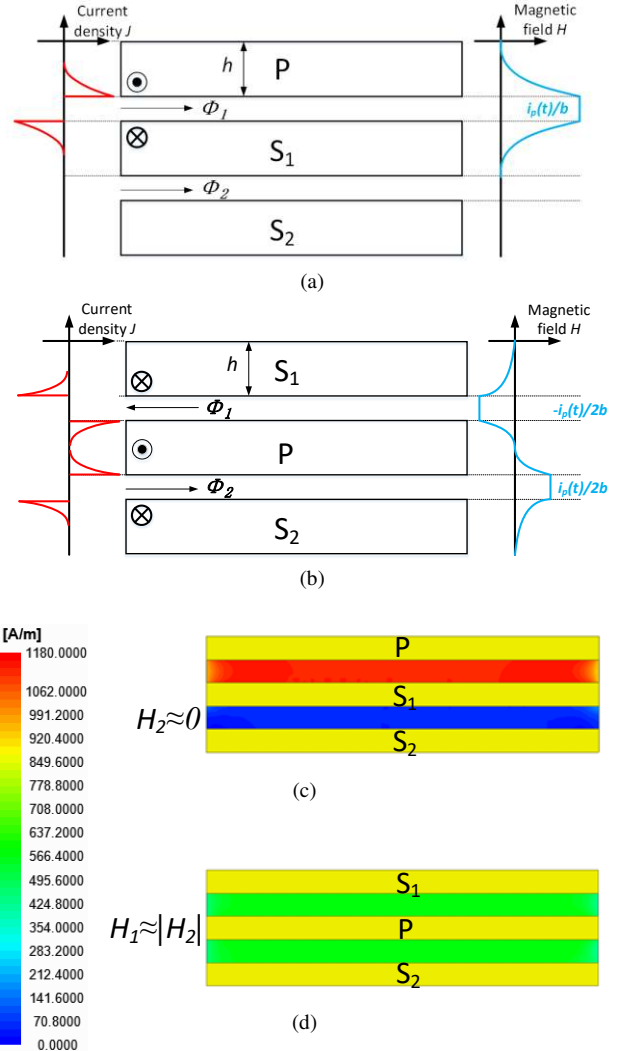


Fig.2 Two transformers (a) non-interleaved and (b) interleaved examples illustrating the proximity effect in parallel conductors. Conductor P carries  $i_p(t)$ . Conductors  $S_1$  and  $S_2$  are connected in parallel. Simulated  $H$  filed at 5MHz in insulation layers for (c) non-interleaved and (d) interleaved windings. The copper thickness is 105 $\mu$ m and the spacing is 100 $\mu$ m for each layer

These two windings, non-interleaved and interleaved winding layouts, are simulated in Ansys Maxwell 2D (finite element analysis) and the corresponding absolute  $H$  fields with the same color scale in insulation layers are plotted, as shown in Fig.2 (c) and (d). In Fig.2 (c), the magnetic field  $H_2$

approaches zero and thereby the magnetic flux  $\Phi_2$  approximates zero, as the magnetic flux is expressed by

$$\Phi = B \cdot S = \mu_0 H \cdot S \quad (2)$$

where  $B$  is flux density;  $S$  is the cross-section. In Fig.2 (d), the  $H_1$  and  $H_2$  are identical and opposite to each other, such that the magnetic flux between two parallel conductors  $\Phi_1 + \Phi_2 \approx 0$ . Hence, the simulation implies the effectiveness of the theoretical analysis.

From the above-mentioned analysis, it can be concluded that the magnetic flux in the space between two parallel conductors approaches zero at high frequency where eddy current effects dominate. Actually, the magnetic flux is also closing to zero in medium frequency range. The method proposed in the next part to predict the parallel current distribution can be applied to medium frequency. Despite the larger mismatch, it is still acceptable,

### B. Proposed approach to predict parallel current distributions

TABLE I  
WINDING DETAILS

Parameters	Values
Copper thickness ( $h$ )	70 $\mu$ m
Turn ratio ( $n:1$ )	2:1
Insulation thickness ( $t$ )	0.3mm
Window width ( $b$ )	9.275mm
Copper width ( $b_w$ )	8.5mm
Resistivity ( $\rho$ )	$1.71 \times 10^{-8}$ $\Omega$ /m
Air permeability ( $\mu_0$ )	$4\pi \times 10^{-7}$ H/m
Magnetic core	E32/6/20

Mean turn length (MTL) 20.32mm

This paper also discovers insulation thickness affects the current distribution. Ansys 2D Maxwell is used to simulate the parallel currents for two identical PCB winding layouts  $P_1S_2P_2S_1$  shown in Fig.3 (a) and (b). TABLE I illustrates details about the winding arrangement. Secondary conductors  $S_1$  and  $S_2$  are connected in parallel. Primary conductors  $P_1$  and  $P_2$  are in series. A sinusoidal current with the peak value  $I_p=1A$  is injected into each primary conductor. The boundary conditions are selected to be balloon. The mesh is also assigned before the simulation starts. The maximum element length is less than the skin depth. The current density is measured at 1 MHz with the same scale. Fig.3 (a) shows Case I with identical insulation thickness  $t_h=0.3$ mm for each layer, while Fig.3 (b) shows Case II with different insulation thicknesses. Since Case I and Case II have the same winding layout, the magnetic field  $H$  in every insulation layer in Case I is identical with that in Case II.

The currents distributed on  $S_2$  and  $S_1$  as a function of the frequency sweeping from 10kHz to 1GHz are shown in Fig.3 (c) and (d).  $I_{S1}$  and  $I_{S2}$  are peak currents (at  $\omega t = \pi/2$ ) on conductors  $S_1$  and  $S_2$ , respectively. It can be observed that the same winding layout yields different current distributions due to the different insulation thicknesses. In low frequency (LF) range (30 to 300kHz), the parallel currents are changing with frequency for Case I and Case II. They are becoming gradually stable in medium frequency (MF) range (0.3 to 3MHz), where two parallel conductors always carry the constant current no matter how the frequency changes in each case. In Case I,  $S_1$  and  $S_2$  carry about 1.5A and 0.5A, respectively. In Case II,  $S_2$

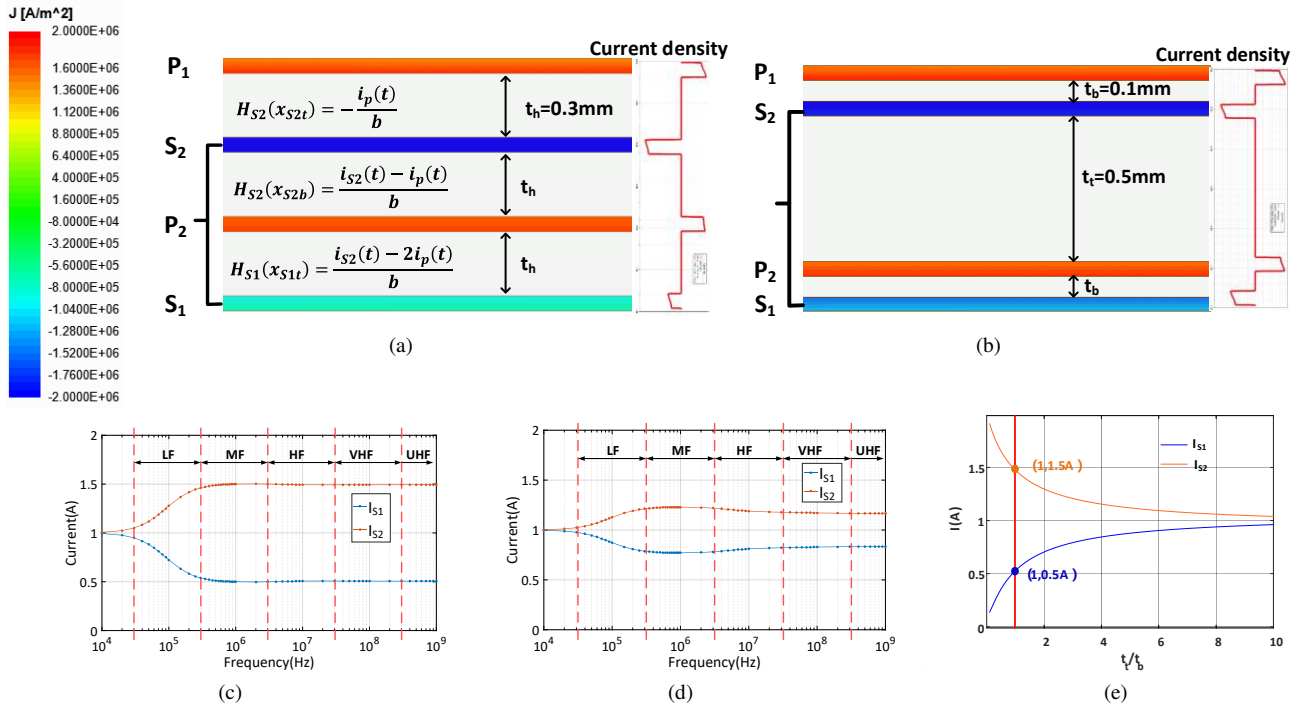


Fig.3 Investigation over the effect of the insulation thickness on parallel current distribution. (a) Case I has identical insulation thickness  $t_h$  for each layer. Case II has different insulation thicknesses. Current distributions as a function of frequency from 10kHz to 1GHz are measured for (c) Case I and (d) Case II. From 10kHz to 100kHz, parallel currents  $I_1$  and  $I_2$  are measured every 10kHz. From 100kHz to 1MHz, they are measured every 50kHz. From 1MHz to 10MHz, the scale is 1MHz. From 10 MHz to 100MHz, the scale changes to 10MHz. From 100MHz to 1GHz, the sample scale is 100MHz. (e)  $I_1$  and  $I_2$  versus insulation ratio  $t_t/t_b$  with  $t_t + t_b = 0.6$ mm at 1 MHz

conducts around 1.23A, while  $S_1$  carries 0.77A. In higher frequency ranges,  $S_1$  and  $S_2$  in Case I still keeps constant. Case II shows a small change, but almost follow the same pattern illustrated in medium frequency.  $S_2$  conducts 1.18A and  $S_1$  has 0.82 A.

To further analyze the insulation impact on parallel current distribution at high frequency,  $I_{S1}$  and  $I_{S2}$  as a function of the insulation ratio  $t/t_b$  with the constant  $t_r+t_b=0.6\text{mm}$  are plotted in Fig.3 (e). The frequency is set at 1MHz where the current distribution is obviously constant. It can be observed that the smaller insulation ratio  $t/t_b$  yields a much higher current on  $I_2$  but lower current on  $I_{S1}$ . By contrast, the parallel winding tends to have more uniformly distributed currents with larger insulation ratio  $t/t_b$ .

From the above analyses, it can be concluded: 1) the parallel current distribution is gradually becoming frequency independent in medium frequency range and still following almost the same pattern in higher frequency ranges; 2) the insulation thickness affects the current distribution.

In order to predict the current distribution with the consideration of the insulation thickness, the discovered phenomena in parallel conductors is used here. No simulation tool or complex calculation is required. For Case I, the magnetic flux in the space between conductors  $S_1$  and  $S_2$  is expressed by

$$\begin{aligned}\Phi_{12} &= \mu_o l t_h (H_{S_2}(x_{S_2b}) + H_{S_1}(x_{S_1t})) \\ &= \frac{\mu_o l t_h}{b} (2i_{S_2}(t) - 3i_p(t))\end{aligned}\quad (3)$$

$$H_{S_2}(x_{S_2b}) = \frac{i_{S_2}(t) - i_p(t)}{b}\quad (4)$$

$$H_{S_1}(x_{S_1t}) = \frac{i_{S_2}(t) - 2i_p(t)}{b}\quad (5)$$

where  $\mu_o$  is the air permeability;  $l$  is the mean turn length (MTL);  $b$  is the window width;  $H_{S_2}(x_{S_2b})$  and  $H_{S_1}(x_{S_1t})$  are magnetic fields in the insulation layer, as shown in Fig.3 (a).  $H_{S_2}(x_{S_2b})$  is the magnetic field along the bottom surface of the conductor  $S_2$ ;  $H_{S_1}(x_{S_1t})$  is the magnetic field along the top surface of the conductor  $S_1$ . Assume the secondary winding perfectly couples with the primary winding. The total secondary current is thus given by

$$i_{S_1}(t) + i_{S_2}(t) = 2i_p(t)\quad (6)$$

where  $i_{S_1}(t)$  and  $i_{S_2}(t)$  are the currents on conductors  $S_1$  and  $S_2$  respectively. Using the discovered phenomenon that the magnetic flux in the space between two parallel conductors approaches zero at high frequency, (3) is assigned to be zero. Combining (3) and (6), the parallel currents for Case I are solved by

$$\begin{cases} i_{S_1}(t) = i_p(t)/2 \\ i_{S_2}(t) = 3i_p(t)/2 \end{cases}\quad (7)$$

Likewise, for Case II, the magnetic flux in the space between conductors  $S_1$  and  $S_2$  is expressed by

$$\begin{aligned}\Phi_{12} &= \mu_o l (H_{S_2}(x_{S_2b})t_r + H_{S_1}(x_{S_1t})t_b) \\ &= \frac{\mu_o l}{b} [i_{S_2}(t)(t_r + t_b) - i_p(t)(t_r + 2t_b)]\end{aligned}\quad (8)$$

Assign (8) to be zero, and combine (6) and (8). The parallel currents for Case II are solved by

$$\begin{cases} i_{S_1}(t) = i_p(t)t_r / (t_r + t_b) = 0.833i_p(t) \\ i_{S_2}(t) = i_p(t)(t_r + 2t_b) / (t_r + t_b) = 1.167i_p(t) \end{cases}\quad (9)$$

Assume the primary peak current  $I_p=1\text{A}$ . Recall the simulated current distribution on each parallel conductor at high frequency. The calculation shows excellent agreement with the simulation. Hence, the simulation suggests our finding that the magnetic flux in the space between two parallel conductors approaches zero at high frequency.

The proposed method and discovered phenomena can be applied to any parallel connections and winding layouts. The following part theoretically and mathematically proves our findings.

### III. THEORETICAL AND MATHEMATICAL PROOF FOR FINDINGS

The current distribution is analyzed in this part based on the same assumptions given initially in Section II.

The current distribution in parallel conductors can be derived by Faraday's law and Kirchhoff's law. The model is illustrated in Fig.4 (a). The magnetic flux  $\Phi_{12}$  flowing through the space between conductors  $S_1$  and  $S_2$  can be expressed by the current densities ( $J_1$  and  $J_2$ ) on the surfaces. Additionally, assume the primary windings perfectly couples with secondary windings. The sum of the secondary currents is thus  $2i_p(t)$ , such that

$$\underbrace{\rho l}_{\Omega \cdot \text{m}^2} \underbrace{(J_1 - J_2)}_{\text{A/m}^2} = \underbrace{j\omega\Phi_{12}}_V\quad (10)$$

$$i_{S_1}(t) + i_{S_2}(t) = 2i_p(t)\quad (11)$$

where  $\rho$  is the conductor resistivity;  $l$  is the conductor mean turn length (MTL);  $J_1$  is the current density on the top surface of the conductor  $S_1$ ;  $J_2$  is the current density on the bottom surface of the conductor  $S_2$ ;  $\Phi_{12}$  is the magnetic flux flowing through the loop formed by  $J_1$  and  $J_2$ ;  $i_{S_1}(t)$  and  $i_{S_2}(t)$  are currents on  $S_2$  and  $S_1$ , respectively.

The magnetic field inside the conductor is described by the Helmholtz equation.

$$\frac{d^2 H_{S_2}(x)}{dx^2} = \gamma^2 H_{S_2}(x)\quad (12)$$

where the complex propagation constant  $\gamma$  is

$$\gamma = \frac{1+j}{\delta}\quad (13)$$

A general solution of the Helmholtz equation is

$$H_i(x) = H_1 e^{\gamma x} + H_2 e^{-\gamma x}\quad (14)$$

Fig.4 (b) shows an  $i^{\text{th}}$  conductor in a planar transformer. The center of the coordinate system is located in the center of the magnetic core.  $x_{it}$  and  $x_{ib}$  are the distances from y-axis to the top and bottom surfaces of the  $i^{\text{th}}$  conductor, respectively. From the boundary conditions,  $H_{ib}$  and  $H_{it}$ , the magnetic field in the  $i^{\text{th}}$  conductor  $H_i$  is expressed by

$$\begin{cases} H_i(x_{it}) = H_1 e^{\gamma x_{it}} + H_2 e^{-\gamma x_{it}} = H_{it} \\ H_i(x_{ib}) = H_1 e^{\gamma x_{ib}} + H_2 e^{-\gamma x_{ib}} = H_{ib} \end{cases} \quad (15)$$

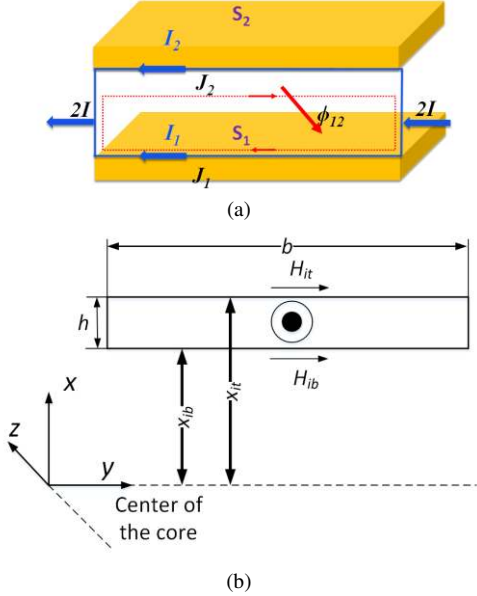


Fig.4 Theoretical verification of the parallel current distributions. (a) Model of two parallel layers. (b) An  $i^{\text{th}}$  conductor in a planar transformer.

$H_1$  and  $H_2$  can be solved by

$$H_1 = H_{it} \frac{\cosh(\gamma x_{ib}) - \sinh(\gamma x_{ib})}{2 \sinh(\gamma h)} + H_{ib} \frac{\sinh(\gamma x_{it}) - \cosh(\gamma x_{it})}{2 \sinh(\gamma h)} \quad (16)$$

$$H_2 = -H_{it} \frac{\sinh(\gamma x_{ib}) + \cosh(\gamma x_{ib})}{2 \sinh(\gamma h)} + H_{ib} \frac{\cosh(\gamma x_{it}) + \sinh(\gamma x_{it})}{2 \sinh(\gamma h)} \quad (17)$$

The magnetic field  $H_i(x)$  in the conductor is thus given by

$$H_i(x) = \frac{H_{it} \sinh(\gamma(x - x_{ib})) - H_{ib} \sinh(\gamma(x - x_{it}))}{\sinh(\gamma h)} \quad (18)$$

The current density expression for the  $i^{\text{th}}$  conductor  $J_i(x)$  is then derived by

$$J_i(x) = -\frac{dH_i(x)}{dx} = \gamma \frac{H_{ib} \cosh(\gamma(x - x_{it})) - H_{it} \cosh(\gamma(x - x_{ib}))}{\sinh(\gamma h)} \quad (19)$$

In Case I, the magnetic flux  $\Phi_{12}$  is rewritten here

$$\Phi_{12} = \mu_o l t_h (H_{S2}(x_{S2b}) + H_{S1}(x_{S1r})) \quad (20)$$

$$H_{S2}(x_{S2b}) = \frac{i_{S2}(t) - i_p(t)}{b} \quad (21)$$

$$H_{S1}(x_{S1r}) = \frac{i_{S2}(t) - 2i_p(t)}{b} = -\frac{i_{S1}(t)}{b} \quad (22)$$

In Case II, the magnetic flux  $\Phi_{12}$  is also rewritten here

$$\Phi_{12} = \mu_o l (t_r \cdot H_{S2}(x_{S2b}) + t_b \cdot H_{S1}(x_{S1r})) \quad (23)$$

Combining (10), (11) and (19) to (23),  $i_{S1}(t)$  and  $i_{S2}(t)$  for each case can be solved. For Case I, the expressions for  $i_{S1}(t)$  and  $i_{S2}(t)$  are

$$i_{S1}(t) = I_p \left( \frac{jw\mu_o t_h \left( \sin(wt) - \frac{1}{2} \right) \cdot \sinh(\gamma h)}{jw\mu_o t_h \cdot \sinh(\gamma h) - \gamma\rho \cdot \cosh(\gamma h)} - \frac{\gamma\rho \left( \left( \sin(wt) - \frac{1}{2} \right) \cdot \cosh(\gamma h) + \frac{1}{2} \right)}{jw\mu_o t_h \cdot \sinh(\gamma h) - \gamma\rho \cdot \cosh(\gamma h)} \right) \quad (24)$$

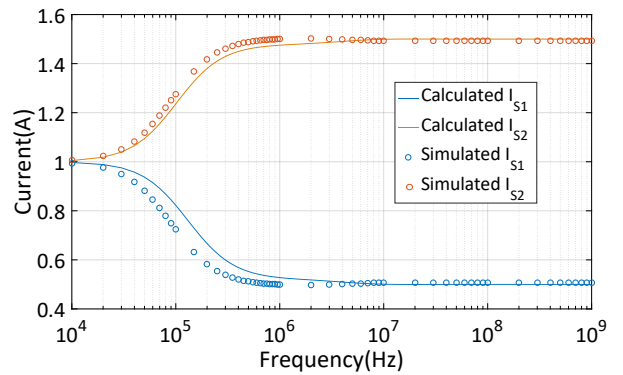
$$i_{S2}(t) = I_p \left( \frac{\left( \sin(wt) + \frac{1}{2} \right) \cdot jw\mu_o t_h \cdot \sinh(\gamma h)}{jw\mu_o t_h \cdot \sinh(\gamma h) - \gamma\rho \cdot \cosh(\gamma h)} - \frac{\gamma\rho \cdot \left( \left( \sin(wt) + \frac{1}{2} \right) \cdot \cosh(\gamma h) - \frac{1}{2} \right)}{jw\mu_o t_h \cdot \sinh(\gamma h) - \gamma\rho \cdot \cosh(\gamma h)} \right) \quad (25)$$

For Case II, the expressions for  $i_{S1}(t)$  and  $i_{S2}(t)$  are

$$i_{S1}(t) = I_p \left( \frac{jw\mu_o t_r \cdot (2 \sin(wt) - 1) \cdot \sinh(\gamma h)}{jw\mu_o (t_b + t_r) \cdot \sinh(\gamma h) - 2\gamma\rho \cdot \cosh(\gamma h)} - \frac{\gamma\rho \left( (2 \sin(wt) - 1) \cdot \cosh(\gamma h) + 1 \right)}{jw\mu_o (t_b + t_r) \cdot \sinh(\gamma h) - 2\gamma\rho \cdot \cosh(\gamma h)} \right) \quad (26)$$

$$i_{S2}(t) = I_p \left( \frac{jw\mu_o (2t_b \sin(wt) + t_r) \cdot \sinh(\gamma h)}{jw\mu_o (t_b + t_r) \cdot \sinh(\gamma h) - 2\gamma\rho \cdot \cosh(\gamma h)} - \frac{\gamma\rho \left( (2 \sin(wt) + 1) \cdot \cosh(\gamma h) - 1 \right)}{jw\mu_o (t_b + t_r) \cdot \sinh(\gamma h) - 2\gamma\rho \cdot \cosh(\gamma h)} \right) \quad (27)$$

Fig.5 (a) and (b) show  $I_{S1}$  and  $I_{S2}$  as a function of the frequency for Case I and Case II, respectively. The calculated instants  $I_{S1}$  and  $I_{S2}$  are peak currents of (26) and (27), respectively. The theoretical results illustrate excellent agreement with the simulation for Case I. There is a maximum 10% mismatch between the calculation and simulation for Case II, because of the assumption that the primary windings perfectly couples with secondary windings.



(a)

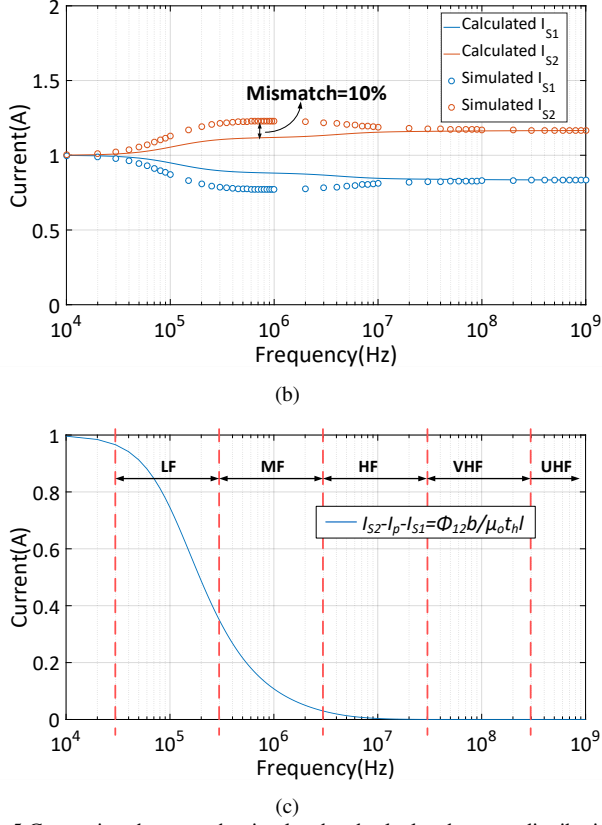


Fig.5 Comparison between the simulated and calculated current distribution for (a) Case I and (b) Case II. (c)  $I_{S2}-I_p-I_{S1}$  versus frequency for Case I

Equations (10) and (11) are not limited to 2 parallel layers, but any parallel connections. However, solving these equations is becoming extremely time-consuming and complex when it comes to multiple turns in parallel and varying insulation thicknesses for each layer. The phenomena and the straightforward method proposed in this paper can be used to predict the parallel current distribution at medium frequency or higher frequency. To suggest our finding, (20), (21) and (22) are rearranged. The new relation among  $i_{S1}(t)$ ,  $i_{S2}(t)$ ,  $i_p(t)$  and  $\Phi_{12}$  can be found, as given in (28).

$$i_{S2}(t) - i_p(t) - i_{S1}(t) = \frac{\Phi_{12}b}{\mu_o t_h l} \quad (28)$$

Equation (28) as a function of the frequency at  $\omega t = \pi/2$  (peak currents) is illustrated in Fig.5 (c). The curve approaches zero as the frequency increases, which implies the effectiveness of our findings.

To further prove our findings can be applied to any parallel connections, two winding layouts are analyzed in the next section.

#### IV. DEMONSTRATIONS OF THE PROPOSED THEORY

The following analyses consider that: 1) the excitation to every primary conductor is a sinusoidal current; 2) the calculated currents are the amplitudes at  $\omega t = \pi/2$ ; 3) Except for the different insulation thicknesses, other parameters keeps the same with TABLE I. To suggest the effectiveness of our finding,

the theory mentioned in Section II is used to predict the current distribution. Two different parallel connections with identical copper thickness  $h=70\mu m$  for each conductor, as shown in Fig.6 (a) and (b), will be discussed in the subsequent part.

For Case III, 4 primary conductors are connected in series, while 4 secondary conductors are in parallel. The currents on primary conductors, namely  $I_{p1}$ ,  $I_{p2}$ ,  $I_{p3}$ , and  $I_{p4}$ , are thus identical. Using the proposed method, as given in (29), the parallel current distribution can be solved.

$$\begin{cases} \Phi_{12} = \mu_o l(t_{h2}H_{m2} + t_{h3}H_{m3}) = 0 \\ \Phi_{23} = \mu_o l(t_{h4}H_{m4} + t_{h5}H_{m5}) = 0 \\ \Phi_{34} = \mu_o l(t_{h6}H_{m6} + t_{h7}H_{m7}) = 0 \\ I_1 + I_2 + I_3 + I_4 = 4I_p \end{cases} \quad (29)$$

where  $\Phi_{12}$ ,  $\Phi_{23}$  and  $\Phi_{34}$  are the magnetic fluxes between conductors  $S_1$  and  $S_2$ ,  $S_1$  and  $S_2$ , and  $S_3$  and  $S_4$ , respectively;  $I_1$ ,  $I_2$ ,  $I_3$ , and  $I_4$  are secondary peak currents on  $S_1$ ,  $S_2$ ,  $S_3$ , and  $S_4$ , separately;  $I_p$  is the peak current on each primary conductor. Other quantities can be found in Fig.6 (a) and (b).

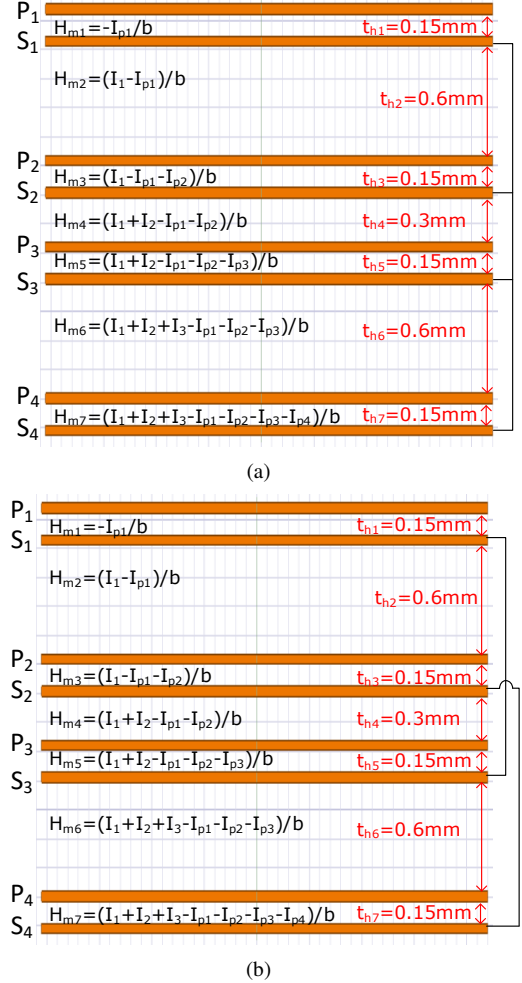


Fig.6 Two different winding layouts (a) Case III: a 4:1 winding layout with  $H$  field in insulation layer; (b) Case IV: a 4:2 winding layout with  $H$  field in insulation layer.

Case IV is a 4:2 winding layout whose primary conductors are in series, and secondary conductors are series-parallel

connected. Conductors  $S_1$  and  $S_3$ ,  $S_2$  and  $S_4$  are in parallel, respectively. 4 parallel currents can be solved from (30) which represents the magnetic fluxes between two parallel conductors and current balances.

$$\begin{cases} \Phi_{13} = \mu_o l(t_{h2}H_{m2} + t_{h3}H_{m3} + t_{h4}H_{m4} + t_{h5}H_{m5}) = 0 \\ \Phi_{24} = \mu_o l(t_{h4}H_{m4} + t_{h5}H_{m5} + t_{h6}H_{m6} + t_{h7}H_{m7}) = 0 \\ I_1 + I_3 = 2I_p \\ I_2 + I_4 = 2I_p \end{cases} \quad (30)$$

To prove the validity of the calculation, TABLE II and TABLE III present the comparisons between the Ansys Maxwell 2D simulation at 1MHz and the calculated results for Case III and Case IV. The total secondary current is less than 4A in simulation as the leakage energy is considered. The proposed method suggests an excellent performance: the calculated parallel current on each conductor illustrates good consistency with the simulation. The maximum mismatch is below 9%, which is primarily due to the assumption that secondary and primary windings are perfectly coupled with each other.

TABLE II  
CASE III: COMPARISON BETWEEN SIMULATION AND CALCULATION

Quantities	Simulation (A)	Calculation (A)	Error
$I_1$	1.229	1.2	2.4%
$I_2$	1.117	1.133	1.4%
$I_3$	0.863	0.867	0.5%
$I_4$	0.74	0.8	8.1%
Total	3.949	4	-

TABLE III  
CASE IV: COMPARISON BETWEEN SIMULATION AND CALCULATION

Quantities	Simulation (A)	Calculation (A)	Error
$I_1$	1.18	1.182	0.17%
$I_2$	1.2	1.182	1.5%
$I_3$	0.78	0.818	4.8%
$I_4$	0.76	0.818	7.6%
Total	3.92	4	-

Acknowledging the current distribution on each conductor, the AC resistance  $R_{ac}$  for each case can be determined afterward. The power loss of a conductor is calculated by (31)

$$P = \frac{1}{2} \rho b l \int_{x_m}^{x_n} |J|^2 dx \quad (31)$$

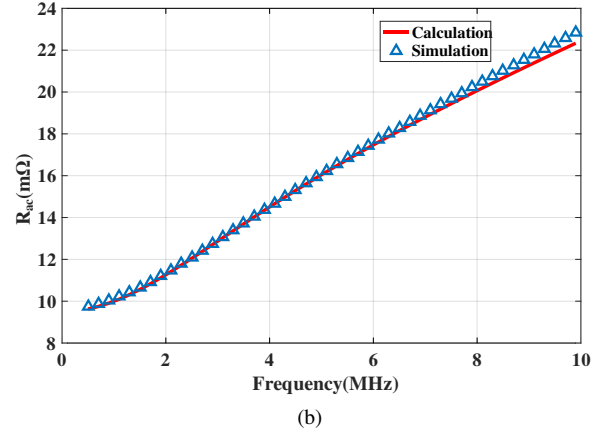
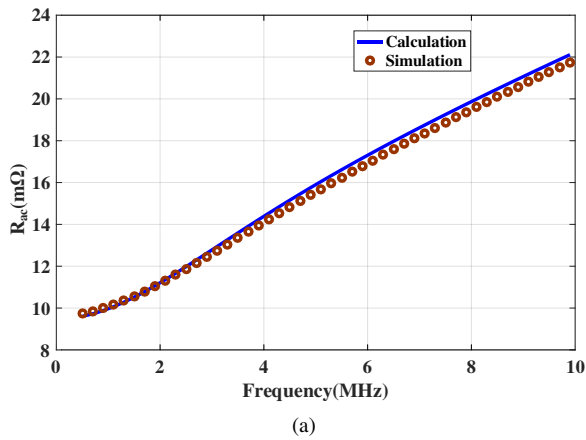


Fig.7 Comparisons between the calculated AC resistance and simulated AC resistance for (a) Case III and (b) Case IV

Fig.7 shows the calculated AC resistance and simulated AC resistance as a function of frequency for each case. The excellent agreement further proves the effectiveness of the propose method.

TABLE IV  
WINDING DETAILS

Parameters	Values
Copper thickness ( $h$ )	70 $\mu$ m
Turn ratio ( $n:I$ )	2:1
Window width ( $b$ )	5.9mm
Winding width ( $b_w$ )	4.8mm
Core material	ML91S
Relative permeability of the core( $\mu_c$ )	900
Magnetic core	E22/6/16

## V. EXPERIMENT

This paper demonstrated the theory presented above in an experiment. The two PCB winding layouts, Case III and Case IV, are fabricated. The magnetic core is E22/6/16. The insulation and copper thickness for each layer keeps almost the same with Fig.6 (a) and (b), respectively, despite the 10% PCB manufacture tolerance. Other details are summarized in TABLE IV. To show the insulation thicknesses satisfy the requirement, the PCB is cut off and the cross-section view captured by the Micromanipulator 2210-LS is presented in Fig.8 (a). The experiment setup is shown in Fig.8 (b) and (c). The bipolar amplifier HSA4101 provides the sinusoidal voltage excitation to the primary winding. Secondary conductors were short circuited. The primary current was measured by the current probe AP015 from Lecory. The bandwidth is up to 50MHz. The current probe CWT 015 Ultramini from PEM was used to measure the secondary current of one conductor. The sensitivity is 200mV/A and the bandwidth ranges from 116Hz to 30MHz.



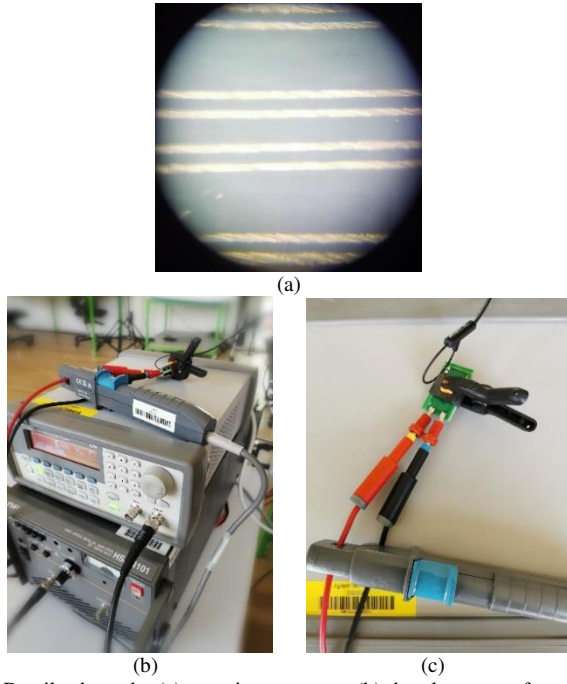


Fig.8 Details about the (a) experiment setups, (b) the planar transformer with current probes, and (c) PCB cross section view captured by Micromanipulator 2210-LS.

Under the same 4V peak-to-peak sinusoidal voltage excitation, the current waveforms on each secondary conductor at 1MHz for Case III were measured and captured in Fig.9. Currents on conductor  $S_1$  and  $S_2$  shows higher amplitude than currents on conductors  $S_3$  and  $S_4$ . The corresponding current amplitudes and the ratios of the peak current on each conductor over the secondary average peak current are documented in TABLE V. Compared with the theoretical calculation, the maximum error is below 7%. Likewise, the same procedure is performed for Case IV. Fig. 10 shows the secondary and primary current waveforms and TABLE VI illustrates the comparison between the experiment and calculation. The maximum mismatch is also below 7%.

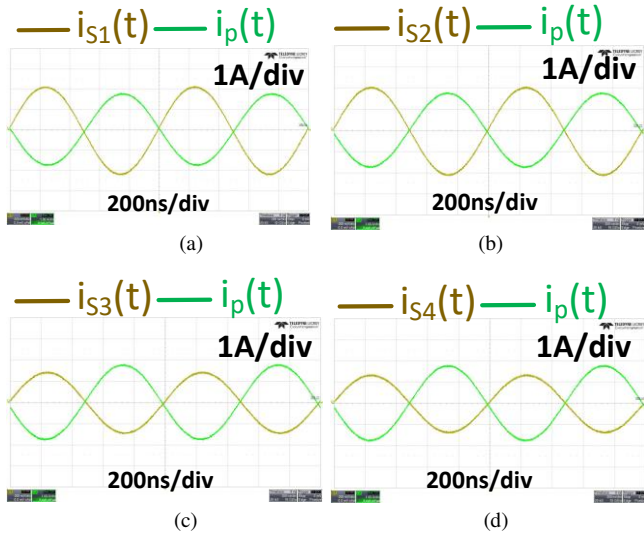


Fig.9 Current waveforms at 1MHz with 4V voltage excitation for Case III: (a) the current on conductor  $S_1$  and the primary current waveforms. (b) the current

on conductor  $S_2$  and the primary current waveforms.(c) the current on conductor  $S_3$  and the primary current waveforms.(d) the current on conductor  $S_4$  and the primary current waveforms

TABLE V  
CASE III: COMPARISON BETWEEN EXPERIMENT AND CALCULATION

Peak currents	Experiment (mA)	Experiment ratios ( $4I_i/I_{total}$ )	Calculation ratios	Error(%)
$I_1$	2157	1.25	1.2	3.90
$I_2$	2001	1.15	1.133	2.21
$I_3$	1407	0.814	0.867	6.41
$I_4$	1343	0.777	0.8	2.84
Total ( $I_{total}$ )	6908	-	-	-

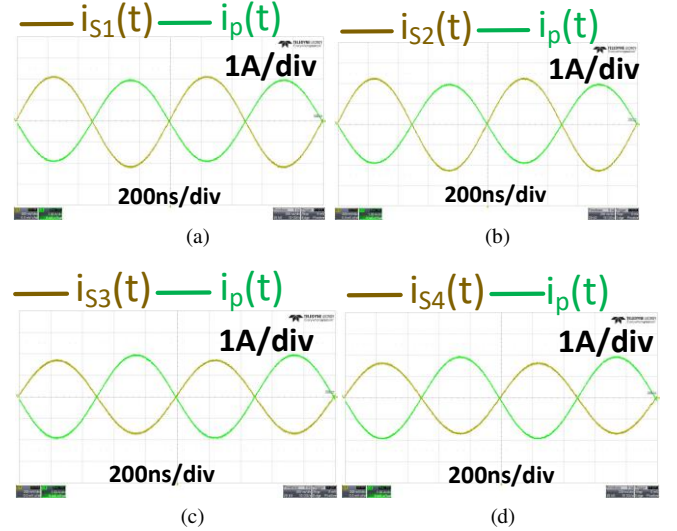
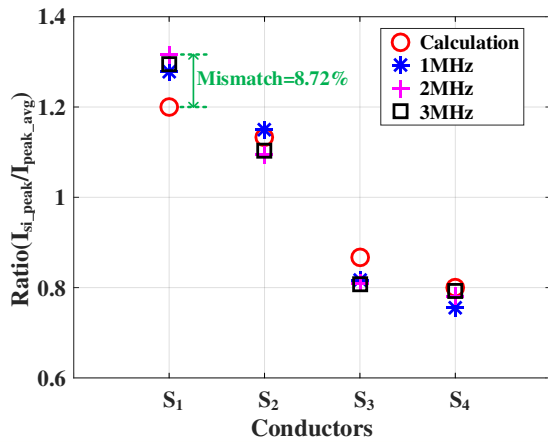


Fig.10 Current waveforms at 1MHz with 4V voltage excitation for Case IV: (a) the current on conductor  $S_1$  and the primary current waveforms. (b) the current on conductor  $S_2$  and the primary current waveforms.(c) the current on conductor  $S_3$  and the primary current waveforms.(d) the current on conductor  $S_4$  and the primary current waveforms

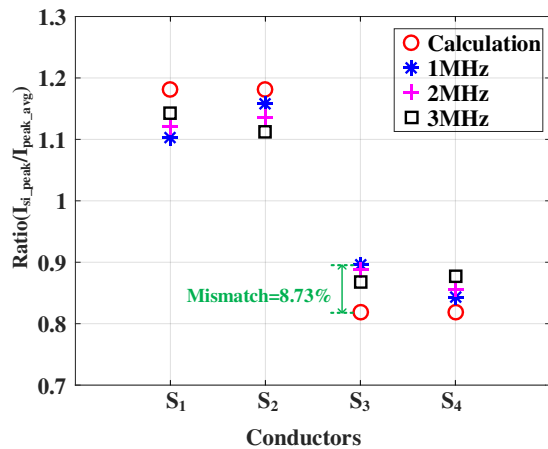
TABLE VI  
CASE IV: COMPARISON BETWEEN EXPERIMENT AND CALCULATION

Peak currents	Experiment (mA)	Experiment ratios ( $4I_i/I_{total}$ )	Calculation ratios	Error(%)
$I_1$	2220	1.14	1.2	4.90
$I_2$	2178	1.12	1.133	1.15
$I_3$	1711	0.884	0.867	1.65
$I_4$	1654	0.852	0.8	6.15
Total ( $I_{total}$ )	7764	-	-	-

To minimize the measurement error, the peak currents are measured at 3 different frequencies, namely 1MHz, 2MHz and 3MHz. The peak parallel currents are measured 4 times with 4 different sinusoidal voltage excitations at every frequency. The average ratios of the peak current on each conductor over the secondary average peak current at every frequency are documented and compared with the calculation, as shown in Fig.11 (a) and (b). The maximum mismatch 8.72% happened to the conductor  $S_1$  at 2MHz for Case III. The comparison for Case IV is represented in Fig.11 (b). The maximum mismatch 8.73% occurs to conductor  $S_3$  at 1MHz. Thus, a mismatch of less than 10% implies that our findings are correct.



(a)



(b)

Fig.11 The comparisons between the calculated current ratios and the measured current ratios at 1MHz, 2MHz and 3MHz are given in (a) Case III and (b) Case IV.

## VI. PRACTICAL CONSIDERATIONS

### A. Copper thickness

The proposed method can be used in a planar transformer with arbitrary insulation thicknesses for each layer. Only one premise is required: the transformer is operating at medium or high frequency where the parallel current becomes independent of frequency. If the copper thickness is much thinner than the skin depth, the parallel currents are varying with frequency. Thereby, the proposed method cannot be applied to predict the parallel current distribution.

### B. Conductor-to-core clearances

In practical fabrications of PCBs, clearances have to be inserted between conductors and PCB edges. These clearances influence the dissipated loss and accumulate the reactive energy. Throughout the discussion, this paper focus on winding layouts which have only one conductor on each layer, and extremely small conductor-to-core clearances compared to winding width. Thus, the contribution of edge effects can be neglected[27].

### C. Air gaps

Fringing effects induced by air gaps change the current distribution and lead to a mismatch between calculation and

experiment. However, fringing effects have negligible influence when conductors are located away from air gaps. In Literature [30], it concludes that air gaps have insignificant influence if the spacing between the gap and the conductor is at least one forth larger than the window width.

### D. Measurement

In the theoretical analysis, the PCB manufacture tolerance, terminations using to measure the parallel currents, and the accuracy of the measurement apparatus are not considered. However, these factors may lead to the mismatch in the experiment.

## VII. CONCLUSIONS

This paper predict the parallel current distribution in planar transformers. This paper present the findings that the parallel current is gradually becoming constant in medium frequency and still following almost the same pattern in higher frequency ranges, and it is also dependent by the insulation thickness. The phenomenon that the magnetic flux between two parallel conductors is close to zero from medium frequency is proposed theoretically and demonstrate experimentally that. Together with Ampere's circuital law, the parallel current distribution for planar transformers at high frequency can be derived. This approach does not require complex mathematical calculation or simulation tools. Any applications using planar transformers with parallel conductors at medium or higher frequency can adopt this method to effectively predict the parallel current distribution for design optimization.

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